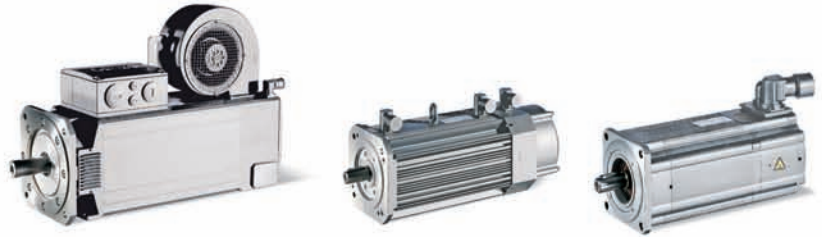


L-force *Servo motors*



Dynamic, powerful and compact

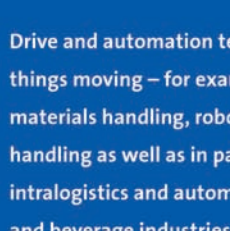
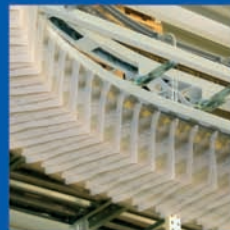
NEW

MCA 9 kW - 53.8 kW
MQA 10.6 kW - 60.2 kW

Lenze

This is what we stand for.

You want to implement your machine and plant concepts efficiently and easily or optimise existing concepts to reduce costs? Then, Lenze is the partner you are looking for. For more than 60 years, drive and automation systems have been our core competence.

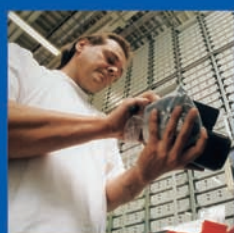
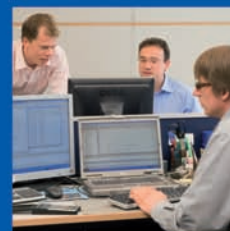


Drive and automation technology from Lenze keep things moving – for example in the areas of materials handling, robotics and component handling as well as in packaging facilities for the intralogistics and automotive sectors and the food and beverage industries.

Lenze | about us

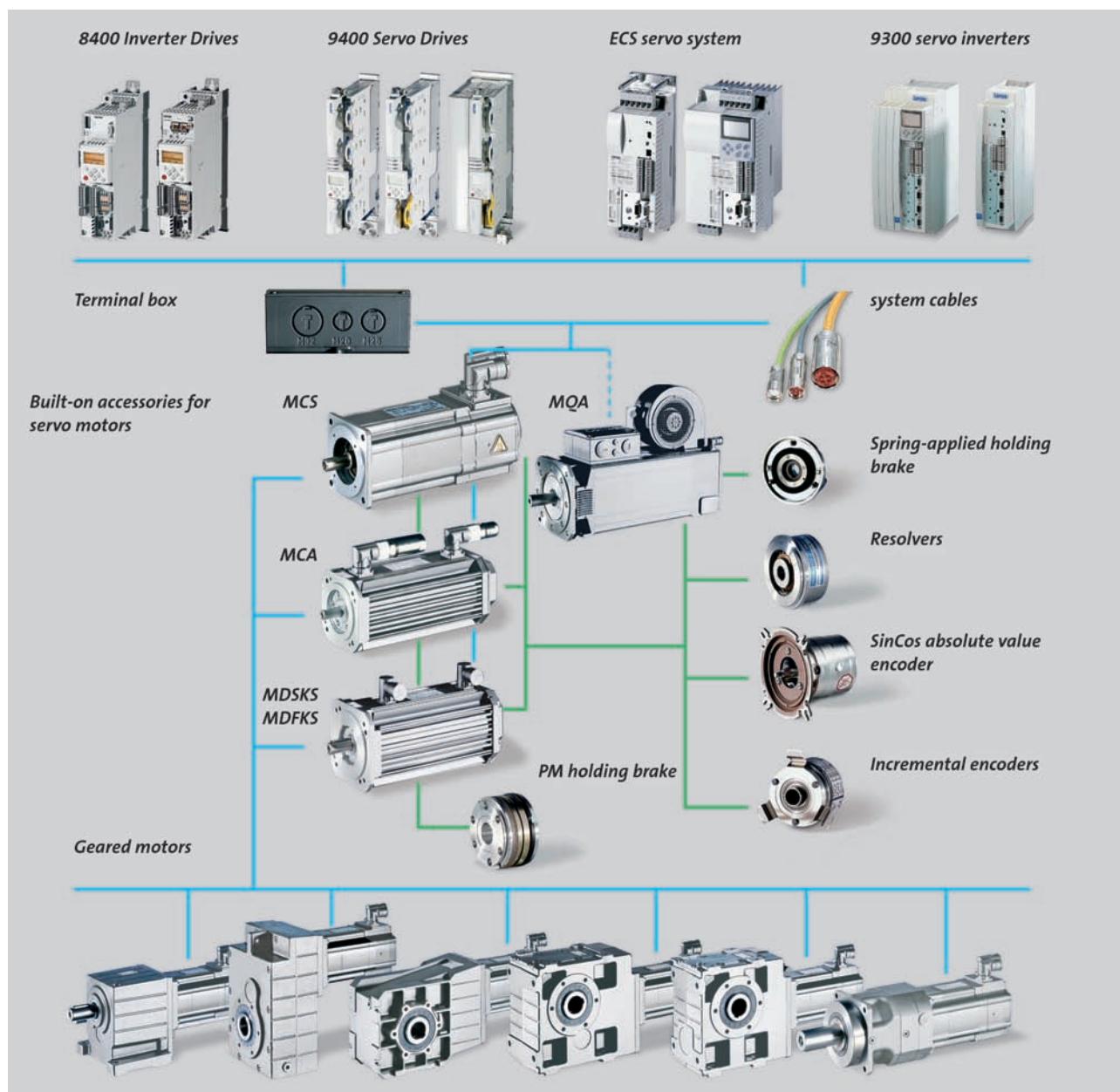
We can offer you automation solutions including control, visualisation and drive technology from a single source. Our drive systems will improve the performance of your machines. From project planning to commissioning, we have the know-how, whilst our international sales and service network can provide you with expert help and advice at any time.

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At your side all over the world – with thorough and professional support from our motivated team.

System overview | L-force Servo motors



Other catalogues

In this catalogue, servo motors are described. The other components of the above system overview can be found in the following catalogues:

| Components | |
|----------------------|---|
| Servo Drives 9400 | Catalogue: Servo Drives 9400 |
| ECS servo system | Catalogue: ECS servo system |
| 9300 servo inverter | Catalogue: 9300 servo inverters |
| Geared servo motors | Catalogue: G-motion servo MC |
| Inverter Drives 8400 | Catalogue: L-force Inverter Drives 8400 |

Overview | L-force Servo motors

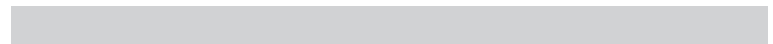
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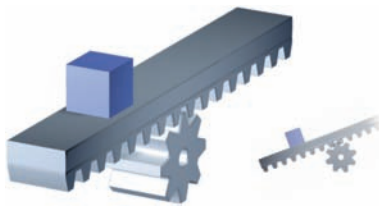
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Drive dimensioning



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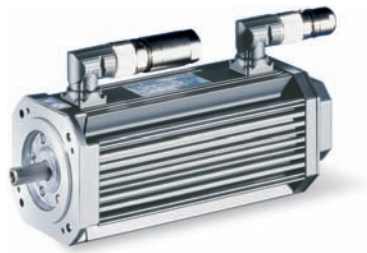
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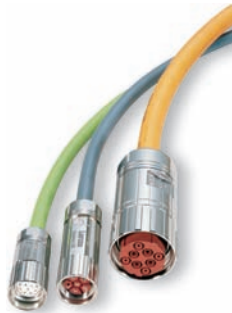
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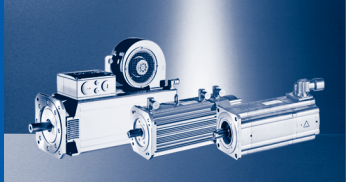
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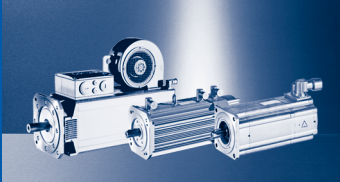


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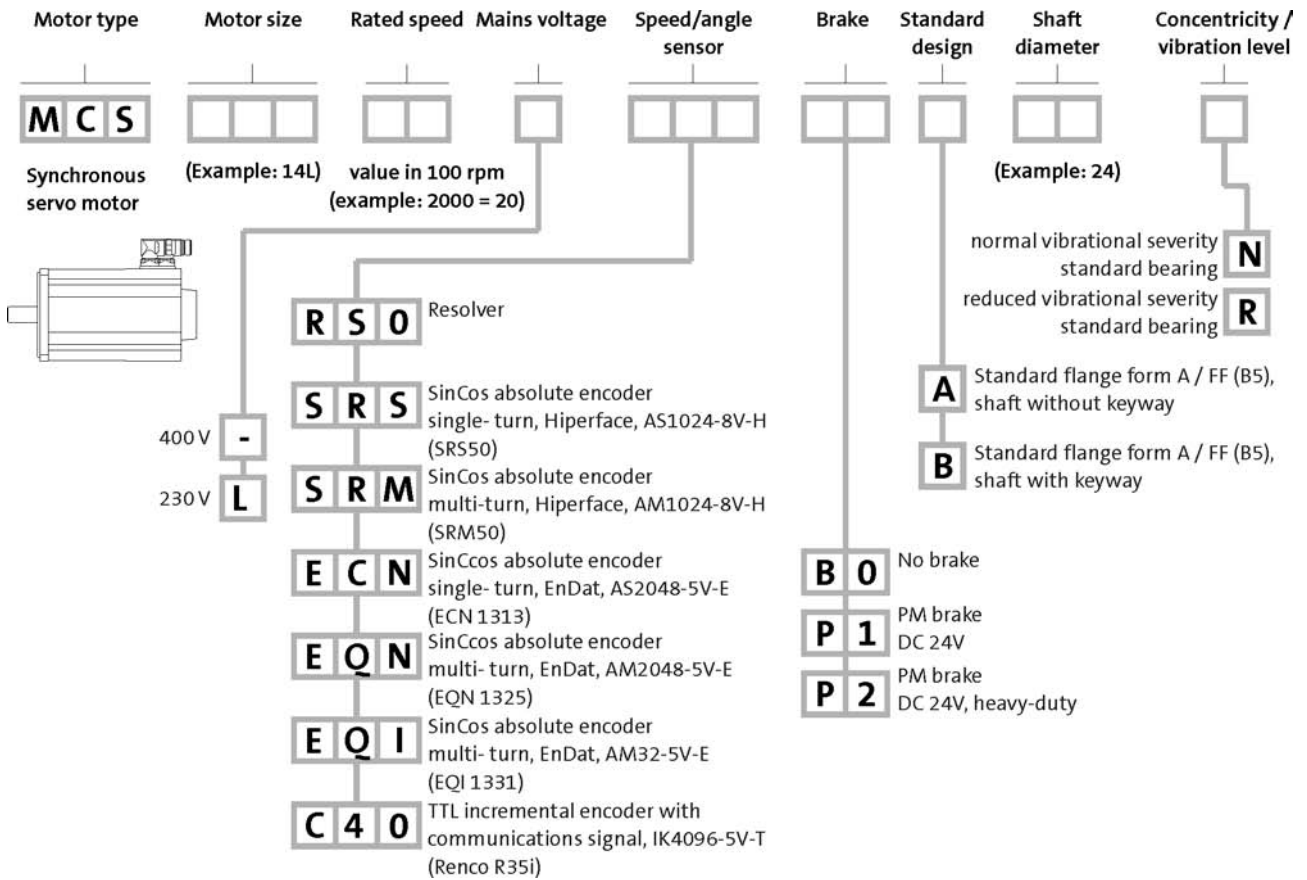




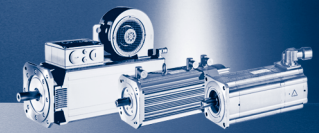
General information

Product key

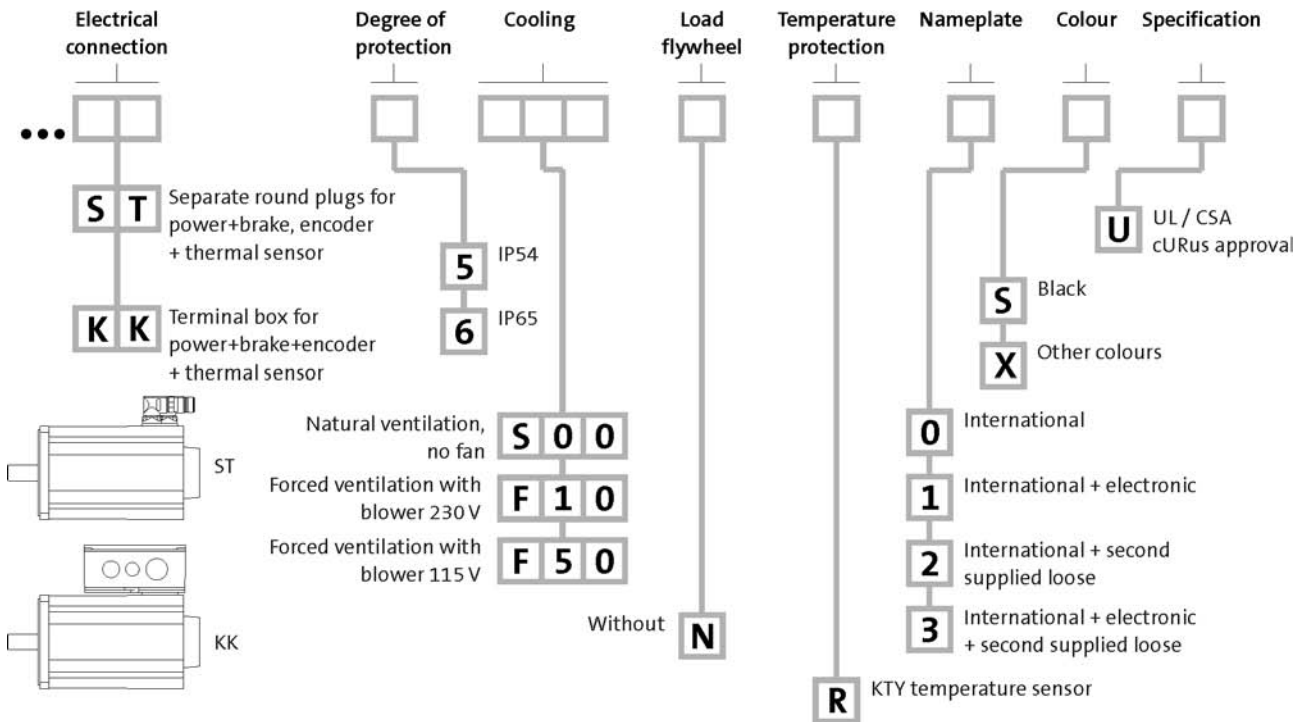
MCS synchronous servo motors



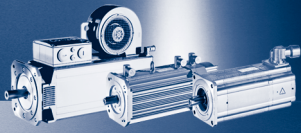
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MCS synchronous servo motors



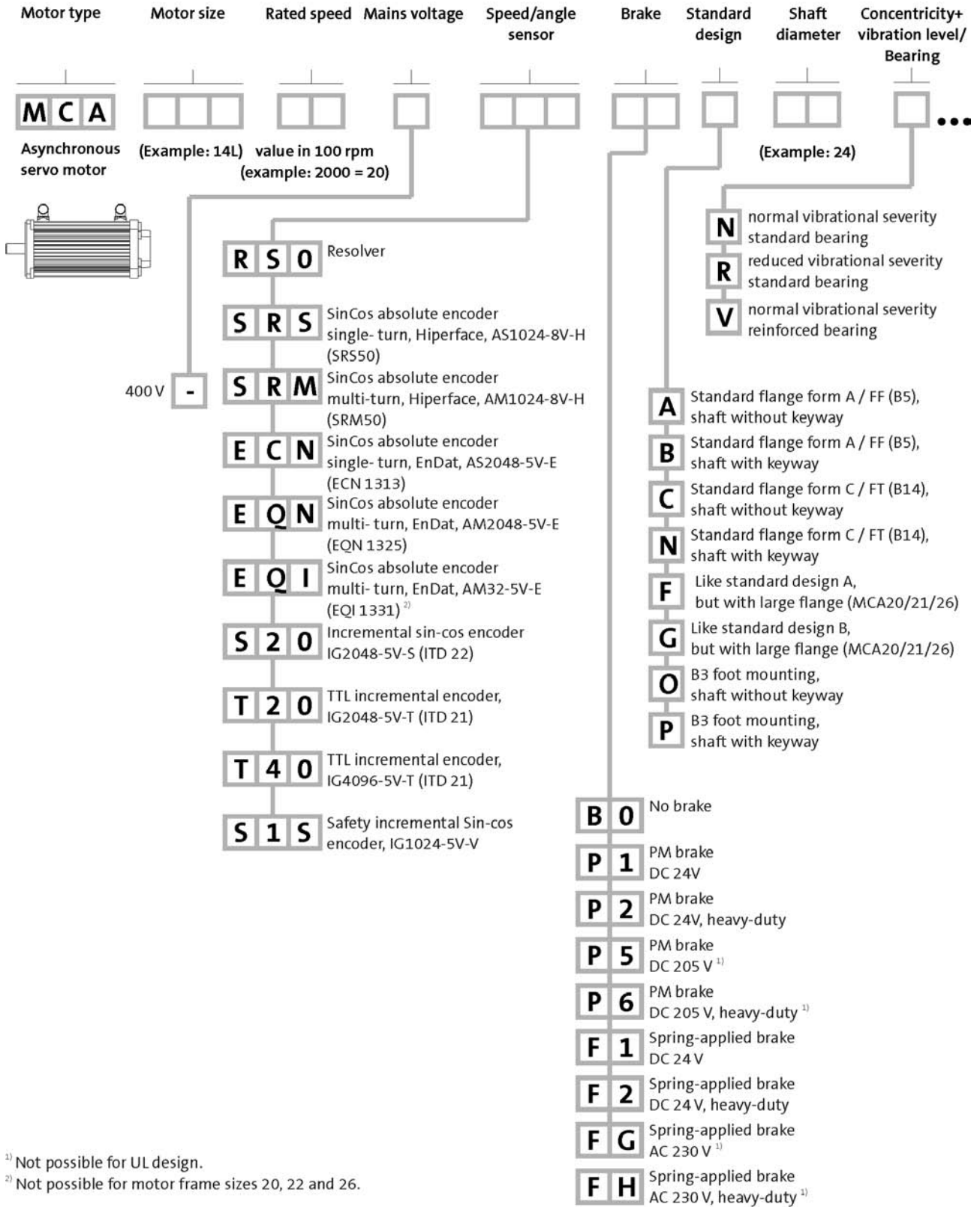
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General information

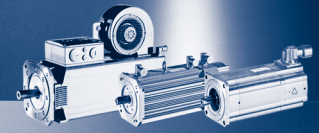
Product key

MCA asynchronous servo motors

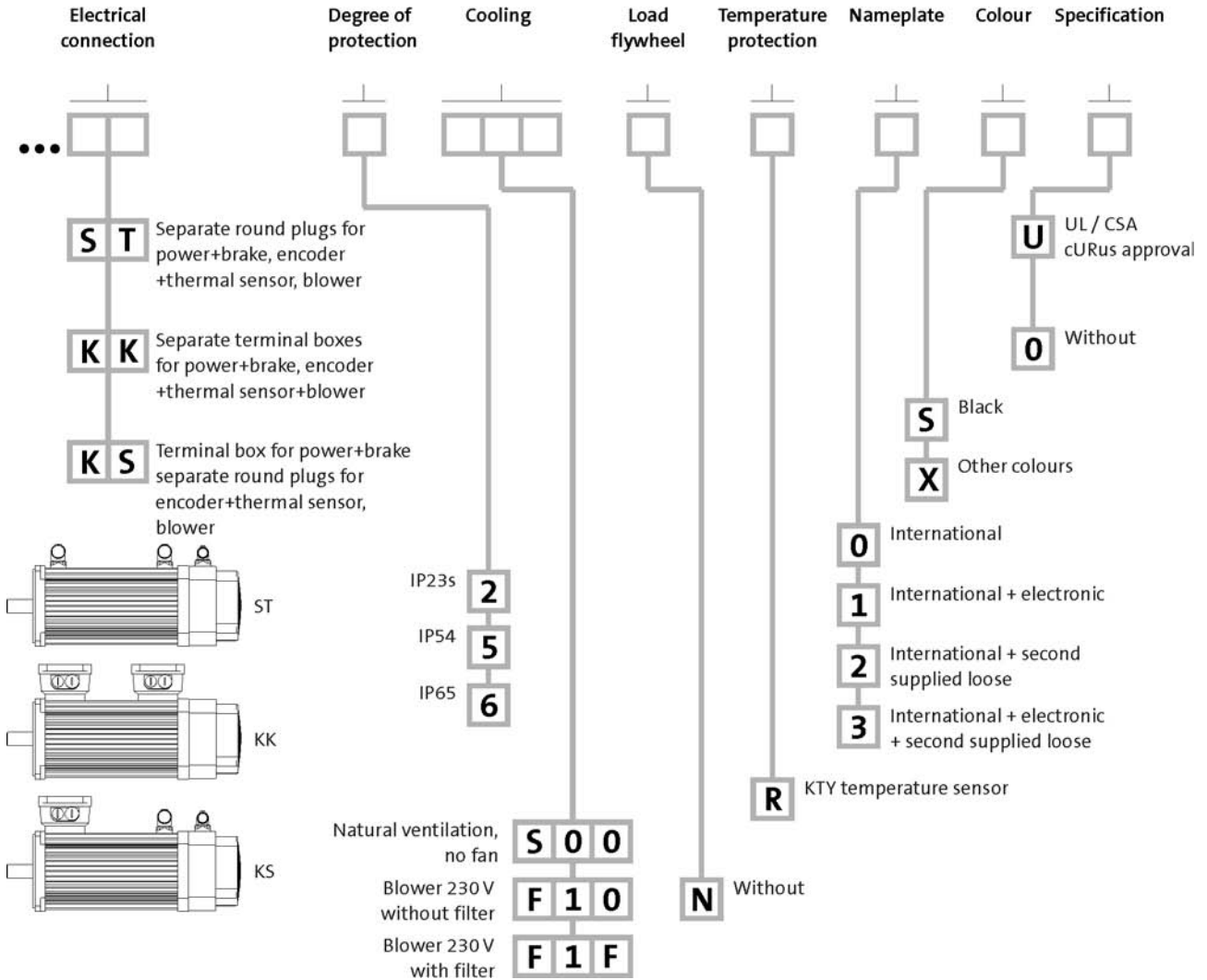


¹⁾ Not possible for UL design.

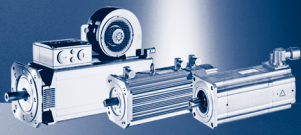
²⁾ Not possible for motor frame sizes 20, 22 and 26.



MCA asynchronous servo motors



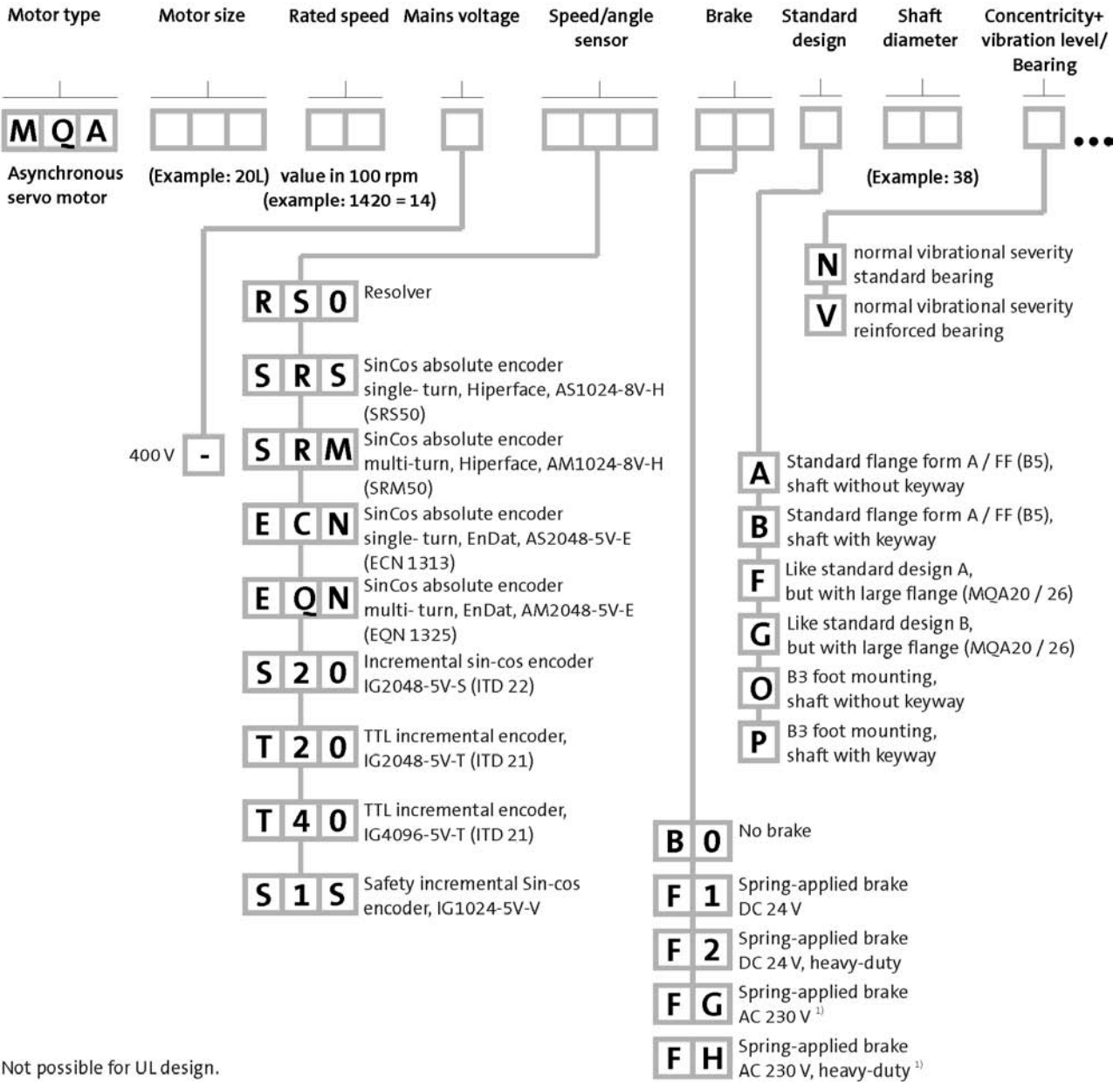
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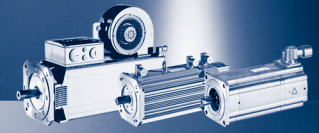
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Product key

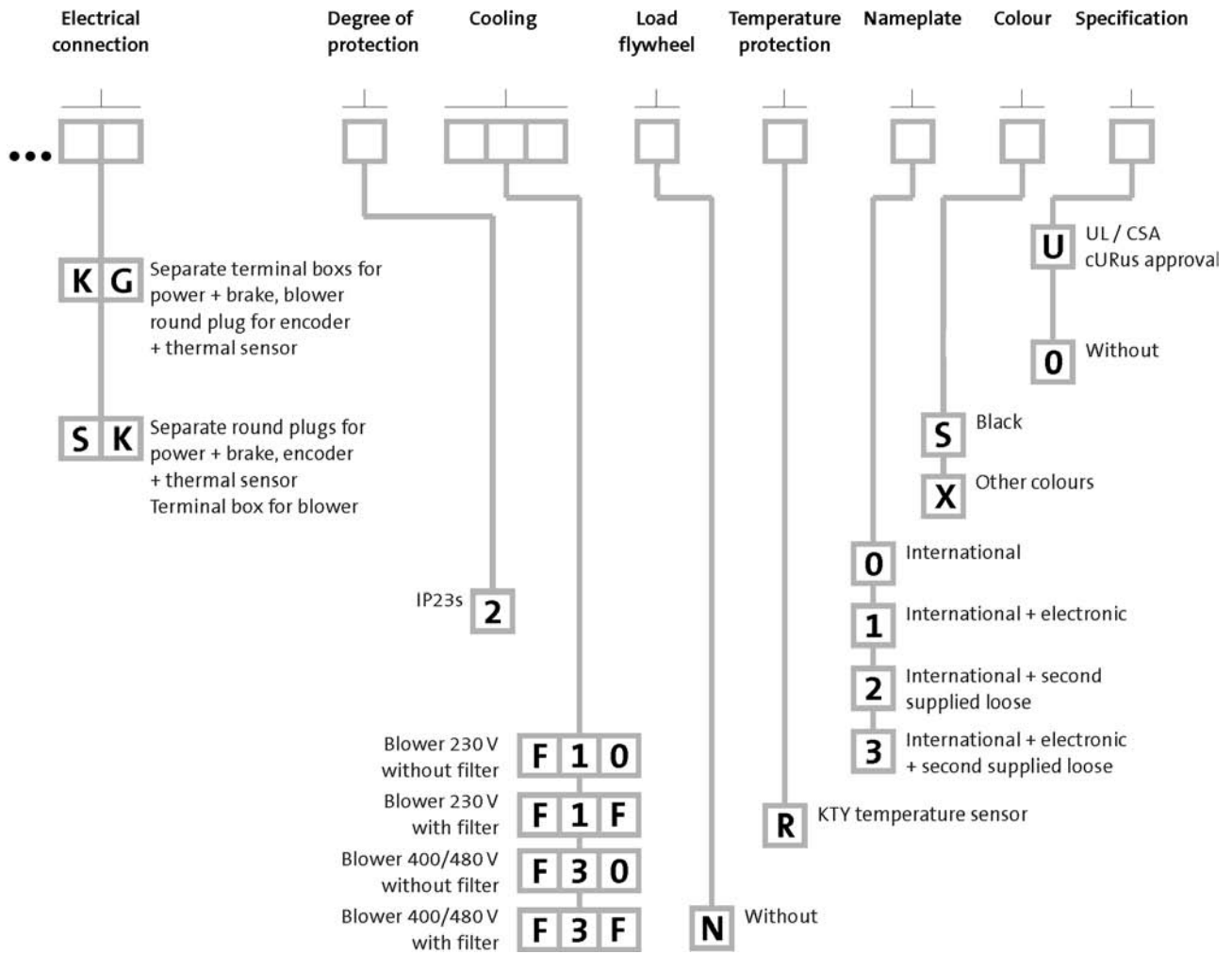
MQA asynchronous servo motors



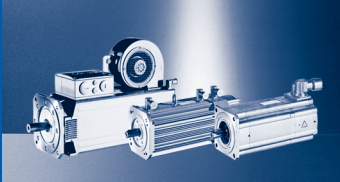
¹⁾ Not possible for UL design.



MQA asynchronous servo motors



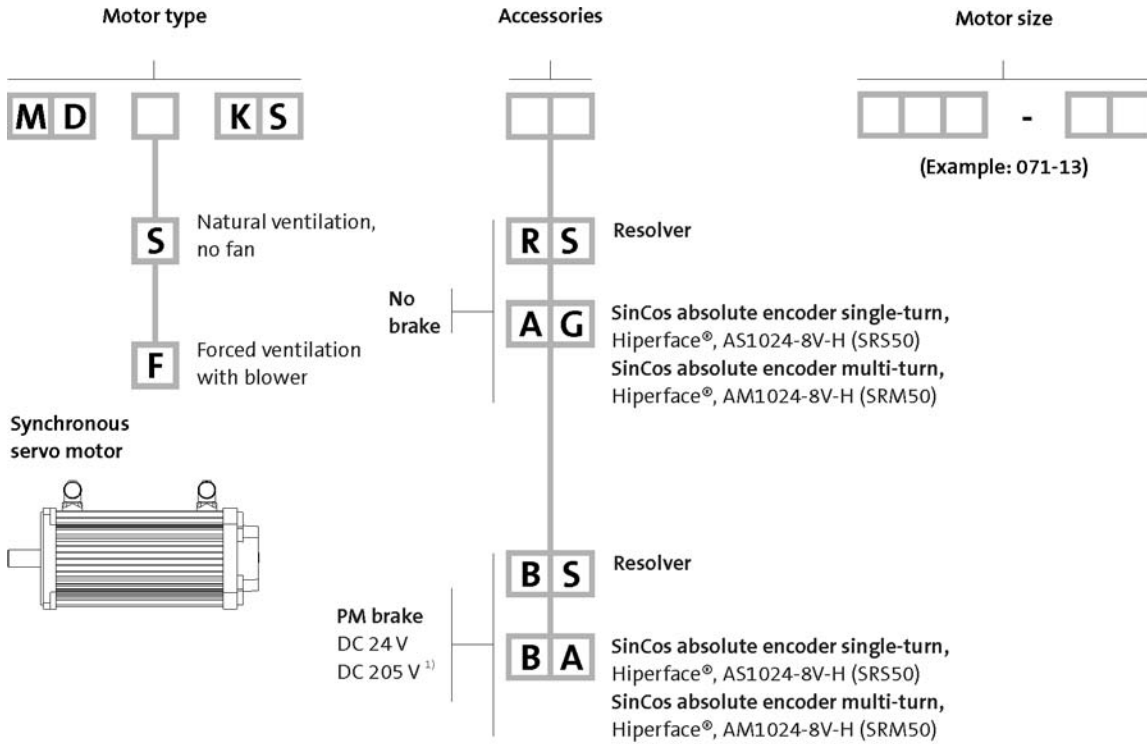
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General information


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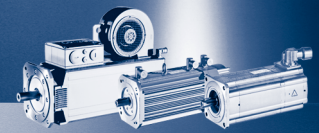
MDKS synchronous servo motors



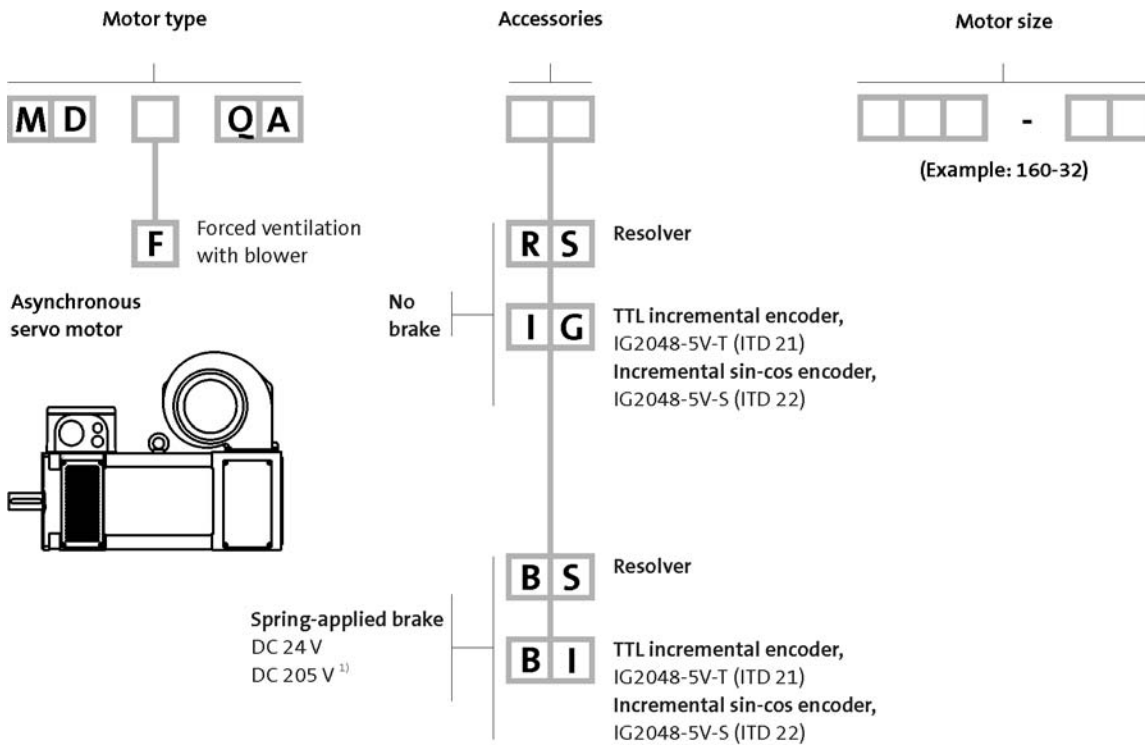
¹⁾ Not possible for UL design.

| Ordering details checklist | |
|-----------------------------|--------------------------------|
| Product key | MDSKS... / MDFKS... |
| Built-on accessories: brake | Without/24 V DC/205 V DC |
| Motor design | B14 / B5 design |
| Shaft design | with/without keyway |
| Enclosure | IP54 / IP65 |
| Motor connection | Plug connector/terminal box... |
| Colour | RAL 9005 (jet black) / RAL... |

→  30 - Servo motor designs



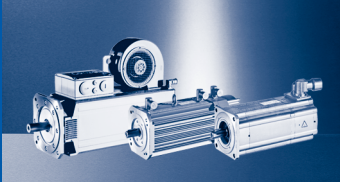
MDFQA asynchronous servo motors



¹⁾ Not possible for UL design.

| Ordering details checklist | |
|------------------------------|-------------------------------|
| Product key | MDFQA... |
| Built-on accessories: brake | Without/24 V DC/205 V DC |
| Built-on accessories: Blower | G2D120 without filters ... |
| Motor design | B35 / B5 design |
| Shaft design | with/without keyway |
| Colour | RAL 9005 (jet black) / RAL... |

→ 33 - Servo motor designs



Servo motors

Today servo drive systems are subjected to the most stringent demands. The differing drive components all have to complement each other perfectly. The Lenze servo motors have an important role to play in this system. Tailored to the various applications, synchronous and asynchronous motors that have been optimised to satisfy the various requirements in terms of dynamic response, accuracy and drive behaviour, are available across a wide torque and power range.

Dynamic

All servo motors are characterised by a low moment of inertia and a high overload capacity. Continuous temperature measurement using an integrated thermal sensor means that a largely temperature-independent optimum control behaviour is achieved. In combination with the servo inverters, high speed accuracy, the best smooth running characteristics and high angular accelerations can be achieved.

Precise

In combination with the specially designed neodymium iron boron (NdFeB) high-energy magnets, the new SEpT design (Single Element Pole Technology) enables a distortion-free, entirely sinusoidal working field to be generated on MCS synchronous servo motors. This ensures both excellent smooth running characteristics (due to the absence of field distortion) and maximum power density (as the working field is generated almost entirely from the induced energy). This optimised field form also eliminates practically all distorting cogging and latching torques.

Long-lived

The high quality level demanded of the components used meets the requirements made on modern drive technology in respect of operational reliability and service life. A reinforced insulation system with thermal reserve (enamel-insulated wire complying with temperature class H, utilisation according to F) ensures a long service life of the winding. In addition, the winding of MCS servo motors is best protected by the full stator encapsulation, even when exposed to severe vibrations, and the heat can be even better dissipated. This increases the load capacity and ensures a long, trouble-free service life. Pre-stressed and generously dimensioned roller bearings with high-temperature resistant grease further guarantee a long bearing service life.

Reliable in operation

The IP54 degree of protection design ensures good protection against dust and water for the motors in the MCS, MD□KS and MCA series. Where enhanced requirements are made on the protection of the drive, the naturally ventilated design MCS, MD□KS and MCA motors can also be supplied to IP65.

CE conformity

Naturally, all servo motors comply with EU directives:

- ▶ CE conformity with the Low Voltage Directive
- ▶ CE conformity with the EMC Directive for a typical drive configuration with inverter

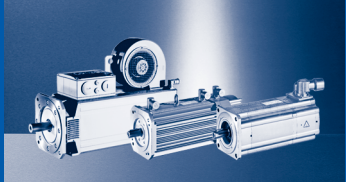
Compliance with electromagnetic compatibility can be guaranteed quite simply by using pre-assembled system cables.

UL certification

All servo motors are prepared for use on the continent of America. MCS, MCA and MQA series servo motors are cURus certified, MDSKS, MDFKS and MDFQA series motors are UR certified. (Exception: version with the 205 V brake.)

No compromises in terms of output speed

The wide ratio range of Lenze gearboxes, combined with the small ratio step of 1.12, allows the required output speed range to be chosen very precisely. The ability to connect the gearboxes directly in the case of the servo motors in the MCS, MD□KS and MCA series produces an extremely compact drive unit with a minimal volume. It goes without saying that all servo motors can also be combined with gearboxes in the conventional manner.



Adaptable

The modular design of the motors and the variants make it easier to make the correct choice for the application case concerned.

The drives are a match for practically any drive task thanks to the variety of output-side designs of the motors and geared motors:

- ▶ Servo motor with round shaft end with or without keyway
- ▶ Geared servo motors with solid shaft, hollow shaft or hollow shaft with shrink disc
- ▶ Geared servo motors with or without flange, foot or centring
- ▶ Different integrated angle sensors allow adaptation to the desired accuracy: resolver as a standard solution with optimised behaviour thanks to internal improvement of the resolver accuracy, sincos absolute value encoder for the greatest accuracy or even incremental encoder for general applications.
- ▶ Matched to the motor type concerned, permanent magnet or spring-applied holding brakes with different torque ranges ensure exact positioning in all application cases, even when the drive is deenergised.

Bold

The high chopper frequencies of the servo inverters (up to 16 kHz) and a cleverly designed magnetic circuit result in extremely low noise levels. Optimised gear teeth geometry in the Lenze gearboxes prevents noise developing, while the internally ribbed cast iron gearbox housing also helps reduce noise levels.

Compact

The high power density of all servo motors permits small, highly dynamic drive units. The use of geared servo motors with direct mounting of the motors leads to particularly compact drives.

Reduced backlash

The use of backlash-free permanent magnet holding brakes allows a position to be held precisely, even if the drive is deenergised.

Backlash-free connecting elements in the Lenze gearboxes and the high quality of the teeth thanks to precision manufacturing result in extremely low output backlash on the servo geared motors in comparison with comparable gearboxes. All servo motors in the MCS and MCA 10...19 / 21 series can be combined with directly mounted GPA series planetary gearboxes to meet the highest requirements on reduced backlash.

Here too, just as with all our motor-gearbox combinations, we consistently use friction-type connections which will also reliably cope with highly dynamic servo applications.

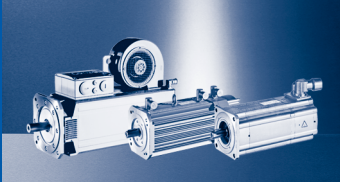
Special types

We can also provide special models tailored to meet the requirements of specific applications.

Easy to install

All Lenze servo motors are guaranteed to be extremely easy to install, with short down times whenever one needs to be replaced. All connections on the MCS, MD□KS and MCA motors are keyed to prevent incorrect connection and can be turned through about 320° to allow them to be fitted and removed easily in all situations.





About this catalogue

This catalogue brings together all the synchronous servo motors in the MCS, MDSKS, MDFKS and the asynchronous servo motors in the MCA, MQA, MDFQA series. The motor-inverter combinations are listed for the default settings for the servo inverters. All further possible assignments can be downloaded from the Internet.

The same product range is also covered in the electronic DSC catalogue. The electronic catalogue is available on DVD and on the Internet at www.lenze.de/dsc.

On the Internet you can also find and download a PDF containing additional information such as torque characteristics for the individual motor inverter combinations. Various operating modes, e.g. different maximum currents at different switching frequencies, are listed.

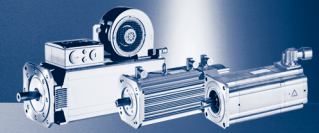
Please observe the Drive Dimensioning chapter.

Here you will find general data, designs and definitions (references to the assignment tables).

To ensure rapid and correct delivery we require:

- ▶ your delivery data such as delivery date and delivery address
- ▶ the complete product key of our products. Please also take note of the ordering details checklist for the MD□KS and MDFQA series of servo motor.

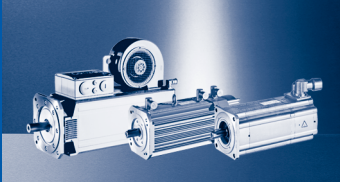
A list of Lenze sales offices can be found at the end of this catalogue.



List of abbreviations

| | | |
|-------------------------------------|----------------------|--------------------------------|
| $\eta_{100\%}$ | [%] | Efficiency |
| $\cos \varphi$ | | Power factor |
| du / dt | [kV / μ s] | Insulation resistance |
| $F_{ax,-}$ | [N] | Min. axial force |
| $F_{ax,+}$ | [N] | Max. axial force |
| $f_{in,max}$ | [Hz] | Max. input frequency |
| f_{max} | [kHz] | Limit frequency |
| f_{max} | [kHz] | Max. switching frequency |
| f_N | [Hz] | Rated frequency |
| F_{rad} | [N] | Max. radial force |
| H_{max} | [m] | Site altitude |
| I_0 | [A] | Standstill current |
| I_{max} | [A] | Max. short-time DC-bus current |
| I_{max} | [A] | Max. current |
| I_{max} | [A] | Max. current consumption |
| I_{max} | [A] | Max. current |
| I_{max} | [A] | Max. DC-bus current |
| I_N | [A] | Rated current |
| J | [kgcm ²] | Moment of inertia |
| J_{MB} | [kgcm ²] | Moment of inertia |
| $KE_{LL 150\text{ }^\circ\text{C}}$ | [V /1000 rp] | Voltage constant |
| $Kt_{0 150\text{ }^\circ\text{C}}$ | [Nm/A] | Torque constant |
| L | [mH] | Mutual inductance |
| $L_{1\sigma}$ | [mH] | Stator leakage inductance |
| $L_{2\sigma}$ | [mH] | Rotor leakage inductance |
| L_N | [mH] | Rated inductance |
| m | [kg] | Mass |
| M_0 | [Nm] | Stall torque |
| $M_{0,max}$ | [Nm] | Max. standstill torque |
| M_{av} | [Nm] | Average dynamic torque |
| M_{max} | [Nm] | Max. torque |
| M_N | [Nm] | rated torque |
| n_k | [r/min] | Speed |
| n_{max} | [r/min] | Max. speed |

| | | |
|------------------------------------|----------------------|--|
| n_N | [r/min] | Rated speed |
| P_N | [kW] | Rated power |
| Q_E | [J] | Maximum switching energy |
| R | [Ω] | Insulation resistance |
| R | [Ω] | Min. insulation resistance |
| R_1 | [Ω] | Stator impedance |
| R_2 | [Ω] | Charging resistor |
| R_2 | [Ω] | Rotor impedance |
| $R_{UV 150\text{ }^\circ\text{C}}$ | [Ω] | Stator impedance |
| $R_{UV 20\text{ }^\circ\text{C}}$ | [Ω] | Stator impedance |
| $S_{h\u00fc}$ | [1/h] | Transition operating frequency |
| T | [$^\circ\text{C}$] | Operating temperature |
| T | [$^\circ\text{C}$] | Rated temperature |
| T | [$^\circ\text{C}$] | Max. ambient temperature of bearing |
| T | [$^\circ\text{C}$] | Max. surface temperature |
| T | [$^\circ\text{C}$] | Max. ambient temperature for transport |
| T | [$^\circ\text{C}$] | Min. ambient storage temperature |
| T | [$^\circ\text{C}$] | Min. ambient temperature for transport |
| T | [$^\circ\text{C}$] | Ambient temperature |
| t_1 | [ms] | Engagement time |
| t_2 | [ms] | Disengagement time |
| $T_{opr,max}$ | [$^\circ\text{C}$] | Max. ambient operating temperature |
| $T_{opr,min}$ | [$^\circ\text{C}$] | Min. ambient operating temperature |
| $U_{in,max}$ | [V] | Max. input voltage |
| $U_{in,min}$ | [V] | Min. input voltage |
| U_{max} | [V] | Max. mains voltage |
| U_{max} | [V] | Min. input voltage |
| U_{min} | [V] | Min. mains voltage |
| $U_{N, AC}$ | [V] | Rated voltage |
| $U_{N, DC}$ | [V] | Rated voltage |
| Z_{ro} | [Ω] | Rotor impedance |
| Z_{rs} | [Ω] | Impedance |
| Z_{so} | [Ω] | Stator impedance |



General information

Product information

| | |
|------|---|
| CE | Communauté Européenne |
| CSA | Canadian Standards Association |
| DIN | Deutsches Institut für Normung e.V. |
| EMC | Electromagnetic compatibility |
| EN | European standard |
| IEC | International Electrotechnical Commission |
| IM | International Mounting Code |
| IP | International Protection Code |
| NEMA | National Electrical Manufacturers Association |
| UL | Underwriters Laboratory Listed Product |
| UR | Underwriters Laboratory Recognized Product |
| VDE | Verband deutscher Elektrotechniker (Association of German Electrical Engineers) |

1



| | | | MCS | | MDSKS | | MDFKS | |
|---|---------------|------------|---|--------|----------------------------|-----|--------|--|
| Cooling type | | | Naturally ventilated | Blower | Naturally ventilated | | Blower | |
| Enclosure EN 60529 | | | IP54 IP65 | IP54 | IP54 IP65 | | IP54 | |
| Temperature class IEC/EN 60034-1; utilisation IEC/EN 60034-1; insulation system (enamel-insulated wire) | | | | | F | | | |
| | | | | | H | | | |
| Approval Class | | | cURus ¹⁾ GOST-R | | GOST-R UR ¹⁾ | | | |
| Max. voltage load IEC/TS 60034-25 | | | Limit curve A of pulse voltage (Fig. 14) | | | | | |
| Smooth running IEC 60072 | | | Normal class | | | | | |
| Axial run-out IEC 60072 | | | Normal class | | | | | |
| Concentricity IEC 60072 | | | Normal class | | | | | |
| Mechanical ambient conditions (vibration) IEC/EN 60721-3-3 | | | 3M6 | | | | | |
| Min. ambient operating temperature Without brake | $T_{opr,min}$ | [°C] | -20 | -15 | -20 | -15 | | |
| With brake | $T_{opr,min}$ | [°C] | | | -10 | | | |
| Max. ambient operating temperature | $T_{opr,max}$ | [°C] | 40 | | | | | |
| Max. surface temperature | T | [°C] | 140 | 110 | 140 | 110 | | |
| Mechanical tolerance Flange centring diameter | | | $b_2 \leq 230 \text{ mm} = j6$ $b_2 > 230 \text{ mm} = h6$ | | | | | |
| Shaft diameter | | | $d \leq 50 \text{ mm} = k6$ $d > 50 \text{ mm} = m6$ | | | | | |
| Site altitude Amsl | H_{max} | [m] | 4000 | | | | | |
| power reduction above 1000 m | | [%/1000 m] | 5.00 | | | | | |

¹⁾ Recognized component File No. E 210321.

General information

Standards and operating conditions

| | | | MCA | MQA | MDFQA |
|---|----------------------|------------|--|-----------------------------|----------------------------|
| Cooling type | | | Naturally ventilated | Blower | |
| Enclosure EN 60529 | | | IP54 IP65 | IP54 IP23s ²⁾ | IP23s |
| Temperature class IEC/EN 60034-1; utilisation IEC/EN 60034-1; insulation system (enamel-insulated wire) | | | F H | | |
| Approval Class | | | cURus ^{4,6)} GOST-R | | GOST-R UR ⁵⁾ |
| Max. voltage load IEC/TS 60034-25 | | | Limit curve A of pulse voltage (Fig. 14) | | |
| Smooth running IEC 60072 | | | Precision class ¹⁾ Normal class | Normal class | |
| Axial run-out IEC 60072 | | | Precision class ¹⁾ Normal class | Normal class | |
| Concentricity IEC 60072 | | | Precision class ¹⁾ Normal class | Normal class | |
| Mechanical ambient conditions (vibration) IEC/EN 60721-3-3 | | | 3M6 | | |
| Min. ambient operating temperature Without brake | T _{opr,min} | [°C] | -20 | -15 | |
| With brake | T _{opr,min} | [°C] | | -10 | |
| Max. ambient operating temperature | T _{opr,max} | [°C] | 40 | | |
| Max. surface temperature | T | [°C] | 140 | 110 | |
| Mechanical tolerance Flange centring diameter | | | b ₂ ≤ 230 mm = j6 b ₂ > 230 mm = h6 | | |
| Shaft diameter | | | d ≤ 50 mm = k6 d > 50 mm = m6 | | |
| Site altitude Amsl | H _{max} | [m] | 4000 | | |
| power reduction above 1000 m | | [%/1000 m] | 5.00 | | |

¹⁾ MCA14, 17, 19 and 21.

²⁾ MCA20, 22 and 26.

³⁾ Not possible on MCA20.

⁴⁾ Recognized component File No. E 210321.

⁵⁾ MDFQA160: on request, Recognized component File No. E 217551.

⁶⁾ MCA20X29, MCA21X35, MQA20L29 with plug connector motor connection UR only



MCS synchronous servo motors

| | MCS06 | MCS09 | MCS12 | MCS14 | MCS19 |
|---|---|--------------------------------|---|----------|----------|
| Type | B5-FF75 | B5-FF100 | B5-FF130 | B5-FF165 | B5-FF215 |
| Shaft end (with and without keyway) | 11 x 23 | 14 x 30 | 19 x 40 | 24 x 50 | 28 x 60 |
| A end shield | Not oil-tight | | | | |
| Brake Permanent magnetic brake | DC 24 V | DC 24 V 24 V DC, reinforced | | | |
| Speed and angle encoder | Resolver SinCos single-turn/multi-turn | | | | |
| Cooling Without blower Axial blower, 1 phase | Naturally ventilated | | 230 V; 50 Hz 115 V; 60 Hz | | |
| Temperature sensor Thermal detector PTC thermistor | KTY 2x PTC additional (3-phase monitoring) | | | | |
| Motor connection: plug connector | Power + brake Encoder + thermal sensor | | Power + brake Encoder + thermal sensor Blower | | |
| Motor connection: terminal box | Power + brake + encoder + thermal sensor | | | | |
| Shaft bearings Bearing type Position of the locating bearing | Deep-groove ball bearing with high-temperature resistant grease, sealing disc or cover plate Non-drive end | | | | |
| Colour | RAL9005M | | | | |

► Terminal boxes not possible if blower is fitted.

MD□KS synchronous servo motors

| | MDSKS□□056 | MDSKS□□071 | MDFKS□□071 |
|--|---|------------|---|
| Type | B14-FT85 B5-FF100 | | B14-FT130 B5-FF130 |
| Shaft end (with and without keyway) | 14 x 30 | | 19 x 40 |
| A end shield | Not oil-tight | | |
| Brake Permanent magnetic brake | DC 24 V AC 230 V ¹⁾ DC 205 V ¹⁾ | | |
| Speed and angle encoder | Resolver SinCos single-turn/multi-turn | | |
| Cooling Without blower Axial blower, 1 phase | Naturally ventilated | | 230 V; 50 Hz |
| Temperature sensor Thermal detector | KTY | | |
| Motor connection: plug connector | Power + brake Encoder + thermal sensor | | Power + brake Encoder + thermal sensor Blower |
| Motor connection: terminal box | Power + brake Encoder + thermal sensor | | Power + brake Encoder + thermal sensor + blower |
| Motor connection: Terminal box + plug connector Terminal box | Power + brake Encoder + thermal sensor | | |
| Plug connector | | | Blower |
| Shaft bearings Bearing type Position of the locating bearing | Deep-groove ball bearing with high-temperature resistant grease, sealing disc or cover plate Drive end | | |
| Colour | RAL9005M | | |

¹⁾ Not possible for UR version.



MCA asynchronou servo motors

| | MCA10 | MCA13 | MCA14 | MCA17 | MCA19 |
|--|---|--|-----------------------|-------|-----------------------|
| Type | B14-FT85 B5-FF100 | B14-FT130 B5-FF130 | B14-FT130 B5-FF165 | | B14-FT130 B5-FF215 |
| Shaft end (with and without keyway) | 14 x 30 | 19 x 40 | 24 x 50 | | 28 x 60 |
| A end shield | Not oil-tight Oil-tight | | | | |
| Brake Spring-applied brake Permanent magnetic brake | DC 24 V AC 230 V ¹⁾ DC 205 V ¹⁾ | | | | |
| Speed and angle encoder | Resolver SinCos single-turn/multi-turn Incremental encoder | | | | |
| Cooling Without blower Axial blower, 1 phase | Naturally ventilated 230 V; 50 Hz | | | | |
| Temperature sensor Thermal detector | KTY | | | | |
| Motor connection: plug connector | Power + brake Encoder + thermal sensor Blower | | | | |
| Motor connection: terminal box | Power + brake Encoder + thermal sensor | Power + brake Encoder + thermal sensor + blower | | | |
| Motor connection: Terminal box + plug connector Terminal box Plug connector | | Power + brake Encoder + thermal sensor | | | Blower |
| Shaft bearings Bearing type Position of the locating bearing Installation of the locating bearing Position of the locating bearing on reinforced design | Deep-groove ball bearing with high-temperature resistant grease, sealing disc or cover plate Drive end | | | | |
| Colour | RAL9005M | | | | |

¹⁾ Not possible for UR version.

MCA asynchronou servo motors

| | MCA20 | MCA21 | MCA22 | MCA26 |
|--|--|---|------------------------------------|-----------------------------------|
| Type | B3 B5-FF215 B5-FF265 | B14-FT130 B5-FF215 B5-FF265 | B3 B5-FF265 | B3 B5-FF265 B5-FF350 |
| Shaft end (with and without keyway) | 38 x 80 | | | 55 x 110 |
| A end shield | Not oil-tight Oil-tight | | | |
| Brake | | | | |
| Spring-applied brake | DC 24 V AC 230 V ¹⁾ | | | DC 24 V AC 230 V ¹⁾ |
| Permanent magnetic brake | | DC 24 V AC 230 V ¹⁾ DC 205 V ¹⁾ | | |
| Speed and angle encoder | Resolver SinCos single-turn/multi-turn Incremental encoder | | | |
| Cooling | | | | |
| Without blower | | Naturally ventilated | | |
| Axial blower, 1 phase | 230 V; 50 Hz 230 V; 60 Hz | 230 V; 50 Hz | | 230 V; 50 Hz 230 V; 60 Hz |
| Temperature sensor | | | | |
| Thermal detector | KTY | | | |
| Motor connection: plug connector | | | | |
| | Power + brake Encoder + thermal sensor Blower | | | |
| Motor connection: terminal box | | | | |
| | | Power + brake Encoder + thermal sensor + blower | | |
| Motor connection: Terminal box + plug connector | | | | |
| Terminal box | Power + brake | Power + brake Encoder + thermal sensor | Power + brake | |
| Plug connector | Encoder + thermal sensor Blower | Blower | Encoder + thermal sensor Blower | |
| Shaft bearings | Deep-groove ball bearing with high-temperature resistant grease, sealing disc or cover plate | | | |
| Bearing type | | | | |
| Position of the locating bearing | Non-drive end | Drive end | Non-drive end | |
| Installation of the locating bearing | insulation | | insulation | |
| Position of the locating bearing on reinforced design | Drive end | | Drive end | |
| Colour | RAL9005M | | | |

¹⁾ Not possible for UR version.



MQA/MDFQA asynchronous servo motors

| | MQA20 | MQA22 | MQA26 | MDFQA□□160 |
|--|--|--------------------------|----------------------------|---|
| Type | B3 B5-FF215 B5-FF265 | B3 B5-FF265 | B3 B5-FF265 B5-FF350 | B35-FF350 |
| Shaft end (with and without keyway) | 38 x 80 | | 55 x 110 | |
| A end shield | Not oil-tight Oil-tight | | | Not oil-tight |
| Brake Spring-applied brake | DC 24 V AC 230 V ^{1, 2)} | | | DC 24 V AC 230 V ¹⁾ DC 205 V ¹⁾ |
| Speed and angle encoder | Resolver SinCos single-turn/multi-turn Incremental encoder | | | Without Resolver SinCos single- turn/multi-turn Incremental encoder |
| Cooling Radial blower, 1 phase | 230 V; 50 Hz 230 V; 60 Hz | | | |
| Radial blower, 3 phase | 400 V; 50 Hz 400 V; 60 Hz 460 V; 50 Hz 460 V; 60 Hz 480 V; 60 Hz | | | |
| Temperature sensor Thermal detector | KTY | | | |
| Thermal contact | TKO ²⁾ | | | |
| Motor connection: Terminal box + plug connector Terminal box | | Power + brake Blower | | Power + thermal sensor Blower |
| Plug connector | Power + brake Encoder + thermal sensor | Encoder + thermal sensor | | Brake + encoder |
| Shaft bearings Bearing type | Deep-groove ball bearing with high-temperature resistant grease, sealing disc or cover plate | | | |
| Position of the locating bearing | Non-drive end | | | |
| Installation of the locating bearing | insulation | | | |
| Position of the locating bearing on reinforced design | Drive end | | | |
| Colour | Primed (grey) RAL9005M | | | |

¹⁾ Not possible for UR version.

²⁾ Not possible for MQA motor type with plug connector motor connection.

Cooling effect of mounting flange

Installation on a thermally conducting/insulating plate or chassis has an influence on how the motors heat up, in particular in the naturally ventilated motors. The influence is slight or negligible in the case of the MQA and MDFQA series servo motors.

The motor rating data stated in the catalogue is valid for installation on a steel plate set up in free convection with the dimensions listed below:

- ▶ MCS06: 270 x 270 mm
- ▶ MCS09: 330 x 330 mm
- ▶ MCS12 / 14 / 19: 450 x 450 mm
- ▶ MDSKS□□036 / 056 / 071: 270 x 270 mm
- ▶ MCA10 / 13: 270 x 270 mm
- ▶ MCA14 / 17: 330 x 330 mm
- ▶ MCA19 ... 26: 450 x 450 mm

Vibration severities

| | | MCS06 | MCS09 | MCS12 | MCS14 | MCS19 |
|--|--------|-------|-------|-------|-------|-------|
| Vibrational severity IEC/EN 60034-14 | | | | A | | |
| Maximum r.m.s. value of the vibration velocity ¹⁾ | [mm/s] | | | 1.60 | | |

| | | MDSKS□□036 | MDSKS□□056 | MDSKS□□071 | MDFKS□□071 |
|--|--------|------------|------------|------------|------------|
| Vibrational severity IEC/EN 60034-14 | | | | A | |
| Maximum r.m.s. value of the vibration velocity ¹⁾ | [mm/s] | | | 1.60 | |

| | | MCA10 | MCA13 | MCA14 | MCA17 | MCA19 | MCA20 | MCA21 | MCA22 | MCA26 |
|--|--------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| Vibrational severity IEC/EN 60034-14 | | A | | | B | | A | B | | A |
| Maximum r.m.s. value of the vibration velocity ¹⁾ | [mm/s] | 1.60 | | | 0.70 | | 1.60 | 0.70 | | 1.60 |

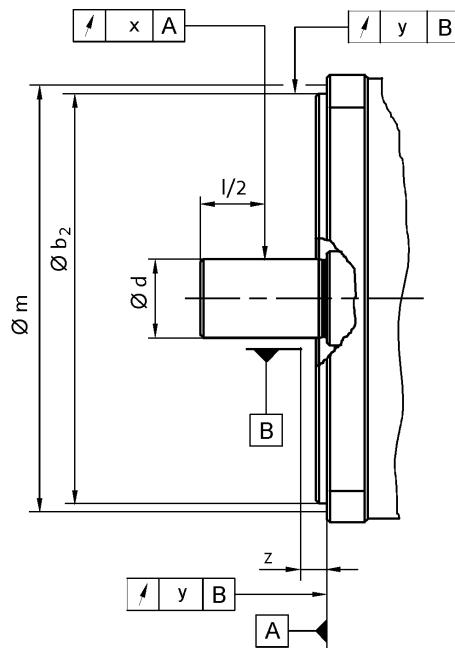
| | | MQA20 | MQA22 | MQA26 | MDFQA□□160 |
|--|--------|-------|-------|-------|------------|
| Vibrational severity IEC/EN 60034-14 | | | | A | |
| Maximum r.m.s. value of the vibration velocity ¹⁾ | [mm/s] | | | 1.60 | |

- ▶ at n = 600...3600 r/min

¹⁾ Free suspension



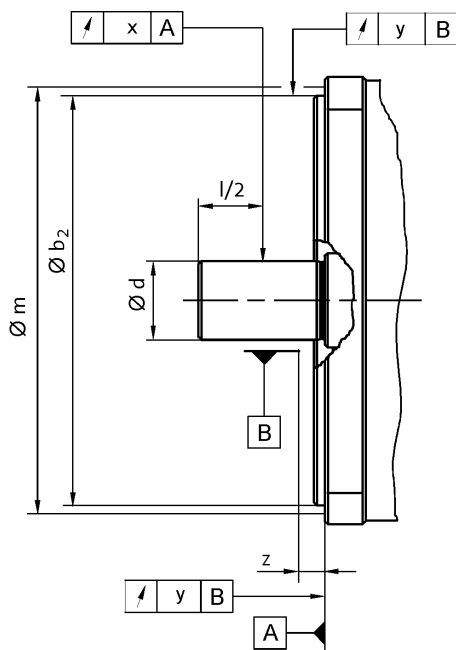
Concentricity and axial run-out of the mounting flanges and smooth running of the shaft ends



| | | | | MCS06 | MCS09 | MCS12 | MCS14 | MCS19 |
|-----------------------|-------|-------|------|-------|-------|--------------|-------|-------|
| Flange size | | | | FF75 | FF100 | FF130 | FF165 | FF215 |
| Dimensions | b_2 | j6 | [mm] | 60 | 80 | 110 | 130 | 180 |
| | d | k6 | [mm] | 11 | 14 | 19 | 24 | 28 |
| Distance | m | | [mm] | 65.0 | 85.0 | 115 | 135 | 185 |
| | z | +/- 1 | [mm] | | | 10.0 | | |
| Concentricity | | | | | | Normal class | | |
| IEC 60072 | | | | | | | | |
| Value | y | | [mm] | 0.080 | | | 0.10 | |
| Axial run-out | | | | | | Normal class | | |
| IEC 60072 | | | | | | | | |
| Value | y | | [mm] | 0.080 | | | 0.10 | |
| Smooth running | | | | | | Normal class | | |
| IEC 60072 | | | | | | | | |
| Value | x | | [mm] | 0.035 | | | 0.040 | |

- Limit values for checking the smooth running of the shaft ends as well as the concentricity and axial run-out of the mounting flange to IEC 60072

Concentricity and axial run-out of the mounting flanges and smooth running of the shaft ends

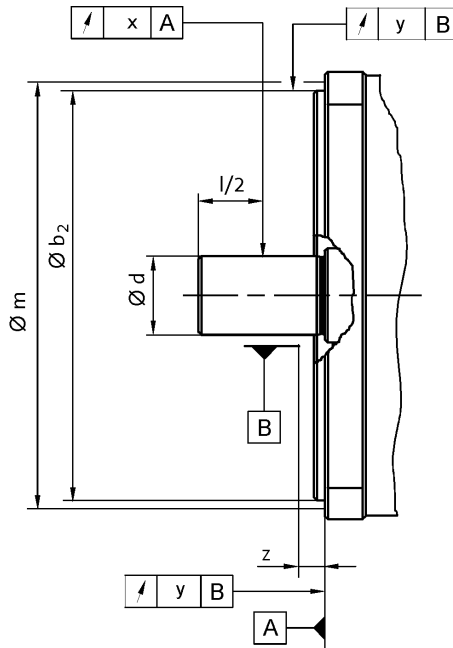


| | | | | MDSKS□□036 | | MDSKS□□056 | | MDSKS□□071 | | MDFKS□□071 | |
|-----------------------|------------------------------------|-----|------------|------------|-------|------------|-------|--------------|-------|------------|--|
| Flange size | | | | FF75 | FF100 | FT85 | FF130 | FT130 | FF130 | FT130 | |
| Dimensions | b_2 | j6 | [mm] | 60 | 80 | 70 | | | 110 | | |
| | d | k6 | [mm] | 11 | 14 | | | | 19 | | |
| Distance | Measuring diameter | m | [mm] | 86.0 | 113 | 98.0 | | | 149 | | |
| | Dial gauge holder for flange check | z | +/- 1 [mm] | | | | | 10.0 | | | |
| Concentricity | | | | | | | | Normal class | | | |
| IEC 60072 | | | | | | | | | | | |
| Value | y | | [mm] | 0.080 | | | | | | 0.10 | |
| Axial run-out | | | | | | | | Normal class | | | |
| IEC 60072 | | | | | | | | | | | |
| Value | y | | [mm] | 0.080 | | | | | | 0.10 | |
| Smooth running | | | | | | | | Normal class | | | |
| IEC 60072 | | | | | | | | | | | |
| Value | x | | [mm] | 0.035 | | | | | | 0.040 | |

- Limit values for checking the smooth running of the shaft ends as well as the concentricity and axial run-out of the mounting flange to IEC 60072



Concentricity and axial run-out of the mounting flanges and smooth running of the shaft ends



| | | | | MCA10 | | MCA13 | | MCA14 | | MCA17 | | MCA19 | |
|------------------------------------|----------------|-------|------|--------------|------|-------|-------|-----------------|-------|-------|-------|-------|-------|
| Flange size | | | | FF100 | FT85 | FF130 | FT130 | FF165 | FT130 | FF165 | FT130 | FF215 | FT130 |
| Dimensions | b ₂ | j6 | [mm] | 80 | 70 | 110 | | 130 | 110 | 130 | 110 | 180 | 110 |
| | b ₂ | h6 | [mm] | | | | | | | | | | |
| | d | k6 | [mm] | 14 | | 19 | | | | 24 | | | 28 |
| | d | m6 | [mm] | | | | | | | | | | |
| Distance | | | | | | | | | | | | | |
| Measuring diameter | m | | [mm] | 113 | 98.0 | 149 | | 188 | 149 | 188 | 149 | 239 | 149 |
| Dial gauge holder for flange check | z | +/- 1 | [mm] | | | | | 10.0 | | | | | |
| Concentricity IEC 60072 | | | | Normal class | | | | Precision class | | | | | |
| Value | y | | [mm] | 0.080 | | 0.10 | | 0.050 | | | | | |
| Axial run-out IEC 60072 | | | | Normal class | | | | Precision class | | | | | |
| Value | y | | [mm] | 0.080 | | 0.10 | | 0.050 | | | | | |
| Smooth running IEC 60072 | | | | Normal class | | | | Precision class | | | | | |
| Value | x | | [mm] | 0.035 | | 0.040 | | 0.021 | | | | | |

- Limit values for checking the smooth running of the shaft ends as well as the concentricity and axial run-out of the mounting flange to IEC 60072

Drive dimensioning

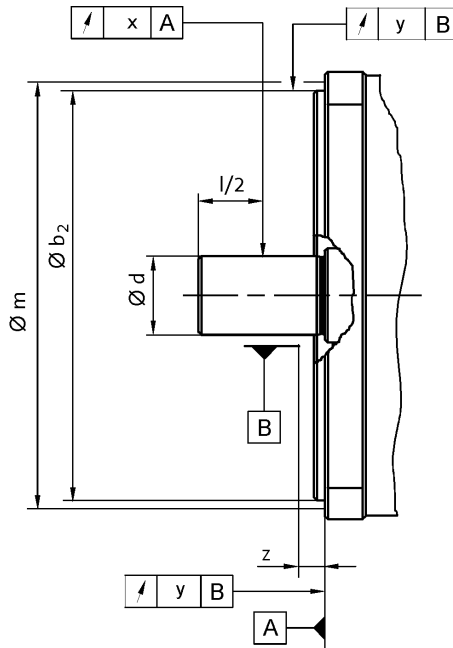
Servo motor designs

| | | | | MCA20 | | MCA21 | | | MCA22 | MCA26 | |
|--|-------|-------|------|-----------------------|-------|--------------------------|-------|-------|----------------------|-----------------------|-------|
| Flange size | | | | FF215 | FF265 | FF215 | FF265 | FT130 | | FF265 | FF350 |
| Dimensions | b_2 | j6 | [mm] | 180 | 230 | 180 | 230 | 110 | | 230 | |
| | b_2 | h6 | [mm] | | | | | | | | 300 |
| | d | k6 | [mm] | | | 38 | | | | | |
| | d | m6 | [mm] | | | | | | | | 55 |
| Distance Measuring diameter Dial gauge holder for flange check | m | | [mm] | 239 | 289 | 239 | 289 | 149 | | 289 | 384 |
| | z | +/- 1 | [mm] | | | | 10.0 | | | | |
| Concentricity IEC 60072 Value | y | | [mm] | Normal class 0.10 | | Precision class 0.050 | | | Normal class 0.10 | | |
| | y | | [mm] | Normal class 0.10 | | Precision class 0.050 | | | Normal class 0.10 | | |
| Smooth running IEC 60072 Value | x | | [mm] | Normal class 0.050 | | Precision class 0.060 | | | 0.050 | Normal class 0.060 | |

- ▶ Limit values for checking the smooth running of the shaft ends as well as the concentricity and axial run-out of the mounting flange to IEC 60072



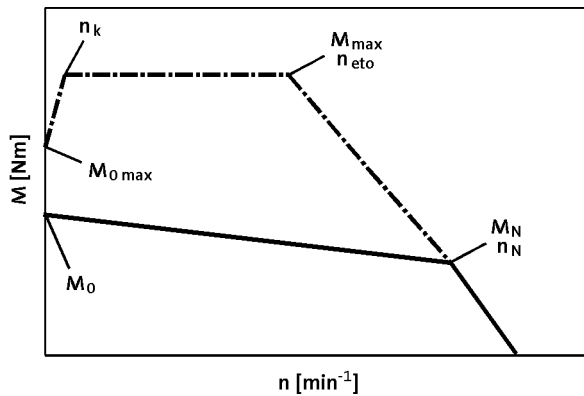
Concentricity and axial run-out of the mounting flanges and smooth running of the shaft ends



| | | | | MQA20 | MQA22 | MQA26 | MD-FQA□□160 |
|------------------------------------|-------|-------|------|-------|--------------|-------|-------------|
| Flange size | | | | FF215 | FF265 | | FF350 |
| Dimensions | b_2 | j6 | [mm] | 180 | 230 | | |
| | b_2 | h6 | [mm] | | | | 300 |
| | d | k6 | [mm] | | 38 | | |
| | d | m6 | [mm] | | | 55 | |
| Distance | | | | | | | |
| Measuring diameter | m | | [mm] | 239 | 289 | | 384 |
| Dial gauge holder for flange check | z | +/- 1 | [mm] | | 10.0 | | |
| Concentricity | | | | | Normal class | | |
| IEC 60072 | | | | | | | |
| Value | y | | [mm] | | 0.10 | | 0.13 |
| Axial run-out | | | | | Normal class | | |
| IEC 60072 | | | | | | | |
| Value | y | | [mm] | | 0.10 | | 0.13 |
| Smooth running | | | | | Normal class | | |
| IEC 60072 | | | | | | | |
| Value | x | | [mm] | 0.050 | | 0.060 | |

- Limit values for checking the smooth running of the shaft ends as well as the concentricity and axial run-out of the mounting flange to IEC 60072

Notes on the selection tables



Graphical display of the operating points

Please note:

- ▶ Under live load (e.g. vertical drive axes, hoists, test benches, unwinders) $M_{0\max}$ must be taken into consideration
- ▶ Under passive load (e.g. horizontal drive axes) M_{\max} can, as a rule, be used
- ▶ With speeds $< n_k$ the torque $M_{0\max}$ achievable is less than M_{\max} depending on the inverter
- ▶ In the case of servo inverters, the switching frequency-dependent overload capacity is taken into consideration at the default setting. For further information, see the Servo inverter catalogue.

| | n_k |
|-------|---------|
| | [r/min] |
| MCS | 75.0 |
| MDSKS | 100 |
| MDFKS | 100 |
| MCA | 150 |
| MQA | 150 |
| MDFQA | 150 |

Further selection tables with different switching frequencies are available with the following codes:

- ▶ DS_ZT_MCS_0001
- ▶ DS_ZT_MCA_0001
- ▶ DS_ZT_MDSKS_0001
- ▶ DS_ZT_MDFKS_0001

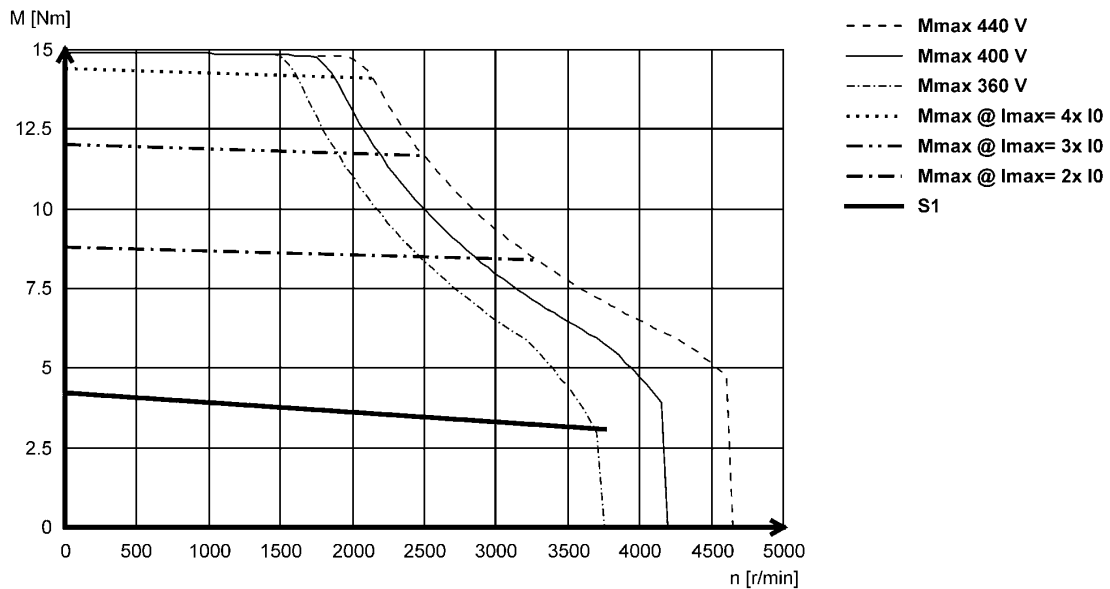
Simply enter this code (e.g. DS_ZT_MCS_0001) as a search string at www.lenze.de/dsc and you will be given the information immediately in the form of a PDF format.



Notes on the torque characteristics

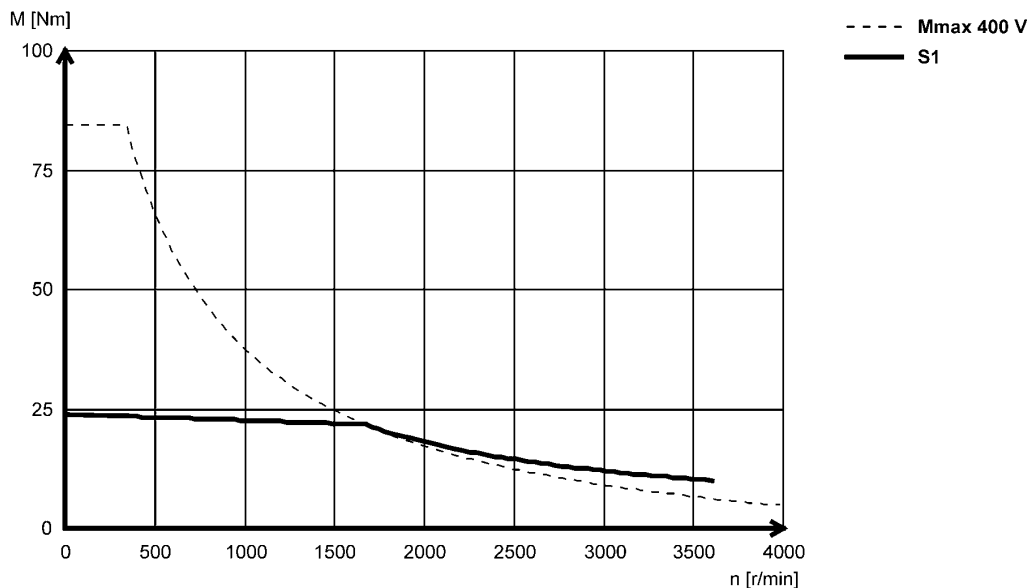
This catalogue contains continuous and limit torque characteristics for synchronous and asynchronous servo motors. You will find characteristics for intermittent operation online at www.lenze.de/dsc.

Characteristics for synchronous motors



For the synchronous servo motors, both the continuous operation characteristic (S1) and the limit torque characteristic are shown; these result from the selection of servo inverters with maximum currents that correspond to a multiple of the motor standstill current (2x I₀ ... 4x I₀).

Characteristics for asynchronous motors



With asynchronous servo motors, two characteristics are shown in each case. The continuous operation characteristic (S1) shows the speed-dependent continuous torque of the motor during operation on a servo inverter running with a constant switching frequency. The limit torque characteristic corresponds to the one produced when operating the motor on the largest possible Servo Drive 9400 in each case (see the selection tables), with the servo inverter set to a variable switching frequency.

Characteristics in the Internet

The torque characteristics for inverter motor combinations can be found online at www.lenze.de/dsc. This page shows all sensible combinations featuring the servo inverter series 9400, 9300, ECS and Inverter Drives 8400 TopLine. The limiting characteristics are each determined with the inverters' default settings:

- ▶ 9400 with a variable switching frequency.
In a limit case, this means that up to 6 times the overcurrent can be used.
- ▶ 9300 and ECS with fixed switching frequency.
- ▶ 8400 TopLine and HighLine with variable switching frequency.

The continuous operation characteristics (S1) show the motor rated values regardless of inverter used.

For more information on the terms switching frequency and default setting, please consult the relevant servo inverter operating instructions.

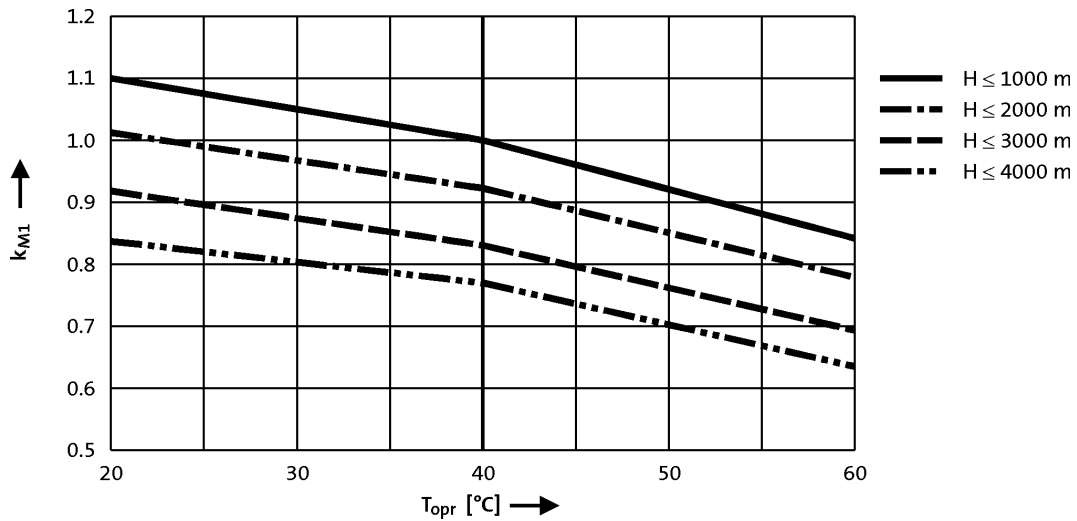


Influence of ambient temperature and site altitude

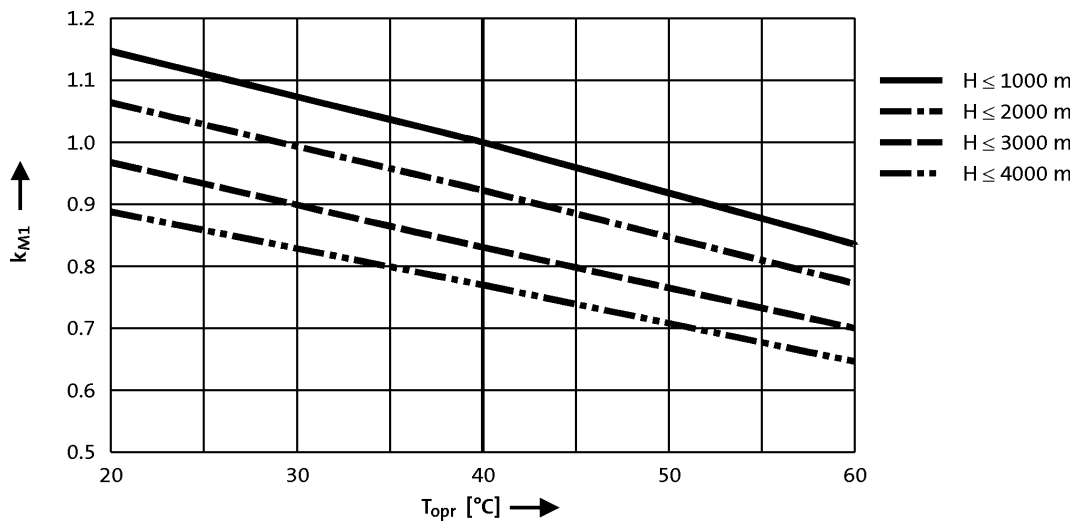
The information relating to the servo motors in the tables and graphs is valid for a maximum ambient temperature (T_{opr}) of 40 °C and a site altitude (H) up to 1000 m above sea level. The torque correction factor (k_{M1}) shall be applied to the S1 torque characteristic ($M_0...M_N$) in the event of differing installation conditions.

- ▶ The maximum permissible ambient temperature (T_{opr}) for servo motors with blowers is 40 °C

MCS, MD□KS synchronous servo motors



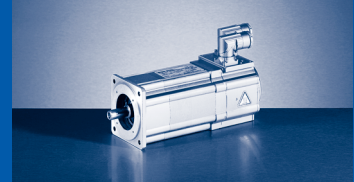
MCA, MQA, MDFQA asynchronous servo motors





Drive dimensioning

2



Mains connection 3x 400 V

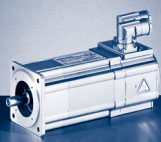
Motors without blower

| | n_N | M_0 | M_{max} | M_N | P_N | I_0 | I_N | I_{max} | $U_{N,AC}$ | f_N |
|-----------|---------|-------|-----------|-------|-------|-------|-------|-----------|------------|-------|
| | [r/min] | [Nm] | [Nm] | [Nm] | [kW] | [A] | [A] | [A] | [V] | [Hz] |
| MCS06C41- | 4050 | 0.80 | 2.40 | 0.60 | 0.25 | 1.30 | 1.30 | 5.40 | 225 | 270 |
| MCS06C60- | 6000 | 0.80 | 2.40 | 0.50 | 0.31 | 2.50 | 2.40 | 10.8 | 135 | 400 |
| MCS06F41- | 4050 | 1.50 | 4.40 | 1.20 | 0.51 | 1.50 | 1.50 | 5.30 | 320 | 270 |
| MCS06F60- | 6000 | 1.50 | 4.40 | 0.90 | 0.57 | 2.90 | 2.50 | 10.5 | 180 | 400 |
| MCS06I41- | 4050 | 2.00 | 6.20 | 1.50 | 0.64 | 1.70 | 1.60 | 5.90 | 325 | 270 |
| MCS06I60- | 6000 | 2.00 | 6.20 | 1.20 | 0.75 | 3.40 | 2.90 | 11.8 | 190 | 400 |
| MCS09D41- | 4050 | 3.30 | 9.50 | 2.30 | 1.00 | 2.60 | 2.30 | 10.0 | 320 | 270 |
| MCS09D60- | 6000 | 3.30 | 9.50 | 1.80 | 1.10 | 5.30 | 3.80 | 20.0 | 210 | 400 |
| MCS09F38- | 3750 | 4.20 | 15.0 | 3.10 | 1.20 | 3.00 | 2.50 | 15.0 | 330 | 250 |
| MCS09F60- | 6000 | 4.20 | 15.0 | 2.40 | 1.50 | 6.00 | 4.50 | 30.0 | 230 | 400 |
| MCS09H41- | 4050 | 5.50 | 20.0 | 3.80 | 1.60 | 4.30 | 3.40 | 20.0 | 300 | 270 |
| MCS09H60- | 6000 | 5.50 | 20.0 | 3.00 | 1.90 | 8.50 | 6.00 | 40.0 | 190 | 400 |
| MCS09L41- | 4050 | 7.50 | 32.0 | 4.50 | 1.90 | 6.20 | 4.20 | 32.0 | 295 | 270 |
| MCS09L51- | 5100 | 7.50 | 32.0 | 3.60 | 1.90 | 12.4 | 6.90 | 64.0 | 180 | 340 |

| | $\eta_{100\%}$ | $J^1)$ | $KE_{LL 150\text{ }^\circ\text{C}}$ | $R_{UV 20\text{ }^\circ\text{C}}$ | $R_{UV 150\text{ }^\circ\text{C}}$ | L_N | $Kt_{0 150\text{ }^\circ\text{C}}$ | $n_{max}^2)$ | $m^1)$ |
|-----------|----------------|----------------------|-------------------------------------|-----------------------------------|------------------------------------|-------|------------------------------------|--------------|--------|
| | [%] | [kgcm ²] | [V /1000 rp] | [Ω] | [Ω] | [mH] | [Nm/A] | [r/min] | [kg] |
| MCS06C41- | 65 | 0.14 | 36.6 | 27.1 | 36.5 | 51.0 | 0.66 | 8000 | 1.80 |
| MCS06C60- | 70 | 0.14 | 18.3 | 6.80 | 9.10 | 12.8 | 0.33 | 8000 | 1.80 |
| MCS06F41- | 77 | 0.22 | 60.1 | 21.9 | 29.5 | 63.5 | 1.05 | 8000 | 2.20 |
| MCS06F60- | 81 | 0.22 | 30.0 | 5.50 | 7.40 | 15.9 | 0.53 | 8000 | 2.20 |
| MCS06I41- | 81 | 0.30 | 73.4 | 18.8 | 25.4 | 60.2 | 1.21 | 8000 | 2.90 |
| MCS06I60- | 84 | 0.30 | 36.7 | 4.70 | 6.30 | 15.1 | 0.60 | 8000 | 2.90 |
| MCS09D41- | 87 | 1.10 | 71.2 | 7.00 | 9.40 | 25.1 | 1.25 | 7000 | 4.30 |
| MCS09D60- | 87 | 1.10 | 35.6 | 1.80 | 2.40 | 6.30 | 0.62 | 7000 | 4.30 |
| MCS09F38- | 91 | 1.50 | 79.8 | 5.20 | 7.00 | 24.6 | 1.40 | 7000 | 5.20 |
| MCS09F60- | 91 | 1.50 | 39.9 | 1.30 | 1.80 | 6.20 | 0.70 | 7000 | 5.20 |
| MCS09H41- | 91 | 1.90 | 75.7 | 3.20 | 4.30 | 16.1 | 1.29 | 7000 | 6.10 |
| MCS09H60- | 91 | 1.90 | 37.8 | 0.80 | 1.10 | 4.00 | 0.65 | 7000 | 6.10 |
| MCS09L41- | 91 | 2.80 | 71.7 | 1.80 | 2.40 | 9.90 | 1.21 | 7000 | 7.90 |
| MCS09L51- | 91 | 2.80 | 35.9 | 0.44 | 0.59 | 2.50 | 0.60 | 7000 | 7.90 |

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.



MCS synchronous servo motors

Rated data

Mains connection 3x 400 V

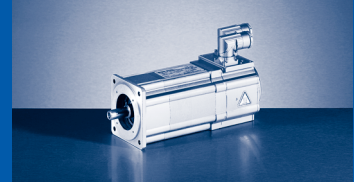
Motors without blower

| | n_N | M_0 | M_{max} | M_N | P_N | I_0 | I_N | I_{max} | $U_{N,AC}$ | f_N |
|-----------|---------|-------|-----------|-------|-------|-------|-------|-----------|------------|-------|
| | [r/min] | [Nm] | [Nm] | [Nm] | [kW] | [A] | [A] | [A] | [V] | [Hz] |
| MCS12D20- | 1950 | 6.40 | 18.0 | 5.50 | 1.10 | 2.70 | 2.60 | 10.0 | 345 | 130 |
| MCS12D41- | 4050 | 6.40 | 18.0 | 4.30 | 1.80 | 5.50 | 4.50 | 20.0 | 310 | 270 |
| MCS12H15- | 1500 | 11.4 | 29.0 | 10.0 | 1.60 | 4.10 | 3.80 | 12.0 | 300 | 100 |
| MCS12H35- | 3525 | 11.4 | 29.0 | 7.50 | 2.80 | 8.20 | 5.70 | 24.0 | 325 | 235 |
| MCS12L20- | 1950 | 15.0 | 56.0 | 13.5 | 2.80 | 6.20 | 5.90 | 28.0 | 330 | 130 |
| MCS12L41- | 4050 | 15.0 | 56.0 | 11.0 | 4.70 | 12.4 | 10.2 | 57.0 | 300 | 270 |
| MCS14D15- | 1500 | 11.0 | 29.0 | 9.20 | 1.45 | 5.00 | 4.50 | 17.0 | 305 | 100 |
| MCS14D36- | 3600 | 11.0 | 29.0 | 7.50 | 2.80 | 10.0 | 7.50 | 33.0 | 295 | 240 |
| MCS14H15- | 1500 | 21.0 | 55.0 | 16.0 | 2.50 | 8.50 | 6.60 | 26.0 | 325 | 100 |
| MCS14H32- | 3225 | 21.0 | 55.0 | 14.0 | 4.70 | 16.9 | 11.9 | 52.0 | 295 | 215 |
| MCS14L15- | 1500 | 28.0 | 77.0 | 23.0 | 3.60 | 12.0 | 9.70 | 37.0 | 315 | 100 |
| MCS14L32- | 3225 | 28.0 | 77.0 | 17.2 | 5.80 | 24.0 | 15.0 | 75.0 | 275 | 215 |
| MCS14P14- | 1350 | 37.0 | 105 | 30.0 | 4.20 | 12.2 | 10.8 | 46.0 | 340 | 90 |
| MCS14P32- | 3225 | 37.0 | 105 | 21.0 | 7.10 | 24.3 | 15.6 | 92.0 | 315 | 215 |

| | $\eta_{100\%}$ | $J^1)$ | $KE_{LL 150^\circ C}$ | $R_{UV 20^\circ C}$ | $R_{UV 150^\circ C}$ | L_N | $Kt_{0 150^\circ C}$ | $n_{max}^2)$ | $m^1)$ |
|-----------|----------------|----------------------|-----------------------|---------------------|----------------------|-------|----------------------|--------------|--------|
| | [%] | [kgcm ²] | [V / 1000 rp] | [Ω] | [Ω] | [mH] | [Nm/A] | [r/min] | [kg] |
| MCS12D20- | 79 | 4.00 | 137 | 8.70 | 11.8 | 52.2 | 2.34 | 6000 | 6.40 |
| MCS12D41- | 84 | 4.00 | 68.6 | 2.20 | 2.90 | 13.0 | 1.17 | 6000 | 6.40 |
| MCS12H15- | 88 | 7.30 | 173 | 5.70 | 7.70 | 42.1 | 2.79 | 6000 | 9.50 |
| MCS12H35- | 91 | 7.30 | 86.5 | 1.40 | 1.90 | 10.5 | 1.40 | 6000 | 9.50 |
| MCS12L20- | 90 | 10.6 | 149 | 2.20 | 3.00 | 21.8 | 2.42 | 6000 | 12.6 |
| MCS12L41- | 91 | 10.6 | 74.6 | 0.55 | 0.75 | 5.50 | 1.21 | 6000 | 12.6 |
| MCS14D15- | 88 | 8.10 | 129 | 4.00 | 5.40 | 49.8 | 2.19 | 6000 | 10.7 |
| MCS14D36- | 92 | 8.10 | 64.2 | 1.00 | 1.35 | 12.5 | 1.09 | 6000 | 10.7 |
| MCS14H15- | 92 | 14.2 | 153 | 1.94 | 2.61 | 34.1 | 2.48 | 6000 | 15.5 |
| MCS14H32- | 93 | 14.2 | 76.3 | 0.48 | 0.65 | 8.50 | 1.24 | 6000 | 15.5 |
| MCS14L15- | 90 | 23.4 | 152 | 1.21 | 1.64 | 22.0 | 2.33 | 6000 | 20.1 |
| MCS14L32- | 93 | 23.4 | 76.2 | 0.30 | 0.41 | 5.50 | 1.16 | 6000 | 20.1 |
| MCS14P14- | 90 | 34.7 | 179 | 1.10 | 1.49 | 23.9 | 3.04 | 6000 | 24.9 |
| MCS14P32- | 93 | 34.7 | 89.4 | 0.28 | 0.37 | 6.00 | 1.52 | 6000 | 24.9 |

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.



Mains connection 3x 400 V

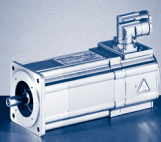
Motors without blower

| | n_N | M_0 | M_{max} | M_N | P_N | I_0 | I_N | I_{max} | $U_{N,AC}$ | f_N |
|------------------|---------|-------|-----------|-------|-------|-------|-------|-----------|------------|-------|
| | [r/min] | [Nm] | [Nm] | [Nm] | [kW] | [A] | [A] | [A] | [V] | [Hz] |
| MCS19F14- | 1425 | 32.0 | 86.0 | 27.0 | 4.00 | 9.90 | 8.60 | 31.0 | 335 | 95 |
| MCS19F30- | 3000 | 32.0 | 86.0 | 21.0 | 6.60 | 19.8 | 14.0 | 63.0 | 300 | 200 |
| MCS19J14- | 1425 | 51.0 | 129 | 40.0 | 6.00 | 15.2 | 12.3 | 45.0 | 330 | 95 |
| MCS19J30- | 3000 | 51.0 | 129 | 29.0 | 9.10 | 30.5 | 18.5 | 90.0 | 300 | 200 |
| MCS19P14- | 1350 | 64.0 | 190 | 51.0 | 7.20 | 17.5 | 14.3 | 60.0 | 330 | 90 |
| MCS19P30- | 3000 | 64.0 | 190 | 32.0 | 10.0 | 34.9 | 19.0 | 120 | 320 | 200 |

| | $\eta_{100\%}$ | J^1 | $KE_{LL\ 150\ ^\circ C}$ | $R_{UV\ 20\ ^\circ C}$ | $R_{UV\ 150\ ^\circ C}$ | L_N | $Kt_{0\ 150\ ^\circ C}$ | n_{max}^2 | m^1 |
|------------------|----------------|----------------------|--------------------------|------------------------|-------------------------|-------|-------------------------|-------------|-------|
| | [%] | [kgcm ²] | [V /1000 rp] | [Ω] | [Ω] | [mH] | [Nm/A] | [r/min] | [kg] |
| MCS19F14- | 92 | 65.0 | 195 | 1.30 | 1.75 | 20.8 | 3.23 | 4000 | 23.0 |
| MCS19F30- | 93 | 65.0 | 97.2 | 0.32 | 0.44 | 5.20 | 1.62 | 4000 | 23.0 |
| MCS19J14- | 92 | 105 | 199 | 0.65 | 0.88 | 12.8 | 3.31 | 4000 | 30.0 |
| MCS19J30- | 93 | 105 | 99.5 | 0.16 | 0.22 | 3.20 | 1.65 | 4000 | 30.0 |
| MCS19P14- | 92 | 160 | 216 | 0.54 | 0.73 | 9.60 | 3.66 | 4000 | 40.0 |
| MCS19P30- | 93 | 160 | 108 | 0.14 | 0.18 | 2.40 | 1.83 | 4000 | 40.0 |

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.



MCS synchronous servo motors

Rated data

Mains connection 3x 400 V

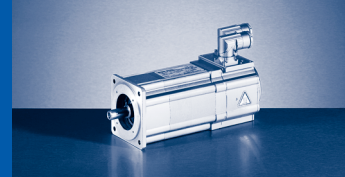
Motors with blower

| | n_N | M_0 | M_{max} | M_N | P_N | I_0 | I_N | I_{max} | $U_{N,AC}$ | f_N |
|-----------|---------|-------|-----------|-------|-------|-------|-------|-----------|------------|-------|
| | [r/min] | [Nm] | [Nm] | [Nm] | [kW] | [A] | [A] | [A] | [V] | [Hz] |
| MCS12D17- | 1650 | 7.50 | 17.7 | 7.00 | 1.20 | 3.20 | 3.00 | 10.0 | 330 | 110 |
| MCS12D35- | 3525 | 7.50 | 17.7 | 6.00 | 2.20 | 6.40 | 5.60 | 20.0 | 300 | 235 |
| MCS12H14- | 1350 | 12.8 | 29.0 | 12.0 | 1.70 | 4.30 | 4.10 | 12.0 | 310 | 90 |
| MCS12H34- | 3375 | 12.8 | 29.0 | 10.5 | 3.70 | 8.50 | 7.50 | 24.0 | 320 | 225 |
| MCS12L17- | 1650 | 19.0 | 56.4 | 17.0 | 2.90 | 7.20 | 6.70 | 28.0 | 300 | 110 |
| MCS12L39- | 3900 | 19.0 | 56.4 | 14.0 | 5.70 | 14.4 | 11.7 | 57.0 | 295 | 260 |
| MCS14D14- | 1350 | 12.5 | 29.0 | 12.0 | 1.70 | 5.70 | 5.40 | 17.0 | 345 | 90 |
| MCS14D30- | 3000 | 12.5 | 29.0 | 10.5 | 3.30 | 11.4 | 9.70 | 33.0 | 325 | 200 |
| MCS14H12- | 1200 | 25.5 | 54.8 | 13.5 | 3.00 | 9.30 | 8.30 | 26.0 | 335 | 80 |
| MCS14H28- | 2775 | 25.5 | 54.8 | 20.5 | 6.00 | 18.4 | 15.0 | 52.0 | 325 | 185 |
| MCS14L14- | 1350 | 34.5 | 77.1 | 30.5 | 4.30 | 13.4 | 11.8 | 37.0 | 335 | 90 |
| MCS14L30- | 3000 | 34.5 | 77.1 | 25.5 | 8.00 | 26.7 | 20.8 | 75.0 | 310 | 200 |
| MCS14P11- | 1050 | 43.5 | 105 | 42.0 | 4.60 | 14.1 | 13.4 | 46.0 | 330 | 70 |
| MCS14P26- | 2625 | 43.5 | 105 | 33.0 | 9.10 | 28.3 | 21.9 | 92.0 | 325 | 175 |

| | $\eta_{100\%}$ | $J^1)$ | $KE_{LL 150^\circ C}$ | $R_{UV 20^\circ C}$ | $R_{UV 150^\circ C}$ | L_N | $Kt_{0 150^\circ C}$ | $n_{max}^2)$ | $m^1)$ |
|-----------|----------------|----------------------|-----------------------|---------------------|----------------------|-------|----------------------|--------------|--------|
| | [%] | [kgcm ²] | [V / 1000 rp] | [Ω] | [Ω] | [mH] | [Nm/A] | [r/min] | [kg] |
| MCS12D17- | 75 | 4.00 | 137 | 8.72 | 11.8 | 52.2 | 2.34 | 6000 | 8.50 |
| MCS12D35- | 82 | 4.00 | 68.6 | 2.18 | 2.94 | 13.0 | 1.17 | 6000 | 8.50 |
| MCS12H14- | 80 | 7.30 | 173 | 5.72 | 7.72 | 42.1 | 2.98 | 6000 | 11.6 |
| MCS12H34- | 86 | 7.30 | 86.5 | 1.39 | 1.88 | 10.5 | 1.51 | 6000 | 11.6 |
| MCS12L17- | 90 | 10.6 | 149 | 2.22 | 2.99 | 21.8 | 2.64 | 6000 | 14.7 |
| MCS12L39- | 94 | 10.6 | 74.6 | 0.55 | 0.75 | 5.50 | 1.32 | 6000 | 14.7 |
| MCS14D14- | 84 | 8.10 | 129 | 4.00 | 5.40 | 49.8 | 2.19 | 6000 | 14.5 |
| MCS14D30- | 92 | 8.10 | 64.2 | 1.00 | 1.35 | 12.5 | 1.09 | 6000 | 14.5 |
| MCS14H12- | 87 | 14.2 | 153 | 1.94 | 2.61 | 34.1 | 2.75 | 6000 | 19.5 |
| MCS14H28- | 93 | 14.2 | 76.3 | 0.48 | 0.65 | 8.50 | 1.39 | 6000 | 19.5 |
| MCS14L14- | 88 | 23.4 | 152 | 1.21 | 1.64 | 22.0 | 2.57 | 6000 | 24.0 |
| MCS14L30- | 92 | 23.4 | 76.2 | 0.30 | 0.41 | 5.50 | 1.29 | 6000 | 24.0 |
| MCS14P11- | 86 | 34.7 | 179 | 1.10 | 1.49 | 23.9 | 3.08 | 6000 | 29.0 |
| MCS14P26- | 92 | 34.7 | 89.4 | 0.28 | 0.37 | 6.00 | 1.54 | 6000 | 29.0 |

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.



Mains connection 3x 400 V

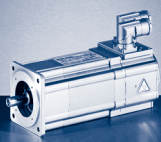
Motors with blower

| | n_N | M_0 | M_{max} | M_N | P_N | I_0 | I_N | I_{max} | $U_{N,AC}$ | f_N |
|------------------|---------|-------|-----------|-------|-------|-------|-------|-----------|------------|-------|
| | [r/min] | [Nm] | [Nm] | [Nm] | [kW] | [A] | [A] | [A] | [V] | [Hz] |
| MCS19F12- | 1200 | 41.5 | 86.0 | 38.0 | 4.80 | 12.2 | 11.3 | 31.0 | 320 | 80 |
| MCS19F29- | 2850 | 41.5 | 86.0 | 32.5 | 9.70 | 24.5 | 20.1 | 63.0 | 320 | 190 |
| MCS19J12- | 1200 | 70.5 | 129 | 62.5 | 7.90 | 20.3 | 18.3 | 45.0 | 320 | 80 |
| MCS19J29- | 2850 | 70.5 | 129 | 50.5 | 15.1 | 40.6 | 31.0 | 90.0 | 315 | 190 |
| MCS19P12- | 1200 | 86.0 | 190 | 72.0 | 9.00 | 22.4 | 21.3 | 60.0 | 310 | 80 |
| MCS19P29- | 2850 | 86.0 | 190 | 53.0 | 15.8 | 44.7 | 29.5 | 120 | 315 | 190 |

| | $\eta_{100\%}$ | J^1 | $KE_{LL 150\text{ }^\circ\text{C}}$ | $R_{UV 20\text{ }^\circ\text{C}}$ | $R_{UV 150\text{ }^\circ\text{C}}$ | L_N | $Kt_{0 150\text{ }^\circ\text{C}}$ | n_{max}^2 | m^1 |
|------------------|----------------|----------------------|-------------------------------------|-----------------------------------|------------------------------------|-------|------------------------------------|-------------|-------|
| | [%] | [kgcm ²] | [V /1000 rp] | [Ω] | [Ω] | [mH] | [Nm/A] | [r/min] | [kg] |
| MCS19F12- | 90 | 65.0 | 195 | 1.30 | 1.75 | 20.8 | 3.40 | 4000 | 29.0 |
| MCS19F29- | 95 | 65.0 | 97.2 | 0.32 | 0.44 | 5.20 | 1.69 | 4000 | 29.0 |
| MCS19J12- | 89 | 105 | 199 | 0.65 | 0.88 | 12.8 | 3.47 | 4000 | 36.0 |
| MCS19J29- | 93 | 105 | 99.5 | 0.16 | 0.22 | 3.20 | 1.74 | 4000 | 36.0 |
| MCS19P12- | 90 | 160 | 216 | 0.54 | 0.73 | 9.60 | 3.84 | 4000 | 46.0 |
| MCS19P29- | 93 | 160 | 108 | 0.14 | 0.18 | 2.40 | 1.92 | 4000 | 46.0 |

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.



MCS synchronous servo motors

Rated data

Mains connection 3x 230 V

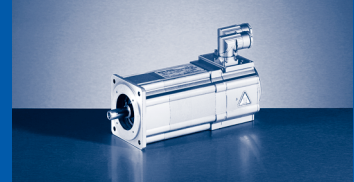
Motors without blower

| | n_N | M_0 | M_{max} | M_N | P_N | I_0 | I_N | I_{max} | $U_{N,AC}$ | f_N |
|-----------|---------|-------|-----------|-------|-------|-------|-------|-----------|------------|-------|
| | [r/min] | [Nm] | [Nm] | [Nm] | [kW] | [A] | [A] | [A] | [V] | [Hz] |
| MCS06C41L | 4050 | 0.80 | 2.40 | 0.60 | 0.25 | 2.50 | 2.50 | 10.8 | 125 | 270 |
| MCS06C60L | 6000 | 0.80 | 2.40 | 0.50 | 0.31 | 4.30 | 4.00 | 18.5 | 85 | 400 |
| MCS06F41L | 4050 | 1.50 | 4.40 | 1.20 | 0.51 | 2.90 | 2.90 | 10.5 | 165 | 270 |
| MCS06F60L | 6000 | 1.50 | 4.40 | 0.90 | 0.57 | 3.80 | 3.40 | 16.5 | 125 | 400 |
| MCS06I41L | 4050 | 2.00 | 6.20 | 1.50 | 0.64 | 3.10 | 2.90 | 11.8 | 175 | 270 |
| MCS06I60L | 6000 | 2.00 | 6.20 | 1.20 | 0.75 | 4.20 | 3.60 | 16.0 | 150 | 400 |
| MCS09D41L | 4050 | 3.30 | 9.50 | 2.30 | 1.00 | 5.30 | 4.60 | 20.0 | 165 | 270 |
| MCS09D60L | 6000 | 3.30 | 9.50 | 1.80 | 1.10 | 10.3 | 7.00 | 39.0 | 110 | 400 |
| MCS09F38L | 3750 | 4.20 | 15.0 | 3.10 | 1.20 | 6.00 | 5.00 | 30.0 | 160 | 250 |
| MCS09F60L | 6000 | 4.20 | 15.0 | 2.40 | 1.50 | 10.5 | 7.90 | 53.0 | 125 | 400 |
| MCS09H41L | 4050 | 5.50 | 20.0 | 3.80 | 1.60 | 8.50 | 6.80 | 40.0 | 160 | 270 |
| MCS09H60L | 6000 | 5.50 | 20.0 | 3.00 | 1.90 | 12.0 | 8.00 | 57.0 | 145 | 400 |
| MCS09L41L | 4050 | 7.50 | 32.0 | 4.50 | 1.90 | 12.4 | 8.40 | 64.0 | 145 | 270 |

| | $\eta_{100\%}$ | J^1 | $KE_{LL 150\text{ }^\circ\text{C}}$ | $R_{UV 20\text{ }^\circ\text{C}}$ | $R_{UV 150\text{ }^\circ\text{C}}$ | L_N | $Kt_{0 150\text{ }^\circ\text{C}}$ | n_{max}^2 | m^1 |
|-----------|----------------|----------------------|-------------------------------------|-----------------------------------|------------------------------------|-------|------------------------------------|-------------|-------|
| | [%] | [kgcm ²] | [V / 1000 rp] | [Ω] | [Ω] | [mH] | [Nm/A] | [r/min] | [kg] |
| MCS06C41L | 65 | 0.14 | 21.5 | 6.00 | 8.00 | 12.8 | 0.33 | 8000 | 1.80 |
| MCS06C60L | 70 | 0.14 | 12.5 | 2.20 | 2.90 | 4.30 | 0.19 | 8000 | 1.80 |
| MCS06F41L | 81 | 0.22 | 34.5 | 5.50 | 7.40 | 15.9 | 0.62 | 8000 | 2.20 |
| MCS06F60L | 82 | 0.22 | 22.2 | 2.30 | 3.00 | 6.90 | 0.40 | 8000 | 2.20 |
| MCS06I41L | 81 | 0.30 | 38.0 | 4.70 | 6.20 | 15.1 | 0.64 | 8000 | 2.90 |
| MCS06I60L | 84 | 0.30 | 28.5 | 2.50 | 3.40 | 9.30 | 0.48 | 8000 | 2.90 |
| MCS09D41L | 87 | 1.10 | 35.6 | 1.80 | 2.40 | 6.30 | 0.62 | 7000 | 4.30 |
| MCS09D60L | 87 | 1.10 | 18.3 | 0.45 | 1.20 | 1.70 | 0.32 | 7000 | 4.30 |
| MCS09F38L | 90 | 1.50 | 39.9 | 1.30 | 1.80 | 6.20 | 0.70 | 7000 | 5.20 |
| MCS09F60L | 91 | 1.50 | 22.8 | 0.42 | 0.56 | 2.00 | 0.40 | 7000 | 5.20 |
| MCS09H41L | 91 | 1.90 | 37.8 | 0.80 | 1.10 | 4.00 | 0.65 | 7000 | 6.10 |
| MCS09H60L | 91 | 1.90 | 26.6 | 0.36 | 0.48 | 2.00 | 0.46 | 7000 | 6.10 |
| MCS09L41L | 91 | 2.80 | 35.9 | 0.44 | 0.59 | 2.50 | 0.60 | 7000 | 7.90 |

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.



Mains connection 3x 230 V

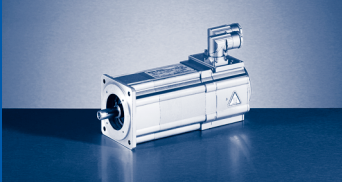
Motors without blower

| | n_N | M_0 | M_{max} | M_N | P_N | I_0 | I_N | I_{max} | $U_{N,AC}$ | f_N |
|------------------|---------|-------|-----------|-------|-------|-------|-------|-----------|------------|-------|
| | [r/min] | [Nm] | [Nm] | [Nm] | [kW] | [A] | [A] | [A] | [V] | [Hz] |
| MCS12D20L | 1950 | 6.40 | 18.0 | 5.50 | 1.10 | 5.50 | 5.20 | 20.0 | 175 | 130 |
| MCS12D41L | 4050 | 6.40 | 18.0 | 4.30 | 1.80 | 10.7 | 8.80 | 40.0 | 155 | 270 |
| MCS12H15L | 1500 | 11.4 | 29.0 | 10.0 | 1.60 | 8.20 | 7.80 | 24.0 | 158 | 100 |
| MCS12H30L | 3000 | 11.4 | 29.0 | 8.00 | 2.50 | 13.5 | 10.5 | 39.0 | 165 | 200 |
| MCS12L20L | 1950 | 15.0 | 56.0 | 13.5 | 2.80 | 12.4 | 11.8 | 57.0 | 165 | 130 |

| | $\eta_{100\%}$ | J^1 | $KE_{LL 150^\circ C}$ | $R_{UV 20^\circ C}$ | $R_{UV 150^\circ C}$ | L_N | $Kt_{0 150^\circ C}$ | n_{max}^2 | m^1 |
|------------------|----------------|----------------------|-----------------------|---------------------|----------------------|-------|----------------------|-------------|-------|
| | [%] | [kgcm ²] | [V / 1000 rp] | [Ω] | [Ω] | [mH] | [Nm/A] | [r/min] | [kg] |
| MCS12D20L | 79 | 4.00 | 68.6 | 2.20 | 2.90 | 13.0 | 1.17 | 6000 | 6.40 |
| MCS12D41L | 84 | 4.00 | 35.0 | 0.55 | 0.75 | 3.40 | 0.60 | 6000 | 6.40 |
| MCS12H15L | 82 | 7.30 | 86.5 | 1.43 | 1.93 | 10.5 | 1.40 | 6000 | 9.50 |
| MCS12H30L | 87 | 7.30 | 53.0 | 0.50 | 0.67 | 4.00 | 0.86 | 6000 | 9.50 |
| MCS12L20L | 90 | 10.6 | 76.9 | 0.55 | 0.75 | 5.50 | 1.21 | 6000 | 12.6 |

¹⁾ Without brake.

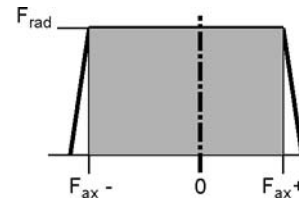
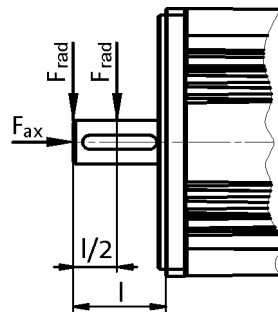
²⁾ Mechanically permissible maximum speed.



MCS synchronous servo motors

Rated data

Permissible radial and axial forces



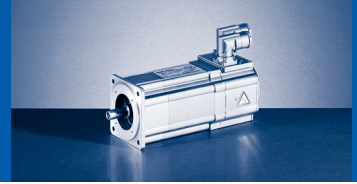
Application of force at l/2

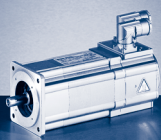
| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|--------------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MCS06 | 740 | -260 | 140 | 590 | -210 | 80 | 470 | -170 | 40 | 410 | -150 | 30 | 340 | -140 | 10 |
| MCS09 | 1040 | -700 | 470 | 830 | -550 | 310 | 660 | -440 | 200 | 580 | -380 | 150 | 490 | -330 | 90 |
| MCS12 | 1030 | -880 | 560 | 820 | -690 | 370 | 650 | -550 | 230 | 570 | -490 | 160 | 480 | -420 | 100 |
| MCS14 | 1830 | -1150 | 720 | 1450 | -900 | 470 | 1150 | -720 | 290 | 1010 | -640 | 200 | 850 | -550 | 120 |
| MCS19 | 3840 | -1550 | 950 | 3050 | -1210 | 620 | 2430 | -960 | 360 | 2120 | -840 | 250 | 1790 | -730 | 130 |

Application of force at l

| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|--------------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MCS06 | 630 | -210 | 90 | 500 | -170 | 50 | 400 | -140 | 20 | 350 | -130 | 0 | 290 | -120 | -10 |
| MCS09 | 900 | -630 | 400 | 710 | -500 | 260 | 570 | -400 | 160 | 500 | -350 | 120 | 420 | -300 | 70 |
| MCS12 | 890 | -820 | 490 | | -640 | 320 | 560 | -520 | 190 | 490 | -460 | 130 | | -400 | |
| MCS14 | 1590 | -1040 | 610 | 1260 | -820 | 390 | 1000 | -660 | 230 | 880 | -580 | 150 | 740 | -510 | |
| MCS19 | 3330 | -1320 | 730 | 2650 | -1040 | 450 | 2100 | -830 | 240 | 1840 | -740 | 140 | 1550 | -640 | 40 |

- The values for the bearing service life L_{10} refer to an average speed of 4000 r/min. Depending on the ambient temperatures, the service life of the bearings is also reduced by the grease lifetime.





MCS synchronous servo motors

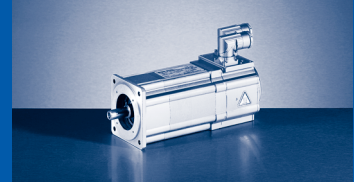
9400 Servo Drives selection tables

Mains connection 3 x 400 V and switching frequency 4 kHz

Motors without blower

| | | | | | E94A□□ | E0024 | E0034 | E0044 | E0074 | E0094 | E0134 | E0174 | E0244 | E0324 | E0474 | E0594 |
|--------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 1.9 | 3.1 | 5.0 | 8.8 | 11.7 | 16.3 | 20.6 | 29.4 | 38.4 | 47.0 | 59.0 |
| | | | | | $I_{0,max}$ | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 |
| 06C41- | 0.6 | 4050 | 1.3 | 0.25 | M_0 | 0.8 | | | | | | | | | | |
| | | | | | M_N | 0.6 | | | | | | | | | | |
| | | | | | $M_{0,max}$ | 2.4 | | | | | | | | | | |
| | | | | | M_{max} | 2.4 | | | | | | | | | | |
| | | | | | η_{eto} | - | | | | | | | | | | |
| 06C60- | 0.5 | 6000 | 2.4 | 0.31 | M_0 | 0.6 | 0.8 | | | | | | | | | |
| | | | | | M_N | 0.4 | 0.5 | | | | | | | | | |
| | | | | | $M_{0,max}$ | 1.5 | 2.3 | | | | | | | | | |
| | | | | | M_{max} | 1.5 | 2.3 | | | | | | | | | |
| | | | | | η_{eto} | - | | | | | | | | | | |
| 06F41- | 1.2 | 4050 | 1.5 | 0.51 | M_0 | 1.5 | | | | | | | | | | |
| | | | | | M_N | 1.2 | | | | | | | | | | |
| | | | | | $M_{0,max}$ | 4.4 | | | | | | | | | | |
| | | | | | M_{max} | 4.4 | | | | | | | | | | |
| | | | | | η_{eto} | - | | | | | | | | | | |
| 06F60- | 0.9 | 6000 | 2.5 | 0.57 | M_0 | 1.0 | 1.5 | | | | | | | | | |
| | | | | | M_N | 0.7 | 0.9 | | | | | | | | | |
| | | | | | $M_{0,max}$ | 3.0 | 4.3 | | | | | | | | | |
| | | | | | M_{max} | 3.0 | 4.3 | | | | | | | | | |
| | | | | | η_{eto} | - | | | | | | | | | | |
| 06I41- | 1.5 | 4050 | 1.6 | 0.64 | M_0 | 2.0 | | | | | | | | | | |
| | | | | | M_N | 1.5 | | | | | | | | | | |
| | | | | | $M_{0,max}$ | 6.2 | | | | | | | | | | |
| | | | | | M_{max} | 6.2 | | | | | | | | | | |
| | | | | | η_{eto} | - | | | | | | | | | | |
| 06I60- | 1.2 | 6000 | 2.9 | 0.75 | M_0 | 1.1 | 1.8 | 2.0 | | | | | | | | |
| | | | | | M_N | 0.8 | 1.2 | 1.2 | | | | | | | | |
| | | | | | $M_{0,max}$ | 3.3 | 5.5 | 6.2 | | | | | | | | |
| | | | | | M_{max} | 3.3 | 5.5 | 6.2 | | | | | | | | |
| | | | | | η_{eto} | - | | | | | | | | | | |
| 09D41- | 2.3 | 4050 | 2.3 | 1.00 | M_0 | 2.4 | 3.3 | | | | | | | | | |
| | | | | | M_N | 1.9 | 2.3 | | | | | | | | | |
| | | | | | $M_{0,max}$ | 6.3 | 9.5 | | | | | | | | | |
| | | | | | M_{max} | 6.3 | 9.5 | | | | | | | | | |
| | | | | | η_{eto} | - | | | | | | | | | | |
| 09D60- | 1.8 | 6000 | 3.8 | 1.10 | M_0 | | | 3.1 | 3.3 | | | | | | | |
| | | | | | M_N | | | 1.8 | 1.8 | | | | | | | |
| | | | | | $M_{0,max}$ | | | 8.0 | 9.5 | | | | | | | |
| | | | | | M_{max} | | | 8.0 | 9.5 | | | | | | | |
| | | | | | η_{eto} | | | - | - | | | | | | | |
| 09F38- | 3.1 | 3750 | 2.5 | 1.20 | M_0 | | 4.2 | 4.2 | | | | | | | | |
| | | | | | M_N | | 3.1 | 3.1 | | | | | | | | |
| | | | | | $M_{0,max}$ | | 11.6 | 14.9 | | | | | | | | |
| | | | | | M_{max} | | 11.6 | 14.9 | | | | | | | | |
| | | | | | η_{eto} | | - | - | | | | | | | | |
| 09F60- | 2.4 | 6000 | 4.5 | 1.50 | M_0 | | | 3.5 | 4.2 | 4.2 | 4.2 | | | | | |
| | | | | | M_N | | | 2.4 | 2.4 | 2.4 | 2.4 | | | | | |
| | | | | | $M_{0,max}$ | | | 9.8 | 12.0 | 14.4 | 14.9 | | | | | |
| | | | | | M_{max} | | | 9.8 | 12.0 | 14.4 | 14.9 | | | | | |
| | | | | | η_{eto} | | | - | - | - | - | | | | | |

► I... [A], M... [Nm], n... [r/min], P... [kW]

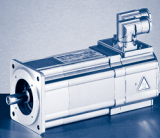


Mains connection 3 x 400 V and switching frequency 4 kHz

Motors without blower

| | | | | | E94A□□ | E0024 | E0034 | E0044 | E0074 | E0094 | E0134 | E0174 | E0244 | E0324 | E0474 | E0594 |
|--------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 1.9 | 3.1 | 5.0 | 8.8 | 11.7 | 16.3 | 20.6 | 29.4 | 38.4 | 47.0 | 59.0 |
| | | | | | $I_{0,max}$ | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 |
| 09H41- | 3.8 | 4050 | 3.4 | 1.60 | M_0 | | 4.0 | 5.5 | 5.5 | | | | | | | |
| | | | | | M_N | | 3.5 | 3.8 | 3.8 | | | | | | | |
| | | | | | $M_{0,max}$ | | 12.0 | 17.5 | 20.4 | | | | | | | |
| | | | | | M_{max} | | 12.0 | 17.5 | 20.4 | | | | | | | |
| | | | | | η_{eto} | | - | - | - | | | | | | | |
| 09H60- | 3.0 | 6000 | 6.0 | 1.90 | M_0 | | | | 5.5 | 5.5 | 5.5 | 5.5 | | | | |
| | | | | | M_N | | | | 3.0 | 3.0 | 3.0 | 3.0 | | | | |
| | | | | | $M_{0,max}$ | | | | 12.5 | 15.8 | 20.1 | 20.4 | | | | |
| | | | | | M_{max} | | | | 12.5 | 15.8 | 20.1 | 20.4 | | | | |
| | | | | | η_{eto} | | | | - | - | - | - | | | | |
| 09L41- | 4.5 | 4050 | 4.2 | 1.90 | M_0 | | | 6.0 | 7.5 | 7.5 | | | | | | |
| | | | | | M_N | | | 4.5 | 4.5 | 4.5 | | | | | | |
| | | | | | $M_{0,max}$ | | | 17.4 | 22.2 | 28.5 | | | | | | |
| | | | | | M_{max} | | | 17.4 | 22.2 | 28.5 | | | | | | |
| | | | | | η_{eto} | | | - | - | - | | | | | | |
| 09L51- | 3.6 | 5100 | 6.9 | 1.90 | M_0 | | | | 5.3 | 7.0 | 7.5 | 7.5 | 7.5 | | | |
| | | | | | M_N | | | | 3.6 | 3.6 | 3.6 | 3.6 | 3.6 | | | |
| | | | | | $M_{0,max}$ | | | | 11.9 | 15.5 | 20.9 | 25.8 | 29.7 | | | |
| | | | | | M_{max} | | | | 11.9 | 15.5 | 20.9 | 25.8 | 29.7 | | | |
| | | | | | η_{eto} | | | | - | - | - | - | - | | | |
| 12D20- | 5.5 | 1950 | 2.6 | 1.10 | M_0 | 4.4 | 6.4 | | | | | | | | | |
| | | | | | M_N | 4.0 | 5.5 | | | | | | | | | |
| | | | | | $M_{0,max}$ | 11.8 | 17.7 | | | | | | | | | |
| | | | | | M_{max} | 11.8 | 17.7 | | | | | | | | | |
| | | | | | η_{eto} | - | - | | | | | | | | | |
| 12D41- | 4.3 | 4050 | 4.5 | 1.80 | M_0 | | | 5.9 | 6.4 | | | | | | | |
| | | | | | M_N | | | 4.3 | 4.3 | | | | | | | |
| | | | | | $M_{0,max}$ | | | 14.7 | 17.7 | | | | | | | |
| | | | | | M_{max} | | | 14.7 | 17.7 | | | | | | | |
| | | | | | η_{eto} | | | - | - | | | | | | | |
| 12H15- | 10.0 | 1500 | 3.8 | 1.60 | M_0 | | 8.7 | 11.4 | | | | | | | | |
| | | | | | M_N | | 8.2 | 10.0 | | | | | | | | |
| | | | | | $M_{0,max}$ | | 24.6 | 29.0 | | | | | | | | |
| | | | | | M_{max} | | 24.6 | 29.0 | | | | | | | | |
| | | | | | η_{eto} | | - | - | | | | | | | | |
| 12H35- | 7.5 | 3525 | 5.7 | 2.80 | M_0 | | | 7.0 | 11.4 | 11.4 | 11.4 | | | | | |
| | | | | | M_N | | | 6.6 | 7.5 | 7.5 | 7.5 | | | | | |
| | | | | | $M_{0,max}$ | | | 20.1 | 25.8 | 29.0 | 29.0 | | | | | |
| | | | | | M_{max} | | | 20.1 | 25.8 | 29.0 | 29.0 | | | | | |
| | | | | | η_{eto} | | | - | - | - | - | | | | | |
| 12L20- | 13.5 | 1950 | 5.9 | 2.80 | M_0 | | | 12.1 | 15.0 | 15.0 | 15.0 | | | | | |
| | | | | | M_N | | | 11.4 | 13.5 | 13.5 | 13.5 | | | | | |
| | | | | | $M_{0,max}$ | | | 35.5 | 44.6 | 55.7 | 56.4 | | | | | |
| | | | | | M_{max} | | | 35.5 | 44.6 | 55.7 | 56.4 | | | | | |
| | | | | | η_{eto} | | | - | - | - | - | | | | | |
| 12L41- | 11.0 | 4050 | 10.2 | 4.70 | M_0 | | | | 10.6 | 14.0 | 15.0 | 15.0 | 15.0 | | | |
| | | | | | M_N | | | | 9.5 | 11.0 | 11.0 | 11.0 | 11.0 | | | |
| | | | | | $M_{0,max}$ | | | | 24.4 | 31.6 | 41.9 | 50.8 | 56.4 | | | |
| | | | | | M_{max} | | | | 24.4 | 31.6 | 41.9 | 50.8 | 56.4 | | | |
| | | | | | η_{eto} | | | | - | - | - | - | - | | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MCS synchronous servo motors

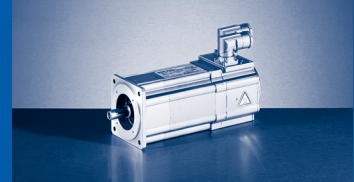
9400 Servo Drives selection tables

Mains connection 3 x 400 V and switching frequency 4 kHz

Motors without blower

| | | | | | E94A□□ | E0024 | E0034 | E0044 | E0074 | E0094 | E0134 | E0174 | E0244 | E0324 | E0474 | E0594 |
|--------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 1.9 | 3.1 | 5.0 | 8.8 | 11.7 | 16.3 | 20.6 | 29.4 | 38.4 | 47.0 | 59.0 |
| | | | | | $I_{0,max}$ | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 |
| 14D15- | 9.2 | 1500 | 4.5 | 1.45 | M_0 | | | 11.0 | 11.0 | | | | | | | |
| | | | | | M_N | | | 9.2 | 9.2 | | | | | | | |
| | | | | | $M_{0,max}$ | | | 28.3 | 29.0 | | | | | | | |
| | | | | | M_{max} | | | 28.3 | 29.0 | | | | | | | |
| | | | | | η_{eto} | | | - | - | | | | | | | |
| 14D36- | 7.5 | 3600 | 7.5 | 2.80 | M_0 | | | | 9.6 | 11.0 | 11.0 | | | | | |
| | | | | | M_N | | | | 7.5 | 7.5 | 7.5 | | | | | |
| | | | | | $M_{0,max}$ | | | | 20.2 | 25.6 | 29.0 | | | | | |
| | | | | | M_{max} | | | | 20.2 | 25.6 | 29.0 | | | | | |
| | | | | | η_{eto} | | | | - | - | - | | | | | |
| 14H15- | 16.0 | 1500 | 6.6 | 2.50 | M_0 | | | 12.4 | 21.0 | 21.0 | 21.0 | | | | | |
| | | | | | M_N | | | 12.1 | 16.0 | 16.0 | 16.0 | | | | | |
| | | | | | $M_{0,max}$ | | | 37.1 | 46.6 | 54.8 | 54.8 | | | | | |
| | | | | | M_{max} | | | 37.1 | 46.6 | 54.8 | 54.8 | | | | | |
| | | | | | η_{eto} | | | - | - | - | - | | | | | |
| 14H32- | 14.0 | 3225 | 11.9 | 4.70 | M_0 | | | | | 14.4 | 20.3 | 21.0 | 21.0 | | | |
| | | | | | M_N | | | | | 13.6 | 14.0 | 14.0 | 14.0 | | | |
| | | | | | $M_{0,max}$ | | | | | 33.0 | 43.9 | 53.2 | 54.8 | | | |
| | | | | | M_{max} | | | | | 33.0 | 43.9 | 53.2 | 54.8 | | | |
| | | | | | η_{eto} | | | | | - | - | - | - | | | |
| 14L15- | 23.0 | 1500 | 9.7 | 3.60 | M_0 | | | | 20.5 | 27.1 | 28.0 | | | | | |
| | | | | | M_N | | | | 20.9 | 23.0 | 23.0 | | | | | |
| | | | | | $M_{0,max}$ | | | | 48.0 | 61.4 | 77.1 | | | | | |
| | | | | | M_{max} | | | | 48.0 | 61.4 | 77.1 | | | | | |
| | | | | | η_{eto} | | | | - | - | - | | | | | |
| 14L32- | 17.2 | 3225 | 15.0 | 5.80 | M_0 | | | | | | 19.0 | 24.0 | 28.0 | 28.0 | 28.0 | |
| | | | | | M_N | | | | | | 17.2 | 17.2 | 17.2 | 17.2 | 17.2 | |
| | | | | | $M_{0,max}$ | | | | | | 45.0 | 55.3 | 63.9 | 77.1 | 77.1 | |
| | | | | | M_{max} | | | | | | 45.0 | 55.3 | 63.9 | 77.1 | 77.1 | |
| | | | | | η_{eto} | | | | | | - | - | - | - | - | |
| 14P14- | 30.0 | 1350 | 10.8 | 4.20 | M_0 | | | | 26.7 | 35.2 | 37.0 | 37.0 | | | | |
| | | | | | M_N | | | | 24.4 | 30.0 | 30.0 | 30.0 | | | | |
| | | | | | $M_{0,max}$ | | | | 56.1 | 71.7 | 93.3 | 105.1 | | | | |
| | | | | | M_{max} | | | | 56.1 | 71.7 | 93.3 | 105.1 | | | | |
| | | | | | η_{eto} | | | | - | - | - | - | | | | |
| 14P32- | 21.0 | 3225 | 15.6 | 7.10 | M_0 | | | | | | 24.8 | 31.4 | 37.0 | 37.0 | 37.0 | |
| | | | | | M_N | | | | | | 21.0 | 21.0 | 21.0 | 21.0 | 21.0 | |
| | | | | | $M_{0,max}$ | | | | | | 52.5 | 64.6 | 74.7 | 92.2 | 105.1 | |
| | | | | | M_{max} | | | | | | 52.5 | 64.6 | 74.7 | 92.2 | 105.1 | |
| | | | | | η_{eto} | | | | | | - | - | - | - | - | |
| 19F14- | 27.0 | 1425 | 8.6 | 4.00 | M_0 | | | | 28.4 | 32.0 | 32.0 | | | | | |
| | | | | | M_N | | | | 27.0 | 27.0 | 27.0 | | | | | |
| | | | | | $M_{0,max}$ | | | | 62.1 | 78.9 | 86.0 | | | | | |
| | | | | | M_{max} | | | | 62.1 | 78.9 | 86.0 | | | | | |
| | | | | | η_{eto} | | | | - | - | - | | | | | |
| 19F30- | 21.0 | 3000 | 14.0 | 6.60 | M_0 | | | | | | 26.3 | 32.0 | 32.0 | 32.0 | | |
| | | | | | M_N | | | | | | 21.0 | 21.0 | 21.0 | 21.0 | | |
| | | | | | $M_{0,max}$ | | | | | | 56.6 | 70.2 | 81.6 | 86.0 | | |
| | | | | | M_{max} | | | | | | 56.6 | 70.2 | 81.6 | 86.0 | | |
| | | | | | η_{eto} | | | | | | - | - | - | - | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

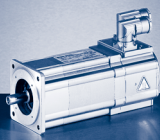


Mains connection 3 x 400 V and switching frequency 4 kHz

Motors without blower

| | | | | | E94A□□ | E0024 | E0034 | E0044 | E0074 | E0094 | E0134 | E0174 | E0244 | E0324 | E0474 | E0594 |
|--------|-------|-------|-------|-------|-------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 1.9 | 3.1 | 5.0 | 8.8 | 11.7 | 16.3 | 20.6 | 29.4 | 38.4 | 47.0 | 59.0 |
| | | | | | $I_{0,max}$ | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 |
| 19J14- | 40.0 | 1425 | 12.3 | 6.00 | M_0 | | | | | 38.9 | 51.0 | 51.0 | | | | |
| | | | | | M_N | | | | | 37.7 | 40.0 | 40.0 | | | | |
| | | | | | $M_{0,max}$ | | | | | 85.0 | 114.4 | 129.0 | | | | |
| | | | | | M_{max} | | | | | 85.0 | 114.4 | 129.0 | | | | |
| | | | | | n_{eto} | | | | | - | - | - | | | | |
| 19J30- | 29.0 | 3000 | 18.5 | 9.10 | M_0 | | | | | | 27.3 | 34.4 | 49.2 | 51.0 | 51.0 | |
| | | | | | M_N | | | | | 25.6 | 29.0 | 29.0 | 29.0 | 29.0 | | |
| | | | | | $M_{0,max}$ | | | | | 60.8 | 75.9 | 88.9 | 112.9 | 129.0 | | |
| | | | | | M_{max} | | | | | 60.8 | 75.9 | 88.9 | 112.9 | 129.0 | | |
| | | | | | n_{eto} | | | | | - | - | - | - | - | | |
| 19P14- | 51.0 | 1350 | 14.3 | 7.20 | M_0 | | | | | | 59.6 | 64.0 | 64.0 | 64.0 | | |
| | | | | | M_N | | | | | 51.0 | 51.0 | 51.0 | 51.0 | | | |
| | | | | | $M_{0,max}$ | | | | | 128.4 | 159.9 | 186.6 | 190.0 | | | |
| | | | | | M_{max} | | | | | 128.4 | 159.9 | 186.6 | 190.0 | | | |
| | | | | | n_{eto} | | | | | - | - | - | - | | | |
| 19P30- | 32.0 | 3000 | 19.0 | 10.00 | M_0 | | | | | | 29.9 | 37.8 | 53.9 | 64.0 | 64.0 | 64.0 |
| | | | | | M_N | | | | | 27.5 | 32.0 | 32.0 | 32.0 | 32.0 | 32.0 | |
| | | | | | $M_{0,max}$ | | | | | 65.7 | 83.6 | 98.5 | 126.6 | 152.5 | 187.2 | |
| | | | | | M_{max} | | | | | 65.7 | 83.6 | 98.5 | 126.6 | 152.5 | 187.2 | |
| | | | | | n_{eto} | | | | | - | - | - | - | - | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MCS synchronous servo motors

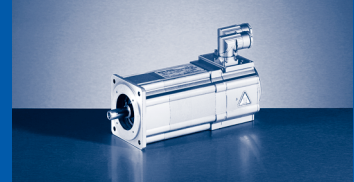
9400 Servo Drives selection tables

Mains connection 3 x 400 V and switching frequency 4 kHz

Motors with blower

| | | | | | E94A□□ | E0024 | E0034 | E0044 | E0074 | E0094 | E0134 | E0174 | E0244 | E0324 | E0474 | E0594 |
|--------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 1.9 | 3.1 | 5.0 | 8.8 | 11.7 | 16.3 | 20.6 | 29.4 | 38.4 | 47.0 | 59.0 |
| | | | | | $I_{0,max}$ | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 |
| 12D17- | 7.0 | 1650 | 3.0 | 1.20 | M_0 | 4.4 | 7.3 | | | | | | | | | |
| | | | | | M_N | 4.0 | 7.0 | | | | | | | | | |
| | | | | | $M_{0,max}$ | 11.8 | 17.7 | | | | | | | | | |
| | | | | | M_{max} | 11.8 | 17.7 | | | | | | | | | |
| | | | | | η_{eto} | - | - | | | | | | | | | |
| 12D35- | 6.0 | 3525 | 5.6 | 2.20 | M_0 | | | 5.9 | 7.5 | | | | | | | |
| | | | | | M_N | | | 5.4 | 6.0 | | | | | | | |
| | | | | | $M_{0,max}$ | | | 14.7 | 17.7 | | | | | | | |
| | | | | | M_{max} | | | 14.7 | 17.7 | | | | | | | |
| | | | | | η_{eto} | | | - | - | | | | | | | |
| 12H14- | 12.0 | 1350 | 4.1 | 1.70 | M_0 | | 8.7 | 12.8 | | | | | | | | |
| | | | | | M_N | | 8.2 | 12.0 | | | | | | | | |
| | | | | | $M_{0,max}$ | | 24.6 | 29.0 | | | | | | | | |
| | | | | | M_{max} | | 24.6 | 29.0 | | | | | | | | |
| | | | | | η_{eto} | | - | - | | | | | | | | |
| 12H34- | 10.5 | 3375 | 7.5 | 3.70 | M_0 | | | 7.0 | 12.8 | 12.8 | 12.8 | | | | | |
| | | | | | M_N | | | 6.6 | 10.5 | 10.5 | 10.5 | | | | | |
| | | | | | $M_{0,max}$ | | | 20.1 | 25.8 | 29.0 | 29.0 | | | | | |
| | | | | | M_{max} | | | 20.1 | 25.8 | 29.0 | 29.0 | | | | | |
| | | | | | η_{eto} | | | - | - | - | - | | | | | |
| 12L17- | 17.0 | 1650 | 6.7 | 2.90 | M_0 | | | 12.1 | 19.0 | 19.0 | 19.0 | | | | | |
| | | | | | M_N | | | 11.4 | 17.0 | 17.0 | 17.0 | | | | | |
| | | | | | $M_{0,max}$ | | | 35.5 | 44.6 | 55.7 | 56.4 | | | | | |
| | | | | | M_{max} | | | 35.5 | 44.6 | 55.7 | 56.4 | | | | | |
| | | | | | η_{eto} | | | - | - | - | - | | | | | |
| 12L39- | 14.0 | 3900 | 11.7 | 5.70 | M_0 | | | | 10.6 | 15.3 | 19.0 | 19.0 | 19.0 | | | |
| | | | | | M_N | | | | 9.5 | 13.9 | 14.0 | 14.0 | 14.0 | | | |
| | | | | | $M_{0,max}$ | | | | 24.4 | 31.6 | 41.9 | 50.8 | 56.4 | | | |
| | | | | | M_{max} | | | | 24.4 | 31.6 | 41.9 | 50.8 | 56.4 | | | |
| | | | | | η_{eto} | | | | - | - | - | - | - | | | |
| 14D14- | 12.0 | 1350 | 5.4 | 1.70 | M_0 | | | 11.0 | 12.5 | | | | | | | |
| | | | | | M_N | | | 11.0 | 12.0 | | | | | | | |
| | | | | | $M_{0,max}$ | | | 28.3 | 29.0 | | | | | | | |
| | | | | | M_{max} | | | 28.3 | 29.0 | | | | | | | |
| | | | | | η_{eto} | | | - | - | | | | | | | |
| 14D30- | 10.5 | 3000 | 9.7 | 3.30 | M_0 | | | | 9.6 | 12.5 | 12.5 | | | | | |
| | | | | | M_N | | | | 9.5 | 10.5 | 10.5 | | | | | |
| | | | | | $M_{0,max}$ | | | | 20.2 | 25.6 | 29.0 | | | | | |
| | | | | | M_{max} | | | | 20.2 | 25.6 | 29.0 | | | | | |
| | | | | | η_{eto} | | | | - | - | - | | | | | |
| 14H12- | 23.5 | 1200 | 8.3 | 3.00 | M_0 | | | 12.4 | 24.1 | 25.5 | 25.5 | | | | | |
| | | | | | M_N | | | 12.1 | 23.5 | 23.5 | 23.5 | | | | | |
| | | | | | $M_{0,max}$ | | | 37.1 | 46.6 | 54.8 | 54.8 | | | | | |
| | | | | | M_{max} | | | 37.1 | 46.6 | 54.8 | 54.8 | | | | | |
| | | | | | η_{eto} | | | - | - | - | - | | | | | |
| 14H28- | 20.5 | 2775 | 15.0 | 6.00 | M_0 | | | | | 16.1 | 20.5 | 25.5 | 25.5 | | | |
| | | | | | M_N | | | | | 15.9 | 20.5 | 20.5 | 20.5 | | | |
| | | | | | $M_{0,max}$ | | | | | 33.0 | 43.9 | 53.2 | 54.8 | | | |
| | | | | | M_{max} | | | | | 33.0 | 43.9 | 53.2 | 54.8 | | | |
| | | | | | η_{eto} | | | | | - | - | - | - | | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

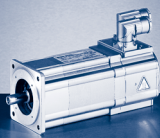


Mains connection 3 x 400 V and switching frequency 4 kHz

Motors with blower

| | | | | | E94A□□ | E0024 | E0034 | E0044 | E0074 | E0094 | E0134 | E0174 | E0244 | E0324 | E0474 | E0594 |
|--------|-------|-------|-------|-------|-------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 1.9 | 3.1 | 5.0 | 8.8 | 11.7 | 16.3 | 20.6 | 29.4 | 38.4 | 47.0 | 59.0 |
| | | | | | $I_{0,max}$ | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 |
| 14L14- | 30.5 | 1350 | 11.8 | 4.30 | M_0 | | | | 20.5 | 30.0 | 34.5 | | | | | |
| | | | | | M_N | | | | 20.5 | 30.0 | 30.5 | | | | | |
| | | | | | $M_{0,max}$ | | | | 48.0 | 61.4 | 77.1 | | | | | |
| | | | | | M_{max} | | | | 48.0 | 61.4 | 77.1 | | | | | |
| | | | | | n_{eto} | | | | - | - | - | | | | | |
| 14L30- | 25.5 | 3000 | 20.8 | 8.00 | M_0 | | | | | | 21.0 | 26.6 | 34.5 | 34.5 | 34.5 | |
| | | | | | M_N | | | | | | 20.0 | 25.3 | 25.5 | 25.5 | 25.5 | |
| | | | | | $M_{0,max}$ | | | | | | 45.0 | 55.3 | 63.9 | 77.1 | 77.1 | |
| | | | | | M_{max} | | | | | | 45.0 | 55.3 | 63.9 | 77.1 | 77.1 | |
| | | | | | n_{eto} | | | | | | - | - | - | - | - | |
| 14P11- | 42.0 | 1050 | 13.4 | 4.60 | M_0 | | | | 26.7 | 36.4 | 43.5 | 43.5 | | | | |
| | | | | | M_N | | | | 24.4 | 36.4 | 42.0 | 42.0 | | | | |
| | | | | | $M_{0,max}$ | | | | 56.1 | 71.7 | 93.3 | 105.1 | | | | |
| | | | | | M_{max} | | | | 56.1 | 71.7 | 93.3 | 105.1 | | | | |
| | | | | | n_{eto} | | | | - | - | - | - | | | | |
| 14P26- | 33.0 | 2625 | 21.9 | 9.10 | M_0 | | | | | | 24.8 | 31.4 | 43.5 | 43.5 | 43.5 | |
| | | | | | M_N | | | | | | 24.6 | 31.0 | 33.0 | 33.0 | 33.0 | |
| | | | | | $M_{0,max}$ | | | | | | 52.5 | 64.6 | 74.7 | 92.2 | 105.1 | |
| | | | | | M_{max} | | | | | | 52.5 | 64.6 | 74.7 | 92.2 | 105.1 | |
| | | | | | n_{eto} | | | | | | - | - | - | - | - | |
| 19F12- | 38.0 | 1200 | 11.3 | 4.80 | M_0 | | | | 29.9 | 39.5 | 41.5 | | | | | |
| | | | | | M_N | | | | 29.3 | 38.0 | 38.0 | | | | | |
| | | | | | $M_{0,max}$ | | | | 62.1 | 78.9 | 86.0 | | | | | |
| | | | | | M_{max} | | | | 62.1 | 78.9 | 86.0 | | | | | |
| | | | | | n_{eto} | | | | - | - | - | | | | | |
| 19F29- | 32.5 | 2850 | 20.1 | 9.70 | M_0 | | | | | | 26.3 | 34.9 | 41.5 | 41.5 | | |
| | | | | | M_N | | | | | | 26.0 | 32.5 | 32.5 | 32.5 | | |
| | | | | | $M_{0,max}$ | | | | | | 56.6 | 70.2 | 81.6 | 86.0 | | |
| | | | | | M_{max} | | | | | | 56.6 | 70.2 | 81.6 | 86.0 | | |
| | | | | | n_{eto} | | | | | | - | - | - | - | | |
| 19J12- | 62.5 | 1200 | 18.3 | 7.90 | M_0 | | | | | | 56.6 | 70.5 | | | | |
| | | | | | M_N | | | | | | 55.7 | 62.5 | | | | |
| | | | | | $M_{0,max}$ | | | | | | 114.4 | 129.0 | | | | |
| | | | | | M_{max} | | | | | | 114.4 | 129.0 | | | | |
| | | | | | n_{eto} | | | | | | - | - | | | | |
| 19J29- | 50.5 | 2850 | 31.0 | 15.10 | M_0 | | | | | | | | 49.2 | 66.7 | 70.5 | |
| | | | | | M_N | | | | | | | | 47.9 | 50.5 | 50.5 | |
| | | | | | $M_{0,max}$ | | | | | | | | 88.9 | 112.9 | 129.0 | |
| | | | | | M_{max} | | | | | | | | 88.9 | 112.9 | 129.0 | |
| | | | | | n_{eto} | | | | | | | | - | - | - | |
| 19P12- | 72.0 | 1200 | 21.3 | 9.00 | M_0 | | | | | | | 79.1 | 86.0 | 86.0 | | |
| | | | | | M_N | | | | | | | 69.6 | 72.0 | 72.0 | | |
| | | | | | $M_{0,max}$ | | | | | | | 159.9 | 186.6 | 190.0 | | |
| | | | | | M_{max} | | | | | | | 159.9 | 186.6 | 190.0 | | |
| | | | | | n_{eto} | | | | | | | - | - | - | | |
| 19P29- | 53.0 | 2850 | 29.5 | 15.80 | M_0 | | | | | | | | 56.5 | 73.9 | 86.0 | 86.0 |
| | | | | | M_N | | | | | | | | 52.8 | 53.0 | 53.0 | 53.0 |
| | | | | | $M_{0,max}$ | | | | | | | | 98.5 | 126.6 | 152.5 | 187.2 |
| | | | | | M_{max} | | | | | | | | 98.5 | 126.6 | 152.5 | 187.2 |
| | | | | | n_{eto} | | | | | | | | - | - | - | - |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MCS synchronous servo motors

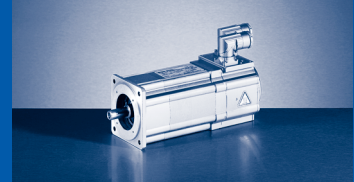
9400 Servo Drives selection tables

Mains connection 3 x 230 V and switching frequency 4 kHz

Motors without blower

| | | | | | E94A□□ | E0024 | E0034 | E0044 | E0074 | E0094 | E0134 | E0174 | E0244 | E0324 |
|--------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 1.9 | 3.1 | 5.0 | 8.8 | 11.7 | 16.3 | 20.6 | 29.4 | 38.4 |
| | | | | | $I_{0,max}$ | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 |
| 06C41L | 0.6 | 4050 | 2.6 | 0.25 | M_0 | 0.6 | 0.8 | | | | | | | |
| | | | | | M_N | 0.5 | 0.6 | | | | | | | |
| | | | | | $M_{0,max}$ | 1.5 | 2.3 | | | | | | | |
| | | | | | M_{max} | 1.5 | 2.3 | | | | | | | |
| | | | | | η_{eto} | - | - | | | | | | | |
| 06C60L | 0.5 | 6000 | 4.0 | 0.31 | M_0 | | 0.6 | 0.8 | 0.8 | | | | | |
| | | | | | M_N | | 0.4 | 0.5 | 0.5 | | | | | |
| | | | | | $M_{0,max}$ | | 1.5 | 2.2 | 2.4 | | | | | |
| | | | | | M_{max} | | 1.5 | 2.2 | 2.4 | | | | | |
| | | | | | η_{eto} | | - | - | - | | | | | |
| 06F41L | 1.2 | 4050 | 2.9 | 0.51 | M_0 | 1.0 | 1.5 | 1.5 | | | | | | |
| | | | | | M_N | 0.8 | 1.2 | 1.2 | | | | | | |
| | | | | | $M_{0,max}$ | 2.7 | 4.2 | 4.4 | | | | | | |
| | | | | | M_{max} | 2.7 | 4.2 | 4.4 | | | | | | |
| | | | | | η_{eto} | - | - | - | | | | | | |
| 06F60L | 0.9 | 6000 | 3.8 | 0.57 | M_0 | | 1.2 | 1.5 | 1.5 | | | | | |
| | | | | | M_N | | 0.8 | 0.9 | 0.9 | | | | | |
| | | | | | $M_{0,max}$ | | 3.1 | 4.3 | 4.4 | | | | | |
| | | | | | M_{max} | | 3.1 | 4.3 | 4.4 | | | | | |
| | | | | | η_{eto} | | - | - | - | | | | | |
| 06I41L | 1.5 | 4050 | 3.2 | 0.64 | M_0 | | 2.0 | 2.0 | | | | | | |
| | | | | | M_N | | 1.5 | 1.5 | | | | | | |
| | | | | | $M_{0,max}$ | | 5.4 | 6.2 | | | | | | |
| | | | | | M_{max} | | 5.4 | 6.2 | | | | | | |
| | | | | | η_{eto} | | - | - | | | | | | |
| 06I60L | 1.2 | 6000 | 3.8 | 0.75 | M_0 | | 1.5 | 2.0 | | | | | | |
| | | | | | M_N | | 1.0 | 1.2 | | | | | | |
| | | | | | $M_{0,max}$ | | 4.4 | 6.2 | | | | | | |
| | | | | | M_{max} | | 4.4 | 6.2 | | | | | | |
| | | | | | η_{eto} | | - | - | | | | | | |
| 09D41L | 2.3 | 4050 | 4.6 | 1.00 | M_0 | | | 3.1 | 3.3 | | | | | |
| | | | | | M_N | | | 2.3 | 2.3 | | | | | |
| | | | | | $M_{0,max}$ | | | 8.0 | 9.5 | | | | | |
| | | | | | M_{max} | | | 8.0 | 9.5 | | | | | |
| | | | | | η_{eto} | | | - | - | | | | | |
| 09D60L | 1.8 | 6000 | 7.0 | 1.10 | M_0 | | | | 2.8 | 3.3 | 3.3 | | | |
| | | | | | M_N | | | | 1.8 | 1.8 | 1.8 | | | |
| | | | | | $M_{0,max}$ | | | | 5.7 | 7.3 | 9.5 | | | |
| | | | | | M_{max} | | | | 5.7 | 7.3 | 9.5 | | | |
| | | | | | η_{eto} | | | | - | - | - | | | |
| 09F38L | 3.1 | 3750 | 5.0 | 1.20 | M_0 | | | 3.5 | 4.2 | 4.2 | 4.2 | | | |
| | | | | | M_N | | | 3.1 | 3.1 | 3.1 | 3.1 | | | |
| | | | | | $M_{0,max}$ | | | 9.8 | 12.0 | 13.8 | 15.0 | | | |
| | | | | | M_{max} | | | 9.8 | 12.0 | 13.8 | 15.0 | | | |
| | | | | | η_{eto} | | | - | - | - | - | | | |
| 09F60L | 2.4 | 6000 | 7.9 | 1.50 | M_0 | | | | 3.5 | 4.2 | 4.2 | 4.2 | 4.2 | |
| | | | | | M_N | | | | 2.4 | 2.4 | 2.4 | 2.4 | 2.4 | |
| | | | | | $M_{0,max}$ | | | | 7.8 | 9.8 | 12.6 | 14.5 | 15.0 | |
| | | | | | M_{max} | | | | 7.8 | 9.8 | 12.6 | 14.5 | 15.0 | |
| | | | | | η_{eto} | | | | - | - | - | - | - | |

► I... [A], M... [Nm], n... [r/min], P... [kW]

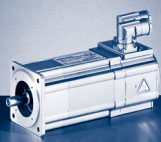


Mains connection 3 x 230 V and switching frequency 4 kHz

Motors without blower

| | | | | | E94A□□ | E0024 | E0034 | E0044 | E0074 | E0094 | E0134 | E0174 | E0244 | E0324 |
|--------|-------|-------|-------|-------|-------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 1.9 | 3.1 | 5.0 | 8.8 | 11.7 | 16.3 | 20.6 | 29.4 | 38.4 |
| | | | | | $I_{0,max}$ | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 |
| 09H41L | 3.8 | 4050 | 6.8 | 1.60 | M_0 | | | | 5.5 | 5.3 | 5.5 | 5.5 | | |
| | | | | | M_N | | | | 3.8 | 3.0 | 3.8 | 3.8 | | |
| | | | | | $M_{0,max}$ | | | | 12.4 | 11.8 | 19.7 | 20.0 | | |
| | | | | | M_{max} | | | | 12.4 | 11.8 | 19.7 | 20.0 | | |
| | | | | | n_{eto} | | | | - | - | - | - | | |
| 09H60L | 3.0 | 6000 | 8.0 | 1.90 | M_0 | | | | 4.0 | 5.5 | 5.5 | 5.5 | 5.5 | |
| | | | | | M_N | | | | 3.0 | 3.8 | 3.0 | 3.0 | 3.0 | |
| | | | | | $M_{0,max}$ | | | | 9.2 | 15.6 | 15.4 | 18.3 | 20.0 | |
| | | | | | M_{max} | | | | 9.2 | 15.6 | 15.4 | 18.3 | 20.0 | |
| | | | | | n_{eto} | | | | - | - | - | - | | |
| 09L41L | 4.5 | 4050 | 8.4 | 1.90 | M_0 | | | | 5.3 | 7.0 | 7.5 | 7.5 | 7.5 | 7.5 |
| | | | | | M_N | | | | 4.5 | 4.5 | 4.5 | 4.5 | 4.5 | 4.5 |
| | | | | | $M_{0,max}$ | | | | 11.9 | 15.5 | 20.9 | 25.8 | 29.7 | 31.9 |
| | | | | | M_{max} | | | | 11.9 | 15.5 | 20.9 | 25.8 | 29.7 | 31.9 |
| | | | | | n_{eto} | | | | - | - | - | - | - | - |
| 12D20L | 5.5 | 1950 | 5.2 | 1.10 | M_0 | | | 5.9 | 6.4 | | | | | |
| | | | | | M_N | | | 5.3 | 5.5 | | | | | |
| | | | | | $M_{0,max}$ | | | 14.9 | 17.7 | | | | | |
| | | | | | M_{max} | | | 14.9 | 17.7 | | | | | |
| | | | | | n_{eto} | | | - | - | | | | | |
| 12D41L | 4.3 | 4050 | 8.8 | 1.80 | M_0 | | | | 5.3 | 6.4 | 6.4 | 6.4 | | |
| | | | | | M_N | | | | 4.3 | 4.3 | 4.3 | 4.3 | | |
| | | | | | $M_{0,max}$ | | | | 10.6 | 13.6 | 17.7 | 17.9 | | |
| | | | | | M_{max} | | | | 10.6 | 13.6 | 17.7 | 17.9 | | |
| | | | | | n_{eto} | | | | - | - | - | - | | |
| 12H15L | 10.0 | 1500 | 7.6 | 1.60 | M_0 | | | | 11.4 | 11.4 | 10.0 | | | |
| | | | | | M_N | | | | 10.0 | 10.0 | 11.4 | | | |
| | | | | | $M_{0,max}$ | | | | 25.8 | 29.0 | 29.0 | | | |
| | | | | | M_{max} | | | | 25.8 | 29.0 | 29.0 | | | |
| | | | | | n_{eto} | | | | - | - | - | | | |
| 12H30L | 8.0 | 3000 | 10.5 | 2.50 | M_0 | | | | 7.4 | 9.8 | 11.4 | | | |
| | | | | | M_N | | | | 6.7 | 8.0 | 8.0 | | | |
| | | | | | $M_{0,max}$ | | | | 16.4 | 21.5 | 29.0 | | | |
| | | | | | M_{max} | | | | 16.4 | 21.5 | 29.0 | | | |
| | | | | | n_{eto} | | | | - | - | - | | | |
| 12L20L | 13.5 | 1950 | 11.8 | 2.80 | M_0 | | | | 10.6 | 14.0 | 15.0 | 15.0 | 15.0 | |
| | | | | | M_N | | | | 10.1 | 13.3 | 13.5 | 13.5 | 13.5 | |
| | | | | | $M_{0,max}$ | | | | 24.4 | 31.5 | 41.8 | 50.5 | 56.0 | |
| | | | | | M_{max} | | | | 24.4 | 31.5 | 41.8 | 50.5 | 56.0 | |
| | | | | | n_{eto} | | | | - | - | - | - | - | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MCS synchronous servo motors

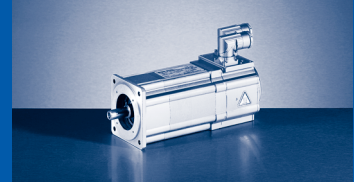
Selection tables for Inverter Drives 8400 TopLine

Mains connection 3 x 400 V and switching frequency 8 kHz

Motors without blower

| | | | | | E84AVTC | □3714 | □5514 | □7514 | □1124 | □1524 | □2224 | □3024 | |
|--------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|-------|-----|
| | | | | | I_N | 1.3 | 1.8 | 2.4 | 3.2 | 3.9 | 5.9 | 7.3 | |
| | | | | | $I_{0,max}$ | 2.0 | 2.7 | 3.6 | 4.8 | 5.9 | 8.4 | 11.0 | |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 2.6 | 3.6 | 4.8 | 6.4 | 7.8 | 11.8 | 14.6 | |
| 06C41- | 0.6 | 4050 | 1.3 | 0.25 | M_0 | 0.8 | 0.8 | 0.8 | 0.8 | 0.8 | | | |
| | | | | | M_N | 0.6 | 0.6 | 0.6 | 0.6 | 0.6 | | | |
| | | | | | $M_{0,max}$ | 1.4 | 1.7 | 2.3 | 2.4 | 2.4 | | | |
| | | | | | M_{max} | 1.4 | 1.7 | 2.3 | 2.4 | 2.4 | | | |
| | | | | | η_{eto} | - | - | - | - | - | | | |
| 06C60- | 0.5 | 6000 | 2.4 | 0.31 | M_0 | | | 0.8 | 0.8 | 0.8 | 0.8 | 0.8 | |
| | | | | | M_N | | | 0.5 | 0.5 | 0.5 | 0.5 | 0.5 | |
| | | | | | $M_{0,max}$ | | | 1.3 | 1.6 | 2.0 | 2.4 | 2.4 | |
| | | | | | M_{max} | | | 1.3 | 1.6 | 2.0 | 2.4 | 2.4 | |
| | | | | | η_{eto} | | | - | - | - | - | - | |
| 06F41- | 1.2 | 4050 | 1.5 | 0.51 | M_0 | 1.3 | 1.5 | 1.5 | 1.5 | 1.5 | | | |
| | | | | | M_N | 1.0 | 1.2 | 1.2 | 1.2 | 1.2 | | | |
| | | | | | $M_{0,max}$ | 2.3 | 3.2 | 4.3 | 4.4 | 4.4 | | | |
| | | | | | M_{max} | 2.3 | 3.2 | 4.3 | 4.4 | 4.4 | | | |
| | | | | | η_{eto} | - | - | - | - | - | | | |
| 06F60- | 0.9 | 6000 | 2.5 | 0.57 | M_0 | | | 1.2 | 1.5 | 1.5 | 1.5 | 1.5 | |
| | | | | | M_N | | | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | |
| | | | | | $M_{0,max}$ | | | 2.1 | 3.3 | 4.0 | 4.4 | 4.4 | |
| | | | | | M_{max} | | | 2.1 | 3.3 | 4.0 | 4.4 | 4.4 | |
| | | | | | η_{eto} | | | - | - | - | - | - | |
| 06I41- | 1.5 | 4050 | 1.6 | 0.64 | M_0 | 1.6 | 2.0 | 2.0 | 2.0 | 2.0 | | | |
| | | | | | M_N | 1.2 | 1.5 | 1.5 | 1.5 | 1.5 | | | |
| | | | | | $M_{0,max}$ | 2.9 | 4.0 | 5.3 | 6.2 | 6.2 | | | |
| | | | | | M_{max} | 2.9 | 4.0 | 5.3 | 6.2 | 6.2 | | | |
| | | | | | η_{eto} | - | - | - | - | - | | | |
| 06I60- | 1.2 | 6000 | 2.9 | 0.75 | M_0 | | | | 2.0 | 2.0 | 2.0 | 2.0 | |
| | | | | | M_N | | | | 1.2 | 1.2 | 1.2 | 1.2 | |
| | | | | | $M_{0,max}$ | | | | 3.6 | 4.4 | 5.7 | 5.7 | |
| | | | | | M_{max} | | | | 3.6 | 4.4 | 5.7 | 5.7 | |
| | | | | | η_{eto} | | | | - | - | - | - | |
| 09D41- | 2.3 | 4050 | 2.3 | 1.00 | M_0 | | 2.2 | 3.1 | 3.3 | 3.3 | 3.3 | 3.3 | |
| | | | | | M_N | | 1.7 | 2.3 | 2.3 | 2.3 | 2.3 | 2.3 | |
| | | | | | $M_{0,max}$ | | 4.0 | 5.3 | 6.7 | 8.2 | 9.4 | 9.4 | |
| | | | | | M_{max} | | 4.0 | 5.3 | 6.7 | 8.2 | 9.4 | 9.4 | |
| | | | | | η_{eto} | | - | - | - | - | - | - | |
| 09D60- | 1.8 | 6000 | 3.8 | 1.10 | M_0 | | | | 2.0 | 2.4 | 3.3 | 3.3 | |
| | | | | | M_N | | | | 1.5 | 1.8 | 1.8 | 1.8 | |
| | | | | | $M_{0,max}$ | | | | 3.5 | 4.2 | 6.3 | 7.8 | |
| | | | | | M_{max} | | | | 3.5 | 4.2 | 6.3 | 7.8 | |
| | | | | | η_{eto} | | | | - | - | - | - | |
| 09F38- | 3.1 | 3750 | 2.5 | 1.20 | M_0 | | | 3.4 | 4.2 | 4.2 | 4.2 | 4.2 | |
| | | | | | M_N | | | 3.0 | 3.1 | 3.1 | 3.1 | 3.1 | |
| | | | | | $M_{0,max}$ | | | 6.6 | 8.4 | 10.2 | 12.0 | 12.0 | |
| | | | | | M_{max} | | | 6.6 | 8.4 | 10.2 | 12.0 | 12.0 | |
| | | | | | η_{eto} | | | - | - | - | - | - | |
| 09F60- | 2.4 | 6000 | 4.5 | 1.50 | M_0 | | | | | | 4.2 | 4.2 | |
| | | | | | M_N | | | | | | | 2.4 | 2.4 |
| | | | | | $M_{0,max}$ | | | | | | | 7.8 | 9.6 |
| | | | | | M_{max} | | | | | | | 7.8 | 9.6 |
| | | | | | η_{eto} | | | | | | | - | - |

► I... [A], M... [Nm], n... [r/min], P... [kW]

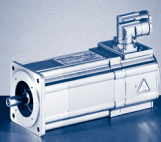


Mains connection 3 x 400 V and switching frequency 8 kHz

Motors without blower

| □4024 | □5524 | □7524 | □1134 | □1534 | □1834 | □2234 | □3034 | E84AVTC | | | | | |
|---------------------------------|---------------------------------|-------|-------|-------|-------|-------|-------|---|-------|-------|-------|-------|--------|
| 9.5 | 13.0 | 16.5 | 23.5 | 32.0 | 39.0 | 47.0 | 61.0 | I_N | P_N | I_N | n_N | M_N | MCS |
| 14.3 | 19.5 | 26.4 | 32.9 | 43.2 | 60.0 | 70.5 | 91.5 | $I_{0,max}$ | | | | | |
| 19.0 | 26.0 | 33.0 | 47.0 | 64.0 | 78.0 | 94.0 | 122.0 | I_{max} | | | | | |
| | | | | | | | | M_0 M_N $M_{0,max}$ M_{max} n_{eto} | | | | | |
| | | | | | | | | M_0 M_N $M_{0,max}$ M_{max} n_{eto} | 0.25 | 1.3 | 4050 | 0.6 | 06C41- |
| | | | | | | | | M_0 M_N $M_{0,max}$ M_{max} n_{eto} | 0.31 | 2.4 | 6000 | 0.5 | 06C60- |
| | | | | | | | | M_0 M_N $M_{0,max}$ M_{max} n_{eto} | 0.51 | 1.5 | 4050 | 1.2 | 06F41- |
| | | | | | | | | M_0 M_N $M_{0,max}$ M_{max} n_{eto} | 0.57 | 2.5 | 6000 | 0.9 | 06F60- |
| | | | | | | | | M_0 M_N $M_{0,max}$ M_{max} n_{eto} | 0.64 | 1.6 | 4050 | 1.5 | 06I41- |
| | | | | | | | | M_0 M_N $M_{0,max}$ M_{max} n_{eto} | 0.75 | 2.9 | 6000 | 1.2 | 06I60- |
| | | | | | | | | M_0 M_N $M_{0,max}$ M_{max} n_{eto} | 1.00 | 2.3 | 4050 | 2.3 | 09D41- |
| 3.3 1.8 9.1 9.1 - | 3.3 1.8 9.3 9.3 - | | | | | | | M_0 M_N $M_{0,max}$ M_{max} n_{eto} | 1.10 | 3.8 | 6000 | 1.8 | 09D60- |
| | | | | | | | | M_0 M_N $M_{0,max}$ M_{max} n_{eto} | 1.20 | 2.5 | 3750 | 3.1 | 09F38- |
| 4.2 2.4 11.1 11.1 - | 4.2 2.4 11.4 11.4 - | | | | | | | M_0 M_N $M_{0,max}$ M_{max} n_{eto} | 1.50 | 4.5 | 6000 | 2.4 | 09F60- |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MCS synchronous servo motors

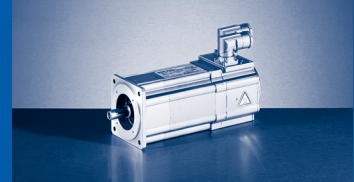
Selection tables for Inverter Drives 8400 TopLine

Mains connection 3 x 400 V and switching frequency 8 kHz

Motors without blower

| | | | | | E84AVTC | □3714 | □5514 | □7514 | □1124 | □1524 | □2224 | □3024 |
|--------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 1.3 | 1.8 | 2.4 | 3.2 | 3.9 | 5.9 | 7.3 |
| | | | | | $I_{0,max}$ | 2.0 | 2.7 | 3.6 | 4.8 | 5.9 | 8.4 | 11.0 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 2.6 | 3.6 | 4.8 | 6.4 | 7.8 | 11.8 | 14.6 |
| 09H41- | 3.8 | 4050 | 3.4 | 1.60 | M_0 | | | | 4.7 | 5.0 | 5.5 | 5.5 |
| | | | | | M_N | | | | 3.6 | 3.8 | 3.8 | 3.8 |
| | | | | | $M_{0,max}$ | | | | 8.1 | 9.9 | 14.0 | 17.4 |
| | | | | | M_{max} | | | | 8.1 | 9.9 | 14.0 | 17.4 |
| | | | | | η_{eto} | | | | - | - | - | - |
| 09H60- | 3.0 | 6000 | 6.0 | 1.90 | M_0 | | | | | | 4.4 | 4.5 |
| | | | | | M_N | | | | | | 3.0 | 3.0 |
| | | | | | $M_{0,max}$ | | | | | | 7.5 | 9.3 |
| | | | | | M_{max} | | | | | | 7.5 | 9.3 |
| | | | | | η_{eto} | | | | | | - | - |
| 09L41- | 4.5 | 4050 | 4.2 | 1.90 | M_0 | | | | 3.9 | 4.7 | 7.5 | 7.5 |
| | | | | | M_N | | | | 3.4 | 4.2 | 4.5 | 4.5 |
| | | | | | $M_{0,max}$ | | | | 7.3 | 8.9 | 13.1 | 16.3 |
| | | | | | M_{max} | | | | 7.3 | 8.9 | 13.1 | 16.3 |
| | | | | | η_{eto} | | | | - | - | - | - |
| 09L51- | 3.6 | 5100 | 6.9 | 1.90 | M_0 | | | | | | | 4.2 |
| | | | | | M_N | | | | | | | 3.6 |
| | | | | | $M_{0,max}$ | | | | | | | 8.3 |
| | | | | | M_{max} | | | | | | | 8.3 |
| | | | | | η_{eto} | | | | | | | - |
| 12D20- | 5.5 | 1950 | 2.6 | 1.10 | M_0 | | | 5.7 | 6.4 | 6.4 | 6.4 | 6.4 |
| | | | | | M_N | | | 5.1 | 5.5 | 5.5 | 5.5 | 5.5 |
| | | | | | $M_{0,max}$ | | | 9.6 | 12.6 | 15.3 | 17.7 | 17.7 |
| | | | | | M_{max} | | | 9.6 | 12.6 | 15.3 | 17.7 | 17.7 |
| | | | | | η_{eto} | | | - | - | - | - | - |
| 12D41- | 4.3 | 4050 | 4.5 | 1.80 | M_0 | | | | 3.8 | 4.6 | 6.4 | 6.4 |
| | | | | | M_N | | | | 3.0 | 3.7 | 4.3 | 4.3 |
| | | | | | $M_{0,max}$ | | | | 6.4 | 7.8 | 11.4 | 14.0 |
| | | | | | M_{max} | | | | 6.4 | 7.8 | 11.4 | 14.0 |
| | | | | | η_{eto} | | | | - | - | - | - |
| 12H15- | 10.0 | 1500 | 3.8 | 1.60 | M_0 | | | | 9.2 | 10.9 | 11.4 | 11.4 |
| | | | | | M_N | | | | 8.4 | 10.0 | 10.0 | 10.0 |
| | | | | | $M_{0,max}$ | | | | 16.4 | 20.0 | 29.0 | 29.0 |
| | | | | | M_{max} | | | | 16.4 | 20.0 | 29.0 | 29.0 |
| | | | | | η_{eto} | | | | - | - | - | - |
| 12H35- | 7.5 | 3525 | 5.7 | 2.80 | M_0 | | | | | | 9.8 | 9.8 |
| | | | | | M_N | | | | | | 7.5 | 7.5 |
| | | | | | $M_{0,max}$ | | | | | | 15.2 | 18.8 |
| | | | | | M_{max} | | | | | | 15.2 | 18.8 |
| | | | | | η_{eto} | | | | | | - | - |
| 12L20- | 13.5 | 1950 | 5.9 | 2.80 | M_0 | | | | | | 15.0 | 15.0 |
| | | | | | M_N | | | | | | 13.5 | 13.5 |
| | | | | | $M_{0,max}$ | | | | | | 27.4 | 33.9 |
| | | | | | M_{max} | | | | | | 27.4 | 33.9 |
| | | | | | η_{eto} | | | | | | - | - |
| 12L41- | 11.0 | 4050 | 10.2 | 4.70 | M_0 | | | | | | | |
| | | | | | M_N | | | | | | | |
| | | | | | $M_{0,max}$ | | | | | | | |
| | | | | | M_{max} | | | | | | | |
| | | | | | η_{eto} | | | | | | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

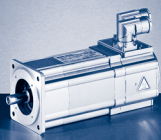


Mains connection 3 x 400 V and switching frequency 8 kHz

Motors without blower

| □4024 | □5524 | □7524 | □1134 | □1534 | □1834 | □2234 | □3034 | E84AVTC | | | | | |
|-------|-------|-------|-------|-------|-------|-------|--------------|-------------|-------|-------|-------|-------|--------|
| 9.5 | 13.0 | 16.5 | 23.5 | 32.0 | 39.0 | 47.0 | 61.0 | I_N | | | | | |
| 14.3 | 19.5 | 26.4 | 32.9 | 43.2 | 60.0 | 70.5 | 91.5 | $I_{0,max}$ | | | | | |
| 19.0 | 26.0 | 33.0 | 47.0 | 64.0 | 78.0 | 94.0 | 122.0 | I_{max} | P_N | I_N | n_N | M_N | MCS |
| 5.5 | 5.5 | | | | | | | M_0 | 1.60 | 3.4 | 4050 | 3.8 | 09H41- |
| 3.8 | 3.8 | | | | | | M_N | | | | | | |
| 19.6 | 20.1 | | | | | | $M_{0,max}$ | | | | | | |
| 19.6 | 20.1 | | | | | | M_{max} | | | | | | |
| - | - | | | | | | η_{eto} | | | | | | |
| 5.5 | 5.5 | | | | | | | M_0 | 1.90 | 6.0 | 6000 | 3.0 | 09H60- |
| 3.0 | 3.0 | | | | | | M_N | | | | | | |
| 11.4 | 11.7 | | | | | | $M_{0,max}$ | | | | | | |
| 11.4 | 11.7 | | | | | | M_{max} | | | | | | |
| - | - | | | | | | η_{eto} | | | | | | |
| 7.5 | 7.5 | | | | | | | M_0 | 1.90 | 4.2 | 4050 | 4.5 | 09L41- |
| 4.5 | 4.5 | | | | | | M_N | | | | | | |
| 20.3 | 20.8 | | | | | | $M_{0,max}$ | | | | | | |
| 20.3 | 20.8 | | | | | | M_{max} | | | | | | |
| - | - | | | | | | η_{eto} | | | | | | |
| 7.5 | 7.5 | 7.5 | 7.5 | | | | | M_0 | 1.90 | 6.9 | 5100 | 3.6 | 09L51- |
| 3.6 | 3.6 | 3.6 | 3.6 | | | | M_N | | | | | | |
| 10.8 | 19.1 | 19.1 | 19.1 | | | | $M_{0,max}$ | | | | | | |
| 10.8 | 19.1 | 19.1 | 19.1 | | | | M_{max} | | | | | | |
| - | - | - | - | | | | η_{eto} | | | | | | |
| | | | | | | | | M_0 | 1.10 | 2.6 | 1950 | 5.5 | 12D20- |
| | | | | | | | M_N | | | | | | |
| | | | | | | | $M_{0,max}$ | | | | | | |
| | | | | | | | M_{max} | | | | | | |
| | | | | | | | η_{eto} | | | | | | |
| 6.4 | 6.4 | | | | | | | M_0 | 1.80 | 4.5 | 4050 | 4.3 | 12D41- |
| 4.3 | 4.3 | | | | | | M_N | | | | | | |
| 16.9 | 17.3 | | | | | | $M_{0,max}$ | | | | | | |
| 16.9 | 17.3 | | | | | | M_{max} | | | | | | |
| - | - | | | | | | η_{eto} | | | | | | |
| 11.4 | 11.4 | | | | | | | M_0 | 1.60 | 3.8 | 1500 | 10.0 | 12H15- |
| 10.0 | 10.0 | | | | | | M_N | | | | | | |
| 28.3 | 29.0 | | | | | | $M_{0,max}$ | | | | | | |
| 28.3 | 29.0 | | | | | | M_{max} | | | | | | |
| - | - | | | | | | η_{eto} | | | | | | |
| 11.4 | 11.4 | | | | | | | M_0 | 2.80 | 5.7 | 3525 | 7.5 | 12H35- |
| 7.5 | 7.5 | | | | | | M_N | | | | | | |
| 23.5 | 24.1 | | | | | | $M_{0,max}$ | | | | | | |
| 23.5 | 24.1 | | | | | | M_{max} | | | | | | |
| - | - | | | | | | η_{eto} | | | | | | |
| 15.0 | 15.0 | | | | | | | M_0 | 2.80 | 5.9 | 1950 | 13.5 | 12L20- |
| 13.5 | 13.5 | | | | | | M_N | | | | | | |
| 40.8 | 41.9 | | | | | | $M_{0,max}$ | | | | | | |
| 40.8 | 41.9 | | | | | | M_{max} | | | | | | |
| - | - | | | | | | η_{eto} | | | | | | |
| 14.0 | 15.0 | 15.0 | 15.0 | 15.0 | | | | M_0 | 4.70 | 10.2 | 4050 | 11.0 | 12L41- |
| 10.2 | 11.0 | 11.0 | 11.0 | 11.0 | | | M_N | | | | | | |
| 22.2 | 30.4 | 35.5 | 35.5 | 35.5 | | | $M_{0,max}$ | | | | | | |
| 22.2 | 30.4 | 49.6 | 49.6 | 49.6 | | | M_{max} | | | | | | |
| - | - | - | - | - | | | η_{eto} | | | | | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MCS synchronous servo motors

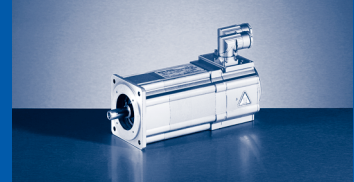
Selection tables for Inverter Drives 8400 TopLine

Mains connection 3 x 400 V and switching frequency 8 kHz

Motors without blower

| | | | | | E84AVTC | □3714 | □5514 | □7514 | □1124 | □1524 | □2224 | □3024 |
|--------|-------|-------|-------|-------|-------------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 1.3 | 1.8 | 2.4 | 3.2 | 3.9 | 5.9 | 7.3 |
| | | | | | $I_{0,max}$ | 2.0 | 2.7 | 3.6 | 4.8 | 5.9 | 8.4 | 11.0 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 2.6 | 3.6 | 4.8 | 6.4 | 7.8 | 11.8 | 14.6 |
| 14D15- | 9.2 | 1500 | 4.5 | 1.45 | M_0 | | | | 7.0 | 8.5 | 11.0 | 11.0 |
| | | | | | M_N | | | | 6.6 | 8.0 | 9.2 | 9.2 |
| | | | | | $M_{0,max}$ | | | | 13.1 | 16.0 | 22.7 | 28.1 |
| | | | | | M_{max} | | | | 13.1 | 16.0 | 22.7 | 28.1 |
| | | | | | n_{eto} | | | | - | - | - | - |
| 14D36- | 7.5 | 3600 | 7.5 | 2.80 | M_0 | | | | | | | 8.0 |
| | | | | | M_N | | | | | | | 7.3 |
| | | | | | $M_{0,max}$ | | | | | | | 15.2 |
| | | | | | M_{max} | | | | | | | 15.2 |
| | | | | | n_{eto} | | | | | | | - |
| 14H15- | 16.0 | 1500 | 6.6 | 2.50 | M_0 | | | | | | | 17.3 |
| | | | | | M_N | | | | | | | 16.0 |
| | | | | | $M_{0,max}$ | | | | | | | 35.3 |
| | | | | | M_{max} | | | | | | | 35.3 |
| | | | | | n_{eto} | | | | | | | - |
| 14H32- | 14.0 | 3225 | 11.9 | 4.70 | M_0 | | | | | | | |
| | | | | | M_N | | | | | | | |
| | | | | | $M_{0,max}$ | | | | | | | |
| | | | | | M_{max} | | | | | | | |
| | | | | | n_{eto} | | | | | | | |
| 14L15- | 23.0 | 1500 | 9.7 | 3.60 | M_0 | | | | | | | |
| | | | | | M_N | | | | | | | |
| | | | | | $M_{0,max}$ | | | | | | | |
| | | | | | M_{max} | | | | | | | |
| | | | | | n_{eto} | | | | | | | |
| 14L32- | 17.2 | 3225 | 15.0 | 5.80 | M_0 | | | | | | | |
| | | | | | M_N | | | | | | | |
| | | | | | $M_{0,max}$ | | | | | | | |
| | | | | | M_{max} | | | | | | | |
| | | | | | n_{eto} | | | | | | | |
| 14P14- | 30.0 | 1350 | 10.8 | 4.20 | M_0 | | | | | | | |
| | | | | | M_N | | | | | | | |
| | | | | | $M_{0,max}$ | | | | | | | |
| | | | | | M_{max} | | | | | | | |
| | | | | | n_{eto} | | | | | | | |
| 14P32- | 21.0 | 3225 | 15.6 | 7.10 | M_0 | | | | | | | |
| | | | | | M_N | | | | | | | |
| | | | | | $M_{0,max}$ | | | | | | | |
| | | | | | M_{max} | | | | | | | |
| | | | | | n_{eto} | | | | | | | |
| 19F14- | 27.0 | 1425 | 8.6 | 4.00 | M_0 | | | | | | | 23.6 |
| | | | | | M_N | | | | | | | 22.9 |
| | | | | | $M_{0,max}$ | | | | | | | 45.9 |
| | | | | | M_{max} | | | | | | | 45.9 |
| | | | | | n_{eto} | | | | | | | - |
| 19F30- | 21.0 | 3000 | 14.0 | 6.60 | M_0 | | | | | | | |
| | | | | | M_N | | | | | | | |
| | | | | | $M_{0,max}$ | | | | | | | |
| | | | | | M_{max} | | | | | | | |
| | | | | | n_{eto} | | | | | | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

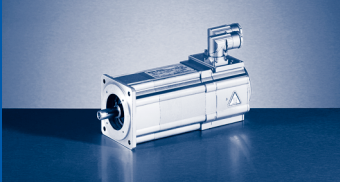


Mains connection 3 x 400 V and switching frequency 8 kHz

Motors without blower

| □4024 | □5524 | □7524 | □1134 | □1534 | □1834 | □2234 | □3034 | E84AVTC | | | | | |
|-------|-------|-------|-------|-------|-------|-------|-------------|-------------|-------|-------|-------|-------|--------|
| 9.5 | 13.0 | 16.5 | 23.5 | 32.0 | 39.0 | 47.0 | 61.0 | I_N | | | | | |
| 14.3 | 19.5 | 26.4 | 32.9 | 43.2 | 60.0 | 70.5 | 91.5 | $I_{0,max}$ | | | | | |
| 19.0 | 26.0 | 33.0 | 47.0 | 64.0 | 78.0 | 94.0 | 122.0 | I_{max} | P_N | I_N | n_N | M_N | MCS |
| 11.0 | 11.0 | | | | | | | M_0 | 1.45 | 4.5 | 1500 | 9.2 | 14D15- |
| 9.2 | 9.2 | | | | | | M_N | | | | | | |
| 28.3 | 29.0 | | | | | | $M_{0,max}$ | | | | | | |
| 28.3 | 29.0 | | | | | | M_{max} | | | | | | |
| - | - | | | | | | n_{eto} | | | | | | |
| 11.0 | 11.0 | 11.0 | 11.0 | | | | | M_0 | 2.80 | 7.5 | 3600 | 7.5 | 14D36- |
| 7.5 | 7.5 | 7.5 | 7.5 | | | | M_N | | | | | | |
| 18.5 | 25.3 | 29.0 | 29.0 | | | | $M_{0,max}$ | | | | | | |
| 18.5 | 22.2 | 22.2 | 22.2 | | | | M_{max} | | | | | | |
| - | - | - | - | | | | n_{eto} | | | | | | |
| 21.0 | 21.0 | | | | | | | M_0 | 2.50 | 6.6 | 1500 | 16.0 | 14H15- |
| 16.0 | 16.0 | | | | | | M_N | | | | | | |
| 42.8 | 43.9 | | | | | | $M_{0,max}$ | | | | | | |
| 42.8 | 43.9 | | | | | | M_{max} | | | | | | |
| - | - | | | | | | n_{eto} | | | | | | |
| 12.9 | 16.2 | 21.0 | 21.0 | 21.0 | | | | M_0 | 4.70 | 11.9 | 3225 | 14.0 | 14H32- |
| 11.2 | 14.0 | 14.0 | 14.0 | 14.0 | | | M_N | | | | | | |
| 23.2 | 31.7 | 37.1 | 37.1 | 37.1 | | | $M_{0,max}$ | | | | | | |
| 23.2 | 31.7 | 51.9 | 51.9 | 51.9 | | | M_{max} | | | | | | |
| - | - | - | - | - | | | n_{eto} | | | | | | |
| 27.4 | 28.0 | 28.0 | 28.0 | | | | | M_0 | 3.60 | 9.7 | 1500 | 23.0 | 14L15- |
| 22.5 | 23.0 | 23.0 | 23.0 | | | | M_N | | | | | | |
| 43.8 | 52.9 | 52.9 | 52.9 | | | | $M_{0,max}$ | | | | | | |
| 43.8 | 60.0 | 73.8 | 73.8 | | | | M_{max} | | | | | | |
| - | - | - | - | | | | n_{eto} | | | | | | |
| | 15.2 | 27.4 | 27.4 | 28.0 | 28.0 | 28.0 | | M_0 | 5.80 | 15.0 | 3225 | 17.2 | 14L32- |
| | 14.9 | 17.2 | 17.2 | 17.2 | 17.2 | 17.2 | M_N | | | | | | |
| | 31.3 | 39.7 | 52.9 | 52.9 | 52.9 | 52.9 | $M_{0,max}$ | | | | | | |
| | 31.3 | 57.6 | 73.9 | 73.9 | 73.9 | 73.9 | M_{max} | | | | | | |
| | - | - | - | - | - | - | n_{eto} | | | | | | |
| 32.5 | 37.0 | 37.0 | 37.0 | 37.0 | | | | M_0 | 4.20 | 10.8 | 1350 | 30.0 | 14P14- |
| 26.4 | 30.0 | 30.0 | 30.0 | 30.0 | | | M_N | | | | | | |
| 51.2 | 70.0 | 80.0 | 80.0 | 80.0 | | | $M_{0,max}$ | | | | | | |
| 51.2 | 70.0 | 105.1 | 105.1 | 105.1 | | | M_{max} | | | | | | |
| - | - | - | - | - | | | n_{eto} | | | | | | |
| | 19.8 | 35.8 | 35.8 | 37.0 | 37.0 | 37.0 | | M_0 | 7.10 | 15.6 | 3225 | 21.0 | 14P32- |
| | 17.5 | 21.0 | 21.0 | 21.0 | 21.0 | 21.0 | M_N | | | | | | |
| | 36.5 | 46.3 | 61.8 | 61.8 | 61.8 | 61.8 | $M_{0,max}$ | | | | | | |
| | 36.5 | 67.3 | 86.4 | 86.4 | 86.4 | 86.4 | M_{max} | | | | | | |
| | - | - | - | - | - | - | n_{eto} | | | | | | |
| 32.0 | 32.0 | 32.0 | 32.0 | | | | | M_0 | 4.00 | 8.6 | 1425 | 27.0 | 19F14- |
| 27.0 | 27.0 | 27.0 | 27.0 | | | | M_N | | | | | | |
| 56.7 | 68.3 | 68.3 | 68.3 | | | | $M_{0,max}$ | | | | | | |
| 56.7 | 77.6 | 86.0 | 86.0 | | | | M_{max} | | | | | | |
| - | - | - | - | | | | n_{eto} | | | | | | |
| | 21.0 | 32.0 | 32.0 | 32.0 | | | | M_0 | 6.60 | 14.0 | 3000 | 21.0 | 19F30- |
| | 19.5 | 21.0 | 21.0 | 21.0 | | | M_N | | | | | | |
| | 47.2 | 47.2 | 47.2 | 47.2 | | | $M_{0,max}$ | | | | | | |
| | 38.9 | 68.3 | 68.3 | 68.3 | | | M_{max} | | | | | | |
| | - | - | - | - | | | n_{eto} | | | | | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MCS synchronous servo motors

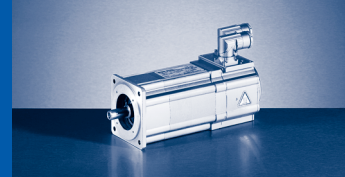
Selection tables for Inverter Drives 8400 TopLine

**Mains connection 3 x 400 V and switching frequency
8 kHz**

Motors without blower

| | | | | | E84AVTC | □3714 | □5514 | □7514 | □1124 | □1524 | □2224 | □3024 |
|--------|-------|-------|-------|-------|-------------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 1.3 | 1.8 | 2.4 | 3.2 | 3.9 | 5.9 | 7.3 |
| | | | | | $I_{0,max}$ | 2.0 | 2.7 | 3.6 | 4.8 | 5.9 | 8.4 | 11.0 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 2.6 | 3.6 | 4.8 | 6.4 | 7.8 | 11.8 | 14.6 |
| 19J14- | 40.0 | 1425 | 12.3 | 6.00 | M_0 | | | | | | | |
| | | | | | M_N | | | | | | | |
| | | | | | $M_{0,max}$ | | | | | | | |
| | | | | | M_{max} | | | | | | | |
| | | | | | n_{eto} | | | | | | | |
| 19J30- | 29.0 | 3000 | 18.5 | 9.10 | M_0 | | | | | | | |
| | | | | | M_N | | | | | | | |
| | | | | | $M_{0,max}$ | | | | | | | |
| | | | | | M_{max} | | | | | | | |
| | | | | | n_{eto} | | | | | | | |
| 19P14- | 51.0 | 1350 | 14.3 | 7.20 | M_0 | | | | | | | |
| | | | | | M_N | | | | | | | |
| | | | | | $M_{0,max}$ | | | | | | | |
| | | | | | M_{max} | | | | | | | |
| | | | | | n_{eto} | | | | | | | |
| 19P30- | 32.0 | 3000 | 19.0 | 10.00 | M_0 | | | | | | | |
| | | | | | M_N | | | | | | | |
| | | | | | $M_{0,max}$ | | | | | | | |
| | | | | | M_{max} | | | | | | | |
| | | | | | n_{eto} | | | | | | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

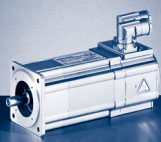


Mains connection 3 x 400 V and switching frequency 8 kHz

Motors without blower

| □4024 | □5524 | □7524 | □1134 | □1534 | □1834 | □2234 | □3034 | E84AVTC | | | | | |
|-------|-------|-------|-------|-------|-------|-------|-------|-------------|-------|-------|-------|-------|--------|
| 9.5 | 13.0 | 16.5 | 23.5 | 32.0 | 39.0 | 47.0 | 61.0 | I_N | | | | | |
| 14.3 | 19.5 | 26.4 | 32.9 | 43.2 | 60.0 | 70.5 | 91.5 | $I_{0,max}$ | | | | | |
| 19.0 | 26.0 | 33.0 | 47.0 | 64.0 | 78.0 | 94.0 | 122.0 | I_{max} | P_N | I_N | n_N | M_N | MCS |
| | 43.6 | 51.0 | 51.0 | 51.0 | | | | M_0 | 6.00 | 12.3 | 1425 | 40.0 | 19J14- |
| | 40.0 | 40.0 | 40.0 | 40.0 | | | | M_N | | | | | |
| | 81.1 | 96.0 | 96.0 | 96.0 | | | | $M_{0,max}$ | | | | | |
| | 81.1 | 129.0 | 129.0 | 129.0 | | | | M_{max} | | | | | |
| | - | - | - | - | | | | n_{eto} | | | | | |
| | | | 39.3 | 51.0 | 51.0 | 51.0 | 51.0 | M_0 | 9.10 | 18.5 | 3000 | 29.0 | 19J30- |
| | | | 29.0 | 29.0 | 29.0 | 29.0 | 29.0 | M_N | | | | | |
| | | | 73.6 | 79.5 | 79.5 | 79.5 | 79.5 | $M_{0,max}$ | | | | | |
| | | | 110.4 | 127.6 | 127.6 | 127.6 | 127.6 | M_{max} | | | | | |
| | | | - | - | - | - | - | n_{eto} | | | | | |
| | 47.5 | 64.0 | 64.0 | 64.0 | | | | M_0 | 7.20 | 14.3 | 1350 | 51.0 | 19P14- |
| | 46.4 | 51.0 | 51.0 | 51.0 | | | | M_N | | | | | |
| | 92.7 | 106.7 | 106.7 | 106.7 | | | | $M_{0,max}$ | | | | | |
| | 92.7 | 155.5 | 155.5 | 155.5 | | | | M_{max} | | | | | |
| | - | - | - | - | | | | n_{eto} | | | | | |
| | | | 43.1 | 58.7 | 64.0 | 64.0 | 64.0 | M_0 | 10.00 | 19.0 | 3000 | 32.0 | 19P30- |
| | | | 32.0 | 32.0 | 32.0 | 32.0 | 32.0 | M_N | | | | | |
| | | | 79.2 | 87.6 | 87.6 | 87.6 | 87.6 | $M_{0,max}$ | | | | | |
| | | | 118.6 | 144.3 | 144.3 | 144.3 | 144.3 | M_{max} | | | | | |
| | | | - | - | - | - | - | n_{eto} | | | | | |

► I... [A], M... [Nm], n... [r/min], P... [kW]



MCS synchronous servo motors

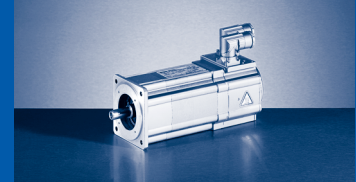
Selection tables for Inverter Drives 8400 TopLine

Mains connection 3 x 400 V and switching frequency 8 kHz

Motors with blower

| | | | | | E84AVTC | □1124 | □1524 | □2224 | □3024 | □4024 | □5524 | □7524 | □1134 | □1534 | □1834 | □2234 | □3034 |
|--------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 3.2 | 3.9 | 5.9 | 7.3 | 9.5 | 13.0 | 16.5 | 23.5 | 32.0 | 39.0 | 47.0 | 61.0 |
| | | | | | $I_{0,max}$ | 4.8 | 5.9 | 8.4 | 11.0 | 14.3 | 19.5 | 26.4 | 32.9 | 43.2 | 60.0 | 70.5 | 91.5 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 6.4 | 7.8 | 11.8 | 14.6 | 19.0 | 26.0 | 33.0 | 47.0 | 64.0 | 78.0 | 94.0 | 122.0 |
| 12D17- | 7.0 | 1650 | 3.0 | 1.20 | M_0 | 7.5 | 7.5 | 7.5 | 7.5 | | | | | | | | |
| | | | | | M_N | 7.0 | 7.0 | 7.0 | 7.0 | | | | | | | | |
| | | | | | $M_{0,max}$ | 12.6 | 15.3 | 17.7 | 17.7 | | | | | | | | |
| | | | | | M_{max} | 12.6 | 15.3 | 17.7 | 17.7 | | | | | | | | |
| | | | | | η_{eto} | - | - | - | - | | | | | | | | |
| 12D35- | 6.0 | 3525 | 5.6 | 2.20 | M_0 | | 4.6 | 7.5 | 7.5 | 7.5 | 7.5 | | | | | | |
| | | | | | M_N | | 3.7 | 6.0 | 6.0 | 6.0 | 6.0 | | | | | | |
| | | | | | $M_{0,max}$ | | 7.8 | 11.4 | 14.0 | 16.9 | 17.3 | | | | | | |
| | | | | | M_{max} | | 7.8 | 11.4 | 14.0 | 16.9 | 17.3 | | | | | | |
| | | | | | η_{eto} | | - | - | - | - | - | | | | | | |
| 12H14- | 12.0 | 1350 | 4.1 | 1.70 | M_0 | 8.9 | 10.9 | 12.8 | 12.8 | 12.8 | 12.8 | | | | | | |
| | | | | | M_N | 8.5 | 10.3 | 12.0 | 12.0 | 12.0 | 12.0 | | | | | | |
| | | | | | $M_{0,max}$ | 16.4 | 20.0 | 29.0 | 29.0 | 28.3 | 29.0 | | | | | | |
| | | | | | M_{max} | 16.4 | 20.0 | 29.0 | 29.0 | 28.3 | 29.0 | | | | | | |
| | | | | | η_{eto} | - | - | - | - | - | - | | | | | | |
| 12H34- | 10.5 | 3375 | 7.5 | 3.70 | M_0 | | | | 10.2 | 12.8 | 12.8 | | | | | | |
| | | | | | M_N | | | | 10.0 | 10.5 | 10.5 | | | | | | |
| | | | | | $M_{0,max}$ | | | | 18.8 | 23.5 | 24.1 | | | | | | |
| | | | | | M_{max} | | | | 18.8 | 23.5 | 24.1 | | | | | | |
| | | | | | η_{eto} | | | | - | - | - | | | | | | |
| 12L17- | 17.0 | 1650 | 6.7 | 2.90 | M_0 | | | | 18.5 | 19.0 | 19.0 | | | | | | |
| | | | | | M_N | | | | 17.0 | 17.0 | 17.0 | | | | | | |
| | | | | | $M_{0,max}$ | | | | 33.9 | 40.8 | 41.9 | | | | | | |
| | | | | | M_{max} | | | | 33.9 | 40.8 | 41.9 | | | | | | |
| | | | | | η_{eto} | | | | - | - | - | | | | | | |
| 12L39- | 14.0 | 3900 | 11.7 | 5.70 | M_0 | | | | | 17.2 | 17.2 | 19.0 | 19.0 | 19.0 | | | |
| | | | | | M_N | | | | 14.0 | 14.0 | 14.0 | 14.0 | 14.0 | | | | |
| | | | | | $M_{0,max}$ | | | | 22.2 | 30.4 | 35.5 | 35.5 | 35.5 | | | | |
| | | | | | M_{max} | | | | 22.2 | 30.4 | 49.6 | 49.6 | 49.6 | | | | |
| | | | | | η_{eto} | | | | - | - | - | - | - | | | | |
| 14D14- | 12.0 | 1350 | 5.4 | 1.70 | M_0 | | 8.5 | 12.5 | 12.5 | 12.5 | 12.5 | | | | | | |
| | | | | | M_N | | 8.0 | 12.0 | 12.0 | 12.0 | 12.0 | | | | | | |
| | | | | | $M_{0,max}$ | | 16.0 | 22.7 | 28.1 | 28.3 | 29.0 | | | | | | |
| | | | | | M_{max} | | 16.0 | 22.7 | 28.1 | 28.3 | 29.0 | | | | | | |
| | | | | | η_{eto} | | - | - | - | - | - | | | | | | |
| 14D30- | 10.5 | 3000 | 9.7 | 3.30 | M_0 | | | | 7.7 | 12.2 | 12.5 | 12.5 | 12.5 | | | | |
| | | | | | M_N | | | | 7.0 | 9.8 | 10.0 | 10.0 | 10.0 | | | | |
| | | | | | $M_{0,max}$ | | | | 15.2 | 18.5 | 25.3 | 29.0 | 29.0 | | | | |
| | | | | | M_{max} | | | | 15.2 | 18.5 | 22.2 | 22.2 | 22.2 | | | | |
| | | | | | η_{eto} | | | | - | - | - | - | - | | | | |
| 14H12- | 23.5 | 1200 | 8.3 | 3.00 | M_0 | | | | 18.0 | 25.5 | 25.5 | | | | | | |
| | | | | | M_N | | | | 17.9 | 23.5 | 23.5 | | | | | | |
| | | | | | $M_{0,max}$ | | | | 35.3 | 42.8 | 43.9 | | | | | | |
| | | | | | M_{max} | | | | 35.3 | 42.8 | 43.9 | | | | | | |
| | | | | | η_{eto} | | | | - | - | - | | | | | | |
| 14H28- | 20.5 | 2775 | 15.0 | 6.00 | M_0 | | | | | | 16.2 | 25.5 | 25.5 | 25.5 | | | |
| | | | | | M_N | | | | | | 16.1 | 20.5 | 20.5 | 20.5 | | | |
| | | | | | $M_{0,max}$ | | | | | | 31.7 | 37.1 | 37.1 | 37.1 | | | |
| | | | | | M_{max} | | | | | | 31.7 | 51.9 | 51.9 | 51.9 | | | |
| | | | | | η_{eto} | | | | | | - | - | - | - | | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

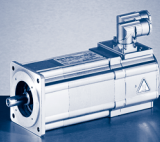


Mains connection 3 x 400 V and switching frequency 8 kHz

Motors with blower

| | | | | | E84AVTC | □1124 | □1524 | □2224 | □3024 | □4024 | □5524 | □7524 | □1134 | □1534 | □1834 | □2234 | □3034 |
|--------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 3.2 | 3.9 | 5.9 | 7.3 | 9.5 | 13.0 | 16.5 | 23.5 | 32.0 | 39.0 | 47.0 | 61.0 |
| | | | | | $I_{0,max}$ | 4.8 | 5.9 | 8.4 | 11.0 | 14.3 | 19.5 | 26.4 | 32.9 | 43.2 | 60.0 | 70.5 | 91.5 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 6.4 | 7.8 | 11.8 | 14.6 | 19.0 | 26.0 | 33.0 | 47.0 | 64.0 | 78.0 | 94.0 | 122.0 |
| 14L14- | 30.5 | 1350 | 11.8 | 4.30 | M_0 | | | | | 26.9 | 33.4 | 34.5 | 34.5 | | | | |
| | | | | | M_N | | | | 24.6 | 30.5 | 30.5 | 30.5 | | | | | |
| | | | | | $M_{0,max}$ | | | | 43.8 | 52.9 | 52.9 | 52.9 | | | | | |
| | | | | | M_{max} | | | | 43.8 | 60.0 | 73.8 | 73.8 | | | | | |
| | | | | | η_{eto} | | | | - | - | - | - | | | | | |
| 14L30- | 25.5 | 3000 | 20.8 | 8.00 | M_0 | | | | | | | | 27.4 | 34.5 | 34.5 | 34.5 | |
| | | | | | M_N | | | | | | | 25.5 | 25.5 | 25.5 | 25.5 | | |
| | | | | | $M_{0,max}$ | | | | | | | 52.9 | 52.9 | 52.9 | 52.9 | | |
| | | | | | M_{max} | | | | | | | 73.9 | 73.9 | 73.9 | 73.9 | | |
| | | | | | η_{eto} | | | | | | | - | - | - | - | | |
| 14P11- | 42.0 | 1050 | 13.4 | 4.60 | M_0 | | | | | | 38.9 | 43.5 | 43.5 | 43.5 | | | |
| | | | | | M_N | | | | | | 38.8 | 42.0 | 42.0 | 42.0 | | | |
| | | | | | $M_{0,max}$ | | | | | | 70.0 | 80.0 | 80.0 | 80.0 | | | |
| | | | | | M_{max} | | | | | | 70.0 | 105.1 | 105.1 | 105.1 | | | |
| | | | | | η_{eto} | | | | | | - | - | - | - | | | |
| 14P26- | 33.0 | 2625 | 21.9 | 9.10 | M_0 | | | | | | | | 35.8 | 43.5 | 43.5 | 43.5 | |
| | | | | | M_N | | | | | | | 33.0 | 33.0 | 33.0 | 33.0 | | |
| | | | | | $M_{0,max}$ | | | | | | | 66.0 | 86.4 | 86.4 | 86.4 | | |
| | | | | | M_{max} | | | | | | | 86.4 | 86.4 | 86.4 | 86.4 | | |
| | | | | | η_{eto} | | | | | | | - | - | - | - | | |
| 19F12- | 38.0 | 1200 | 11.3 | 4.80 | M_0 | | | 23.6 | 34.9 | 41.5 | 41.5 | 41.5 | | | | | |
| | | | | | M_N | | | 22.9 | 31.9 | 38.0 | 38.0 | 38.0 | | | | | |
| | | | | | $M_{0,max}$ | | | 45.9 | 56.7 | 68.3 | 68.3 | 68.3 | | | | | |
| | | | | | M_{max} | | | 45.9 | 56.7 | 77.6 | 86.0 | 86.0 | | | | | |
| | | | | | η_{eto} | | | - | - | - | - | - | | | | | |
| 19F29- | 32.5 | 2850 | 20.1 | 9.70 | M_0 | | | | | | | | 39.9 | 41.5 | | | |
| | | | | | M_N | | | | | | | 32.5 | 32.5 | | | | |
| | | | | | $M_{0,max}$ | | | | | | | 47.2 | 47.2 | | | | |
| | | | | | M_{max} | | | | | | | 68.3 | 68.3 | | | | |
| | | | | | η_{eto} | | | | | | | - | - | | | | |
| 19J12- | 62.5 | 1200 | 18.3 | 7.90 | M_0 | | | | | | 43.6 | | 70.5 | 70.5 | | | |
| | | | | | M_N | | | | | | 43.4 | 62.5 | 62.5 | | | | |
| | | | | | $M_{0,max}$ | | | | | | 81.1 | 96.0 | 96.0 | | | | |
| | | | | | M_{max} | | | | | | 81.1 | 129.0 | 129.0 | | | | |
| | | | | | η_{eto} | | | | | | - | - | - | | | | |
| 19J29- | 50.5 | 2850 | 31.0 | 15.10 | M_0 | | | | | | | | | 55.5 | 70.5 | 70.5 | 70.5 |
| | | | | | M_N | | | | | | | 50.5 | 50.5 | 50.5 | 50.5 | | |
| | | | | | $M_{0,max}$ | | | | | | | 87.6 | 87.6 | 87.6 | 87.6 | | |
| | | | | | M_{max} | | | | | | | 127.6 | 127.6 | 127.6 | 127.6 | | |
| | | | | | η_{eto} | | | | | | | - | - | - | - | | |
| 19P12- | 72.0 | 1200 | 21.3 | 9.00 | M_0 | | | | | | 47.5 | | 86.0 | 86.0 | | | |
| | | | | | M_N | | | | | | 46.4 | 72.0 | 72.0 | | | | |
| | | | | | $M_{0,max}$ | | | | | | 92.7 | 106.7 | 106.7 | | | | |
| | | | | | M_{max} | | | | | | 92.7 | 155.5 | 155.5 | | | | |
| | | | | | η_{eto} | | | | | | - | - | - | | | | |
| 19P29- | 53.0 | 2850 | 29.5 | 15.80 | M_0 | | | | | | | | | 58.7 | 86.0 | 86.0 | 86.0 |
| | | | | | M_N | | | | | | | 53.0 | 53.0 | 53.0 | 53.0 | | |
| | | | | | $M_{0,max}$ | | | | | | | 87.6 | 87.6 | 87.6 | 87.6 | | |
| | | | | | M_{max} | | | | | | | 144.3 | 144.3 | 144.3 | 144.3 | | |
| | | | | | η_{eto} | | | | | | | - | - | - | - | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MCS synchronous servo motors

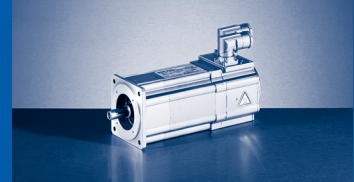
ECS servo system selection tables

Mains connection 3 x 400 V and switching frequency 4 kHz

Motors without blower

| | | | | | ECS□□ | 004C□B | 008C□B | 016C□B | 032C□B | 048C□B | 064C□B |
|--------|-------|-------|-------|-------|-------------|--------|--------|--------|--------|--------|--------|
| | | | | | I_N | 2.0 | 4.0 | 8.0 | 12.7 | 17.0 | 20.0 |
| | | | | | $I_{0,max}$ | 2.3 | 4.6 | 9.1 | 18.1 | 27.2 | 36.3 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 4.0 | 8.0 | 16.0 | 32.0 | 48.0 | 64.0 |
| 06C41- | 0.6 | 4050 | 1.3 | 0.25 | M_0 | 0.8 | | | | | |
| | | | | | M_N | 0.6 | | | | | |
| | | | | | $M_{0,max}$ | 1.2 | | | | | |
| | | | | | M_{max} | 1.9 | | | | | |
| | | | | | n_{eto} | 2747 | | | | | |
| 06C60- | 0.5 | 6000 | 2.4 | 0.31 | M_0 | 0.6 | 0.8 | | | | |
| | | | | | M_N | 0.4 | 0.5 | | | | |
| | | | | | $M_{0,max}$ | 0.6 | 1.2 | | | | |
| | | | | | M_{max} | 1.0 | 1.9 | | | | |
| | | | | | n_{eto} | 7000 | 6814 | | | | |
| 06F41- | 1.2 | 4050 | 1.5 | 0.51 | M_0 | 1.5 | | | | | |
| | | | | | M_N | 1.2 | | | | | |
| | | | | | $M_{0,max}$ | 2.0 | | | | | |
| | | | | | M_{max} | 3.6 | | | | | |
| | | | | | n_{eto} | 1902 | | | | | |
| 06F60- | 0.9 | 6000 | 2.5 | 0.57 | M_0 | 1.0 | 1.5 | | | | |
| | | | | | M_N | 0.7 | 0.9 | | | | |
| | | | | | $M_{0,max}$ | 1.0 | 2.0 | | | | |
| | | | | | M_{max} | 1.8 | 3.7 | | | | |
| | | | | | n_{eto} | 7000 | 4602 | | | | |
| 06I41- | 1.5 | 4050 | 1.6 | 0.64 | M_0 | 2.0 | 2.0 | | | | |
| | | | | | M_N | 1.5 | 1.5 | | | | |
| | | | | | $M_{0,max}$ | 2.6 | 5.0 | | | | |
| | | | | | M_{max} | 4.4 | 6.2 | | | | |
| | | | | | n_{eto} | 1898 | 1384 | | | | |
| 06I60- | 1.2 | 6000 | 2.9 | 0.75 | M_0 | 1.2 | 2.0 | 2.0 | | | |
| | | | | | M_N | 0.8 | 1.2 | 1.2 | | | |
| | | | | | $M_{0,max}$ | 1.3 | 2.6 | 5.2 | | | |
| | | | | | M_{max} | 2.2 | 4.7 | 6.2 | | | |
| | | | | | n_{eto} | 6407 | 4200 | 3157 | | | |
| 09D41- | 2.3 | 4050 | 2.3 | 1.00 | M_0 | | 3.3 | 3.3 | | | |
| | | | | | M_N | | 2.3 | 2.3 | | | |
| | | | | | $M_{0,max}$ | | 5.0 | 8.8 | | | |
| | | | | | M_{max} | | 8.0 | 9.4 | | | |
| | | | | | n_{eto} | | 2361 | 2008 | | | |
| 09D60- | 1.8 | 6000 | 3.8 | 1.10 | M_0 | | 2.5 | 3.3 | | | |
| | | | | | M_N | | 1.8 | 1.8 | | | |
| | | | | | $M_{0,max}$ | | 2.5 | 4.9 | | | |
| | | | | | M_{max} | | 4.4 | 8.0 | | | |
| | | | | | n_{eto} | | 7000 | 5217 | | | |
| 09F38- | 3.1 | 3750 | 2.5 | 1.20 | M_0 | | 4.2 | 4.2 | | | |
| | | | | | M_N | | 3.1 | 3.1 | | | |
| | | | | | $M_{0,max}$ | | 6.2 | 10.8 | | | |
| | | | | | M_{max} | | 9.8 | 14.9 | | | |
| | | | | | n_{eto} | | 2589 | 1737 | | | |
| 09F60- | 2.4 | 6000 | 4.5 | 1.50 | M_0 | | 2.8 | 4.2 | 4.2 | | |
| | | | | | M_N | | 2.1 | 2.4 | 2.4 | | |
| | | | | | $M_{0,max}$ | | 3.2 | 6.1 | 10.8 | | |
| | | | | | M_{max} | | 5.4 | 9.8 | 14.9 | | |
| | | | | | n_{eto} | | 7000 | 5906 | 3715 | | |

► I... [A], M... [Nm], n... [r/min], P... [kW]

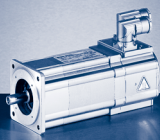


Mains connection 3 x 400 V and switching frequency 4 kHz

Motors without blower

| | | | | | ECS□□ | 004C□B | 008C□B | 016C□B | 032C□B | 048C□B | 064C□B |
|--------|-------|-------|-------|-------|-------------|--------|--------|--------|--------|--------|--------|
| | | | | | I_N | 2.0 | 4.0 | 8.0 | 12.7 | 17.0 | 20.0 |
| | | | | | $I_{0,max}$ | 2.3 | 4.6 | 9.1 | 18.1 | 27.2 | 36.3 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 4.0 | 8.0 | 16.0 | 32.0 | 48.0 | 64.0 |
| 09H41- | 3.8 | 4050 | 3.4 | 1.60 | M_0 | | 5.2 | 5.5 | | | |
| | | | | | M_N | | 3.8 | 3.8 | | | |
| | | | | | $M_{0,max}$ | | 5.9 | 11.1 | | | |
| | | | | | M_{max} | | 9.9 | 17.5 | | | |
| | | | | | n_{eto} | | 3675 | 2231 | | | |
| 09H60- | 3.0 | 6000 | 6.0 | 1.90 | M_0 | | | 5.2 | 5.5 | 5.5 | |
| | | | | | M_N | | | 3.0 | 3.0 | 3.0 | |
| | | | | | $M_{0,max}$ | | | 5.9 | 11.0 | 15.5 | |
| | | | | | M_{max} | | | 9.9 | 17.5 | 20.4 | |
| | | | | | n_{eto} | | | 7000 | 5061 | 4375 | |
| 09L41- | 4.5 | 4050 | 4.2 | 1.90 | M_0 | | 4.8 | 7.5 | 7.5 | | |
| | | | | | M_N | | 4.3 | 4.5 | 4.5 | | |
| | | | | | $M_{0,max}$ | | 5.2 | 10.3 | 19.5 | | |
| | | | | | M_{max} | | 9.1 | 17.4 | 31.9 | | |
| | | | | | n_{eto} | | 4450 | 3188 | 1878 | | |
| 09L51- | 3.6 | 5100 | 6.9 | 1.90 | M_0 | | | 4.8 | 7.5 | 7.5 | 7.5 |
| | | | | | M_N | | | 3.6 | 3.6 | 3.6 | 3.6 |
| | | | | | $M_{0,max}$ | | | 5.2 | 10.3 | 15.1 | 19.6 |
| | | | | | M_{max} | | | 9.1 | 17.5 | 25.1 | 31.9 |
| | | | | | n_{eto} | | | 7000 | 7000 | 5647 | 4076 |
| 12D20- | 5.5 | 1950 | 2.6 | 1.10 | M_0 | 4.7 | 6.4 | 6.4 | | | |
| | | | | | M_N | 4.2 | 5.5 | 5.5 | | | |
| | | | | | $M_{0,max}$ | 4.6 | 9.1 | 17.0 | | | |
| | | | | | M_{max} | 8.0 | 15.3 | 17.7 | | | |
| | | | | | n_{eto} | 1730 | 1089 | 919 | | | |
| 12D41- | 4.3 | 4050 | 4.5 | 1.80 | M_0 | | 4.7 | 6.4 | | | |
| | | | | | M_N | | 3.8 | 4.3 | | | |
| | | | | | $M_{0,max}$ | | 4.6 | 8.8 | | | |
| | | | | | M_{max} | | 7.8 | 14.7 | | | |
| | | | | | n_{eto} | | 3902 | 2433 | | | |
| 12H15- | 10.0 | 1500 | 3.8 | 1.60 | M_0 | | 11.2 | 11.4 | | | |
| | | | | | M_N | | 10.0 | 10.0 | | | |
| | | | | | $M_{0,max}$ | | 11.9 | 22.6 | | | |
| | | | | | M_{max} | | 20.1 | 29.0 | | | |
| | | | | | n_{eto} | | 1220 | 918 | | | |
| 12H35- | 7.5 | 3525 | 5.7 | 2.80 | M_0 | | 5.6 | 11.2 | 11.4 | | |
| | | | | | M_N | | 5.3 | 7.5 | 7.5 | | |
| | | | | | $M_{0,max}$ | | 6.0 | 11.8 | 22.5 | | |
| | | | | | M_{max} | | 10.4 | 20.1 | 29.0 | | |
| | | | | | n_{eto} | | 3850 | 2838 | 2092 | | |
| 12L20- | 13.5 | 1950 | 5.9 | 2.80 | M_0 | | | 15.0 | 15.0 | | |
| | | | | | M_N | | | 13.5 | 13.5 | | |
| | | | | | $M_{0,max}$ | | | 21.4 | 39.4 | | |
| | | | | | M_{max} | | | 35.5 | 56.4 | | |
| | | | | | n_{eto} | | | 1324 | 863 | | |
| 12L41- | 11.0 | 4050 | 10.2 | 4.70 | M_0 | | | 9.7 | 15.0 | 15.0 | 15.0 |
| | | | | | M_N | | | 8.6 | 11.0 | 11.0 | 11.0 |
| | | | | | $M_{0,max}$ | | | 10.8 | 21.3 | 30.8 | 39.5 |
| | | | | | M_{max} | | | 19.0 | 35.5 | 49.6 | 56.4 |
| | | | | | n_{eto} | | | 4450 | 3013 | 2236 | 1907 |

► I... [A], M... [Nm], n... [r/min], P... [kW]



MCS synchronous servo motors

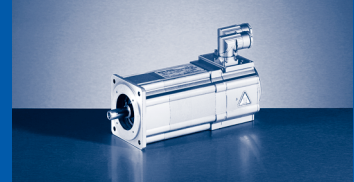
ECS servo system selection tables

Mains connection 3 x 400 V and switching frequency 4 kHz

Motors without blower

| | | | | | ECS□□ | 004C□B | 008C□B | 016C□B | 032C□B | 048C□B | 064C□B | |
|--------|-------|-------|-------|-------|-------------|--------|--------|--------|--------|--------|--------|--|
| | | | | | I_N | 2.0 | 4.0 | 8.0 | 12.7 | 17.0 | 20.0 | |
| | | | | | $I_{0,max}$ | 2.3 | 4.6 | 9.1 | 18.1 | 27.2 | 36.3 | |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 4.0 | 8.0 | 16.0 | 32.0 | 48.0 | 64.0 | |
| 14D15- | 9.2 | 1500 | 4.5 | 1.45 | M_0 | | 8.8 | 11.0 | | | | |
| | | | | | M_N | | 8.2 | 9.2 | | | | |
| | | | | | $M_{0,max}$ | | 9.6 | 17.9 | | | | |
| | | | | | M_{max} | | 15.9 | 28.3 | | | | |
| | | | | | n_{eto} | | 1141 | 689 | | | | |
| 14D36- | 7.5 | 3600 | 7.5 | 2.80 | M_0 | | | 8.8 | 11.0 | | | |
| | | | | | M_N | | | 7.5 | 7.5 | | | |
| | | | | | $M_{0,max}$ | | | 9.5 | 17.8 | | | |
| | | | | | M_{max} | | | 15.9 | 28.3 | | | |
| | | | | | n_{eto} | | | 2496 | 1614 | | | |
| 14H15- | 16.0 | 1500 | 6.6 | 2.50 | M_0 | | | 19.8 | 21.0 | | | |
| | | | | | M_N | | | 16.0 | 16.0 | | | |
| | | | | | $M_{0,max}$ | | | 22.3 | 41.2 | | | |
| | | | | | M_{max} | | | 37.1 | 54.8 | | | |
| | | | | | n_{eto} | | | 920 | 667 | | | |
| 14H32- | 14.0 | 3225 | 11.9 | 4.70 | M_0 | | | | 15.8 | 21.0 | 21.0 | |
| | | | | | M_N | | | | 14.0 | 14.0 | 14.0 | |
| | | | | | $M_{0,max}$ | | | | 22.2 | 32.1 | 41.3 | |
| | | | | | M_{max} | | | | 37.1 | 51.9 | 54.8 | |
| | | | | | n_{eto} | | | | 1953 | 1471 | 1409 | |
| 14L15- | 23.0 | 1500 | 9.7 | 3.60 | M_0 | | | 18.7 | 28.0 | 28.0 | | |
| | | | | | M_N | | | 19.0 | 23.0 | 23.0 | | |
| | | | | | $M_{0,max}$ | | | 21.9 | 42.1 | 59.9 | | |
| | | | | | M_{max} | | | 37.6 | 68.5 | 77.1 | | |
| | | | | | n_{eto} | | | 1284 | 828 | 767 | | |
| 14L32- | 17.2 | 3225 | 15.0 | 5.80 | M_0 | | | | 14.8 | 19.8 | 23.3 | |
| | | | | | M_N | | | | 14.6 | 17.2 | 17.2 | |
| | | | | | $M_{0,max}$ | | | | 21.8 | 32.4 | 42.2 | |
| | | | | | M_{max} | | | | 37.6 | 53.9 | 68.5 | |
| | | | | | n_{eto} | | | | 2801 | 2096 | 1757 | |
| 14P14- | 30.0 | 1350 | 10.8 | 4.20 | M_0 | | | | 37.0 | 37.0 | 37.0 | |
| | | | | | M_N | | | | 30.0 | 30.0 | 30.0 | |
| | | | | | $M_{0,max}$ | | | | 49.1 | 70.0 | 88.4 | |
| | | | | | M_{max} | | | | 80.0 | 105.1 | 105.1 | |
| | | | | | n_{eto} | | | | 710 | 573 | 573 | |
| 14P32- | 21.0 | 3225 | 15.6 | 7.10 | M_0 | | | | 19.3 | 25.9 | 30.5 | |
| | | | | | M_N | | | | 17.1 | 21.0 | 21.0 | |
| | | | | | $M_{0,max}$ | | | | 25.4 | 37.9 | 49.3 | |
| | | | | | M_{max} | | | | 43.9 | 63.0 | 80.0 | |
| | | | | | n_{eto} | | | | 2469 | 1829 | 1495 | |
| 19F14- | 27.0 | 1425 | 8.6 | 4.00 | M_0 | | | 25.9 | 32.0 | | | |
| | | | | | M_N | | | 25.1 | 27.0 | | | |
| | | | | | $M_{0,max}$ | | | 28.6 | 54.6 | | | |
| | | | | | M_{max} | | | 48.9 | 86.0 | | | |
| | | | | | n_{eto} | | | 1204 | 746 | | | |
| 19F30- | 21.0 | 3000 | 14.0 | 6.60 | M_0 | | | | 20.5 | 27.5 | 32.0 | |
| | | | | | M_N | | | | 19.0 | 21.0 | 21.0 | |
| | | | | | $M_{0,max}$ | | | | 27.2 | 40.5 | 53.0 | |
| | | | | | M_{max} | | | | 47.2 | 68.3 | 86.0 | |
| | | | | | n_{eto} | | | | 2774 | 2033 | 1653 | |

► I... [A], M... [Nm], n... [r/min], P... [kW]

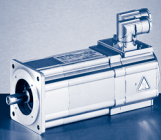


Mains connection 3 x 400 V and switching frequency 4 kHz

Motors without blower

| | | | | | ECS□□ | 004C□B | 008C□B | 016C□B | 032C□B | 048C□B | 064C□B |
|--------|-------|-------|-------|-------|-------------|--------|--------|--------|--------|--------|--------|
| | | | | | I_N | 2.0 | 4.0 | 8.0 | 12.7 | 17.0 | 20.0 |
| | | | | | $I_{0,max}$ | 2.3 | 4.6 | 9.1 | 18.1 | 27.2 | 36.3 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 4.0 | 8.0 | 16.0 | 32.0 | 48.0 | 64.0 |
| 19J14- | 40.0 | 1425 | 12.3 | 6.00 | M_0 | | | | 42.6 | 51.0 | |
| | | | | | M_N | | | | 40.0 | 40.0 | |
| | | | | | $M_{0,max}$ | | | | 58.9 | 82.8 | |
| | | | | | M_{max} | | | | 96.0 | 129.0 | |
| | | | | | n_{eto} | | | | 1063 | 839 | |
| 19J30- | 29.0 | 3000 | 18.5 | 9.10 | M_0 | | | | | 28.4 | 33.4 |
| | | | | | M_N | | | | | 26.6 | 29.0 |
| | | | | | $M_{0,max}$ | | | | | 42.6 | 56.9 |
| | | | | | M_{max} | | | | | 73.8 | 96.0 |
| | | | | | n_{eto} | | | | | 2850 | 2323 |
| 19P14- | 51.0 | 1350 | 14.3 | 7.20 | M_0 | | | | 46.4 | 62.2 | 64.0 |
| | | | | | M_N | | | | 45.3 | 51.0 | 51.0 |
| | | | | | $M_{0,max}$ | | | | 64.6 | 91.5 | 120.1 |
| | | | | | M_{max} | | | | 106.7 | 155.5 | 190.0 |
| | | | | | n_{eto} | | | | 1227 | 996 | 870 |
| 19P30- | 32.0 | 3000 | 19.0 | 10.00 | M_0 | | | | | 31.2 | 36.7 |
| | | | | | M_N | | | | | 28.6 | 32.0 |
| | | | | | $M_{0,max}$ | | | | | 45.8 | 61.1 |
| | | | | | M_{max} | | | | | 81.2 | 106.7 |
| | | | | | n_{eto} | | | | | 2938 | 2715 |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MCS synchronous servo motors

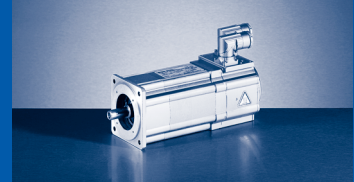
ECS servo system selection tables

Mains connection 3 x 400 V and switching frequency 4 kHz

Motors with blower

| | | | | | ECS□□ | 004C□B | 008C□B | 016C□B | 032C□B | 048C□B | 064C□B |
|--------|-------|-------|-------|-------|-------------|--------|--------|--------|--------|--------|--------|
| | | | | | I_N | 2.0 | 4.0 | 8.0 | 12.7 | 17.0 | 20.0 |
| | | | | | $I_{0,max}$ | 2.3 | 4.6 | 9.1 | 18.1 | 27.2 | 36.3 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 4.0 | 8.0 | 16.0 | 32.0 | 48.0 | 64.0 |
| 12D17- | 7.0 | 1650 | 3.0 | 1.20 | M_0 | 4.7 | 7.5 | 7.5 | | | |
| | | | | | M_N | 4.2 | 7.0 | 7.0 | | | |
| | | | | | $M_{0,max}$ | 4.6 | 9.1 | 17.0 | | | |
| | | | | | M_{max} | 8.0 | 15.3 | 17.7 | | | |
| | | | | | n_{eto} | 1730 | 1089 | 919 | | | |
| 12D35- | 6.0 | 3525 | 5.6 | 2.20 | M_0 | | 4.7 | 7.5 | | | |
| | | | | | M_N | | 3.8 | 6.0 | | | |
| | | | | | $M_{0,max}$ | | 4.6 | 8.8 | | | |
| | | | | | M_{max} | | 7.8 | 14.7 | | | |
| | | | | | n_{eto} | | 3902 | 2433 | | | |
| 12H14- | 12.0 | 1350 | 4.1 | 1.70 | M_0 | | 11.2 | 12.8 | | | |
| | | | | | M_N | | 10.6 | 12.0 | | | |
| | | | | | $M_{0,max}$ | | 11.9 | 22.6 | | | |
| | | | | | M_{max} | | 20.1 | 29.0 | | | |
| | | | | | n_{eto} | | 1220 | 918 | | | |
| 12H34- | 10.5 | 3375 | 7.5 | 3.70 | M_0 | | 5.6 | 11.2 | 12.8 | | |
| | | | | | M_N | | 5.3 | 10.0 | 7.5 | | |
| | | | | | $M_{0,max}$ | | 6.0 | 11.8 | 22.5 | | |
| | | | | | M_{max} | | 10.4 | 20.1 | 29.0 | | |
| | | | | | n_{eto} | | 3850 | 2838 | 2092 | | |
| 12L17- | 17.0 | 1650 | 6.7 | 2.90 | M_0 | | | 19.0 | 19.0 | | |
| | | | | | M_N | | | 17.0 | 17.0 | | |
| | | | | | $M_{0,max}$ | | | 21.4 | 39.4 | | |
| | | | | | M_{max} | | | 35.5 | 56.4 | | |
| | | | | | n_{eto} | | | 1324 | 863 | | |
| 12L39- | 14.0 | 3900 | 11.7 | 5.70 | M_0 | | | 9.7 | 16.7 | 19.0 | 19.0 |
| | | | | | M_N | | | 8.6 | 14.0 | 14.0 | 14.0 |
| | | | | | $M_{0,max}$ | | | 10.8 | 21.3 | 30.8 | 39.5 |
| | | | | | M_{max} | | | 19.0 | 35.5 | 49.6 | 56.4 |
| | | | | | n_{eto} | | | 4450 | 3013 | 2236 | 1907 |
| 14D14- | 12.0 | 1350 | 5.4 | 1.70 | M_0 | | 8.8 | 12.5 | | | |
| | | | | | M_N | | 8.2 | 12.0 | | | |
| | | | | | $M_{0,max}$ | | 9.6 | 17.9 | | | |
| | | | | | M_{max} | | 15.9 | 28.3 | | | |
| | | | | | n_{eto} | | 1141 | 689 | | | |
| 14D30- | 10.5 | 3000 | 9.7 | 3.30 | M_0 | | | 8.8 | 11.4 | | |
| | | | | | M_N | | | 8.6 | 9.7 | | |
| | | | | | $M_{0,max}$ | | | 9.5 | 17.8 | | |
| | | | | | M_{max} | | | 15.9 | 28.3 | | |
| | | | | | n_{eto} | | | 2496 | 1614 | | |
| 14H12- | 23.5 | 1200 | 8.3 | 3.00 | M_0 | | | 19.8 | 25.5 | | |
| | | | | | M_N | | | 19.6 | 23.5 | | |
| | | | | | $M_{0,max}$ | | | 22.3 | 41.2 | | |
| | | | | | M_{max} | | | 37.1 | 54.8 | | |
| | | | | | n_{eto} | | | 920 | 667 | | |
| 14H28- | 20.5 | 2775 | 15.0 | 6.00 | M_0 | | | | 15.8 | 23.5 | 25.5 |
| | | | | | M_N | | | | 15.6 | 20.5 | 20.5 |
| | | | | | $M_{0,max}$ | | | | 22.2 | 32.1 | 41.3 |
| | | | | | M_{max} | | | | 37.1 | 51.9 | 54.8 |
| | | | | | n_{eto} | | | | 1953 | 1471 | 1409 |

► I... [A], M... [Nm], n... [r/min], P... [kW]

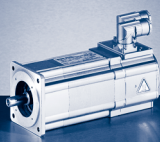


Mains connection 3 x 400 V and switching frequency 4 kHz

Motors with blower

| | | | | | ECS□□ | 004C□B | 008C□B | 016C□B | 032C□B | 048C□B | 064C□B |
|--------|-------|-------|-------|-------|-------------|--------|--------|--------|--------|--------|--------|
| | | | | | I_N | 2.0 | 4.0 | 8.0 | 12.7 | 17.0 | 20.0 |
| | | | | | $I_{0,max}$ | 2.3 | 4.6 | 9.1 | 18.1 | 27.2 | 36.3 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 4.0 | 8.0 | 16.0 | 32.0 | 48.0 | 64.0 |
| 14L14- | 30.5 | 1350 | 11.8 | 4.30 | M_0 | | | 18.7 | 32.7 | 34.5 | |
| | | | | | M_N | | | 19.0 | 30.5 | 30.5 | |
| | | | | | $M_{0,max}$ | | | 21.9 | 42.1 | 59.9 | |
| | | | | | M_{max} | | | 37.6 | 68.5 | 77.1 | |
| | | | | | n_{eto} | | | 1284 | 828 | 767 | |
| 14L30- | 25.5 | 3000 | 20.8 | 8.00 | M_0 | | | | | 19.8 | 23.3 |
| | | | | | M_N | | | | | 19.7 | 23.3 |
| | | | | | $M_{0,max}$ | | | | | 32.4 | 42.2 |
| | | | | | M_{max} | | | | | 53.9 | 68.5 |
| | | | | | n_{eto} | | | | | 2096 | 1757 |
| 14P11- | 42.0 | 1050 | 13.4 | 4.60 | M_0 | | | | 39.1 | 43.5 | 43.5 |
| | | | | | M_N | | | | 38.9 | 42.0 | 42.0 |
| | | | | | $M_{0,max}$ | | | | 49.1 | 70.0 | 88.4 |
| | | | | | M_{max} | | | | 80.0 | 105.1 | 105.1 |
| | | | | | n_{eto} | | | | 710 | 573 | 573 |
| 14P26- | 33.0 | 2625 | 21.9 | 9.10 | M_0 | | | | | 25.9 | 30.5 |
| | | | | | M_N | | | | | 25.6 | 30.1 |
| | | | | | $M_{0,max}$ | | | | | 37.9 | 49.3 |
| | | | | | M_{max} | | | | | 63.0 | 80.0 |
| | | | | | n_{eto} | | | | | 1829 | 1495 |
| 19F12- | 38.0 | 1200 | 11.3 | 4.80 | M_0 | | | 25.9 | 41.5 | | |
| | | | | | M_N | | | 25.1 | 38.0 | | |
| | | | | | $M_{0,max}$ | | | 28.6 | 54.6 | | |
| | | | | | M_{max} | | | 48.9 | 86.0 | | |
| | | | | | n_{eto} | | | 1204 | 746 | | |
| 19F29- | 32.5 | 2850 | 20.1 | 9.70 | M_0 | | | | | 27.5 | 33.9 |
| | | | | | M_N | | | | | 27.4 | 32.5 |
| | | | | | $M_{0,max}$ | | | | | 40.5 | 53.0 |
| | | | | | M_{max} | | | | | 68.3 | 86.0 |
| | | | | | n_{eto} | | | | | 2033 | 1653 |
| 19J12- | 62.5 | 1200 | 18.3 | 7.90 | M_0 | | | | | 59.0 | 69.4 |
| | | | | | M_N | | | | | 58.1 | 62.5 |
| | | | | | $M_{0,max}$ | | | | | 82.8 | 82.8 |
| | | | | | M_{max} | | | | | 129.0 | 129.0 |
| | | | | | n_{eto} | | | | | 839 | 839 |
| 19J29- | 50.5 | 2850 | 31.0 | 15.10 | M_0 | | | | | | 34.3 |
| | | | | | M_N | | | | | | 32.6 |
| | | | | | $M_{0,max}$ | | | | | | 56.9 |
| | | | | | M_{max} | | | | | | 96.0 |
| | | | | | n_{eto} | | | | | | 2323 |
| 19P12- | 72.0 | 1200 | 21.3 | 9.00 | M_0 | | | | | 62.2 | 76.8 |
| | | | | | M_N | | | | | 57.5 | 67.6 |
| | | | | | $M_{0,max}$ | | | | | 91.5 | 120.1 |
| | | | | | M_{max} | | | | | 155.5 | 190.0 |
| | | | | | n_{eto} | | | | | 996 | 870 |
| 19P29- | 53.0 | 2850 | 29.5 | 15.80 | M_0 | | | | | | 36.7 |
| | | | | | M_N | | | | | | 35.9 |
| | | | | | $M_{0,max}$ | | | | | | 61.1 |
| | | | | | M_{max} | | | | | | 106.7 |
| | | | | | n_{eto} | | | | | | 2715 |

► I... [A], M... [Nm], n... [r/min], P... [kW]



MCS synchronous servo motors

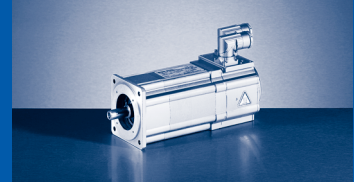
ECS servo system selection tables

Mains connection 3 x 230 V and switching frequency 4 kHz

Motors without blower

| | | | | | ECS□□ | 004C□B | 008C□B | 016C□B | 032C□B | 048C□B | 064C□B |
|--------|-------|-------|-------|-------|-------------|--------|--------|--------|--------|--------|--------|
| | | | | | I_N | 2.0 | 4.0 | 8.0 | 12.7 | 17.0 | 20.0 |
| | | | | | $I_{0,max}$ | 2.3 | 4.6 | 9.1 | 18.1 | 27.2 | 36.3 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 4.0 | 8.0 | 16.0 | 32.0 | 48.0 | 64.0 |
| 06C41L | 0.6 | 4050 | 2.6 | 0.25 | M_0 | 0.6 | 0.8 | | | | |
| | | | | | M_N | 0.5 | 0.6 | | | | |
| | | | | | $M_{0,max}$ | 0.6 | 1.1 | | | | |
| | | | | | M_{max} | 1.0 | 1.9 | | | | |
| | | | | | n_{eto} | 6298 | 2835 | | | | |
| 06C60L | 0.5 | 6000 | 4.0 | 0.31 | M_0 | | 0.7 | 0.8 | | | |
| | | | | | M_N | | 0.5 | 0.5 | | | |
| | | | | | $M_{0,max}$ | | 0.7 | 1.3 | | | |
| | | | | | M_{max} | | 1.2 | 2.2 | | | |
| | | | | | n_{eto} | | 7000 | 1149 | | | |
| 06F41L | 1.2 | 4050 | 2.9 | 0.51 | M_0 | 1.0 | 1.5 | 1.5 | | | |
| | | | | | M_N | 0.8 | 1.2 | 1.2 | | | |
| | | | | | $M_{0,max}$ | 1.2 | 2.1 | 3.9 | | | |
| | | | | | M_{max} | 1.9 | 3.5 | 4.4 | | | |
| | | | | | n_{eto} | 3838 | 2118 | 2831 | | | |
| 06F60L | 0.9 | 6000 | 3.8 | 0.57 | M_0 | | 1.5 | 1.5 | | | |
| | | | | | M_N | | 0.9 | 0.9 | | | |
| | | | | | $M_{0,max}$ | | 1.5 | 2.9 | | | |
| | | | | | M_{max} | | 2.6 | 4.3 | | | |
| | | | | | n_{eto} | | 6138 | 3182 | | | |
| 06I41L | 1.5 | 4050 | 3.2 | 0.64 | M_0 | 1.3 | 2.0 | 2.0 | | | |
| | | | | | M_N | 1.0 | 1.5 | 1.5 | | | |
| | | | | | $M_{0,max}$ | 1.4 | 2.8 | 5.0 | | | |
| | | | | | M_{max} | 2.4 | 4.4 | 6.2 | | | |
| | | | | | n_{eto} | 3549 | 1947 | 2831 | | | |
| 06I60L | 1.2 | 6000 | 3.8 | 0.75 | M_0 | | 1.9 | 2.0 | | | |
| | | | | | M_N | | 1.2 | 1.2 | | | |
| | | | | | $M_{0,max}$ | | 2.1 | 4.1 | | | |
| | | | | | M_{max} | | 3.6 | 6.2 | | | |
| | | | | | n_{eto} | | 3417 | 1149 | | | |
| 09D41L | 2.3 | 4050 | 4.6 | 1.00 | M_0 | | 2.5 | 3.3 | 3.3 | | |
| | | | | | M_N | | 2.0 | 2.3 | 2.3 | | |
| | | | | | $M_{0,max}$ | | 2.5 | 4.9 | 8.8 | | |
| | | | | | M_{max} | | 4.4 | 8.0 | 9.5 | | |
| | | | | | n_{eto} | | 4091 | 2547 | 2170 | | |
| 09D60L | 1.8 | 6000 | 7.0 | 1.10 | M_0 | | | 2.6 | 3.3 | 3.3 | |
| | | | | | M_N | | | 1.8 | 1.8 | 1.8 | |
| | | | | | $M_{0,max}$ | | | 2.6 | 5.0 | 7.1 | |
| | | | | | M_{max} | | | 4.5 | 8.1 | 9.5 | |
| | | | | | n_{eto} | | | 7000 | 5373 | 4626 | |
| 09F38L | 3.1 | 3750 | 5.0 | 1.20 | M_0 | | | 4.2 | 4.2 | | |
| | | | | | M_N | | | 3.1 | 3.1 | | |
| | | | | | $M_{0,max}$ | | | 6.1 | 10.8 | | |
| | | | | | M_{max} | | | 9.8 | 15.0 | | |
| | | | | | n_{eto} | | | 1149 | 1951 | | |
| 09F60L | 2.4 | 6000 | 7.9 | 1.50 | M_0 | | | 3.2 | 4.2 | 4.2 | 4.2 |
| | | | | | M_N | | | 2.4 | 2.4 | 2.4 | 2.4 |
| | | | | | $M_{0,max}$ | | | 3.6 | 6.8 | 9.6 | 11.9 |
| | | | | | M_{max} | | | 6.1 | 10.9 | 14.3 | 15.0 |
| | | | | | n_{eto} | | | 6985 | 3448 | 2612 | 2397 |

► I... [A], M... [Nm], n... [r/min], P... [kW]

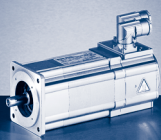


Mains connection 3 x 230 V and switching frequency 4 kHz

Motors without blower

| | | | | | ECS□□ | 004C□B | 008C□B | 016C□B | 032C□B | 048C□B | 064C□B |
|--------|-------|-------|-------|-------|-------------|--------|--------|--------|--------|--------|--------|
| | | | | | I_N | 2.0 | 4.0 | 8.0 | 12.7 | 17.0 | 20.0 |
| | | | | | $I_{0,max}$ | 2.3 | 4.6 | 9.1 | 18.1 | 27.2 | 36.3 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 4.0 | 8.0 | 16.0 | 32.0 | 48.0 | 64.0 |
| 09H41L | 3.8 | 4050 | 6.8 | 1.60 | M_0 | | | 5.2 | 5.5 | 5.5 | |
| | | | | | M_N | | | 3.8 | 3.8 | 3.8 | |
| | | | | | $M_{0,max}$ | | | 5.9 | 11.0 | 15.3 | |
| | | | | | M_{max} | | | 9.9 | 17.2 | 20.0 | |
| | | | | | n_{eto} | | | 1149 | 2138 | 1852 | |
| 09H60L | 3.0 | 6000 | 8.0 | 1.90 | M_0 | | | 3.7 | 5.5 | 5.5 | 5.5 |
| | | | | | M_N | | | 3.0 | 3.0 | 3.0 | 3.0 |
| | | | | | $M_{0,max}$ | | | 4.1 | 8.0 | 11.5 | 14.5 |
| | | | | | M_{max} | | | 7.2 | 13.2 | 17.9 | 20.0 |
| | | | | | n_{eto} | | | 1149 | 4081 | 2984 | 2695 |
| 09L41L | 4.5 | 4050 | 8.4 | 1.90 | M_0 | | | 4.8 | 7.5 | 7.5 | 7.5 |
| | | | | | M_N | | | 4.3 | 4.5 | 4.5 | 4.5 |
| | | | | | $M_{0,max}$ | | | 5.2 | 10.3 | 15.1 | 19.6 |
| | | | | | M_{max} | | | 9.1 | 17.5 | 25.1 | 31.9 |
| | | | | | n_{eto} | | | 4562 | 3243 | 2497 | 1909 |
| 12D20L | 5.5 | 1950 | 5.2 | 1.10 | M_0 | | 4.7 | 6.4 | | | |
| | | | | | M_N | | 4.2 | 5.5 | | | |
| | | | | | $M_{0,max}$ | | 4.6 | 9.0 | | | |
| | | | | | M_{max} | | 8.0 | 14.9 | | | |
| | | | | | n_{eto} | | 1878 | 1181 | | | |
| 12D41L | 4.3 | 4050 | 8.8 | 1.80 | M_0 | | | 4.8 | 6.4 | 6.4 | |
| | | | | | M_N | | | 3.9 | 4.3 | 4.3 | |
| | | | | | $M_{0,max}$ | | | 4.6 | 9.2 | 13.3 | |
| | | | | | M_{max} | | | 8.1 | 15.2 | 17.9 | |
| | | | | | n_{eto} | | | 4102 | 2535 | 2187 | |
| 12H15L | 10.0 | 1500 | 7.6 | 1.60 | M_0 | | | 11.2 | 11.4 | | |
| | | | | | M_N | | | 10.0 | 10.0 | | |
| | | | | | $M_{0,max}$ | | | 11.8 | 22.5 | | |
| | | | | | M_{max} | | | 20.1 | 29.0 | | |
| | | | | | n_{eto} | | | 1098 | 827 | | |
| 12H30L | 8.0 | 3000 | 10.5 | 2.50 | M_0 | | | 6.8 | 10.7 | 11.4 | |
| | | | | | M_N | | | 6.1 | 8.0 | 8.0 | |
| | | | | | $M_{0,max}$ | | | 7.2 | 14.3 | 20.9 | |
| | | | | | M_{max} | | | 12.7 | 24.3 | 29.0 | |
| | | | | | n_{eto} | | | 2831 | 1849 | 1591 | |
| 12L20L | 13.5 | 1950 | 11.8 | 2.80 | M_0 | | | | 15.0 | 15.0 | 15.0 |
| | | | | | M_N | | | | 13.5 | 13.5 | 13.5 |
| | | | | | $M_{0,max}$ | | | | 21.3 | 30.7 | 39.4 |
| | | | | | M_{max} | | | | 35.4 | 49.3 | 56.0 |
| | | | | | n_{eto} | | | | 1307 | 1004 | 866 |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MCS synchronous servo motors

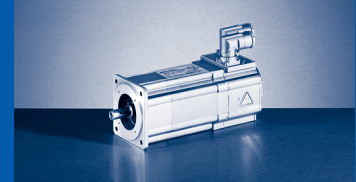
EVS9300 servo inverter selection tables

Mains connection 3 x 400 V and switching frequency 8 kHz

Motors without blower

| | | | | | EVS | 9321-E□ | 9322-E□ | 9323-E□ | 9324-E□ | 9325-E□ | 9326-E□ | 9327-E□ | 9328-E□ | 9329-E□ |
|--------|-------|-------|-------|-------|-------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|
| | | | | | I_N | 1.5 | 2.5 | 3.9 | 7.0 | 13.0 | 23.5 | 32.0 | 47.0 | 59.0 |
| | | | | | $I_{0,max}$ | 2.3 | 3.8 | 5.9 | 10.5 | 19.5 | 23.5 | 32.0 | 47.0 | 52.0 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 2.3 | 3.8 | 5.9 | 10.5 | 19.5 | 35.3 | 48.0 | 70.5 | 88.5 |
| 06C41- | 0.6 | 4050 | 1.3 | 0.25 | M_0 | 0.8 | 0.8 | 0.8 | | | | | | |
| | | | | | M_N | 0.6 | 0.6 | 0.6 | | | | | | |
| | | | | | $M_{0,max}$ | 1.2 | 1.8 | 2.4 | | | | | | |
| | | | | | M_{max} | 1.2 | 1.8 | 2.4 | | | | | | |
| | | | | | n_{eto} | 4635 | 2871 | 2019 | | | | | | |
| 06C60- | 0.5 | 6000 | 2.4 | 0.31 | M_0 | | 0.8 | 0.8 | 0.8 | | | | | |
| | | | | | M_N | | 0.5 | 0.5 | 0.5 | | | | | |
| | | | | | $M_{0,max}$ | | 1.0 | 1.5 | 2.4 | | | | | |
| | | | | | M_{max} | | 1.0 | 1.5 | 2.4 | | | | | |
| | | | | | n_{eto} | | 7000 | 7000 | 5368 | | | | | |
| 06F41- | 1.2 | 4050 | 1.5 | 0.51 | M_0 | 1.5 | 1.5 | 1.5 | | | | | | |
| | | | | | M_N | 1.2 | 1.2 | 1.2 | | | | | | |
| | | | | | $M_{0,max}$ | 2.0 | 3.4 | 4.4 | | | | | | |
| | | | | | M_{max} | 2.0 | 3.4 | 4.4 | | | | | | |
| | | | | | n_{eto} | 2819 | 1973 | 1562 | | | | | | |
| 06F60- | 0.9 | 6000 | 2.5 | 0.57 | M_0 | | 1.3 | 1.5 | 1.5 | | | | | |
| | | | | | M_N | | 0.9 | 0.9 | 0.9 | | | | | |
| | | | | | $M_{0,max}$ | | 1.7 | 3.0 | 4.4 | | | | | |
| | | | | | M_{max} | | 1.7 | 3.0 | 4.4 | | | | | |
| | | | | | n_{eto} | | 7000 | 5714 | 3773 | | | | | |
| 06I41- | 1.5 | 4050 | 1.6 | 0.64 | M_0 | 1.8 | 2.0 | 2.0 | | | | | | |
| | | | | | M_N | 1.4 | 1.5 | 1.5 | | | | | | |
| | | | | | $M_{0,max}$ | 2.6 | 4.2 | 6.2 | | | | | | |
| | | | | | M_{max} | 2.6 | 4.2 | 6.2 | | | | | | |
| | | | | | n_{eto} | 2994 | 1980 | 1384 | | | | | | |
| 06I60- | 1.2 | 6000 | 2.9 | 0.75 | M_0 | | 1.5 | 2.0 | 2.0 | | | | | |
| | | | | | M_N | | 1.0 | 1.2 | 1.2 | | | | | |
| | | | | | $M_{0,max}$ | | 2.1 | 3.3 | 5.7 | | | | | |
| | | | | | M_{max} | | 2.1 | 3.3 | 5.7 | | | | | |
| | | | | | n_{eto} | | 7000 | 5486 | 3414 | | | | | |
| 09D41- | 2.3 | 4050 | 2.3 | 1.00 | M_0 | | 3.1 | 3.3 | 3.3 | | | | | |
| | | | | | M_N | | 2.3 | 2.3 | 2.3 | | | | | |
| | | | | | $M_{0,max}$ | | 4.2 | 6.2 | 9.4 | | | | | |
| | | | | | M_{max} | | 4.2 | 6.2 | 9.4 | | | | | |
| | | | | | n_{eto} | | 4895 | 2937 | 2008 | | | | | |
| 09D60- | 1.8 | 6000 | 3.8 | 1.10 | M_0 | | | 2.4 | 3.3 | 3.3 | | | | |
| | | | | | M_N | | | 1.8 | 1.8 | 1.8 | | | | |
| | | | | | $M_{0,max}$ | | | 3.2 | 5.6 | 9.3 | | | | |
| | | | | | M_{max} | | | 3.2 | 5.6 | 9.3 | | | | |
| | | | | | n_{eto} | | | 7000 | 7000 | 4492 | | | | |
| 09F38- | 3.1 | 3750 | 2.5 | 1.20 | M_0 | | 3.5 | 4.2 | 4.2 | | | | | |
| | | | | | M_N | | 3.1 | 3.1 | 3.1 | | | | | |
| | | | | | $M_{0,max}$ | | 5.2 | 7.7 | 12.0 | | | | | |
| | | | | | M_{max} | | 5.2 | 7.7 | 12.0 | | | | | |
| | | | | | n_{eto} | | 4000 | 3250 | 2173 | | | | | |
| 09F60- | 2.4 | 6000 | 4.5 | 1.50 | M_0 | | | | 4.2 | 4.2 | | | | |
| | | | | | M_N | | | | 2.4 | 2.4 | | | | |
| | | | | | $M_{0,max}$ | | | | 6.9 | 11.4 | | | | |
| | | | | | M_{max} | | | | 6.9 | 11.4 | | | | |
| | | | | | n_{eto} | | | | 7000 | 5035 | | | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

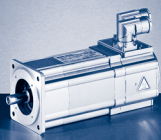


**Mains connection 3 x 400 V and switching frequency
8 kHz**

Motors without blower

| | | | | | EVS | 9321-E□ | 9322-E□ | 9323-E□ | 9324-E□ | 9325-E□ | 9326-E□ | 9327-E□ | 9328-E□ | 9329-E□ |
|--------|----------------|----------------|----------------|----------------|--------------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|
| | | | | | I _N | 1.5 | 2.5 | 3.9 | 7.0 | 13.0 | 23.5 | 32.0 | 47.0 | 59.0 |
| | | | | | I _{0,max} | 2.3 | 3.8 | 5.9 | 10.5 | 19.5 | 23.5 | 32.0 | 47.0 | 52.0 |
| MCS | M _N | n _N | I _N | P _N | I _{max} | 2.3 | 3.8 | 5.9 | 10.5 | 19.5 | 35.3 | 48.0 | 70.5 | 88.5 |
| 09H41- | 3.8 | 4050 | 3.4 | 1.60 | M ₀ | | | 5.0 | 5.5 | 5.5 | | | | |
| | | | | | M _N | | | 3.8 | 3.8 | 3.8 | | | | |
| | | | | | M _{0,max} | | | 7.5 | 12.5 | 20.1 | | | | |
| | | | | | M _{max} | | | 7.5 | 12.5 | 20.1 | | | | |
| | | | | | n _{eto} | | | 4250 | 2977 | 1988 | | | | |
| 09H60- | 3.0 | 6000 | 6.0 | 1.90 | M ₀ | | | | 4.5 | 5.5 | | | | |
| | | | | | M _N | | | | 3.0 | 3.0 | | | | |
| | | | | | M _{0,max} | | | | 6.7 | 11.7 | | | | |
| | | | | | M _{max} | | | | 6.7 | 11.7 | | | | |
| | | | | | n _{eto} | | | | 7000 | 7000 | | | | |
| 09L41- | 4.5 | 4050 | 4.2 | 1.90 | M ₀ | | | 4.7 | 7.5 | 7.5 | | | | |
| | | | | | M _N | | | 4.2 | 4.5 | 4.5 | | | | |
| | | | | | M _{0,max} | | | 6.7 | 11.7 | 20.8 | | | | |
| | | | | | M _{max} | | | 6.7 | 11.7 | 20.8 | | | | |
| | | | | | n _{eto} | | | 4450 | 4154 | 2796 | | | | |
| 09L51- | 3.6 | 5100 | 6.9 | 1.90 | M ₀ | | | | 4.2 | 7.5 | 7.5 | | | |
| | | | | | M _N | | | | 3.6 | 3.6 | 3.6 | | | |
| | | | | | M _{0,max} | | | | 6.0 | 11.1 | 13.2 | | | |
| | | | | | M _{max} | | | | 6.0 | 11.1 | 19.1 | | | |
| | | | | | n _{eto} | | | | 7000 | 7000 | | | | |
| 12D20- | 5.5 | 1950 | 2.6 | 1.10 | M ₀ | | 5.9 | 6.4 | 6.4 | | | | | |
| | | | | | M _N | | 5.3 | 5.5 | 5.5 | | | | | |
| | | | | | M _{0,max} | | 7.6 | 11.6 | 17.7 | | | | | |
| | | | | | M _{max} | | 7.6 | 11.6 | 17.7 | | | | | |
| | | | | | n _{eto} | | 1790 | 1358 | 919 | | | | | |
| 12D41- | 4.3 | 4050 | 4.5 | 1.80 | M ₀ | | | 4.6 | 6.4 | 6.4 | | | | |
| | | | | | M _N | | | 3.7 | 4.3 | 4.3 | | | | |
| | | | | | M _{0,max} | | | 5.9 | 10.1 | 17.3 | | | | |
| | | | | | M _{max} | | | 5.9 | 10.1 | 17.3 | | | | |
| | | | | | n _{eto} | | | 4344 | 3275 | 2116 | | | | |
| 12H15- | 10.0 | 1500 | 3.8 | 1.60 | M ₀ | | | 10.9 | 11.4 | 11.4 | | | | |
| | | | | | M _N | | | 10.0 | 10.0 | 10.0 | | | | |
| | | | | | M _{0,max} | | | 15.1 | 25.8 | 29.0 | | | | |
| | | | | | M _{max} | | | 15.1 | 25.8 | 29.0 | | | | |
| | | | | | n _{eto} | | | 1676 | 1013 | 918 | | | | |
| 12H35- | 7.5 | 3525 | 5.7 | 2.80 | M ₀ | | | | 9.8 | 11.4 | | | | |
| | | | | | M _N | | | | 7.5 | 7.5 | | | | |
| | | | | | M _{0,max} | | | | 13.5 | 24.1 | | | | |
| | | | | | M _{max} | | | | 13.5 | 24.1 | | | | |
| | | | | | n _{eto} | | | | 3618 | 2447 | | | | |
| 12L20- | 13.5 | 1950 | 5.9 | 2.80 | M ₀ | | | | 15.0 | 15.0 | | | | |
| | | | | | M _N | | | | 13.5 | 13.5 | | | | |
| | | | | | M _{0,max} | | | | 24.4 | 41.9 | | | | |
| | | | | | M _{max} | | | | 24.4 | 41.9 | | | | |
| | | | | | n _{eto} | | | | 1718 | 1158 | | | | |
| 12L41- | 11.0 | 4050 | 10.2 | 4.70 | M ₀ | | | | | 15.0 | 15.0 | 15.0 | | |
| | | | | | M _N | | | | | 11.0 | 11.0 | 11.0 | | |
| | | | | | M _{0,max} | | | | | 22.8 | 27.0 | 35.5 | | |
| | | | | | M _{max} | | | | | 22.8 | 38.5 | 49.6 | | |
| | | | | | n _{eto} | | | | | 4287 | 2799 | 2236 | | |

► I... [A], M... [Nm], n... [r/min], P... [kW]



MCS synchronous servo motors

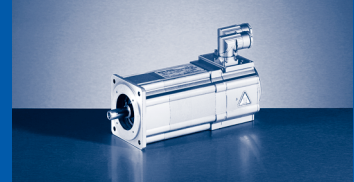
EVS9300 servo inverter selection tables

Mains connection 3 x 400 V and switching frequency 8 kHz

Motors without blower

| | | | | | EVS | 9321-E□ | 9322-E□ | 9323-E□ | 9324-E□ | 9325-E□ | 9326-E□ | 9327-E□ | 9328-E□ | 9329-E□ |
|--------|-------|-------|-------|-------|-------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|
| | | | | | I_N | 1.5 | 2.5 | 3.9 | 7.0 | 13.0 | 23.5 | 32.0 | 47.0 | 59.0 |
| | | | | | $I_{0,max}$ | 2.3 | 3.8 | 5.9 | 10.5 | 19.5 | 23.5 | 32.0 | 47.0 | 52.0 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 2.3 | 3.8 | 5.9 | 10.5 | 19.5 | 35.3 | 48.0 | 70.5 | 88.5 |
| 14D15- | 9.2 | 1500 | 4.5 | 1.45 | M_0 | | | 8.5 | 11.0 | 11.0 | | | | |
| | | | | | M_N | | | 8.0 | 9.2 | 9.2 | | | | |
| | | | | | $M_{0,max}$ | | | 12.1 | 20.2 | 29.0 | | | | |
| | | | | | M_{max} | | | 12.1 | 20.2 | 29.0 | | | | |
| | | | | | n_{eto} | | | 1437 | 928 | 676 | | | | |
| 14D36- | 7.5 | 3600 | 7.5 | 2.80 | M_0 | | | | 7.7 | 11.0 | 11.0 | | | |
| | | | | | M_N | | | | 7.0 | 7.5 | 7.5 | | | |
| | | | | | $M_{0,max}$ | | | | 10.9 | 19.0 | 22.2 | | | |
| | | | | | M_{max} | | | | 10.9 | 19.0 | 29.0 | | | |
| | | | | | n_{eto} | | | | 3479 | 2159 | 1593 | | | |
| 14H15- | 16.0 | 1500 | 6.6 | 2.50 | M_0 | | | | 17.3 | 21.0 | | | | |
| | | | | | M_N | | | | 16.0 | 16.0 | | | | |
| | | | | | $M_{0,max}$ | | | | 25.4 | 43.9 | | | | |
| | | | | | M_{max} | | | | 25.4 | 43.9 | | | | |
| | | | | | n_{eto} | | | | 1247 | 800 | | | | |
| 14H32- | 14.0 | 3225 | 11.9 | 4.70 | M_0 | | | | | 16.2 | 21.0 | 21.0 | | |
| | | | | | M_N | | | | | 14.0 | 14.0 | 14.0 | | |
| | | | | | $M_{0,max}$ | | | | | 23.8 | 28.2 | 37.1 | | |
| | | | | | M_{max} | | | | | 23.8 | 40.2 | 51.9 | | |
| | | | | | n_{eto} | | | | | 2875 | 1817 | 1471 | | |
| 14L15- | 23.0 | 1500 | 9.7 | 3.60 | M_0 | | | | | 28.0 | 28.0 | | | |
| | | | | | M_N | | | | | 23.0 | 23.0 | | | |
| | | | | | $M_{0,max}$ | | | | | 45.0 | 52.9 | | | |
| | | | | | M_{max} | | | | | 45.0 | 73.8 | | | |
| | | | | | n_{eto} | | | | | 1126 | 788 | | | |
| 14L32- | 17.2 | 3225 | 15.0 | 5.80 | M_0 | | | | | 15.2 | 27.4 | 28.0 | 28.0 | |
| | | | | | M_N | | | | | 14.9 | 17.2 | 17.2 | 17.2 | |
| | | | | | $M_{0,max}$ | | | | | 23.5 | 28.3 | 37.6 | 52.9 | |
| | | | | | M_{max} | | | | | 23.5 | 41.0 | 53.9 | 73.9 | |
| | | | | | n_{eto} | | | | | 3953 | 2608 | 2096 | 1672 | |
| 14P14- | 30.0 | 1350 | 10.8 | 4.20 | M_0 | | | | | 37.0 | 37.0 | 37.0 | | |
| | | | | | M_N | | | | | 30.0 | 30.0 | 30.0 | | |
| | | | | | $M_{0,max}$ | | | | | 52.5 | 61.8 | 80.0 | | |
| | | | | | M_{max} | | | | | 52.5 | 86.3 | 105.1 | | |
| | | | | | n_{eto} | | | | | 998 | 668 | 573 | | |
| 14P32- | 21.0 | 3225 | 15.6 | 7.10 | M_0 | | | | | 19.8 | 35.8 | 37.0 | 37.0 | |
| | | | | | M_N | | | | | 17.5 | 21.0 | 21.0 | 21.0 | |
| | | | | | $M_{0,max}$ | | | | | 27.4 | 33.0 | 43.9 | 61.8 | |
| | | | | | M_{max} | | | | | 27.4 | 47.9 | 63.0 | 86.4 | |
| | | | | | n_{eto} | | | | | 3300 | 2299 | 1829 | 1404 | |
| 19F14- | 27.0 | 1425 | 8.6 | 4.00 | M_0 | | | | 22.6 | 32.0 | 32.0 | | | |
| | | | | | M_N | | | | 22.0 | 27.0 | 27.0 | | | |
| | | | | | $M_{0,max}$ | | | | 33.0 | 58.2 | 68.3 | | | |
| | | | | | M_{max} | | | | 33.0 | 58.2 | 86.0 | | | |
| | | | | | n_{eto} | | | | 1459 | 1056 | 746 | | | |
| 19F30- | 21.0 | 3000 | 14.0 | 6.60 | M_0 | | | | | 21.0 | 32.0 | 32.0 | | |
| | | | | | M_N | | | | | 19.5 | 21.0 | 21.0 | | |
| | | | | | $M_{0,max}$ | | | | | 29.2 | 35.2 | 47.2 | | |
| | | | | | M_{max} | | | | | 29.2 | 51.5 | 68.3 | | |
| | | | | | n_{eto} | | | | | 3352 | 2573 | 2033 | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

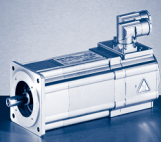


**Mains connection 3 x 400 V and switching frequency
8 kHz**

Motors without blower

| | | | | | EVS | 9321-E□ | 9322-E□ | 9323-E□ | 9324-E□ | 9325-E□ | 9326-E□ | 9327-E□ | 9328-E□ | 9329-E□ |
|--------|-------|-------|-------|-------|-------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|
| | | | | | I_N | 1.5 | 2.5 | 3.9 | 7.0 | 13.0 | 23.5 | 32.0 | 47.0 | 59.0 |
| | | | | | $I_{0,max}$ | 2.3 | 3.8 | 5.9 | 10.5 | 19.5 | 23.5 | 32.0 | 47.0 | 52.0 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 2.3 | 3.8 | 5.9 | 10.5 | 19.5 | 35.3 | 48.0 | 70.5 | 88.5 |
| 19J14- | 40.0 | 1425 | 12.3 | 6.00 | M_0 | | | | | 43.6 | 51.0 | 51.0 | | |
| | | | | | M_N | | | | | 40.0 | 40.0 | 40.0 | | |
| | | | | | $M_{0,max}$ | | | | | 60.8 | 72.4 | 96.0 | | |
| | | | | | M_{max} | | | | | 60.8 | 104.5 | 129.0 | | |
| | | | | | n_{eto} | | | | | 1376 | 996 | 839 | | |
| 19J30- | 29.0 | 3000 | 18.5 | 9.10 | M_0 | | | | | | 39.3 | 51.0 | 51.0 | 51.0 |
| | | | | | M_N | | | | | 29.0 | 29.0 | 29.0 | 29.0 | 29.0 |
| | | | | | $M_{0,max}$ | | | | | 36.8 | 50.2 | 72.4 | 79.5 | 79.5 |
| | | | | | M_{max} | | | | | 55.2 | 73.8 | 104.7 | 127.6 | 127.6 |
| | | | | | n_{eto} | | | | | 3150 | 2850 | 2162 | 1817 | 1817 |
| 19P14- | 51.0 | 1350 | 14.3 | 7.20 | M_0 | | | | | 47.5 | 64.0 | 64.0 | | |
| | | | | | M_N | | | | | 46.4 | 51.0 | 51.0 | | |
| | | | | | $M_{0,max}$ | | | | | 69.5 | 79.6 | 106.7 | | |
| | | | | | M_{max} | | | | | 69.5 | 116.7 | 155.5 | | |
| | | | | | n_{eto} | | | | | 1400 | 1187 | 996 | | |
| 19P30- | 32.0 | 3000 | 19.0 | 10.00 | M_0 | | | | | | 43.1 | 58.7 | 64.0 | 64.0 |
| | | | | | M_N | | | | | | 32.0 | 32.0 | 32.0 | 32.0 |
| | | | | | $M_{0,max}$ | | | | | | 39.6 | 53.9 | 79.6 | 87.6 |
| | | | | | M_{max} | | | | | | 59.3 | 81.2 | 116.9 | 144.3 |
| | | | | | n_{eto} | | | | | | 3000 | 2938 | 2638 | 2298 |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MCS synchronous servo motors

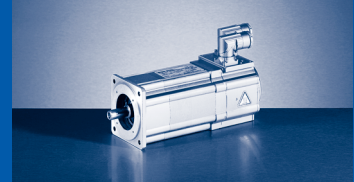
EVS9300 servo inverter selection tables

Mains connection 3 x 400 V and switching frequency 8 kHz

Motors with blower

| | | | | | EVS | 9322-E□ | 9323-E□ | 9324-E□ | 9325-E□ | 9326-E□ | 9327-E□ | 9328-E□ | 9329-E□ |
|--------|-------|-------|-------|-------|-------------|---------|---------|---------|---------|---------|---------|---------|---------|
| | | | | | I_N | 2.5 | 3.9 | 7.0 | 13.0 | 23.5 | 32.0 | 47.0 | 59.0 |
| | | | | | $I_{0,max}$ | 3.8 | 5.9 | 10.5 | 19.5 | 23.5 | 32.0 | 47.0 | 52.0 |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 3.8 | 5.9 | 10.5 | 19.5 | 35.3 | 48.0 | 70.5 | 88.5 |
| 12D17- | 7.0 | 1650 | 3.0 | 1.20 | M_0 | 5.9 | 7.5 | 7.5 | | | | | |
| | | | | | M_N | 5.3 | 7.0 | 7.0 | | | | | |
| | | | | | $M_{0,max}$ | 7.6 | 11.6 | 17.7 | | | | | |
| | | | | | M_{max} | 7.6 | 11.6 | 17.7 | | | | | |
| | | | | | n_{eto} | 1790 | 1358 | 919 | | | | | |
| 12D35- | 6.0 | 3525 | 5.6 | 2.20 | M_0 | | 4.6 | 7.5 | 7.5 | | | | |
| | | | | | M_N | | 3.7 | 6.0 | 6.0 | | | | |
| | | | | | $M_{0,max}$ | | 5.9 | 10.1 | 17.3 | | | | |
| | | | | | M_{max} | | 5.9 | 10.1 | 17.3 | | | | |
| | | | | | n_{eto} | | 4344 | 3275 | 2116 | | | | |
| 12H14- | 12.0 | 1350 | 4.1 | 1.70 | M_0 | | 10.9 | 12.8 | 12.8 | | | | |
| | | | | | M_N | | 10.3 | 12.0 | 12.0 | | | | |
| | | | | | $M_{0,max}$ | | 15.1 | 25.8 | 29.0 | | | | |
| | | | | | M_{max} | | 15.1 | 25.8 | 29.0 | | | | |
| | | | | | n_{eto} | | 1676 | 1013 | 918 | | | | |
| 12H34- | 10.5 | 3375 | 7.5 | 3.70 | M_0 | | | 9.8 | 12.8 | | | | |
| | | | | | M_N | | | 9.6 | 10.5 | | | | |
| | | | | | $M_{0,max}$ | | | 13.5 | 24.1 | | | | |
| | | | | | M_{max} | | | 13.5 | 24.1 | | | | |
| | | | | | n_{eto} | | | 3618 | 2447 | | | | |
| 12L17- | 17.0 | 1650 | 6.7 | 2.90 | M_0 | | | 18.5 | 19.0 | | | | |
| | | | | | M_N | | | 17.0 | 17.0 | | | | |
| | | | | | $M_{0,max}$ | | | 24.4 | 41.9 | | | | |
| | | | | | M_{max} | | | 24.4 | 41.9 | | | | |
| | | | | | n_{eto} | | | 1718 | 1158 | | | | |
| 12L39- | 14.0 | 3900 | 11.7 | 5.70 | M_0 | | | | 17.2 | 19.0 | 19.0 | | |
| | | | | | M_N | | | | 14.0 | 14.0 | 14.0 | | |
| | | | | | $M_{0,max}$ | | | | 22.8 | 27.0 | 35.5 | | |
| | | | | | M_{max} | | | | 22.8 | 38.5 | 49.6 | | |
| | | | | | n_{eto} | | | | 4287 | 2799 | 2236 | | |
| 14D14- | 12.0 | 1350 | 5.4 | 1.70 | M_0 | | 8.5 | 12.5 | 12.5 | | | | |
| | | | | | M_N | | 8.0 | 12.0 | 12.0 | | | | |
| | | | | | $M_{0,max}$ | | 12.1 | 20.2 | 29.0 | | | | |
| | | | | | M_{max} | | 12.1 | 20.2 | 29.0 | | | | |
| | | | | | n_{eto} | | 1437 | 928 | 676 | | | | |
| 14D30- | 10.5 | 3000 | 9.7 | 3.30 | M_0 | | | 7.7 | 12.5 | 12.5 | | | |
| | | | | | M_N | | | 7.0 | 10.0 | 10.0 | | | |
| | | | | | $M_{0,max}$ | | | 10.9 | 19.0 | 22.2 | | | |
| | | | | | M_{max} | | | 10.9 | 19.0 | 29.0 | | | |
| | | | | | n_{eto} | | | 3479 | 2159 | 1593 | | | |
| 14H12- | 23.5 | 1200 | 8.3 | 3.00 | M_0 | | | 17.3 | 25.5 | | | | |
| | | | | | M_N | | | 17.2 | 23.5 | | | | |
| | | | | | $M_{0,max}$ | | | 25.4 | 43.9 | | | | |
| | | | | | M_{max} | | | 25.4 | 43.9 | | | | |
| | | | | | n_{eto} | | | 1247 | 800 | | | | |
| 14H28- | 20.5 | 2775 | 15.0 | 6.00 | M_0 | | | | 16.2 | 25.5 | 25.5 | | |
| | | | | | M_N | | | | 16.1 | 20.5 | 20.5 | | |
| | | | | | $M_{0,max}$ | | | | 23.8 | 28.2 | 37.1 | | |
| | | | | | M_{max} | | | | 23.8 | 40.2 | 51.9 | | |
| | | | | | n_{eto} | | | | 2875 | 1817 | 1471 | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

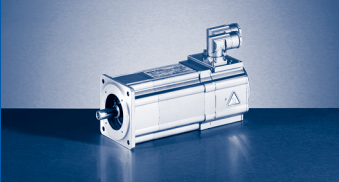


**Mains connection 3 x 400 V and switching frequency
8 kHz**

Motors with blower

| | | | | | EVS | 9322-E□ | 9323-E□ | 9324-E□ | 9325-E□ | 9326-E□ | 9327-E□ | 9328-E□ | 9329-E□ | |
|--------|-------|-------|-------|-------|-------------|---------|---------|---------|---------|---------|---------|---------|---------|--|
| | | | | | I_N | 2.5 | 3.9 | 7.0 | 13.0 | 23.5 | 32.0 | 47.0 | 59.0 | |
| | | | | | $I_{0,max}$ | 3.8 | 5.9 | 10.5 | 19.5 | 23.5 | 32.0 | 47.0 | 52.0 | |
| MCS | M_N | n_N | I_N | P_N | I_{max} | 3.8 | 5.9 | 10.5 | 19.5 | 35.3 | 48.0 | 70.5 | 88.5 | |
| 14L14- | 30.5 | 1350 | 11.8 | 4.30 | M_0 | | | | 33.4 | 34.5 | | | | |
| | | | | | M_N | | | 30.5 | 30.5 | | | | | |
| | | | | | $M_{0,max}$ | | | 45.0 | 52.9 | | | | | |
| | | | | | M_{max} | | | 45.0 | 73.8 | | | | | |
| | | | | | n_{eto} | | | 1126 | 788 | | | | | |
| 14L30- | 25.5 | 3000 | 20.8 | 8.00 | M_0 | | | | | 27.4 | 34.5 | 34.5 | | |
| | | | | | M_N | | | | 25.5 | 25.5 | 25.5 | | | |
| | | | | | $M_{0,max}$ | | | | 28.3 | 37.6 | 52.9 | | | |
| | | | | | M_{max} | | | | 41.0 | 53.9 | 73.9 | | | |
| | | | | | n_{eto} | | | | 2608 | 2096 | 1672 | | | |
| 14P11- | 42.0 | 1050 | 13.4 | 4.60 | M_0 | | | | 40.1 | 43.5 | 43.5 | | | |
| | | | | | M_N | | | | 40.0 | 42.0 | 42.0 | | | |
| | | | | | $M_{0,max}$ | | | | 52.5 | 61.8 | 80.0 | | | |
| | | | | | M_{max} | | | | 52.5 | 86.3 | 105.1 | | | |
| | | | | | n_{eto} | | | | 998 | 668 | 573 | | | |
| 14P26- | 33.0 | 2625 | 21.9 | 9.10 | M_0 | | | | | 35.8 | 43.5 | 43.5 | | |
| | | | | | M_N | | | | 33.0 | 33.0 | 33.0 | | | |
| | | | | | $M_{0,max}$ | | | | 33.0 | 43.9 | 61.8 | | | |
| | | | | | M_{max} | | | | 47.9 | 63.0 | 86.4 | | | |
| | | | | | n_{eto} | | | | 2299 | 1829 | 1404 | | | |
| 19F12- | 38.0 | 1200 | 11.3 | 4.80 | M_0 | | | 22.6 | 41.5 | 41.5 | | | | |
| | | | | | M_N | | | | 22.0 | 38.0 | 38.0 | | | |
| | | | | | $M_{0,max}$ | | | | 33.0 | 58.2 | 68.3 | | | |
| | | | | | M_{max} | | | | 33.0 | 58.2 | 86.0 | | | |
| | | | | | n_{eto} | | | | 1459 | 1056 | 746 | | | |
| 19F29- | 32.5 | 2850 | 20.1 | 9.70 | M_0 | | | | | 39.9 | 41.5 | | | |
| | | | | | M_N | | | | | 32.5 | 32.5 | | | |
| | | | | | $M_{0,max}$ | | | | | 35.2 | 47.2 | | | |
| | | | | | M_{max} | | | | | 51.5 | 68.3 | | | |
| | | | | | n_{eto} | | | | | 2573 | 2033 | | | |
| 19J12- | 62.5 | 1200 | 18.3 | 7.90 | M_0 | | | | 43.6 | 70.5 | 70.5 | | | |
| | | | | | M_N | | | | 43.4 | 62.5 | 62.5 | | | |
| | | | | | $M_{0,max}$ | | | | 60.8 | 72.4 | 96.0 | | | |
| | | | | | M_{max} | | | | 60.8 | 104.5 | 129.0 | | | |
| | | | | | n_{eto} | | | | 1376 | 996 | 839 | | | |
| 19J29- | 50.5 | 2850 | 31.0 | 15.10 | M_0 | | | | | | 55.5 | 70.5 | 70.5 | |
| | | | | | M_N | | | | | 50.5 | 50.5 | 50.5 | | |
| | | | | | $M_{0,max}$ | | | | | 50.2 | 72.4 | 79.5 | | |
| | | | | | M_{max} | | | | | 73.8 | 104.7 | 127.6 | | |
| | | | | | n_{eto} | | | | | 2850 | 2162 | 1817 | | |
| 19P12- | 72.0 | 1200 | 21.3 | 9.00 | M_0 | | | | 47.5 | 86.0 | 86.0 | | | |
| | | | | | M_N | | | | 46.4 | 72.0 | 72.0 | | | |
| | | | | | $M_{0,max}$ | | | | 69.5 | 79.6 | 106.7 | | | |
| | | | | | M_{max} | | | | 69.5 | 116.7 | 155.5 | | | |
| | | | | | n_{eto} | | | | 1400 | 1187 | 996 | | | |
| 19P29- | 53.0 | 2850 | 29.5 | 15.80 | M_0 | | | | | | 58.7 | 86.0 | 86.0 | |
| | | | | | M_N | | | | | 53.0 | 53.0 | 53.0 | | |
| | | | | | $M_{0,max}$ | | | | | 53.9 | 79.6 | 87.6 | | |
| | | | | | M_{max} | | | | | 81.2 | 116.9 | 144.3 | | |
| | | | | | n_{eto} | | | | | 2938 | 2638 | 2298 | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

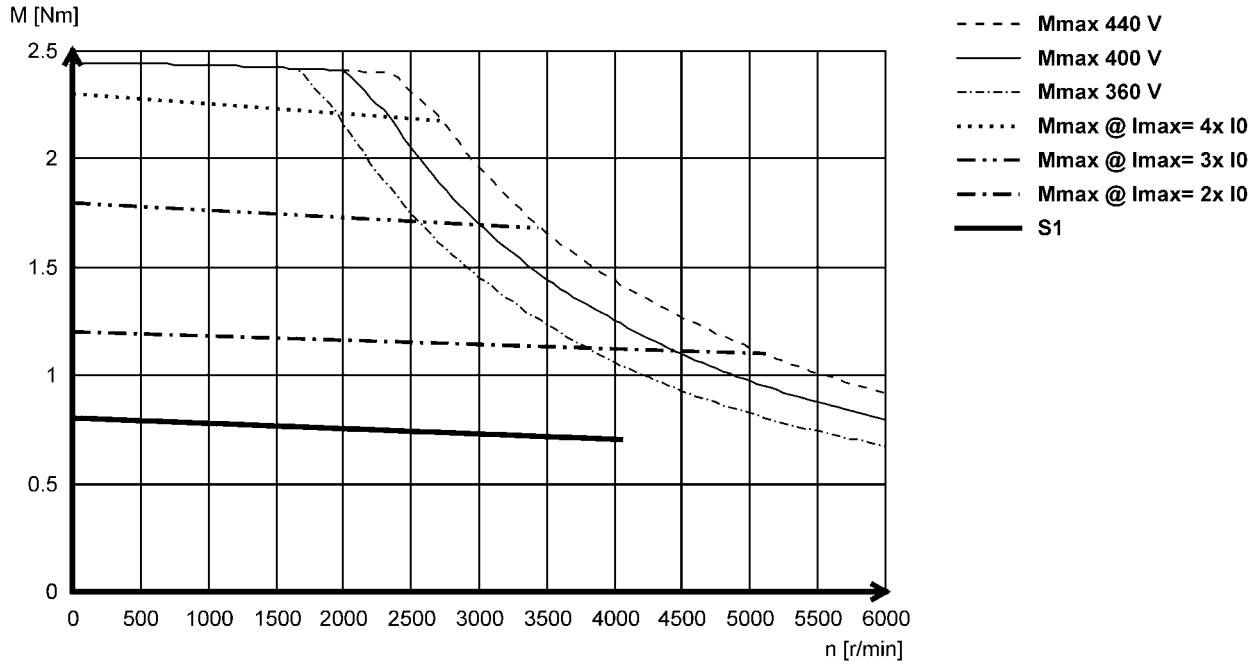


MCS synchronous servo motors

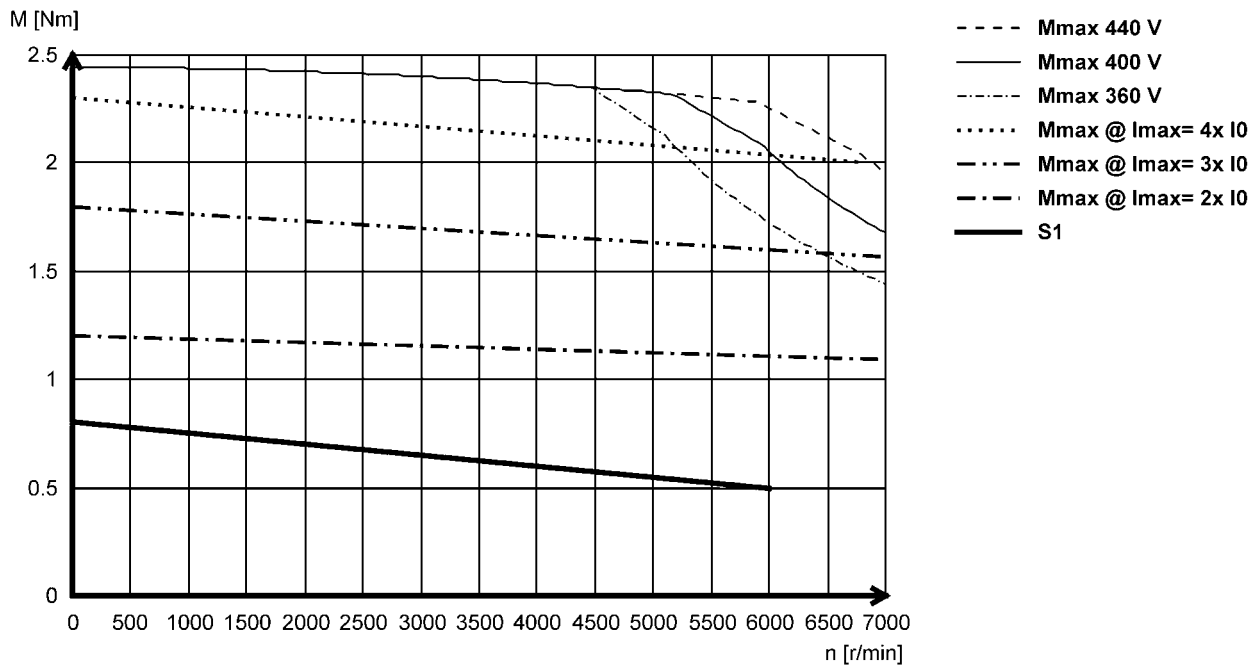
Torque characteristics

Mains connection 3x 400 V

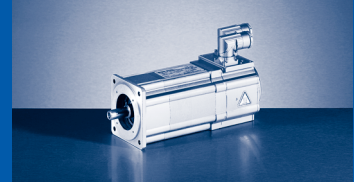
MCS06C41



MCS06C60

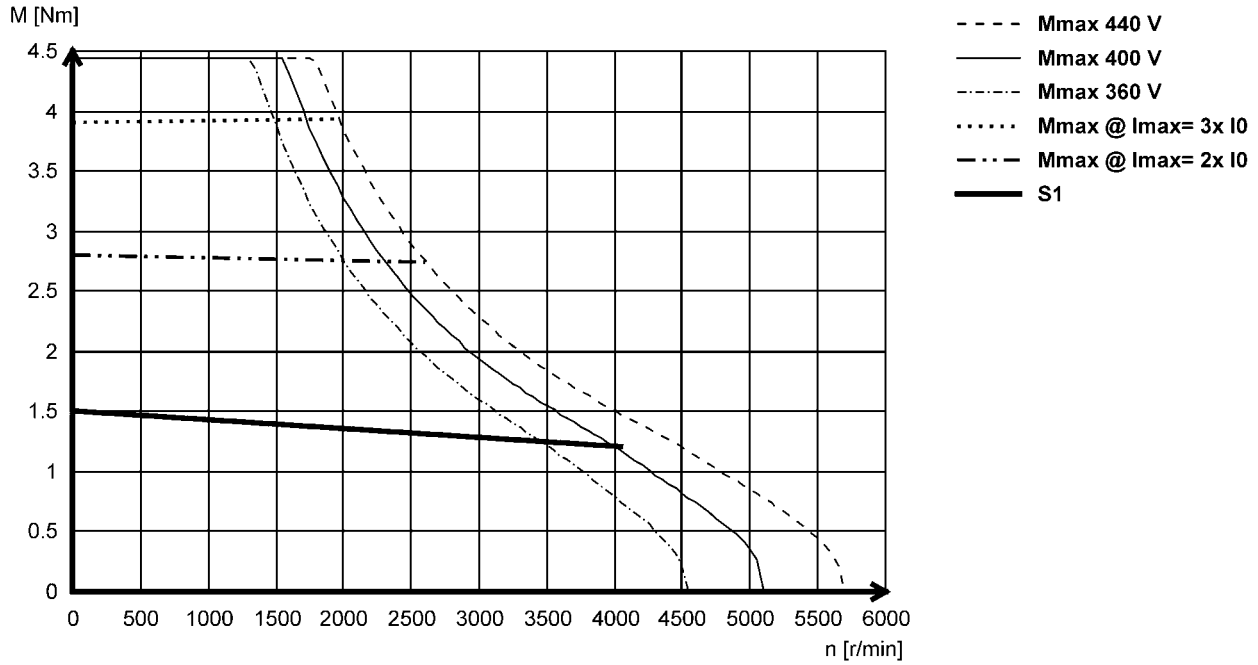


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

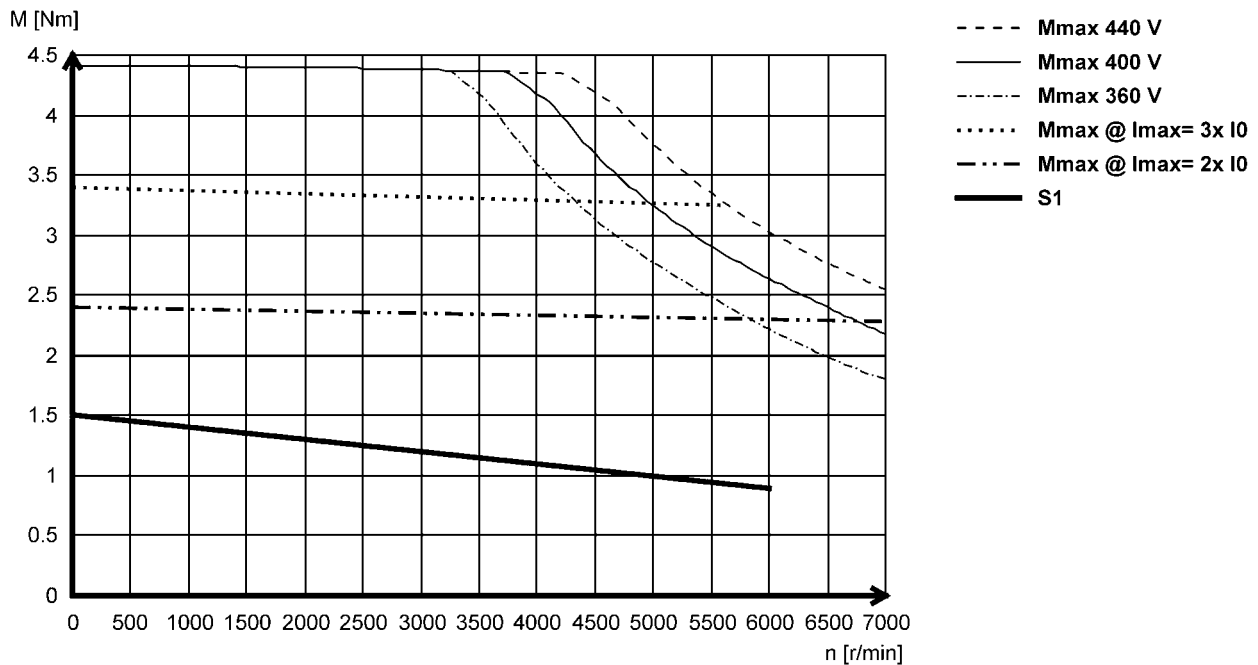


Mains connection 3x 400 V

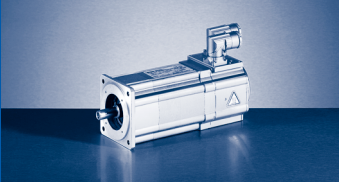
MCS06F41



MCS06F60



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

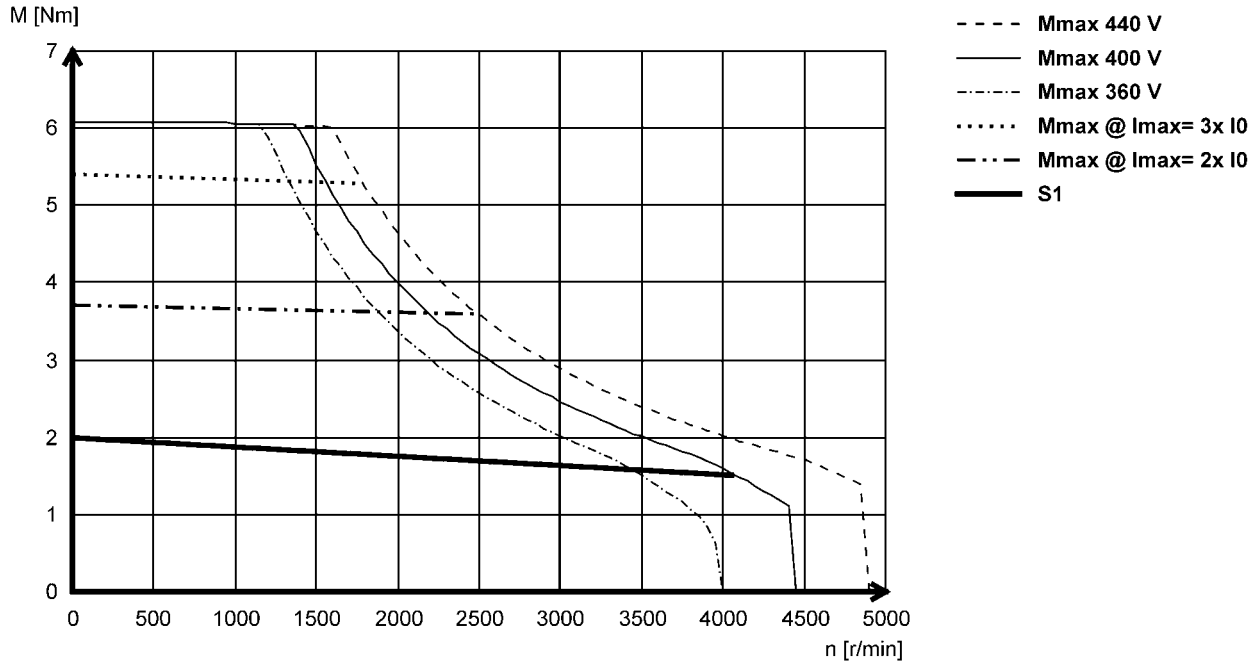


MCS synchronous servo motors

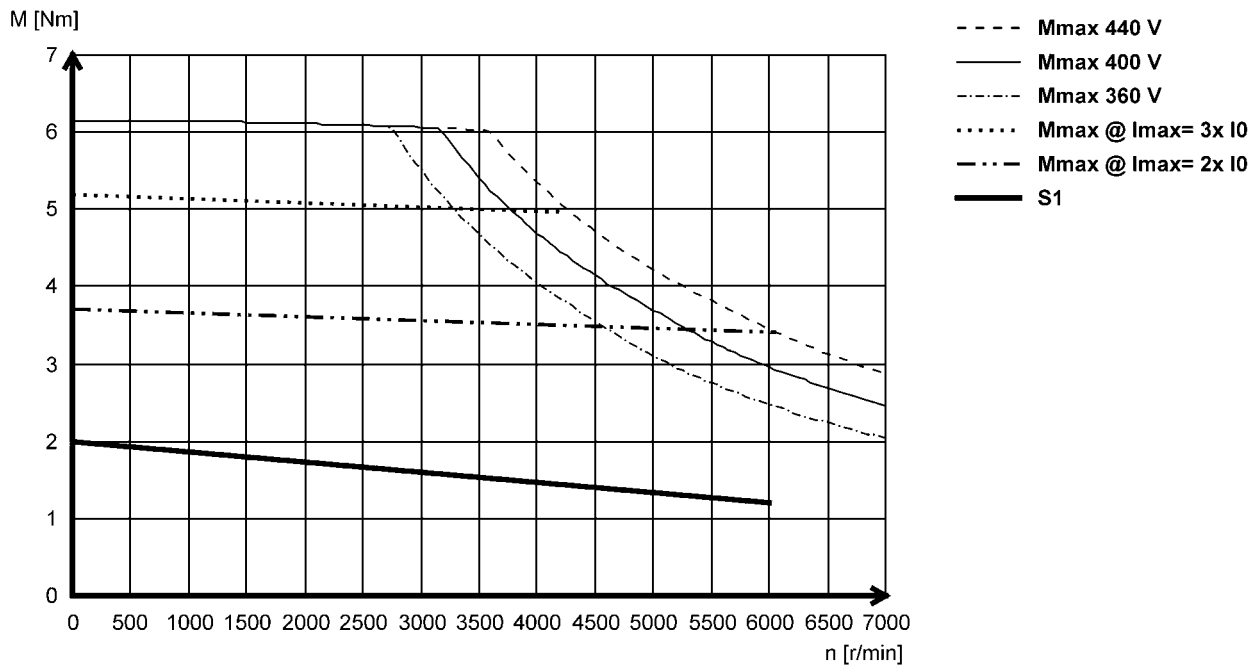
Torque characteristics

Mains connection 3x 400 V

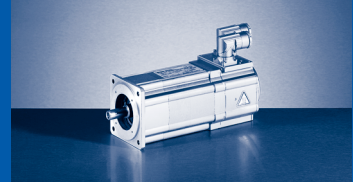
MCS06I41



MCS06I60

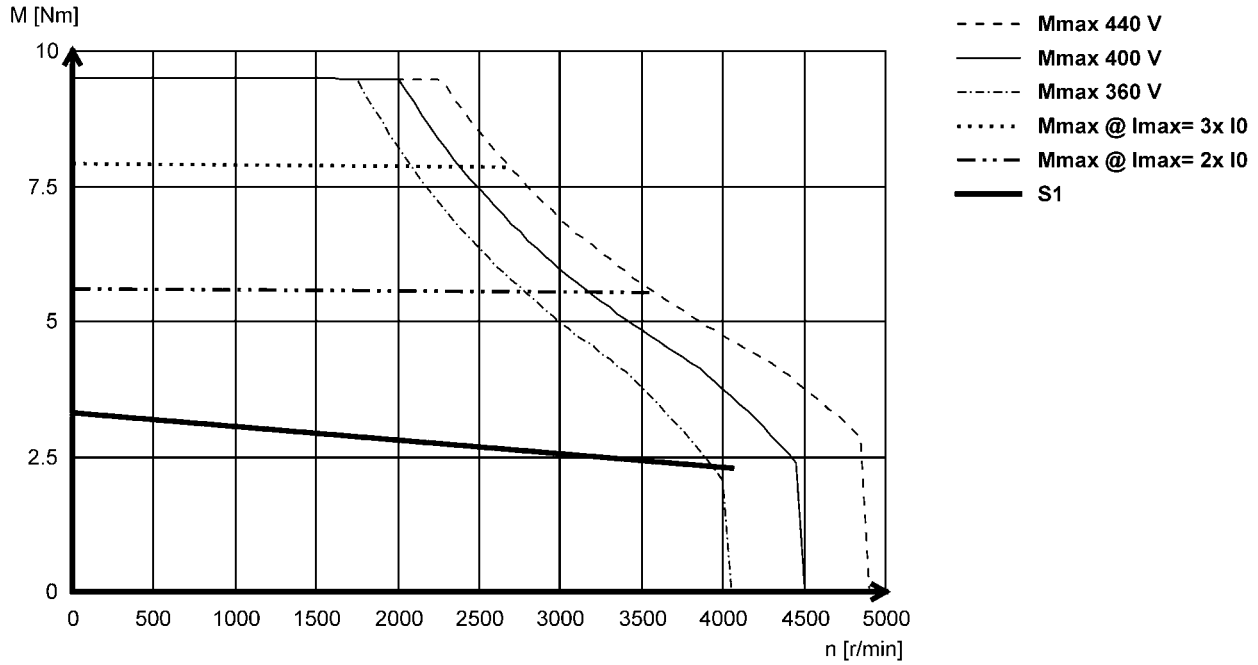


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

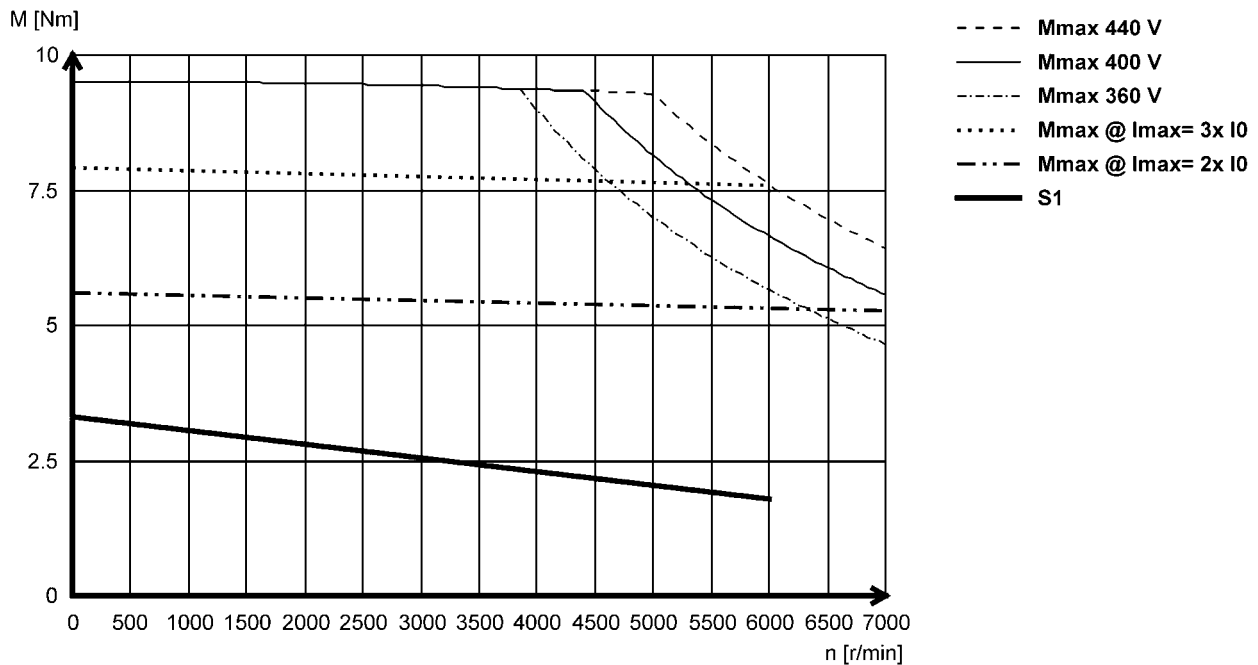


Mains connection 3x 400 V

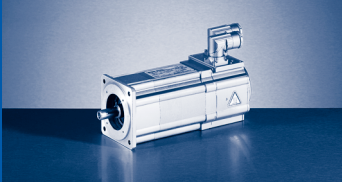
MCS09D41



MCS09D60



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

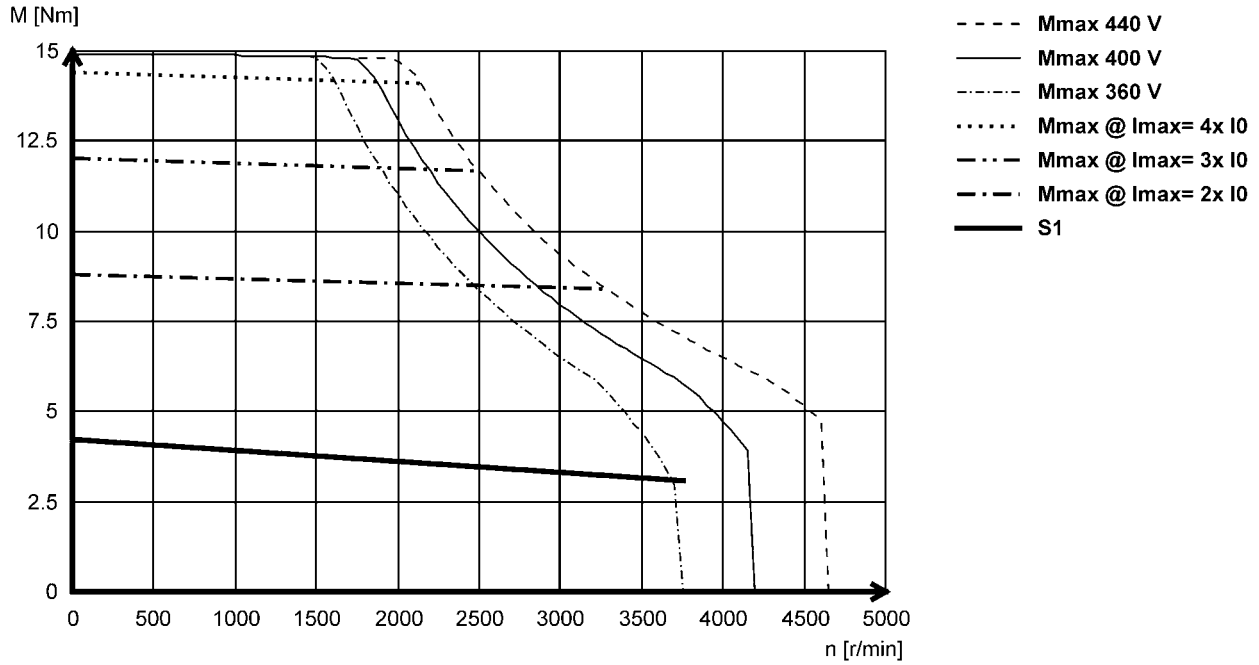


MCS synchronous servo motors

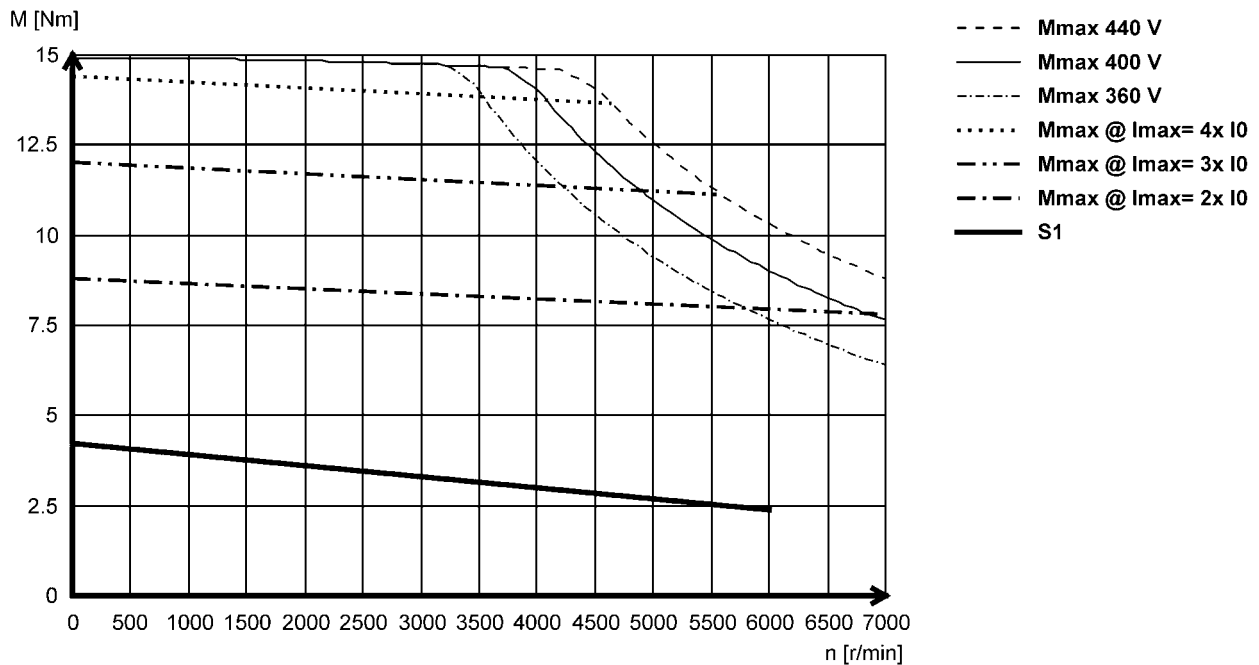
Torque characteristics

Mains connection 3x 400 V

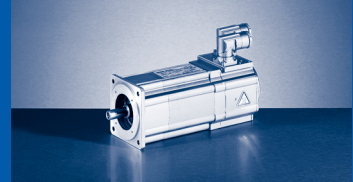
MCS09F38



MCS09F60

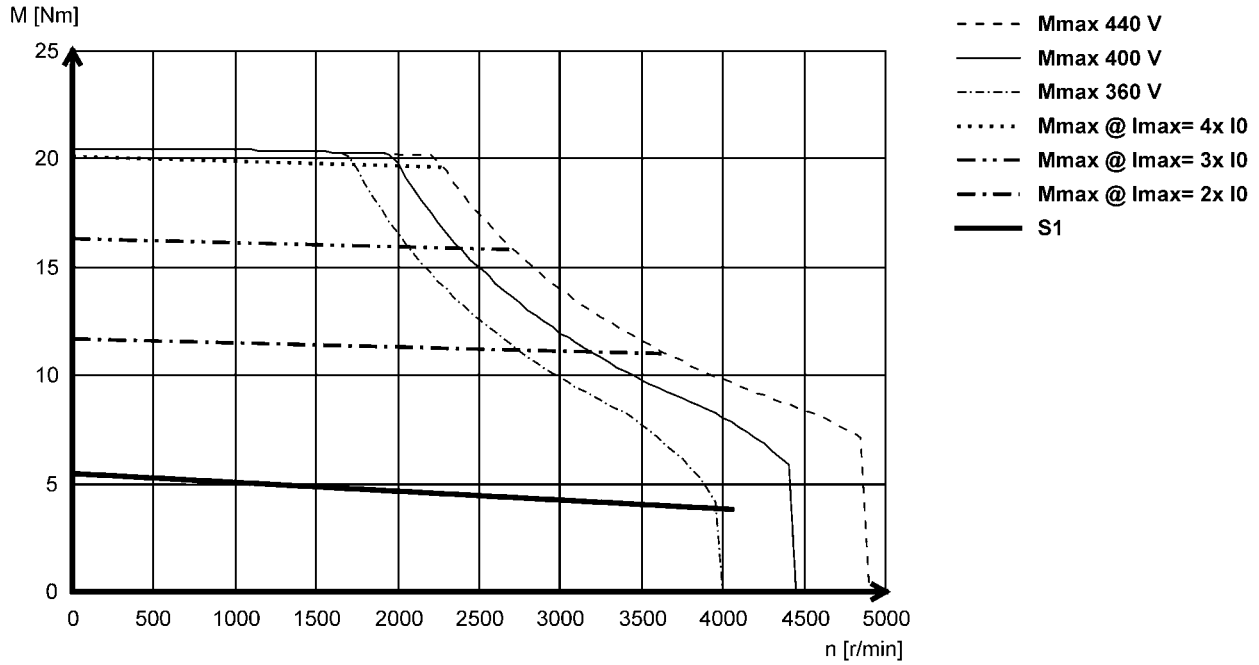


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

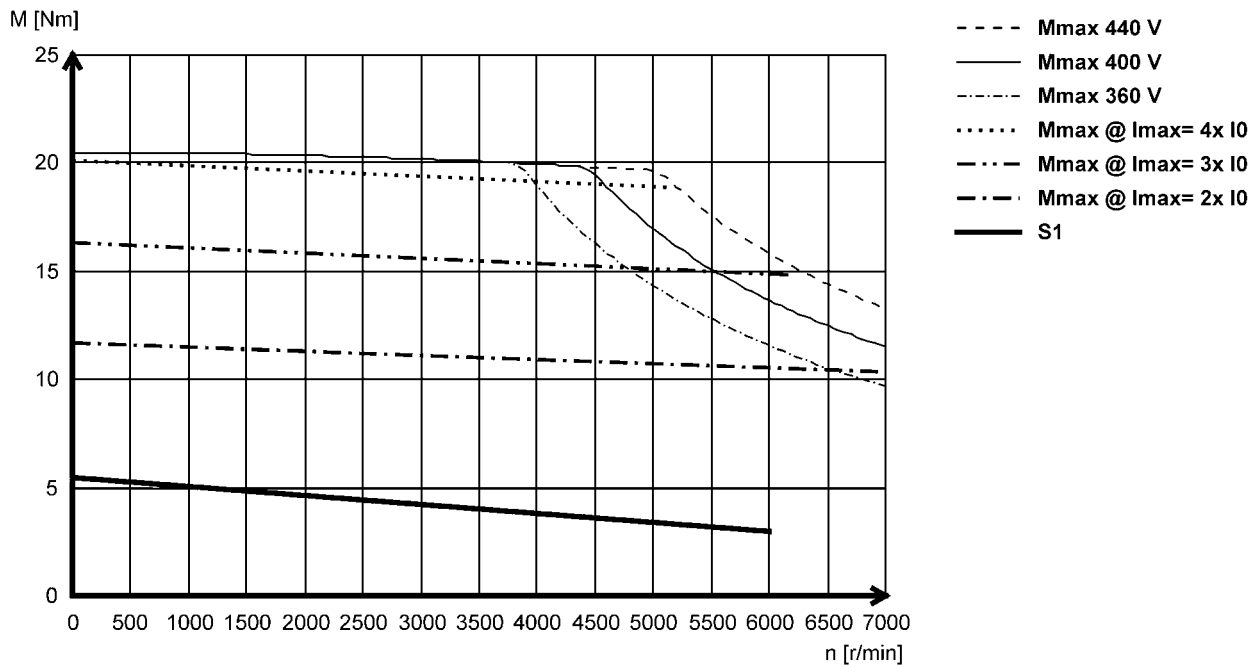


Mains connection 3x 400 V

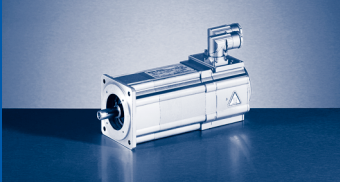
MCS09H41



MCS09H60



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

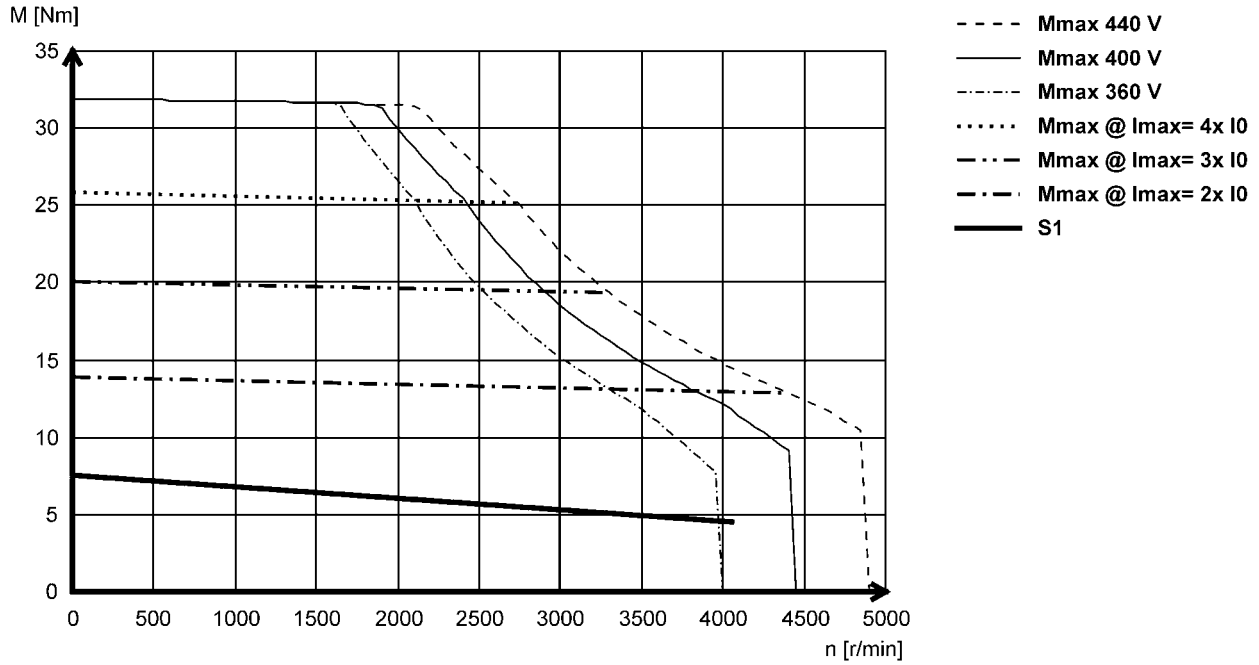


MCS synchronous servo motors

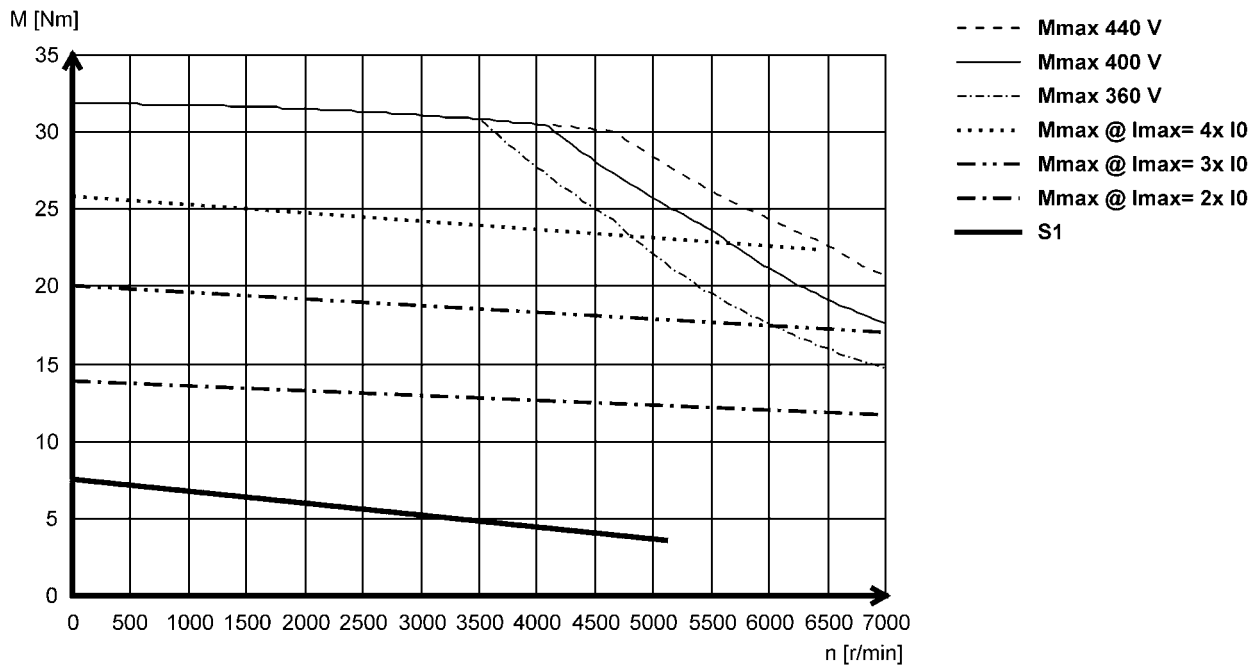
Torque characteristics

Mains connection 3x 400 V

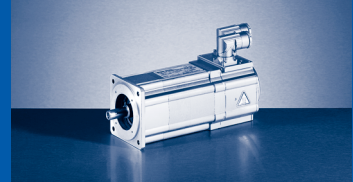
MCS09L41



MCS09L51

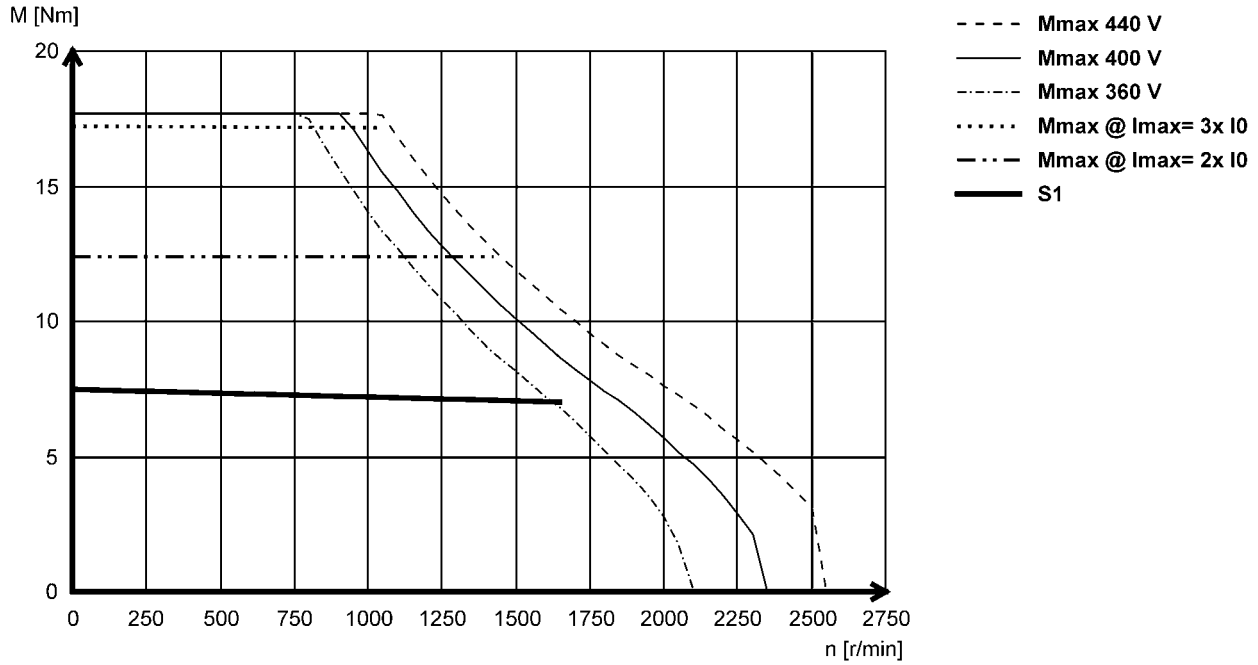


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

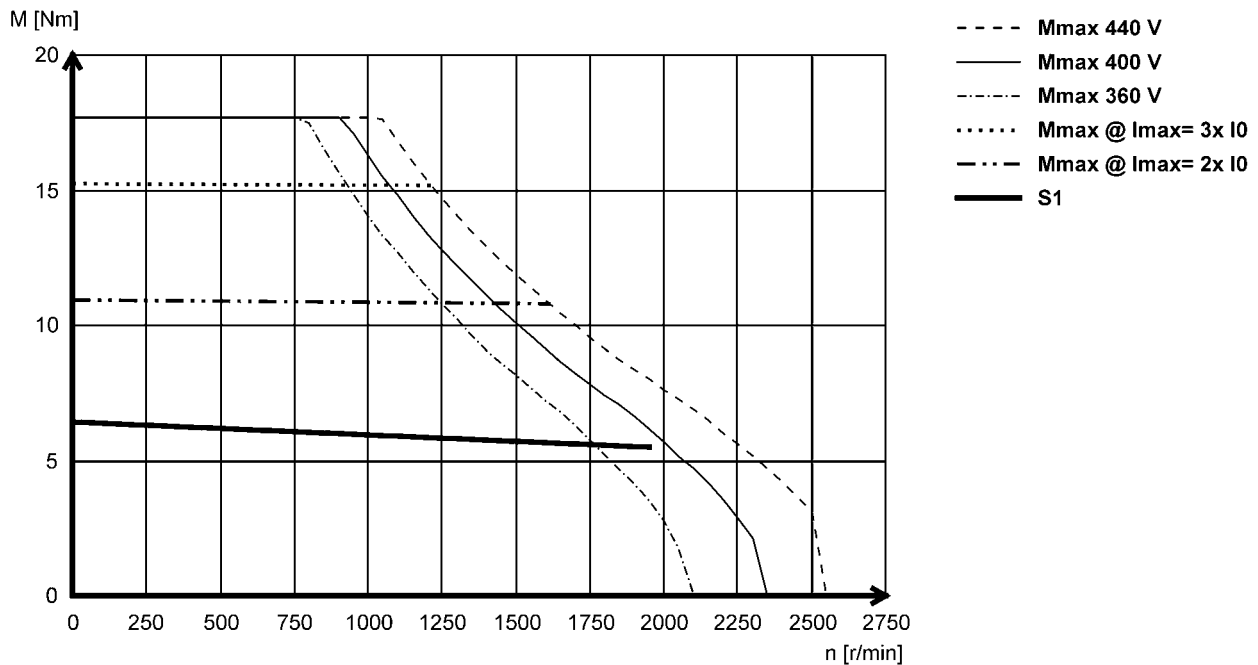


Mains connection 3x 400 V

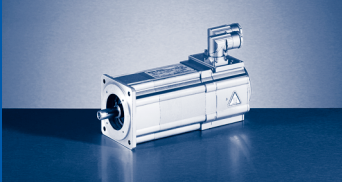
MCS12D17



MCS12D20



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

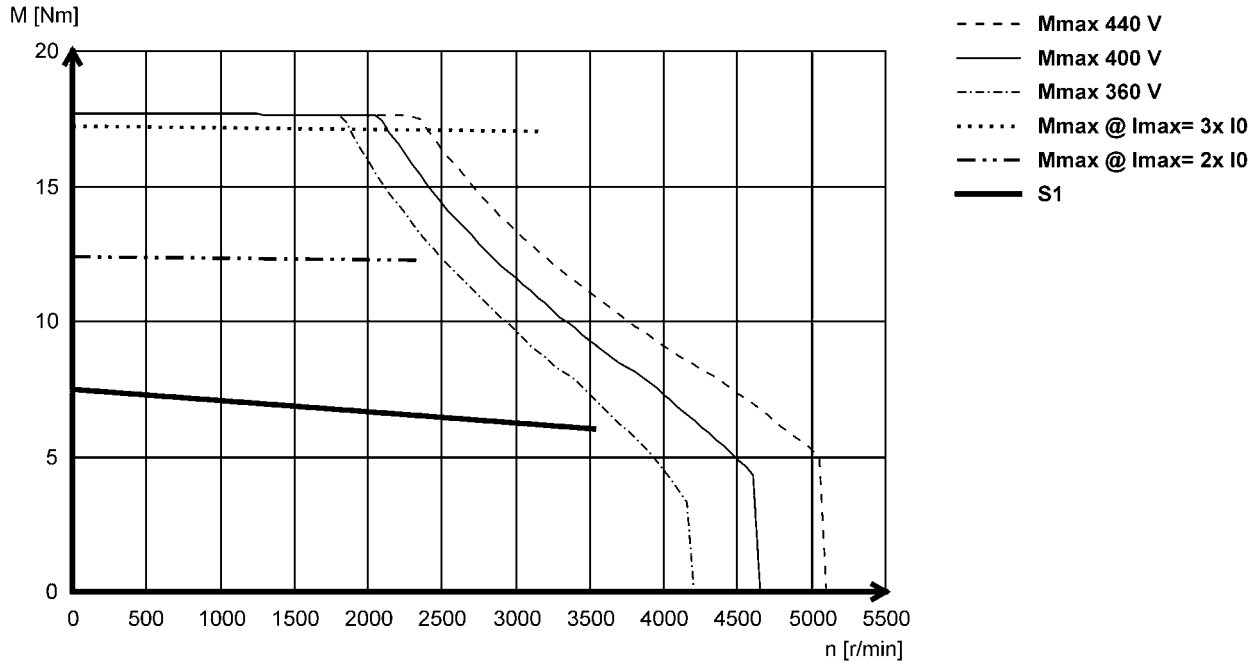


MCS synchronous servo motors

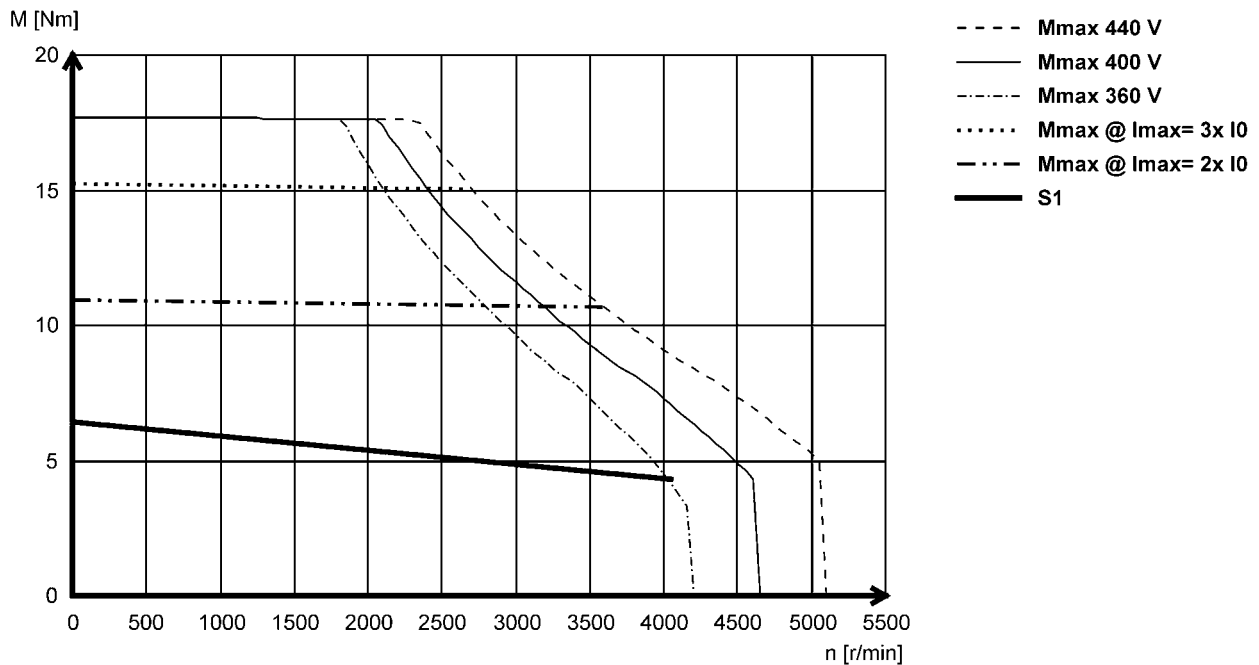
Torque characteristics

Mains connection 3x 400 V

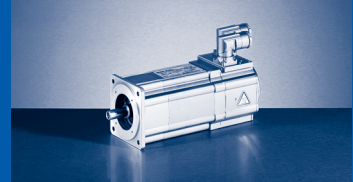
MCS12D35



MCS12D41

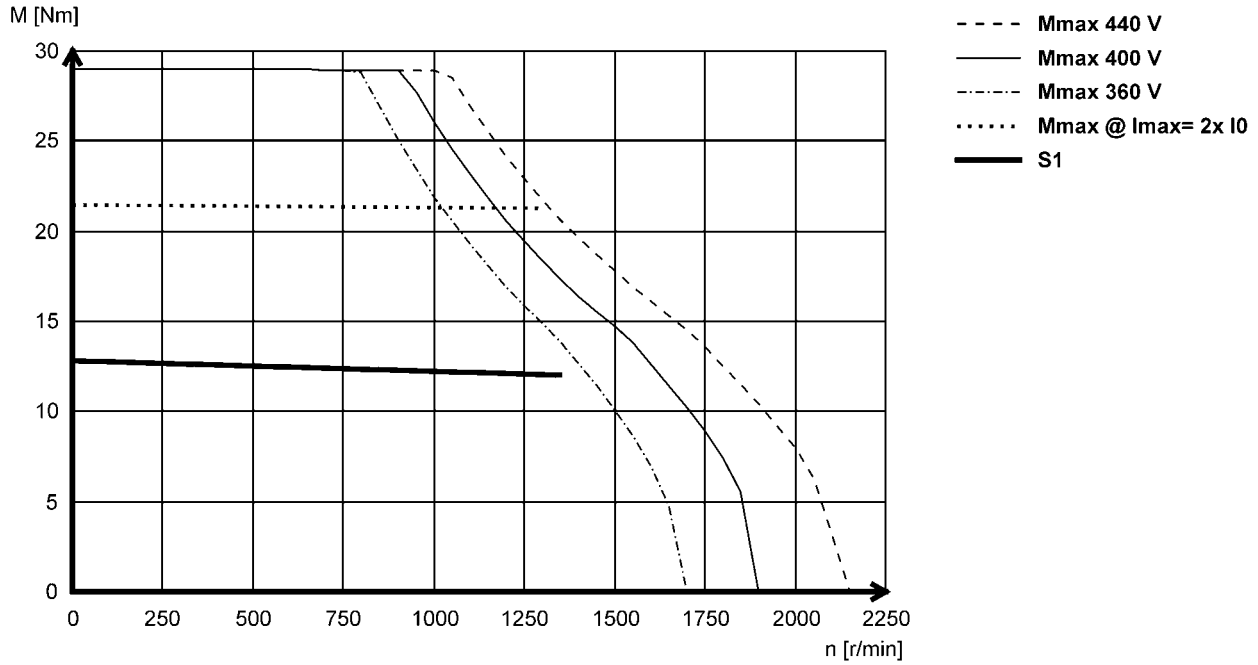


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

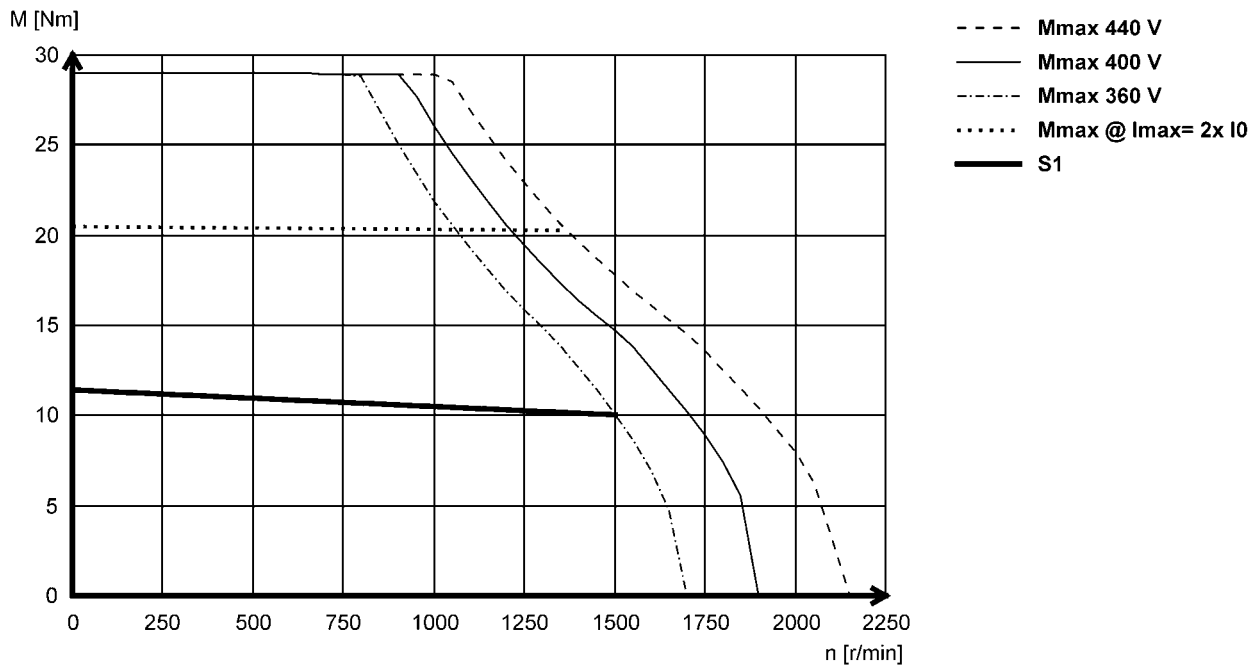


Mains connection 3x 400 V

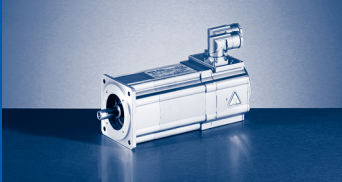
MCS12H14



MCS12H15



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

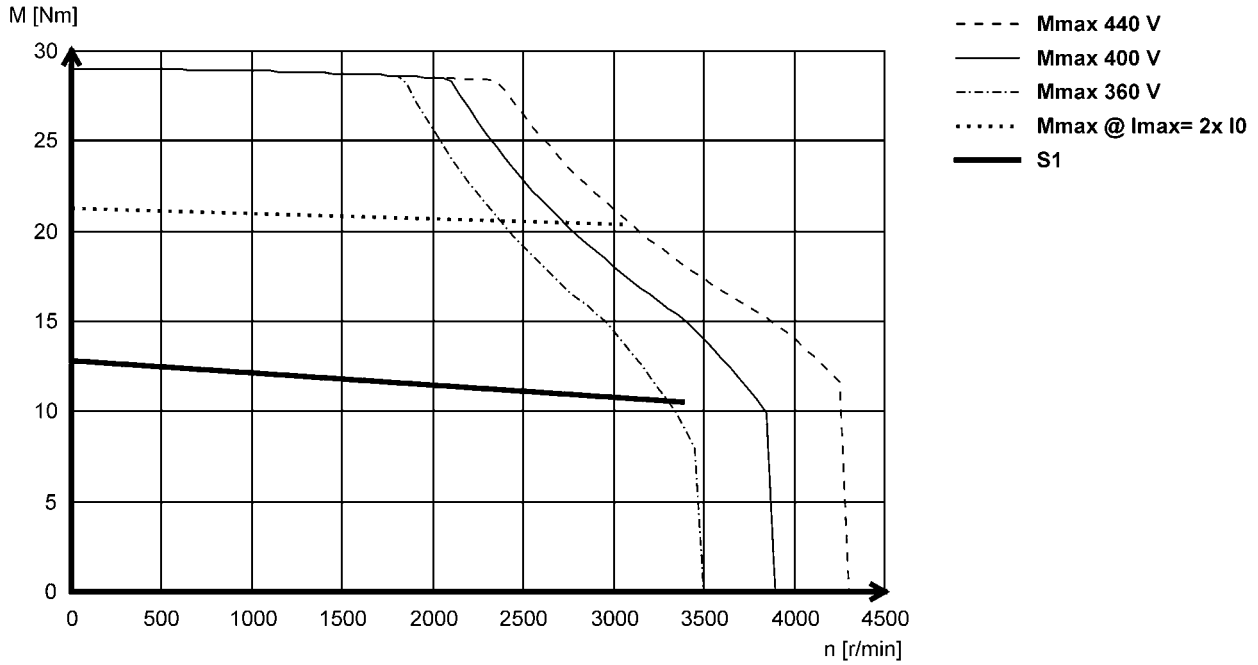


MCS synchronous servo motors

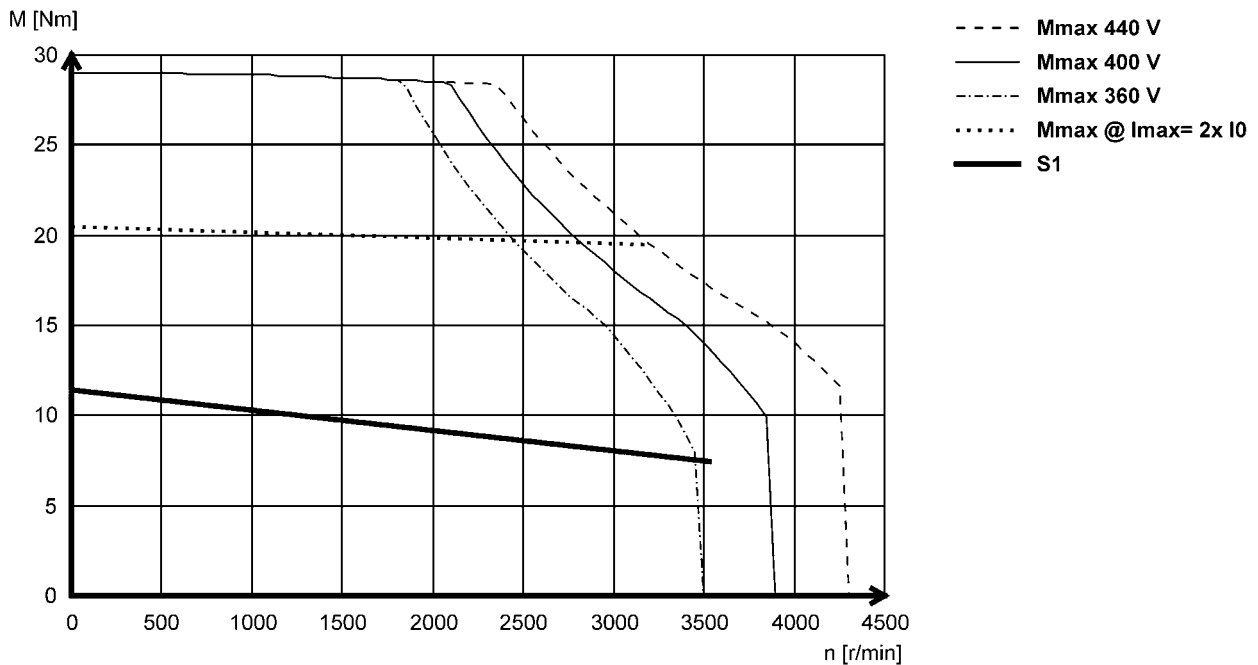
Torque characteristics

Mains connection 3x 400 V

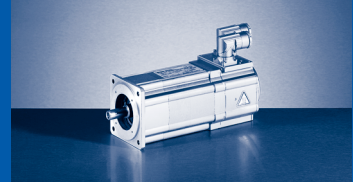
MCS12H34



MCS12H35

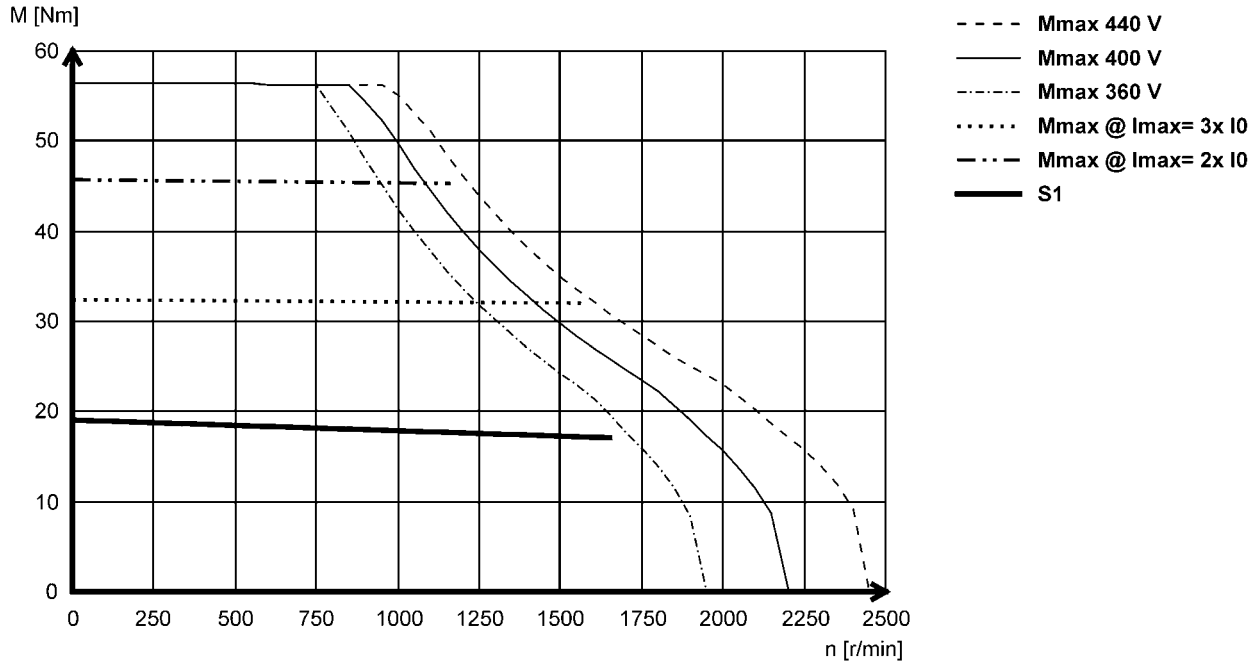


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

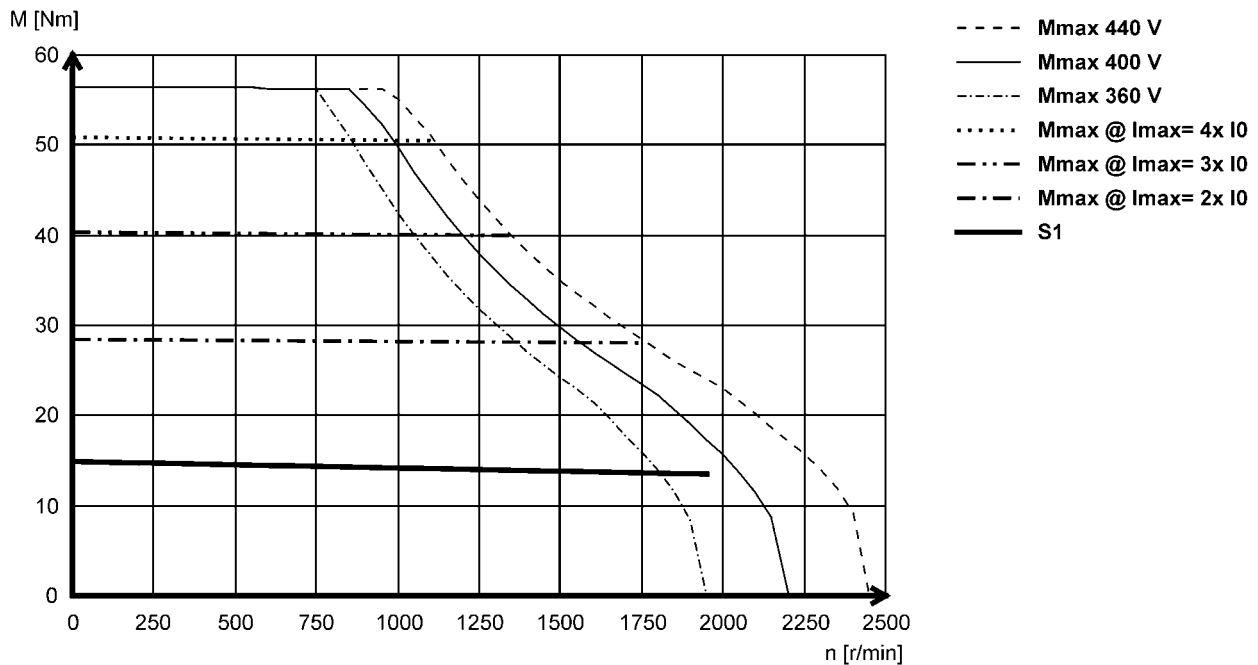


Mains connection 3x 400 V

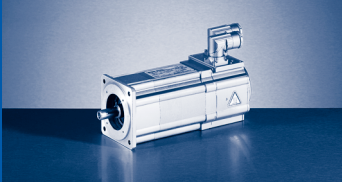
MCS12L17



MCS12L20



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

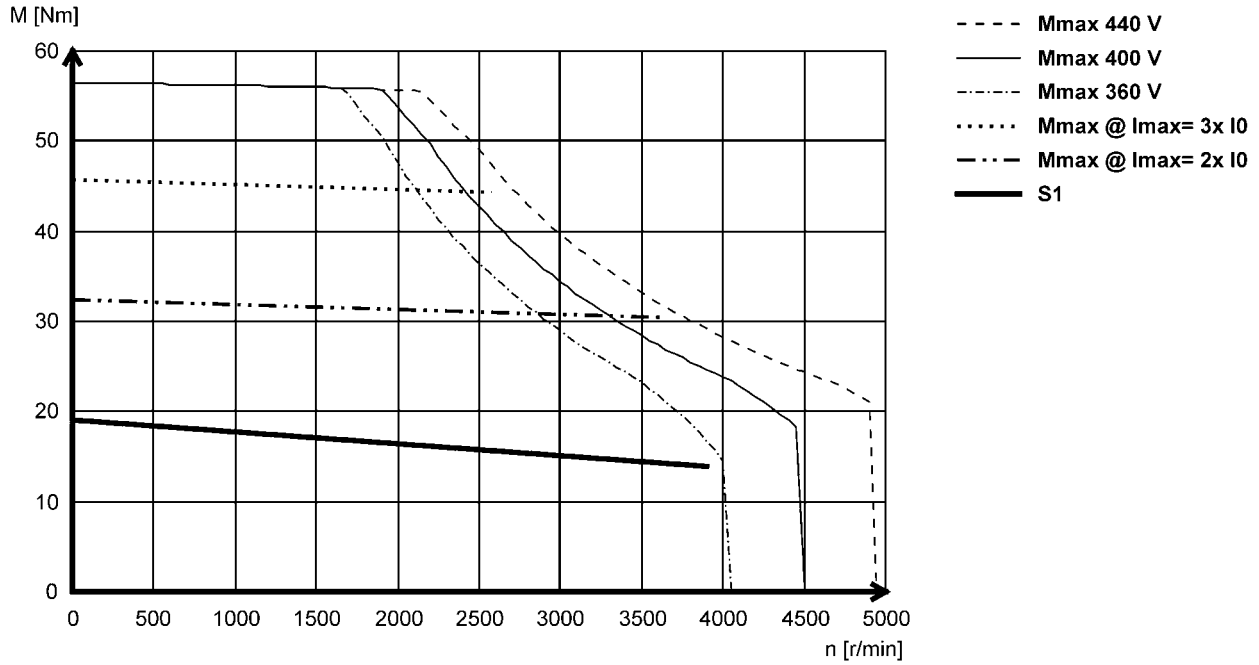


MCS synchronous servo motors

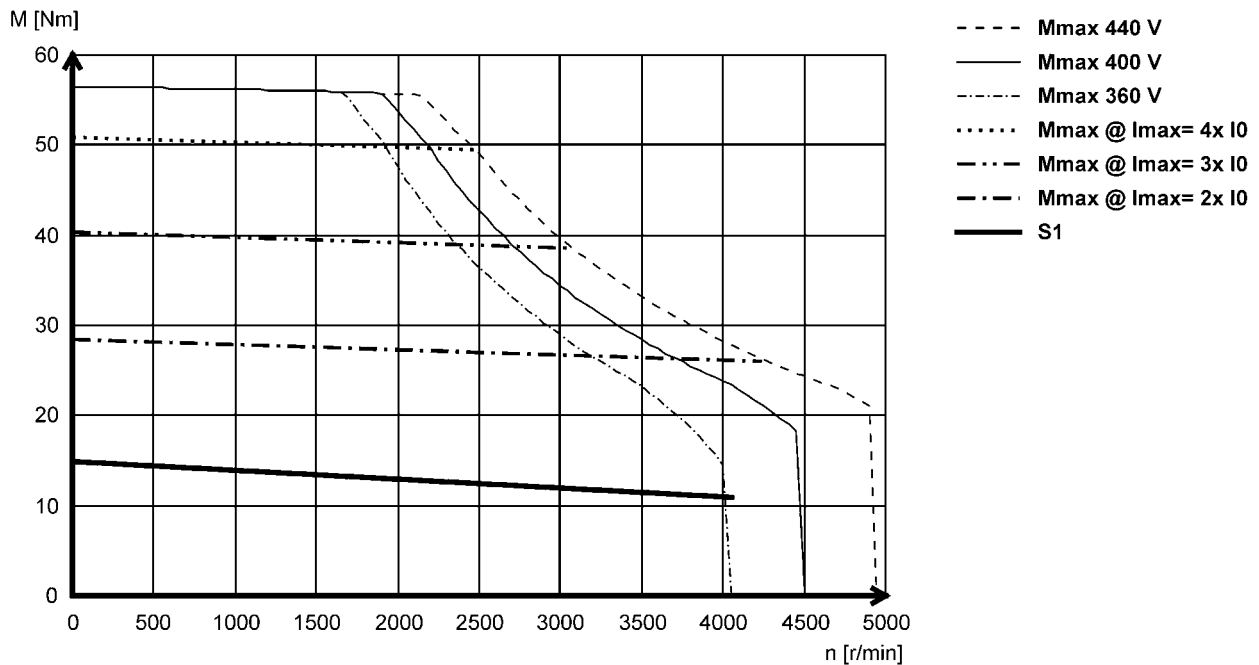
Torque characteristics

Mains connection 3x 400 V

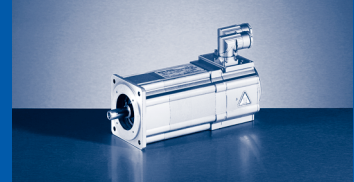
MCS12L39



MCS12L41

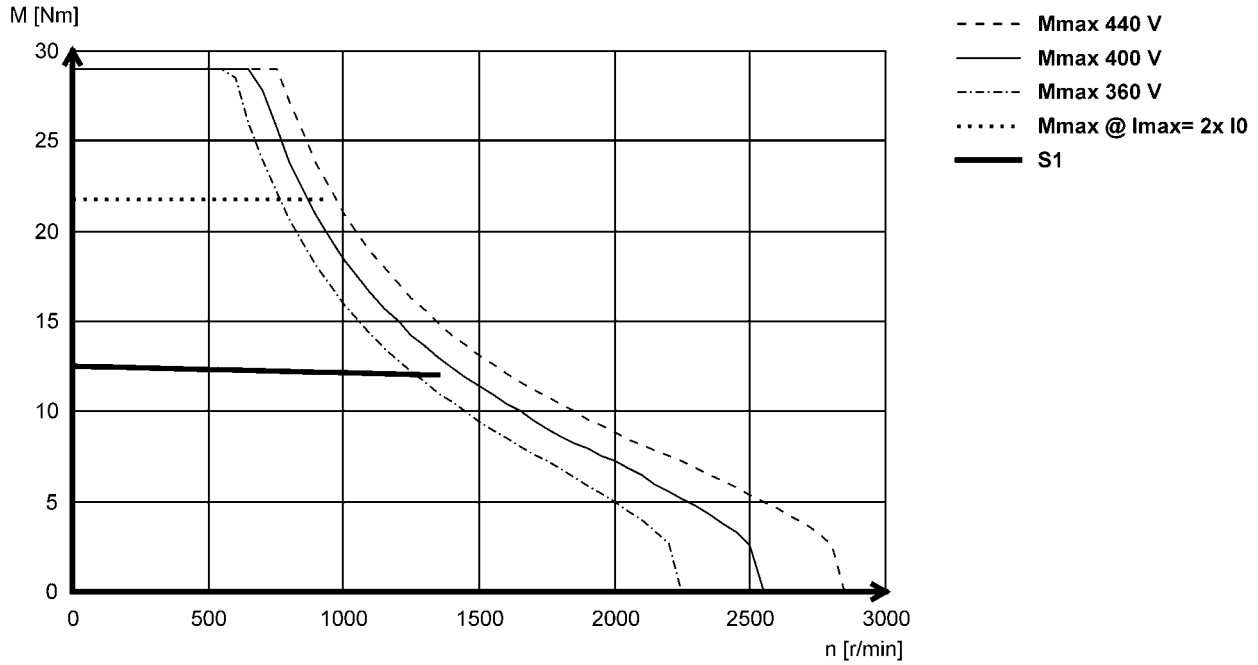


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

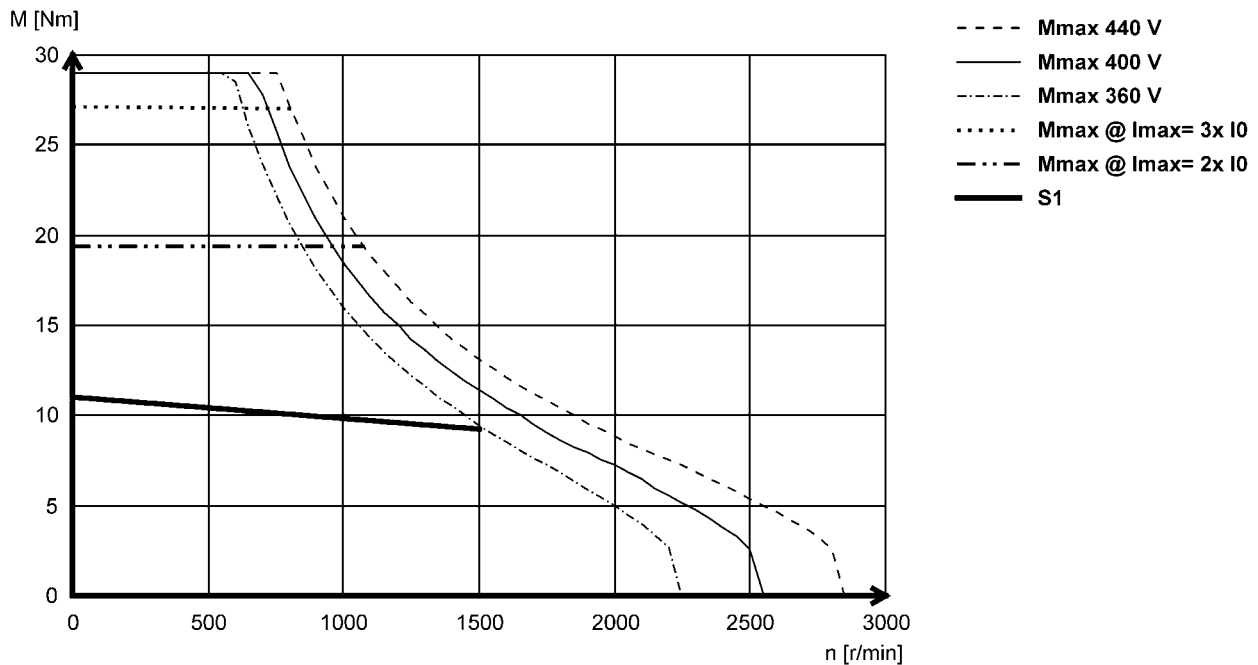


Mains connection 3x 400 V

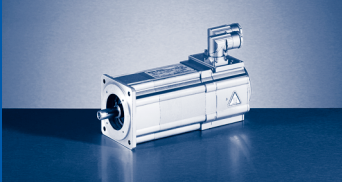
MCS14D14



MCS14D15



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

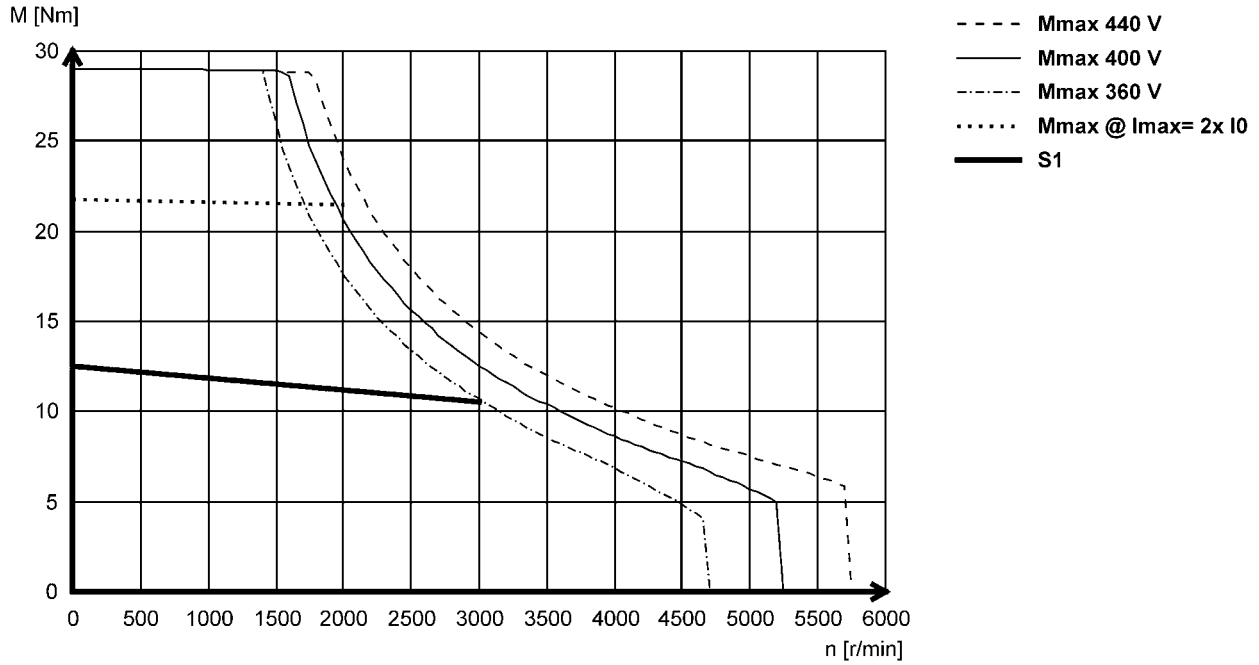


MCS synchronous servo motors

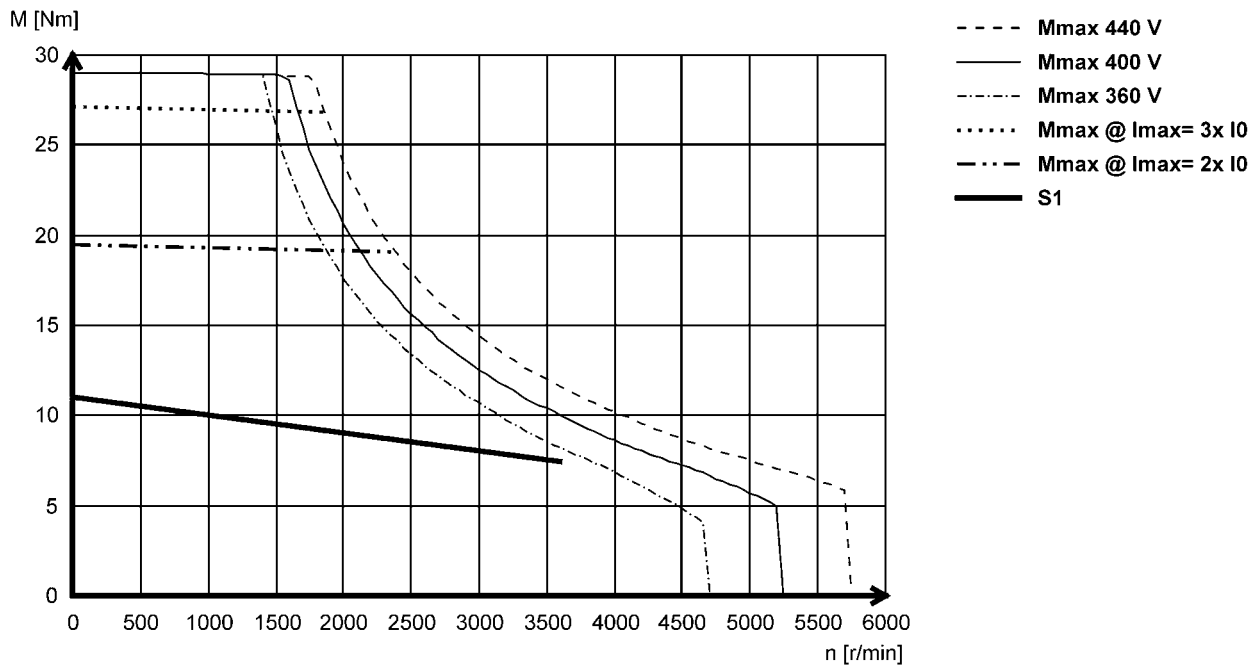
Torque characteristics

Mains connection 3x 400 V

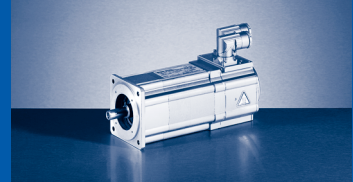
MCS14D30



MCS14D36

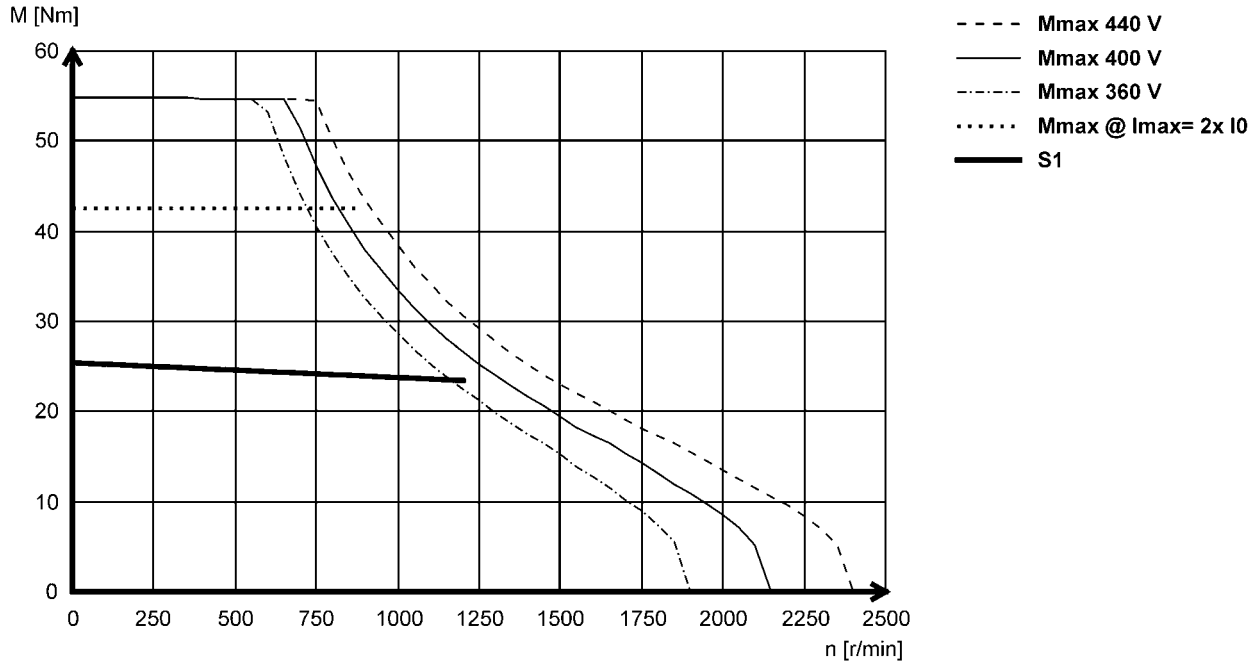


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

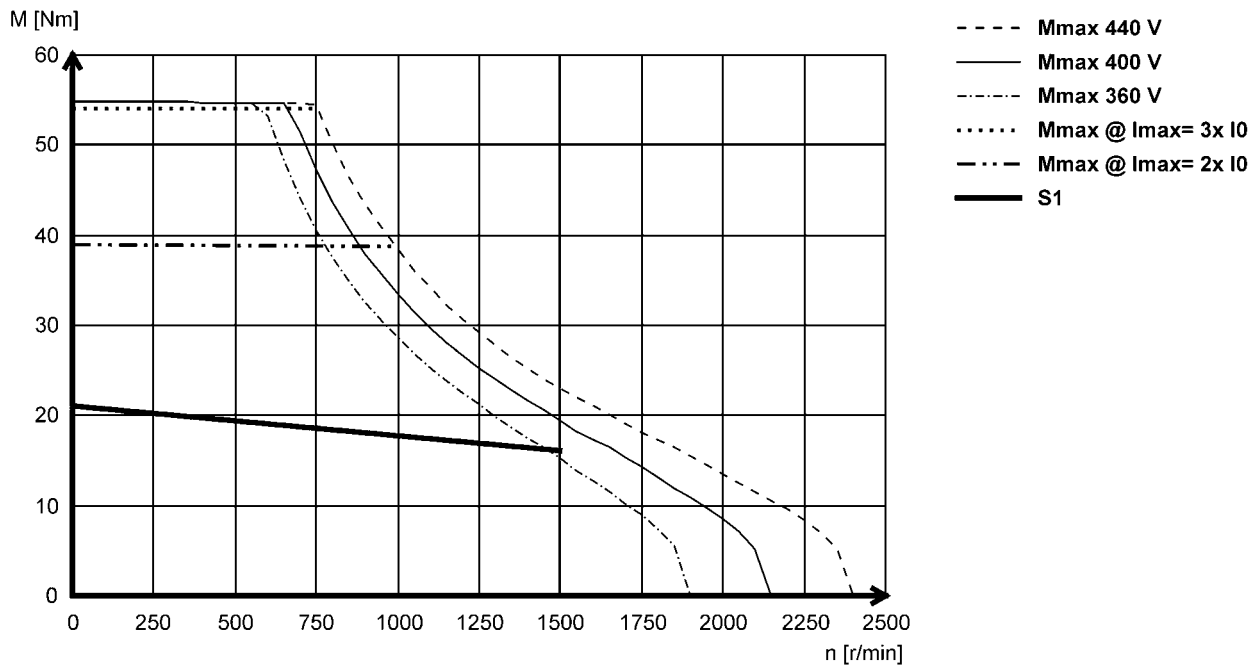


Mains connection 3x 400 V

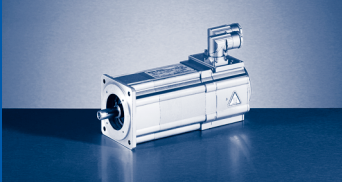
MCS14H12



MCS14H15



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

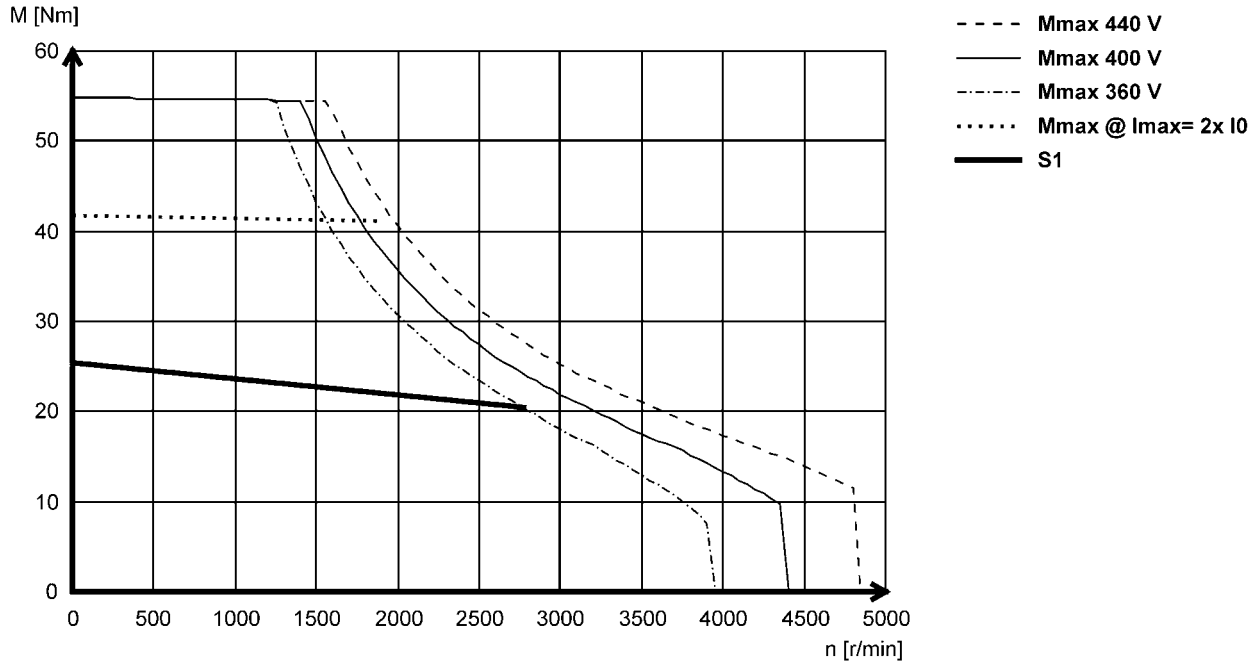


MCS synchronous servo motors

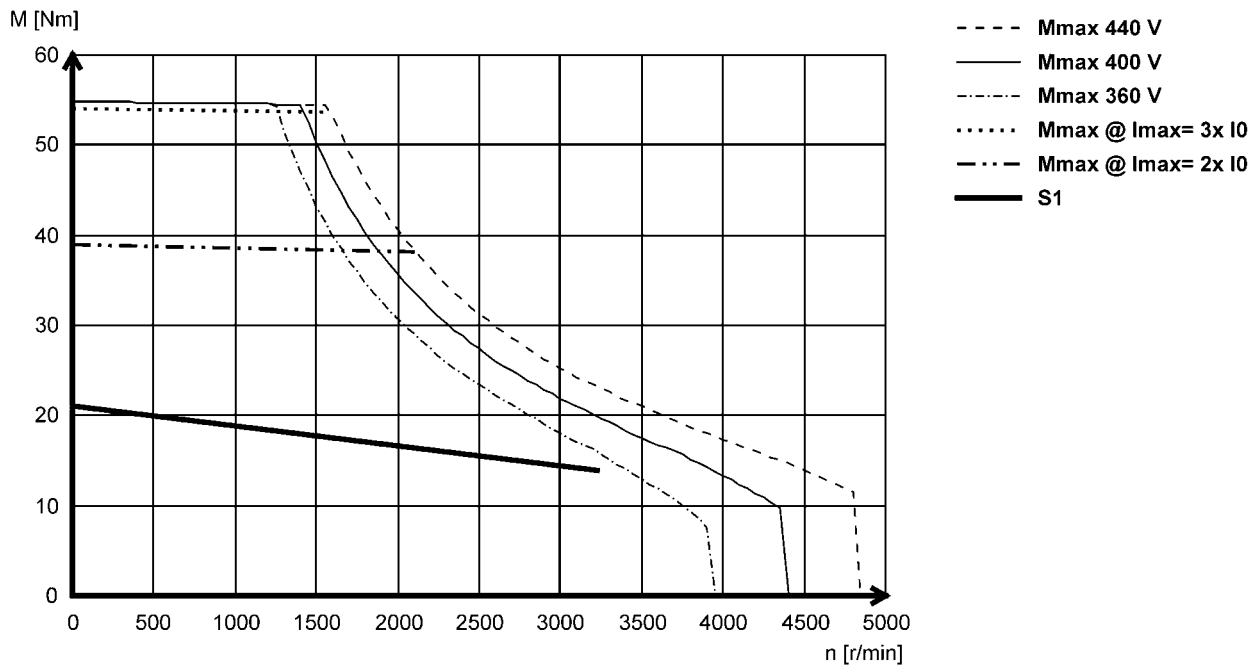
Torque characteristics

Mains connection 3x 400 V

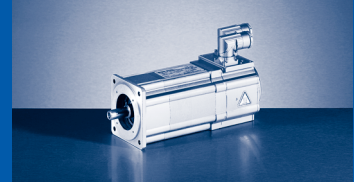
MCS14H28



MCS14H32

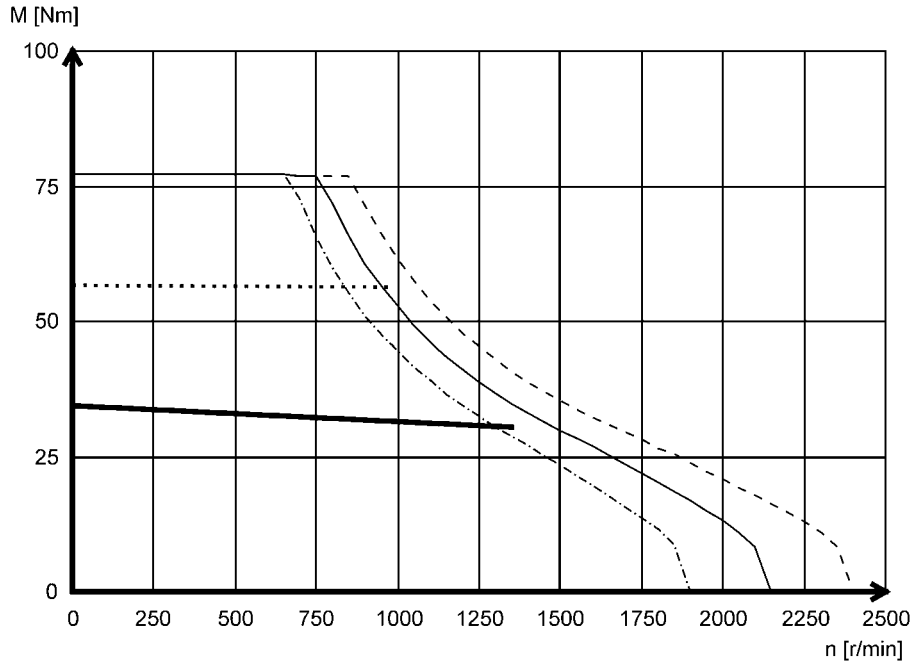


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.



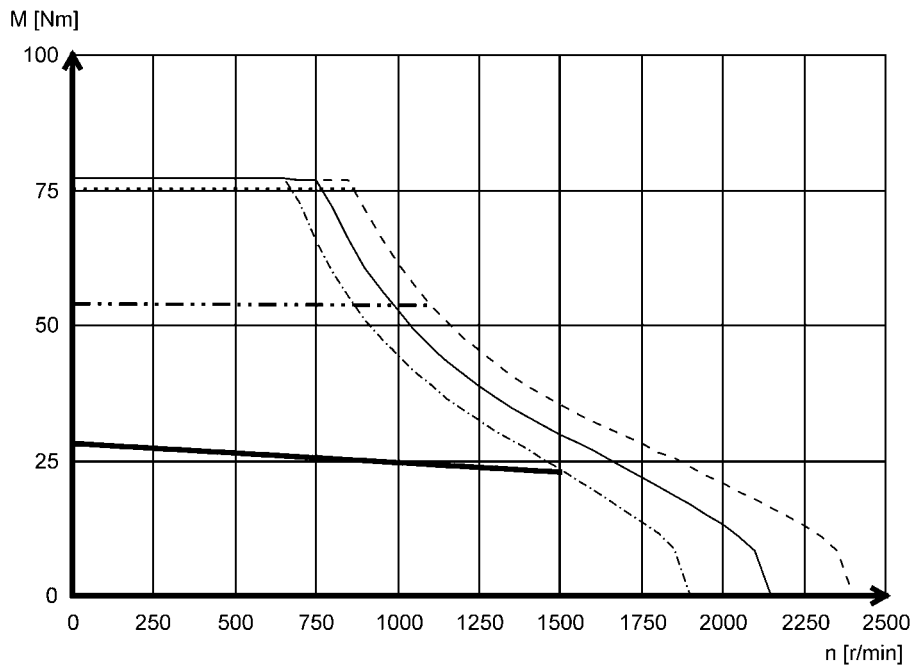
Mains connection 3x 400 V

MCS14L14



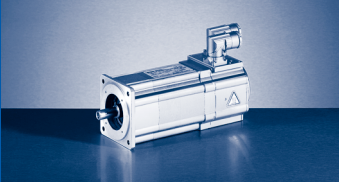
- Mmax 440 V
- Mmax 400 V
- · - · Mmax 360 V
- Mmax @ Imax= 2x I0
- S1

MCS14L15



- Mmax 440 V
- Mmax 400 V
- · - · Mmax 360 V
- Mmax @ Imax= 3x I0
- · - · Mmax @ Imax= 2x I0
- S1

► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

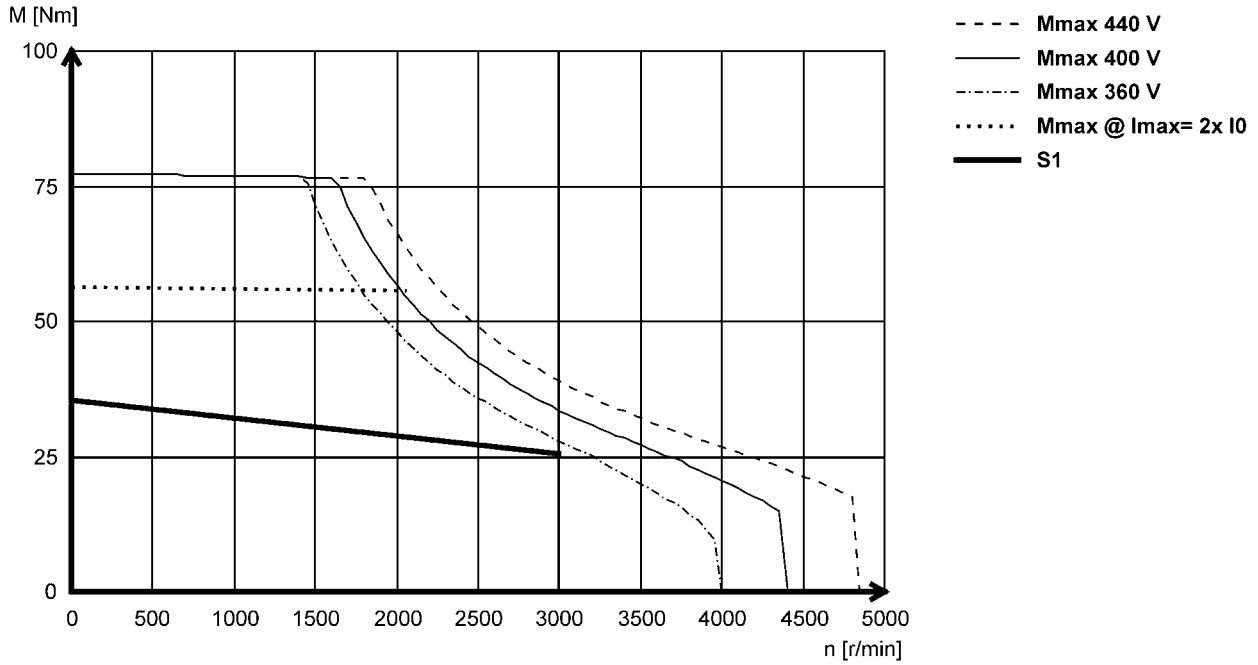


MCS synchronous servo motors

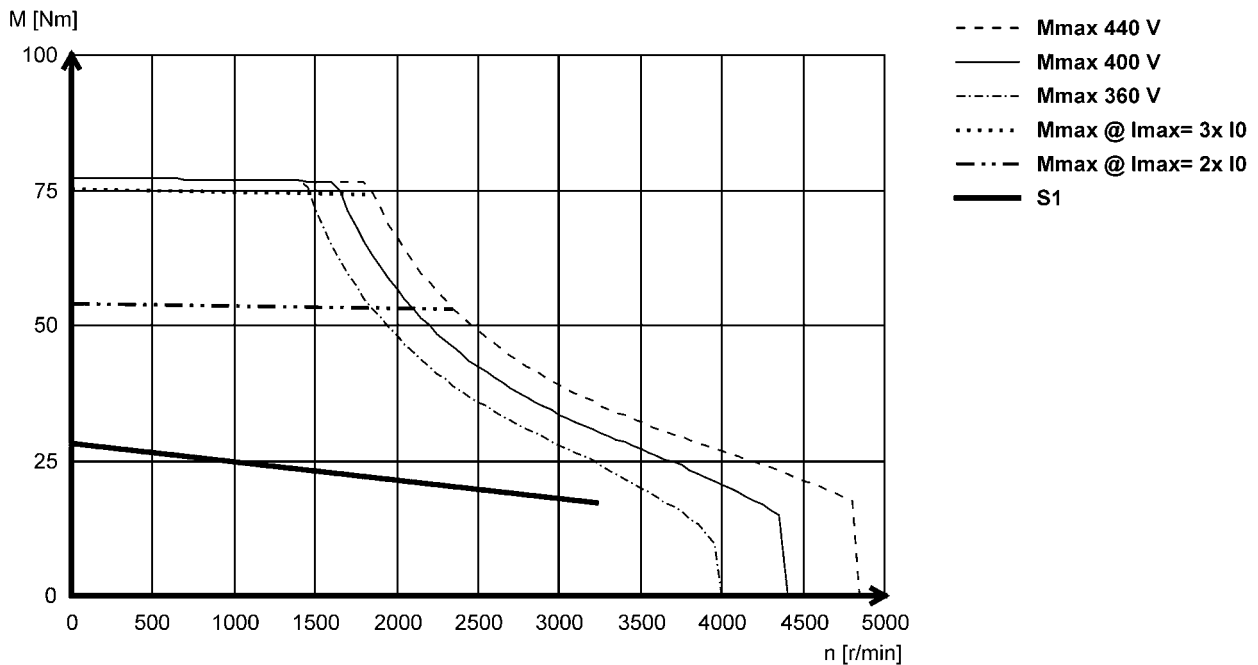
Torque characteristics

Mains connection 3x 400 V

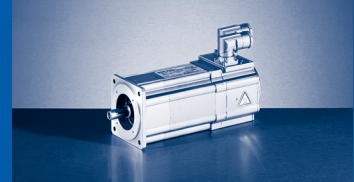
MCS14L30



MCS14L32

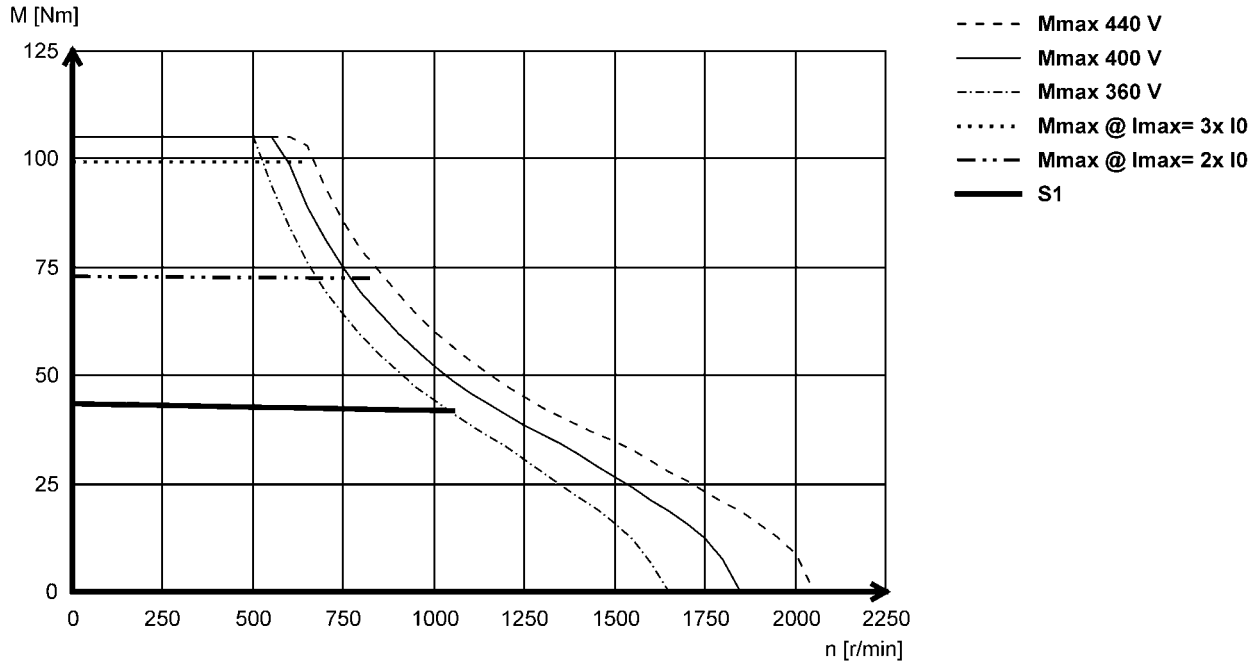


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

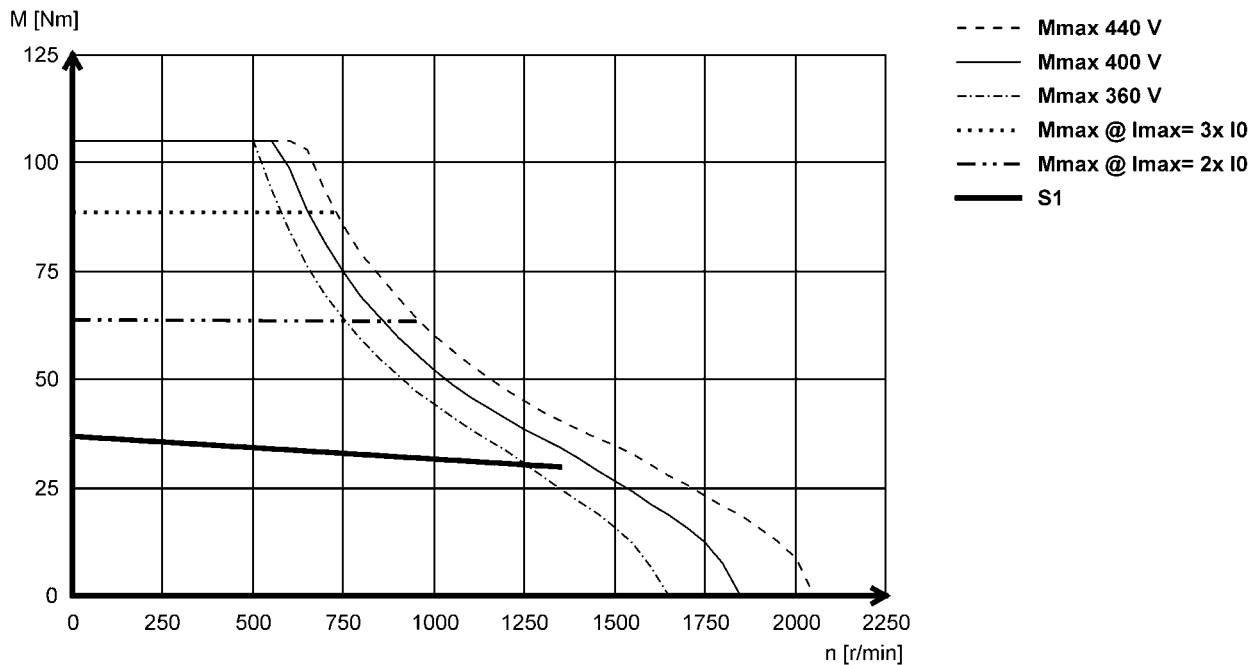


Mains connection 3x 400 V

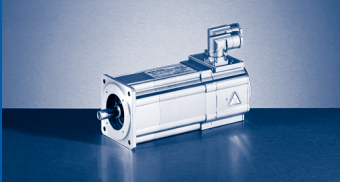
MCS14P11



MCS14P14



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

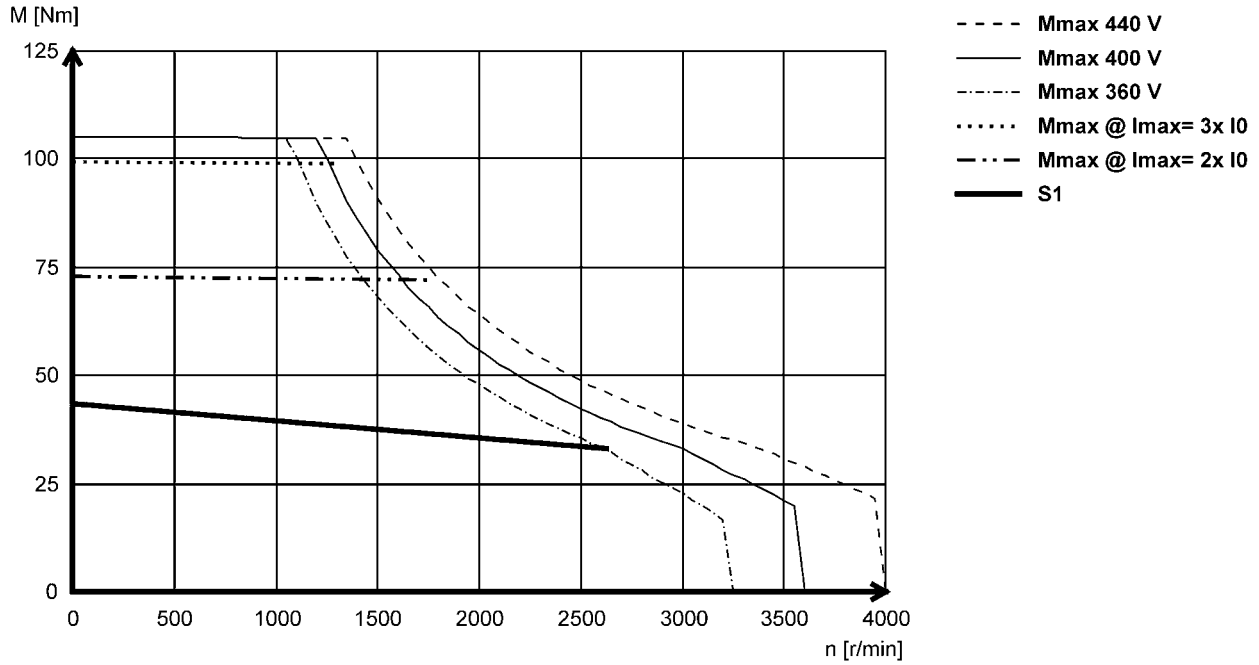


MCS synchronous servo motors

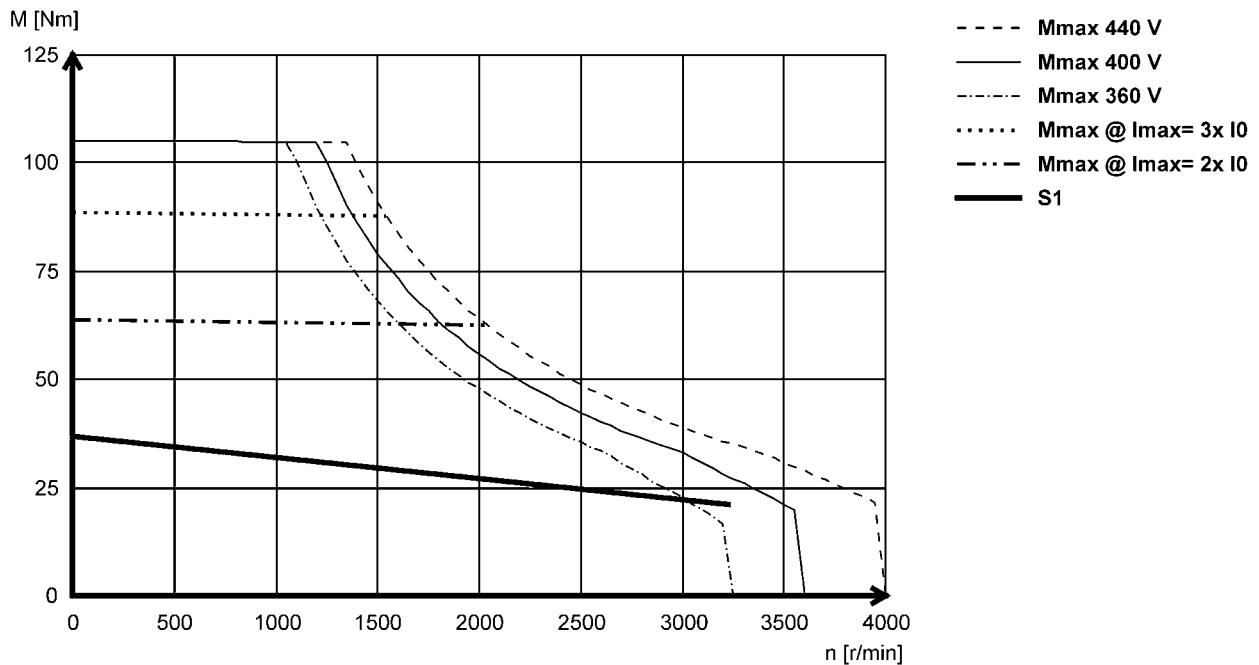
Torque characteristics

Mains connection 3x 400 V

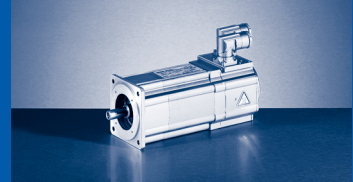
MCS14P26



MCS14P32

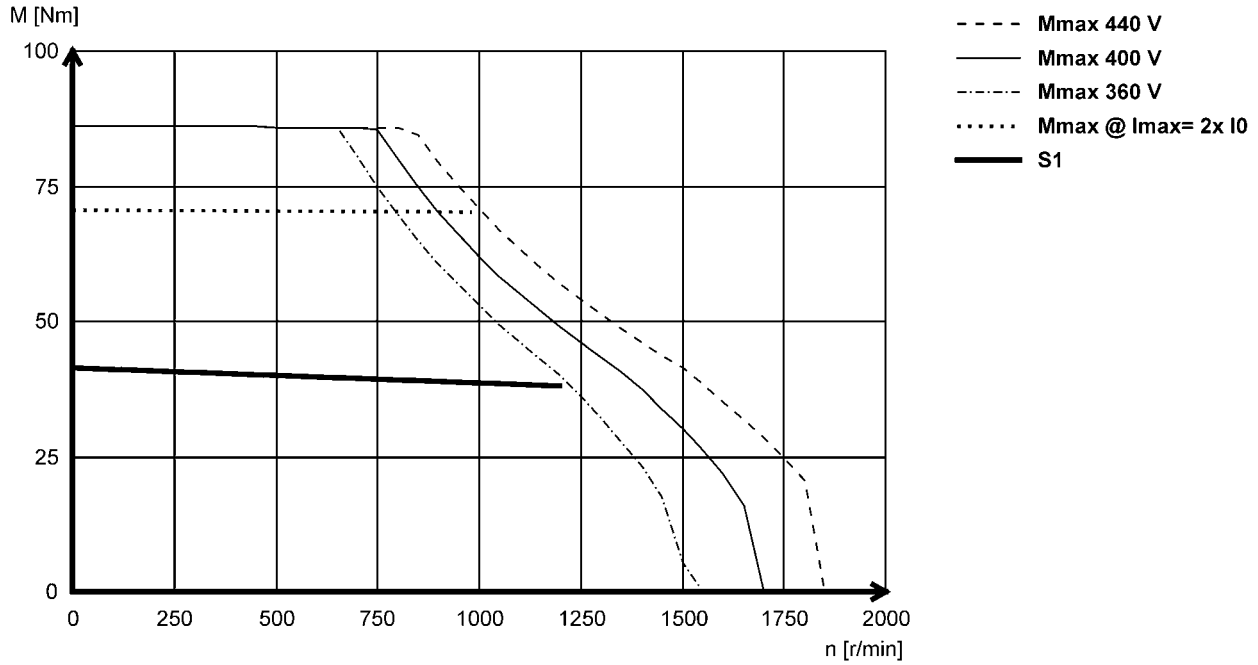


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

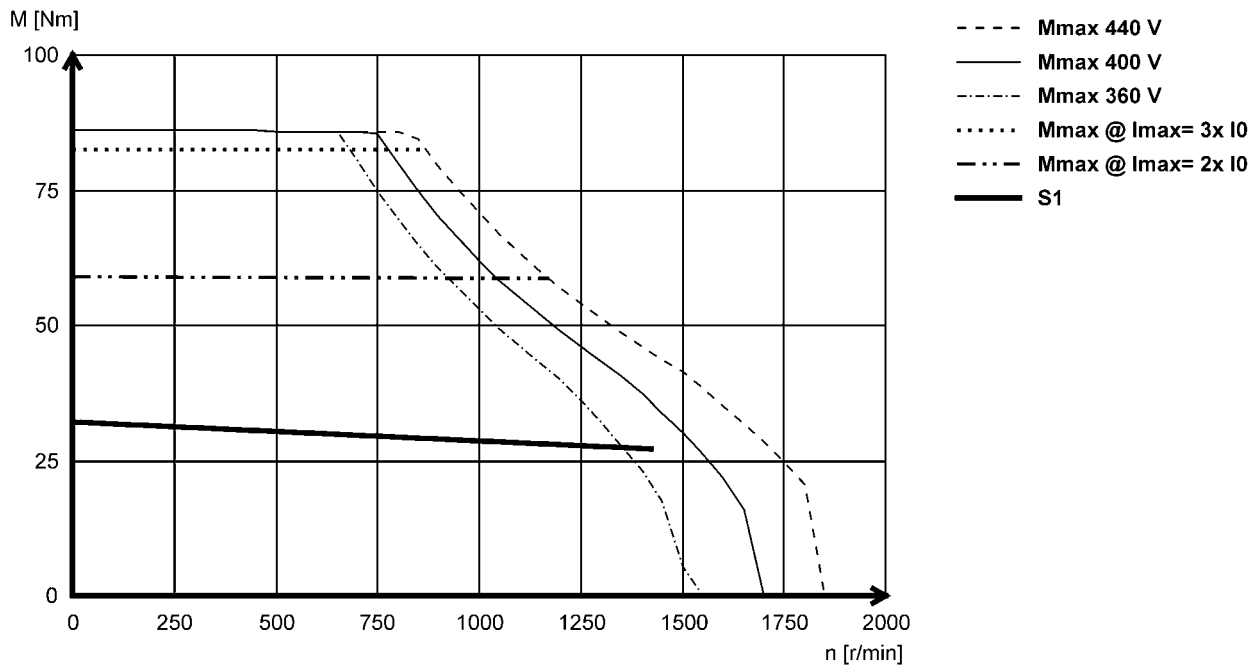


Mains connection 3x 400 V

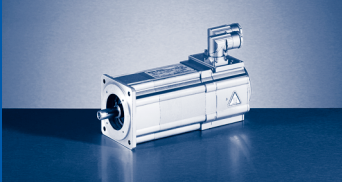
MCS19F12



MCS19F14



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

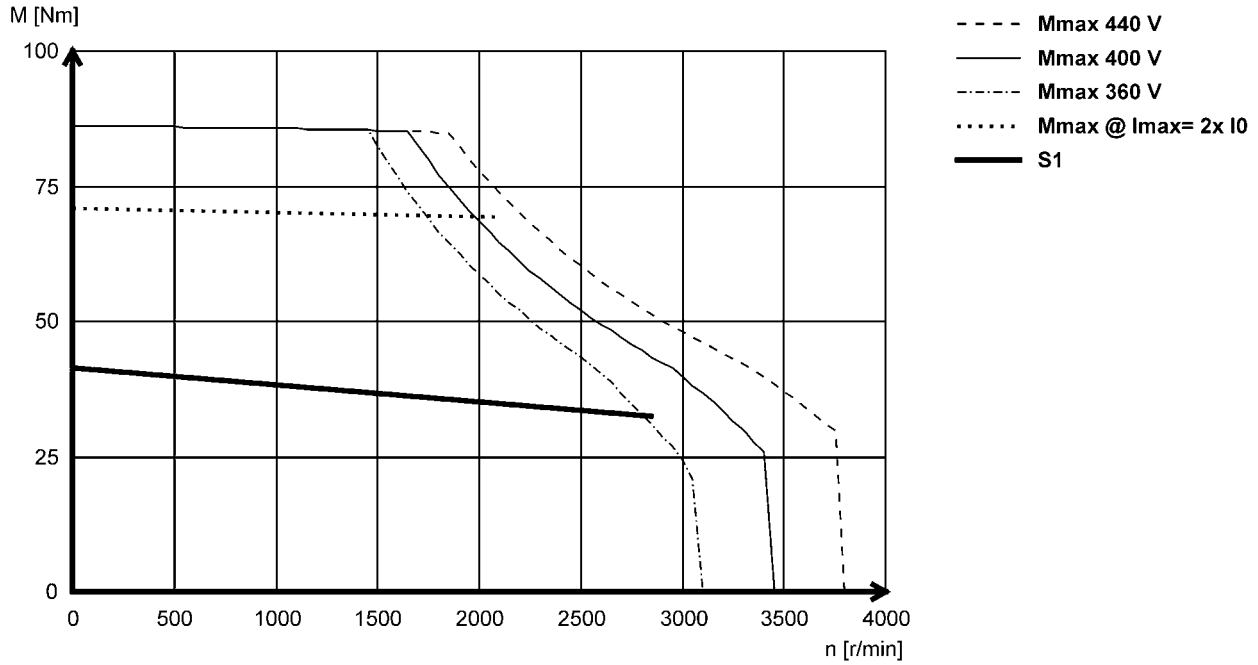


MCS synchronous servo motors

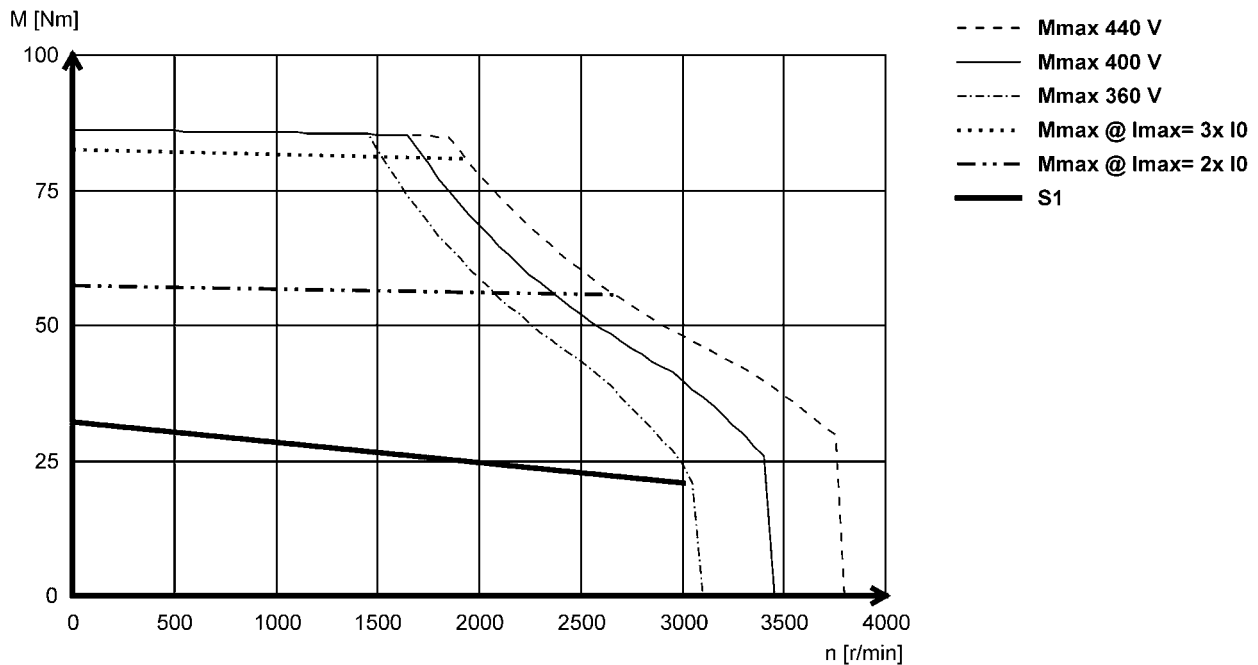
Torque characteristics

Mains connection 3x 400 V

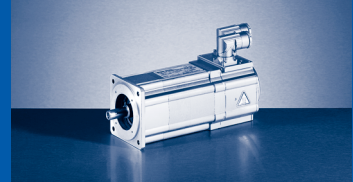
MCS19F29



MCS19F30

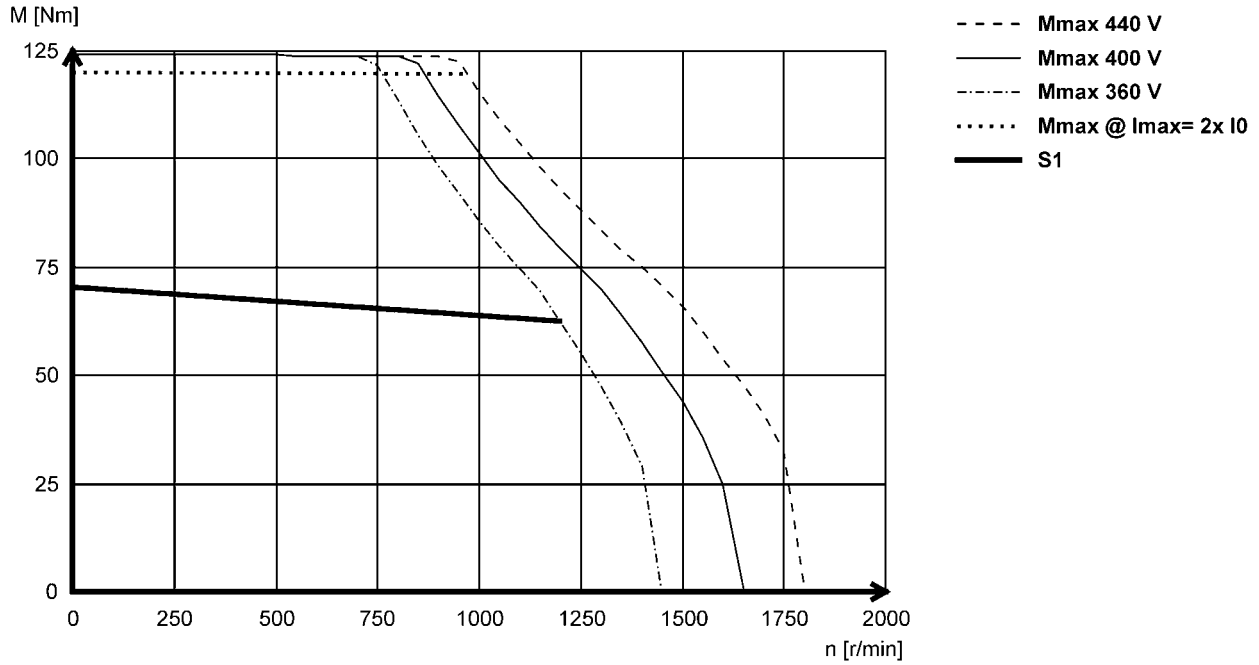


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

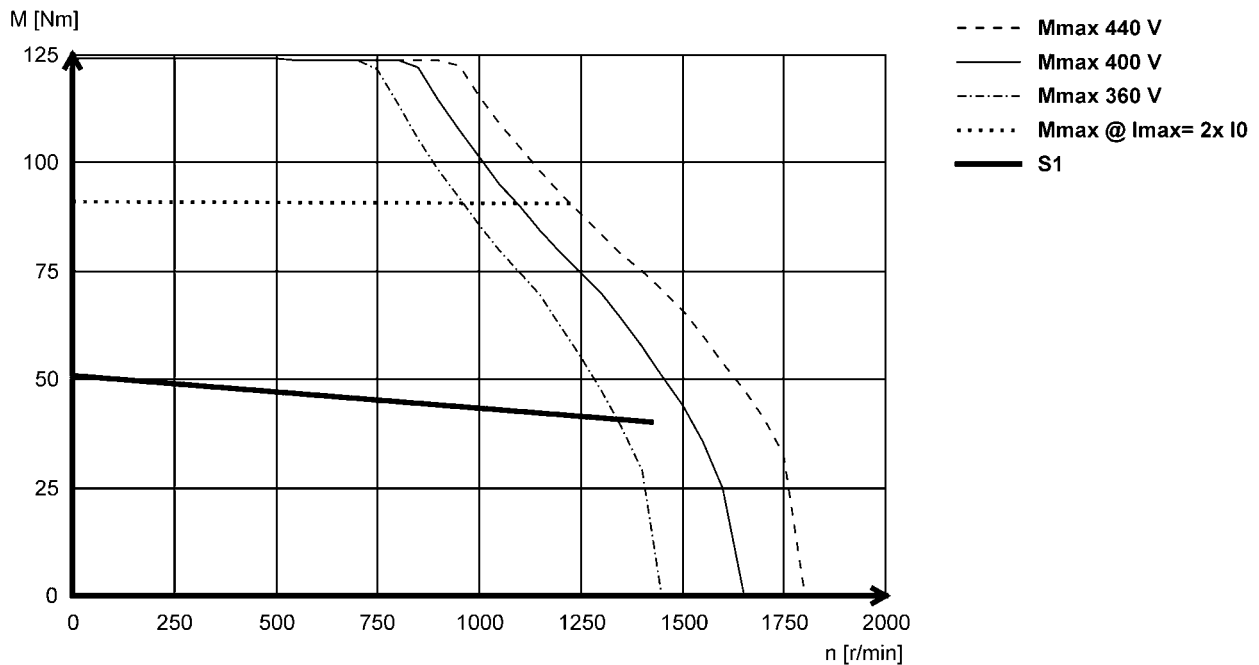


Mains connection 3x 400 V

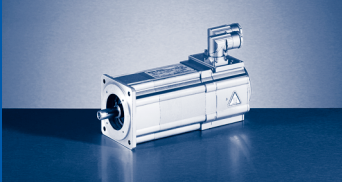
MCS19J12



MCS19J14



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

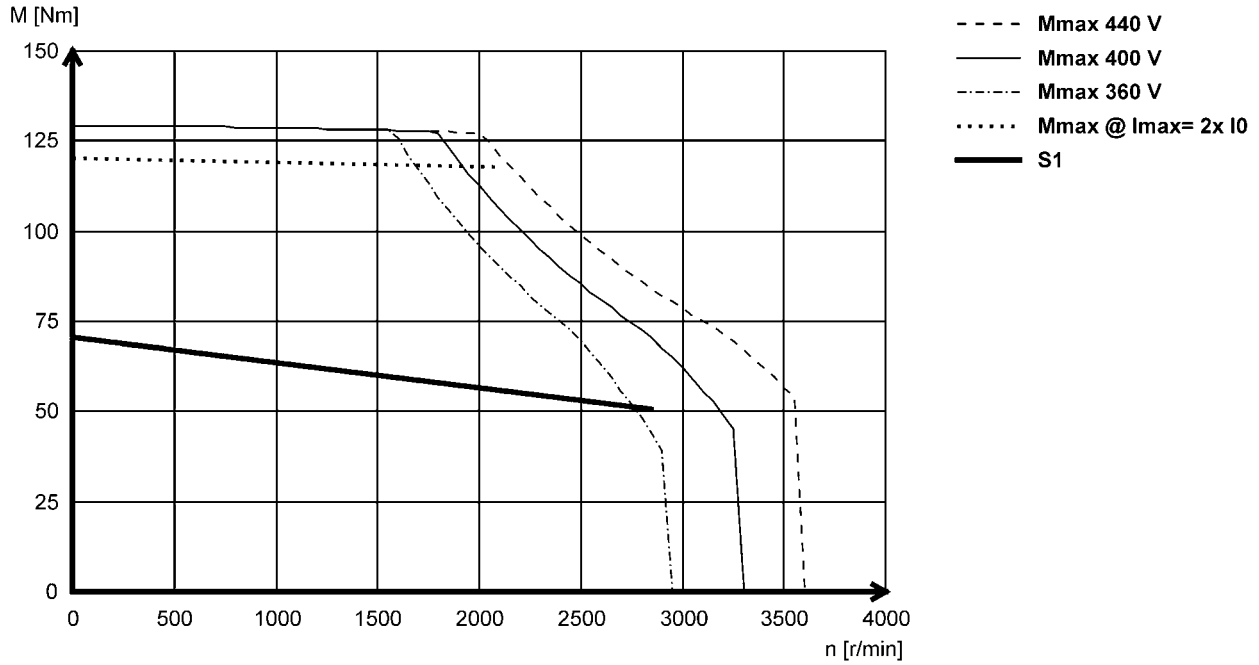


MCS synchronous servo motors

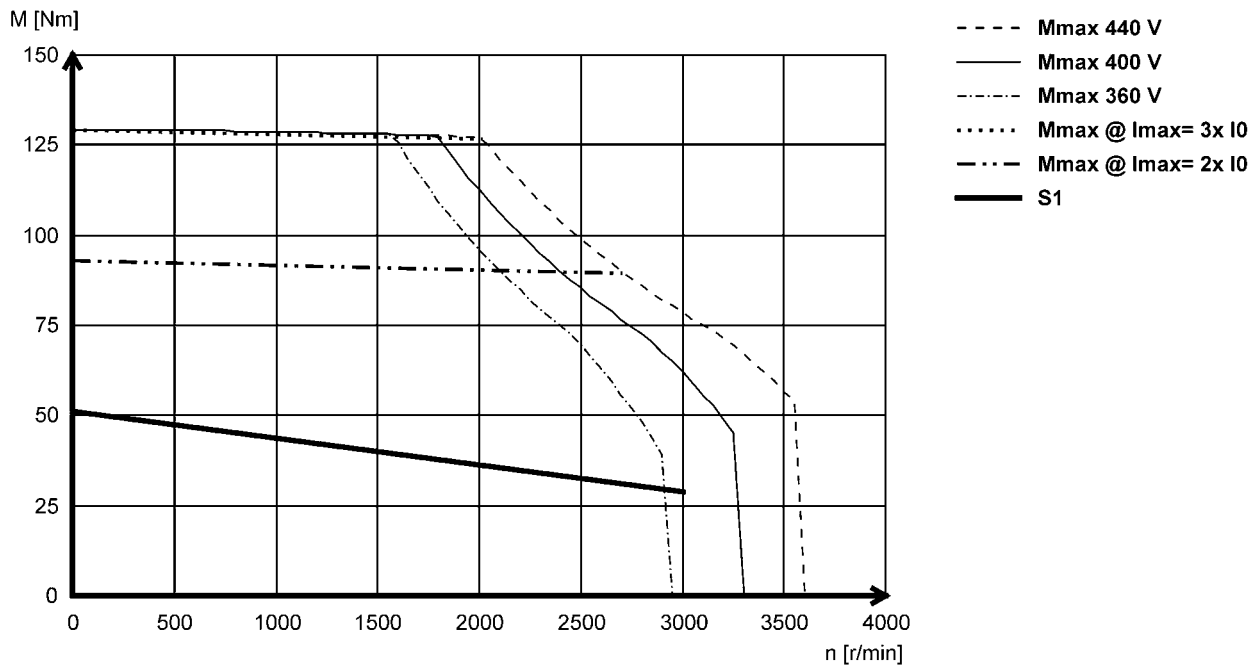
Torque characteristics

Mains connection 3x 400 V

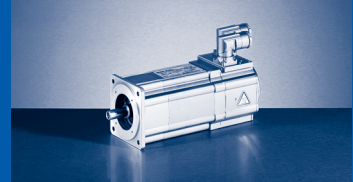
MCS19J29



MCS19J30

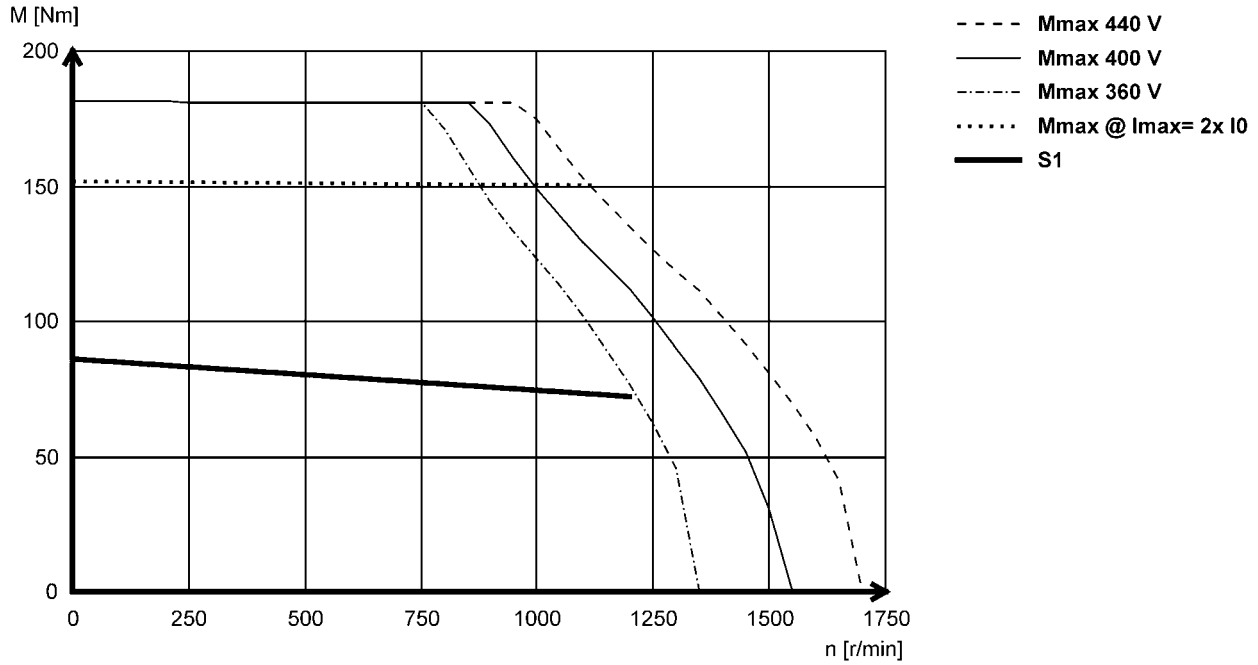


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

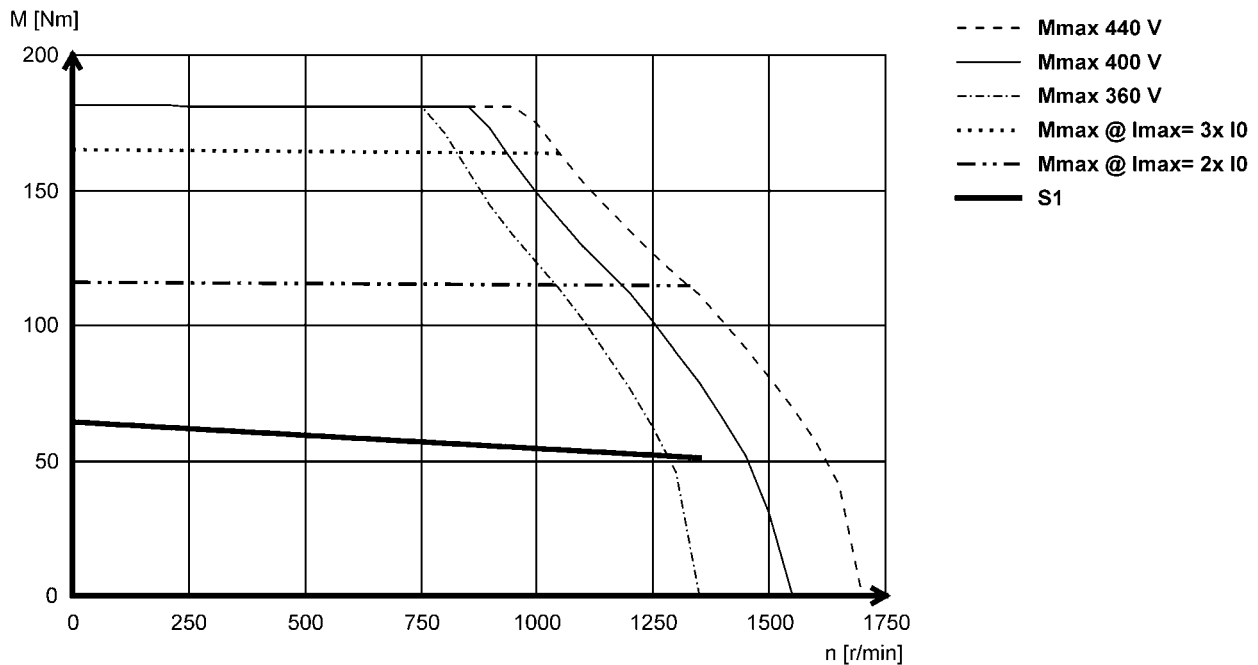


Mains connection 3x 400 V

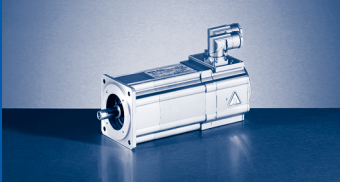
MCS19P12



MCS19P14



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

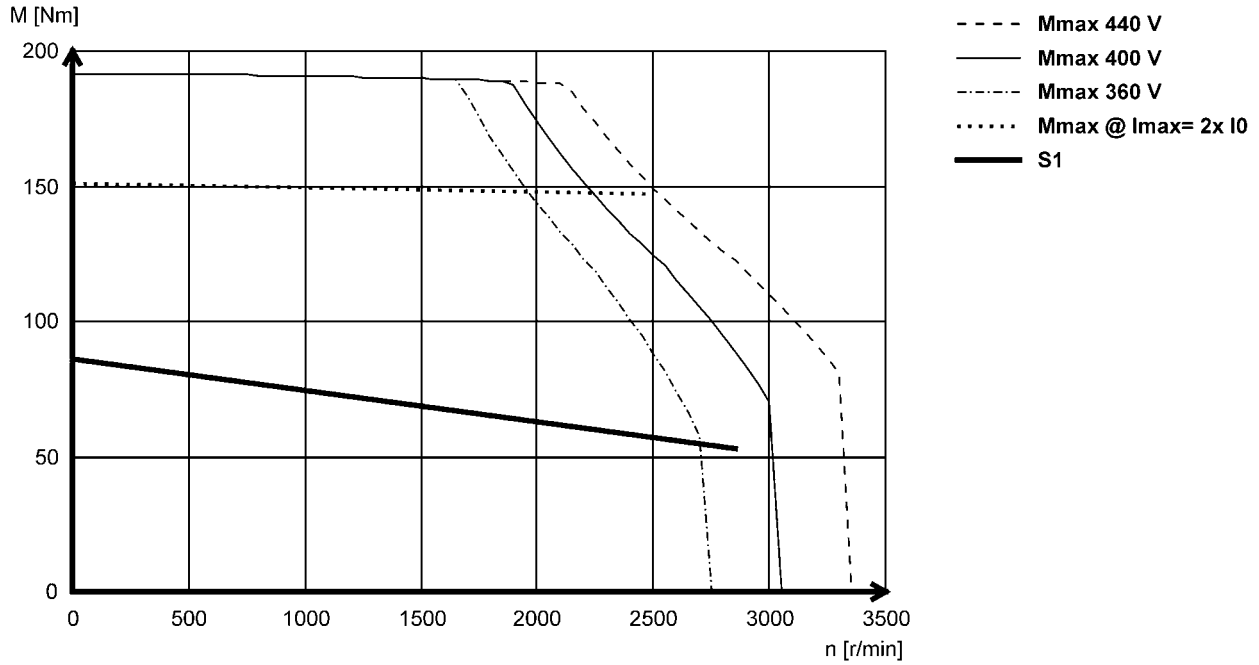


MCS synchronous servo motors

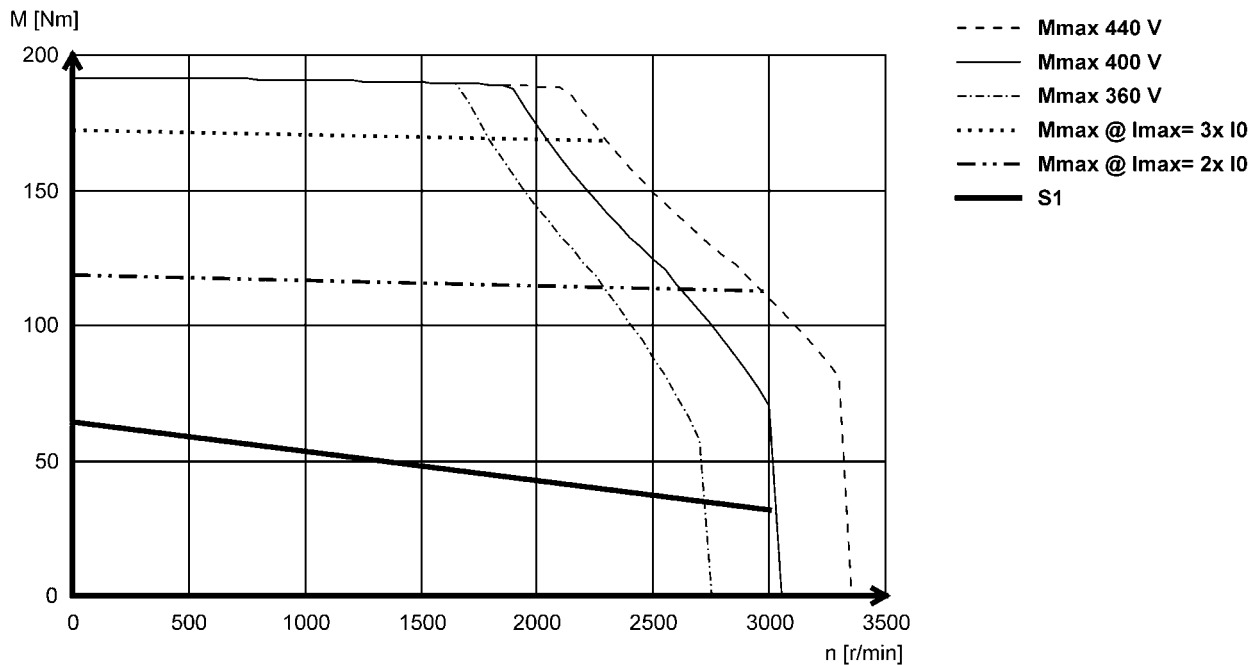
Torque characteristics

Mains connection 3x 400 V

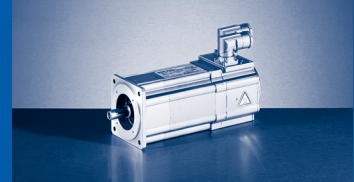
MCS19P29



MCS19P30

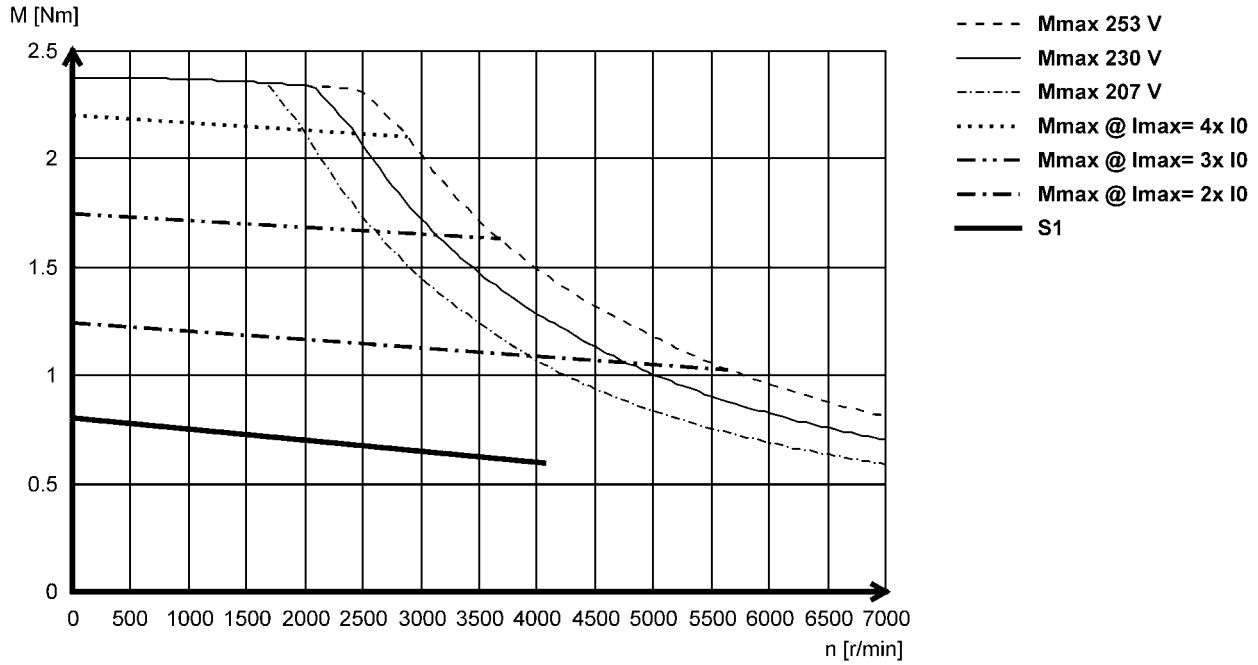


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

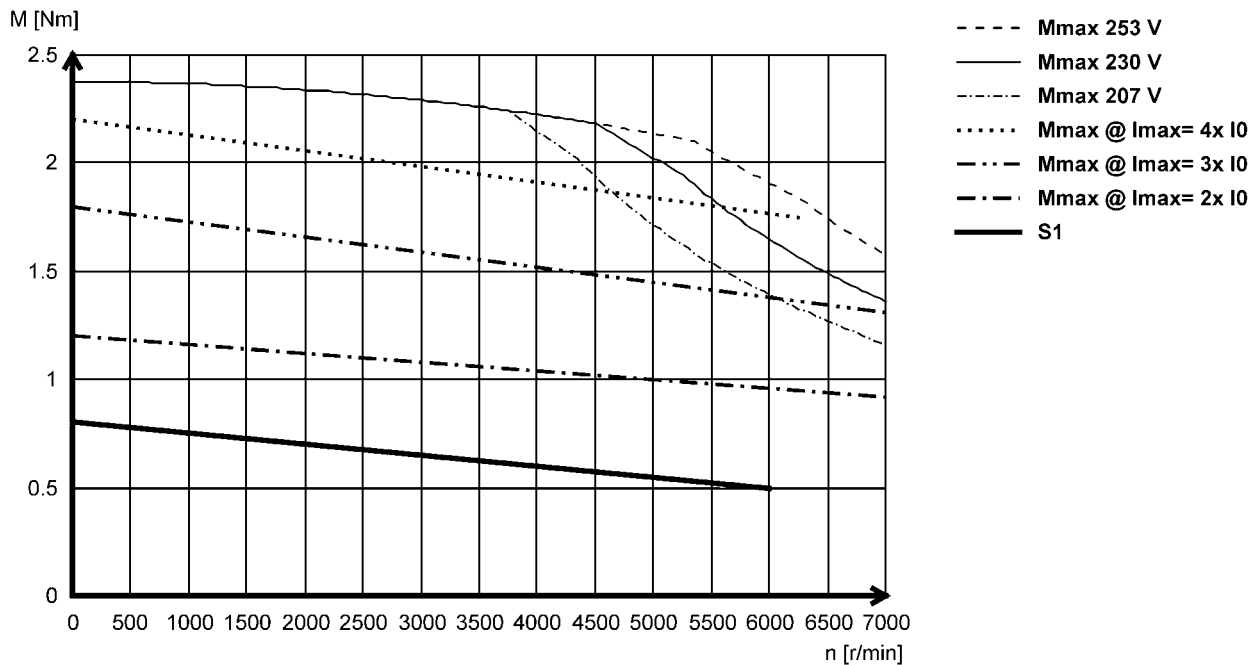


Mains connection 3x 230 V

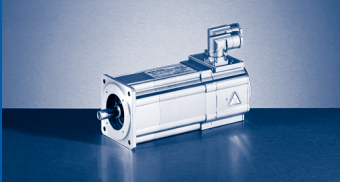
MCS06C41L



MCS06C60L



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

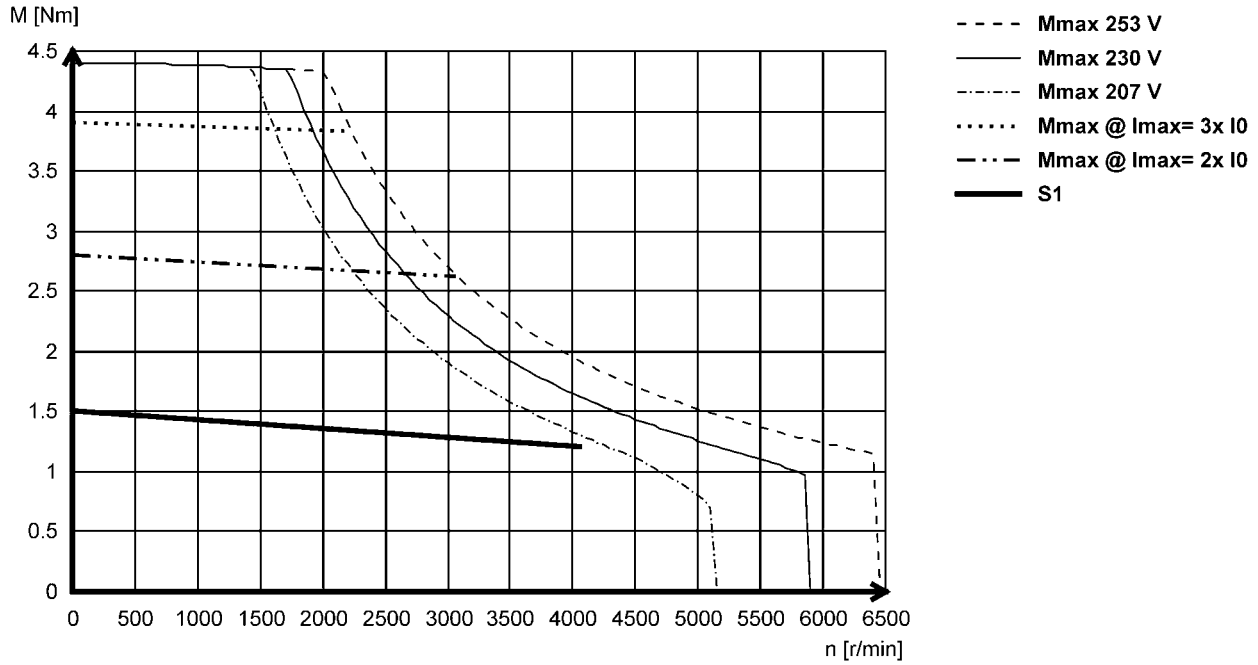


MCS synchronous servo motors

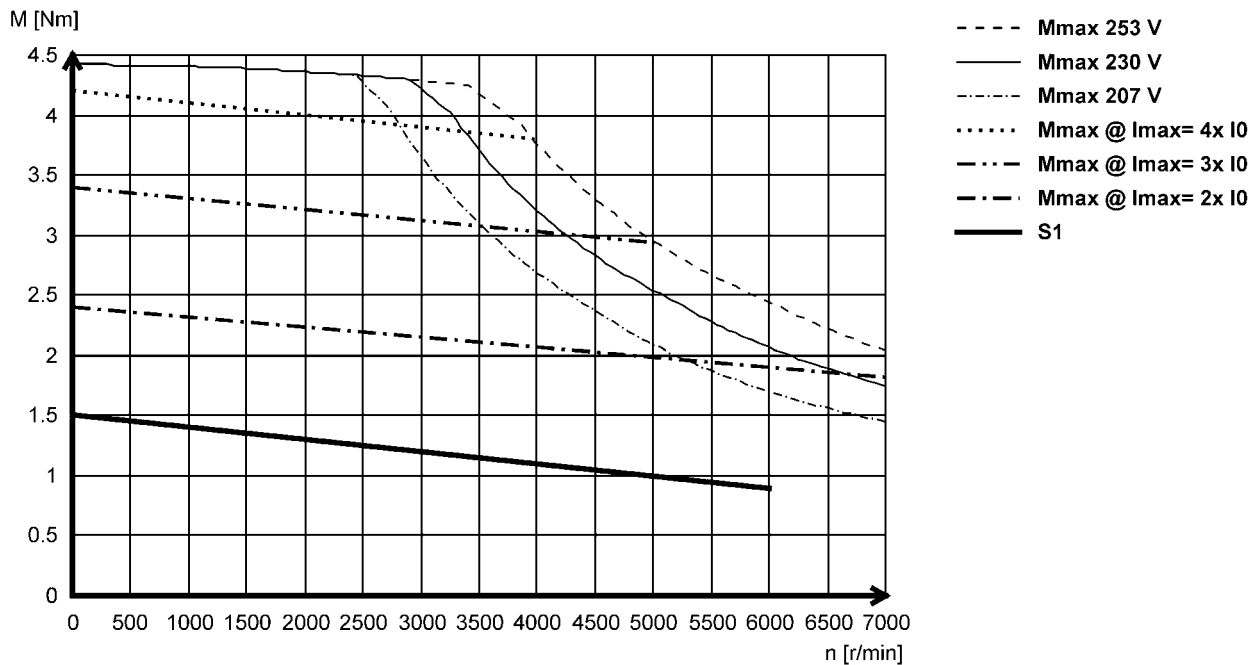
Torque characteristics

Mains connection 3x 230 V

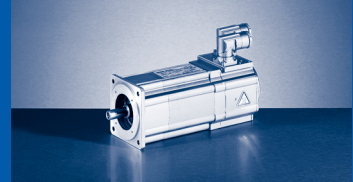
MCS06F41L



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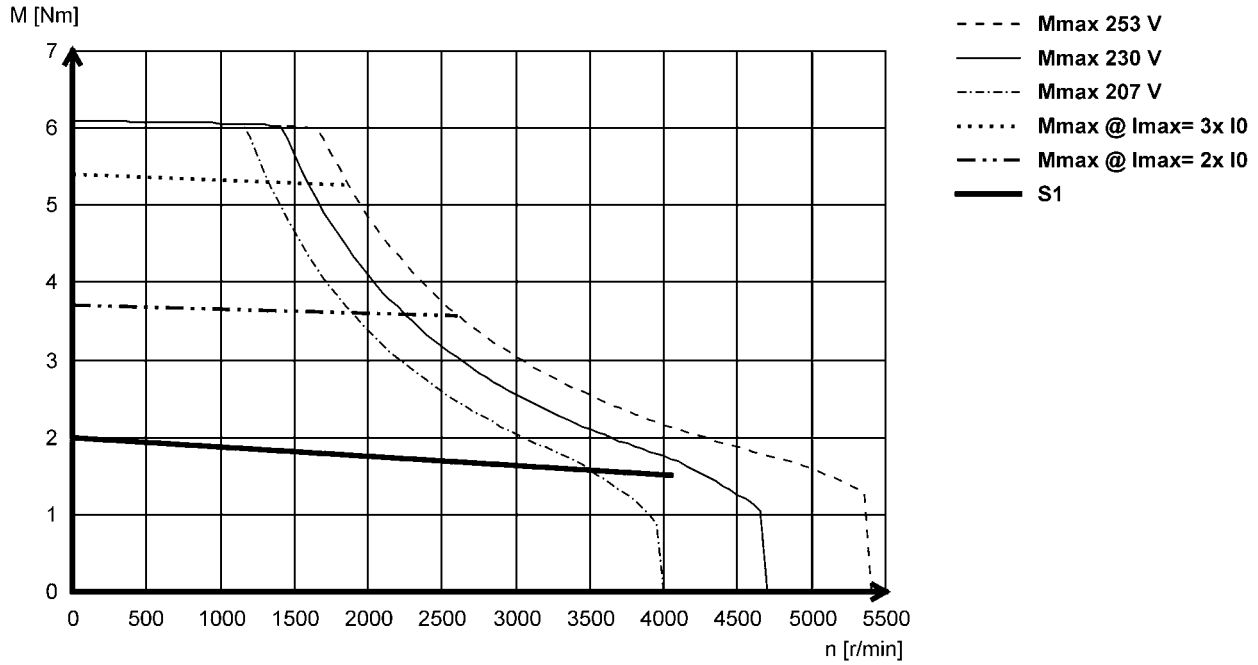


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

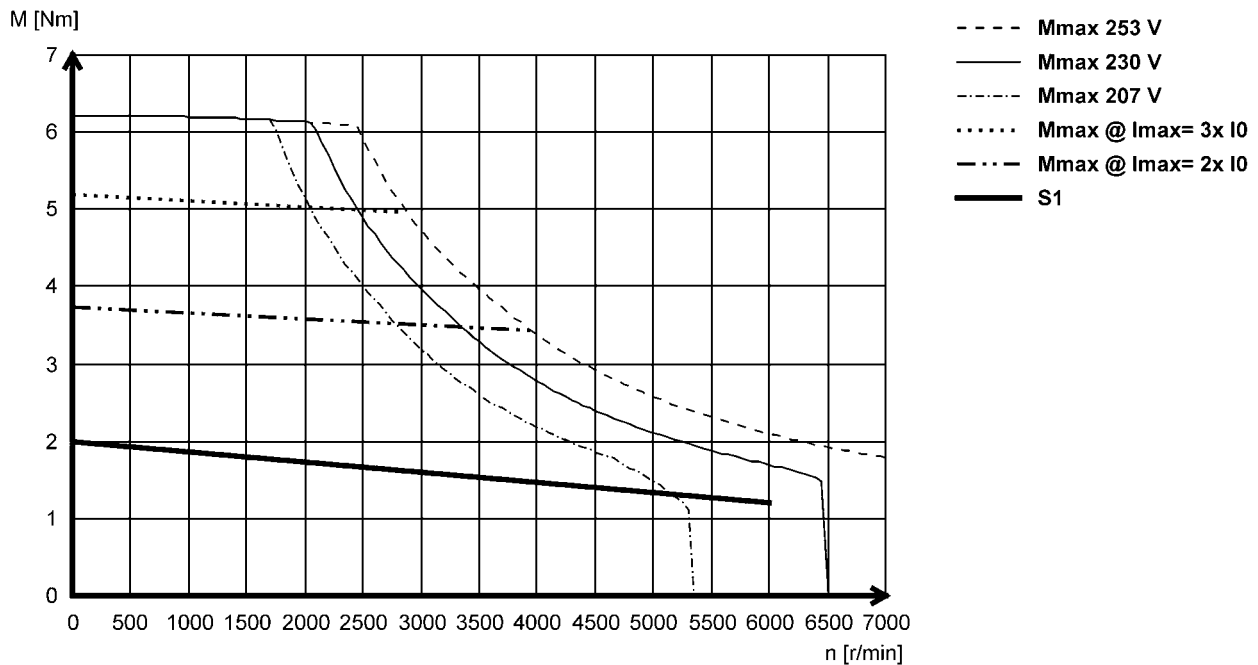


Mains connection 3x 230 V

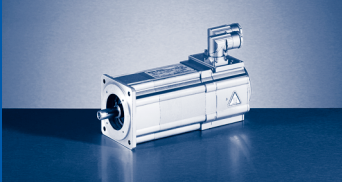
MCS06I41L



MCS06I60L



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

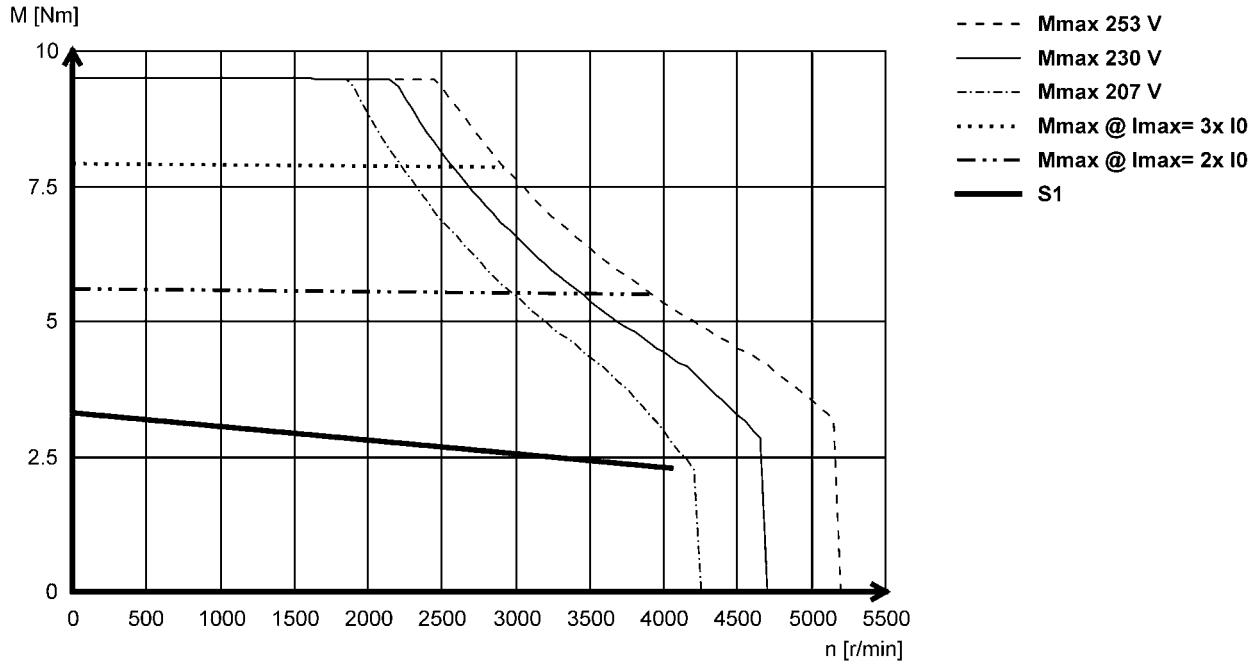


MCS synchronous servo motors

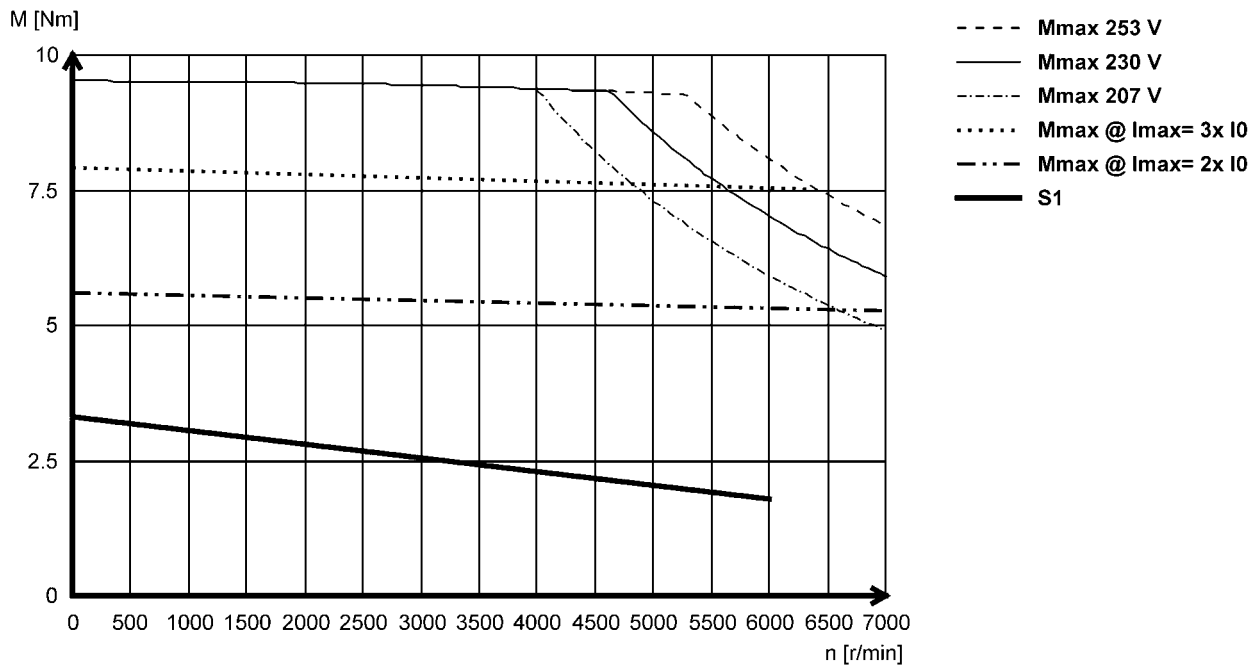
Torque characteristics

Mains connection 3x 230 V

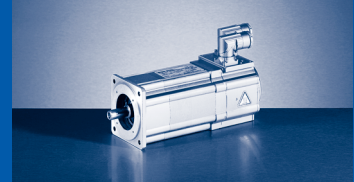
MCS09D41L



MCS09D60L

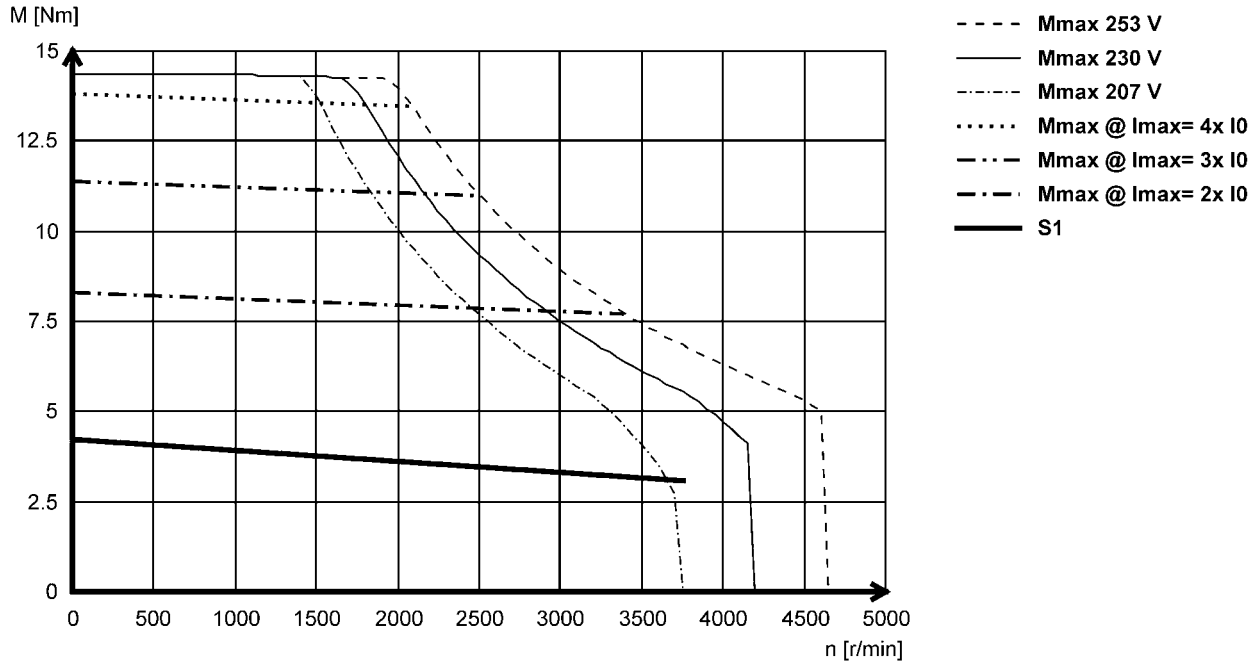


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

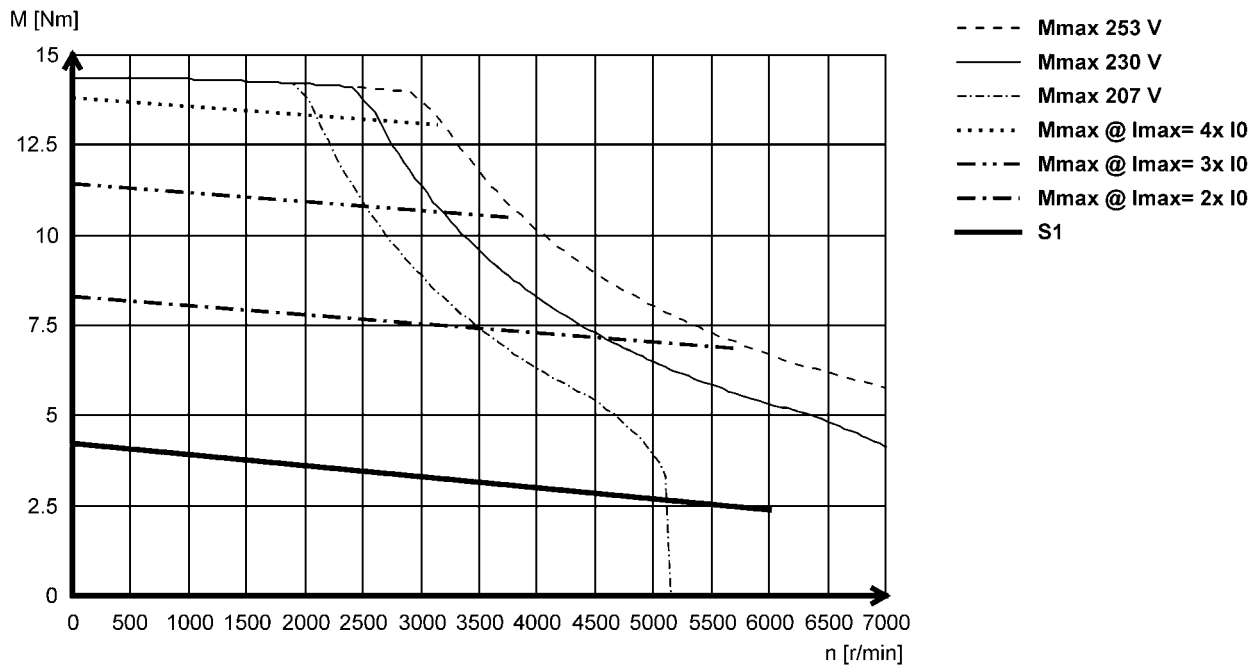


Mains connection 3x 230 V

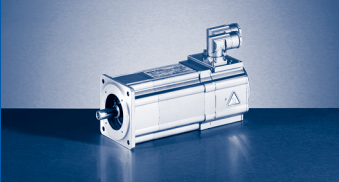
MCS09F38L



MCS09F60L



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

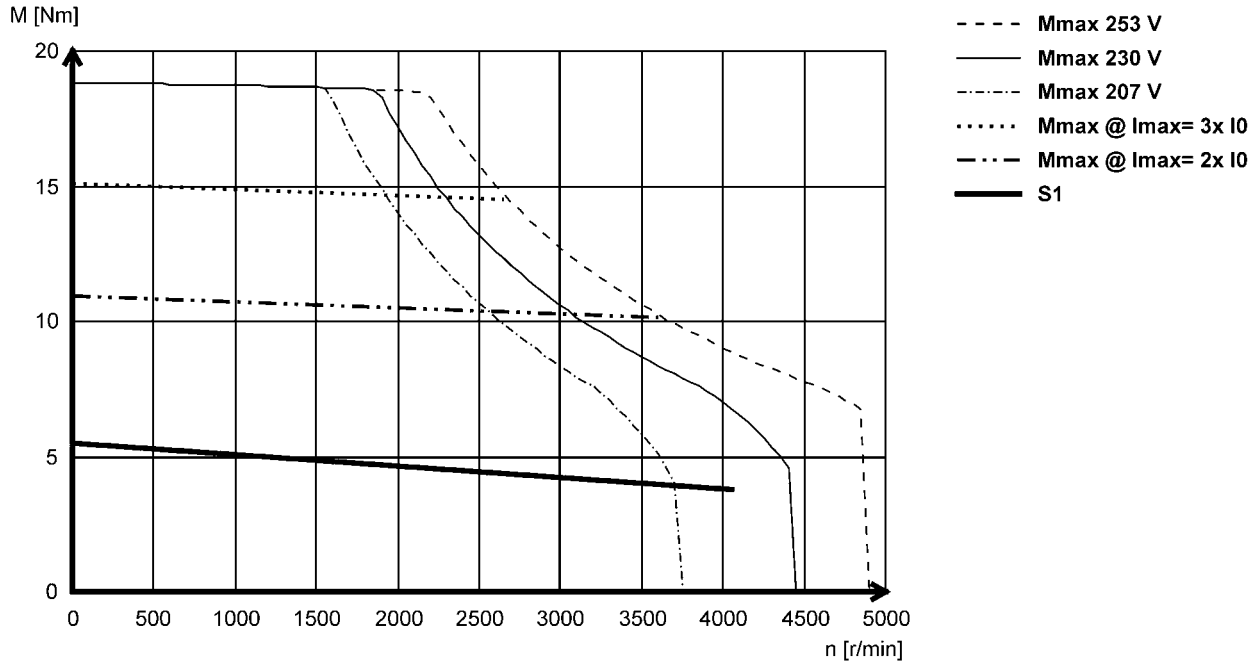


MCS synchronous servo motors

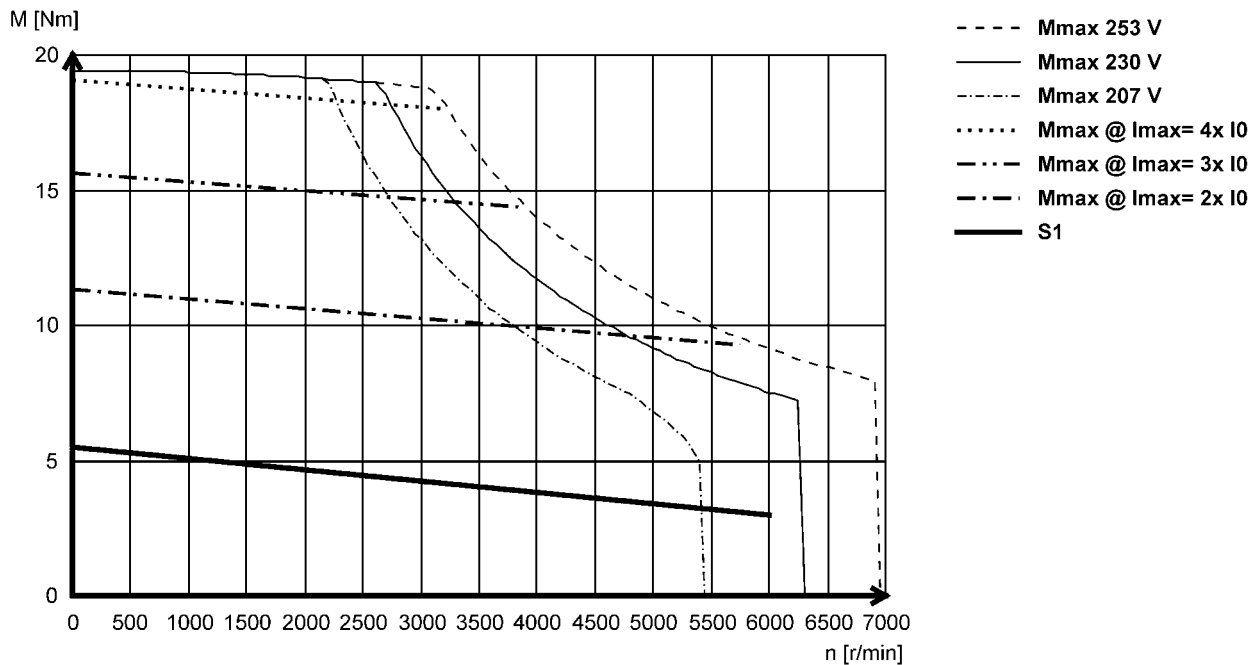
Torque characteristics

Mains connection 3x 230 V

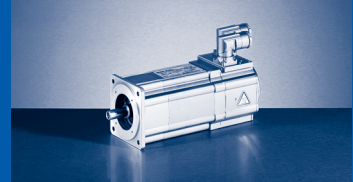
MCS09H41L



MCS09H60L

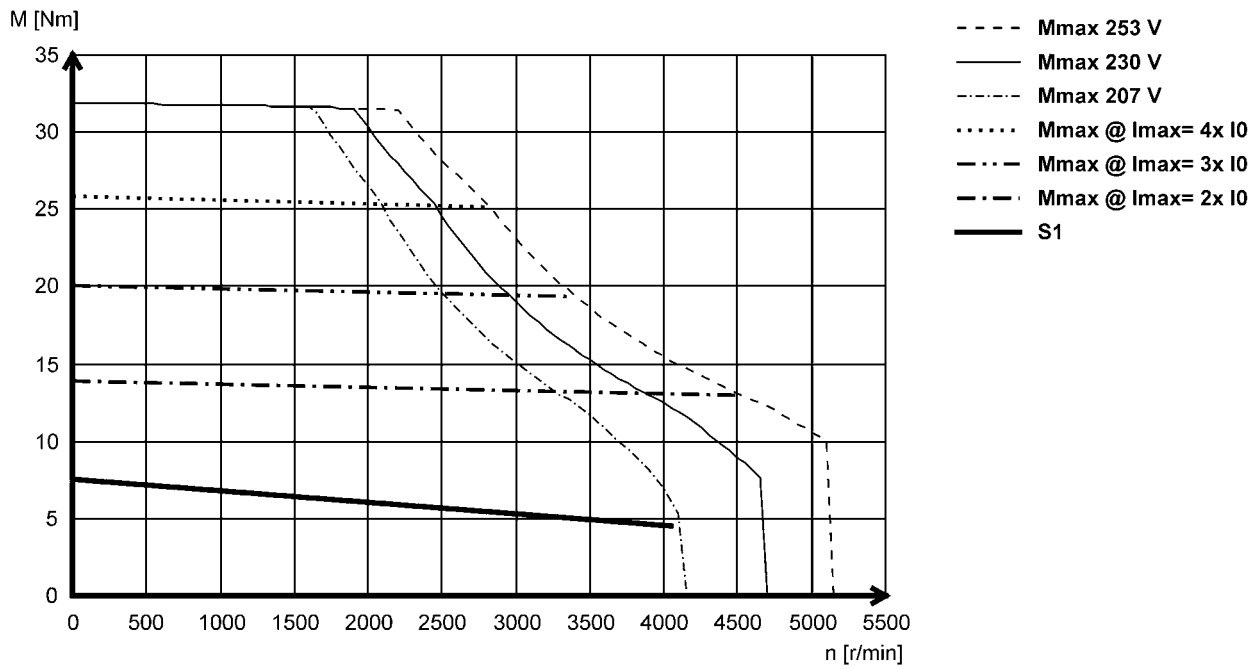


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.



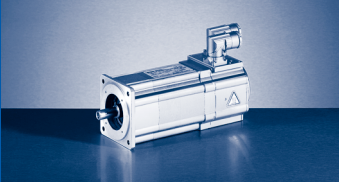
Mains connection 3x 230 V

MCS09L41L



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

3

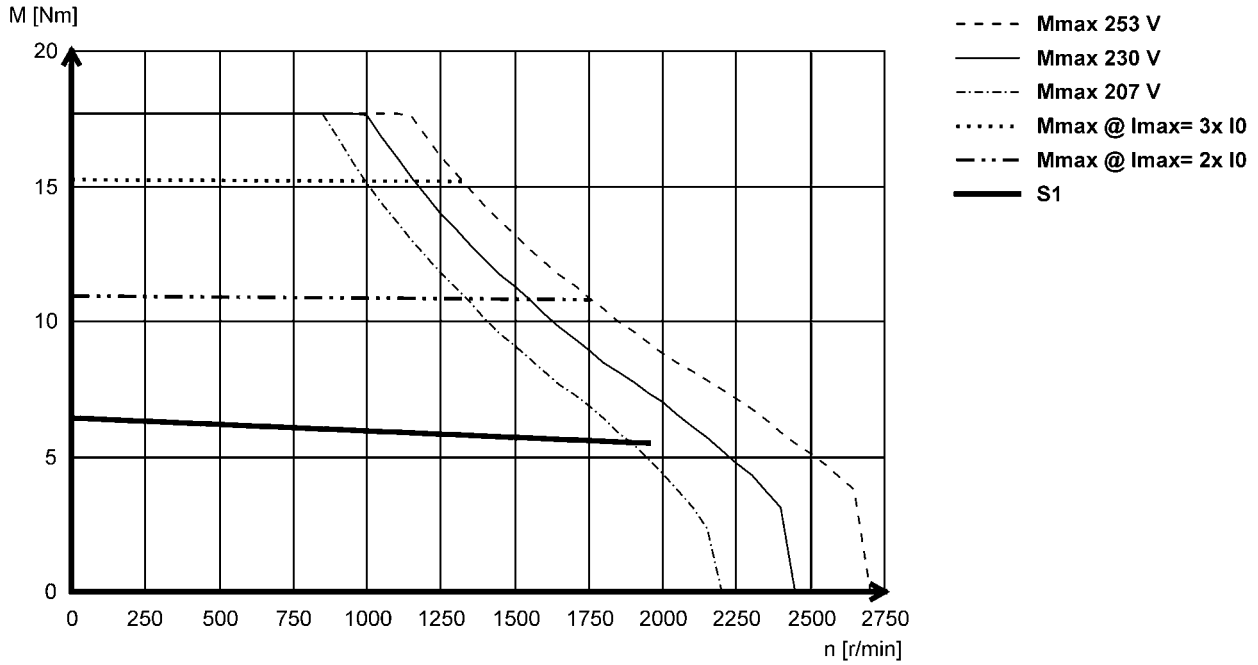


MCS synchronous servo motors

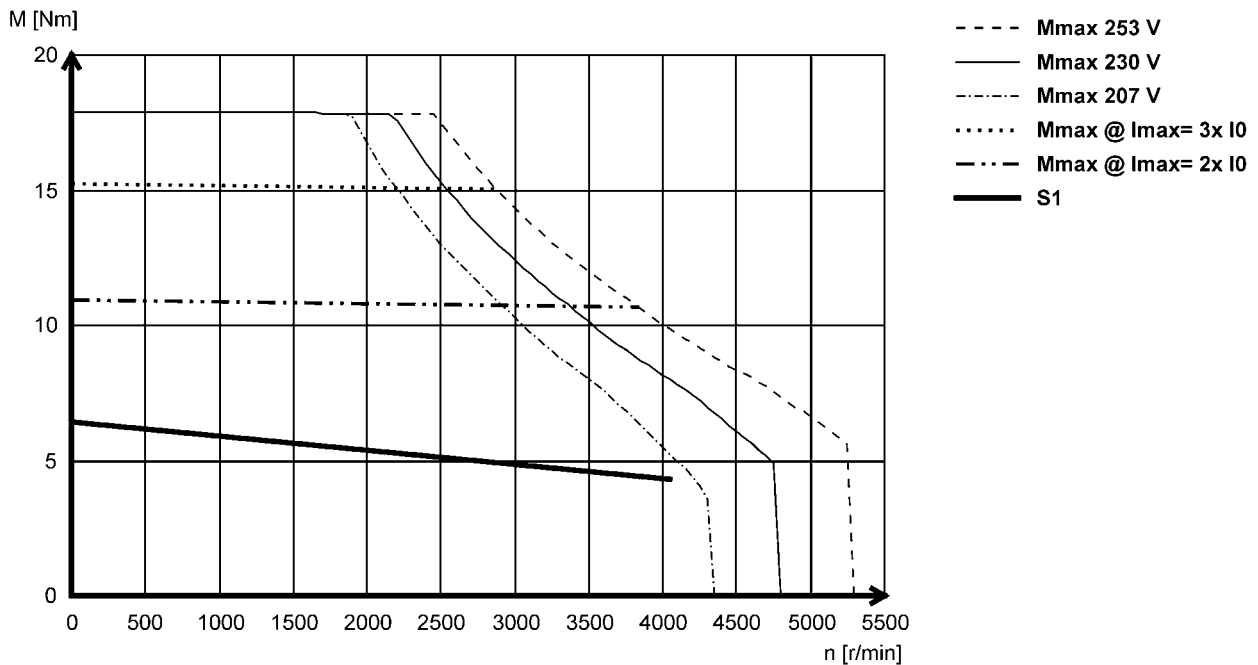
Torque characteristics

Mains connection 3x 230 V

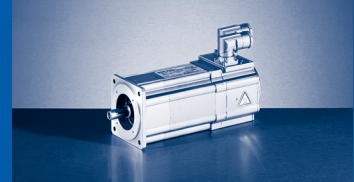
MCS12D20L



MCS12D41L

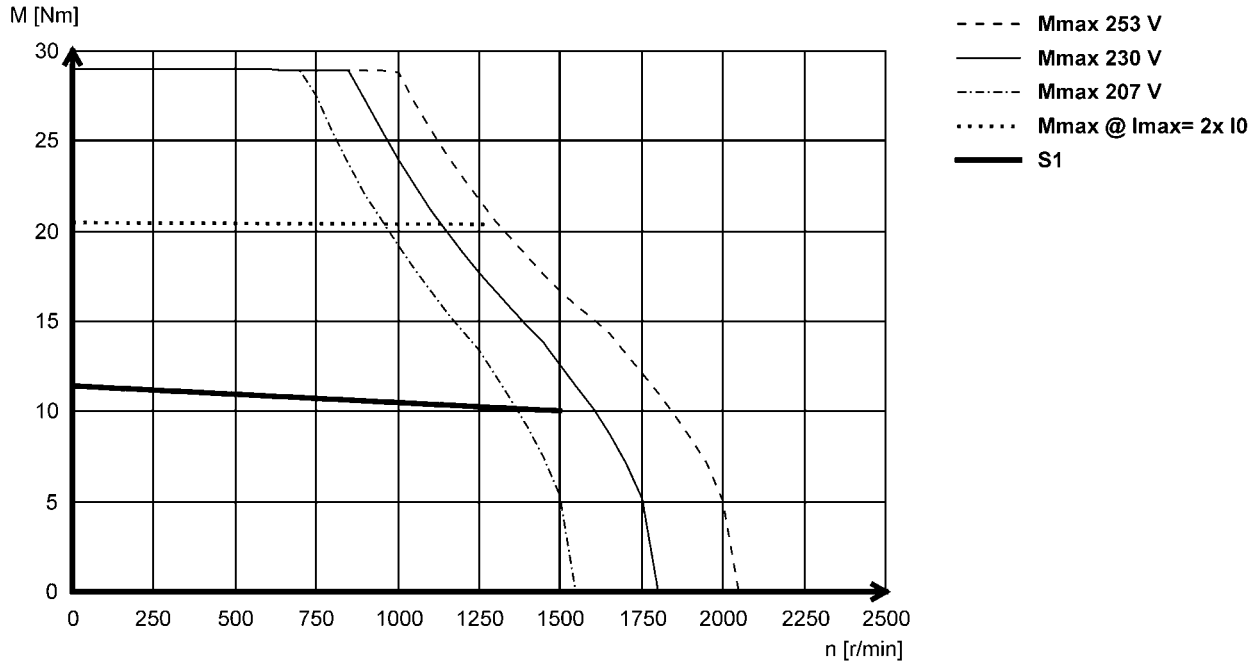


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

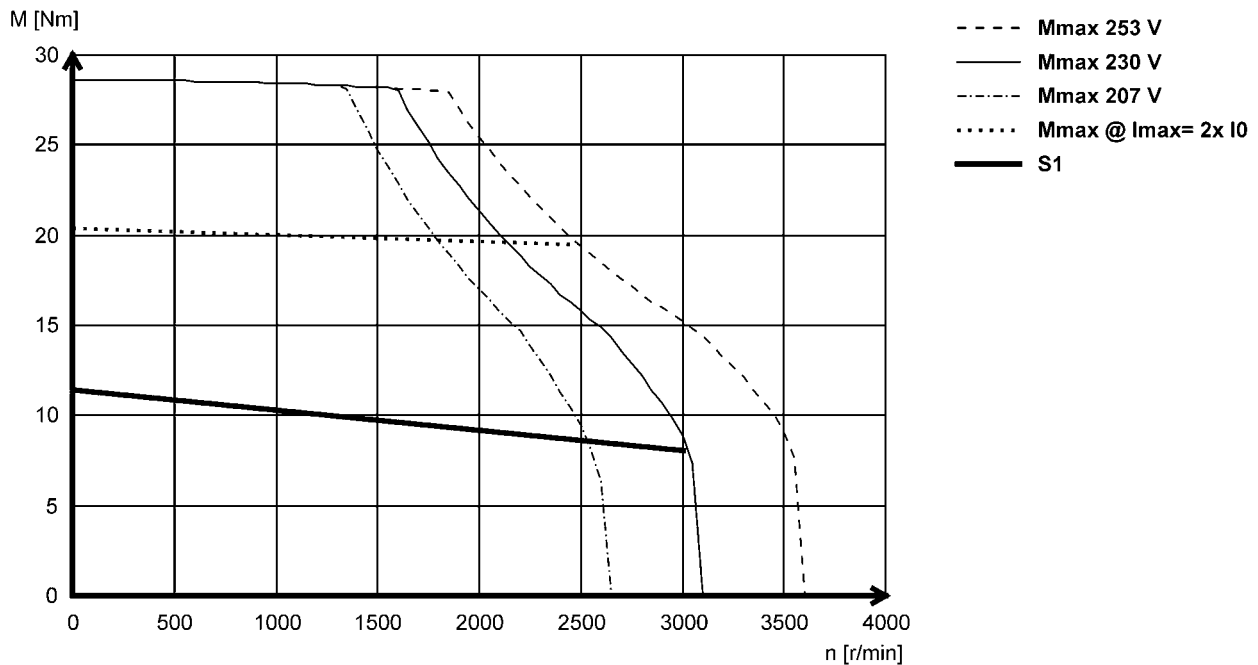


Mains connection 3x 230 V

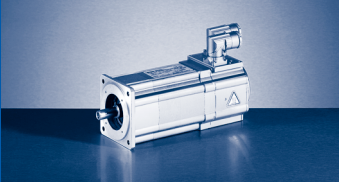
MCS12H15L



MCS12H30L



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

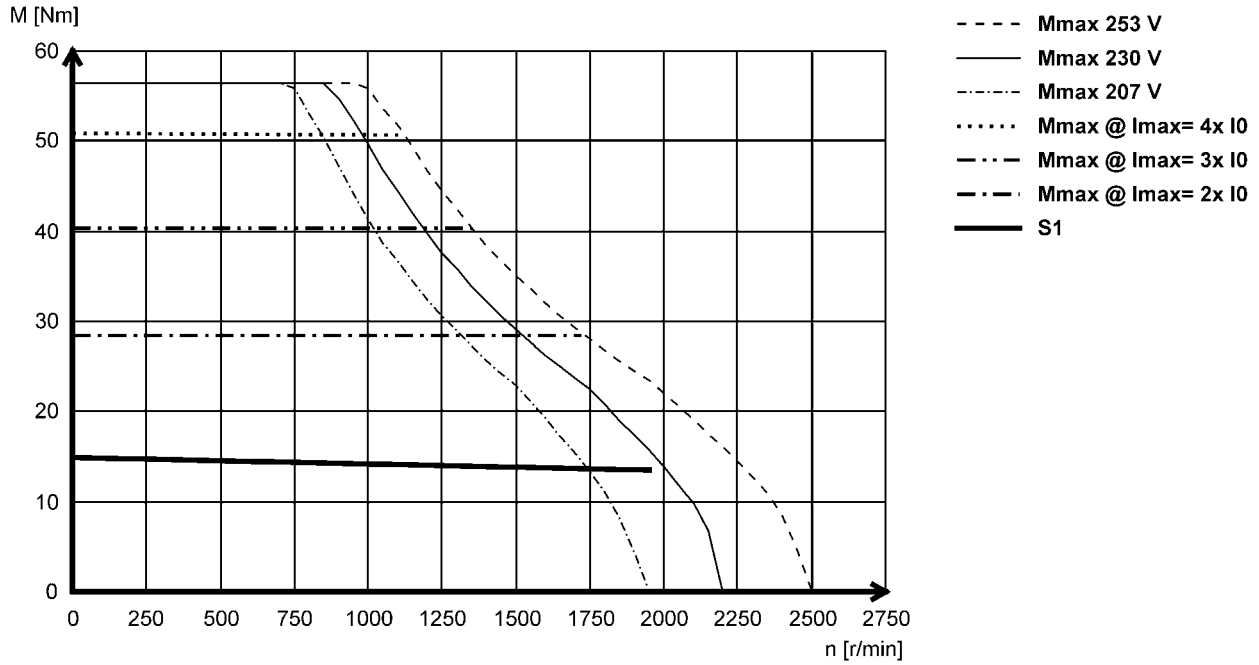


MCS synchronous servo motors

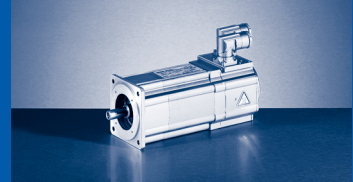
Torque characteristics

Mains connection 3x 230 V

MCS12L20L



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.



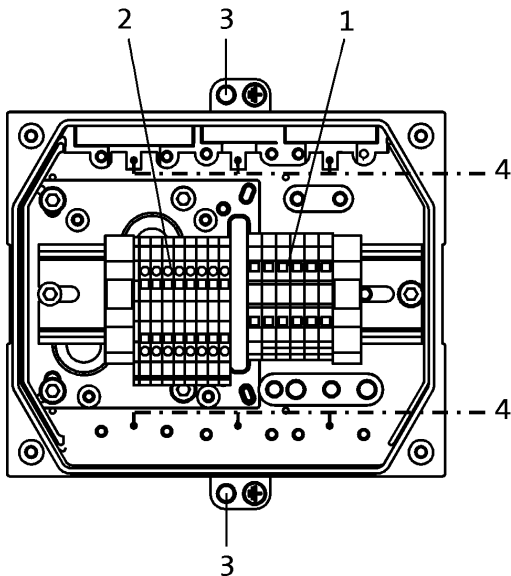
Motor connection terminal box

If a servo motor is to be connected to an existing cable or plug connectors are not to be used for other reasons, the connection can also be made via a terminal box.

The terminals are designed as tension spring terminals to ensure here the long-term vibration resistance of the cable contacts with adequate contact pressure required.

The terminal boxes have generously dimensioned space for the customer's own wiring and large surface shield connection areas to ensure a secure EMC-compliant connection. The cable outlet may be to the left or to the right, depending on requirements.

It is not possible to attach a terminal box to the MCS06 or to models with the blower.



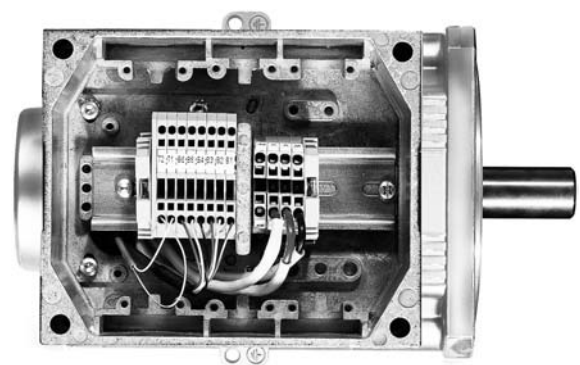
1: Power connection (terminals loadable up to 65 A) + brake connection.

2: Angle/speed sensor connection + thermal sensor connection.

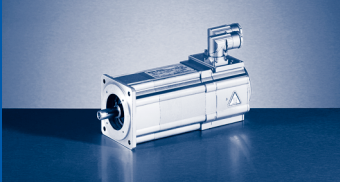
3: PE connection.

4: Large area shield contact.

5: Openings for 2x M32, 2x M25, 2x M20 fittings. The openings are plugged and can be opened up as required by the customer.



3



Holding brakes

The MCS synchronous servo motors can be equipped with integral permanent magnet holding brakes for 24 V DC. The brakes are active once the supply voltage is switched off (closed-circuit principle). Where the brakes are used purely as holding brakes, there is practically no wear on the friction surfaces.

With traversing axes, maintaining the permissible mass inertia ratio J_L/J_{MB} ensures that the permissible maximum switching energy of the brake is not exceeded and at least 2000 emergency stop functions are possible when running at a speed of 3000 r/min.

With lifting axes, the load torque resulting from the force due to weight comes into play as an additional factor. In this case, the data specified for J_L/J_{MB} does not apply.

Caution:

The brakes used are not safety brakes in the sense that a reduction in torque may arise as a result of disruptive factors that cannot be influenced, e.g. oil ingress.

The ohmic voltage drop along the cable must be taken into consideration in long motor supply cables and must be compensated for by a higher voltage at the line input.

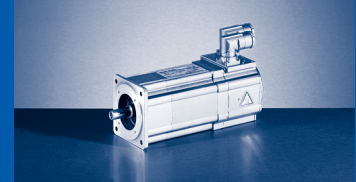
The following applies for Lenze system cables:

$$U[V] = U_B[V] + 0.08 \frac{[V]}{[A] \cdot [m]} \cdot I_{Lg}[m] \cdot I_B[A]$$

If no suitable voltage (incorrect value, incorrect polarity) is applied to the brake, the brake will be applied and can be overheated and destroyed by the motor continuing to rotate. The shortest switching times of the brakes are achieved by DC switching of the voltage. A spark suppressor is required to suppress interference and to increase the service life of the relay contacts here.



Permanent magnet holding brake



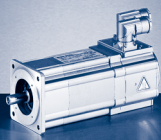
Holding brake data

| | $U_{N,DC}^{3,5)}$ | M_N | M_N | M_{av} | $I_N^{2)}$ | J | $t_1^{1)}$ | $t_2^{1)}$ | $Q_E^{4)}$ | m | J_{MB} | J_L / J_{MB} |
|---------------|-------------------|-------|--------|----------|------------|----------------------|------------|------------|------------|------|----------------------|----------------|
| | | 20 °C | 120 °C | 120 °C | | | | | | | | |
| | [V] | [Nm] | [Nm] | [Nm] | [A] | [kgcm ²] | [ms] | [ms] | [J] | [kg] | [kgcm ²] | |
| MCS06C | 24 | 2.20 | 2.00 | 0.60 | 0.34 | 0.12 | 15.0 | 30.0 | 30.0 | 0.30 | 0.26 | 22.1 |
| MCS06F | | | | | | | | | | | 0.34 | 16.6 |
| MCS06I | | | | | | | | | | | 0.42 | 13.3 |
| MCS09D | | 8.00 | 6.00 | 4.50 | 0.65 | 1.07 | 20.0 | 40.0 | 400 | 0.80 | 2.17 | 36.4 |
| MCS09F | | | | | | | | | | | 2.57 | 30.5 |
| MCS09H | | | | | | | | | | | 2.97 | 26.3 |
| MCS09L | | | | | | | | | | | 3.87 | 19.9 |
| MCS12D | | 12.0 | 10.0 | 7.00 | 0.65 | 1.07 | 13.0 | 43.0 | 400 | 0.90 | 5.07 | 15.0 |
| MCS12H | | | | | | | | | | | 8.40 | 8.70 |
| MCS12L | | | | | | | | | | | 11.7 | 5.90 |
| MCS14D | | 22.0 | 18.0 | 8.00 | 0.88 | 3.20 | 15.0 | 150 | 640 | 1.90 | 11.3 | 10.5 |
| MCS14H | | | | | | | | | | | 17.4 | 6.50 |
| MCS14L | | | | | | | | | | | 26.6 | 3.90 |
| MCS14P | | | | | | | | | | | 37.9 | 2.40 |
| MCS19F | | 37.0 | 32.0 | 15.0 | 0.93 | 12.4 | 96.0 | 113 | 2350 | 3.10 | 77.4 | 5.20 |

Holding brake data, reinforced design

| | $U_{N,DC}^{3,5)}$ | M_N | M_N | M_{av} | $I_N^{2)}$ | J | $t_1^{1)}$ | $t_2^{1)}$ | $Q_E^{4)}$ | m | J_{MB} | J_L / J_{MB} |
|---------------|-------------------|-------|--------|----------|------------|----------------------|------------|------------|------------|------|----------------------|----------------|
| | | 20 °C | 120 °C | 120 °C | | | | | | | | |
| | [V] | [Nm] | [Nm] | [Nm] | [A] | [kgcm ²] | [ms] | [ms] | [J] | [kg] | [kgcm ²] | |
| MCS09D | 24 | 12.0 | 10.0 | 7.00 | 0.65 | 1.07 | 20.0 | 40.0 | 400 | 0.80 | 2.17 | 36.4 |
| MCS09F | | | | | | | | | | | 2.57 | 30.5 |
| MCS09H | | | | | | | | | | | 2.97 | 26.3 |
| MCS09L | | | | | | | | | | | 3.87 | 19.9 |
| MCS12D | | 24.0 | 19.0 | 12.0 | 0.71 | 3.13 | 16.0 | 90.0 | 890 | 1.20 | 7.10 | 24.3 |
| MCS12H | | | | | | | | | | | 10.4 | 16.3 |
| MCS12L | | | | | | | | | | | 13.7 | 12.1 |
| MCS14D | | 37.0 | 32.0 | 15.0 | 0.93 | 12.4 | 96.0 | 113 | 2350 | 3.10 | 20.5 | 22.2 |
| MCS14H | | | | | | | | | | | 26.6 | 16.9 |
| MCS14L | | | | | | | | | | | 35.8 | 12.3 |
| MCS14P | | | | | | | | | | | 47.1 | 9.10 |
| MCS19J | | 100 | 80.0 | 43.0 | 1.29 | 30.0 | 30.0 | 90.0 | 2100 | 4.30 | 135 | 2.20 |
| MCS19P | | | | | | | | | | | 190 | 1.20 |

- 1) Engagement and disengagement times are valid for rated voltage ($\pm 0\%$) and protective circuit for brakes with varistor for DC switching. The times may increase without a protective circuit.
- 2) The currents are the maximum values when the brake is cold (value used for dimensioning the current supply). The values for a motor at operating temperature are considerably lower.
- 3) With 24V DC brake: smoothed DC voltage, ripple $\leq 1\%$.
- 4) Maximum switching energy per emergency stop at $n = 3000$ r/min for at least 2000 emergency stops.
- 5) Voltage tolerance: $-10\% \dots +5\%$



MCS synchronous servo motors

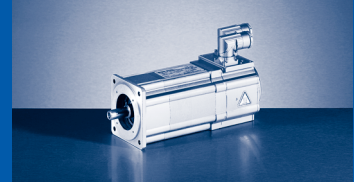
Accessories

Blower data 50 Hz

| | | Enclosure | Number of phases | | | | | |
|-------|-----|-----------|------------------|-----------|-----------|-------------|-------|-------|
| | | | | U_{min} | U_{max} | $U_{N, AC}$ | P_N | I_N |
| | | | | [V] | [V] | [V] | [kW] | [A] |
| MCS12 | F10 | IP54 | 1 | 210 | 240 | 230 | 0.019 | 0.12 |
| | F50 | | | 104 | 122 | 115 | 0.018 | 0.22 |
| MCS14 | F10 | | | 210 | 240 | 230 | 0.040 | 0.25 |
| | F50 | | | 104 | 122 | 115 | | 0.53 |
| MCS19 | F10 | | | 210 | 240 | 230 | 0.060 | 0.26 |
| | F50 | | | 104 | 122 | 115 | 0.047 | 0.45 |

Blower data 60 Hz

| | | Enclosure | Number of phases | | | | | |
|-------|-----|-----------|------------------|-----------|-----------|-------------|-------|-------|
| | | | | U_{min} | U_{max} | $U_{N, AC}$ | P_N | I_N |
| | | | | [V] | [V] | [V] | [kW] | [A] |
| MCS12 | F10 | IP54 | 1 | 210 | 240 | 230 | 0.019 | 0.12 |
| | F50 | | | 104 | 122 | 115 | 0.018 | 0.22 |
| MCS14 | F10 | | | 210 | 240 | 230 | 0.040 | 0.25 |
| | F50 | | | 104 | 122 | 115 | | 0.53 |
| MCS19 | F10 | | | 210 | 240 | 230 | 0.060 | 0.26 |
| | F50 | | | 104 | 122 | 115 | 0.047 | 0.45 |




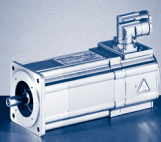
Tailored to meet the requirements of the various applications and necessary accuracies, the following feedback systems are available.

Resolver

Stator-fed resolver with two stator windings offset by 90° and one rotor winding with transformer winding.

| | | | | |
|-----------------------------------|---------------|-----------|---------|---------------------------------|
| Speed/angle sensor | ¹⁾ | | | RS0 |
| Resolution | | | [°] | 0.80 |
| Angle | | | | |
| Accuracy | | | [°] | -10 ... 10 |
| Absolute positioning | | | | 1 revolution |
| Max. speed | n_{max} | | [r/min] | 8000 |
| Max. input voltage | $U_{in,max}$ | | [V] | 10.0 |
| DC | | | | |
| Max. input frequency | $f_{in,max}$ | | [kHz] | 4.00 |
| Ratio | | $\pm 5\%$ | | 0.30 |
| Stator / rotor | | | | |
| Rotor impedance | Z_{ro} | | [Ω] | 51 + j90 |
| Stator impedance | Z_{so} | | [Ω] | 102 + j150 |
| Impedance | Z_{rs} | | [Ω] | 44 + j76 |
| Min. insulation resistance | R | | [MΩ] | 10.0 |
| At DC 500 V | | | | |
| Number of pole pairs | | | | 1 |
| Max. angle error | | | [°] | -10 ... 10 |
| Inverter assignment | | | | E84AVTC E94A ECS EVS93 |

¹⁾ →  14 - Product key > speed/angle sensor




MCS synchronous servo motors

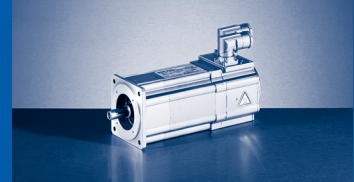
Accessories

Incremental encoder and SinCos absolute value encoder

| Encoder type | | | TTL incremental | SinCos absolute value | | | | |
|-----------------------------------|--------------|---------|-----------------|-----------------------|---------------------------------|-------------|--------------|-------------|
| Speed/angle sensor | 1) | | C40 | EQI | SRS | SRM | ECN | EQN |
| | | | IK4096-5V-T | AM32-5V-E | AS1024-8V-H | AM1024-8V-H | AS2048-5V-E | AM2048-5V-E |
| Encoder type | | | Single-turn | Multi-turn | Single-turn | Multi-turn | Single-turn | Multi-turn |
| Pulses | | | 4096 | 32 | 1024 | | 2048 | |
| Output signals | | | TTL | 1 V _{ss} | | | | |
| Interfaces | | | | EnDat | Hiperface | | EnDat | |
| Absolute revolutions | | | 0 | 4096 | 1 | 4096 | 1 | 4096 |
| Resolution Angle ²⁾ | | [°] | 1.30 | 0.40 | | | | |
| Accuracy | | [°] | -1 ... 1 | -5 ... 5 | -0.8 ... 0.8 | | -0.6 ... 0.6 | |
| Min. input voltage DC | $U_{in,min}$ | [V] | 4.50 | 4.75 | 7.00 | | 4.75 | |
| Max. input voltage DC | $U_{in,max}$ | [V] | 5.50 | 5.25 | 12.0 | | 5.25 | |
| Max. speed | n_{max} | [r/min] | 7324 | 12000 | 6000 | | 12000 | |
| Max. current consumption | I_{max} | [A] | 0.075 | 0.17 | 0.080 | | 0.15 | 0.25 |
| Limit frequency | f_{max} | [kHz] | 500 | 6.00 | 200 | | | |
| Inverter assignment | | | E94P | E94A | E84AVTC E94A ECS EVS93 | | E94A | |

1) →  14 - Product key > speed/angle sensor

2) Dependent on inverter.



Thermal sensor

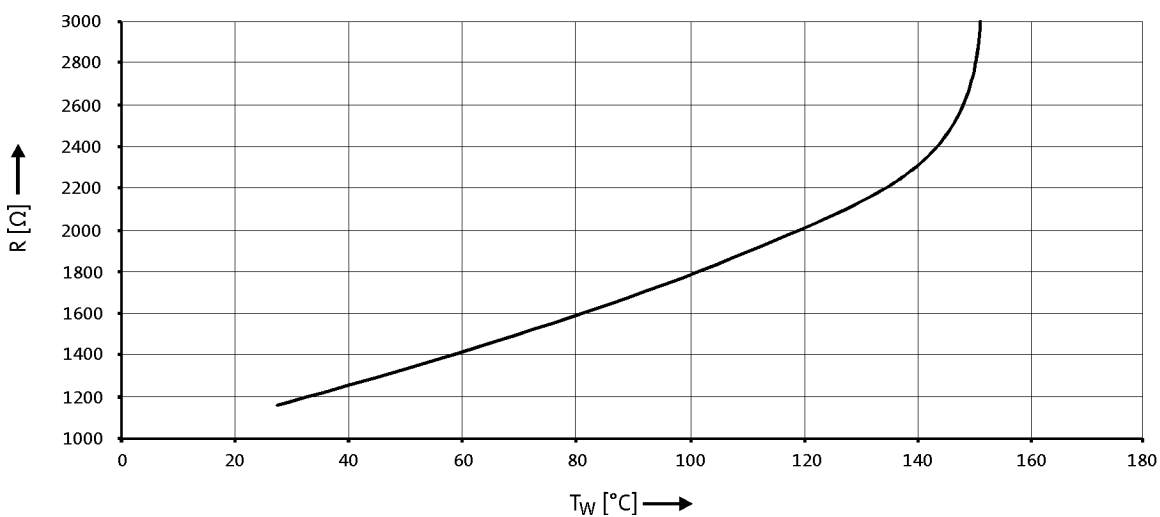
The thermal sensors used in the MCS motors monitor the motor temperature continuously. The temperature signal is transmitted over the system cable of the feedback system to the servo controller. Because of the different physical conditions, there are two temperature monitoring mechanisms on the MCS motors (there is no complete motor protection in either case)

MCS06

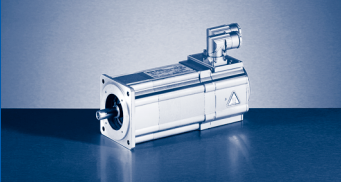
On this motor, the winding temperature of one winding phase is monitored with a KTY 83-110 type thermal sensor.

MCS09 ... 19

These motors are monitored by three thermal sensors (1x KTY 83-110 + 2x PTC 150 °C) connected in series. This means that the temperature of the motor is determined with great accuracy in the permitted operating range and at the same time the overtemperature response configured in the controller is executed in the event of overtemperature in one of the winding phases.



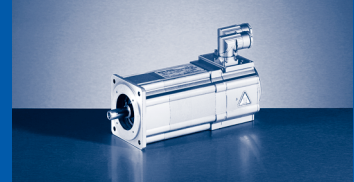
- If the detector is supplied with a measured current of 1 mA, the above relationship between the temperature and the resistance applies.



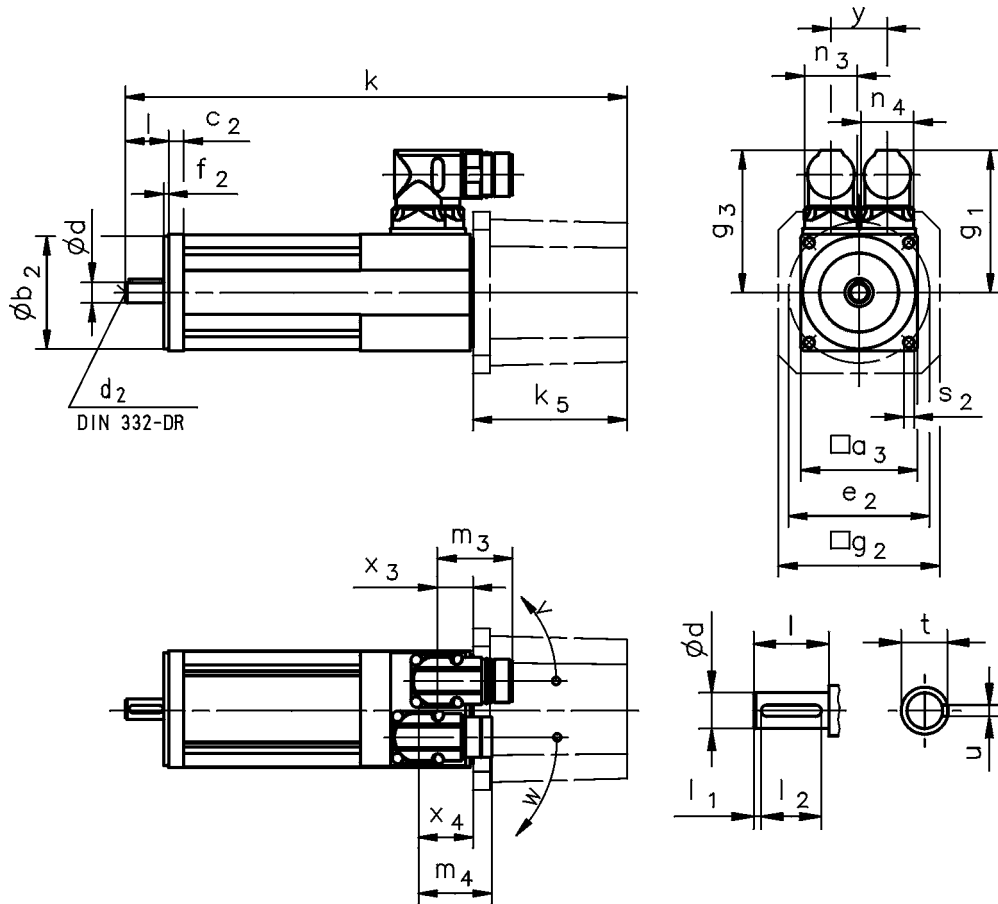
MCS synchronous servo motors

Rated data

3



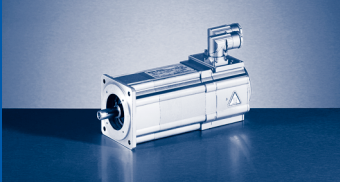
Motors without blower



| | | | MCS06C | MCS06F | MCS06I |
|--------------|----------------|------|--------|--------|--------|
| RS0 / C40 B0 | k | [mm] | 155 | 185 | 215 |
| RS0 / C40 P□ | k | [mm] | 174 | 204 | 233 |
| SR□ / E□□ B0 | k | [mm] | 237 | 266 | 297 |
| SR□ / E□□ P□ | k | [mm] | 255 | 285 | 315 |
| SR□ / E□□ | k ₅ | [mm] | | 82 | |
| | g ₂ | [mm] | | 86 | |

- ▶ Speed/angle sensor: RS0 / C40 / SR□ / E□□
- ▶ Brake: B0 / P□

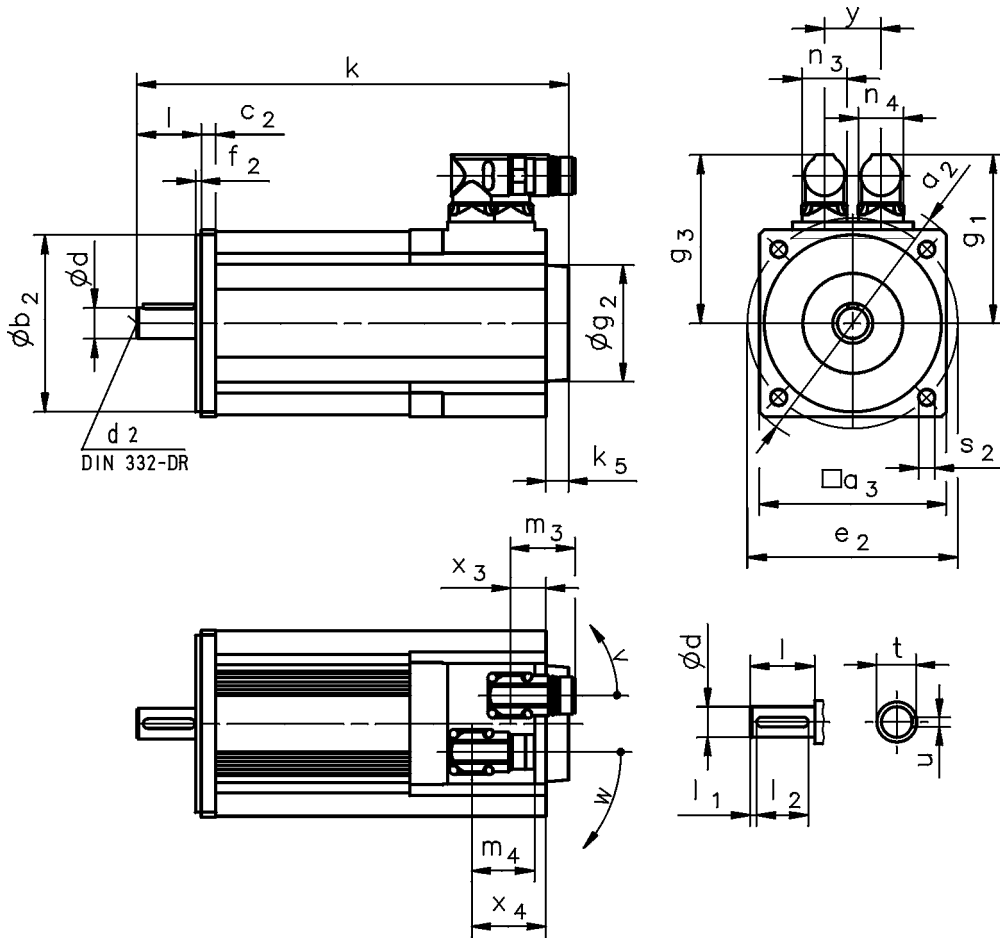
| | g ₁ | g ₃ | x ₃ | x ₄ | m ₃ | m ₄ | n ₃ | n ₄ | y | v | w |
|--------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|------|-----|-----|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [°] | [°] |
| MCS06 | 77 | 77 | 19 | 29 | 40 | 40 | 28 | 28 | 30 | 190 | 230 |
| | d | d ₂ | l | l ₁ | l ₂ | u | t | | | | |
| | k ₆ | | -0.7 ... 0.3 | | | | | | | | |
| | [mm] | [mm] | | [mm] | [mm] | [mm] | [mm] | | | | |
| MCS06 | 11 | M4 | 23 | 2.0 | 18 | 4.0 | 13 | | | | |
| | a ₃ | b ₂ | c ₂ | e ₂ | f ₂ | s ₂ | | | | | |
| | j ₆ | | | | | | | | | | |
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | | | | | |
| MCS06 | 62 | 60 | 8 | 75 | 2.5 | 5.5 | | | | | |



MCS synchronous servo motors

Dimensions [mm]

Motors without blower

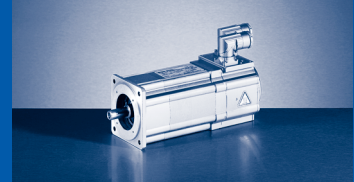


| | | | MCS09D | MCS09F | MCS09H | MCS09L | MCS12D | MCS12H | MCS12L |
|--------------|----------------|------|--------|--------|--------|--------|--------|--------|--------|
| RS0 / C40 B0 | k | [mm] | 213 | 233 | 253 | 293 | 228 | 268 | 308 |
| RS0 / C40 P□ | k | [mm] | 233 | 253 | 273 | 313 | 248 | 288 | 328 |
| RS0 / C40 | k ₅ | [mm] | 13 | | | | | 14 | |
| | g ₂ | [mm] | 67 | | | | | 72 | |
| SR□ / E□□ B0 | k | [mm] | 264 | 284 | 304 | 344 | 277 | 317 | 357 |
| SR□ / E□□ P□ | k | [mm] | 284 | 304 | 324 | 364 | 297 | 337 | 377 |
| SR□ / E□□ | k ₅ | [mm] | 64 | | | | | 63 | |
| | g ₂ | [mm] | 81 | | | | | 89 | |
| | | | MCS14D | MCS14H | MCS14L | MCS14P | MCS19F | MCS19J | MCS19P |
| RS0 / C40 B0 | k | [mm] | 251 | 291 | 331 | 371 | 280 | 320 | 380 |
| RS0 / C40 P□ | k | [mm] | 279 | 319 | 359 | 399 | 314 | 364 | 424 |
| RS0 / C40 | k ₅ | [mm] | 24 | | | | | 15 | |
| | g ₂ | [mm] | | | | 78 | | | |
| SR□ / E□□ B0 | k | [mm] | 301 | 341 | 381 | 421 | 329 | 369 | 429 |
| SR□ / E□□ P□ | k | [mm] | 329 | 369 | 409 | 449 | 363 | 413 | 473 |
| SR□ / E□□ | k ₅ | [mm] | 74 | | | | | 64 | |
| | g ₂ | [mm] | | | | 101 | | | |

- ▶ Speed/angle sensor: RS0 / C40 / SR□ / E□□
- ▶ Brake: B0 / P□

MCS synchronous servo motors

Dimensions [mm]



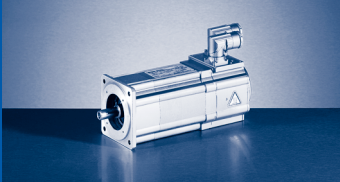
| | g_1 | g_3 | x_3 | x_4 | m_3 | m_4 | n_3 | n_4 | y | v | w |
|--------------|-------|-------|-------|-------|-------|-------|-------|-------|------|-----|-----|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [°] | [°] |
| MCS09 | 90 | 90 | 20 | 44 | 40 | 40 | 28 | 28 | 35 | 195 | 260 |
| MCS12 | 105 | 105 | 22 | 46 | | | | | | | |

| | g_1 | g_3 | x_3 | x_4 | m_3 | m_4 | n_3 | n_4 | y | v | w |
|------------------|-------|-------|------------------------|------------------------|-------|-------|-------|-------|------|-----|-----|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [°] | [°] |
| MCS14D15- | 117 | 117 | 24 | 48 | 40 | 40 | 28 | 28 | 35 | 195 | 260 |
| MCS14D36- | | | | | | | | | | | |
| MCS14H15- | | | | | | | | | | | |
| MCS14H32- | | | | | | | | | | | |
| MCS14L15- | | | | | | | | | | | |
| MCS14L32- | 146 | 126 | 29 | 36 | | 75 | | 45 | | 180 | 205 |
| MCS14P14- | 117 | 117 | 24 | 48 | | 40 | | 28 | | 195 | 260 |
| MCS14P32- | 146 | 126 | 29 | 36 | | 75 | | 45 | | 180 | 205 |
| MCS19F14- | 142 | 142 | 24 51 ¹⁾ | 48 75 ¹⁾ | | 40 | | 28 | | 195 | 260 |
| MCS19F30- | 171 | 151 | 29 56 ¹⁾ | 36 63 ¹⁾ | | 75 | | 45 | | 180 | 205 |
| MCS19J14- | 142 | 142 | 24 51 ¹⁾ | 48 75 ¹⁾ | 40 | 28 | 195 | 260 | | | |
| MCS19J30- | 171 | 151 | 29 56 ¹⁾ | 36 63 ¹⁾ | 75 | 45 | 180 | 205 | | | |
| MCS19P14- | 142 | 142 | 24 51 ¹⁾ | 48 75 ¹⁾ | 40 | 28 | 195 | 260 | | | |
| MCS19P30- | 171 | 151 | 29 56 ¹⁾ | 36 63 ¹⁾ | 75 | 45 | 180 | 205 | | | |

| | d | d_2 | l | l_1 | l_2 | u | t |
|--------------|------|-------|--------------|-------|-------|------|------|
| | k6 | | -0.7 ... 0.3 | | | | |
| | [mm] | [mm] | | [mm] | [mm] | [mm] | [mm] |
| MCS09 | 14 | M5 | 30 | 2.5 | 25 | 5.0 | 16 |
| MCS12 | 19 | M6 | 40 | 4.0 | 32 | 6.0 | 22 |
| MCS14 | 24 | M8 | 50 | 5.0 | 40 | 8.0 | 27 |
| MCS19 | 28 | M10 | 60 | | 50 | | 31 |

| | a_2 | a_3 | b_2 | c_2 | e_2 | f_2 | s_2 |
|--------------|-------|-------|-------|-------|-------|-------|-------|
| | | | j6 | | | | |
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MCS09 | 120 | 89 | 80 | 8 | 100 | 3.0 | 7.0 |
| MCS12 | 160 | 116 | 110 | 9 | 130 | 3.5 | 10.0 |
| MCS14 | 188 | 143 | 130 | 13 | 165 | | 12.0 |
| MCS19 | 250 | 192 | 180 | 11 | 215 | 4.0 | 14.0 |

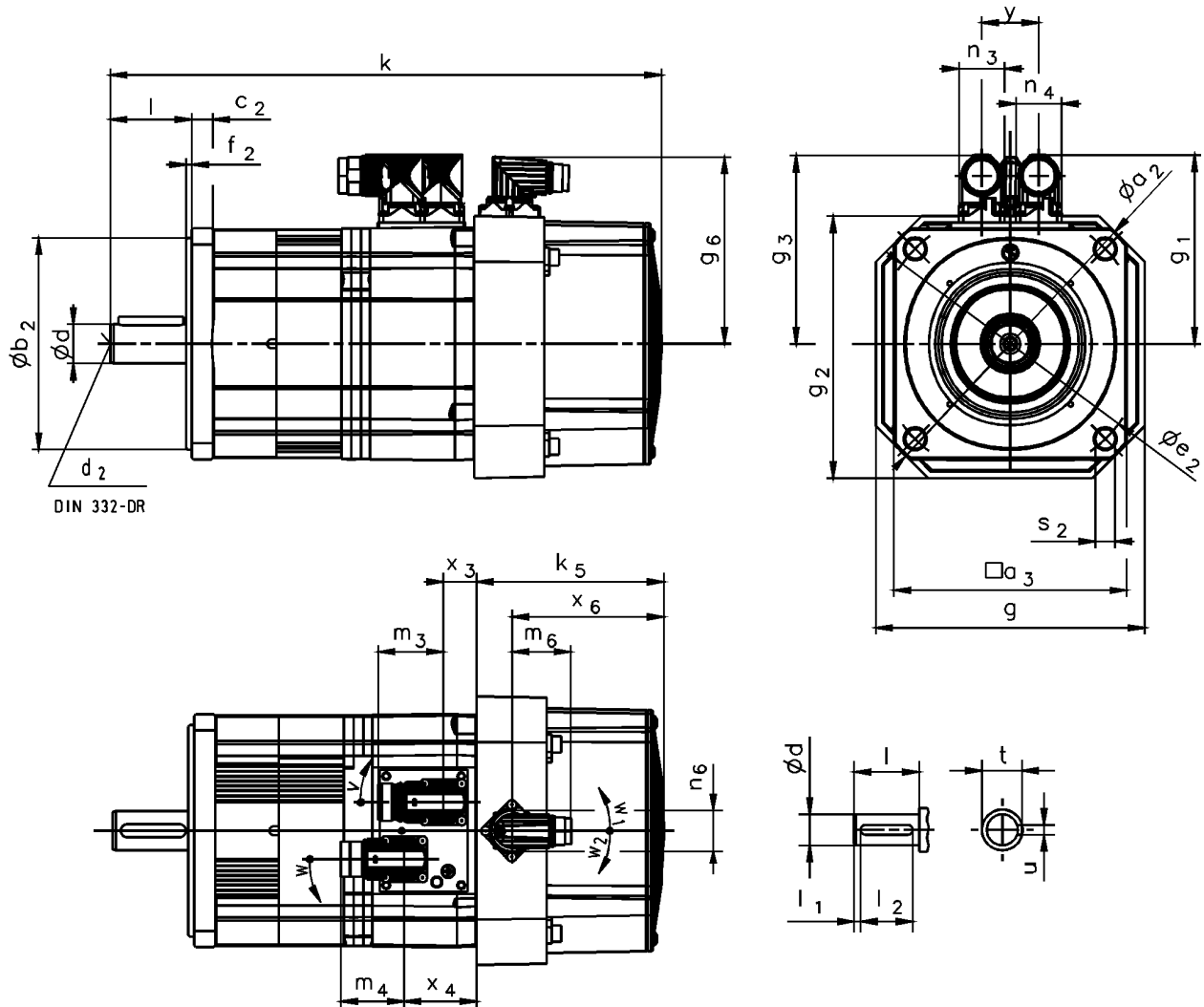
¹⁾ On version with brake (P□)



MCS synchronous servo motors

Dimensions [mm]

Motors with blower



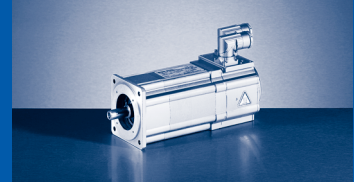
DIN 332-DR

| | | | MCS12D | MCS12H | MCS12L | MCS14D | MCS14H | MCS14L | MCS14P | MCS19F | MCS19J | MCS19P |
|--------------|----------------|------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| RS0 / C40 B0 | k | [mm] | 301 | 341 | 381 | 339 | 379 | 419 | 459 | 387 | 427 | 487 |
| RS0 / C40 P□ | k | [mm] | 321 | 361 | 401 | 368 | 408 | 448 | 488 | 421 | 471 | 531 |
| RS0 / C40 | k ₅ | [mm] | 92 | | | 115 | | | 126 | | | |
| SR□ / E□□ B0 | k | [mm] | 344 | 384 | 424 | 392 | 432 | 472 | 512 | 425 | 465 | 525 |
| SR□ / E□□ P□ | k | [mm] | 364 | 404 | 444 | 421 | 461 | 501 | 541 | 459 | 509 | 569 |
| SR□ / E□□ | k ₅ | [mm] | 135 | | | 169 | | | 165 | | | |
| | g | [mm] | 140 | | | 167 | | | 212 | | | |
| | g ₂ | [mm] | 140 | | | 163 | | | 210 | | | |

- ▶ Speed/angle sensor: RS0 / C40 / SR□ / E□□
- ▶ Brake: B0 / P□

MCS synchronous servo motors

Dimensions [mm]



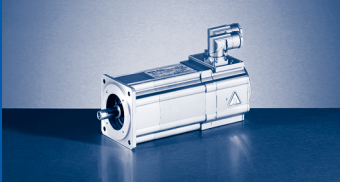
3

| | g ₁ | g ₃ | g ₆ | x ₃ | x ₄ | x ₆ | m ₃ | m ₄ | m ₆ | n ₃ | n ₄ | n ₆ | y | v | w | w ₁ | w ₂ | |
|----------|----------------|----------------|----------------|----------------|------------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|------|-----|-----|----------------|----------------|--|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [°] | [°] | [°] | [°] | |
| MCS12D17 | 105 | 105 | 107 | 16 | 40 | 67 | | 40 | | | 28 | | | | | | | |
| MCS12D35 | | | | | | | | | | | | | | | | | | |
| MCS12H14 | | | | | | | | | | | | | | | | | | |
| MCS12H34 | | | | | | | | | | | | | | | | | | |
| MCS12L17 | | | | | | | | | | | | | | | | | | |
| MCS12L39 | | | | | | | | | | | | | | | | | | |
| MCS14D14 | 117 | 117 | 115 | 20 | 44 | 93 | 40 | 40 | 37 | 28 | 45 | 28 | 35 | 160 | 160 | 120 | 130 | |
| MCS14D30 | | | | | | | | | | | | | | | | | | |
| MCS14H12 | | | | | | | | | | | | | | | | | | |
| MCS14H28 | | | | | | | | | | | | | | | | | | |
| MCS14L14 | | | | | | | | | | | | | | | | | | |
| MCS14L30 | | | | | | | | | | | | | | | | | | |
| MCS14P11 | 146 | 126 | 142 | 19 | 43 | 96 | 75 | 40 | | 28 | 45 | | | | | | | |
| MCS14P26 | | | | | | | | | | | | | | | | | | |
| MCS19F12 | | | | | | | | | | | | | | | | | | |
| MCS19F29 | | | | | | | | | | | | | | | | | | |
| MCS19J12 | | | | | | | | | | | | | | | | | | |
| MCS19J29 | | | | | | | | | | | | | | | | | | |
| MCS19P12 | 171 | 151 | 24 | 31 | 58 ¹⁾ | | | | | | | | | | | | | |
| MCS19P29 | | | | | | | | | | | | | | | | | | |

| | d | d ₂ | l | l ₁ | l ₂ | u | t |
|-------|------|----------------|--------------|----------------|----------------|------|------|
| | k6 | | -0.7 ... 0.3 | | | | |
| | [mm] | [mm] | | [mm] | [mm] | [mm] | [mm] |
| MCS12 | 19 | M6 | 40 | 4.0 | 32 | 6.0 | 22 |
| MCS14 | 24 | M8 | 50 | 5.0 | 40 | 8.0 | 27 |
| MCS19 | 28 | M10 | 60 | | 50 | | 31 |

| | a ₂ | a ₃ | b ₂ | c ₂ | e ₂ | f ₂ | s ₂ |
|-------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
| | | | j6 | | | | |
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MCS12 | 160 | 116 | 110 | 9 | 130 | 3.5 | 10.0 |
| MCS14 | 188 | 143 | 130 | 13 | 165 | | 12.0 |
| MCS19 | 250 | 192 | 180 | 11 | 215 | 4.0 | 14.0 |

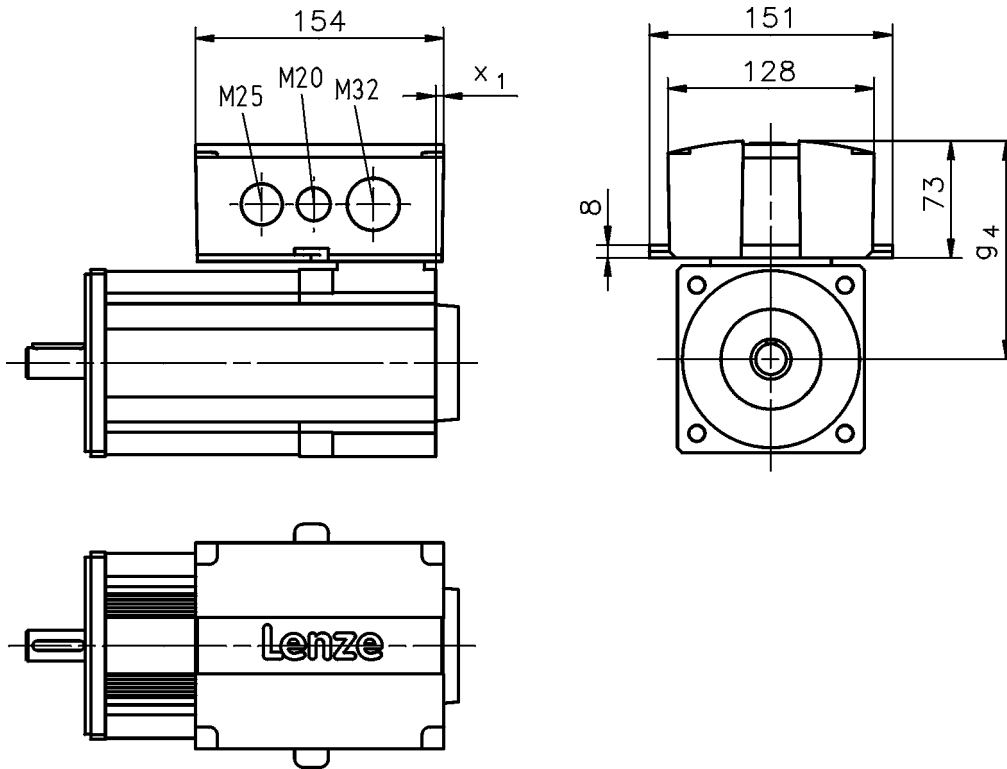
¹⁾ On version with brake (P□)



MCS synchronous servo motors

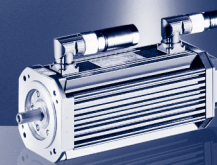
Dimensions [mm]

Motors with terminal box



| | g_4 | x_1 |
|--------------|-------|-------|
| | [mm] | [mm] |
| MCS09 | 121 | 8 |
| MCS12 | 136 | 5 |
| MCS14 | 147 | 3 |
| MCS19 | 172 | |

3



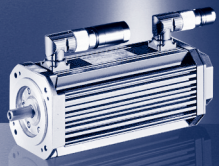
Mains connection 3x 400 V

| | n_N | M_0 | M_{max} | M_N | P_N | I_0 | I_N | I_{max} | $U_{N, AC}$ | f_N |
|----------------------|---------|-------|-----------|-------|-------|-------|-------|-----------|-------------|-------|
| | [r/min] | [Nm] | [Nm] | [Nm] | [kW] | [A] | [A] | [A] | [V] | [Hz] |
| MDSKS□□056-23 | 3800 | 3.20 | 11.6 | 2.80 | 1.10 | 2.60 | 2.30 | 10.0 | 330 | 190 |
| MDSKS□□056-33 | 4000 | 4.70 | 17.2 | 4.20 | 1.80 | 4.00 | 3.60 | 16.0 | 325 | 200 |
| MDSKS□□071-03 | 3400 | 6.70 | 23.6 | 5.70 | 2.00 | 4.90 | 4.20 | 19.0 | 330 | 170 |
| MDSKS□□071-13 | 3700 | 10.0 | 35.2 | 8.30 | 3.20 | 8.40 | 7.00 | 32.0 | 325 | 185 |
| MDSKS□□071-33 | 3600 | 14.7 | 52.0 | 12.3 | 4.60 | 11.9 | 10.0 | 45.0 | 325 | 180 |
| MDFKS□□071-03 | 3300 | 8.80 | 23.6 | 7.50 | 2.60 | 6.60 | 5.60 | 19.0 | 330 | 165 |
| MDFKS□□071-13 | 3600 | 13.3 | 35.2 | 11.0 | 4.10 | 11.1 | 9.20 | 32.0 | 325 | 180 |
| MDFKS□□071-33 | 3500 | 19.3 | 52.0 | 16.2 | 5.90 | 15.6 | 13.1 | 45.0 | 325 | 175 |

| | $\eta_{100\%}$ | $J^1)$ | $KE_{LL 150\text{ °C}}$ | $R_{UV 20\text{ °C}}$ | $R_{UV 150\text{ °C}}$ | L_N | $Kt_{0 150\text{ °C}}$ | $n_{max}^2)$ | $m^1)$ |
|----------------------|----------------|----------------------|-------------------------|-----------------------|------------------------|-------|------------------------|--------------|--------|
| | [%] | [kgcm ²] | [V / 1000 rp] | [Ω] | [Ω] | [mH] | [Nm/A] | [r/min] | [kg] |
| MDSKS□□056-23 | 85 | 1.20 | 78.1 | 10.1 | 13.6 | 17.1 | 1.23 | 5500 | 5.30 |
| MDSKS□□056-33 | 87 | 1.80 | 74.6 | 5.10 | 6.90 | 10.8 | 1.18 | 5500 | 6.30 |
| MDSKS□□071-03 | 85 | 6.00 | 93.0 | 3.40 | 4.60 | 10.6 | 1.37 | 5000 | 8.90 |
| MDSKS□□071-13 | 82 | 8.00 | 84.5 | 1.50 | 2.10 | 5.30 | 1.19 | 5000 | 10.9 |
| MDSKS□□071-33 | 82 | 10.0 | 88.2 | 1.10 | 1.60 | 5.80 | 1.24 | 5000 | 13.0 |
| MDFKS□□071-03 | 81 | 6.00 | 93.0 | 3.40 | 4.60 | 10.6 | 1.33 | 5000 | 10.2 |
| MDFKS□□071-13 | 79 | 8.00 | 84.5 | 1.50 | 2.10 | 5.30 | 1.20 | 5000 | 12.2 |
| MDFKS□□071-33 | 80 | 10.0 | 88.2 | 1.10 | 1.60 | 5.80 | 1.24 | 5000 | 12.2 |

¹⁾ Without brake.

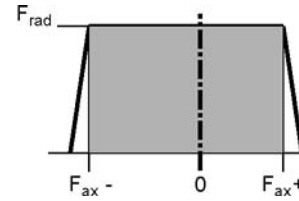
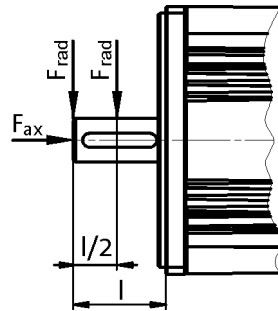
²⁾ Mechanically permissible maximum speed.



MDKS synchronous servo motors

Rated data

Permissible radial and axial forces



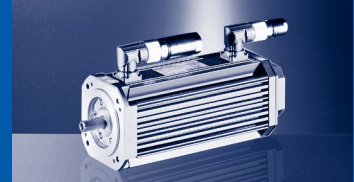
Application of force at l/2

| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|------------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MDSKS□□056 | 590 | -90 | 280 | 470 | -40 | 230 | 370 | 0 | 190 | 310 | 10 | 180 | 220 | 10 | 180 |
| MDSKS□□071 | 910 | -50 | 520 | 700 | 20 | 450 | 430 | 20 | 450 | | 20 | 450 | 50 | -50 | 520 |
| MDFKS□□071 | | | | | | | | | | | | | | | |

Application of force at l

| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|------------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MDSKS□□056 | 550 | -90 | 280 | 430 | -40 | 230 | 340 | 0 | 190 | 290 | 10 | 180 | 200 | 10 | 180 |
| MDSKS□□071 | 820 | -50 | 520 | 630 | 20 | 450 | 390 | 20 | 450 | 280 | 20 | 450 | 40 | -50 | 520 |
| MDFKS□□071 | | | | | | | | | | | | | | | |

- ▶ The values for the bearing service life L_{10} refer to an average speed of 4000 r/min. Depending on the ambient temperatures, the service life of the bearings is also reduced by the grease lifetime.

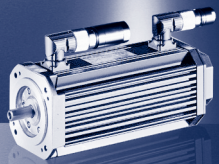


**Mains connection 3 x 400 V and switching frequency
4 kHz**

Motors without blower

| | | | | | E94A□□ | E0024 | E0034 | E0044 | E0074 | E0094 | E0134 | E0174 |
|--------|-------|-------|-------|-------|-------------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 1.9 | 3.1 | 5.0 | 8.8 | 11.7 | 16.3 | 20.6 |
| | | | | | $I_{0,max}$ | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 |
| MDSKS | M_N | n_N | I_N | P_N | I_{max} | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 |
| 056-23 | 2.8 | 3800 | 2.3 | 1.10 | M_0 | 2.3 | 3.2 | | | | | |
| | | | | | M_N | 2.3 | 2.8 | | | | | |
| | | | | | $M_{0,max}$ | 7.5 | 11.6 | | | | | |
| | | | | | M_{max} | 7.5 | 11.6 | | | | | |
| | | | | | n_{eto} | - | - | | | | | |
| 056-33 | 4.2 | 4000 | 3.6 | 1.80 | M_0 | | 3.6 | 4.7 | | | | |
| | | | | | M_N | | 3.6 | 4.2 | | | | |
| | | | | | $M_{0,max}$ | | 12.0 | 17.2 | | | | |
| | | | | | M_{max} | | 12.0 | 17.2 | | | | |
| | | | | | n_{eto} | | - | - | | | | |
| 071-03 | 5.7 | 3400 | 4.2 | 2.00 | M_0 | | 4.2 | 6.7 | 6.7 | | | |
| | | | | | M_N | | 4.2 | 5.7 | 5.7 | | | |
| | | | | | $M_{0,max}$ | | 15.2 | 21.4 | 23.6 | | | |
| | | | | | M_{max} | | 15.2 | 21.4 | 23.6 | | | |
| | | | | | n_{eto} | | - | - | - | | | |
| 071-13 | 8.3 | 3700 | 7.0 | 3.20 | M_0 | | | 6.0 | 10.0 | 10.0 | 10.0 | |
| | | | | | M_N | | | 5.9 | 8.3 | 8.3 | 8.3 | |
| | | | | | $M_{0,max}$ | | | 22.0 | 27.1 | 32.7 | 35.2 | |
| | | | | | M_{max} | | | 22.0 | 27.1 | 32.7 | 35.2 | |
| | | | | | n_{eto} | | | - | - | - | - | |
| 071-33 | 12.3 | 3600 | 10.0 | 4.60 | M_0 | | | | 10.9 | 14.3 | 14.7 | 14.7 |
| | | | | | M_N | | | | 10.8 | 12.3 | 12.3 | 12.3 |
| | | | | | $M_{0,max}$ | | | | 31.2 | 38.9 | 48.3 | 52.0 |
| | | | | | M_{max} | | | | 31.2 | 38.9 | 48.3 | 52.0 |
| | | | | | n_{eto} | | | | - | - | - | - |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MD□KS synchronous servo motors

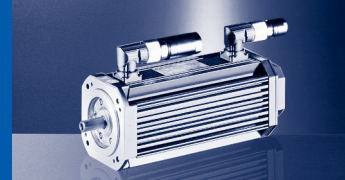
9400 Servo Drives selection tables

Mains connection 3 x 400 V and switching frequency
4 kHz

Motors with blower

| | | | | | E94A□□ | E0044 | E0074 | E0094 | E0134 | E0174 |
|--------|-------|-------|-------|-------|-------------|-------|-------|-------|-------|-------|
| | | | | | I_N | 5.0 | 8.8 | 11.7 | 16.3 | 20.6 |
| | | | | | $I_{0,max}$ | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 |
| MDFKS | M_N | n_N | I_N | P_N | I_{max} | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 |
| 071-03 | 7.5 | 3300 | 5.6 | 2.60 | M_0 | 6.7 | 8.8 | | | |
| | | | | | M_N | 6.7 | 7.5 | | | |
| | | | | | $M_{0,max}$ | 21.6 | 23.6 | | | |
| | | | | | M_{max} | 21.6 | 23.6 | | | |
| | | | | | n_{eto} | - | - | | | |
| 071-13 | 11.0 | 3600 | 9.2 | 4.10 | M_0 | | 10.5 | 13.3 | 13.3 | |
| | | | | | M_N | | 10.5 | 11.0 | 11.0 | |
| | | | | | $M_{0,max}$ | | 27.8 | 33.1 | 35.2 | |
| | | | | | M_{max} | | 27.8 | 33.1 | 35.2 | |
| | | | | | n_{eto} | | - | - | - | |
| 071-33 | 16.2 | 3500 | 13.1 | 5.90 | M_0 | | | 14.4 | 19.3 | 19.3 |
| | | | | | M_N | | | 14.3 | 16.2 | 16.2 |
| | | | | | $M_{0,max}$ | | | 40.0 | 48.8 | 52.0 |
| | | | | | M_{max} | | | 40.0 | 48.8 | 52.0 |
| | | | | | n_{eto} | | | - | - | - |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

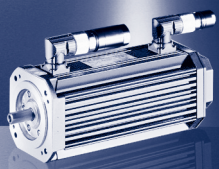


Mains connection 3 x 400 V and switching frequency 8 kHz

Motors without blower

| | | | | | E84AVTC | □5514 | □7514 | □1124 | □1524 | □2224 | □3024 | □4024 | □5524 | □7524 | □1134 | □1534 |
|--------|-------|-------|-------|-------|-------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 1.8 | 2.4 | 3.2 | 3.9 | 5.9 | 7.3 | 9.5 | 13.0 | 16.5 | 23.5 | 32.0 |
| | | | | | $I_{0,max}$ | 2.7 | 3.6 | 4.8 | 5.9 | 8.4 | 11.0 | 14.3 | 19.5 | 26.4 | 32.9 | 43.2 |
| MDSKS | M_N | n_N | I_N | P_N | I_{max} | 3.6 | 4.8 | 6.4 | 7.8 | 11.8 | 14.6 | 19.0 | 26.0 | 33.0 | 47.0 | 64.0 |
| 056-23 | 2.8 | 3800 | 2.3 | 1.10 | M_0 | 2.4 | 3.1 | 3.2 | 3.2 | 3.2 | 3.2 | | | | | |
| | | | | | M_N | 2.2 | 2.8 | 2.8 | 2.8 | 2.8 | 2.8 | | | | | |
| | | | | | $M_{0,max}$ | 4.6 | 6.2 | 8.0 | 9.8 | 11.6 | 11.6 | | | | | |
| | | | | | M_{max} | 4.6 | 6.2 | 8.0 | 9.8 | 11.6 | 11.6 | | | | | |
| | | | | | n_{eto} | - | - | - | - | - | - | | | | | |
| 056-33 | 4.2 | 4000 | 3.6 | 1.80 | M_0 | | | 4.1 | 4.6 | 4.7 | 4.7 | 4.7 | 4.7 | | | |
| | | | | | M_N | | | 3.7 | 4.2 | 4.2 | 4.2 | 4.2 | 4.2 | | | |
| | | | | | $M_{0,max}$ | | | 8.2 | 10.0 | 14.0 | 17.2 | 16.8 | 17.2 | | | |
| | | | | | M_{max} | | | 8.2 | 10.0 | 14.0 | 17.2 | 16.8 | 17.2 | | | |
| | | | | | n_{eto} | | | - | - | - | - | - | - | | | |
| 071-03 | 5.7 | 3400 | 4.2 | 2.00 | M_0 | | | 4.3 | 5.3 | 6.7 | 6.7 | 6.7 | 6.7 | | | |
| | | | | | M_N | | | 4.3 | 5.3 | 5.7 | 5.7 | 5.7 | 5.7 | | | |
| | | | | | $M_{0,max}$ | | | 10.5 | 12.8 | 17.8 | 22.0 | 23.0 | 23.6 | | | |
| | | | | | M_{max} | | | 10.5 | 12.8 | 17.8 | 22.0 | 23.0 | 23.6 | | | |
| | | | | | n_{eto} | | | - | - | - | - | - | - | | | |
| 071-13 | 8.3 | 3700 | 7.0 | 3.20 | M_0 | | | | | 7.0 | 8.7 | 10.0 | 10.0 | 10.0 | 10.0 | |
| | | | | | M_N | | | | | 7.0 | 8.7 | 8.3 | 8.3 | 8.3 | 8.3 | |
| | | | | | $M_{0,max}$ | | | | | 17.4 | 21.6 | 25.0 | 29.3 | 29.3 | 29.3 | |
| | | | | | M_{max} | | | | | 17.4 | 21.6 | 25.0 | 34.3 | 35.2 | 35.2 | |
| | | | | | n_{eto} | | | | | - | - | - | - | - | - | |
| 071-33 | 12.3 | 3600 | 10.0 | 4.60 | M_0 | | | | | | | 14.0 | 14.7 | 14.7 | 14.7 | 14.7 |
| | | | | | M_N | | | | | | | 11.7 | 12.3 | 12.3 | 12.3 | 12.3 |
| | | | | | $M_{0,max}$ | | | | | | | 28.5 | 39.1 | 42.7 | 42.7 | 42.7 |
| | | | | | M_{max} | | | | | | | 28.5 | 39.1 | 52.0 | 52.0 | 52.0 |
| | | | | | n_{eto} | | | | | | | - | - | - | - | - |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MDKS synchronous servo motors

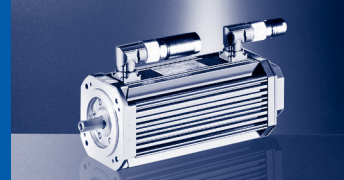
Selection tables for Inverter Drives 8400 TopLine

Mains connection 3 x 400 V and switching frequency
8 kHz

Motors with blower

| | | | | | E84AVTC | □1124 | □1524 | □2224 | □3024 | □4024 | □5524 | □7524 | □1134 | □1534 |
|--------|-------|-------|-------|-------|-------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 3.2 | 3.9 | 5.9 | 7.3 | 9.5 | 13.0 | 16.5 | 23.5 | 32.0 |
| | | | | | $I_{0,max}$ | 4.8 | 5.9 | 8.4 | 11.0 | 14.3 | 19.5 | 26.4 | 32.9 | 43.2 |
| MDFKS | M_N | n_N | I_N | P_N | I_{max} | 6.4 | 7.8 | 11.8 | 14.6 | 19.0 | 26.0 | 33.0 | 47.0 | 64.0 |
| 071-03 | 7.5 | 3300 | 5.6 | 2.60 | M_0 | 4.3 | 5.2 | 8.8 | 8.8 | 8.8 | 8.8 | | | |
| | | | | | M_N | 4.3 | 5.2 | 7.5 | 7.5 | 7.5 | 7.5 | | | |
| | | | | | $M_{0,max}$ | 8.6 | 10.4 | 18.3 | 22.7 | 23.0 | 23.6 | | | |
| | | | | | M_{max} | 8.6 | 10.4 | 18.3 | 22.7 | 23.0 | 23.6 | | | |
| | | | | | n_{eto} | - | - | - | - | - | - | | | |
| 071-13 | 11.0 | 3600 | 9.2 | 4.10 | M_0 | | | 7.1 | 8.8 | 13.3 | 13.3 | 13.3 | 13.3 | |
| | | | | | M_N | | | 7.1 | 8.8 | 11.0 | 11.0 | 11.0 | 11.0 | |
| | | | | | $M_{0,max}$ | | | 14.2 | 17.5 | 25.7 | 29.9 | 29.9 | 29.3 | |
| | | | | | M_{max} | | | 14.2 | 17.5 | 25.7 | 35.2 | 35.2 | 35.2 | |
| | | | | | n_{eto} | | | - | - | - | - | - | - | |
| 071-33 | 16.2 | 3500 | 13.1 | 5.90 | M_0 | | | | | 11.8 | 16.1 | 19.3 | 19.3 | 19.3 |
| | | | | | M_N | | | | | 11.8 | 16.1 | 16.2 | 16.2 | 16.2 |
| | | | | | $M_{0,max}$ | | | | | 29.7 | 40.7 | 43.6 | 43.6 | 43.6 |
| | | | | | M_{max} | | | | | 29.7 | 40.7 | 52.0 | 52.0 | 52.0 |
| | | | | | n_{eto} | | | | | - | - | - | - | - |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

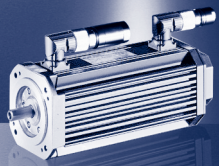


**Mains connection 3 x 400 V and switching frequency
4 kHz**

Motors without blower

| | | | | | ECS□□ | 008C□B | 016C□B | 032C□B | 048C□B |
|--------|-------|-------|-------|-------|-------------|--------|--------|--------|--------|
| | | | | | I_N | 4.0 | 8.0 | 12.7 | 17.0 |
| | | | | | $I_{0,max}$ | 4.6 | 9.1 | 18.1 | 27.2 |
| MDSKS | M_N | n_N | I_N | P_N | I_{max} | 8.0 | 16.0 | 32.0 | 48.0 |
| 056-23 | 2.8 | 3800 | 2.3 | 1.10 | M_0 | 3.2 | 3.2 | | |
| | | | | | M_N | 2.8 | 2.8 | | |
| | | | | | $M_{0,max}$ | 5.9 | 10.7 | | |
| | | | | | M_{max} | 9.6 | 11.6 | | |
| | | | | | n_{eto} | 2816 | 2452 | | |
| 056-33 | 4.2 | 4000 | 3.6 | 1.80 | M_0 | 4.7 | 4.7 | | |
| | | | | | M_N | 4.2 | 4.2 | | |
| | | | | | $M_{0,max}$ | 5.4 | 11.1 | | |
| | | | | | M_{max} | 9.9 | 17.2 | | |
| | | | | | n_{eto} | 3620 | 2705 | | |
| 071-03 | 5.7 | 3400 | 4.2 | 2.00 | M_0 | 5.5 | 6.7 | | |
| | | | | | M_N | 5.4 | 5.7 | | |
| | | | | | $M_{0,max}$ | 6.2 | 14.1 | | |
| | | | | | M_{max} | 12.7 | 21.4 | | |
| | | | | | n_{eto} | 3177 | 2750 | | |
| 071-13 | 8.3 | 3700 | 7.0 | 3.20 | M_0 | | 9.5 | 10.0 | |
| | | | | | M_N | | 8.3 | 8.3 | |
| | | | | | $M_{0,max}$ | | 10.8 | 24.3 | |
| | | | | | M_{max} | | 22.0 | 35.2 | |
| | | | | | n_{eto} | | 3517 | 3000 | |
| 071-33 | 12.3 | 3600 | 10.0 | 4.60 | M_0 | | 9.9 | 14.7 | 14.7 |
| | | | | | M_N | | 9.8 | 12.3 | 12.3 |
| | | | | | $M_{0,max}$ | | 11.2 | 27.6 | 38.1 |
| | | | | | M_{max} | | 24.8 | 42.7 | 52.0 |
| | | | | | n_{eto} | | 3368 | 2840 | 2350 |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MDKS synchronous servo motors

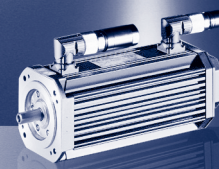
ECS servo system selection tables

Mains connection 3 x 400 V and switching frequency
4 kHz

Motors with blower

| | | | | | ECS□□ | 008C□B | 016C□B | 032C□B | 048C□B |
|--------|-------|-------|-------|-------|-------------|--------|--------|--------|--------|
| | | | | | I_N | 4.0 | 8.0 | 12.7 | 17.0 |
| | | | | | $I_{0,max}$ | 4.6 | 9.1 | 18.1 | 27.2 |
| MDFKS | M_N | n_N | I_N | P_N | I_{max} | 8.0 | 16.0 | 32.0 | 48.0 |
| 071-03 | 7.5 | 3300 | 5.6 | 2.60 | M_0 | 5.3 | 8.8 | | |
| | | | | | M_N | 5.4 | 7.5 | | |
| | | | | | $M_{0,max}$ | 6.2 | 14.6 | | |
| | | | | | M_{max} | 13.2 | 21.6 | | |
| | | | | | n_{eto} | 3177 | 2750 | | |
| 071-13 | 11.0 | 3600 | 9.2 | 4.10 | M_0 | | 9.6 | 13.3 | |
| | | | | | M_N | | 9.6 | 11.0 | |
| | | | | | $M_{0,max}$ | | 10.9 | 25.0 | |
| | | | | | M_{max} | | 22.8 | 35.2 | |
| | | | | | n_{eto} | | 3517 | 3000 | |
| 071-33 | 16.2 | 3500 | 13.1 | 5.90 | M_0 | | | 15.7 | 19.3 |
| | | | | | M_N | | | 15.7 | 16.2 |
| | | | | | $M_{0,max}$ | | | 22.4 | 39.2 |
| | | | | | M_{max} | | | 43.6 | 52.0 |
| | | | | | n_{eto} | | | 2840 | 2350 |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

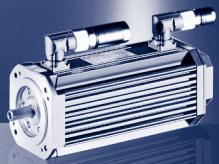


Mains connection 3 x 400 V and switching frequency
8 kHz

Motors without blower

| | | | | | EVS | 9322-E□ | 9323-E□ | 9324-E□ | 9325-E□ | 9326-E□ | 9327-E□ |
|--------|-------|-------|-------|-------|-------------|---------|---------|---------|---------|---------|---------|
| | | | | | I_N | 2.5 | 3.9 | 7.0 | 13.0 | 23.5 | 32.0 |
| | | | | | $I_{0,max}$ | 3.8 | 5.9 | 10.5 | 19.5 | 23.5 | 32.0 |
| MDSKS | M_N | n_N | I_N | P_N | I_{max} | 3.8 | 5.9 | 10.5 | 19.5 | 35.3 | 48.0 |
| 056-23 | 2.8 | 3800 | 2.3 | 1.10 | M_0 | 3.1 | 3.2 | 3.2 | | | |
| | | | | | M_N | 2.8 | 2.8 | 2.8 | | | |
| | | | | | $M_{0,max}$ | 4.9 | 7.4 | 11.6 | | | |
| | | | | | M_{max} | 4.9 | 7.4 | 11.6 | | | |
| | | | | | n_{eto} | 3601 | 3248 | 2452 | | | |
| 056-33 | 4.2 | 4000 | 3.6 | 1.80 | M_0 | | 4.6 | 4.7 | 4.7 | | |
| | | | | | M_N | | 4.2 | 4.2 | 4.2 | | |
| | | | | | $M_{0,max}$ | | 7.6 | 12.5 | 17.2 | | |
| | | | | | M_{max} | | 7.6 | 12.5 | 17.2 | | |
| | | | | | n_{eto} | | 3834 | 3360 | 2455 | | |
| 071-03 | 5.7 | 3400 | 4.2 | 2.00 | M_0 | | 5.3 | 6.7 | 6.7 | | |
| | | | | | M_N | | 5.3 | 5.7 | 5.7 | | |
| | | | | | $M_{0,max}$ | | 9.7 | 15.8 | 23.6 | | |
| | | | | | M_{max} | | 9.7 | 15.8 | 23.6 | | |
| | | | | | n_{eto} | | 3291 | 3047 | 2500 | | |
| 071-13 | 8.3 | 3700 | 7.0 | 3.20 | M_0 | | | 8.3 | 10.0 | 10.0 | |
| | | | | | M_N | | | 8.3 | 8.3 | 8.3 | |
| | | | | | $M_{0,max}$ | | | 15.5 | 25.7 | 29.3 | |
| | | | | | M_{max} | | | 15.5 | 25.7 | 35.2 | |
| | | | | | n_{eto} | | | 3690 | 3418 | 3000 | |
| 071-33 | 12.3 | 3600 | 10.0 | 4.60 | M_0 | | | | 14.7 | 14.7 | 14.7 |
| | | | | | M_N | | | | 12.3 | 12.3 | 12.3 |
| | | | | | $M_{0,max}$ | | | | 29.3 | 34.1 | 42.7 |
| | | | | | M_{max} | | | | 29.3 | 45.4 | 52.0 |
| | | | | | n_{eto} | | | | 3252 | 2716 | 2350 |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MDKS synchronous servo motors

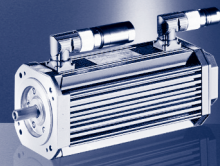
EVS9300 servo inverter selection tables

Mains connection 3 x 400 V and switching frequency
8 kHz

Motors with blower

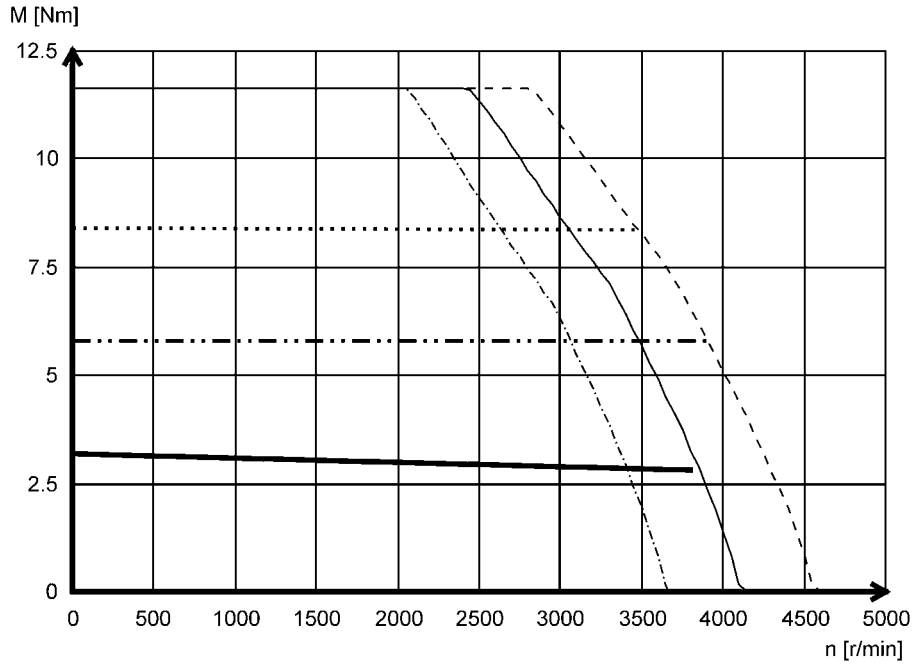
| | | | | | EVS | 9323-E□ | 9324-E□ | 9325-E□ | 9326-E□ | 9327-E□ |
|--------|-------|-------|-------|-------|-------------|---------|---------|---------|---------|---------|
| | | | | | I_N | 3.9 | 7.0 | 13.0 | 23.5 | 32.0 |
| | | | | | $I_{0,max}$ | 5.9 | 10.5 | 19.5 | 23.5 | 32.0 |
| MDFKS | M_N | n_N | I_N | P_N | I_{max} | 5.9 | 10.5 | 19.5 | 35.3 | 48.0 |
| 071-03 | 7.5 | 3300 | 5.6 | 2.60 | M_0 | 5.2 | 8.8 | 8.8 | | |
| | | | | | M_N | 5.2 | 7.5 | 7.5 | | |
| | | | | | $M_{0,max}$ | 7.9 | 16.3 | 23.6 | | |
| | | | | | M_{max} | 7.9 | 16.3 | 23.6 | | |
| | | | | | n_{eto} | 3291 | 3047 | 2500 | | |
| 071-13 | 11.0 | 3600 | 9.2 | 4.10 | M_0 | | 8.4 | 13.3 | 13.3 | |
| | | | | | M_N | | 8.4 | 11.0 | 11.0 | |
| | | | | | $M_{0,max}$ | | 12.6 | 26.4 | 29.9 | |
| | | | | | M_{max} | | 12.6 | 26.4 | 35.2 | |
| | | | | | n_{eto} | | 3690 | 3418 | 3000 | |
| 071-33 | 16.2 | 3500 | 13.1 | 5.90 | M_0 | | | 16.1 | 19.3 | 19.3 |
| | | | | | M_N | | | 16.1 | 16.2 | 16.2 |
| | | | | | $M_{0,max}$ | | | 30.5 | 35.2 | 43.6 |
| | | | | | M_{max} | | | 30.5 | 46.2 | 52.0 |
| | | | | | n_{eto} | | | 3252 | 2716 | 2350 |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



Mains connection 3x 400 V

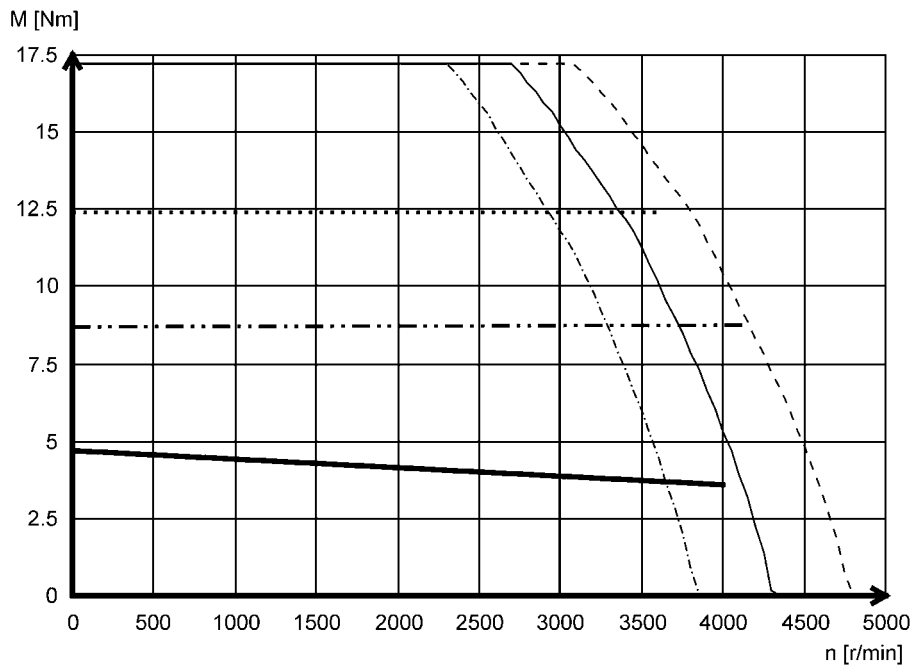
MDSKS□□056-23



- Mmax 440 V
- Mmax 400 V
- · - · Mmax 360 V
- Mmax @ I_{max}= 3x I₀
- · - · Mmax @ I_{max}= 2x I₀
- S1

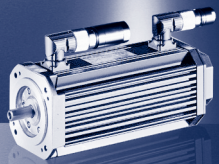
4

MDSKS□□056-33



- Mmax 440 V
- Mmax 400 V
- · - · Mmax 360 V
- Mmax @ I_{max}= 3x I₀
- · - · Mmax @ I_{max}= 2x I₀
- S1

► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

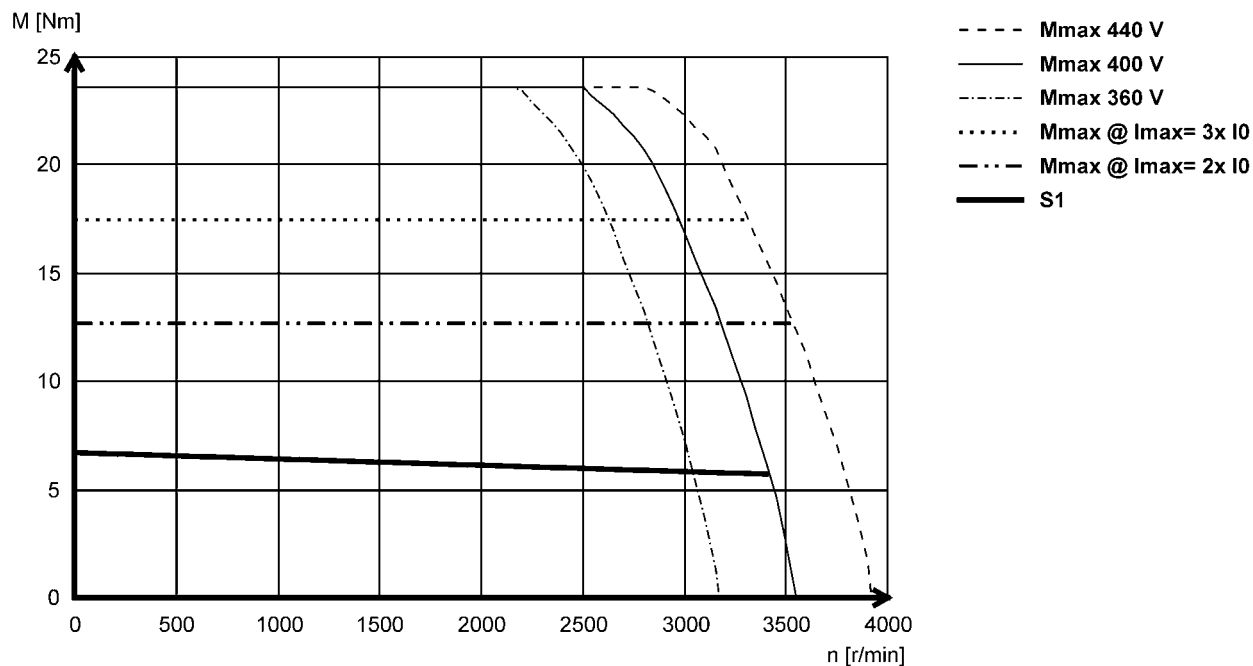


MDKS synchronous servo motors

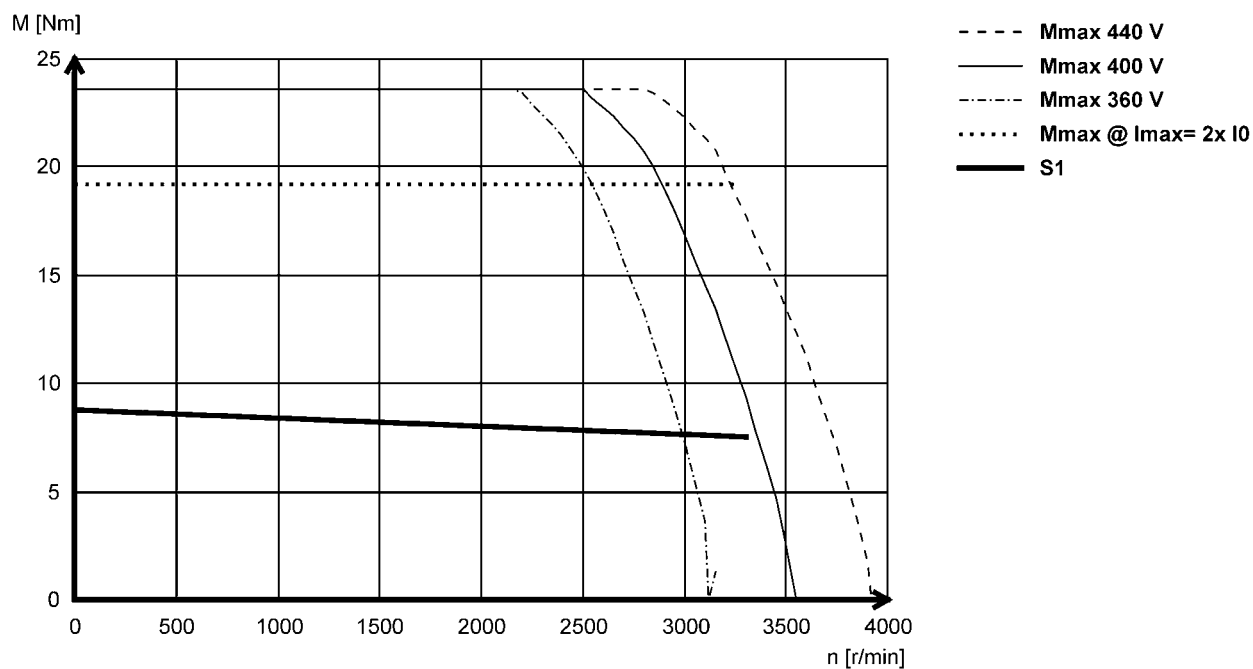
Torque characteristics

Mains connection 3x 400 V

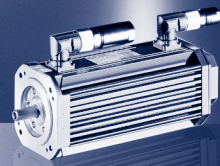
MDSKS□□071-03



MDFKS□□071-03

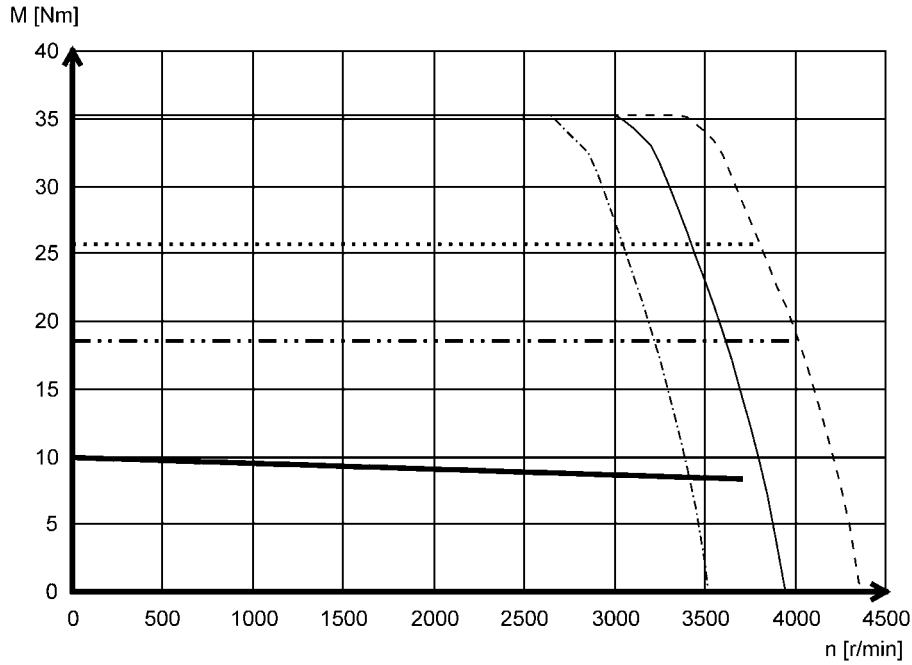


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.



Mains connection 3x 400 V

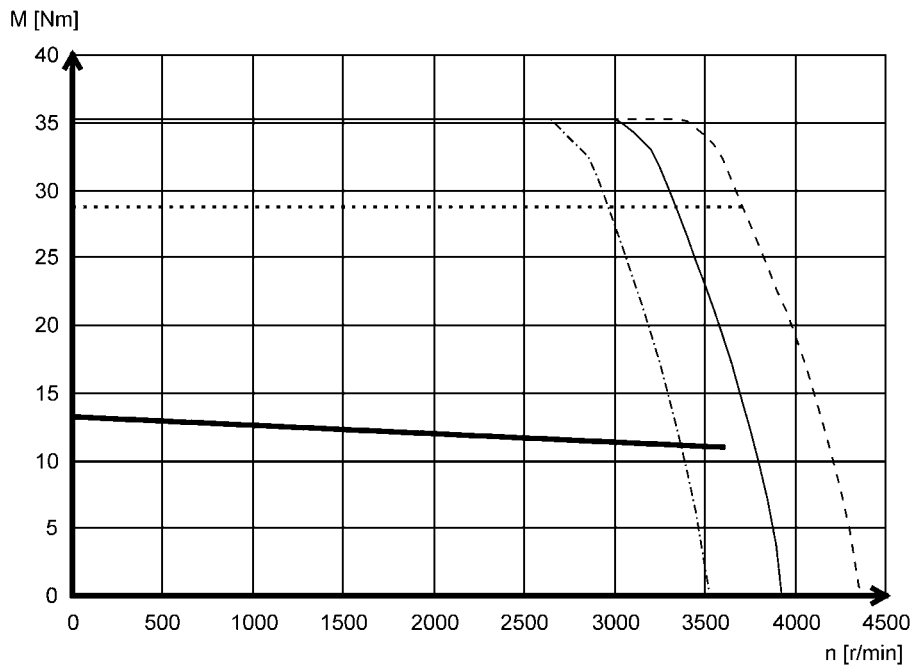
MDSKS□□071-13



- Mmax 440 V
- Mmax 400 V
- · - · - Mmax 360 V
- Mmax @ Imax= 3x I0
- · - · - Mmax @ Imax= 2x I0
- S1

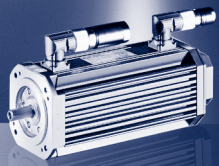
4

MDFKS□□071-13



- Mmax 440 V
- Mmax 400 V
- · - · - Mmax 360 V
- Mmax @ Imax= 2x I0
- S1

► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

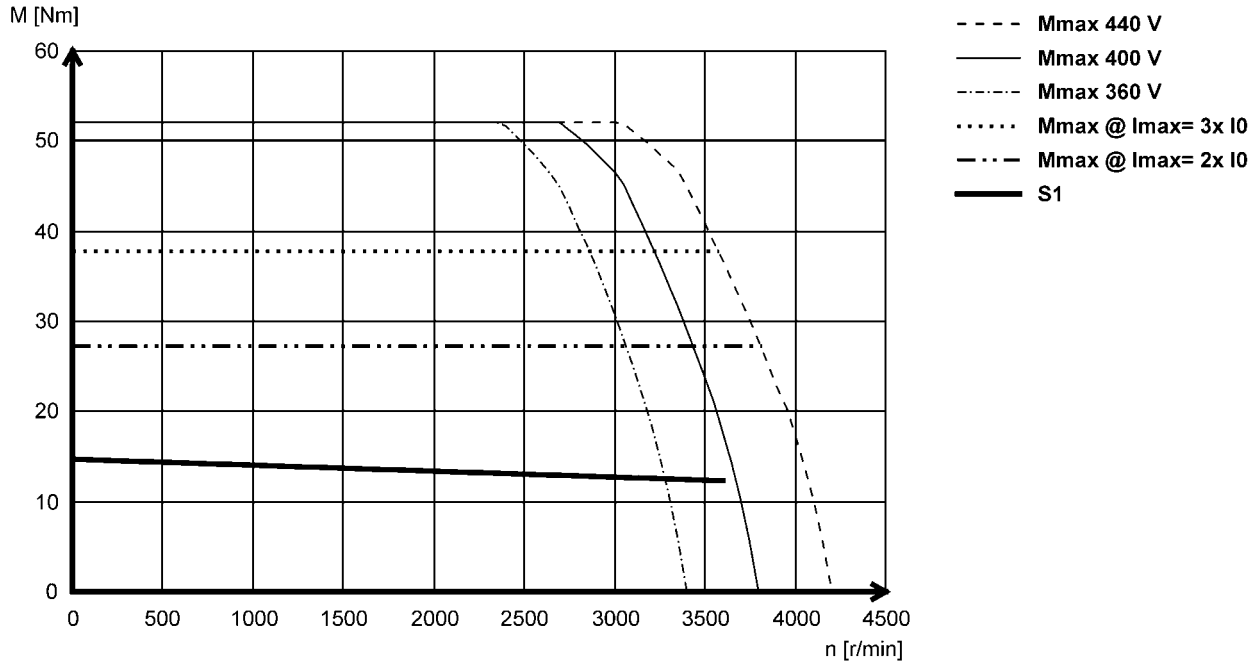


MDKS synchronous servo motors

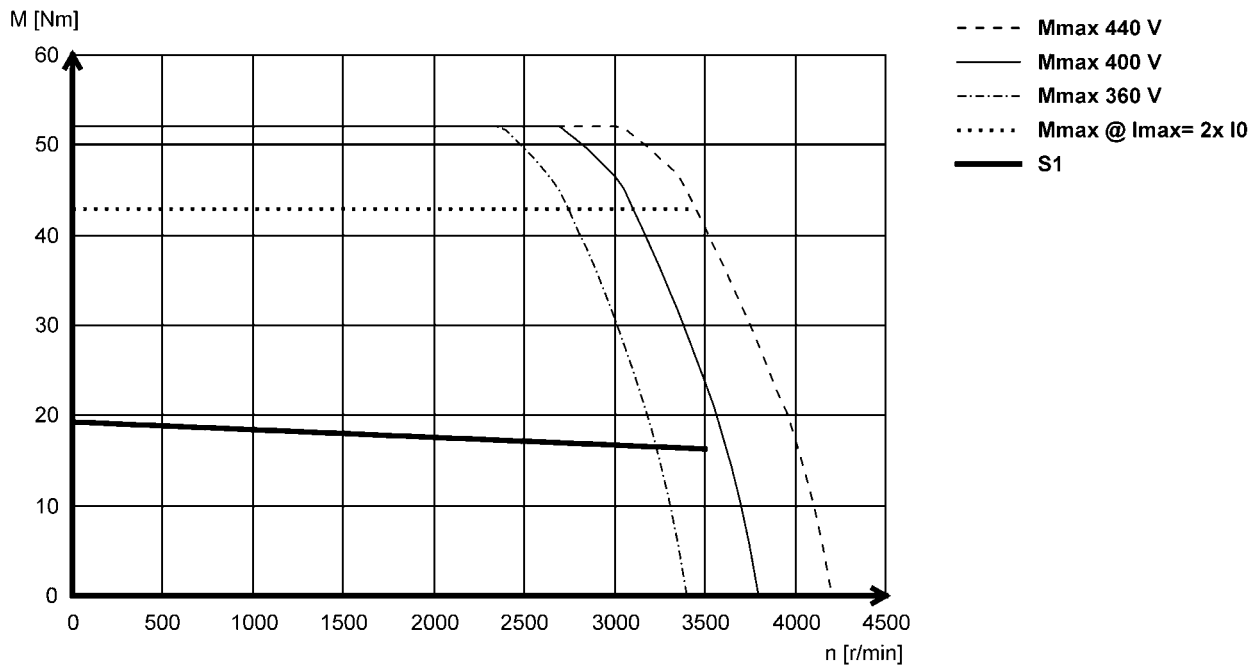
Torque characteristics

Mains connection 3x 400 V

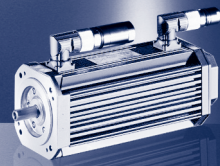
MDSKS□□071-33



MDFKS□□071-33



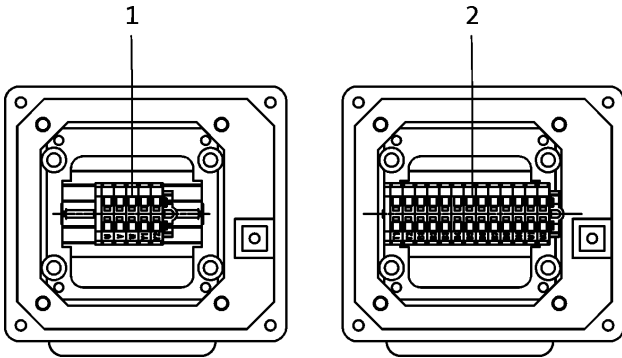
► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.



Motor connection terminal box

If a servo motor is to be connected to an existing cable or plug connectors are not to be used for other reasons, the connection can also be made via a terminal box.

The motor can either be fitted with a terminal box for the power connection and motor holding brake or a second terminal box provided to connect the motor feedback and blower (if applicable).

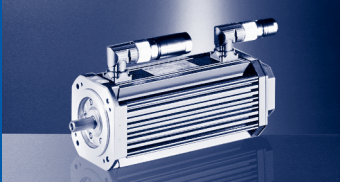


1: Power connection + brake connection + PE connection.

2: Angle/speed sensor connection + thermal sensor connection



MD□KS synchronous servo motors with blower and terminal box



Holding brakes

The MD□KS synchronous servo motors can be equipped with integral permanent magnet holding brakes. The voltages available for this model are 24 V DC and 205 V DC. The brakes are active once the supply voltage is switched off (closed-circuit principle).

With traversing axes, maintaining the permissible mass inertia ratio J_L/J_{MB} ensures that the permissible maximum switching energy of the brake is not exceeded and at least 2000 emergency stop functions are possible when running at a speed of 3000 r/min.

With lifting axes, the load torque resulting from the force due to weight comes into play as an additional factor. In this case, the data specified for J_L/J_{MB} does not apply.

Caution:

The brakes used are not safety brakes in the sense that a reduction in torque may arise as a result of disruptive factors that cannot be influenced, e.g. oil ingress.

The ohmic voltage drop along the cable must be taken into consideration in long motor supply cables and must be compensated for by a higher voltage at the line input.

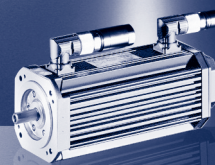
The following applies for Lenze system cables:

$$U[V] = U_B[V] + 0.08 \frac{[V]}{[A] \cdot [m]} \cdot I_{Lg}[m] \cdot I_B[A]$$

If no suitable voltage (incorrect value, incorrect polarity) is applied to the brake, the brake will be applied and can be overheated and destroyed by the motor continuing to rotate. The shortest switching times of the brakes are achieved by DC switching of the voltage. A spark suppressor is required to suppress interference and to increase the service life of the relay contacts here.



Permanent magnet holding brake



Holding brake data

- ▶ The ratings apply only for servo motors and for geared servo motors if the servo motor is mounted by way of a mounting flange.

B5 / B14 design servo motors GPA servo geared motors

| | $U_{N,DC}$ ^{3,4,6)} | M_N | M_N | M_{av} | I_N ²⁾ | J | t_1 ¹⁾ | t_2 ¹⁾ | Q_E ⁵⁾ | m | J_{MB} | J_L / J_{MB} |
|---------------|------------------------------|-------|--------|----------|---------------------|----------------------|---------------------|---------------------|---------------------|------|----------------------|----------------|
| | | 20 °C | 120 °C | 120 °C | | | | | | | | |
| | [V] | [Nm] | [Nm] | [Nm] | [A] | [kgcm ²] | [ms] | [ms] | [J] | [kg] | [kgcm ²] | |
| MDSKS□□056-23 | 24 | 3.30 | 2.50 | 1.20 | 0.50 | 0.38 | 10.0 | 20.0 | 350 | 0.90 | 1.58 | 43.9 |
| MDSKS□□056-33 | | | | | 2.18 | | | | | | 31.5 | |
| MDSKS□□056-23 | 205 | 3.30 | 2.50 | 1.20 | 0.060 | 0.38 | 10.0 | 20.0 | 350 | 0.90 | 1.58 | 43.9 |
| MDSKS□□056-33 | | | | | 2.18 | | | | | | 31.5 | |
| MDSKS□□071-03 | 24 | 12.0 | 11.0 | 5.50 | 0.67 | 1.06 | 20.0 | 29.0 | 400 | 0.80 | 7.06 | 10.5 |
| MDSKS□□071-13 | | | | | 9.06 | | | | | | 8.20 | |
| MDSKS□□071-33 | | | | | 11.1 | | | | | | 6.70 | |
| MDSKS□□071-03 | 205 | 12.0 | 11.0 | 5.50 | 0.080 | 1.06 | 20.0 | 29.0 | 400 | 0.80 | 7.06 | 10.5 |
| MDSKS□□071-13 | | | | | 9.06 | | | | | | 8.20 | |
| MDSKS□□071-33 | | | | | 11.1 | | | | | | 6.70 | |
| MDFKS□□071-03 | 24 | 12.0 | 11.0 | 5.50 | 0.67 | 1.06 | 20.0 | 29.0 | 400 | 0.80 | 7.06 | 10.5 |
| MDFKS□□071-13 | | | | | 9.06 | | | | | | 8.20 | |
| MDFKS□□071-33 | | | | | 11.1 | | | | | | 6.70 | |
| MDFKS□□071-03 | 205 | 12.0 | 11.0 | 5.50 | 0.080 | 1.06 | 20.0 | 29.0 | 400 | 0.80 | 7.06 | 10.5 |
| MDFKS□□071-13 | | | | | 9.06 | | | | | | 8.20 | |
| MDFKS□□071-33 | | | | | 11.1 | | | | | | 6.70 | |

¹⁾ Engagement and disengagement times are valid for rated voltage ($\pm 0\%$) and protective circuit for brakes with varistor for DC switching. The times may increase without a protective circuit.

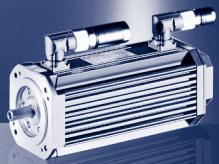
²⁾ The currents are the maximum values when the brake is cold (value used for dimensioning the current supply). The values for a motor at operating temperature are considerably lower.

³⁾ With 24 V DC brake: smoothed DC voltage, ripple $\leq 1\%$.
With 205 V DC brake: connection to 230 V AC through rectifier.

⁴⁾ UR not possible in the case of a brake with a 205 V supply voltage.

⁵⁾ Maximum switching energy per emergency stop at $n = 3000$ r/min for at least 2000 emergency stops.

⁶⁾ Voltage tolerance: $-10 \dots +5\%$



MD□KS synchronous servo motors Accessories

Holding brake data

- ▶ These ratings apply only for geared servo motors with integrated servo motor (without mounting flange).

GST, GFL, GKR, GKS, GSS geared servo motors

| | $U_{N,DC}$ ^{3,4,6)} | M_N | M_N | M_{av} | I_N ²⁾ | J | t_1 ¹⁾ | t_2 ¹⁾ | Q_E ⁵⁾ | m | J_{MB} | J_L / J_{MB} |
|---------------|------------------------------|-------|--------|----------|---------------------|----------------------|---------------------|---------------------|---------------------|------|----------------------|----------------|
| | | 20 °C | 120 °C | 120 °C | | | | | | | | |
| | [V] | [Nm] | [Nm] | [Nm] | [A] | [kgcm ²] | [ms] | [ms] | [J] | [kg] | [kgcm ²] | |
| MDSKS□□056-23 | 24 | 6.00 | 5.00 | 2.50 | 0.67 | 1.06 | 20.0 | 29.0 | 400 | 5.30 | 2.26 | 34.9 |
| MDSKS□□056-33 | | | | | | | | | | 6.30 | 2.86 | 27.3 |
| MDSKS□□056-23 | 205 | 6.00 | 5.00 | 2.50 | 0.80 | 1.06 | 20.0 | 29.0 | 400 | 5.30 | 2.26 | 34.9 |
| MDSKS□□056-33 | | | | | | | | | | 6.30 | 2.86 | 27.3 |
| MDSKS□□071-03 | 24 | 15.0 | 12.0 | 6.00 | 0.75 | 3.60 | 13.0 | 30.0 | 700 | 8.90 | 9.60 | 10.6 |
| MDSKS□□071-13 | | | | | | | | | | 10.9 | 11.6 | 8.80 |
| MDSKS□□071-33 | | | | | | | | | | 13.0 | 13.6 | 7.50 |
| MDSKS□□071-03 | 205 | 15.0 | 12.0 | 6.00 | 0.090 | 3.60 | 13.0 | 30.0 | 700 | 8.90 | 9.60 | 10.6 |
| MDSKS□□071-13 | | | | | | | | | | 10.9 | 11.6 | 8.80 |
| MDSKS□□071-33 | | | | | | | | | | 13.0 | 13.6 | 7.50 |
| MDFKS□□071-03 | 24 | 15.0 | 12.0 | 6.00 | 0.75 | 3.60 | 13.0 | 30.0 | 700 | 10.2 | 9.60 | 10.6 |
| MDFKS□□071-13 | | | | | | | | | | 12.2 | 11.6 | 8.80 |
| MDFKS□□071-33 | | | | | | | | | | 13.6 | 7.50 | |
| MDFKS□□071-03 | 205 | 15.0 | 12.0 | 6.00 | 0.090 | 3.60 | 13.0 | 30.0 | 700 | 10.2 | 9.60 | 10.6 |
| MDFKS□□071-13 | | | | | | | | | | 12.2 | 11.6 | 8.80 |
| MDFKS□□071-33 | 13.6 | 7.50 | | | | | | | | | | |

¹⁾ Engagement and disengagement times are valid for rated voltage ($\pm 0\%$) and protective circuit for brakes with varistor for DC switching. The times may increase without a protective circuit.

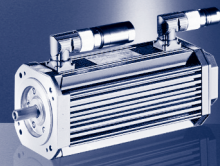
²⁾ The currents are the maximum values when the brake is cold (value used for dimensioning the current supply). The values for a motor at operating temperature are considerably lower.

³⁾ With 24 V DC brake: smoothed DC voltage, ripple $\leq 1\%$.
With 205 V DC brake: connection to 230 V AC through rectifier.

⁴⁾ UR not possible in the case of a brake with a 205 V supply voltage.

⁵⁾ Maximum switching energy per emergency stop at $n = 3000$ r/min for at least 2000 emergency stops.

⁶⁾ Voltage tolerance: $-10 \dots +5\%$

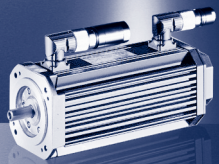


Blower data 50 Hz

| | | Enclosure | Number of phases | | | | | |
|------------|-----|-----------|------------------|-----------|-----------|-------------|-------|-------|
| | | | | U_{min} | U_{max} | $U_{N, AC}$ | P_N | I_N |
| | | | | [V] | [V] | [V] | [kW] | [A] |
| MDFKS□□071 | F10 | IP54 | 1 | 210 | 240 | 230 | 0.019 | 0.12 |

Blower data 60 Hz

| | | Enclosure | Number of phases | | | | | |
|------------|-----|-----------|------------------|-----------|-----------|-------------|-------|-------|
| | | | | U_{min} | U_{max} | $U_{N, AC}$ | P_N | I_N |
| | | | | [V] | [V] | [V] | [kW] | [A] |
| MDFKS□□071 | F10 | IP54 | 1 | 210 | 240 | 230 | 0.019 | 0.12 |



MD□KS synchronous servo motors


Accessories

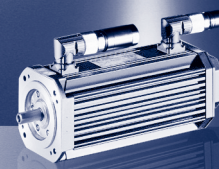
Tailored to meet the requirements of the various applications and necessary accuracies, the following feedback systems are available.

Resolver

Stator-fed resolver with two stator windings offset by 90° and one rotor winding with transformer winding.


| Built-on accessories | 1) | | | BS RS |
|-----------------------------------|---------------------|-----------|---------------|---------------------------------|
| Resolution | | | [°] | 0.80 |
| Angle | | | [°] | -10 ... 10 |
| Accuracy | | | [°] | -10 ... 10 |
| Absolute positioning | | | | 1 revolution |
| Max. speed | n_{\max} | | [r/min] | 8000 |
| Max. input voltage | $U_{\text{in,max}}$ | | [V] | 10.0 |
| DC | | | | |
| Max. input frequency | $f_{\text{in,max}}$ | | [kHz] | 4.00 |
| Ratio | | $\pm 5\%$ | | 0.30 |
| Stator / rotor | | | | |
| Rotor impedance | Z_{ro} | | [Ω] | 51 + j90 |
| Stator impedance | Z_{so} | | [Ω] | 102 + j150 |
| Impedance | Z_{rs} | | [Ω] | 44 + j76 |
| Min. insulation resistance | R | | [M Ω] | 10.0 |
| At DC 500 V | | | | |
| Number of pole pairs | | | | 1 |
| Max. angle error | | | [°] | -10 ... 10 |
| Inverter assignment | | | | E84AVTC E94A ECS EVS93 |

1) →  20 - Product key > built-on accessories

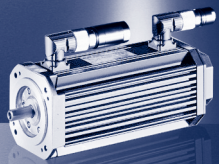


Incremental encoder and SinCos absolute value encoder

| Encoder type | | | SinCos absolute value | |
|-----------------------------------|--------------|---------|---------------------------------|-------------|
| Built-on accessories | 1) | | AG BA | |
| | | | AS1024-8V-H | AM1024-8V-H |
| Encoder type | | | Single-turn | Multi-turn |
| Pulses | | | 1024 | |
| Output signals | | | 1 Vss | |
| Interfaces | | | Hiperface | |
| Absolute revolutions | | | 1 | 4096 |
| Resolution Angle ²⁾ | | [°] | 0.40 | |
| Accuracy | | [°] | -0.8 ... 0.8 | |
| Min. input voltage DC | $U_{in,min}$ | [V] | 7.00 | |
| Max. input voltage DC | $U_{in,max}$ | [V] | 12.0 | |
| Max. speed | n_{max} | [r/min] | 6000 | |
| Max. current consumption | I_{max} | [A] | 0.080 | |
| Limit frequency | f_{max} | [kHz] | 200 | |
| Inverter assignment | | | E84AVTC E94A ECS EVS93 | |

1) →  20 - Product key > built-on accessories

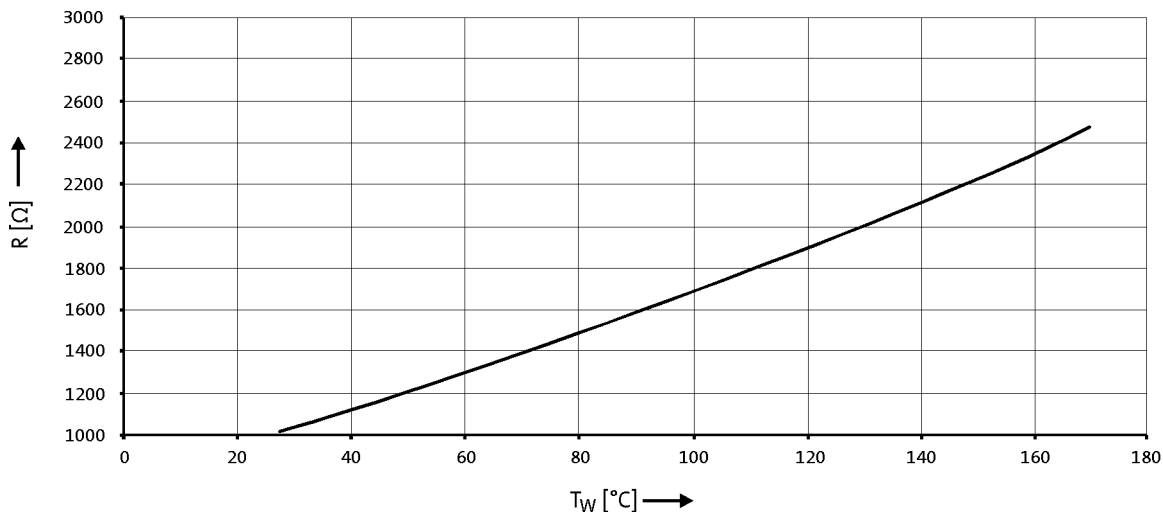
2) Dependent on inverter.



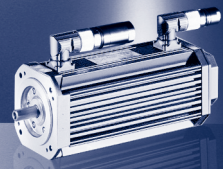
Thermal sensor

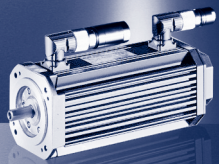
The thermal sensors (1x KTY 83-110) used continuously monitor the motor temperature. The temperature signal is transmitted over the system cable of the feedback system to the servo controller.

This means that the temperature of the motor is determined with great accuracy in the permitted operating range and at the same time the overtemperature response configured in the controller is executed in the event of overtemperature in one of the winding phases.



- If the detector is supplied with a measured current of 1 mA, the above relationship between the temperature and the resistance applies.

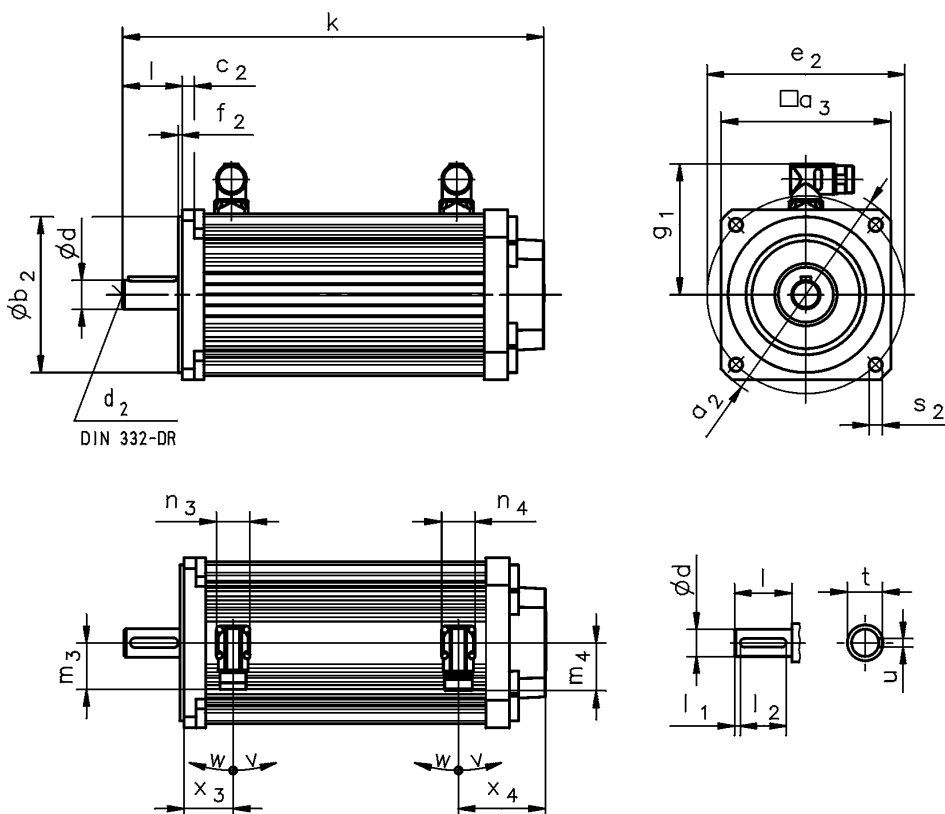




MD□KS synchronous servo motors

Dimensions [mm]

Motors without blower



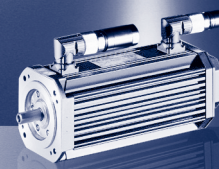
DIN 332-DR

4

| | | | MDSKS□□056-23 | | MDSKS□□056-33 | |
|---------|----------------|------|---------------|---------------|---------------|--|
| RS | k | [mm] | 241 | | 276 | |
| | x ₃ | [mm] | | | 36 | |
| | x ₄ | [mm] | | | 60 | |
| BS | k | [mm] | 267 | | 302 | |
| | x ₃ | [mm] | | | 59 | |
| | x ₄ | [mm] | | | 60 | |
| AG / IG | k | [mm] | 295 | | 330 | |
| | x ₃ | [mm] | | | 36 | |
| | x ₄ | [mm] | | | 114 | |
| BA / BI | k | [mm] | 321 | | 356 | |
| | x ₃ | [mm] | | | 59 | |
| | x ₄ | [mm] | | | 114 | |
| | | | MDSKS□□071-03 | MDSKS□□071-13 | MDSKS□□071-33 | |
| RS | k | [mm] | 259 | 294 | 329 | |
| | x ₃ | [mm] | | 39 | | |
| | x ₄ | [mm] | | 58 | | |
| BS | k | [mm] | 294 | 329 | 364 | |
| | x ₃ | [mm] | | 72 | | |
| | x ₄ | [mm] | | 58 | | |
| AG / IG | k | [mm] | 314 | 349 | 384 | |
| | x ₃ | [mm] | | 39 | | |
| | x ₄ | [mm] | | 113 | | |
| BA / BI | k | [mm] | 349 | 384 | 419 | |
| | x ₃ | [mm] | | 72 | | |
| | x ₄ | [mm] | | 113 | | |

MD□KS synchronous servo motors

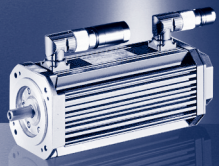
Dimensions [mm]



| | g_1 | n_3 | n_4 | m_3 | m_4 | v | w |
|----------------------|-------|-------|-------|-------|-------|-----|-----|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [°] | [°] |
| MDSKS□□056-23 | 90 | 28 | 28 | 40 | 40 | 195 | 80 |
| MDSKS□□056-33 | | | | | | | |
| MDSKS□□071-03 | | | | | | | |
| MDSKS□□071-13 | | | | | | | |
| MDSKS□□071-33 | | | | | | | |

| | d | d_2 | l | l_1 | l_2 | u | t |
|-------------------|-------|-------|------|-------|-------|------|------|
| | k_6 | | | | | | |
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MDSKS□□056 | 14 | M5 | 30 | 2.5 | 25 | 5.0 | 16 |
| MDSKS□□071 | 19 | M6 | 40 | 2.0 | 36 | 6.0 | 22 |

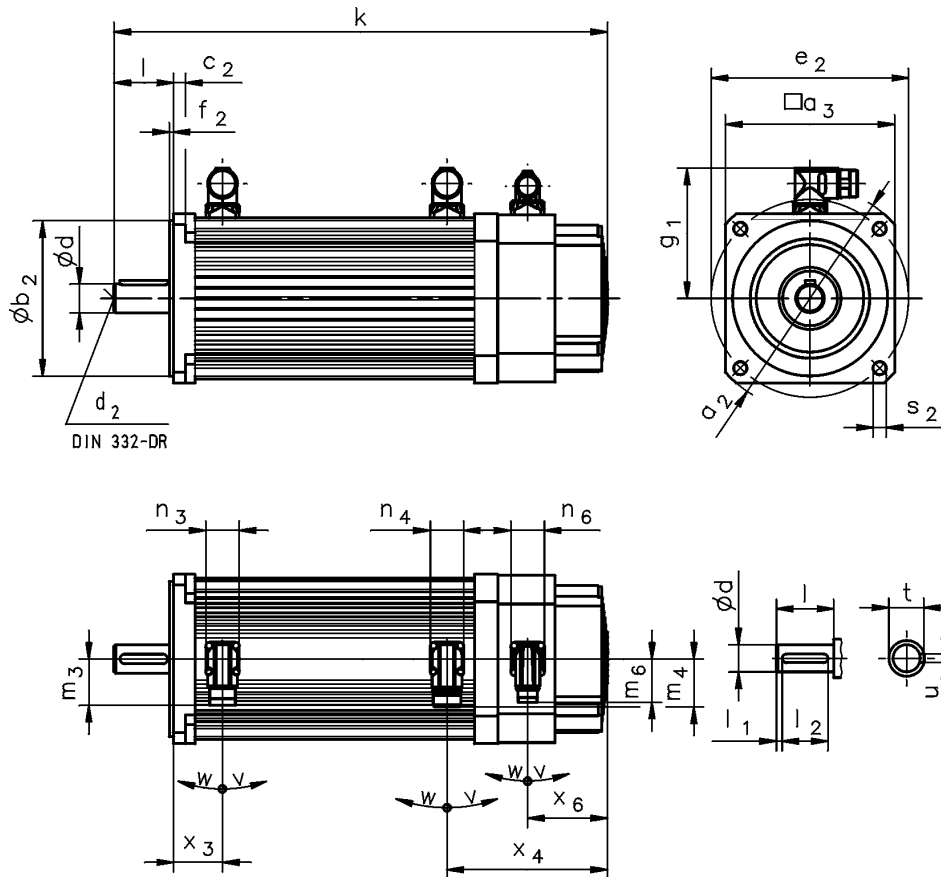
| | | a_2 | a_3 | b_2 | c_2 | e_2 | f_2 | s_2 |
|-------------------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | j_6 | | | | |
| | | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MDSKS□□056 | FF100 | 120 | 102 | 80 | 8 | 100 | 3.0 | 7 |
| | FT85 | | | 70 | | 85 | 2.5 | M6 |
| MDSKS□□071 | FF130 | 160 | 130 | 110 | 9 | 130 | 3.5 | 9.0 |
| | FT130 | | | | | | | M8 |



MDKS synchronous servo motors

Dimensions [mm]

Motors with blower

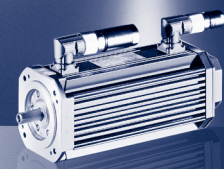


| | | | MDFKS□□071-03 | MDFKS□□071-13 | MDFKS□□071-33 |
|---------|----------------|------|---------------|---------------|---------------|
| RS | k | [mm] | 327 | 362 | 397 |
| | x ₃ | [mm] | | 39 | |
| | x ₄ | [mm] | | 126 | |
| BS | k | [mm] | 362 | 397 | 432 |
| | x ₃ | [mm] | | 72 | |
| | x ₄ | [mm] | | 126 | |
| AG / IG | k | [mm] | 382 | 417 | 452 |
| | x ₃ | [mm] | | 39 | |
| | x ₄ | [mm] | | 181 | |
| BA / BI | k | [mm] | 417 | 452 | 487 |
| | x ₃ | [mm] | | 72 | |
| | x ₄ | [mm] | | 181 | |
| | x ₆ | [mm] | | 73 | |

4

MD□KS synchronous servo motors

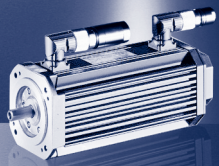
Dimensions [mm]



| | g_1 | n_3 | n_4 | n_6 | m_3 | m_4 | m_6 | v | w |
|----------------------|-------|-------|-------|-------|-------|-------|-------|-----|-----|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [°] | [°] |
| MDFKS□□071-03 | 102 | 28 | 28 | 28 | 40 | 40 | 40 | 195 | 80 |
| MDFKS□□071-13 | | | | | | | | | |
| MDFKS□□071-33 | | | | | | | | | |

| | d | d_2 | l | l_1 | l_2 | u | t |
|-------------------|-------|-------|------|-------|-------|------|------|
| | k_6 | | | | | | |
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MDFKS□□071 | 19 | M6 | 40 | 2.0 | 36 | 6.0 | 22 |

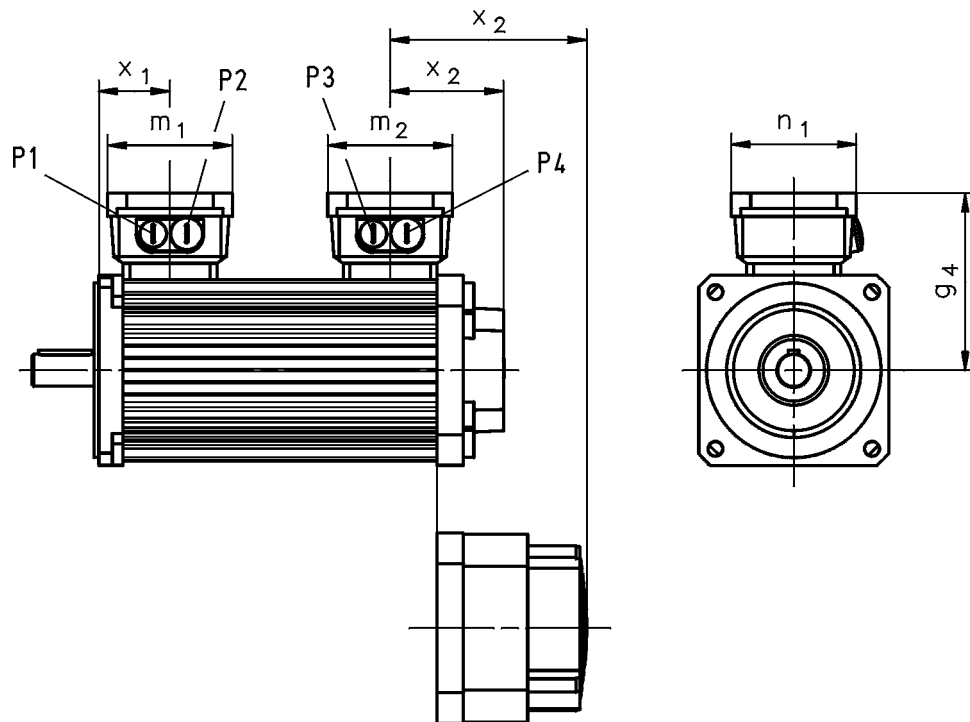
| | | a_2 | a_3 | b_2 | c_2 | e_2 | f_2 | s_2 |
|-------------------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | j_6 | | | | |
| | | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MDFKS□□071 | FF130 | 160 | 130 | 110 | 9 | 130 | 3.5 | 9.0 |
| | FT130 | | | | | | | M8 |



MD□KS synchronous servo motors

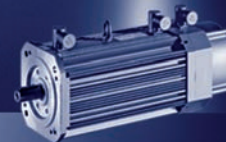
Dimensions [mm]

Motors with terminal box



| | | | MDSKS□□056-23 | MDSKS□□056-33 | MDSKS□□071-03 | MDSKS□□071-13 | MDSKS□□071-33 | |
|---------|----------------|------|---------------|---------------|---------------|---------------|---------------|--|
| RS | x ₂ | [mm] | 63 | 78 | 62 | 77 | | |
| BS | x ₂ | [mm] | 78 | | 77 | | | |
| AG / IG | x ₂ | [mm] | 117 | 132 | 116 | 131 | | |
| BA / IG | x ₂ | [mm] | 132 | | 131 | | | |
| | | | MDFKS□□071-03 | MDFKS□□071-13 | | MDFKS□□071-33 | | |
| RS | x ₂ | [mm] | 130 | 145 | | | | |
| BS | x ₂ | [mm] | 145 | | | | | |
| AG / IG | x ₂ | [mm] | 184 | 199 | | | | |
| BA / IG | x ₂ | [mm] | 199 | | | | | |

| | g ₄ | m ₁ | m ₂ | n ₁ | x ₁ | P ₁ | P ₂ | P ₃ | P ₄ |
|------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MDSKS□□056 | 113 | 93 | 93 | 93 | 54 | M16x1.5 | M20x1.5 | M16x1.5 | M20x1.5 |
| MDSKS□□071 | 125 | | | | 57 | | | | |
| MDFKS□□071 | | | | | | | | | |



Mains connection 3x 400 V

Motors without blower

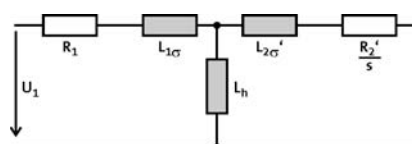
| | n_N | M_0 | M_{max} | M_N | P_N | I_0 | I_N | $U_{N, AC}$ | f_N | $J^{1)}$ | $\eta_{100\%}$ |
|----------|---------|-------|-----------|-------|-------|-------|-------|-------------|-------|----------------------|----------------|
| | [r/min] | [Nm] | [Nm] | [Nm] | [kW] | [A] | [A] | [V] | [Hz] | [kgcm ²] | [%] |
| MCA10I40 | 3950 | 2.30 | 10.0 | 2.00 | 0.80 | 2.60 | 2.40 | 390 | 140 | 2.40 | 70 |
| MCA13I41 | 4050 | 4.60 | 32.0 | 4.00 | 1.70 | 4.60 | 4.40 | 390 | 140 | 8.30 | 75 |
| MCA14L20 | 2000 | 8.00 | 60.0 | 6.70 | 1.40 | 3.90 | 3.30 | 390 | 70 | 19.2 | 84 |
| MCA14L41 | 4100 | 8.00 | 60.0 | 5.40 | 2.30 | 7.70 | 5.80 | 390 | 140 | 19.2 | 78 |
| MCA17N23 | 2300 | 12.8 | 100 | 10.8 | 2.60 | 6.00 | 5.50 | 390 | 80 | 36.0 | 86 |
| MCA17N41 | 4110 | 12.8 | 100 | 9.50 | 4.10 | 12.0 | 10.2 | 350 | 140 | 36.0 | 83 |
| MCA19S23 | 2340 | 22.5 | 180 | 16.3 | 4.00 | 9.90 | 8.20 | 390 | 80 | 72.0 | 90 |
| MCA19S42 | 4150 | 22.5 | 180 | 12.0 | 5.20 | 19.7 | 14.0 | 330 | 140 | 72.0 | 83 |
| MCA21X25 | 2490 | 39.0 | 300 | 24.6 | 6.40 | 15.9 | 13.5 | 390 | 85 | 180 | 85 |
| MCA21X42 | 4160 | 39.0 | 300 | 17.0 | 7.40 | 31.8 | 19.8 | 320 | 140 | 180 | 84 |

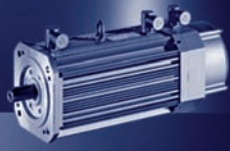
| | R_1 | $R_{UV\ 20^\circ C}$ | $R_{UV\ 150^\circ C}$ | R_2 | $L_{1\sigma}$ | L | $L_{2\sigma}$ | $n_{max}^{2)}$ | $m^{1)}$ |
|----------|--------------|----------------------|-----------------------|--------------|---------------|------|---------------|----------------|----------|
| | [Ω] | [Ω] | [Ω] | [Ω] | [mH] | [mH] | [mH] | [r/min] | [kg] |
| MCA10I40 | 4.70 | 9.40 | 12.7 | 8.20 | 9.80 | 168 | 10.0 | 8000 | 6.40 |
| MCA13I41 | 1.70 | 3.40 | 4.60 | 2.20 | 5.40 | 98.1 | 4.90 | | 10.4 |
| MCA14L20 | 3.00 | 6.00 | 8.10 | 4.90 | 10.0 | 269 | 10.0 | | 15.1 |
| MCA14L41 | 0.75 | 1.50 | 2.00 | 1.20 | 2.50 | 66.6 | 2.50 | | 22.9 |
| MCA17N23 | 1.52 | 3.04 | 4.10 | 2.20 | 6.20 | 176 | 6.80 | | |
| MCA17N41 | 0.38 | 0.76 | 1.00 | 0.50 | 1.50 | 43.5 | 1.70 | | 44.7 |
| MCA19S23 | 0.69 | 1.38 | 1.90 | 1.00 | 3.20 | 102 | 3.90 | | |
| MCA19S42 | 0.18 | 0.35 | 0.50 | 0.20 | 0.80 | 25.8 | 1.00 | | 60.0 |
| MCA21X25 | 0.36 | 0.72 | 1.00 | 0.60 | 2.30 | 78.8 | 2.80 | | |
| MCA21X42 | 0.090 | 0.18 | 0.20 | 0.10 | 0.60 | 19.5 | 0.70 | | |

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.

The data in the R_1 , $L_{1\sigma}$, L_h , R_2' and $L_{2\sigma}'$ columns is based on a single-phase equivalent circuit diagram at 20°C.





MCA asynchronous servo motors

Rated data

Mains connection 3x 400 V

Motors with blower, IP54

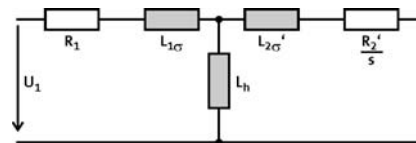
| | n_N | M_0 | M_{max} | M_N | P_N | I_0 | I_N | $U_{N, AC}$ | f_N | $J^{1)}$ | $\eta_{100\%}$ |
|-----------------|---------|-------|-----------|-------|-------|-------|-------|-------------|-------|----------------------|----------------|
| | [r/min] | [Nm] | [Nm] | [Nm] | [kW] | [A] | [A] | [V] | [Hz] | [kgcm ²] | [%] |
| MCA13I34 | 3410 | 7.00 | 32.0 | 6.30 | 2.20 | 6.30 | 6.00 | 390 | 120 | 8.30 | 72 |
| MCA14L16 | 1635 | 13.5 | 60.0 | 12.0 | 2.10 | 5.30 | 4.80 | 390 | 60 | 19.2 | 80 |
| MCA14L35 | 3455 | 13.5 | 60.0 | 10.8 | 3.90 | 10.5 | 9.10 | 390 | 120 | 19.2 | 79 |
| MCA17N17 | 1680 | 23.9 | 100 | 21.5 | 3.80 | 9.10 | 8.50 | 390 | 60 | 36.0 | 83 |
| MCA17N35 | 3480 | 23.9 | 100 | 19.0 | 6.90 | 18.1 | 15.8 | 390 | 120 | 36.0 | 81 |
| MCA19S17 | 1700 | 40.0 | 180 | 36.3 | 6.40 | 15.4 | 13.9 | 390 | 60 | 72.0 | 82 |
| MCA19S35 | 3510 | 40.0 | 180 | 36.0 | 13.2 | 30.8 | 28.7 | 390 | 120 | 72.0 | 85 |
| MCA21X17 | 1710 | 75.0 | 300 | 61.4 | 11.0 | 25.8 | 22.5 | 390 | 60 | 180 | 85 |
| MCA21X35 | 3520 | 75.0 | 300 | 55.0 | 20.3 | 49.5 | 42.5 | 390 | 120 | 180 | 88 |
| MCA22P08...5F□□ | 760 | 120 | 500 | 110 | 8.75 | 23.4 | 22.1 | 345 | 28 | 487 | 80 |
| MCA22P14...5F□□ | 1425 | 120 | 500 | 107 | 16.0 | 40.5 | 37.7 | 350 | 50 | 487 | 87 |
| MCA22P17...5F□□ | 1670 | 120 | 500 | 106 | 18.5 | 46.7 | 42.7 | 360 | 58 | 487 | 88 |
| MCA22P29...5F□□ | 2935 | 120 | 500 | 100 | 30.7 | 80.9 | 72.1 | 360 | 100 | 487 | 87 |
| MCA26T05...5F□□ | 550 | 220 | 1100 | 216 | 12.4 | 35.4 | 34.9 | 350 | 19 | 1335 | 83 |
| MCA26T10...5F□□ | 1030 | 220 | 1100 | 210 | 22.7 | 62.9 | 61.5 | 350 | 36 | 1335 | 88 |
| MCA26T12...5F□□ | 1200 | 220 | 1100 | 207 | 26.0 | 78.4 | 75.1 | 350 | 41 | 1335 | 87 |
| MCA26T22...5F□□ | 2235 | 220 | 1100 | 195 | 45.6 | 125 | 113 | 340 | 76 | 1335 | 92 |

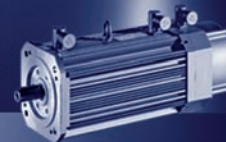
| | R_1 | $R_{UV\ 20^\circ C}$ | $R_{UV\ 150^\circ C}$ | R_2 | $L_{1\sigma}$ | L | $L_{2\sigma}$ | $n_{max}^{2)}$ | $m^{1)}$ | |
|-----------------|-------|----------------------|-----------------------|-------|---------------|------|---------------|----------------|----------|-----|
| | [Ω] | [Ω] | [Ω] | [Ω] | [mH] | [mH] | [mH] | [r/min] | [kg] | |
| MCA13I34 | 1.70 | 3.40 | 4.60 | 2.20 | 4.90 | 81.9 | 4.40 | 8000 | 12.0 | |
| MCA14L16 | 3.00 | 6.00 | 8.10 | 4.90 | 9.50 | 252 | 9.30 | | 16.9 | |
| MCA14L35 | 0.75 | 1.50 | 2.00 | 1.20 | 2.40 | 56.8 | 2.30 | | 25.5 | |
| MCA17N17 | 1.52 | 3.04 | 4.10 | 2.20 | 5.60 | 143 | 6.00 | | 48.2 | |
| MCA17N35 | 0.38 | 0.76 | 1.00 | 0.50 | 1.40 | 33.1 | 1.50 | | 63.5 | |
| MCA19S17 | 0.69 | 1.38 | 1.90 | 1.00 | 2.60 | 56.1 | 3.10 | | 6500 | 105 |
| MCA19S35 | 0.18 | 0.35 | 0.50 | 0.20 | 0.70 | 13.0 | 0.80 | | | |
| MCA21X17 | 0.36 | 0.72 | 1.00 | 0.60 | 2.10 | 68.7 | 2.60 | | | |
| MCA21X35 | 0.090 | 0.18 | 0.20 | 0.10 | 0.50 | 16.6 | 0.60 | | | |
| MCA22P08...5F□□ | 0.54 | 1.07 | 1.62 | 0.75 | 3.56 | 85.7 | 4.80 | | | |
| MCA22P14...5F□□ | | 0.36 | 0.54 | | 3.60 | 88.4 | 4.85 | | | |
| MCA22P17...5F□□ | 0.13 | 0.27 | 0.40 | 0.19 | 0.90 | 22.2 | 1.21 | | | |
| MCA22P29...5F□□ | | 0.080 | 0.12 | | 22.1 | | | | | |
| MCA26T05...5F□□ | 0.44 | 0.59 | 0.89 | 0.39 | 2.58 | 54.9 | 4.79 | | | |
| MCA26T10...5F□□ | | 0.20 | 0.30 | | 2.62 | 59.4 | 4.87 | | | |
| MCA26T12...5F□□ | 0.11 | 0.15 | 0.23 | 0.098 | 0.64 | 13.2 | 1.19 | | | |
| MCA26T22...5F□□ | | 0.050 | 0.075 | | 0.68 | 17.6 | 1.26 | | | |

1) Without brake.

2) Mechanically permissible maximum speed.

The data in the R_1 , $L_{1\sigma}$, L_h , R_2' and $L_{2\sigma}'$ columns is based on a single-phase equivalent circuit diagram at 20°C.





Mains connection 3x 400 V

Motors with blower, IP23s

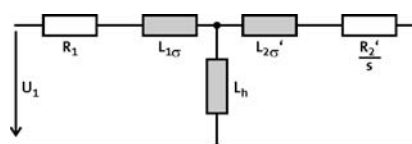
| | n_N | M_0 | M_{max} | M_N | P_N | I_0 | I_N | $U_{N, AC}$ | f_N | $J^{1)}$ | $\eta_{100\%}$ |
|-----------------|---------|-------|-----------|-------|-------|-------|-------|-------------|-------|----------------------|----------------|
| | [r/min] | [Nm] | [Nm] | [Nm] | [kW] | [A] | [A] | [V] | [Hz] | [kgcm ²] | [%] |
| MCA20X14...2F□□ | 1420 | 68.0 | 250 | 61.0 | 9.07 | 26.0 | 23.0 | 350 | 50 | 171 | 82 |
| MCA20X29...2F□□ | 2930 | 68.0 | 250 | 53.5 | 16.4 | 52.0 | 42.4 | 350 | 100 | 171 | 87 |
| MCA22P08...2F□□ | 760 | 135 | 500 | 120 | 9.55 | 26.0 | 23.5 | 355 | 28 | 487 | 80 |
| MCA22P14...2F□□ | 1425 | 135 | 500 | 115 | 17.2 | 45.1 | 40.0 | 360 | 50 | 487 | 86 |
| MCA22P17...2F□□ | 1670 | 135 | 500 | 112 | 19.6 | 52.1 | 44.5 | 360 | 58 | 487 | 88 |
| MCA22P29...2F□□ | 2935 | 135 | 500 | 110 | 33.8 | 90.2 | 77.8 | 360 | 100 | 487 | 89 |
| MCA26T05...2F□□ | 550 | 290 | 1100 | 280 | 16.1 | 44.0 | 42.4 | 350 | 20 | 1335 | 81 |
| MCA26T10...2F□□ | 1030 | 290 | 1100 | 260 | 28.0 | 78.0 | 69.6 | 350 | 36 | 1335 | 87 |
| MCA26T12...2F□□ | 1200 | 290 | 1100 | 255 | 32.0 | 101 | 83.3 | 350 | 41 | 1335 | 87 |
| MCA26T22...2F□□ | 2235 | 290 | 1100 | 230 | 53.8 | 160 | 127 | 340 | 76 | 1335 | 92 |

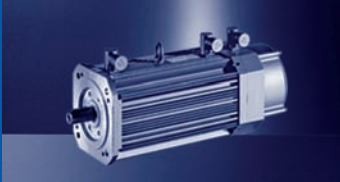
| | R_1 | $R_{UV\ 20^\circ C}$ | $R_{UV\ 150^\circ C}$ | R_2 | $L_{1\sigma}$ | L | $L_{2\sigma}$ | $n_{max}^{2)}$ | $m^{1)}$ |
|-----------------|-------|----------------------|-----------------------|-------|---------------|------|---------------|----------------|----------|
| | [Ω] | [Ω] | [Ω] | [Ω] | [mH] | [mH] | [mH] | [r/min] | [kg] |
| MCA20X14...2F□□ | 0.37 | 0.73 | 1.10 | 0.57 | 2.01 | 54.8 | 2.14 | 6500 | 64.0 |
| MCA20X29...2F□□ | 0.091 | 0.18 | 0.28 | 0.14 | 0.50 | 13.6 | 0.54 | | |
| MCA22P08...2F□□ | 0.54 | 1.07 | 1.62 | 0.75 | 4.74 | 81.6 | 3.50 | | |
| MCA22P14...2F□□ | | 0.36 | 0.54 | | 3.55 | 85.1 | 4.79 | | |
| MCA22P17...2F□□ | 0.13 | 0.27 | 0.40 | 0.19 | 0.90 | 22.2 | 1.22 | | 105 |
| MCA22P29...2F□□ | | 0.080 | 0.12 | | | | 1.21 | | |
| MCA26T05...2F□□ | 0.44 | 0.59 | 0.89 | 0.39 | 2.60 | 57.4 | 4.83 | | 194 |
| MCA26T10...2F□□ | | 0.20 | 0.30 | | 2.63 | 60.2 | 4.88 | | |
| MCA26T12...2F□□ | 0.11 | 0.15 | 0.23 | 0.098 | 0.64 | 13.3 | 1.19 | | |
| MCA26T22...2F□□ | | 0.050 | 0.077 | | 0.68 | 17.7 | 1.27 | | |

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.

The data in the R_1 , $L_{1\sigma}$, L_h , R_2' and $L_{2\sigma}'$ columns is based on a single-phase equivalent circuit diagram at 20°C.

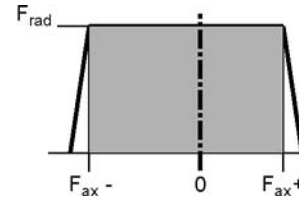
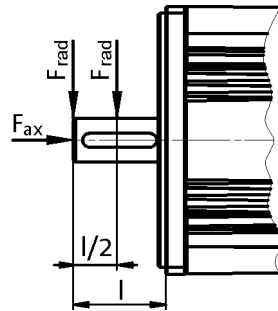




MCA asynchronous servo motors

Rated data

Permissible radial and axial forces



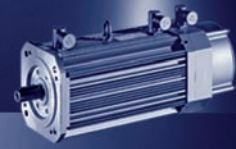
Application of force at l/2

| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|-------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MCA10 | 630 | -130 | 320 | 500 | -60 | 250 | 400 | -30 | 210 | 330 | -10 | 190 | 230 | 0 | 200 |
| MCA13 | 850 | -110 | 570 | 700 | -10 | 450 | 470 | 0 | 450 | | 0 | 450 | | | |
| MCA14 | 1000 | -140 | 500 | 780 | -60 | 420 | 550 | -30 | 380 | 400 | -10 | 360 | 250 | 0 | 350 |
| MCA17 | 1380 | -180 | 790 | 1040 | -70 | 680 | 660 | -40 | 650 | 440 | -20 | 630 | 280 | | 610 |
| MCA19 | 1880 | -50 | 1530 | 1080 | -30 | 1510 | 500 | -100 | 1490 | 160 | 0 | 1470 | | | |
| MCA20 | 3400 | -1330 | 690 | 2500 | -1020 | 380 | 1950 | -780 | 140 | 1700 | -690 | 40 | | | |
| MCA21 | 3200 | -260 | 1740 | 2360 | -70 | 1550 | 1470 | -20 | 1504 | 1030 | 0 | 1480 | | | |
| MCA22 | 3600 | -2370 | 1700 | 2800 | -1740 | 1090 | 2200 | -1280 | 640 | 1900 | -1080 | 440 | 1600 | -880 | 240 |
| MCA26 | 6950 | -2500 | 1580 | 5400 | -1800 | 880 | 4300 | -1300 | 380 | 3700 | -1090 | 160 | | | |

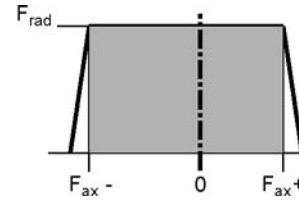
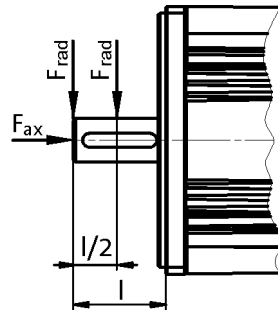
Application of force at l

| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|-------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MCA10 | 590 | -130 | 320 | 470 | -60 | 250 | 370 | -30 | 210 | 310 | -10 | 190 | 220 | 0 | 200 |
| MCA13 | 780 | -110 | 570 | 640 | -10 | 450 | 430 | 0 | 450 | 300 | 0 | 450 | | | |
| MCA14 | 930 | -140 | 500 | 710 | -60 | 420 | 490 | -30 | 380 | 370 | -10 | 360 | 230 | 0 | 350 |
| MCA17 | 1270 | -180 | 790 | 960 | -70 | 680 | 610 | -40 | 650 | 400 | -20 | 630 | 260 | | 610 |
| MCA19 | 1740 | -50 | 1530 | 1000 | -30 | 1510 | 420 | -100 | 1490 | 140 | 0 | 1470 | | | |
| MCA20 | 3150 | -1170 | 530 | 2300 | -920 | 280 | 1800 | -710 | 70 | 1400 | -650 | 0 | | | |
| MCA21 | 2940 | -260 | 1740 | 2160 | -70 | 1550 | 1350 | -20 | 1504 | 950 | 0 | 1480 | | | |
| MCA22 | 3500 | -2240 | 1600 | 2600 | -1640 | 1100 | 2050 | -1200 | 560 | 1800 | -1020 | 380 | 1450 | -850 | 200 |
| MCA26 | 6400 | -2080 | 1150 | 5000 | -1600 | 680 | 4000 | -1160 | 230 | 3400 | -1090 | 50 | | | |

- The values for the bearing service life L_{10} relate to an average speed of 4000 r/min. For MCA20/22/26 the speed is 3000 r/min. Depending on the ambient temperatures, the service life of the bearings is also reduced by the grease lifetime.



Permissible radial and axial forces



Reinforced bearings

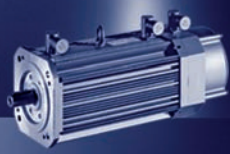
Application of force at l/2

| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|--------------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MCA20 | 7100 | -970 | 330 | 5100 | -800 | 160 | 3900 | -640 | 0 | | | | | | |
| MCA22 | 8500 | -1850 | 1200 | 7000 | -1400 | 760 | 5600 | -1030 | 390 | 4350 | -930 | 290 | 3200 | -800 | 160 |
| MCA26 | 10500 | -2180 | 1250 | 8370 | -1530 | 600 | 6670 | -1130 | 200 | 5840 | -960 | 30 | | | |

Application of force at l

| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|--------------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MCA20 | 6350 | -720 | 80 | 4100 | -680 | 40 | 2800 | | 0 | | | | | | |
| MCA22 | 7000 | -1750 | 1100 | 5500 | -1300 | 660 | 4700 | -920 | 280 | 3900 | -820 | 180 | 3000 | -700 | 60 |
| MCA26 | 9600 | -2200 | 1280 | 7700 | -1280 | 360 | 6000 | -960 | 30 | | | | | | |

- ▶ The values for the bearing service life L_{10} refer to an average speed of 3000 r/min. Depending on the ambient temperatures, the service life of the bearings is also reduced by the grease lifetime.



MCA asynchronous servo motors

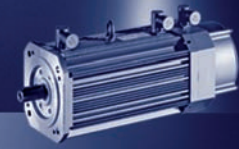
9400 Servo Drives selection tables

Mains connection 3 x 400 V and switching frequency 4 kHz

Motors without blower

| | | | | | E94A□□ | E0024 | E0034 | E0044 | E0074 | E0094 | E0134 | E0174 | E0244 | E0324 | |
|-------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|------|
| | | | | | I_N | 1.9 | 3.1 | 5.0 | 8.8 | 11.7 | 16.3 | 20.6 | 29.4 | 38.4 | |
| | | | | | $I_{0,max}$ | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 6.0 | 10.0 | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | |
| 10I40 | 2.0 | 3950 | 2.4 | 0.80 | M_0 | 1.1 | 2.3 | | | | | | | | |
| | | | | | M_N | 1.0 | 2.0 | | | | | | | | |
| | | | | | $M_{0,max}$ | 6.9 | 10.0 | | | | | | | | |
| | | | | | M_{max} | 6.9 | 10.0 | | | | | | | | |
| | | | | | η_{eto} | - | - | | | | | | | | |
| 13I41 | 4.0 | 4050 | 4.4 | 1.70 | M_0 | | | 4.6 | 4.6 | | | | | | |
| | | | | | M_N | | | 4.0 | 4.0 | | | | | | |
| | | | | | $M_{0,max}$ | | | 18.9 | 20.8 | | | | | | |
| | | | | | M_{max} | | | 18.9 | 20.8 | | | | | | |
| | | | | | η_{eto} | | | - | - | | | | | | |
| 14L20 | 6.7 | 2000 | 3.3 | 1.40 | M_0 | | 5.1 | 8.0 | | | | | | | |
| | | | | | M_N | | 4.4 | 6.7 | | | | | | | |
| | | | | | $M_{0,max}$ | | 25.0 | 42.8 | | | | | | | |
| | | | | | M_{max} | | 25.0 | 42.8 | | | | | | | |
| | | | | | η_{eto} | | - | - | | | | | | | |
| 14L41 | 5.4 | 4100 | 5.8 | 2.30 | M_0 | | | 3.5 | 8.0 | 8.0 | | | | | |
| | | | | | M_N | | | 3.5 | 5.4 | 5.4 | | | | | |
| | | | | | $M_{0,max}$ | | | 21.5 | 27.0 | 31.3 | | | | | |
| | | | | | M_{max} | | | 21.5 | 27.0 | 31.3 | | | | | |
| | | | | | η_{eto} | | | - | - | - | | | | | |
| 17N23 | 10.8 | 2300 | 5.5 | 2.60 | M_0 | | | 9.5 | 12.8 | | | | | | |
| | | | | | M_N | | | 9.0 | 10.8 | | | | | | |
| | | | | | $M_{0,max}$ | | | 38.0 | 50.0 | | | | | | |
| | | | | | M_{max} | | | 38.0 | 50.0 | | | | | | |
| | | | | | η_{eto} | | | - | - | | | | | | |
| 17N41 | 9.5 | 4110 | 10.2 | 4.10 | M_0 | | | | 7.1 | 11.5 | 12.8 | 12.8 | | | |
| | | | | | M_N | | | | 6.7 | 9.5 | 9.5 | 9.5 | | | |
| | | | | | $M_{0,max}$ | | | | 24.0 | 33.3 | 45.8 | 49.9 | | | |
| | | | | | M_{max} | | | | 24.0 | 33.3 | 45.8 | 49.9 | | | |
| | | | | | η_{eto} | | | | - | - | - | - | | | |
| 19S23 | 16.3 | 2340 | 8.2 | 4.00 | M_0 | | | | 18.4 | 22.5 | 22.5 | | | | |
| | | | | | M_N | | | | 15.6 | 16.3 | 16.3 | | | | |
| | | | | | $M_{0,max}$ | | | | 55.0 | 73.7 | 86.0 | | | | |
| | | | | | M_{max} | | | | 55.0 | 73.7 | 86.0 | | | | |
| | | | | | η_{eto} | | | | - | - | - | | | | |
| 19S42 | 12.0 | 4150 | 14.0 | 5.20 | M_0 | | | | | | 15.0 | 22.5 | 22.5 | | |
| | | | | | M_N | | | | | | | 12.0 | 12.0 | 12.0 | |
| | | | | | $M_{0,max}$ | | | | | | | 48.8 | 62.0 | 70.0 | |
| | | | | | M_{max} | | | | | | | 48.8 | 62.0 | 70.0 | |
| | | | | | η_{eto} | | | | | | | - | - | - | |
| 21X25 | 24.6 | 2490 | 13.5 | 6.40 | M_0 | | | | | 21.4 | 39.0 | 39.0 | 39.0 | | |
| | | | | | M_N | | | | | | 19.6 | 24.6 | 24.6 | 24.6 | |
| | | | | | $M_{0,max}$ | | | | | | 71.7 | 96.0 | 126.0 | 136.0 | |
| | | | | | M_{max} | | | | | | 71.7 | 96.0 | 126.0 | 136.0 | |
| | | | | | η_{eto} | | | | | | - | - | - | - | |
| 21X42 | 17.0 | 4160 | 19.8 | 7.40 | M_0 | | | | | | | | 31.3 | 39.0 | |
| | | | | | M_N | | | | | | | | | 17.0 | 17.0 |
| | | | | | $M_{0,max}$ | | | | | | | | | 71.7 | 91.0 |
| | | | | | M_{max} | | | | | | | | | 71.7 | 91.0 |
| | | | | | η_{eto} | | | | | | | | | - | - |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

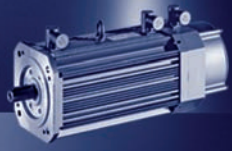


Mains connection 3 x 400 V and switching frequency 4 kHz

Motors with blower, IP54

| | | | | | E94A□□ | E0044 | E0074 | E0094 | E0134 | E0174 | E0244 | E0324 | E0474 | E0594 | E0864 |
|-------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 5.0 | 8.8 | 11.7 | 16.3 | 20.6 | 29.4 | 38.4 | 47.0 | 59.0 | 86.0 |
| | | | | | $I_{0,max}$ | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 | 172.0 |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 16.0 | 21.0 | 28.0 | 39.0 | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 | 172.0 |
| 13I34 | 6.3 | 3410 | 6.0 | 2.20 | M_0 | 4.6 | 7.0 | 7.0 | | | | | | | |
| | | | | | M_N | 4.4 | 6.3 | 6.3 | | | | | | | |
| | | | | | $M_{0,max}$ | 20.8 | 26.0 | 29.2 | | | | | | | |
| | | | | | M_{max} | 20.8 | 26.0 | 29.2 | | | | | | | |
| | | | | | η_{eto} | - | - | - | | | | | | | |
| 14L16 | 12.0 | 1635 | 4.8 | 2.10 | M_0 | 12.0 | 13.5 | | | | | | | | |
| | | | | | M_N | 12.0 | 12.0 | | | | | | | | |
| | | | | | $M_{0,max}$ | 45.4 | 52.6 | | | | | | | | |
| | | | | | M_{max} | 45.4 | 52.6 | | | | | | | | |
| | | | | | η_{eto} | - | - | | | | | | | | |
| 14L35 | 10.8 | 3455 | 9.1 | 3.90 | M_0 | | 10.1 | 13.5 | 13.5 | | | | | | |
| | | | | | M_N | | 9.7 | 10.8 | 10.8 | | | | | | |
| | | | | | $M_{0,max}$ | | 32.4 | 46.0 | 60.0 | | | | | | |
| | | | | | M_{max} | | 32.4 | 46.0 | 60.0 | | | | | | |
| | | | | | η_{eto} | | - | - | - | | | | | | |
| 17N17 | 21.5 | 1680 | 8.5 | 3.80 | M_0 | | 21.6 | 23.9 | 23.9 | | | | | | |
| | | | | | M_N | | 21.5 | 21.5 | 21.5 | | | | | | |
| | | | | | $M_{0,max}$ | | 59.4 | 81.4 | 84.5 | | | | | | |
| | | | | | M_{max} | | 59.4 | 81.4 | 84.5 | | | | | | |
| | | | | | η_{eto} | | - | - | - | | | | | | |
| 17N35 | 19.0 | 3480 | 15.8 | 6.90 | M_0 | | | | 19.4 | 23.9 | 23.9 | | | | |
| | | | | | M_N | | | | 19.0 | 19.0 | 19.0 | | | | |
| | | | | | $M_{0,max}$ | | | | 59.2 | 75.0 | 90.0 | | | | |
| | | | | | M_{max} | | | | 59.2 | 75.0 | 90.0 | | | | |
| | | | | | η_{eto} | | | | - | - | - | | | | |
| 19S17 | 36.3 | 1700 | 13.9 | 6.40 | M_0 | | | | 40.0 | 40.0 | 40.0 | | | | |
| | | | | | M_N | | | | 36.3 | 36.3 | 36.3 | | | | |
| | | | | | $M_{0,max}$ | | | | 105.0 | 133.0 | 148.0 | | | | |
| | | | | | M_{max} | | | | 105.0 | 133.0 | 148.0 | | | | |
| | | | | | η_{eto} | | | | - | - | - | | | | |
| 19S35 | 36.0 | 3510 | 28.7 | 13.20 | M_0 | | | | | | 36.9 | 40.0 | 40.0 | 40.0 | |
| | | | | | M_N | | | | | | 36.0 | 36.0 | 36.0 | 36.0 | |
| | | | | | $M_{0,max}$ | | | | | | 82.0 | 112.0 | 132.0 | 160.0 | |
| | | | | | M_{max} | | | | | | 82.0 | 112.0 | 132.0 | 160.0 | |
| | | | | | η_{eto} | | | | | | - | - | - | - | |
| 21X17 | 61.4 | 1710 | 22.5 | 11.00 | M_0 | | | | | 54.4 | 75.0 | 75.0 | 75.0 | | |
| | | | | | M_N | | | | | 50.4 | 61.4 | 61.4 | 61.4 | | |
| | | | | | $M_{0,max}$ | | | | | 134.0 | 158.0 | 215.0 | 246.0 | | |
| | | | | | M_{max} | | | | | 134.0 | 158.0 | 215.0 | 246.0 | | |
| | | | | | η_{eto} | | | | | - | - | - | - | | |
| 21X35 | 55.0 | 3520 | 42.5 | 20.30 | M_0 | | | | | | | | 63.9 | 75.0 | 75.0 |
| | | | | | M_N | | | | | | | | 55.0 | 55.0 | 55.0 |
| | | | | | $M_{0,max}$ | | | | | | | | 134.0 | 167.0 | 232.0 |
| | | | | | M_{max} | | | | | | | | 134.0 | 167.0 | 232.0 |
| | | | | | η_{eto} | | | | | | | | - | - | - |

► I... [A], M... [Nm], n... [r/min], P... [kW]



MCA asynchronous servo motors

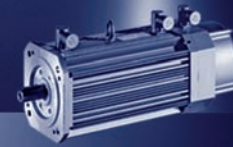
9400 Servo Drives selection tables

Mains connection 3 x 400 V and switching frequency 8 kHz

Motors with blower, IP54

| | | | | | E94A□□ | E0174 | E0244 | E0324 | E0474 | E0594 | E0864 | E1044 | E1454 | E1724 | E2024 | E2454 |
|---------------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|--------|-------|--------|-------|-------|-------|
| | | | | | I_N | 16.5 | 23.5 | 32.0 | 41.0 | 41.0 | 73.0 | 78.0 | 102.0 | 120.0 | 131.0 | 160.0 |
| | | | | | $I_{0,max}$ | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 | 172.0 | 208.0 | 261.0 | 310.0 | 364.0 | 441.0 |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 | 172.0 | 208.0 | 261.0 | 310.0 | 364.0 | 441.0 |
| 22P08-...5F□□ | 110.0 | 760 | 22.1 | 8.80 | M_0 | 64.0 | 110.0 | 120.0 | | | | | | | | |
| | | | | | M_N | 64.0 | 110.0 | 110.0 | | | | | | | | |
| | | | | | $M_{0,max}$ | 261.0 | 313.0 | 402.0 | | | | | | | | |
| | | | | | M_{max} | 261.0 | 313.0 | 402.0 | | | | | | | | |
| | | | | | η_{eto} | - | - | - | | | | | | | | |
| 22P14-...5F□□ | 107.0 | 1425 | 37.7 | 16.00 | M_0 | | | 82.0 | 120.0 | 120.0 | | | | | | |
| | | | | | M_N | | | 82.0 | 107.0 | 107.0 | | | | | | |
| | | | | | $M_{0,max}$ | | | 242.0 | 300.0 | 372.0 | | | | | | |
| | | | | | M_{max} | | | 242.0 | 300.0 | 372.0 | | | | | | |
| | | | | | η_{eto} | | | - | - | - | | | | | | |
| 22P17-...5F□□ | 105.0 | 1670 | 42.7 | 18.50 | M_0 | | | | | 99.0 | 120.0 | | | | | |
| | | | | | M_N | | | | | 99.0 | 106.0 | | | | | |
| | | | | | $M_{0,max}$ | | | | | 325.0 | 463.0 | | | | | |
| | | | | | M_{max} | | | | | 325.0 | 463.0 | | | | | |
| | | | | | η_{eto} | | | | | - | - | | | | | |
| 22P29-...5F□□ | 100.0 | 2935 | 72.1 | 30.70 | M_0 | | | | | | | 110.0 | 120.0 | 120.0 | | |
| | | | | | M_N | | | | | | 100.0 | 100.0 | 100.0 | | | |
| | | | | | $M_{0,max}$ | | | | | | 335.0 | 416.0 | 465.0 | | | |
| | | | | | M_{max} | | | | | | 335.0 | 416.0 | 465.0 | | | |
| | | | | | η_{eto} | | | | | | | - | - | - | | |
| 26T05-...5F□□ | 216.0 | 550 | 34.9 | 12.40 | M_0 | | | 191.0 | 220.0 | 220.0 | 220.0 | | | | | |
| | | | | | M_N | | | 191.0 | 216.0 | 216.0 | 216.0 | | | | | |
| | | | | | $M_{0,max}$ | | | 531.0 | 665.0 | 826.0 | 1010.0 | | | | | |
| | | | | | M_{max} | | | 531.0 | 665.0 | 826.0 | 1010.0 | | | | | |
| | | | | | η_{eto} | | | - | - | - | - | | | | | |
| 26T10-...5F□□ | 210.0 | 1030 | 61.5 | 22.70 | M_0 | | | | | 77.0 | 220.0 | 220.0 | 220.0 | | | |
| | | | | | M_N | | | | | 77.0 | 210.0 | 210.0 | 210.0 | | | |
| | | | | | $M_{0,max}$ | | | | | 472.0 | 713.0 | 855.0 | 1044.0 | | | |
| | | | | | M_{max} | | | | | 472.0 | 713.0 | 855.0 | 1044.0 | | | |
| | | | | | η_{eto} | | | | | - | - | - | - | | | |
| 26T12-...5F□□ | 207.0 | 1200 | 75.1 | 26.00 | M_0 | | | | | | 204.0 | 219.0 | 220.0 | 220.0 | | |
| | | | | | M_N | | | | | 204.0 | 207.0 | 207.0 | 207.0 | | | |
| | | | | | $M_{0,max}$ | | | | | 502.0 | 609.0 | 739.0 | 819.0 | | | |
| | | | | | M_{max} | | | | | 502.0 | 609.0 | 739.0 | 819.0 | | | |
| | | | | | η_{eto} | | | | | - | - | - | - | | | |
| 26T22-...5F□□ | 195.0 | 2235 | 112.9 | 45.60 | M_0 | | | | | | | | 154.0 | 211.0 | 220.0 | 220.0 |
| | | | | | M_N | | | | | | | | 154.0 | 195.0 | 195.0 | 195.0 |
| | | | | | $M_{0,max}$ | | | | | | | | 523.0 | 611.0 | 711.0 | 843.0 |
| | | | | | M_{max} | | | | | | | | 523.0 | 611.0 | 711.0 | 843.0 |
| | | | | | η_{eto} | | | | | | | | - | - | - | - |

- ▶ $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]
- ▶ If the motors are operated at a lower switching frequency, please contact your Lenze sales office!
- ▶ When operating at 4 kHz, the motor generates just 95 % of its rated torque with increased noise emissions.

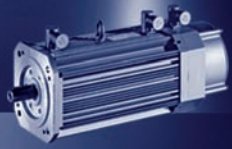


Mains connection 3 x 400 V and switching frequency 8 kHz

Motors with blower, IP23s

| | | | | | E94A□□ | E0174 | E0244 | E0324 | E0474 | E0594 | E0864 | E1044 | E1454 | E1724 | E2024 | E2454 | E2924 | |
|---------------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|--------|-------|--------|-------|-------|-------|-------|--------|
| | | | | | I_N | 16.5 | 23.5 | 32.0 | 41.0 | 41.0 | 73.0 | 78.0 | 102.0 | 120.0 | 131.0 | 160.0 | 191.0 | |
| | | | | | $I_{0,max}$ | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 | 172.0 | 208.0 | 261.0 | 310.0 | 364.0 | 441.0 | 526.0 | |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 | 172.0 | 208.0 | 261.0 | 310.0 | 364.0 | 441.0 | 526.0 | |
| 20X14-...2F□□ | 61.0 | 1420 | 23.0 | 9.10 | M_0 | 32.5 | 66.0 | | | | | | | | | | | |
| | | | | | M_N | 32.5 | 61.0 | | | | | | | | | | | |
| | | | | | $M_{0,max}$ | 154.2 | 190.0 | | | | | | | | | | | |
| | | | | | M_{max} | 154.2 | 190.0 | | | | | | | | | | | |
| | | | | | η_{eto} | - | - | | | | | | | | | | | |
| 20X29-...2F□□ | 53.5 | 2930 | 42.4 | 16.40 | M_0 | | | 28.0 | 51.6 | 51.6 | | | | | | | | |
| | | | | | M_N | | | 28.0 | 51.6 | 51.6 | | | | | | | | |
| | | | | | $M_{0,max}$ | | | 116.0 | 148.2 | 192.8 | | | | | | | | |
| | | | | | M_{max} | | | 116.0 | 148.2 | 192.8 | | | | | | | | |
| | | | | | η_{eto} | | | - | - | - | | | | | | | | |
| 22P08-...2F□□ | 120.0 | 760 | 23.5 | 9.60 | M_0 | | 120.0 | 135.0 | | | | | | | | | | |
| | | | | | M_N | | 120.0 | 120.0 | | | | | | | | | | |
| | | | | | $M_{0,max}$ | | 313.0 | 402.0 | | | | | | | | | | |
| | | | | | M_{max} | | 313.0 | 402.0 | | | | | | | | | | |
| | | | | | η_{eto} | | - | - | | | | | | | | | | |
| 22P14-...2F□□ | 115.0 | 1425 | 40.0 | 17.20 | M_0 | | | | 118.0 | 118.0 | | | | | | | | |
| | | | | | M_N | | | | 115.0 | 115.0 | | | | | | | | |
| | | | | | $M_{0,max}$ | | | | 300.0 | 372.0 | | | | | | | | |
| | | | | | M_{max} | | | | 300.0 | 372.0 | | | | | | | | |
| | | | | | η_{eto} | | | | - | - | | | | | | | | |
| 22P17-...2F□□ | 112.0 | 1670 | 44.5 | 19.60 | M_0 | | | | | 99.0 | 135.0 | | | | | | | |
| | | | | | M_N | | | | 99.0 | 112.0 | | | | | | | | |
| | | | | | $M_{0,max}$ | | | | 325.0 | 463.0 | | | | | | | | |
| | | | | | M_{max} | | | | 325.0 | 463.0 | | | | | | | | |
| | | | | | η_{eto} | | | | - | - | | | | | | | | |
| 22P29-...2F□□ | 110.0 | 2935 | 77.8 | 33.80 | M_0 | | | | | | | 110.0 | 135.0 | 135.0 | | | | |
| | | | | | M_N | | | | | | 110.0 | 110.0 | 110.0 | | | | | |
| | | | | | $M_{0,max}$ | | | | | | 335.0 | 416.0 | 486.0 | | | | | |
| | | | | | M_{max} | | | | | | 335.0 | 416.0 | 486.0 | | | | | |
| | | | | | η_{eto} | | | | | | - | - | - | | | | | |
| 26T05-...2F□□ | 280.0 | 550 | 42.4 | 16.10 | M_0 | | | | 268.0 | 268.0 | 290.0 | | | | | | | |
| | | | | | M_N | | | | 268.0 | 268.0 | 280.0 | | | | | | | |
| | | | | | $M_{0,max}$ | | | | 665.0 | 826.0 | 1100.0 | | | | | | | |
| | | | | | M_{max} | | | | 665.0 | 826.0 | 1100.0 | | | | | | | |
| | | | | | η_{eto} | | | | - | - | - | | | | | | | |
| 26T10-...2F□□ | 260.0 | 1030 | 69.6 | 28.00 | M_0 | | | | | | 270.0 | 290.0 | 290.0 | | | | | |
| | | | | | M_N | | | | | | 260.0 | 260.0 | 260.0 | | | | | |
| | | | | | $M_{0,max}$ | | | | | | 713.0 | 855.0 | 1044.0 | | | | | |
| | | | | | M_{max} | | | | | | 713.0 | 855.0 | 1044.0 | | | | | |
| | | | | | η_{eto} | | | | | | - | - | - | | | | | |
| 26T12-...2F□□ | 255.0 | 1200 | 83.3 | 32.00 | M_0 | | | | | | 204.0 | 219.0 | 290.0 | 290.0 | | | | |
| | | | | | M_N | | | | | | 204.0 | 219.0 | 255.0 | 255.0 | | | | |
| | | | | | $M_{0,max}$ | | | | | | 502.0 | 609.0 | 739.0 | 840.0 | 896.0 | | | |
| | | | | | M_{max} | | | | | | 502.0 | 609.0 | 739.0 | 840.0 | 896.0 | | | |
| | | | | | η_{eto} | | | | | | - | - | - | - | - | | | |
| 26T22-...2F□□ | 230.0 | 2235 | 126.7 | 53.80 | M_0 | | | | | | | | | 211.0 | 242.0 | 290.0 | 290.0 | |
| | | | | | M_N | | | | | | | | | | 211.0 | 230.0 | 230.0 | 230.0 |
| | | | | | $M_{0,max}$ | | | | | | | | | | 611.0 | 711.0 | 843.0 | 1001.0 |
| | | | | | M_{max} | | | | | | | | | | 611.0 | 711.0 | 843.0 | 1001.0 |
| | | | | | η_{eto} | | | | | | | | | | - | - | - | - |

- ▶ $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]
- ▶ If the motors are operated at a lower switching frequency, please contact your Lenze sales office!
- ▶ When operating at 4 kHz, the motor generates just 95 % of its rated torque with increased noise emissions.



MCA asynchronou servo motors

Selection tables for Inverter Drives 8400 TopLine

Mains connection 3 x 400 V and switching frequency 8 kHz

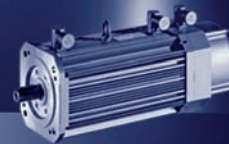
Motors without blower

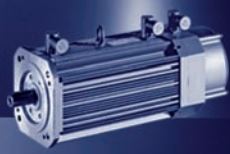
| | | | | | E84AVTC | □5514 | □7514 | □1124 | □1524 | □2224 | □3024 | □4024 | □5524 | □7524 | □1134 | □1534 | □1834 | | |
|-------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|--|--|
| | | | | | I_N | 1.8 | 2.4 | 3.2 | 3.9 | 5.9 | 7.3 | 9.5 | 13.0 | 16.5 | 23.5 | 32.0 | 39.0 | | |
| | | | | | $I_{0,max}$ | 2.7 | 3.6 | 4.8 | 5.9 | 8.4 | 11.0 | 14.3 | 19.5 | 26.4 | 32.9 | 43.2 | 60.0 | | |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 3.6 | 4.8 | 6.4 | 7.8 | 11.8 | 14.6 | 19.0 | 26.0 | 33.0 | 47.0 | 64.0 | 78.0 | | |
| 10I40 | 2.0 | 3950 | 2.4 | 0.80 | M_0 | - | 2.3 | 2.3 | 2.3 | 2.3 | | | | | | | | | |
| | | | | | M_N | - | 1.9 | 1.9 | 1.9 | 1.9 | | | | | | | | | |
| | | | | | $M_{0,max}$ | 4.2 | 5.8 | 8.0 | 9.8 | 11.4 | | | | | | | | | |
| | | | | | M_{max} | 4.2 | 5.8 | 8.0 | 9.8 | 11.4 | | | | | | | | | |
| | | | | | η_{eto} | - | - | - | - | - | | | | | | | | | |
| 13I41 | 4.0 | 4050 | 4.4 | 1.70 | M_0 | | | - | - | 4.6 | 4.6 | 4.6 | | | | | | | |
| | | | | | M_N | | | - | - | 4.0 | 4.0 | 4.0 | | | | | | | |
| | | | | | $M_{0,max}$ | | | 7.6 | 9.6 | 14.3 | 18.9 | 22.9 | | | | | | | |
| | | | | | M_{max} | | | 7.6 | 9.6 | 14.3 | 18.9 | 22.9 | | | | | | | |
| | | | | | η_{eto} | | | - | - | - | - | - | | | | | | | |
| 14L20 | 6.7 | 2000 | 3.3 | 1.40 | M_0 | | - | - | 8.0 | 8.0 | 8.0 | | | | | | | | |
| | | | | | M_N | | - | - | 6.7 | 6.7 | 6.7 | | | | | | | | |
| | | | | | $M_{0,max}$ | | 11.6 | 16.2 | 20.1 | 29.4 | 34.7 | | | | | | | | |
| | | | | | M_{max} | | 11.6 | 16.2 | 20.1 | 29.4 | 34.7 | | | | | | | | |
| | | | | | η_{eto} | | - | - | - | - | - | | | | | | | | |
| 14L41 | 5.4 | 4100 | 5.8 | 2.30 | M_0 | | | | | - | 8.0 | 8.0 | 8.0 | | | | | | |
| | | | | | M_N | | | | | - | 5.4 | 5.4 | 5.4 | | | | | | |
| | | | | | $M_{0,max}$ | | | | | 14.1 | 19.0 | 25.1 | 31.0 | | | | | | |
| | | | | | M_{max} | | | | | 14.1 | 19.0 | 25.1 | 31.0 | | | | | | |
| | | | | | η_{eto} | | | | | - | - | - | - | | | | | | |
| 17N23 | 10.8 | 2300 | 5.5 | 2.60 | M_0 | | | | - | 12.8 | 12.8 | 12.8 | 12.8 | | | | | | |
| | | | | | M_N | | | | - | 10.8 | 10.8 | 10.8 | 10.8 | | | | | | |
| | | | | | $M_{0,max}$ | | | 17.1 | 25.3 | 33.3 | 43.8 | 51.1 | | | | | | | |
| | | | | | M_{max} | | | 17.1 | 25.3 | 33.3 | 43.8 | 51.1 | | | | | | | |
| | | | | | η_{eto} | | | - | - | - | - | - | | | | | | | |
| 17N41 | 9.5 | 4110 | 10.2 | 4.10 | M_0 | | | | | | - | 12.8 | 12.8 | 12.8 | | | | | |
| | | | | | M_N | | | | | | - | 9.5 | 9.5 | 9.5 | | | | | |
| | | | | | $M_{0,max}$ | | | | | | 16.5 | 22.3 | 31.1 | 39.9 | 49.5 | | | | |
| | | | | | M_{max} | | | | | | 16.5 | 22.3 | 31.1 | 39.9 | 49.5 | | | | |
| | | | | | η_{eto} | | | | | | - | - | - | - | - | | | | |
| 19S23 | 16.3 | 2340 | 8.2 | 4.00 | M_0 | | | | | | | - | 22.5 | 22.5 | 22.5 | | | | |
| | | | | | M_N | | | | | | - | 16.3 | 16.3 | 16.3 | | | | | |
| | | | | | $M_{0,max}$ | | | | | | 32.8 | 43.6 | 60.9 | 77.5 | | | | | |
| | | | | | M_{max} | | | | | | 32.8 | 43.7 | 61.0 | 77.5 | | | | | |
| | | | | | η_{eto} | | | | | | - | - | - | - | | | | | |
| 19S42 | 12.0 | 4150 | 14.0 | 5.20 | M_0 | | | | | | | | - | 22.5 | 22.5 | 22.5 | | | |
| | | | | | M_N | | | | | | | | - | 12.0 | 12.0 | 12.0 | | | |
| | | | | | $M_{0,max}$ | | | | | | | | | 28.5 | 37.0 | 53.7 | 64.7 | | |
| | | | | | M_{max} | | | | | | | | | 28.5 | 37.0 | 53.8 | 64.7 | | |
| | | | | | η_{eto} | | | | | | | | | - | - | - | - | | |
| 21X25 | 24.6 | 2490 | 13.5 | 6.40 | M_0 | | | | | | | | - | 39.0 | 39.0 | 39.0 | | | |
| | | | | | M_N | | | | | | | | - | 24.5 | 24.5 | 24.5 | | | |
| | | | | | $M_{0,max}$ | | | | | | | | 33.6 | 46.7 | 59.3 | 85.9 | 97.3 | | |
| | | | | | M_{max} | | | | | | | | 33.6 | 46.7 | 59.3 | 85.9 | 97.6 | | |
| | | | | | η_{eto} | | | | | | | | - | - | - | - | - | | |
| 21X42 | 17.0 | 4160 | 19.8 | 7.40 | M_0 | | | | | | | | | - | 39.0 | 39.0 | 39.0 | | |
| | | | | | M_N | | | | | | | | | - | 17.0 | 17.0 | 17.0 | | |
| | | | | | $M_{0,max}$ | | | | | | | | | 35.3 | 52.2 | 72.1 | 88.5 | | |
| | | | | | M_{max} | | | | | | | | | 35.3 | 52.2 | 72.1 | 88.5 | | |
| | | | | | η_{eto} | | | | | | | | | - | - | - | - | | |

► I_N [A], M_N [Nm], n_N [r/min], P_N [kW]

MCA asynchronou servo motors

Selection tables for Inverter Drives 8400 TopLine





MCA asynchronou servo motors

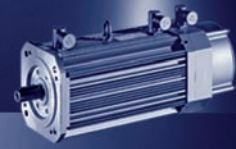
Selection tables for Inverter Drives 8400 TopLine

Mains connection 3 x 400 V and switching frequency
8 kHz

Motors with blower, IP54

| | | | | | E84AVTC | □1524 | □2224 | □3024 | □4024 | □5524 | □7524 | |
|-------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|---|
| | | | | | I_N | 3.9 | 5.9 | 7.3 | 9.5 | 13.0 | 16.5 | |
| | | | | | $I_{0,max}$ | 5.9 | 8.4 | 11.0 | 14.3 | 19.5 | 26.4 | |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 7.8 | 11.8 | 14.6 | 19.0 | 26.0 | 33.0 | |
| 13I34 | 6.3 | 3410 | 6.0 | 2.20 | M_0 | | - | 7.0 | 7.0 | 7.0 | | |
| | | | | | M_N | | - | 6.2 | 6.2 | 6.2 | | |
| | | | | | $M_{0,max}$ | | 16.0 | 21.4 | 28.2 | 35.9 | | |
| | | | | | M_{max} | | 16.0 | 21.4 | 28.2 | 35.9 | | |
| | | | | | η_{eto} | | - | - | - | - | | |
| 14L16 | 12.0 | 1635 | 4.8 | 2.10 | M_0 | - | 13.5 | 13.5 | 13.5 | | | |
| | | | | | M_N | - | 12.3 | 12.3 | 12.3 | | | |
| | | | | | $M_{0,max}$ | 23.4 | 34.7 | 45.5 | 50.8 | | | |
| | | | | | M_{max} | 23.4 | 34.7 | 45.5 | 50.8 | | | |
| | | | | | η_{eto} | - | - | - | - | | | |
| 14L35 | 10.8 | 3455 | 9.1 | 3.90 | M_0 | | | - | 13.5 | 13.5 | 13.5 | |
| | | | | | M_N | | | - | 10.8 | 10.8 | 10.8 | |
| | | | | | $M_{0,max}$ | | | 21.1 | 28.4 | 39.8 | 51.1 | |
| | | | | | M_{max} | | | 21.1 | 28.4 | 39.8 | 51.1 | |
| | | | | | η_{eto} | | | - | - | - | - | |
| 17N17 | 21.5 | 1680 | 8.5 | 3.80 | M_0 | | | - | 23.9 | 23.9 | 23.9 | |
| | | | | | M_N | | | - | 21.6 | 21.6 | 21.6 | |
| | | | | | $M_{0,max}$ | | | 42.1 | 55.9 | 77.5 | 93.3 | |
| | | | | | M_{max} | | | 42.2 | 56.0 | 77.5 | 93.3 | |
| | | | | | η_{eto} | | | - | - | - | - | |
| 17N35 | 19.0 | 3480 | 15.8 | 6.90 | M_0 | | | | - | - | 23.9 | |
| | | | | | M_N | | | | - | - | 18.9 | |
| | | | | | $M_{0,max}$ | | | | | 38.0 | 49.5 | |
| | | | | | M_{max} | | | | | 38.0 | 49.5 | |
| | | | | | η_{eto} | | | | | - | - | |
| 19S17 | 36.3 | 1700 | 13.9 | 6.40 | M_0 | | | | | - | 40.0 | |
| | | | | | M_N | | | | | - | 36.0 | |
| | | | | | $M_{0,max}$ | | | | | 71.6 | 94.7 | |
| | | | | | M_{max} | | | | | 71.6 | 94.7 | |
| | | | | | η_{eto} | | | | | - | - | |
| 19S35 | 36.0 | 3510 | 28.7 | 13.20 | M_0 | | | | | | | |
| | | | | | M_N | | | | | | | |
| | | | | | $M_{0,max}$ | | | | | | | |
| | | | | | M_{max} | | | | | | | |
| | | | | | η_{eto} | | | | | | | |
| 21X17 | 61.4 | 1710 | 22.5 | 11.00 | M_0 | | | | | | - | |
| | | | | | M_N | | | | | | | - |
| | | | | | $M_{0,max}$ | | | | | | 99.0 | |
| | | | | | M_{max} | | | | | | 99.0 | |
| | | | | | η_{eto} | | | | | | - | |
| 21X35 | 55.0 | 3520 | 42.5 | 20.30 | M_0 | | | | | | | |
| | | | | | M_N | | | | | | | |
| | | | | | $M_{0,max}$ | | | | | | | |
| | | | | | M_{max} | | | | | | | |
| | | | | | η_{eto} | | | | | | | |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

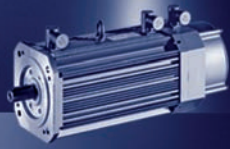


Mains connection 3 x 400 V and switching frequency 8 kHz

Motors with blower, IP54

| □1134 | □1534 | □1834 | □2234 | □3034 | □3734 | □4534 | E84AVTC | | | | | |
|-------|-------|-------|-------|-------|-------|-------|--------------------|----------------|----------------|----------------|----------------|-------|
| 23.5 | 32.0 | 39.0 | 47.0 | 61.0 | 76.0 | 89.0 | I _N | P _N | I _N | n _N | M _N | MCA |
| 32.9 | 43.2 | 60.0 | 70.5 | 91.5 | 114.0 | 133.5 | I _{0,max} | | | | | |
| 47.0 | 64.0 | 78.0 | 94.0 | 122.0 | 152.0 | 178.0 | I _{max} | | | | | |
| | | | | | | | M ₀ | 2.20 | 6.0 | 3410 | 6.3 | 13I34 |
| | | | | | | | M _N | | | | | |
| | | | | | | | M _{0,max} | | | | | |
| | | | | | | | M _{max} | | | | | |
| | | | | | | | n _{eto} | | | | | |
| | | | | | | | M ₀ | 2.10 | 4.8 | 1635 | 12.0 | 14L16 |
| | | | | | | | M _N | | | | | |
| | | | | | | | M _{0,max} | | | | | |
| | | | | | | | M _{max} | | | | | |
| | | | | | | | n _{eto} | | | | | |
| 13.5 | | | | | | | M ₀ | 3.90 | 9.1 | 3455 | 10.8 | 14L35 |
| 10.8 | | | | | | | M _N | | | | | |
| 56.5 | | | | | | | M _{0,max} | | | | | |
| 56.6 | | | | | | | M _{max} | | | | | |
| - | | | | | | | n _{eto} | | | | | |
| | | | | | | | M ₀ | 3.80 | 8.5 | 1680 | 21.5 | 17N17 |
| | | | | | | | M _N | | | | | |
| | | | | | | | M _{0,max} | | | | | |
| | | | | | | | M _{max} | | | | | |
| | | | | | | | n _{eto} | | | | | |
| 23.9 | 23.9 | | | | | | M ₀ | 6.90 | 15.8 | 3480 | 19.0 | 17N35 |
| 18.9 | 18.9 | | | | | | M _N | | | | | |
| 72.5 | 97.8 | | | | | | M _{0,max} | | | | | |
| 72.5 | 97.8 | | | | | | M _{max} | | | | | |
| - | - | | | | | | n _{eto} | | | | | |
| 40.0 | 40.0 | | | | | | M ₀ | 6.40 | 13.9 | 1700 | 36.3 | 19S17 |
| 36.0 | 36.0 | | | | | | M _N | | | | | |
| 138.9 | 165.2 | | | | | | M _{0,max} | | | | | |
| 139.0 | 165.3 | | | | | | M _{max} | | | | | |
| - | - | | | | | | n _{eto} | | | | | |
| - | 40.0 | 40.0 | 40.0 | 40.0 | | | M ₀ | 13.20 | 28.7 | 3510 | 36.0 | 19S35 |
| - | 35.9 | 35.9 | 35.9 | 35.9 | | | M _N | | | | | |
| 55.1 | 78.8 | 97.8 | 112.8 | 146.2 | | | M _{0,max} | | | | | |
| 55.1 | 78.8 | 97.8 | 112.9 | 146.2 | | | M _{max} | | | | | |
| - | - | - | - | - | | | n _{eto} | | | | | |
| 75.0 | 75.0 | 75.0 | 75.0 | | | | M ₀ | 11.00 | 22.5 | 1710 | 61.4 | 21X17 |
| 61.4 | 61.4 | 61.4 | 61.4 | | | | M _N | | | | | |
| 143.7 | 198.5 | 242.2 | 277.2 | | | | M _{0,max} | | | | | |
| 144.0 | 198.7 | 242.3 | 277.2 | | | | M _{max} | | | | | |
| - | - | - | - | | | | n _{eto} | | | | | |
| | - | - | 75.0 | 75.0 | 75.0 | 75.0 | M ₀ | 20.30 | 42.5 | 3520 | 55.0 | 21X35 |
| | - | - | 55.1 | 55.1 | 55.1 | 55.1 | M _N | | | | | |
| | 97.5 | 120.6 | 138.5 | 177.5 | 216.7 | 267.8 | M _{0,max} | | | | | |
| | 97.5 | 120.6 | 138.6 | 178.0 | 217.5 | 269.8 | M _{max} | | | | | |
| | - | - | - | - | - | - | n _{eto} | | | | | |

► I... [A], M... [Nm], n... [r/min], P... [kW]



MCA asynchronous servo motors

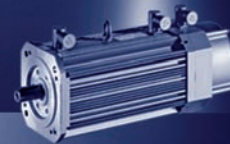
Selection tables for Inverter Drives 8400 TopLine

Mains connection 3 x 400 V and switching frequency
8 kHz

Motors with blower, IP54

| | | | | | E84AVTC | □7524 | □1134 | □1534 | □1834 | □2234 | □3034 | □3734 | □4534 | |
|-------------------|-------|-------|-------|-------|-------------|-------|-------|-------|-------|-------|-------|-------|-------|------|
| | | | | | I_N | 16.5 | 23.5 | 32.0 | 39.0 | 47.0 | 61.0 | 76.0 | 89.0 | |
| | | | | | $I_{0,max}$ | 26.4 | 32.9 | 43.2 | 60.0 | 70.5 | 91.5 | 114.0 | 133.5 | |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 33.0 | 47.0 | 64.0 | 78.0 | 94.0 | 122.0 | 152.0 | 178.0 | |
| 22P08- ...5F□□ | 110.0 | 760 | 22.1 | 8.80 | M_0 | - | - | 120.0 | 120.0 | 135.0 | | | | |
| | | | | | M_N | - | 120.6 | 144.5 | 110.6 | 144.5 | | | | |
| | | | | | $M_{0,max}$ | 157.8 | 222.8 | 323.3 | 377.0 | 372.9 | | | | |
| | | | | | M_{max} | 157.8 | 223.0 | 323.3 | 377.0 | 400.9 | | | | |
| | | | | | n_{eto} | - | - | - | - | - | | | | |
| 22P14- ...5F□□ | 107.0 | 1425 | 37.7 | 16.00 | M_0 | | | - | - | 120.0 | 118.0 | 156.0 | 118.0 | |
| | | | | | M_N | | | - | 107.2 | 115.3 | 107.2 | 134.7 | 107.2 | |
| | | | | | $M_{0,max}$ | | | 188.4 | 232.5 | 270.8 | 343.7 | 425.8 | 458.8 | |
| | | | | | M_{max} | | | 186.7 | 235.1 | 269.0 | 344.4 | 423.7 | 514.4 | |
| | | | | | n_{eto} | | | - | - | - | - | - | - | |
| 22P17- ...5F□□ | 105.0 | 1670 | 42.7 | 18.50 | M_0 | | | - | - | 135.0 | 120.0 | 156.0 | 135.0 | |
| | | | | | M_N | | | - | - | 112.1 | 112.1 | 129.8 | 105.8 | |
| | | | | | $M_{0,max}$ | | | 162.7 | 204.6 | 236.9 | 309.7 | 376.9 | 461.2 | |
| | | | | | M_{max} | | | 162.7 | 198.6 | 237.1 | 300.0 | 367.5 | 449.9 | |
| | | | | | n_{eto} | | | - | - | - | - | - | - | |
| 22P29- ...5F□□ | 100.0 | 2935 | 72.1 | 30.70 | M_0 | | | | | | - | 120.0 | 120.0 | |
| | | | | | M_N | | | | | | | - | 99.9 | 99.9 |
| | | | | | $M_{0,max}$ | | | | | | 180.0 | 218.9 | 263.2 | |
| | | | | | M_{max} | | | | | | 180.7 | 225.0 | 264.1 | |
| | | | | | n_{eto} | | | | | | - | - | - | |

- ▶ $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]
- ▶ If the motors are operated at a lower switching frequency, please contact your Lenze sales office!

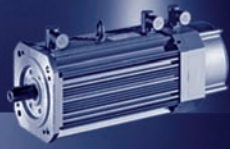


Mains connection 3 x 400 V and switching frequency 8 kHz

Motors with blower, IP23s

| | | | | | E84AVTC | □7524 | □1134 | □1534 | □1834 | □2234 | □3034 | □3734 | □4534 | | |
|-------------------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|-------|-------|------|------|
| | | | | | I_N | 16.5 | 23.5 | 32.0 | 39.0 | 47.0 | 61.0 | 76.0 | 89.0 | | |
| | | | | | $I_{0,max}$ | 26.4 | 32.9 | 43.2 | 60.0 | 70.5 | 91.5 | 114.0 | 133.5 | | |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 33.0 | 47.0 | 64.0 | 78.0 | 94.0 | 122.0 | 152.0 | 178.0 | | |
| 20X14- ...2F□□ | 61.0 | 1420 | 23.0 | 9.10 | M_0 | - | 67.0 | 67.0 | 67.0 | 67.0 | | | | | |
| | | | | | M_N | - | 61.2 | 61.2 | 61.2 | 61.2 | | | | | |
| | | | | | $M_{0,max}$ | 94.8 | 139.9 | 192.6 | 235.5 | 272.2 | | | | | |
| | | | | | M_{max} | 94.9 | 139.9 | 192.8 | 235.7 | 272.5 | | | | | |
| | | | | | η_{eto} | - | - | - | - | - | | | | | |
| 20X29- ...2F□□ | 53.5 | 2930 | 42.4 | 16.40 | M_0 | | | - | - | 57.0 | 57.0 | 57.0 | 57.0 | | |
| | | | | | M_N | | | - | - | 53.4 | 53.4 | 53.4 | 53.4 | | |
| | | | | | $M_{0,max}$ | | | 96.8 | 121.2 | 140.3 | 182.5 | 222.1 | 272.5 | | |
| | | | | | M_{max} | | | 96.8 | 121.2 | 140.4 | 182.6 | 223.0 | 274.5 | | |
| | | | | | η_{eto} | | | - | - | - | - | - | - | | |
| 22P08- ...2F□□ | 120.0 | 760 | 23.5 | 9.60 | M_0 | - | 135.0 | 120.0 | 120.0 | 135.0 | | | | | |
| | | | | | M_N | - | 120.6 | 144.5 | 110.6 | 120.6 | | | | | |
| | | | | | $M_{0,max}$ | 157.8 | 234.2 | 323.3 | 377.0 | 394.3 | | | | | |
| | | | | | M_{max} | 157.8 | 234.8 | 323.3 | 377.0 | 372.9 | | | | | |
| | | | | | η_{eto} | - | - | - | - | - | | | | | |
| 22P14- ...2F□□ | 115.0 | 1425 | 40.0 | 17.20 | M_0 | | | - | - | 120.0 | 156.0 | 156.0 | 118.0 | | |
| | | | | | M_N | | | - | 107.2 | 115.3 | 107.2 | 134.7 | 107.2 | | |
| | | | | | $M_{0,max}$ | | | 188.4 | 232.5 | 268.8 | 345.7 | 422.7 | 493.6 | | |
| | | | | | M_{max} | | | 188.7 | 230.6 | 271.0 | 350.3 | 423.7 | 460.9 | | |
| | | | | | η_{eto} | | | - | - | - | - | - | - | | |
| 22P17- ...2F□□ | 112.0 | 1670 | 44.5 | 19.60 | M_0 | | | - | - | 135.0 | 120.0 | 156.0 | 135.0 | | |
| | | | | | M_N | | | - | - | 112.1 | 112.1 | 129.8 | 105.8 | | |
| | | | | | $M_{0,max}$ | | | 162.7 | 204.6 | 236.9 | 309.7 | 376.9 | 461.2 | | |
| | | | | | M_{max} | | | 162.7 | 198.6 | 238.2 | 308.3 | 367.5 | 449.9 | | |
| | | | | | η_{eto} | | | - | - | - | - | - | - | | |
| 22P29- ...2F□□ | 110.0 | 2935 | 77.8 | 33.80 | M_0 | | | | | | - | 120.0 | 120.0 | | |
| | | | | | M_N | | | | | | | | - | 99.9 | 99.9 |
| | | | | | $M_{0,max}$ | | | | | | 180.0 | 218.9 | 263.2 | | |
| | | | | | M_{max} | | | | | | 180.7 | 225.0 | 264.1 | | |
| | | | | | η_{eto} | | | | | | - | - | - | | |

- ▶ $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]
- ▶ If the motors are operated at a lower switching frequency, please contact your Lenze sales office!



MCA asynchronous servo motors

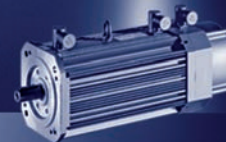
ECS servo system selection tables

Mains connection 3 x 400 V and switching frequency 4 kHz

Motors without blower

| | | | | | ECS□□ | 008C□B | 016C□B | 032C□B | 048C□B | 064C□B |
|-------|-------|-------|-------|-------|--------------|--------|--------|--------|--------|--------|
| | | | | | I_N | 4.0 | 8.0 | 12.7 | 17.0 | 20.0 |
| | | | | | $I_{0,max}$ | 4.6 | 9.1 | 18.1 | 27.2 | 36.3 |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 8.0 | 16.0 | 32.0 | 48.0 | 64.0 |
| 10I40 | 2.0 | 3950 | 2.4 | 0.80 | M_0 | 2.3 | | | | |
| | | | | | M_N | 2.0 | | | | |
| | | | | | $M_{0,max}$ | 5.6 | | | | |
| | | | | | M_{max} | 8.1 | | | | |
| | | | | | η_{eto} | - | | | | |
| 13I41 | 4.0 | 4050 | 4.4 | 1.70 | M_0 | 3.0 | 4.6 | | | |
| | | | | | M_N | 3.0 | 4.0 | | | |
| | | | | | $M_{0,max}$ | 4.3 | 11.0 | | | |
| | | | | | M_{max} | 9.4 | 18.2 | | | |
| | | | | | η_{eto} | - | - | | | |
| 14L20 | 6.7 | 2000 | 3.3 | 1.40 | M_0 | 8.0 | 8.0 | | | |
| | | | | | M_N | 6.7 | 6.7 | | | |
| | | | | | $M_{0,max}$ | 10.7 | 25.3 | | | |
| | | | | | M_{max} | 21.6 | 42.8 | | | |
| | | | | | η_{eto} | - | - | | | |
| 14L41 | 5.4 | 4100 | 5.8 | 2.30 | M_0 | | 8.0 | 8.0 | | |
| | | | | | M_N | | 5.4 | 5.4 | | |
| | | | | | $M_{0,max}$ | | 11.0 | 24.0 | | |
| | | | | | M_{max} | | 20.7 | 29.1 | | |
| | | | | | η_{eto} | | - | - | | |
| 17N23 | 10.8 | 2300 | 5.5 | 2.60 | M_0 | | 12.8 | 12.8 | | |
| | | | | | M_N | | 10.8 | 10.8 | | |
| | | | | | $M_{0,max}$ | | 20.5 | 43.5 | | |
| | | | | | M_{max} | | 40.2 | 63.7 | | |
| | | | | | η_{eto} | | - | - | | |
| 17N41 | 9.5 | 4110 | 10.2 | 4.10 | M_0 | | 6.1 | 12.8 | 12.8 | |
| | | | | | M_N | | 6.1 | 9.5 | 9.5 | |
| | | | | | $M_{0,max}$ | | 7.8 | 21.5 | 33.5 | |
| | | | | | M_{max} | | 17.4 | 29.6 | 57.7 | |
| | | | | | η_{eto} | | - | - | - | |
| 19S23 | 16.3 | 2340 | 8.2 | 4.00 | M_0 | | 15.1 | 22.5 | | |
| | | | | | M_N | | 15.1 | 16.3 | | |
| | | | | | $M_{0,max}$ | | 18.7 | 43.5 | | |
| | | | | | M_{max} | | 38.5 | 67.9 | | |
| | | | | | η_{eto} | | - | - | | |
| 19S42 | 12.0 | 4150 | 14.0 | 5.20 | M_0 | | | 9.8 | 16.7 | |
| | | | | | M_N | | | 9.8 | 12.0 | |
| | | | | | $M_{0,max}$ | | | 18.4 | 31.9 | |
| | | | | | M_{max} | | | 29.9 | 58.2 | |
| | | | | | η_{eto} | | | - | - | |
| 21X25 | 24.6 | 2490 | 13.5 | 6.40 | M_0 | | | 21.0 | 39.0 | |
| | | | | | M_N | | | 21.0 | 24.6 | |
| | | | | | $M_{0,max}$ | | | 41.0 | 64.5 | |
| | | | | | M_{max} | | | 64.4 | 120.5 | |
| | | | | | η_{eto} | | | - | - | |
| 21X42 | 17.0 | 4160 | 19.8 | 7.40 | M_0 | | | | 13.0 | 17.0 |
| | | | | | M_N | | | | 13.0 | 17.0 |
| | | | | | $M_{0,max}$ | | | | 30.0 | 45.0 |
| | | | | | M_{max} | | | | 59.4 | 83.0 |
| | | | | | η_{eto} | | | | - | - |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

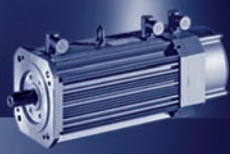


Mains connection 3 x 400 V and switching frequency 4 kHz

Motors with blower, IP54

| | | | | | ECS□□ | 008C□B | 016C□B | 032C□B | 048C□B | 064C□B |
|-------|-------|-------|-------|-------|-------------|--------|--------|--------|--------|--------|
| | | | | | I_N | 4.0 | 8.0 | 12.7 | 17.0 | 20.0 |
| | | | | | $I_{0,max}$ | 4.6 | 9.1 | 18.1 | 27.2 | 36.3 |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 8.0 | 16.0 | 32.0 | 48.0 | 64.0 |
| 13I34 | 6.3 | 3410 | 6.0 | 2.20 | M_0 | | 7.0 | | | |
| | | | | | M_N | | 6.3 | | | |
| | | | | | $M_{0,max}$ | | 10.7 | | | |
| | | | | | M_{max} | | 20.8 | | | |
| | | | | | n_{eto} | | - | | | |
| 14L16 | 12.0 | 1635 | 4.8 | 2.10 | M_0 | 8.9 | 13.5 | | | |
| | | | | | M_N | 8.9 | 12.0 | | | |
| | | | | | $M_{0,max}$ | 11.5 | 25.4 | | | |
| | | | | | M_{max} | 21.6 | 46.7 | | | |
| | | | | | n_{eto} | - | - | | | |
| 14L35 | 10.8 | 3455 | 9.1 | 3.90 | M_0 | | 8.3 | 13.5 | 13.5 | |
| | | | | | M_N | | 8.3 | 10.8 | 10.8 | |
| | | | | | $M_{0,max}$ | | 11.0 | 27.0 | 41.0 | |
| | | | | | M_{max} | | 22.2 | 42.0 | 67.8 | |
| | | | | | n_{eto} | | - | - | - | |
| 17N17 | 21.5 | 1680 | 8.5 | 3.80 | M_0 | | 19.5 | 23.9 | | |
| | | | | | M_N | | 19.5 | 21.5 | | |
| | | | | | $M_{0,max}$ | | 23.0 | 53.0 | | |
| | | | | | M_{max} | | 44.8 | 80.0 | | |
| | | | | | n_{eto} | | - | - | | |
| 17N35 | 19.0 | 3480 | 15.8 | 6.90 | M_0 | | | 12.7 | 23.0 | |
| | | | | | M_N | | | 12.7 | 19.0 | |
| | | | | | $M_{0,max}$ | | | 23.0 | 37.5 | |
| | | | | | M_{max} | | | 37.7 | 64.4 | |
| | | | | | n_{eto} | | | - | - | |
| 19S17 | 36.3 | 1700 | 13.9 | 6.40 | M_0 | | | 28.3 | 40.0 | 40.0 |
| | | | | | M_N | | | 28.3 | 36.3 | 36.3 |
| | | | | | $M_{0,max}$ | | | 46.5 | 72.0 | 98.0 |
| | | | | | M_{max} | | | 75.4 | 130.8 | 158.9 |
| | | | | | n_{eto} | | | - | - | - |
| 21X17 | 61.4 | 1710 | 22.5 | 11.00 | M_0 | | | | | 52.5 |
| | | | | | M_N | | | | | 52.5 |
| | | | | | $M_{0,max}$ | | | | | 107.0 |
| | | | | | M_{max} | | | | | 190.0 |
| | | | | | n_{eto} | | | | | - |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MCA asynchrone servo motors

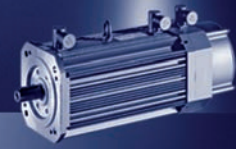
EVS9300 servo inverter selection tables

Mains connection 3 x 400 V and switching frequency
8 kHz

Motors without blower

| | | | | | EVS | 9322-E□ | 9323-E□ | 9324-E□ | 9325-E□ | 9326-E□ | 9327-E□ | 9328-E□ | 9329-E□ |
|-------|-------|-------|-------|-------|--------------|---------|---------|---------|---------|---------|---------|---------|---------|
| | | | | | I_N | 2.5 | 3.9 | 7.0 | 13.0 | 23.5 | 32.0 | 47.0 | 59.0 |
| | | | | | $I_{0,max}$ | 3.8 | 5.9 | 10.5 | 19.5 | 23.5 | 32.0 | 47.0 | 52.0 |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 3.8 | 5.9 | 10.5 | 19.5 | 35.3 | 48.0 | 70.5 | 88.5 |
| 10I40 | 2.0 | 3950 | 2.4 | 0.80 | M_0 | 2.2 | 2.3 | | | | | | |
| | | | | | M_N | 2.0 | 2.0 | | | | | | |
| | | | | | $M_{0,max}$ | 4.4 | 7.3 | | | | | | |
| | | | | | M_{max} | 4.4 | 7.3 | | | | | | |
| | | | | | η_{eto} | - | - | | | | | | |
| 13I41 | 4.0 | 4050 | 4.4 | 1.70 | M_0 | | | 4.6 | 4.6 | | | | |
| | | | | | M_N | | | 4.0 | 4.0 | | | | |
| | | | | | $M_{0,max}$ | | | 12.6 | 19.5 | | | | |
| | | | | | M_{max} | | | 12.6 | 19.5 | | | | |
| | | | | | η_{eto} | | | - | - | | | | |
| 14L20 | 6.7 | 2000 | 3.3 | 1.40 | M_0 | | 8.0 | 8.0 | | | | | |
| | | | | | M_N | | 6.7 | 6.7 | | | | | |
| | | | | | $M_{0,max}$ | | 15.1 | 29.3 | | | | | |
| | | | | | M_{max} | | 15.1 | 29.3 | | | | | |
| | | | | | η_{eto} | | - | - | | | | | |
| 14L41 | 5.4 | 4100 | 5.8 | 2.30 | M_0 | | | 7.0 | 8.0 | | | | |
| | | | | | M_N | | | 5.4 | 5.4 | | | | |
| | | | | | $M_{0,max}$ | | | 13.2 | 26.0 | | | | |
| | | | | | M_{max} | | | 13.2 | 26.0 | | | | |
| | | | | | η_{eto} | | | - | - | | | | |
| 17N23 | 10.8 | 2300 | 5.5 | 2.60 | M_0 | | | 12.8 | 12.8 | | | | |
| | | | | | M_N | | | 10.8 | 10.8 | | | | |
| | | | | | $M_{0,max}$ | | | 24.4 | 46.2 | | | | |
| | | | | | M_{max} | | | 24.4 | 46.2 | | | | |
| | | | | | η_{eto} | | | - | - | | | | |
| 17N41 | 9.5 | 4110 | 10.2 | 4.10 | M_0 | | | | 12.8 | 12.8 | | | |
| | | | | | M_N | | | | 9.5 | 9.5 | 9.5 | | |
| | | | | | $M_{0,max}$ | | | | 23.4 | 37.0 | 54.0 | | |
| | | | | | M_{max} | | | | 23.4 | 43.7 | 59.4 | | |
| | | | | | η_{eto} | | | | - | - | - | | |
| 19S23 | 16.3 | 2340 | 8.2 | 4.00 | M_0 | | | | 22.5 | 22.5 | | | |
| | | | | | M_N | | | | 16.3 | 16.3 | | | |
| | | | | | $M_{0,max}$ | | | | 47.2 | 78.0 | | | |
| | | | | | M_{max} | | | | 47.2 | 88.2 | | | |
| | | | | | η_{eto} | | | | - | - | - | | |
| 19S42 | 12.0 | 4150 | 14.0 | 5.20 | M_0 | | | | 10.0 | 22.5 | 22.5 | | |
| | | | | | M_N | | | | 10.0 | 12.0 | 12.0 | | |
| | | | | | $M_{0,max}$ | | | | 20.7 | 33.5 | 51.0 | | |
| | | | | | M_{max} | | | | 20.7 | 43.3 | 60.7 | | |
| | | | | | η_{eto} | | | | - | - | - | | |
| 21X25 | 24.6 | 2490 | 13.5 | 6.40 | M_0 | | | | 23.7 | 39.0 | 39.0 | | |
| | | | | | M_N | | | | 23.7 | 24.6 | 24.6 | | |
| | | | | | $M_{0,max}$ | | | | 46.2 | 66.0 | 84.0 | | |
| | | | | | M_{max} | | | | 46.2 | 78.0 | 92.4 | | |
| | | | | | η_{eto} | | | | - | - | - | | |
| 21X42 | 17.0 | 4160 | 19.8 | 7.40 | M_0 | | | | | 24.0 | 39.0 | 39.0 | 39.0 |
| | | | | | M_N | | | | | 17.0 | 17.0 | 17.0 | 17.0 |
| | | | | | $M_{0,max}$ | | | | | 24.0 | 47.0 | 84.0 | 94.0 |
| | | | | | M_{max} | | | | | 43.9 | 63.3 | 96.8 | 123.0 |
| | | | | | η_{eto} | | | | | - | - | - | - |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

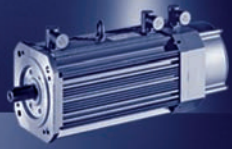


**Mains connection 3 x 400 V and switching frequency
8 kHz**

Motors with blower, IP54

| | | | | | EVS | 9324-E□ | 9325-E□ | 9326-E□ | 9327-E□ | 9328-E□ | 9329-E□ | 9330-E□ | 9331-E□ |
|-------|-------|-------|-------|-------|--------------|---------|---------|---------|---------|---------|---------|---------|---------|
| | | | | | I_N | 7.0 | 13.0 | 23.5 | 32.0 | 47.0 | 59.0 | 89.0 | 110.0 |
| | | | | | $I_{0,max}$ | 10.5 | 19.5 | 23.5 | 32.0 | 47.0 | 52.0 | 80.0 | 110.0 |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 10.5 | 19.5 | 35.3 | 48.0 | 70.5 | 88.5 | 133.5 | 165.0 |
| 13I34 | 6.3 | 3410 | 6.0 | 2.20 | M_0 | 7.0 | 7.0 | | | | | | |
| | | | | | M_N | 6.3 | 6.3 | | | | | | |
| | | | | | $M_{0,max}$ | 13.0 | 25.0 | | | | | | |
| | | | | | M_{max} | 13.0 | 25.0 | | | | | | |
| | | | | | η_{eto} | - | - | | | | | | |
| 14L16 | 12.0 | 1635 | 4.8 | 2.10 | M_0 | 13.5 | | | | | | | |
| | | | | | M_N | 12.0 | | | | | | | |
| | | | | | $M_{0,max}$ | 29.6 | | | | | | | |
| | | | | | M_{max} | 29.6 | | | | | | | |
| | | | | | η_{eto} | - | | | | | | | |
| 14L35 | 10.8 | 3455 | 9.1 | 3.90 | M_0 | | 13.5 | 13.5 | | | | | |
| | | | | | M_N | | 10.8 | 10.8 | | | | | |
| | | | | | $M_{0,max}$ | | 29.3 | 47.0 | | | | | |
| | | | | | M_{max} | | 29.3 | 53.8 | | | | | |
| | | | | | η_{eto} | | - | - | | | | | |
| 17N17 | 21.5 | 1680 | 8.5 | 3.80 | M_0 | | 23.9 | | | | | | |
| | | | | | M_N | | 21.5 | | | | | | |
| | | | | | $M_{0,max}$ | | 57.2 | | | | | | |
| | | | | | M_{max} | | 57.2 | | | | | | |
| | | | | | η_{eto} | | - | | | | | | |
| 17N35 | 19.0 | 3480 | 15.8 | 6.90 | M_0 | | | 23.9 | 23.9 | 23.9 | | | |
| | | | | | M_N | | | 19.0 | 19.0 | 19.0 | | | |
| | | | | | $M_{0,max}$ | | | 27.5 | 57.0 | 89.0 | | | |
| | | | | | M_{max} | | | 50.7 | 69.2 | 100.2 | | | |
| | | | | | η_{eto} | | | - | - | - | | | |
| 19S17 | 36.3 | 1700 | 13.9 | 6.40 | M_0 | | 34.0 | 40.0 | 40.0 | | | | |
| | | | | | M_N | | 34.0 | 36.3 | 36.3 | | | | |
| | | | | | $M_{0,max}$ | | 50.1 | 76.0 | 112.0 | | | | |
| | | | | | M_{max} | | 50.1 | 95.9 | 130.8 | | | | |
| | | | | | η_{eto} | | - | - | - | | | | |
| 19S35 | 36.0 | 3510 | 28.7 | 13.20 | M_0 | | | 21.0 | 39.0 | 40.0 | 40.0 | 40.0 | |
| | | | | | M_N | | | 21.0 | 36.0 | 36.0 | 36.0 | 36.0 | |
| | | | | | $M_{0,max}$ | | | 21.0 | 39.0 | 73.0 | 80.0 | 161.5 | |
| | | | | | M_{max} | | | 45.7 | 67.6 | 104.3 | 132.9 | 180.0 | |
| | | | | | η_{eto} | | | - | - | - | - | - | |
| 21X17 | 61.4 | 1710 | 22.5 | 11.00 | M_0 | | | 65.5 | 75.0 | 75.0 | 75.0 | | |
| | | | | | M_N | | | 61.4 | 61.4 | 61.4 | 61.4 | | |
| | | | | | $M_{0,max}$ | | | 65.5 | 102.0 | 178.0 | 200.0 | | |
| | | | | | M_{max} | | | 104.1 | 143.3 | 210.7 | 257.3 | | |
| | | | | | η_{eto} | | | - | - | - | - | | |
| 21X35 | 55.0 | 3520 | 42.5 | 20.30 | M_0 | | | | | 68.0 | 75.0 | 75.0 | 75.0 |
| | | | | | M_N | | | | | 55.0 | 55.0 | 55.0 | 55.0 |
| | | | | | $M_{0,max}$ | | | | | 68.0 | 88.0 | 156.0 | 219.0 |
| | | | | | M_{max} | | | | | 107.7 | 135.9 | 205.0 | 250.1 |
| | | | | | η_{eto} | | | | | - | - | - | - |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]



MCA asynchronous servo motors

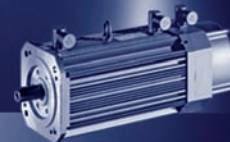
EVS9300 servo inverter selection tables

Mains connection 3 x 400 V and switching frequency 8 kHz

Motors with blower, IP54

| | | | | | EVS | 9326-E□ | 9327-E□ | 9328-E□ | 9329-E□ | 9330-E□ | 9331-E□ | 9332-E□ |
|-------------------|-------|-------|-------|-------|-------------|---------|---------|---------|---------|---------|---------|---------|
| | | | | | I_N | 23.5 | 32.0 | 47.0 | 59.0 | 89.0 | 110.0 | 145.0 |
| | | | | | $I_{0,max}$ | 23.5 | 32.0 | 47.0 | 52.0 | 80.0 | 110.0 | 126.0 |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 35.3 | 48.0 | 70.5 | 88.5 | 133.5 | 165.0 | 217.5 |
| 22P08- ...5F□□ | 110.0 | 760 | 22.1 | 8.80 | M_0 | 115.0 | 120.0 | 120.0 | 120.0 | | | |
| | | | | | M_N | 108.0 | 110.0 | 110.0 | 110.0 | | | |
| | | | | | $M_{0,max}$ | 115.0 | 166.0 | 242.0 | 267.0 | | | |
| | | | | | M_{max} | 185.0 | 247.0 | 338.8 | 345.8 | | | |
| | | | | | n_{eto} | - | - | - | - | | | |
| 22P14- ...5F□□ | 107.0 | 1425 | 37.7 | 16.00 | M_0 | | | 120.0 | 120.0 | 120.0 | | |
| | | | | | M_N | | | 107.0 | 107.0 | 107.0 | | |
| | | | | | $M_{0,max}$ | | | 146.0 | 160.0 | 264.0 | | |
| | | | | | M_{max} | | | 230.1 | 292.9 | 341.8 | | |
| | | | | | n_{eto} | | | - | - | - | | |
| 22P17- ...5F□□ | 105.0 | 1670 | 42.7 | 18.50 | M_0 | | | 120.0 | 120.0 | 120.0 | 120.0 | |
| | | | | | M_N | | | 106.0 | 106.0 | 106.0 | 106.0 | |
| | | | | | $M_{0,max}$ | | | 124.0 | 140.0 | 240.0 | 335.0 | |
| | | | | | M_{max} | | | 180.5 | 227.7 | 342.1 | 378.3 | |
| | | | | | n_{eto} | | | - | - | - | - | |
| 22P29- ...5F□□ | 100.0 | 2935 | 72.1 | 30.70 | M_0 | | | | | 118.0 | 120.0 | 120.0 |
| | | | | | M_N | | | | | 100.0 | 100.0 | 100.0 |
| | | | | | $M_{0,max}$ | | | | | 122.0 | 171.0 | 200.0 |
| | | | | | M_{max} | | | | | 215.6 | 273.1 | 355.1 |
| | | | | | n_{eto} | | | | | - | - | - |
| 26T05- ...5F□□ | 216.0 | 550 | 34.9 | 12.40 | M_0 | | 191.0 | 220.0 | 220.0 | 220.0 | | |
| | | | | | M_N | | 191.0 | 216.0 | 216.0 | 216.0 | | |
| | | | | | $M_{0,max}$ | | 191.0 | 303.0 | 333.0 | 615.0 | | |
| | | | | | M_{max} | | 313.0 | 482.0 | 612.0 | 751.0 | | |
| | | | | | n_{eto} | | - | - | - | - | | |
| 26T10- ...5F□□ | 210.0 | 1030 | 61.5 | 22.70 | M_0 | | | | 159.0 | 220.0 | 220.0 | |
| | | | | | M_N | | | | 197.0 | 210.0 | 210.0 | |
| | | | | | $M_{0,max}$ | | | | 159.0 | 300.0 | 440.0 | |
| | | | | | M_{max} | | | | 343.0 | 552.0 | 671.0 | |
| | | | | | n_{eto} | | | | - | - | - | |
| 26T12- ...5F□□ | 207.0 | 1200 | 75.1 | 26.00 | M_0 | | | | | 207.0 | 220.0 | 220.0 |
| | | | | | M_N | | | | 255.0 | 207.0 | 207.0 | |
| | | | | | $M_{0,max}$ | | | | 258.0 | 327.0 | 397.0 | |
| | | | | | M_{max} | | | | 424.0 | 512.0 | 663.0 | |
| | | | | | n_{eto} | | | | - | - | - | |
| 26T22- ...5F□□ | 195.0 | 2235 | 112.9 | 45.60 | M_0 | | | | | | 177.0 | 220.0 |
| | | | | | M_N | | | | | | 177.0 | 195.0 |
| | | | | | $M_{0,max}$ | | | | | | 203.0 | 220.0 |
| | | | | | M_{max} | | | | | | 315.0 | 432.0 |
| | | | | | n_{eto} | | | | | | - | - |

- ▶ $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]
- ▶ If the motors are operated at a lower switching frequency, please contact your Lenze sales office!

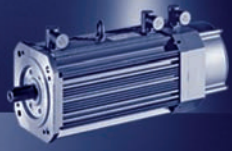


**Mains connection 3 x 400 V and switching frequency
8 kHz**

Motors with blower, IP23s

| | | | | | EVS | 9326-E□ | 9327-E□ | 9328-E□ | 9329-E□ | 9330-E□ | 9331-E□ | 9332-E□ |
|-------------------|-------|-------|-------|-------|--------------|---------|---------|---------|---------|---------|---------|---------|
| | | | | | I_N | 23.5 | 32.0 | 47.0 | 59.0 | 89.0 | 110.0 | 145.0 |
| | | | | | $I_{0,max}$ | 23.5 | 32.0 | 47.0 | 52.0 | 80.0 | 110.0 | 126.0 |
| MCA | M_N | n_N | I_N | P_N | I_{max} | 35.3 | 48.0 | 70.5 | 88.5 | 133.5 | 165.0 | 217.5 |
| 20X14- ...2F□□ | 61.0 | 1420 | 23.0 | 9.10 | M_0 | 61.0 | 68.0 | 68.0 | | | | |
| | | | | | M_N | 61.0 | 61.0 | 61.0 | | | | |
| | | | | | $M_{0,max}$ | 61.0 | 93.0 | 153.0 | | | | |
| | | | | | M_{max} | 109.3 | 156.7 | 232.1 | | | | |
| | | | | | η_{eto} | - | - | - | | | | |
| 20X29- ...2F□□ | 53.5 | 2930 | 42.4 | 16.40 | M_0 | | 28.0 | 66.3 | 68.0 | 68.0 | | |
| | | | | | M_N | | 28.0 | 53.5 | 53.5 | 53.5 | | |
| | | | | | $M_{0,max}$ | | 28.0 | 66.3 | 72.0 | 129.0 | | |
| | | | | | M_{max} | | 68.5 | 112.5 | 146.4 | 226.7 | | |
| | | | | | η_{eto} | | - | - | - | - | | |
| 22P08- ...2F□□ | 120.0 | 760 | 23.5 | 9.60 | M_0 | 115.0 | 135.0 | 135.0 | 135.0 | | | |
| | | | | | M_N | 115.0 | 120.0 | 120.0 | 120.0 | | | |
| | | | | | $M_{0,max}$ | 115.0 | 166.0 | 242.0 | 267.0 | | | |
| | | | | | M_{max} | 185.0 | 247.0 | 338.8 | 345.8 | | | |
| | | | | | η_{eto} | - | - | - | - | | | |
| 22P14- ...2F□□ | 115.0 | 1425 | 40.0 | 17.20 | M_0 | | | 135.0 | 135.0 | 135.0 | | |
| | | | | | M_N | | | 115.0 | 115.0 | 115.0 | | |
| | | | | | $M_{0,max}$ | | | 146.0 | 160.0 | 264.0 | | |
| | | | | | M_{max} | | | 230.1 | 292.9 | 341.8 | | |
| | | | | | η_{eto} | | | - | - | - | | |
| 22P17- ...2F□□ | 112.0 | 1670 | 44.5 | 19.60 | M_0 | | | 124.0 | 134.0 | 135.0 | 135.0 | |
| | | | | | M_N | | | 112.0 | 112.0 | 112.0 | 112.0 | |
| | | | | | $M_{0,max}$ | | | 124.0 | 140.0 | 240.0 | 335.0 | |
| | | | | | M_{max} | | | 180.5 | 227.7 | 342.1 | 378.3 | |
| | | | | | η_{eto} | | | - | - | - | - | |
| 22P29- ...2F□□ | 110.0 | 2935 | 77.8 | 33.80 | M_0 | | | | | 118.0 | 135.0 | 135.0 |
| | | | | | M_N | | | | | 110.0 | 110.0 | 110.0 |
| | | | | | $M_{0,max}$ | | | | | 122.0 | 171.0 | 200.0 |
| | | | | | M_{max} | | | | | 215.6 | 273.1 | 355.1 |
| | | | | | η_{eto} | | | | | - | - | - |
| 26T05- ...2F□□ | 280.0 | 550 | 42.4 | 16.10 | M_0 | | 191.0 | 290.0 | 290.0 | 290.0 | | |
| | | | | | M_N | | 191.0 | 280.0 | 280.0 | 280.0 | | |
| | | | | | $M_{0,max}$ | | 191.0 | 303.0 | 333.0 | 615.0 | | |
| | | | | | M_{max} | | 313.0 | 482.0 | 612.0 | 751.0 | | |
| | | | | | η_{eto} | | - | - | - | - | | |
| 26T10- ...2F□□ | 260.0 | 1030 | 69.6 | 28.00 | M_0 | | | | 159.0 | 290.0 | 290.0 | |
| | | | | | M_N | | | | 197.0 | 260.0 | 260.0 | |
| | | | | | $M_{0,max}$ | | | | 159.0 | 300.0 | 440.0 | |
| | | | | | M_{max} | | | | 343.0 | 552.0 | 671.0 | |
| | | | | | η_{eto} | | | | - | - | - | |
| 26T12- ...2F□□ | 255.0 | 1200 | 83.3 | 32.00 | M_0 | | | | | 232.0 | 290.0 | 290.0 |
| | | | | | M_N | | | | 255.0 | 255.0 | 255.0 | |
| | | | | | $M_{0,max}$ | | | | 258.0 | 327.0 | 397.0 | |
| | | | | | M_{max} | | | | 424.0 | 512.0 | 663.0 | |
| | | | | | η_{eto} | | | | - | - | - | |
| 26T22- ...2F□□ | 230.0 | 2235 | 126.7 | 53.80 | M_0 | | | | | | 177.0 | 222.0 |
| | | | | | M_N | | | | 177.0 | 230.0 | 230.0 | |
| | | | | | $M_{0,max}$ | | | | 203.0 | 220.0 | 220.0 | |
| | | | | | M_{max} | | | | 315.0 | 432.0 | 432.0 | |
| | | | | | η_{eto} | | | | - | - | - | |

- ▶ $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]
- ▶ If the motors are operated at a lower switching frequency, please contact your Lenze sales office!

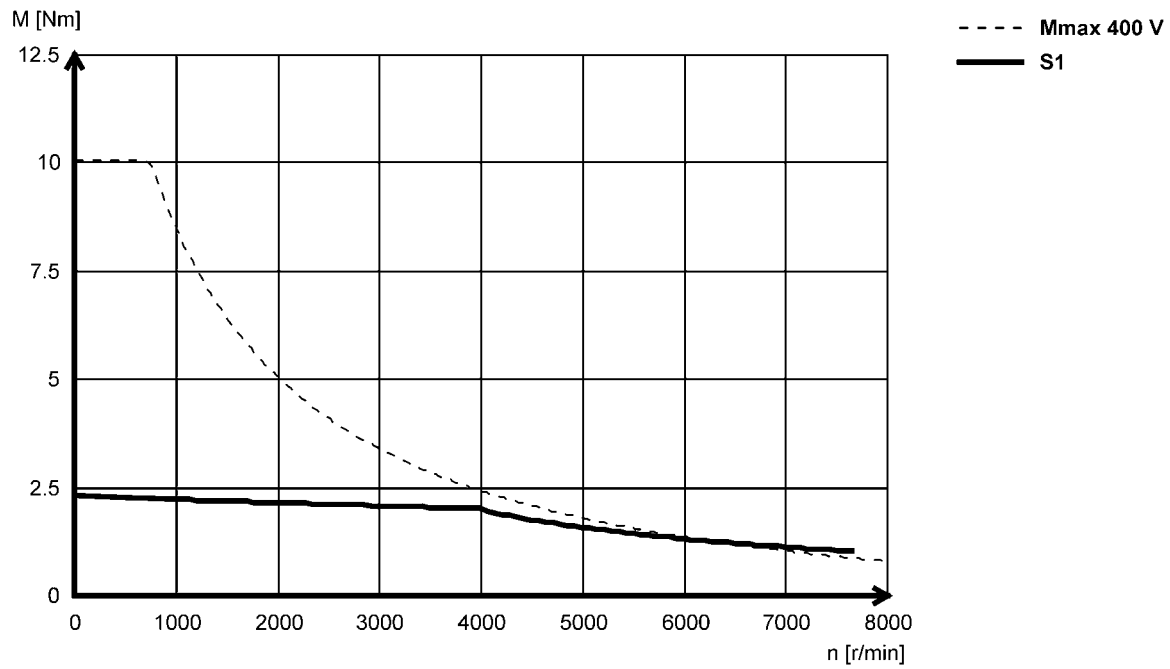


MCA asynchronous servo motors

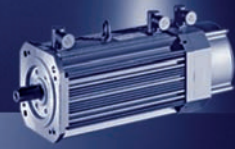
Torque characteristics

Mains connection 3x 400 V

MCA10I40

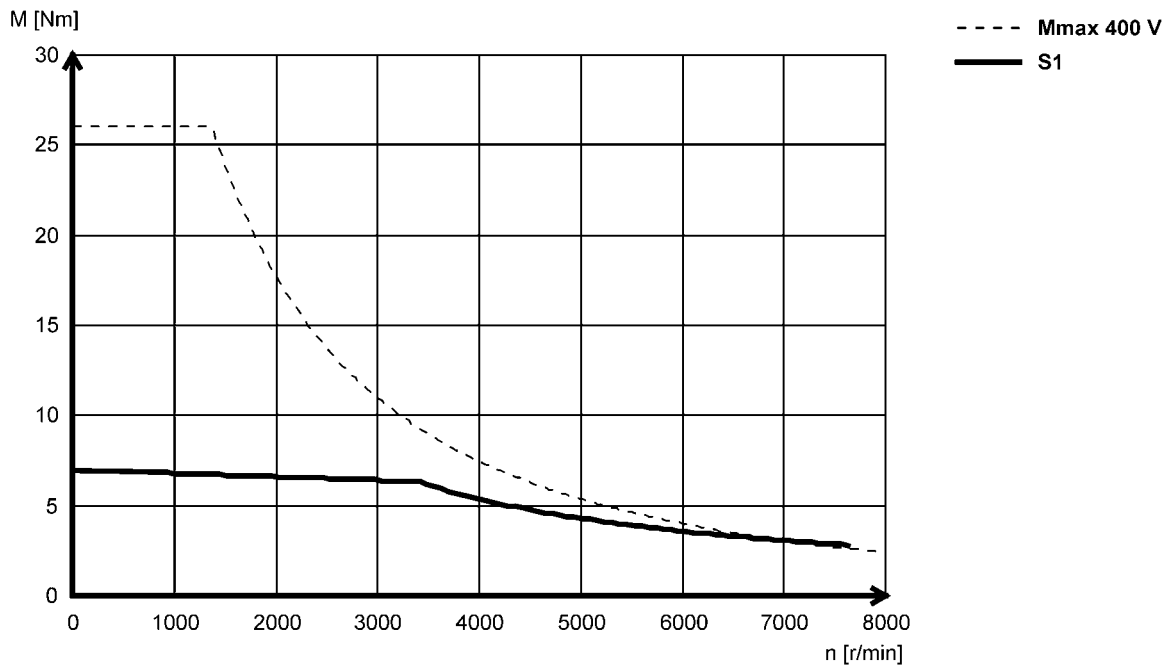


- ▶ Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

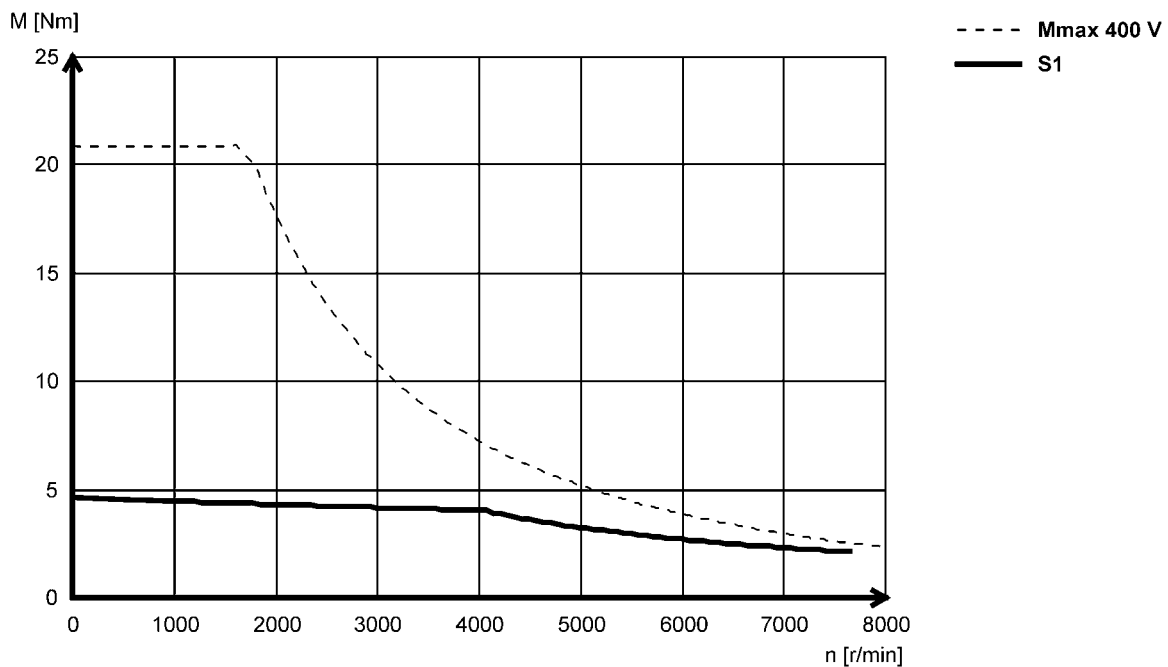


Mains connection 3x 400 V

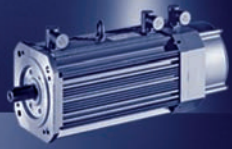
MCA13I34



MCA13I41



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

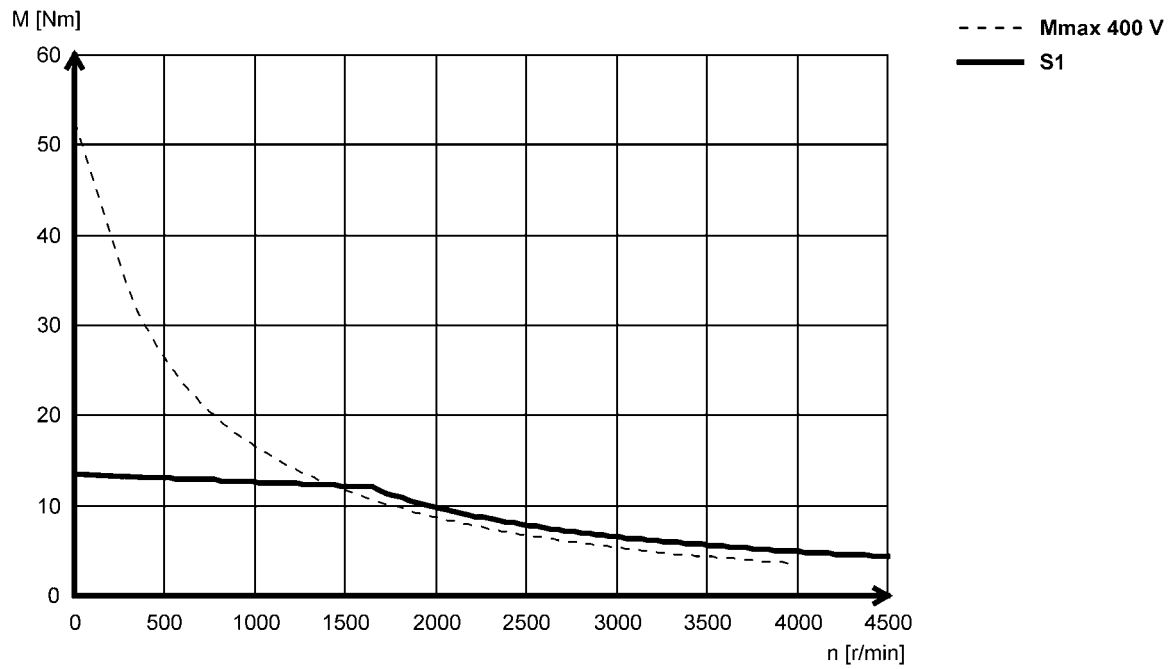


MCA asynchronous servo motors

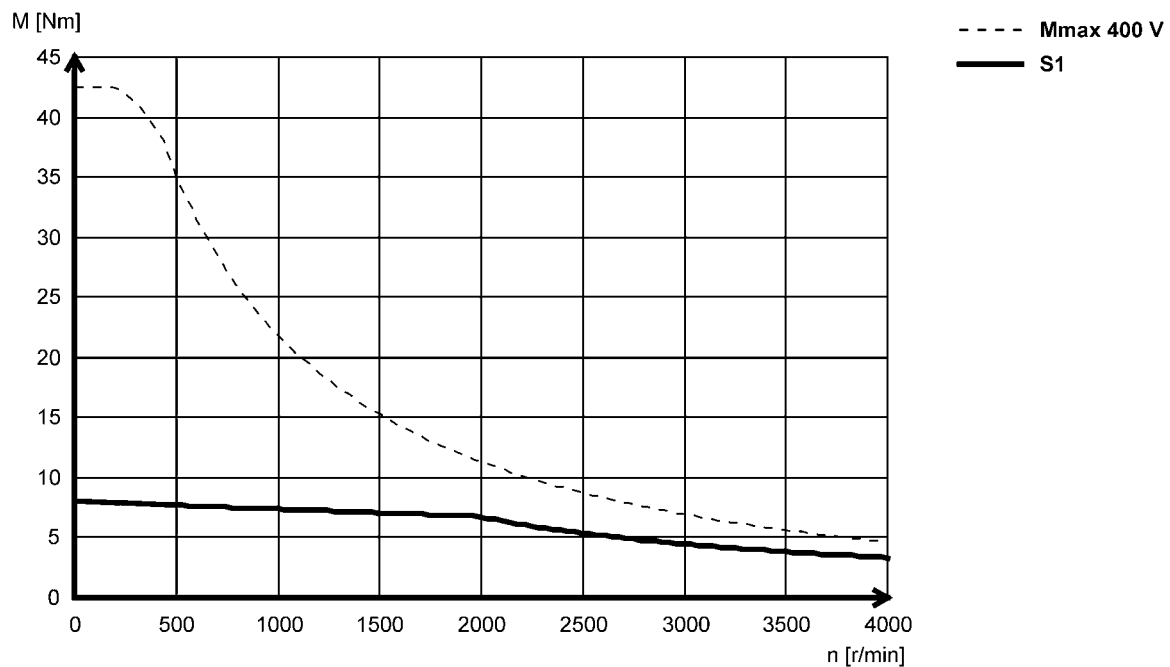
Torque characteristics

Mains connection 3x 400 V

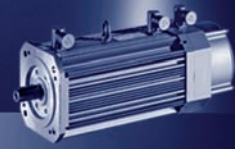
MCA14L16



MCA14L20

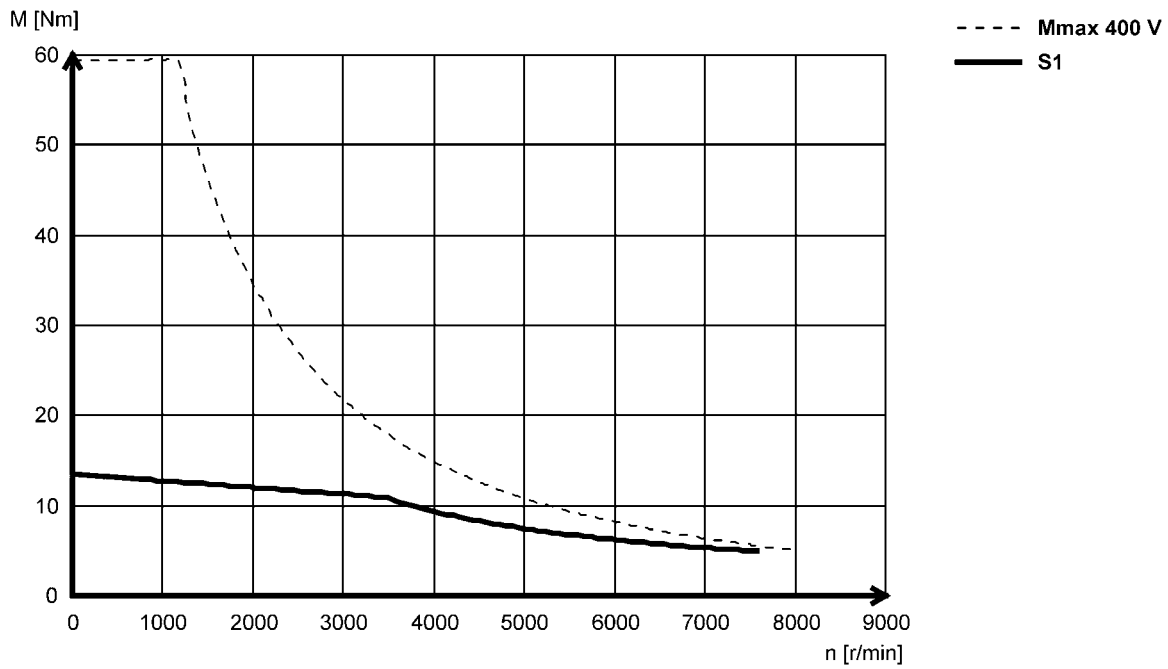


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

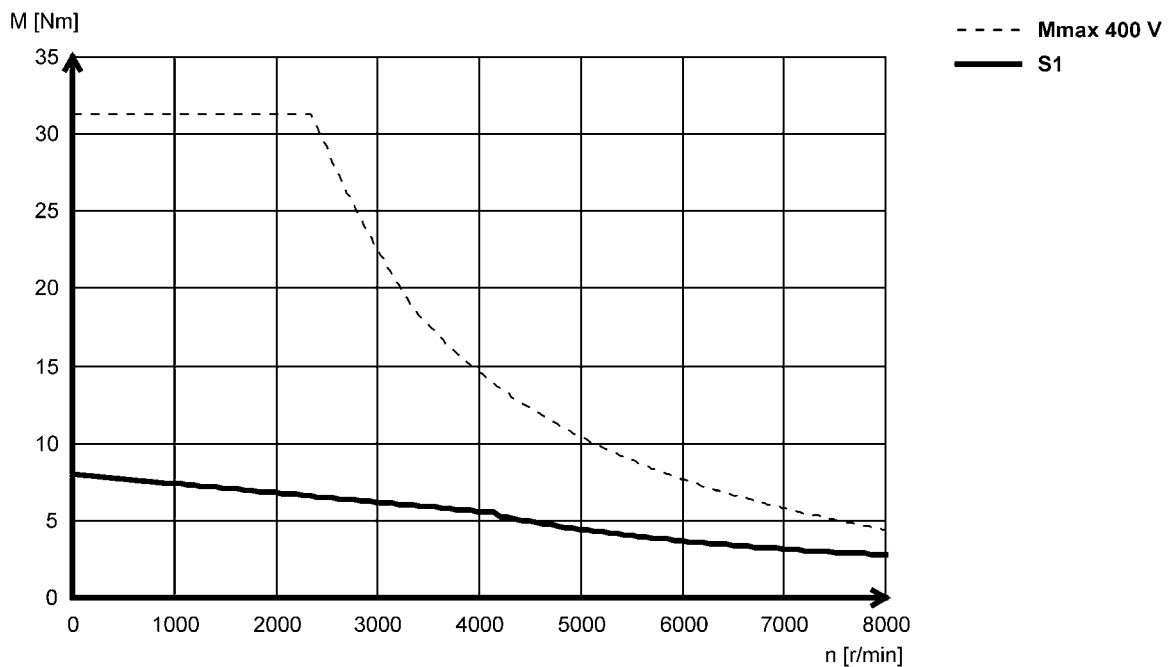


Mains connection 3x 400 V

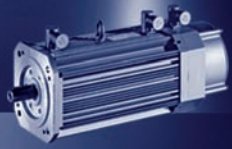
MCA14L35



MCA14L41



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

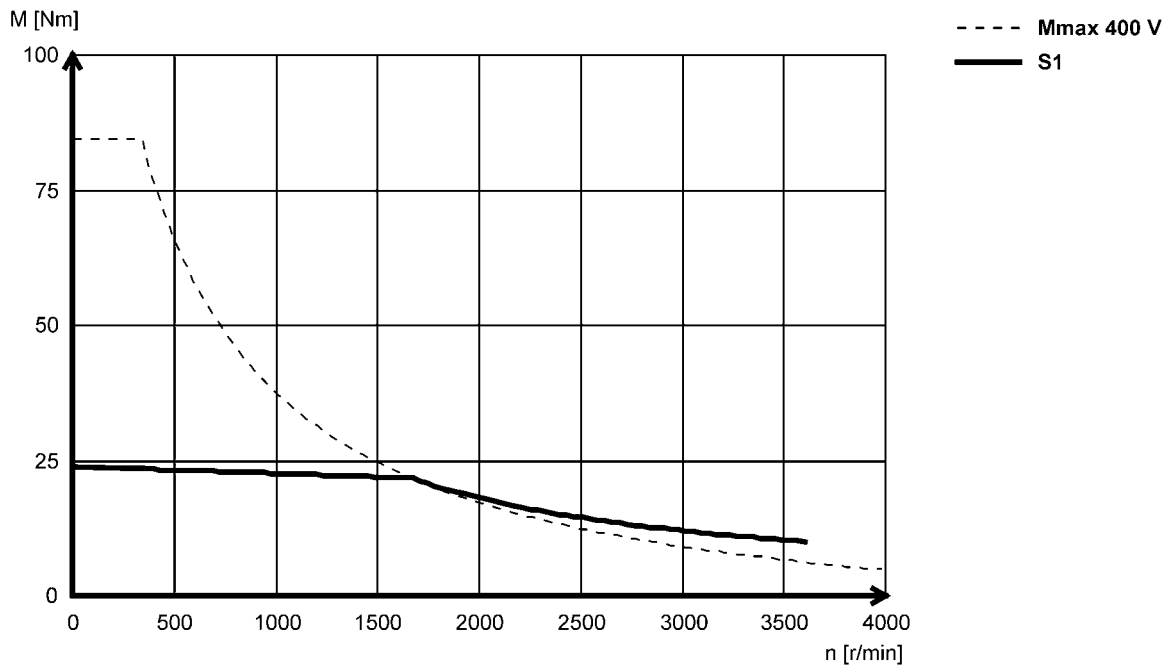


MCA asynchronous servo motors

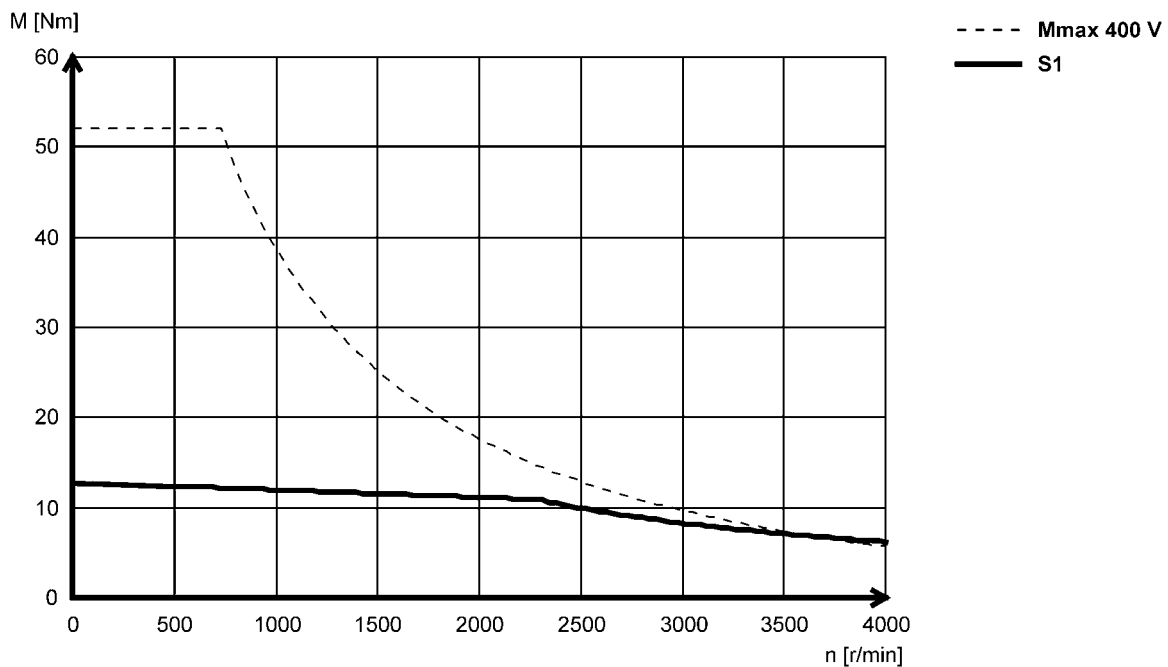
Torque characteristics

Mains connection 3x 400 V

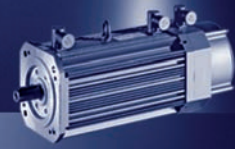
MCA17N17



MCA17N23

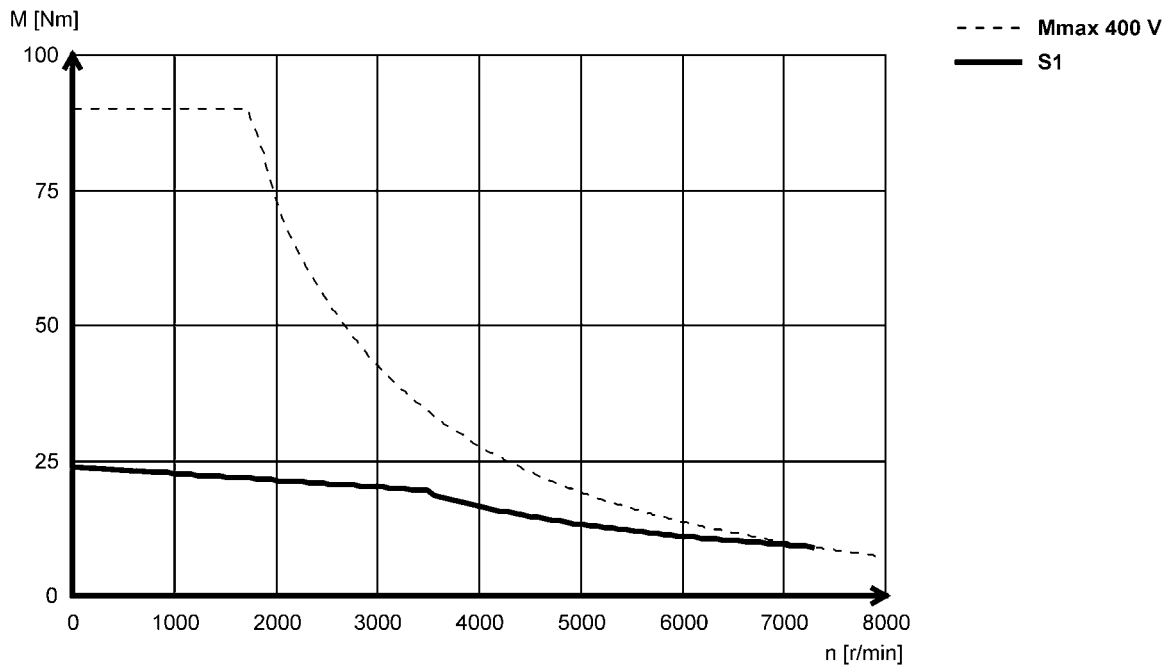


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

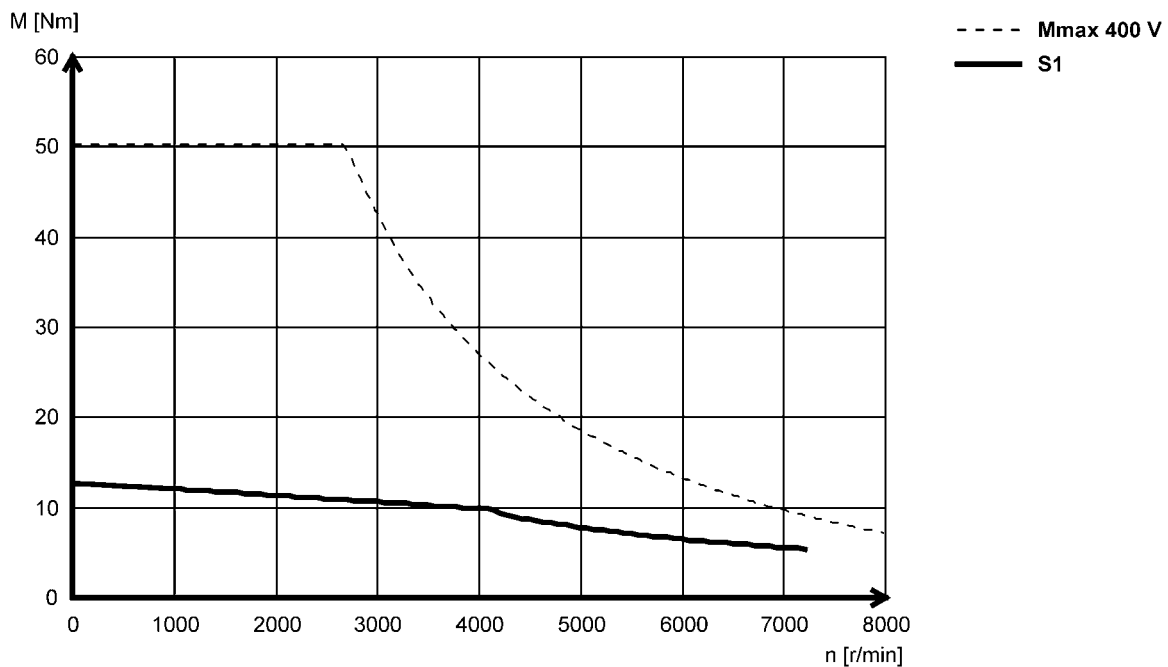


Mains connection 3x 400 V

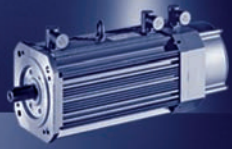
MCA17N35



MCA17N41



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

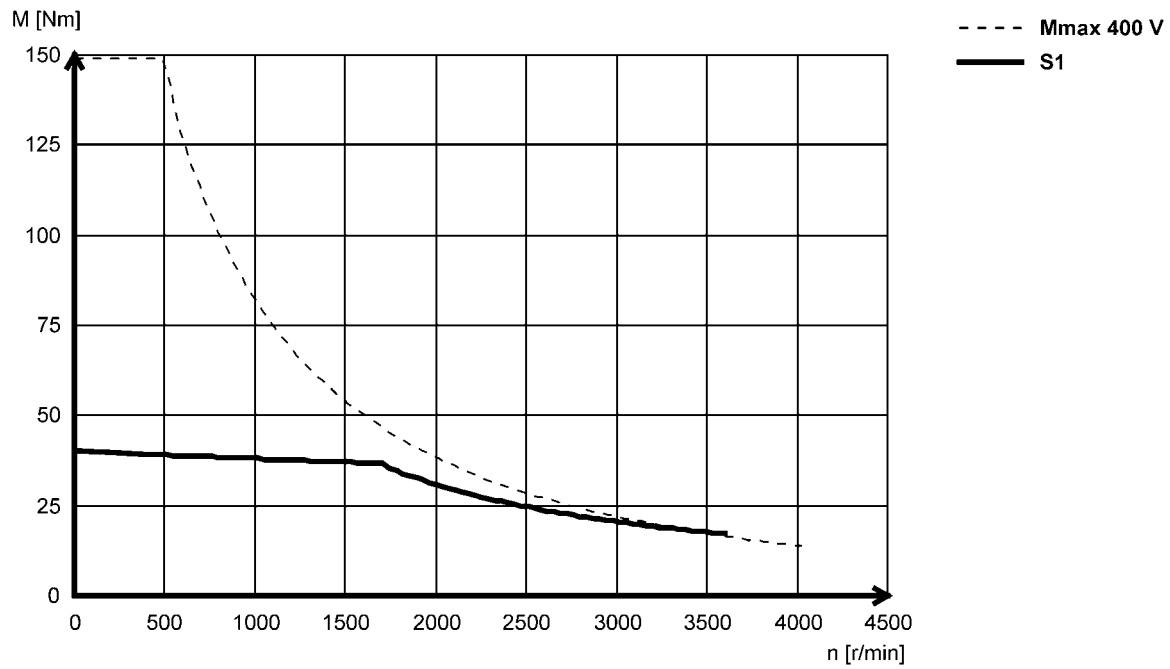


MCA asynchronous servo motors

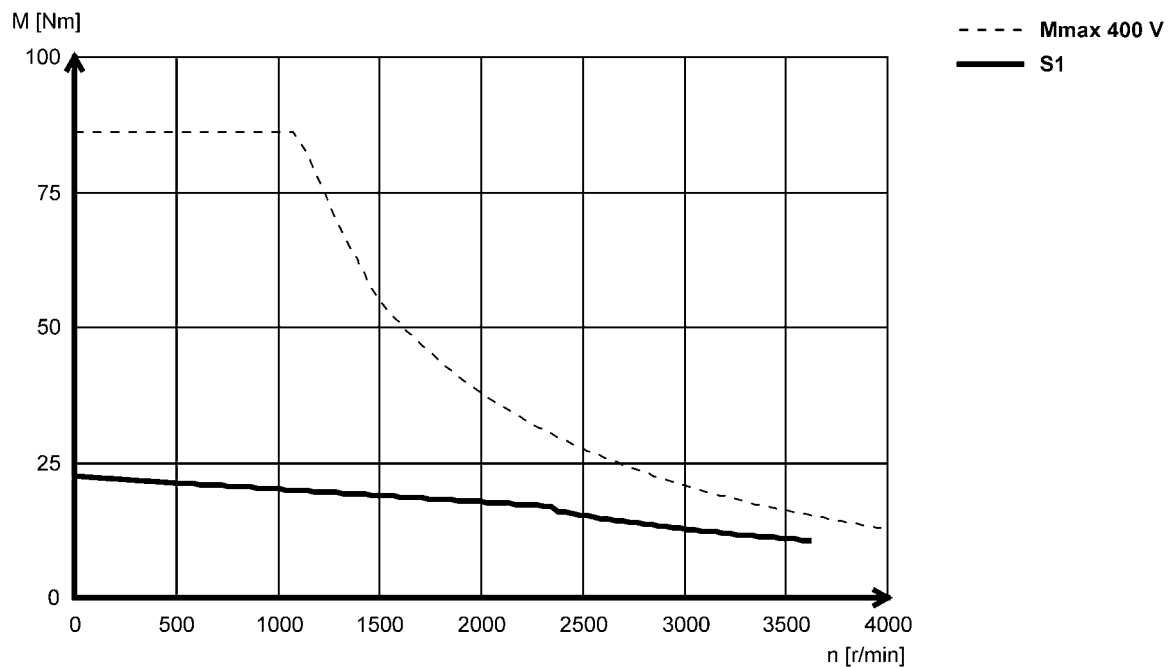
Torque characteristics

Mains connection 3x 400 V

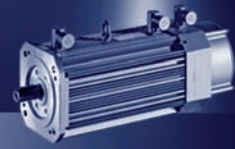
MCA19S17



MCA19S23

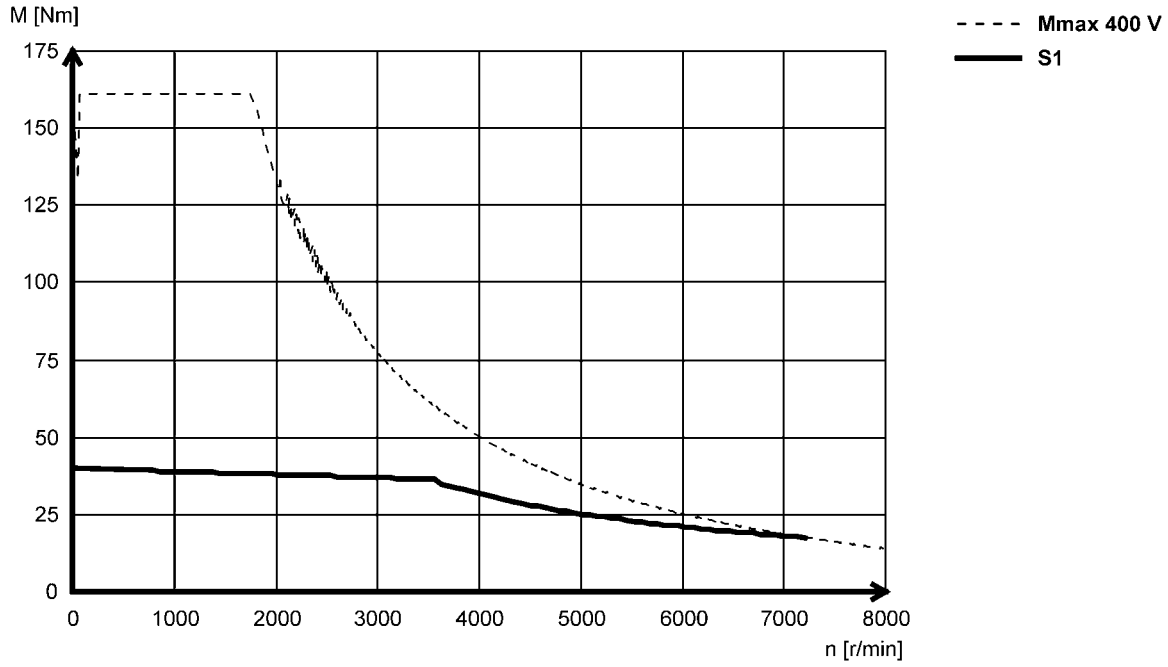


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

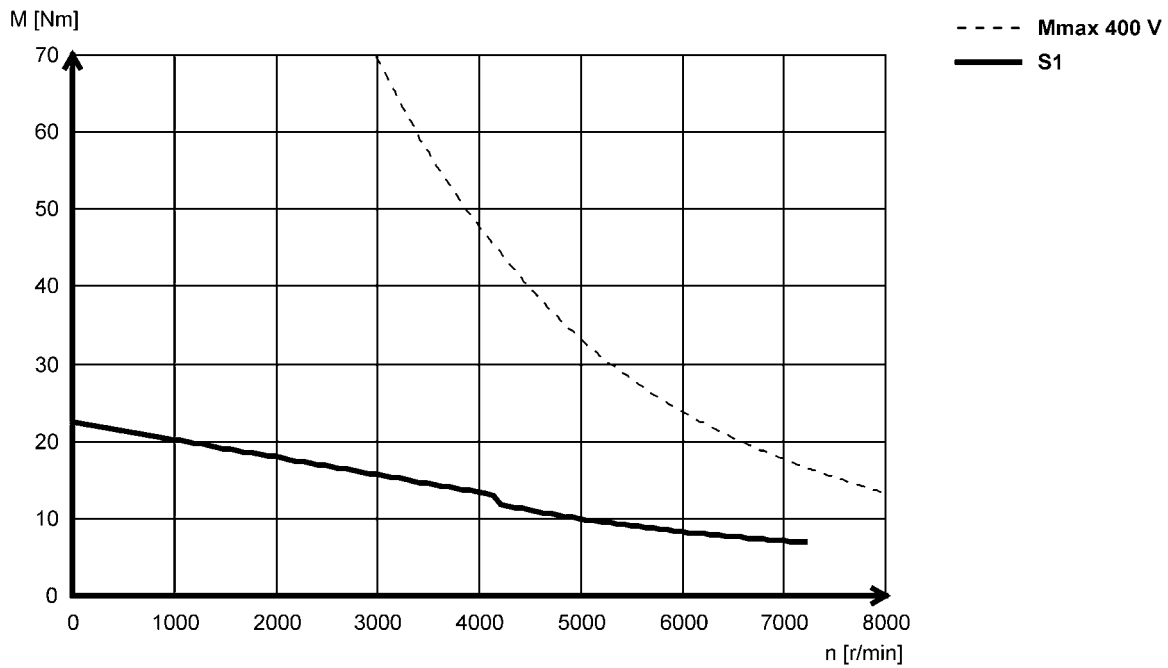


Mains connection 3x 400 V

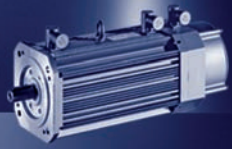
MCA19S35



MCA19S42



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

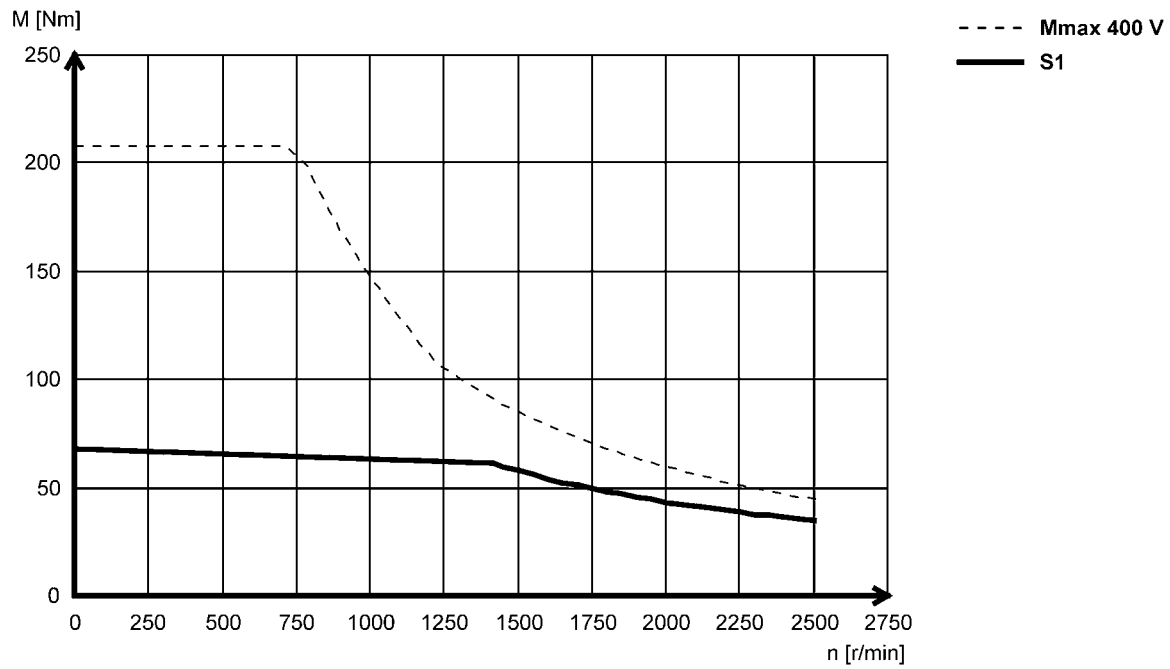


MCA asynchronous servo motors

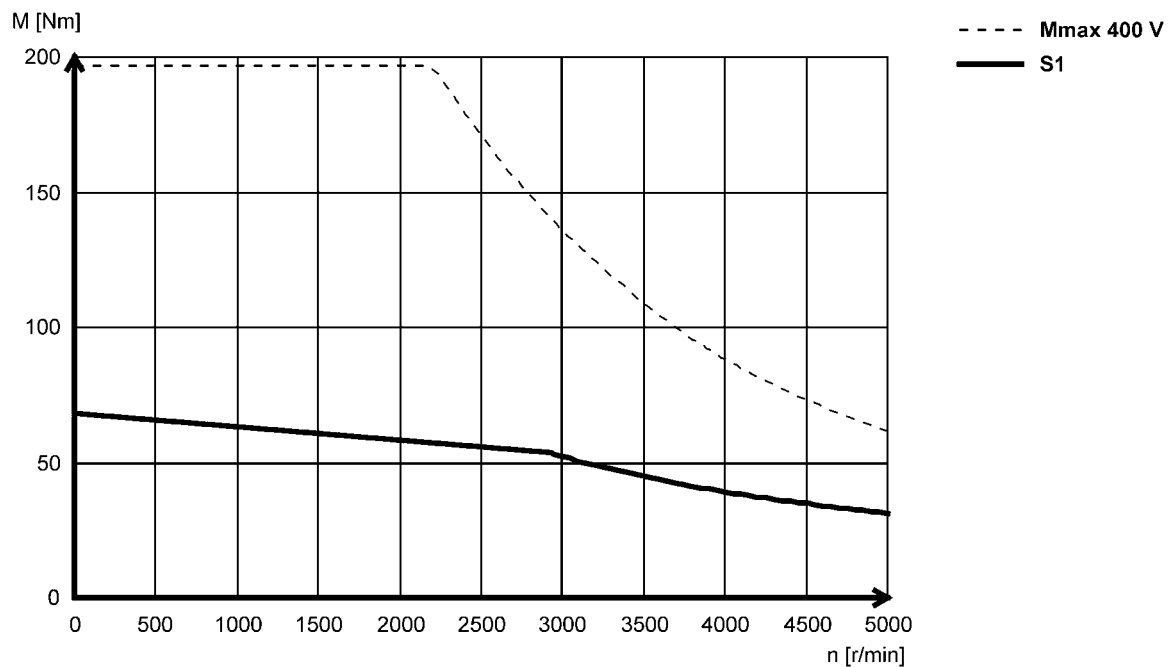
Torque characteristics

Mains connection 3x 400 V

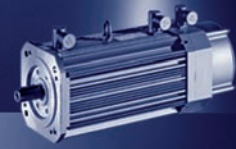
MCA20X14...2F□□



MCA20X29...2F□□

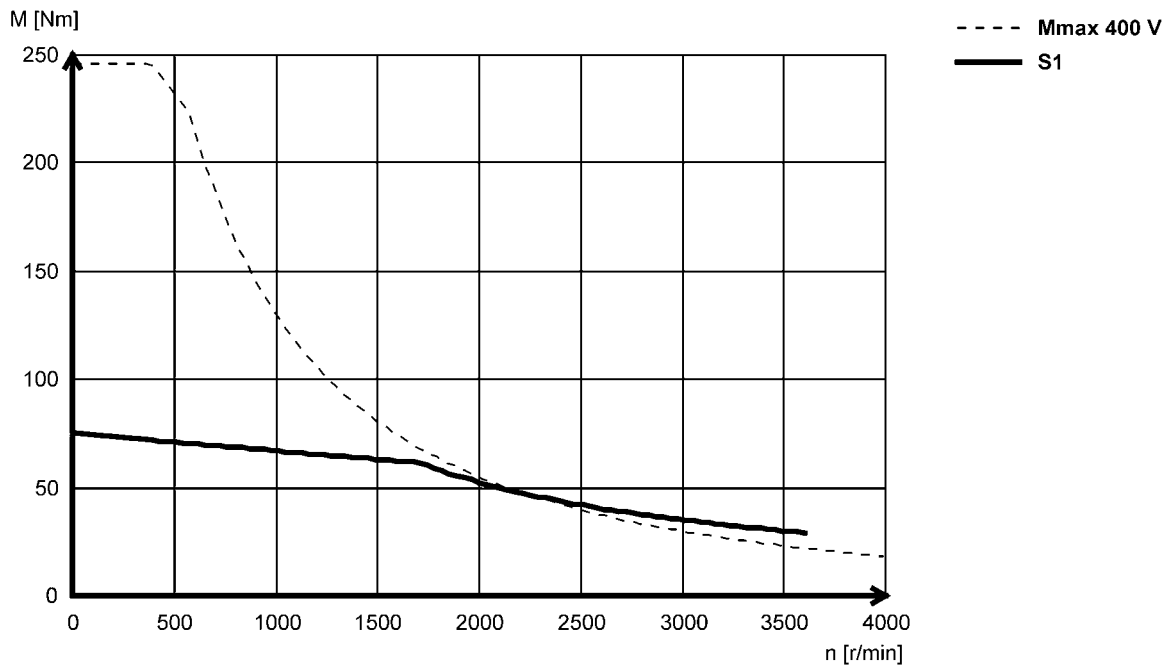


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

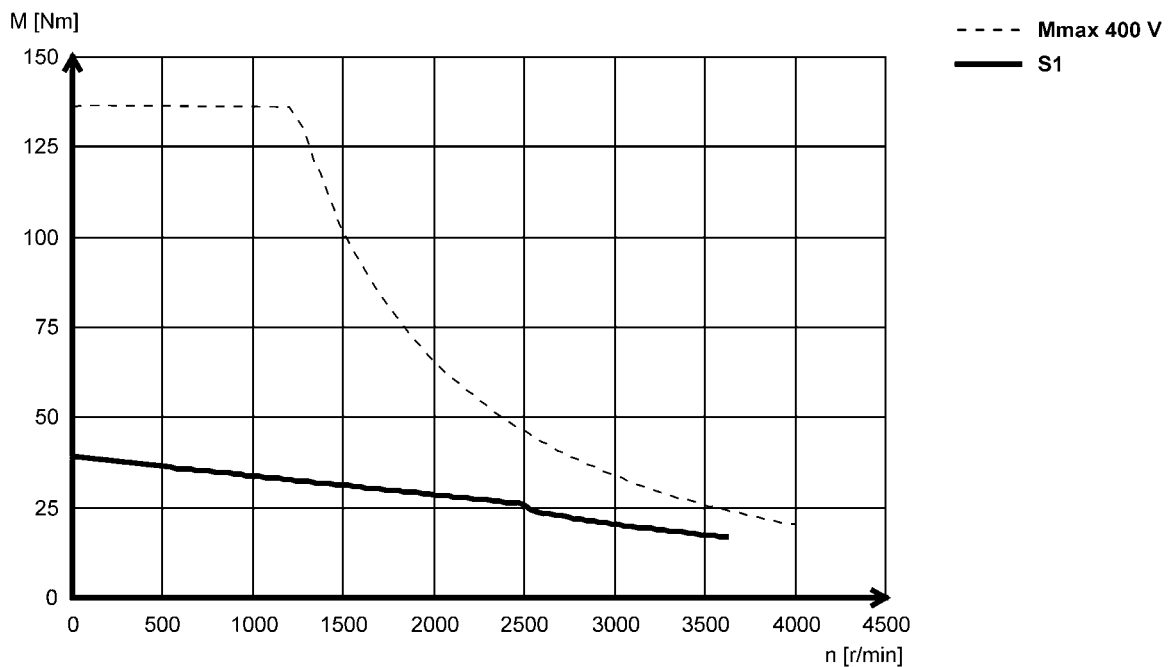


Mains connection 3x 400 V

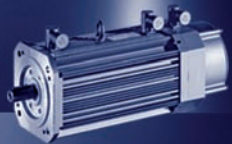
MCA21X17



MCA21X25



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

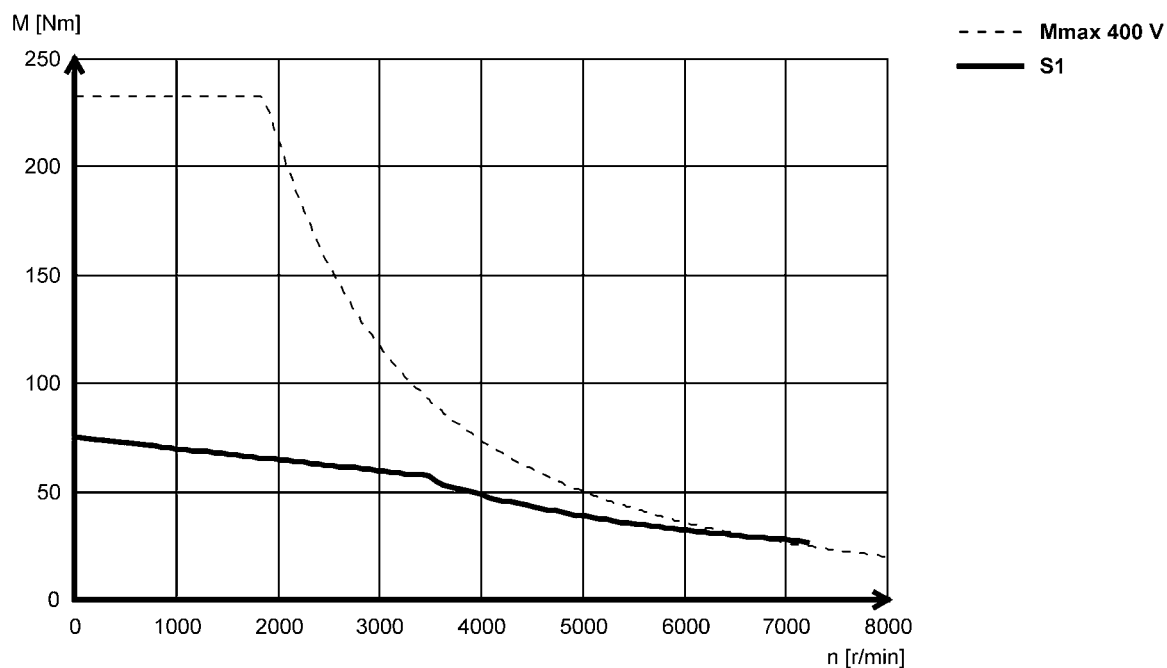


MCA asynchronous servo motors

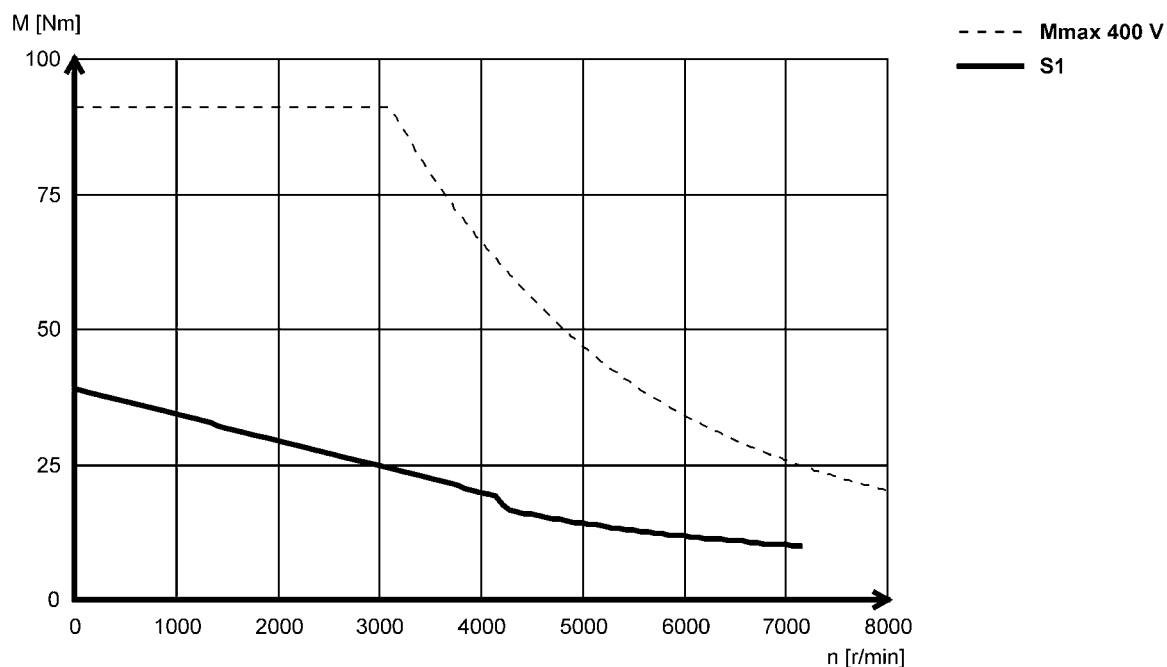
Torque characteristics

Mains connection 3x 400 V

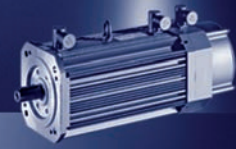
MCA21X35



MCA21X42

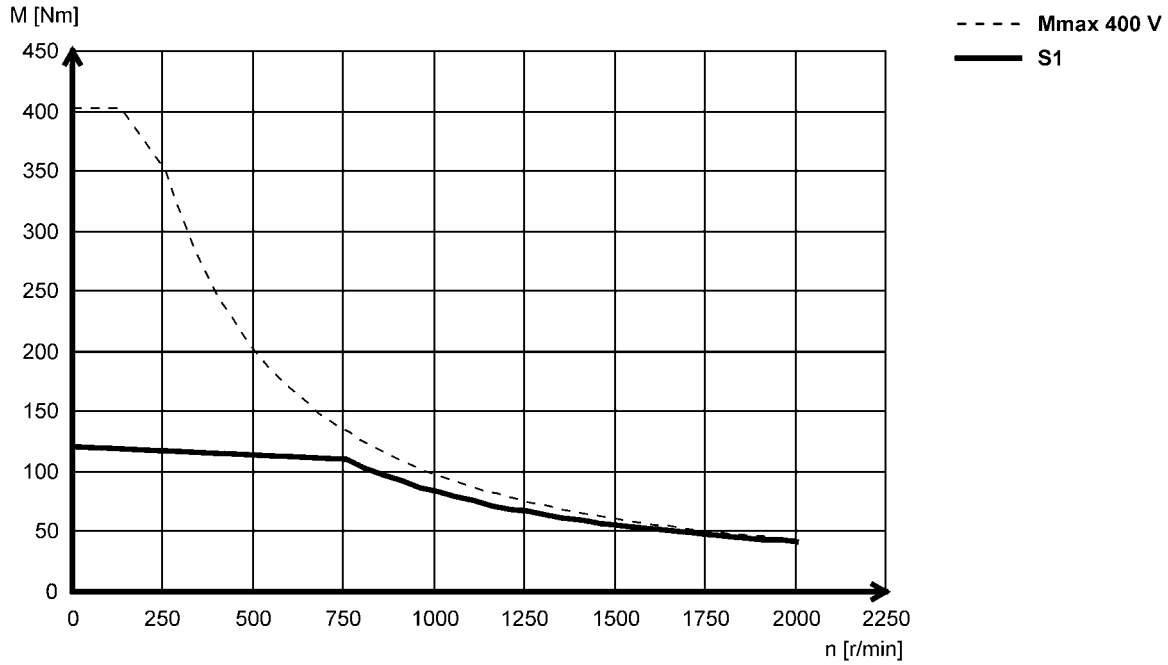


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

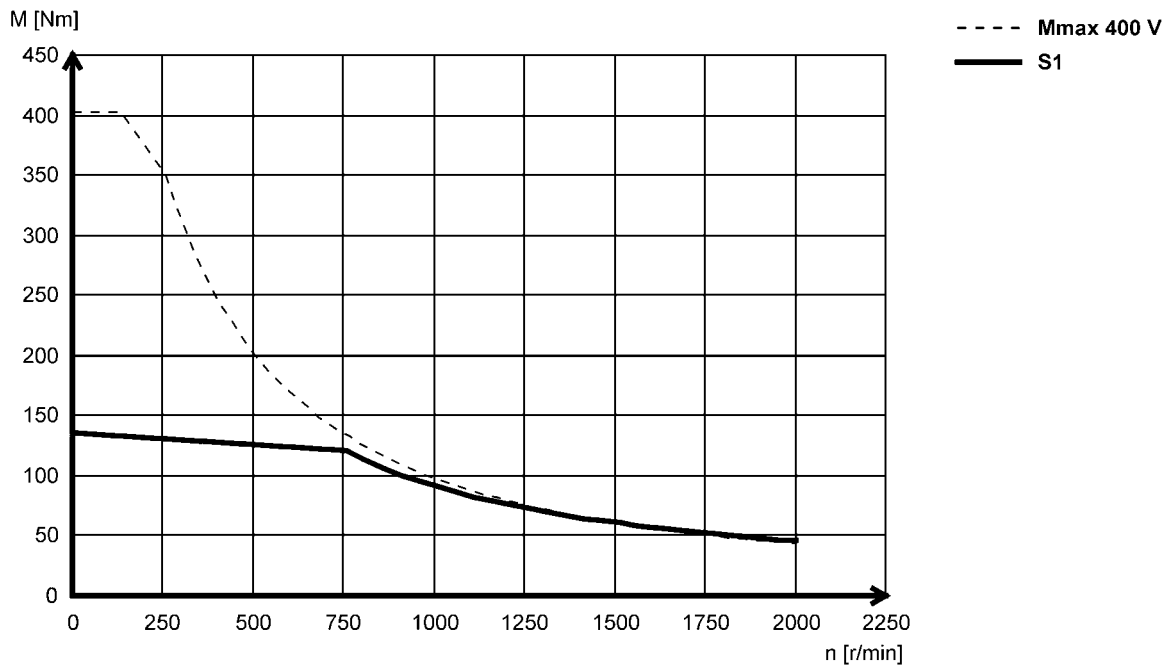


Mains connection 3x 400 V

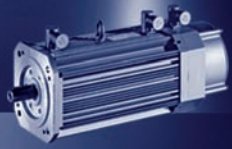
MCA22P08...5F□□



MCA22P08...2F□□



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

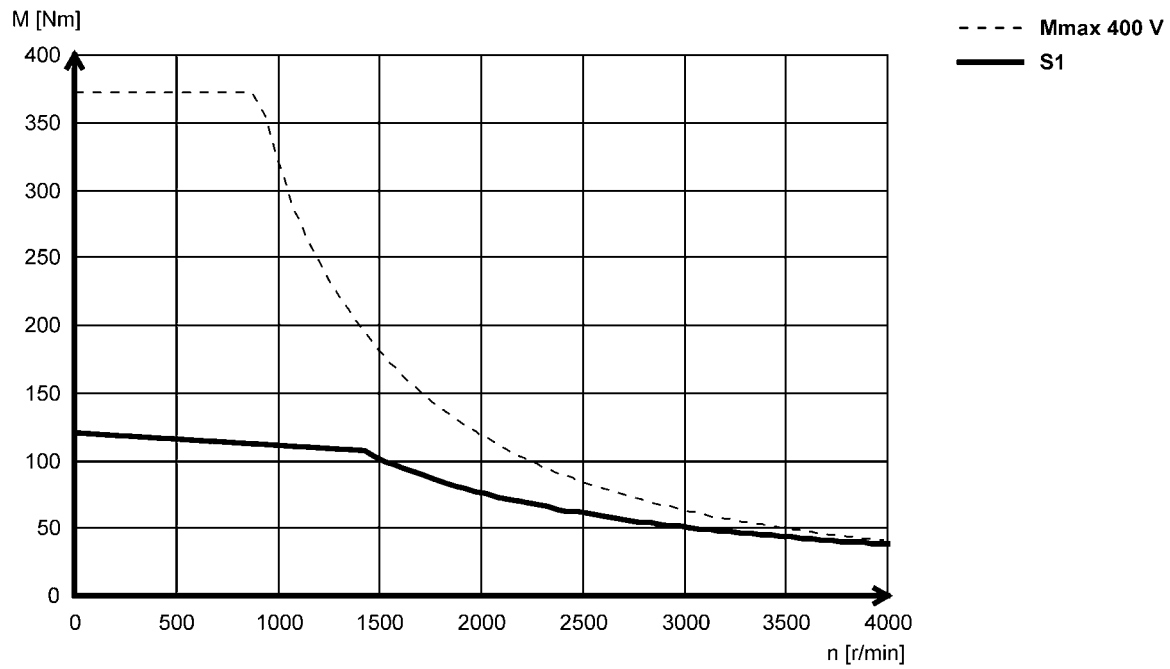


MCA asynchronous servo motors

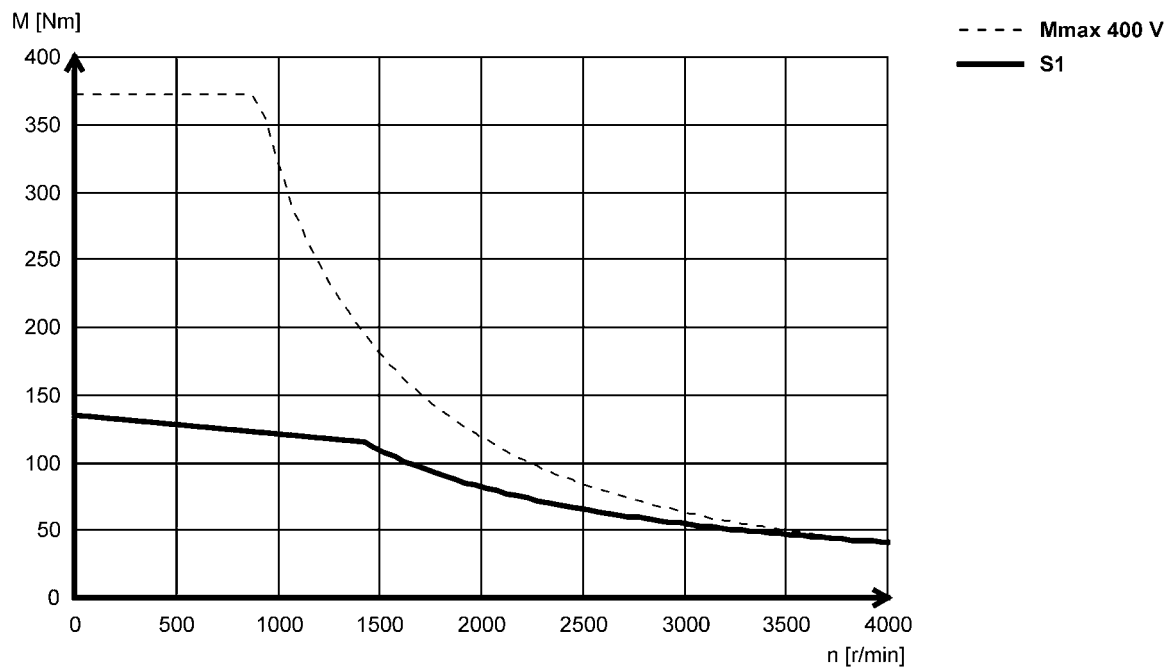
Torque characteristics

Mains connection 3x 400 V

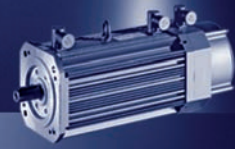
MCA22P14...5F□□



MCA22P14...2F□□

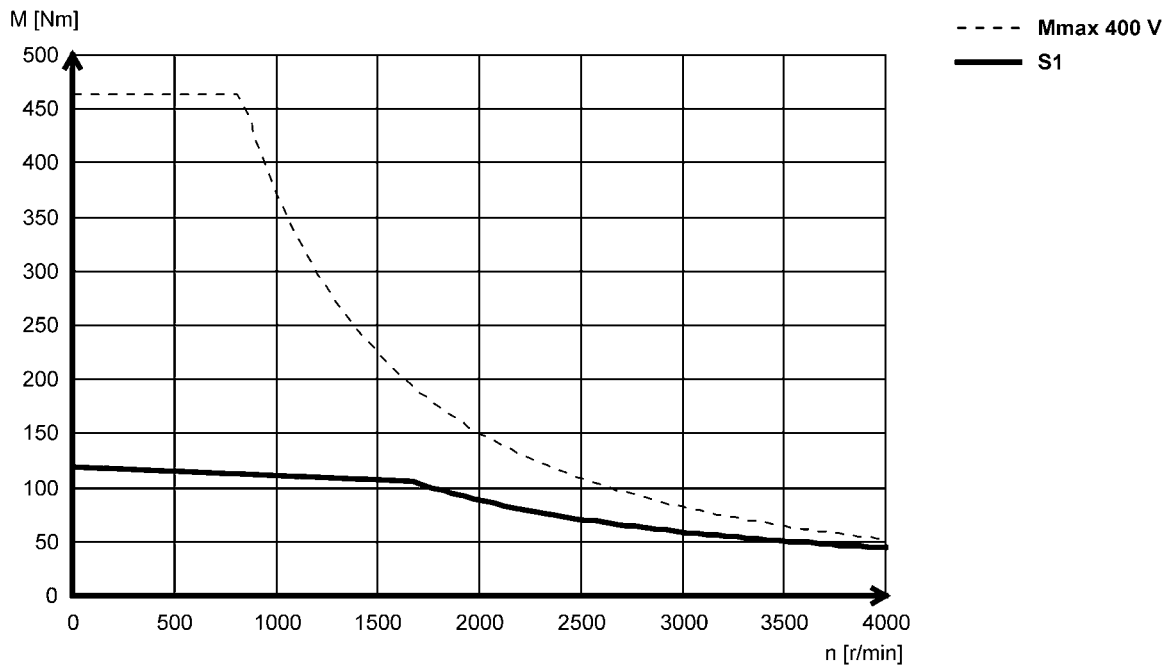


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

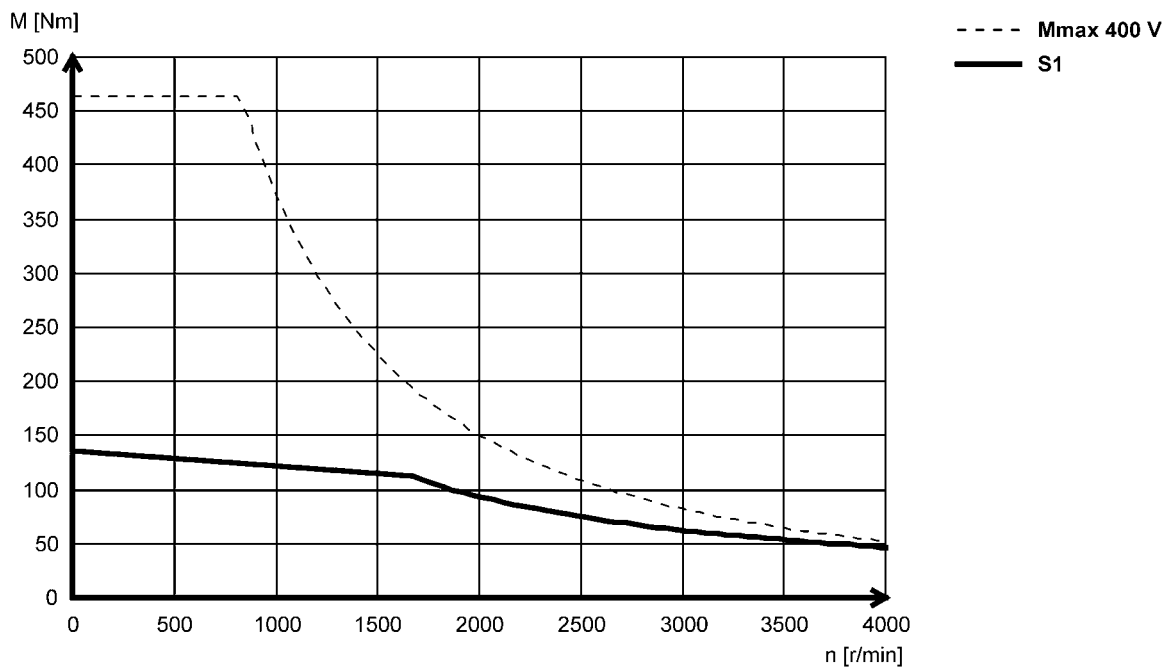


Mains connection 3x 400 V

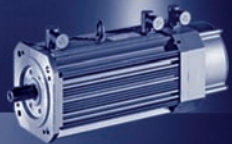
MCA22P17...5F□□



MCA22P17...2F□□



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

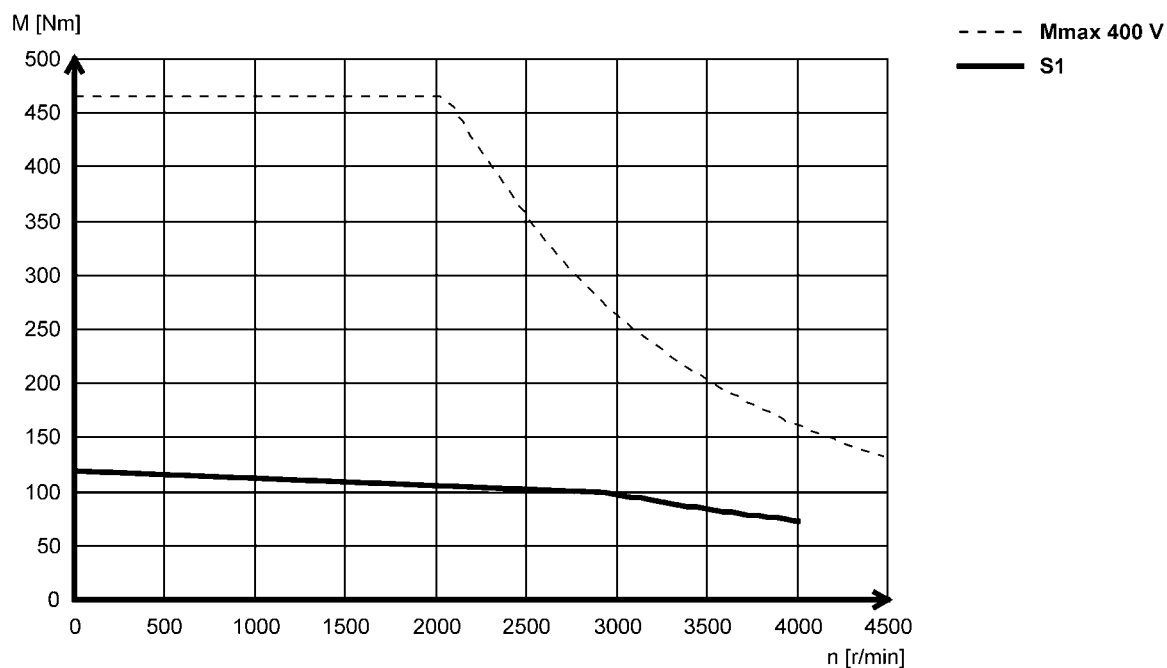


MCA asynchronous servo motors

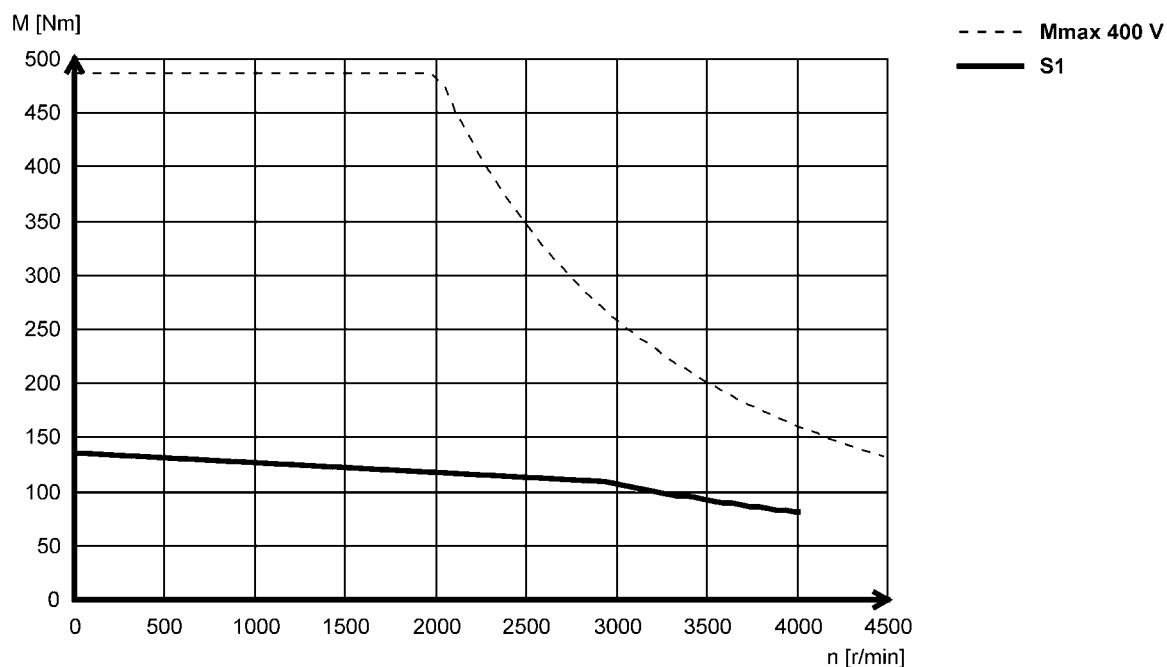
Torque characteristics

Mains connection 3x 400 V

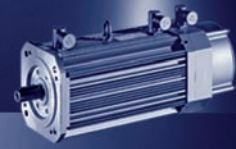
MCA22P29...5F□□



MCA22P29...2F□□

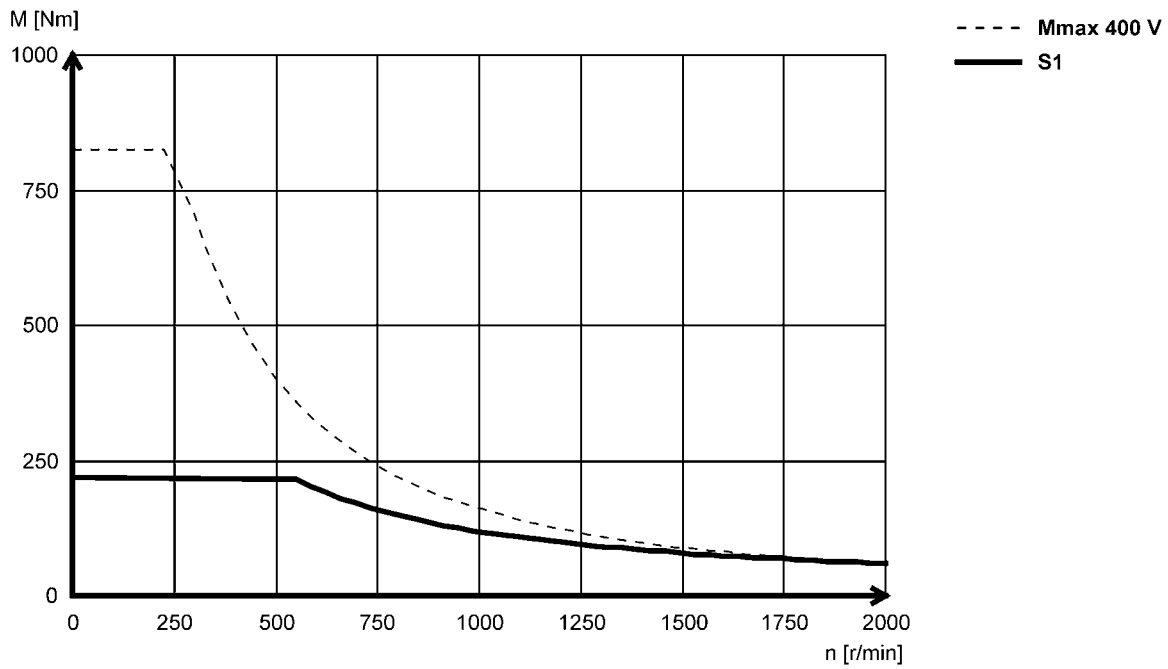


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

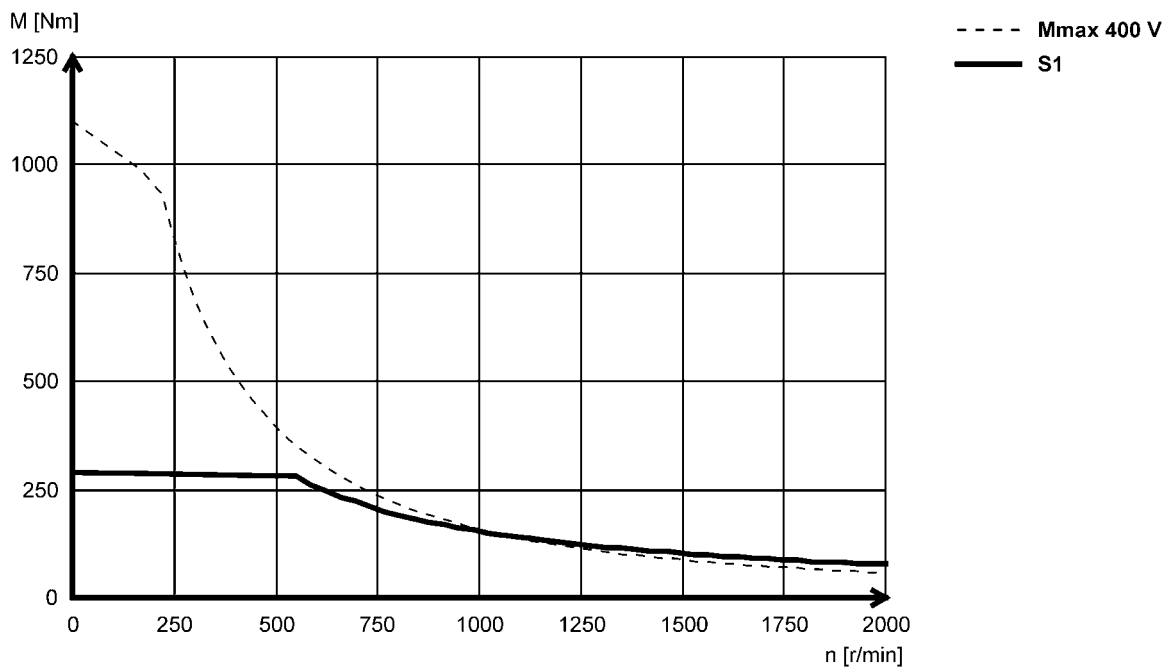


Mains connection 3x 400 V

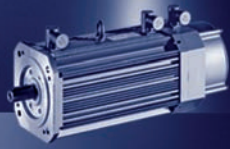
MCA26T05...5F□□



MCA26T05...2F□□



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

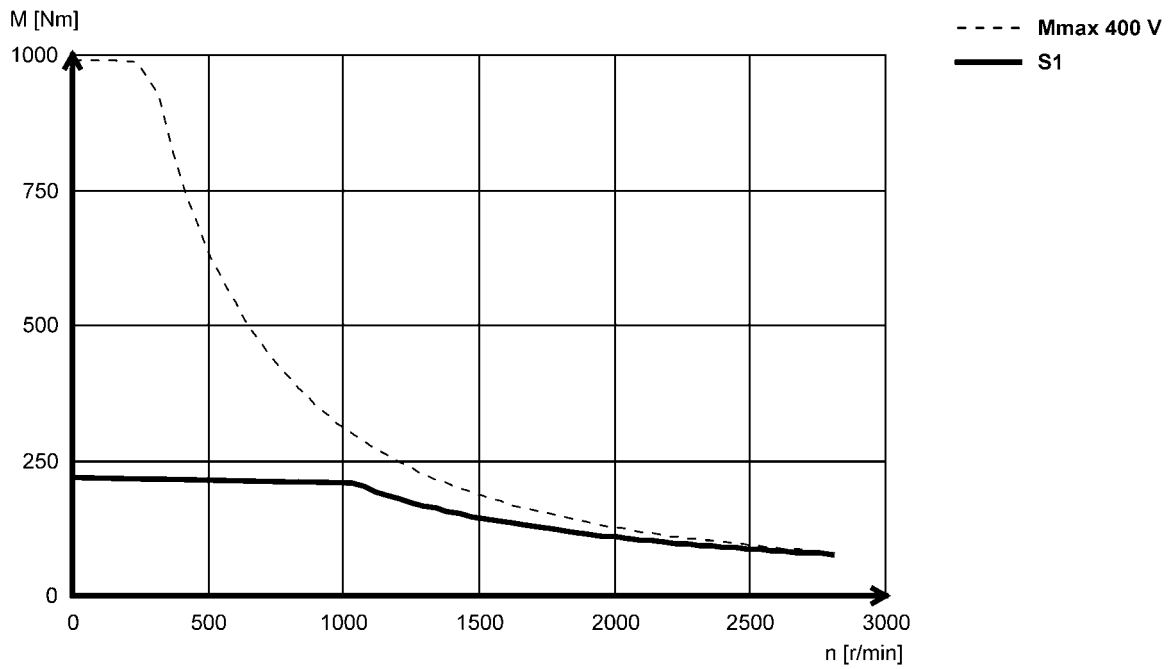


MCA asynchronous servo motors

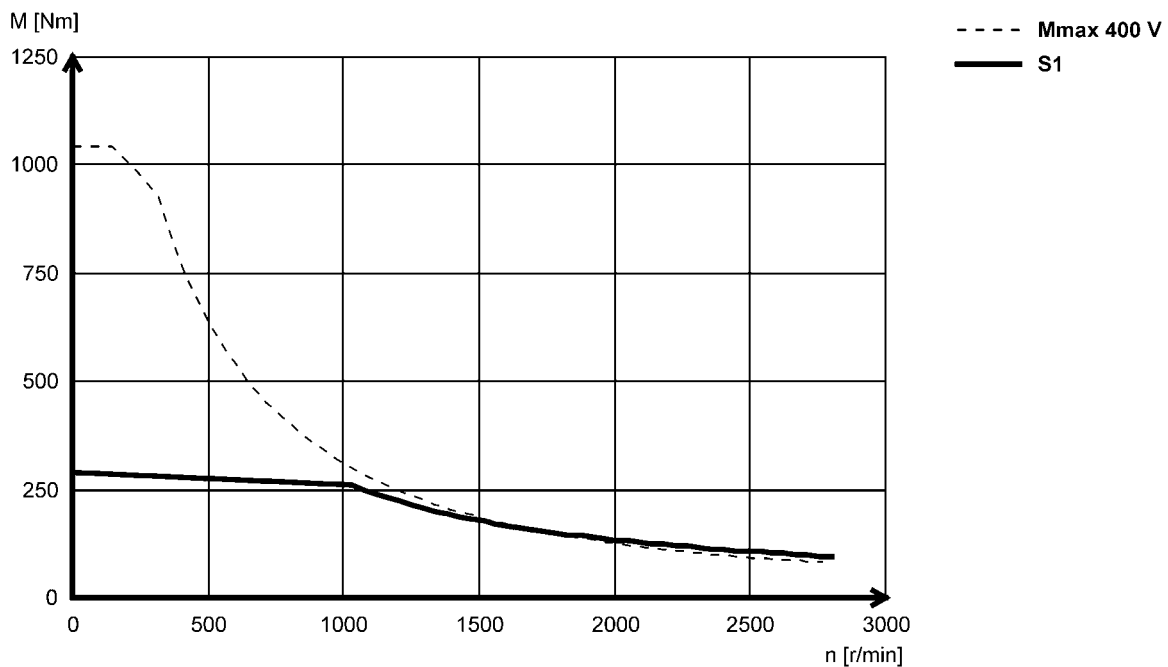
Torque characteristics

Mains connection 3x 400 V

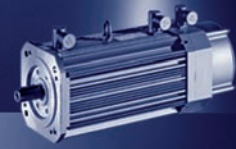
MCA26T10...5F□□



MCA26T10...2F□□

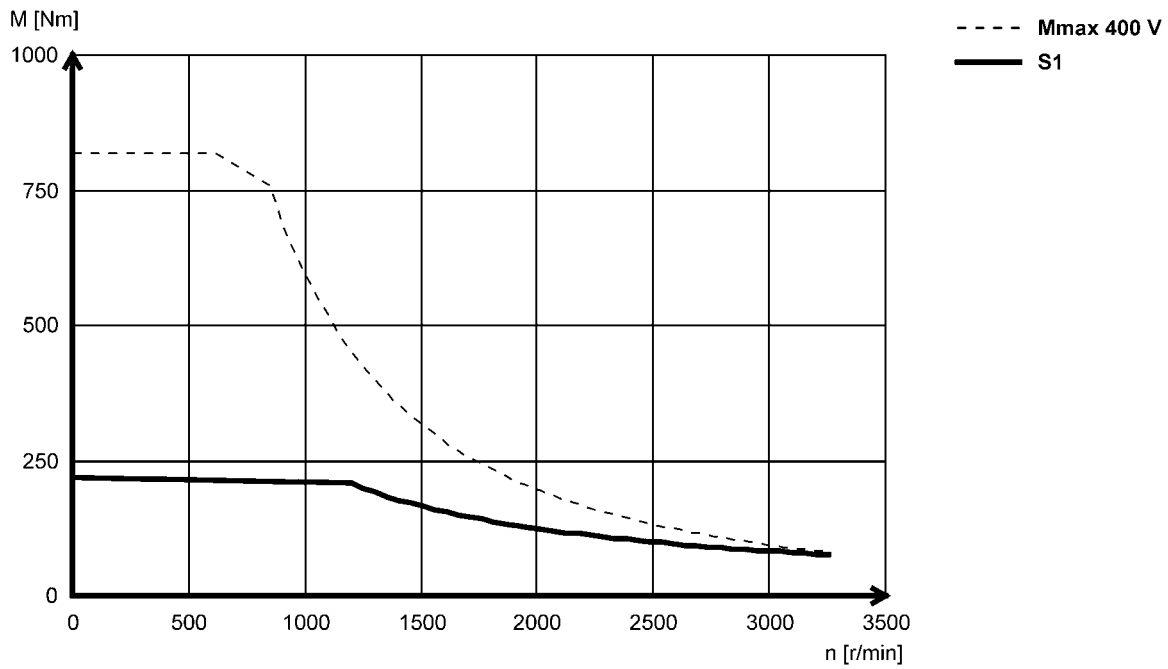


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

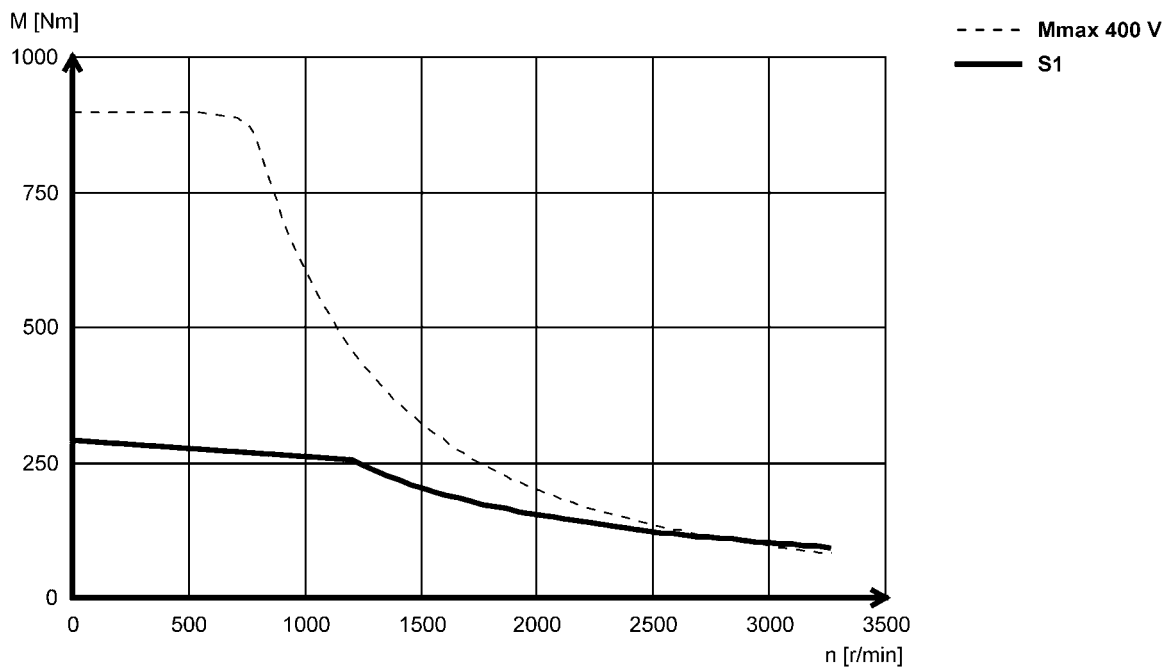


Mains connection 3x 400 V

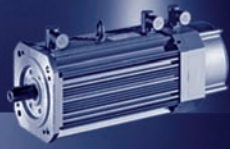
MCA26T12...5F□□



MCA26T12...2F□□



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

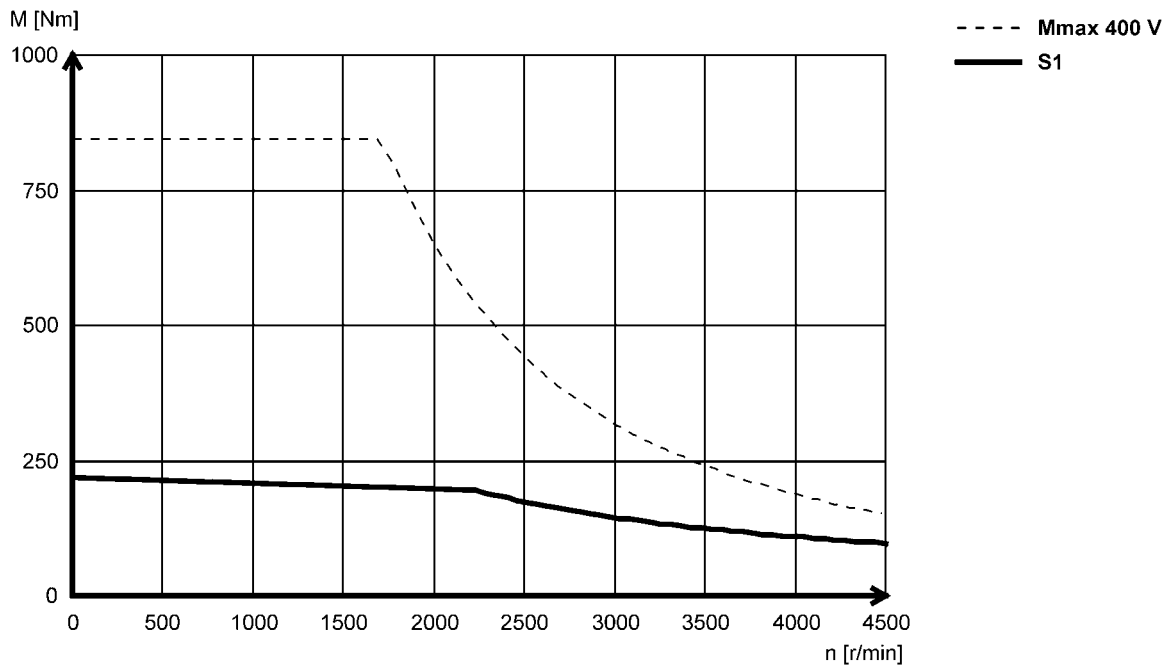


MCA asynchronous servo motors

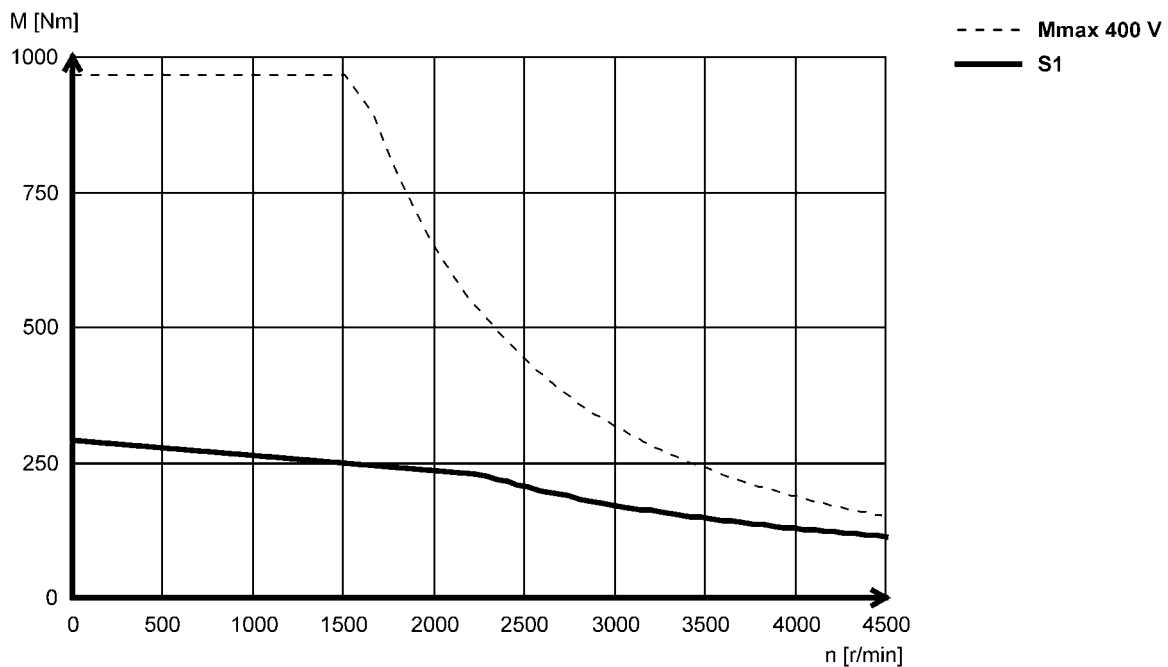
Torque characteristics

Mains connection 3x 400 V

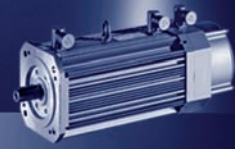
MCA26T22...5F□□



MCA26T22...2F□□



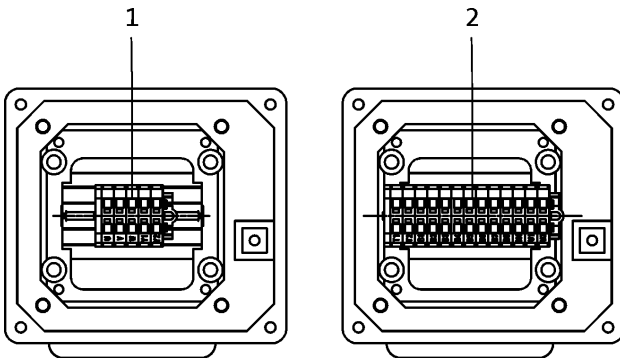
► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.



Motor connection terminal box

If a servo motor is to be connected to an existing cable or plug connectors are not to be used for other reasons, the connection can also be made via a terminal box.

The motor can either be fitted with a terminal box for the power connection and motor holding brake or a second terminal box provided to connect the motor feedback and blower (if applicable).

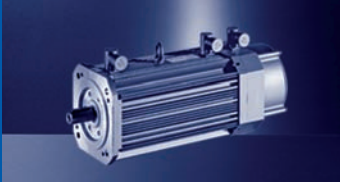


1: Power connection + brake connection + PE connection.

2: Angle/speed sensor connection + thermal sensor connection



MCA asynchronous servo motors with blower and terminal box



MCA asynchronous servo motors

Accessories

Holding brakes

The MCA10...19 and 21 asynchronous servo motors can be equipped with integral permanent magnet holding brakes. The brake voltage available for this model is 24 V DC or 205 V DC.

Spring-applied holding brakes with voltages of 24 V DC or 230 V AC are available for MCA20, 22 and 26.

The brakes are active once the supply voltage is switched off (closed-circuit principle).

With traversing axes, maintaining the permissible mass inertia ratio J_L/J_{MB} ensures that the permissible maximum switching energy of the brake is not exceeded and at least 2000 emergency stop functions are possible when running at a speed of 3000 r/min.

With lifting axes, the load torque resulting from the force due to weight comes into play as an additional factor. In this case, the data specified for J_L/J_{MB} does not apply.

Caution:

The brakes used are not safety brakes in the sense that a reduction in torque may arise as a result of disruptive factors that cannot be influenced, e.g. oil ingress.

The ohmic voltage drop along the cable must be taken into consideration in long motor supply cables and must be compensated for by a higher voltage at the line input.

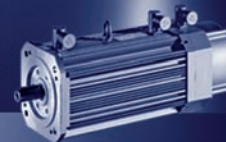
The following applies for Lenze system cables:

$$U[V] = U_B[V] + 0.08 \frac{[V]}{[A] \cdot [m]} \cdot l_{lg}[m] \cdot I_B[A]$$

If no suitable voltage (incorrect value, incorrect polarity) is applied to the brake, the brake will be applied and can be overheated and destroyed by the motor continuing to rotate. The shortest switching times of the brakes are achieved by DC switching of the voltage. A spark suppressor is required to suppress interference and to increase the service life of the relay contacts here.



Permanent magnet holding brake



Holding brake data

- ▶ The ratings apply only for servo motors and for geared servo motors if the servo motor is mounted by way of a mounting flange.

B5 / B14 design servo motors GPA servo geared motors

| | $U_{N,DC}^{3,4,7)}$ | $U_{N,AC}^{5,7)}$ | M_N | M_N | M_{av} | $I_N^{2)}$ | J | $t_1^{1)}$ | $t_2^{1)}$ | $Q_E^{6)}$ | m | J_{MB} | J_L / J_{MB} |
|--------------|---------------------|-------------------|-------|--------|----------|------------|----------------------|------------|------------|------------|------|----------------------|----------------|
| | [V] | [V] | 20 °C | 120 °C | 120 °C | [A] | [kgcm ²] | [ms] | [ms] | [J] | [kg] | [kgcm ²] | |
| MCA10 | 24 | 230 | 3.30 | 2.50 | 1.20 | 0.50 | 0.38 | 10.0 | 20.0 | 350 | 0.90 | 2.78 | 24.5 |
| | 205 | | | | | 0.060 | | | | | | | |
| MCA13 | 24 | | 12.0 | 11.0 | 5.50 | 0.67 | 1.06 | 20.0 | 29.0 | 400 | 0.80 | 9.36 | 7.70 |
| | 205 | | | | | 0.080 | | | | | | | |
| MCA14 | 24 | | 15.0 | 12.0 | 6.00 | 0.75 | 3.60 | 13.0 | 30.0 | 700 | 1.50 | 22.8 | 5.20 |
| | 205 | | | | | 0.090 | | | | | | | |
| MCA17 | 24 | | 24.0 | 22.0 | 11.0 | 0.75 | 9.50 | 25.0 | 50.0 | 1200 | 39.6 | 5.10 | |
| | 205 | | | | | 0.090 | | | | | | | |
| MCA19 | 24 | | 46.0 | 40.0 | 18.0 | 1.00 | 6.88 | 70.0 | 220 | 18000 | 13.0 | 177 | 19.6 |
| | 205 | | | | | 0.12 | | | | | | | |
| MCA20 | 24 | | 90.0 | 80.0 | 50.0 | 3.13 | 31.8 | 53.0 | 97.0 | 2800 | 5.00 | 212 | 1.70 |
| MCA21 | 24 | | | | | 1.46 | | | | | | | |
| | 205 | | 0.18 | | | | | | | | | | |
| MCA22 | 24 | | 150 | 130 | 80.0 | 3.75 | 18.1 | 50.0 | 260 | 23000 | 20.5 | 505 | 8.20 |
| | 230 | 0.44 | | | | | | | | | | | |
| MCA26 | 24 | 300 | 260 | 160 | 3.75 | 36.3 | 175 | 320 | 39000 | 26.0 | 1405 | 12.7 | |
| | 230 | | | | 0.37 | | | | | | | | 70.4 |

- ¹⁾ Engagement and disengagement times are valid for rated voltage ($\pm 0\%$) and protective circuit for brakes with varistor for DC switching. The times may increase without a protective circuit.
- ²⁾ The currents are the maximum values when the brake is cold (value used for dimensioning the current supply). The values for a motor at operating temperature are considerably lower.
- ³⁾ With 24 V DC brake: smoothed DC voltage, ripple $\leq 1\%$.
With 205 V DC brake: connection to 230 V AC through rectifier.
- ⁴⁾ UR not possible in the case of a brake with a 205 V supply voltage.
- ⁵⁾ UR not possible in the case of a brake with 230 V supply voltage.
- ⁶⁾ Maximum switching energy per emergency stop at $n = 3000$ r/min for at least 2000 emergency stops.
- ⁷⁾ Voltage tolerance: permanent magnet brakes -10 ... 5 %
spring-applied brakes $\pm 10\%$



MCA asynchronous servo motors

Accessories

Holding brake data, reinforced design

| | U _{N, DC} ^{3, 4, 7)} | U _{N, AC} ^{5, 7)} | M _N | M _N | M _{av} | I _N ²⁾ | J | t ₁ ¹⁾ | t ₂ ¹⁾ | Q _E ⁶⁾ | m | J _{MB} | J _L / J _{MB} |
|-------|--|-------------------------------------|----------------|----------------|-----------------|------------------------------|----------------------|------------------------------|------------------------------|------------------------------|------|----------------------|----------------------------------|
| | | | 20 °C | 120 °C | 120 °C | | | | | | | | |
| | [V] | [V] | [Nm] | [Nm] | [Nm] | [A] | [kgcm ²] | [ms] | [ms] | [J] | [kg] | [kgcm ²] | |
| MCA20 | 24 | 230 | 150 | 130 | 100 | 2.58 | 14.1 | 70.0 | 240 | 31000 | 15.4 | 189 | 33.0 |
| | 0.30 | | | | | | | | | | | | |
| MCA22 | 24 | 230 | 300 | 260 | 160 | 3.75 | 36.3 | 175 | 320 | 39000 | 26.0 | 523 | 14.1 |
| | 0.44 | | | | | 130 | | 310 | | | | | |
| MCA26 | 24 | 230 | 500 | 430 | 260 | 3.75 | 70.4 | 175 | 390 | 51000 | 30.8 | 1405 | 12.7 |
| | 0.44 | | | | | | | | | | | | |

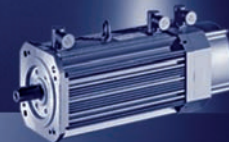
Holding brake data

- These ratings apply only for geared servo motors with integrated servo motor (without mounting flange).

GST, GFL, GKR, GKS, GSS geared servo motors

| | U _{N, DC} ^{3, 4, 7)} | M _N | M _N | M _{av} | I _N ²⁾ | J | t ₁ ¹⁾ | t ₂ ¹⁾ | Q _E ⁶⁾ | m | J _{MB} | J _L / J _{MB} |
|-------|--|----------------|----------------|-----------------|------------------------------|----------------------|------------------------------|------------------------------|------------------------------|------|----------------------|----------------------------------|
| | | 20 °C | 120 °C | 120 °C | | | | | | | | |
| | [V] | [Nm] | [Nm] | [Nm] | [A] | [kgcm ²] | [ms] | [ms] | [J] | [kg] | [kgcm ²] | |
| MCA10 | 24 | 6.00 | 5.00 | 2.50 | 0.67 | 1.06 | 20.0 | 29.0 | 400 | 0.80 | 3.46 | 22.4 |
| | 205 | | | | 0.80 | | | | | | | |
| MCA13 | 24 | 15.0 | 12.0 | 6.00 | 0.75 | 3.60 | 13.0 | 30.0 | 700 | 1.50 | 11.9 | 8.40 |
| | 205 | | | | 0.090 | | | | | | | |
| MCA14 | 24 | 23.0 | 20.0 | 20.0 | 0.92 | 9.50 | 18.0 | 55.0 | 1350 | 2.40 | 22.8 | 6.60 |
| | 205 | | | | 0.12 | | | | | | | |
| MCA17 | 24 | 23.0 | 20.0 | 20.0 | 0.92 | 9.50 | 18.0 | 55.0 | 1350 | 2.40 | 45.5 | 5.00 |
| | 205 | | | | 0.12 | | | | | | | |
| MCA19 | 24 | 48.0 | 40.0 | 35.0 | 1.46 | 31.8 | 30.0 | 100 | 2800 | 4.80 | 104 | 4.50 |
| | 205 | | | | 0.18 | | | | | | | |
| MCA21 | 24 | 88.0 | 80.0 | 35.0 | 1.46 | 31.8 | 53.0 | 97.0 | 2800 | 5.00 | 212 | 1.70 |
| | 205 | | | | 0.18 | | | | | | | |

- 1) Engagement and disengagement times are valid for rated voltage (± 0 %) and protective circuit for brakes with varistor for DC switching. The times may increase without a protective circuit.
- 2) The currents are the maximum values when the brake is cold (value used for dimensioning the current supply). The values for a motor at operating temperature are considerably lower.
- 3) With 24 V DC brake: smoothed DC voltage, ripple ≤ 1 %.
With 205 V DC brake: connection to 230 V AC through rectifier.
- 4) UR not possible in the case of a brake with a 205 V supply voltage.
- 5) UR not possible in the case of a brake with 230 V supply voltage.
- 6) Maximum switching energy per emergency stop at n = 3000 r/min for at least 2000 emergency stops.
- 7) Voltage tolerance: permanent magnet brakes -10 ... 5 %
spring-applied brakes ±10 %

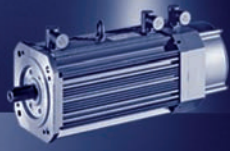


Blower data 50 Hz

| | | Enclosure | Number of phases | | | | | |
|-------|------------|-----------|------------------|-----------|-----------|-------------|-------|-------|
| | | | | U_{min} | U_{max} | $U_{N, AC}$ | P_N | I_N |
| | | | | [V] | [V] | [V] | [kW] | [A] |
| MCA13 | F10 | IP54 | 1 | 210 | 240 | 230 | 0.019 | 0.12 |
| MCA14 | | | | | | | 0.040 | 0.25 |
| MCA17 | | | | | | | 0.17 | 0.73 |
| MCA19 | | | | | | | 0.060 | 0.26 |
| MCA20 | F10 F1F | IP23s | | | 250 | | 0.24 | 1.05 |
| MCA21 | F10 | IP54 | | | 240 | | 0.40 | 1.75 |
| MCA22 | F10 | IP23s | | | 250 | | | |
| MCA26 | F1F | IP54 | | | | | | |

Blower data 60 Hz

| | | Enclosure | Number of phases | | | | | |
|-------|------------|-----------|------------------|-----------|-----------|-------------|-------|-------|
| | | | | U_{min} | U_{max} | $U_{N, AC}$ | P_N | I_N |
| | | | | [V] | [V] | [V] | [kW] | [A] |
| MCA13 | F10 | IP54 | 1 | 210 | 240 | 230 | 0.019 | 0.12 |
| MCA14 | | | | | | | 0.040 | 0.25 |
| MCA17 | | | | | | | 0.20 | 0.90 |
| MCA19 | | | | | | | 0.060 | 0.26 |
| MCA20 | F10 F1F | IP23s | | | 250 | | 0.28 | 1.23 |
| MCA21 | F10 | IP54 | | | 240 | | 0.41 | 1.82 |
| MCA22 | F10 | IP23s | | | 250 | | | |
| MCA26 | F1F | IP54 | | | | | | |



MCA asynchronous servo motors


Accessories

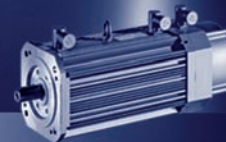
Tailored to meet the requirements of the various applications and necessary accuracies, the following feedback systems are available.

Resolver

Stator-fed resolver with two stator windings offset by 90° and one rotor winding with transformer winding.


| | | | | |
|-----------------------------------|---------------|-----------|---------|---------------------------------|
| Speed/angle sensor | ¹⁾ | | | RS0 |
| Resolution | | | [°] | 0.80 |
| Angle | | | [°] | -10 ... 10 |
| Accuracy | | | [°] | -10 ... 10 |
| Absolute positioning | | | | 1 revolution |
| Max. speed | n_{max} | | [r/min] | 8000 |
| Max. input voltage | $U_{in,max}$ | | [V] | 10.0 |
| DC | | | | |
| Max. input frequency | $f_{in,max}$ | | [kHz] | 4.00 |
| Ratio | | $\pm 5\%$ | | 0.30 |
| Stator / rotor | | | | |
| Rotor impedance | Z_{ro} | | [Ω] | 51 + j90 |
| Stator impedance | Z_{so} | | [Ω] | 102 + j150 |
| Impedance | Z_{rs} | | [Ω] | 44 + j76 |
| Min. insulation resistance | R | | [MΩ] | 10.0 |
| At DC 500 V | | | | |
| Number of pole pairs | | | | 1 |
| Max. angle error | | | [°] | -10 ... 10 |
| Inverter assignment | | | | E84AVTC E94A ECS EVS93 |

¹⁾ →  16 - Product key > speed/angle sensor

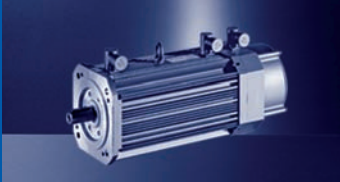


Incremental encoder and SinCos absolute value encoder

| Encoder type | | | TTL incremental | | SinCos incremental | SinCos absolute value | | | | |
|-----------------------------------|--------------|---------|---------------------------------|-------------|--------------------|-----------------------|---------------------------------|-------------|--------------|-------------|
| | | | T20 | T40 | S20 | EQI | SRS | SRM | ECN | EQN |
| Speed/angle sensor | 1) | | IG2048-5V-T | IG4096-5V-T | IG2048-5V-S | AM32-5V-E | AS1024-8V-H | AM1024-8V-H | AS2048-5V-E | AM2048-5V-E |
| Encoder type | | | | | Single-turn | Multi-turn | Single-turn | Multi-turn | Single-turn | Multi-turn |
| Pulses | | | 2048 | 4096 | 2048 | 32 | 1024 | | 2048 | |
| Output signals | | | TTL | | | 1 Vss | | | | |
| Interfaces | | | | | | EnDat | Hiperface | | EnDat | |
| Absolute revolutions | | | 0 | | | 4096 | 1 | 4096 | 1 | 4096 |
| Resolution Angle ²⁾ | | [°] | 2.60 | | | 0.40 | | | | |
| Accuracy | | [°] | -2 ... 2 | | -0.8 ... 0.8 | -5 ... 5 | -0.8 ... 0.8 | | -0.6 ... 0.6 | |
| Min. input voltage DC | $U_{in,min}$ | [V] | 4.75 | | 4.50 | 4.75 | 7.00 | | 4.75 | |
| Max. input voltage DC | $U_{in,max}$ | [V] | 5.25 | | 5.50 | 5.25 | 12.0 | | 5.25 | |
| Max. speed | n_{max} | [r/min] | 8789 | | 5273 | 12000 | 6000 | | 12000 | |
| Max. current consumption | I_{max} | [A] | 0.15 | | 0.10 | 0.17 | 0.080 | | 0.15 | 0.25 |
| Limit frequency | f_{max} | [kHz] | 300 | | 180 | 6.00 | 200 | | | |
| Inverter assignment | | | E84AVTC E94A ECS EVS93 | | | E94A | E84AVTC E94A ECS EVS93 | | E94A | |

1) →  16 - Product key > speed/angle sensor


2) Dependent on inverter.

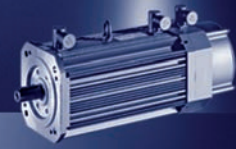


Safety SinCos incremental encoder

- ▶ Safe encoder thanks to integrated functional safety

| Encoder type | | | SinCos incremental |
|--|--------------|---------|---|
| Speed/angle sensor | 1) | | S1S |
| | | | IG1024-5V-V |
| Encoder type | | | Single-turn |
| Pulses | | | 1024 |
| Output signals | | | 1 Vss |
| Min. input voltage DC | $U_{in,min}$ | [V] | 4.75 |
| Max. input voltage DC | $U_{in,max}$ | [V] | 5.25 |
| Max. speed | n_{max} | [r/min] | 8000 |
| Max. current consumption | I_{max} | [A] | 0.070 |
| Limit frequency | f_{max} | [kHz] | 200 |
| Functional safety EN 13849-1 EN 954-1 IEC 61508 | | | Up to Performance Level e Category 4 SIL3 |
| Inverter assignment | | | E94A |

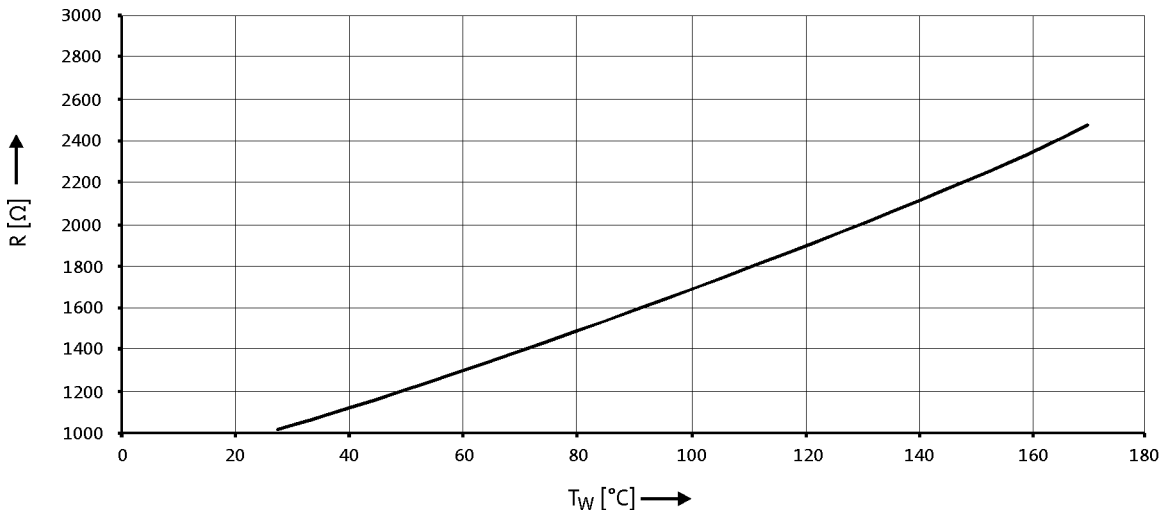
1) →  16 - Product key > speed/angle sensor



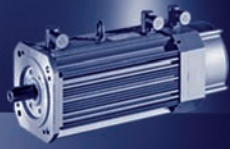
Thermal sensor

The thermal sensors (1x KTY 83-110) used continuously monitor the motor temperature. The temperature signal is transmitted over the system cable of the feedback system to the servo controller.

This means that the temperature of the motor is determined with great accuracy in the permitted operating range and at the same time the overtemperature response configured in the controller is executed in the event of overtemperature in one of the winding phases.



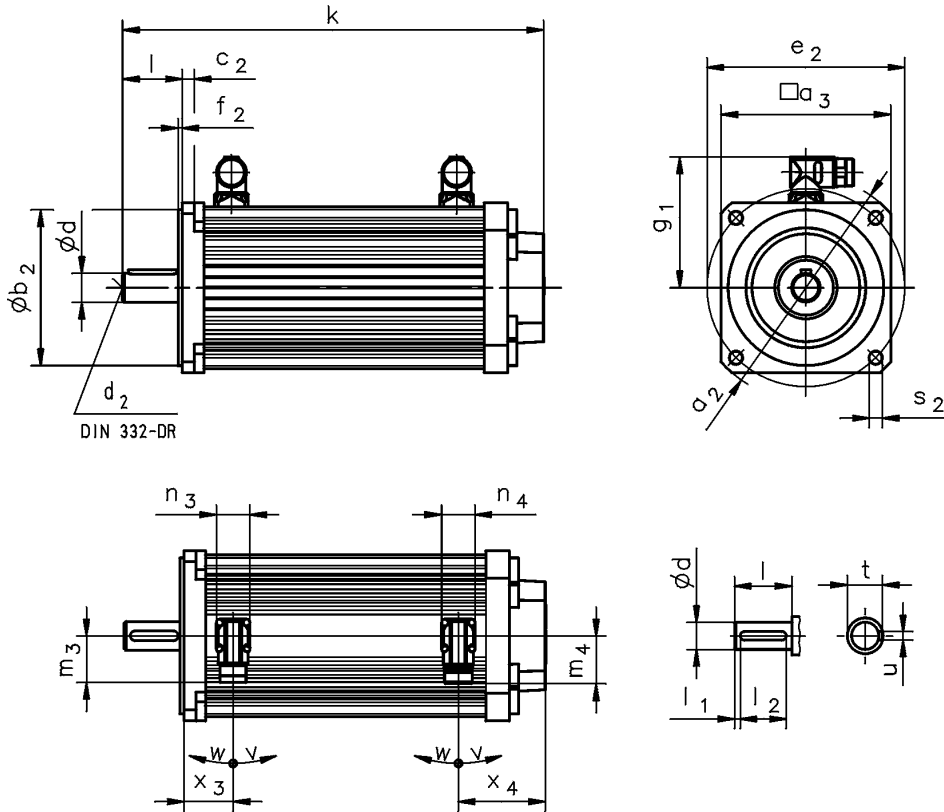
- If the detector is supplied with a measured current of 1 mA, the above relationship between the temperature and the resistance applies.



MCA asynchronous servo motors

Dimensions [mm]

Motors without blower

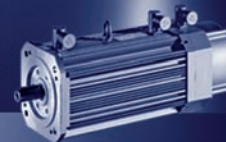


| | | | MCA10I40 | MCA13I41 | MCA14L20 | MCA17N23 | MCA19S23 | MCA21X25 |
|----------------------|----------------|------|----------|----------|----------|----------|----------|----------|
| | | | | | MCA14L41 | MCA17N41 | MCA19S42 | MCA21X42 |
| RSO B0 | k | [mm] | 292 | 311 | 352 | 390 | 461 | 550 |
| | x ₃ | [mm] | 37 | 45 | 41 | 43 | 56 | 62 |
| | x ₄ | [mm] | 61 | 65 | 73 | | 78 | |
| RSO P□ | k | [mm] | 317 | 346 | 385 | 425 | 499 | 592 |
| | x ₃ | [mm] | 59 | 72 | 68 | 75 | 91 | 102 |
| | x ₄ | [mm] | 61 | 65 | 73 | | 78 | |
| S□□ / E□□ / T20 / B0 | k | [mm] | 346 | 365 | 407 | 444 | 511 | 599 |
| | x ₃ | [mm] | 37 | 45 | 41 | 43 | 56 | 62 |
| | x ₄ | [mm] | 115 | 119 | 128 | 127 | 123 | 127 |
| S□□ / E□□ / T20 / P□ | k | [mm] | 371 | 400 | 440 | 479 | 549 | 641 |
| | x ₃ | [mm] | 59 | 72 | 68 | 75 | 91 | 102 |
| | x ₄ | [mm] | 115 | 119 | 128 | 127 | 123 | 127 |

- ▶ Speed/angle sensor: RSO / S□□ / E□□ / T20
- ▶ Brake: B0 / P□

MCA asynchronou servo motors

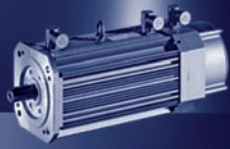
Dimensions [mm]



| | g_1 | n_3 | n_4 | m_3 | m_4 | v | w |
|----------|-------|-------|-------|-------|-------|-----|-----|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [°] | [°] |
| MCA10I40 | 90 | 28 | 28 | 40 | 40 | 195 | 80 |
| MCA13I41 | 102 | | | | | | |
| MCA14L20 | 109 | | | | | | |
| MCA14L41 | 118 | | | | | | |
| MCA17N23 | 118 | 40 | 71 | 71 | 71 | 195 | 80 |
| MCA17N41 | 151 | | | | | | |
| MCA19S23 | 151 | | | | | | |
| MCA19S42 | 162 | | | | | | |
| MCA21X25 | 162 | | | | | | |
| MCA21X42 | | | | | | | |

| | d | d_2 | l | l_1 | l_2 | u | t |
|-------|------|-------|------|-------|-------|------|------|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MCA10 | 14 | M5 | 30 | 2.5 | 25 | 5.0 | 16 |
| MCA13 | 19 | M6 | 40 | 2.0 | 36 | 6.0 | 22 |
| MCA14 | 24 | M8 | 50 | 5.0 | 40 | 8.0 | 27 |
| MCA17 | | | | | 50 | | 31 |
| MCA19 | 28 | M10 | 60 | | 70 | 10.0 | 41 |
| MCA21 | 38 | M12 | 80 | | | | |

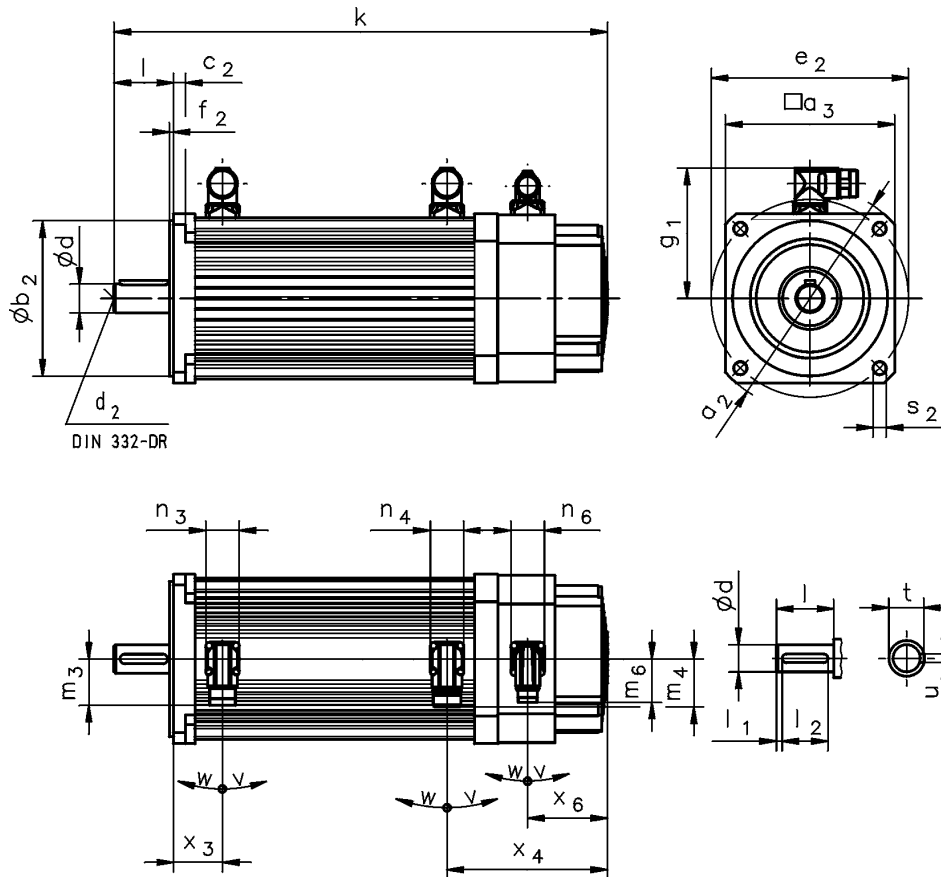
| | | a_2 | a_3 | b_2 | c_2 | e_2 | f_2 | s_2 |
|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MCA10 | FF100 | 120 | 102 | 80 | 8 | 100 | 3.0 | 7 |
| | FT85 | | | 70 | | 85 | 2.5 | M6 |
| MCA13 | FF130 | 160 | 130 | 110 | 9 | 130 | 3.5 | 9.0 |
| | FT130 | | | | | | | |
| MCA14 | FF165 | 188 | 142 | 130 | 10 | 165 | | 11.0 |
| | FT130 | | | 110 | | | | 130 |
| MCA17 | FF165 | 200 | 165 | 130 | 12 | 165 | 11.0 | |
| | FT130 | | | 110 | | | 130 | M8 |
| MCA19 | FF215 | 250 | 192 | 180 | 11 | 215 | 4.0 | 13.0 |
| | FT130 | | | 110 | | 130 | 3.5 | M8 |
| MCA21 | FF215 | 300 | 214 | 180 | 12 | 215 | 4.0 | 13.0 |
| | FF265 | | | 230 | | 265 | | |
| | FT130 | | | 110 | | 130 | 3.5 | M8 |



MCA asynchronous servo motors

Dimensions [mm]

Motors with blower, MCA13...19/21

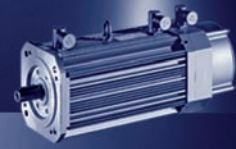


| | | | MCA13B4 | MCA14L16 | MCA17N17 | MCA19S17 | MCA21X17 |
|----------------------|----------------|------|---------|----------|----------|----------|----------|
| | | | | MCA14L35 | MCA17N35 | MCA19S35 | MCA21X35 |
| RSO B0 | k | [mm] | 379 | 414 | 476 | 558 | 646 |
| | x ₃ | [mm] | 45 | 41 | 43 | 56 | 62 |
| | x ₄ | [mm] | 133 | 135 | 159 | 170 | 174 |
| RSO P□ | k | [mm] | 414 | 447 | 511 | 596 | 688 |
| | x ₃ | [mm] | 72 | 68 | 75 | 91 | 102 |
| | x ₄ | [mm] | 133 | 135 | 159 | 170 | 174 |
| S□□ / E□□ / T20 / B0 | k | [mm] | 433 | 469 | 530 | 608 | 695 |
| | x ₃ | [mm] | 45 | 41 | 43 | 56 | 62 |
| | x ₄ | [mm] | 187 | 190 | 213 | 220 | 223 |
| S□□ / E□□ / T20 / P□ | k | [mm] | 468 | 502 | 565 | 646 | 737 |
| | x ₃ | [mm] | 72 | 68 | 75 | 91 | 102 |
| | x ₄ | [mm] | 187 | 190 | 213 | 220 | 223 |
| | x ₆ | [mm] | 73 | 67 | 94 | 103 | 96 |

- ▶ Speed/angle sensor: RSO / S□□ / E□□ / T20
- ▶ Brake: B0 / P□

MCA asynchronou servo motors

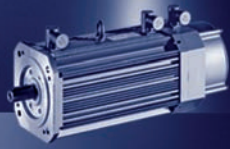
Dimensions [mm]



| | g_1 | n_3 | n_4 | n_6 | m_3 | m_4 | m_6 | v | w |
|----------|-------|-------|-------|-------|-------|-------|-------|-----|-----|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [°] | [°] |
| MCA13B4 | 102 | 28 | 28 | 28 | 40 | 40 | 37 | 195 | 80 |
| MCA14L16 | 109 | | | | | | | | |
| MCA14L35 | 118 | | | | | | | | |
| MCA17N17 | 118 | 40 | 28 | 28 | 71 | 40 | 37 | 195 | 80 |
| MCA17N35 | 151 | | | | | | | | |
| MCA19S17 | 151 | | | | | | | | |
| MCA19S35 | 162 | 40 | 28 | 28 | 71 | 40 | 37 | 195 | 80 |
| MCA21X17 | 162 | | | | | | | | |
| MCA21X35 | 162 | | | | | | | | |

| | d | d_2 | l | l_1 | l_2 | u | t |
|-------|------|-------|------|-------|-------|------|------|
| | k6 | | | | | | |
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MCA13 | 19 | M6 | 40 | 2.0 | 36 | 6.0 | 22 |
| MCA14 | 24 | M8 | 50 | 5.0 | 40 | 8.0 | 27 |
| MCA17 | | | | | 50 | | |
| MCA19 | 28 | M10 | 60 | | 70 | 10.0 | 31 |
| MCA21 | 38 | M12 | 80 | | | | 41 |

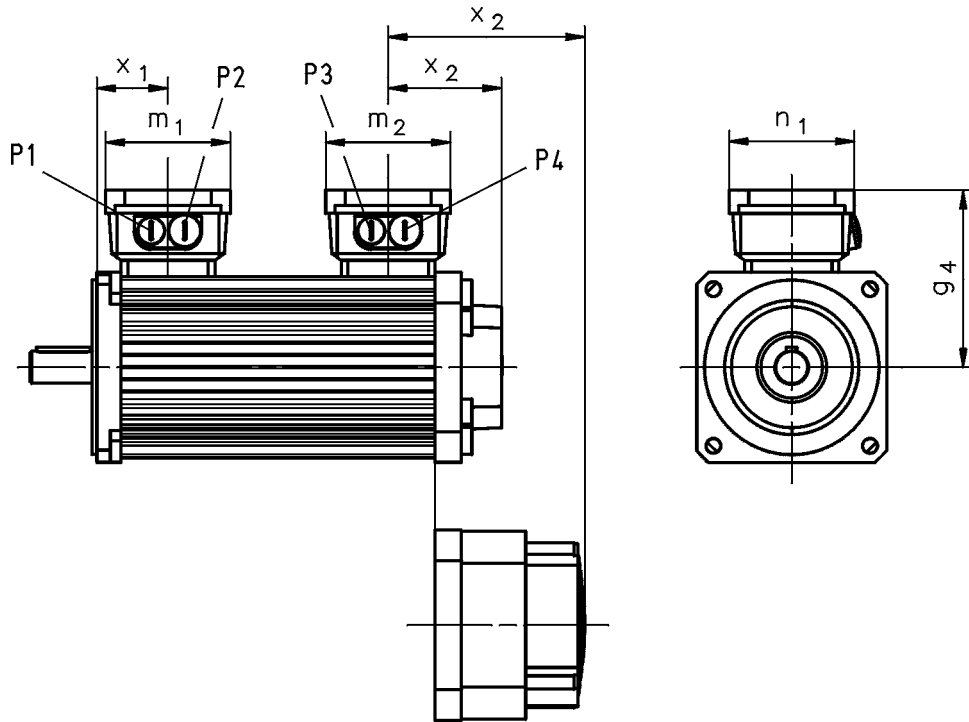
| | | a_2 | a_3 | b_2 | c_2 | e_2 | f_2 | s_2 |
|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | j6 | | | | |
| | | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MCA13 | FF130 | 160 | 130 | 110 | 9 | 130 | 3.5 | 9.0 |
| | FT130 | | | | | | | M8 |
| MCA14 | FF165 | 188 | 142 | 130 | 10 | 165 | | 11.0 |
| | FT130 | | | 110 | | | | M8 |
| MCA17 | FF165 | 200 | 165 | 130 | 12 | 165 | | 11.0 |
| | FT130 | | | 110 | | | | M8 |
| MCA19 | FF215 | 250 | 192 | 180 | 11 | 215 | 4.0 | 13.0 |
| | FT130 | | | 110 | | 130 | 3.5 | M8 |
| MCA21 | FF215 | 300 | 214 | 180 | 12 | 215 | 4.0 | 13.0 |
| | FF265 | | 250 | 230 | | 265 | | |
| | FT130 | | 250 | 214 | | 110 | 11 | 130 |



MCA asynchrone servo motors

Dimensions [mm]

Motors with terminal box, MCA10...19/21



| | | | MCA10I40 | MCA13I41 | MCA14L20 | MCA17N23 | MCA19S23 | MCA21X25 |
|----------------------|----------------|------|----------|----------|----------|----------|--|--|
| | | | | | MCA14L41 | MCA17N41 | MCA19S42 | MCA21X42 |
| RSO B0 | x ₂ | [mm] | 78 | 77 | 85 | | 87 ²⁾ 93 ¹⁾ | 91 ²⁾ 97 ¹⁾ |
| RSO P□ | x ₂ | [mm] | 78 | 77 | 85 | | 87 ²⁾ 93 ¹⁾ | 91 ²⁾ 97 ¹⁾ |
| S□□ / E□□ / T20 / B0 | x ₂ | [mm] | 132 | 131 | 140 | 139 | 137 ²⁾ 143 ¹⁾ | 141 ²⁾ 147 ¹⁾ |
| S□□ / E□□ / T20 / P□ | x ₂ | [mm] | 132 | 131 | 140 | 139 | 137 ²⁾ 143 ¹⁾ | 141 ²⁾ 147 ¹⁾ |

| | | | MCA13I34 | MCA14L16 | MCA17N17 | MCA19S17 | MCA21X17 |
|----------------------|----------------|------|----------|----------|----------|----------|----------|
| | | | | MCA14L35 | MCA17N35 | MCA19S35 | MCA21X35 |
| RSO B0 | x ₂ | [mm] | 145 | 147 | 171 | 190 | 193 |
| RSO P□ | x ₂ | [mm] | 145 | 147 | 171 | 190 | 193 |
| S□□ / E□□ / T20 / B0 | x ₂ | [mm] | 199 | 202 | 225 | 240 | 243 |
| S□□ / E□□ / T20 / P□ | x ₂ | [mm] | 199 | 202 | 225 | 240 | 243 |

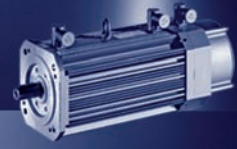
- ▶ Speed/angle sensor: RSO / S□□ / E□□ / T20
- ▶ Brake: B0 / P□

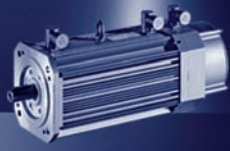
| | g ₄ | m ₁ | m ₂ | n ₁ | x ₁ | P ₁ | P ₂ | P ₃ | P ₄ |
|-------|----------------|----------------|---------------------------------------|---------------------------------------|----------------|----------------|----------------|----------------|----------------|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MCA10 | 113 | 93 | 93 | 93 | 54 | M16x1.5 | M20x1.5 | M16x1.5 | M20x1.5 |
| MCA13 | 125 | | | | 57 | | | | |
| MCA14 | 132 | | | | 53 | | | | |
| MCA17 | 140 | | | | 55 | | | | |
| MCA19 | 158 | 120 | 93 ¹⁾ 120 ²⁾ | 93 ¹⁾ 109 ²⁾ | 73 | M25x1.5 | M32x1.5 | | |
| MCA21 | 169 | | | | 84 | | | | |

¹⁾ IP54
²⁾ IP65

MCA asynchronou servo motors

Dimensions [mm]

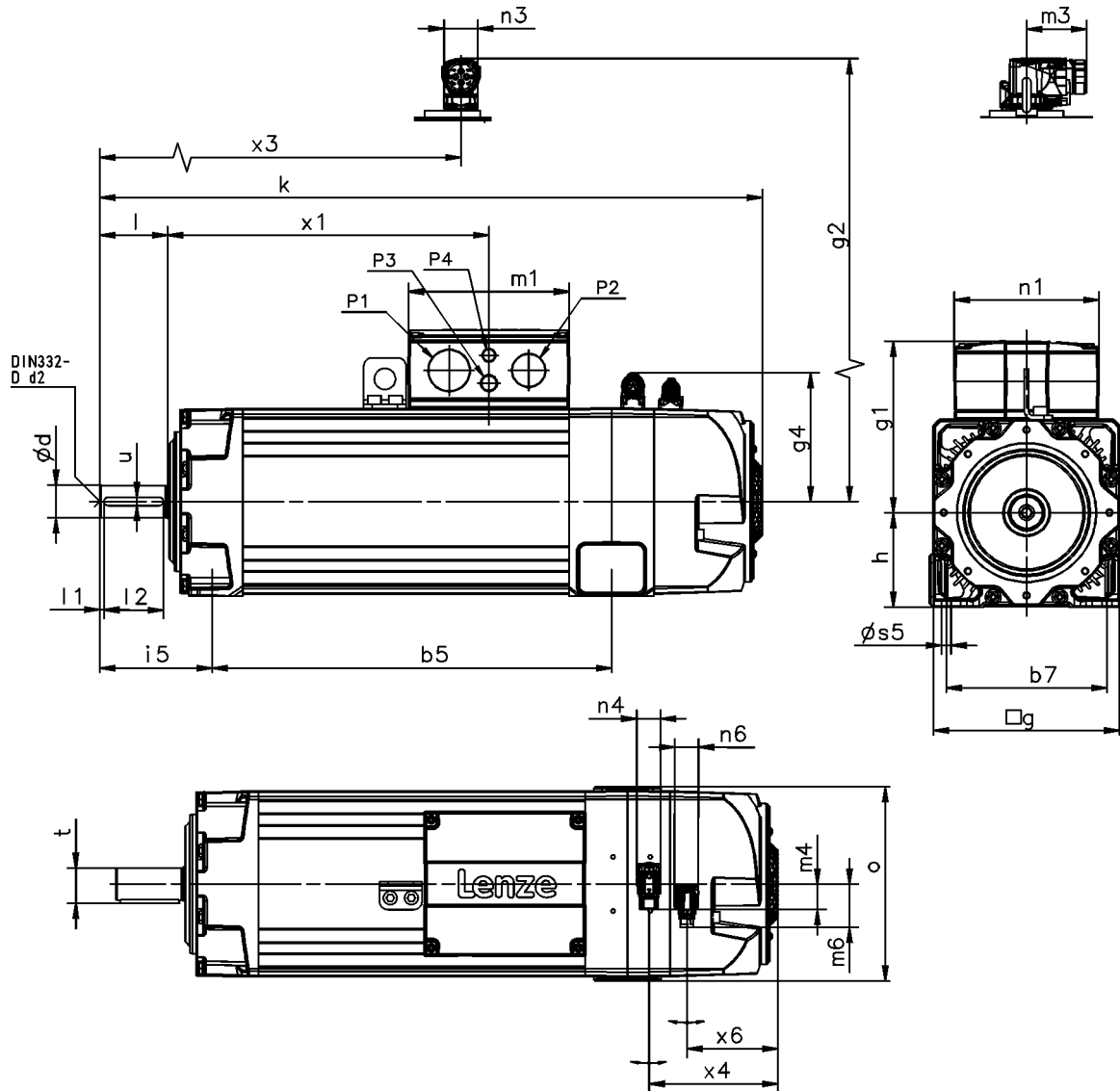




MCA asynchrone servo motors

Dimensions [mm]

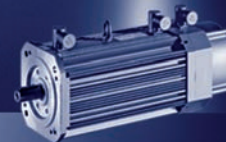
Motors with blower, MCA20/22/26, B3



| | | | MCA20 | MCA22 | MCA26 |
|----------------------------------|----------------|------|-------|-------|-------|
| RS0 / E□□ / T□□ / S□□ / B0...F10 | k | [mm] | 666 | 783 | 970 |
| RS0 / E□□ / T□□ / S□□ / B0...F1F | k | [mm] | 754 | 865 | 1022 |
| RS0 / E□□ / T□□ / S□□ / B0 | x ₄ | [mm] | 146 | 153 | 194 |
| | m ₄ | [mm] | 25.0 | 31.0 | 25.0 |
| RS0 F1...F10 | k | [mm] | 753 | 878 | 1125 |
| RS0 F1...F1F | k | [mm] | 842 | 959 | 1177 |
| RS0 F1 | x ₄ | [mm] | 151 | 157 | 201 |
| | m ₄ | [mm] | | 31.0 | |
| E□□ / T□□ / S□□ / F1...F10 | k | [mm] | 797 | 916 | 1163 |
| E□□ / T□□ / S□□ / F1...F1F | k | [mm] | 885 | 998 | 1215 |
| E□□ / T□□ / S□□ / F1 | x ₄ | [mm] | 146 | 162 | 200 |
| | m ₄ | [mm] | | 31.0 | |
| RS0 / E□□ / T□□ / S□□ / F2...F10 | k | [mm] | 822 | 948 | 1163 |
| RS0 / E□□ / T□□ / S□□ / F2...F1F | k | [mm] | 910 | 1030 | 1215 |
| RS0 / E□□ / T□□ / S□□ / F2 | x ₄ | [mm] | 146 | 162 | 200 |
| | m ₄ | [mm] | | 31.0 | |

MCA asynchronou servo motors

Dimensions [mm]



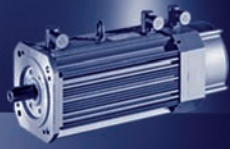
| | g | g₁ | g₂ | g₄ | m₁ | m₃ | m₆ | n₁ | n₃ | n₄ | n₆ |
|--------------|----------|----------------------|----------------------|----------------------|----------------------|----------------------|----------------------|----------------------|----------------------|----------------------|----------------------|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MCA20 | 200 | 171 | 168 | 141 | 154 | 72 | 51 | 128 | 40 | 28 | 28 |
| MCA22 | 220 | 203 | | 153 | 190 | 171 | | | | | |
| MCA26 | 260 | 256 | | 173 | 238 | 212 | | | | | |

| | o | P₁ | P₂ | P₃ | P₄ | x₁ | x₃ | x₆ |
|--------------|----------|----------------------|----------------------|----------------------|----------------------|----------------------|----------------------|----------------------|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MCA20 | 206 | M32x1.5 | M25x1.5 | M20x1.5 | M16x1.5 | 299 | 422 | 101 |
| MCA22 | 230 | M50x1.5 | M40x1.5 | | | 380 | 108 | |
| MCA26 | 269 | M63x1.5 | M50x1.5 | | | 465 | 152 | |

| | d | d | d₂ | l | l₁ | l₂ | u | t |
|--------------|----------|----------|----------------------|--------------|----------------------|----------------------|----------|----------|
| | k6 | m6 | | -0.7 ... 0.3 | | | | |
| | [mm] | [mm] | [mm] | | [mm] | [mm] | [mm] | [mm] |
| MCA20 | 38 | | M12 | 80 | 5.0 | 70 | 10.0 | 41 |
| MCA22 | | | M20 | 110 | | 100 | 16.0 | 59 |
| MCA26 | | | 55 | | | | | |

| | h | b₅ | b₇ | s₅ | i₅ |
|--------------|----------|----------------------|----------------------|----------------------|----------------------|
| | [mm] | [mm] | [mm] | [mm] | [mm] |
| MCA20 | 100 | 366 | 160 | 11.5 | 134 |
| MCA22 | 112 | 472 | 190 | | 133 |
| MCA26 | 132 | 581 | 215 | | 14.0 |

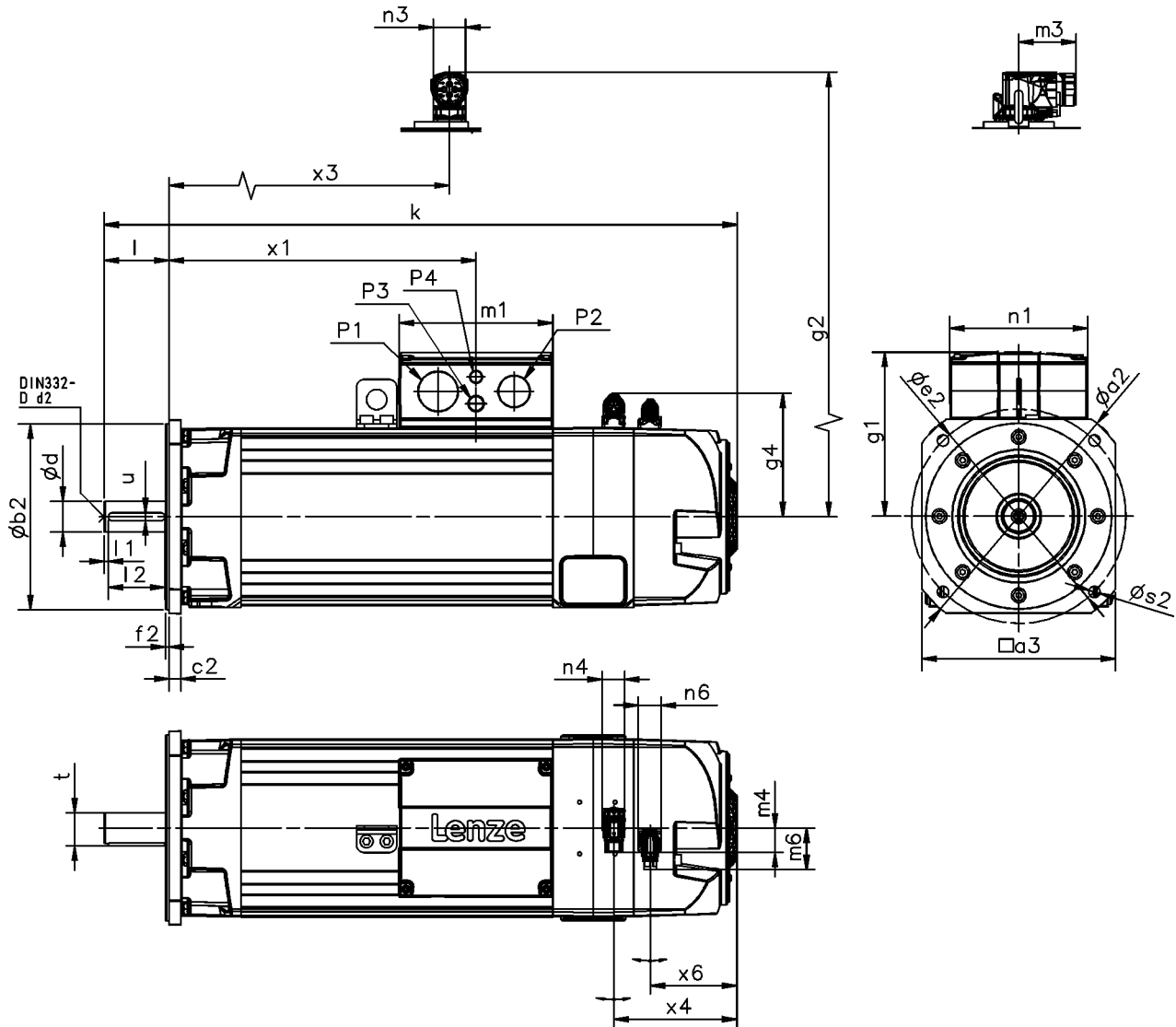
- ▶ Speed/angle sensor: R50 / S□□ / E□□ / T□□
- ▶ Brake: B0 / F1 / F2
- ▶ Blower: F10 / F1F



MCA asynchrone servo motors

Dimensions [mm]

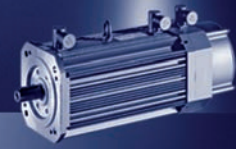
Motors with blower, MCA20/22/26, B5



| | | | MCA20 | MCA22 | MCA26 |
|----------------------------------|----------------|------|-------|-------|-------|
| RS0 / E□□ / T□□ / S□□ / B0...F10 | k | [mm] | 666 | 783 | 970 |
| RS0 / E□□ / T□□ / S□□ / B0...F1F | k | [mm] | 754 | 865 | 1022 |
| RS0 / E□□ / T□□ / S□□ / B0 | x ₄ | [mm] | 146 | 153 | 194 |
| | m ₄ | [mm] | 25.0 | 31.0 | 25.0 |
| RS0 F1...F10 | k | [mm] | 753 | 878 | 1125 |
| RS0 F1...F1F | k | [mm] | 842 | 959 | 1177 |
| RS0 F1 | x ₄ | [mm] | 151 | 157 | 201 |
| | m ₄ | [mm] | | 31.0 | |
| E□□ / T□□ / S□□ / F1...F10 | k | [mm] | 797 | 916 | 1163 |
| E□□ / T□□ / S□□ / F1...F1F | k | [mm] | 885 | 998 | 1215 |
| E□□ / T□□ / S□□ / F1 | x ₄ | [mm] | 146 | 162 | 200 |
| | m ₄ | [mm] | | 31.0 | |
| RS0 / E□□ / T□□ / S□□ / F2...F10 | k | [mm] | 822 | 948 | 1163 |
| RS0 / E□□ / T□□ / S□□ / F2...F1F | k | [mm] | 910 | 1030 | 1215 |
| RS0 / E□□ / T□□ / S□□ / F2 | x ₄ | [mm] | 146 | 162 | 200 |
| | m ₄ | [mm] | | 31.0 | |

MCA asynchronou servo motors

Dimensions [mm]



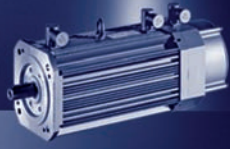
| | g | g ₁ | g ₂ | g ₄ | m ₁ | m ₃ | m ₆ | n ₁ | n ₃ | n ₄ | n ₆ |
|-------|------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MCA20 | 200 | 171 | 168 | 141 | 154 | 72 | 51 | 128 | 40 | 28 | 28 |
| MCA22 | 220 | 203 | | 153 | 190 | 171 | | | | | |
| MCA26 | 260 | 256 | | 173 | 238 | 212 | | | | | |

| | o | P ₁ | P ₂ | P ₃ | P ₄ | x ₁ | x ₃ | x ₆ |
|-------|------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MCA20 | 206 | M32x1.5 | M25x1.5 | M20x1.5 | M16x1.5 | 299 | 422 | 101 |
| MCA22 | 230 | M50x1.5 | M40x1.5 | | | 380 | 108 | |
| MCA26 | 269 | M63x1.5 | M50x1.5 | | | 465 | 152 | |

| | d | d | d ₂ | l | l ₁ | l ₂ | u | t |
|-------|------|------|----------------|--------------|----------------|----------------|------|------|
| | k6 | m6 | | -0.7 ... 0.3 | | | | |
| | [mm] | [mm] | [mm] | | [mm] | [mm] | [mm] | [mm] |
| MCA20 | 38 | | M12 | 80 | 5.0 | 70 | 10.0 | 41 |
| MCA22 | | | | | | | | |
| MCA26 | | | 55 | M20 | | 110 | 100 | 16.0 |

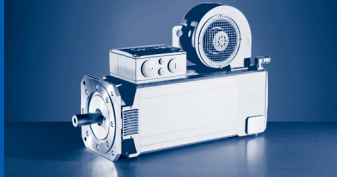
| | | | MCA20 | | MCA22 | MCA26 | |
|----------------|----|------|-------|--|-------|-------|-------|
| | | | FF215 | | FF265 | | FF350 |
| a ₂ | | [mm] | 250 | | 300 | | 400 |
| a ₃ | | [mm] | 196 | | 240 | | 320 |
| b ₂ | j6 | [mm] | 180 | | 230 | | |
| b ₂ | h6 | [mm] | | | | | 300 |
| c ₂ | | [mm] | | | 15 | | |
| e ₂ | | [mm] | 215 | | 265 | | 350 |
| f ₂ | | [mm] | | | 4.0 | | 5.0 |
| s ₂ | | [mm] | | | 14 | | 18 |

- ▶ Speed/angle sensor: R50 / S□□ / E□□ / T□□
- ▶ Brake: B0 / F1 / F2
- ▶ Blower: F10 / F1F



MCA asynchronous servo motors

Dimensions [mm]



Mains connection 3x 400 V

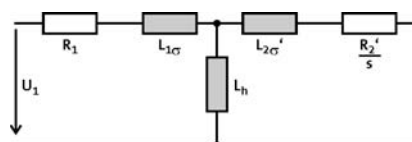
| | n_N | M_0 | M_{max} | M_N | P_N | I_0 | I_N | $U_{N, AC}$ | f_N | $J^{1)}$ | $\eta_{100\%}$ |
|-----------------|---------|-------|-----------|-------|-------|-------|-------|-------------|-------|----------------------|----------------|
| | [r/min] | [Nm] | [Nm] | [Nm] | [kW] | [A] | [A] | [V] | [Hz] | [kgcm ²] | [%] |
| MQA20L14...2F□□ | 1420 | 76.0 | 250 | 71.3 | 10.6 | 27.0 | 26.5 | 360 | 50 | 171 | 80 |
| MQA20L29...2F□□ | 2930 | 76.0 | 250 | 66.2 | 20.3 | 54.0 | 46.9 | 360 | 100 | 171 | 90 |
| MQA22P08...2F□□ | 760 | 156 | 500 | 145 | 11.5 | 29.5 | 27.6 | 360 | 28 | 487 | 77 |
| MQA22P14...2F□□ | 1425 | 156 | 500 | 135 | 20.1 | 51.0 | 45.6 | 360 | 50 | 487 | 86 |
| MQA22P17...2F□□ | 1670 | 156 | 500 | 130 | 22.7 | 59.0 | 50.3 | 360 | 58 | 487 | 88 |
| MQA22P29...2F□□ | 2935 | 156 | 500 | 125 | 38.4 | 102 | 86.0 | 360 | 100 | 487 | 90 |
| MQA26T05...2F□□ | 550 | 325 | 1100 | 296 | 17.0 | 48.5 | 44.5 | 360 | 20 | 1335 | 81 |
| MQA26T10...2F□□ | 1030 | 325 | 1100 | 288 | 31.1 | 85.5 | 76.2 | 360 | 36 | 1335 | 87 |
| MQA26T12...2F□□ | 1200 | 325 | 1100 | 282 | 35.4 | 109 | 88.8 | 360 | 42 | 1335 | 82 |
| MQA26T22...2F□□ | 2235 | 325 | 1100 | 257 | 60.2 | 171 | 138 | 340 | 76 | 1335 | 92 |

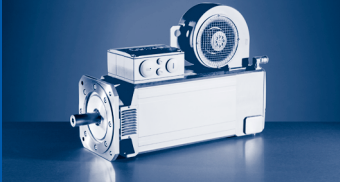
| | R_1 | $R_{UV\ 20^\circ C}$ | $R_{UV\ 150^\circ C}$ | R_2 | $L_{1\sigma}$ | L | $L_{2\sigma}$ | $n_{max}^{2)}$ | $m^{1)}$ |
|-----------------|-------|----------------------|-----------------------|-------|---------------|------|---------------|----------------|----------|
| | [Ω] | [Ω] | [Ω] | [Ω] | [mH] | [mH] | [mH] | [r/min] | [kg] |
| MQA20L14...2F□□ | 0.37 | 0.73 | 1.10 | 0.57 | 1.98 | 52.5 | 2.10 | 6500 | 63.0 |
| MQA20L29...2F□□ | 0.091 | 0.18 | 0.28 | 0.14 | 0.49 | 13.0 | 0.52 | | |
| MQA22P08...2F□□ | 0.54 | 1.07 | 1.62 | 0.75 | 5.05 | 83.0 | 4.76 | | |
| MQA22P14...2F□□ | | 0.36 | 0.54 | | 3.57 | 86.9 | 4.81 | | |
| MQA22P17...2F□□ | 0.13 | 0.27 | 0.40 | 0.19 | 0.90 | 21.7 | 1.21 | | |
| MQA22P29...2F□□ | | 0.080 | 0.12 | | 0.89 | 21.5 | 1.20 | | |
| MQA26T05...2F□□ | 0.29 | 0.59 | 0.89 | 0.39 | 2.57 | 54.0 | 4.78 | | |
| MQA26T10...2F□□ | | 0.20 | 0.30 | | 2.33 | 57.4 | 4.91 | | |
| MQA26T12...2F□□ | 0.080 | 0.15 | 0.23 | 0.098 | 0.63 | 12.6 | 1.18 | | |
| MQA26T22...2F□□ | | 0.050 | 0.075 | | 0.73 | 17.8 | 1.34 | | |

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.

The data in the R_1 , $L_{1\sigma}$, L_h , R_2' and $L_{2\sigma}'$ columns is based on a single-phase equivalent circuit diagram at 20°C.

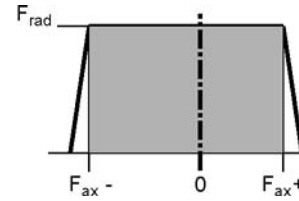
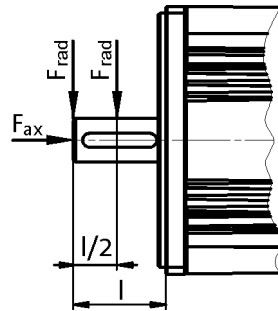




MQA asynchronous servo motors

Rated data

Permissible radial and axial forces



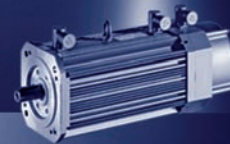
Application of force at l/2

| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|--------------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MQA20 | 3400 | -1330 | 690 | 2500 | -1020 | 380 | 1950 | -780 | 140 | 1700 | -690 | 40 | | | |
| MQA22 | 3600 | -2370 | 1700 | 2800 | -1740 | 1090 | 2200 | -1280 | 640 | 1900 | -1080 | 440 | 1600 | -880 | 240 |
| MQA26 | 6950 | -2500 | 1580 | 5400 | -1800 | 880 | 4300 | -1300 | 380 | 3700 | -1090 | 160 | | | |

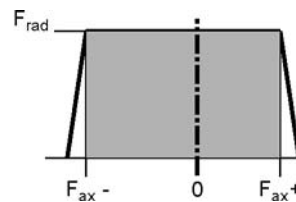
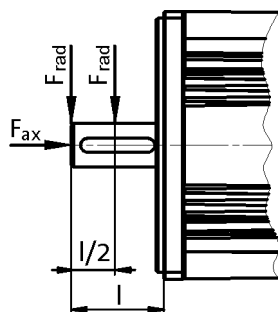
Application of force at l

| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|--------------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MQA20 | 3150 | -1170 | 530 | 2300 | -920 | 280 | 1800 | -710 | 70 | 1400 | -650 | 0 | | | |
| MQA22 | 3500 | -2240 | 1600 | 2600 | -1640 | 1100 | 2050 | -1200 | 560 | 1800 | -1020 | 380 | 1450 | -850 | 200 |
| MQA26 | 6400 | -2080 | 1150 | 5000 | -1600 | 680 | 4000 | -1160 | 230 | 3400 | -1090 | 50 | | | |

- ▶ The values for the bearing service life L_{10} refer to an average speed of 3000 r/min. Depending on the ambient temperatures, the service life of the bearings is also reduced by the grease lifetime.



Permissible radial and axial forces



Reinforced bearings

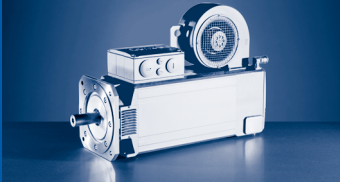
Application of force at l/2

| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|--------------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MQA20 | 7100 | -970 | 330 | 5100 | -800 | 160 | 3900 | -640 | 0 | | | | | | |
| MQA22 | 8500 | -1850 | 1200 | 7000 | -1400 | 760 | 5600 | -1030 | 390 | 4350 | -930 | 290 | 3200 | -800 | 160 |
| MQA26 | 10500 | -2180 | 1250 | 8370 | -1530 | 600 | 6670 | -1130 | 200 | 5840 | -960 | 30 | | | |

Application of force at l

| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|--------------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MQA20 | 6350 | -720 | 80 | 4100 | -680 | 40 | 2800 | | 0 | | | | | | |
| MQA22 | 7000 | -1750 | 1100 | 5500 | -1300 | 660 | 4700 | -920 | 280 | 3900 | -820 | 180 | 3000 | -700 | 60 |
| MQA26 | 9600 | -2200 | 1280 | 7700 | -1280 | 360 | 6000 | -960 | 30 | | | | | | |

- The values for the bearing service life L_{10} refer to an average speed of 3000 r/min. Depending on the ambient temperatures, the service life of the bearings is also reduced by the grease lifetime.

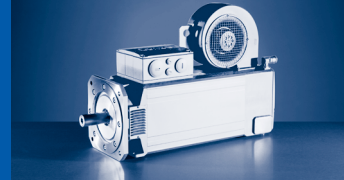


MQA asynchronous servo motors 9400 Servo Drives selection tables

Mains connection 3 x 400 V and switching frequency 8 kHz

| | | | | | E94A□□ | E0174 | E0244 | E0324 | E0474 | E0594 | E0864 | E1044 | E1454 | E1724 |
|-------------------|-------|-------|-------|-------|-------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | | | | | I_N | 16.5 | 23.5 | 32.0 | 41.0 | 41.0 | 73.0 | 78.0 | 102.0 | 120.0 |
| | | | | | $I_{0,max}$ | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 | 172.0 | 208.0 | 261.0 | 310.0 |
| MQA | M_N | n_N | I_N | P_N | I_{max} | 49.5 | 58.8 | 76.8 | 94.0 | 118.0 | 172.0 | 208.0 | 261.0 | 310.0 |
| 20L14- ...2F□□ | 71.3 | 1420 | 26.5 | 10.60 | M_0 | 32.5 | 66.0 | | | | | | | |
| | | | | | M_N | 32.5 | 66.0 | | | | | | | |
| | | | | | $M_{0,max}$ | 154.2 | 190.0 | | | | | | | |
| | | | | | M_{max} | 154.2 | 190.0 | | | | | | | |
| | | | | | n_{eto} | - | - | | | | | | | |
| 20L29- ...2F□□ | 66.2 | 2930 | 46.9 | 20.30 | M_0 | | | 28.0 | 51.6 | 51.6 | | | | |
| | | | | | M_N | | | 28.0 | 51.6 | 51.6 | | | | |
| | | | | | $M_{0,max}$ | | | 116.0 | 148.2 | 192.8 | | | | |
| | | | | | M_{max} | | | 116.0 | 148.2 | 192.8 | | | | |
| | | | | | n_{eto} | | | - | - | - | | | | |
| 22P08- ...2F□□ | 145.0 | 760 | 27.6 | 11.50 | M_0 | | 116.0 | 156.0 | | | | | | |
| | | | | | M_N | | 116.0 | 145.0 | | | | | | |
| | | | | | $M_{0,max}$ | | 313.0 | 402.0 | | | | | | |
| | | | | | M_{max} | | 313.0 | 402.0 | | | | | | |
| | | | | | n_{eto} | | - | - | | | | | | |
| 22P14- ...2F□□ | 135.0 | 1425 | 45.6 | 20.10 | M_0 | | | | | 118.0 | | | | |
| | | | | | M_N | | | | | 118.0 | | | | |
| | | | | | $M_{0,max}$ | | | | | 372.0 | | | | |
| | | | | | M_{max} | | | | | 372.0 | | | | |
| | | | | | n_{eto} | | | | | - | | | | |
| 22P17- ...2F□□ | 130.0 | 1670 | 50.3 | 22.70 | M_0 | | | | | 99.0 | 156.0 | | | |
| | | | | | M_N | | | | | 99.0 | 130.0 | | | |
| | | | | | $M_{0,max}$ | | | | | 325.0 | 463.0 | | | |
| | | | | | M_{max} | | | | | 325.0 | 463.0 | | | |
| | | | | | n_{eto} | | | | | - | - | | | |
| 22P29- ...2F□□ | 125.0 | 2935 | 86.0 | 38.40 | M_0 | | | | | | | 109.0 | 156.0 | 156.0 |
| | | | | | M_N | | | | | | | 109.0 | 125.0 | 125.0 |
| | | | | | $M_{0,max}$ | | | | | | | 335.0 | 416.0 | 486.0 |
| | | | | | M_{max} | | | | | | | 335.0 | 416.0 | 486.0 |
| | | | | | n_{eto} | | | | | | | - | - | - |

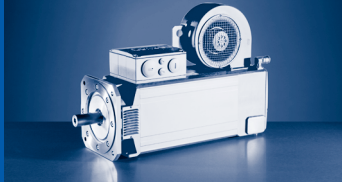
- ▶ $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]
- ▶ If the motors are operated at a lower switching frequency, please contact your Lenze sales office!
- ▶ When operating at 4 kHz, the motor generates just 95 % of its rated torque with increased noise emissions.



Mains connection 3 x 400 V and switching frequency 8 kHz

| | | | | | E94A□□ | E0474 | E0594 | E0864 | E1044 | E1454 | E1724 | E2024 | E2454 | E2924 | E3664 |
|-------------------|-------|-------|-------|-------|-------------|-------|-------|--------|-------|--------|-------|-------|-------|--------|--------|
| | | | | | I_N | 41.0 | 41.0 | 73.0 | 78.0 | 102.0 | 120.0 | 131.0 | 160.0 | 191.0 | 240.0 |
| | | | | | $I_{0,max}$ | 94.0 | 118.0 | 172.0 | 208.0 | 261.0 | 310.0 | 364.0 | 441.0 | 526.0 | 659.0 |
| MQA | M_N | n_N | I_N | P_N | I_{max} | 94.0 | 118.0 | 172.0 | 208.0 | 261.0 | 310.0 | 364.0 | 441.0 | 526.0 | 659.0 |
| 26T05- ...2F□□ | 296.0 | 550 | 44.5 | 17.00 | M_0 | 268.0 | 268.0 | 325.0 | | | | | | | |
| | | | | | M_N | 268.0 | 268.0 | 296.0 | | | | | | | |
| | | | | | $M_{0,max}$ | 665.0 | 826.0 | 1100.0 | | | | | | | |
| | | | | | M_{max} | 665.0 | 826.0 | 1100.0 | | | | | | | |
| | | | | | n_{eto} | - | - | - | | | | | | | |
| 26T10- ...2F□□ | 288.0 | 1030 | 76.2 | 31.10 | M_0 | | | 270.0 | 298.0 | 325.0 | | | | | |
| | | | | | M_N | | | 270.0 | 288.0 | 288.0 | | | | | |
| | | | | | $M_{0,max}$ | | | 713.0 | 855.0 | 1044.0 | | | | | |
| | | | | | M_{max} | | | 713.0 | 855.0 | 1044.0 | | | | | |
| | | | | | n_{eto} | | | - | - | - | | | | | |
| 26T12- ...2F□□ | 282.0 | 1200 | 88.8 | 35.40 | M_0 | | | | 219.0 | 291.0 | 325.0 | 325.0 | | | |
| | | | | | M_N | | | | 219.0 | 282.0 | 282.0 | 282.0 | | | |
| | | | | | $M_{0,max}$ | | | | 609.0 | 739.0 | 840.0 | 950.0 | | | |
| | | | | | M_{max} | | | | 609.0 | 739.0 | 840.0 | 950.0 | | | |
| | | | | | n_{eto} | | | | - | - | - | - | | | |
| 26T22- ...2F□□ | 257.0 | 2235 | 138.1 | 60.10 | M_0 | | | | | | | 242.0 | 290.0 | 325.0 | 325.0 |
| | | | | | M_N | | | | | | | 242.0 | 257.0 | 257.0 | 257.0 |
| | | | | | $M_{0,max}$ | | | | | | | 711.0 | 843.0 | 1001.0 | 1100.0 |
| | | | | | M_{max} | | | | | | | 711.0 | 843.0 | 1001.0 | 1100.0 |
| | | | | | n_{eto} | | | | | | | - | - | - | - |

- ▶ $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]
- ▶ If the motors are operated at a lower switching frequency, please contact your Lenze sales office!
- ▶ When operating at 4 kHz, the motor generates just 95 % of its rated torque with increased noise emissions.



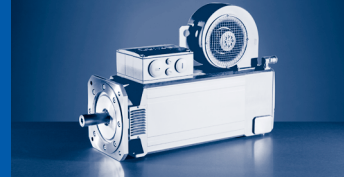
MQA asynchronous servo motors

Selection tables for Inverter Drives 8400 TopLine

Mains connection 3 x 400 V and switching frequency 8 kHz

| | | | | | E84AVTC | □1134 | □1534 | □1834 | □2234 | □3034 | □3734 | □4534 | |
|---------------|-------|-------|-------|-------|--------------|-------|-------|-------|-------|-------|-------|--------|------|
| | | | | | I_N | 23.5 | 32.0 | 39.0 | 47.0 | 61.0 | 76.0 | 89.0 | |
| | | | | | $I_{0,max}$ | 32.9 | 43.2 | 60.0 | 70.5 | 91.5 | 114.0 | 133.5 | |
| MQA | M_N | n_N | I_N | P_N | I_{max} | 47.0 | 64.0 | 78.0 | 94.0 | 122.0 | 152.0 | 178.0 | |
| 20L14-...2F□□ | 71.3 | 1420 | 26.5 | 10.60 | M_0 | - | 76.0 | 76.0 | 76.0 | 76.0 | | | |
| | | | | | M_N | - | 71.3 | 71.3 | 71.3 | 71.3 | | | |
| | | | | | $M_{0,max}$ | 146.0 | 202.0 | 249.2 | 286.3 | 339.1 | | | |
| | | | | | M_{max} | 146.0 | 202.2 | 249.2 | 286.3 | 339.1 | | | |
| | | | | | η_{eto} | - | - | - | - | - | | | |
| 20L29-...2F□□ | 66.2 | 2930 | 46.9 | 20.30 | M_0 | | | - | 76.0 | 76.0 | 76.0 | 76.0 | |
| | | | | | M_N | | | - | 66.2 | 66.2 | 66.2 | 66.2 | 66.2 |
| | | | | | $M_{0,max}$ | | | 121.8 | 140.9 | 183.7 | 224.5 | 275.9 | |
| | | | | | M_{max} | | | 121.8 | 140.9 | 183.9 | 225.5 | 276.6 | |
| | | | | | η_{eto} | | | - | - | - | - | - | |
| 22P08-...2F□□ | 145.0 | 760 | 27.6 | 11.50 | M_0 | - | 156.0 | 156.0 | 156.0 | 156.0 | | | |
| | | | | | M_N | - | 144.5 | 144.5 | 144.5 | 144.5 | | | |
| | | | | | $M_{0,max}$ | 222.8 | 310.5 | 377.0 | 372.9 | 374.6 | | | |
| | | | | | M_{max} | 223.0 | 310.5 | 377.0 | 372.9 | 374.6 | | | |
| | | | | | η_{eto} | - | - | - | - | - | | | |
| 22P14-...2F□□ | 135.0 | 1425 | 45.6 | 20.10 | M_0 | | - | - | 156.0 | 156.0 | 156.0 | 156.0 | |
| | | | | | M_N | | - | - | 134.7 | 134.7 | 134.7 | 134.7 | |
| | | | | | $M_{0,max}$ | | 185.1 | 230.6 | 267.1 | 343.7 | 418.3 | 512.3 | |
| | | | | | M_{max} | | 185.1 | 230.6 | 267.1 | 344.4 | 420.0 | 514.4 | |
| | | | | | η_{eto} | | - | - | - | - | - | - | |
| 22P17-...2F□□ | 130.0 | 1670 | 50.3 | 22.70 | M_0 | | | - | - | 156.0 | 156.0 | 156.0 | |
| | | | | | M_N | | | - | - | 129.8 | 129.8 | 129.8 | |
| | | | | | $M_{0,max}$ | | | 198.6 | 230.2 | 300.0 | 365.3 | 447.0 | |
| | | | | | M_{max} | | | 198.6 | 230.4 | 300.0 | 367.5 | 449.9 | |
| | | | | | η_{eto} | | | - | - | - | - | - | |
| 22P29-...2F□□ | 125.0 | 2935 | 86.0 | 38.40 | M_0 | | | | | - | - | 156.0 | |
| | | | | | M_N | | | | | - | - | 124.9 | |
| | | | | | $M_{0,max}$ | | | | | 176.1 | 218.9 | 263.2 | |
| | | | | | M_{max} | | | | | 176.4 | 219.6 | 264.1 | |
| | | | | | η_{eto} | | | | | - | - | - | |
| 26T05-...2F□□ | 296.0 | 550 | 44.5 | 17.00 | M_0 | | - | - | 325.0 | 325.0 | 325.0 | 325.0 | |
| | | | | | M_N | | - | - | 295.2 | 295.2 | 295.2 | 295.2 | |
| | | | | | $M_{0,max}$ | | 390.4 | 489.6 | 567.1 | 744.4 | 902.3 | 1080.2 | |
| | | | | | M_{max} | | 390.4 | 490.2 | 568.0 | 744.8 | 904.7 | 1080.2 | |
| | | | | | η_{eto} | | - | - | - | - | - | - | |
| 26T10-...2F□□ | 288.0 | 1030 | 76.2 | 31.10 | M_0 | | | | | - | - | 325.0 | |
| | | | | | M_N | | | | | - | - | 288.3 | |
| | | | | | $M_{0,max}$ | | | | | 429.7 | 532.5 | 638.2 | |
| | | | | | M_{max} | | | | | 431.4 | 534.1 | 641.5 | |
| | | | | | η_{eto} | | | | | - | - | - | |
| 26T12-...2F□□ | 282.0 | 1200 | 88.8 | 35.40 | M_0 | | | | | | - | 325.0 | |
| | | | | | M_N | | | | | | - | 281.7 | |
| | | | | | $M_{0,max}$ | | | | | | 458.2 | 550.4 | |
| | | | | | M_{max} | | | | | | 460.6 | 552.9 | |
| | | | | | η_{eto} | | | | | | - | - | |

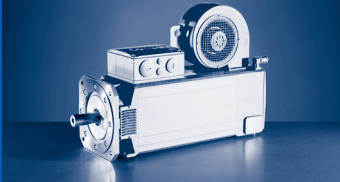
- ▶ $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]
- ▶ If the motors are operated at a lower switching frequency, please contact your Lenze sales office!



Mains connection 3 x 400 V and switching frequency 8 kHz

| | | | | | EVS | 9326-E□ | 9327-E□ | 9328-E□ | 9329-E□ | 9330-E□ | 9331-E□ | 9332-E□ |
|---------------|-------|-------|-------|-------|--------------|---------|---------|---------|---------|---------|---------|---------|
| | | | | | I_N | 23.5 | 32.0 | 47.0 | 59.0 | 89.0 | 110.0 | 145.0 |
| | | | | | $I_{0,max}$ | 23.5 | 32.0 | 47.0 | 52.0 | 80.0 | 110.0 | 126.0 |
| MQA | M_N | n_N | I_N | P_N | I_{max} | 35.3 | 48.0 | 70.5 | 88.5 | 133.5 | 165.0 | 217.5 |
| 20L14-...2F□□ | 71.3 | 1420 | 26.5 | 10.60 | M_0 | 61.0 | 76.0 | 76.0 | | | | |
| | | | | | M_N | 61.0 | 71.3 | 71.3 | | | | |
| | | | | | $M_{0,max}$ | 61.0 | 112.0 | 187.0 | | | | |
| | | | | | M_{max} | 109.3 | 156.7 | 232.1 | | | | |
| | | | | | η_{eto} | - | - | - | | | | |
| 20L29-...2F□□ | 66.2 | 2930 | 46.9 | 20.30 | M_0 | | 28.0 | 66.3 | 76.0 | 76.0 | | |
| | | | | | M_N | | 28.0 | 66.2 | 66.2 | 66.2 | | |
| | | | | | $M_{0,max}$ | | 28.0 | 66.3 | 95.0 | 169.0 | | |
| | | | | | M_{max} | | 68.5 | 112.5 | 146.4 | 226.7 | | |
| | | | | | η_{eto} | | - | - | - | - | | |
| 22P08-...2F□□ | 145.0 | 760 | 27.6 | 11.50 | M_0 | | 156.0 | 156.0 | 156.0 | | | |
| | | | | | M_N | | 145.0 | 145.0 | 145.0 | | | |
| | | | | | $M_{0,max}$ | | 177.0 | 280.0 | 293.0 | | | |
| | | | | | M_{max} | | 247.0 | 338.8 | 345.8 | | | |
| | | | | | η_{eto} | | - | - | - | | | |
| 22P14-...2F□□ | 135.0 | 1425 | 45.6 | 20.10 | M_0 | | | 146.0 | 156.0 | 156.0 | | |
| | | | | | M_N | | | 135.0 | 135.0 | 135.0 | | |
| | | | | | $M_{0,max}$ | | | 146.0 | 186.0 | 188.0 | | |
| | | | | | M_{max} | | | 230.1 | 292.9 | 341.8 | | |
| | | | | | η_{eto} | | | - | - | - | | |
| 22P17-...2F□□ | 130.0 | 1670 | 50.3 | 22.70 | M_0 | | | 124.0 | 156.0 | 156.0 | 156.0 | |
| | | | | | M_N | | | 124.0 | 130.0 | 130.0 | 130.0 | |
| | | | | | $M_{0,max}$ | | | 124.0 | 140.0 | 240.0 | 335.0 | |
| | | | | | M_{max} | | | 180.5 | 227.7 | 342.1 | 378.3 | |
| | | | | | η_{eto} | | | - | - | - | - | |
| 22P29-...2F□□ | 125.0 | 2935 | 86.0 | 38.40 | M_0 | | | | | 135.5 | 156.0 | 156.0 |
| | | | | | M_N | | | | | 125.0 | 125.0 | 125.0 |
| | | | | | $M_{0,max}$ | | | | | 137.0 | 195.0 | 250.0 |
| | | | | | M_{max} | | | | | 215.6 | 273.1 | 355.1 |
| | | | | | η_{eto} | | | | | - | - | - |
| 26T05-...2F□□ | 296.0 | 550 | 44.5 | 17.00 | M_0 | | | 303.0 | 325.0 | 325.0 | | |
| | | | | | M_N | | | 296.0 | 296.0 | 296.0 | | |
| | | | | | $M_{0,max}$ | | | 303.0 | 333.0 | 615.0 | | |
| | | | | | M_{max} | | | 482.0 | 612.0 | 751.0 | | |
| | | | | | η_{eto} | | | - | - | - | | |
| 26T10-...2F□□ | 288.0 | 1030 | 76.2 | 31.10 | M_0 | | | | | 319.0 | 325.0 | |
| | | | | | M_N | | | | | 288.0 | 288.0 | |
| | | | | | $M_{0,max}$ | | | | | 300.0 | 440.0 | |
| | | | | | M_{max} | | | | | 552.0 | 671.0 | |
| | | | | | η_{eto} | | | | | - | - | |
| 26T12-...2F□□ | 282.0 | 1200 | 88.8 | 35.40 | M_0 | | | | | 284.0 | 325.0 | 325.0 |
| | | | | | M_N | | | | | 282.0 | 282.0 | 282.0 |
| | | | | | $M_{0,max}$ | | | | | 258.0 | 327.0 | 397.0 |
| | | | | | M_{max} | | | | | 424.0 | 512.0 | 663.0 |
| | | | | | η_{eto} | | | | | - | - | - |
| 26T22-...2F□□ | 257.0 | 2235 | 138.1 | 60.10 | M_0 | | | | | | 177.0 | 222.0 |
| | | | | | M_N | | | | | | 177.0 | 257.0 |
| | | | | | $M_{0,max}$ | | | | | | 203.0 | 220.0 |
| | | | | | M_{max} | | | | | | 315.0 | 432.0 |
| | | | | | η_{eto} | | | | | | - | - |

- ▶ $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]
- ▶ If the motors are operated at a lower switching frequency, please contact your Lenze sales office!

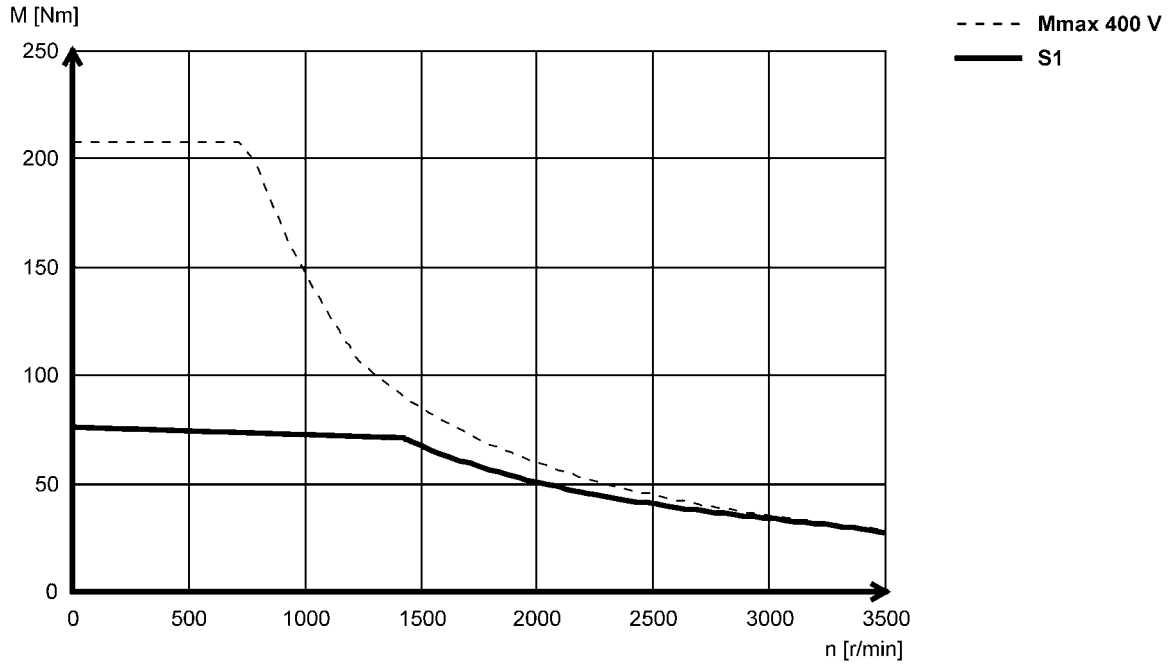


MQA asynchronous servo motors

Torque characteristics

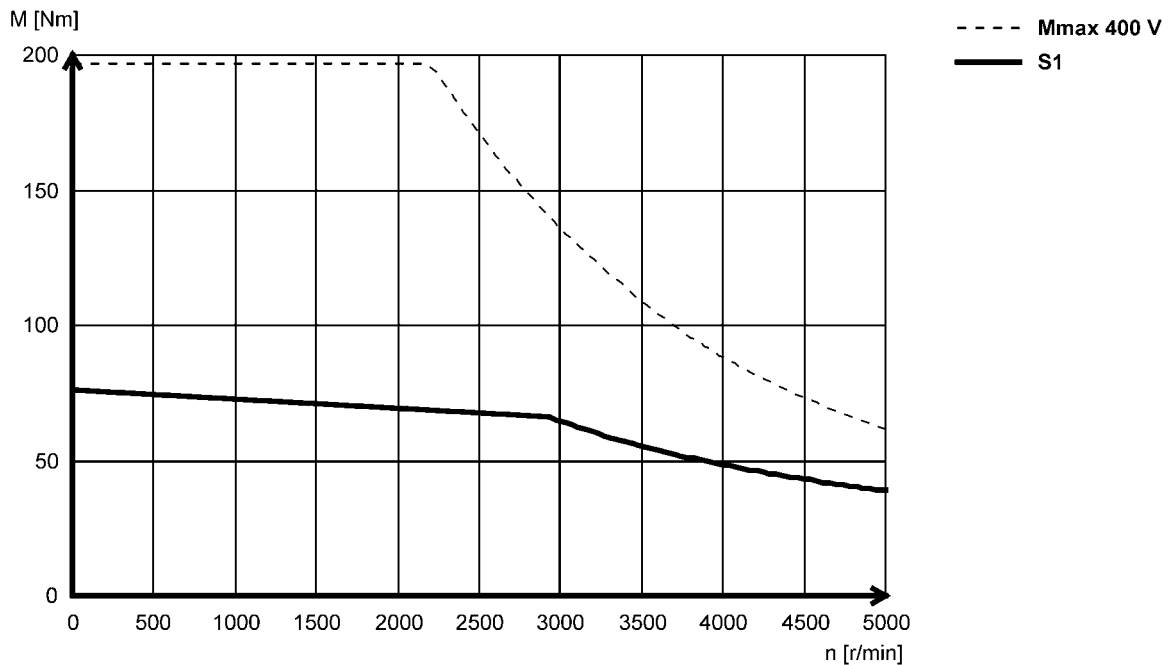
Mains connection 3x 400 V

MQA20L14...2F□□

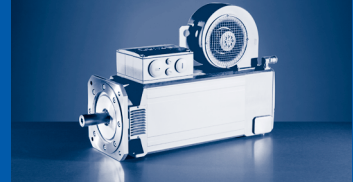


6

MQA20L29...2F□□

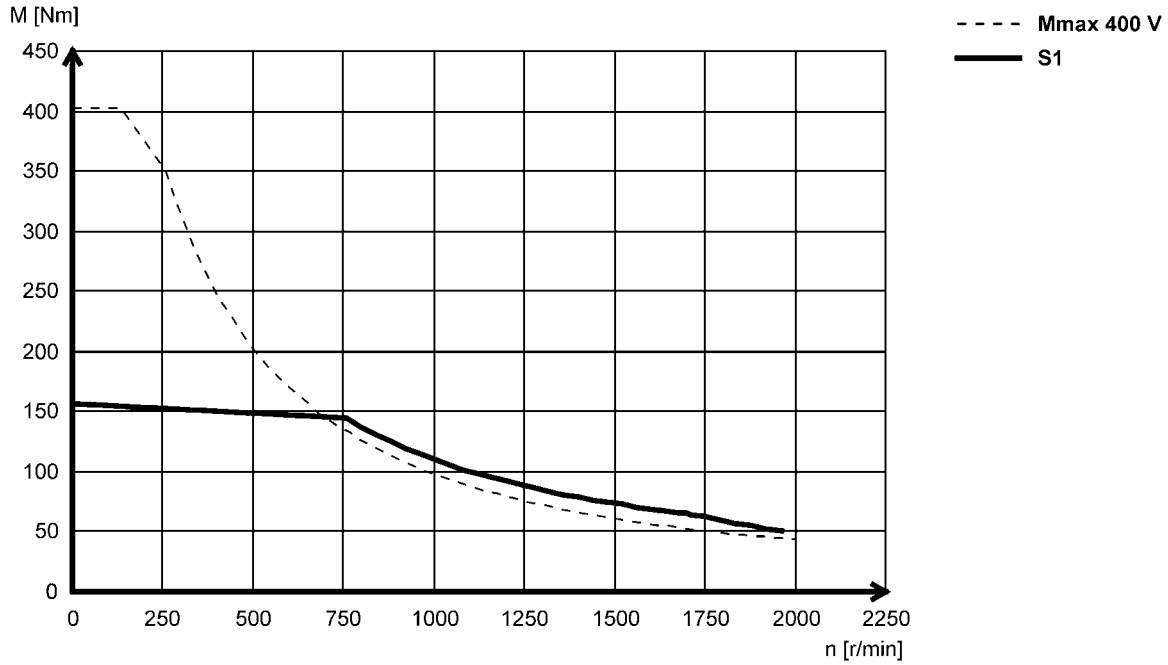


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

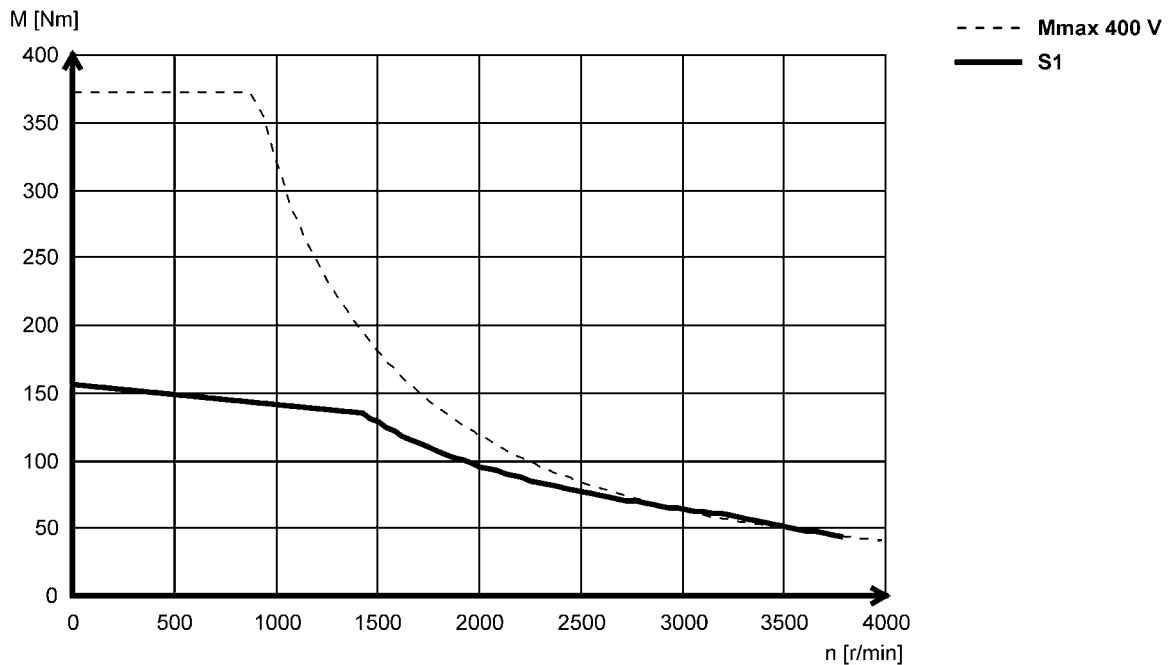


Mains connection 3x 400 V

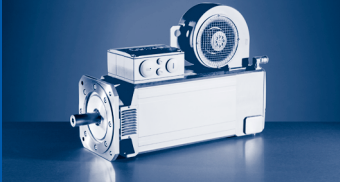
MQA22P08...2F□□



MQA22P14...2F□□



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

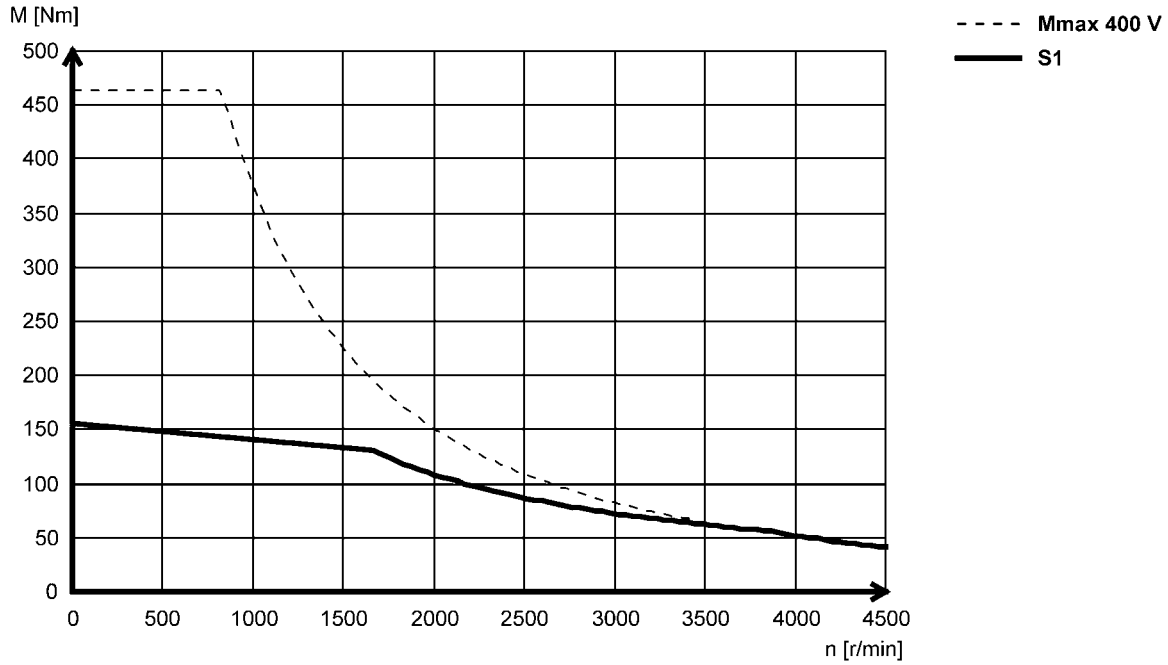


MQA asynchronous servo motors

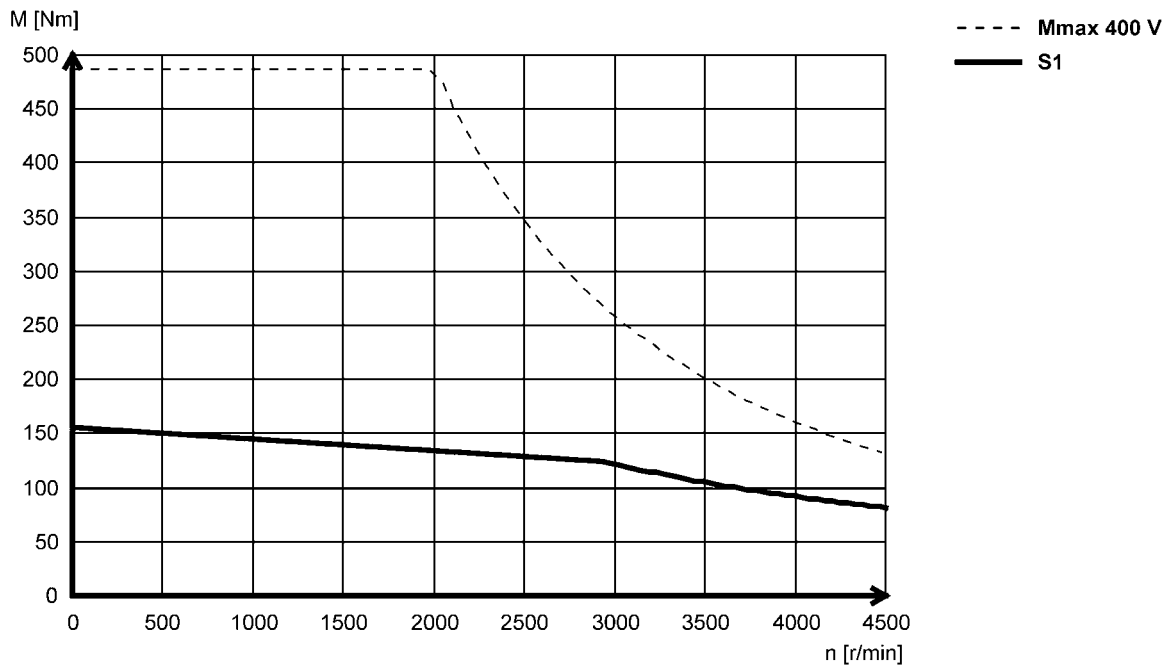
Torque characteristics

Mains connection 3x 400 V

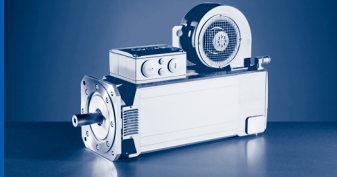
MQA22P17...2F□□



MQA22P29...2F□□

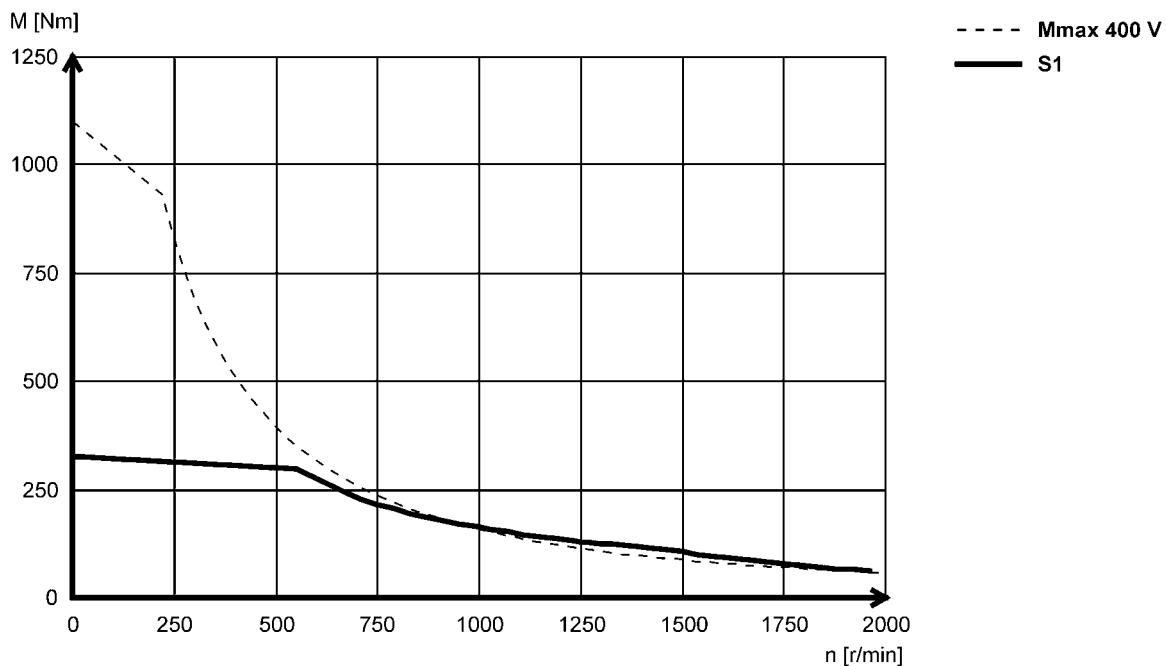


► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

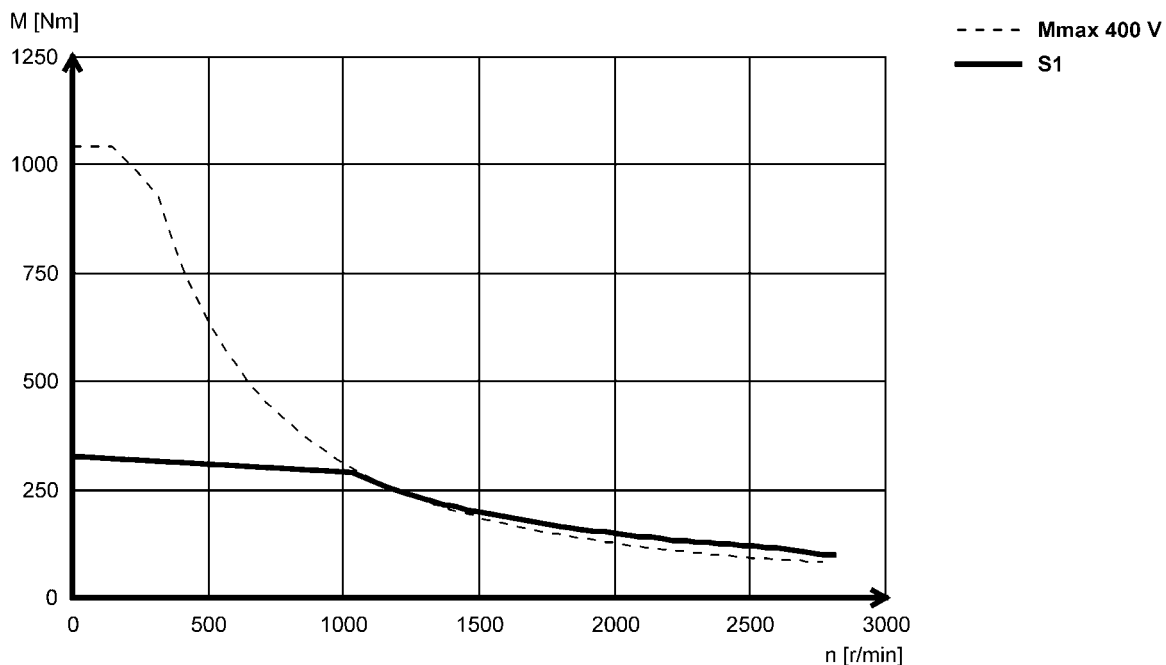


Mains connection 3x 400 V

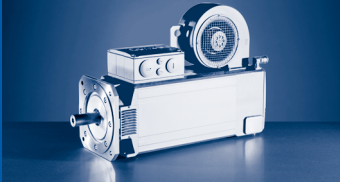
MQA26T05...2F□□



MQA26T10...2F□□



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

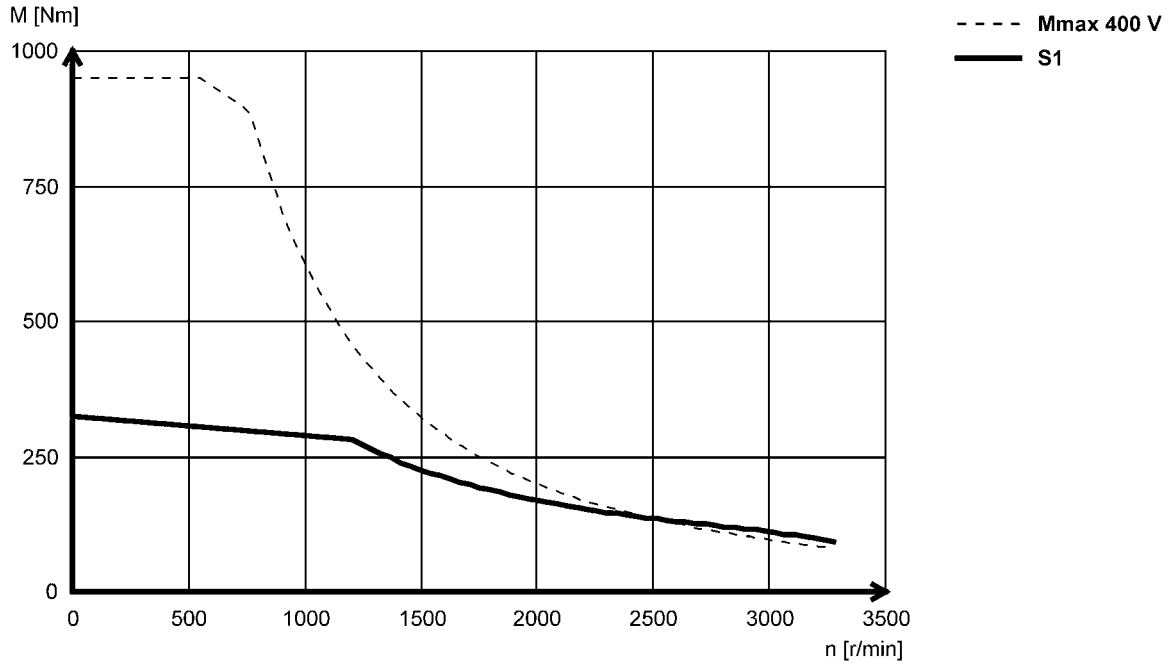


MQA asynchronous servo motors

Torque characteristics

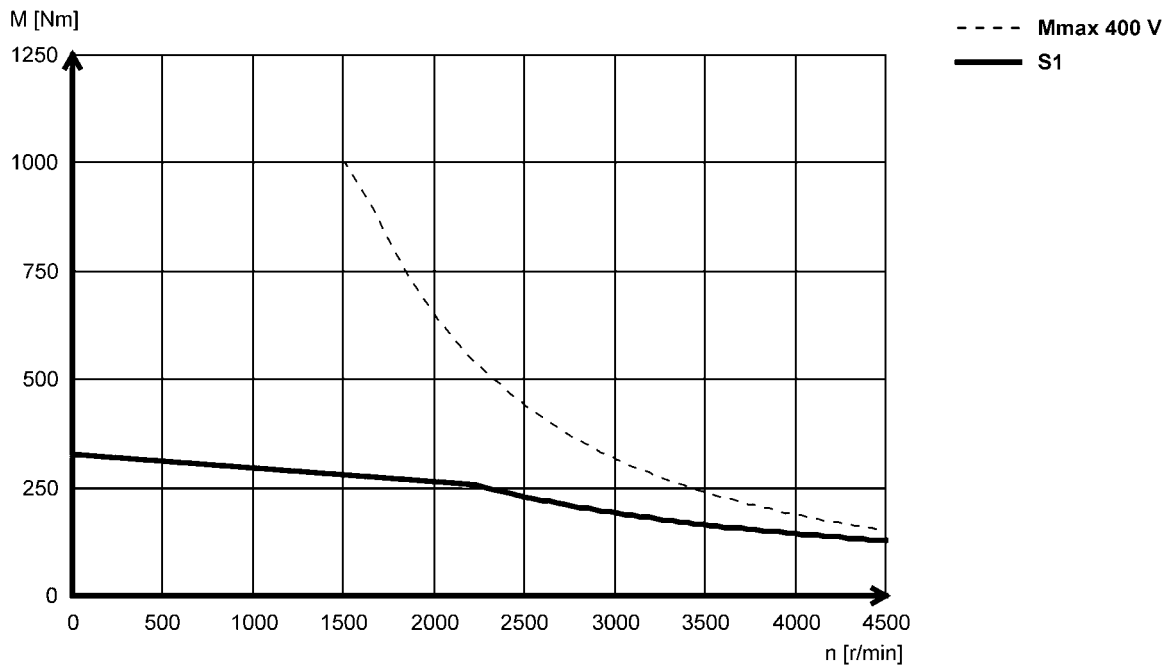
Mains connection 3x 400 V

MQA26T12...2F□□

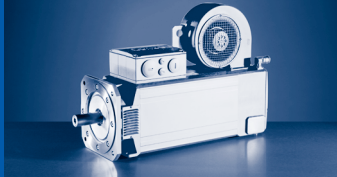


6

MQA26T22...2F□□



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.



Holding brakes

The servo motors can be equipped with integral spring-applied holding brakes. The voltages available for this model are 24 V DC and 230 V AC.

The brakes are active once the supply voltage is switched off (closed-circuit principle). Where the brakes are used purely as holding brakes, there is practically no wear on the friction surfaces.

Caution:

The brakes used are not safety brakes in the sense that a reduction in torque may arise as a result of disruptive factors that cannot be influenced, e.g. oil ingress.

The ohmic voltage drop along the cable must be taken into consideration in long motor supply cables and must be compensated for by a higher voltage at the line input.

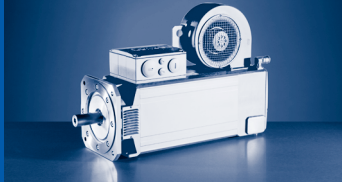
The following applies for Lenze system cables:

$$U[V] = U_B[V] + 0.08 \frac{[V]}{[A] \cdot [m]} \cdot l_g[m] \cdot I_B[A]$$

If no suitable voltage (incorrect value, incorrect polarity) is applied to the brake, the brake will be applied and can be overheated and destroyed by the motor continuing to rotate. The shortest switching times of the brakes are achieved by DC switching of the voltage. A spark suppressor is required to suppress interference and to increase the service life of the relay contacts here.



Spring-applied brake



MQA asynchronous servo motors

Accessories

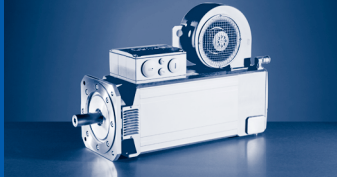
Holding brake data

| | $U_{N, DC}^{3, 6)}$ | $U_{N, AC}^{4, 6)}$ | M_N | M_N | M_{av} | $I_N^{2)}$ | J | $t_1^{1)}$ | $t_2^{1)}$ | $Q_E^{5)}$ | m | J_{MB} | J_L / J_{MB} |
|-------|---------------------|---------------------|-------|--------|----------|------------|----------------------|------------|------------|------------|------|----------------------|----------------|
| | | | 20 °C | 120 °C | 120 °C | | | | | | | | |
| | [V] | [V] | [Nm] | [Nm] | [Nm] | [A] | [kgcm ²] | [ms] | [ms] | [J] | [kg] | [kgcm ²] | |
| MQA20 | 24 | | 90.0 | 80.0 | 50.0 | 3.13 | 6.88 | 70.0 | 220 | 18000 | 13.0 | 177 | 19.6 |
| | | 230 | | | | 0.37 | | | | | | | |
| MQA22 | 24 | | 150 | 130 | 80.0 | 3.75 | 18.1 | 50.0 | 260 | 23000 | 20.5 | 505 | 8.20 |
| | | 230 | | | | 0.44 | | 130 | | | | | |
| MQA26 | 24 | | 300 | 260 | 200 | 3.13 | 70.4 | 175 | 320 | 51000 | 30.7 | 1405 | 12.7 |
| | | 230 | | | | 0.37 | | | 360 | | | | |

Holding brake data, reinforced design

| | $U_{N, DC}^{3, 6)}$ | $U_{N, AC}^{4, 6)}$ | M_N | M_N | M_{av} | $I_N^{2)}$ | J | $t_1^{1)}$ | $t_2^{1)}$ | $Q_E^{5)}$ | m | J_{MB} | J_L / J_{MB} |
|-------|---------------------|---------------------|-------|--------|----------|------------|----------------------|------------|------------|------------|------|----------------------|----------------|
| | | | 20 °C | 120 °C | 120 °C | | | | | | | | |
| | [V] | [V] | [Nm] | [Nm] | [Nm] | [A] | [kgcm ²] | [ms] | [ms] | [J] | [kg] | [kgcm ²] | |
| MQA20 | 24 | | 150 | 130 | 100 | 2.58 | 14.1 | 70.0 | 240 | 31000 | 15.4 | 185 | 33.0 |
| | | 230 | | | | 0.30 | | | | | | | |
| MQA22 | 24 | | 300 | 260 | 160 | 3.75 | 36.3 | 175 | 320 | 39000 | 26.0 | 523 | 14.1 |
| | | 230 | | | | 0.44 | | 130 | | | | | |
| MQA26 | 24 | | 500 | 430 | 260 | 3.75 | 70.4 | 175 | 390 | 51000 | 30.8 | 1405 | 12.7 |
| | | 230 | | | | 0.44 | | | | | | | |

- 1) Engagement and disengagement times are valid for rated voltage ($\pm 0\%$) and protective circuit for brakes with varistor for DC switching. The times may increase without a protective circuit.
- 2) The currents are the maximum values when the brake is cold (value used for dimensioning the current supply). The values for a motor at operating temperature are considerably lower.
- 3) With 24V DC brake: smoothed DC voltage, ripple $\leq 1\%$.
- 4) UR not possible in the case of a brake with 230 V supply voltage.
- 5) Maximum switching energy per emergency stop at $n = 3000$ r/min for at least 2000 emergency stops.
- 6) Voltage tolerance: permanent magnet brakes $-10 \dots 5\%$
spring-applied brakes $\pm 10\%$

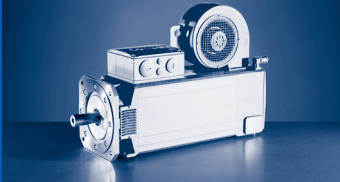


Blower data 50 Hz

| | | Enclosure | Number of phases | U_{\min} | U_{\max} | $U_{N,AC}$ | P_N | I_N |
|-------|------------|-----------|------------------|------------|------------|------------|-------|-------|
| | | | | [V] | [V] | [V] | [kW] | [A] |
| MQA20 | F10 F1F | IP23s | 1 | 210 | 250 | 230 | 0.090 | 0.39 |
| | F30 F3F | | 3 | 360 | 440 | 400 | 0.067 | 0.13 |
| MQA22 | F10 F1F | | 1 | 210 | 250 | 230 | 0.26 | 1.10 |
| | F30 F3F | | 3 | 360 | 440 | 400 | 0.23 | 0.37 |
| MQA26 | F10 F1F | | 1 | 210 | 250 | 230 | 0.40 | 1.75 |
| | F30 F3F | | 3 | 360 | 440 | 400 | 0.43 | 0.68 |

Blower data 60 Hz

| | | Enclosure | Number of phases | U_{\min} | U_{\max} | $U_{N,AC}$ | P_N | I_N |
|-------|------------|-----------|------------------|------------|------------|------------|-------|-------|
| | | | | [V] | [V] | [V] | [kW] | [A] |
| MQA20 | F10 F1F | IP23s | 1 | 210 | 250 | 230 | 0.12 | 0.49 |
| | F30 F3F | | 3 | 440 | 520 | 480 | 0.10 | 0.16 |
| MQA22 | F10 F1F | | 1 | 210 | 250 | 230 | 0.30 | 1.28 |
| | F30 F3F | | 3 | 440 | 520 | 480 | 0.37 | 0.48 |
| MQA26 | F10 F1F | | 1 | 210 | 250 | 230 | 0.41 | 1.82 |
| | F30 F3F | | 3 | 440 | 520 | 480 | 0.60 | 0.79 |



MQA asynchronous servo motors

Accessories

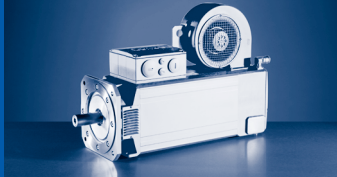
Tailored to meet the requirements of the various applications and necessary accuracies, the following feedback systems are available.

Resolver

Stator-fed resolver with two stator windings offset by 90° and one rotor winding with transformer winding.


| | | | | |
|-----------------------------------|---------------|-----------|---------|---------------------------------|
| Speed/angle sensor | ¹⁾ | | | R50 |
| Resolution | | | [°] | 0.80 |
| Angle | | | [°] | -10 ... 10 |
| Accuracy | | | [°] | -10 ... 10 |
| Absolute positioning | | | | 1 revolution |
| Max. speed | n_{max} | | [r/min] | 8000 |
| Max. input voltage | $U_{in,max}$ | | [V] | 10.0 |
| DC | | | | |
| Max. input frequency | $f_{in,max}$ | | [kHz] | 4.00 |
| Ratio | | $\pm 5\%$ | | 0.30 |
| Stator / rotor | | | | |
| Rotor impedance | Z_{ro} | | [Ω] | 51 + j90 |
| Stator impedance | Z_{so} | | [Ω] | 102 + j150 |
| Impedance | Z_{rs} | | [Ω] | 44 + j76 |
| Min. insulation resistance | R | | [MΩ] | 10.0 |
| At DC 500 V | | | | |
| Number of pole pairs | | | | 1 |
| Max. angle error | | | [°] | -10 ... 10 |
| Inverter assignment | | | | E84AVTC E94A ECS EVS93 |

¹⁾ → 18 - Product key > speed/angle sensor

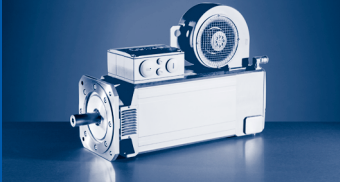


Incremental encoder and SinCos absolute value encoder

| Encoder type | | | TTL incremental | | SinCos incremental | SinCos absolute value | | | | |
|--------------------------|--------------|---------|---------------------------------|-------------|--------------------|-----------------------|--------------|-------------|-------------|--|
| | | | T20 | T40 | S20 | SRS | SRM | ECN | EQN | |
| Speed/angle sensor | 1) | | IG2048-5V-T | IG4096-5V-T | IG2048-5V-S | AS1024-8V-H | AM1024-8V-H | AS2048-5V-E | AM2048-5V-E | |
| Encoder type | | | Single-turn | | | Multi-turn | Single-turn | Multi-turn | | |
| Pulses | | | 2048 | 4096 | 2048 | 1024 | | 2048 | | |
| Output signals | | | TTL | | | 1 Vss | | | | |
| Interfaces | | | | | | Hiperface | | EnDat | | |
| Absolute revolutions | | | 0 | | 1 | 4096 | 1 | 4096 | | |
| Resolution Angle 2) | | [°] | 2.60 | | 0.40 | | | | | |
| Accuracy | | [°] | -2 ... 2 | | -0.8 ... 0.8 | | -0.6 ... 0.6 | | | |
| Min. input voltage DC | $U_{in,min}$ | [V] | 4.75 | 4.50 | 7.00 | 4.75 | | | | |
| Max. input voltage DC | $U_{in,max}$ | [V] | 5.25 | 5.50 | 12.0 | 5.25 | | | | |
| Max. speed | n_{max} | [r/min] | 8789 | 5273 | 6000 | 12000 | | | | |
| Max. current consumption | I_{max} | [A] | 0.15 | 0.10 | 0.080 | 0.15 | 0.25 | | | |
| Limit frequency | f_{max} | [kHz] | 300 | 180 | 200 | | | | | |
| Inverter assignment | | | E84AVTC E94A ECS EVS93 | | | | E94A | | | |

1) →  18 - Product key > speed/angle sensor

2) Dependent on inverter.

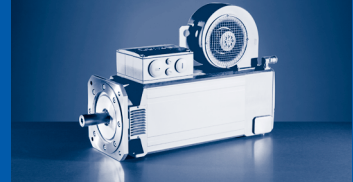


Safety SinCos incremental encoder

- ▶ Safe encoder thanks to integrated functional safety

| Encoder type | | | SinCos incremental |
|--|--------------|---------|---|
| Speed/angle sensor | 1) | | S1S |
| | | | IG1024-5V-V |
| Encoder type | | | Single-turn |
| Pulses | | | 1024 |
| Output signals | | | 1 Vss |
| Min. input voltage DC | $U_{in,min}$ | [V] | 4.75 |
| Max. input voltage DC | $U_{in,max}$ | [V] | 5.25 |
| Max. speed | n_{max} | [r/min] | 8000 |
| Max. current consumption | I_{max} | [A] | 0.070 |
| Limit frequency | f_{max} | [kHz] | 200 |
| Functional safety EN 13849-1 EN 954-1 IEC 61508 | | | Up to Performance Level e Category 4 SIL3 |
| Inverter assignment | | | E94A |

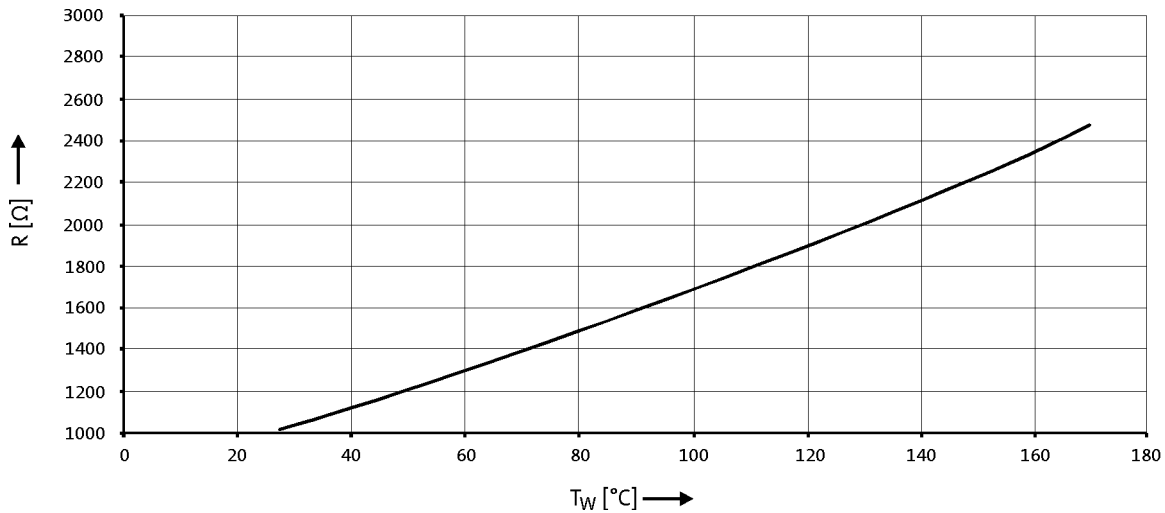
1) → 18 - Product key > speed/angle sensor



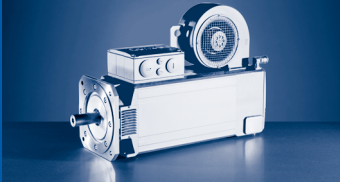
Thermal sensor

The thermal sensors (1x KTY 83-110) used continuously monitor the motor temperature. The temperature signal is transmitted over the system cable of the feedback system to the servo controller.

This means that the temperature of the motor is determined with great accuracy in the permitted operating range and at the same time the overtemperature response configured in the controller is executed in the event of overtemperature in one of the winding phases.



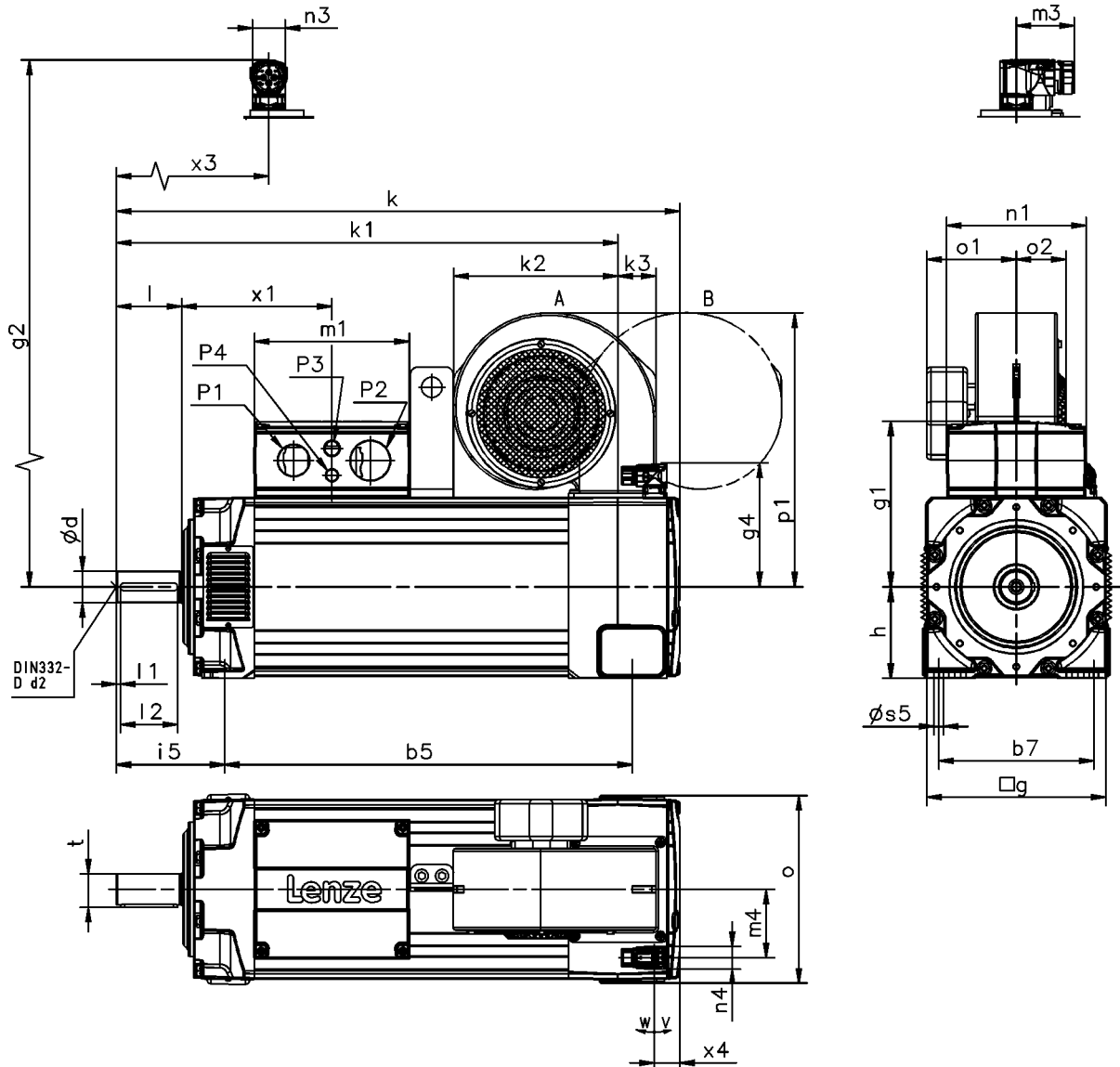
- ▶ If the detector is supplied with a measured current of 1 mA, the above relationship between the temperature and the resistance applies.



MQA asynchronous servo motors

Dimensions [mm]

Motors with blower, B3

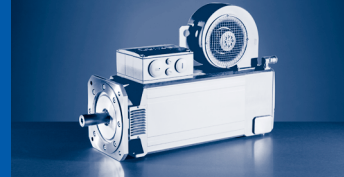


| | | | MQA20 | MQA22 | MQA26 |
|----------------------------|-------|------|-------|-------|-------|
| RS0 / E□□ / T□□ / S□□ / B0 | k | [mm] | 577 | 691 | 841 |
| | x_4 | [mm] | 33.0 | 31.0 | 24.0 |
| | m_4 | [mm] | 74.0 | 84.0 | 100 |
| RS0 F1 | k | [mm] | 661 | 773 | 979 |
| | x_4 | [mm] | 41.0 | 40.0 | |
| | m_4 | [mm] | 70.0 | 76.0 | 96.0 |
| E□□ / T□□ / S□□ / F1 | k | [mm] | 704 | 816 | 1017 |
| | x_4 | [mm] | 46.0 | 45.0 | 40.0 |
| | m_4 | [mm] | 70.0 | 76.0 | 96.0 |
| RS0 / E□□ / T□□ / S□□ / F2 | k | [mm] | 729 | 848 | 1017 |
| | x_4 | [mm] | 46.0 | 45.0 | 40.0 |
| | m_4 | [mm] | 70.0 | 76.0 | 96.0 |

- ▶ Speed/angle sensor: RS0 / S□□ / E□□ / T□□
- ▶ Brake: B0 / F1 / F2

MQA asynchronous servo motors

Dimensions [mm]



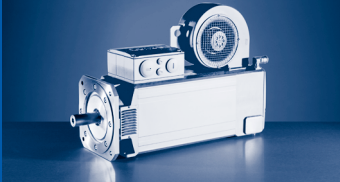
| | g | g ₁ | g ₂ | g ₄ | m ₁ | m ₃ | n ₁ | n ₃ | n ₄ |
|--------------|------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MQA20 | 200 | 171 | 168 | 141 | 154 | 72 | 128 | 40 | 28 |
| MQA22 | 220 | 203 | | 153 | 190 | | 171 | | |
| MQA26 | 260 | 256 | | 173 | 238 | | 212 | | |

| | o | P ₁ | P ₂ | P ₃ | P ₄ | v | w | x ₁ | x ₃ |
|--------------|------|----------------|----------------|----------------|----------------|-----|-----|----------------|----------------|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [°] | [°] | [mm] | [mm] |
| MQA20 | 206 | M32x1.5 | M25x1.5 | M20x1.5 | | 195 | 80 | 155 | 192 |
| MQA22 | 230 | M50x1.5 | M40x1.5 | | M16x1.5 | | | 174 | |
| MQA26 | 266 | M63x1.5 | M50x1.5 | | 218 | | | | |

| | d | d | d ₂ | l | l ₁ | l ₂ | u | t |
|--------------|------|------|----------------|--------------|----------------|----------------|------|------|
| | k6 | m6 | | -0.7 ... 0.3 | | | | |
| | [mm] | [mm] | [mm] | | [mm] | [mm] | [mm] | [mm] |
| MQA20 | 38 | | M12 | 80 | 5.0 | 70 | 10.0 | 41 |
| MQA22 | | | | | | | | |
| MQA26 | | 55 | M20 | 110 | | 100 | 16.0 | 59 |

| | h | b ₅ | b ₇ | s ₅ | i ₅ |
|--------------|------|----------------|----------------|----------------|----------------|
| | [mm] | [mm] | [mm] | [mm] | [mm] |
| MQA20 | 100 | 386 | 160 | 11.5 | 134 |
| MQA22 | 112 | 500 | 190 | | 133 |
| MQA26 | 132 | 605 | 215 | 14.0 | 165 |

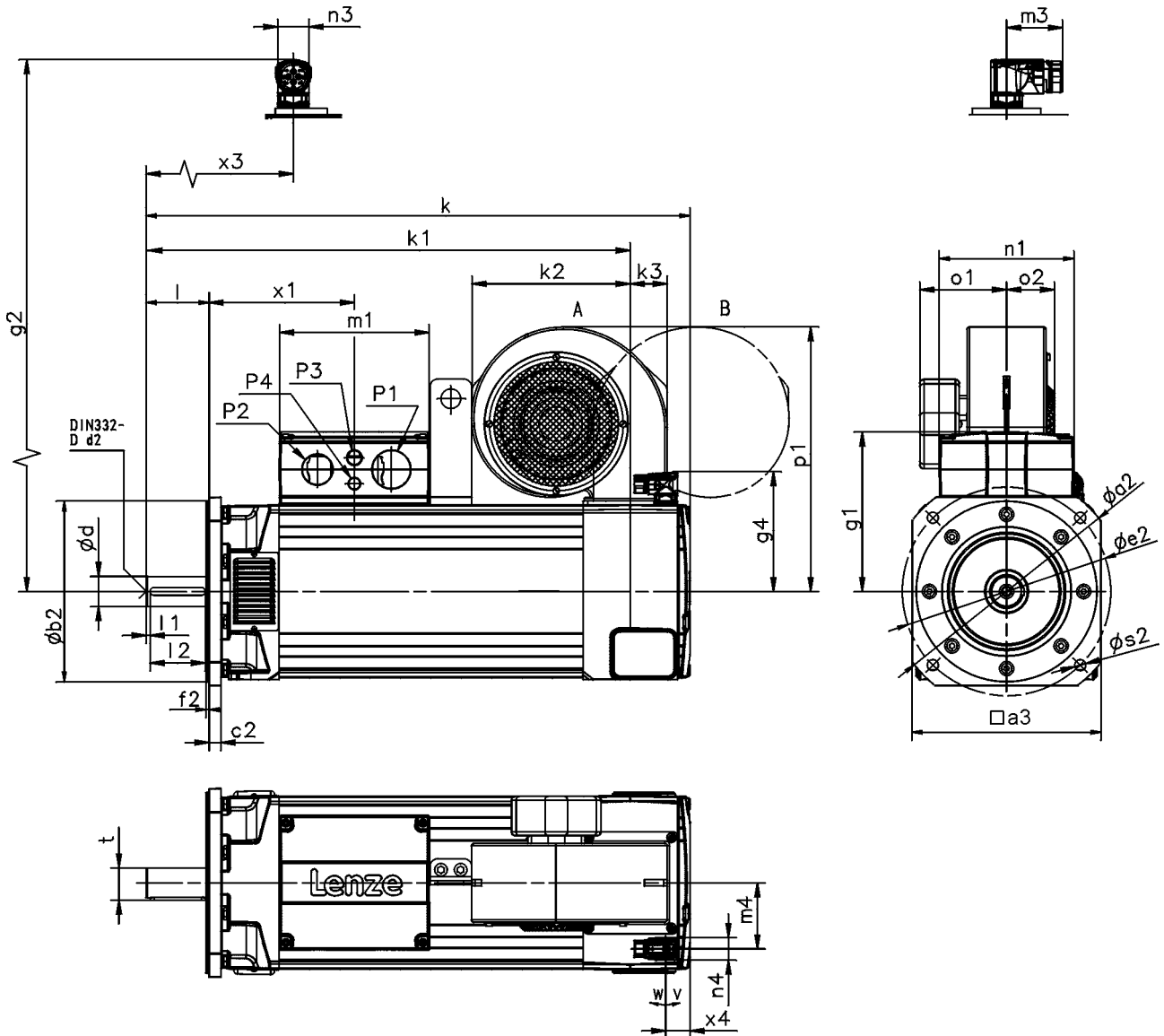
| | F10 / F30 | | | | | | F1F / F3F | | | | | | |
|--------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|------|
| | k ₁ | k ₂ | k ₃ | o ₁ | o ₂ | p ₁ | k ₁ | k ₂ | k ₃ | o ₁ | o ₂ | p ₁ | |
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MQA20 | 498 | 152 | 32.0 | 118 | 47.0 | 276 | 498 | 152 | 32.0 | 118 | 124 | 276 | |
| MQA22 | 615 | 201 | 47.0 | 104 | 63.0 | 336 | 615 | 201 | 47.0 | 104 | 144 | 336 | |
| MQA26 | 764 | 221 | 60.0 | 120 | 86.0 | 391 | 764 | 221 | 60.0 | 120 | 140 | 391 | |



MQA asynchronous servo motors

Dimensions [mm]

Motors with blower, B5

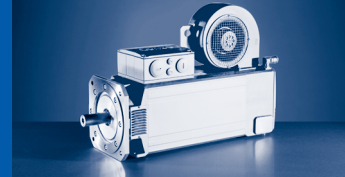


| | | | MQA20 | MQA22 | MQA26 |
|----------------------------|-------|------|-------|-------|-------|
| RS0 / E□□ / T□□ / S□□ / B0 | k | [mm] | 577 | 691 | 841 |
| | x_4 | [mm] | 33.0 | 31.0 | 24.0 |
| | m_4 | [mm] | 74.0 | 84.0 | 100 |
| RS0 F1 | k | [mm] | 661 | 773 | 979 |
| | x_4 | [mm] | 41.0 | 40.0 | |
| | m_4 | [mm] | 70.0 | 76.0 | 96.0 |
| E□□ / T□□ / S□□ / F1 | k | [mm] | 704 | 816 | 1017 |
| | x_4 | [mm] | 46.0 | 45.0 | 40.0 |
| | m_4 | [mm] | 70.0 | 76.0 | 96.0 |
| RS0 / E□□ / T□□ / S□□ / F2 | k | [mm] | 729 | 848 | 1017 |
| | x_4 | [mm] | 46.0 | 45.0 | 40.0 |
| | m_4 | [mm] | 70.0 | 76.0 | 96.0 |

- ▶ Speed/angle sensor: RS0 / S□□ / E□□ / T□□
- ▶ Brake: B0 / F1 / F2

MQA asynchronous servo motors

Dimensions [mm]



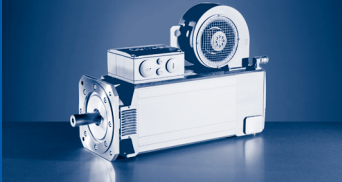
| | g | g ₁ | g ₂ | g ₄ | m ₁ | m ₃ | n ₁ | n ₃ | n ₄ |
|--------------|------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MQA20 | 200 | 171 | 168 | 141 | 154 | 72 | 128 | 40 | 28 |
| MQA22 | 220 | 203 | | 153 | 190 | | 171 | | |
| MQA26 | 260 | 256 | | 173 | 238 | | 212 | | |

| | o | P ₁ | P ₂ | P ₃ | P ₄ | v | w | x ₁ | x ₃ |
|--------------|------|----------------|----------------|----------------|----------------|-----|-----|----------------|----------------|
| | [mm] | [mm] | [mm] | [mm] | [mm] | [°] | [°] | [mm] | [mm] |
| MQA20 | 206 | M32x1.5 | M25x1.5 | M20x1.5 | M16x1.5 | 195 | 80 | 155 | 192 |
| MQA22 | 230 | M50x1.5 | M40x1.5 | | | | | 174 | |
| MQA26 | 266 | M63x1.5 | M50x1.5 | | | | | 218 | |

| | d | d | d ₂ | l | l ₁ | l ₂ | u | t | |
|--------------|------|------|----------------|--------------|----------------|----------------|------|------|--|
| | k6 | m6 | | -0.7 ... 0.3 | | | | | |
| | [mm] | [mm] | [mm] | | [mm] | [mm] | [mm] | [mm] | |
| MQA20 | 38 | | M12 | 80 | 5.0 | 70 | 10.0 | 41 | |
| MQA22 | | | | | | | | | |
| MQA26 | | 55 | M20 | 110 | | 100 | 16.0 | 59 | |

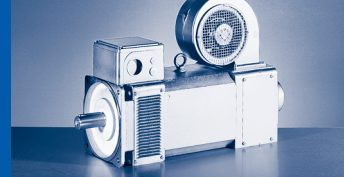
| | | | MQA20 | MQA22 | MQA26 |
|----------------|----|------|-------|-------|-------|
| | | | FF215 | FF265 | FF350 |
| a ₂ | | [mm] | 250 | 300 | 400 |
| a ₃ | | [mm] | 196 | 240 | 320 |
| b ₂ | j6 | [mm] | 180 | 230 | |
| b ₂ | h6 | [mm] | | | 300 |
| c ₂ | | [mm] | | 15 | |
| e ₂ | | [mm] | 215 | 265 | 350 |
| f ₂ | | [mm] | | 4.0 | 5.0 |
| s ₂ | | [mm] | | 14 | 18 |

| | F10 / F30 | | | | | | F1F / F3F | | | | | |
|--------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
| | k ₁ | k ₂ | k ₃ | o ₁ | o ₂ | p ₁ | k ₁ | k ₂ | k ₃ | o ₁ | o ₂ | p ₁ |
| | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] | [mm] |
| MQA20 | 498 | 152 | 32.0 | 118 | 47.0 | 276 | 498 | 152 | 32.0 | 118 | 124 | 276 |
| MQA22 | 615 | 201 | 47.0 | 104 | 63.0 | 336 | 615 | 201 | 47.0 | 104 | 144 | 336 |
| MQA26 | 764 | 221 | 60.0 | 120 | 86.0 | 391 | 764 | 221 | 60.0 | 120 | 140 | 391 |



MQA asynchronous servo motors

Dimensions [mm]



Mains connection 3x 400 V

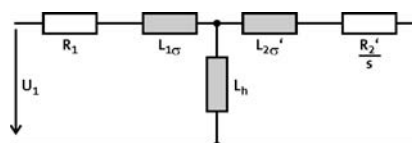
| | n_N | M_0 | M_{max} | M_N | P_N | I_0 | I_N | $U_{N, AC}$ | f_N | $J^{1)}$ | $\eta_{100\%}$ |
|----------------------|---------|-------|-----------|-------|-------|-------|-------|-------------|-------|----------------------|----------------|
| | [r/min] | [Nm] | [Nm] | [Nm] | [kW] | [A] | [A] | [V] | [Hz] | [kgcm ²] | [%] |
| MDFQA□□160-32, 18, Y | 498 | 480 | 1400 | 433 | 22.6 | 56.0 | 51.5 | 360 | 18 | 2900 | 81 |
| MDFQA□□160-32, 31, Δ | 890 | 480 | 1400 | 434 | 40.5 | 95.0 | 87.0 | 355 | 31 | 2900 | 89 |
| MDFQA□□160-32, 44, Y | 1280 | 470 | 1400 | 410 | 55.0 | 130 | 116 | 340 | 44 | 2900 | 91 |
| MDFQA□□160-32, 78, Δ | 2295 | 470 | 1400 | 395 | 95.0 | 230 | 196 | 340 | 78 | 2900 | 93 |

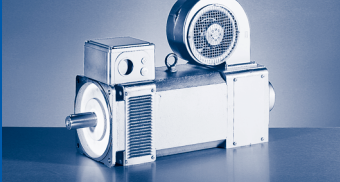
| | R_1 | $R_{UV\ 20\ ^\circ C}$ | $R_{UV\ 150\ ^\circ C}$ | R_2 | $L_{1\sigma}$ | L | $L_{2\sigma}$ | $n_{max}^{2)}$ | $m^{1)}$ |
|----------------------|-------|------------------------|-------------------------|-------|---------------|------|---------------|----------------|----------|
| | [Ω] | [Ω] | [Ω] | [Ω] | [mH] | [mH] | [mH] | [r/min] | [kg] |
| MDFQA□□160-32, 18, Y | 0.22 | 0.45 | 0.60 | 0.20 | 2.65 | 73.8 | 2.23 | 6500 | 300 |
| MDFQA□□160-32, 31, Δ | | 0.15 | 0.20 | | | 76.1 | | | |
| MDFQA□□160-32, 44, Y | 0.040 | 0.078 | 0.10 | 0.040 | 0.47 | 15.6 | 0.39 | | |
| MDFQA□□160-32, 78, Δ | | 0.026 | 0.035 | | 0.48 | 16.2 | 0.38 | | |

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.

The data in the R_1 , $L_{1\sigma}$, L_h , R_2' and $L_{2\sigma}'$ columns is based on a single-phase equivalent circuit diagram at 20°C.

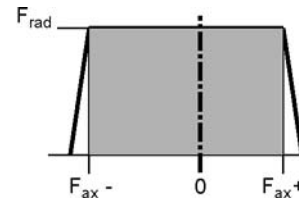
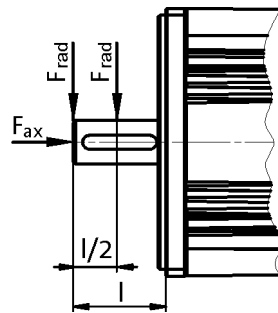




MDFQA asynchronous servo motors

Rated data

Permissible radial and axial forces



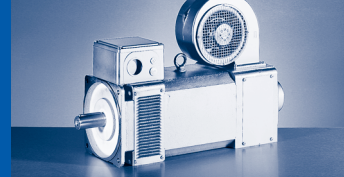
Application of force at l/2

| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|-------------------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MDFQA□□160 | 5400 | -3610 | 2530 | 4330 | -2650 | 1570 | 3480 | -1940 | 860 | 3070 | -1610 | 530 | 2620 | -1280 | 200 |

Application of force at l

| | Bearing service life L_{10} | | | | | | | | | | | | | | |
|-------------------|-------------------------------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|-----------|------------|------------|
| | 5000 h | | | 10000 h | | | 20000 h | | | 30000 h | | | 50000 h | | |
| | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ | F_{rad} | $F_{ax,-}$ | $F_{ax,+}$ |
| | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] | [N] |
| MDFQA□□160 | 4950 | -3400 | 2320 | 3970 | -2490 | 1410 | 3200 | -1820 | 740 | 2820 | -1510 | 430 | 2410 | -1200 | 120 |

- The values for the bearing service life L_{10} refer to an average speed of 3000 r/min. Depending on the ambient temperatures, the service life of the bearings is also reduced by the grease lifetime.



Mains connection 3 x 400 V and switching frequency 8 kHz

Y-connection motors

| | | | | | E94A□□ | E0594 |
|--------|-------|-------|-------|-------|-------------|--------|
| | | | | | I_N | 41.0 |
| | | | | | $I_{0,max}$ | 118.0 |
| MDFQA | M_N | n_N | I_N | P_N | I_{max} | 118.0 |
| 160-32 | 433.0 | 498 | 51.5 | 22.60 | M_0 | 342.0 |
| | | | | | M_N | 342.0 |
| | | | | | $M_{0,max}$ | 1064.0 |
| | | | | | M_{max} | 1064.0 |
| | | | | | n_{eto} | - |

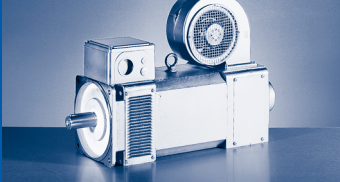
| | | | | | E94A□□ | E1454 | E1724 | E2024 |
|--------|-------|-------|-------|-------|-------------|-------|--------|--------|
| | | | | | I_N | 102.0 | 120.0 | 131.0 |
| | | | | | $I_{0,max}$ | 261.0 | 310.0 | 364.0 |
| MDFQA | M_N | n_N | I_N | P_N | I_{max} | 261.0 | 310.0 | 364.0 |
| 160-32 | 410.0 | 1280 | 115.5 | 55.00 | M_0 | 363.0 | 433.0 | 470.0 |
| | | | | | M_N | 363.0 | 410.0 | 410.0 |
| | | | | | $M_{0,max}$ | 991.0 | 1177.0 | 1375.0 |
| | | | | | M_{max} | 991.0 | 1177.0 | 1375.0 |
| | | | | | n_{eto} | - | - | - |

Δ connected motors

| | | | | | E94A□□ | E0864 | E1044 | E1454 |
|--------|-------|-------|-------|-------|-------------|-------|--------|--------|
| | | | | | I_N | 73.0 | 78.0 | 102.0 |
| | | | | | $I_{0,max}$ | 172.0 | 208.0 | 261.0 |
| MDFQA | M_N | n_N | I_N | P_N | I_{max} | 172.0 | 208.0 | 261.0 |
| 160-32 | 434.0 | 890 | 87.0 | 40.50 | M_0 | 350.0 | 378.0 | 480.0 |
| | | | | | M_N | 350.0 | 378.0 | 434.0 |
| | | | | | $M_{0,max}$ | 915.0 | 1110.0 | 1390.0 |
| | | | | | M_{max} | 915.0 | 1110.0 | 1390.0 |
| | | | | | n_{eto} | - | - | - |

| | | | | | E94A□□ | E2454 | E2924 | E3664 |
|--------|-------|-------|-------|-------|-------------|-------|--------|--------|
| | | | | | I_N | 160.0 | 191.0 | 240.0 |
| | | | | | $I_{0,max}$ | 441.0 | 526.0 | 659.0 |
| MDFQA | M_N | n_N | I_N | P_N | I_{max} | 441.0 | 526.0 | 659.0 |
| 160-32 | 395.0 | 2295 | 195.5 | 95.00 | M_0 | 308.0 | 380.0 | 470.0 |
| | | | | | M_N | 308.0 | 380.0 | 395.0 |
| | | | | | $M_{0,max}$ | 881.0 | 1048.0 | 1301.0 |
| | | | | | M_{max} | 881.0 | 1048.0 | 1301.0 |
| | | | | | n_{eto} | - | - | - |

- ▶ $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]
- ▶ If the motors are operated at a lower switching frequency, please contact your Lenze sales office!
- ▶ When operating at 4 kHz, the motor generates just 95 % of its rated torque with increased noise emissions.



MDFQA asynchronous servo motors

EVS9300 servo inverter selection tables

Mains connection 3 x 400 V and switching frequency 8 kHz

Y-connection motors

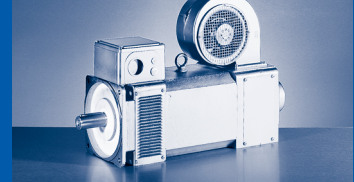
| | | | | | EVS | 9328-E□ | 9329-E□ | 9330-E□ |
|--------|-------|-------|-------|-------|-------------|---------|---------|---------|
| | | | | | I_N | 47.0 | 59.0 | 89.0 |
| | | | | | $I_{0,max}$ | 47.0 | 52.0 | 80.0 |
| MDFQA | M_N | n_N | I_N | P_N | I_{max} | 70.5 | 88.5 | 133.5 |
| 160-32 | 433.0 | 498 | 51.5 | 22.60 | M_0 | 395.0 | 435.0 | 480.0 |
| | | | | | M_N | 395.0 | 433.0 | 433.0 |
| | | | | | $M_{0,max}$ | 395.0 | 435.0 | 680.0 |
| | | | | | M_{max} | 615.0 | 795.0 | 1260.0 |
| | | | | | n_{eto} | - | - | - |

| | | | | | EVS | 9331-E□ | 9332-E□ |
|--------|-------|-------|-------|-------|-------------|---------|---------|
| | | | | | I_N | 110.0 | 145.0 |
| | | | | | $I_{0,max}$ | 110.0 | 126.0 |
| MDFQA | M_N | n_N | I_N | P_N | I_{max} | 165.0 | 217.5 |
| 160-32 | 410.0 | 1280 | 115.5 | 55.00 | M_0 | 365.0 | 470.0 |
| | | | | | M_N | 365.0 | 410.0 |
| | | | | | $M_{0,max}$ | 365.0 | 455.0 |
| | | | | | M_{max} | 630.0 | 850.0 |
| | | | | | n_{eto} | - | - |

Δ connected motors

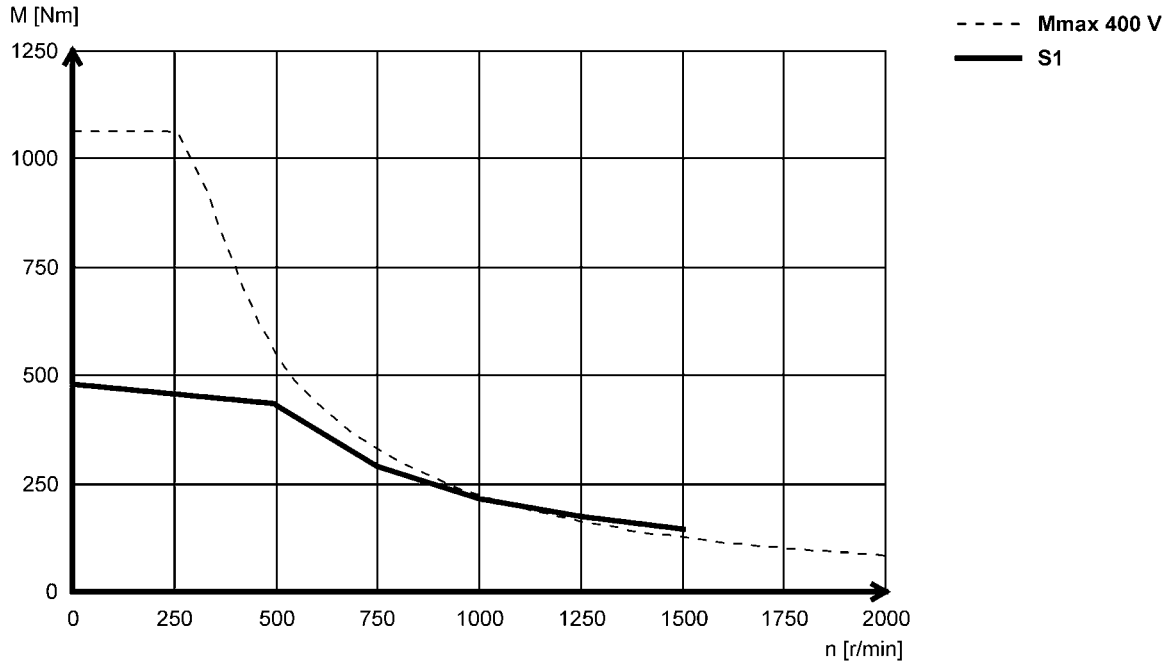
| | | | | | EVS | 9330-E□ | 9331-E□ | 9332-E□ |
|--------|-------|-------|-------|-------|-------------|---------|---------|---------|
| | | | | | I_N | 89.0 | 110.0 | 145.0 |
| | | | | | $I_{0,max}$ | 80.0 | 110.0 | 126.0 |
| MDFQA | M_N | n_N | I_N | P_N | I_{max} | 133.5 | 165.0 | 217.5 |
| 160-32 | 434.0 | 890 | 87.0 | 40.50 | M_0 | 435.0 | 480.0 | 480.0 |
| | | | | | M_N | 434.0 | 434.0 | 434.0 |
| | | | | | $M_{0,max}$ | 385.0 | 585.0 | 731.0 |
| | | | | | M_{max} | 668.0 | 850.0 | 1140.0 |
| | | | | | n_{eto} | - | - | - |

► $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

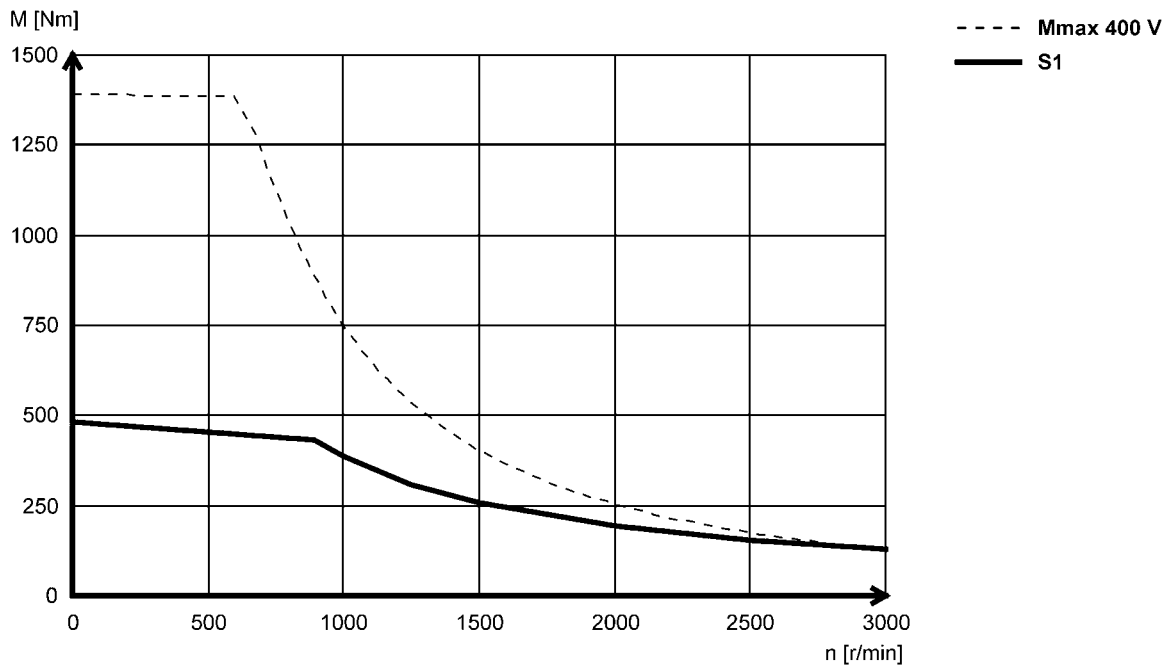


Mains connection 3x 400 V

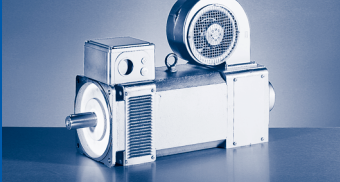
MDFQA160-32, 31, Y



MDFQA160-32, 31, Δ



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.

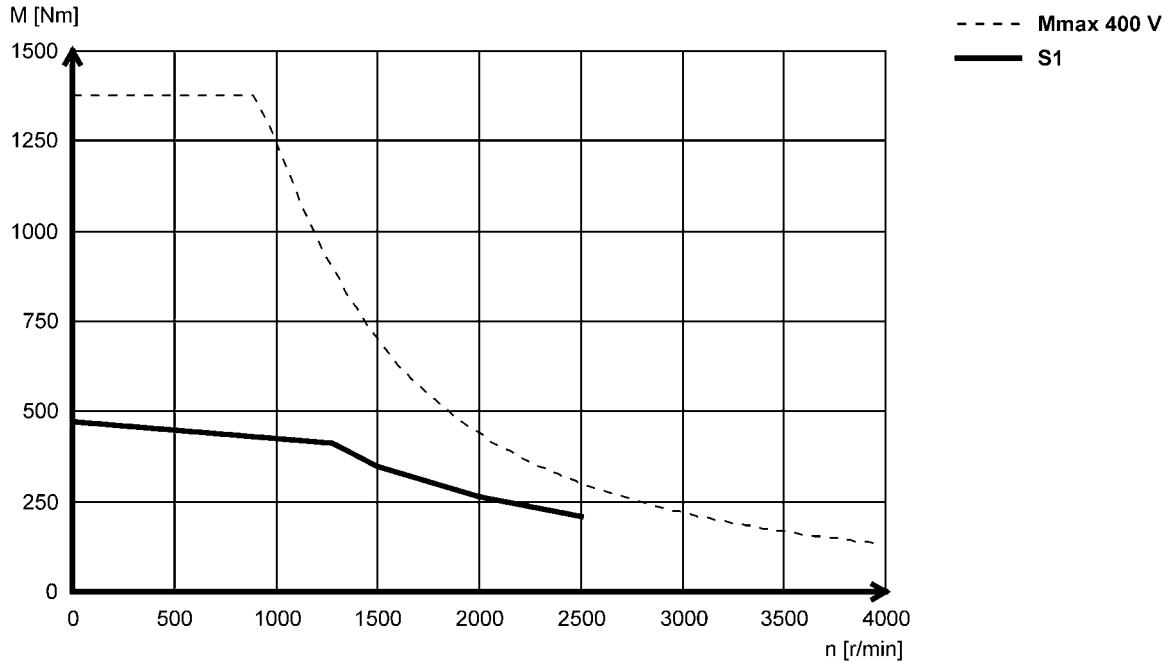


MDFQA asynchronous servo motors

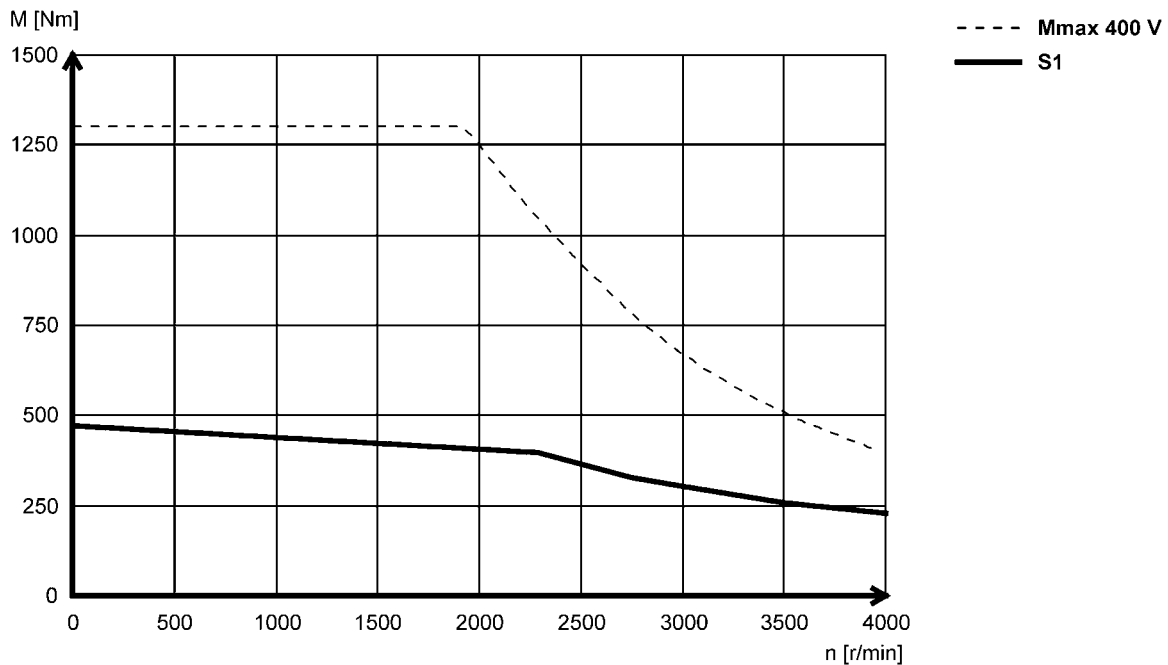
Torque characteristics

Mains connection 3x 400 V

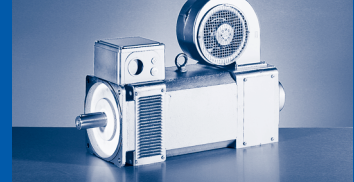
MDFQA160-32, 78, Y



MDFQA160-32, 78, Δ



► Other torque characteristics with Lenze inverters can be found at www.lenze.de/dsc.



Holding brakes

The MDFQA asynchronous servo motors can be equipped with integral spring-applied holding brakes. The voltages available for this model are 24 V DC and 205 V DC.

The brakes are active once the supply voltage is switched off (closed-circuit principle). Where the brakes are used purely as holding brakes, there is practically no wear on the friction surfaces.

Caution:

The brakes used are not safety brakes in the sense that a reduction in torque may arise as a result of disruptive factors that cannot be influenced, e.g. oil ingress.

The ohmic voltage drop along the cable must be taken into consideration in long motor supply cables and must be compensated for by a higher voltage at the line input.

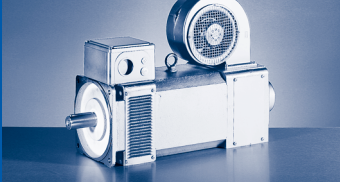
The following applies for Lenze system cables:

$$U[V] = U_B[V] + 0.08 \frac{[V]}{[A] \cdot [m]} \cdot l_g[m] \cdot I_B[A]$$

If no suitable voltage (incorrect value, incorrect polarity) is applied to the brake, the brake will be applied and can be overheated and destroyed by the motor continuing to rotate. The shortest switching times of the brakes are achieved by DC switching of the voltage. A spark suppressor is required to suppress interference and to increase the service life of the relay contacts here.



Spring-applied brake



MDFQA asynchronous servo motors

Accessories

Holding brake data

| | | $U_{N,DC}^{4)}$ | $M_N^{1)}$ | $I_N^{5)}$ | J | $t_1^{2,3)}$ | $t_2^{2)}$ | $Q_E^{-1)}$ | $S_{h\ddot{u}}$ |
|------------|----|-----------------|------------|------------|----------------------|--------------|------------|-------------|-----------------|
| | | [V] | [Nm] | [A] | [kgcm ²] | [ms] | [ms] | [J] | [1/h] |
| MDFQA□□160 | F1 | 24 | 400 | 4.17 | 73.0 | 165 | 340 | 80000 | 19.0 |
| | F5 | 205 | | 0.49 | | | | | |

Holding brake data, reinforced design

| | | $U_{N,DC}^{4)}$ | $M_N^{1)}$ | $I_N^{5)}$ | J | $t_1^{2,3)}$ | $t_2^{2)}$ | $Q_E^{-1)}$ | $S_{h\ddot{u}}$ |
|------------|----|-----------------|------------|------------|----------------------|--------------|------------|-------------|-----------------|
| | | [V] | [Nm] | [A] | [kgcm ²] | [ms] | [ms] | [J] | [1/h] |
| MDFQA□□160 | F2 | 24 | 600 | 4.58 | 200 | 175 | 585 | 120000 | 15.0 |
| | F6 | 205 | | 0.54 | | | | | |

¹⁾ Rated torques are related to the relative speed $\Delta n = 100$ r/min.

²⁾ Engagement and disengagement times are valid for rated voltage ($\pm 0\%$) and suppressor circuit for brakes with spark suppressors. The times may increase without a suppressor circuit. The operating times are mean values. Leakage depends on the type of rectifier, the air path and the coil current.

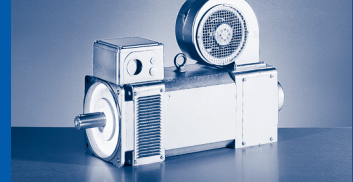
³⁾ Engagement times with DC side switching, in the case of AC side switching t_1 increases by a factor of about 10.

⁴⁾ With 24 V DC brake: smoothed DC voltage, ripple $\leq 1\%$.

With 205 V DC brake: connection to 230 V AC through rectifier.

⁵⁾ The currents are the maximum values when the brake is cold (value used for dimensioning the current supply). The values for a motor at operating temperature are considerably lower.

⁶⁾ Maximum switching energy per emergency stop at $n = 3000$ r/min for at least 2000 emergency stops.

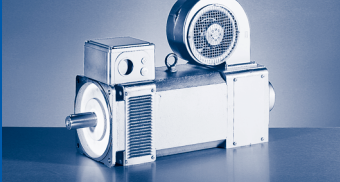


Blower data 50 Hz

| | Enclosure | Number of phases | | | | | |
|-------------------|-----------|------------------|------------|------------|-------------|-------|-------|
| | | | U_{\min} | U_{\max} | $U_{N, AC}$ | P_N | I_N |
| | | | [V] | [V] | [V] | [kW] | [A] |
| MDFQA□□160 | IP23s | 3 | 350 | 540 | 400 | 0.65 | 1.40 |

Blower data 60 Hz

| | Enclosure | Number of phases | | | | | |
|-------------------|-----------|------------------|------------|------------|-------------|-------|-------|
| | | | U_{\min} | U_{\max} | $U_{N, AC}$ | P_N | I_N |
| | | | [V] | [V] | [V] | [kW] | [A] |
| MDFQA□□160 | IP23s | 3 | 350 | 540 | 400 | 0.65 | 1.40 |



MDFQA asynchronous servo motors


Accessories

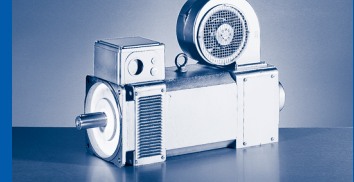
Tailored to meet the requirements of the various applications and necessary accuracies, the following feedback systems are available.

Resolver

Stator-fed resolver with two stator windings offset by 90° and one rotor winding with transformer winding.


| | | | | |
|-----------------------------------|---------------------|-----------|---------------|---------------------------------|
| Built-on accessories | ¹⁾ | | | BS RS |
| Resolution | | | | |
| Angle | | | [°] | 0.80 |
| Accuracy | | | | |
| | | | [°] | -10 ... 10 |
| Absolute positioning | | | | |
| | | | | 1 revolution |
| Max. speed | | | | |
| | n_{\max} | | [r/min] | 8000 |
| Max. input voltage | | | | |
| DC | $U_{\text{in,max}}$ | | [V] | 10.0 |
| Max. input frequency | | | | |
| | $f_{\text{in,max}}$ | | [kHz] | 4.00 |
| Ratio | | | | |
| Stator / rotor | | $\pm 5\%$ | | 0.30 |
| Rotor impedance | | | | |
| | Z_{ro} | | [Ω] | 51 + j90 |
| Stator impedance | | | | |
| | Z_{so} | | [Ω] | 102 + j150 |
| Impedance | | | | |
| | Z_{rs} | | [Ω] | 44 + j76 |
| Min. insulation resistance | | | | |
| At DC 500 V | R | | [M Ω] | 10.0 |
| Number of pole pairs | | | | |
| | | | | 1 |
| Max. angle error | | | | |
| | | | [°] | -10 ... 10 |
| Inverter assignment | | | | |
| | | | | E84AVTC E94A ECS EVS93 |

¹⁾ →  21 - Product key > built-on accessories

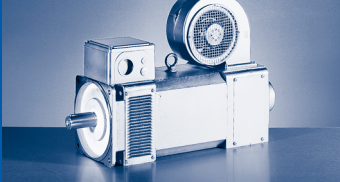


Incremental encoder and SinCos absolute value encoder

| Encoder type | | | TTL incremental | SinCos incremental |
|-----------------------------------|--------------|---------|---------------------------------|--------------------|
| Built-on accessories | 1) | | BI IG | |
| | | | IG2048-5V-T | IG2048-5V-S |
| Encoder type | | | | Single-turn |
| Pulses | | | 2048 | |
| Output signals | | | TTL | 1 V _{SS} |
| Interfaces | | | | |
| Absolute revolutions | | | 0 | |
| Resolution Angle ²⁾ | | [°] | 2.60 | 0.40 |
| Accuracy | | [°] | -2 ... 2 | -0.8 ... 0.8 |
| Min. input voltage DC | $U_{in,min}$ | [V] | 4.75 | 4.50 |
| Max. input voltage DC | $U_{in,max}$ | [V] | 5.25 | 5.50 |
| Max. speed | n_{max} | [r/min] | 8789 | 5273 |
| Max. current consumption | I_{max} | [A] | 0.15 | 0.10 |
| Limit frequency | f_{max} | [kHz] | 300 | 180 |
| Inverter assignment | | | E84AVTC E94A ECS EVS93 | |

1) →  21 - Product key > built-on accessories

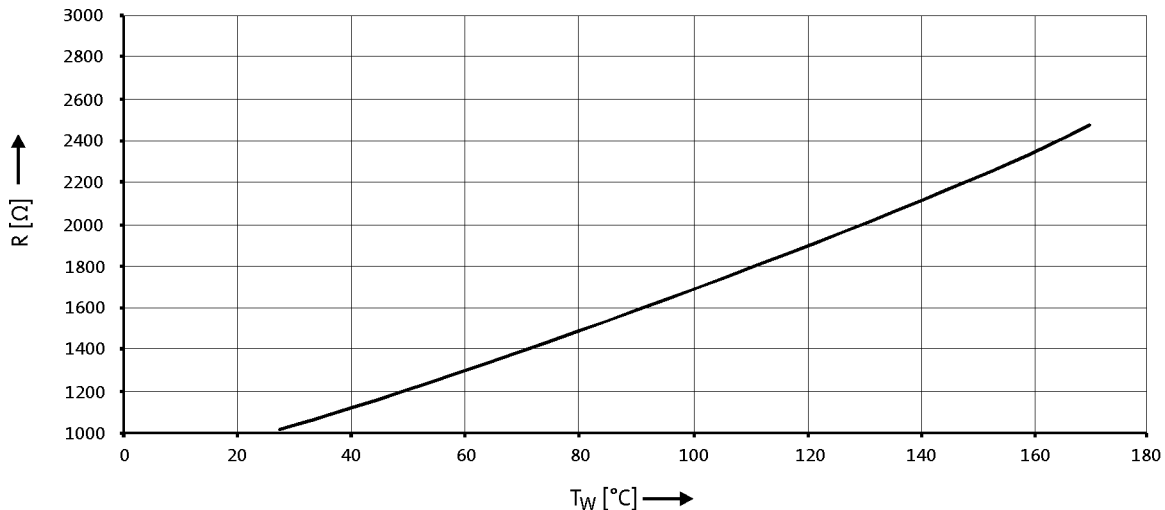
2) Dependent on inverter.



Thermal sensor

The thermal sensors (1x KTY 83-110) used continuously monitor the motor temperature. The temperature signal is transmitted over the system cable of the feedback system to the servo controller.

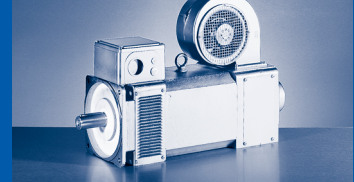
This means that the temperature of the motor is determined with great accuracy in the permitted operating range and at the same time the overtemperature response configured in the controller is executed in the event of overtemperature in one of the winding phases.



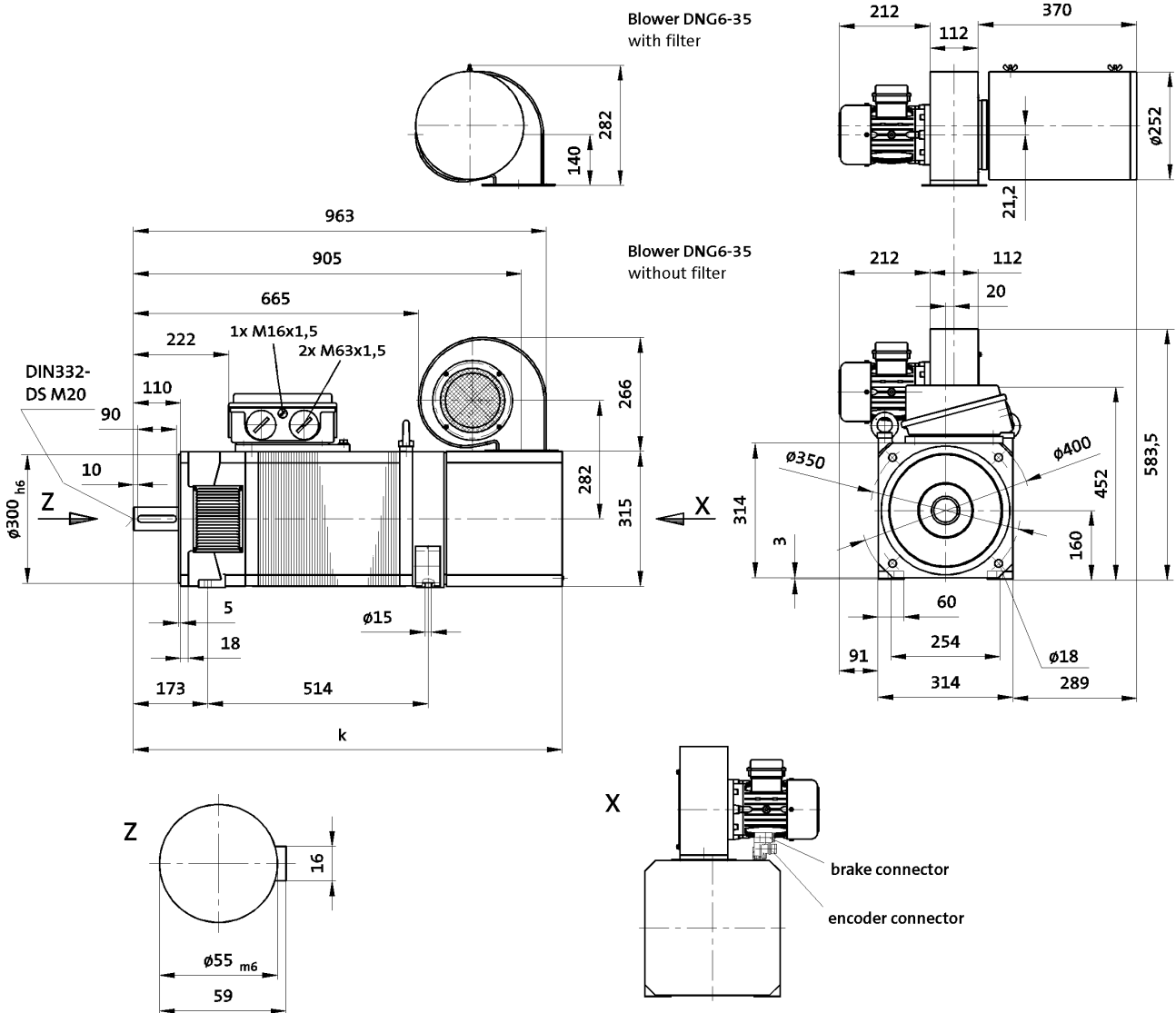
- If the detector is supplied with a measured current of 1 mA, the above relationship between the temperature and the resistance applies.

MDFQA asynchronous servo motors

Dimensions [mm]

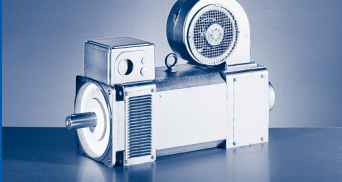


MDFQA□□160-32
B35A400



| | | | |
|--------------------|---|------|------|
| NN | k | [mm] | 1000 |
| RS | k | [mm] | 1000 |
| IG (ITD21 / ITD22) | k | [mm] | 1000 |
| AG | k | [mm] | 1000 |

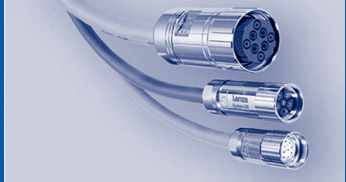
| | | | |
|--------------------|---|------|------|
| BR | k | [mm] | 1000 |
| BS | k | [mm] | 1000 |
| BI (ITD21 / ITD22) | k | [mm] | 1000 |
| BA | k | [mm] | 1000 |



MDFQA asynchronous servo motors

Dimensions [mm]

7



The motor cable is selected from the available cable cross-sections using the socket identifier M01/M02... (system cables – cable end product key).

- ▶ The following pages describe the socket/motor assignment.
- ▶ The available cable cross-sections can be found in the system cables product key.
- ▶ It is not possible to connect the MCS06 and MDSKS036 synchronous servo motors via terminal boxes.
- ▶ The cross-section of a cable and its current capacity must always be checked when a cable is connected to a motor through a terminal box.
- ▶ Every possible combination is described in detail in the System Cables Manual.
- ▶ This manual can be found at www.lenze.com - **Services & Downloads - Technical documentation - Library - X1_Accessories - X15_External_accessories.**

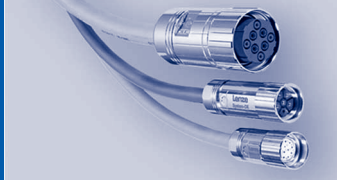


System cables

Assignment of socket to servo motor

MCS synchronous servo motors

| | Power / brake | | Blower | |
|----------|------------------|-----------------|------------------|-----------------|
| | Screw cap socket | SpeedTec socket | Screw cap socket | SpeedTec socket |
| MCS06 | M01 | M04 | | |
| MCS09 | | | | |
| MCS12D17 | M01 | M04 | L02 | L04 |
| MCS12D20 | | | | |
| MCS12D35 | | | L02 | L04 |
| MCS12D41 | | | | |
| MCS12H14 | | | L02 | L04 |
| MCS12H15 | | | | |
| MCS12H30 | | | | |
| MCS12H34 | | | L02 | L04 |
| MCS12H35 | | | | |
| MCS12L17 | | | L02 | L04 |
| MCS12L20 | | | | |
| MCS12L39 | | | L02 | L04 |
| MCS12L41 | | | | |
| MCS14D14 | | | L02 | L04 |
| MCS14D15 | | | | |
| MCS14D30 | | | L02 | L04 |
| MCS14D36 | | | | |
| MCS14H12 | | | L02 | L04 |
| MCS14H15 | | | | |
| MCS14H28 | | | M02 M03 | M05 M06 |
| MCS14H32 | | | | |
| MCS14L14 | M01 | M04 | L02 | L04 |
| MCS14L15 | | | | |
| MCS14L30 | M02 | M05 | L02 | L04 |
| MCS14L32 | M03 | M06 | | |
| MCS14P11 | M01 | M04 | L02 | L04 |
| MCS14P14 | | | | |
| MCS14P26 | M02 | M05 | L02 | L04 |
| MCS14P32 | M03 | M06 | | |



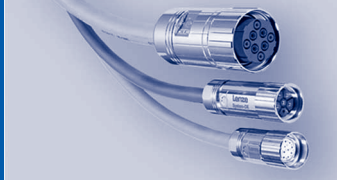
| | Power / brake | | Blower | |
|----------|------------------|-----------------|------------------|-----------------|
| | Screw cap socket | SpeedTec socket | Screw cap socket | SpeedTec socket |
| MCS19F12 | M01 | M04 | L02 | L04 |
| MCS19F14 | | | | |
| MCS19F29 | M02 M03 | M05 M06 | L02 | L04 |
| MCS19F30 | | | | |
| MCS19J12 | | | L02 | L04 |
| MCS19J14 | M01 | M04 | | |
| MCS19J29 | M03 | M06 | L02 | L04 |
| MCS19J30 | M02 M03 | M05 M06 | | |
| MCS19P12 | | | L02 | L04 |
| MCS19P14 | M01 | M04 | | |
| MCS19P29 | M03 | M06 | L02 | L04 |
| MCS19P30 | | | | |

MD□KS synchronous servo motors

| | Power / brake | | Blower | |
|------------|------------------|-----------------|------------------|-----------------|
| | Screw cap socket | SpeedTec socket | Screw cap socket | SpeedTec socket |
| MDSKS□□056 | M01 | M04 | | |
| MDSKS□□071 | | | | |
| MDFKS□□071 | | | L01 | L03 |

MCA asynchronou servo motors

| | Power / brake | | Blower | | | |
|-----------------|------------------|-----------------|------------------|-----------------|-----|-----|
| | Screw cap socket | SpeedTec socket | Screw cap socket | SpeedTec socket | | |
| MCA10I40 | M01 | M04 | | | | |
| MCA13I34 | | | L02 | L04 | | |
| MCA13I41 | | | | | | |
| MCA14L16 | | | L02 | L04 | | |
| MCA14L20 | | | | | | |
| MCA14L35 | | | L02 | L04 | | |
| MCA14L41 | | | | | | |
| MCA17N17 | | | L02 | L04 | | |
| MCA17N23 | | | | | | |
| MCA17N35 | | | L02 | L04 | | |
| MCA17N41 | | | | | | |
| MCA19S17 | | | M02 | M05 | L02 | L04 |
| MCA19S23 | | | | | | |
| MCA19S35 | M02 | M05 | L02 | L04 | | |
| MCA19S42 | M03 | M06 | | | | |
| MCA20X14...2F□□ | | | | | | |
| MCA20X29...2F□□ | M03 | M06 | L02 | L04 | | |
| MCA21X17 | M02 | M05 | | | | |
| | M03 | M06 | | | | |
| MCA21X25 | M02 | M05 | | | | |
| MCA21X35 | M03 | M06 | L02 | L04 | | |
| MCA21X42 | M02 | M05 | | | | |
| | M03 | M06 | | | | |
| MCA22P08...2F□□ | | | L02 | L04 | | |
| MCA22P08...5F□□ | | | | | | |
| MCA22P14...2F□□ | | | | | | |
| MCA22P14...5F□□ | | | | | | |
| MCA22P17...2F□□ | | | | | | |
| MCA22P17...5F□□ | | | | | | |
| MCA22P29...2F□□ | | | | | | |
| MCA22P29...5F□□ | | | | | | |
| MCA26T05...2F□□ | | | | | | |
| MCA26T05...5F□□ | | | | | | |
| MCA26T10...2F□□ | | | | | | |
| MCA26T10...5F□□ | | | | | | |
| MCA26T12...2F□□ | | | | | | |
| MCA26T12...5F□□ | | | | | | |
| MCA26T22...2F□□ | | | | | | |
| MCA26T22...5F□□ | | | | | | |



MQA asynchronous servo motors

| | Power / brake | | Blower | |
|-----------------|------------------|-----------------|------------------|-----------------|
| | Screw cap socket | SpeedTec socket | Screw cap socket | SpeedTec socket |
| MQA20L14...2F□□ | M02 | M05 | | |
| MQA20L29...2F□□ | M03 | M06 | | |

Feedback

| | Feedback | |
|-------------|------------------|-----------------|
| | Screw cap socket | SpeedTec socket |
| AM1024-8V-H | F02 | F06 |
| AM2048-5V-E | | |
| AM32-5V-E | F03 | F07 |
| AS1024-8V-H | F02 | F06 |
| AS2048-5V-E | F03 | F07 |
| IG2048-5V-S | | |
| IG2048-5V-T | | |
| IG4096-5V-T | F02 | F06 |
| IG1024-5V-V | | |
| IK4096-5V-T | F04 | F08 |
| RS0 | F01 | F05 |

Motor connecting cables

| Product series | Cable type | Connection cable | Cable length in decimetres | Cable end on the motor side (socket) | Cable end on the controller side |
|--------------------------|----------------|----------------------|--|--------------------------------------|--|
| E Y P Motor | | A | 0 0 0 3 Minimum length 5 0 0 0 Maximum length | | |
| Fixed installation | 0 0 0 3 | 1.0 mm ² | | M 0 1 Screw plug | A 0 0 Without plug-in connector |
| | 0 0 0 4 | 1.5 mm ² | | M 0 4 SpeedTec | |
| | 0 0 0 5 | 2.5 mm ² | | | |
| | 0 0 0 5 | 2.5 mm ² | | M 0 2 Screw plug | A 0 0 Without plug-in connector |
| | 0 0 0 6 | 4.0 mm ² | | M 0 5 SpeedTec | |
| | 0 0 0 7 | 6.0 mm ² | | M 0 3 Screw plug | A 0 0 Without plug-in connector |
| | 0 0 0 8 | 10.0 mm ² | | M 0 6 SpeedTec | |
| | 0 0 0 9 | 16.0 mm ² | | | |
| | Trailing cable | 0 0 1 0 | 1.0 mm ² | | M 0 1 Screw plug |
| 0 0 1 1 | | 1.5 mm ² | | M 0 4 SpeedTec | |
| 0 0 1 2 | | 2.5 mm ² | | | |
| 0 0 1 2 | | 2.5 mm ² | | M 0 2 Screw plug | A 0 0 Without plug-in connector |
| 0 0 1 3 | | 4.0 mm ² | | M 0 5 SpeedTec | |
| 0 0 1 4 | | 6.0 mm ² | | M 0 3 Screw plug | A 0 0 Without plug-in connector |
| 0 0 1 5 | | 10.0 mm ² | | M 0 6 SpeedTec | |
| 0 0 1 6 | | 16.0 mm ² | | | |

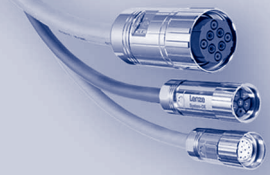


Motor connecting cables

| Product series | Cable type | Cable without plug-in connector | Cable length in decimetres | Cable end on the motor side | Cable end on the controller side |
|---------------------------------|--|---|--|---|---|
| E Y P Motor | | Y | 0 0 0 3 5 0 0 0 Minimum length Maximum length | | |
| Fixed installation | 0 0 0 3 0 0 0 4 0 0 0 5 0 0 0 6 0 0 0 7 0 0 0 8 0 0 0 9 | 1.0 mm ² 1.5 mm ² 2.5 mm ² 4.0 mm ² 6.0 mm ² 10.0 mm ² 16.0 mm ² | | A 0 0 Without plug-in connector | A 0 0 Without plug-in connector |
| Trailing cable | 0 0 1 0 0 0 1 1 0 0 1 2 0 0 1 3 0 0 1 4 0 0 1 5 0 0 1 6 | 1.0 mm ² 1.5 mm ² 2.5 mm ² 4.0 mm ² 6.0 mm ² 10.0 mm ² 16.0 mm ² | | A 0 0 Without plug-in connector | A 0 0 Without plug-in connector |

Feedback connecting cables

| Product series | Cable type | Connection cable | Cable length in decimetres | Cable end on the motor side (socket) | Cable end on the controller side | For use with |
|------------------------|-------------|--|--|--|--|--|
| E Y Feedback | | A | 0003 Minimum length 5000 Maximum length | | | |
| Fixed installation | 0017 | Resolver | | F01 Screw plug F05 SpeedTec | S01 Sub-D plug S02 Sub-D plug A00 Without plug-in connector | EVS93..., ECS..., 931E... E94AS..., E94AM..., E84AVT... |
| | 0021 | Sin/cos absolute value encoder (EnDat) | | F03 Screw plug F07 SpeedTec | S01 Sub-D plug S02 Sub-D plug A00 Without plug-in connector | EVS93..., ECS..., 931E... E94AS..., E94AM..., E84AVT... |
| Trailing cable | 0020 | Resolver | | F01 Screw plug F05 SpeedTec | S03 Sub-D plug A00 Without plug-in connector | E94AS..., E94AM... |
| | 0020 | Resolver | | F01 Screw plug F05 SpeedTec | S04 Sub-D plug S05 Sub-D plug A00 Without plug-in connector | EVS93..., ECS..., 931E... E94AS..., E94AM..., E84AVT... |
| | 0022 | Sin/cos absolute value encoder (EnDat) | | F03 Screw plug F07 SpeedTec | S04 Sub-D plug S05 Sub-D plug A00 Without plug-in connector | EVS93..., ECS..., 931E... E94AS..., E94AM..., E84AVT... |
| | 0022 | Sin/cos absolute value encoder (EnDat) | | F03 Screw plug F07 SpeedTec | A00 Without plug-in connector | |



Feedback connecting cables

| Product series | Cable type | Connection cable | Cable length in decimetres | Cable end on the motor side (socket) | Cable end on the controller side | For use with |
|--------------------|----------------------|---|--|--|--|--|
| E Y | | A | | | | |
| | F Feedback | | 0 0 0 3 Minimum length 5 0 0 0 Maximum length | | | |
| Fixed installation | 0 0 1 8 | Sin/cos absolute value encoder (Hiperface) and incremental encoder (TTL, HTL) | | F 0 2 Screw plug F 0 6 SpeedTec | W 0 2 Sub-D plug S 0 3 Sub-D plug A 0 0 Without plug-in connector | EVS93..., ECS..., 931E... EVF93..., E94AYFLF E94AS..., E94AM..., E84AVT... E82xV... E84AVH..., E84AVT... |
| | 0 0 2 3 | Incremental encoder IK4096-5V-T (Renco R35i) | | F 0 4 Screw plug F 0 8 SpeedTec | W 0 2 Sub-D plug S 0 3 Sub-D plug | EVS93..., ECS..., 931E... EVF93..., E94AYFLF E94AS..., E94AM..., E84AVT... E94P... |
| | 0 0 1 9 | Sin/cos absolute value encoder (Hiperface) and incremental encoder (TTL, HTL) | | F 0 2 Screw plug F 0 6 SpeedTec | S 0 6 Sub-D plug A 0 0 Without plug-in connector | E94P... |
| Trailing cable | 0 0 1 9 | Sin/cos absolute value encoder (Hiperface) and incremental encoder (TTL, HTL) | | F 0 2 Screw plug F 0 6 SpeedTec | S 0 6 Sub-D plug A 0 0 Without plug-in connector | E94P... |
| | 0 0 2 4 | Incremental encoder IK4096-5V-T (Renco R35i) | | F 0 2 Screw plug F 0 6 SpeedTec | W 0 4 Sub-D plug S 0 3 Sub-D plug A 0 0 Without plug-in connector | EVS93..., ECS..., 931E... EVF93..., E94AYFLF E94AS..., E94AM..., E84AVT... E82xV... E84AVH..., E84AVT... |
| | 0 0 2 4 | Incremental encoder IK4096-5V-T (Renco R35i) | | F 0 4 Screw plug F 0 8 SpeedTec | W 0 4 Sub-D plug S 0 3 Sub-D plug A 0 0 Without plug-in connector | EVS93..., ECS..., 931E... EVF93..., E94AYFLF E94AS..., E94AM..., E84AVT... E82xV... E84AVH..., E84AVT... |

Feedback connecting cables

| Product series | Cable type | Cable without plug-in connector | Cable length in decimetres | Cable end on the motor side | Cable end on the controller side |
|--------------------|----------------|---|----------------------------------|--|--|
| E Y | | Y | | | |
| F | | | 0 0 0 3 5 0 0 0 | | |
| Feedback | | | Minimum length Maximum length | | |
| Fixed installation | 0 0 1 7 | Resolver | | A 0 0 Without plug-in connector | A 0 0 Without plug-in connector |
| | 0 0 1 8 | Sin/cos absolute value encoder (Hiperface) and incremental encoder (TTL, HTL) | | | |
| | 0 0 2 1 | Sin/cos absolute value encoder (EnDat) | | | |
| | 0 0 2 3 | Incremental encoder IK4096-5V-T (Renco R35i) | | | |
| Trailing cable | 0 0 2 0 | Resolver | | A 0 0 Without plug-in connector | A 0 0 Without plug-in connector |
| | 0 0 1 9 | Sin/cos absolute value encoder (Hiperface) and incremental encoder (TTL, HTL) | | | |
| | 0 0 2 2 | Sin/cos absolute value encoder (EnDat) | | | |
| | 0 0 2 4 | Incremental encoder IK4096-5V-T (Renco R35i) | | | |
| | 0 0 4 8 | Incremental encoder (HTL) | | | |

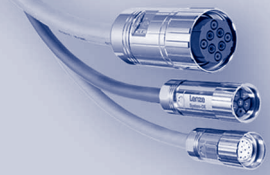


Blower connecting cables

| Product series | Cable type | Connection cable | Cable length in decimetres | Cable end on the motor side (socket) | Cable end (control cabinet) | For use with |
|---------------------------|----------------|------------------|--|--|--|-----------------|
| E Y L Blower | | A | 0 0 0 3 Minimum length 5 0 0 0 Maximum length | | | |
| Fixed installation | 0 0 0 1 | | | L 0 1 Screw plug L 0 3 SpeedTec | A 0 0 Without plug-in connector | MDFKS |
| Trailing cable | 0 0 0 2 | | | L 0 2 Screw plug L 0 4 SpeedTec | A 0 0 Without plug-in connector | MCA, MCS, MDFMA |
| | | | | L 0 5 Screw plug L 0 6 SpeedTec | A 0 0 Without plug-in connector | MDFMA |
| | | | | L 0 1 Screw plug L 0 3 SpeedTec | A 0 0 Without plug-in connector | MDFKS |
| | | | | L 0 2 Screw plug L 0 4 SpeedTec | A 0 0 Without plug-in connector | MCA, MCS, MDFMA |
| | | | | L 0 5 Screw plug L 0 6 SpeedTec | A 0 0 Without plug-in connector | MDFMA |

Blower connecting cables

| Product series | Cable type | Cable without plug-in connector | Cable length in decimetres | Cable end on the motor side | Cable end (control cabinet) |
|--------------------|------------|---------------------------------|--|------------------------------------|------------------------------------|
| E Y L Blower | | Y | 0 0 0 3 5 0 0 0 Minimum length Maximum length | | |
| Fixed installation | 0 0 0 1 | | | A 0 0 Without plug-in connector | A 0 0 Without plug-in connector |
| Trailing cable | 0 0 0 2 | | | A 0 0 Without plug-in connector | A 0 0 Without plug-in connector |



Motor extensions

| Product series | Cable type | Extension cable | Cable length in decimetres | Cable end on the motor side (socket) | Cable end on the controller side (pin) |
|--------------------|----------------|----------------------|--|--|--|
| E Y | | V | | | |
| P Motor | | | 0 0 0 3 5 0 0 0 Minimum length Maximum length | | |
| Fixed installation | 0 0 0 3 | 1.0 mm ² | | M 0 1 Screw plug | P 0 4 SpeedTec |
| | 0 0 0 4 | 1.5 mm ² | | M 0 4 SpeedTec | |
| | 0 0 0 5 | 2.5 mm ² | | A 0 0 Without plug-in connector | |
| | 0 0 0 5 | 2.5 mm ² | | M 0 2 Screw plug | P 0 5 SpeedTec |
| | 0 0 0 6 | 4.0 mm ² | | M 0 5 SpeedTec | |
| | | | | A 0 0 Without plug-in connector | |
| | 0 0 0 7 | 6.0 mm ² | | M 0 3 Screw plug | P 0 6 SpeedTec |
| | 0 0 0 8 | 10.0 mm ² | | M 0 6 SpeedTec | |
| | 0 0 0 9 | 16.0 mm ² | | A 0 0 Without plug-in connector | |
| Trailing cable | 0 0 1 0 | 1.0 mm ² | | M 0 1 Screw plug | P 0 4 SpeedTec |
| | 0 0 1 1 | 1.5 mm ² | | M 0 4 SpeedTec | |
| | 0 0 1 2 | 2.5 mm ² | | A 0 0 Without plug-in connector | |
| | 0 0 1 2 | 2.5 mm ² | | M 0 2 Screw plug | P 0 5 SpeedTec |
| | 0 0 1 3 | 4.0 mm ² | | M 0 5 SpeedTec | |
| | | | | A 0 0 Without plug-in connector | |
| | 0 0 1 4 | 6.0 mm ² | | M 0 3 Screw plug | P 0 6 SpeedTec |
| | 0 0 1 5 | 10.0 mm ² | | M 0 6 SpeedTec | |
| | 0 0 1 6 | 16.0 mm ² | | A 0 0 Without plug-in connector | |

Feedback extensions

| Product series | Cable type | Extension cable | Cable length in decimetres | Cable end on the motor side (socket) | Cable end on the controller side (pin) |
|------------------------|----------------|--|--|--|--|
| E Y Feedback | | V | 0 0 0 3 Minimum length 5 0 0 0 Maximum length | | |
| Fixed installation | 0 0 1 7 | Resolver | | F 0 1 Screw plug F 0 5 SpeedTec A 0 0 Without plug-in connector | G 0 6 SpeedTec |
| | 0 0 2 1 | Sin/cos absolute value encoder (EnDat) | | F 0 3 Screw plug F 0 7 SpeedTec A 0 0 Without plug-in connector | G 0 8 SpeedTec |
| Trailing cable | 0 0 2 0 | Resolver | | F 0 1 Screw plug F 0 5 SpeedTec A 0 0 Without plug-in connector | G 0 6 SpeedTec |
| | 0 0 2 2 | Sin/cos absolute value encoder (EnDat) | | F 0 3 Screw plug F 0 7 SpeedTec A 0 0 Without plug-in connector | G 0 8 SpeedTec |

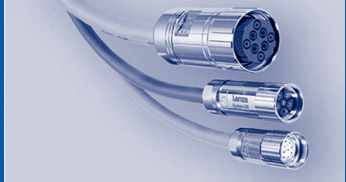


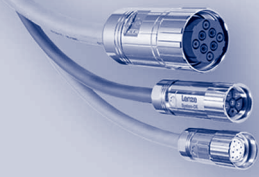
Feedback extensions

| Product series | Cable type | Extension cable | Cable length in decimetres | Cable end on the motor side (socket) | Cable end on the controller side (pin) |
|------------------------|----------------|---|--|--|--|
| E Y Feedback | | V | 0 0 0 3 Minimum length 5 0 0 0 Maximum length | | |
| Fixed installation | 0 0 1 8 | Sin/cos absolute value encoder (Hiperface) and incremental encoder (TTL, HTL) | | F 0 2 Screw plug F 0 6 SpeedTec A 0 0 Without plug-in connector | G 0 7 SpeedTec |
| | 0 0 2 3 | Incremental encoder IK4096-5V-T (Renco R35i) | | F 0 4 Screw plug F 0 8 SpeedTec A 0 0 Without plug-in connector | G 0 9 SpeedTec |
| Trailing cable | 0 0 1 9 | Sin/cos absolute value encoder (Hiperface) and incremental encoder (TTL, HTL) | | F 0 2 Screw plug F 0 6 SpeedTec A 0 0 Without plug-in connector | G 0 7 SpeedTec |
| | 0 0 2 4 | Incremental encoder IK4096-5V-T (Renco R35i) | | F 0 4 Screw plug F 0 8 SpeedTec A 0 0 Without plug-in connector | G 0 9 SpeedTec |
| | 0 0 4 8 | Incremental encoder (HTL) | | D 0 1 M12-A socket A 0 0 Without plug-in connector | G 0 7 SpeedTec |

Blower extensions

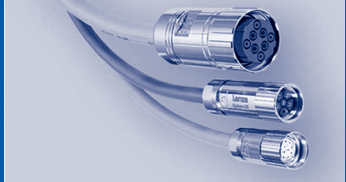
| Product series | Cable type | Extension cable | Cable length in decimetres | Cable end on the motor side (socket) | Cable end (pin) | For use with |
|--------------------|------------|-----------------|----------------------------------|---|-----------------|-----------------|
| E Y | | V | 0 0 0 3 5 0 0 0 | | | |
| L | | | Minimum length Maximum length | | | |
| Blower | | | | | | |
| Fixed installation | 0 0 0 1 | | | L 0 1 Screw plug L 0 3 SpeedTec A 0 0 Without plug-in connector | J 0 3 SpeedTec | MDFKS |
| | | | | L 0 2 Screw plug L 0 4 SpeedTec A 0 0 Without plug-in connector | J 0 4 SpeedTec | MCA, MCS, MDFMA |
| | | | | L 0 5 Screw plug L 0 6 SpeedTec A 0 0 Without plug-in connector | J 0 5 SpeedTec | MDFMA |
| Trailing cable | 0 0 0 2 | | | L 0 1 Screw plug L 0 3 SpeedTec A 0 0 Without plug-in connector | J 0 3 SpeedTec | MDFKS |
| | | | | L 0 2 Screw plug L 0 4 SpeedTec A 0 0 Without plug-in connector | J 0 4 SpeedTec | MCA, MCS, MDFMA |
| | | | | L 0 5 Screw plug L 0 6 SpeedTec A 0 0 Without plug-in connector | J 0 5 SpeedTec | MDFMA |





System cables

Product key





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