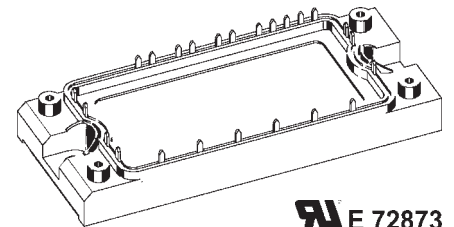
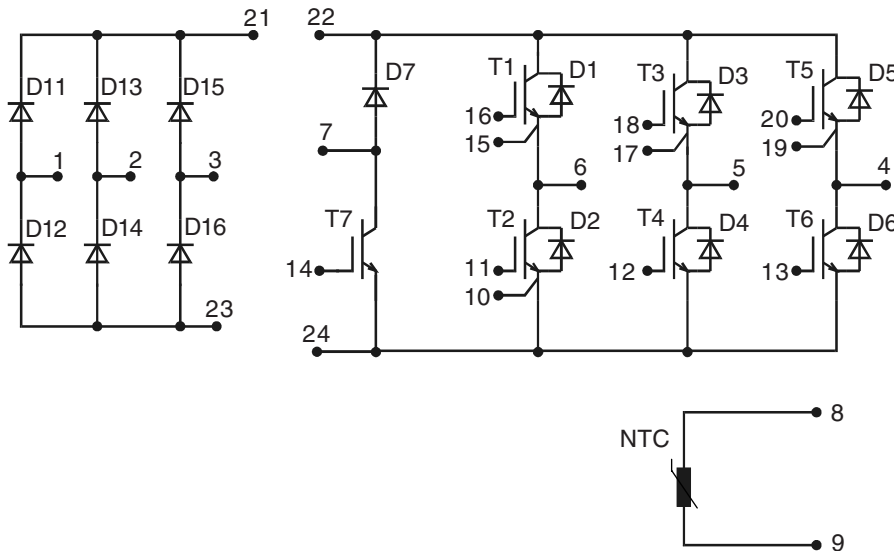


Converter - Brake - Inverter Module (CBI2)



E 72873

| Three Phase Rectifier | Brake Chopper | Three Phase Inverter |
|-----------------------|-----------------------|-----------------------|
| $V_{RRM} = 1600V$ | $V_{CES} = 1200 V$ | $V_{CES} = 1200 V$ |
| $I_{DAVM} = 44 A$ | $I_{C25} = 35 A$ | $I_{C25} = 50 A$ |
| $I_{FSM} = 400 A$ | $V_{CE(sat)} = 2.3 V$ | $V_{CE(sat)} = 2.6 V$ |

Input Rectifier Bridge D11 - D16

| Symbol | Conditions | Maximum Ratings | |
|------------|---|-----------------|---|
| V_{RRM} | | 1600 | V |
| I_{FAV} | $T_C = 80^\circ C$; sine 180° | 30 | A |
| I_{DAVM} | $T_C = 80^\circ C$; rectangular; $d = 1/3$ | 29 | A |
| I_{FSM} | $T_{VJ} = 25^\circ C$; $t = 10$ ms; sine 50 Hz | 400 | A |
| P_{tot} | $T_C = 25^\circ C$ | 120 | W |

| Symbol | Conditions | Characteristic Values ($T_{VJ} = 25^\circ C$, unless otherwise specified) | | |
|------------|---|--|------------|-----------------|
| | | min. | typ. | max. |
| V_F | $I_F = 35 A$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$ | | 1.4 1.4 | 1.7 V V |
| I_R | $V_R = V_{RRM}$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$ | | 2.0 | 0.2 mA mA |
| t_{rr} | $V_R = 100 V$; $I_F = 20 A$; $di/dt = -20 A/\mu s$ | | 1 | μs |
| R_{thJC} | (per diode) | | | 1.06 K/W |

Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- electric braking operation

Features

- High level of integration - only one power semiconductor module required for the whole drive
- Fast rectifier diodes for enhanced EMC behaviour
- NPT IGBT technology with low saturation voltage, low switching losses, high RBSOA and short circuit ruggedness
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

Output Inverter T1 - T6

| Symbol | Conditions | Maximum Ratings | |
|---------------------|--|---|---------------|
| V_{CES} | $T_{VJ} = 25^{\circ}\text{C}$ to 150°C | 1200 | V |
| V_{GES} | Continuous | ± 20 | V |
| V_{GEM} | Transient | ± 30 | V |
| I_{C25} | $T_C = 25^{\circ}\text{C}$ | 50 | A |
| I_{C80} | $T_C = 80^{\circ}\text{C}$ | 35 | A |
| RBSOA | $V_{GE} = \pm 15\text{ V}$; $R_G = 47\ \Omega$; $T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100\ \mu\text{H}$ | $I_{CM} = 70$ $V_{CEK} \leq V_{CES}$ | A |
| t_{SC} (SCSOA) | $V_{CE} = V_{CES}$; $V_{GE} = \pm 15\text{ V}$; $R_G = 47\ \Omega$; $T_{VJ} = 125^{\circ}\text{C}$ non-repetitive | 10 | μs |
| P_{tot} | $T_C = 25^{\circ}\text{C}$ | 225 | W |

| Symbol | Conditions | Characteristic Values ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified) | | |
|--|--|--|------|----------|
| | | min. | typ. | max. |
| $V_{CE(sat)}$ | $I_C = 35\text{ A}$; $V_{GE} = 15\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | 2.6 2.9 | 3.1 | V V |
| $V_{GE(th)}$ | $I_C = 1\text{ mA}$; $V_{GE} = V_{CE}$ | 4.5 | 6.5 | V |
| I_{CES} | $V_{CE} = V_{CES}$; $V_{GE} = 0\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | 1 | 1.1 | mA mA |
| I_{GES} | $V_{CE} = 0\text{ V}$; $V_{GE} = \pm 20\text{ V}$ | | 200 | nA |
| $t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off} | Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 600\text{ V}$; $I_C = 35\text{ A}$ $V_{GE} = \pm 15\text{ V}$; $R_G = 47\ \Omega$ | 100 | | ns |
| | | 70 | | ns |
| | | 500 | | ns |
| | | 70 | | ns |
| | | 5.3 | | mJ |
| | | 3.9 | | mJ |
| C_{ies} | $V_{CE} = 25\text{ V}$; $V_{GE} = 0\text{ V}$; $f = 1\text{ MHz}$ | 1650 | | pF |
| Q_{Gon} | $V_{CE} = 600\text{ V}$; $V_{GE} = 15\text{ V}$; $I_C = 35\text{ A}$ | 120 | | nC |
| R_{thJC} | (per IGBT) | | 0.55 | K/W |

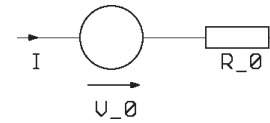
Output Inverter D1 - D6

| Symbol | Conditions | Maximum Ratings | |
|-----------|----------------------------|-----------------|---|
| I_{F25} | $T_C = 25^{\circ}\text{C}$ | 50 | A |
| I_{F80} | $T_C = 80^{\circ}\text{C}$ | 33 | A |

| Symbol | Conditions | Characteristic Values | | |
|----------------------|--|-----------------------|------|---------------|
| | | min. | typ. | max. |
| V_F | $I_F = 35\text{ A}$; $V_{GE} = 0\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 1.8 | 2.8 V V |
| I_{RM} t_{rr} | $I_F = 30\text{ A}$; $di_F/dt = -500\text{ A}/\mu\text{s}$; $T_{VJ} = 125^{\circ}\text{C}$ $V_R = 600\text{ V}$; $V_{GE} = 0\text{ V}$ | | 27 | A |
| | | | 150 | ns |
| R_{thJC} | (per diode) | | 1.19 | K/W |

Equivalent Circuits for Simulation

Conduction



D11 - D16

Rectifier Diode (typ. at $T_J = 125^{\circ}\text{C}$)
 $V_o = 0.96\text{ V}$; $R_o = 13\text{ m}\Omega$

T1 - T6 / D1 - D6

IGBT (typ. at $V_{GE} = 15\text{ V}$; $T_J = 125^{\circ}\text{C}$)
 $V_o = 1.13\text{ V}$; $R_o = 50\text{ m}\Omega$

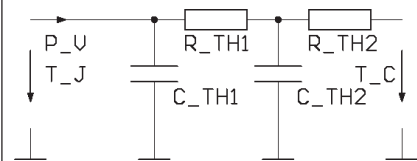
Free Wheeling Diode (typ. at $T_J = 125^{\circ}\text{C}$)
 $V_o = 1.26\text{ V}$; $R_o = 15\text{ m}\Omega$

T7 / D7

IGBT (typ. at $V_{GE} = 15\text{ V}$; $T_J = 125^{\circ}\text{C}$)
 $V_o = 1.37\text{ V}$; $R_o = 62\text{ m}\Omega$

Free Wheeling Diode (typ. at $T_J = 125^{\circ}\text{C}$)
 $V_o = 1.39\text{ V}$; $R_o = 56\text{ m}\Omega$

Thermal Response



D11 - D16

Rectifier Diode (typ.)
 $C_{th1} = 0.131\text{ J/K}$; $R_{th1} = 0.851\text{ K/W}$
 $C_{th2} = 0.839\text{ J/K}$; $R_{th2} = 0.209\text{ K/W}$

T1 - T6 / D1 - D6

IGBT (typ.)
 $C_{th1} = 0.201\text{ J/K}$; $R_{th1} = 0.419\text{ K/W}$
 $C_{th2} = 1.25\text{ J/K}$; $R_{th2} = 0.131\text{ K/W}$

Free Wheeling Diode (typ.)
 $C_{th1} = 0.116\text{ J/K}$; $R_{th1} = 0.973\text{ K/W}$
 $C_{th2} = 0.879\text{ J/K}$; $R_{th2} = 0.217\text{ K/W}$

T7 / D7

IGBT (typ.)
 $C_{th1} = 0.156\text{ J/K}$; $R_{th1} = 0.545\text{ K/W}$
 $C_{th2} = 1.162\text{ J/K}$; $R_{th2} = 0.155\text{ K/W}$

Free Wheeling Diode (typ.)
 $C_{th1} = 0.043\text{ J/K}$; $R_{th1} = 2.738\text{ K/W}$
 $C_{th2} = 0.54\text{ J/K}$; $R_{th2} = 0.462\text{ K/W}$

Brake Chopper T7

| Symbol | Conditions | Maximum Ratings | |
|----------------------------|--|---|---------------|
| V_{CES} | $T_{VJ} = 25^{\circ}\text{C}$ to 150°C | 1200 | V |
| V_{GES} | Continuous | ± 20 | V |
| V_{GEM} | Transient | ± 30 | V |
| I_{C25} | $T_C = 25^{\circ}\text{C}$ | 35 | A |
| I_{C80} | $T_C = 80^{\circ}\text{C}$ | 25 | A |
| RBSOA | $V_{GE} = \pm 15\text{ V}$; $R_G = 82\ \Omega$; $T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100\ \mu\text{H}$ | $I_{CM} = 35$ $V_{CEK} \leq V_{CES}$ | A |
| t_{SC} (SCSOA) | $V_{CE} = V_{CES}$; $V_{GE} = \pm 15\text{ V}$; $R_G = 82\ \Omega$; $T_{VJ} = 125^{\circ}\text{C}$ non-repetitive | 10 | μs |
| P_{tot} | $T_C = 25^{\circ}\text{C}$ | 180 | W |

| Symbol | Conditions | Characteristic Values | | |
|---------------|--|--|------|--------------|
| | | $(T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified) | | |
| | | min. | typ. | max. |
| $V_{CE(sat)}$ | $I_C = 20\text{ A}$; $V_{GE} = 15\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 2.3 | 3 V |
| | | | 2.6 | V |
| $V_{GE(th)}$ | $I_C = 0.6\text{ mA}$; $V_{GE} = V_{CE}$ | 4.5 | | 6.5 V |
| I_{CES} | $V_{CE} = V_{CES}$; $V_{GE} = 0\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 0.8 | 0.8 mA mA |
| I_{GES} | $V_{CE} = 0\text{ V}$; $V_{GE} = \pm 20\text{ V}$ | | | 200 nA |
| $t_{d(on)}$ | Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 600\text{ V}$; $I_C = 20\text{ A}$ $V_{GE} = \pm 15\text{ V}$; $R_G = 82\ \Omega$ | | 100 | ns |
| t_r | | | 75 | ns |
| $t_{d(off)}$ | | | 500 | ns |
| t_f | | | 70 | ns |
| E_{on} | | | 3.1 | mJ |
| E_{off} | | | 2.4 | mJ |
| C_{ies} | $V_{CE} = 25\text{ V}$; $V_{GE} = 0\text{ V}$; $f = 1\text{ MHz}$ | | 1000 | pF |
| Q_{Gon} | $V_{CE} = 600\text{ V}$; $V_{GE} = 15\text{ V}$; $I_C = 20\text{ A}$ | | 70 | nC |
| R_{thJC} | | | | 0.7 K/W |

Brake Chopper D7

| Symbol | Conditions | Maximum Ratings | |
|-----------|--|-----------------|---|
| V_{RRM} | $T_{VJ} = 25^{\circ}\text{C}$ to 150°C | 1200 | V |
| I_{F25} | $T_C = 25^{\circ}\text{C}$ | 16 | A |
| I_{F80} | $T_C = 80^{\circ}\text{C}$ | 11 | A |

| Symbol | Conditions | Characteristic Values | | |
|------------|--|-----------------------|------|---------------|
| | | min. | typ. | max. |
| V_F | $I_F = 20\text{ A}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | | 3.6 V |
| | | | 2.6 | V |
| I_R | $V_R = V_{RRM}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 0.07 | 0.06 mA mA |
| I_{RM} | $I_F = 20\text{ A}$; $di_F/dt = -400\text{ A}/\mu\text{s}$; $T_{VJ} = 125^{\circ}\text{C}$ $V_R = 600\text{ V}$ | | 13 | A |
| t_{tr} | | | 110 | ns |
| R_{thJC} | | | | 3.2 K/W |

Temperature Sensor NTC

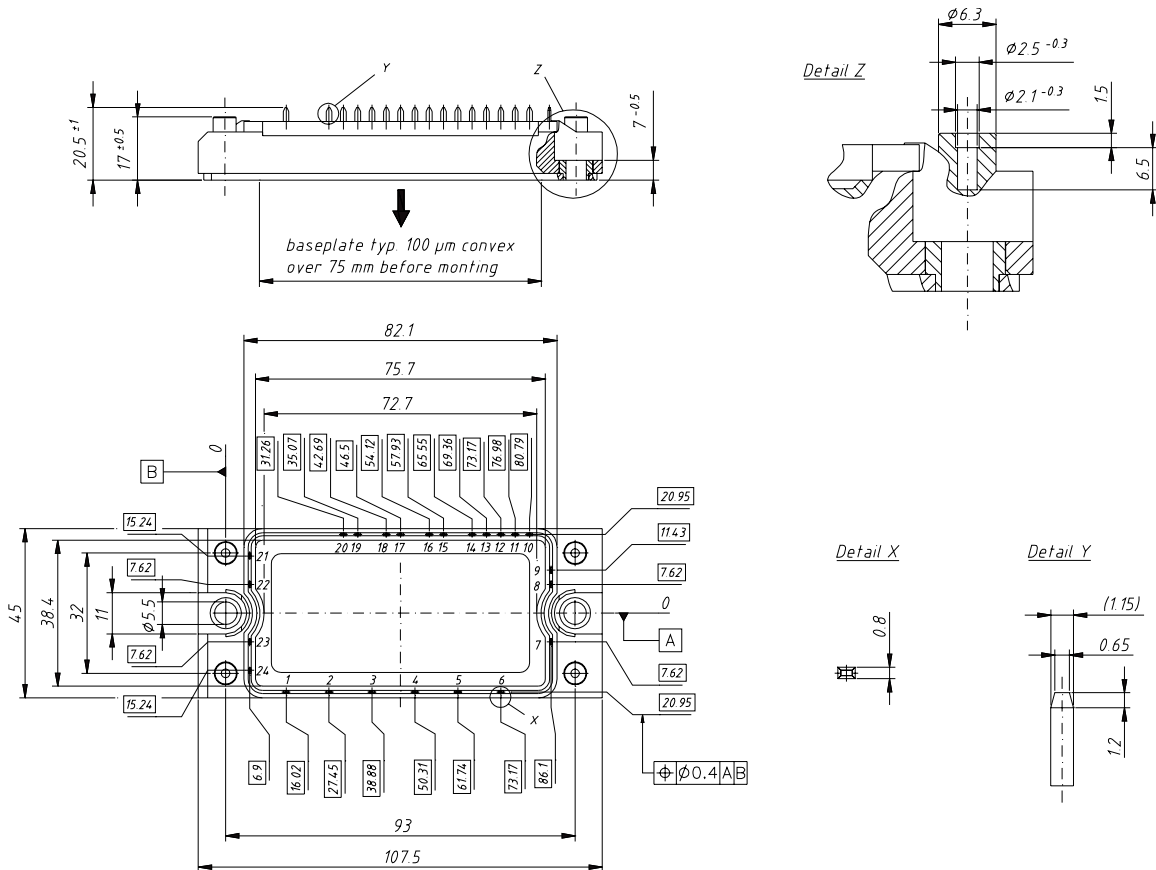
| Symbol | Conditions | Characteristic Values | | |
|-------------|--------------------------|-----------------------|------|------|
| | | min. | typ. | max. |
| R_{25} | $T = 25^{\circ}\text{C}$ | 4.75 | 5.0 | 5.25 |
| $B_{25/50}$ | | | 3375 | |

Module

| Symbol | Conditions | Maximum Ratings | |
|------------|--|-----------------|--------------------|
| | | | |
| T_{VJ} | Operating | -40...+125 | $^{\circ}\text{C}$ |
| T_{JM} | | 150 | $^{\circ}\text{C}$ |
| T_{stg} | | -40...+125 | $^{\circ}\text{C}$ |
| V_{ISOL} | $I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$ | 2500 | V~ |
| M_d | Mounting torque (M5) | 2.7 - 3.3 | Nm |

| Symbol | Conditions | Characteristic Values | | |
|----------------|------------------------------|-----------------------|------|------------|
| | | min. | typ. | max. |
| $R_{pin-chip}$ | | | 5 | m Ω |
| d_S | Creepage distance on surface | 6 | | mm |
| d_A | Strike distance in air | 6 | | mm |
| R_{thCH} | with heatsink compound | 0.02 | | K/W |
| Weight | | 180 | | g |

Dimensions in mm (1 mm = 0.0394")



Input Rectifier Bridge D11 - D16

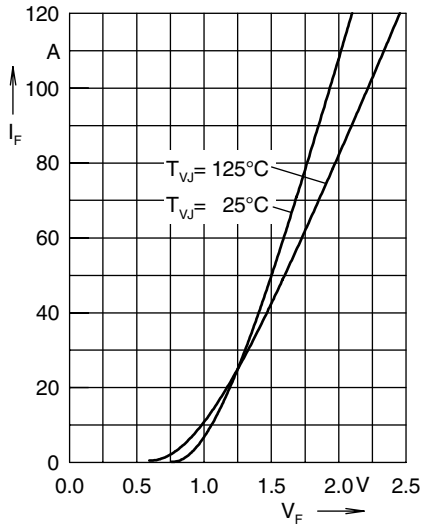


Fig. 1 Forward current versus voltage drop per diode

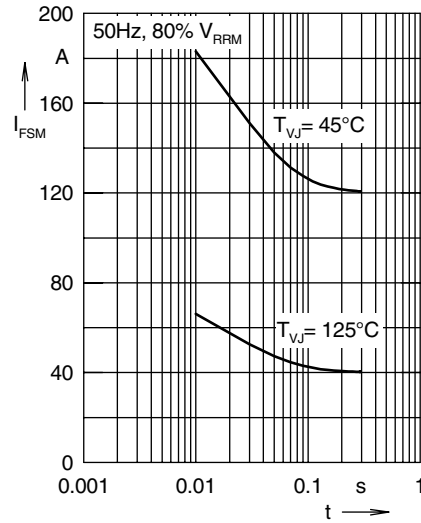


Fig. 2 Surge overload current

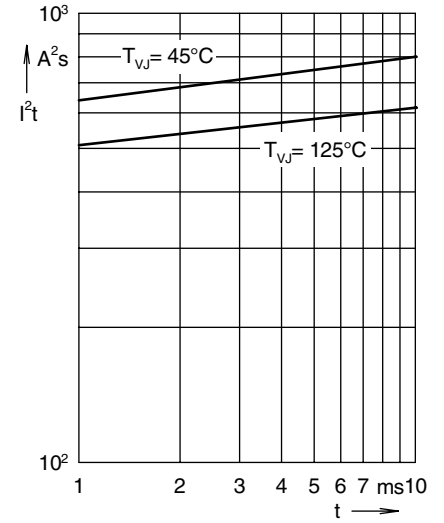


Fig. 3 I^2t versus time per diode

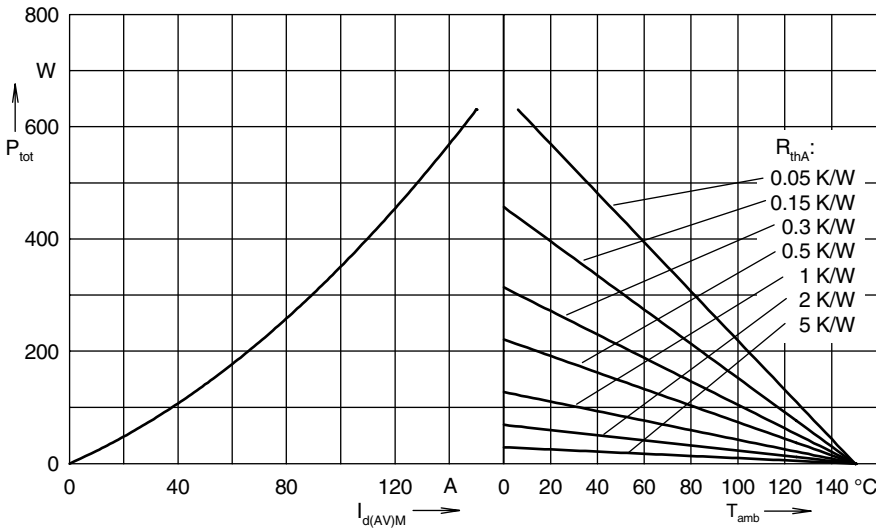


Fig. 4 Power dissipation versus direct output current and ambient temperature, sin 180°

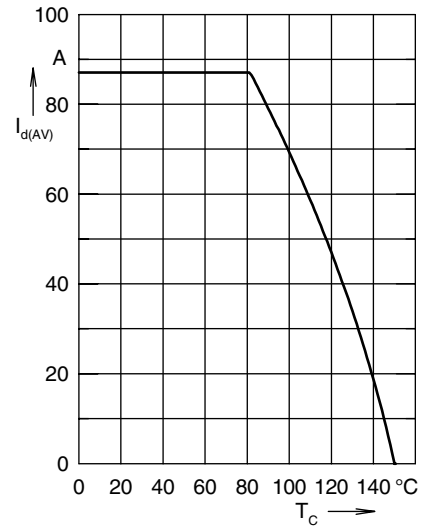


Fig. 5 Max. forward current versus case temperature

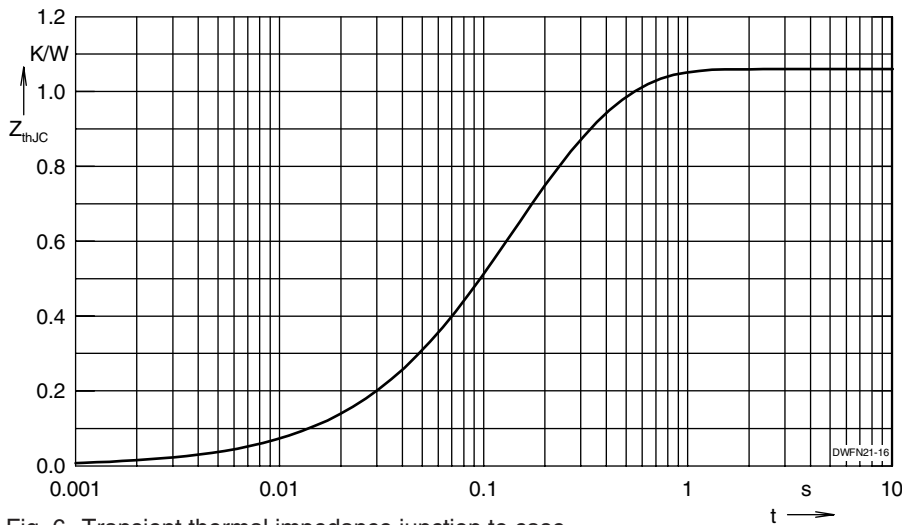


Fig. 6 Transient thermal impedance junction to case

Output Inverter T1 - T6 / D1 - D6

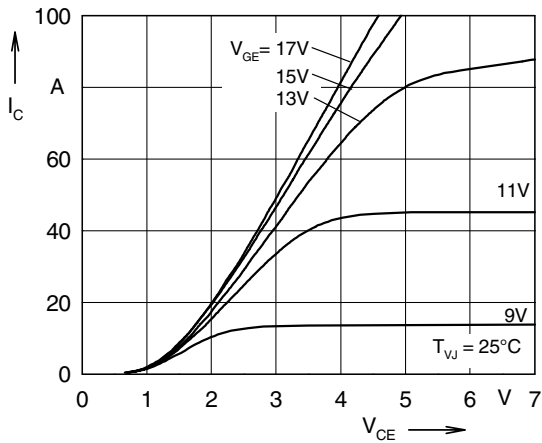


Fig. 7 Typ. output characteristics

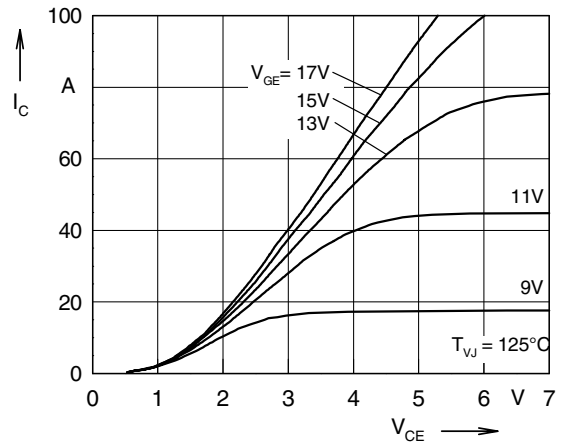


Fig. 8 Typ. output characteristics

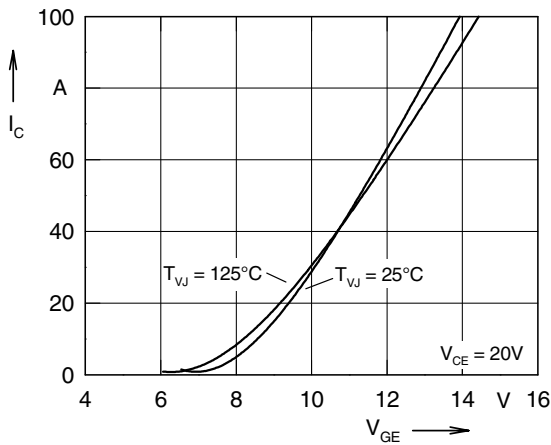


Fig. 9 Typ. transfer characteristics

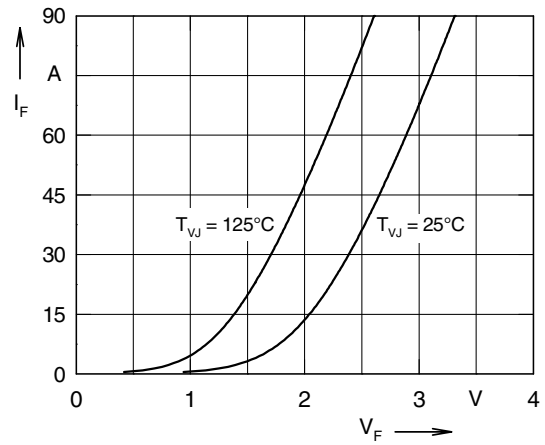


Fig. 10 Typ. forward characteristics of free wheeling diode

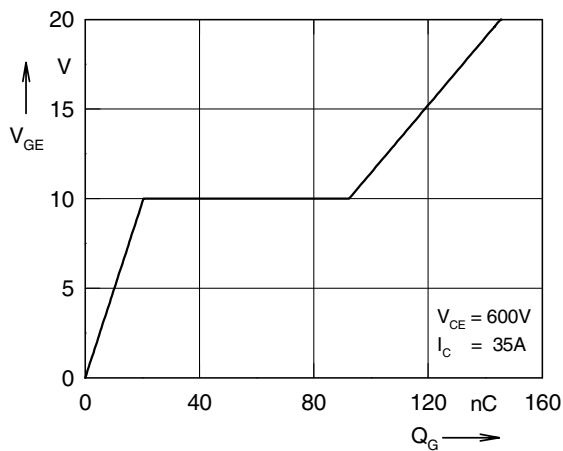


Fig. 11 Typ. turn on gate charge

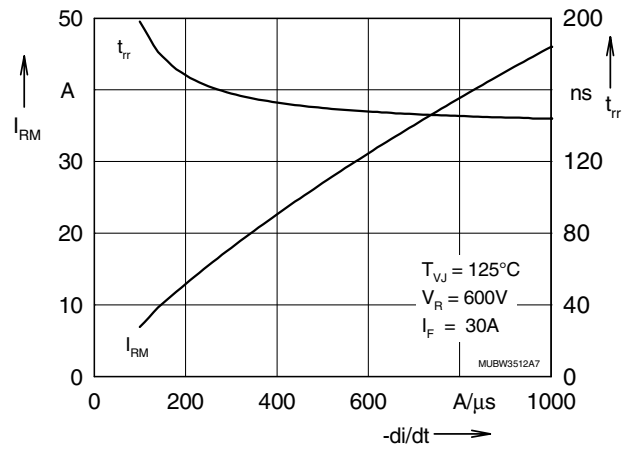


Fig. 12 Typ. turn off characteristics of free wheeling diode

Output Inverter T1 - T6 / D1 - D6

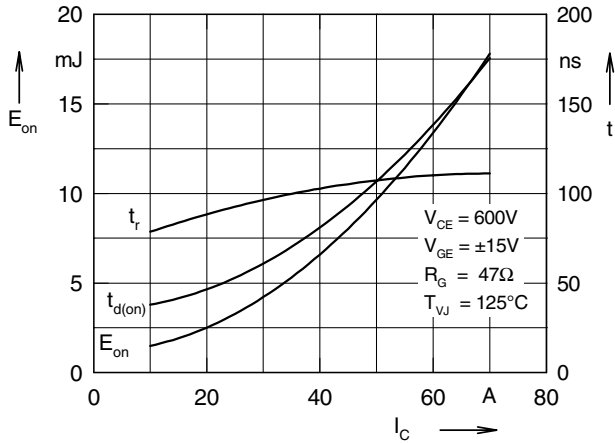


Fig. 13 Typ. turn on energy and switching times versus collector current

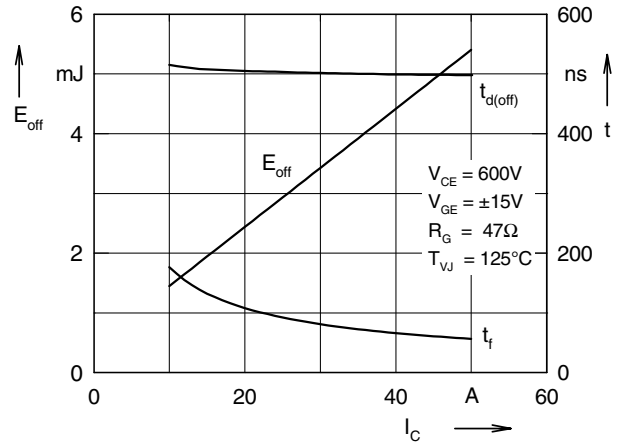


Fig. 14 Typ. turn off energy and switching times versus collector current

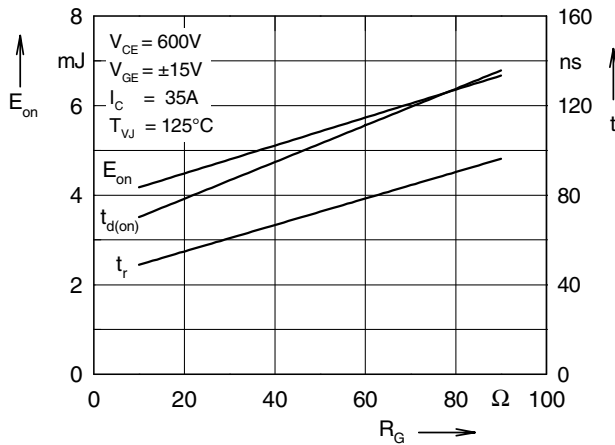


Fig. 15 Typ. turn on energy and switching times versus gate resistor

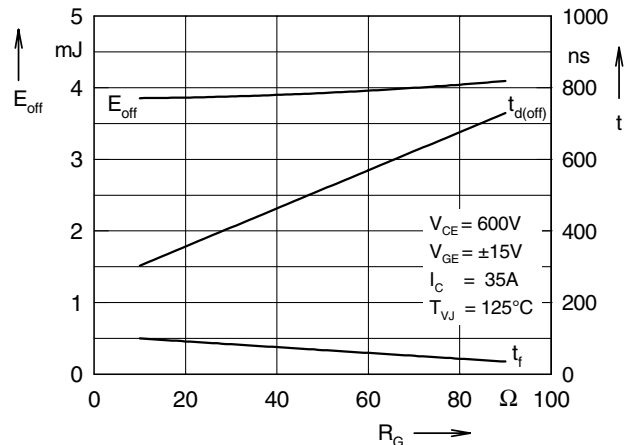


Fig. 16 Typ. turn off energy and switching times versus gate resistor

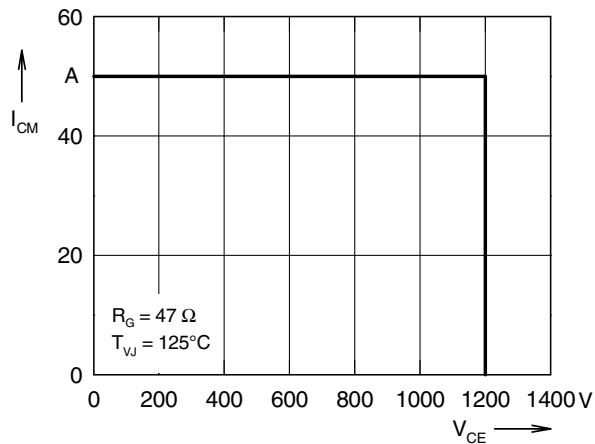


Fig. 17 Reverse biased safe operating area RBSOA

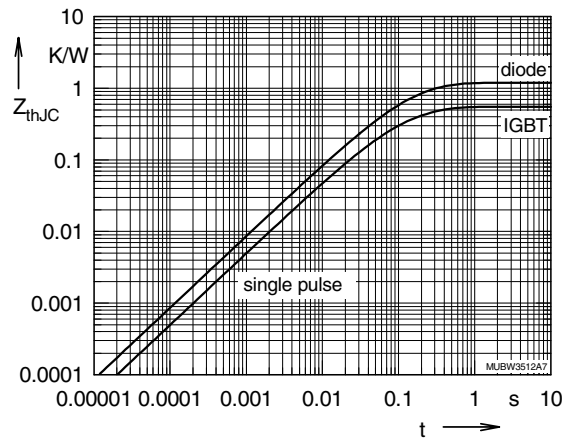


Fig. 18 Typ. transient thermal impedance

Brake Chopper T7 / D7

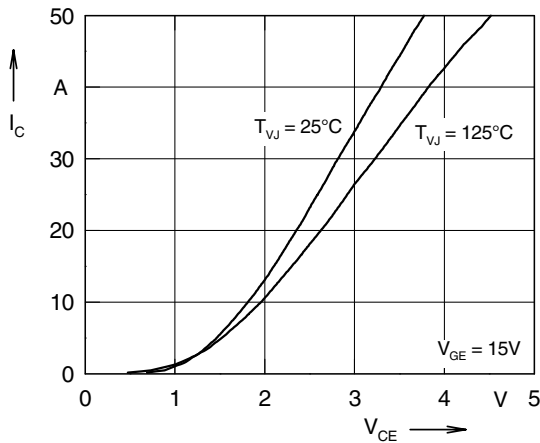


Fig. 19 Typ. output characteristics

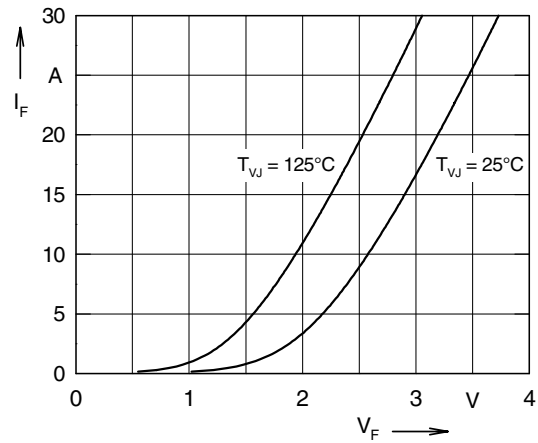


Fig. 20 Typ. forward characteristics of free wheeling diode

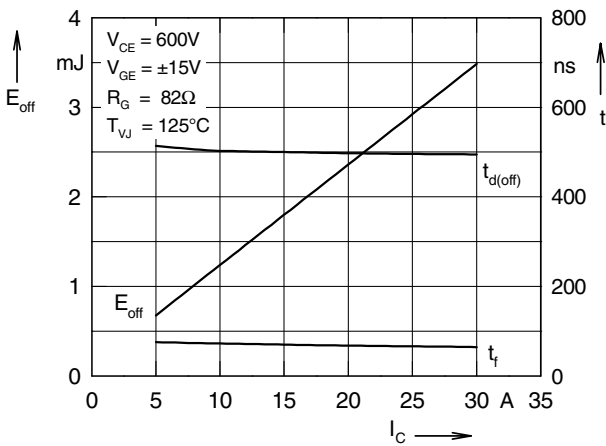


Fig. 21 Typ. turn off energy and switching times versus collector current

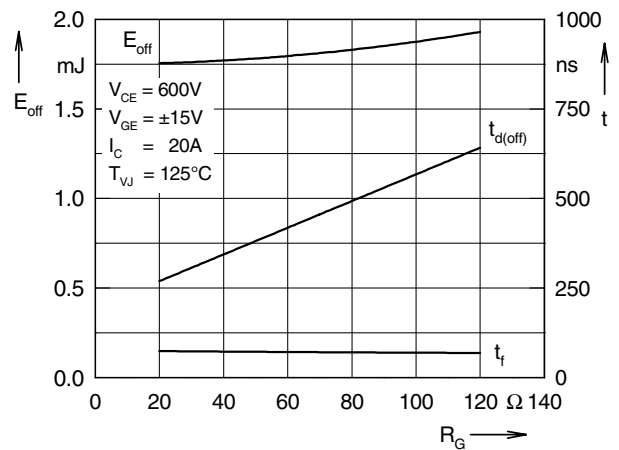


Fig. 22 Typ. turn off energy and switching times versus gate resistor

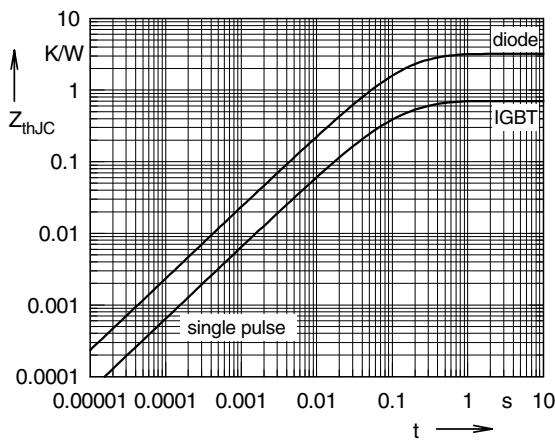


Fig. 23 Typ. transient thermal impedance

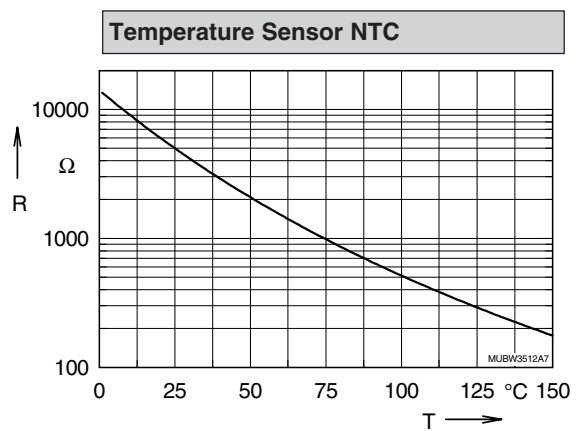


Fig. 24 Typ. thermistorresistance versus temperature