SinuTrain

Beginner's Manual: Milling and Turning SINUMERIK 810D / 840D / 840Di

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Training Documentation · 10/2003

SINUMERIK



2nd revised edition Oct. 2003 valid for software versions from HMI06.03

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Order No.: 6FC5095-0AB00-0BP1

Preface

The ditigital control systems SINUMERIK 810 D, 840d and 840Di are characterized by their large "openness", i.e. they can be configured by the machine manufacturer and partially also by the user himself according to their own requirements. They can thus efficiently be used in many fields of application both in the small-series production and in fully automatic manufacturing lines.

When creating this Manual, it has been the objective to provide the large range of users an **easily understandable access** to these powerful control systems.

The control systems 810D, 840D und 840Di can be used to control many different machining processes. This Manual deals with the two essential technologies **turning and milling**.

It has been created in cooperation with NC experts and lecturers. We would like to express our special thanks to Mr. Markus Sartor for his valuable hints and criticism.

The Manual is practice-oriented and action-oriented. The keys and their use are explained step by step. The comprehensive presentation of screenshots enables you to compare your own inputs at the control system with the values and specifications given in this Manual.

This Manual can also be used as a preparation or assessment away from the control system with the control-identical system **SinuTrain** on the PC.

The examples of this Manual were created using mainly Software Version 5.2.

Further developments of the software and the already described "openness" of the control system do not exclude that the operation of your control system differs in certain details from the configuration described. It might also happen that - in dependence on the position of the keyswitch on the machine - not all described functions are available. In such cases you are kindly asked to refer to the documents of the machine manufacturer or to company-internal documents.

We wish you much pleasure and success for the work with your SINUMERIK control system.

The authors

Erlangen/Wuppertal, in March 2001

North Indiante 810D/840D/840Di Beginner's Manual

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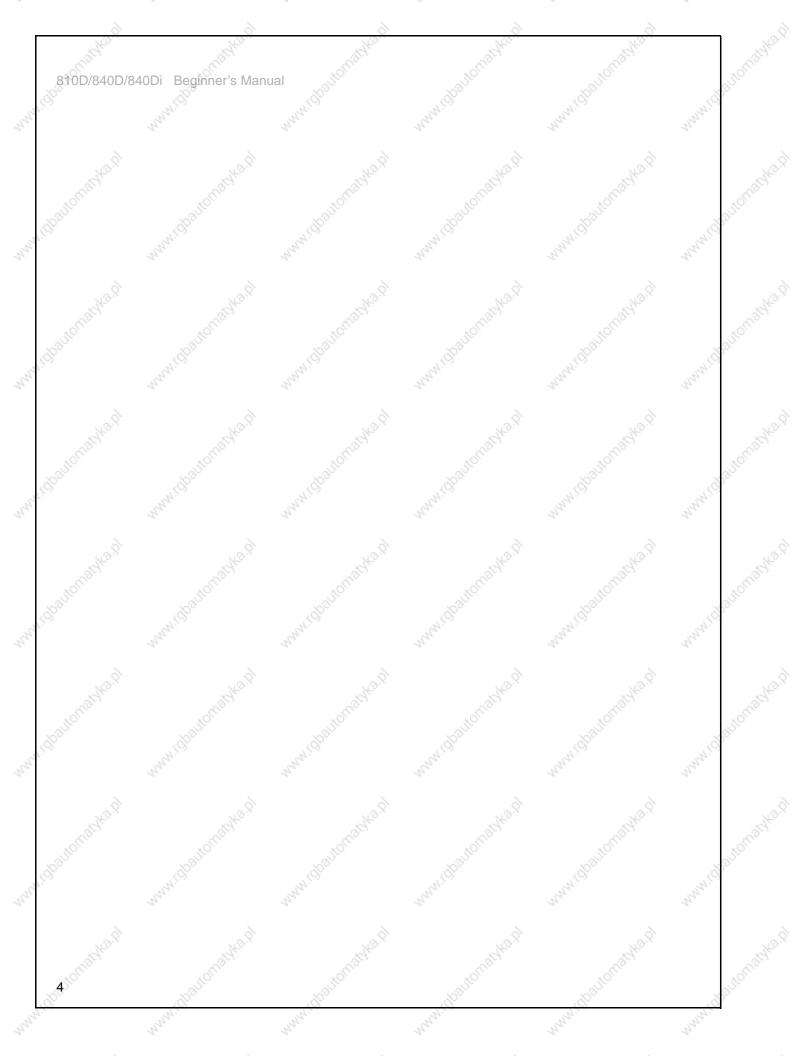
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1 Fundamentals

This Chapter provides some general geometric and technological fundamentals for the programming of milling and turning procedures for CNC beginners.

1.1 Geometric fundamentals of milling and turning

The geometric fundamentals presented here refer mainly to the graphical SINUMERIK contour calculator. The screenshots used in this Manual are intended to support the theory.

To understand the theoretical examples provided by the control already in advance: Operating area "Program" > Create new part program > Horizontal softkey (Contour) in the text editor > vertical softkey (Generate contour) > ...

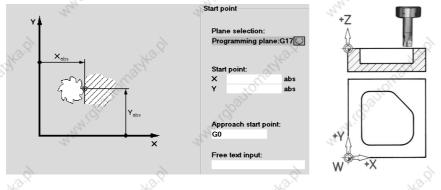
You will find a practical example presenting this contour calculator in the Chapter "Programming/Turning".

.1.1 Tool axes and working planes

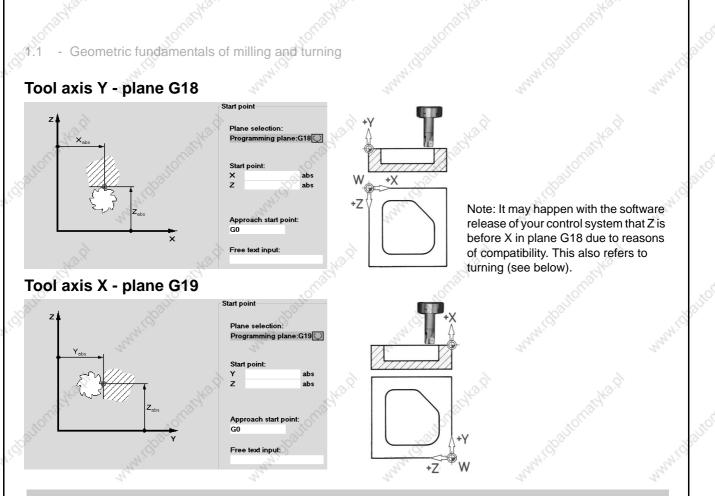
MILLING

On universal milling machines the tool is installed in most cases parallel to the main axes. These axes rightangled to each other are aligned according to DIN 66217 or ISO 841 to the main guideways of the machine. The appropriate working plane results from the mounting position of the tool. The Z axis is mostly the tool axis for milling.

Tool axis Z - working plane G17



If the shown coordinate system is turned correspondingly, the axes and their directions in the associated working plane will change (DIN 66217).

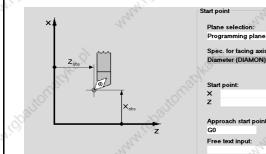


TURNING

On universal turning machines the tool is installed in most cases parallel to the main axes. These axes rightangled to each other are aligned according to DIN 66217 or ISO 841 towards the main guideways of the machine. The Z axis is mostly the workpiece axis for turning.

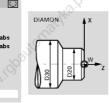
Rotating axis Z - plane G18 *

Since it is relatively easy to control the diameter of turned workpieces, the dimensions of the transverse axis always refer to the diameter. Thus, the worker can compare the actual dimension directly with the drawing dimensions.



6



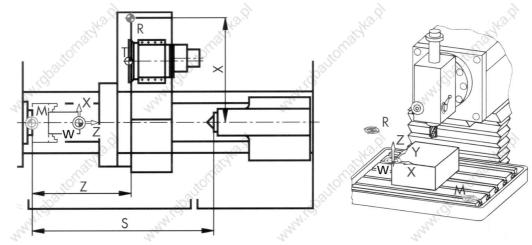


DIAMO

The radius dimension shown here also exists in the help screenform, but it "hardly never occurs".

* All turning operations are programmed in plane G18.

Drilling and milling operations at the end face of the turned part are programmed in plane G17. Drilling and milling operations at the peripheral surface of the turned part are programmed in plane G19. To enable a CNC control system, such as the SINUMERIK 840D, to orient itself in the existing working area, there are some important reference points.



Machine zero M



The machine zero M is defined by the manufacturer and cannot be changed. When milling, it is in the origin of the machine coordinate system, and when turning, on the contact surface of the spindle nose.

Workpiece zero W



The workpiece zero W, also referred to as the program zero, is the origin of the workpiece coordinate system. It can also be freely selected and when milling, it should also be located at a position in the drawing from which most of the dimensions are measured.

When turning, the workpiece zero is always located on the rotary axis and mostly on the plane surface

Reference point R

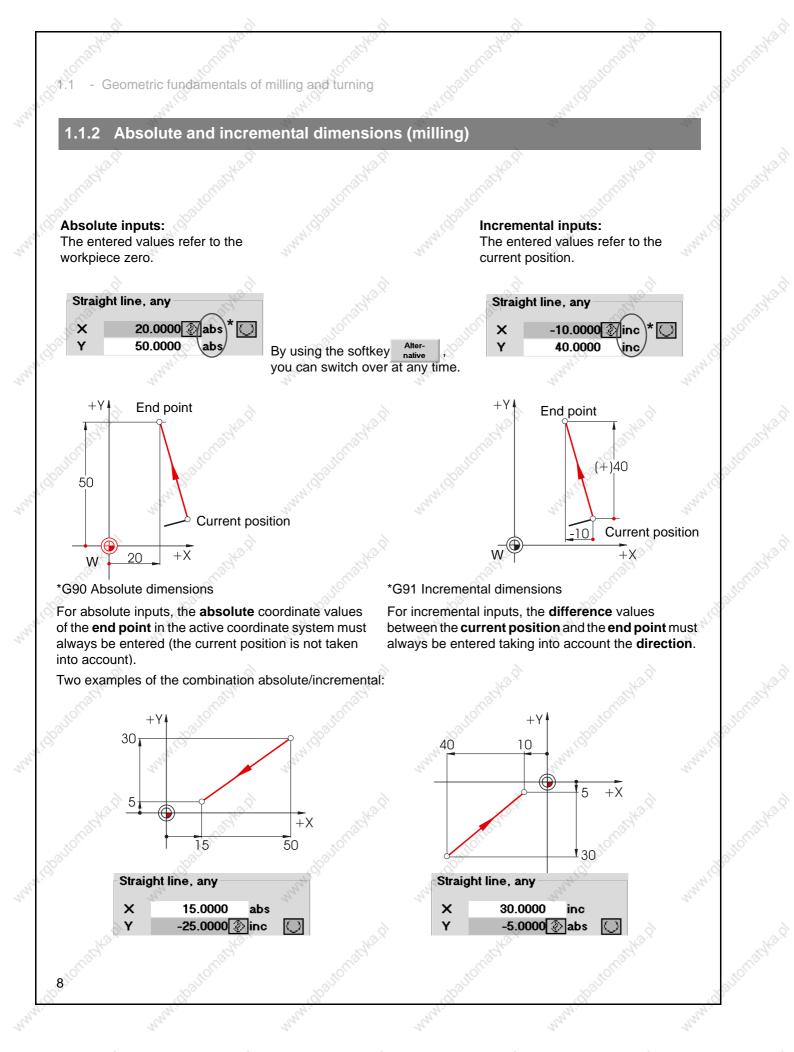


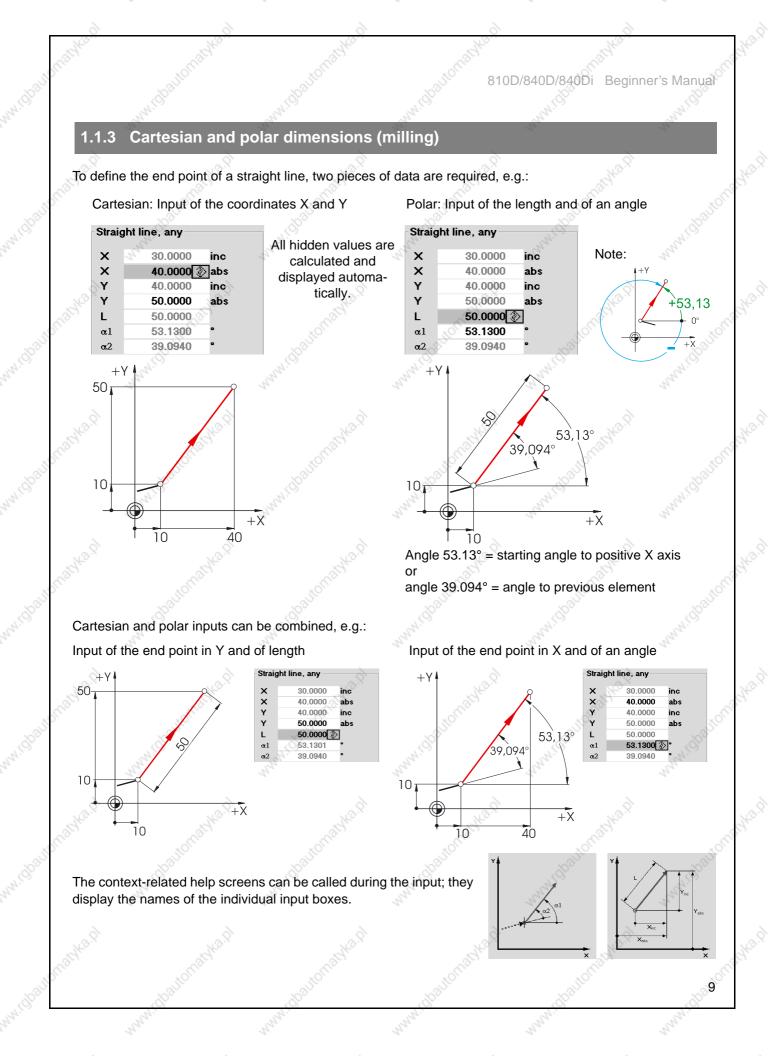
The reference point R is approached when setting the measuring system, since in most cases the machine zero cannot be approached. The control system will thus find its reference point in the position measuring system.

Toolholder reference point T



The toolholder reference point T is important for setting up with default tools. The lengths L and Q shown in the diagram below are used as tool calculation values and are entered in the tool memory of the control system.





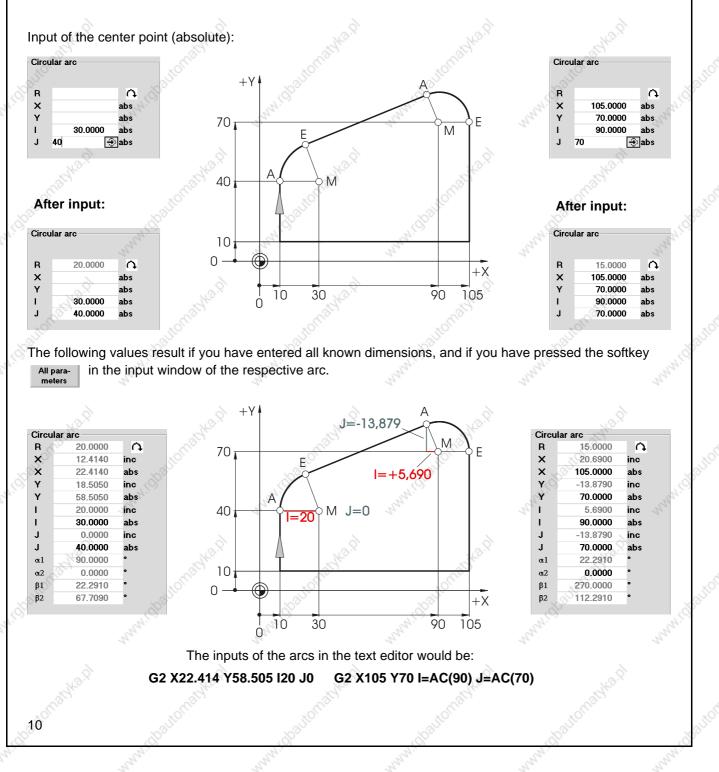
- Geometric fundamentals of milling and turning

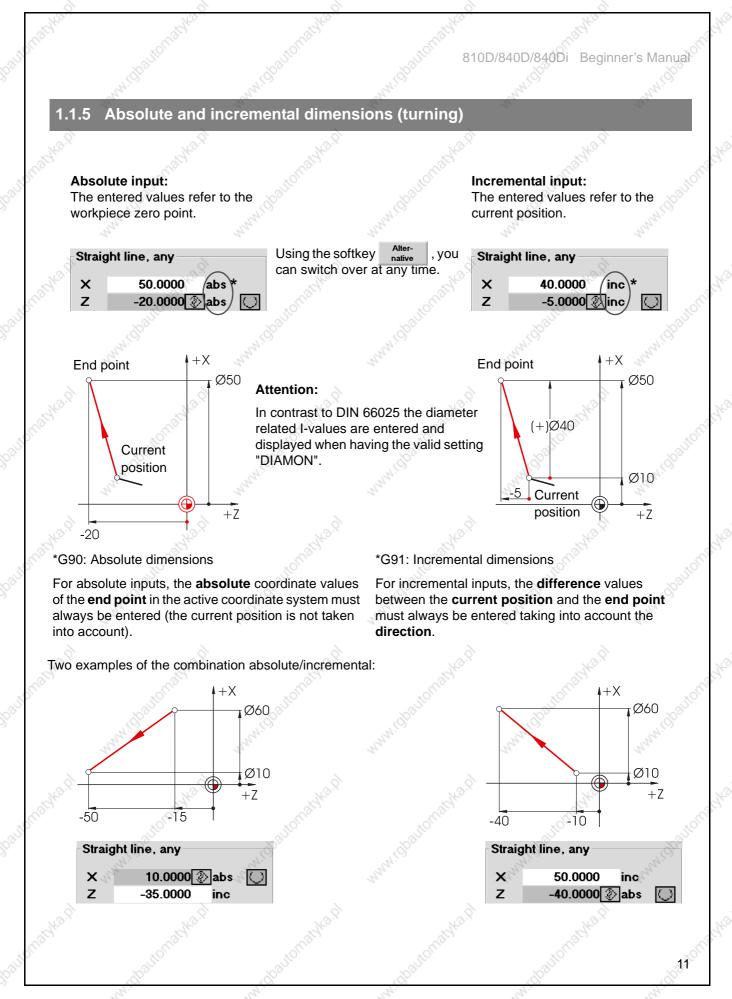
1.1.4 Circular movements (milling)

According to DIN, the end point of the arc (coordinates X and Y in the G17 plane) and the center point (I and J in the G17 plane) have to be indicated for arcs.

The SINUMERIK contour calculator also allows you in case of circular arcs to accept any dimension from the drawing without much conversion.

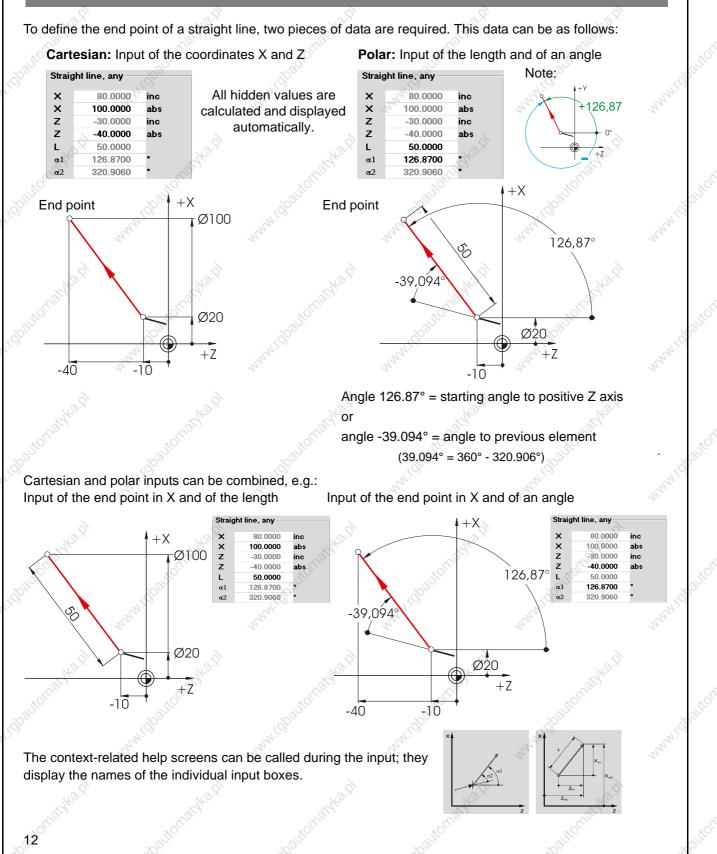
In the following you will find an example with two - at first only partially determined - arcs.





- Geometric fundamentals of milling and turning

1.1.6 Cartesian and polar dimensions (turning)



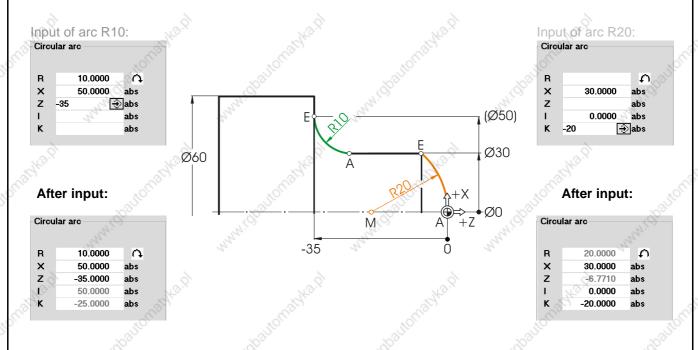
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1.1.7 Circular movements (turning)

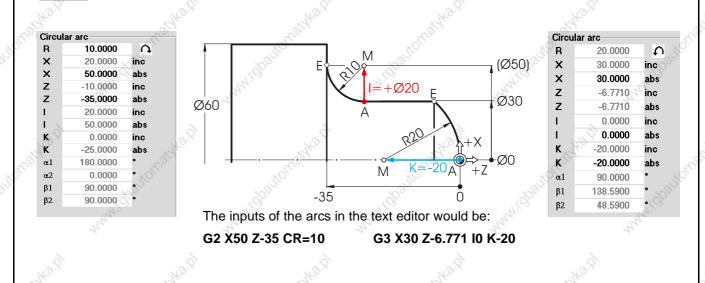
According to DIN, the end point of the arc (coordinates X and Z in the G18 plane) and the center point (I and K in the G18 plane) have to be specified for arcs.

The SINUMERIK contour computer also allows you in case of arcs to accept any dimension from the drawing without much conversion.

In the following you will find an example with two - at first only partially determined - circular arcs.



The following values result if you have entered all known dimensions, and if you have pressed the softkey All parameters in the input window of the respective arc.



- Technical fundamentals of milling and turning

1.2 Technical fundamentals of milling and turning

1.2.1 Cutting rate and speeds (milling)

The optimum speed of a tool in each individual case depends on the cutting tool material grade, the material of the workpiece and the tool diameter. In the practice, this speed is also often entered immediately without any calculations, based on many years of experience. The better way, however, is to calculate the speed from the cutting rate specified in the appropriate tables.

Determination of the cutting rate:

First, determine the optimum cutting rate on the basis of the manufacturer catalogs or a table book.

Cutting tool material grade: Hard metal Workpiece material:

C45

 $v_c = 80 \dots 150$ m/min: The mean value $v_c = 115$ m/min should be selected.

Calculating the speed:

Use this cutting rate and the known tool diameter to calculate the speed n.

$$n = \frac{v_c \cdot 1000}{d \cdot \pi}$$

The example below shows how to calculate the speed for two tools: $d_1 = 63mm$ $d_2 = d_2 = d_2 = d_2$

 $d_2 = 40 mm$

 $n_2 \approx 900 \frac{1}{min}$

115mm · 1000 40mm · π · min

(in the workshop also often referred to

as r.p.m.)

 $1 = \frac{115 \text{mm} \cdot 1000}{63 \text{mm} \cdot \pi \cdot \text{min}}$

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The NC coding uses the acronym "s" for the speed.

In this case, the inputs will be S580 and S900.

With these speeds, the cutting rate of 115 m/min is achieved.

1.2.2 Feedrate per tooth and feedrate (milling)

On the previous page, you have learned how to determine the cutting rate and how to calculate speeds. To make sure that the tool cuts, a tool feedrate must be assigned to this cutting rate or speed.

The basic value of the feedrate is the characteristic quantity "feed per tooth".

Determining the feed per tooth:

Like the cutting rate, the value for the feed per tooth is also determined using either the table book or the appropriate documents of the tool manufacturer.

ROTATING TOOL

Cutting tool material grade:

Workpiece material:

C45

Hard metal

Feed per tooth $f_z = 0.1 \dots 0.2$ mm:

The mean value $f_z = 0.15 \text{ mm}$ should be selected.

Determining the feedrate:

The feedrate v_f is calculated using the feed per tooth, the number of teeth and the known speed.

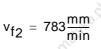
$$v_f = f_z \cdot z \cdot n$$

The example below shows how to calculate the feedrate for two tools with a different number of teeth:

$$d_1 = 63mm, z_1 = 4$$
 $d_2 = 63mm,$

 $v_{f_1} = 0,15\text{mm}\cdot4\cdot580\frac{1}{\text{min}}$





 $z_2 = 9$

 $= 0, 15 \text{mm} \cdot 9 \cdot 580 \frac{1}{\text{mir}}$

The NC coding uses the acronym "F" for the feedrate. In this case, the inputs will be rounded off F340 and F780. With these feedrates, the feed per tooth of 0.15 mm is achieved.

- Technical fundamentals of milling and turning

1.2.3 Cutting rate and speeds (turning)

Unlike milling, turning generally calls for the desired cutting rate to be programmed directly, namely when roughing, finishing and plunge-cutting.

Only when drilling, and (in most cases) when thread cutting, is the desired speed programmed.

Determining the cutting rate:

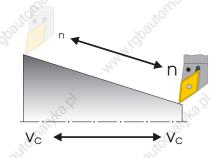
First, determine the optimum cutting rate on the basis of the manufacturer catalog or a table book.

Cutting tool material grade: Hard metal workpiece material: Free-cutting steel



v_c = 180 m/min:

Constant cutting rate vc (G96) when roughing, finishing and plunge-cutting:



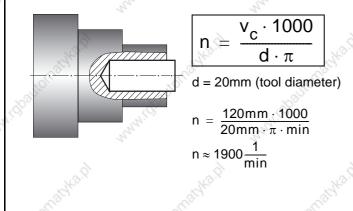
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To make sure that the selected cutting rate is observed on each workpiece diameter, the appropriate speed is adapted by the control system using the command G96 = constant cutting rate. This is carried out using either d.c. motors or variable-frequency three-phase motors.

With reduced diameter, the speed theoretically increases infinitely. To avoid hazards from excessive radial forces, a speed limit, e.g. of 3,000 r.p.m. must be programmed.

In this case, the inputs will be G96 S180 LIMS=3000.

Constant speed n (G97) when drilling and thread cutting:



Since the speed is constant when drilling, the command G97 = constant speed must be used here.

The speed is dependent on the desired cutting rate (120 m/min is selected in this case) and the tool diameter.

In this case, the inputs will be G97 S1900.

1.2.4 Feed (turning)

On the previous page, you have learned how to determine the cutting rate and how to calculate speeds. To make sure that the tool cuts, a tool feedrate must be assigned to this cutting rate or speed. The basic value of the feedrate is the characteristic quantity "feed per tooth".

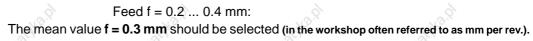
Determining the feed:

Like the cutting rate, the value for the feed is also determined using either the table book or the appropriate documents of the tool manufacturer or else is based on empirical knowledge.

Cutting tool material grade:

Workpiece material: Free-cutting steel



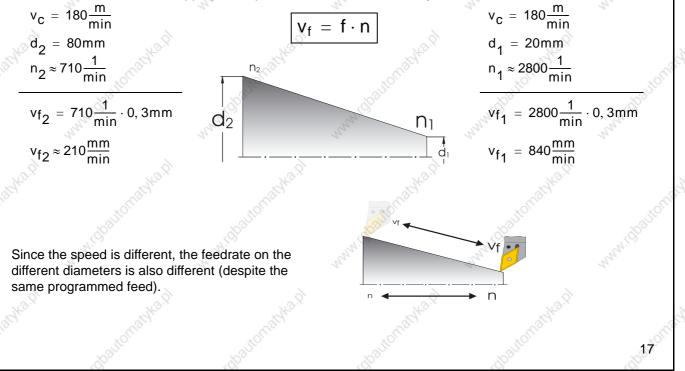


TURNING

In this case, the input will be F0.3.

Interrelation between feed and feedrate:

The constant feed f and the appropriate speed results in the feedrate v_f.



.1 Operation - Overview of the control system

2 Operation

In this manual for beginners the general term "operation" is used for all operating sequences which take place in the direct interaction between user and machine. After a fundamental introduction in Section 2.1, the second subsection deals with setting up tools and workpieces. The third and fourth subsections deal mainly with the production, i. e. the execution of NC programs.

The control systems 810D/840D/840Di are based on an open control concept which allows the machine manufacturers (and partially also you as the user) to configure the control system according to individual requirements. That's why it is possible that there will be differences in the manual as regards the sequences of action. Please, follow the instructions of the machine manufacturer if necessary, and carefully check your inputs before you start the machine.

2.1 Overview of the control system



In this section, you will learn something about structure and handling of the control system components "keyboard" and "display".

Pictures:

• OP 010C operator panel front with TFT color screen, softkey bars (horizontal und vertical) and mechanical CNC full keypad with 65 keys.

These components are used mainly for the programming and processing of data.

 Machine control panel with override potentiometers

This control panel influences the machine movements directly.

To a certain degree, it can also be configured by the machine manufacturer according to the customer's requirements.

For further operating components for the control system and training keyboards for SinuTrain, please refer to the catalog NC60 "Automation systems for machine tools" (SIEMENS order no. E86060-K4460-A101-A8-7600).

2.1.1 Turning on, area switchover, turning off

Depending on whether you train yourself directly on the machine or whether you use the control-identical Sinumerik training system on the PC, you have to start your work in a different way.

Turning on

lf...

machine: Then, of course, first you will have to look for the main switch located either on the side of the

machine or on the control

cubicle.

you are working on the



lf ...

Then you will start the software via the icon on the desktop or via the entry in the start menu (Start > Programs > SinuTrain ... > SinuTrain START).

you are working on the Windows PC:

Then you can choose between the two technologies (milling/ turning) and the kind of tool management (see Sections 2.2.1 and 2.2.2). (With Software Version 6 and higher, machines can also be configured according to the customer's requirements).



After having started the software, the "Machine" operating area is active and the "Auto" mode is selected.

A reference point approach will not be simulated on the PC.

The "JOG" mode for direct selection of traversing axes is not functional on the PC.





After turning on, the control system is in the "Machine" operating area, and the "Ref" function (reference point approach) is selected.

The way how to approach the reference point depends on the machine type and the machine manufacturer and can therefore not be be discussed here in detail.

.1 Operation - Overview of the control system

Area switchover

Keys/inputs

Paramete

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Screen / drawing

Description

By using the <Area switchover key> (not the slimline operator panel or not the PC keyboard), you can - independent of the operating situation you are currently in - unhide the main menu with the six opreating areas of the control system.

// Channe	840DMill		MPF0 Program	aborted		
	NO.			ROV SBL1	2.Q	AUTO
Work	Position	_	Dto-go	Master spindle	S1 🕅	MDA
×	0.000	mm	0.000	Act.	0.000 rpm	
×°	0.000	mm	0.000	Set	0.000 rpm	JOG
z	0.000	mm	0.000	Pos.	0 deg.	
A	0.000	deg	0.000	1 .	100.0 %	REPOS
с	0.000	deg	0.000	Power	0%	
Current bl	ock	0	14	Feedrate [mm/r	nin]	REF
M30				Act.	0.000 100.0 %	
				Set	0.000	
				Tool	1	
				Preselected to	at S 1	
				- N	10 1	
	9.			G01		
				100	\sum	

The main menu is displayed in the active Machine operating area. The softkey of the active operating area is selected.

In this operating area, you will control the machine directly. Here you can traverse manually, scratch, or run NC programs.

Example: Machining center with three linear axes (X, Y, Z) and 2 rotary axes (A, C)

Parameter 840D T	urn		Auto				~	
				IPF0				
🥢 Channel reset			P	rogram abo				Tool/basio
					ROV SBL1			data
								Tool/add.
Magazine list:								data
Magazine: 1- 12er	r-Revolver			Loc	at.: 90	Ì		
						_		Tool/size
LN Tool ident			Length 1	Length 2F		F	Life	status
1BT1	1 :				0.800	0	0 ^	
2RT2		500 3			0.800	0	0	Tool
3FT1		510 3			0.400	0	0	details
4FT2		510 3			0.400	0	0	
5 THREAD		540 8			0.060	0	0	
6 GT_3	1 0	520 3	93.10	0 42.000	0.100	0	0	
7TD5		200 0	94.25		2.500	0	0	124
8 SD16	1 3	205 0	120.43	2 0.000	8.000	0	0	
9EM10	1	120 0	76.36	1 0.000	5.000	0	0	Buffer
10			9				1.1	locations
11								
12								
13								
14	0					1		
15	×					~ X	~	Next
C	1			1		10	>	
							ΠD	magazine

Change with the softkey to the **Parameter** operating area.

This can be done on the slimline operator panel via the appropriate softkey. On the PC, you can click the softkey with the mouse or call the operating area panel with $\boxed{r_2}$.

The Parameters operating area is intended, e.g. to manage your tools and the table of zero offsets.

Active operating area 'Program (called via softkey, via mouse or F3).

In this operating area, you write and simulate NC programs.

The Chapters 3 (milling) and 4 (turning) explain this in detail.

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		8 SD1		1	205	ŏ	120.432	0.000	8,000	0		j 📕	100
		9EM			120	0	76.361	0.000	5.000	ő		ίΓ	Buffer
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MENU Program	Sec.	Program	840D_Mill			A	uto ME	F0					
SELECT	1 2	// Chanr	nel reset			-2	Pro	gram abo	orted			1	
									ROV	DI 1		- 1	
					_		_			DET			
		Program	overview										New
			Name				ype Load	ed Le	ength	Date En	able		
		0	BA_11			V	VPD		2	5/08/2003	×		Load
			CHASSIS			W	VPD		2	5/08/2003			HD -> NC
			FLANGE			v	VPD		2	5/08/2003		- H-	
onableap			IM_32				VPD				×		
		60	INJECTION MOI	I D			VPD				x		Unload
		-	ISLAND MILLING				VPD			5/08/2003			NC -> HD
		0.0	LEVIER	-			VPD			5/08/2003			
		O'H	LG_31				VPD .				~		Simulation
	.0			~							×	1	Simulation
	2.		LONGITUDINAL	G	UIDE		VPD				×		
			MSPLINE_BC			N	VPD		2	5/08/2003			124

Keys/inputs

0000000

Services

Diagnosis

Start-up

Screen / drawing

DIR DIR DIR DIR DIR ROV SBL1

ROV SBL1

ROV SBL1

RS232C

PG Disk/ Card

Acknow MMC ala

> Change anguage

> > NCK Reset

Description

Active operating area Services

In this operating area, you can manage files and read them in and out via the serial interface or a floppy disk.

Active operating area **Diagnosis** Alarm and and service information are displayed and documented here.

Active Coperating area Start-up

As the name already tells, this operating area is intended for system engineers in order to adapt NC data to the machine.

It is hardly of any importance in the daily use and will therefore not be discussed in detail in this Manual.

Example: Turning machine with two spindles

Start-up Custom

X1 Z1

wZ1

ess level: Se

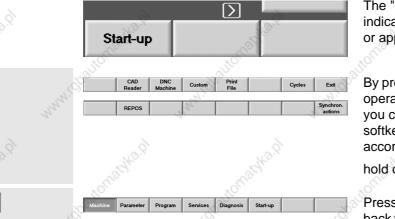
Depending on the configuration of your system, the 7th or 8th softkeys of the main menu can also be labeled; you can use them to call other applications (e.g. AutoTurn).





By pressing the <Area switchover key> () repeatedly, you are able to go back and forth between the two operating areas last active what is quite useful, e.g. when programming to see the tool data in parallel.

Just try it with both operating areas "Program" and "Parameters".



The "etc. arrow" down on the right indicates that there are other functions or applications.

By pressing the key > on the slimline operator panel or \bigcirc + F9 on the PC *, you can extend the menu, and the softkeys are reassigned - differently according to the configuration -

hold down * 😰 , then 🔊

Pressing the key once again brings you back to the main menu of the operating areas.

lf ...

22

you work on the machine:

Please, observe the instructions of the machine manufacturer!

Trip the main switch to disconnect the system from the mains.

you work with SinuTrain on the PC:

On the extended main menu bar, you will find a softkey to exit SinuTrain! (PC keyboard: F10 > 10 + F9 > F8)

When quitting the software, all user data are automatically stored for the next session.

(Alternatives: EXIT, see page 26.)

2.1.2 Keyboard and screen layout

During your first contacts with the user interfaces of the control systems, you have already learnt something about the key <Area switchover> (), the <etc.> key (>) and the horizontal softkeys of the main menu. In the following, further important keys are introduced to you (using the example of the SinuTrain training keyboard "QWERTY" and the control system screen.

Turning off

lf ...

Exit

All keys of the slimline operator panel and of the CNC keyboard are integrated in the shown training keyboard, and in addition, you will also find here the most important keys of the machine control panel, which are also used on the PC.

All functions required for working with SinuTrain can be operated directly or via key combinations with a normal PC keyboard. They are listed in the following table. 2

Slimline operator panel

Description

PC keys

F1 F8

- F8

- F9

F 10

F9

SINUMERIK

SIEMENS

Key

By using the horizontal softkeys (numbered from the left to the right), you change between the operating areas. Within one operating area, you get into further menu areas and functions which can be called via the vertical softkeys.

By using the vertical softkeys (numbered from the top to the bottom), you activate functions or branch to further subfunctions which are called via the vertical softkey bar.

By using the <Area switchover> key, the main menu with the operating areas is displayed.

By using the <etc.> key, you extend the horizontal softkey bar.

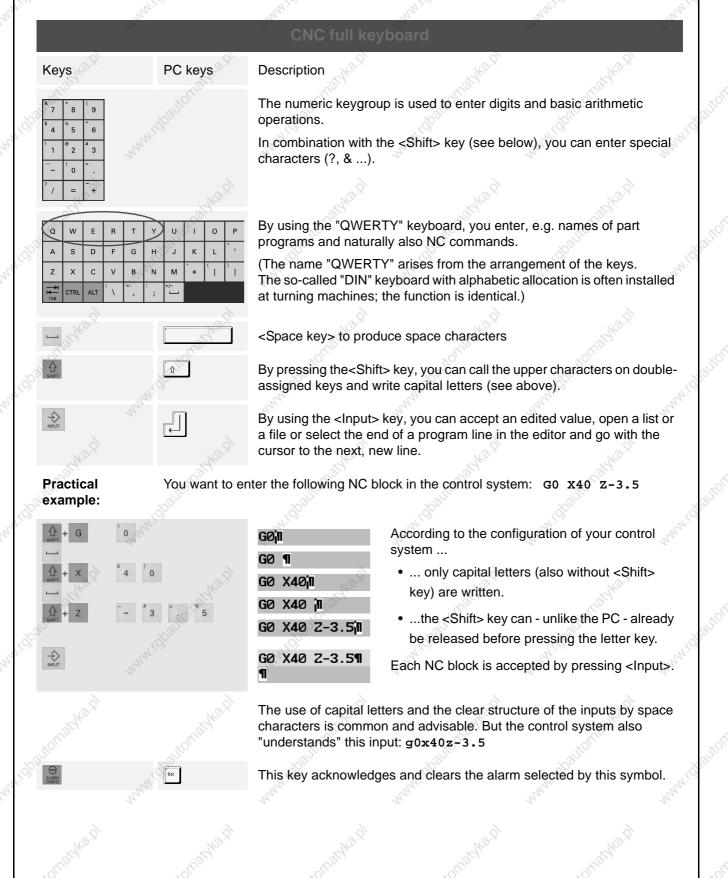
By using <Machine area key>, you can go directly to the operating area "Machine".

The <Recall> key closes the window on top and lets you return to the higher-level menu. This function is always available if the key symbol above the first horizontal softkey is displayed.

23

Hold down * ____, then press the appropriate <F> key.

1 Operation - Overview of the control system



The display of the "i" symbol in the dialog line shows that you can call further explanations on the current operating status by using this information key. The "online help", for instance, is especially useful for certain NC commands. (see page 76).

If several windows are displayed on the screen, only one of them has got the focus; you can see this by the window frame having a different color. With the help of this key you can go from one window to the next (alternative: mouse click into the window). Key inputs always refer only to the window with focus!

The keys <Page Up> und <Page Down> are used to move the scrollbar of a window, allowing you to scroll, e.g. through long part programs.

By pressing this key, you move the cursor to the end of the line.

You can move the cursor with the four <arrow keys> .

By pressing the <selection key> or the <toggle key> (or) or) on the numeric keygroup with "NUM LOCK" switched off), you activate or deactivate a field or select in input fields (if you can see the toggle symbol) one of various options (alternative: mouse click).

By pressing the <Delete> key, you delete the selected character or the value of an input field.

You delete the character left of the cursor with the <Delete key> (<Backspace>).

Practical example:

You have entered the NC block G1 x0 F0.2 and completed with <Input>. Now you want to change the feedrate to 0.3. This can be done using various possibilities:

END BACKSPACE			tomati	
▼				
DEL	► I	•		42.9

F12

Page Page Down

F1	XØ	FØ.2¶	
G1	XØ	F0.2/1	S
G1	xø	F0.¶	i
G1	XØ	F0.3¶	્ય
G1	XØ	F0.3¶	and in the
a			LT-
¶			
11		8	
	xø	F0.2¶	2
G1	- X	FØ.2¶ FØ.3¶	2
G1 G1	XØ	FØ.3¶	
G1 G1	XØ	3° .	/

1st possibility:

Since the last character has to be replaced here,
it is useful to go directly to the end of the line with
<end> and to delete the 2 (the character left of</end>
the cursor) with <backspace>.</backspace>

2nd possibility:

Alternatively, you can move the cursor to the right character by character, and if the cursor is on the **2**, you can delete it with .

2.1 Operation - Overview of the control system

In the input fields, you can use the <Edit> or <Undo> key to switch over to the editing mode (see practical example).

If you want to undo an erroneous entry in the editing mode, then press again. The overwritten entry will be recovered.

Enable editing mode.

to the next input field.)

Position cursor.

Add digit 5.

Practical example:

You want to change the value -82.47 to -82.475 in the input field without entering the whole digit once again. The value to be changed is selected (-82.470).



Key

→ 0

26

Ctrl + Alt +	
î +4 *	
Ctrl + Alt +	
E E.	

Alt

Alt

Alt

î **H** 5

PC key

Description

-82.470

-82.470

-82.475

-82.475

The key <NC Start> is intended mainly to start the execution of programs.

By pressing the key <NC Stop>, you stop the execution of the current program. Then you can continue the execution of the current program in the current block by pressing <NC Start>.

By pressing the <Reset> key, you interrupt the program execution, messages are cleared (see also), and the control system is reset to its initial state (ready for a new program execution).

The key <Single block> allows you to execute a program block by block. The program execution stops automatically after each block and can be continued with <NC Start>. Pressing <Single block> again lets you return to the following block.

> Each of these buttons activates the operating mode of the same name: AUTO, MDA, JOG. (in SinuTrain-Standard, only AUTO is operational).

Accept changed value (the orange selection changes

+9/-/0 Alt 🕂 û

8/6

Ctrl + Alt + 1 + 2 *

Ctrl

Use these buttons to switch the spindle on and off (not operational in SinuTrain-Standard).

The <EXIT> button is only available on the training keyboard. This stops and exits from the software program (softkey alternative available).

* Always press the keys one after the other as shown here and then hold them down!

achill CHAN	14 A	CHASSI			
Channel re 2	3	8)gram	aborted ROV SBL1	9	G fct.+ transf.
Work		Dto-go	Master spine	dle} 12	Auxiliary functions
x z	0.000 Ømm 0.000 mm	0.000	Act. Set Pos.	0.000 rpm 0.000 rpm 0 deg.	Spindles
c wz	0.000 deg 0.000 deg	0.000	Pos. Power	0 deg. 100.0 %	Axis feedrate 17
Current block	ă	N ^{O.}	Feedrate [m	m/min]	✓ Program blocks
M30	autornio		Act. Set	0.000 100.0 %	Zoom act. val.
			Tool Preselected	l tool:	Act. val. MCS
	13	_	G01	40,000	Program levels
0ver- store	DRF offset	Program 16 control	Block search Ha	andwheel 10 1 >	Program

1 The current operating area (machine, parameter... is shown here).

- 2 Channel status (reset, interrupted, active)
- 3 Program status (interrupted, running, stopped)

4 Channel name (in SinuTrain, the selected technology is displayed here, e.g. 'SinuTrain_Mill')

5 Alarm and messages are displayed in this field, together with a number under which further explanations can be read in the documentation.

6 Mode (AUTO, MDA, JOG) in operating area "Machine". (The training software SinuTrain includes only the mode AUTO.)

7 Path and program name of the selected program

Screen layout

8 Channel status messages (e.g. "Stop: EMERGENCY STOP active" or "Wait: Dwell time active")

9 Channel status display (e.g. ROV: The override for the feedrate is also effective for the rapid traverse feed, SBL1: single block with stop after each machine function block.

10 If the symbol i is displayed, additional help features can be called (see) key on the CNC full keyboard).

11 In the middle area of the screen, there are operating windows, according to the operating area (e.g. program editor) and/or - as in this case - NC displays (position, feedrate, ...).

12 Only one operating window has got the focus. It is marked by a different color. In this window, inputs are possibly active (see also key).

13 Here you will find instructions for the operator (if any).

14 The Recall symbol \frown indicates that you are in a submenu and that can you quit it by pressing the \land key.

15 The etc. symbol \searrow indicates that there are further functions which you can display by pressing the > key in the horizontal softkey bar.

16 Horizontal softkeys: Here you will find the operating areas or main functions.

17 Vertical softkeys: Here you will find submenus

27

and functions.

and a second second

Operation -

28

2.2 Setting up

In this section, you will learn fundamental sequences of operations required to set up SINUMERIK control systems 840D/810D/840Di.

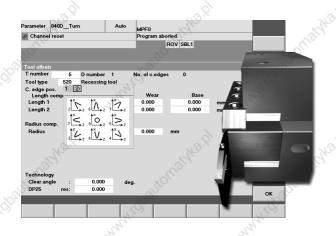
Setting up

Using a milling machine in the configuration "with tool **management**"*, you will learn ...

· how to create a new tool in the tool management

 how to "install" it in the real magazine and in the magazine image of the control system (Section 2.2.1).

8			. BX		
Parameter	840D_Mill	Auto	MPF0		1000
// Channe	l reset	20	Program aborted		
			ROV	SBL1	CN I
)*
Tool detail					New cuttgEdge
Name: FM	63	Duplo: 1	120 End mill	- 2	
Cutting ed	ges: #1	#2 #3	120 End mill		Cutt.
D	ges: #1	#2 #3		with edge rounding	
<u> </u>			130 Anglehea	d cutter d cutter w corner round.	
Location ty	pe: normal		V S140 Face mill	a caller w comer round.	M
Location c	oding: fixed		145 Thread cu	itter	
	-		150 Side mill		
Monitoring	type: None		v 151 Saw		¥
Magazine	no.: 0 Lo	c. no.: 0	(left, right)	Being changed [0 Was in use [0	
Tool sequ	ence: 0	L	22		M D LONG
10013640	ence. U		dir.	Unload [0	
				🗌 In (load) 🛛 [í	1829
Heavy tool	l [mm] 0.000	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	OEM_T2 [mm]	0.000	U.S.
OEM_T3 [mm] 0.000		OEM_T4 [mm]	0.000	
OEM_T5 [89	OEM_T6 [mm]	0.000	100
OEM_T7[mm] 0.000	<u></u>	OEM_T8 [mm]	0.000	×
Magazine list	Tool list			1.59	
	24			Sec.	G C
	-0			74	· · · ·



Machines with a simple "Tool compensation" naturally also manage tools, not with names, but via T numbers.

Especially with turning machines where all tools are clearly arranged on the turret, this easier configuaration is easy to use in practice.

This configuration "with tool compensation"* is described in Section 2.2.2.

Section 2.2.3 lists all tools which will be used in the following sample programs, and Section 2.2.4 deals with scratching and zero setting.

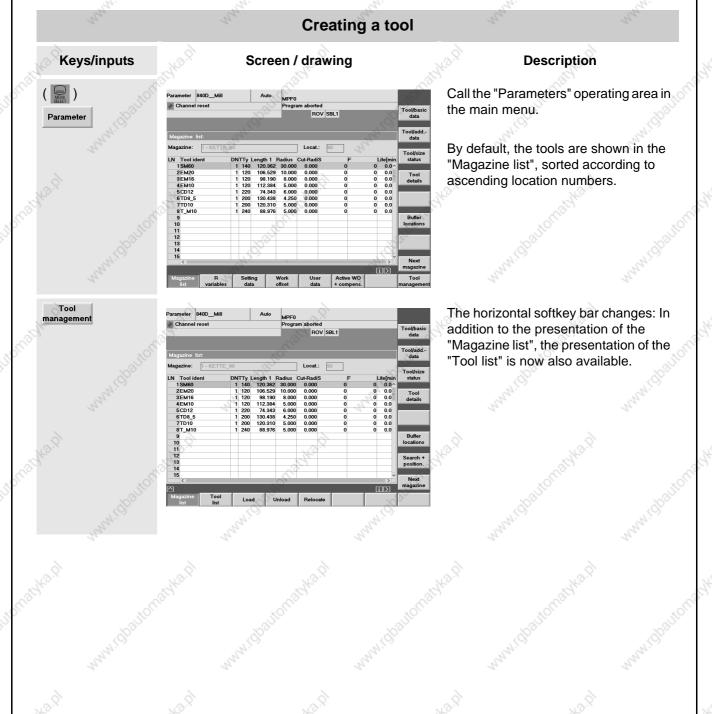
The procedure can be transferred to the correspondingly other technology without any problem.

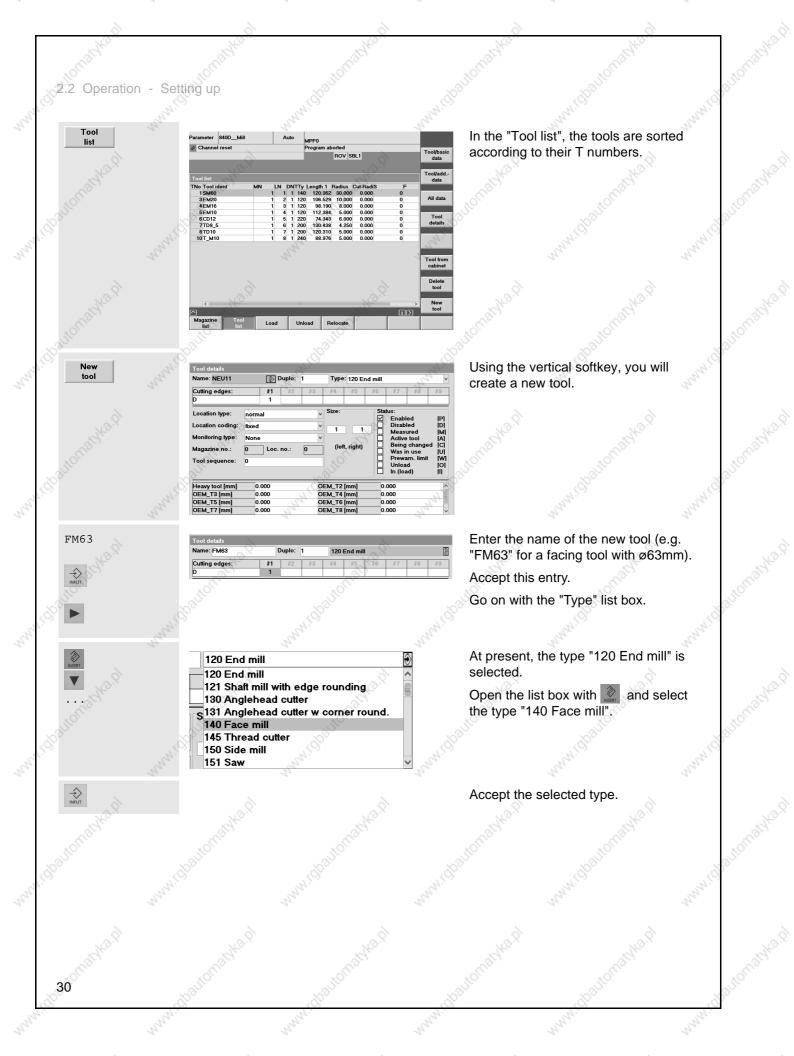
29

2.2.1 Tool management: Creating a tool and loading it into the magazine

Supposed you have a **machining center with a (chain) magazine**. You want to create a 63 milling head in the tool management and load it into any of the free magazine locations.

First, mount the tool manually in the spindle. When doing so, observe the instructions of the machine manufacturer. Then turn again to the control system screen.





A facing tool has been created. It has got *one* defined cutting edge D.

ROV SBL1

OEM_S6 OEM S8

0.000

mm]

0.000

134 2

0.000

Radius

[mm] 31.500

0.000

1

#1 1 💿

840D Tur

Cutt. edge

data

134.26

31.5

 \Rightarrow

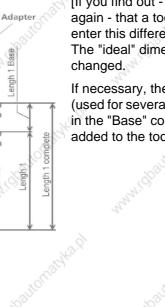
Use the appropriate softkey to change to the next window for the offset values of this cutting edge.

If you have measured the offset value for the length by using a tool-presetting station beforehand, you can enter it here.

The radius of a 63 milling head is 31.5...

[If you find out - when measuring again - that a tool runs out you can enter this difference in the line "wear". The "ideal" dimensions will not be changed.

If necessary, the length of an adapter (used for several tools) can be entered in the "Base" column. This size will be added to the tool length.]



Parameter 840D_Mill Auto					MPF0						
// Channel reset						Program at					
ROV SBL1									-	Tool/basic data	
Tool list:	X							the second		Tool/add data	
TNo Tool i	dent	MN	LN	DNT	Πу	Length 1	Radius	Cut-RadiS	F		
1 SM60		1	1	1	14(120.362	30.000		0		
3EM20	1	1	2		120	0 106.529			0	All data	
4EM16		1	3	1	120				0	_	
5EM10		1	- 4		120				0	Tool	
6 CD 12		1	5		220				0	details	
7TD8_	5	1	6		200				0	details	
8TD10		1	7		200				0		
10T_M1		1	8		240				0		
11 FM63				1	140	134.260	31.500	0.000	0		
									4	Tool from cabinet Delete	
<	?				Π			10.9		tool New	
	20							200	üΣ	tool	
Magazine list	Tool list	Loa	d		Unl	oad R	elocate				
- XO-							<u> </u>				

The tool data are complete. Back to the tool list.

A T number was automatically assigned to the tool.

But in the program, it will be easily called via its - more meaningful - name (see Chapters 3 and 4).

you want to change the data of a tool later ...

Select the line of the appropriate tool in the tool list.

Use the softkey [Tool details] to open the input field for the tool data.

Implement the changes.

Operation -

lf.

Tool detail:

Load

32

<<

Press the softkey [<<] to close the input box and to return to the tool list.

Loading the magazine

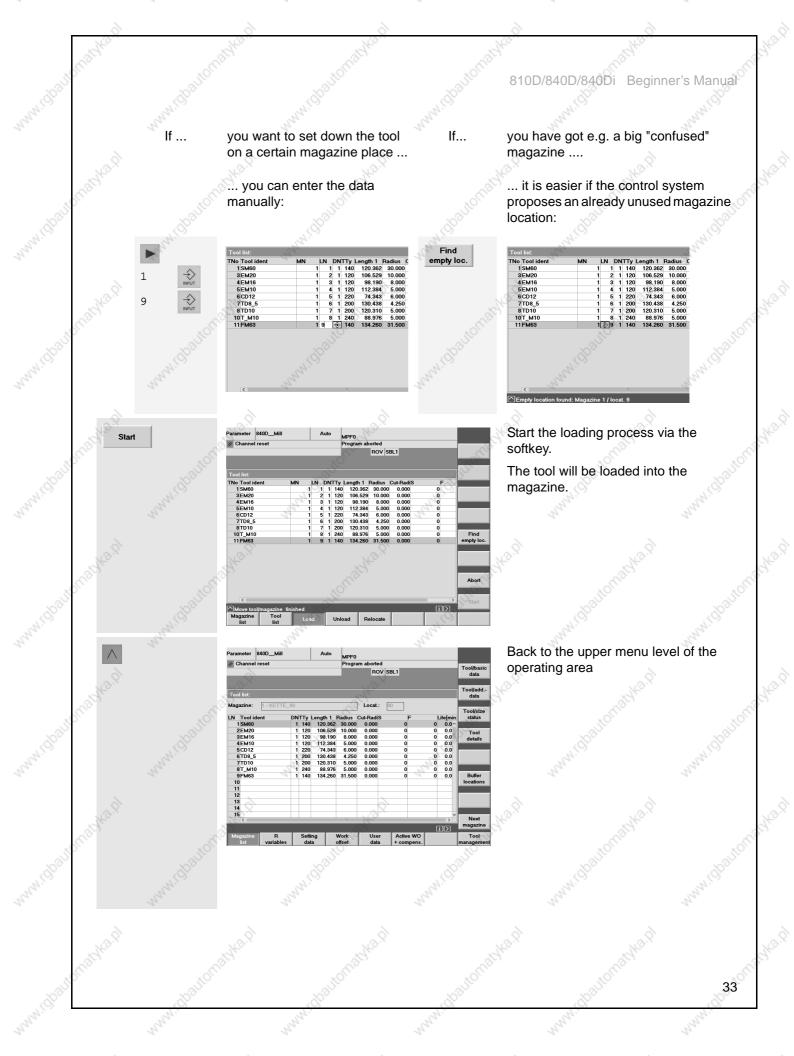
TNo Tool ident 📣	MN	LN	DNTTy
11 FM63			1 14

Select the line of the tool which you want to load into the magazine.

The fields MN (magazine number) und PI (location) are still free. This means that the tool is in the tool cabinet and has to be loaded into the magazine....

arameter	840D_Mill		٨	uto	S.	MPF0				and a second
// Channel	reset			-5		Program at	orted			
			-3		-	•	ROV S	BI 1		1 C
							nov o	DET		
TNo Tool id	lent 🔿	MN	LN	DN'	Πу	Length 1	Radius	Cut-RadiS	°∕ ⊨	
1 SM60	- N	1	1	1	140	120.362	30.000	0.000	0	
3EM20	N.O.	1	2	1	120	106.529	10.000	0.000	0	
4EM16	100	1	3	1	120	98.190	8.000	0.000	0	
5EM10	20	1	4		120	112.384	5.000	0.000	0	
6 CD 12	0	1	5	1	220	74.343	6.000	0.000	0	
7TD8_5		1	6	1	200	130.438	4.250	0.000	0	
8TD10		1	7	1	200	120.310	5.000	0.000	0	
10T_M10		1	8	1	240	88.976	5.000	0.000	0	Find
11 FM63				1	140	134.260	31.500	0.000	0	empty loc.
<			12	24	4	50				Abort Start
		_						4	<u> </u>	
Magazine list	Tool list	Loa	d		Unl	oad R	elocate		×	
.6	25						à.	20		

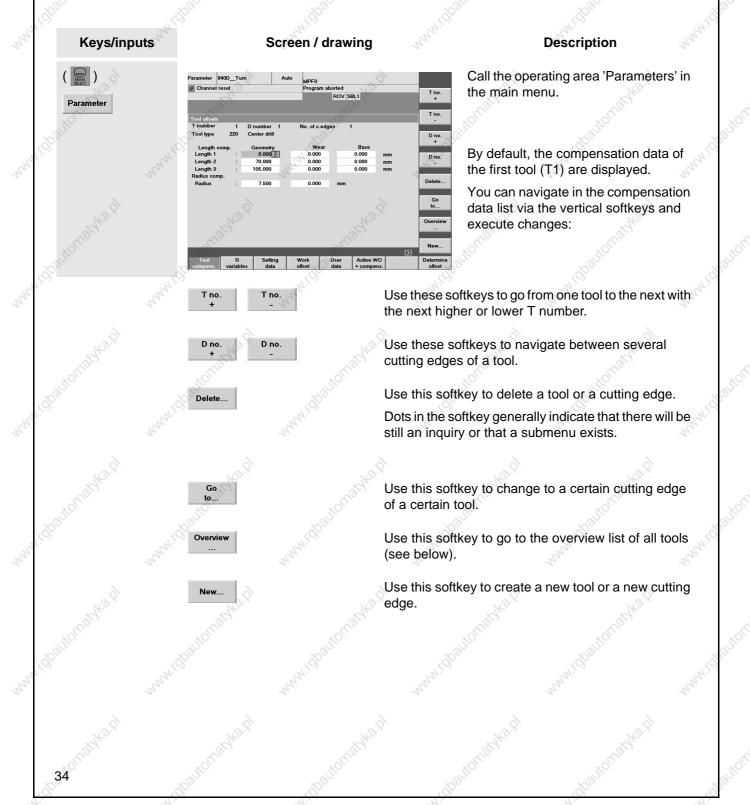
By using the horizontal softkey, you call the function for loading.



2.2 Operation - Setting up

2.2.2 Tool compensation: Creating a tool

Now, the **way of the easy tool management:** Your SINUMERIK control system manages T numbers and no tool names. Supposed you have a **turning machine** and you want to set down a 3mm recessing tool on the turret location 5.



 Parameter
 6400_Turn
 Auto
 MPF0

 © Channel reset
 POrgam aborted
 New.

 ROV (SBL1
 ROV (SBL1

 Counciew of bods
 Image: Source data stress of the source data stressource data stress of the source data stress of the sourc

Overview

New...

New tool

(5)

Parameter 84	10D_Tu	m 🗼	Auto	MPF0				ř.
// Channel re	eset	. 24		Program ab	orted		164	
		S.			ROV SBL	.1	for a	
		P.						
-								
Tool offsets								
Tnumber	1	D number	1	No. of c.edg	es 1			
Tool type	220	Center drill						New cuttgEdge
Length co	mp.	Geometry		Wear		Base		oungEuge
Length 1		0.000	Þ	0.000	1 I	0.000	mm	New
Length 2	:	70.000		0.000		0.000	mm	tool
Length 3	:	105.000		0.000		0.000	mm	
Radius comp) .							20
Radius	:	7.500		0.000	mm			201
								100
								32
								Abort

We: 0.000 0.000

0.000

0.000

In this overview list you can see that the T number 5 has not yet been assigned.

Use the appropriate softkeys to create a new tool.

If you have an older software version you have to enter the T number manually. If you enter a number already assigned then this is indicated as a note.
 With Software Version 6.0 and higher, the first for T and the sector of the

With Software Version 6.0 and higher, the first free T number is entered automatically.

Each type of tool has got a number. The first digit classifies the group of tools:

1xx - milling tools

5 D number 220 D Center drill

0.000

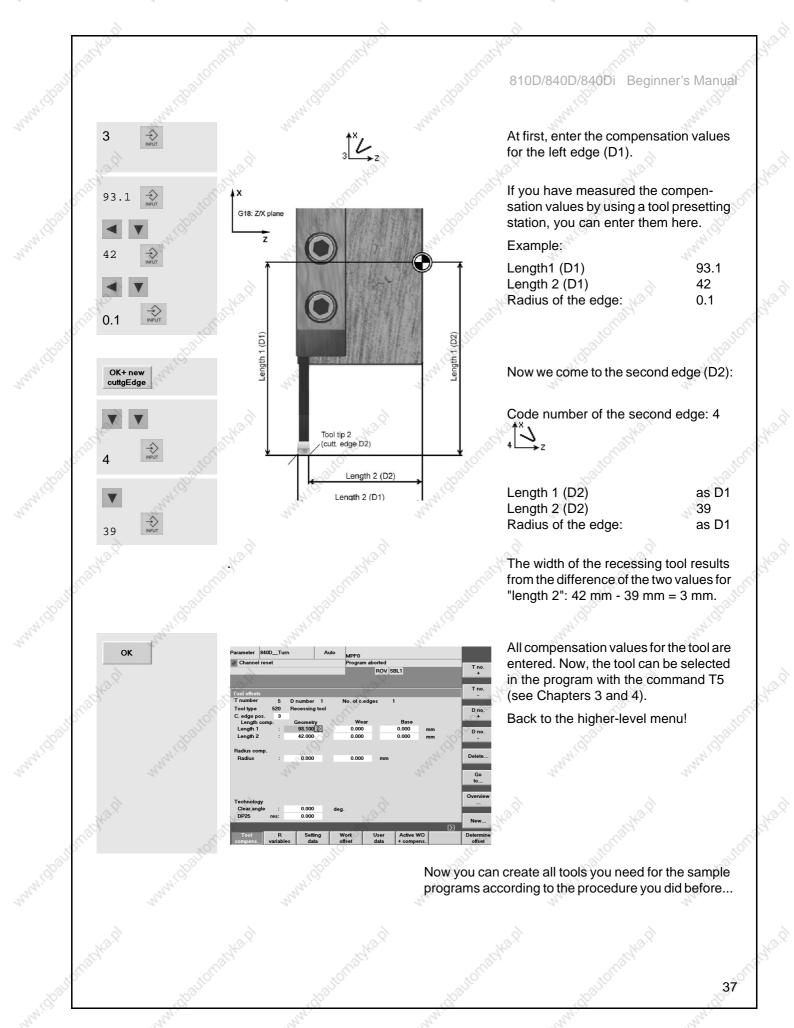
0.000

0.000

- 2xx drilling tools
- 4xx grinding tools
- 5xx turning tools
- 7xx special tools

The field is assigned the number 220 for the type "center drill" by default.

Operation - Setting up you have not yet known the If you know the type number for the lf type number for the "recessing "recessing tool" ... tool".... ... you can select the type from ... you can enter the number directly: the list: Already when entering the first digit, the At the same time, the list box with the tool groups will be list box of the turning tools will be opened automatically for orientation. opened when deleting the default number. Of course, you can use both described ways to deal with a list box also in combination. Select the group "5xx turning Just try several ways how to enter in tools" and accept the selection. order to get used to it. Select the type "520 Recessing tool" from the list in the same way you did before. The tool type was selected; next Tool offsets subject is the cutting edge T number 5 D number 1 Tool type 520 **Recessing tool** C. edge pos. 1 🔊 A help screen is provided for the cutting \odot edge position list box, which you can $2 \begin{bmatrix} x \\ y \\ z \end{bmatrix} z = 6 \begin{bmatrix} x \\ y \\ z \end{bmatrix} z = 1 \\ z \end{bmatrix} z = 1 \begin{bmatrix} x \\ y \\ z \end{bmatrix} z = 1 \\ z \end{bmatrix} z = 1 \begin{bmatrix} x \\ y \\ z \end{bmatrix} z = 1 \\ z \end{bmatrix}$ call with 36



2.2.3 Tools of the sample programs

Operation

In the previous sections, you created both one milling and one turning tool as an example. The sample programs of the Chapters 3 and 4 use the following tools. In order to be able to carry out these programs with the help of the simulation diagrams, you have to create these tools also in the operating area "Parameters".

(Of course, you can also use your "own" tools of the same type with different names. When programming remember the changed names for calling the tools.)

and a second		loois in the millin	ng programs	and Contraction of the Contracti	5
Туре	Name	Cu	utting data (extract)		
140 Face mill	SM60	D1	Radius 30	2	
120 End mill	EM20	Call D1	Radius 10	Carlos .	
120 End mill	EM16	J ^{ON} D1	Radius 8	J.C.	
120 End mill	EM10	് D1	Radius 5	1 Soc	
220 Centre drill	CD12	D1	Radius 6 *	. States	
200 Twist drill	TD8_5	D1	Radius 4.25 *	4	1
200 Twist drill	TD10 🔬	D1	Radius 5 *	à d	
240 Tap, regular	T_M10	J D1	Radius 5 *	St.	
tome	torne	BOLLE	ACT IL	10mc	

* Depending on the particular software version, the radius of a drill can be entered only by direct editing of the tool initialization file. If you are not familiar with it, you should create drills for the simulation as end mills!

There are the following types of tools available for milling:

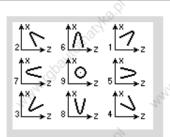
- 110 Ballhead cutter
- 130 Anglehead cutter
- 145 Thread cutter
- 200 Twist drill
- 220 Centre drill 240 Tap, regular
- 250 Reamer
- 711 Edge probe

120 End mill121 Shaft Mill with edge rounding131 Anglehead cutter w. corner rounding140 Face mill150 Side mill155 Bevelled cutter205 Solid drill210 Boring bar230 Countersink231 Counterbore241 Tap, fine242 Tap Withwirth thread700 Groove saw710 3D probe720 Directional probe900 Special tool

Tools in the turning programs

When creating turning tools, in addition to the cutting edge radius and the length compensations which you can determine by scratching or using the tool presetting station, the cutting edge position also plays an important part.

That's why you will find the cutting edge position help screen for your orientation.



3	Туре	Name	Cuttir	ng data (extr	ract)
	500 Roughing tool	RT1	D1,8	Radius 0.8	Cutting edge pos. 3
	500 Roughing tool	RT2	D1	Radius 0.8	Cutting edge pos. 3 clear. angle 44° **
	510 Finishing tool	FT1	D1	Radius 0.4	Cutting edge pos. 3
	510 Finishing tool	FT2	D1	Radius 0.4	Cutting edge pos. 3 clear. angle 44° **
	540 Threading tool	THREAD	D1	243.	Cutting edge pos. 8
	520 Recessing tool	GT_3 ***	D1 D2	Radius 0.1 Radius 0.1	Cutting edge pos. 3 Length 2 e.g. 42 Cutting edge pos. 4 Length 2 e.g. 39
	200 Twist drill	TD5	D18	Radius 2.5	* **** 🖉
	205 Solid drill	SD16	D1	Radius 8 * *	***

* Depending on the particular software version, the radius of a drill can only be entered by direct editing of the tool initialization file. If you are not used to it you should create the drill for the simulation as an end mill.

** If, when creating a tool, a "clearance angle" or "tool clearance angle" not equal to 0 is entered this is monitored for collosion when turning undercuts (see example in Section 4.2).

*** This tool was discussed in Section 2.2.2.

**** If you drill in the G17 plane (recommended), length 1 refers to the Z axis in the tool compensation, deviating from the compensation values of the turning tools (see Chapter 5 of the Operator's Guide)

The following tool types are available for turning:500 Roughing tool510 Finishing tool520 Recessing tool530 Parting tool540 Threading tool730 Stock stopIn addition, there are the drilling, milling and special tools which have already been mentioned on page 38 (milling tools).

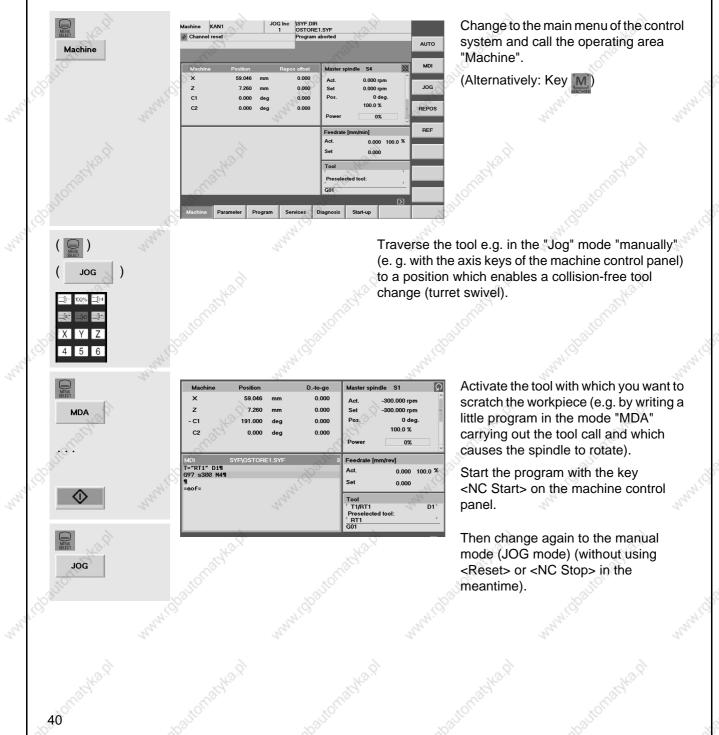
2.2.4 Scratching the tool and setting zero

Operation - Setting up

2.2

When scratching you carefully traverse a tool gauged beforehand to the workpiece until this "scratches". The control system can calculate the zero offset which the coordinates of the NC program are related to on the basis of the tool compensation data and the current position of the toolholder.

Scratching and setting zero of the workpiece is a direct interaction of control and machine or of tool and clamped workpiece. The function "Scratching" is therefore **not simulated in the training software SinuTrain**.



C Cł G fct.+ z 7.260 -0.000 Pos - C1 227.000 0.000 C2 0.000 Po Zoom act. val Set 0.000 Tool T1/RT1 Act. va WCS D1 Prese RT1 set Q 59.04 -0.000 300.000 rpm Act -0.000 Set z 7.260 300.000 rpm Pos 0 deg - C1 227.000 0.000 100.0 % C2 0.000 0.000 Powe 0% Tool name RT1 G54 Duplo no CuttEdge 0.000 0.000 mm 0.000 2 L2 34.021 mn C1 C8 0.000

Repos offset

-160.300

-0.000

0.000

0.000

Tool n

Positi

-101.254

7 260

173.000

0.000 deg

G54

Offset Setp 0.000

2

-27.761

0.000

0 000

×

z

- C1

C2

C1 C8 Master spindle S1

Set

Pos

RT1

-300.000 rpm

-300.000 rpr

0 deg 100.0 %

0%

deg

deg

Scratch

G54

100% Th

XYZ

4 5 6

1

Ek

Here you can activate the function "Scratch" via a horizontal softkey.

In the function window you determine in which zero offset (G54, G55, ...) you want to store the result.

Then position the cursor (with <Arrow down>, not with <Input>!) on the input field "Setpoint position" for the axis in which you want to scratch at first (here Z axis in turning).

Traverse the tool carefully with the axis keys, a separate handheld unit or electronic handwheels until it comes into contact with the workpiece. (If necessary, you can then retract the tool vertically to the scratching direction and stop the spindle).

<mark>ନ</mark>

In the field "Setpoint position", enter the value which you wish this coordinate to have later in the program. When doing so, take into account the length compensation of the tool (see help screen below).

The offset is displayed on the left next to the input field.

41

The length compensation of the tool in Z ("length 2") is opposite to the axis.

The geometry of the tool is thus considered *negatively* when calculating the offset.

This is done by switching over to "-" in the field after the setpoint position.

If necessary, determine the zero offset for the remaining axes in the same way (for turning, it is not necessary, because the turning center has always got the X value 0).

Finally accept all values in the selected zero offset, in this case G54.

You can "read again" all zero offsets of the control system in the "Parameters" operating area.

Axes +

Axes

Base WO

Tool

The zero offset becomes active when calling the appropriate command (G54, G55, ...) in the NC program.

ROV SBL1

Z [mm] -27,761 0,000 0,000 0,000 0,000 0,000 0,000 0,000 0,000 0,000 0,000 0,000 0,000 0,000 0,000 D

× [mm) 0.000

0.000 0.000 0.000 0.000 0.000 0.000

0.000

0.000 0.000 0.000 0.000 0.000 0.000 0.000

2.2 Operation -

ок

Parameter

Work

offse

42

Setting up

G57

3507

Fine Coar Fine Coar Fine Coar

Fine Coar Fine

2.3 Managing and executing programs

This section deals with swarf and swarf removal.

Provided that there is already an executable and tested program (see Chapters 3 and 4 regarding programming) ...

... then you will learn here how you can load it from a floppy disk into the control system, from the program management into the kernel of the control system and finally execute it.



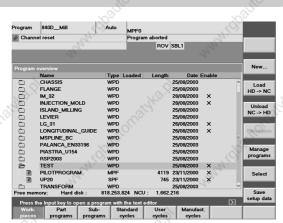
2.3.1 Saving data to floppy disk and reading them from floppy disk

Your SINUMERIK control system offers you several opportunities to read in and read out data. You can select them in the operating area "Services" via the vertical softkey bar:

[V24]	Serial interface
[Disk]	Floppy disk drive
disk	-8

[PG] Programming device [Archive...]Archive directory on the hard

The data exchange between control system and floppy disk will be discussed in the following. Insert a formatted, non write-protected floppy disk.

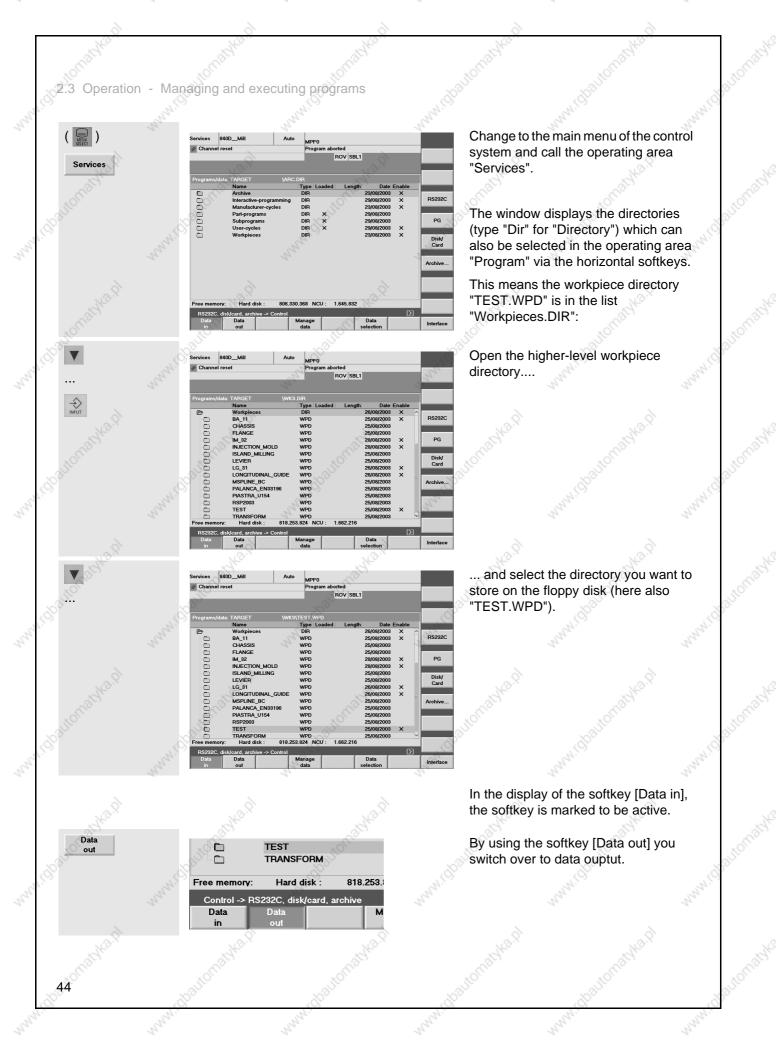


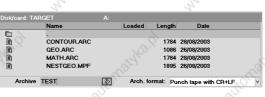
The basis of this example is any workpiece directory (here "TEST.WPD") you have created in the operating area 'Program' and to which, e.g. a part program ("PILOTPROGRAM.MPF") and a subroutine ("UP20.SPF") belong.

43

You find a detailed example regarding the creation of workpiece directories and programs in Section 3.1.

Control system -> floppy disk (reading out)





Disk/ Card

Start

Disk/

Card

Star

lf 💮

The window shows the contents of the floppy disk. The field "Archive name" has the focus; it is already assigned the workpiece name by default.

You advance the focus with the <Tab>key or the <END> key until the orange

bar has marked a line in the file list.

you want to know before saving which data have already been stored on the floppy disk



1784

178/

818.253.

818 253

MATH.AR

NESTGEO N

. CONTOUR.ARC GEO.ARC

 \otimes

TRANSFORM

Hard disk :

PILOTPROGRAM

Hard disk :

TEST

Data

TEST

UP20

Data

MATH.ARC

 \frown

Free memory:

in

Job is ready Data

B

Free memory: Job is ready Data

You can move the cursor in the file list with the keys <Arrow down> and <Arrow up>. The name of the selected file is accepted into the field "Archive name" (and it would possibly be overwritten!).

Switch the focus back to the field "Archive name" with <Tab> and enter the name of the workpiece again.

Start loading of the data from the control system to the floppy disk.

The loading process is logged in the notice line. If data have been successfully loaded, the message "Job completed" is displayed.

Open now the workpiece directory "TEST.WPD", select part program "PILOTPROGRAM.MPF" ...

... and load it separately as an exercise once again to the floppy disk.

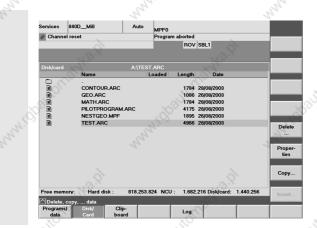
2.3 Operation - Managing and executing programs

Manage

data

Disk

Caro



Then, change into the menu [Manage data] and ask for the content of the [Disk].

The workpiece directory "TEST.WPD" was stored as "TEST.ARC" with the data contained therein.

The program file "PILOT-PROGRAM.MPF" was stored as "PILOTPROGRAM.ARC" .

Background:

The extension "ARC" stands for 'archive'. The complete data structure with workpiece directory, part program and subroutine is kept within the archive file "TEST.ARC.

This structure will be recovered when restoring an ARC file.

3	- <u>e</u> _	TEST	Salle.				
p		PILOTPRO UP20	PILOTPROGRAM				
	Free memory		k: 818	.253.			
	Control ->	RS232C, disk/c	ard, archive	,			
	Data	Data		м			
	in	out		Sugar.			

Quit the menu with the <Recall> key.

The cursor selects the file which was just copied to the floppy disk.

Floppy disk -> control system (reading in)

Data Select now the menu for reading in TEST e PILOTPROGRAM data. B **UP20** 818 253 Free memory: Hard disk RS232C, disk/card, archive Data out The part program which was Disk Care stored as ROV SBL1 "PILOTPROGRAM.ARC" on the floppy disk is to transfer back to RS232C the control system. PG 46



ROV SBL1

840D Mil

WKS\TEST\PILOTPROGR

Select the file "PILOTPROGRAM.ARC" from the file list of the floppy disk ...

... and start the transfer.

Because the original part program still exists on the control system, you will be asked once again whether you want to overwrite it.

Answer this question with [Yes]

The file will be replaced by its own copy.

Yes all Yes

Sto

2.3.2 Enabling, loading, selecting and executing a program

If a program is not yet completed or if it has still to be tested, you can withdraw its "**release**", preventing it from being loaded, selected and executed.

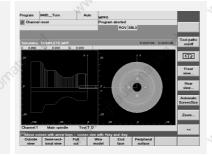
In order to execute a program, it must be in the NC main memory. If the control system possesses a hard disk, this is carried out using the "**Load**" function. Because the memory capacity of the NC main memory is limited, you should unload programs you temporarily do not need, i.e. to store them back to the hard disk (if any).

One of the loaded programs can be selected for execution. This is done using the "**Select**" function. The name of the selected program is shown in the top right of the head line of the screen.

Before you start a program you should remember the following things:

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Starl



Check carefully using the simulation whether the program is error-free.

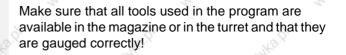
We do not assume any warranty for the sample programs in this Manual.

Especially cutting data (speed, feedrate, cutting width) have possibly to be adapted to the conditions of your machine.

2.3 Operation - Managing and executing programs



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Make sure that the workpiece was clamped reliably and that the zero point has been set correctly!

Under certain circumstances it is advisable to carry out first a dry run of the program, i.e. without workpiece in order to test all programmed movements for collision once again.

Set the feed override before the first test run of a program to ZERO just to have enough time also to intervene later in case of incorrectly programmed rapid traverse motions.

In especially critical places, you should switch over to single block mode.

Now we come to a concrete example: You have programmed the workpiece "Complete" in the operating area "Program" or you have loaded the program data in the operating area "Services", e.g. from floppy disk.

Machine (______) (______)

Program

Alter enable

Load HD -> NC

ок

Alter

enable

1000

CHESSTOWER

, onann			29 Ingin	ROV SE	BL1		G i tra
Work	Position	.00	Dto-go	Masters	pindle S1		Aux
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z	0.000	mm	0.000	Set	0.000 r		Spi
с	0.000	deg	0.000	Pos.		leg.	
wz	0.000	deg	0.000		100.0 9	6	/ fee
				Power	09	6	
Current b	lock				e [mm/min]		Pro
M30				Act. Set	0.000	0 100.0 %	z
					0.000	,	ac
			201	Tool		4	Ac
				P	cted tool:		
	_	- 22	_	G01		~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	Pro
Over-		DRF	Program	Block		Correct	Pro
store		offset	control	search	Handwheel	program	ove
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Machine	840DTurn	Au	uto				
// Channe			MPHU	n aborted			
125				ROV SE	BL1		
4°			×	J.			
Program o	verview			1	Data		
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00000	BOLT BULLONE_K24	WP WP	D	28/	08/2003 23:00: 08/2003 23:00:		HD
	CHESSTOWER	WP	D	28/	08/2003 23:00	15 X	Ur
	COM_42 COMPLETE	WP	D D	27/	08/2003 20:41: 08/2003 23:00:	29 X	NC
	CYCDIV	WP	D	28/	08/2003 23:00:	23 X	Exe
	EVANIK5 MUNON_EJE210	WP WP		28/	08/2003 23:00: 08/2003 23:00:	26 X 35 X	ha
100	RECHUCK_PART	WP	D	25/	08/2003 11:09:	11 X	-
1000	SAVC SHA_41	WP WP	D D	28/	08/2003 23:00: 08/2003 00:14:	39 X 22 X	e
100	SHAFT	WP	D	27/	08/2003 00:07:	20 X	
Bar	SUPPORT_BASE	WP	D	28/	08/2003 23:00:	43 X	s
Free merr	ory: Hard disk	: 817.	135.616 NCU	: 1.702.15	2	×	
∕⊂Job is r	eady		0			\sum	
Work- pieces	Part	Sub- rograms	Standard cycles	User cycles	Manufact. cycles		Ex
			5			~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	8
						- 8	
Machine	840D_Turn	Au					
// Channe	al reset	_	Progra	n aborted	20	14 ·	-
	1.		- 10	ROV SE	3L1		
Program o	verview						
	Name	Typ	e Loaded	Length	Date Tir 08/2003 11:09:	ne Enable 12 X ^	
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0	BULLONE_K24 CHESSTOWER	WP WP		25/	08/2003 11:09: 08/2003 11:09:	12 X	
1	COM_42	WP	D	27/	08/2003 20:41:	29 X	
000000000000	COMPLETE	WP WP			08/2003 22:56: 08/2003 11:09:	11 12 X	
10			2	201	03 11:09	12 X	2
	EVANIK5 MUNON_E RECHUCK	IR\COMPLI	ETE.WPD		03 11:09		
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	SHA_41 SHAFT				03 00:14		
6	SUPPORT				03 11:09	11 X	
F					2	×	
Free merr			246.208 NCU	: 1.702.15	2		
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Program	overview Name		Type Loa	ded Ler	ngth D	ate Tin	ne Er
0	Name BA_11	~1	WPD	ded Ler	25/08/2	003 11:09:1	12
	Name	.8		ded Ler	25/08/2 28/08/2		12 07

WPD

Change to the operating area "Machine".

If another mode is active, then activate the mode "AUTO".

Open the program overview ...

... and select the workpiece (directory) COMPLETE.

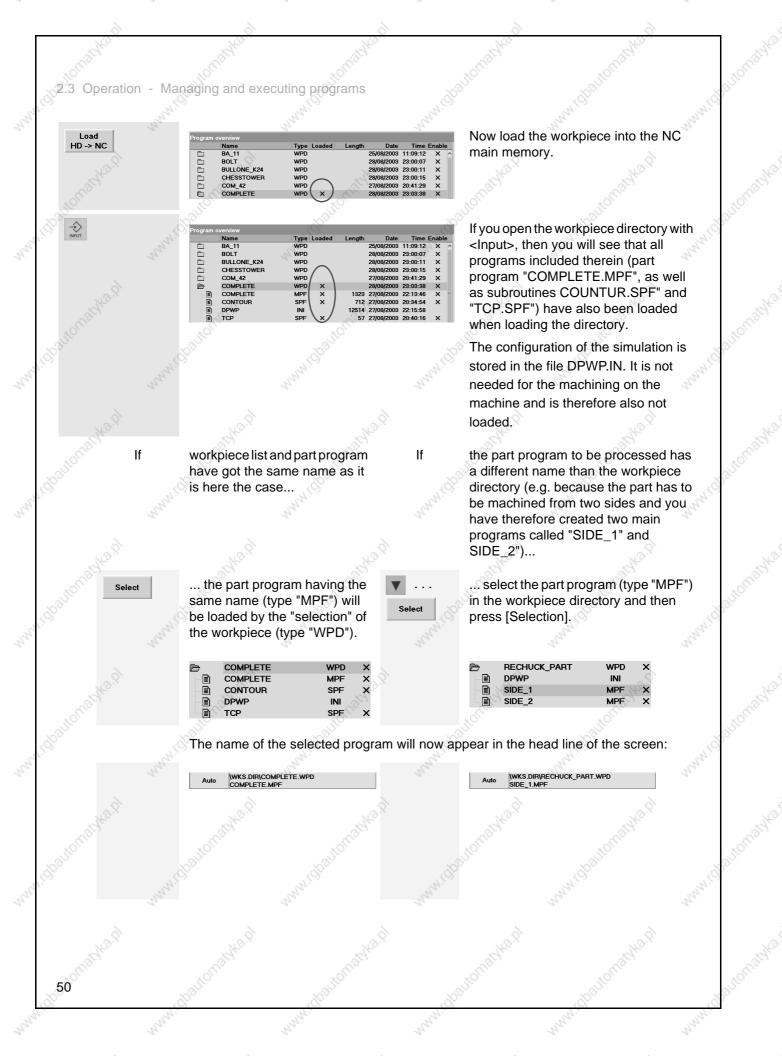
The workpiece is already released.

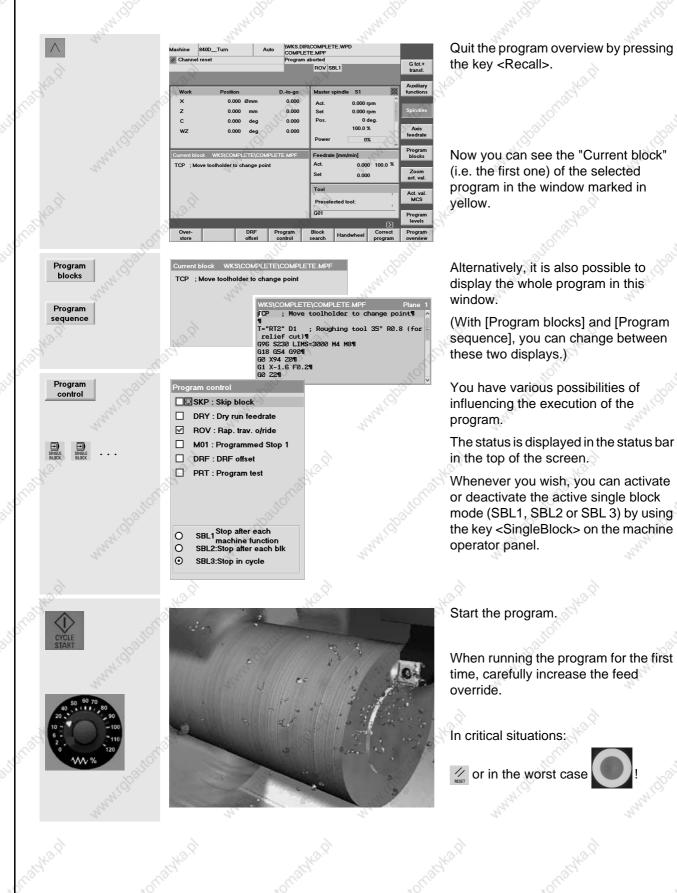
Just to exercise you can ...

- withdraw the workpiece release, ...
- try to load it (in vain) ...

• acknowledge the message...

• and finally release the workpiece.





3.1 Programming: Milling - Workpiece "Longitudinal guide"

Programming: Milling

In this chapter you will learn how to program the control systems SINUMERIK 810D/8450D/840Di, using the example of two simple sample workpieces.

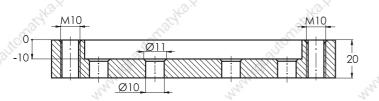
3

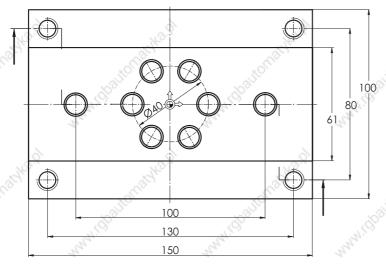
52

Of course, not everything will be discussed here what is possible to do with these powerful control systems. But, if you have programmed these both workpieces, then you will be able to start working without any help.

3.1 Workpiece "Longitudinal guide"

Using the workpiece "Longitudinal guide" as an example, you will learn the complete way from the drawing to the finished NC program key by key. In this context, the following topics will be discussed:





- Structuring into workpiece, part program and subroutine
- Tool call and tool change
- Fundamental functions
- Technological functions (cutting data)
- Simple traversing paths without cutter radius compensation
- Drilling with cycles and subroutine technique
- Simulation to check the programming

3.1.1 Creating workpiece and part program

Keys / inputs

(//

Program

Work-

Screen / drawing 840D Mi G fct.+ transf. ROV SBL1 D.-to-ao Master sc **S1** 0.000 Set 0.000 Pos 0 de 0.000 0.000 0% 0.000 0.000 Program blocks Feed 0.000 Zoom act. val. 0.000 Act. val. MCS 601 Program levels Program

ROV SBL1 AUTO MDA D.-to-go JOG 0.00 Set Pos 0.000 0.00 0.000 0.000 00.0 % REPOS 0.00 Pow 0% 0.000 REF Feed 0.000 100.0 Act Set 0.000 Tool G01

Description

Initial status:

- Any operating area (here "Machine") and mode (here "AUTO")
- Channel status RESET, i.e. no program is currently executed.
 If not yet done, press the <Reset> key to reset the control system (see status bar in the top left corner).

Change to the main menu

The operating areas are displayed on the horizontal softkey bar. The active "Machine" operating area is green.

Use the appropriate softkey to the "Program" operating area.

There are various program types which are now displayed in the softkey bar.

The selected type "Workpieces" (WPD) is a directory in which all relevant data of a machining task (part programs, subroutines etc.) can be stored.

It is thus possible to structure all data clearly.

3.1 Programming: Milling - Workpiece "Longitudinal guide"

New..

Longit.

OK

54



Create a new workpiece directory for the "Longitudinal guide".

Enter the name of the workpiece (there is no distinction between capital and small letters).

Please observe that each name can be used only once. (You have possibly to choose another name).

At the control system keyboard, text and digit inputs are always accepted by pressing the yellow <Input> key, and at the PC with <Return>.

Because you want to create a workpiece (WPD = WorkPieceDirectory), you can accept the file type without any changes.

The heart of the machining is the part program.

An appropriate program segment is to be saved in the workpiece directory.



When saved for the first time, the name of the toll directory is automatically used.

However, the file type is still preset to 'workpiece (WPD)'.

To open the list of file types, press the <Edit> button. Select and apply the type 'program segment (MPF)'.

(MPF = Main Program File)

(Alternatively, you may select the desired type directly by its initial letter, "T".)

A template is not used in this case.







Horizontal scrolling ON/OFF

veen autom, backur

= No automatic backur

Automatic block numbering ON/O

Number of the first block

Show hidden lines

Skip LF in program

atic block numbering

Increment:

The editor in which the program is written is opened.

The name of the workpiece directory is written in the headline, followed by the name of the main program.

The first program line is selected.

eof = marks the end of the program (end of file).

automatic block numbering is active on your control system.

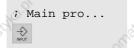
Programming is to be carried out without automatic line numbering.

The control runs also without block numbers and writing of a program is more convenient without numbers.

You can add block numbers later automatically via <Renumber>.

Accept the changed setting screen.

Delete the line number first created automatically.



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ок

Settings

The semicolon marks a comment line. To accept each program block, use the <Input> key ...

If you like, you can specify, e.g. the used tools in further comment lines....

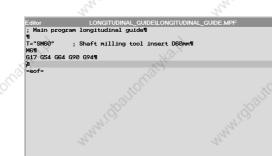
55

; Tool list:
; shell end mill 60mm

An additional space line (by 'Input') is used for structuring the program.

100

Workpiece "Longitudinal guide" ogramming: Milling -Tool call and tool change you are using a control system Or you are using a control system which ither which manages tools with manages tools with T numbers plain-text names (see Section (see Section 2.2.2). 2.2.1). T="SM60" ; Shaft milling tool T17 ; Shaft milling tool The tool (T = tool) is selected with its The tool (T = tool) is selected with its T number which plain-text name which was assigned was assigned in the tool management (operating area in the tool management (operating 'Parameters'). area 'Parameters'). Notice: This case differentiation in the tool management will later not be explained once more in detail. Then you have to change tool call yourself! MG With machines equipped with a tool changer, M6 will call the tool change. **Fundamental functions** G17 G54 G64 G90 G94 These are fundamental functions which are explained more in detail in the following overview: These functions are often valid for a complete program. But it is proposed to carry out these funtions at each tool change. **Description of functions** Functions of the same group G17 - Selection of XY plane G18 - Selection of XZ plane G19 - Selection of YZ plane G54 - Activation of first zero offset G55, G56, G57 - further zero offsets G53 - Cancelation of all zero offsets (non-modal) G500 - Disabling of all zero offsets G64 - Approximate positioning. The target point of a traversing block is not exactly approached, G60 - Exact stop. The target point is approached but there is a little rounding to the exactly. To this aim, all axis drives are subsequent traversing path. decelerated until they stop. G90 - Programming of absolute dimensions G91 - Programming of incremental dimensions G94 - F is used to program the feedrate in mm/min. G95 - F is used to program the feedrate in mm (per revolution) The functions of a group cancel each other. To see which functions are currently active, press the softkey G fct.in the operating area 'Machine'.



These are the first lines of the program!

The first tool was loaded and important, general basic settings have been defined.

This tool with a width of 60 mm will now be used to rough-mill the slot with a width of 61 mm.

3.1.4 Simple traversing paths without cutter radius compensation

G0 X110 Y0

In rapid traverse (G0), the tool is moved first to its starting position in the plane XY. 110 = X value of the workpiece edge + cutter radius + safety clearance = 150/2+60/2+5

(The 2 key for accepting a program line is not given here in detail because of better legibility. Accept each line manually by pressing the 2 key!)

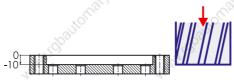
G0 Z2 S600 M3 M8

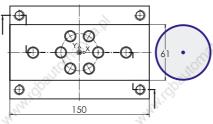
GO Z-10

Before the cutter is traversed to the required milling depth, position it on an intermediate plane (Z2) above the workpiece surface.

This guarantees safety when starting up the program (if the workpiece zero or the tool compensation were inadvertently set incorrectly). Furthermore, it is possible to accelerate the spindle in this block and to turn on the coolant.*

- S600 speed S = 600 min-1
- M3 tool rotates clockwise (CW rotation)
- M8 coolant is turned on
- Caution: All technological data used are only example values. Use your own empirical values on the machine and observe the information provided in the tool catalog.





In rapid traverse (G0), the cutter will go on traversing up to the required machining depth.

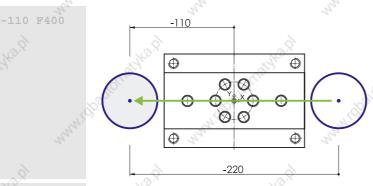
Note:

For reasons of safety, this traversing path should be realized as a G1 block with feedrate:

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G1 Z-10 F400

3.1 Programming: Milling - Workpiece "Longitudinal guide"



The cutter traverses at feedrate (feedrate 400 mm/min) along a straight line (G1) **to** the target point X-110 (absolute dimension referred to zero).

For G91 (incremental dimension), X-220 would have been programmed because the cutter traverses **by** 220 mm in the negative axis direction.

With rapid traverse (G0), the cutter is traversed away from the workpiece in Z direction. At the same time, the spindle is stopped with M5 and the coolant is turned off with M9.

Space line for structuring at the end of the machining with the shell end mill

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0 0

150

T="EM16" ; End milling cutter D16mm M6

-10

 \oplus

The two edges of the groove (61 mm in width rough-milled with a Ø60 shell end mill) will be milled to dimension using the 16 mm end mill.

The same G functions as we had for the first machining will also be used as the basis for machining with the end mill.

> In this first example, the contour is finished without taking into account the cutter radius automatically, i.e. the center point path of the cutter is programmed:

- 22.5 = 61/2-16/2
- X85 means 2 mm overflow.

With F200, the feedrate is selected less than before with the shell end mill.

G0 Z100 M5 M9

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G0 Z100 M5 M9

G17 G54 G64 G90 G94

G0 X85 Y22.5

G1 X-85 F200

G0 Z-10

G0 Y-22.5

G0 Z2 S500 M3 M8

At the end, the workpiece is left at rapid traverse rate, the spindle is stopped and the coolant is turned off.



Space line for structuring

you only want to mill (not drill), or if you just want to have a closer look at the simulation then you can end the progam now:

M30 is used to end the part program.

lf ...

M30

Simulation

Machine

When the program is executed, M30 will cause it to return to the beginning, and it can be restarted. M30 has therefore always to be written in the last program line.

You can simulate the finished program ... (for more details, see Section 3.1.7)

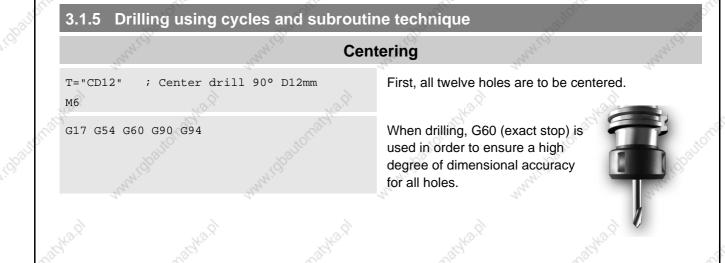
... and after quitting the simulation

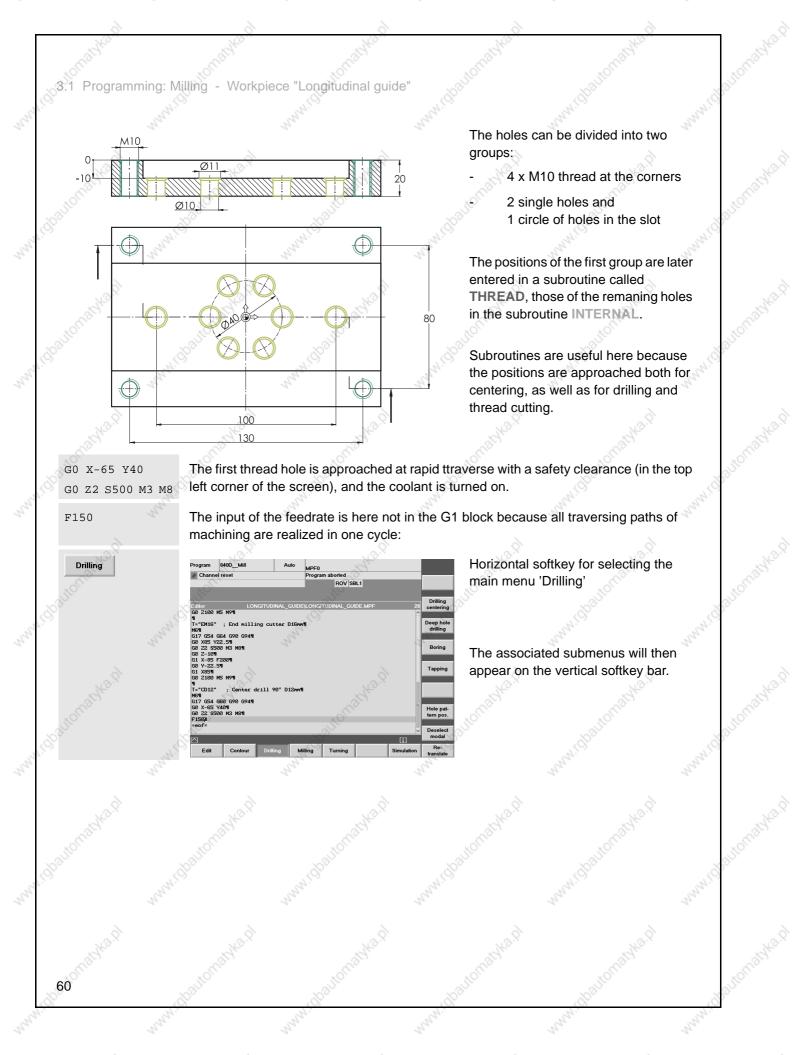
... execute it in the operating area "Machine" in AUTOMATIC mode (see Section 2.3.2).

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To be able to supplement the program later by the drilling machining operations, select the workpiece directory "LAENGSFUHERUNG.WPD" in the operating area "Program", open it with <Input>, select the part program and open this with <Input>.

Please make sure that the following program lines (see below: T="CD12" ...) are inserted **before** the command M30.





The dialog box for the drilling cycle CYCLE82 (drilling, counterboring) is opened via the vertical softkey.

The cursor is positioned on the first input field. The meaning of the field is explained graphically in the help screen, and in the yellow headline you will find an appropriate text.

Some of the fields in the dialog box are already assigned default values.

At first, change or supplement the first three entries according to the values given in the screenform.

* ... or here (because already loaded with the appropriate default values) simply **v** or

According to the drawing, the holes have a diameter of 10 mm and are to have a chamfer of 1 mm in width. A 90° center drill must therefore be inserted 5.5 mm.

This 'final drilling depth' can be entered in two different ways:

Final drilling depth, absolute

2.000

0.000

1.000

0.000

abs

RTP

RFP

SDIS

DP DTB

Retract plane

Ref. plane

Safety dist.

Dwell time

Fin.dr.depth

ROV SBL1

Fin.dr.depth	DP	-5.500	abs	Α
Annel C		And MIL		
Fin.dr.depth	DPR	5.500	inc	, N
	HOLL		10h	

Drilling

centering

2

0

Notice ...

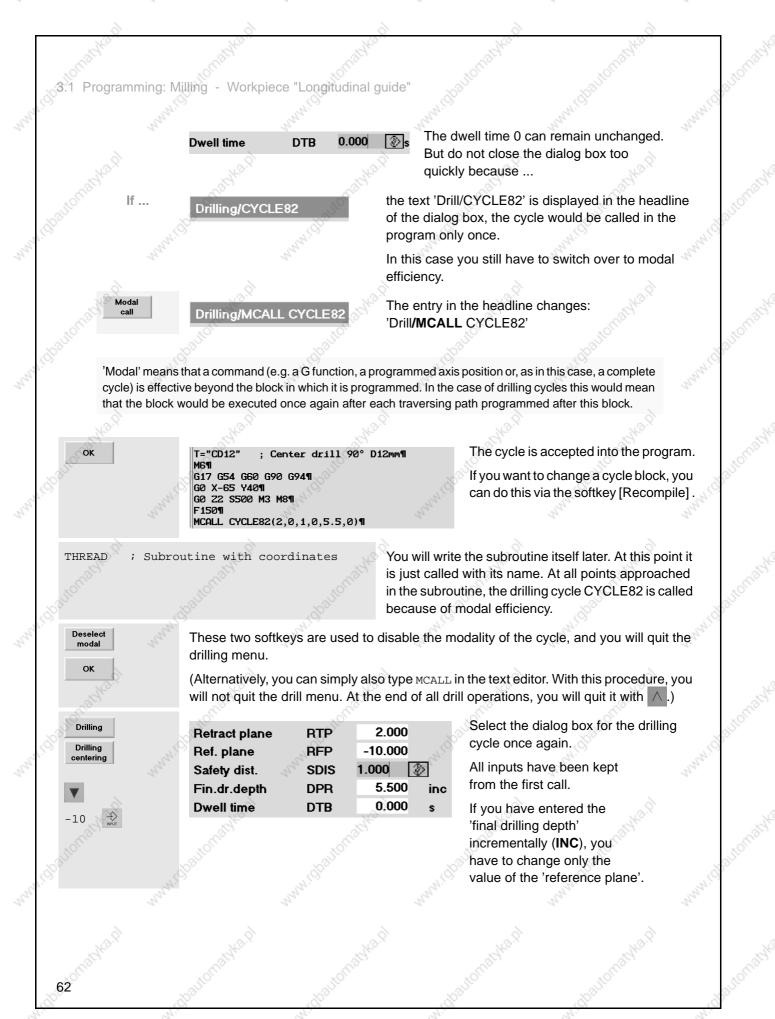
Drilling

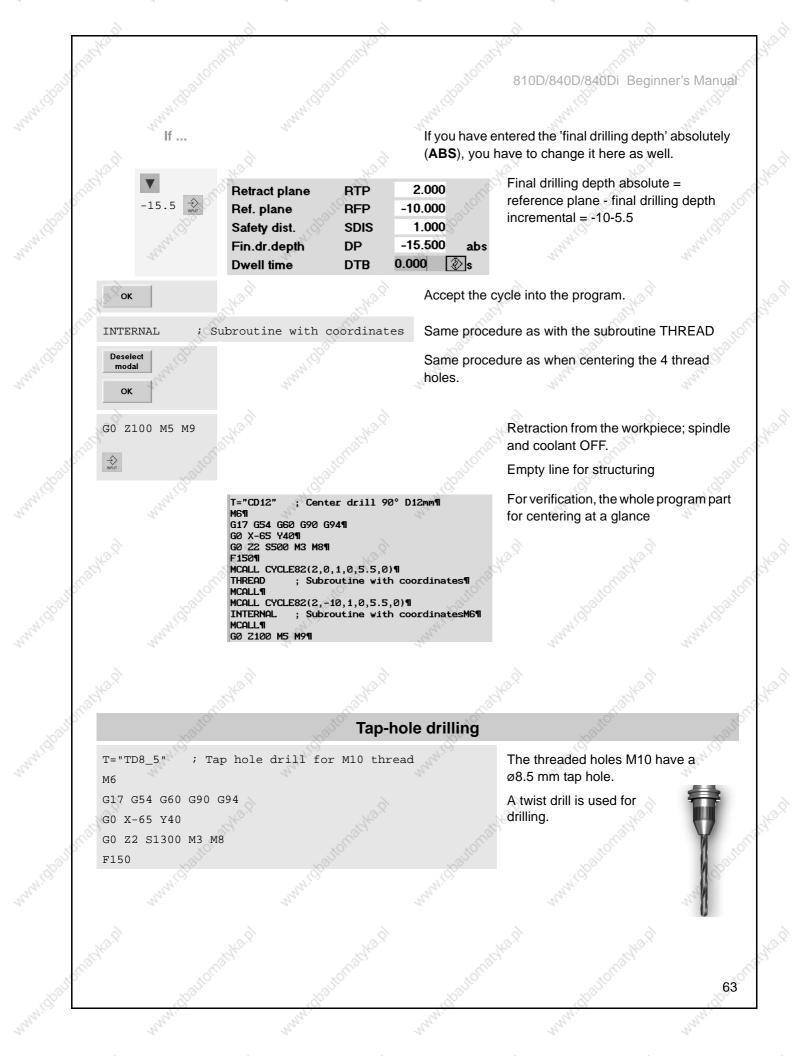
- ABS Absolute, i.e. the depth gauge referred to the workpiece zero is entered. Here: -5.5 ABS
- NC Incremental, i.e. relatively to 'reference plane'. Because only one 'downward' machining is useful, a (negative) sign is not entered for incremental depths. Here: 5.5 INC

61

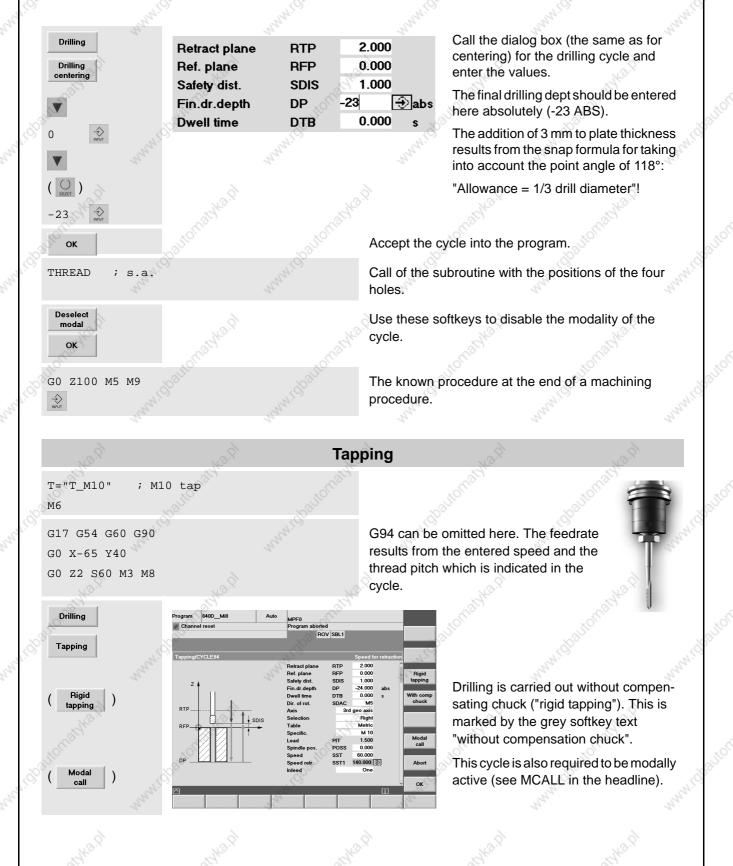
You can also change between ABS and INC with the <Shift> key O or with the softkey [Alternative] if the field 'Final drilling depth' is selected.

Both input options are correct. The setting INC is, however, recommended for centering because it is thus possible to center drill holes with *one incremental* depth on different reference planes.

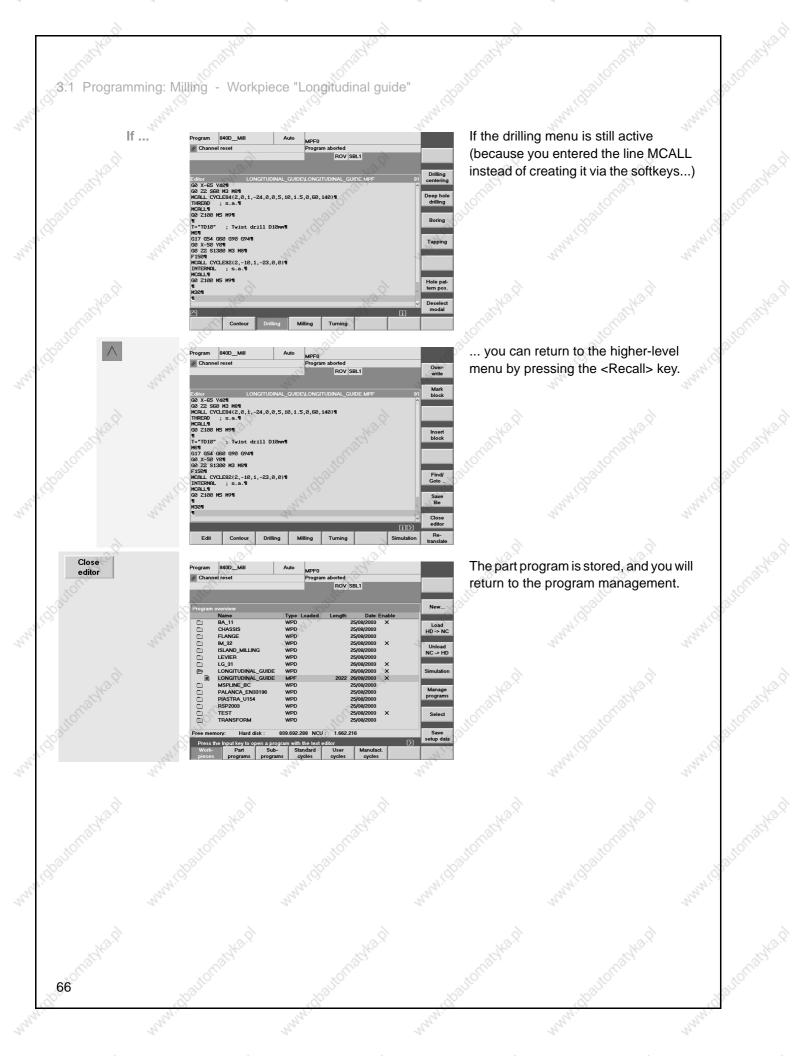




3.1 Programming: Milling - Workpiece "Longitudinal guide"



2 2.000 **Retract plane** RTP \Rightarrow 00 0.000 Ref. plane RFP Safety dist. SDIS 1.000 -24.000 DP Fin.dr.depth abs 0.000 Dwell time DTB s SDAC M5 Dir. of rot. Axis 3rd geo axis Selection Right If the entries in the "Table" and Metric Table "Selection" fields do not comply M 10 Specific. with the given values, you can Lead PIT 1.500 switch over with the key \bigcirc . 0.000 POSS Spindle pos. Speed SST 60.000 A higher speed when retracting 140.000 Speed retr. SST1 saves production time. Infeed One \odot Accept the cycle into the program. ок Same procedure ... THREAD s.a. Deselect modal ... as for the tap hole! ок G0 Z100 M5 M9 \Rightarrow Drilling through holes ø10 ; Twist drill D10mm Program lines for through holes T="TD10" Мб INTERNAL G17 G54 G60 G90 G94 G0 X-50 Y0 G0 Z2 S1300 M3 M8 The drilling cycle is also entered via F150 the softkeys and the input dialog. MCALL CYCLE82(2,-10,1,-23,0,0) INTERNAL ; s.a. MCALL G0 Z100 M5 M9





(Vertical softkey in the program management in the "Program" operating area, see previous page)

The first subroutine is given the name THREAD (see call in part program).

The file type "part program", however, is set by default.

Use the <Edit> key to open the list of the file types. Select the type "Subroutine" and accept! (SPF = Sub Program File)

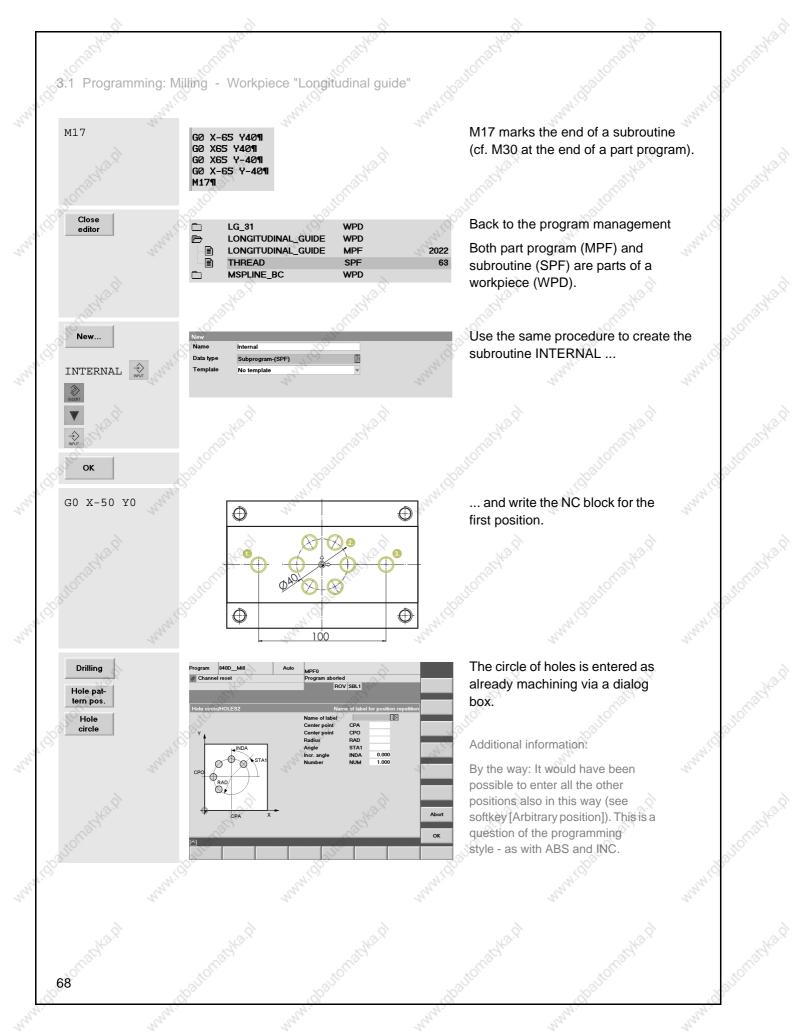
(Alternatively, you can select the required type via the first letter "s".)

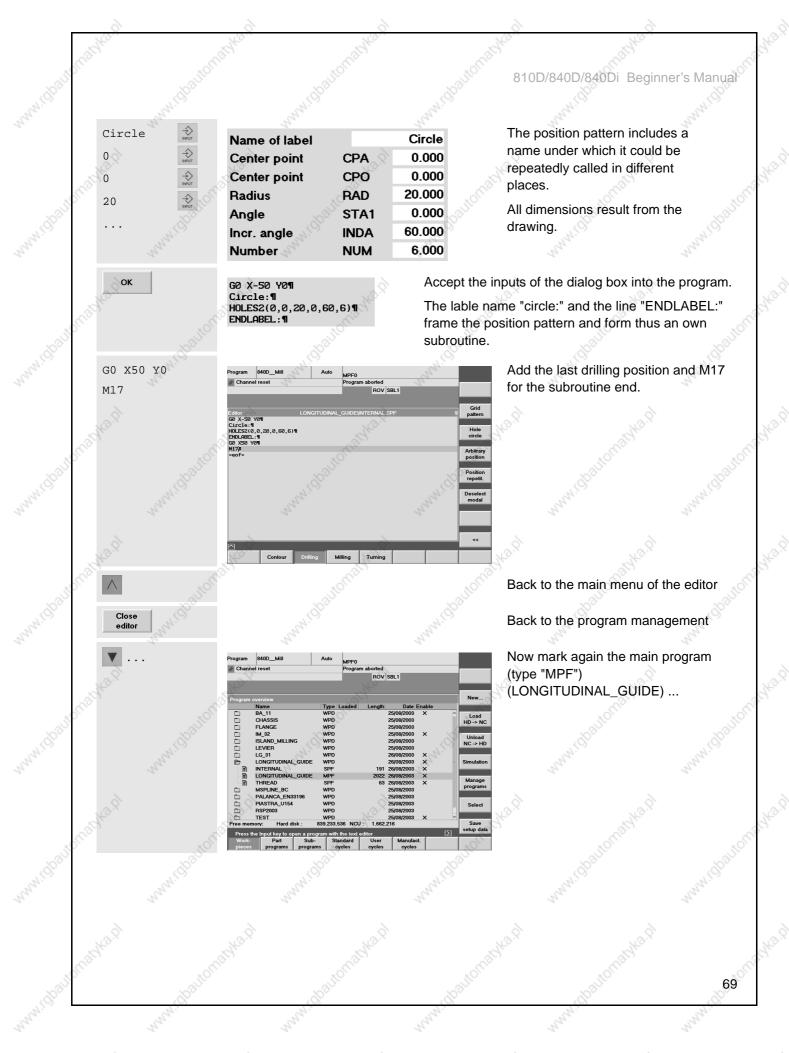
The subroutine is created and the editor is opened.

Now, write the program...

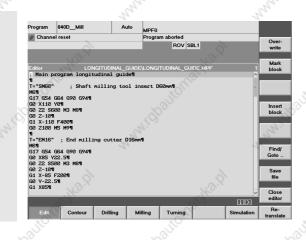
The four positions of the threaded holes are approached with G0 blocks at rapid traverse.

The modal efficiency of the cycles in the part program has the effect that the appropriate cycle is executed after each G0 block (see page 62).





3.1 Programming: Milling - Workpiece "Longitudinal guide"



... and open it with the <Input> key.

3.1.7 Simulating a program

C

nk dim.. cuboid

Simulation

Settings

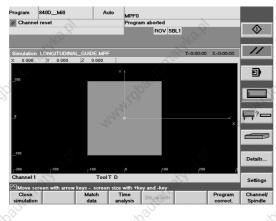
 \Rightarrow

-75

75

70

ок



Settings: SIMNCK51.03	.00 LONGITUDIN	AL_GUIDE				
Blank	Active view					
without model	⊙ X-Y					
O Cuboid	0 z-x					
O Cylinder	0 Y-Z					
Blank dim., cuboid						
X-min -100	Y-min	-100		Z-min	-20	
X-max 100	Y-max	100		Z-max	1	
Program control			1			
/SKP: Skip block		M01: Prog.	stop	D	ispl. trav. block	s only
- C		SBL1: Stop after	. ·			v
Tool data						
• with tools						
0						

Y-min -50 Y-max 50 Z-min -20

The simulation graphics is created and the workpiece is shown in top view (see softkey with the ***türkisfarbenenem*** margin).

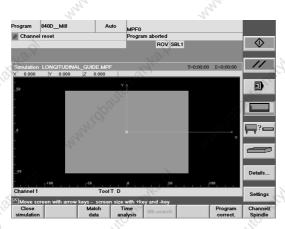
Workpiece zero and workpiece dimensions, however, do not yet correspond to the program to be simulated.

Use the appropriate softkey to open the interactive screenform for the simulation settings.

Enter the blank dimensions (coordinates of the corner points) of the cuboid.

Xmin -75	Ymin -50	Zmin -20
Xmax 75	Ymax 50	Zmax 0

Accept the settings.



lf ...

D

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D

W %

The workpiece dimensions are now correct.

Start the simulation!

you want to track a part of the simulation very exactly ...

then use the softkey [Single Block] to switch to single block simulation. The simulation will stop after each block; to continue, press [NC Start].

Pressing [Single Block] once more lets you return to subsequent block simulation.

You can relocate a certain part with the < Arrow Keys>, and with <+>/<-> you can zoom it.



By using [Override] and <+>/<-> or arrow keys, you can influence their speed during simulation.

3D presentation at the end of the simulation.

3.1 Programming: Milling - Workpiece "Longitudinal guide"

Close

simulation

Close

editor

72

To quit the simulation press this softkey or the <Recall> key (

To quit the editor press the appropriate softkey.

LONGITUDINAL_GUIDE	WPD
DPWP	INI
INTERNAL	SPF
LONGITUDINAL_GUIDE	MPF
THREAD	SPF
	DPWP INTERNAL LONGITUDINAL_GUIDE

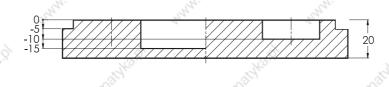
The file DPWP.INI is created automatically. Among other settings, it includes the customer's settings for the simulation of the "Longitudinal guide".

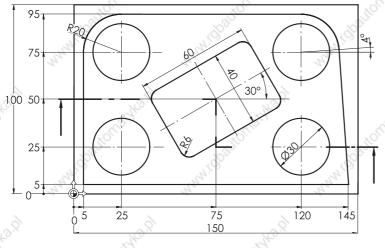
		<u>(0</u> 1		MPF0	Auto	D_Mill	19.	Program
		. · · · · · · · · · · · · · · · · · · ·	n aborted	Program		et	el rese	// Chann
		SBL1	ROV					20
New						iew	overvie	Program
	ble	Date Er	Length	Loaded	Type		Name	
Load	< ^	25/08/2003		24.	WPD	11	BA_1	-
HD -> NC		25/08/2003			WPD	SSIS	CHAS	
		25/08/2003			WPD	NGE	FLAN	
Unload	< 1	25/08/2003			WPD	32	IM_3	00000
NC -> HD		25/08/2003			WPD	ND_MILLING	ISLA	
110 110		25/08/2003			WPD	1ER	LEVI	
	<	26/08/2003			WPD	31	LG_3	
Simulation	<				WPD	IGITUDINAL_GUIDE		Ð
		26/08/2003	11650		INI	S. 1. C.P.	DPW	
Manage	<		191		SPF	ERNAL		
programs	<		2022		MPF	IGITUDINAL_GUIDE		
programs	<		63		SPF		THR	
		25/08/2003			WPD	LINE_BC		
Select		25/08/2003			WPD	ANCA_EN33196		E.
		25/08/2003			WPD	STRA_U154		
Save	×	25/08/2003	0		WPD	2003 Hard disk :	RSP2	<u> </u>
save setup data		216	: 1.662.	288 NCU	838.668.	Hard disk :	nory:	Free mer

Section 2.3.2 decribes in detail how you load the program into the NC main memory in order to be able to start it afterwards in the AUTO mode in the "Machine" operating area for machining.

3.2 Workpiece "Injection mold"

Using the workpiece "Injection mold" as an example, you will become familiar with the functions of the control systems for path milling and pocket milling. We take it for granted that you have already processed the example "Longitudinal guide" or are familiar with the subjects discussed in this context. This chapter will deal with the following new subjects:





Creating workpiece and part program

840D___

2000000000000000

Screen / drawing

OV SBL1

3.2.1

(//)

Program

Work

Keys / inputs

- Arcs (dimensioned using both Cartesian and polar coordinates)
- Milling with workpiece radius compensation
- Rectangular pocket (roughing and finishing)
- Circular pocket
- Copying of a program part

Initial status:

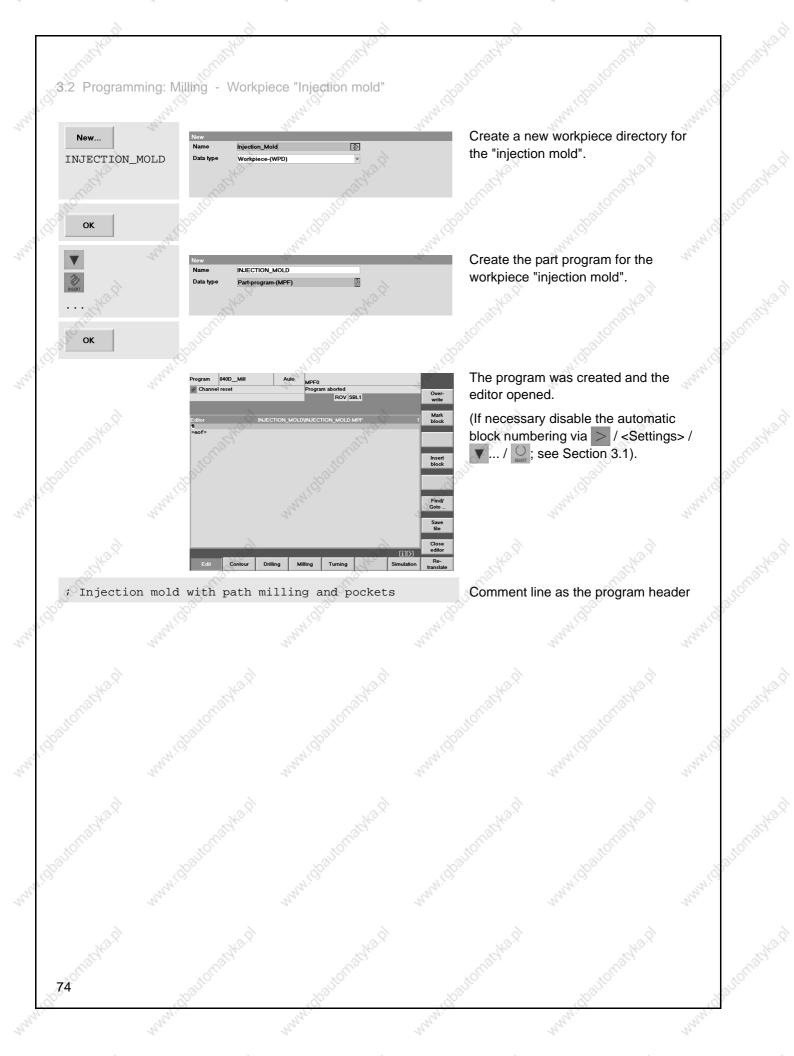
• "Program" operating area

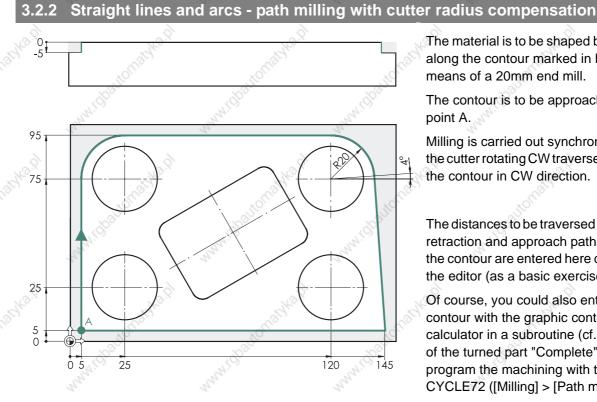
Workpiece management

(same procedure as for the workpiece "Longitudinal guide" in Section 3.1)

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Description





The material is to be shaped by cutting along the contour marked in blue by means of a 20mm end mill.

The contour is to be approached at point A.

Milling is carried out synchronously, the cutter rotating CW traverses around the contour in CW direction.

The distances to be traversed including retraction and approach paths along the contour are entered here directly in the editor (as a basic exercise).

Of course, you could also enter the contour with the graphic contour calculator in a subroutine (cf. contour of the turned part "Complete") and program the machining with the cycle CYCLE72 ([Milling] > [Path milling] ...).

75

T="EM20"

G17 G54 G64 G90 G94

; End mill D20mm

with tool management) Workpiece change **Basic settings** (see Section 3.1.3)

Tool call (configuration

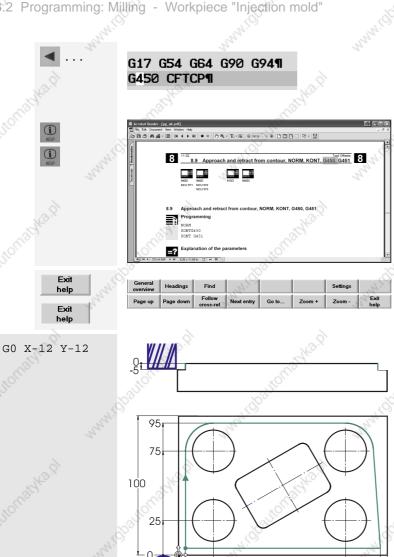
G450 CFTCP

Мб

G450 defines the approaching behavior at the starting point of the contour and the behaviour when traversing along contour corners: As far as contour corners are concerned, the appropriate traversing or approaching movements are carried out along a circular path.

CFTCP (acronym for "Constant Feed Tool Center Path") defines that the programmed feedrate refers to the cutter center-point path (not to the contour).

These commands (and of course all the other) are described in detail in the online help, which you can call - as described in the following - if your control system possesses a hard disk:



25

150

Simply position the cursor on the command on which you want to get more information.

Then press **1** to get a short description and once again **1** to open the electronic programming manual.

You can navigate within the manual via the softkeys, and afterwards you can quit it again.

A point near the starting point A on the contour is approached as the starting position of the cutter in the XY plane.

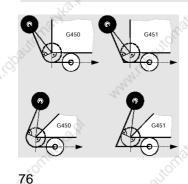
Infeed motion in Z, speed, direction of rotation and coolant ON

Outside the workpiece it is possible to infeed to the milling depth at rapid traverse rate (or better at feedrate: G1 Z-5 F100, see page 57).

G1 G41 X5 Y5 F100

G0 Z2 S1500 M3 M8

G0 Z-5



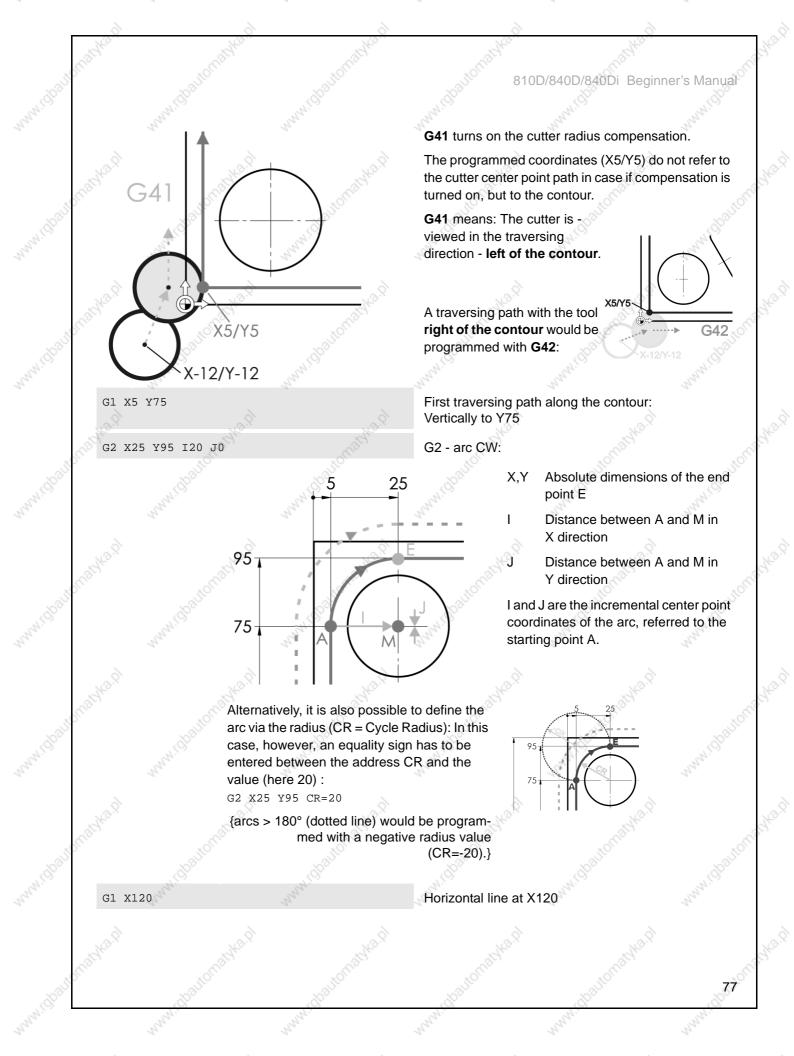
* A tangential approach of the point via an intermediate point at X5/Y6-12 (with G41 active) would be better in view of the manufacturing technology. The procedure selected here (angle between approaching path and first contour straight line < 180°, i.e. starting point before the contour) is normally easier as regards the program: If the first contour element is not paraxial, the exact intermediate point must be calculated.

The contour is approached ... *

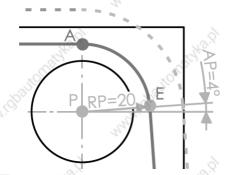
120

145

See also the "intelligence" of the approaching strategy using G450/G451 and the option of processing with the path mill cycle CYCLE72 ([Milling] > [Path milling] ...), generating approach and retract paths.



3.2 Programming: Milling - Workpiece "Injection mold"



The following is known from the following arc:

Center point P

Distance RP between the center point (the pole) P and the end point E

Angle AP between the positive X axis of the path from P to E

G111 X120 Y75 G2 RP=20 AP=4

G1 X145 Y5

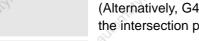
G1 X-12

The dimensions of the distance RP (radius polar) and the angle AP (angle polar) in the following G2 block are entered with an equality sign!

G111 is used to enter the (absolute!) coordinates of the center point (of the pole).

Line G1 bypassing starting and end points of the contour and away from the workpiece.

At the corner formed by the two straight lines, the command G450 just programmed results in a compensating arc of the cutter center path.



(Alternatively, G451 would extend the two straight lines of the cutter center path up to the intersection point.)

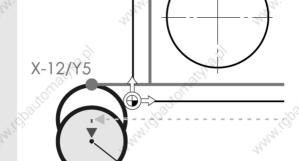
G450

G451

G0 G40 Y-12

G0 Z100 M5 M9

78



X-12/Y-12

G40 - cancel cutter radius compensation

Because the cutter is already outside the workpiece, the radius compensation can be carried out at rapid traverse. The position X-12/Y-12 will then refer to the cutter center point again.

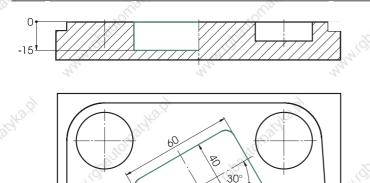
Retraction from the workpiece; spindle and coolant OFF

Empty line for structuring

T="EM20" ; End mill D20mm¶ M6¶ G17 G54 G64 G90 G94¶ G450 CFTCP¶ GØ X-12 Y-12¶ GØ Z-5¶ G1 G41 X5 Y5 F100¶ G1 X5 Y75¶ G2 X25 Y95 I20 J0¶ G1 X1201 G111 X120 Y75¶ G2 RP=20 AP=4¶ G1 X145 Y5¶ G1 X-12¶ GØ G40 Y-12¶ G0 Z100 M5 M9¶

For checking the whole program part of path milling at a glance

3.2.3 Rectangular pocket POCKET3



75

; End mill D10mm

The rectangular pocket requires a smaller cutter due to the corner radius R9.

At first, the pocket is to be roughed at the bottom and at the edge with an allowance of 0.3 mm, followed by finishing.

Both can be realized with the help of the rectangular pocket cycle (POCKET3) ...

Tool call Tool change Basic settings

At rapid speed to the pocket center

Infeed at safety clearance, speed, direction of rotation, coolant ON

G0 X75 Y50

Ó

T="EM10"

Мб

501

G0 Z2 S2000 M3 M8

G17 G54 G60 G90 G94

3.2 Programming: Milling - Workpiece "Injection mold"

Roughing the rectangular pocket

Although the feedrate F is defined within the pocket cycle, it is advisable to program it already in advance: The value already defined in the cycle is no longer valid after the end of the cycle; it could be possible that any following "single" traversing blocks G1, G2, G3) would unintentionally traverse at the feedrate of the previously programmed machining operation.

As the drilling cycles for the workpiece "Longitudinal guide", the input screen for the rectangular pocket cycle is called via softkeys. To open the submenu on the vertical softkey bar, use the softkey in the main menu.

3	Retract plane	BTP	2.000 🛞
	Ref. plane	RFP	0.000
	Safety dist.	SDIS	1.000
	Pocket depth	DP	-15.000 abs
	Operation		Roughing
	Dimensions		Center
	Pocket length	LENG	60.000
ŝ	Pocket width	WID	40.000
	Corner radius	CRAD	6.000
	Ref. point	PA	75.000
	Ref. point	PO	50.000
	Angle	STA	30.000
	Infeed depth	MID	6.000
	Fin. allow.	FAL	0.300
ŝ	Fin. allow.	FALD	0.300
2	Feedr.surface	FFP1	200.000
	Feedr. depth	FFD	150.000
	Mill. direct.		Down-cut
	Insertion		Helix
	Radius	RAD1	2.000
	Depth incr.	DP1	2.000
	Infeed width	MIDA	8.000
3	Solid machin.	ODONE.	Ent.pocket

The input fields for the pocket cycle go beyond the display area of the dialog box.

You can navigate within the dialog box via the scrollbar on the right or with the arrow keys.

For the other entries (CRAD, etc.), please refer to the two screenshots on the left.

When selecting the maximum infeed depth MID, the safety clearance has been taken into account up to Software Version 5.2. The 15.7 mm resulting from pocket depth, safety clearance and finishing allowance are distributed equally. An infeed of 3 x 5.233 mm is carried out whereby a plungecut of of 4.233 mm is carried out during the first cut.

With Software Version 5.3 and higher, it is sufficient to have an infeed depth of 5; the infeed is 3×4.9 mm.

Independent of the software version you are using, you will be on the safe side with 6 mm.

.

Milling

Standard pockets

Rectang.

0

60

40

80

Press this softkey to accept the cycle into the program.

In the text editor, the cycle appears as follows:

ZSD[2]=0 ;*R0*¶

POCKET3(2,0,1,-15,60,40,6,75,50,30,6,0.3,0.3,200,150,0,21,8,,,,2,2)

Finishing pocket edge and pocket bottom

After having carried out the roughing cycle, the cutter returns to the starting point of the machining. The same cutter is used for finishing.

S2400 F160

Rectang

16

OK

Speed and feedrate for finishing.

Because you still are in the menu 'Standard pockets', after roughing you can call the dialog box for the rectangular pocket directly via the softkey.

Retract plane	RTP	2.000	10
Ref. plane	RFP	0.000	
Safety dist.	SDIS	1.000	
Pocket depth	DP	-15.000	abs
Operation		Finishing	
Dimensions		Center	
Pocket length	LENG	60.000	
Pocket width	WID	40.000	
Corner radius	CRAD	6.000	
Ref. point	PA	75.000	
Ref. point	PO	50.000	
Angle	STA	30.000	
Infeed depth	MID	16.000	
Fin. allow.	FAL	0.300	
Fin. allow.	FALD	0.300	
Feedr.surface	FFP1	160.000	
Feedr. depth	FFD	80.000 🛞	Se la
<u> </u>		0	3

All fields still contain the values you have entered for roughing. The input fields have therefore only to be changed ...

Machining:FinishingInfeed depth MID:16Feedrate surface FFP1:160Feedrate depth FFD:80

Notice: The values for the two finishing dimensions are kept by the roughing cycle. The finishing cycle calculates the infeed motion from the finishing allowance and the safety clearance. Milling is finally carried out to the nominal size.

81

Press this softkey to accept the finishing cycle into the program.

_ZSD[2]=0 ;*R0*¶ POCKET3(2,0,1,-15,60,40,6,75,50,30,6,0.3,0.3,200,150,0,21,8,,,,2,2)¶ S2400 F160¶

POCKET3(2,0,1,-15,60,40,6,75,50,30,16,0.3,0.3,160,80,0,22,8,,,,2,2)

According to version and screen resolution, differences might occur in the presentation of the cycles in the editor. It is therefore recommended to use the "Recompile" function to carry out any changes in the cycle paramaterization.

3.2 Programming: Milling - Workpiece "Injection mold"

3.2.4 Circular pocket POCKET4

S2000 F200

 \Rightarrow

 \Rightarrow

->

Circular

pocket

2

0

-10

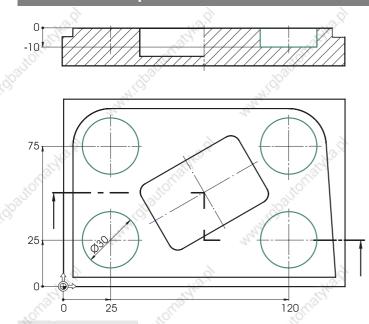
15

25

25

ок

82



All four circular pockets are identical, apart from their position.

At first the circular pocket in the bottom left corner is to be programmed.

The other three pockets will be generated by copying and changing the first one.

Speed and feedrate for machining the pockets.

Select the dialog box for the circular pocket.

	Retract plane	RTP	2.000 🛞
	Ref. plane	RFP	0.000
	Safety dist.	SDIS	1.000
ò	Pocket depth	DP	-10.000
Ĭ	Operation		Roughing
	Pocket radius 🔬	PRAD	15.000
	Center point	PA	25.000
	Center point	PO	25.000
	Infeed depth	MID	6.000
	Fin. allow.	FAL	0.000
	Fin. allow.	FALD	0.000
3	Feedr.surface	FFP1	200.000
	Feedr. depth	FFD	150.000
	Mill. direct. 👋		Down-cut
	Insertion		Helix
	Radius	RAD1	2.000
	Depth incr.	DP1	2.000
	Infeed width	MIDA	8.000
30	Solid machin.	DANE	Ent.pocket

Milling to size (in two steps):

- Machining "Roughing"
- Infeed dimension ... *
- No finishing dimension

All inputs can be found in the illustrations on the left.

Press this softkey to accept the cycle for the first circular pocket into the program.

abs

Now it would be possible to call the dialog box for the second circular pocket cycle with the softkey [Circular pocket]. As already described in the beginning, another procedure will be exercised here.

Quit the menu for pocket milling.

Copying a program part 3.2.5

2100 M5

840D_Mi

1211 10 Y-1211

POCKET3(2,0,1,-1

OCKET4(2,0,1,-10,15,25

: End mill D1

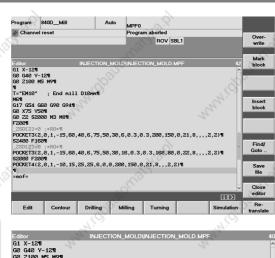
6949

POCKET3(2,0,1,-15,60,40,6,75,50,30,6,0.3,0. S2400 F1601

Mark

block

: End mill D10mm¶



The cycle for the circular pocket has been accepted into the program. The cursor is now in the next (empty) line.

Position the cursor on the program line with circular pocket POCKET4.

G17 G54 G60 G90 G94¶ ΜЗ POCKET3(2,0,1,-15,60,40,6,75,50,30,6,0.3,0.3,200,150,0,21,8,,,,2,2)¶ \$2400 F160¶ ______POCKET3(2,0,1,-15,60,40,6,75,50,30,16,0.3,0.3,160,80,0,22,8,,,,2,2)¶ 2000 F2001 POCKET4(2,0,1,-10,15,25,25,6,0,0,200,150,0,21,8,,,2,2)¶

ROV SBL1

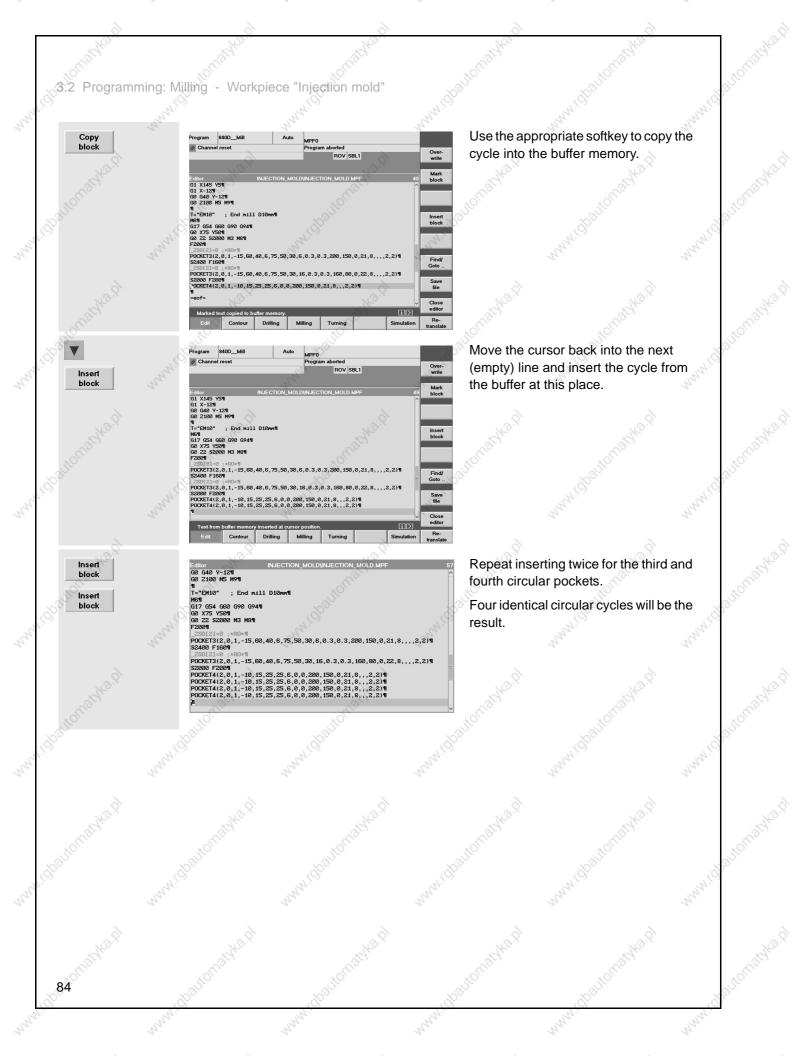
150.0.21.8...2.2)

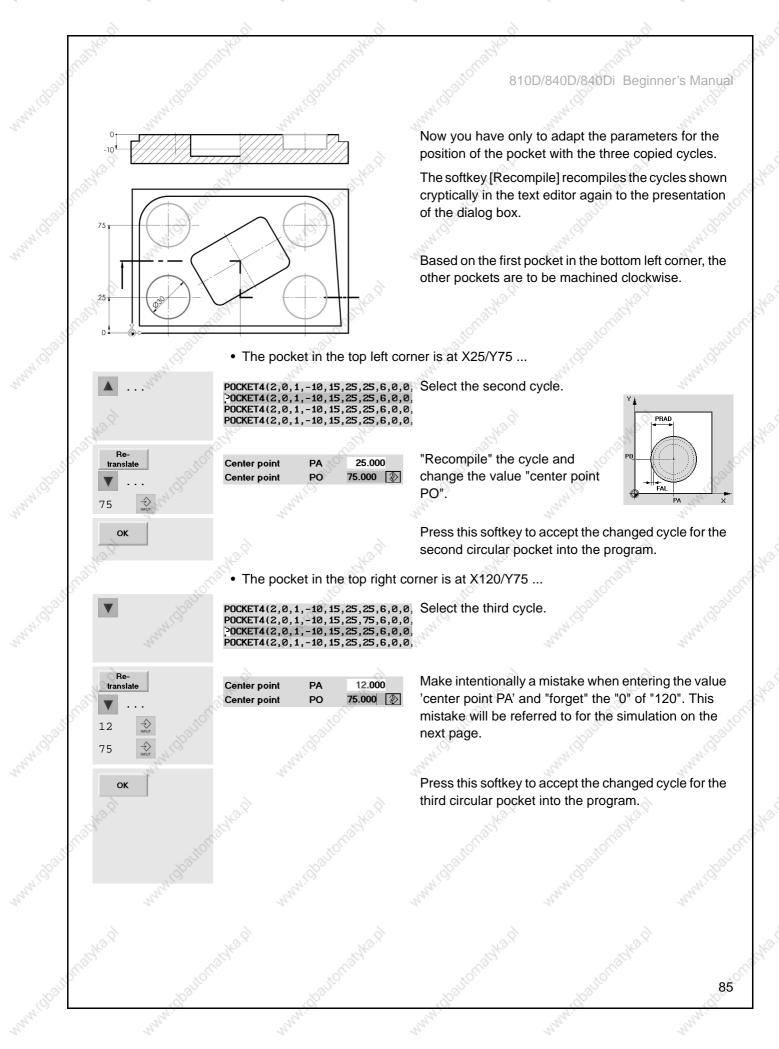
0,150,0,21,8,,,,2,2)¶

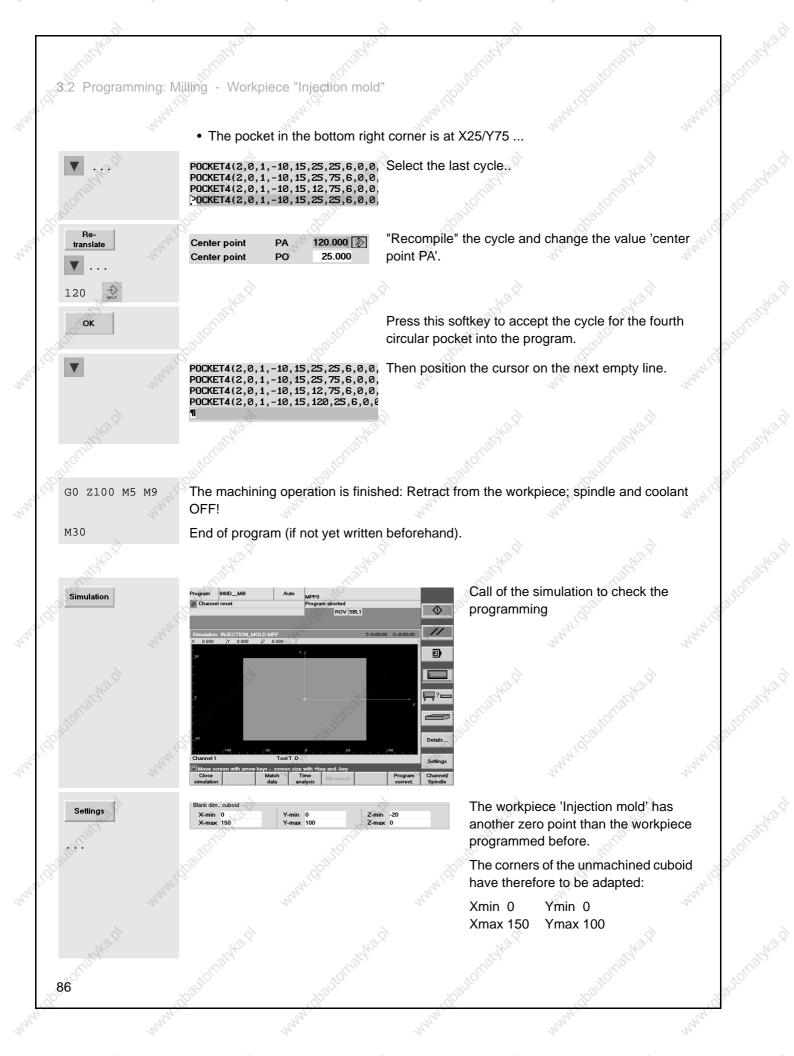
30,0,22,8,...,2,2)

Press the vertical softkey [Mark block].

The cycle is marked with a different color and the softkey appears inversely (white on ***türkis***).







Start the simulation.

ROV SBL1

11

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Details...

♦

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₽?⊂

Details... Settings

Channel/ Spindle

Program correct.

N MOLD.MP

_225[2]=0 ;*R0*¶ POCKET3(2,0,1,-15,60,40,6,75,50,30,16,,0.3,160,80,0,22,8,,,,2,2)¶ \$2000 F200¶

 $\begin{array}{l} 10, 15, 25, 25, 6, 0, 0, 200, 150, 0, 21, 8, . , , 2, 2) \P\\ 10, 15, 25, 75, 6, 0, 0, 200, 150, 0, 21, 8, . , , 2, 2) \P\\ 10, 15, 12, 75, 6, 0, 0, 200, 150, 0, 21, 8, . , 2, 2) \P\\ 10, 15, 120, 25, 6, 0, 0, 200, 100, 0, 21, 8, . , , 2, 2) \P\end{array}$

00,150,0,21,8,,,,2,2)¶

=0:18:18 Σ=0:18:24

T=0:18:18 Σ=0:18:24

ок

 \odot

lf&

(▽

Program correct.

444

Editor F200¶

POCKET3(2,0,1,-15,68 S2400 F1601

. POCKET4(2,0

POCKET4(2 POCKET4(2 POCKET4(2 GØ 2100 MS If you detect a mistake in the simulation like here in case of the third circular pocket incorrectly positioned, then:

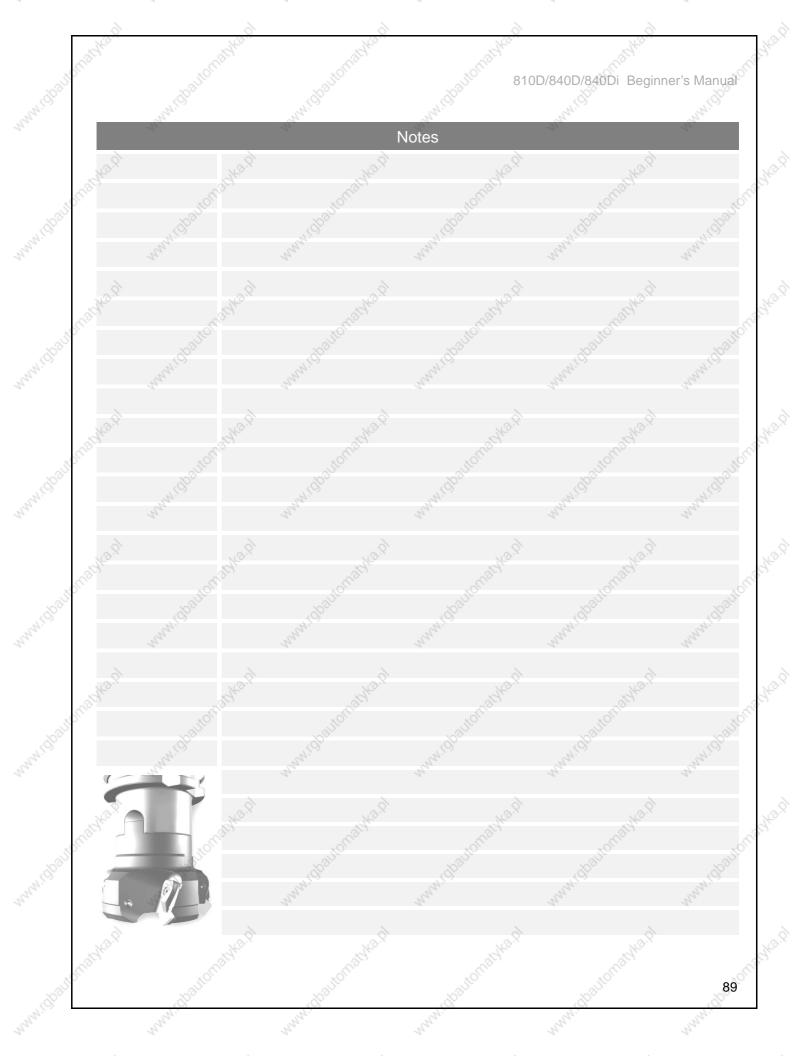
stop the simulation, ...

3444

... and activate the editor for correction.

The cursor is then directly in the line in which you quitted the simulation (in this case at the third circular pocket).

3.2 Workpiece "Injection mold" Programming: Milling -Correct the mistake, ... Over-write ROV SBL1 Mark block 0,150,0,21,8,,,,2,2)¶ POCKETS (2,0,1,-15 ,0,22,8,,,,2,2)¶ OCKET3(2,0 Find/ Goto ... and change again to the simulation Save file Close with [Close editor]. editor Simulation, here in the two-sides _?c presentation (top view and front view) \Diamond ROV SBL1 11 Details Close Press this softkey or the <Recall> key () to close the simulation. simulation Close Press this softkey to quit the editor. editor Later it will be explained more in detail how to load the program into the NC main memory in order to be able to start it afterwards in the mode 'AUTO' in the operating area 'Machine' for machining (Section 2.3.2.)

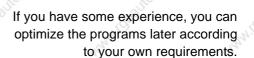


1.1 Programming: Turning - Workpiece "Shaft

4 Programming: Turning

In this chapter you will learn how to program the control systems SINUMERIK 810D/840D/840Di, using the example of two simple sample turned parts.

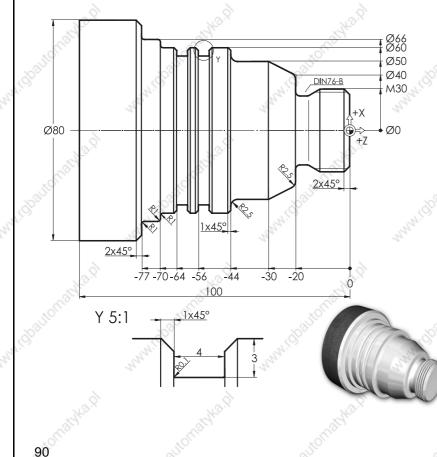
What we told already in the "milling chapter" also applies here: The sample programs are only intended as an entry to give you a first overview as regards the programming possibilities of the control system.



When dealing with the second shaft, you will learn something about the SINUMERIK contour calculator and functions for complete machining.

.1 Workpiece "Shaft"

Using the workpiece "Longitudinal guide" as an example (blank ø80, length 101), you learn the complete way from the drawing to the finished NC program key by key. The following topics will be discussed:



- Structuring into workpiece, part and subroutine
- Subroutine technique for contour description and approaching of the tool change point.
- Tool call, constant cutting speed, fundamental functions
- Face turning
- Cutting cycle CYCLE95
- Finishing with tool radius compensation
- Thread undercut cycle CYCLE96
- Thread cycle CYCLE97
- Grooving cycle CYCLE93

4.1.1 Creating workpiece and subroutine

840D 1

0.00

0.000

0.000

Program

WPD WPD WPD WPD WPD WPD WPD WPD WPD WPD

BA_11 BOLT BULLONE_K24 CHESSTOWER COM_42 CYCDIV

MUNON_EJE210 RECHUCK_PART

SHA_41

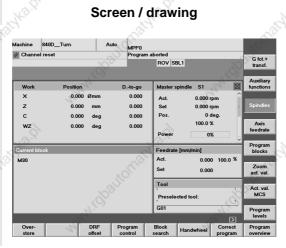
0000000000000

Keys / inputs

(//)

Program

Work-



ROV SBL1

Set Pos

Pow

Act.

Set

Tool

601

ROV SBL1

0%

0.000

Start-ur

0.000 100.0 %

Load HD -> NC

Unload IC -> HD

Manage programs

Select

0.000

0.000

0.000

Description

Initial status:

- Any operating area (here "Machine") and mode (here "AUTO")
- Channel status RESET, i.e. no program is currently executed. If not yet done, press the <Reset> key to reset the control system (see status bar in the top left corner).

Change to main menu

The operating areas are displayed on the horizontal softkey bar. The active "Machine" operating area is highlighted

Use the appropriate softkey to change to the "Program" operating area.

There are various program types which are now displayed in the softkey bar.

The selected type "Workpieces" is a directory in which all relevant data of a machining task (part programs, subroutines etc.) can be stored.

It is thus possible to structure all data clearly.



New.

ок

CONTOUR

92

 \Rightarrow

SHAFT



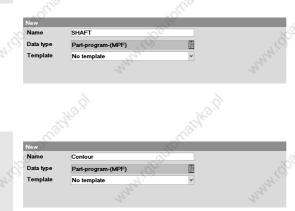
Create a new workpiece directory for the "SHAFT".

Enter the name of the workpiece (there is no distiction between capital and small letters).

Please observe that each name can be used only once. (You have possibly to choose another name.)

When working with the control system keyboard, text and numerical inputs are always accepted by pressing the yellow <Input> key, and when working on the PC - with <Return>. The "File type" field receives the focus.

Because you want to create a workpiece (WPD = WorkPieceDirectory), you can accept the file type without any changes.



An entry window will again appear for saving files in the workpiece directory.

The name "SHAFT" was taken from the workpiece directory and 'Workpiece-(WPD)' can again be seen in the 'Data type' field.

You want to enter the turning profile in a subprogram.

First overwrite the name with "Contour", the name of the subprogram.

Enter it by pressing on <Input>.

w.idballomatikee	Widdautonable	WIGDBUILDIN	and the second	, idbautomat
NA AND AND AND AND AND AND AND AND AND A	New Name Data ty Tempi Free n	Pe Subprogram-(SPF) Part-program-(MPF) Subprogram-(SPF) Job-list Channel-user-data-(GUD) Compensation-data-(IKA) ZeroOfset/Frame(UFR) Tool-plan-(TOP)	702.152	disatoma
MICS BUT	44	MP MP	gram aborted ROV SBL1	
MICOL OK	Free m	be Subprogram-(SPF) te No template	22 VCU: 1.702.162	Abort
MIGDC NORADICO.D	Program Chan Editor =of=	8400_Turn Auto pp Inel reset Pro SHAFT\CON	gram aborted ROV SBL1	Over- write Mark block
widdau madkad	Manna Sha Edi	Contour Drilling Milling	Turning Sim	il> Re- translate
MIGDAU	North Stations	Contour Drilling Milling	ACHER P	, ballona
MIGDAUD.	www.dautonadkar	al www.tobalton	ather pl	, dballomat
15°	and to	JLO.		allo.

Use the <Edit> key to open the directory of the file types. Mark and accept the type "subprogram"! (SPF = Sub Program File)

(Alternatively, it is also possible to select the desired type directly via the first letter <s>).

A template is not used.

This editor in which the subroutine is written is opened automatically.

The name of the workpiece directory is written in the headline, followed by the name of the program. The first program line is selected.

eof = marks the end of the program (end of file).

4.1 Programming: Turning - Workpiece "Shaf

Editor N100/II =eof=

Settinas

OK

ditor settings: ditor settings: Horizontal scrolling ON/OFF Show hidden lines Skip LF in program Interval between autom. backup to hard disk in min. 0 = No automatic backup Automatic block numbering: DAutomatic block numbering ON/OFF Number of the first block: 100 Increment: 100

If automatic block numbering is active on your control system ...

Programming is to be carried out without automatic line numbering.

The control runs also without block numbers and writing of a program is more convenient without numbers.

You can add block numbers later automatically via [Renumber].

Accept the changed setting screen.

Delete the line number first created automatically.

G18 G90 DIAMON

G18 defines the XZ plane as the machining plane (default for turning). G90 defines that all coordinates are entered absolutely, i.e. referred to the workpiece zero point.

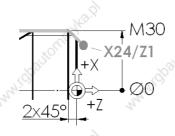
DIAMON means "Diameter ON", i.e. the X values are entered exclusively with reference to the diameter (independently of G90/G91).

Alternatives: DIAMOF Reference to radius ... independently of G90/G91

DIAM90

Reference to diameter... with G90 active (abs. dimens.) Reference to radius ... with G91 active (incr. dimens.)

The line is closed with <Input>. The cursor goes to the next line. (This key will not be explained in detail once again).



The commands for the face turning of the workpiece at Z0 will later be entered in the main program.

The subroutine starts with a G1 command to a starting point in the extension of the chamfer 2x45°.

Please note: The X value refers to the diameter!

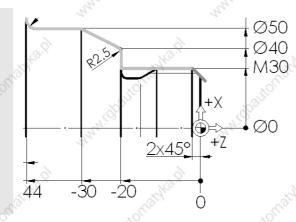
G1 X24 Z1

G1 X30 Z-2

G1 Z-20

G1 X40 RND=2.5

G1 X50 Z-30



Approaching the contour of X24/Z1 and the machining of the 45° chamfer can be done in one block.

The turning tool traverses in X and Z by 3 mm each to the programmed position X30/Z-2.

The G1 command from previous blocks is "modally effective". This means that all subsequent blocks would traverse as straight lines, also without writing G1. (G1 will only be canceled by a command for an arc G2/G3 or a rapid traverse movement). But G1 is here always written because of clarity.

Ø66 Ø60

Ø50

 $\emptyset 40$

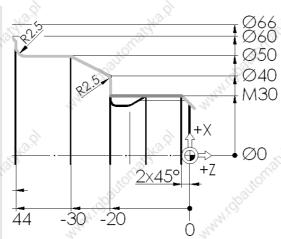
M30

ØC

+X

+7

<u>2x45°</u>



R2.5

-30

-20

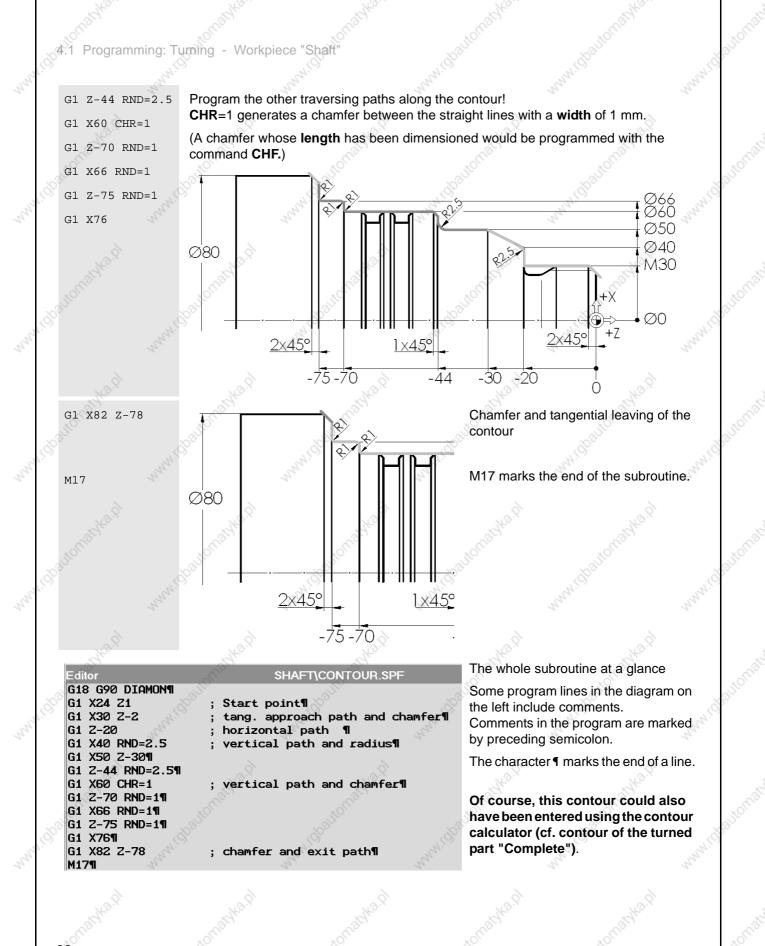
 $\Delta \Delta$

Horizontal skimming of the thread rated diameter.

The X value 30 will be maintained from the block programmed before, i.e. it is "modally effective".

The thread undercut will later be programmed as an independent cycle.

Vertical on X40. The transition to the oblique line at X50/Z-30 will be rounded with 2.5 mm (RND = Rounding).



Program 840_Tun Aule WF6 Program overview Program overview Program overview New BulloNE_K24 WPD 25/08/2003 New CHESSTOWER WPD 25/08/2003 New COOL COOL WPD 25/08/2003 New COOL WPD 25/08/2003 New EVANK5 WPD 25/08/2003 New SAVC WPD 25/08/2003 New SAVC WPD 25/08/2003 New WELLETS04 WPD 25/08/2003 New MUNON_ELE210 WPD 25/08/2003 New

Close

editor

New

ок

Close

editor

TCP

S

The subroutine is stored, and you will return to the program management.

Depending on the configuration of your control system, you can also store your program in the meantime via softkey, or you will be asked when closing it whether you want to store the program.

Use the same procedure to create a subroutine "TCP".

This subroutine will later carry out the approach to the tool change point and is called at each tool change.

G0 G18 G40 G500 G90 X400 Z600 T0 D0 G97 S300 M4 M9 M17

TCP

Copy these two program lines! At the end of the first line, press 😒 to accept them. At the same time, the cursor will go to the next line.

97

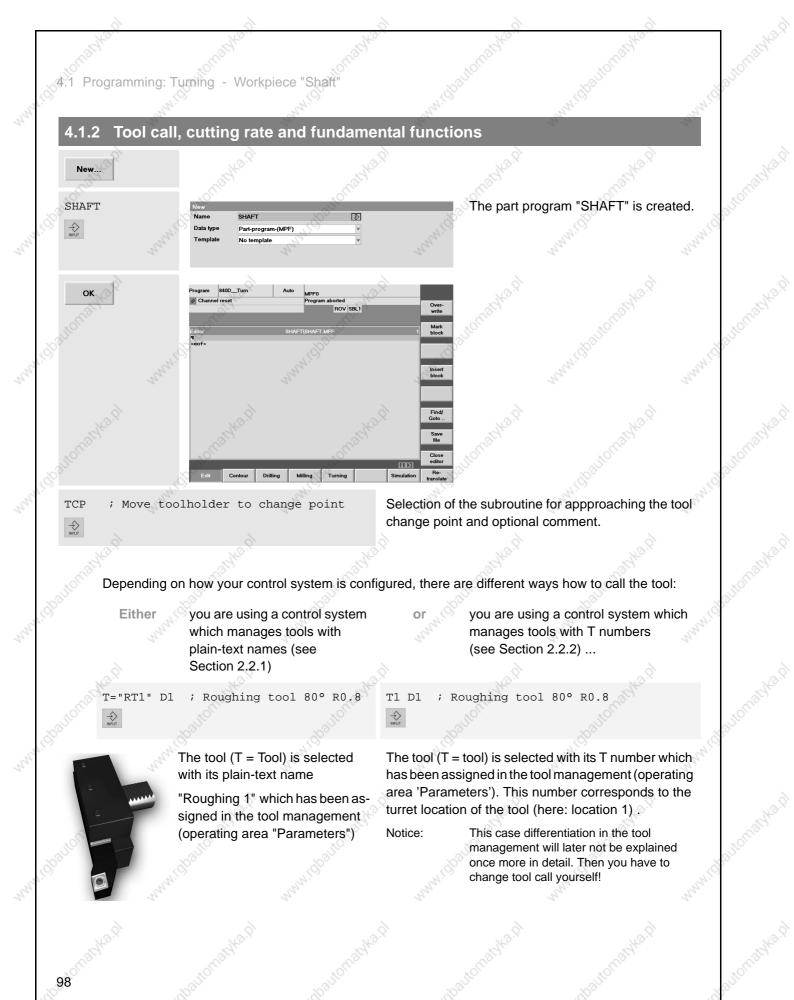
It is traversed...

- at rapid traverse (G0),
- in the XZ plane (G18),
- with the tool radius compensation deselected (G40)
- in the machine coordinate system (G500)
- to the absolute position (G90) X400/Z600.

This position refers to the toolholder (T0 D0). The tool compensations are disabled. Because the axes of some machines are only traversed when the spindle is rotating, the speed (G97 S300) and a direction of rotation (M4) have to programmed. The coolant is turned off (M9).

M17 marks the end of the subroutine.

Store the subroutine by closing the editor.



99

G96 S250 LIMS=3000 M4 M8

G96 enables the constant cutting rate, i.e. the cutting tool cuts - independent of the diameter on which it is located - by 250 m/min (see Section 1.2.3). Because the speed would be infinite, a limit speed is always programmed together with G96 (LIMS for limit speed), here 3,000 1/min.

M4 defines the direction of rotation CCW (viewing direction "back from the chuck") .

M8 turns on the coolant.

G18 G54 G90

->

These are some further fundamental functions which will be explained more in detail in the following overview. These functions often apply to a whole program ("modal efficiency"), and they can be written in the program header once. But it is better to implement these functions at each tool change.

This is especially true for the complete machining on turning machines where several technologies (turning, drilling, milling) occur on different machining planes in combination.

Description of functions	Decsription of functions of the same group
G18 - Selection of the XZ plane	G17 - Selection of the XY plane G19 - Selection of the YZ plane
G41 - Tool radius compensation left of the contour	G42 - Tool radius compensation right of the contour G40 - Selection of tool radius compensation
G54 - Activation of the first zero offset	G55, G56, G57 - Further zero offsets G53 - Cancelation of all zero offsets (non-modal) G500 - Disabling of all zero offsets
G90 - Programming of absolute dimensions	G91 - Programming of incremental dimensions
G95 - Revolutional feedrate in mm/rev. (default for turning; with G96 active, G95 is enabled automatically)	G94 - Linear feedrate in mm/min (default for milling) G97 - Constant speed
G96 - Constant cutting rate (for turning)	(for drilling and milling operations)
The functions of a group cancel each other. To	see which functions are currently active, press

the softkey G fet.+ in the "Machine" operating area.

4.1 Programming: Turning - Workpiece "Shaf

Face turning

FO. 32



These are the first lines of the program.

The toolholder is at the change point, the first tool has been loaded and important general basic settings have been defined.

The workpiece will now be faced with the roughing tool.

At first, the cutting tool is moved at rapid traverse (G0) from the tool change point to a position 2 mm above the workpiece.

0.2 mm allowance is taken into account at the face side for finishing.

The 2 key for accepting a program line is not given here in detail because of better legibility. Accept each line manually by pressing the 2 key!)

Facing is realized at feedrate.

When doing so, the tool traverses in the X direction according to the cutter radius across the turning center (negative X-value):

Cutter radius 0.8 times 2 for the diameter coordinate: X-1.6

G0 Z2 G0 X80

100

4.1.3

G0 X84 Z0.2

Retraction from the workpiece

0,2

Intermediate point near the starting point for subsequent roughing cycle.

Ø1.6

0,8

The starting point itself is calculated by the control system. Because it could be approached from the current position Z2 without collision, the block G0 X80 Z2 is only intended for better legibility of the program or for safety reasons in the case of program changes. It can also be dropped.

4.1.4 Cutting cycle CYCLE95

NPP

Operation

Selection

Selection

Selection

Infeed depth

Fin. allow.

Fin. allow.

Fin. allow.

Dwell time

Path length

Retract. path

Feed roughing

Feed plunging

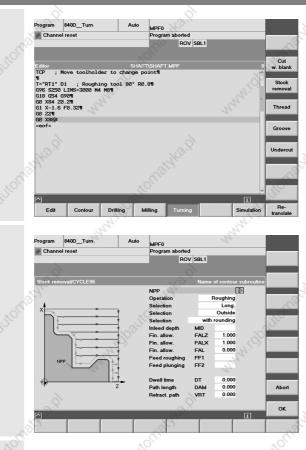
Turning

Stock

removal

CONTOUR

ок



CONTOUR

Roughing

with rounding

MID

FALZ

FALX

FAL

FF1 FF2

DT

DAM

VRT

Long. Outside

3.000

0.200

0.500

0.300

0.300

0.200

0.000

0.000

1.000

The main menus are on the horizontal softkey bar.

By pressing the softkey [Turning] you can see submenus for the various turning cycles on the vertical saftkey bar.

The dialog box for the cutting cycle CYCLE95 is opened by pressing the vertical softkey.

The cursor is positioned on the first input field. The meaning of some fields is explained graphically in the help screen, and in the yellow headline you will find an appropriate text.

The name of the contour subroutine must be entered in the first field.

Change or supplement the entries according to the values given in the screenform.

Select here the rough-machining "roughing".

Finishing will later be carried out separately simply by running the subroutine "CONTOUR".

CYCLE95("CONTOUR",3,0.2,0.5,0.3,0.3,0.2,,1,0,0,1)¶

The cycle is accepted into the program.

1.1 Programming: Turning - Workpiece "Sha

Press the <Recall> key to quit the menu with the turning cycles.

If you want to change a cycle block later, you can do this via the horizontal softkey [Recompile].

Call of the subroutine for approaching the tool change point.

An additional empty line at the end of machining with the cutting tool serves for structuring.

4.1.5 Finishing

T="FT1" D1 ; Finishing tool R0.4 G96 S320 LIMS=3000 M4 M8

G18 G54 G90

G0 X32 Z0

G1 X-0.8 F0.1

G0 Z2

TCP

G0 G42 X22 Z2

CONTOUR

G0 G40 G91 X2

Tool call Cutting rate for finishing 320 m/min Fundamental functions for machining

1² 1²

Face turning of end face to size

X-0.8 considers the cutting radius R0.4

Retracting from workpiece

Approaching near the starting position for the finishing traversing paths of the subroutine "CONTOUR". At the same time, G42 enables the tool radius compensation right of the contour.

Call of the subroutine that contains the finishing contour

At the end (here to exercise once incrementally with G91 and DIAMON) 1 mm are removed from the workpiece.

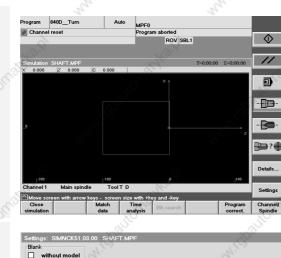
At the same time, the tool radius compensation is turned off (G40).

lf ..

M30

you want to simulate the progam...

The simulation expects the command M30 for marking the end of the program. The simulation would take place even without M30, but then an error message would be provided. It is therefore recommended to write M30 before the simulation is called for the first time.



Simulation

Settings

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D

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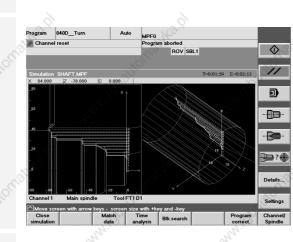
D

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80







Call the simulation screenform.

The workpiece dimensions normally do not yet correspond to the program to be simulated.

Press this softkey to open the dialog box for the simulation settings. Enter the blank dimensions (diameter and length):

- Outer diameter:80Z-min:-100Z-max*:1
- * Allowance for facing

Accept the settings.

Press the softkey [NC Start] to start the simulation.

You can change between single and subsequent block simulation with [Single Block].

Various views are offered to choose from.

Finally, quit the simulation window with the <Recall> key.

Please note that the following program lines must be inserted **before** the command M30.

4.1 Programming: Turning - Workpiece "Shaft

Open 2nd file

Save

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4.1.6 Error correction - parallel editing of main program and subroutine

ROV SBL1

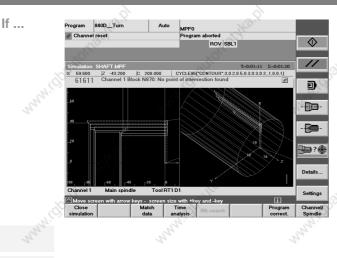
691 X21

ROV SBL1

.,1,0,0,1)

GØ G42 X22 Z21 CONTOUR1 GØ G40 G91 X21

GØ GØ



840D_Turr

8400

If you have detected an error in the simulation which is to be found, e.g. in the subroutine "CONTOUR" ...

Quit the simulation with <Recall> key.

Use the extended softkey bar to load the subroutine "CONTOUR" as the second file into the editor where you can change it.

In this case, the minus sign of the Z value was obviously forgotten.

Overwrite

bloc

Sav file

Close edito Re-

> Overwrite

Mark block

Insert block

Find/

Clo

The missing minus sign was inserted.

Please note that any changes in this second file are not accepted automatically.

First, the file has to be stored per softkey.

Program	840DTurn	Auto	MPF0				
// Chann	el reset		Progra	am aborted			
				ROV SE	L1		Over- write
0.1							
ST.C							Mark
Editor	SHAFTICONTOUR	R.SPF	6 Editor		T\SHAFT.MP	F 26	block
G18 G90 G1 X24 2				84 20.2¶ -1.6 F0.32¶		<u>^</u>	
G1 X30 2			G2 Z				
G1 Z-20			Ge X				
G1 X40				E95("CONTOUR	. 3020	5030	
G1 X50 2	Z-30¶	02		21.0.0.1)			Insert
G1 Z-44	RND=2.59	200	TCP1			ND	block
G1 X60 0			1			.01	DIOCK
G1 Z-70				T1"D1 ; F	inishing t	ool R0.4	_
G1 X66 I			1			Sec.	
G1 Z-75 G1 X76¶				5320 LIMS=30 654 690¶	900 M4 M89	22.	
G1 X82 2				32 201			
M17¶	L-70			-0.8 F0.19			Find/
=eof=			60 Z				Goto
			GØ G	42 X22 Z2¶			
× 1			CONT				Save
0				40 G91 X2¶			file
0.3			9	- AX			
10			1301	×1'0'			Close
17-				11-			editor
1.1			0	Con R		<u> </u>	
Edit	Contour		Milling	Turning		Simulation	Re-
- LE GIN						Linuari	translate

You should also make sure that the main program ("SHAFT.MPF") receives the focus again before the simulation is called once again.

In this respect it is not important for starting the simulation in which line of the program the cursor is.

(REAT) Close editor

Simulation

If, finally, the subroutine is correct, position the focus on the subroutine window and close it with the softkey.

If there still is an error in the simulation, you should generally use the <Recall> key to quit the simulation window and not [Program correct.] since the latter function only allows

.1.7 Thread undercut acc. to DIN76



the editing of the main program.

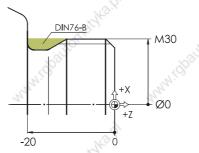
After you have carried out the "digression" as described in Section 4.1.6, you should now have the only main program in the editor.

The traversing path in the last block was programmed incrementally (G91). Use G90 to switch over to absolute programming!

G0 Z-10

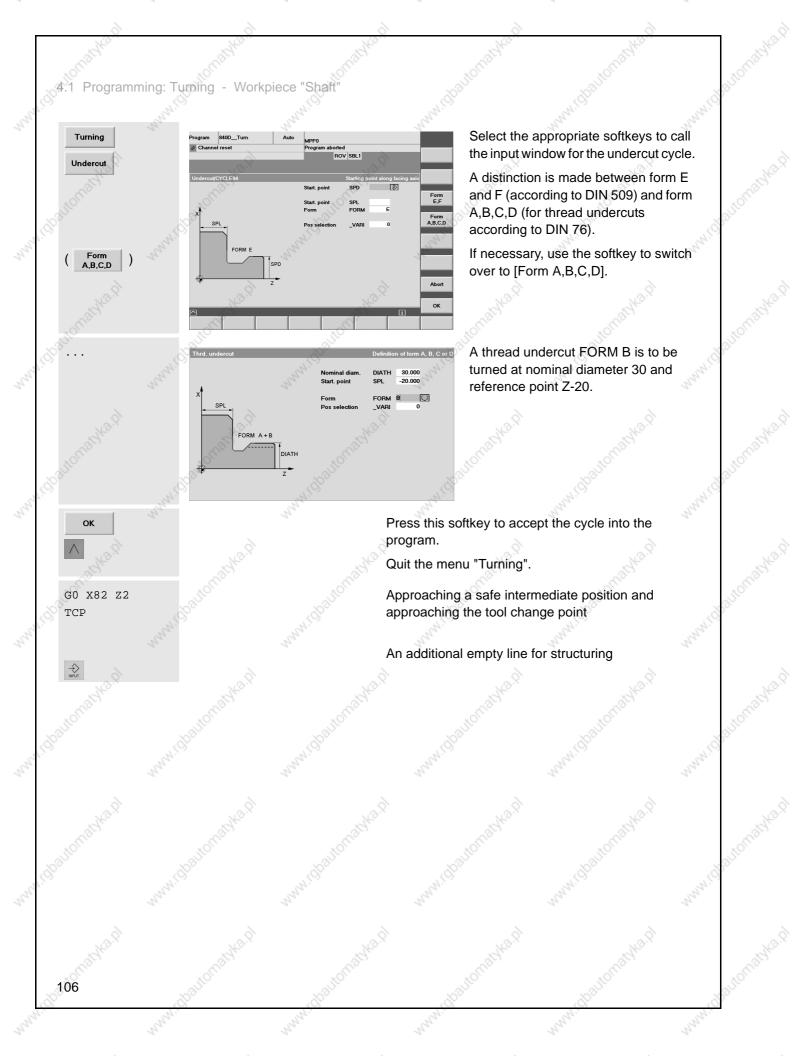
G90

F0.07

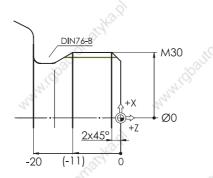


A position is approached at rapid traverse from which the starting position of the undercut can be reached wihout crash.

Feedrate 0.07 mm/revolution



4.1.8 Thread cutting cycle CYCLE97



T="Thread" D1 ; Thread cutting tool G96 S200 LIMS=3000 M3 M8

G18 G54 G90 G0 X40 Z7 After the undercut, the thread M30 is turned.

According to the standard, the undercut is 9 mm in width. The dimension is given in brackets in the diagram just for orientation.

Tool call

Technological data: In order to produce a right-hand thread, the cutting tool has to be installed "the other way around" in the turret. Thus, the spindle has to rotate clockwise (M3).

Fundamental functions

At rapid traverse from the tool change point near the starting point for threading cycle.

According to the standard, an M30 thread has a pitch of 3.5 mm. General rule for the thread run-in path: approx. 2 - 3 x pitch (2 x pitch was selected here)

Turning	1	34	Ser.	
	Program 840D_Turn	Auto MPF0		
Thread	// Channel reset	Program aborted		
Thread	- <u>-</u> 2	ROV	/ SBL1	S.c. 1
Thread	alter a			
cutting	Thread cutting/CYCLE97		Select thread table	Alter- native
3 ⁰	Throad County Croccor	Table	Metric 🔘	nauve
5°		as thread size	MPIT	80
	. (S)	as value	PIT	S.
State .	×	Start. point	SPL	
24	SPL I	End point	FPL	
	FPL	Diameter 1	DM1	
N		Diameter 2	DM2	
S.		Runin path	APP 3.000	2.0
Ato .	TDEP	Runout path	ROP 3.000	
10 M	ROP APP		TDEP FAL 1.000	201
70x 10x		Fin. allow. Infeed angle	FAL 1.000 IANG 0.000	10x
No. and Anna	DM2 DM1	Start pt.offs	NSP 0.000	
	<u>↓</u>	Cuts	NRC 1.000	Abort
1 Marsh		Noncuts	NID 1.000	
1 ²⁴		Selection	Outside	
1	2-	S.		ок
. 0	<u>.</u>	6	- C	
HB?	20°		<u>_</u>	1. O.
20	19 J.	3	200	20
1. St. 1.	r all all all all all all all all all al			
5	-3 ¹⁰		\$°	
2 ⁻				
	20	10°	1	2

1.1 Programming: Turning - Workpiece "Shaft

Table

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Simulation

108

Calif.			8	and the		
Close simulation	Match data	Time analysis	Blk.search	6	Program correct.	Channel/ Spindle
Channel 1 Main spindle		HREAD D1	ev and -key	P		Settings
						Details
)_10						₽ ₽?€
						- 🕞 -
	V					- 800-
	\forall		ć			-80-
× 32.000 Z -17.000	C 0.000	CYCLE97	(3.5,30,0,-11,30	0,30,7,6,2,273,0.1,0		•
Simulation SHAFT.MPF				T=0:02:56		11
// Channel reset		Progra	m aborted ROV S	BL1		\Diamond
Program 840D_Turn	Au	MPF0				
-3 ⁵⁵			3 Stor			
			. S			
TCP1				Stor		
CYCLE97(3.5,30 GØ X40¶	,0,-11,:	30,30,7	,6,2.27	73,0.1,0,1	2,8,1,:	1,1)¶
G18 G54 G90¶ G0 X40 Z7¶						
T="THREAD" ; G96 S200 LIMS=:	Thread. 3000 M3	ing too M8¶	1¶			
TCP¶ ¶						
CYCLE96(30,-20 G0 X82 Z2¶	, "B")¶					
GØ Z-10¶ FØ.07¶						
Stor.				ab/2.01		
	3					1
		NAN'S				paran?
Retract		VB	E.	0.00	-	, è
No.of threa	ads		JMT	1.00	-	
Selection			Cons	t. infee	-	
NO.2				20.9		
Selection				Juisid	e	
Noncuts Selection		NI	,	1.00 Outsid		
Cuts		NF		8.00	-	
Start pt.off	S	NS	2	0.00	-	
Infeed ang		IAI		0.00	-	
Fin. allow.		FA	L	0.10	0	
Thread de	pth	TD	EP	2.27	3	
Runout pa		RC		6.00	0	
Runin path	Gr.	AP		7.00	. 3	
Diameter 2		DN		30.00	-	
End point Diameter 1		FP DN		-11.00 30.00	-	
Start. point	t	SP	- x0°	0.00 ×	-	
as value		PIT	Г	3.50	-	
as thread :	size	MF	ЧT	30.00	0	

Metric

 \bigcirc

Enter the values for the threading cycle.

According to the standard, some values result from the nominal dimension.

The inputs for the thread pitch PIT and the thread depth TDEP are thus implemented automatically.

End point and run-in path are added resulting in a traversing path in Z to -17. Using the simulation, you can check whether this dimension is correct. But consider also the actual geometry of the cutting tool.

The last two last entries in the input window "scrolled" down.

Use these softkeys to accept the cycle into the program and to quit the program.

Approaching a safe intermediate position and movement to the tool change point.

Empty line for structuring

The screenshot shows the program overview for the last two working steps (thread undercut and thread).

Call of the simulation to check the cycle

Use the arrow keys <+>/<-> to zoom the area in which the thread is machined.

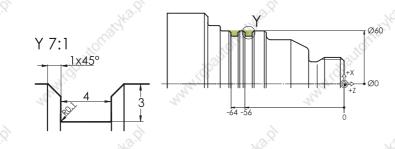
Start of the simulation

The machining of the thread is represented using a different color. The selection of the colors can be configured via [Settings] > [Display & colors ...].

4.1.9 Grooving cycle CYCLE93

Turning

Groove



T="GT_3" D1 ; Grooving tool 3mm, left cutt. edge G96 S200 LIMS=3000 M4 M8 G18 G54 G90 G0 X64 Z-40 F0.05

> Long. Selection \bigcirc Selection Outside Start point right 60.000 Start. point SPD -56.000 Start. point SPL 4.000 Width WIDG Groove depth DIAG 3.000 0.000 STA1 Angle 0.000 ANG1 Flank angle 1 ANG2 0.000 Flank angle 2 CO1 -1.000Transit. Transit. CO2 -1.000 0.100 Transit. RI1 0.100 Transit. RI2 Fin. allow. FAL1 0.000 Fin. allow. 0.000 FAL2 Infeed depth IDEP 3.000 Dwell time DTB 0.000 CHR Selection 0.000 Retract VRT

Then produce two undercuts.

To do so, use the procedure already known:

- Tool call
- Technological data
- Fundamental functions
- Rapid traverse positioning near the first plunge-cut
- Feedrate
- Cycle call

Enter the values for the first plunge-cut.

In this respect, the following is to be observed:

In the fields "Radius / chamfer", a negative sign indicates that "chamfer" has been chosen.

A chamfer can be defined either via its width or its length. The selection "CHR" defines that the entries are interpreted as "chamfer width": (according to the dimensioning in the drawing 1x45°).

The interrelation between the two fields "selection" and "starting point" is shown in the following help screen:

× L	long., outside, left	X long., in	side, left X	face, outside, top X	face, inside, top
	long., outside, right	X Iong., in	side, right	face, outside, bottom	face, inside, bottom ∎ START

4.1 Programming: Turning - Workpiece "Shaft

Start. point

Start. point

Groove depth

Width

SHAFT\SH

; Move toolholder to change point¶

CYCLE95("CONTOUR",3,0.2,0.5,0.3,0.3,0.2,,1,0,0,1)¶

T="RT1" D1 ; Roughing tool 80° R0.8¶ G96 S250 LIMS=3000 M4 M8¶

T="FT1" D1 ; Finishing tool R0.4¶ G96 S320 LIMS=3000 M4 M8¶ IAFT.

OK

Groove

OK

G0 X82

TCP

TCP

G18 G54 G90¶

G18 G54 G90¶ G0 X32 Z0¶

G1 X-0.8 F0.1¶ G0 Z2¶

gø G42 X22 Z2¶ Contour¶

GØ G4Ø G91 X2¶ G9ض GØ Z-1ض

CYCLE96(30,-20,"B")¶ GØ X82 Z2¶

F0.079

TCP¶

GØ Z2 ¶ GØ X80¶

TCP¶

GØ X84 ZØ.2¶ G1 X-1.6 FØ.32¶

-64

Press this softkey to accept the cycle into the program.

All entries from the plunge-cut last created are kept.

In this case, you have only to change the value for the "starting point SPL" for the second plunge-cut.

Use this softkey to accept the cycle into the program Use tis softkey to quit the "Turning" menu.

Retraction from the workpiece

60.000

4.000

3.000

 \odot

-64

SPD

SPL

WIDG

DIAG

Traversing to the tool change point

The whole part program once again at a glance!

Any changes in the "normal" program lines can be carried out directly in the text editor. If you want to overwrite parts of the program, activate the softkey [Overwrite].

For changes in a cycle you should move the cursor into the appropriate line and then you should open the input window of the cycle with the softkey [Recompile].

If you want to change the sequence of machining, e.g. plunge-cutting first, then proceed as follows:

Position the cursor on the first character of the relevant program block (i.e. on the 'T' in the line T="GT_3" D1).

Then press the softkey [Mark block].

Use the arrow keys to move the cursor down and then to the right on the last character of the block (i.e. on the 'P' in the line "TCP").

Then press the softkey [Copy block].

Position the cursor on the place in the program you want to edit and then press [Insert block].

Finally, select the block in the original place in the program once again and delete it there using the softkey [Delete block].

Store the program with [Close editor] and return to program management.

The steps required to execute the program on the machine are described in Section 2.3.2.

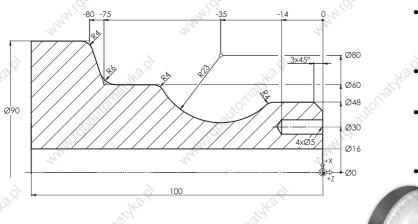
T="THREAD" ; Threading tool¶ G96 S200 LIMS=3000 M3 M8¶ G18 G54 G90¶ G0 X40 Z7¶ CYCLE97(3.5,30,0,-11,30,30,7,6,2.273,0.1,0,0,8,1,1,1)¶ G0 X40¶ TCP¶ ¶ T="GT_3" D1 ; Grooving tool 3mm, left cutt. edge¶ G96 S200 LIMS=3000 M4 M8¶ G18 G54 G90¶

G0 X64 Z-40¶ F0.05¶ CYCLE93(60,-56,4,3,0,0,0,-1,-1,0.1,0.1,0,0,3,0,11)¶ CYCLE93(60,-64,4,3,0,0,0,-1,-1,0.1,0,1,0,0,3,0,11)¶ G0 X82¶ TCP¶

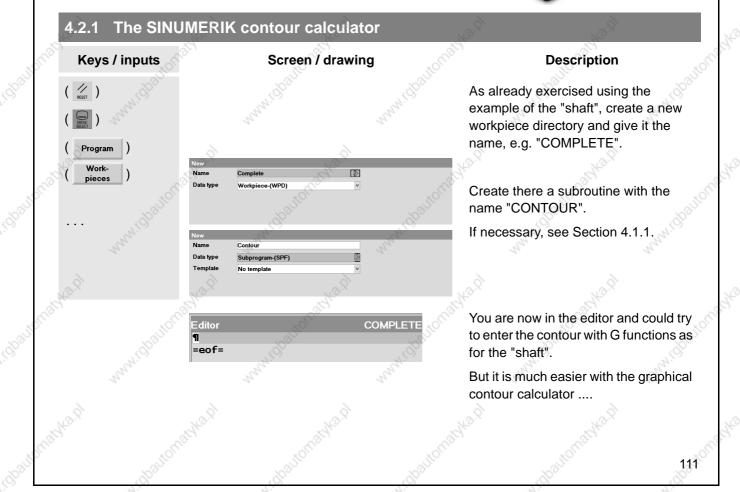
M301

4.2 Workpiece "Complete"

Using the workpiece "Complete" (blank ø90, length 101) as an example, you will learn - apart from a repetition of the "classical" turning machining which has already been discussed using the example of the "shaft" - further elementary and useful aspects of the control system:



- SINUMERIK contour calculator for the simple input even of complex contours with graphics assistance
- Concentric drilling on the turning machine
- Eccentric machining of the end face with the function TRANSMIT (with driven tools)
- Hole circle cycle HOLES2

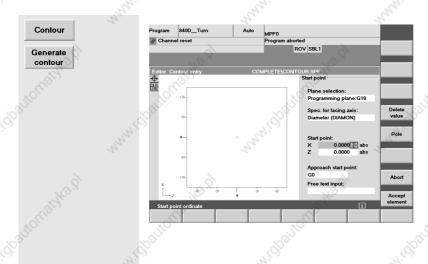


4.2 Programming: Turning - Workpiece "Complete"

40

Accept

112



40D Tu

The user interface of the contour calculator consists of three parts:

- The contour definition is represented by small **icons** on the left of the column. At the beginning, only the symbols for the starting point and the contour end exist.
- In the middle the contour definition will be built up dynamically as a graphics during the input. So you always have a visual control of your inputs.
- These are made via **input fields** as you already know them from the cycles.

The contour definition starts 1 mm in X and 1 mm in Z before the first contour point.

Note: It may happen that with the software version of your control system Z must be programmed before X (and with arcs correspondingly K before I) for reasons of compatibility!

All dimensions in the X direction refer to the 'diameter (DIAMON)'.

gram 8400_Tun Aulo MPF0 Channel reset Program aboited ROV [SBL] Start point Plane selection: Programming plane.G19 Spec. for facing axis: Diameter (DUMON) Start point: X 40 0000 abs 1,000 abs Continue Aboit Free text input: Navigate with arrow key. Select with input. (1)

ROV SBL1

Accept the starting point.

Instead of thinking in cryptic G commands, you can also create the contour definition using simple pictographs (see vertical softkey bar).

It starts with an oblique line ...

abs abs

))))

48

-3

Accept

element

Accept

element

Ø90

... to the (absolutely dimensioned) end point

Х 48.000 abs Ζ -3.000 abs

The angle to the positive X axis

 $\alpha 1 = 135.000$ °

... is calculated and displayed automatically. In addition to the graphics, you can use this display also as an input control.

Accept the first contour element.

All para-

Abort

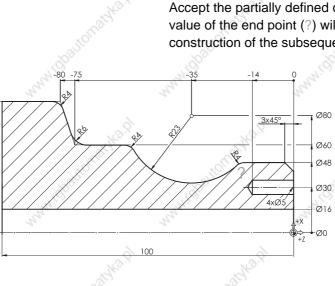
A horizontal line follows. This is indicated by a dotted line.

> The end point Z is not known. The input field remains empty.

The 'transition to the following element', the arc R23, is rounded with R4 .

If necessary use the <toggle key> or the softkey [Alternative] to switch from 'FS' (chamfer) to 'RD' (radius) and enter the value.

Accept the partially defined contour element. The Z value of the end point (?) will later result from the construction of the subsequent arc R23.

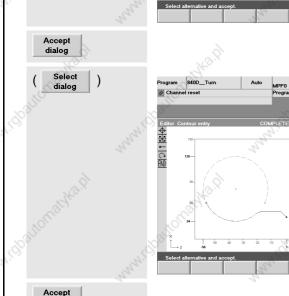




ogramming: Turning - Workpiece 'Complete' Call the input window for arcs: Alter In addition to the direction of rotation Circular arc native and the radius, the diameter value of \Rightarrow 23 the end point is also known: R 23.0000 α 60 \Rightarrow Х 60.000 abs х 60.0000 abs z abs V ... and the absolute coordinates of the ∋abs L 80 center point 80 Κ -35.0000 abs 80.000 abs T -35 -35.000 Κ abs * The meaning of I and K as the center point coordinates in X and Z is illustrated in the help screen which you can call up with the ① key if the cursor is positoned on I or K. Pressing ① lets you return to the online graphics. Selec After the input of R, X, K and I, the arc dialog is determined such that it can also be ROV SBL1 represented in the graphics as a dotted line. 0

Now you can choose between two mathematically possible end point coordinates in Z (-14.288 or -55.712).

Select the alternative where the point at Z-55.712 is marked in black.



dialog

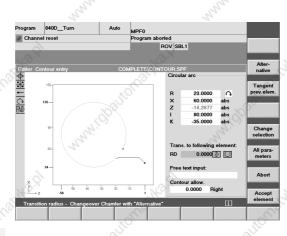
114

Accept the dialog.

abs abs abs Furthermore, it is to be decided whether the transition between the horizontal line and the arc will be at Z-20 or only at Z-50 (see diagram).

Select the alternative at which the black line corresponds to the drawing.

Accept the dialog.



you have made a mistake in the dialog selection ...

... you can call it again using this softkey and change it.

Switch the presentation of the input parameters to [All parameters].

This presentation displays all coordinates of the arc both absolutely and incrementally (the entered values are black, the calculated grey).

In addition to the coordinates, the angles of the arc are also calculated and displayed:

α1 Starting angle referred to the positive Z axis

ROV SBL1

 $\alpha 2$ Starting angle referred to the previous element (here the horizontal line)

inc abs inc abs inc abs inc abs

00 🔊 🖸

- β 1 End angle referred to the positive Z axis
- $\beta 2$ Aperture angle of the arc

840D_______

The starting angle of the arc is important for the subsequent production which (without taking into account the rounding) decreases towards the X axis by less than 46°.

The exact angle taking into account R4 could also be determined if R4 would not be entered as a rounding, but as an "independent" contour element with tangential connections (softkey [Tangent prev.elem.]) to the horizontal line and the arc R 23. This leads to a starting angle R23 of about 42°.

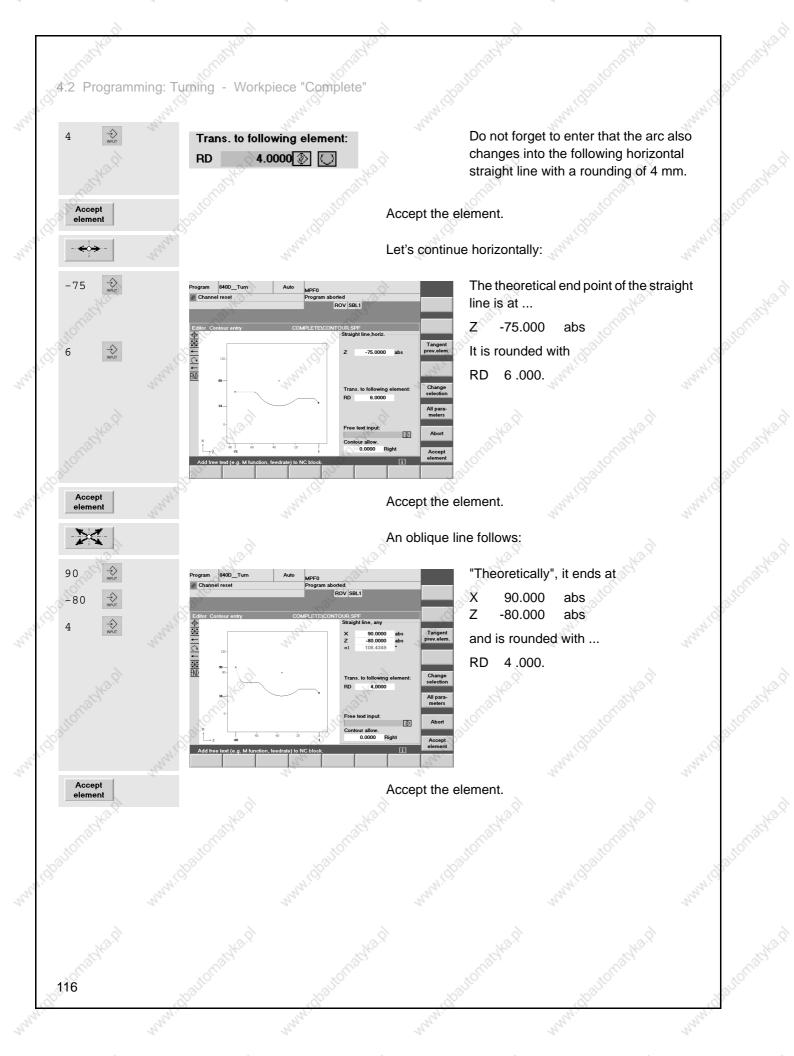
When selecting the tool in the main program, take into account that the **clearance angle of the tool to the Z axis** is greater than this starting angle of the arc (in this regard, see also Section 2.2 "Setting up", page 39).

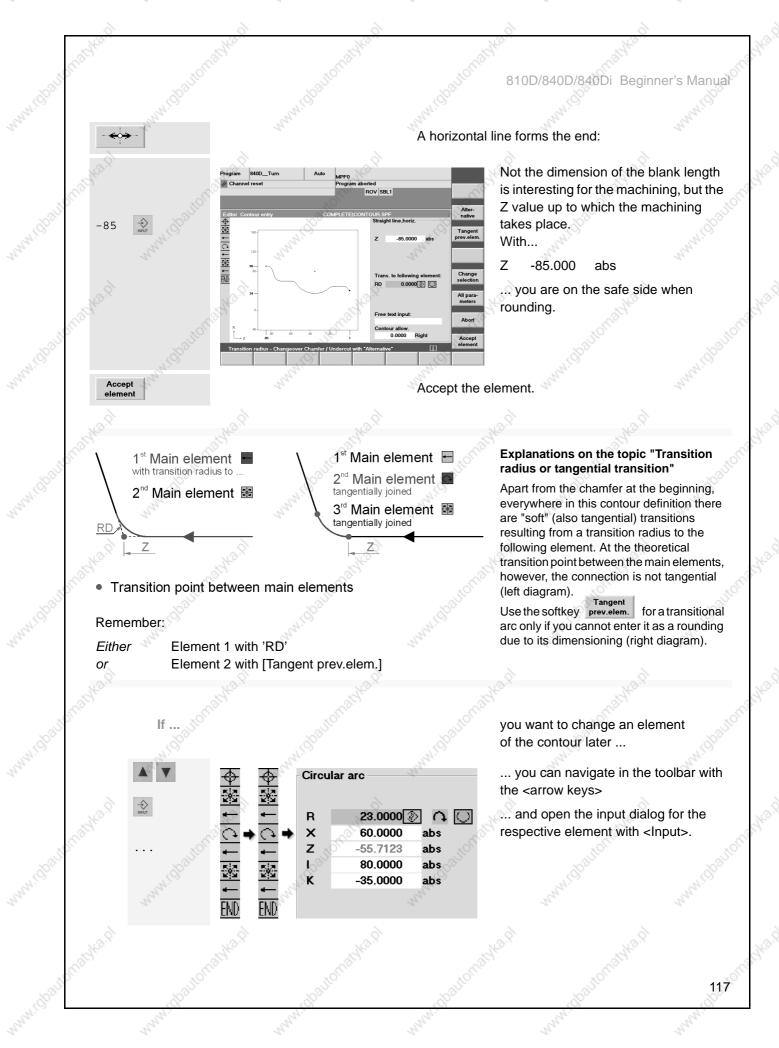


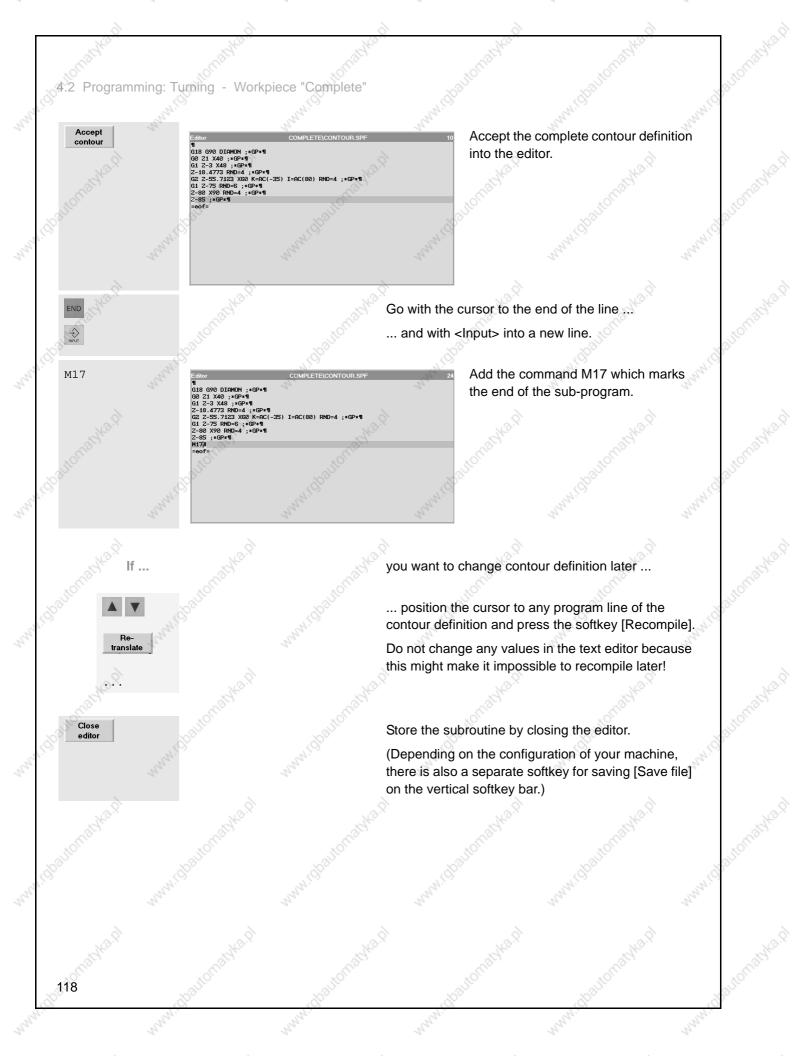
Change

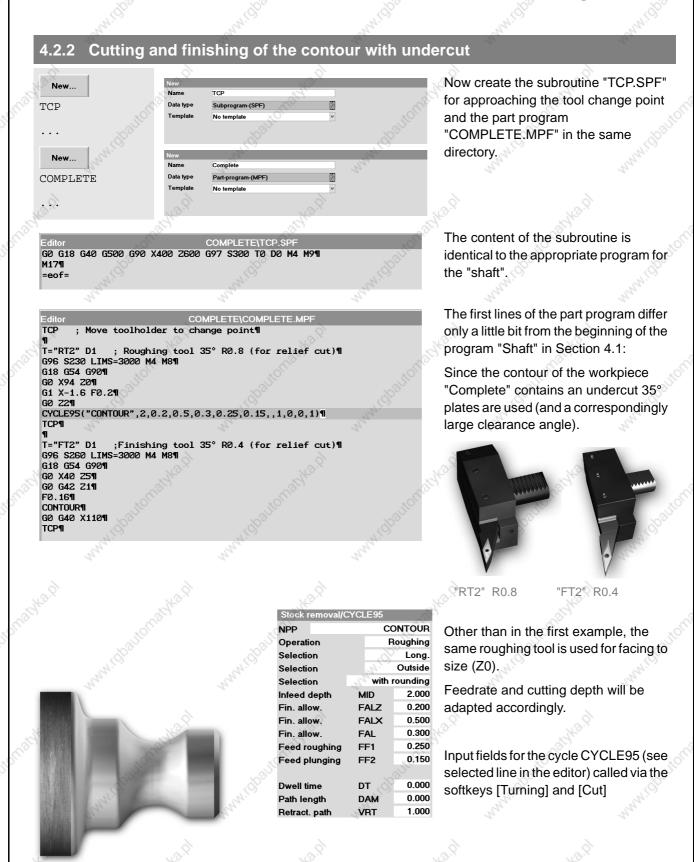
All para

meters









4.2 Programming: Turning - Workpiece "Complete"

4.2.3 Drilling centrally

; Drill centrally

T="SD16" D1 ; Solid drill D16mm

G97 S1200 M3 M8

After turning, the through-hole is to be produced using a 16 drill.

Drilling is carried out at constant speed (G97). Unlike turning, the spindle rotates clockwise (M3).

G17 G54 G90 G95 Plane selection G17* for machining on the end face, activation of zero offset G54, absolute programming G90, feedrate in mm/rev G95

* For drilling centrally, the machining can generally also be programmed in the G18 plane. But when doing so, please note that the length compensation changes: G17: length1 in Z (as for milling) G18: Length3 in Z !!!

G0 X0 Z2

G1 Z-105 F0.1

GO Z2 TCP

Simulation

120

The workpiece is approached at rapid traverse rate. Later, when executing the program, make sure that there is no collision with the tailstock!

Drilling is carried out at feedrate through the workpiece having a length of 100 mm (with an allowance of 5 mm).

 \triangle

- 🕞

The drill is retracted from the workpiece at rapid traverse.

OV SBL1

Finally, the subroutine "TCP" (tool change point) is called again.

Calling the simulation to check the programming and automatic adaptation of the 'Settings' (blank ø90, length 101)

> By using <arrow keys> and <+>/<->, you can "zoom" the area in which you are especially interested.

Simulation of turning and drilling

121

4.2.4 End face machining with TRANSMIT

More and more turning machines provide the possibility of milling or drilling end or peripheral faces by using driven tools.

Your SINUMERIK control system naturally also supports such technologies. The programming for a drill pattern at the end face is presented here as an example.

; Hole circle on end face

Comment line for better legibility of the program.

	G54 G64 G90 G94	Fundamental G functions		2. C.	
õ	G18	Plane selection	COLUMN STOLE	nable	
	SPOS=0	Spindle positioning (C axis) on ()°	~3 ¹⁰	
	T="TD5" D1 ; Tw	wist drill D5mm	Tool call	and a second sec	
	SETMS(2)	Spindle 2 (the spindle driving the so-called "master spindle").	e tool) becomes t	he	
5	S2=1000 M2=3	Speed and direction of rotation of are entered with an equals sign the main spindle of the machine	(see S1000 M3 f		
	TRANSMIT	This function (Trans form M illing milling and drilling at the end fac	2.4	ies out transformation of the axes for	
20	kard	U UUUUUUUU	for milling. The c	ed out in the Cartesian coordinate ontrol system will then convert these s remains unchanged.	
	doane	(The appropriate function for pe	ripheral face mac	hining is called TRACYL).	
	DIAMOF	Manager -		rom now on, the the X values refer to ne radius.	
20.	G17)) n)) a	he XY plane will be selected as the nachining plane. Please note that the xes X and Y are turned by 90°, ompared with milling.	
	G0 X15 Z2	730	st th	pproaching near the starting point for ne first hole. As necessary observe the osition of the tailstock.	
	F140		F	eedrate in mm/min (see G94)	
8	Drilling Deep hole drilling	an www.chaitoman	is	he deep-hole drilling cycle CYCLE83 used here once again as an xcercise.	
20		at the phanet	tonatile		

ogramming: Turning -Workpiece "Complete' Complete the input fields. rtf RFF 2.000 0.000 SDIS 1.000 The cycle is to be called at four Moda 15.700 call -5.000 positions, i.e. it is to be modally EDE 1.000 RT DTE 0.000 effective (cf. workpiece "Longitudinal 1.000 RFF guide when milling"). ding 3.000 FDE To take into account the drill tip, approx. VBT 0.500 0.500 DTE 1/3 x tool ø is added to the final drilling depth. Accept the cycle into the program. OK The positions of the drill pattern can Hole pattern pos also be created via a cycle ... 0.000 Hole CPO 0.000 RAD STA1 circle 15.000 0.000 INDA 90.000 Complete the input fields. 4.000 🛞 8 0 CP RAD (The help screen is static; in reality, the axes are turned by 90°.) CPA Accept the drill pattern into the program. OK Instead of the cycle one could also have programmed the 4 drill positions via simple G0 blocks (cf. milling example "Longitudinal guide"). Now the compensation of both methods as they appear in the editor: ; Cycle 'Hole Circle'¶ Circle4:¶ HOLES2(0,0,15,0,90,4)¶ ENDLABEL : 1 itions programed "by hand"¶ X15 Y0¶ XØ Y15¶ ØЗI X-15 Y0¶ GØ XØ Y-15¶ MCALL The "MCALL" command will cancel the modal efficiency of the drill cycle. 122

Simulation in the 2-side view which you

In the screen shown on the left, it has been switched to the presentation of the

, you can switch the

123

can call via the softkey 🖳?

focus between the two simulation windows, zooming the images

tool paths with Tool path

By using

separately.

The transformation function TRANSMIT is disabled again. The following X values refer to the diameter again. The main spindle becomes the "Master spindle" again.

Approaching the tool change position End of program

TRAFOOF DIAMON

SETMS(1)

Simulation

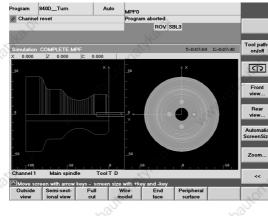
<<

Close

editor

TCP

M30



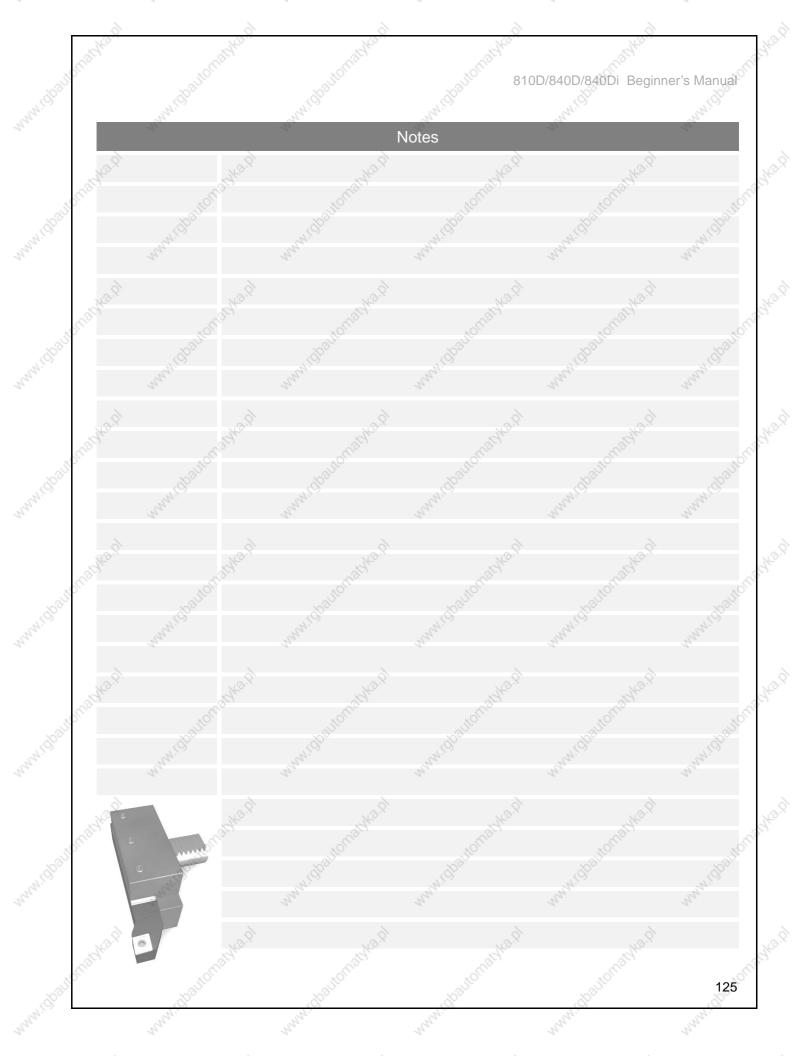
Quit the simulation graphics

Close the editor to save the program.

On the following page you can find again an overview of the whole part program.

4.2 Programming: Turning - Workpiece "Complete"

Editor COMPLETE\COMPLETE.MPF TCP 😗 Move toolholder to change point¶ ¶ ; Roughing tool 35° R0.8 (for relief cut)¶ T="RT2" D1 G96 S230 LIMS=3000 M4 M8¶ G18 G54 G90¶ G0 X94 Z0¶ G1 X-1.6 F0.2¶ GØ Z2¶ CYCLE95("CONTOUR",2,0.2,0.5,0.3,0.25,0.15,,1,0,0,1)¶ TCP¶ **T** T="FT2" D1 ;Finishing tool 35° R0.4 (for relief cut)¶ G96 S260 LIMS=3000 M4 M8¶ G18 G54 G90¶ GØ X40 Z5¶ GØ G42 Z1¶ FØ.16¶ CONTOUR¶ GØ G40 X110¶ TCP¶ 9 ; Drill centrally¶ T="SD16" D1 ; Solid drill D16mm¶ G97 S1200 M3 M8¶ G17 G54 G90 G95¶ G0 X0 Z2¶ G1 Z-105 F0.1¶ GØ Z2¶ TCP¶ 1 ; Hole circle on end face¶ G54 G60 G90 G94¶ G18¶ SPOS=0¶ ; Twist drill D5mm¶ T="TD5" D1 SETMS(2)¶ S2=1000 M2=3¶ TRANSMIT¶ DIAMOF¶ G17¶ GØ X15 Z2¶ F140¶ MCALL CYCLE83(2,0,1,-15.7,,-5,,2,0,,1,0,3,3,0.5,0,)¶ Circle4:¶ HOLES2(0,0,15,0,90,4)¶ ENDLABEL : 1 TRAFOOF¶ DIAMON¶ SETMS(1)¶ TCP¶ M30¶



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DIN keyboard		Р
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Commands and a	ddresses discus	ssed in this Man	ual Cycles	s discussed	
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CFTCP 75	K 13	, 114	Milling	cycles	ANICO AND
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Reference of photos and illustrations

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We would like to express our special thanks to

DMG

Europa-Verlag

Iscar

Reckermann

Sandvik

Seco

for making available the photographs on the pages 14, 15, 16, 17, 38 and 39.

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