

Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Typ	Max	Unit
Output Voltage Set-point (V _{IN} =I _{N, min} , I _O =I _{O, max} , T _A =25°C)	All	V _{O, set}	-2.0	V _{O, set}	+2.0	% V _{O, set}
Output Voltage (Over all operating input voltage, resistive load, and temperature conditions until end of life)	All	V _{O, set}	-2.5%	—	+3.5%	% V _{O, set}
Adjustment Range Selected by an external resistor	All	V _O	0.7525		5.5	Vdc
Output Regulation Line (V _{IN} =V _{IN, min} to V _{IN, max}) Load (I _O =I _{O, min} to I _{O, max}) Temperature (T _{ref} =T _{A, min} to T _{A, max})	All All All		— — —	0.3 0.4 0.4	— — —	% V _{O, set} % V _{O, set} % V _{O, set}
Output Ripple and Noise on nominal output (V _{IN} =V _{IN, nom} and I _O =I _{O, min} to I _{O, max} Cout = 1μF ceramic//10μFtantalum capacitors) RMS (5Hz to 20MHz bandwidth) Peak-to-Peak (5Hz to 20MHz bandwidth)	 All All		 — —	 12 30	 30 75	 mV _{rms} mV _{pk-pk}
External Capacitance ESR ≥ 1 mΩ ESR ≥ 10 mΩ	All All	C _{O, max} C _{O, max}	— —	— —	1000 5000	μF μF
Output Current	All	I _o	0		16	Adc
Output Current Limit Inception (Hiccup Mode) (V _O = 90% of V _{O, set})	All	I _{O, lim}	—	180	—	% I _o
Output Short-Circuit Current (V _O ≤250mV) (Hiccup Mode)	All	I _{O, s/c}	—	3	—	Adc
Efficiency V _{IN} = V _{IN, nom} , T _A =25°C I _o =I _{O, max} , V _O = V _{O, set}	V _{O, set} = 0.75Vdc V _{O, set} = 1.2Vdc V _{O, set} = 1.5Vdc V _{O, set} = 1.8Vdc V _{O, set} = 2.5Vdc V _{O, set} = 3.3Vdc V _{O, set} = 5.0Vdc	η η η η η η η		79.0 85.0 87.0 88.0 90.5 92.0 94.0		% % % % % % %
Switching Frequency	All	f _{sw}	—	300	—	kHz
Dynamic Load Response (dI _o /dt=2.5A/μs; V _{IN} = V _{IN, nom} ; T _A =25°C) Load Change from I _o = 50% to 100% of I _{o,max} ; 1μF ceramic// 10 μF tantalum Peak Deviation Settling Time (Vo<10% peak deviation) (dI _o /dt=2.5A/μs; V _{IN} = V _{IN, nom} ; T _A =25°C) Load Change from I _o = 100% to 50%of I _{o,max} : 1μF ceramic// 10 μF tantalum Peak Deviation Settling Time (Vo<10% peak deviation)	All All All All	V _{pk} t _s V _{pk} t _s	— — — —	200 25 200 25	— — — —	mV μs mV μs

Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Typ	Max	Unit
Dynamic Load Response ($dI_o/dt=2.5A/\mu s$; $V_{IN} = V_{IN, nom}$; $T_A=25^\circ C$) Load Change from $I_o = 50\%$ to 100% of $I_{o,max}$; $C_o = 2 \times 150 \mu F$ polymer capacitors Peak Deviation	All	V_{pk}	—	100	—	mV
Settling Time ($V_o < 10\%$ peak deviation)	All	t_s	—	50	—	μs
($dI_o/dt=2.5A/\mu s$; $V_{IN} = V_{IN, nom}$; $T_A=25^\circ C$) Load Change from $I_o = 100\%$ to 50% of $I_{o,max}$; $C_o = 2 \times 150 \mu F$ polymer capacitors Peak Deviation	All	V_{pk}	—	100	—	mV
Settling Time ($V_o < 10\%$ peak deviation)	All	t_s	—	50	—	μs

General Specifications

Parameter	Min	Typ	Max	Unit
Calculated MTBF ($I_o = I_{o, max}$, $T_A=25^\circ C$) Telecordia SR-332 Issue 1: Method 1 Case 3	9,230,550			Hours
Weight	—	5.6 (0.2)	—	g (oz.)