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The Technology Company



AMP

Hollow Shaft Resolver

Tyco Electronics

Growing to meet your electronic component and system needs

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Hollow Shaft Resolver

General Description

The use of sensors for determining angles increases with progressive automation. The hollow shaft resolver has long won its own steady position on the market and can nowadays be found in many modern, high-precision control systems.

Due to its design, the hollow shaft resolver boasts of a service life above average. Reliability as well as high precision and low space requirements supplement its favorable characteristics. It remains fully operable even under extreme environmental conditions.

Essentially, the resolver mechanically consists of a stationary stator and a movable rotor. Electrically it consists of a transformer for supplying the rotor with power and a second transformer for determining angles.

The first transformer has a concentric design and is functionally independent of angle values. The second, angle-dependent transformer is made of a stator winding and a rotor winding. The windings of these two transformer components are designed such that the number of windings in the grooves correspond to the values of a sinoid.

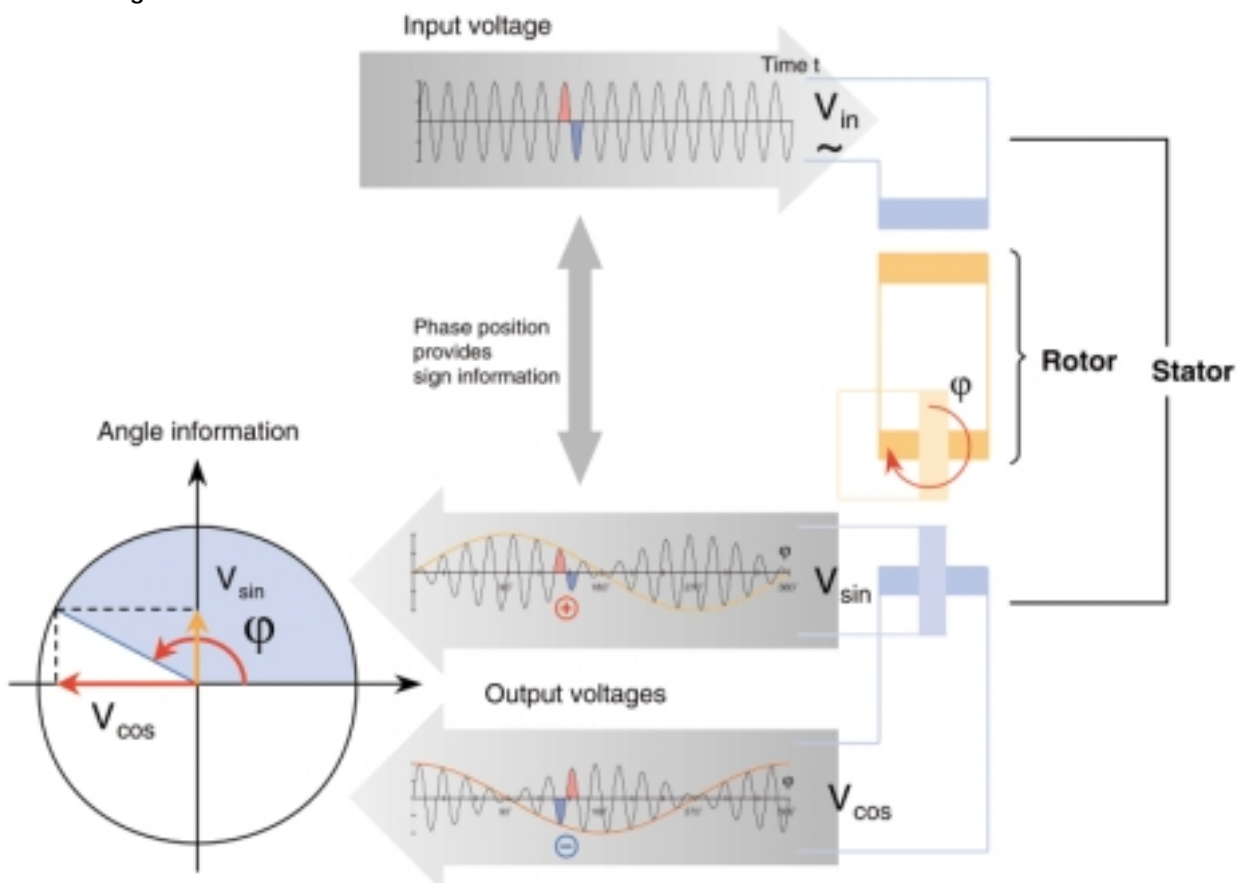
Negative values are realized by reversing the direction of the winding. The stator coils consist of two similar windings that are fitted in a relative position to each other rotated by 90° .

If the rotor winding is energized, a sinusoidal magnetic flux is created that induces voltages in the stator coils as a function of the relative angular position of the rotor and stator. The amplitudes of the two voltages correspond to the sine or cosine. Thus, using a suitable evaluation circuit, it is possible to obtain the absolute angle data.

The term used for the basic version is a resolver with one pair of poles (1-speed-resolver).

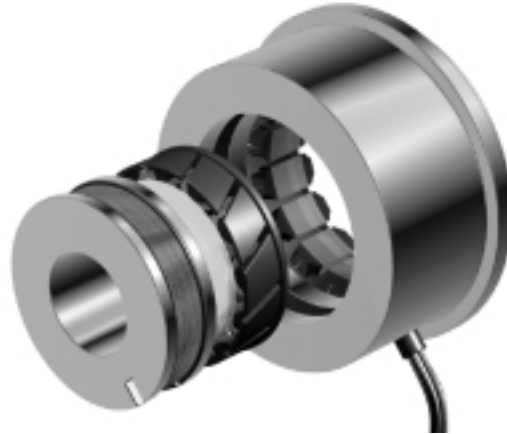
The number of pairs of poles indicates how often the sine distribution of the rotor and stator windings is repeated during one revolution. The higher the number of pairs of poles, the higher the mechanical precision of the resolver. The location deviation of the radial offset increases. With multiple pairs of poles, the absolute angle data are lost, but a higher resolution is possible after digital conversion of the resolver-signals.

Operational diagram



ECL0380-J

Hollow Shaft Resolver



General Terms

Pairs of poles p (speed)

The number of electrical sine and cosine cycles per mechanical revolution.

Residual voltage V_{residual}

The residual voltage is the actual value of the voltage remaining when V_{S1-S3} or V_{S2-S4} takes on the nominal value of zero.

$$V_{\text{residual}} < 0.7 \% \text{ of } r_T \cdot V_{R1-R2}$$

Angle error spread $\Delta\varphi$

The angle error spread is the deviation (unit: arcmin = ') of the angle represented by the electrical signals from the corresponding actual mechanical angle.

$$\Delta\varphi = \varphi_{\text{el}} - \varphi_{\text{mech}} \cdot p \quad \text{with } p = \text{pairs of poles}$$

Applicable definition: the angle error spread lies within $\pm n$ arc minutes in any angular position of the specified band.

DC resistance values

The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K.

Phase shift ψ

The phase shift ψ is the lag between the input signal and output signal.

Transformation ratio r_T

The transformation ratio r_T is the ratio between the input voltage and the maximum output voltage.

$$\begin{aligned} r_T &= V_{S1-S3 \text{ max}} / V_{R1-R2} \\ &= V_{S2-S4 \text{ max}} / V_{R1-R2} \end{aligned}$$

Impedance values Z_{RO} ; Z_{RS} ; Z_{SO} ; Z_{SS}

The impedance values are the ac resistance values and depend on the frequency. Especially Z_{SO} is the value relevant for the output capability of the resolver, while Z_{RS} is decisive for the load on the energizing signal source.

Hollow Shaft Resolver

Overview of Standard Types

Size	Pairs of poles (speed)	Housing material	Angular error range	± 4'	± 6'	± 7'	± 8'	± 10'	± 15'	± 20'	Trans-formation ratio	Notes	
			Ordering number	..33	..10	..02	..09	..01	..22	..14			
15	1	CrNi-steel	V23401-D1001-B1..			X		X	X	X	0.5		
	3	CrNi-steel	V23401-D1008-B1..			X		X	X	X	0.5	3-speed	
	1	CrNi-steel	V23401-D1009-B1..			X		X	X	X	0.5	with low output impedance	
	1	CrMo-steel	V23401-S1001-B1..		X		X	X	X		0.5		
21	3	Aluminum CrNi-steel	V23401-T1002-B1.. V23401-H1002-B1..			X		X	X	X	0.5	3-speed	
	1	Aluminum CrNi-steel	V23401-T1005-B1.. V23401-H1005-B1..			X		X	X	X	0.5		
	1	Aluminum CrNi-steel	V23401-T1009-B1.. V23401-H1009-B1..			X		X	X	X	0.5	with low output impedance	
	1	Aluminum CrNi-steel	V23401-T2001-B2.. V23401-H2001-B2..			X		X	X	X	0.5		
	1	Aluminum CrNi-steel	V23401-T2009-B2.. V23401-H2009-B2..			X		X	X	X	0.5	with low output impedance	
	3	Aluminum CrNi-steel	V23401-T2010-B2.. V23401-H2010-B2..			X		X	X	X	0.46	3-speed	
	4	Aluminum CrNi-steel	V23401-T2014-B2.. V23401-H2014-B2..			X		X	X	X	0.46	4-speed	
	2	Aluminum CrNi-steel	V23401-T2015-B2.. V23401-H2015-B2..			X		X	X	X	0.5	2-speed	
	1	CrMo-steel	V23401-U1016-B1..	X	X		X	X				0.5	
	1	CrMo-steel	V23401-U2017-B2..	X		X		X				0.5	
3	CrMo-steel	V23401-U2020-B2..		X		X	X				0.46	3-speed	

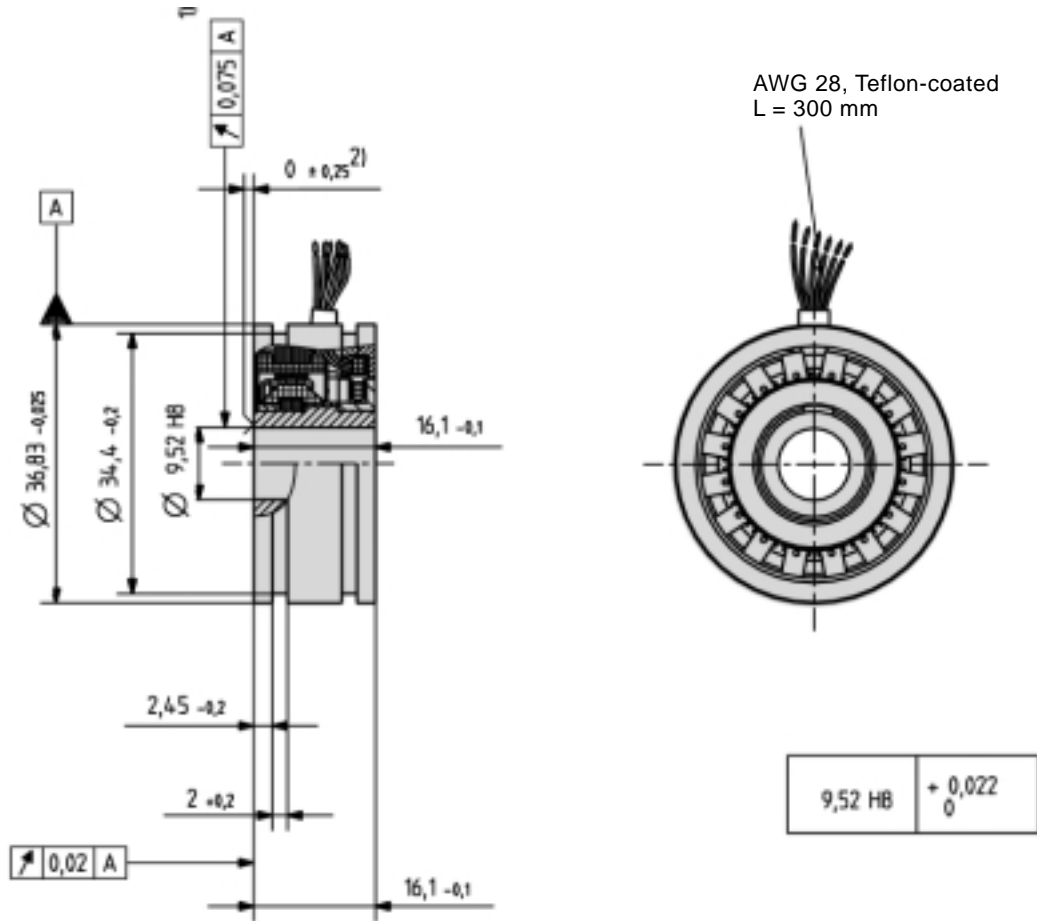
Transfer function	
<p>Function</p> $V_{S1-S3} = +\Gamma_T \cdot V_{R1-R2} \cdot \cos(p \cdot \alpha)$ $V_{S2-S4} = +\Gamma_T \cdot V_{R1-R2} \cdot \sin(p \cdot \alpha)$ <p>p = pairs of poles</p> <p>This function applies to the clockwise rotation of the rotor when looking at the (grooveless) transformer component from the top.</p>	<div style="display: flex; justify-content: space-between;"> <div style="text-align: left;"> <p>Input</p> <p>V_{R1-R2}</p> <p>(red / white) (yellow / white resp. black / white)</p> </div> <div style="text-align: center;"> <p>Transformer Section</p> <p>Resolver Section</p> <p>Rotor</p> <p>Stator</p> <p>α</p> </div> <div style="text-align: right;"> <p>Output</p> <p>V_{S2-S4}</p> <p>V_{S1-S3}</p> </div> </div> <p style="text-align: right; font-size: small;">ECL0379-G</p>

Electrical and thermal limits	
<p>High-voltage test</p> <p>Windings to housing</p> <p>Windings to each other</p>	<p>250 V_{AC}, 50 Hz</p> <p>250 V_{AC}, 50 Hz</p>
<p>Insulation resistance</p> <p>Windings to housing and windings to each other</p>	<p>$R_{\text{insulation}} > 50 \text{ M}\Omega$ at 500 V_{DC}</p>
<p>Operating temperature range</p>	<p>-55 °C ... +150 °C</p>

Mechanical data	
<p>Weight</p> <p>V23401-D...</p> <p>V23401-S...</p>	<p>approx. 90 g</p> <p>approx. 90 g</p>
<p>Momentum of inertia of the rotor</p>	<p>approx. 20 g · cm²</p>
<p>Maximum rational speed</p>	<p>20 000 rpm</p>
<p>Maximum angular acceleration</p>	<p>150 000 rad/s²</p>
<p>Torsional strength of rotor components</p>	<p>0.25 Nm</p>
<p>Shock resistance (11 ms sine)</p>	<p>1000 m/s²</p>
<p>Vibration fatigue limit (0 ... 2 kHz)</p>	<p>200 m/s²</p>
<p>Permissible radial runout (see Dimensioned drawing: Note 1)</p>	<p>0.075 mm</p>
<p>Permissible axial offset (see Dimensioned drawing: Note 2)</p>	<p>± 0.25 mm</p>

Size 15

Dimensioned drawing



- 1) Total runout when installed
- 2) Axial offset

Housing CrNi-steel

Electrical error / Ordering information

<p>Angular error spread $\Delta\phi$ $\pm 20'$ $\pm 15'$ $\pm 10'$ $\pm 7'$</p>	<p>Ordering code V23401-D1001-B114 V23401-D1001-B122 V23401-D1001-B101 V23401-D1001-B102</p>
<p>Residual voltage V_{residual}</p>	<p>25 mV at $V_{R1-R2} = 7\text{ V}$</p>

Electrical data at 22 °C.

Transfer function

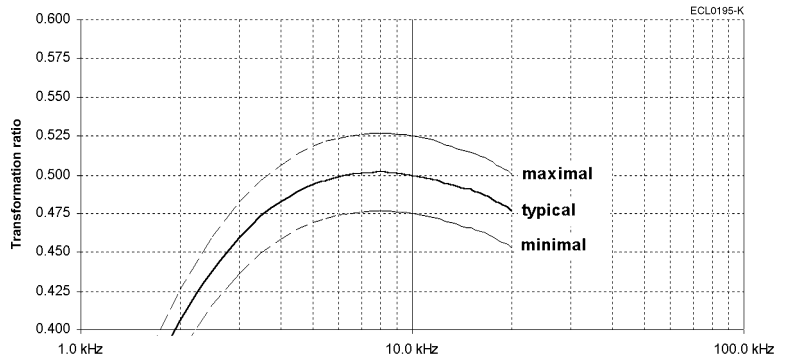
Pairs of poles p $p = 1$

Transformation ratio r_T

$$r_T = \frac{V_{S1-S3 \text{ max}}}{V_{R1-R2}}$$

$$= \frac{V_{S2-S4 \text{ max}}}{V_{R1-R2}}$$

= 0.5 ± 10 % within 4 ... 20 kHz
 = 0.5 ± 5 % at 5 kHz



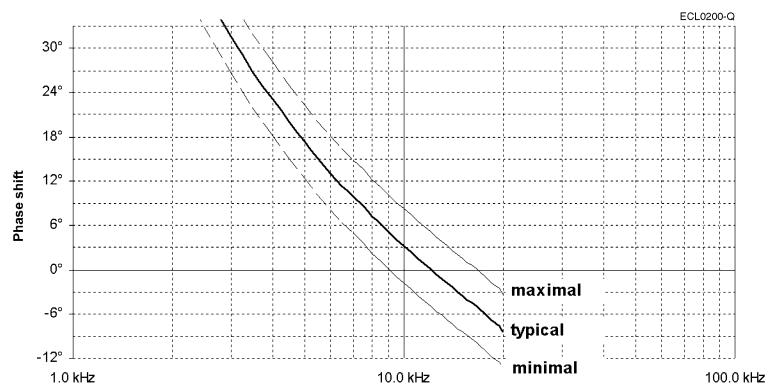
Phase shift ψ

$$V_{R1-R2}(t) = V_{R1-R2 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$$

$$V_{S1-S3}(t) = V_{S1-S3 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$$

for $-90^\circ < \alpha < +90^\circ$

Tolerance: $\pm 5^\circ$



Size 15

Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	$2 V_{rms} \dots 10 V_{rms}$
Frequency f, typical	$4 \text{ kHz} \dots 20 \text{ kHz}$

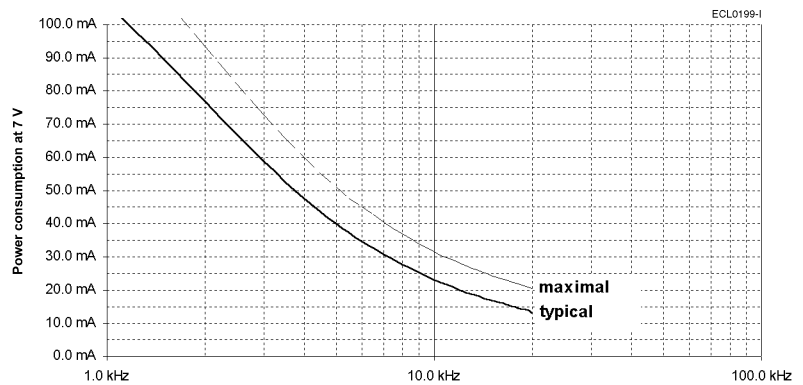
When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.3 \text{ W}$ is not critical.

Input current I

The adjacent figure applies to $V_{R1-R2} = 7 \text{ V}$.

For other input voltages, the input current changes follows as:

$$I = I_{\text{Figure}} \cdot V_{R1-R2} / 7 \text{ V}$$

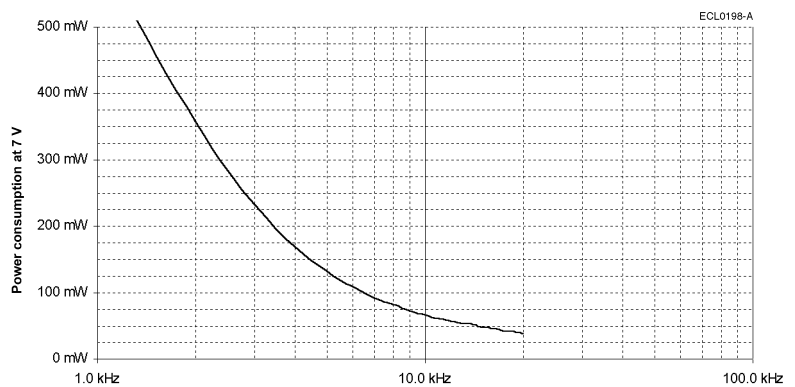


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 7 \text{ V}$.

For other input voltages, the power consumption changes follows as:

$$P = P_{\text{Figure}} \cdot (V_{R1-R2} / 7 \text{ V})^2$$



Size 15

Resistance, impedance and operating parameters (continued)

DC resistance

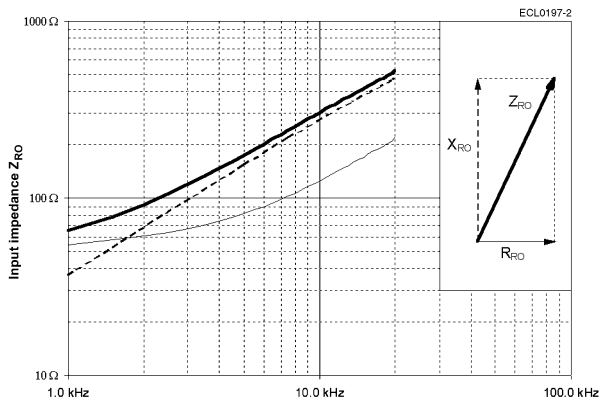
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 46 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 63 \Omega$
 Tolerance: $\pm 10 \%$

Input impedance

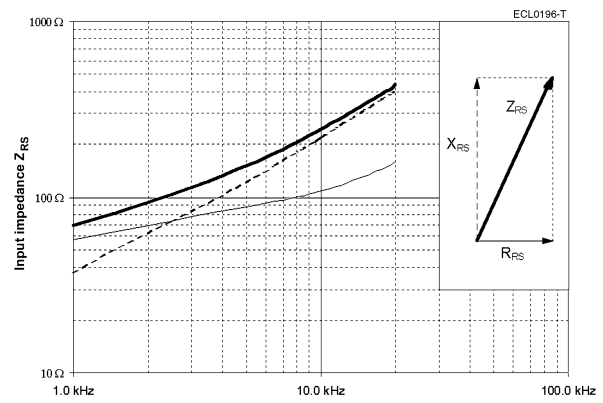
Tolerance: $\pm 15 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 15 \%$

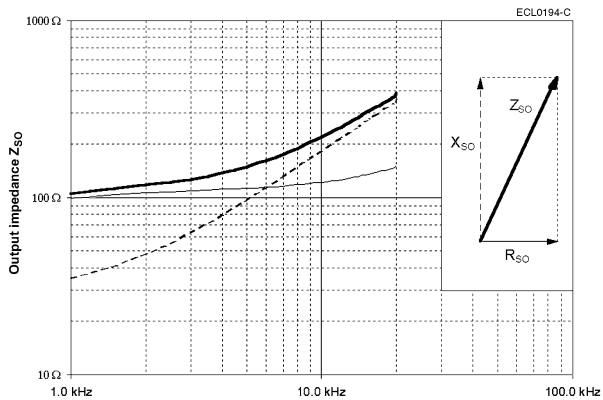
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

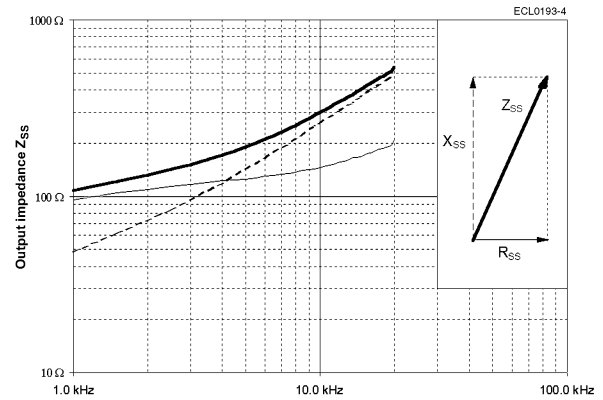
Tolerance: $\pm 15 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 15 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
 at $f = 10 \text{ kHz}$

$L_{RO} = 4.4 \text{ mH}$
 $L_{SS} = 4.1 \text{ mH}$

Size 15

Housing

CrNi-steel

Electrical error / Ordering information

Angular error spread $\Delta\phi$

- $\pm 20'$
- $\pm 15'$
- $\pm 10'$
- $\pm 7'$

Ordering code

- V23401-D1008-B114
- V23401-D1008-B122
- V23401-D1008-B101
- V23401-D1008-B102

Residual voltage V_{residual}

14 mV at $V_{R1-R2} = 4 V$

Electrical data at 22 °C.

Transfer function

Pairs of poles p

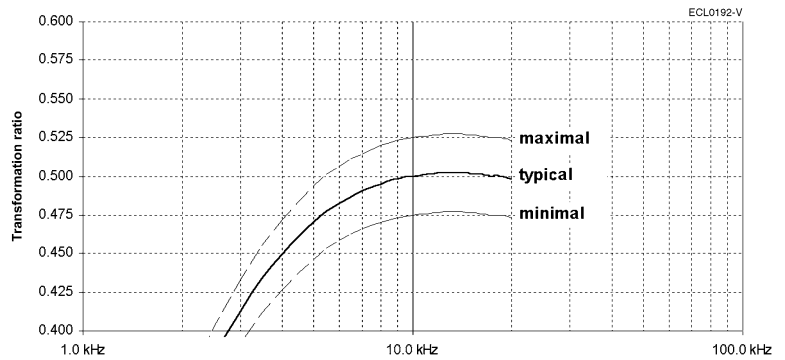
p = 3

Transformation ratio r_T

$$r_T = \frac{V_{S1-S3 \text{ max}}}{V_{R1-R2}}$$

$$= \frac{V_{S2-S4 \text{ max}}}{V_{R1-R2}}$$

- = $0.5 \pm 10\%$ within 5 ... 20 kHz
- = $0.5 \pm 5\%$ at 10 kHz



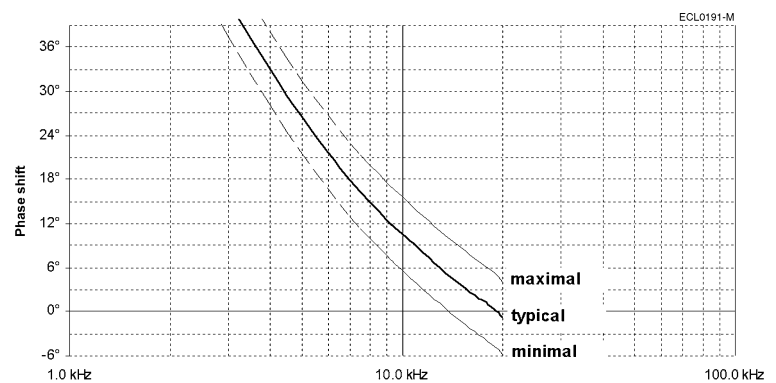
Phase shift ψ

$$V_{R1-R2}(t) = V_{R1-R2 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$$

$$V_{S1-S3}(t) = V_{S1-S3 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$$

for $-90^\circ < \alpha < +90^\circ$

Tolerance: $\pm 5^\circ$



Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	$2 V_{rms} \dots 8 V_{rms}$
Frequency f, typical	5 kHz ... 20 kHz

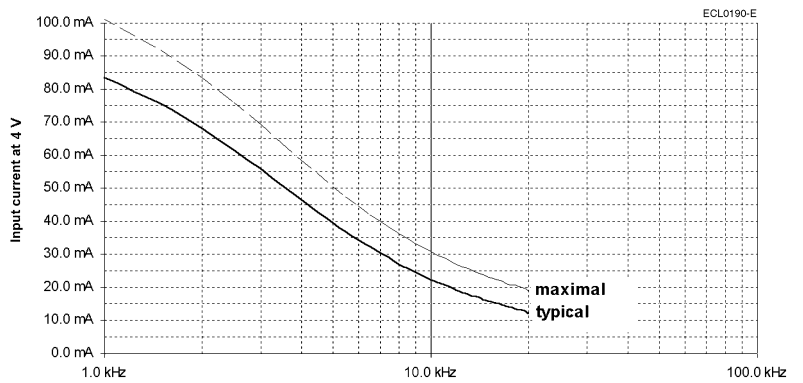
When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.3 \text{ W}$ is not critical.

Input current I

The adjacent figure applies to $V_{R1-R2} = 4 \text{ V}$.

For other input voltages, the input current changes follows as:

$$I = I_{\text{Figure}} \cdot V_{R1-R2} / 4 \text{ V}$$

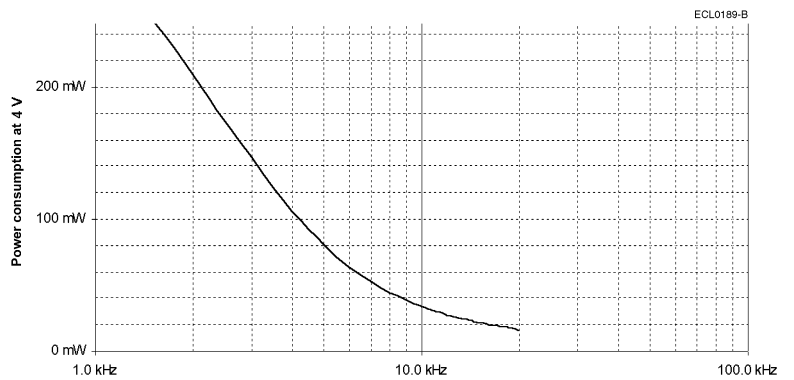


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 4 \text{ V}$.

For other input voltages, the power consumption changes follows as:

$$P = P_{\text{Figure}} \cdot (V_{R1-R2} / 4 \text{ V})^2$$



Size 15

Resistance, impedance and operating parameters (continued)

DC resistance

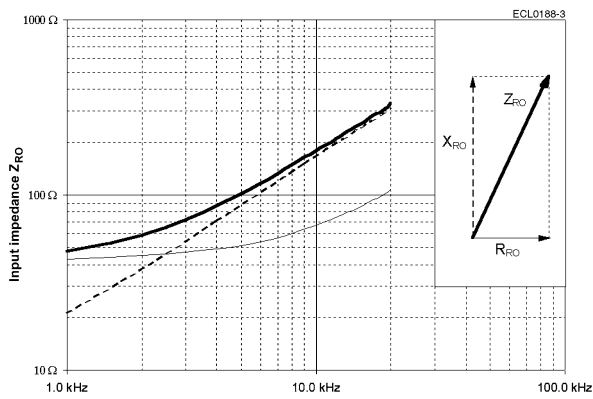
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 33 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 70 \Omega$
 Tolerance: $\pm 10 \%$

Input impedance

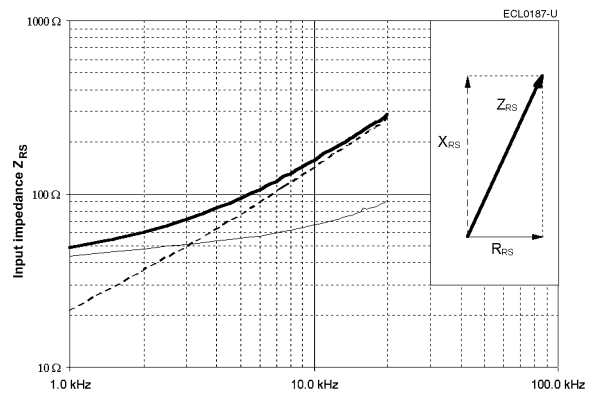
Tolerance: $\pm 15 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 15 \%$

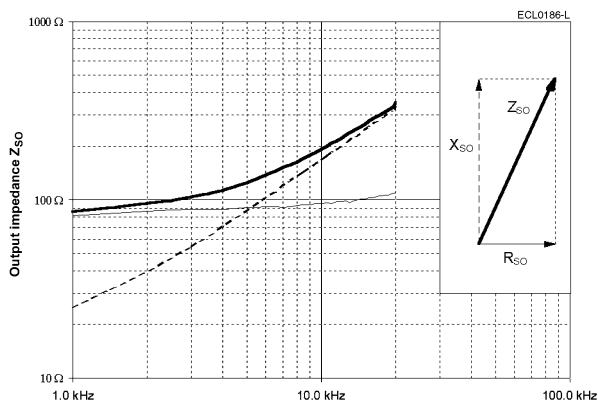
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

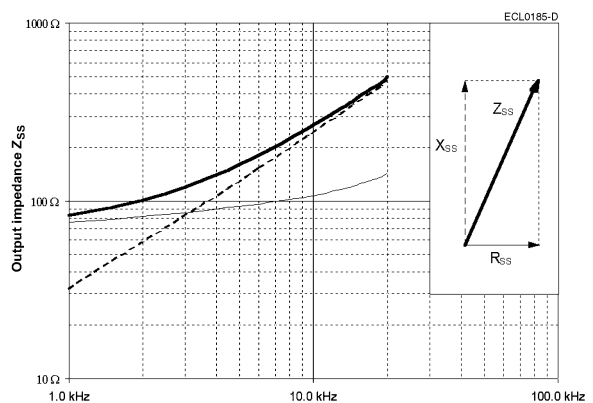
Tolerance: $\pm 15 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 15 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
 at $f = 10 \text{ kHz}$

$L_{RO} = 2.6 \text{ mH}$
 $L_{SS} = 3.9 \text{ mH}$

Housing CrNi-steel

Electrical error / Ordering information

<p>Angular error spread $\Delta\phi$ $\pm 20'$ $\pm 15'$ $\pm 10'$ $\pm 7'$</p>	<p>Ordering code V23401-D1009-B114 V23401-D1009-B122 V23401-D1009-B101 V23401-D1009-B102</p>
<p>Residual voltage V_{residual}</p>	<p>14 mV at $V_{R1-R2} = 4 \text{ V}$</p>

Electrical data at 22 °C.

Transfer function

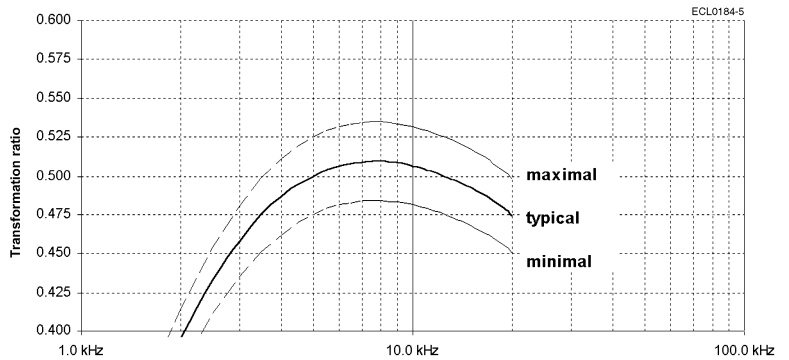
Pairs of poles $p = 1$

Transformation ratio r_T

$$r_T = \frac{V_{S1-S3 \text{ max}}}{V_{R1-R2}}$$

$$= \frac{V_{S2-S4 \text{ max}}}{V_{R1-R2}}$$

= 0.5 ± 10 % within 4 ... 20 kHz
 = 0.5 ± 5 % at 5 kHz



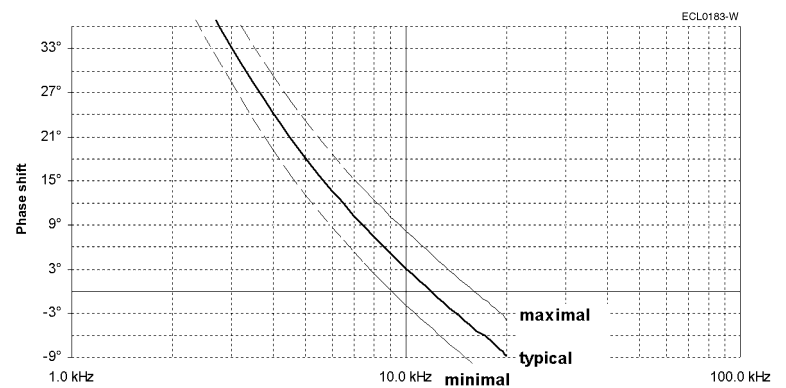
Phase shift ψ

$$V_{R1-R2}(t) = V_{R1-R2 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$$

$$V_{S1-S3}(t) = V_{S1-S3 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$$

for $-90^\circ < \alpha < +90^\circ$

Tolerance: ± 5°



Size 15

Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	$2 V_{rms} \dots 8 V_{rms}$
Frequency f, typical	4 kHz ... 20 kHz

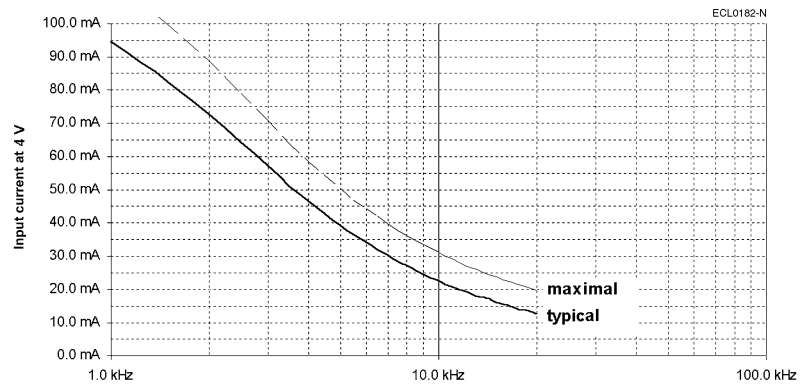
When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.3 \text{ W}$ is not critical.

Input current I

The adjacent figure applies to $V_{R1-R2} = 4 \text{ V}$.

For other input voltages, the input current changes follows as:

$$I = I_{\text{Figure}} \cdot V_{R1-R2} / 4 \text{ V}$$

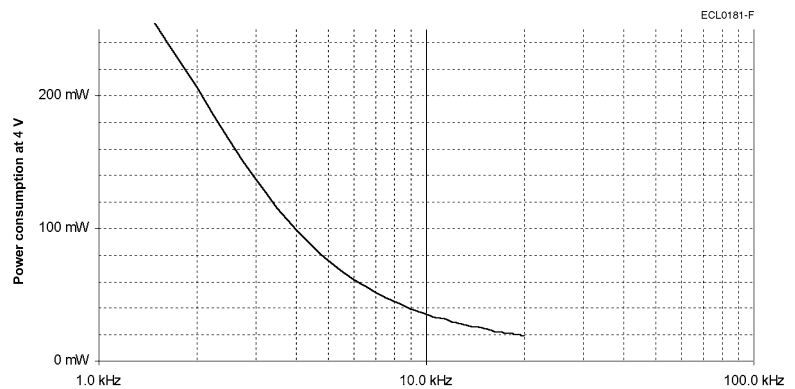


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 4 \text{ V}$.

For other input voltages, the power consumption changes follows as:

$$P = P_{\text{Figure}} \cdot (V_{R1-R2} / 4 \text{ V})^2$$



Size 15

Resistance, impedance and operating parameters (continued)

DC resistance

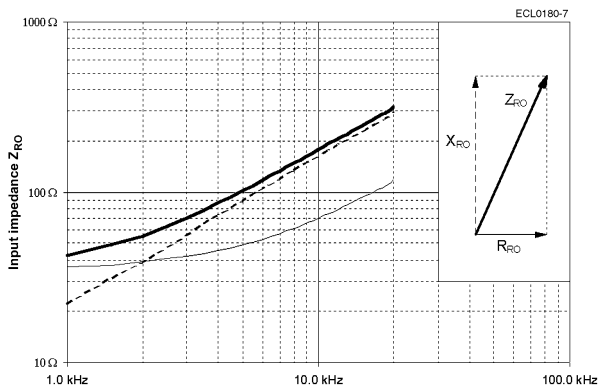
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 31 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 28 \Omega$
 Tolerance: $\pm 10 \%$

Input impedance

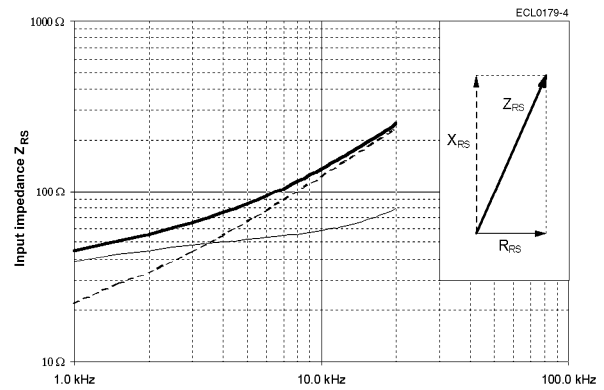
Tolerance: $\pm 15 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 15 \%$

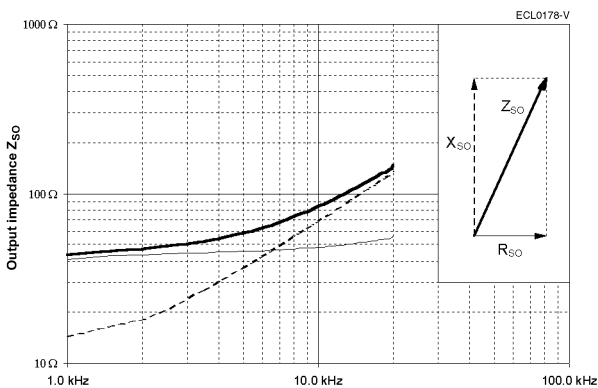
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

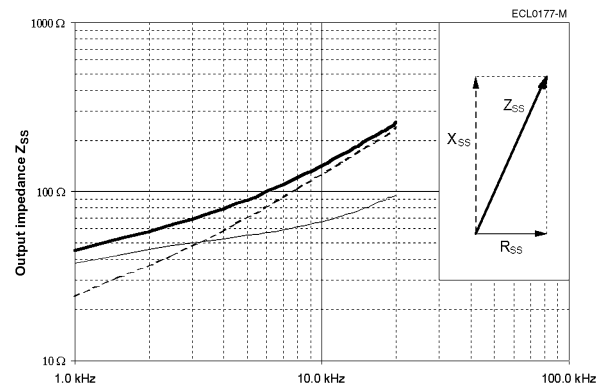
Tolerance: $\pm 15 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 15 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
at $f = 10 \text{ kHz}$

$L_{RO} = 2.6 \text{ mH}$
 $L_{SS} = 2.0 \text{ mH}$

Size 15

Housing CrMo-steel

Electrical error / Ordering information

Angular error spread $\Delta\phi$ $\pm 15'$ $\pm 10'$ $\pm 8'$ $\pm 6'$	Ordering code V23401-S1001-B122 V23401-S1001-B101 V23401-S1001-B109 V23401-S1001-B110
Residual voltage V_{residual}	25 mV at $V_{R1-R2} = 7 \text{ V}$

Electrical data at 22 °C.

Transfer function

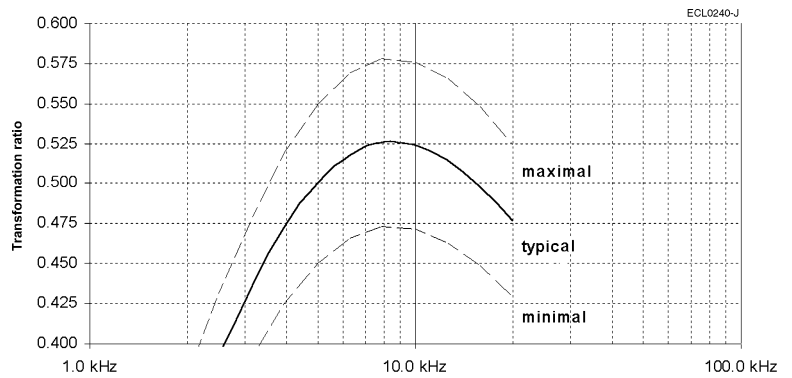
Pairs of poles p $p = 1$

Transformation ratio r_T

$$r_T = \frac{V_{S1-S3 \text{ max}}}{V_{R1-R2}}$$

$$= \frac{V_{S2-S4 \text{ max}}}{V_{R1-R2}}$$

$= 0.5 \pm 10 \% \text{ within } 4 \dots 20 \text{ kHz}$
 $= 0.5 \pm 5 \% \text{ at } 5 \text{ kHz}$



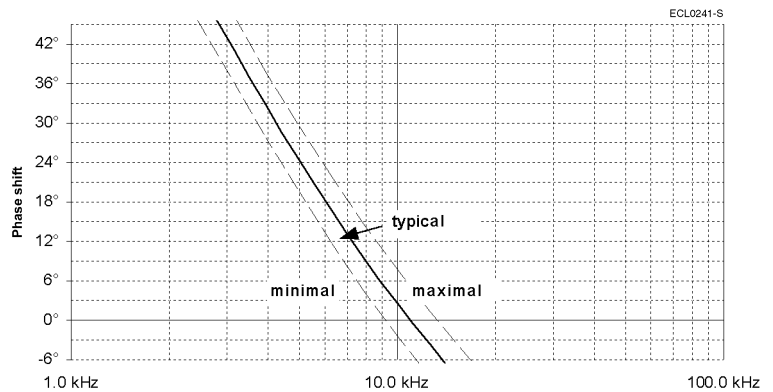
Phase shift ψ

$$V_{R1-R2}(t) = V_{R1-R2 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$$

$$V_{S1-S3}(t) = V_{S1-S3 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$$

for $-90^\circ < \alpha < +90^\circ$

Tolerance: $\pm 5^\circ$



Size 15

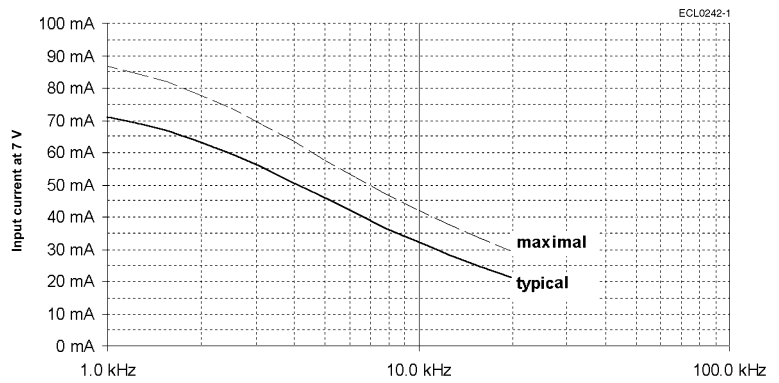
Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	$2 V_{rms} \dots 10 V_{rms}$	When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.3 W$ is not critical.
Frequency f, typical	4 kHz ... 20 kHz	

Input current I

The adjacent figure applies to $V_{R1-R2} = 7 V$.

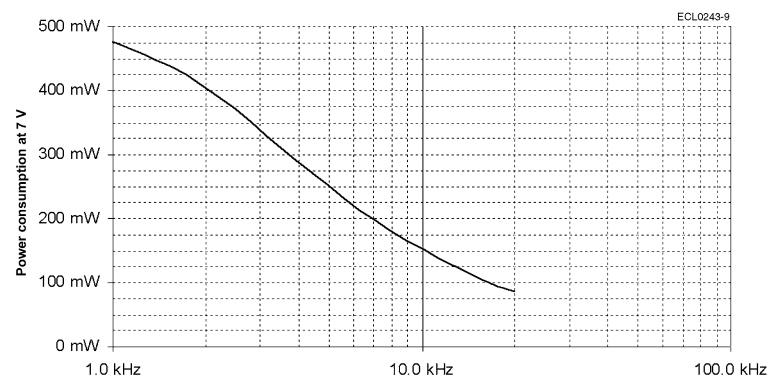
For other input voltages, the input current changes follows as:

$$I = I_{Figure} \cdot V_{R1-R2} / 7 V$$


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 7 V$.

For other input voltages, the power consumption changes follows as:

$$P = P_{Figure} \cdot (V_{R1-R2} / 7 V)^2$$


Resistance, impedance and operating parameters (continued)

DC resistance

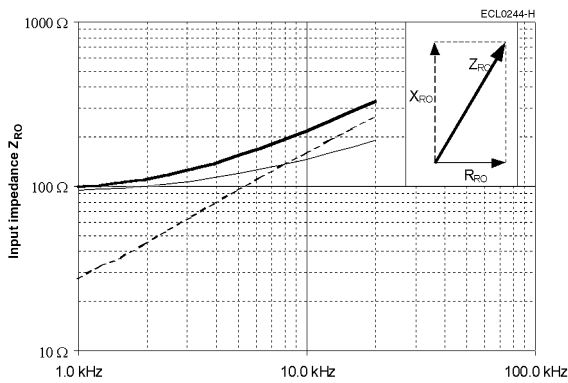
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 82 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 68 \Omega$
 Tolerance: $\pm 10 \%$

Input impedance

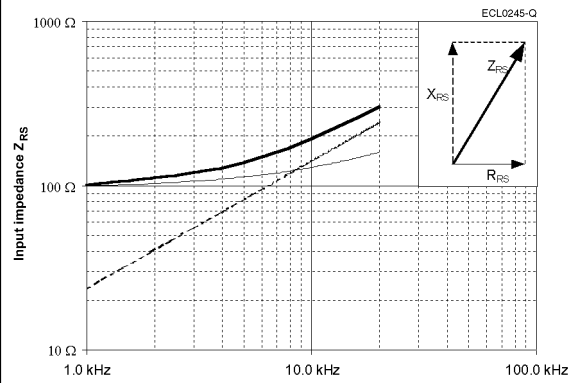
Tolerance: $\pm 15 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 15 \%$

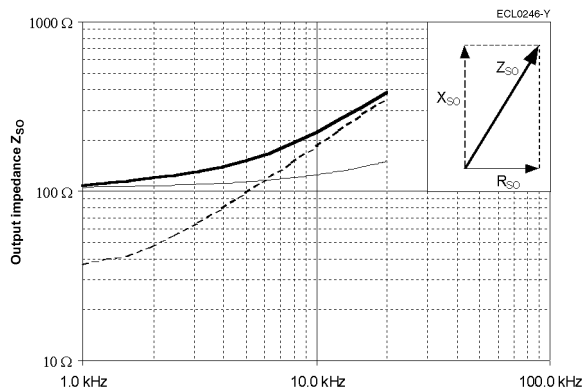
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

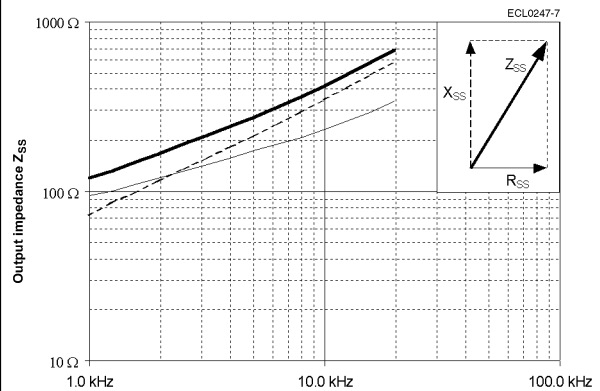
Tolerance: $\pm 15 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 15 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
 at $f = 5 \text{ kHz}$

$L_{RO} = 2.5 \text{ mH}$
 $L_{SS} = 5.8 \text{ mH}$

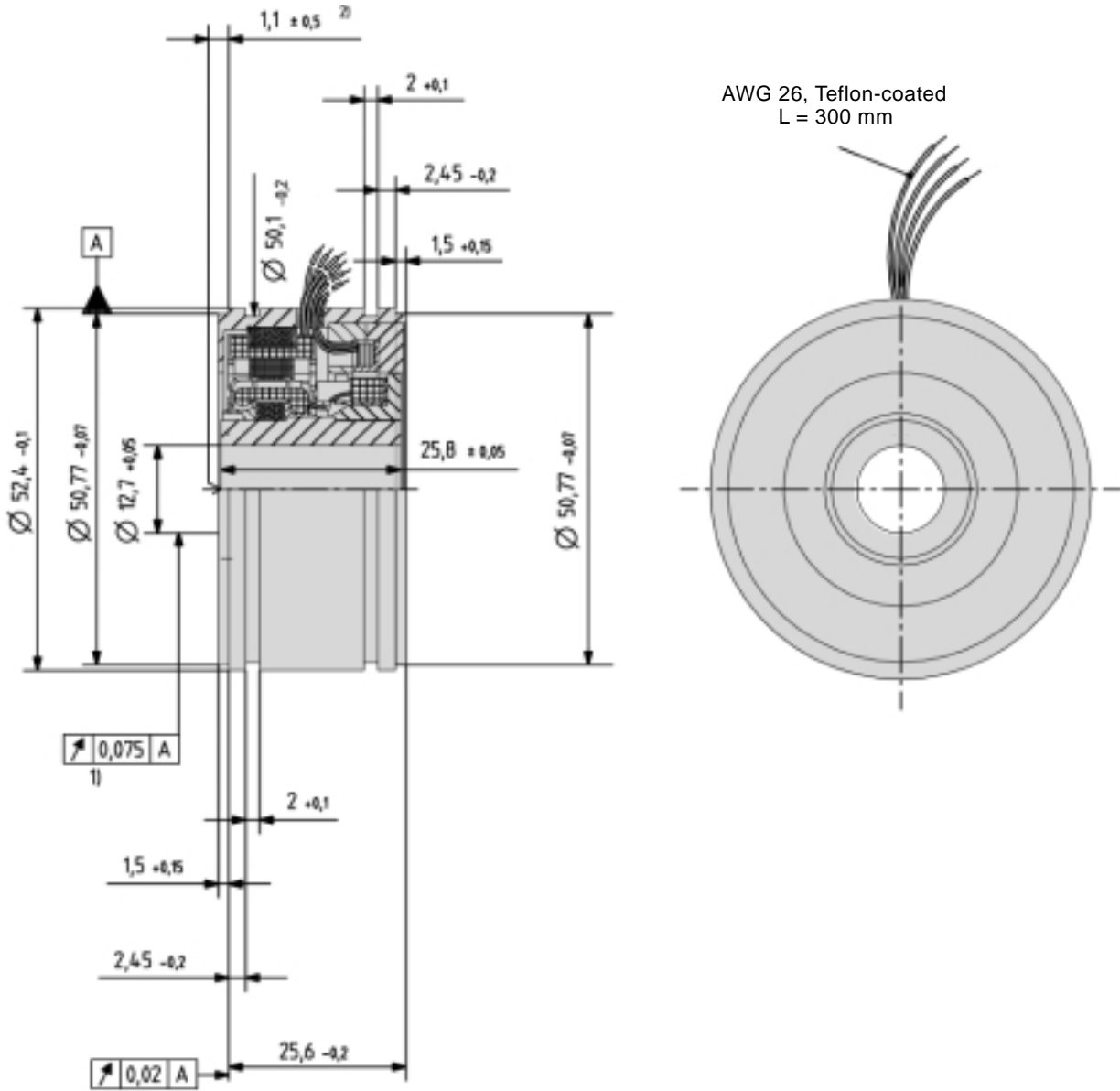
Transfer function				
<p>Function</p> $V_{S1-S3} = +\Gamma_T \cdot V_{R1-R2} \cdot \cos(p \cdot \alpha)$ $V_{S2-S4} = +\Gamma_T \cdot V_{R1-R2} \cdot \sin(p \cdot \alpha)$ <p>p = pairs of poles</p> <p>This function applies to the clockwise rotation of the rotor when looking at the (grooveless) transformer component from the top.</p>	<table border="0" style="width: 100%;"> <tr> <td style="text-align: left;">Input</td> <td style="text-align: center;"> </td> <td style="text-align: right;">Output</td> </tr> </table> <p style="text-align: right; font-size: small;">ECL0379-G</p>	Input		Output
Input		Output		

Electrical and thermal limits	
<p>High-voltage test</p> <ul style="list-style-type: none"> Windings to housing Windings to each other 	<p>500 V_{AC}, 50 Hz</p> <p>250 V_{AC}, 50 Hz</p>
<p>Insulation resistance</p> <ul style="list-style-type: none"> Windings to housing and windings to each other 	<p>$R_{insulation} > 50 \text{ M}\Omega$ at 500 V_{DC}</p>
<p>Operating temperature range</p>	<p>-55 °C ... +150 °C</p>

Mechanical data	
<p>Weight</p> <ul style="list-style-type: none"> V23401-T 10... V23401-H 10... V23401-U 10... V23401-T 20... V23401-H 20... V23401-U 20... 	<p>approx. 240 g</p> <p>approx. 290 g</p> <p>approx. 290 g</p> <p>approx. 210 g</p> <p>approx. 260 g</p> <p>approx. 260 g</p>
<p>Momentum of inertia of the rotor</p>	<p>approx. 200 g · cm²</p>
<p>Maximum rational speed</p>	<p>20 000 rpm</p>
<p>Maximum angular acceleration</p>	<p>64 000 rad/s²</p>
<p>Torsional strength of rotor components</p>	<p>1 Nm</p>
<p>Shock resistance (11 ms sine)</p>	<p>1000 m/s²</p>
<p>Vibration fatigue limit (0 ... 2 kHz)</p>	<p>200 m/s²</p>
<p>Permissible radial runout (see Dimensioned drawing: Note 1)</p>	<p>0.075 mm</p>
<p>Permissible axial offset (see Dimensioned drawing: Note 2)</p>	<p>± 0.5 mm</p>

Dimensioned drawing

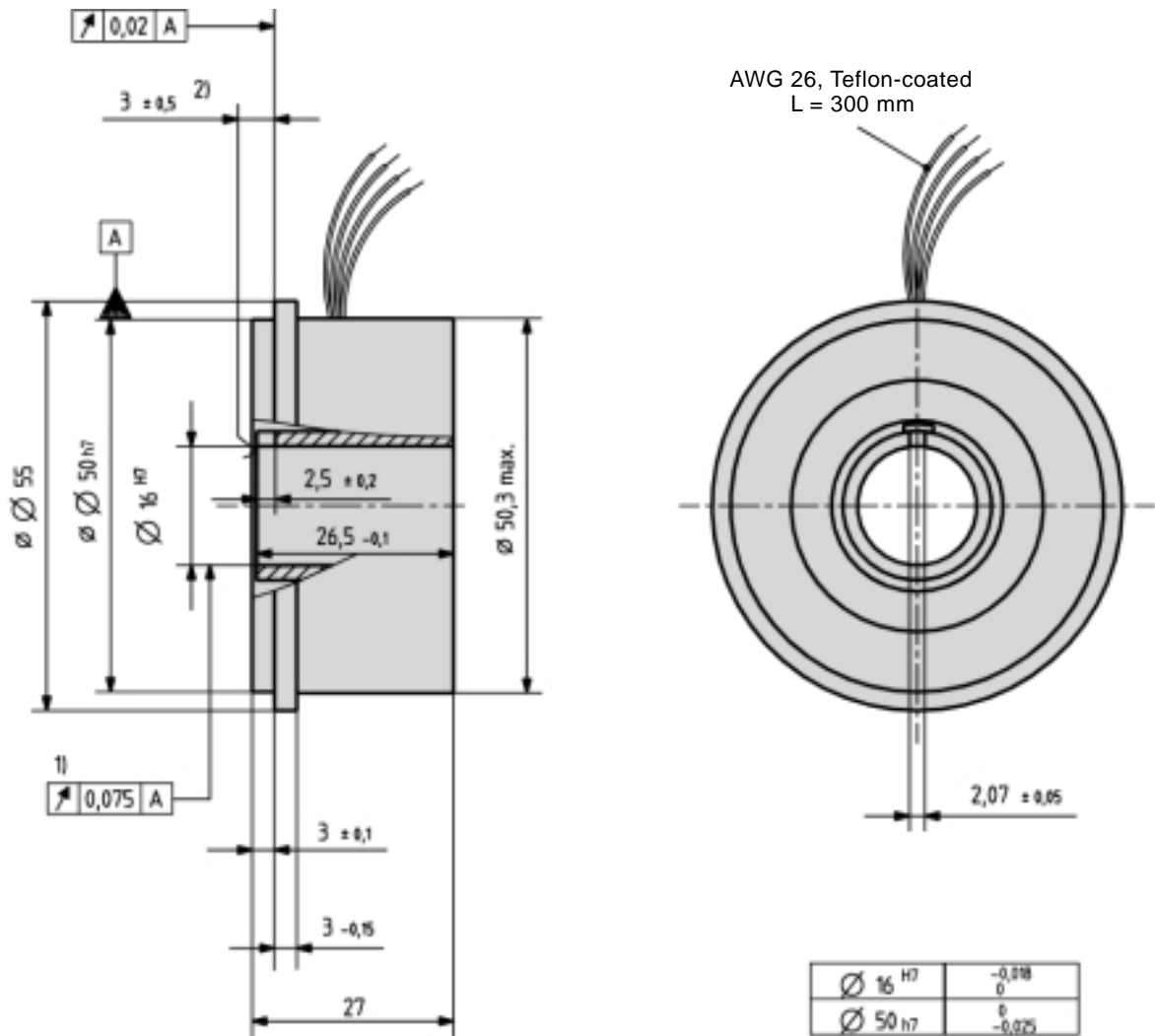
V23401-T1... / H1... / U1...



- 1) Total runout when installed
- 2) Axial offset

Dimensioned drawing

V23401-T2... / H2... / U2...



- 1) Total runout when installed
- 2) Axial offset

Housing	Aluminum	V23401-T 1002-B1..
	CrNi-steel	V23401-H1002-B1..

Electrical error / Ordering information

Angular error spread $\Delta\phi$	Ordering code	
	Aluminum housing	CrNi-steel housing
	$\pm 20'$	V23401-T1002-B114
	$\pm 15'$	V23401-T1002-B122
	$\pm 10'$	V23401-T1002-B101
$\pm 7'$	V23401-T1002-B102	V23401-H1002-B102
Residual voltage $V_{residual}$	25 mV at $V_{R1-R2} = 7 V$	

Electrical data at 22 °C.

Transfer function

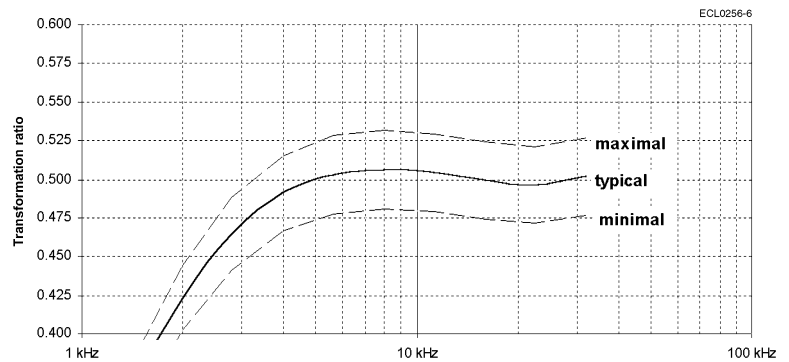
Pairs of poles p	$p = 3$
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Transformation ratio r_T

$$r_T = V_{S1-S3 \max} / V_{R1-R2}$$

$$= V_{S2-S4 \max} / V_{R1-R2}$$

$= 0.5 \pm 10 \% \text{ within } 3 \dots 20 \text{ kHz}$
 $= 0.5 \pm 5 \% \text{ at } 5 \text{ kHz}$



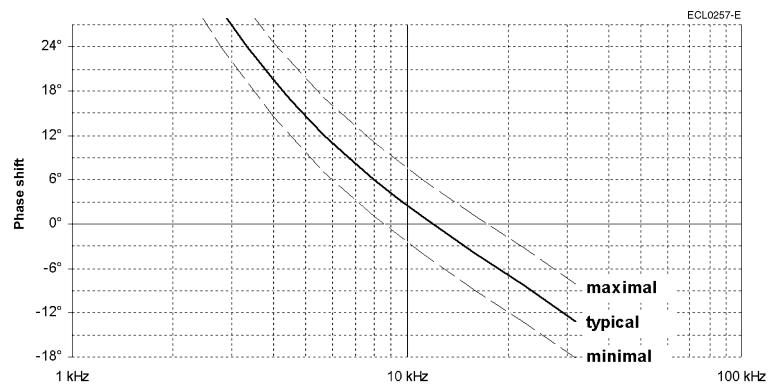
Phase shift ψ

$$V_{R1-R2}(t) = V_{R1-R2 \max} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$$

$$V_{S1-S3}(t) = V_{S1-S3 \max} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$$

for $-90^\circ < \alpha < +90^\circ$

Tolerance: $\pm 5^\circ$



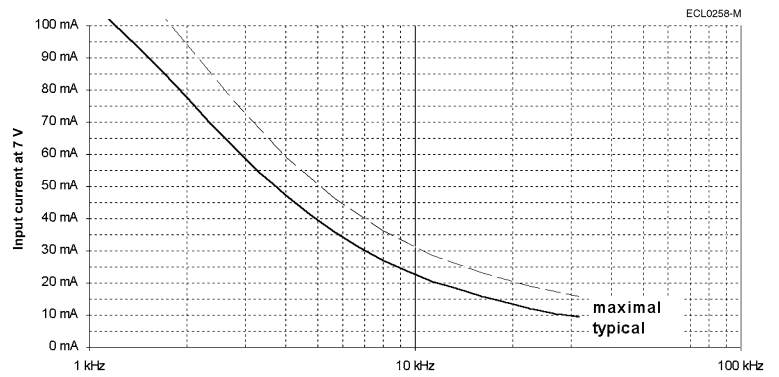
Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	$4 V_{rms} \dots 10 V_{rms}$	When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.5 W$ is not critical.
Frequency f, typical	3 kHz ... 15 kHz	

Input current I

The adjacent figure applies to $V_{R1-R2} = 7 V$.

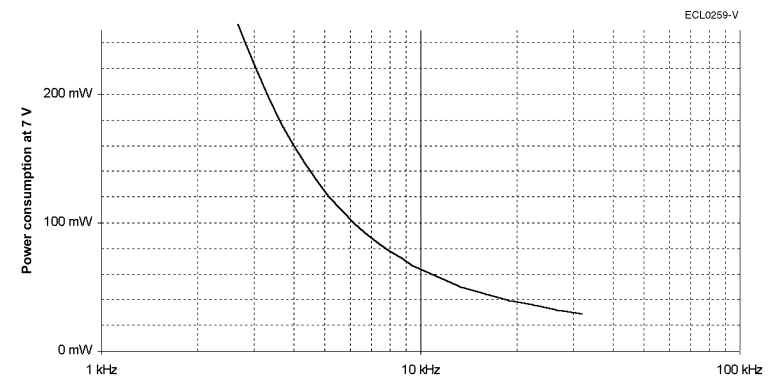
For other input voltages, the input current changes follows as:

$$I = I_{Figure} \cdot V_{R1-R2} / 7 V$$


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 7 V$.

For other input voltages, the power consumption changes follows as:

$$P = P_{Figure} \cdot (V_{R1-R2} / 7 V)^2$$


Resistance, impedance and operating parameters (continued)

DC resistance

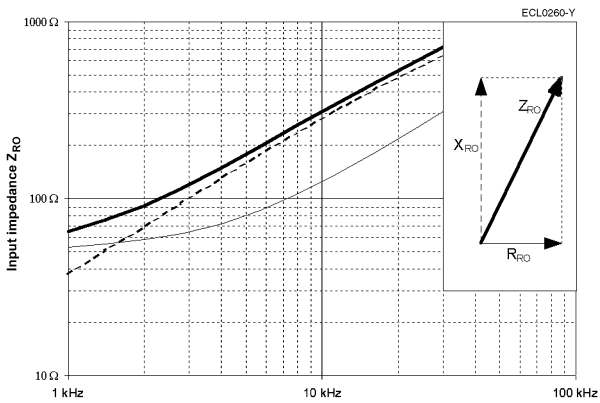
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 39 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 94 \Omega$
 Tolerance: $\pm 10 \%$

Input impedance

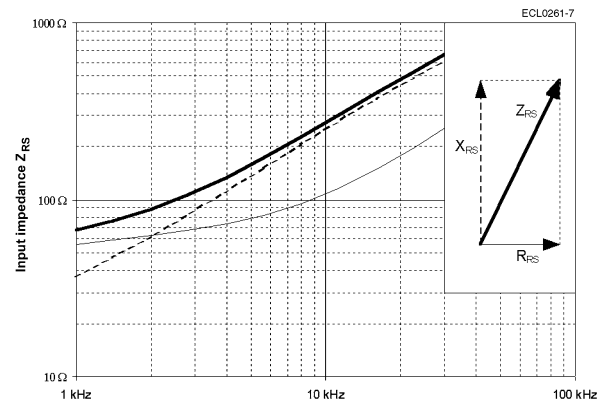
Tolerance: $\pm 15 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 15 \%$

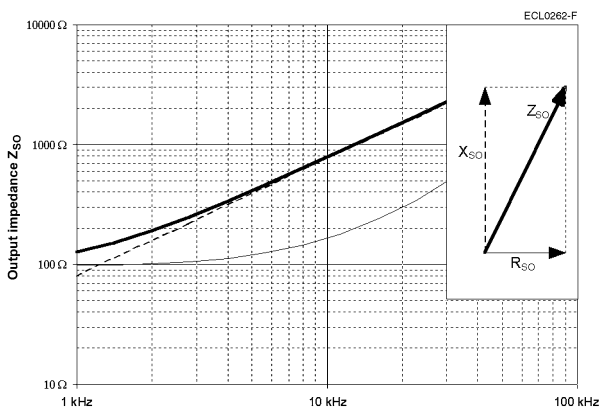
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

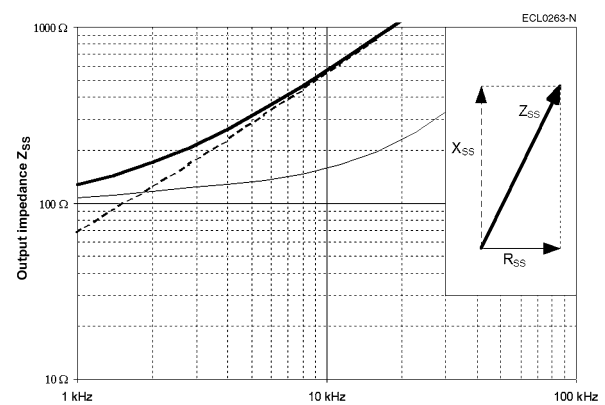
Tolerance: $\pm 15 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 15 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
 at $f = 8 \text{ kHz}$

$L_{RO} = 4.7 \text{ mH}$
 $L_{SS} = 8.8 \text{ mH}$

Housing	Aluminum	V23401-T 1005-B1..
	CrNi-steel	V23401-H1005-B1..

Electrical error / Ordering information

Angular error spread $\Delta\phi$	Ordering code	
	Aluminum housing	CrNi-steel housing
	$\pm 20'$	V23401-T1005-B114
	$\pm 15'$	V23401-H1005-B114
	$\pm 10'$	V23401-T1005-B122
$\pm 10'$	V23401-H1005-B122	
$\pm 7'$	V23401-T1005-B101	
	V23401-H1005-B101	
	V23401-T1005-B102	
	V23401-H1005-B102	
Residual voltage V_{residual}	25 mV at $V_{R1-R2} = 7\text{ V}$	

Electrical data at 22 °C.

Transfer function

Pairs of poles p	p = 1
<p>Transformation ratio r_T</p> $r_T = V_{S1-S3 \text{ max}} / V_{R1-R2}$ $= V_{S2-S4 \text{ max}} / V_{R1-R2}$ <p>= 0.5 ± 10 % within 2 ... 10 kHz = 0.5 ± 5 % at 5 kHz</p>	
<p>Phase shift ψ</p> $V_{R1-R2}(t) = V_{R1-R2 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$ $V_{S1-S3}(t) = V_{S1-S3 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$ <p>for $-90^\circ < \alpha < +90^\circ$</p> <p>Tolerance: ± 5°</p>	

Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	$4 V_{rms} \dots 12 V_{rms}$
Frequency f, typical	2 kHz ... 10 kHz

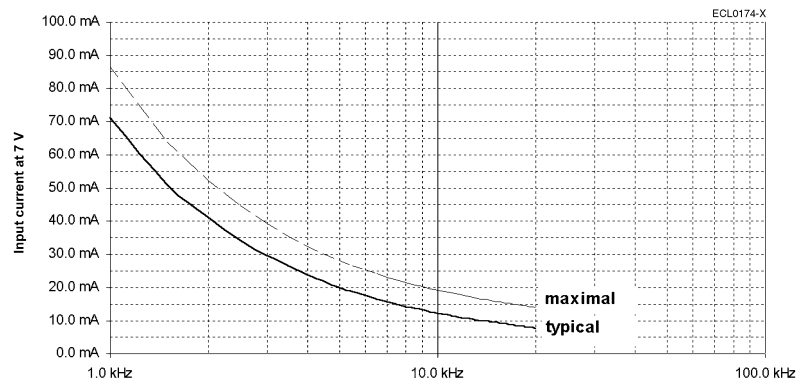
When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.5 W$ is not critical.

Input current I

The adjacent figure applies to $V_{R1-R2} = 7 V$.

For other input voltages, the input current changes follows as:

$$I = I_{Figure} \cdot V_{R1-R2} / 7 V$$

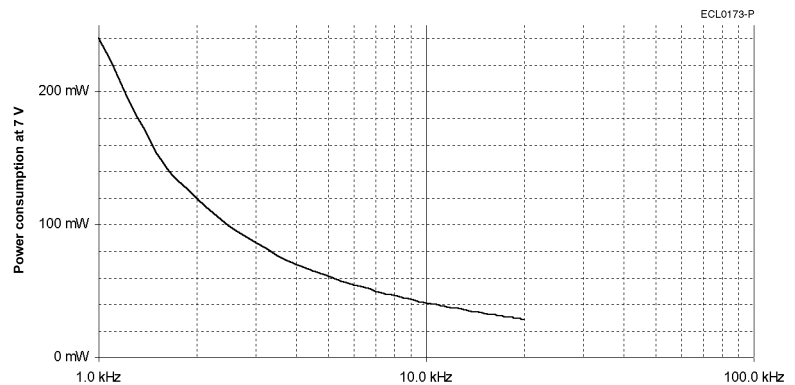


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 7 V$.

For other input voltages, the power consumption changes follows as:

$$P = P_{Figure} \cdot (V_{R1-R2} / 7 V)^2$$



Resistance, impedance and operating parameters (continued)

DC resistance

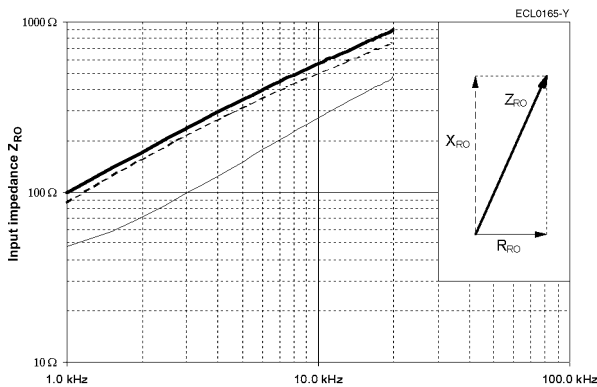
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 24 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 58 \Omega$
Tolerance: $\pm 10 \%$

Input impedance

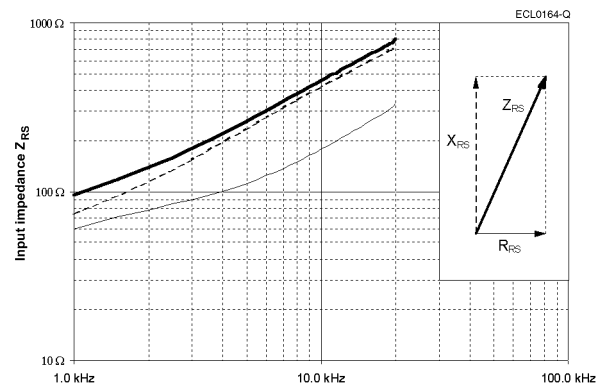
Tolerance: $\pm 15 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 15 \%$

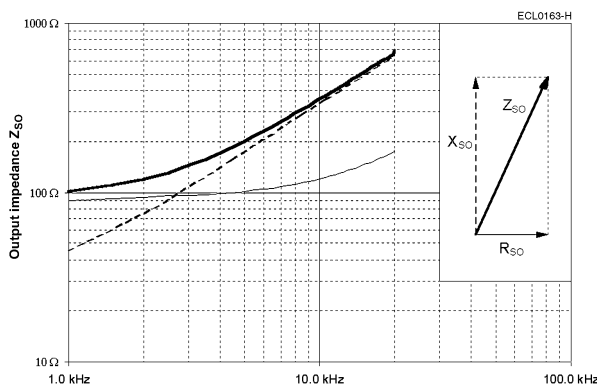
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

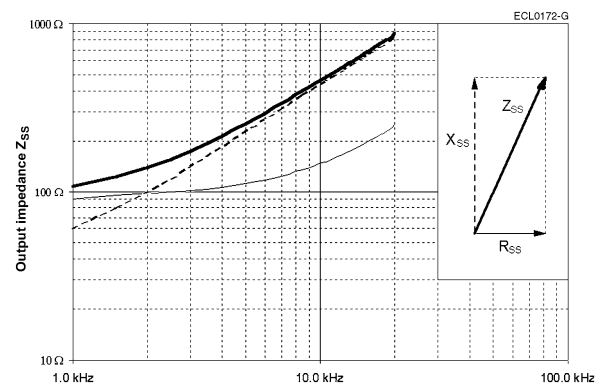
Tolerance: $\pm 15 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 15 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
at $f = 10 \text{ kHz}$

$L_{RO} = 7.9 \text{ mH}$
 $L_{SS} = 6.9 \text{ mH}$

Housing	Aluminum	V23401-T 1009-B1..
	CrNi-steel	V23401-H1009-B1..

Electrical error / Ordering information

Angular error spread $\Delta\phi$

- $\pm 20'$
- $\pm 15'$
- $\pm 10'$
- $\pm 7'$

Ordering code

Aluminum housing	CrNi-steel housing
V23401-T1009-B114	V23401-H1009-B114
V23401-T1009-B122	V23401-H1009-B122
V23401-T1009-B101	V23401-H1009-B101
V23401-T1009-B102	V23401-H1009-B102

Residual voltage V_{residual}

14 mV at $V_{R1-R2} = 4 V$

Electrical data at 22 °C.

Transfer function

Pairs of poles p

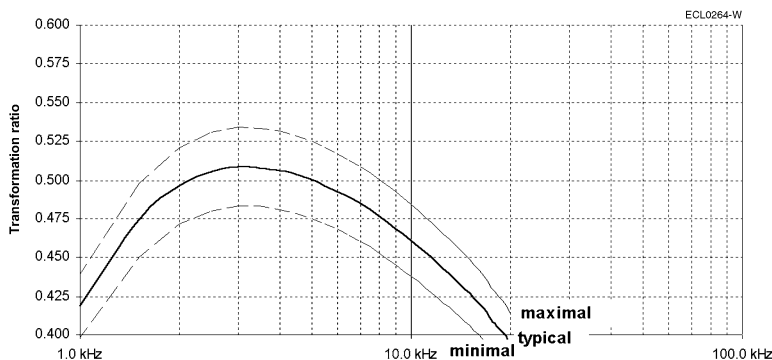
$p = 1$

Transformation ratio r_T

$$r_T = V_{S1-S3 \text{ max}} / V_{R1-R2}$$

$$= V_{S2-S4 \text{ max}} / V_{R1-R2}$$

$= 0.5 \pm 10 \% \text{ within } 2 \dots 8 \text{ kHz}$
 $= 0.5 \pm 5 \% \text{ at } 5 \text{ kHz}$



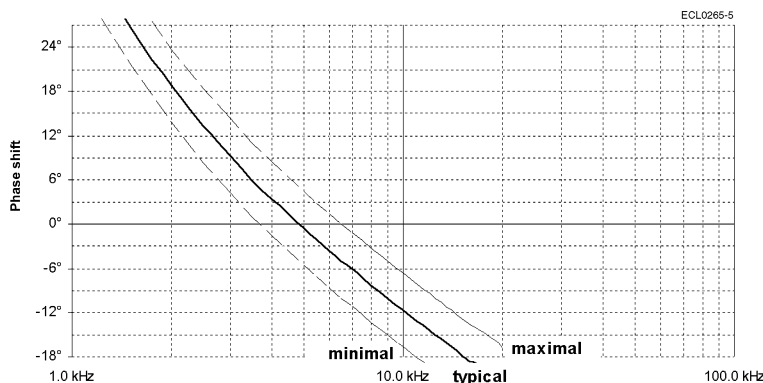
Phase shift ψ

$$V_{R1-R2}(t) = V_{R1-R2 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$$

$$V_{S1-S3}(t) = V_{S1-S3 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$$

for $-90^\circ < \alpha < +90^\circ$

Tolerance: $\pm 5^\circ$



Resistance, impedance and operating parameters

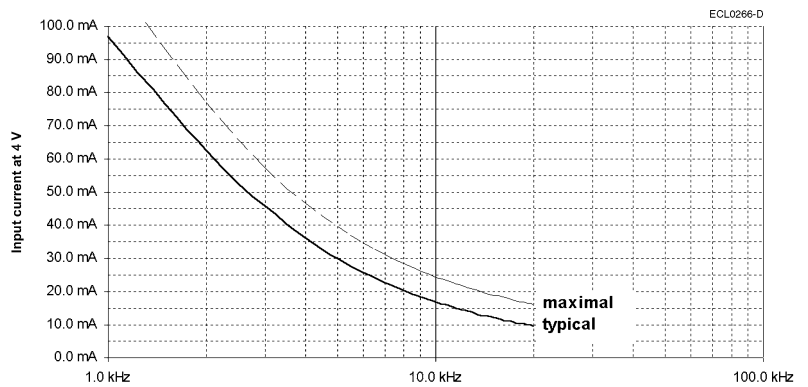
Input voltage V_{R1-R2}, typical	$2 V_{rms} \dots 8 V_{rms}$	When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.5 W$ is not critical.
Frequency f, typical	2 kHz ... 10 kHz	

Input current I

The adjacent figure applies to $V_{R1-R2} = 4 V$.

For other input voltages, the input current changes follows as:

$$I = I_{Figure} \cdot V_{R1-R2} / 4 V$$

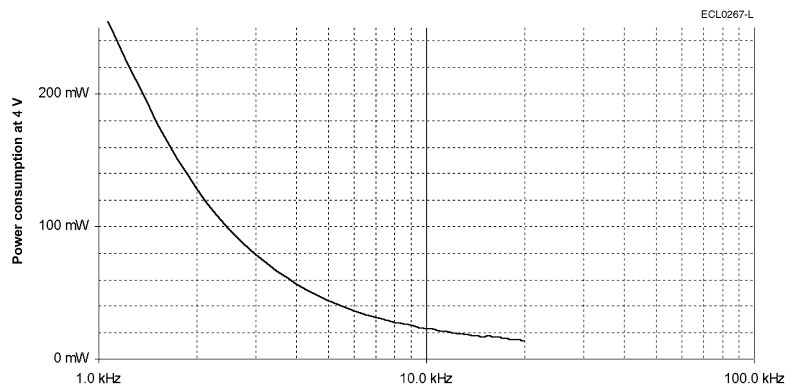


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 4 V$.

For other input voltages, the power consumption changes follows as:

$$P = P_{Figure} \cdot (V_{R1-R2} / 4 V)^2$$



Resistance, impedance and operating parameters (continued)

DC resistance

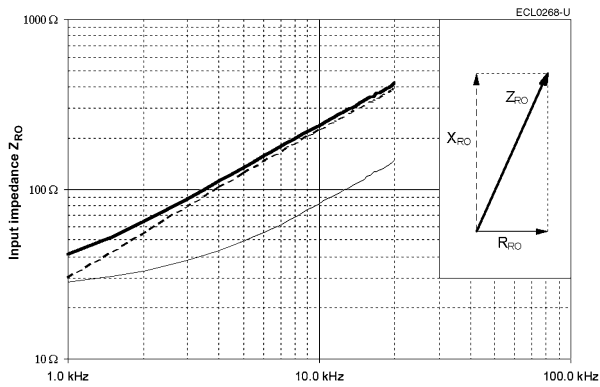
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 21 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 22 \Omega$
 Tolerance: $\pm 10 \%$

Input impedance

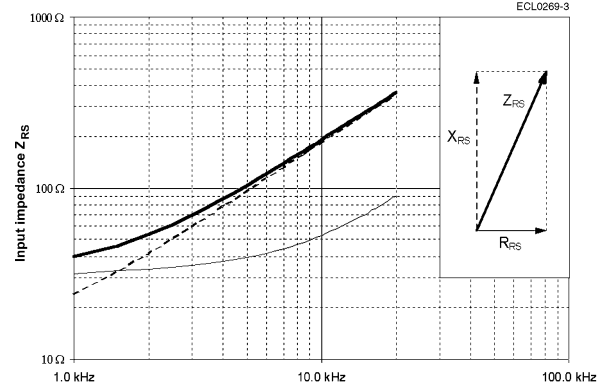
Tolerance: $\pm 15 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 15 \%$

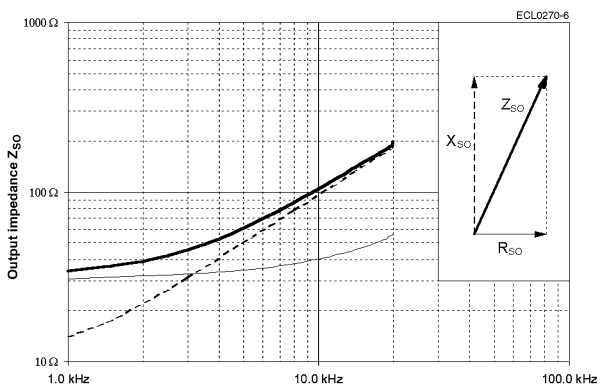
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

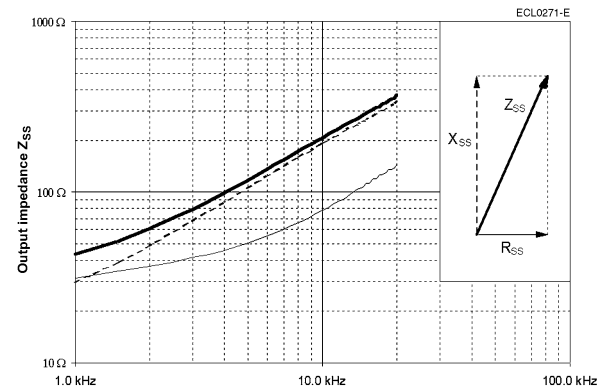
Tolerance: $\pm 15 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 15 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
 at $f = 10 \text{ kHz}$

$L_{RO} = 3.5 \text{ mH}$
 $L_{SS} = 3.1 \text{ mH}$

Housing	Aluminum	V23401-T 2001-B2..
	CrNi-steel	V23401-H2001-B2..

Electrical error / Ordering information

Angular error spread $\Delta\phi$	Ordering code	
	Aluminum housing	CrNi-steel housing
	$\pm 20'$	V23401-T2001-B214
	$\pm 15'$	V23401-H2001-B214
	$\pm 10'$	V23401-T2001-B222
$\pm 10'$	V23401-H2001-B222	
$\pm 7'$	V23401-T2001-B201	
	V23401-H2001-B201	
	V23401-T2001-B202	
	V23401-H2001-B202	
Residual voltage $V_{residual}$	25 mV at $V_{R1-R2} = 7 V$	

Electrical data at 22 °C.

Transfer function

Pairs of poles p	p = 1
<p>Transformation ratio r_T</p> $r_T = V_{S1-S3 \max} / V_{R1-R2}$ $= V_{S2-S4 \max} / V_{R1-R2}$ <p>= 0.5 ± 10 % within 2 ... 10 kHz = 0.5 ± 5 % at 5 kHz</p>	
<p>Phase shift ψ</p> $V_{R1-R2}(t) = V_{R1-R2 \max} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$ $V_{S1-S3}(t) = V_{S1-S3 \max} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$ <p>for $-90^\circ < \alpha < +90^\circ$</p> <p>Tolerance: ± 5°</p>	

Size 21

Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	$4 V_{rms} \dots 12 V_{rms}$
Frequency f, typical	2 kHz ... 10 kHz

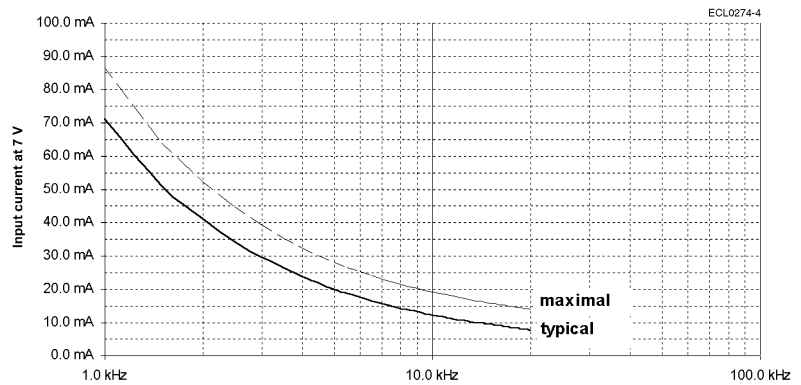
When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.5 W$ is not critical.

Input current I

The adjacent figure applies to $V_{R1-R2} = 7 V$.

For other input voltages, the input current changes follows as:

$$I = I_{Figure} \cdot V_{R1-R2} / 7 V$$

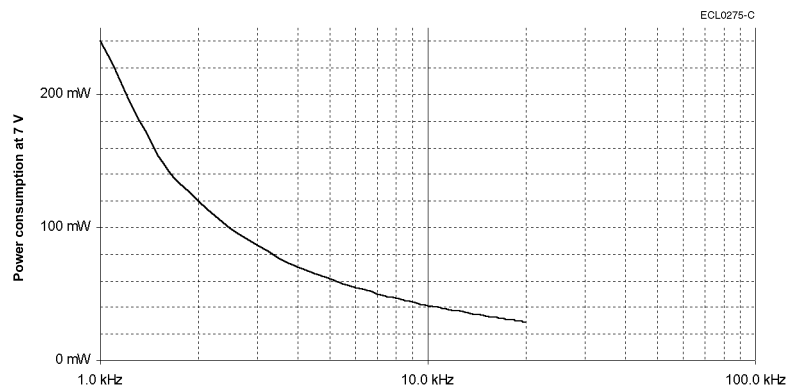


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 7 V$.

For other input voltages, the power consumption changes follows as:

$$P = P_{Figure} \cdot (V_{R1-R2} / 7 V)^2$$



Resistance, impedance and operating parameters (continued)

DC resistance

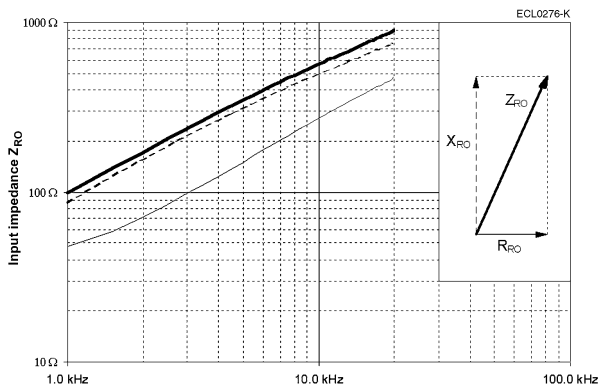
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 24 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 58 \Omega$
Tolerance: $\pm 10 \%$

Input impedance

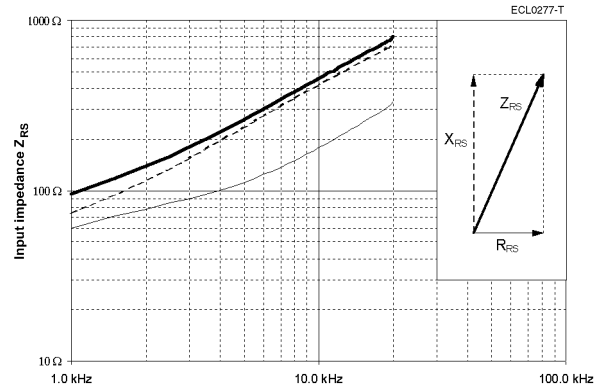
Tolerance: $\pm 15 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 15 \%$

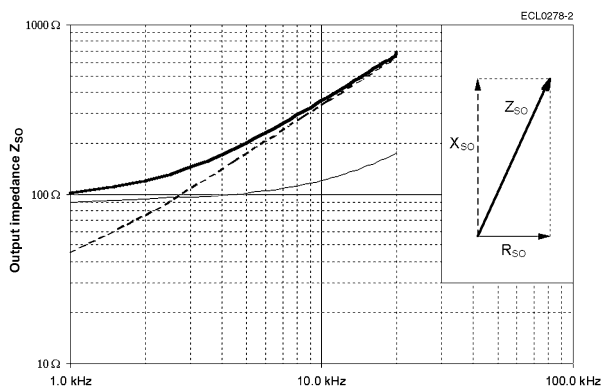
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

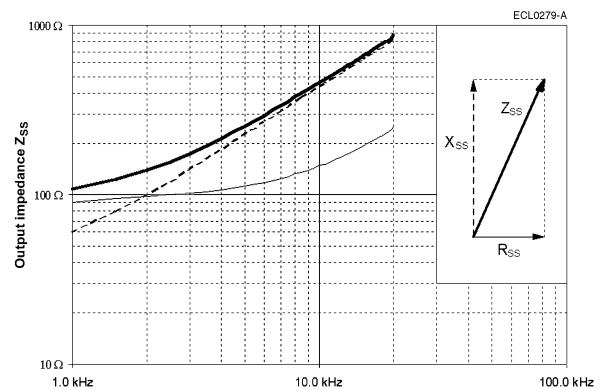
Tolerance: $\pm 15 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 15 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
at $f = 10 \text{ kHz}$

$L_{RO} = 7.9 \text{ mH}$
 $L_{SS} = 6.9 \text{ mH}$

Housing	Aluminum	V23401-T 2009-B2..
	CrNi-steel	V23401-H 2009-B2..

Electrical error / Ordering information

Angular error spread $\Delta\phi$	Ordering code	
	Aluminum housing	CrNi-steel housing
	$\pm 20'$	V23401-T2009-B214
	$\pm 15'$	V23401-H2009-B214
	$\pm 10'$	V23401-T2009-B222
$\pm 10'$	V23401-H2009-B222	
$\pm 7'$	V23401-T2009-B201	
$\pm 7'$	V23401-H2009-B201	
$\pm 7'$	V23401-T2009-B202	
$\pm 7'$	V23401-H2009-B202	
Residual voltage V_{residual}	14 mV at $V_{R1-R2} = 4 \text{ V}$	

Electrical data at 22 °C.

Transfer function

Pairs of poles p	$p = 1$
<p>Transformation ratio r_T</p> $r_T = V_{S1-S3 \text{ max}} / V_{R1-R2}$ $= V_{S2-S4 \text{ max}} / V_{R1-R2}$ <p>$= 0.5 \pm 10 \%$ within 2 ... 8 kHz $= 0.5 \pm 5 \%$ at 5 kHz</p>	
<p>Phase shift ψ</p> $V_{R1-R2}(t) = V_{R1-R2 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$ $V_{S1-S3}(t) = V_{S1-S3 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$ <p>for $-90^\circ < \alpha < +90^\circ$</p> <p>Tolerance: $\pm 5^\circ$</p>	

Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	$2 V_{rms} \dots 8 V_{rms}$
Frequency f, typical	2 kHz ... 10 kHz

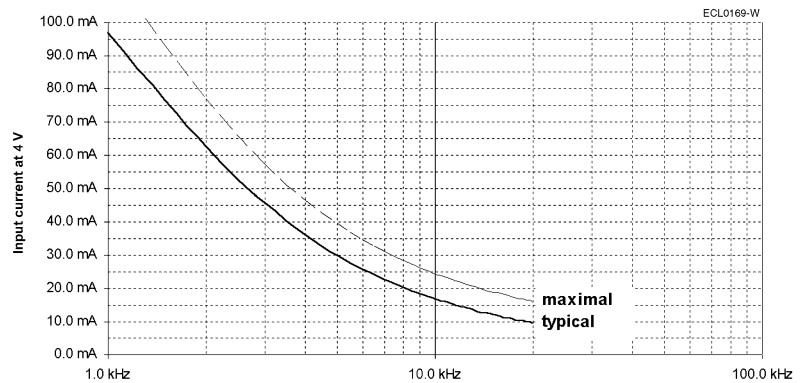
When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.5 \text{ W}$ is not critical.

Input current I

The adjacent figure applies to $V_{R1-R2} = 4 \text{ V}$.

For other input voltages, the input current changes follows as:

$$I = I_{\text{Figure}} \cdot V_{R1-R2} / 4 \text{ V}$$

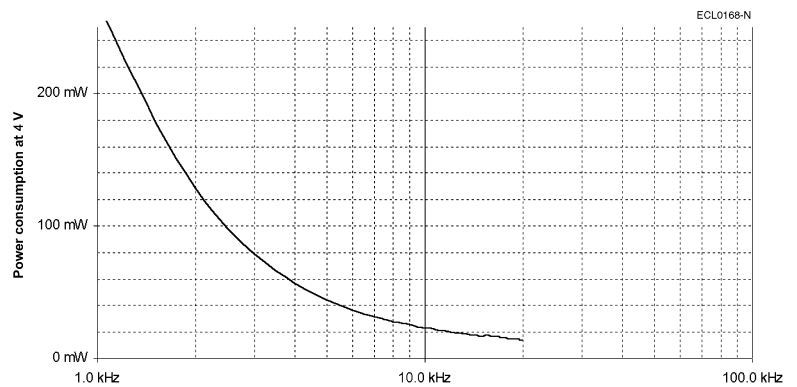


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 4 \text{ V}$.

For other input voltages, the power consumption changes follows as:

$$P = P_{\text{Figure}} \cdot (V_{R1-R2} / 4 \text{ V})^2$$



Resistance, impedance and operating parameters (continued)

DC resistance

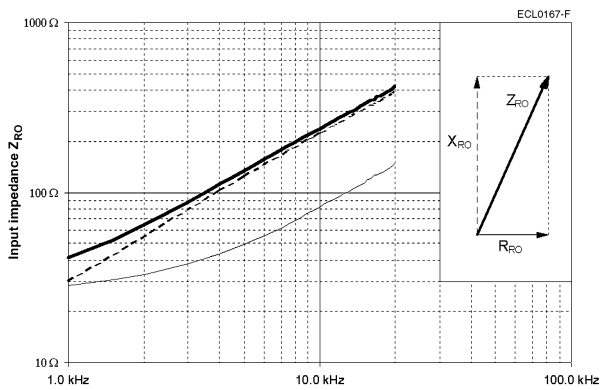
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 21 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 22 \Omega$
 Tolerance: $\pm 10 \%$

Input impedance

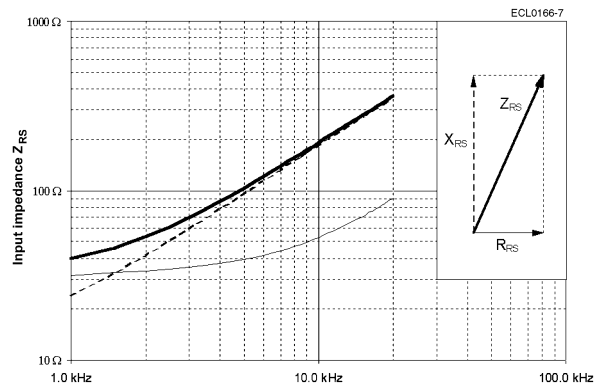
Tolerance: $\pm 15 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 15 \%$

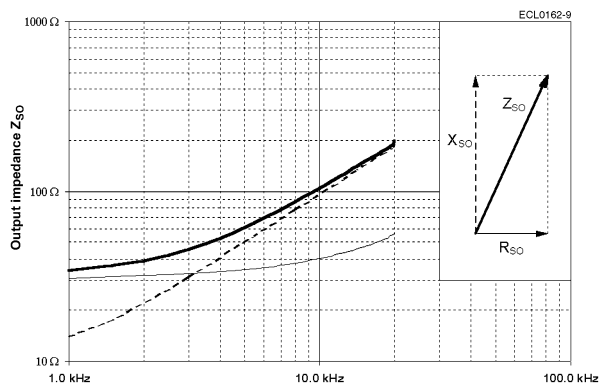
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

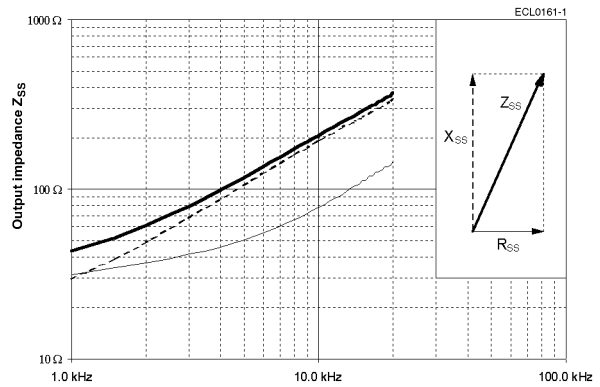
Tolerance: $\pm 15 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 15 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
 at $f = 10 \text{ kHz}$

$L_{RO} = 3.5 \text{ mH}$
 $L_{SS} = 3.1 \text{ mH}$

Housing	Aluminum	V23401-T 2010-B2..
	CrNi-steel	V23401-H 2010-B2..

Electrical error / Ordering information

Angular error spread $\Delta\phi$	Ordering code	
	Aluminum housing	CrNi-steel housing
	$\pm 20'$	V23401-T2010-B214
	$\pm 15'$	V23401-H2010-B214
	$\pm 10'$	V23401-T2010-B222
$\pm 10'$	V23401-H2010-B222	
$\pm 7'$	V23401-T2010-B201	
	V23401-H2010-B201	
	V23401-T2010-B202	
	V23401-H2010-B202	
Residual voltage V_{residual}	20 mV at $V_{R1-R2} = 6 V$	

Electrical data at 22 °C.

Transfer function

Pairs of poles p	p = 3
<p>Transformation ratio r_T</p> $r_T = V_{S1-S3 \text{ max}} / V_{R1-R2}$ $= V_{S2-S4 \text{ max}} / V_{R1-R2}$ <p>= 0.46 ± 10 % within 3 ... 20 kHz = 0.46 ± 5 % at 6 kHz</p>	
<p>Phase shift ψ</p> $V_{R1-R2}(t) = V_{R1-R2 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$ $V_{S1-S3}(t) = V_{S1-S3 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$ <p>for $-90^\circ < \alpha < +90^\circ$</p> <p>Tolerance: ± 5°</p>	

Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	$2 V_{rms} \dots 10 V_{rms}$
Frequency f, typical	4 kHz ... 15 kHz

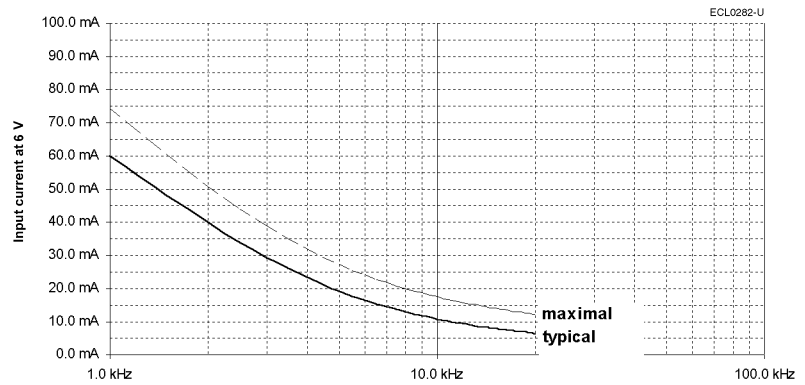
When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.5 \text{ W}$ is not critical.

Input current I

The adjacent figure applies to $V_{R1-R2} = 6 \text{ V}$.

For other input voltages, the input current changes follows as:

$$I = I_{\text{Figure}} \cdot V_{R1-R2} / 6 \text{ V}$$

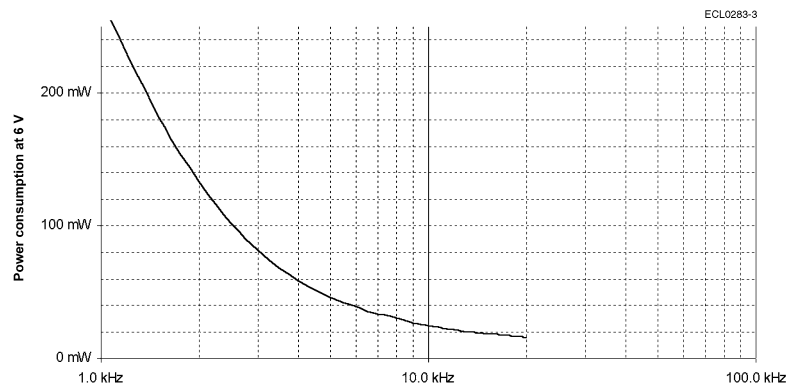


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 6 \text{ V}$.

For other input voltages, the power consumption changes follows as:

$$P = P_{\text{Figure}} \cdot (V_{R1-R2} / 6 \text{ V})^2$$



Resistance, impedance and operating parameters (continued)

DC resistance

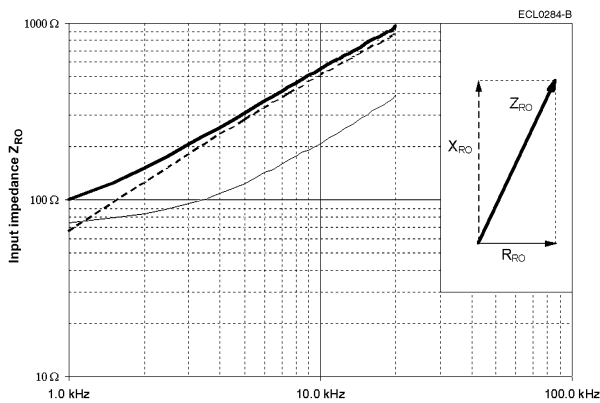
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 55 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 173 \Omega$
 Tolerance: $\pm 10 \%$

Input impedance

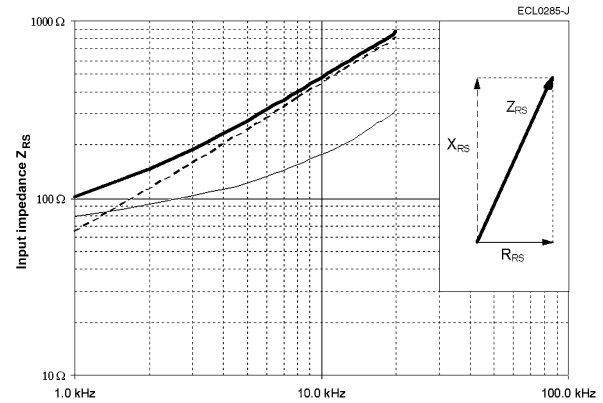
Tolerance: $\pm 15 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 15 \%$

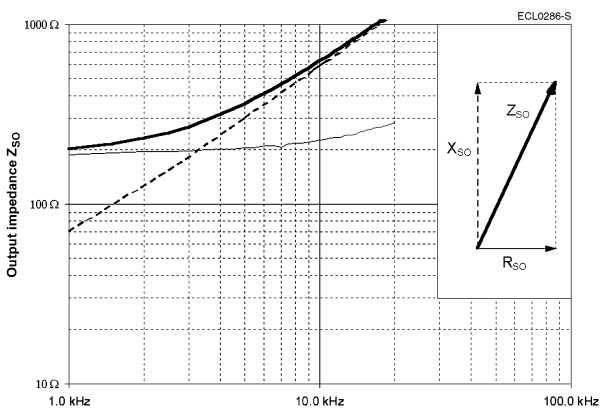
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

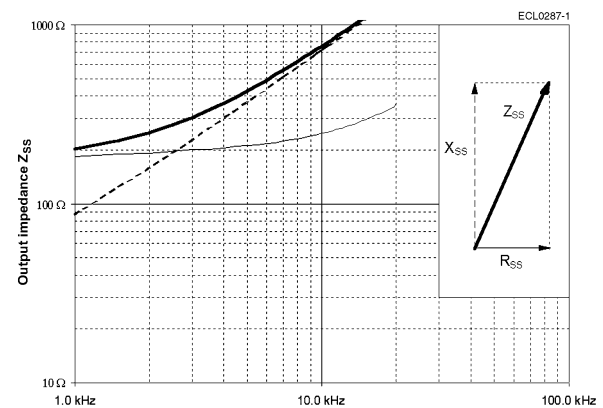
Tolerance: $\pm 15 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 15 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
 at $f = 10 \text{ kHz}$

$L_{RO} = 8.1 \text{ mH}$
 $L_{SS} = 11.4 \text{ mH}$

Housing	Aluminum	V23401-T2014-B2..
	CrNi-steel	V23401-H2014-B2..

Electrical error / Ordering information

Angular error spread $\Delta\phi$	Ordering code	
	Aluminum housing	CrNi-steel housing
	$\pm 20'$	V23401-T2014-B214
	$\pm 15'$	V23401-H2014-B214
	$\pm 10'$	V23401-T2014-B222
$\pm 10'$	V23401-H2014-B222	
$\pm 7'$	V23401-T2014-B201	
	V23401-H2014-B201	
	V23401-T2014-B202	
	V23401-H2014-B202	
Residual voltage $V_{residual}$	20 mV at $V_{R1-R2} = 6 V$	

Electrical data at 22 °C.

Transfer function

Pairs of poles p	$p = 4$
<p>Transformation ratio r_T</p> $r_T = V_{S1-S3 \max} / V_{R1-R2}$ $= V_{S2-S4 \max} / V_{R1-R2}$ <p>$= 0.46 \pm 10 \% \text{ within } 4 \dots 15 \text{ kHz}$ $= 0.46 \pm 5 \% \text{ at } 6 \text{ kHz}$</p>	
<p>Phase shift ψ</p> $V_{R1-R2}(t) = V_{R1-R2 \max} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$ $V_{S1-S3}(t) = V_{S1-S3 \max} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$ <p>for $-90^\circ < \alpha < +90^\circ$</p> <p>Tolerance: $\pm 5^\circ$</p>	

Size 21

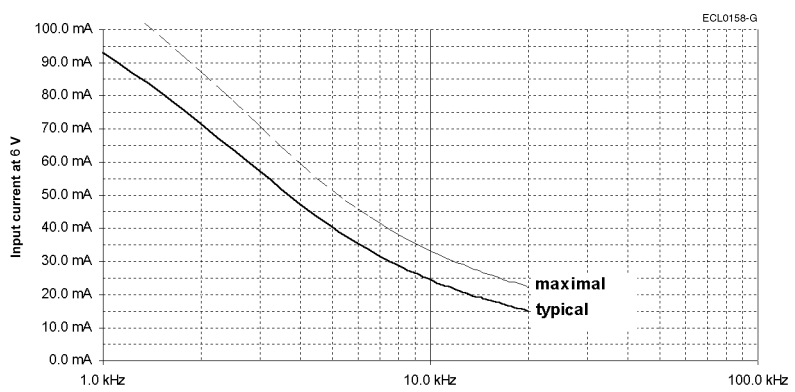
Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	$2 V_{rms} \dots 10 V_{rms}$	When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.5 W$ is not critical.
Frequency f, typical	4 kHz ... 15 kHz	

Input current I

The adjacent figure applies to $V_{R1-R2} = 6 V$.

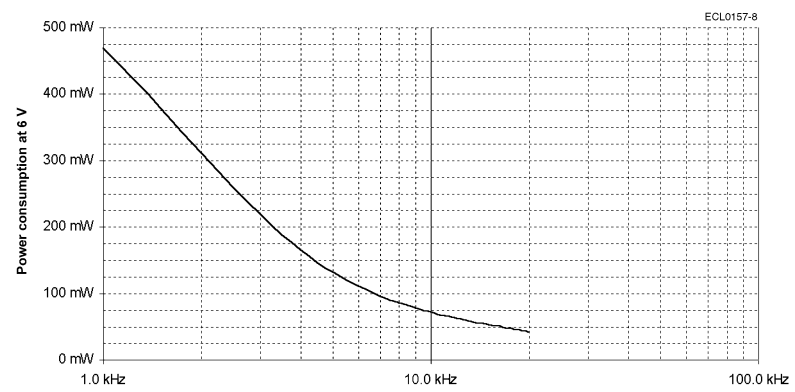
For other input voltages, the input current changes follows as:

$$I = I_{Figure} \cdot V_{R1-R2} / 6 V$$


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 6 V$.

For other input voltages, the power consumption changes follows as:

$$P = P_{Figure} \cdot (V_{R1-R2} / 6 V)^2$$


Resistance, impedance and operating parameters (continued)

DC resistance

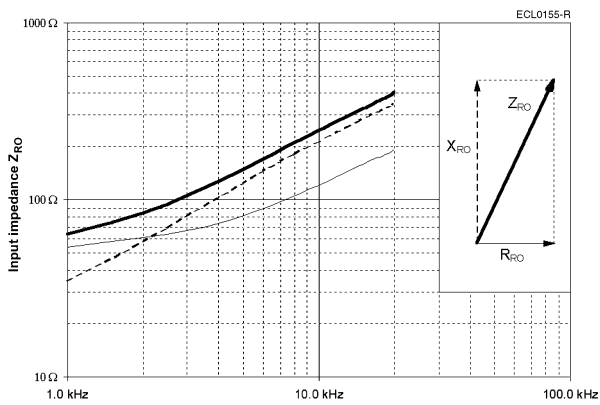
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 36 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 48 \Omega$
 Tolerance: $\pm 10 \%$

Input impedance

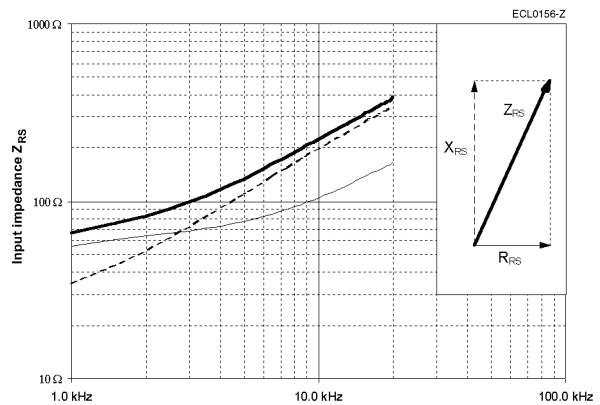
Tolerance: $\pm 15 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 15 \%$

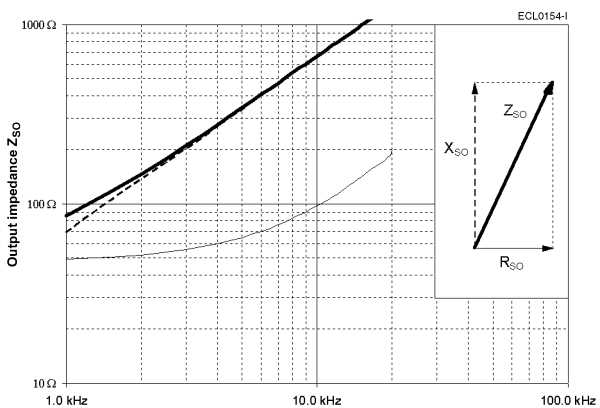
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

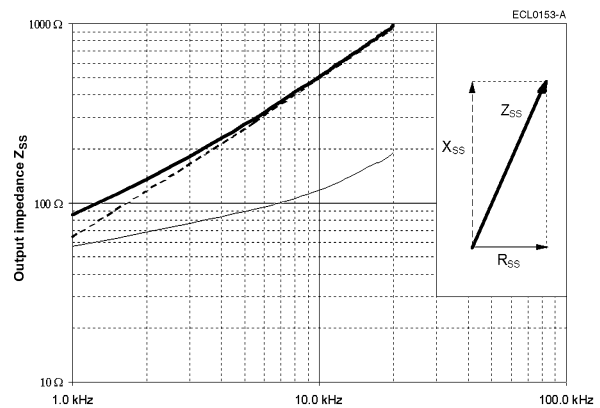
Tolerance: $\pm 15 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 15 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
 at $f = 10 \text{ kHz}$

$L_{RO} = 3.4 \text{ mH}$
 $L_{SS} = 7.8 \text{ mH}$

Housing	Aluminum	V23401-T 2015-B2..
	CrNi-steel	V23401-H 2015-B2..

Electrical error / Ordering information

Angular error spread $\Delta\phi$	Ordering code	
	Aluminum housing	CrNi-steel housing
	$\pm 20'$	V23401-T2015-B214
	$\pm 15'$	V23401-H2015-B214
	$\pm 10'$	V23401-T2015-B222
$\pm 10'$	V23401-H2015-B222	
$\pm 7'$	V23401-T2015-B201	
	V23401-H2015-B201	
	V23401-T2015-B202	
	V23401-H2015-B202	
Residual voltage V_{residual}	21 mV at $V_{R1-R2} = 6\text{ V}$	

Electrical data at 22 °C.

Transfer function

Pairs of poles p	$p = 2$
<p>Transformation ratio r_T</p> $r_T = V_{S1-S3 \text{ max}} / V_{R1-R2}$ $= V_{S2-S4 \text{ max}} / V_{R1-R2}$ <p>$= 0.5 \pm 10\%$ within 4 ... 20 kHz $= 0.5 \pm 5\%$ at 10 kHz</p>	
<p>Phase shift ψ</p> $V_{R1-R2}(t) = V_{R1-R2 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$ $V_{S1-S3}(t) = V_{S1-S3 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$ <p>for $-90^\circ < \alpha < +90^\circ$</p> <p>Tolerance: $\pm 5^\circ$</p>	

Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	$2 V_{rms} \dots 10 V_{rms}$
Frequency f, typical	4 kHz ... 15 kHz

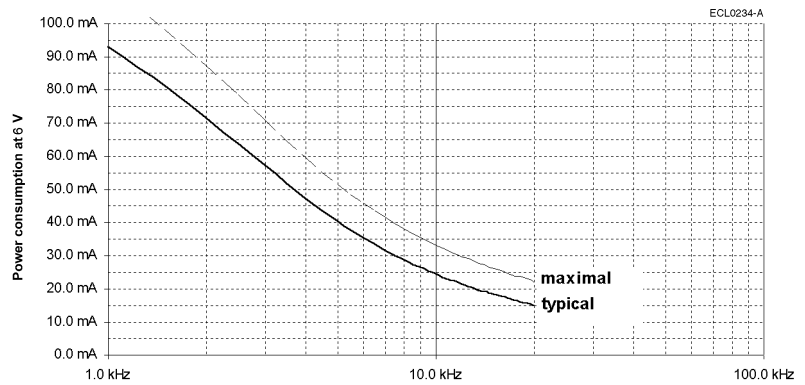
When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.5 W$ is not critical.

Input current I

The adjacent figure applies to $V_{R1-R2} = 6 V$.

For other input voltages, the input current changes follows as:

$$I = I_{Figure} \cdot V_{R1-R2} / 6 V$$

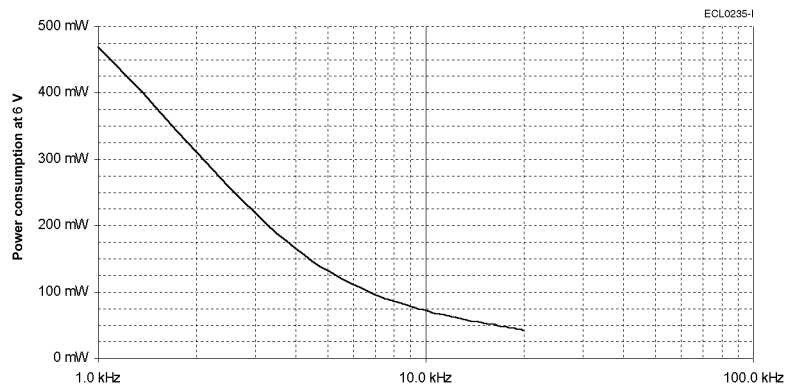


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 6 V$.

For other input voltages, the power consumption changes follows as:

$$P = P_{Figure} \cdot (V_{R1-R2} / 6 V)^2$$



Resistance, impedance and operating parameters (continued)

DC resistance

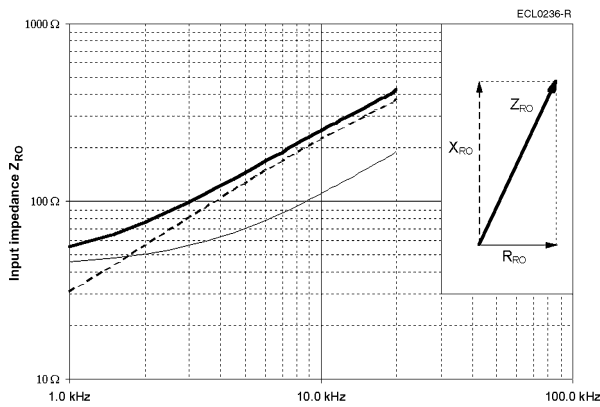
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 33 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 30 \Omega$
 Tolerance: $\pm 10 \%$

Input impedance

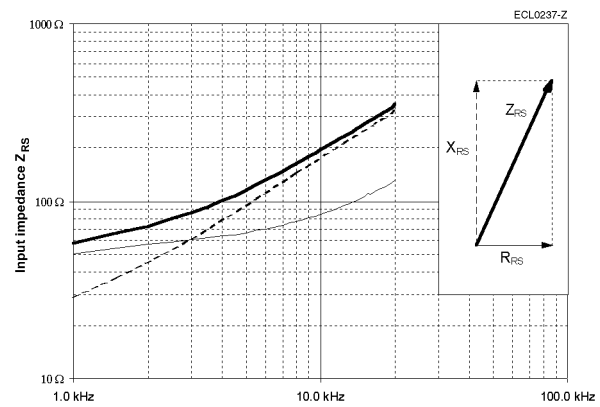
Tolerance: $\pm 15 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 15 \%$

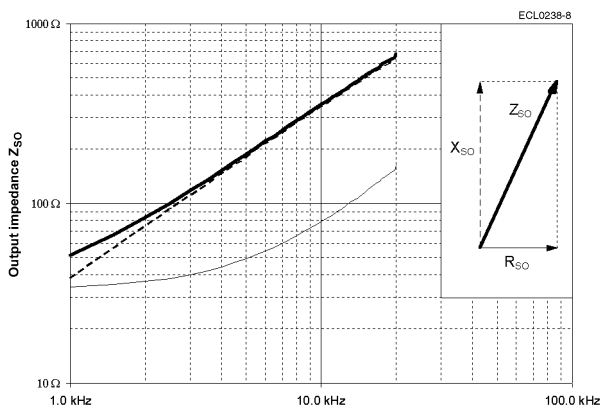
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

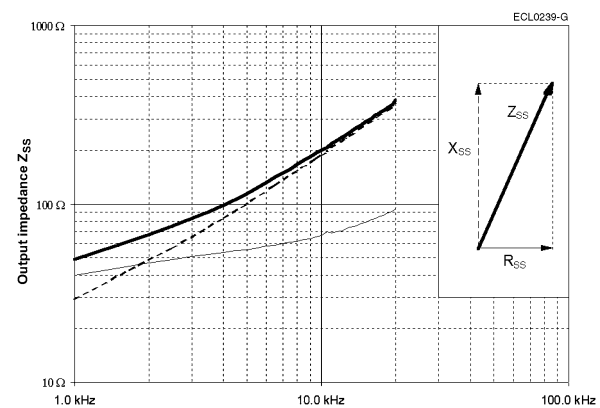
Tolerance: $\pm 15 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 15 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
 at $f = 10 \text{ kHz}$

$L_{RO} = 3.6 \text{ mH}$
 $L_{SS} = 3.0 \text{ mH}$

Housing CrMo-steel

Electrical error / Ordering information

Angular error spread $\Delta\phi$ $\pm 10'$ $\pm 8'$ $\pm 6'$ $\pm 4'$	Ordering code V23401-U1016-B101 V23401-U1016-B109 V23401-U1016-B110 V23401-U1016-B133
Residual voltage V_{residual}	14 mV at $V_{R1-R2} = 4 \text{ V}$

Electrical data at 22 °C.

Transfer function

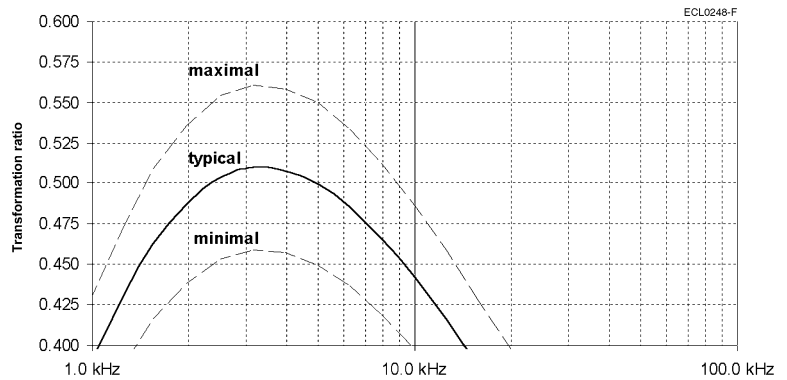
Pairs of poles p $\rho = 1$

Transformation ratio r_T

$$r_T = \frac{V_{S1-S3 \text{ max}}}{V_{R1-R2}}$$

$$= \frac{V_{S2-S4 \text{ max}}}{V_{R1-R2}}$$

$= 0.5 \pm 20 \% \text{ within } 1.5 \dots 10 \text{ kHz}$
 $= 0.5 \pm 10 \% \text{ at } 5 \text{ kHz}$



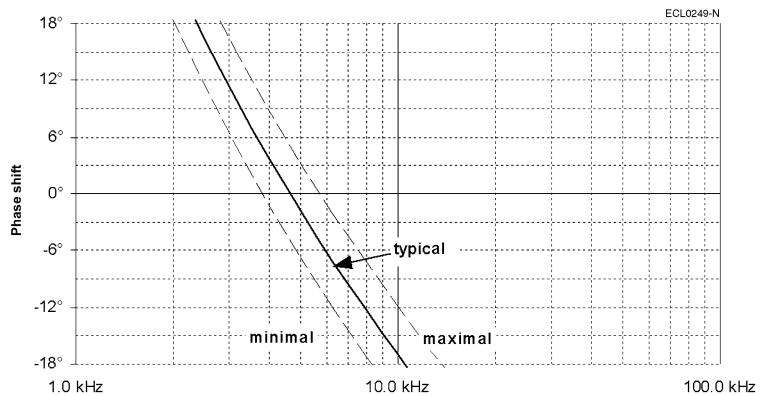
Phase shift ψ

$$V_{R1-R2}(t) = V_{R1-R2 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$$

$$V_{S1-S3}(t) = V_{S1-S3 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$$

for $-90^\circ < \alpha < +90^\circ$

Tolerance: $\pm 5^\circ$



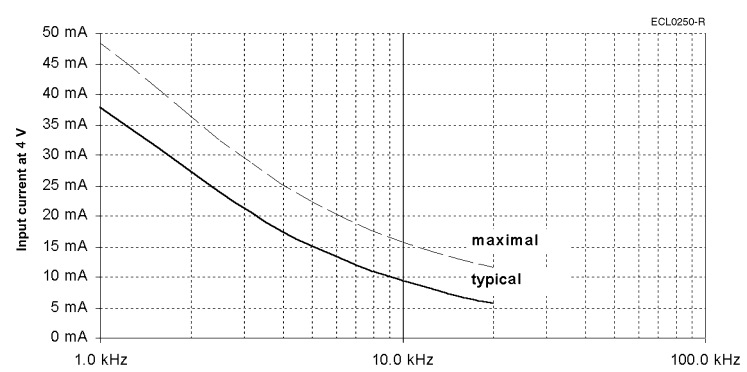
Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	$2 V_{rms} \dots 20 V_{rms}$	When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.5 W$ is not critical.
Frequency f, typical	2 kHz ... 10 kHz	

Input current I

The adjacent figure applies to $V_{R1-R2} = 4 V$.

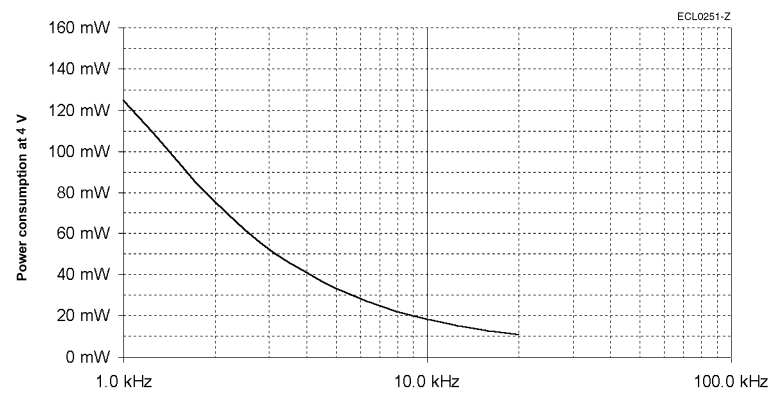
For other input voltages, the input current changes follows as:

$$I = I_{Figure} \cdot V_{R1-R2} / 4 V$$


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 4 V$.

For other input voltages, the power consumption changes follows as:

$$P = P_{Figure} \cdot (V_{R1-R2} / 4 V)^2$$


Resistance, impedance and operating parameters (continued)

DC resistance

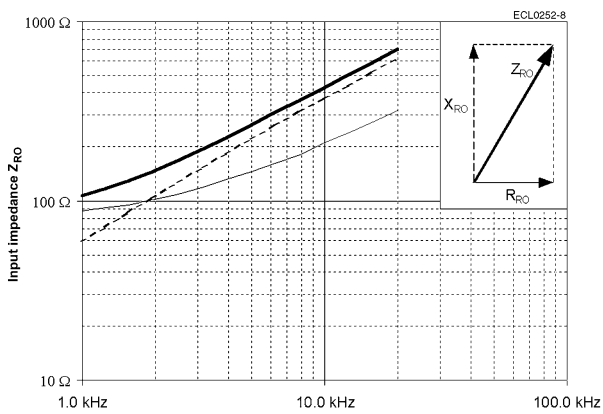
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 65 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 81 \Omega$
 Tolerance: $\pm 15 \%$

Input impedance

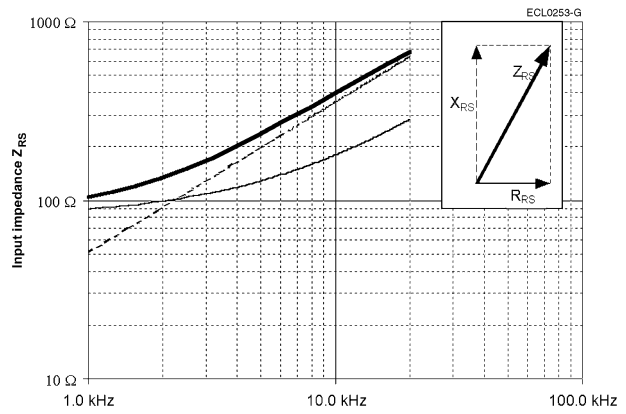
Tolerance: $\pm 20 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 20 \%$

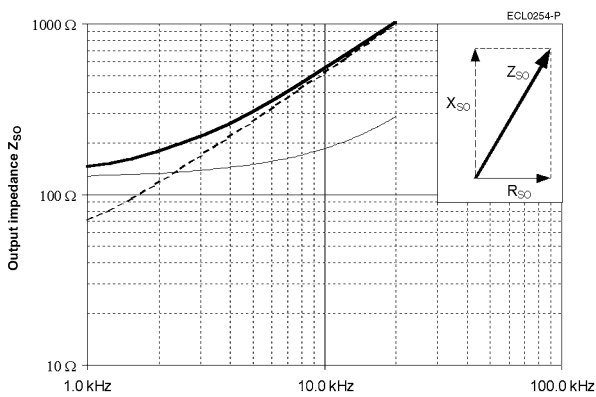
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

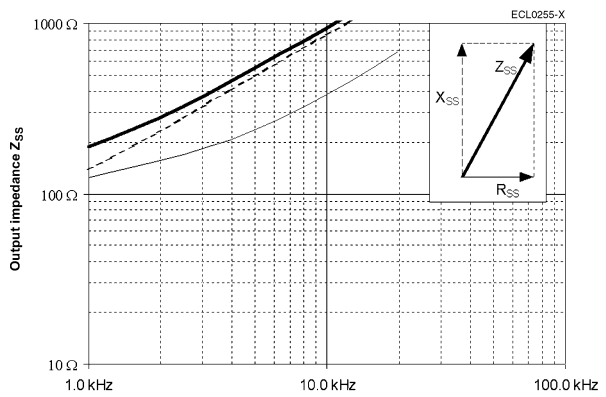
Tolerance: $\pm 20 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 20 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
 at $f = 5 \text{ kHz}$

$L_{RO} = 6 \text{ mH}$
 $L_{SS} = 13 \text{ mH}$

Housing

CrMo-steel

Electrical error / Ordering information

Angular error spread $\Delta\phi$
 $\pm 10'$
 $\pm 7'$
 $\pm 4'$

Ordering code
 V23401-U2017-B201
 V23401-U2017-B202
 V23401-U2017-B233

Residual voltage V_{residual}

18 mV at $V_{R1-R2} = 5 \text{ V}$

Electrical data at 22 °C.

Transfer function

Pairs of poles p

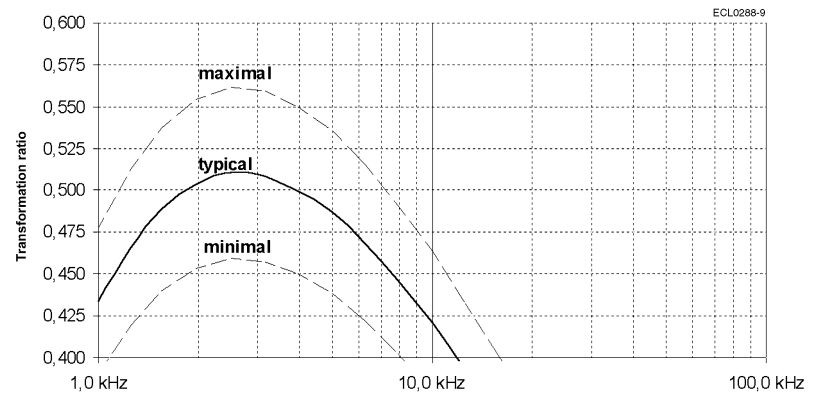
$p = 1$

Transformation ratio r_T

$$r_T = \frac{V_{S1-S3 \text{ max}}}{V_{R1-R2}}$$

$$= \frac{V_{S2-S4 \text{ max}}}{V_{R1-R2}}$$

$= 0.5 \pm 20\%$ within 1 ... 10 kHz
 $= 0.5 \pm 10\%$ at 4 kHz



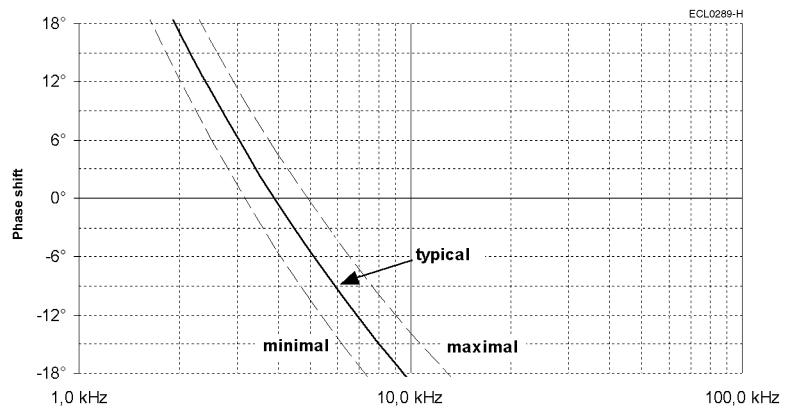
Phase shift ψ

$$V_{R1-R2}(t) = V_{R1-R2 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$$

$$V_{S1-S3}(t) = V_{S1-S3 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$$

for $-90^\circ < \alpha < +90^\circ$

Tolerance: $\pm 5^\circ$



Size 21

Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	4 V_{rms} ... 20 V_{rms}
Frequency f, typical	2 kHz ... 10 kHz

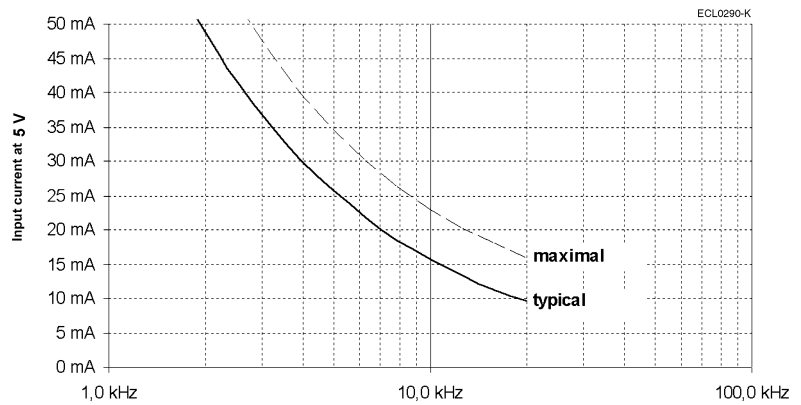
When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.5$ W is not critical.

Input current I

The adjacent figure applies to $V_{R1-R2} = 5$ V.

For other input voltages, the input current changes follows as:

$$I = I_{Figure} \cdot V_{R1-R2} / 5$$

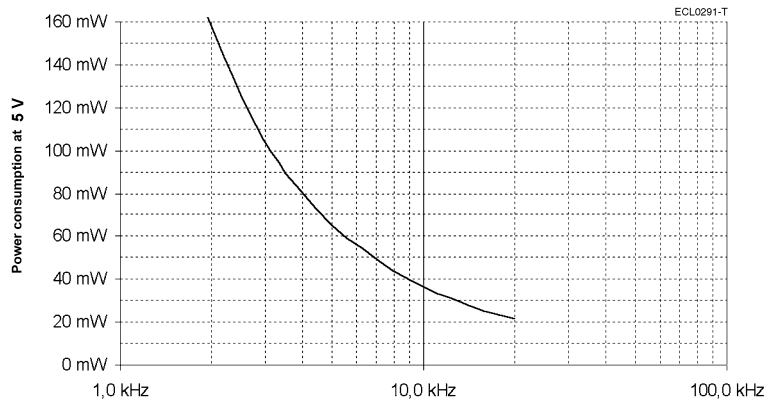


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 5$ V.

For other input voltages, the power consumption changes follows as:

$$P = P_{Figure} \cdot (V_{R1-R2} / 5)^2$$



Resistance, impedance and operating parameters (continued)

DC resistance

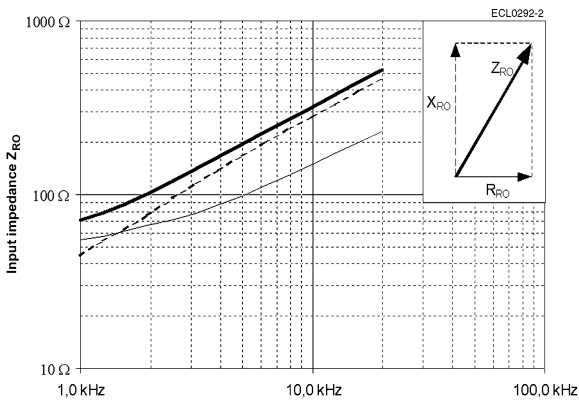
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 36 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 56 \Omega$
 Tolerance: $\pm 15 \%$

Input impedance

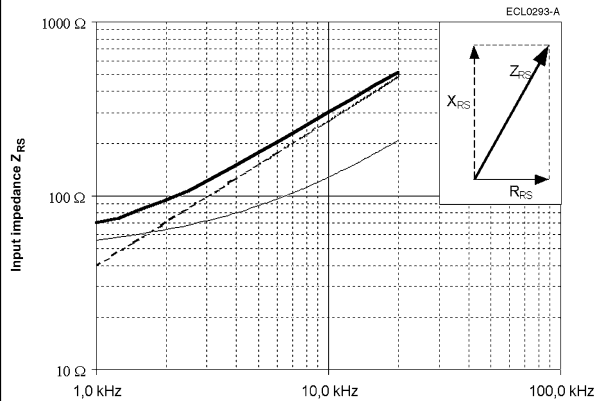
Tolerance: $\pm 20 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 20 \%$

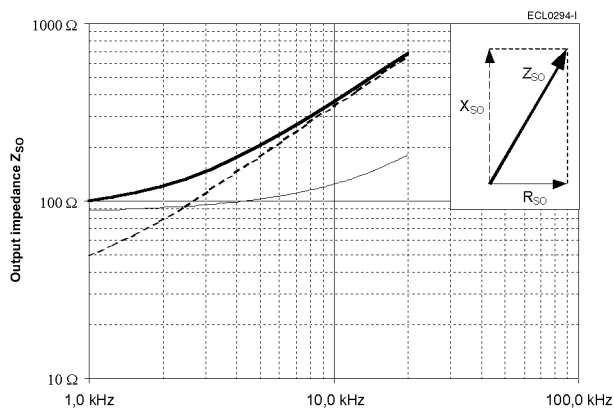
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

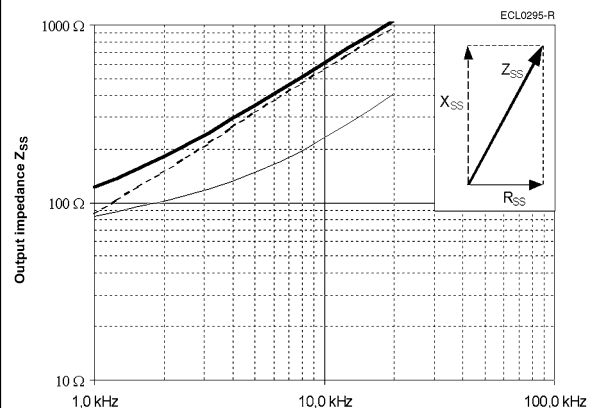
Tolerance: $\pm 20 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 20 \%$

Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2



Inductance L

$L = X / (2 \cdot \pi \cdot f)$
 at $f = 4 \text{ kHz}$

$L_{RO} = 5.5 \text{ mH}$
 $L_{SS} = 10.5 \text{ mH}$

Housing

CrMo-steel

Electrical error / Ordering information

Angular error spread $\Delta\phi$
 $\pm 10'$
 $\pm 8'$
 $\pm 6'$

Ordering code
 V23401-U2020-B201
 V23401-U2020-B209
 V23401-U2020-B210

Residual voltage V_{residual}

20 mV at $V_{R1-R2} = 6\text{ V}$

Electrical data at 22 °C.

Transfer function

Pairs of poles p

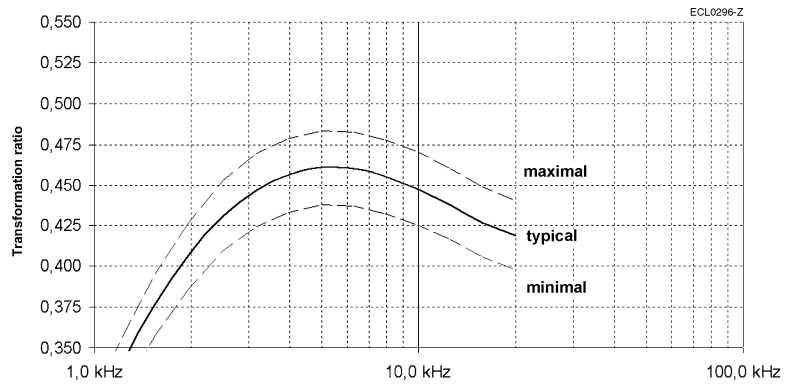
$p = 3$

Transformation ratio r_T

$$r_T = V_{S1-S3 \text{ max}} / V_{R1-R2}$$

$$= V_{S2-S4 \text{ max}} / V_{R1-R2}$$

= 0.5 \pm 10 % within 3 ... 10 kHz
 = 0.5 \pm 5 % at 6 kHz



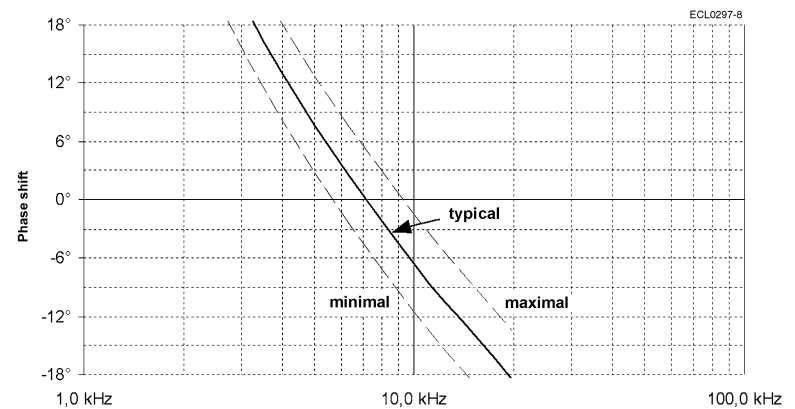
Phase shift ψ

$$V_{R1-R2}(t) = V_{R1-R2 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t)$$

$$V_{S1-S3}(t) = V_{S1-S3 \text{ max}} \cdot \sin(2 \cdot \pi \cdot f \cdot t - \psi)$$

for $-90^\circ < \alpha < +90^\circ$

Tolerance: $\pm 5^\circ$



Resistance, impedance and operating parameters

Input voltage V_{R1-R2}, typical	$2 V_{rms} \dots 10 V_{rms}$
Frequency f, typical	4 kHz ... 10 kHz

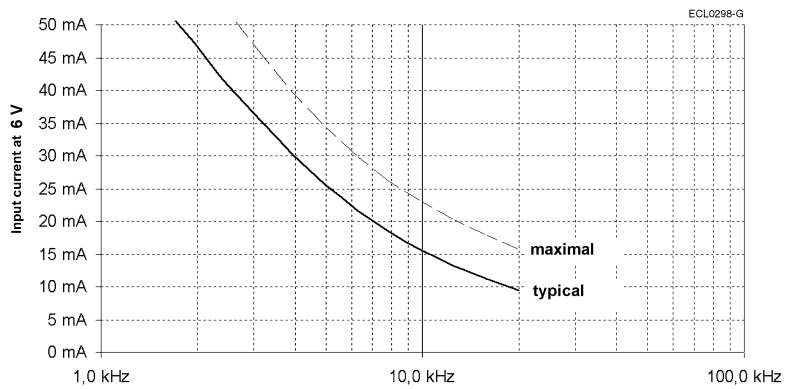
When choosing the values of these parameters take into account power dissipation, max. ambient temperature and the heat dissipation. Including self heating a maximum operating temperature of 150 °C must not be exceeded. Generally a power dissipation of $P \leq 0.5$ W is not critical.

Input current I

The adjacent figure applies to $V_{R1-R2} = 6$ V.

For other input voltages, the input current changes follows as:

$$I = I_{Figure} \cdot V_{R1-R2} / 6$$

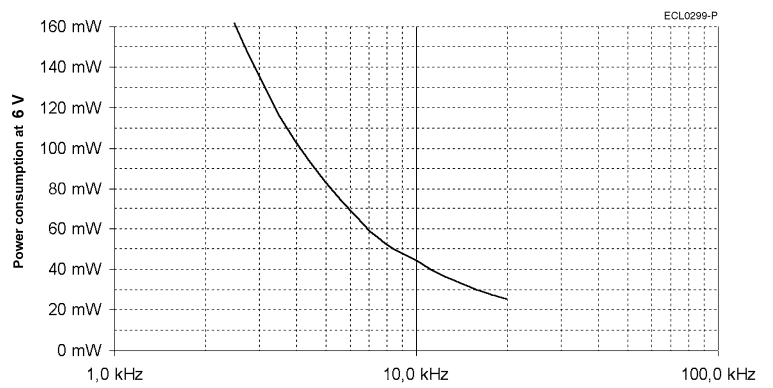


Power consumption P

The adjacent figure applies to $V_{R1-R2} = 6$ V.

For other input voltages, the power consumption changes follows as:

$$P = P_{Figure} \cdot (V_{R1-R2} / 6)^2$$



Resistance, impedance and operating parameters (continued)

DC resistance

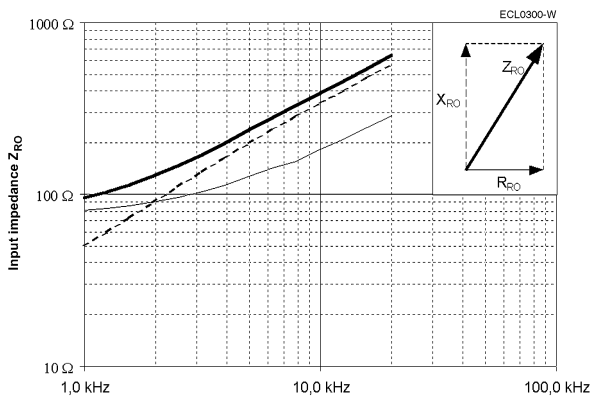
The ohmic resistance values are based on an ambient temperature of 22 °C and change with temperature by 0.39 % / K

$R_{R1-R2} = 62 \Omega$
 $R_{S1-S3} = R_{S2-S4} = 186 \Omega$
 Tolerance: $\pm 10 \%$

Input impedance

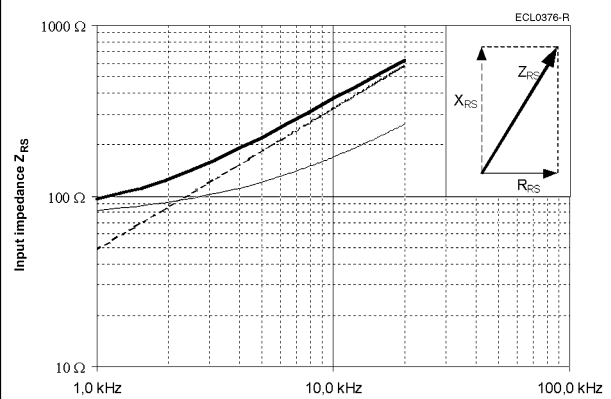
Tolerance: $\pm 15 \%$

Z_{RO} ... Impedance between R1 and R2 with open outputs



Tolerance: $\pm 15 \%$

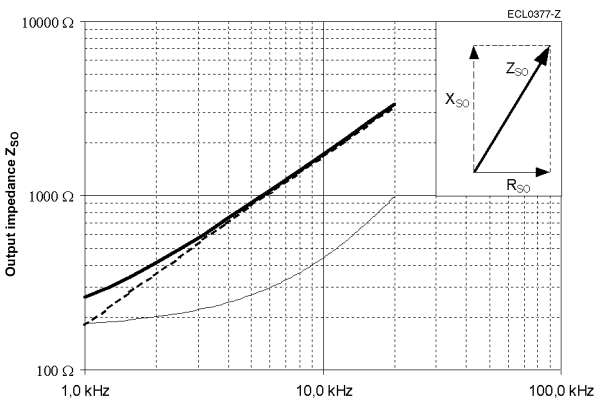
Z_{RS} ... Impedance between R1 and R2 with short circuits between S1 and S3 as well as between S2 and S4



Output impedance

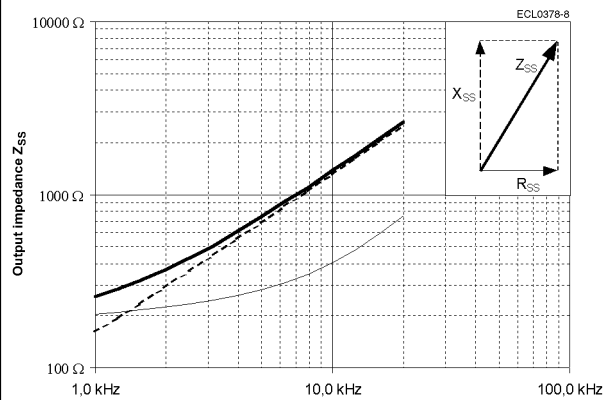
Tolerance: $\pm 15 \%$

Z_{SO} ... Impedance between S2 and S4 in a position of 0° (minimal coupling) with open outputs



Tolerance: $\pm 15 \%$

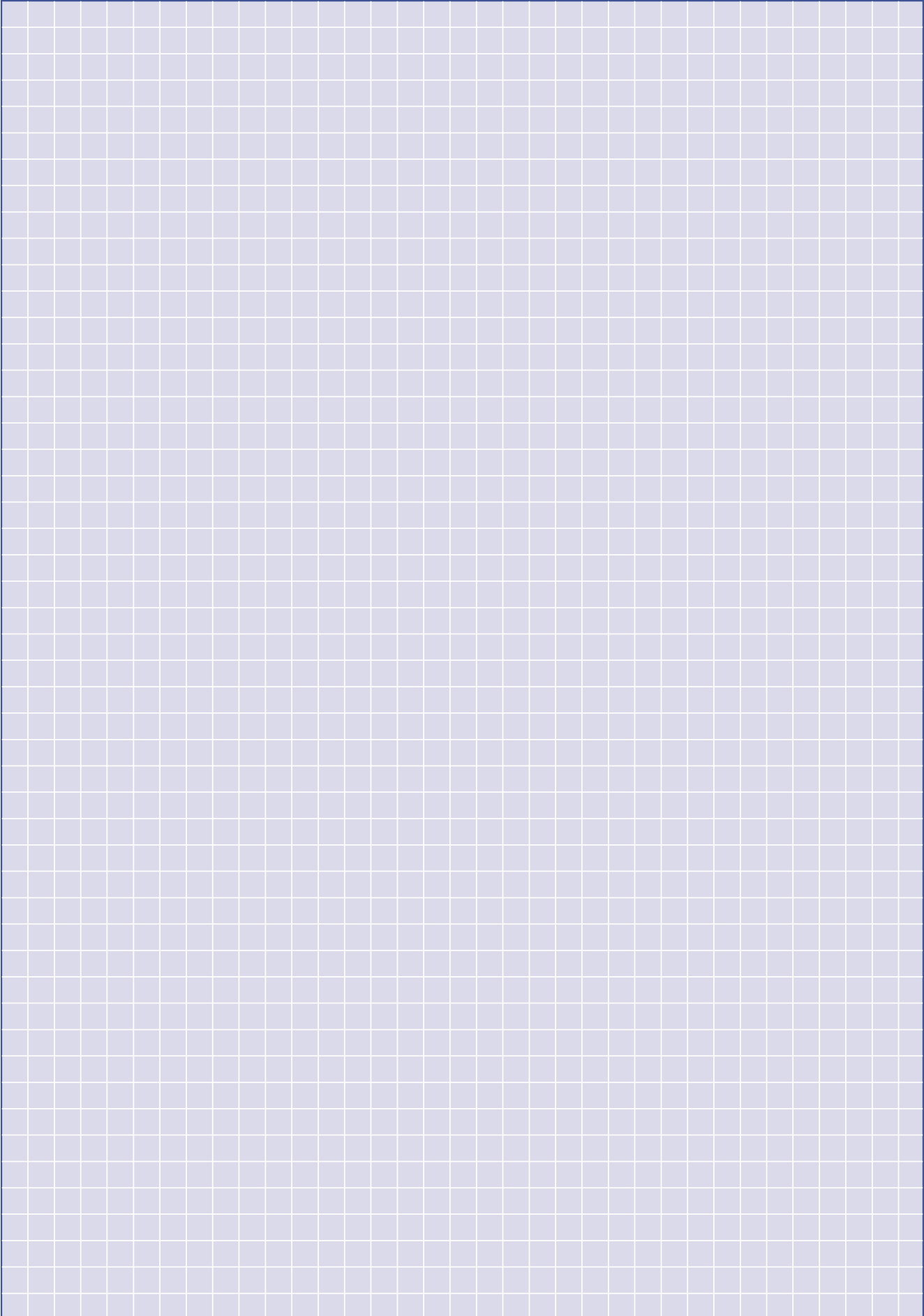
Z_{SS} ... Impedance between S1 and S3 in a position of 0° (max. coupling) with short circuits between R1 and R2

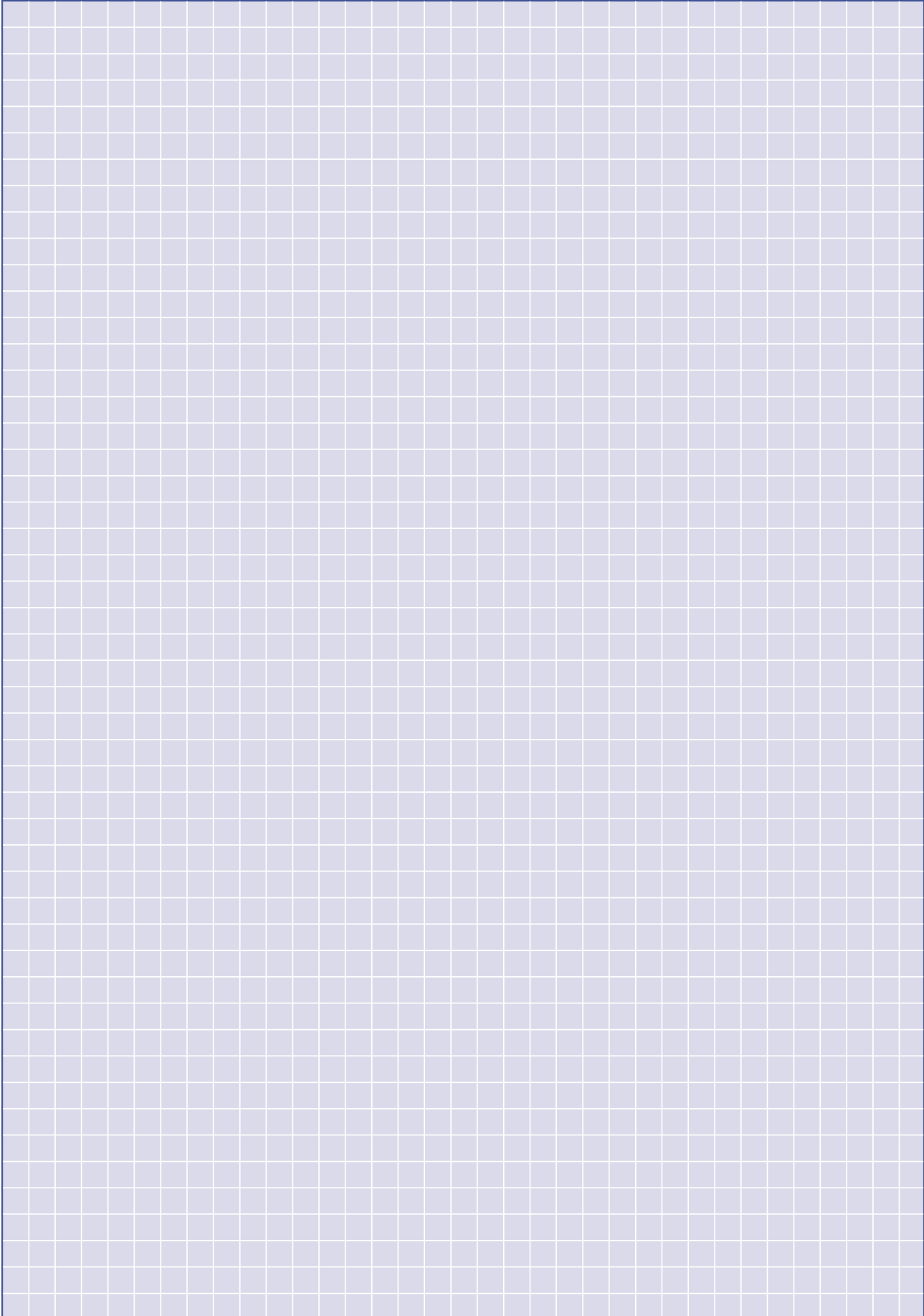


Inductance L

$L = X / (2 \cdot \pi \cdot f)$
 at $f = 6 \text{ kHz}$

$L_{RO} = 4 \text{ mH}$
 $L_{SS} = 14 \text{ mH}$





Size 21

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Colombia – Bogota
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Mexico – Mexico City
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Fax: +52-5-361-8545

United States – Harrisburg, PA
Phone: +717-564-0100
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Venezuela – Caracas
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Korea – Seoul
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Malaysia – Selangor
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Shunde
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Taiwan – Taipei
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Croatia – Zagreb
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France Export – St Ouen L'Aumone
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Fax: +34-93-201-7879

Sweden – Upplands Väsby
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Fax: +46-8-50-72-50-01

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ISO 14000 certification is in preparation**

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