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MAC
AC Servo Motors

Project Planning Manual

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The purpose of this documentation?

This project planning documentation

- lists the technical data and power features of the motor
- offers guidelines on the mechanical integration of the motor into the machine
- offers guidelines on the electrical integration of the motor into the machine
- outlines the available options
- lists the order information for motor and its electrical connecting accessories
- offers guidelines on the transport, handling and storage of motors.

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1. MAC AC Servo Motors

Applications

AC servo motors of the MAC series are rapid-response servo drives in conjunction with TDM, KDS and DSC drive controllers. They are especially well-suited for use in:

- machine tools,
- textile machines,
- printing presses,
- packaging machinery,
- robotics,
- handling equipment and
- transfer facilities.

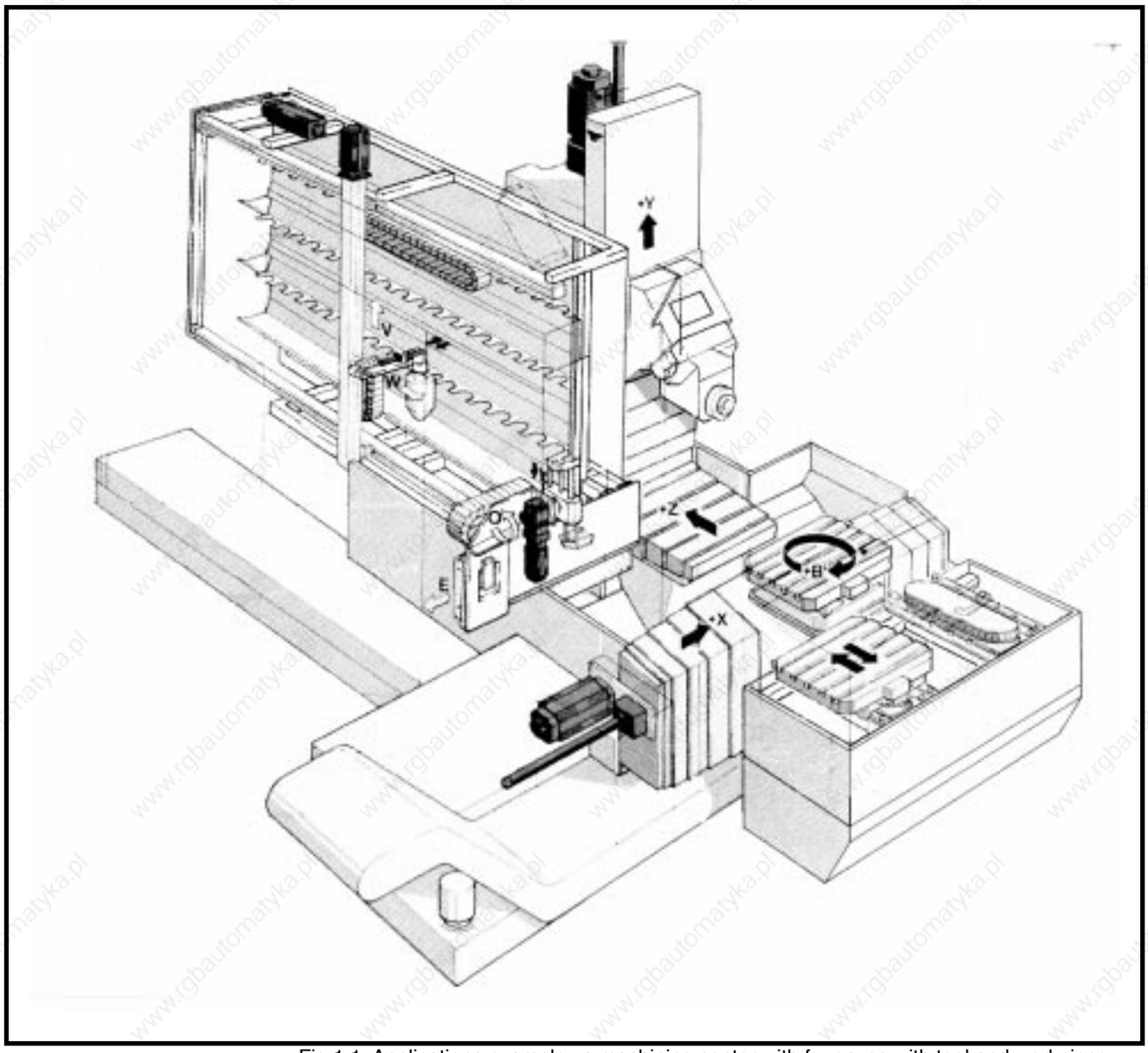


Fig 1.1: Applications example: a machining center with four axes with tool and workpiece handling facilities

Overview of power ratings

Figure1.2 illustrates the available motor line with the power features, "continuous torque at standstill M_{dN}" and "nominal speed n".

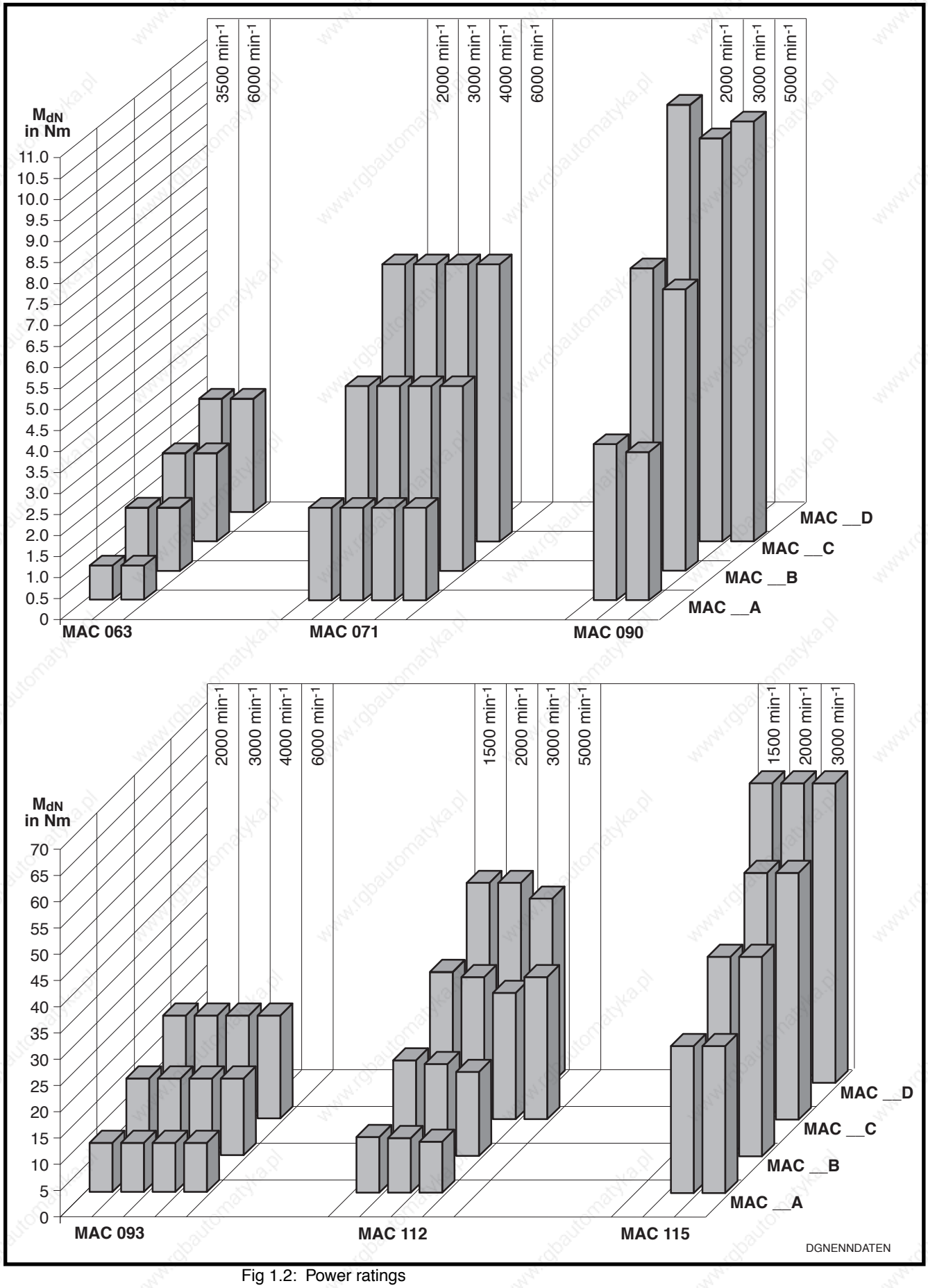


Fig 1.2: Power ratings

Construction and components of the motor

MAC AC servo motors are permanent magnet-excited motors with electronic commutation. The permanent magnets of the rotor are made up of materials which make it possible to construct motors with very low inertia.

Figure 1.3 illustrates the basic construction and components of a MAC AC servo motor.

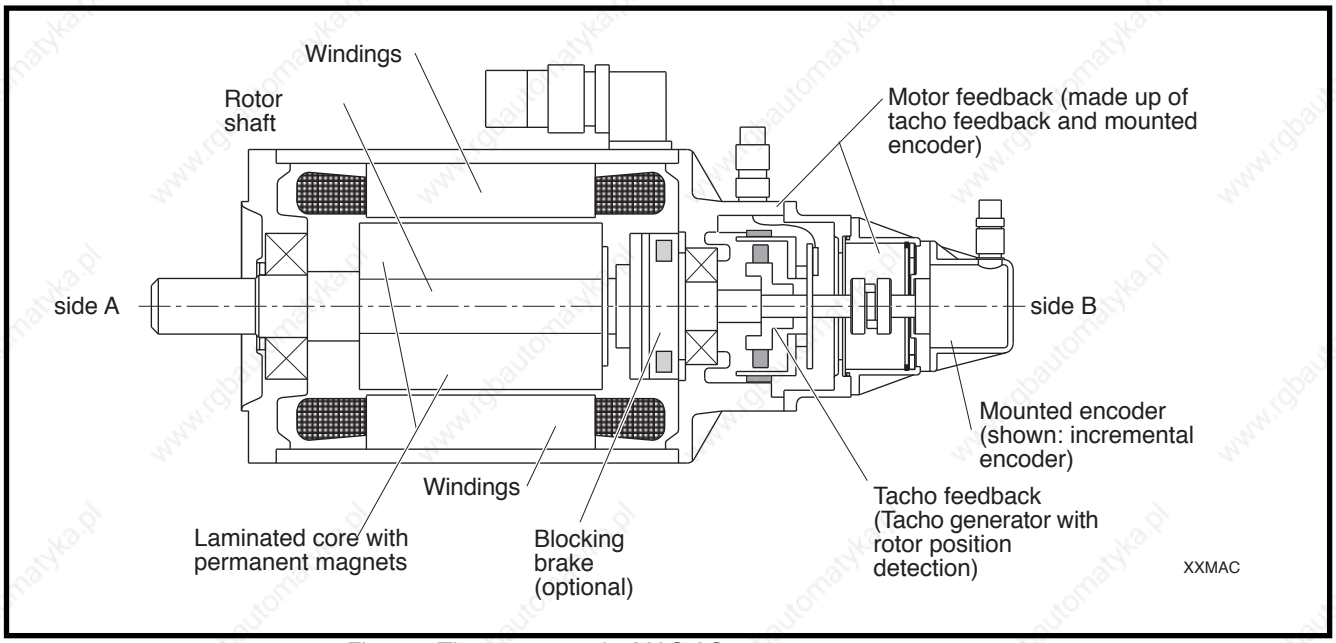


Fig 1.3: The structure of a MAC AC servo motor

Motor feedback

The motor feedback of a MAC AC servo motor is always made up of one tachofeedback. The motor can also be additionally equipped with a mounted encoder for position evaluation.

Tachofeedback

For speed evaluation per tacho-generator and rotor position recognition, the motors are equipped with a tachofeedback especially developed for this series. It is always integrated into the motor.

Mounted encoder

For position evaluation on the motor, the motor can also be equipped with:

- a second shaft end to mount the customer's own encoders,
- an incremental encoder and
- an absolute encoder.

Operating reliability

MAC motors achieve a **high degree of reliability** as a result of the following structural features:

- Maintenance-free operation due to:
  - the brushless design of the motor and
  - the use of life-time lubricated bearings.
- Can be used directly within the working area of the machine even under poor environmental conditions such as affects of coolants, soluble oil emulsions and so on:
  - because the motor housing is totally enclosed as per protection category IP 65
  - because the motor power and tachofeedback cables as well as the encoder cables are designed to meet IP 65 demands.
- Motor temperature is monitored with thermo switches integrated into the motor windings and stator housing. This prevents overload damage.

Output data

The **output data of the motor is high**. This is described in detail as follows:

- High dynamic performance due to favorable torque-inertia ratio.
- A high overload capacity of the motor as the heat is dissipated from the stator windings to the outside wall of the motor housing.
- Utilizaton of peak torque over a wide speed range.
- High power to weight ratio due to compact construction.
- High cyclic load capacity permits continuous start-stop operations with high repetition rates due to electronic commutation of the motor.
- Excellent smooth running qualities resulting from the special design of the stator and high-resolution tachofeedback.

Installation on the machine

Mounting the motor to the machine **is simple**.

- Pinions and belt pulleys can be directly mounted onto the shaft because the design of the bearing assembly makes the application of high radial loads possible.
- There is a defined assimilation of outside forces at the motor shaft. This means that the floating bearing of side A of the motor absorbs the radial forces. Side B absorbs the axial forces.
- Thermal deformations affect side A.
- The motor can be mounted in any orientation.
- Flange design with throughholes in the flange makes it possible to mount as per design IM B5 or with windings in the flange as per design IM B14.
- A variety of ready-made cables is available, eliminating additional installation work.

Cooling

The MAC AC servo motors are available with surface cooling for extreme loads. An overview of the blower options for the individual series is offered in Section 2.2, Figure 2.11.

Holding brake

MAC motors can be delivered with or without holding brakes.

The holding brake makes it possible to clamp (hold into place) the output shaft at standstill. This achieves a safe standstill of the axis even when power is off.

Output shaft

The output shaft is available in two different designs:

- as a plain shaft for non-positive shaft-hub connections and
- shafts with keyways for form-fitting shaft-hub connections.

Smooth run

The MAC 090 and 112 AC servo motors are available with a special windings design which achieves a high degree of smooth run. It is particularly well-suited for use in grinding machines and precision lathes.

It must be designated in type code field 5 with a "G". In this case, the tacho design with increased smooth run should be used as motor feedback (type code field 6 with an "F").

Electrical connections

The power, tachofeedback and encoder cables are directly connected to the motor with the use of connectors on the corresponding flanged sockets.

Labelling the sides

To make sure that the sides of the MAC are clearly labelled and that there is no confusion, they have been fixed and illustrated in the figure below.

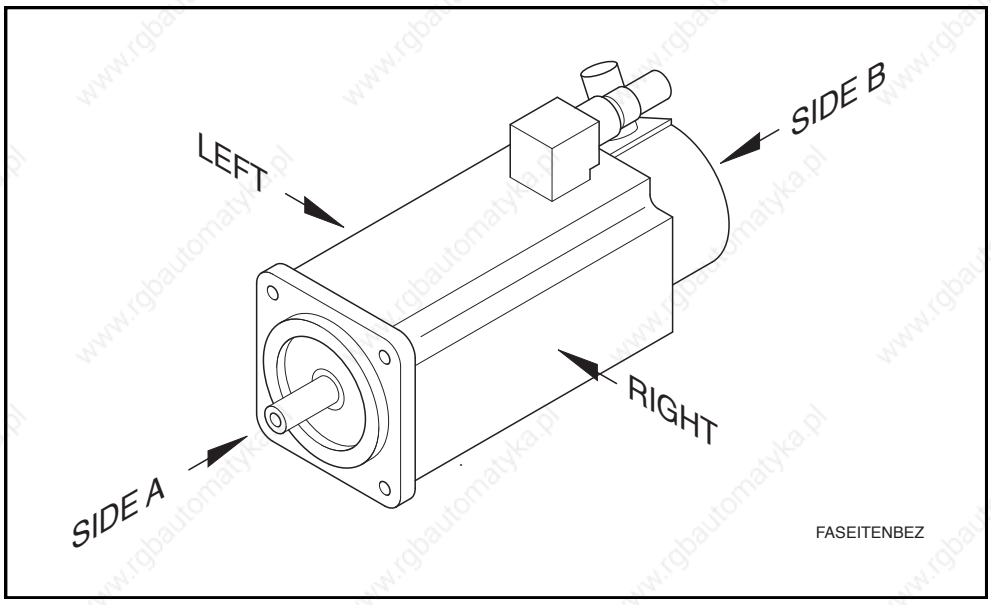


Fig 1.4: Labelling the sides of the MAC servo motor

2. Technical Data

This section outlines a description of the ambient conditions, the mechanical and electrical features of the motor as well as the motor feedback. Section 2.5 offers important details about the torque-speed characteristics which are, in turn, depicted for each motor type in sections 3.2, 4.2 through 8.2.

2.1. Ambient Conditions

Installation elevation and ambient temperatures

The output data outlined in the section "Technical Data" are achieved under the following conditions:

Ambient temperature: 0 ... + 45 °C

Installation elevation: 0 ... 1000 meters above sea level

If the conditions deviate from the values, then the output data will decrease as depicted in the diagrams of Figure 2.1. If higher ambient temperatures and higher installation elevations occur simultaneously, then the load factors f_T and f_H must be multiplied.

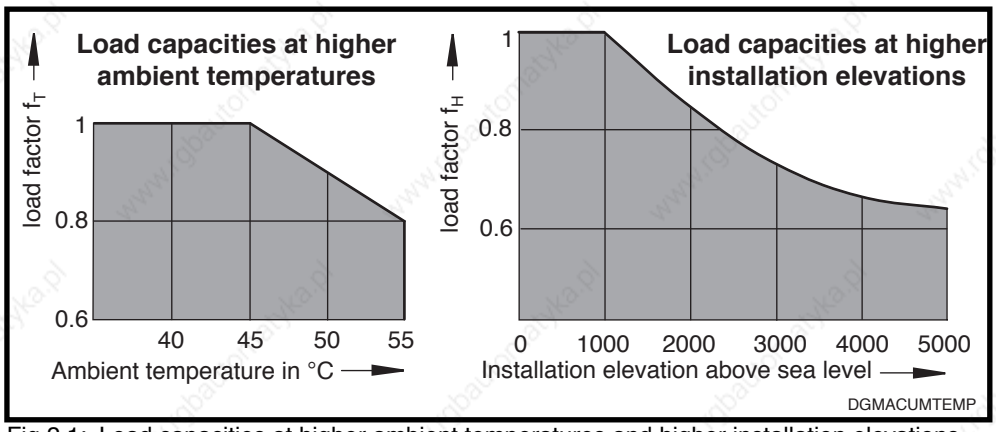


Fig 2.1: Load capacities at higher ambient temperatures and higher installation elevations

Protection category

The MAC motors are protected by their housing and covers which in construction and design adhere to the guidelines found in DIN 40 050 and are, therefore, protected against:

- contact with motor parts either moving or alive (contact guards),
- penetration by extrinsic objects and
- penetration of water.

The protection categories are laid down by the abbreviation IP (**I**nternational **P**rotection) and two numbers for the type of protection, e.g., IP 65.

The first number represents the degree of protection afforded against contact and penetration by extrinsic objects (see Figure 2.2). The second number represents the degree of protection afforded against the damaging penetration by water (see Figure 2.3).

Figure 2.4 depicts the range of the protection categories as applicable to MAC motors.

First digit	Protection against contact and extrinsic objects
0	Little or no protection.
1	Protection against penetration by extrinsic objects with a diameter exceeding 50 mm. No protection against direct access, e.g., by a hand. Will keep larger body surfaces out, however.
2	Protection against penetration by extrinisic objects with a diameter exceeding 12 mm. Will keep fingers or similar objects out.
3	Protection against penetration by extrinsic objects with a diameter exceeding 2.5 mm. Keeps out tools, wiring or similar objects thicker than 2.5 mm.
4	Protection against penetration by extrinsic objects with a diameter exceeding 1 mm. Keeps out tools, wiring or similar objects thicker than 1mm.
5	Protection against damaging dust. Complete penetration by dust is not prevented, but the dust may not be permitted to penetrate to the extent that the operation of the electrical equipment is in any way hindered (protected against dust). Complete protection against penetration by extrinsic objects.
6	Protection against the penetration of dust (dust-free). Complete protection against penetration by extrinsic objects.

Fig 2.2: Protection grades - contact and penetration per DIN 40050, sec. 2 (6/72 edition)

Second digit	Protection against Water
0	Little or not protection.
1	Protection against vertically dripping water (dripping or trickling water). It may not have any destructive affects.
2	Protection against vertically dripping water. It may not have any adverse affects on electrical equipment tilted up to 15° in contrast to its normal position (water dripping or trickling at an angle).
3	Protection against water falling at an angle of up to 60°. Does not permit any damaging affects (sprayed water).
4	Protection against water sprayed at the equipment (housing) from all directions. Does not permit any damaging affects (splashwater).
5	Protection against a jet of water sprayed from a nozzle onto the equipment (housing) from all directions. Does not permit any damaging affects (jet of water).

Fig 2.3: Protection grades for water per DIN 40050, sec. 2 (6/72 edition)

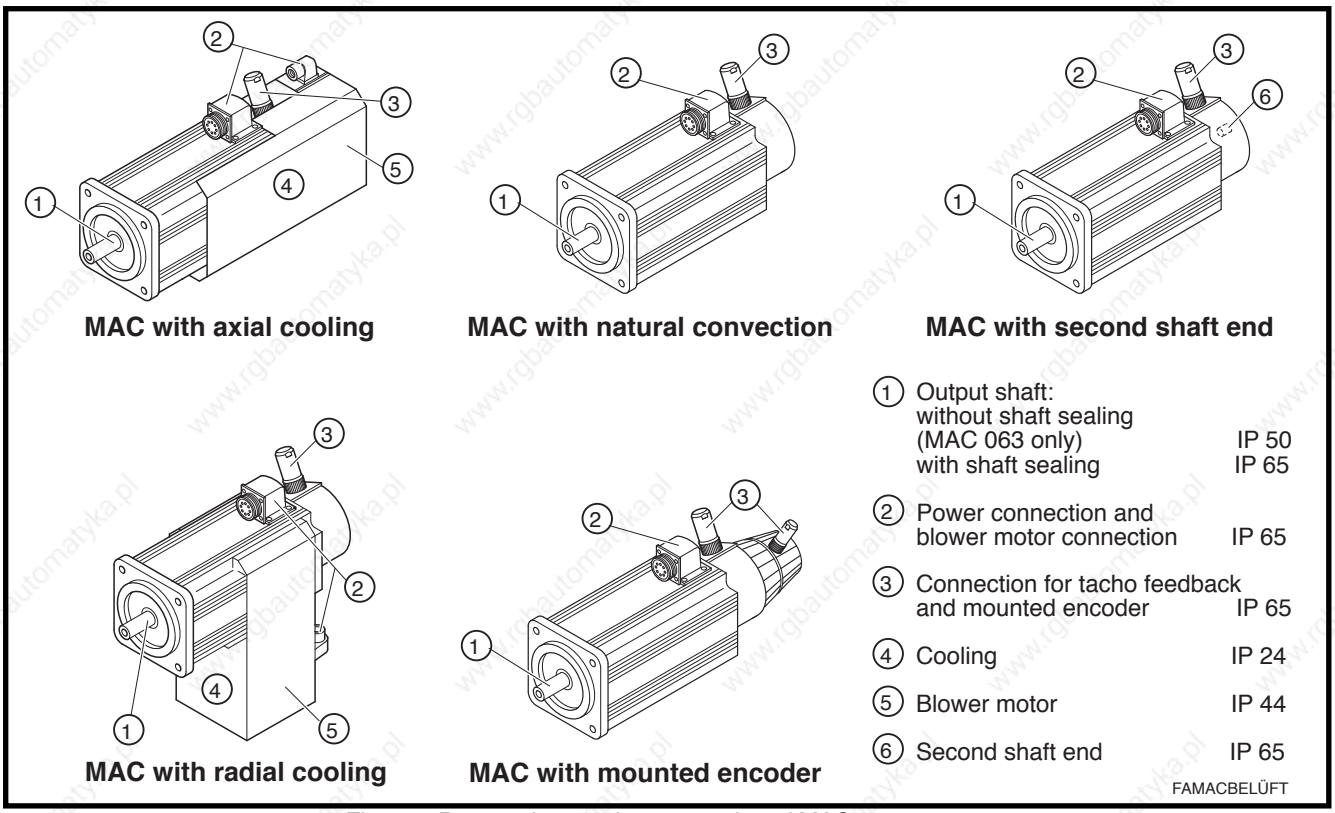


Fig 2.4: Range of protection categories of MAC motors

Ambient mechanical conditions

MAC servo motors can be operated in a stationary manner under weather-proofed conditions as per IEC 721-3-3, the 1987 edition, or EN 60721-3-3 the 6/94 edition:

- as per class 3M1 respective the longitudinal axis of the motor and
- as per class 3M6 respective the lateral axis of the motor.

The maximum values stated in Figure 2.5 thus apply to transportation and operation of MAC servo motors.

Environmental variables		Unit	Maximum values longitudinal axis	Maximum values lateral axis
sinusoidal oscillations	excursion amplitude	mm	0.3	7.0
	frequency range	Hz	2 to 9	2 to 9
	acceleration amplitude	m/s^2	1	20
	frequency range	Hz	9 to 200	9 to 200
shocks	total shock-response spectrum	-	Type L per IEC 721-1 edition of 1990, table 1 section 6	Type II per IEC 721-1 edition of 1990, table 1 section 6
	reference acceleration (in IEC 721-1 peak acceleration)	m/s^2	40	250
	duration	ms	22	6

Fig 2.5: Maximum values of the environmental variables

MAC servo motors are only suited for such extreme demands as is the case with punching, pressing, press feeds and similar applications, if shock-damped mounted or mounted shock decoupled.

We cannot recommend a generally applicable solution for shock-damped mounting. It is dependent on the respective construction of the machine and the results of metrological tests.

A shock-damped variant for incremental encoders is available for the MAC AC servo motors. This has been tested for punching, pressing and press feed applications.

Housing coat

The housing of the MAC motors is painted with a black prime coat. An additional layer of paint can cover this prime coat. The thickness of the layer may, however, not exceed 40 μm.

This prime coat is resistant to:

- weathering, yellowing and chalky build-ups as well as
- diluted acids and lyes

The coat can, however, peel if the housing is frequently cleaned with a steam cleaner.

2.2. Mechanical Features

Construction and mounting orientation

The mounting flange is designed, in all types of motors, in such a way that mounting as per design B5, i.e., mounting with flange with throughholes, is possible.

Mounting mode as per design B14, i.e., mounting flange with windings, is **additionally** possible in the following motors:

- MAC 090
- MAC 093
- MAC 112
- MAC 115

Figure 2.6 demonstrates the ways that the motors can be mounted to the machine as per DIN 42950, section 1, the 8/77 edition.

Construction	Permissible mounting orientations per DIN IEC 34-7		
B05	IM B5	IM V1	IM V3
B14	IM B14	IM V18	IM V19

Fig 2.6: Permissible mounting orientations

In those cases where the motors are mounted in orientations IM V3 and IM V19, it is necessary to prevent liquids from collecting at the output shaft over extended periods of time. Even the use of a shaft sealing does not absolutely prevent liquids from penetrating, along the output shaft, into the housing of the motor.

Pilot diameter

To generate compatibility with the motors of other manufacturers, it is possible to also select a mounting flange with a customized pilot diameter in addition to the standard types. This is possible only with some of the motors. The choices and appropriate dimensions are listed in the table in Figure 2.8.

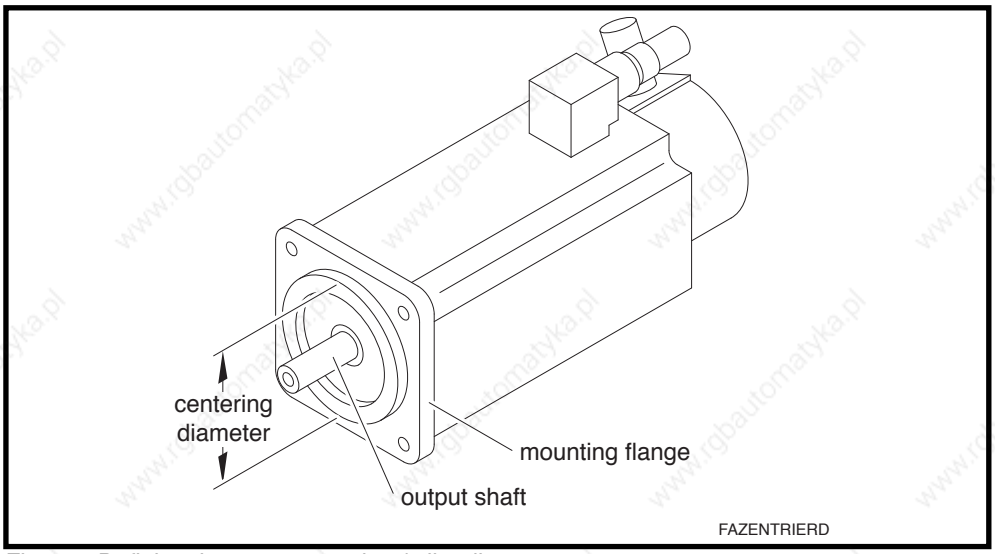


Fig 2.7: Defining the term centering / pilot diameter

Motor Series	Pilot diameter in mm	
	Standard types	Customized types
MAC 063	95	—
MAC 071	95	—
MAC 090	110	130
MAC 093	110	130
MAC 112	130	180
MAC 115	130	180

Fig 2.8: Pilot diameters for the individual motor series

Output shaft

The design of the output shaft can be selected by the user. INDRAMAT recommends the use of plain output shafts.

Plain output shaft

A backlash-free and non-positive transmission of torque can be achieved with a plain shaft. Clamping sets, pressure sleeves or similar clamping components can be used for coupling pinions, belt pulleys or similar elements.

Output shaft with keyway

The output shaft with keyway adheres to the requirements specified in DIN 6885, sheet 1, 8/68 edition. This achieves a form-fitting torque transmission. This type of shaft-hub connection is suitable for lesser demands. A multi-

axial stress state occurs at the shaft-hub connection as a result of torsion, bending, radial and axial loads. It is possible, during powerful reverse operations, for the bottom of the key to turn out and reduce the quality of concentricity. Ever-increasing deformations can cause fractures. The use of plain shaft ends with friction-locked connections is therefore recommended.

Shaft sealing

The shaft sealing is attached to the flange. It ensures that no liquids can penetrate into the motor housing along the shaft. An output shaft with shaft sealing is required for those applications where dirt or the affects of a jet of water can be present. The protection category in this case is IP 65.

In the MAC 071, 090, 093, 112 and 115, the output shafts are always equipped with a shaft sealing.

In the MAC 063 line, the output shaft can be selected with or without the sealing. The output shaft of this line is generally not equipped with the ring. The protection category in this case is IP 50.

Permissible shaft load

Load is applied to the shaft as soon as radial or axial forces affect the motor shaft.

The **permissible radial force** (radial shaft load) is depicted in a diagram in sections "Shaft Load Capacity", i.e., sections 3.3., 4.3 and so on.

The permissible radial force is depicted in terms of

- the average speed
- and the point of application of force.

The **permissible axial force** (axial shaft load) can be calculated with the aid of a formula. It can be found in this section.

Thermal deformations

Thermal deformations in length affect side A of the motor. This means that the A side of the motor shaft end can shift up to 0.6 mm with respect to the motor housing. As a result, there

- **is a shifting of position by using drive pinions with helical teeth mounted to the motor output shaft but not axially fixed to the machine or**
- **thermal stress is occuring by using drive pinions with helical teeth axially fixed to the machine with bevel gear pinions. The latter can lead to damage on side B of the motor.**

Cooling

For extreme loads, as is, for example, the case with continuous start-stop operations with a high level of repetitive frequency, it is possible to mount a surface-cooling unit to some of the motors.

Blower motors, operating with 1 x AC 230 V and AC 115 V, are available.

Axial surface cooling
Axial cooling is suited for those applications that need a slender form.

Axial surface-cooling units are not available for motors with a second shaft end. What is available for each line of motor is listed in the table in Figure 2.11.

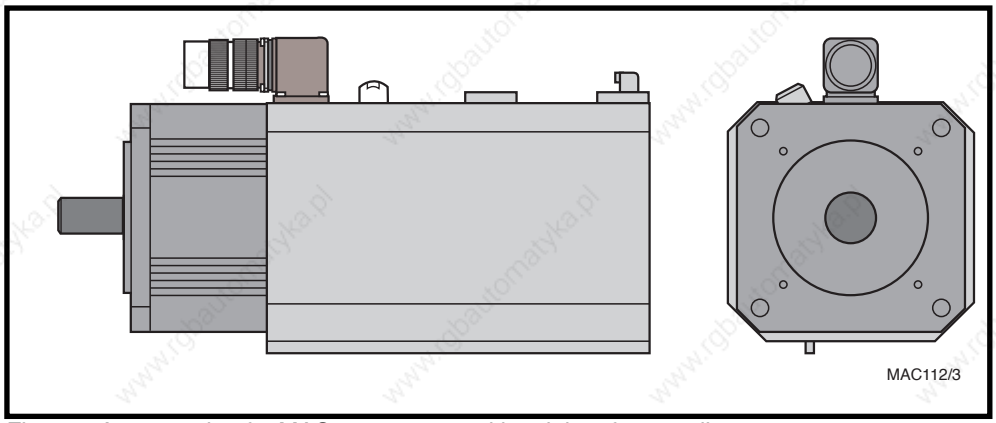


Fig 2.9: An example of a MAC servo motor with axial surface cooling

Radial surface cooling

Radial cooling is suited for those applications that need a short construction.

The use of radial surface-cooling units is recommended in those cases where shock loads are high.

If a radial surface-cooling unit is to be mounted on the motor, then the arrangement of the blower unit on the motor must be determined. The following possibilities are available with every line of motor (looking towards motor shaft):

- the blower is located under the motor shaft,
- the blower is to the left of the motor shaft or
- the blower is to the right of the motor shaft.

Radial surface cooling is not available for the MAC 063 motors with motor length A.

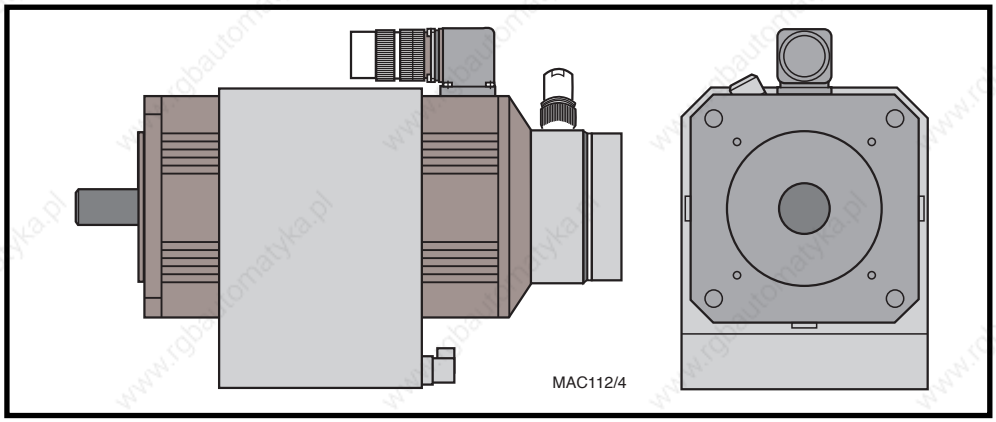


Fig 2.10: An example of a MAC servo motor with radial surface cooling with the blower under the motor shaft

The blower options for the individual motor series are listed in the table found in Figure 2.11.

Motor type	Blower for surface cooling	
	axial	radial
MAC 063	+ [2) 3)]	+ [1)]
MAC 071	+ [2)]	+
MAC 090	+ [2)]	+
MAC 093	+ [2)]	+
MAC 112	+ [2)]	+
MAC 115	+ [2)]	+

+ available
[1)] not available for motor length A
[2)] not available for motors with tachofeedback and second shaft end
[3)] not available for motors with tachofeedback and mounted encoder

Fig 2.11: Blower options

Holding brake

For a backlash-free holding of the servo axes when the machine is powered off, it is possible to equip them with a holding brake.

The holding brake, especially developed for those motors, works along the closed-circuit principle. At zero current, a magnetic force acts on the brake armature disc. This means that the brake is locked and holding off the axis. With the application of 24 V DC, the electrical field cancels the permanent magnetic field and the brake opens.

The customer is responsible for the control of the holding brake with the use of either a PLC or a hardware switch. Various recommendations are outlined in the Applications Manual for "MAC Servo Drives with Servo Drive Modules TDM and KDS".

The holding brake alone cannot guarantee the safety of personnel as it can fail or wear down. Additional measures must be taken to ensure personnel safety. These must be undertaken by the manufacturer of the machine and can, for example, be the mounting of a second brake.

The holding brake is not a working brake. It can wear down after 20,000 motor revolutions against the closed brake.

If the motor has been stored for any extensive period of time, then the following guidelines should be noted before commissioning it:

If the motor is stored for a period exceeding two years, then it is necessary to grind it in before using it.

To grind it in:

1. **Run the motor at a speed of approximately 100 speed.**
2. **Close the holding brake and keep it closed for approximately 60 seconds.**

   Note: Open the conductor of the holding brake to the PLC or the hardware circuitry.
3. **Shut down the drive after 60 seconds.**
4. **Reconnect the holding brake to the PLC or the hardware circuitry.**

The holding brake is available with the following holding torques for each respective motor series.

Holding torque	MAC …					
	063	071	090	093	112	115
3 Nm	X	X				
6.5 Nm		X	X	X		
14 Nm			X	X	X	
22 Nm				X		
40 Nm					X [1)]	
45 Nm						X
60 Nm					X [1)]	X
[1)]Not available for motor length A.						

Fig 2.12: The holding torque of the holding brakes

Power connection

The user must order the output direction of the power connections in accordance with the conditions at the machine. The output direction cannot be altered after delivery.

The following variants are available (also see Figure 2.13):

- connector to side A
- connector to side B
- connector to the right
- connector to the left

Note: With the MAC 063s only the output directions towards side A or side B are available.

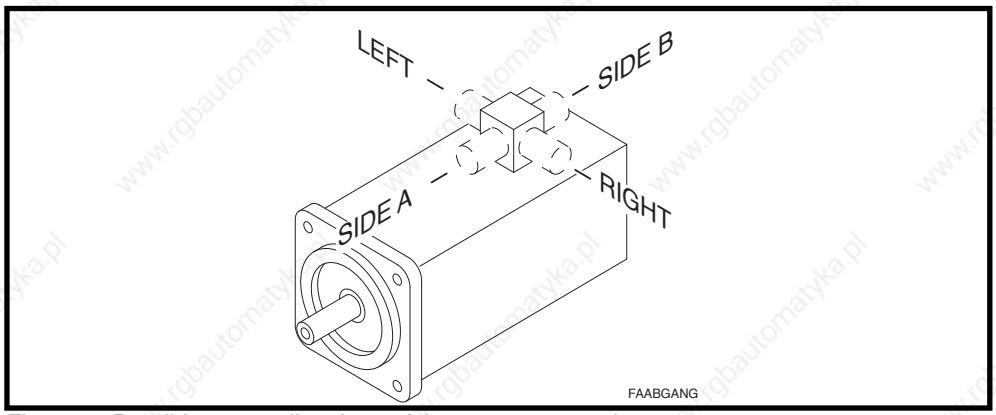


Fig 2.13: Possible output directions of the power connections

Feedback connector

Different types of connectors can be selected for connecting the motor feedback cable depending upon the installation conditions. Available are:

- straight connectors and
- angle connectors.

Information about the allocation of connector type to motor type can be found in the dimensional data sheets and in section 13.2 "Connector for the Feedback".

Straight connector

Figure 2.14 depicts a motor with tachofeedback and straight encoder connector.

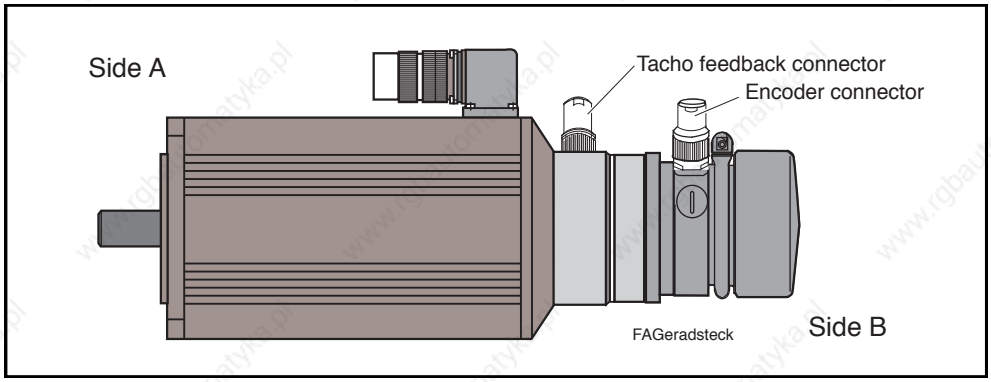


Fig 2.14: A MAC motor with straight tachofeedback and encoder connectors

Angle connector

INDRAMAT supplies and delivers the angle connectors so that the output direction of the cable, once inserted into the flanged socket, is side B of the motor.

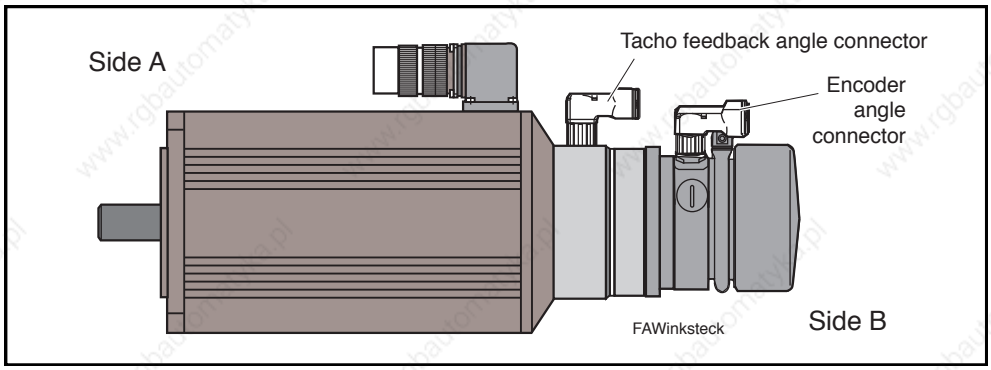


Fig 2.15: A MAC motor with angle connector (side B is output direction at delivery)

The user can change the output direction. Just release the four fixing screws (see Figure 2.16). The connector parts can now be turned in increments of 90° into the position desired.

Make sure that neither the gasket nor the cable cores of the cable are damaged when re-tightening the screws.

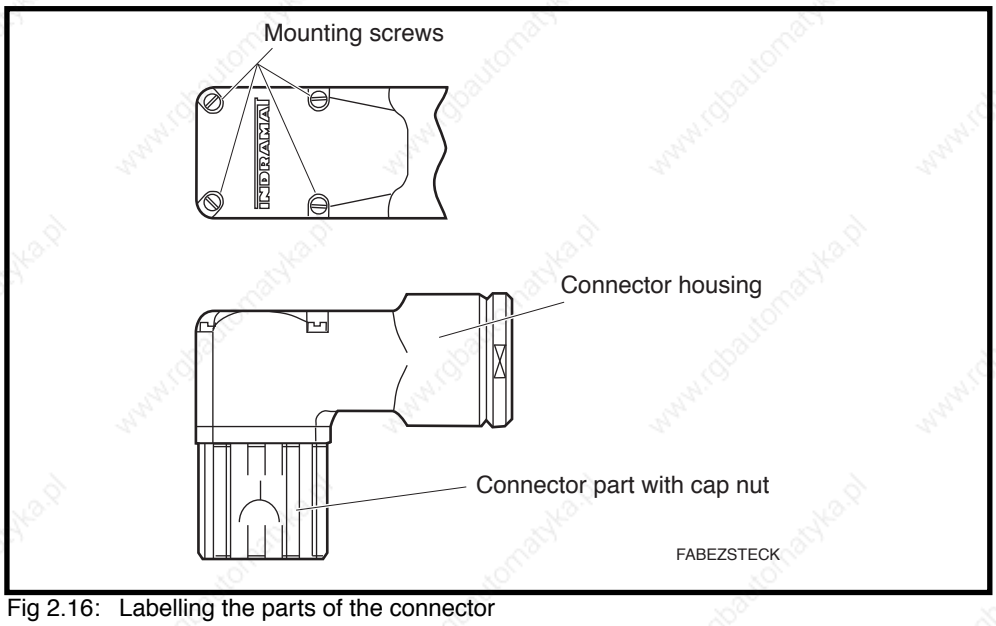


Fig 2.16: Labelling the parts of the connector

Angle connectors cannot be used in conjunction with an axial surface cooling unit.

2.3. Electrical Features

Terminal diagram

The terminal diagram shown in Figure 2.17 is purely schematic. It represents a checklist for all the necessary electrical conections to operate a MAC AC servo motor.

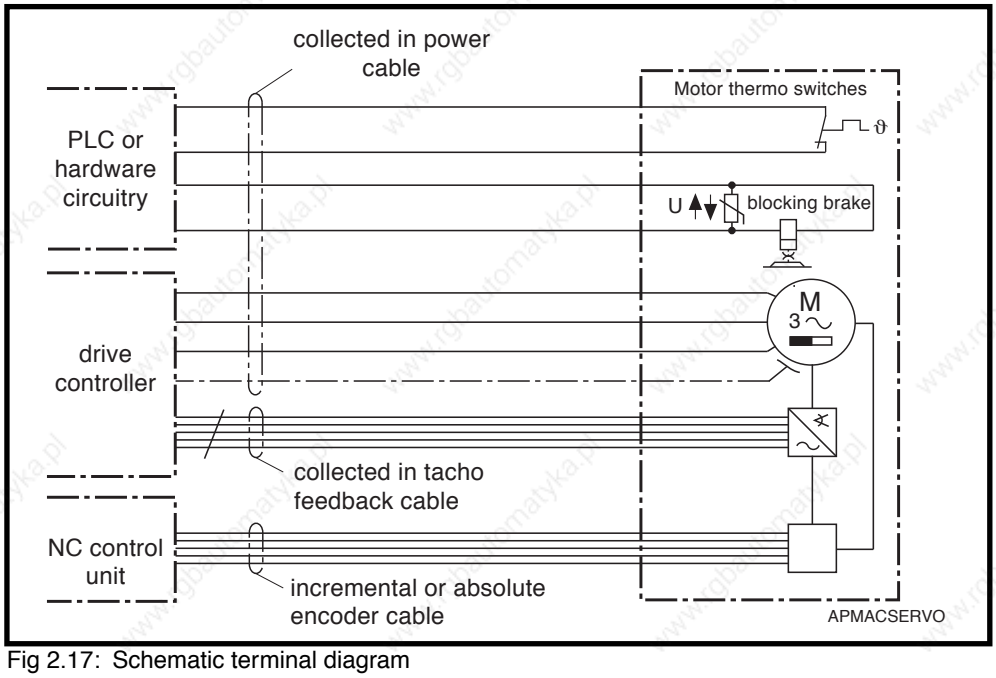


Fig 2.17: Schematic terminal diagram

The following electrical connections are on a MAC motor:

- Power connection (always present)
- Tachofeedback connection (always present)
- Incremental or absolute encoder connection (this depends on the type of motor implemented)

If a blower for surface cooling is mounted to the motor, then a motor blower connection is also there. This is not shown in the terminal diagram.

The electrical connections of INDRAMAT drives have been standardized to minimize cable diversity. Sections 12 and 13 specify the electrical connections for a given application and motor type.

Power connection

The following connections are integrated into the power connection:

- power cable,
- connecting cable for the thermo switch(es)
- and the connecting cable for the holding brake.

There are thermo switches built into the windings of the motor and the stator housing. They are electrically connected in series and conducted together at the power connection out of the motor housing. The opening of the thermo switch must be detected either by a superordinate PLC or hardware circuitry, and then an appropriate error reaction generated as quickly as possible.

Motor power connectors for the electrical power connections are available for either:

- crimping or
- soldering.

Power cables with metrical diameters can be either crimped or soldered to the motor power connector. Power cables with inch diameters can only be soldered.

Feedback connection

There is a 12-pin flanged socket on the motor for the feedback and encoder connections.

The connection diagram, available feedback cables and connectors are all outlined in section 10.

Motor blower connection

The motor blower is integrated into the hardware circuitry as per customer requirements as, for example, via a protective motor switch which would then operate independently of the controller.

The connector cable must have three cores with a diameter of at least 0.75 mm^2.

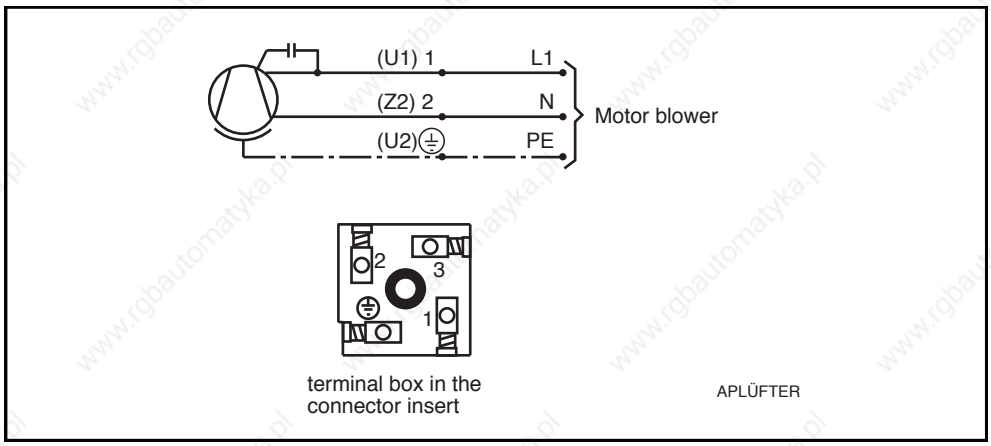


Fig 2.18: How to connect the blower

Connecting the able to the motor blower

The following steps describe how to connect the cable to the motor blower. The individual parts of the connector are illustrated in Figure 2.19.

Procedure:

The cable may only be connected by either an electrician or trained personnel under the supervision of an electrician.

1. Release conduit thread screw (6) (SW 17).
2. Remove slotted screw (1) with screw driver (5) from flanged socket (4).
3. Remove connector housing (2) with connector insert (3) from flanged socket (4).
4. Pull out slotted screw (1).
5. Pull connector insert (3) out of connector housing (2) with screw driver (5) (see Figure 2.19).
6. Slide conduit thread screwed joint (6), ring (7), gasket (8) and connector housing (2) onto the cable (3x0.75 mm^2).
7. Strip cable sheath at a length of approx. 20 mm, strip litz wire for approx. 10 mm. Now connect as per terminal diagram in Figure 2.18 to the terminal box in the connector insert (3).
8. Push connector insert (3) into connector housing (2), atttach slotted screw (1) and screw connector onto flanged socket (4).
9. Remount conduit thread screwed joint (6) making sure strain relief is adequate!

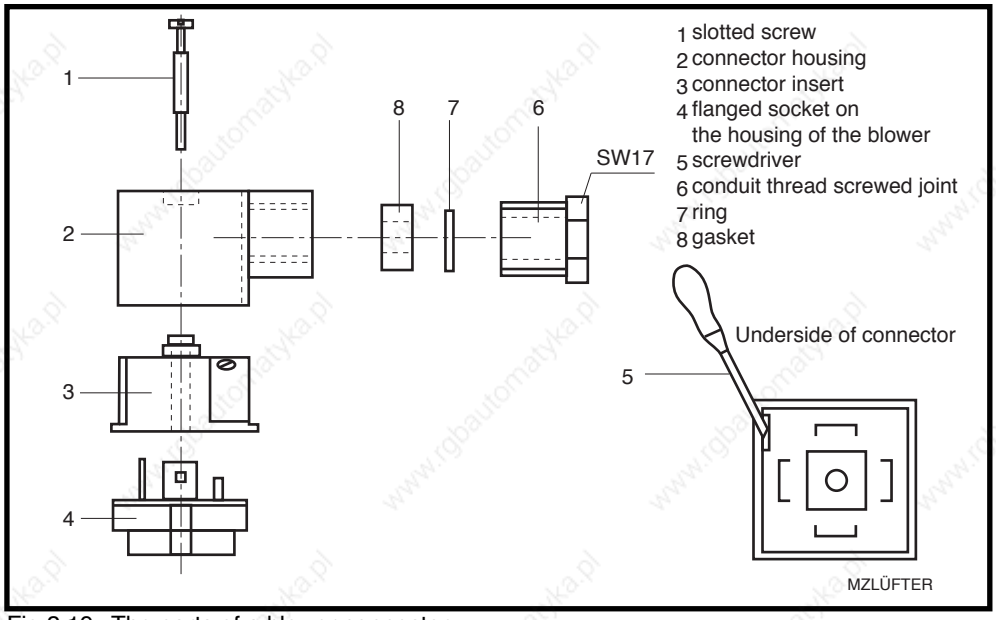


Fig 2.19: The parts of a blower connector

2.4. Motor Feedback

The motors are equipped with a motor feedback for the evaluation of position and speed and for the detection of rotor position. The motors are available in those versions illustrated in Figure 2.20.

Versions

The motor feedback is always made up of a tachofeedback and can be additionally fitted with an encoder.

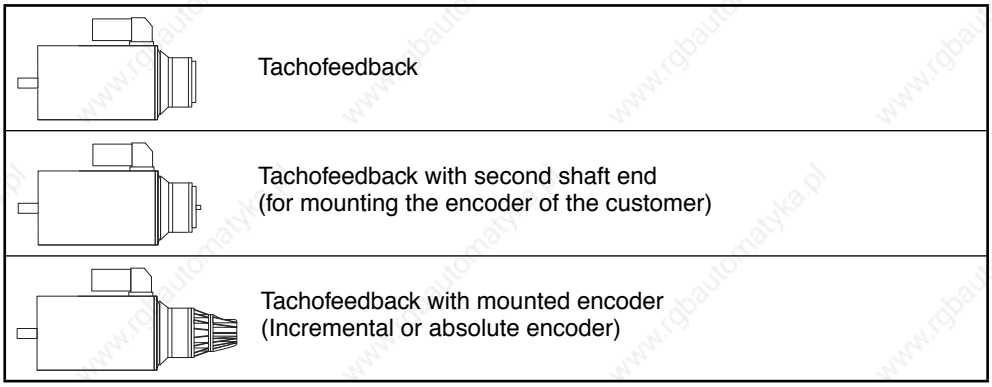


Fig 2.20: Available motor feedback versions

2.4.1. Tachofeedback

This design makes it possible to detect and evaluate both rotor position and velocity. The velocity feedback value is generated with residual ripple in some models and is suited for:

- either standard applications (tacho type „C“; see type code)
- applications with extreme high smooth run qualities
  (tacho type „F“; see type code)

The "Tachofeedback" version can be used in all machines in which there is, for example, a direct position evaluation via a linear scale or with applications with uniform rotations.

Tacho voltage can be selected to meet the following:

- to match nominal motor speed
  With a nominal speed of > 3000 min^{-1} tacho voltage equals 1.5V/1000 min^{-1}.
  With a nominal motor speed of ≤ 3000 min^{-1} tacho voltage equals 3V/1000 min^{-1}.
- 1.5 V/1000 min^{-1} for speeds exceeding 3200 min^{-1} in motors with a maximum nominal speed of 3000 min^{-1}
- 6 V/1000 min^{-1} for applications making higher demands of the resistance to interference in tachofeedback lines or requiring smooth run qualities at a maximum nominal speed of 1600 min^{-1}.

The options for each line of motor have been compiled in Table 2.21.

Motor Series	Tacho version	Tacho Voltage		
		matches nominal motor speed	1.5 V / 1000 min^{-1}	6 V / 1000 min^{-1}
063	standard	X		
	higher smooth run quality	X		
071	standard	X	X	
	higher smooth run quality	X	X	
090	standard	X	X	
	higher smooth run quality	X	X	X
093	standard	X	X	
	higher smooth run quality	X	X	
112	standard	X	X	
	higher smooth run quality	X	X	X
115	standard	X	X	
	higher smooth run quality	X	X	

Fig 2.21: Optional tachofeedbacks and allocation to motor series

2.4.2. Tachofeedback and Second Shaft End

This version is identical to the version "Tachofeedback", expanded, however, with an accessible second shaft end on side B of the motor. Additional components, encoders in particular, can be mounted hereto.

The second shaft end has a protection category of IP 65, i.e., the component mounted does not need to be completely sealed.

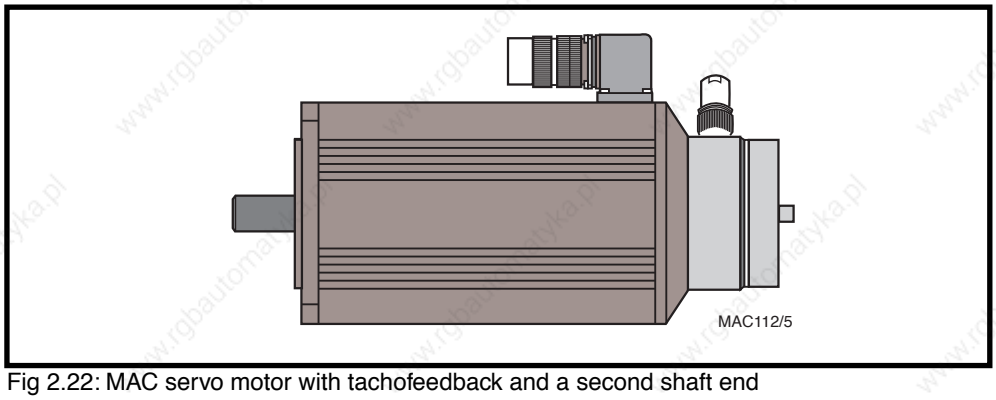


Fig 2.22: MAC servo motor with tachofeedback and a second shaft end

2.4.3. Tachofeedback with Mounted Encoder

This version corresponds to the "Tachofeedback" version with respect to the detection of velocity feedback value and rotor position. Mounted encoders in the following versions are available for position detection and evaluation:

- Standardly mounted incremental encoder for use with machines with lower shock loads.
- Incremental encoders with shock-damped mounting for use in presses, stamping machines and similar machinery
- and an absolute encoder

These mounted encoders have been especially desiged for INDRAMAT motors and are extremely resistant to environmental conditions.

These are introduced in greater detail in sections 2.4.4. and 2.4.5.

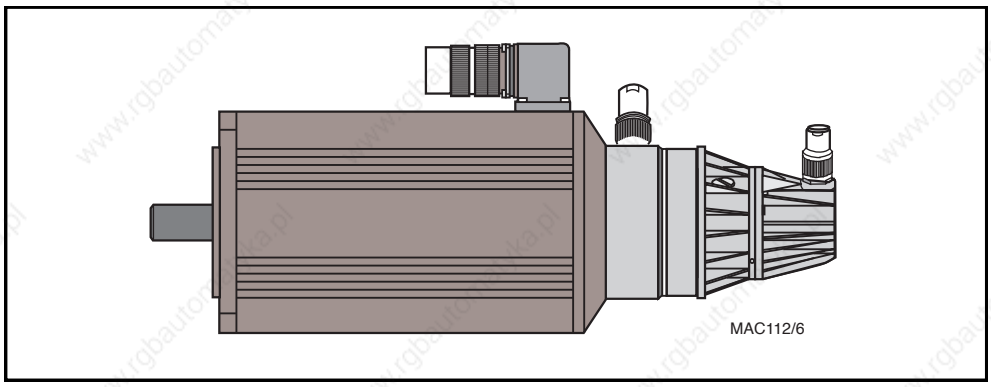


Fig 2.23: MAC servo motor tachofeedback with mounted encoder (ex: incremental encoder)

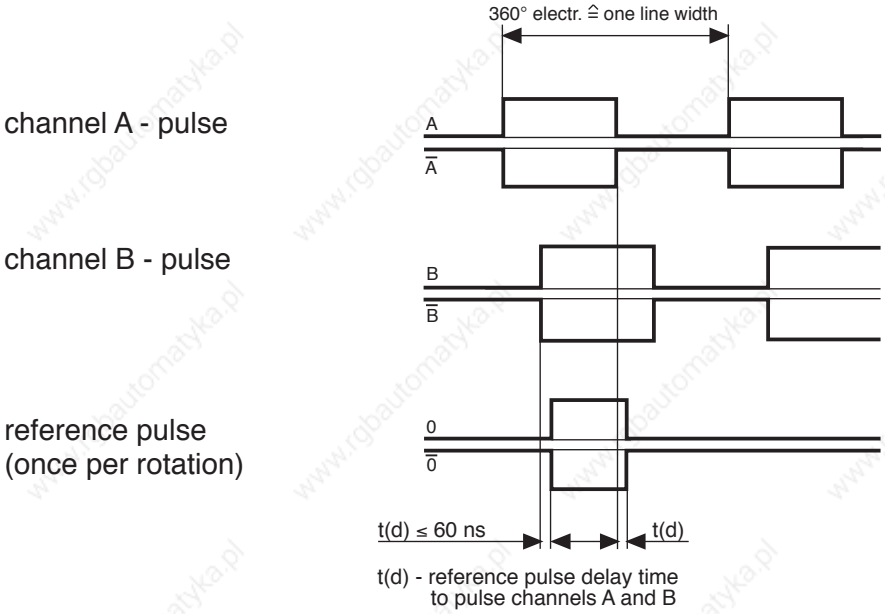
2.4.4. Incremental Encoders

Incremental encoders work with either square-wave pulses or sinusoidal signals. They are available to accomodate different supply voltages. The available versions are listed in Figure 2.24.

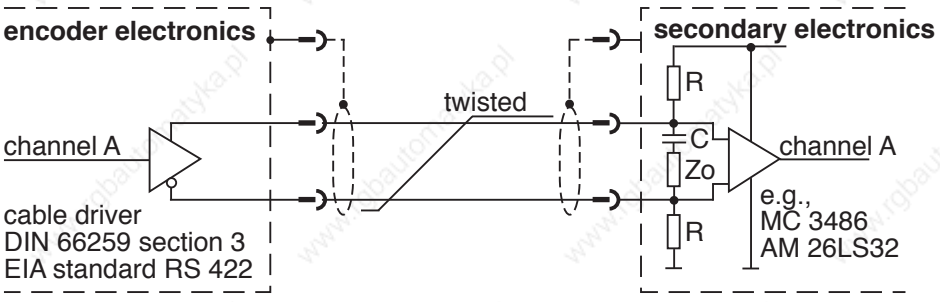
No. of pulses/ no. of lines	Pulse		
	Square-wave signal		Sinusoidal signal
	Supply voltage		Supply voltage
	5V	10 - 16V	5V
50	568LV		
125	542LV		
200	553LV		
250	515LV		527BX
400	516LV	634LX	
500	517LV		
600	572LV		
625	524LV		
900			593BX
1.000	518LV		647BX
1.024	519LV		
1.250	520LV	637LX	
1.500	538LV		
1.800	574LV		
2.000	521LV		
2.500	522LV		
3.600	594LV		
5.000	511LV		
Incremental encoders can only be mounted to MAC 063s with natural convection or radial surface-cooling units.			

Fig 2.24: Incremental encoder options

Voltage source:	5 V, ± 5 %
Current consumption:	150 mA
Signal level:	U(high) ≥ 2.5 V; U(low) ≤ 0.5 V; at 20 mA
Load capacity:	20 mA at "high" and "low" signal
Total operating time:	rise and fall times ≤ 200 ns
Maximum sampling frequency:	300 kHz
Incremental encoder signal:	TTL - square wave pulse sequence and its inverted signals with a rotational field towards the right when looking towards the motor shaft



Recommended switching of the secondary electronics:



R = 4,7 kΩ; prevents switching in the event of a break in the line
C = 1 nF .. 10 nF; decreases the current consumption of the encoder
Zo = 120 Ω ... 140 Ω; as per characteristic wave impedance of cable

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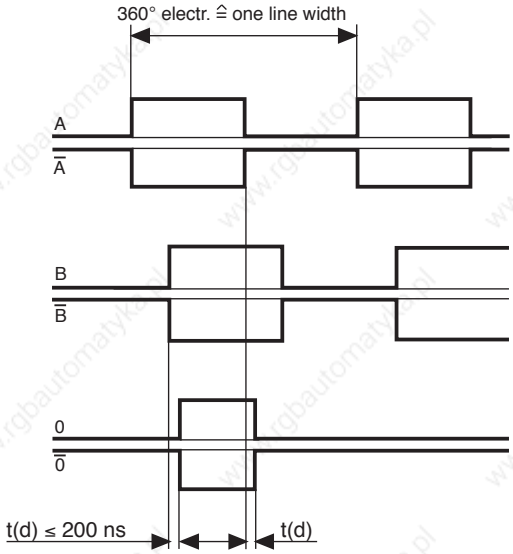
Fig 2.25: Incremental encoder, technical data, 5V voltage supplied, square-wave pulse

Voltage source:	10-16 V
Current consumption:	220 mA
Signal level:	U(high) ≥ 7 V; U(low) ≤ 2 V
Load capacity:	60 mA with "high" and "low" signal
Total operating time:	rise and fall time ≤ 200 ns
Maximum sampling frequency:	75 kHz
Incremental encoder signal:	TTL - square wave pulse sequence and its inverted signals with a rotational field towards the right when looking towards the motor shaft

channel A - pulse

channel B - pulse

reference pulse
(once per rotation)



t(d) - reference pulse delay time to pulse channels A and B

Recommended switching of the secondary electronics:

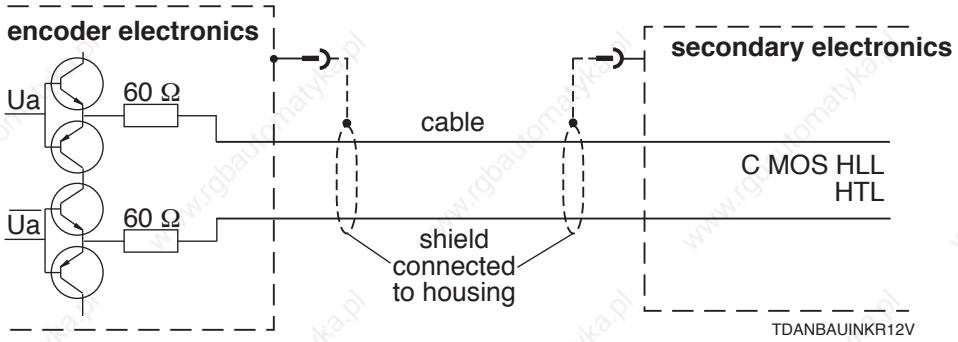


Fig 2.26: Incremental encoder, technical data, 12V voltage supplied, square-wave pulse

Voltage source: 5 V ± 5 %

Current consumption: 120 mA

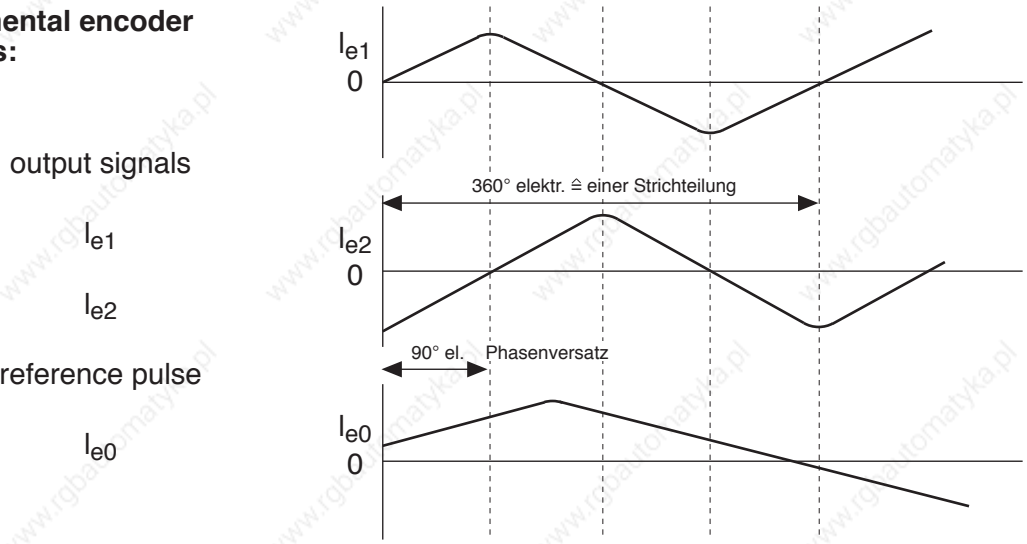
Signal: two current signals I_{e1} and I_{e2} approaching sinusoidal shape

Signal size with load of 1 kΩ: I_{e1} approx. 11 µA ss
I_{e2} approx. 11 µA ss

Reference signal: 1 signal le 0 per revolution

maximum scanning frequency: depends on slave electronics

Incremental encoder signals:



Speed:

$$\frac{0 \text{ to } f_{max}\ (kHz)}{z} \cdot 10^3 \cdot 60\ min^{-1}$$

z = number of lines

f_{max} = maximum input frequency of slave electronics

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Fig 2.27: Incremental encoder, technical data, 5V voltage supplied, sinusoidal signals

Setting the reference point

If INDRAMAT MAC servo motors are supplied with mounted incremental encoders and **motor output shafts with keyway**, then the reference point of the encoder is set to a defined angular position. This defined angular position of the reference point to the keyway of the motor output shaft makes it possible, if procedures are followed, to replace drives without adjustment work thus eliminating the risk of unnoticed dimensional displacements.

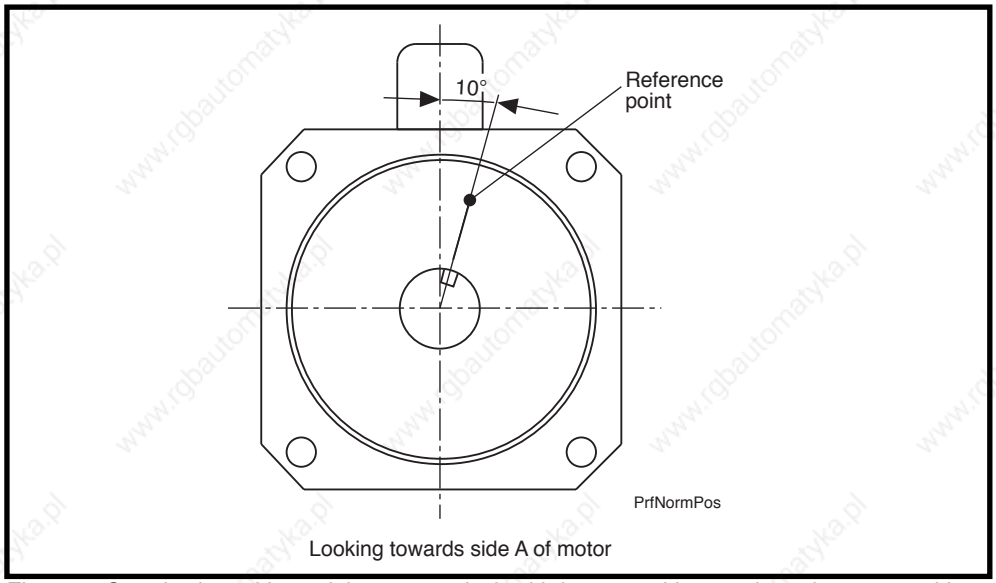


Fig 2.28: Standard position of the output shaft with keyway with encoder reference position in a MAC motor

The reference point can be mechanically changed if incremental encoders are used in MAC AC servo motors.

This is possible with:

- motors without surface cooling (natural convection)
- motors with radial surface cooling

This is not possible with:

- motors with axial surface cooling. The construction of the blower shroud determines the location of the incremental encoder connector with respect to the motor. This allocation changes, however, with the setting of the reference point!

When replacing the drives, changing the reference point setting results in considerable dimensional shifting. It must be checked by someone capable and authorized to do so and the reference point must, then, be reset. To replace a drive without causing this problem, we recommend that the defined reference point not be reset. INDRAMAT instead recommends an adaption of the reference dimension via the control unit.

Changing the reference point setting

Procedure:

Only an electrician or properly trained personnel under the supervision of an electrician may set the reference point.

1. Switch the power section of the drives off.
2. Lock the motor shaft.

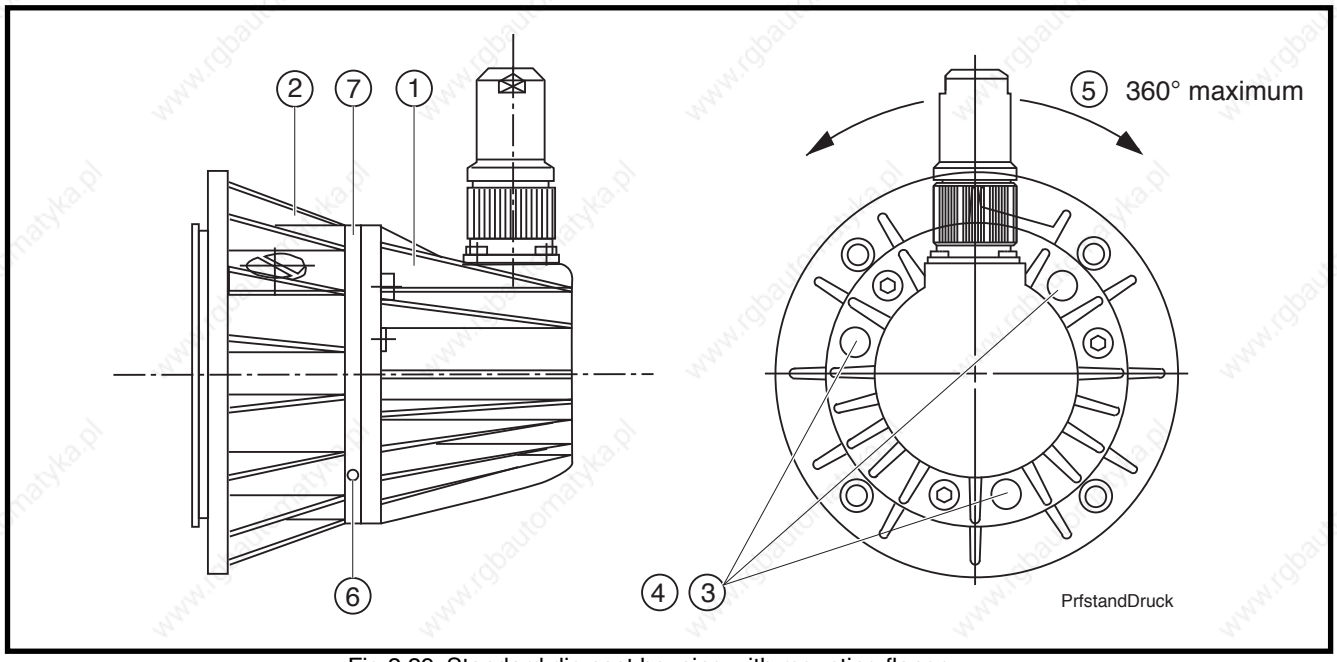


Fig 2.29: Standard die cast housing with mounting flange

3. Remove screw covers (3).
4. Release the allen screws (4) with one-half a turn.
5. Set the desired reference point by turning the encoder housing (1) with respect to the mounting flange (2). The radial drill hole (6), diameter 4 mm, in the plastic flange (7), can be used to assist this procedure. The encoder housing can be turned 360° in both directions. This changes the position of the encoder connector to the motor (interference contour).
6. Tighten allen screw (4) with 3,6 Nm.
7. Press screw covers (3) back into place.
8. Release motor shaft lock.
9. Switch power section of the drive back on.

2.4.5. Absolute Encoder

The absolute encoder supplies an unequivocal (absolute) position value for every position with a change in position.

These values remain available even after there has been an emergency off or a power failure. This eliminates the need for extensive referencing procedures of the individual axes.

The feedback position value remains available after the machine is switched back on even in the event that the axis of the machine were moved when in a currentless state.

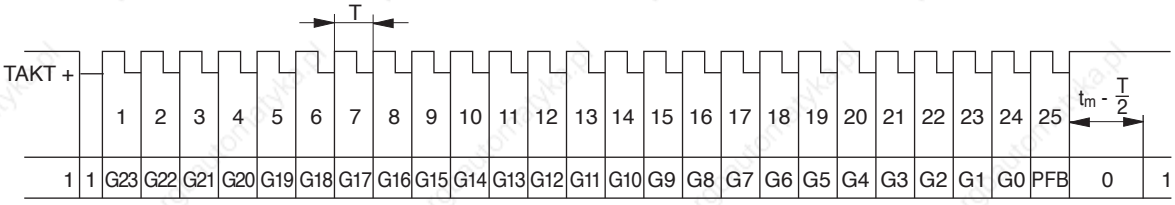
In addition to the absolute position represented in terms of 360°, the absolute encoder also represents a defined number of resolutions in terms of absolute units. This resolution equals 24 bit, gray code, 4096 increments / 360° • 4096 resolutions.

Figure 2.30 lists the designations of the absolute encoder.

Designation	No. of pulses	Supply source in V	MAC…					
			063	071	090	093	112	115
144SG	4096 • 4096	10-32	X					
154SG	4096 • 4096	10-32		X				
164SG	4096 • 4096	10-32			X	X	X	X

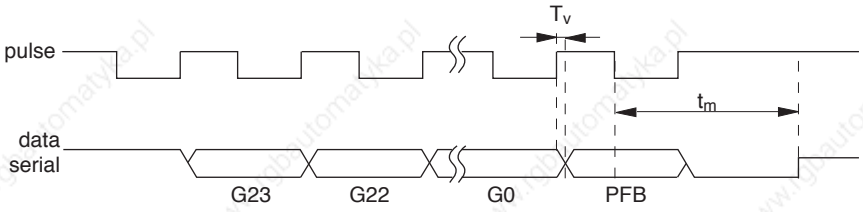
Fig 2.30: Designations of the absolute encoder

Voltage source:	5 V - 32 V DC, protected against polarity reversal
Current consumption:	≤ 3 W
Scan code:	Gray Code
Clockwise counting direction looking onto shaft:	rising
Data transmission:	synchronous, serial
Serial data output:	driver per EIA RS 422, secured against short-circuits
Monoflop time t_m:	15 µs < t_m < 25 µs
Clock frequency:	200 kHz
Minimum phase break:	30 µs
Data format:	24 Bit
Protection category in mounted state:	IP 65



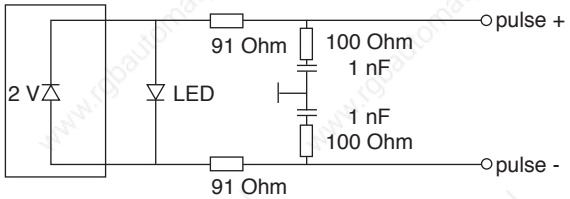
PFB = power failure bit
T = pulse signal duration
t_m = monoflop time

Power failure bit
If the power supply (> 5 V) is interrupted for periods exceeding 100 µs then the encoder information can be false.
The power failure bit (PFB) identifies this error. In the event of a voltage interrupt, the PFB in the serial information is set to logical 1 via a comparator.



Delay time T_v: max 300 ns (clock (+) to data (+) or data (-))

Clock input circuitry



Data output circuitry

As per EIA RS 422, short-circuit proof

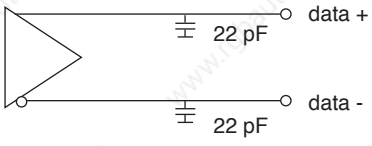


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Fig 2.31: Absolute encoder - technical data

Replacing the encoder

The absolute encoders which INDRAMAT mounts represent measuring systems of the highest quality developed for use on production machinery.

If an encoder should, however, at some point need to be replaced, then an entire replacement unit can be installed on site.

Do not use harsh cleansing agents to clean components.

The encoder may only be operated with a screwed on filler cap (10) (see Figure 2.32) as dirt contamination can cause it to fail.

The tools needed to work on the absolute encoder are:

- Allan key, 90° offset, SW3
- Allan key, straight, SW4
- torque key 0 to 5 Nm
- adjusting tool, part no.: 243 044

The absolute encoder may only be mounted or removed by an electrician or by trained personnel under the supervision of an electrician.

Removing the absolute encoder

Procedure:

1. Switch power section of drive off.
2. Switch control voltage off.
3. Pull out encoder.

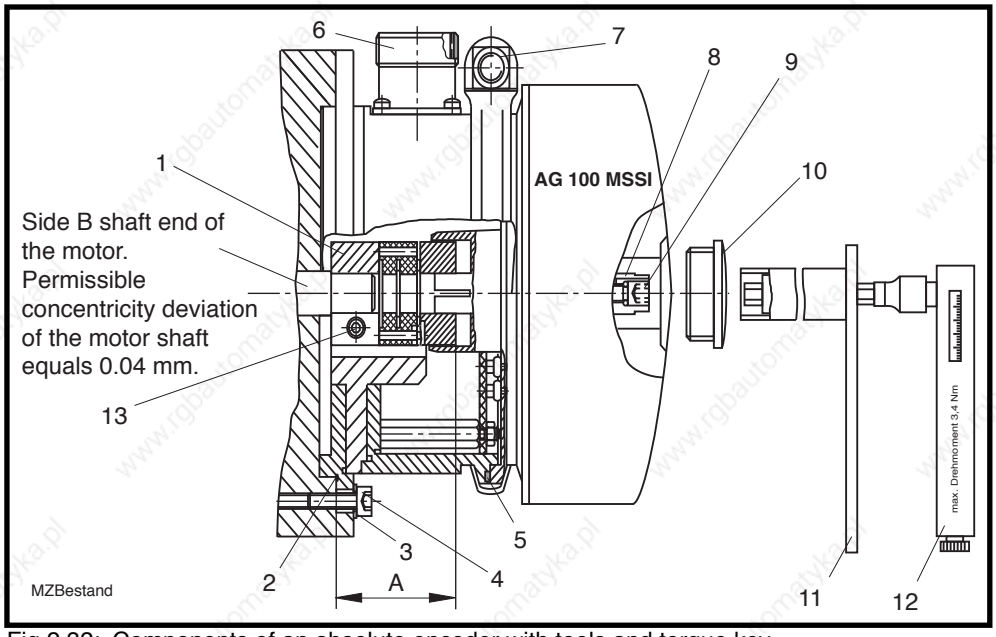

Fig 2.32: Components of an absolute encoder with tools and torque key

4. Remove filler cap (10) (Fig 2.32) out of encoder housing.
5. Place adjusting tool (11) onto the hexagon of the expander (8) and hold in this position.
6. Pull out the expander (9) with the key (SW4) using approximately six turns. **Do not use** the adjusting tool for this task!
7. Release screws (4) with the key (SW4) and pull the mounted encoder unit carefully out.
8. Check the coupling unit for wear and tear.

9. If necessary, pull slotted screw out (13) with key (SW3) and pull out the clamped coupling unit of the motor shaft.

Preparing to mount the absolute encoder

Procedure:

1. Remove the new unit to be mounted from its packaging.
2. Remove the filler cap (10) from the encoder housing.
3. Make sure there is no tension in the expander (8).
4. Check whether the enclosed coupling unit can easily be slid onto the expander (8). If not, put adjusting tool onto hexagon of the expander (8) and hold. Then, using an Allan key (SW4) turn the expander (9) six turns to the left. There should now be no tension in the expander. This is the prerequisite for correctly mounting the encoder unit.

Mounting the absolute encoder

Procedure:

1. Switch power section of drive off.
2. Switch control voltage off.
3. Remove servo motor cover (see Figure 2.33).
4. Remove all grease from side B of the motor.

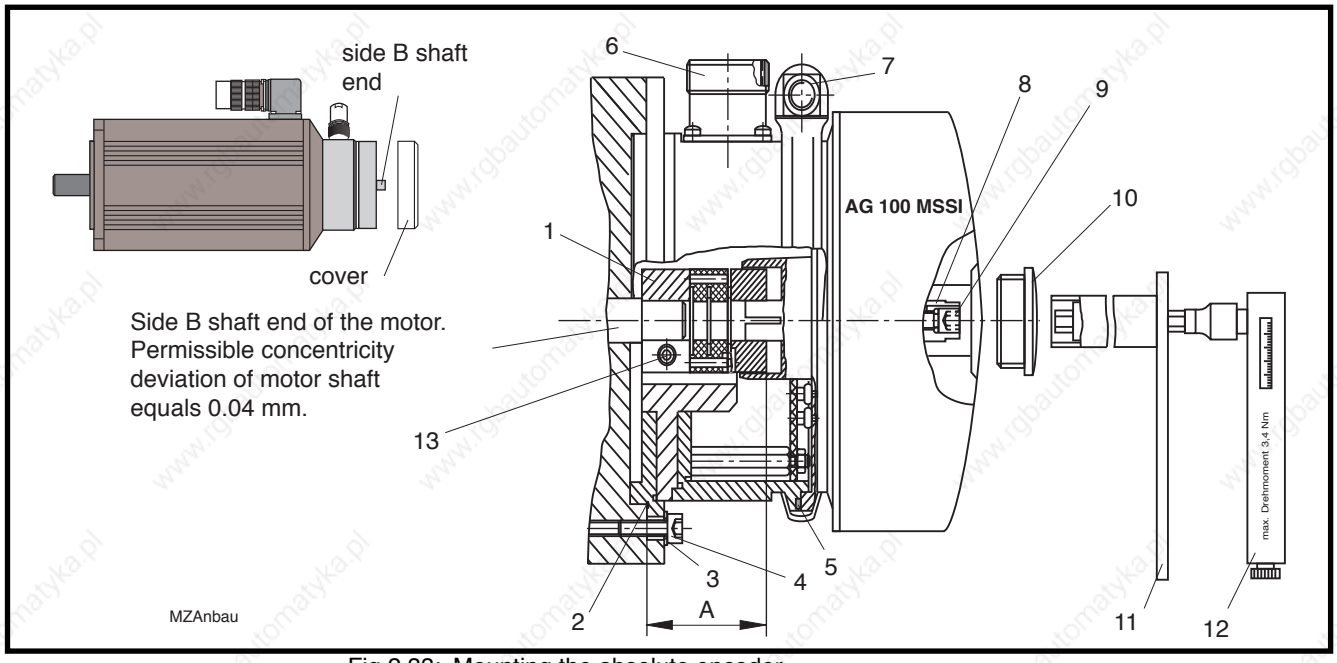

Fig 2.33: Mounting the absolute encoder

5. Push the coupling unit (1) onto side B of the shaft end.
6. Set dimension A (distance flange mounting surface to the end of the coupling unit). Dimension A: MAC 063: 39.7 ± 0.5 mm
   Dimension A: MAC 071 - 115:min. 35.5 mm/max. 37 mm
7. Tighten screw (13) with key (SW3) 3.4 Nm.
8. Check whether O-ring (2) is properly mounted.
9. Place unit carefully onto motor without tipping. Feed expander (8) into coupling unit at the same time.
10. Turn connector (6) so that the angle is set for the respective motor (see dimensional data, sections 3 to 8).
11. Mount unit with screws (4) and washers (3) to the motor.
    Tightening torque: 2.8 Nm for MAC 063
    5.7 Nm for MAC 071 - 115
12. Place adjusting tool (11) onto expander (8) and hold in this position.

13. Tighten expander (9) with torque key (12). Torque: 3.4 Nm.
14. Screw filler cap (10) into encoder housing.
15. Put absolute encoder connector into place.
16. Apply power.
17. Switch drive on and check whether encoder is functional.
18. Run a homing procedure.

Setting the reference point of the absolute encoder

If INDRAMAT MAC servo motors are delivered with absolute encoders mounted, then it is possible to set the reference point in several different ways.

Procedure 1
Set zero point of absolute encoder to the mechanical reference point.

1. Set servo drive to the reference point (in jog mode).
2. Connect absolute encoder to the control unit.
3. Release the connection absolute encoder to motor shaft (adjusting tool, part no.: 243 044).
4. Turn absolute encoder to zero point; evaluate at control unit.
5. Conduct a test run.

Procedure 2
Set the end of the measuring range of the absolute encoder to the mechanical end of the axis.

1. Run the mechanical system into the end position.
2. Connect the absolute encoder to the control unit.
3. Release the connection absolute encoder to motor shaft (adjusting tool, part no.: 243 044).
4. Turn the absolute encoder to relevant end position.
5. Re-establish absolute encoder - motor shaft connection.
6. Conduct a test run.

Procedure 3
Conduct an electronic zero point displacement in the control unit (depends on the control unit used)

1. Absolute encoder remains clamped to the servo drive.
2. The drive is firmly connected to the mechanical system.
3. Run the servo drive to the reference point (in jog mode).
4. The absolute value of the encoder is read in and interpreted as the zero point by the control unit.

2.5. Torque-Speed Characteristics

This section contains explanations about the torque-speed characteristics. These are depicted for each type of motor in sections 3.2, 4.2 through 8.2.

The curves of some of the motors may deviate from the features described here. These deviations are, however, then relevantly documented

What is depicted

The operating curves depict:

- the torque limiting data,
- the speed limiting data and
- the operating curves.

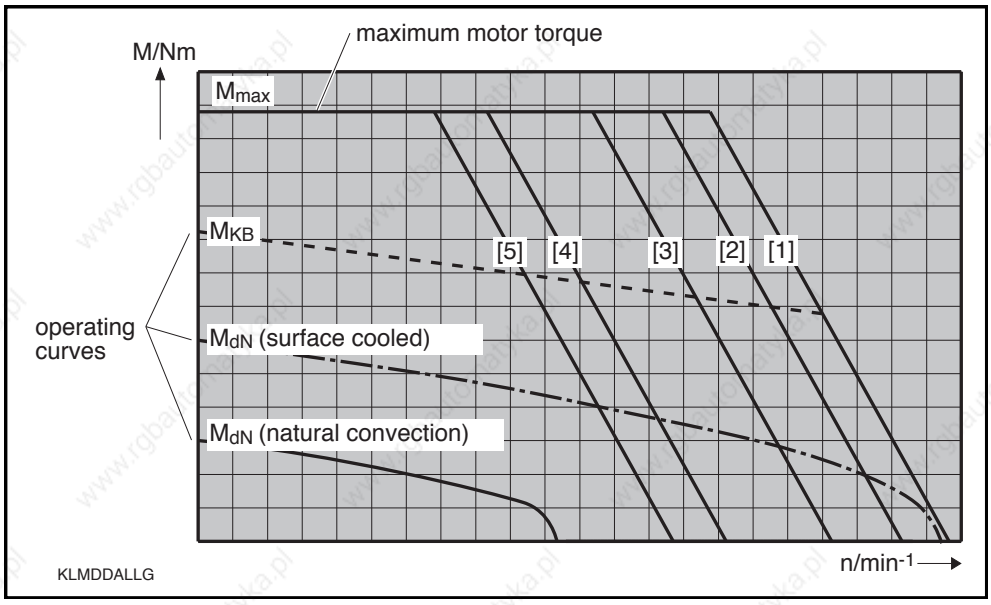

Fig 2.34: The torque-speed characteristics illustrated

Usage

The torque-speed characteristics can be used:

- to record information from the selection documentation,
- to determine the possible maximum usable speed for a special application with known torque requirements and
- to check whether the application remains within the thermal limits of the motor. The effective torque for a critical cycle must be below the S1 continuous operating characteristics curve of the arithmetically averaged speed.

Limiting value for torque

The horizontal line M_{max} depicts the theoretically possible maximum torque of the motor. The drive can limit this maximum torque resulting from the various motor-controller combinations. It is outlined in the selection documentation.

Limiting value for speed

Maximum motor speed is determined by the DC bus voltage produced by the supply source at the drive. Depending upon the DC bus voltage at the drive, maximum torque drops at a breaking point

DC bus with a regulated power supply
In the case of those supply modules with a regulated power supply, the power data of the drive-motor combination are not dependent on the fluctuations of the mains voltage.

DC bus voltage with an unregulated power supply

In the case of those supply modules with an unregulated power supply, the power data of the drive-motor combination are dependent on the fluctuations of the mains voltage. Varying power data are achieved under the following conditions at the mains:

- 10 % overvoltage
- nominal voltage
- 10 % undervoltage

The declining lines are numbered. The following allocations apply:

- [1] -DC bus voltage with a regulated power supply
  (e.g., KDV 4, TVD, KVR, TVR) or an unregulated power supply
  if AC mains input voltage is 10% higher than the rated 3 x 230 volts AC
  (e.g., TVM 2, KDV 1, KDV 2, KDV 3, DSC 3)
- [2] -DC bus voltage with an unregulated power supply connected to
  a three-phase mains rated at 3 x AC 230 V
  (e.g., TVM 2, KDV 1, KDV 2, KDV 3, DSC 3)
- [3] -DC bus voltage with an unregulated power supply connected to
  three-phase mains rated at 3 x AC 230 V with 10% undervoltage
  (e.g., TVM 2, KDV 1, KDV 2, KDV 3, DSC 3)

Furthermore, the speed could be limited by the tacho voltage of the tacho generator.

Allocate the curves determined by the tacho voltage of the tacho generator as follows:

- [4] -tacho generator with 3 V/1000 min^{-1} tacho voltage
- [5] -tacho generator with 6 V/1000 min^{-1} tacho voltage
- [6] -tacho generator with 1.5 V/1000 min^{-1} tacho voltage

Operating curves

The operating curves depict the permissible continuous torque M_{dN} (operating mode S1) and the intermittent operating torque M_{KB} (operating mode S6 per DIN VDE 0530; 7/91 edition).

The following allocations apply:

——— S1-continuous curve of the motor with natural convection

– · – · – S1-continuous curve of a motor with surface cooling

- - - - - - S6-intermittent operating curve:
at an ON time of 25 % of the motor with natural convection or with the ON time indicated in the curve with surface cooling. Maximum duty cycle time is indicated in Figure 2.35.

Motor series MAC …	Maximum duty cycle time
063	10 min.
071, 090, 093, 112, 115	15 min.

Fig 2.35: Maximum duty cycle time with intermittent operations

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3. MAC 063

3.1. Technical Data

Designation	Symbol	Unit	Motor type MAC …			
			063 A - • - ES	063 B - • - GS	063 C - • - MS	063 D - • - JS
Nominal motor speed [1]	n	min^{-1}	3500	3500	3500	3500
Continuous torque at standstill [2]	M_{dN}	Nm	0.8 (1.0) [5]	1.5 (1.7) [5]	2.1(2.7) [5]	2.7 (3.5) [5]
Continuous current at standstill	I_{dN}	A	2.2 (2.7) [5]	3.6 (4.0) [5]	4.1(5.3) [5]	5.1 (6.6) [5]
Rotor moment of inertia [3]	J_M	kgm^2	2.4×10^{-4}	3.2×10^{-4}	4.0×10^{-4}	4.8×10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.370	0.42	0.51	0.53
Windings resistance at 20 °C	R_A	Ohm	9.6	4.1	2.8	1.9
Windings inductance	L_A	mH	9.1	3.9	3.2	2.5
Maximum peak of pulse current	I_{peak}	A	12	19	22	27
Thermal time constant	T_{th}	min	30 (15) [5]	30 (15) [5]	30 (15) [5]	30 (15) [5]
Mass [4]	m_M	kg	3.2	3.9	4.6	5.3
			063 A - • - RS	063 B - • - JS	063 C - • - HS	063 D - • - FS
Nominal motor speed [1]	n	min^{-1}	6000	6000	6000	6000
Continuous torque at standstill [2]	M_{dN}	Nm	0.8 (1.0) [5]	1.5 (1.7) [5]	2.1(2.7) [5]	2.7 (3.5) [5]
Continuous current at standstill	I_{dN}	A	3.5 (4.4) [5]	5.8 (6.6) [5]	6.8 (8.7) [5]	8.4 (11.0) [5]
Rotor moment of inertia [3]	J_M	kgm^2	2.4×10^{-4}	3.2×10^{-4}	4.0×10^{-4}	4.8×10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.230	0.26	0.31	0.32
Windings resistance at 20 °C	R_A	Ohm	3.7	1.6	1.1	0.7
Windings inductance	L_A	mH	3.5	1.5	1.2	0.9
Maximum peak of pulse current	I_{peak}	A	19	31	36	46
Thermal time constant	T_{th}	min	30 (15) [5]	30 (15) [5]	30 (15) [5]	30 (15) [5]
Mass [4]	m_M	kg	3.2	3.9	4.6	5.3

[1] The usable motor speed is determined by the drive used.
Only those usable speeds n_{max} found in the selection lists of the motor-drive combinations are binding.
[2] With 60K overtemperature at the motor housing.
Continuous torque can be limited by the drive. See selection data.
[3] With tacho-generator, without holding brake
[4] With tacho-generator, without holding brake, without blower.
[5] Parenthetical values apply to versions with surface cooling.

Fig 3.1: Type-dependent motor data

Designation	Symbol	Unit	Data
Permissible ambient temperature	T_{um}	°C	0 ... + 45
Permissible storage and transport temperature	T_L	°C	-20 … +80
Maximum installation elevation		m	1000 meters above sea level
Protection category			IP 65 [1]
Insulation classification			F
Housing coat			Black prime coat (RAL 9005)
Voltage constant of the tacho-generator	C_w	Vs/rad V/min^{-1}	0,0143 1.5/1000

[1] Except for the shaft leadthrough in drive shafts, without sealing ring. Protection category is then IP 50.

Fig 3.2: General data MAC 063

Designation	Symbol	Unit	Data holding brake
Principle of action			electrically-actuated release
Holding torque	M_H	Nm	3.0
Nominal voltage	U_N	V	DC 24 ± 10%
Nominal current	I_N	A	0.6
Moment of inertia	J_B	kgm^2	0.38×10^{-4}
Release delay	t_L	ms	30
Clamping delay	t_K	ms	15
Mass	m_B	kg	0.55

Fig 3.3: Technical data - holding brake

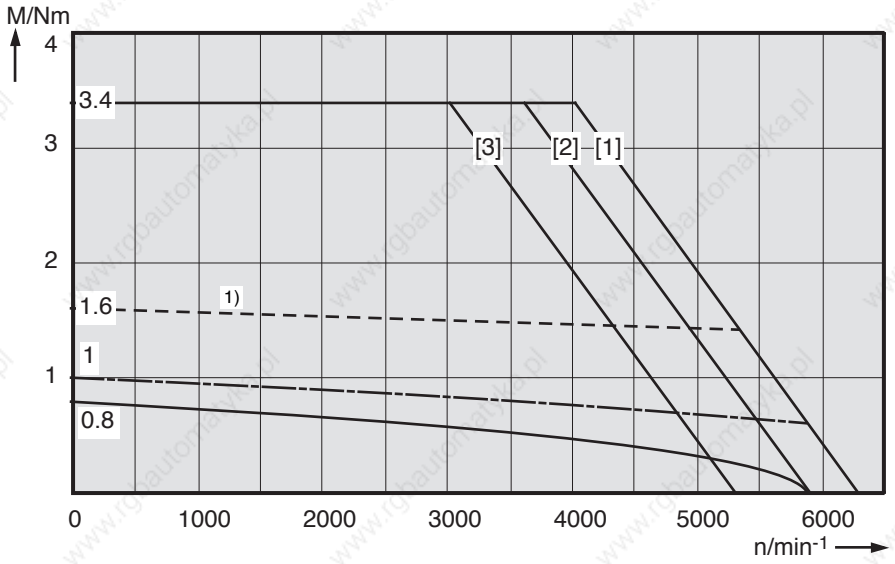
Designation	Symbol	Unit	Data surface cooling	
			Axial cooling	Radial cooling
Power consumption	S_N	VA	20/18	16/14
Nominal voltage	U_N	V	AC 230 or 115 [1]	AC 230 or 115 [1]
Frequency	f	Hz	50/60	50/60
Mass	m_L	kg	approx. 1.1 [2]	approx. 1.0 [2]
Protection category blower unit			IP 24	IP 24
Protection category blower motor			IP 44	IP 44

[1] 115 V special design
[2] Blower shroudshroud for motor with tacho feedback.

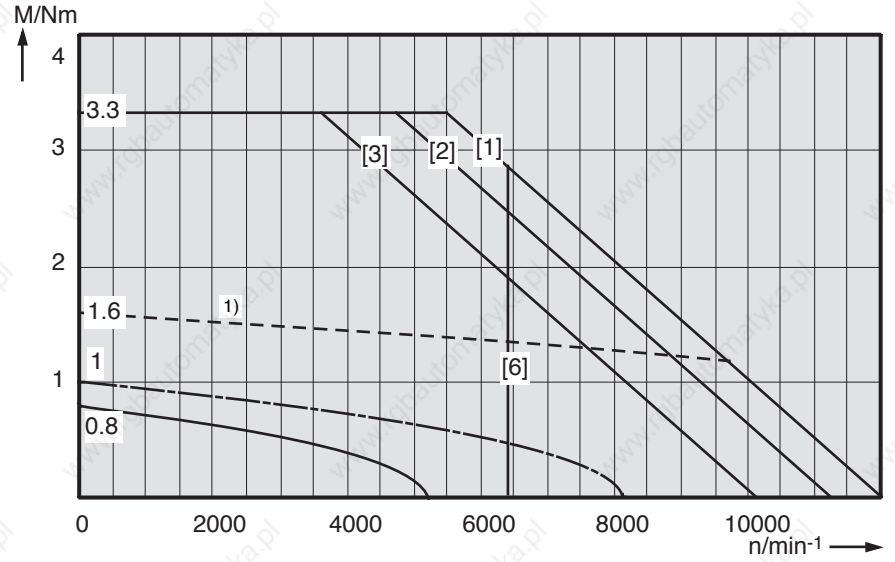
Fig 3.4: Technical data - surface cooling

3.2. Torque-Speed Characteristics

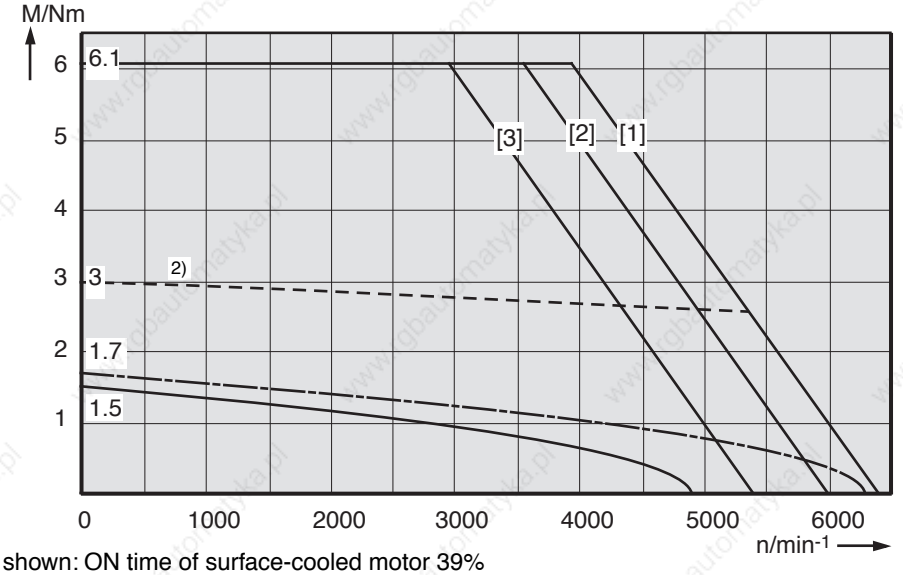
MDD 063 A - • - ES
3500 min^{-1}



MDD 063 A - • - RS
6000 min^{-1}



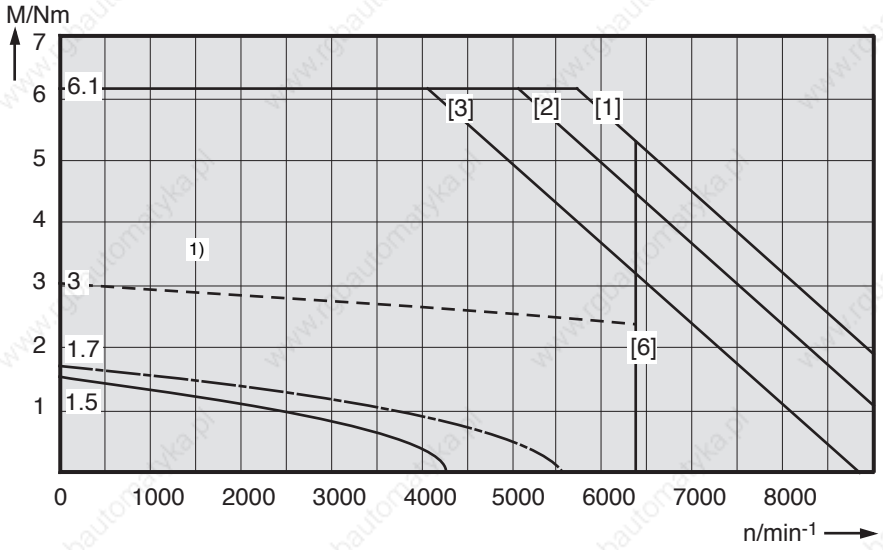
MDD 063 B - • - GS
3500 min^{-1}



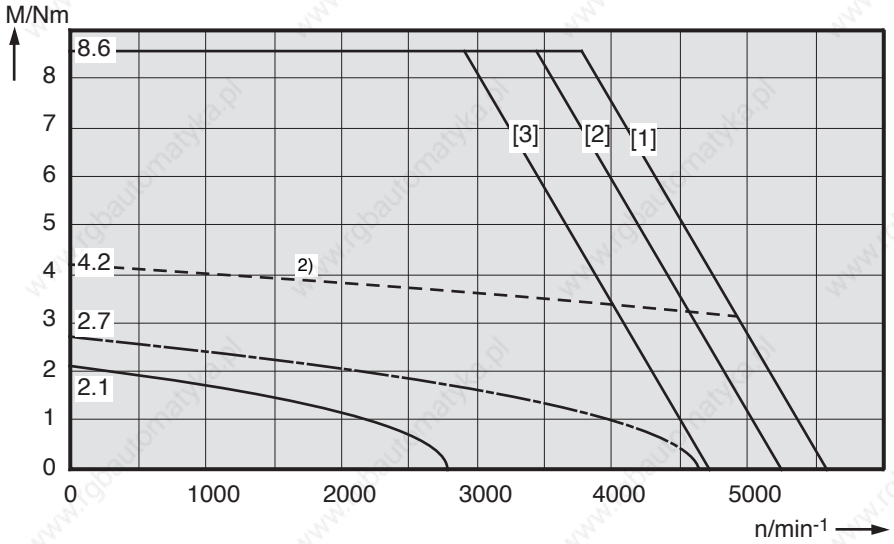
1) shown: ON time of surface-cooled motor 39%
2) shown: ON time of surface-cooled motor 32%

Fig 3.5: Torque-speed Characteristics MAC 063

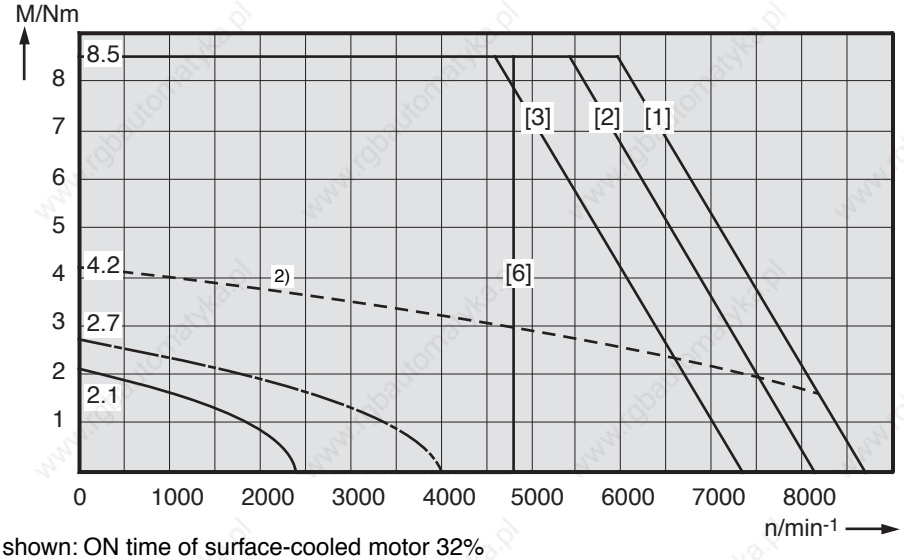
MDD 063 B - • - JS
6000 min^{-1}



MDD 063 C - • - MS
3500 min^{-1}



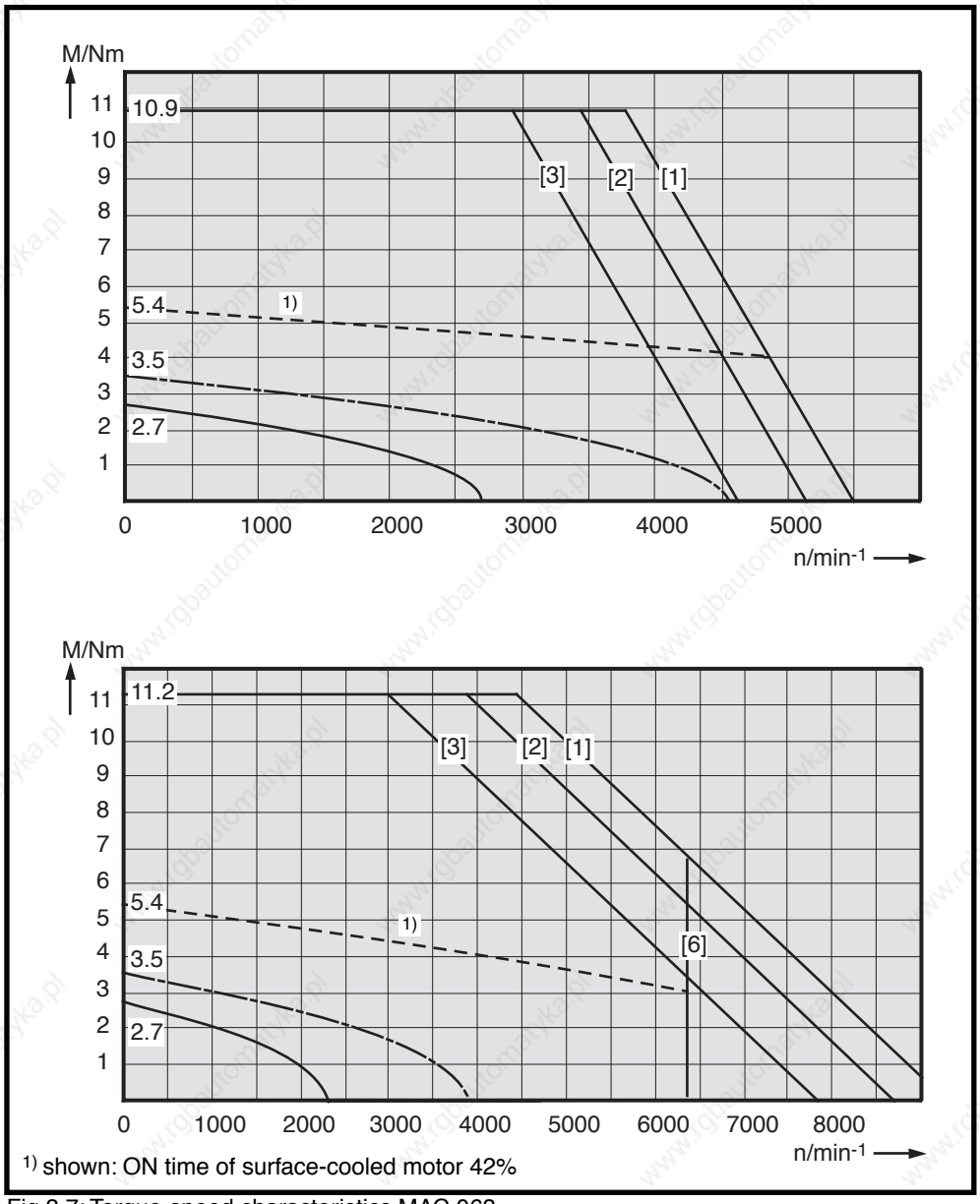
MDD 063 C - • - HS
6000 min^{-1}



1) shown: ON time of surface-cooled motor 32%
2) shown: ON time of surface-cooled motor 41%

Fig 3.6: Torque-speed characteristics MAC 063

MDD 063 D - • - JS
3500 min^{-1}



MDD 063 D - • - FS
6000 min^{-1}

Fig 3.7: Torque-speed characteristics MAC 063

3.3. Shaft Load Capacity

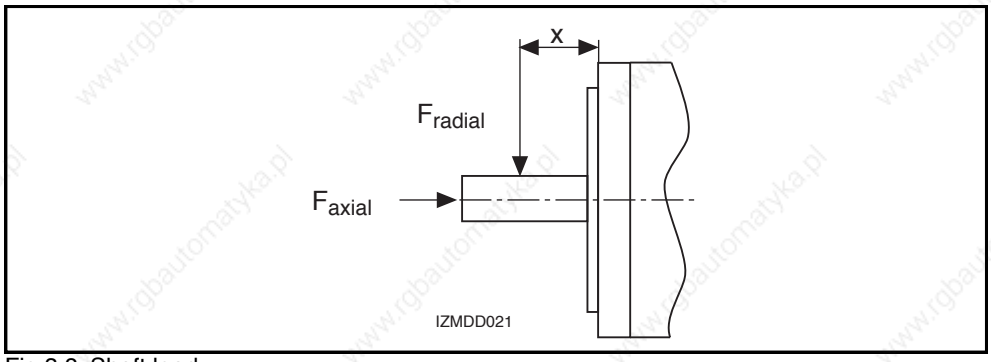


Fig 3.8: Shaft load

Permissible radial force
F_{radial}

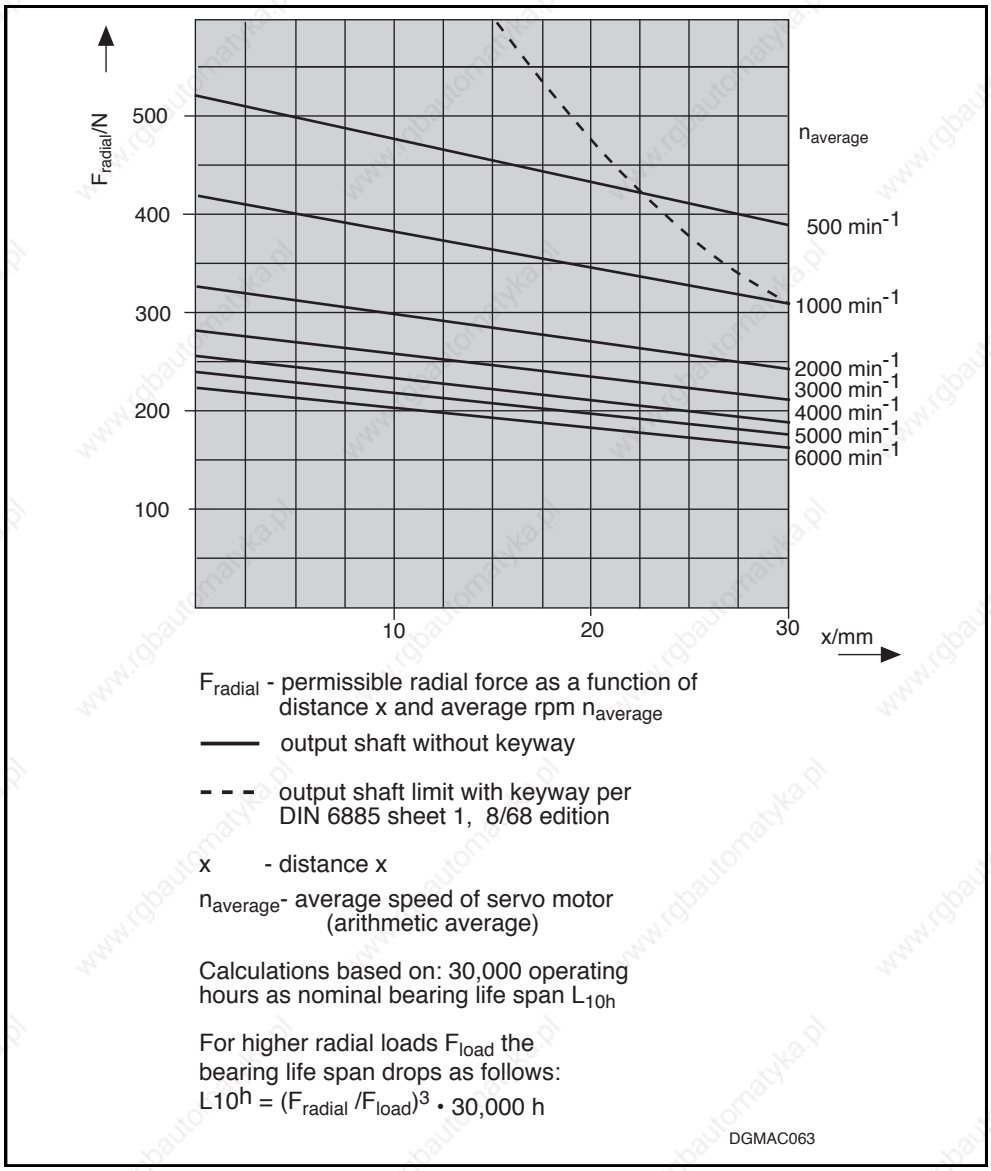


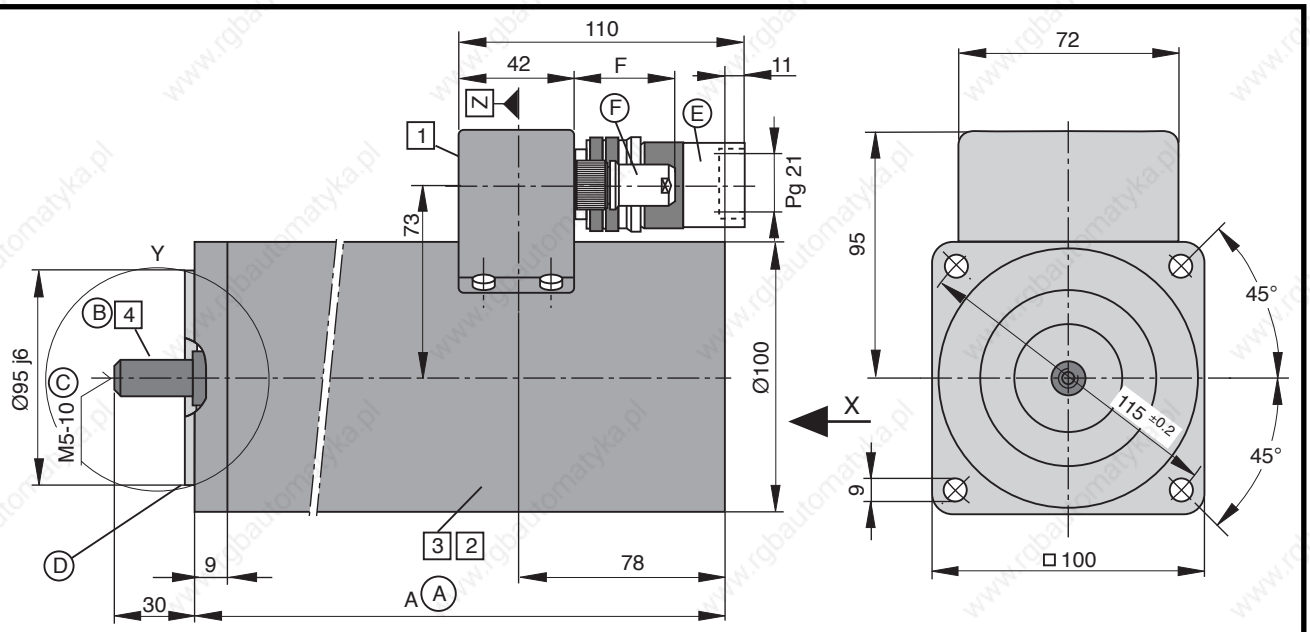
Fig 3.9: Permissible radial force

Permissible axial force
F_{axial}

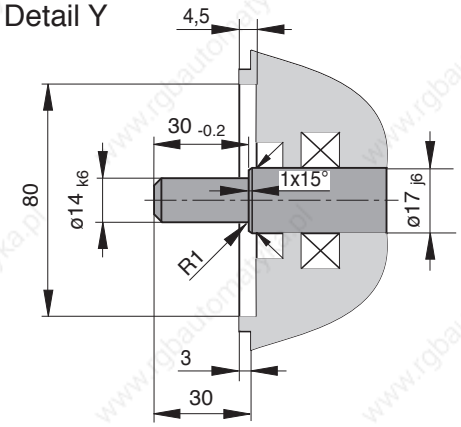
$$F_{axial} = 0.57 \cdot F_{radial}$$

F_{axial} - Permissible axial force
F_{radial} - Permissible radial force

3.4. Dimensional Data - Natural Convection



Detail Y



Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M5-10 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 1Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (drill hole in flange)

Ⓐ **Dimensional table Dim. A**

Size \ Dim.	A[1)]
MAC 063 A	155
MAC 063 B	170
MAC 063 C	185
MAC 063 D	200

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓔ **Motor power connector**
INS 108 must be ordered separately.

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302	56
	INS 102	58

MB063-0/1

Fig 3.10: Dimensional data - MAC 063 (natural convection)

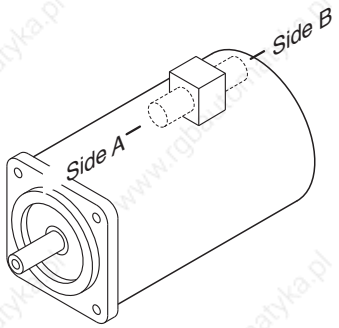
Available options

1 **Power connection**

The output direction of the eletrical power connector is selected at the time the order is placed. Possible output directions are:

- to side A
- to side B

The drawing depicts side B as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.



2 **Motor version**

- Tachofeedback and second shaft end

View X:

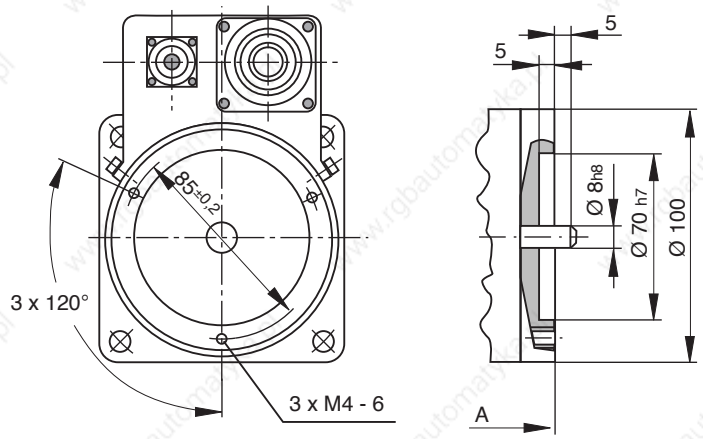


Table	Dim. A
MAC 063 A	162.5
MAC 063 B	177.5
MAC 063 C	192.5
MAC 063 D	207.5

- Tachofeedback and mounted incremental encoder

View X:

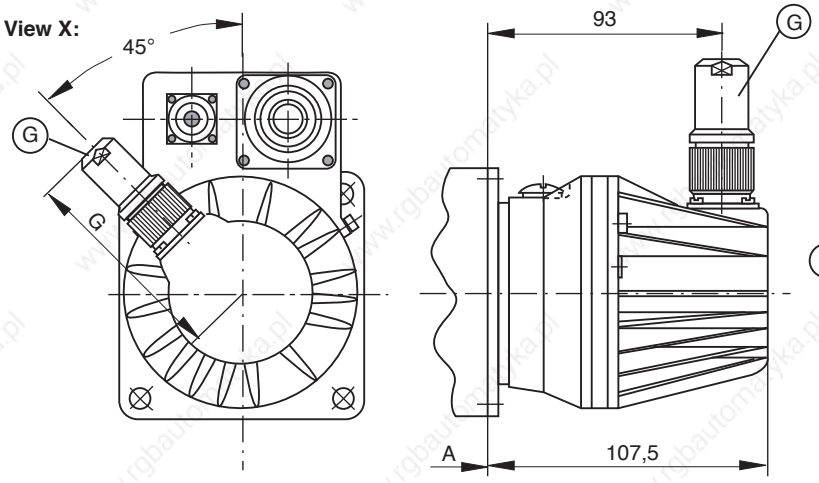


Table	Dim. A
MAC 063 A	162.5
MAC 063 B	177.5
MAC 063 C	192.5
MAC 063 D	207.5

(G) Incremental encoder connector
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder
  (see following page)

MB063-0/2

Fig 3.11: Dimensional data - MAC 063 - available options - (natural convection)

Available options

• Tachofeedback and mounted absolute encoder

View X:

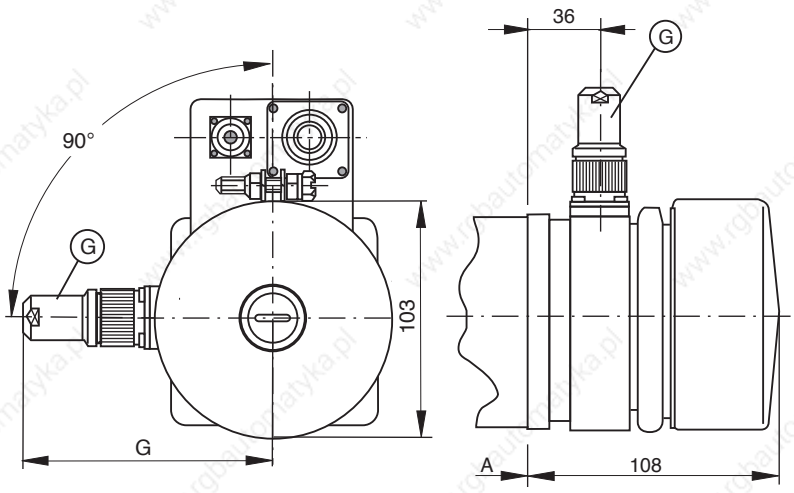


Table	Dim. A
MAC 063 A	162.5
MAC 063 B	177.5
MAC 063 C	192.5
MAC 063 D	207.5

Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104 106
angle conn.	INS 322	102

3 Blocking brake

• without blocking brake
Dim. A retained
• Standard blocking brake: 3 Nm

Table for blocking brake

Dim. / Size	Vers. 2 A	Vers. 3 & 4 A
MAC 063 A	180	187.5
MAC 063 B	195	202.5
MAC 063 C	210	217.5
MAC 063 D	225	232.5

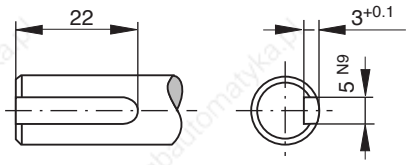
Vers. 2 =
Motor with tachofeedback

Vers. 3 =
Motor with tachofeedback and second shaft end

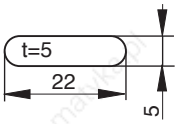
Vers. 4 =
Motor with tachofeedback and mounted encoder

4 Output shaft

• plain shaft (recommended type)
• with keyway per DIN 6885 sh. 1, 8/68 edition
(Note! balanced with entire key.)



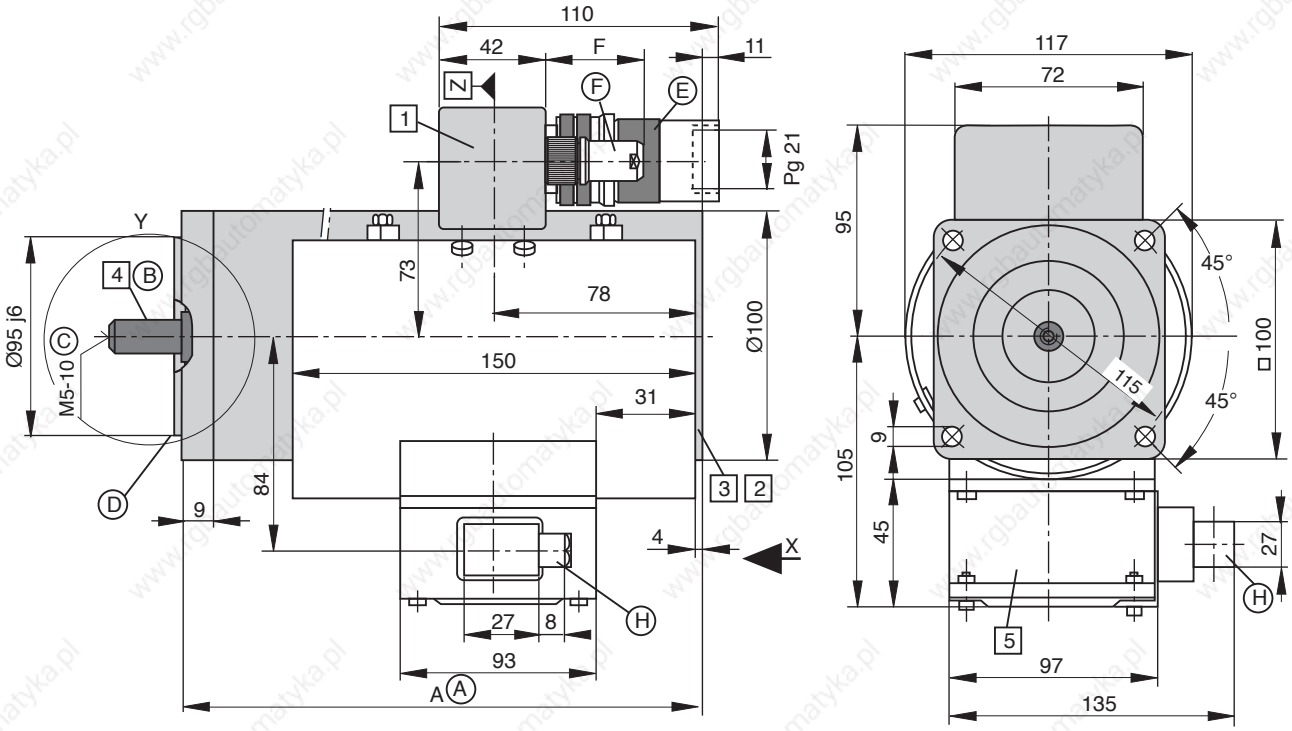
Matching key: DIN 6885-A 5 x 5 x 22
Must be ordered separately.

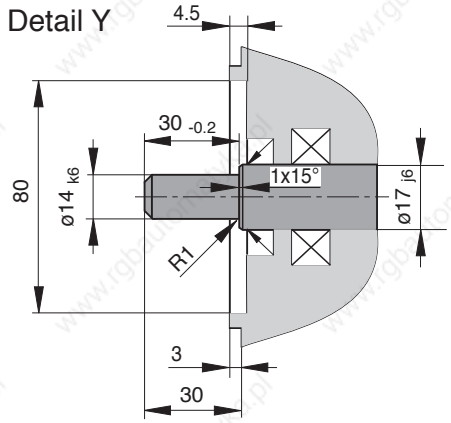


MB063-0/3

Fig 3.12: Dimensional data - MAC 063 - available options - (natural convection)

3.5. Dimensional Data - Radial Cooling





Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M5-10 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the thread of the center spigot: 1Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)

Ⓔ **Motor power connector**
INS 108 must be ordered separately.

Ⓐ **Dimensional table Dim. A**

Size \ Dim.	A[1)]
MAC 063 B	170
MAC 063 C	185
MAC 063 D	200

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302	56
	INS 102	58

Ⓗ **Blower connector: INS 195**
Must be ordered separately.

MB063-1/1

Fig 3.13: Dimensional data - MAC 063 (radial cooling)

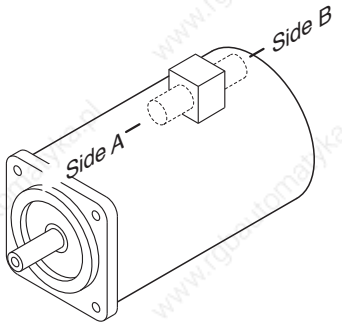
Available options

1 Power connection

The output direction of the eletrical power connector is selected at the time the order is placed. Possible output directions are:

- to side A
- to side B

The drawing depicts side B as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.



2 Motor version

- Tachofeedback and second shaft end

View X:

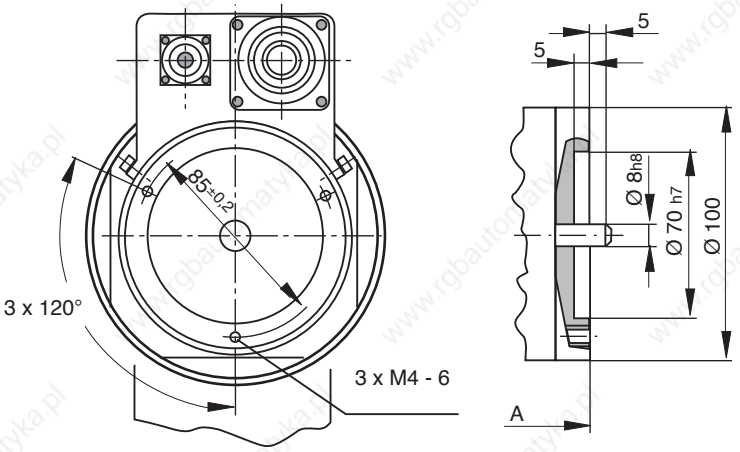
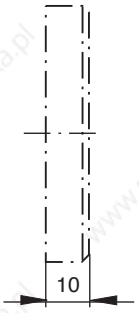


Table	Dim. A
MAC 063 B	177.5
MAC 063 C	192.5
MAC 063 D	207.5



Cover mounted at delivery.

- Tachofeedback and mounted incremental encoder

View X:

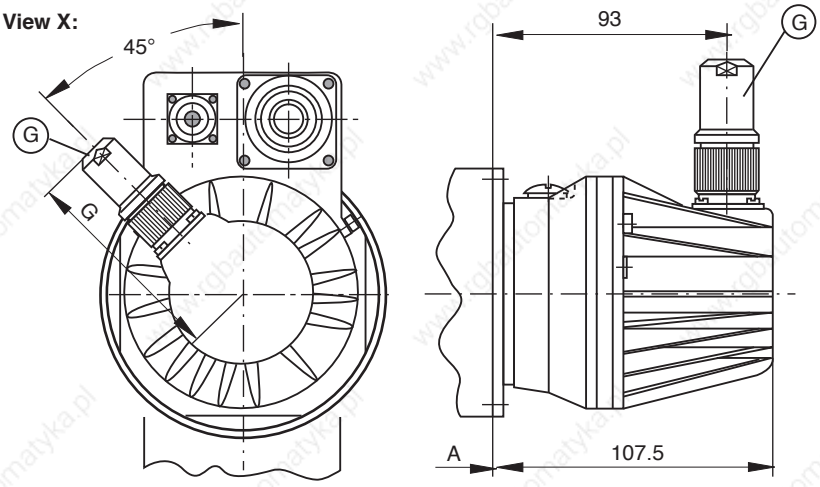


Table	Dim. A
MAC 063 B	177.5
MAC 063 C	192.5
MAC 063 D	207.5

(G) Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder (see following page)

MB063-1/2

Fig 3.14: Dimensional data - MAC 063 - available options - (radial cooling)

Available options

• Tachofeedback and mounted absolute encoder

View X:

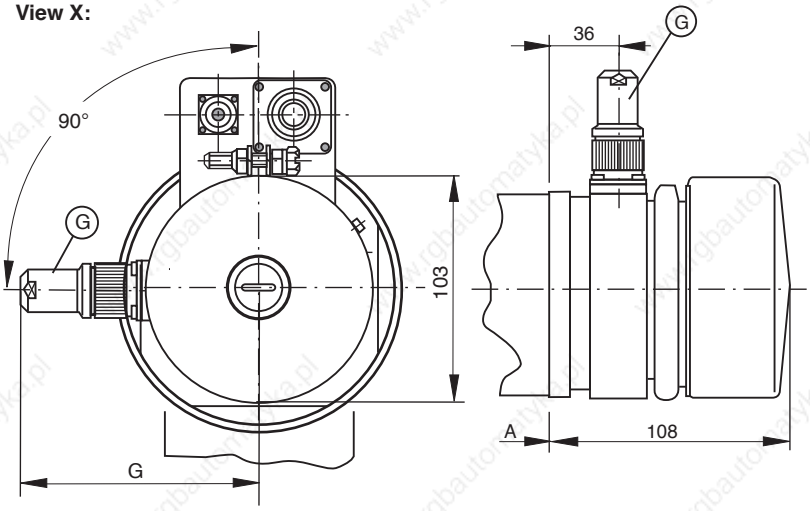


Table	Dim. A
MAC 063 B	177.5
MAC 063 C	192.5
MAC 063 D	207.5

Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104 106
angle conn.	INS 322	102

3 Blocking brake

• without blocking brake
Dim. A retained
• Standard blocking brake: 3 Nm

Table for blocking brake

Dim. / Size	Vers. 2 A	Vers. 3 & 4 A
MAC 063 B	195	202.5
MAC 063 C	210	217.5
MAC 063 D	225	232.5

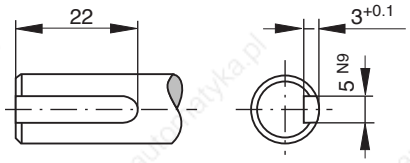
Vers. 2 =
Motor with tachofeedback

Vers. 3 =
Motor with tachofeedback and second shaft end

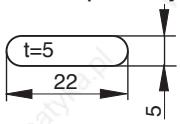
Vers. 4 =
Motor with tachofeedback and mounted encoder

4 Output shaft

• plain shaft (recommended type)
• with keyway per DIN 6885 sh. 1, 8/68 edition
(Note! balanced with entire key.)

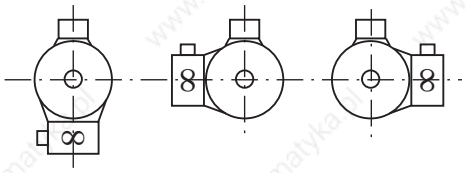


Matching key: DIN 6885-A 5 x 5 x 22
Must be ordered separately.



5 Blower arrangement

Looking towards motor shaft.

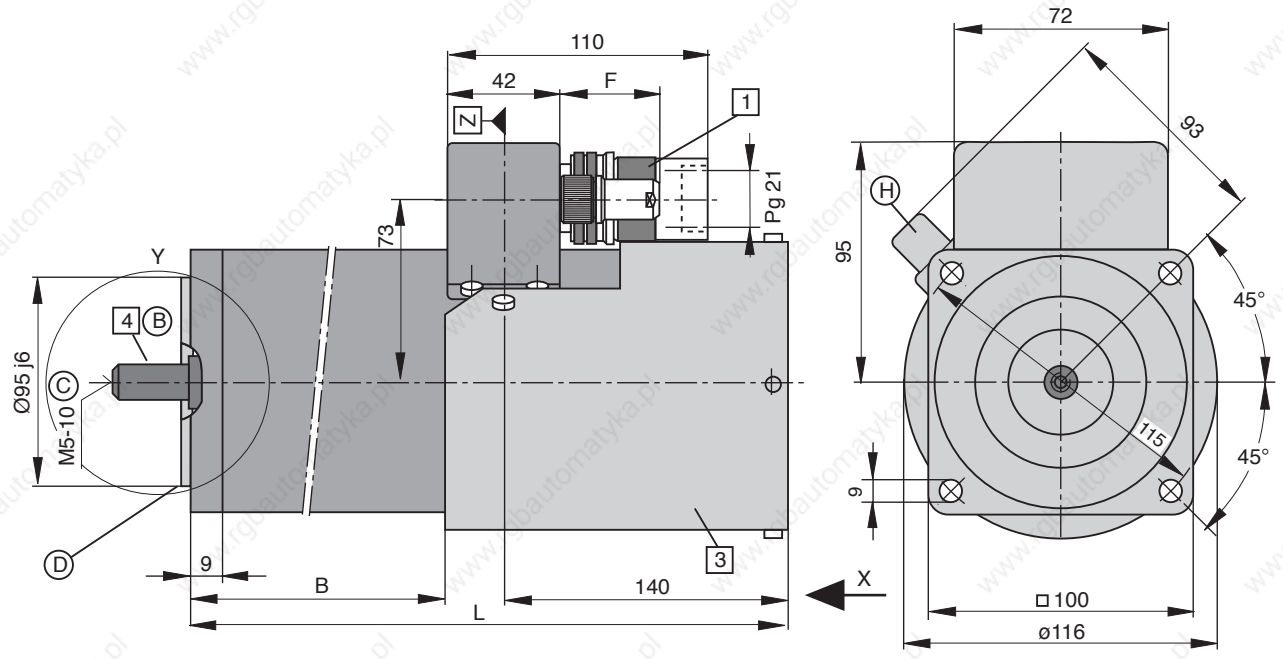


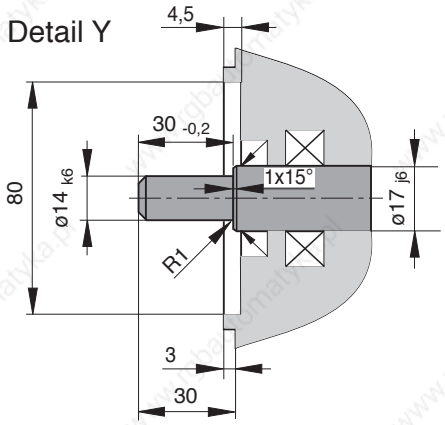
below left right

MB063-1/3

Fig 3.15: Dimensional data - MAC 063 - available options - (radial cooling)

3.6. Dimensional Data - Axial Cooling





Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M5-10 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the thread of the center spigot: 1Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (drill hole in flange)

Ⓔ **Motor power connector**
INS 108 must be ordered separately.

Ⓐ **Dimensional table**

Size \ Dim.	B[1)]	L[1)]
MAC 063 A	57	217
MAC 063 B	72	232
MAC 063 C	87	247
MAC 063 D	102	262

[1)] Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302 INS 102	56 58

Ⓗ **Blower connector: INS 195**
Must be ordered separately.

MB063-1ax/1

Fig 3.16: Dimensional data - MAC 063 (axial cooling)

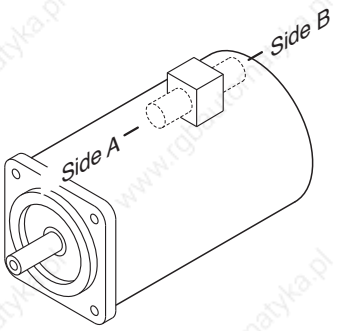
Available options

1 Power connection

The output direction of the eletrical power connector is selected at the time the order is placed. Possible output directions are:

- to side A
- to side B

The drawing depicts side B as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.



3 Blocking brake

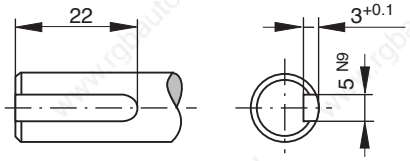
- without brake, dimensions B and L are retained
- Standard blocking brake: 3 Nm

Table with blocking brake 3 Nm holding torque:

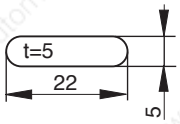
Size \ Dim.	B	L
MAC 063 A	82	242
MAC 063 B	97	257
MAC 063 C	112	272
MAC 063 D	127	287

4 Output shaft

- plain shaft (preferred type)
- with keyway per DIN 6885 sheet 1, 8/68 edition (Note! balanced with entire key.)



Matching key: DIN 6885-A 5 x 5 x 22
Must be ordered separately.



MB063-1ax/2

Fig 3.17: Dimensional data - MAC 063 - available options - (axial cooling)

3.7. Available Options

Type code fields

Example: MAC 063 A-0-RS-4 - C/095-A-0/WI 520LV/S000

1. Motor for analogue drives									MAC
2. Motor size									063
3. Motor length									A, B, C, D
4. Type of cooling:									
natural convection	surface cooling								
	axial		radial						
			blower right		blower below		blower left		
	AC 230 V	AC 115 V	AC 230 V	AC 115 V	AC 230 V	AC 115 V	AC 230 V	AC 115 V	
0	1[1)]	2[1)]	6[3)]	A[3)]	7[3)]	B[3)]	8[3)]	C[3)]	

5. Type of windings

Nominal rpm	Motor length			
	A	B	C	D
3500 min $^{-1}$	ES	GS	MS	JS
6000 min $^{-1}$	RS	JS	HS	FS

6. Motor feedback

Motor type	
with tachofeedback	2
with tachofeedback and second shaft end	3
with tachofeedback and mounted incremental or absolute encoder	4

Tacho voltage	
set to nominal motor speed: 1.5 V/1000 min $^{-1}$	-

Tacho type	
standard	C
increased smooth run quality	F

7. Centering diameter		
for design B05		095
8. Power connection		
connector to side A		A
connector to side B		B
9. Blocking brake		
without blocking brake		0
with standard blocking brake (3 Nm)		1
Mounted encoder	10. Type [2)]	
	Incremental encoder with standard mounting	WI
	Absolute encoder	AM
	11. Encoder code [2)]	
	For available types, see section 2.4 "Motor feedback"	
12. Special types		
Fixed and documented by INDRAMAT with special number (see Drawing no.: 106-0105-4301-XX)		
Does not apply to standard motors.		

1) For type 3 motors (with 2nd shaft end and tachofeedback). Not available with axial surface cooling.

2) Type code fields 10 and 11 do not apply to motor types 2 and 3.

3) not available with motor length A

TLMAC063

Fig 3.18: Type codes - MAC 063

3.8. Special options

Specification of Option	S001	S006	S007
with keyway per DIN 6885, sheet 1	X		X
output shaft with shaft sealing		X	X

Fig 3.19: Special options with a MAC 063

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4. MAC 071

4.1. Technical Data

Designation	Symbol	Unit	Motor type MAC …		
			071 A - • - HS	071 B - • - FS	071 C - • - US
Nominal motor speed [1]	n	min^{-1}	2000	2000	2000
Continuous torque at standstill [2]	M_{dN}	Nm	2.2 (3.3) [5]	4.4 (6.6) [5]	6.6 (9.9) [5]
Continuous current at standstill	I_{dN}	A	2.6 (4.1) [5]	5.0 (7.9) [5]	7.3 (11.8) [5]
Rotor moment of inertia [3]	J_M	kgm^2	5.4×10^{-4}	9.9×10^{-4}	12.9×10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.860	0.880	0.900
Windings resistance at 20 °C	R_A	Ohm	7.6	2.7	1.6
Windings inductance	L_A	mH	42	22	15
Maximum peak of pulse current	I_{peak}	A	13	25	37
Thermal time constant	T_{th}	min	45 (20) [5]	45 (20) [5]	45 (20) [5]
Mass [4]	m_M	kg	6.5	8.8	11
			071 A - • - OS	**071 B - • - TS**	**071 C - • - NS**
Nominal motor speed [1]	n	min^{-1}	3000	3000	3000
Continuous torque at standstill [2]	M_{dN}	Nm	2.2 (3.3) [5]	4.4 (6.6) [5]	6.6 (9.9) [5]
Continuous current at standstill	I_{dN}	A	3.8 (6.0) [5]	7.3 (11.7) [5]	11.0 (17.7) [5]
Rotor moment of inertia [3]	J_M	kgm^2	5.4×10^{-4}	9.9×10^{-4}	12.9×10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.580	0.600	0.600
Windings resistance at 20 °C	R_A	Ohm	3.5	1.24	0.69
Windings inductance	L_A	mH	20	10	7
Maximum peak of pulse current	I_{peak}	A	19	37	55
Thermal time constant	T_{th}	min	45 (20) [5]	45 (20) [5]	45 (20) [5]
Mass [4]	m_M	kg	6.5	8.8	11
			071 A - • - ES	**071 B - • - PS**	**071 C - • - JS**
Nominal motor speed [1]	n	min^{-1}	4000	4000	4000
Continuous torque at standstill [2]	M_{dN}	Nm	2.2 (3.3) [5]	4.4 (6.6) [5]	6.6 (9.9) [5]
Continuous current at standstill	I_{dN}	A	5.0 (7.9) [5]	9.6 (15.3) [5]	15.3 (24.8) [5]
Rotor moment of inertia [3]	J_M	kgm^2	5.4×10^{-4}	9.9×10^{-4}	12.9×10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.440	0.460	0.430
Windings resistance at 20 °C	R_A	Ohm	2.0	0.72	0.35
Windings inductance	L_A	mH	11	5.9	3.5
Maximum peak of pulse current	I_{peak}	A	25	48	77
Thermal time constant	T_{th}	min	45 (20) [5]	45 (20) [5]	45 (20) [5]
Mass [4]	m_M	kg	6.5	8.8	11
			071 A - • - VS	**071 B - • - KS**	**071 C - • - GS**
Nominal motor speed [1]	n	min^{-1}	6000	6000	6000
Continuous torque at standstill [2]	M_{dN}	Nm	2.2 (3.3) [5]	4.4 (6.6) [5]	6.6 (9.9) [5]
Continuous current at standstill	I_{dN}	A	7.3 (11.7) [5]	14.2 (22.3) [5]	22.0 (35.4) [5]
Rotor moment of inertia [3]	J_M	kgm^2	5.4×10^{-4}	9.9×10^{-4}	12.9×10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.300	0.310	0.300
Windings resistance at 20 °C	R_A	Ohm	0.92	0.34	0.17
Windings inductance	L_A	mH	5.1	2.8	1.7
Maximum peak of pulse current	I_{peak}	A	37	71	110
Thermal time constant	T_{th}	min	45 (20) [5]	45 (20) [5]	45 (20) [5]
Mass [4]	m_M	kg	6.5	8.8	11

[1] The usable motor speed is determined by the drive used.
Only those usable speeds n_{max} found in the selection lists of the motor-drive combinations are binding.
[2] With 60K overtemperature at the motor housing.
Continuous torque can be limited by the drive. See selection data.
[3] With tacho-generator, without holding brake
[4] With tacho-generator, without holding brake, without blower.
[5] Parenthetical values apply to versions with surface cooling.

Fig 4.1: Type-dependent motor data

Designation	Symbol	Unit	Data		
Permissible ambient temperature	T_{um}	°C	0 … + 45		
Permissible storage and transport temperature	T_L	°C	-20 … +80		
Maximum installation elevation		m	1000 meters above sea level		
Protection category			IP 65		
Insulation classification			F		
Housing coat			Black prime coat (RAL 9005)		
Voltage constant of the tachogenerator [1]	C_w	Vs/rad V/min^{-1}	0,0143 1.5/1000		0.0286 3/1000

[1] Tacho voltage can be selected application-related.

Fig 4.2: General data MAC 071

Designation	Symbol	Unit	Data holding brake	
			Standard	heavy-duty
Principle of action			electrically-actuated release	
Holding torque	M_H	Nm	3.0	6.5
Nominal voltage	U_N	V	DC 24 ± 10%	
Nominal current	I_N	A	0.6	0.7
Moment of inertia	J_B	kgm^2	0.38 x 10^{-4}	1.06 x 10^{-4}
Release delay	t_L	ms	30	60
Clamping delay	t_K	ms	15	20
Mass	m_B	kg	0.3	0.5

Fig 4.3: Technical data - holding brake

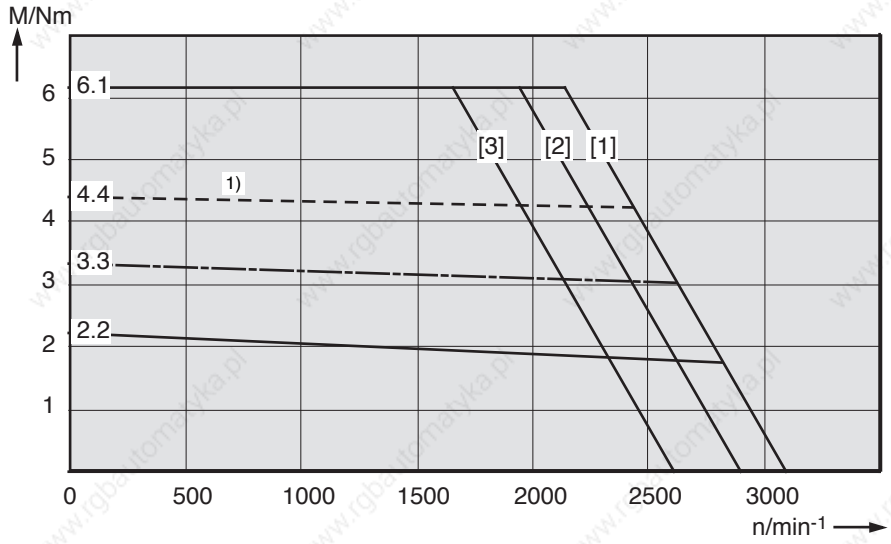
Designation	Symbol	Unit	Axial cooling	Radial cooling
Power consumption	S_N	VA	22/22	22/22
Nominal voltage	U_N	V	AC 230 or 115 [1]	AC 230 or 115 [1]
Frequency	f	Hz	50/60	50/60
Mass	m_L	kg	approx. 0.8 [2]	approx. 0.7 [2]
Protection category blower unit			IP 24	IP 24
Protection category blower motor			IP 44	IP 44

[1] 115 V special design
[2] Blower shroud for motor with tacho feedback.

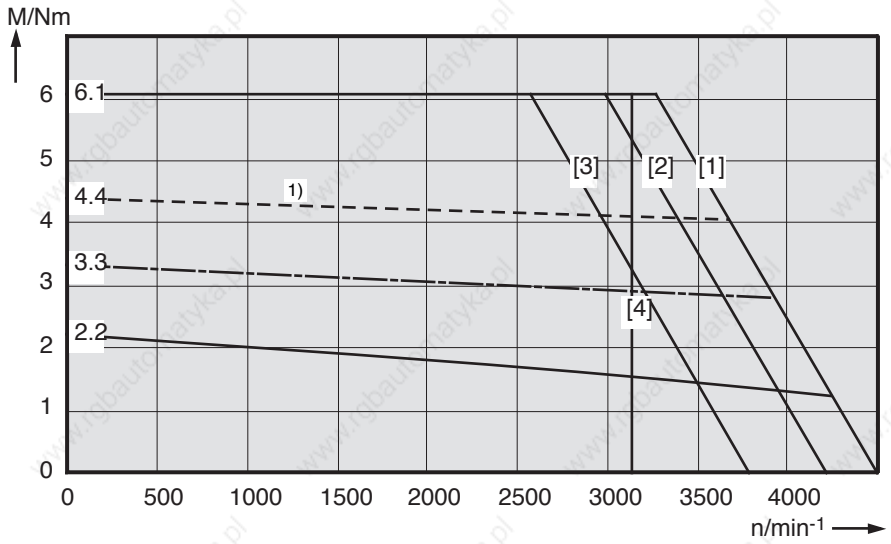
Fig 4.4: Technical data - surface cooling

4.2. Torque-Speed Characteristics

MAC 071 A - • - HS
2000 min^{-1}



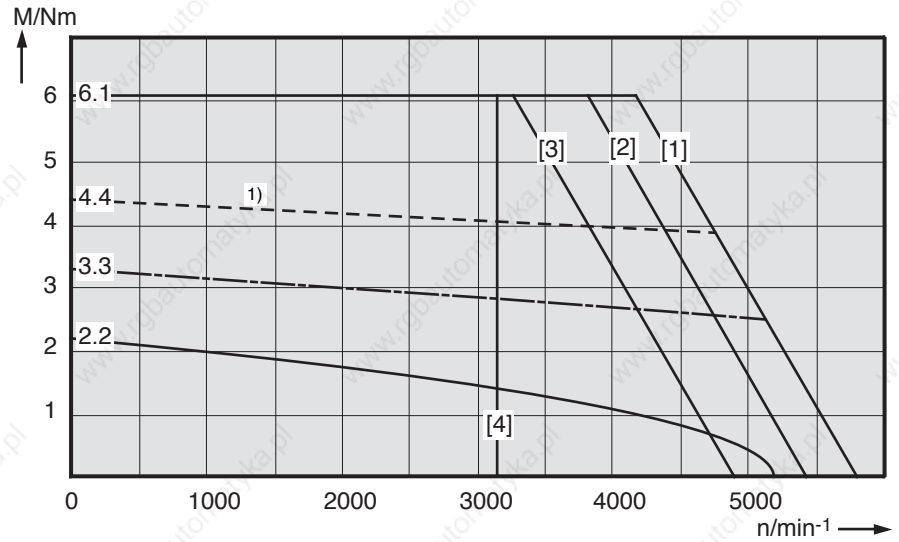
MAC 071 A - • - OS
3000 min^{-1}



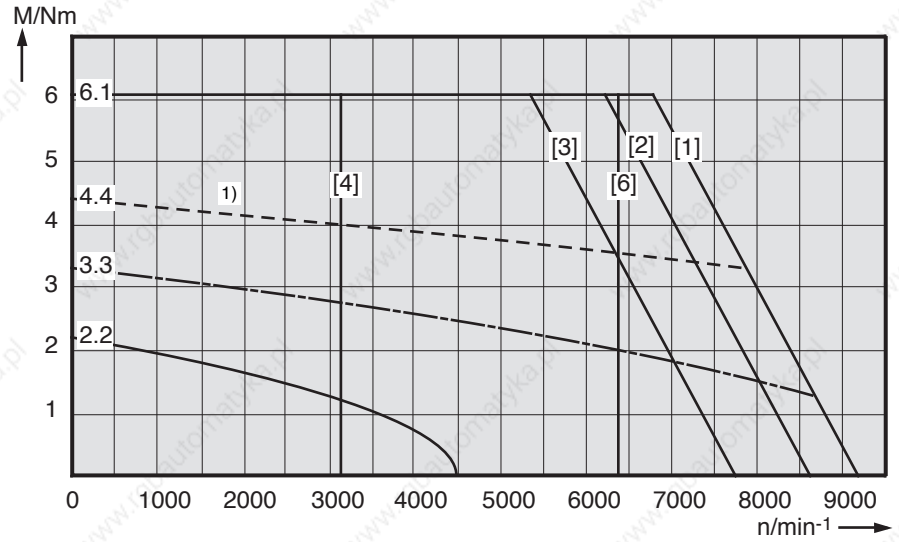
1) shown: ON time of surface-cooled motor 56%

Fig 4.5: Torque-speed characteristics MAC 071

MAC 071 A - • - ES
4000 min^{-1}



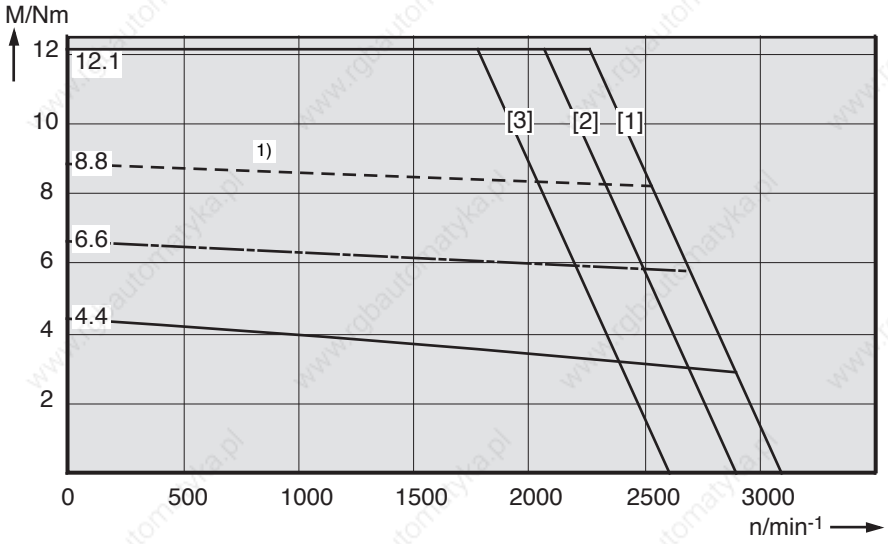
MAC 071 A - • - VS
6000 min^{-1}



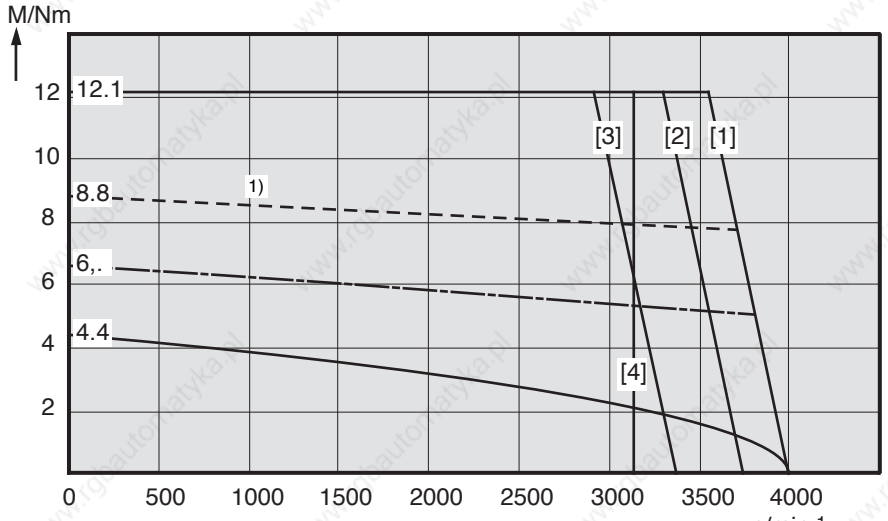
1) shown: ON time of surface-cooled motor 56%

Fig 4.6: Torque-speed characteristics MAC 071

MAC 071 B - • - FS
2000 min^{-1}



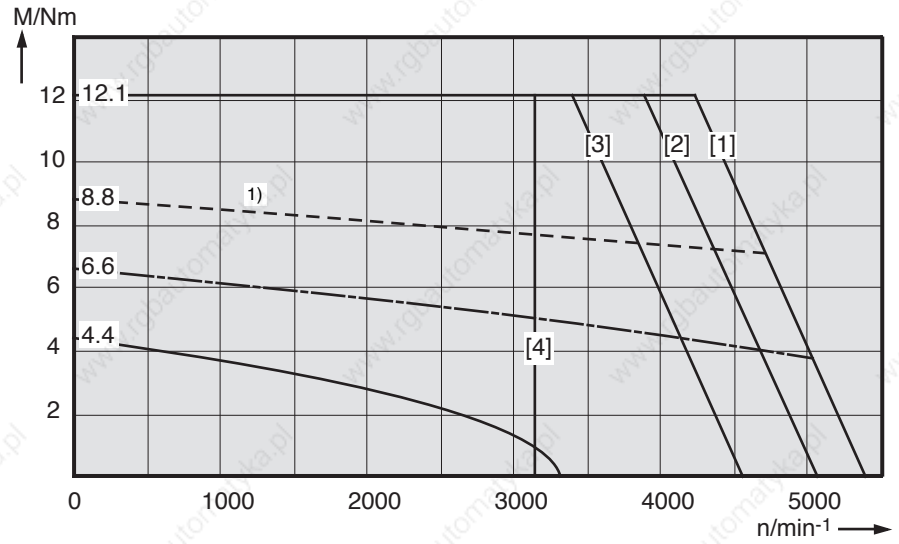
MAC 071 B - • - TS
3000 min^{-1}



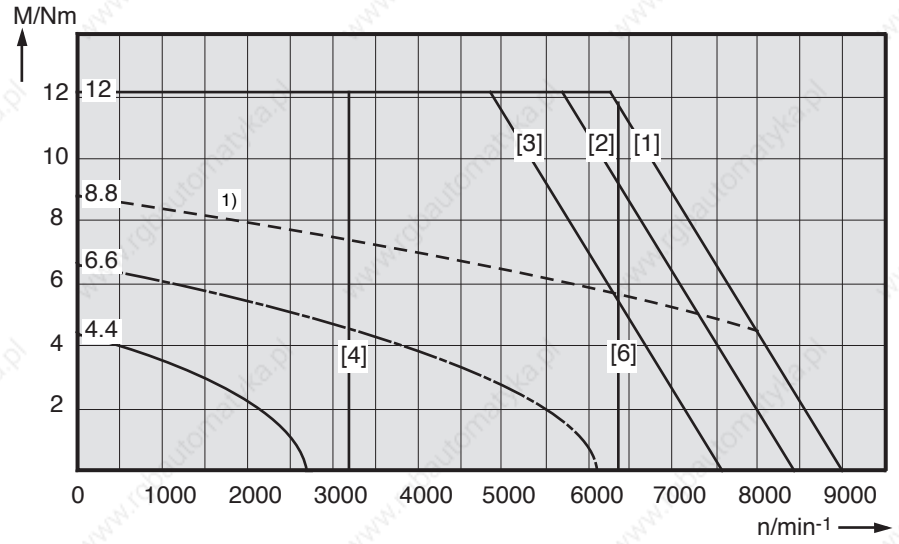
1) shown: ON time of surface-cooled motor 56%

Fig 4.7: Torque-speed characteristics MAC 071

MAC 071 B - • - PS
4000 min^{-1}



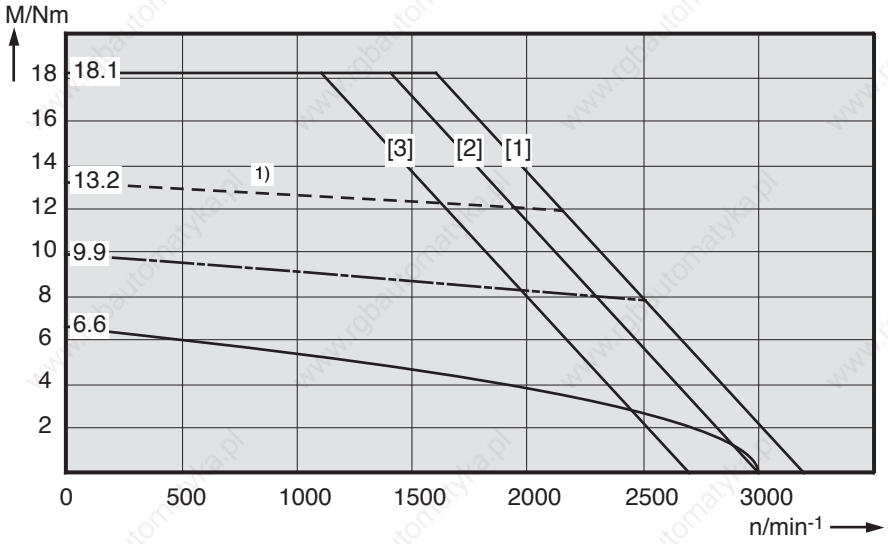
MAC 071 B - • - KS
6000 min^{-1}



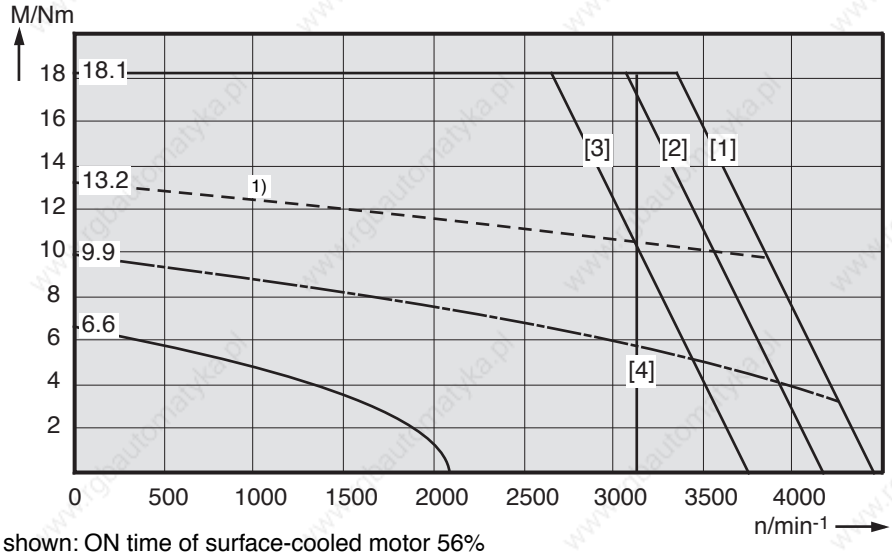
1) shown: ON time of surface-cooled motor 56%

Fig 4.8: Torque-speed characteristics MAC 071

MAC 071 C - • - US
2000 min^{-1}



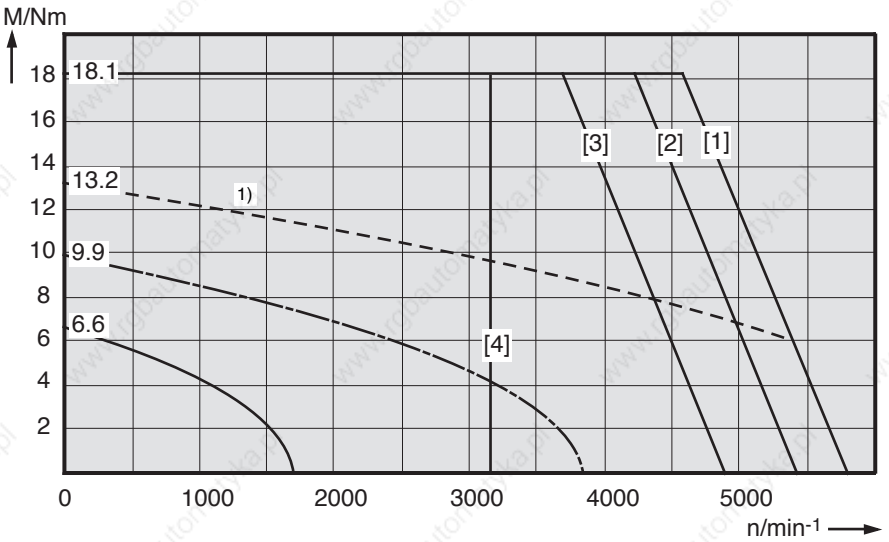
MAC 071 C - • - NS
3000 min^{-1}



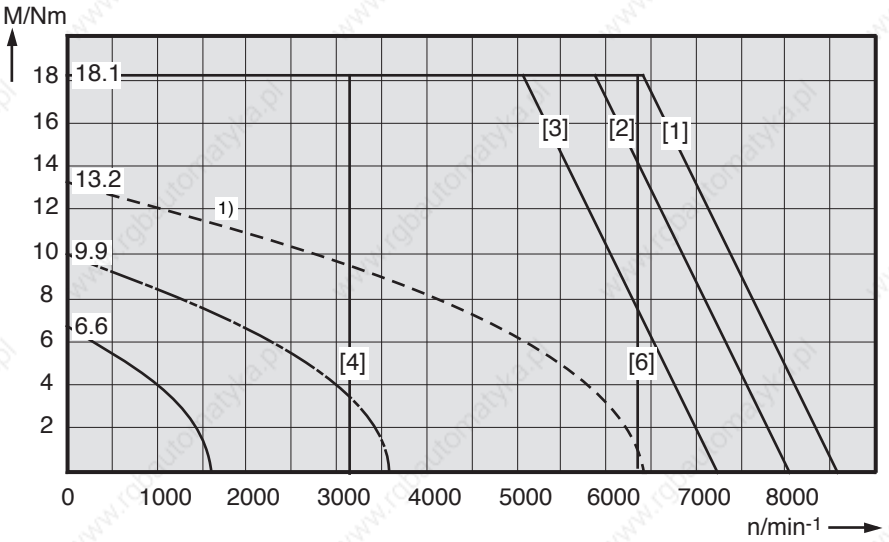
1) shown: ON time of surface-cooled motor 56%

Fig 4.9: Torque-speed characteristics MAC 071

MAC 071 C - • - JS
4000 min^{-1}



MAC 071 C - • - GS
6000 min^{-1}



1) shown: ON time of surface-cooled motor 56%

Fig 4.10: Torque-speed characteristicscharacteristics MAC 071

4.3. Shaft Load Capacity

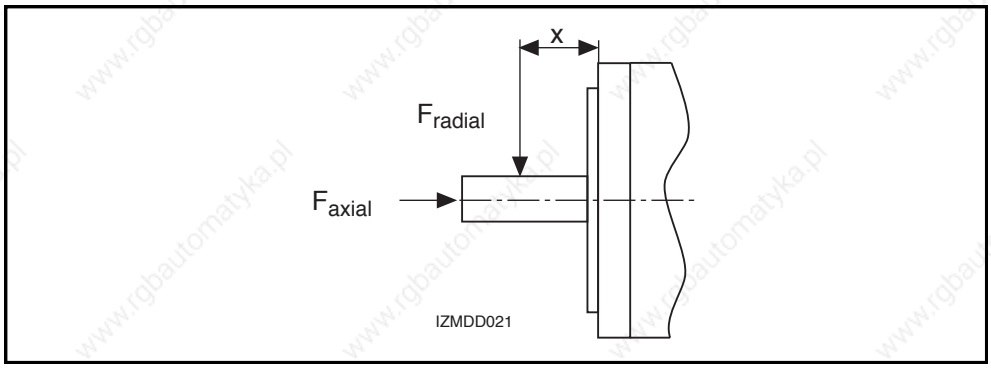


Fig 4.11: Shaft load

Permissible radial force F_{radial}

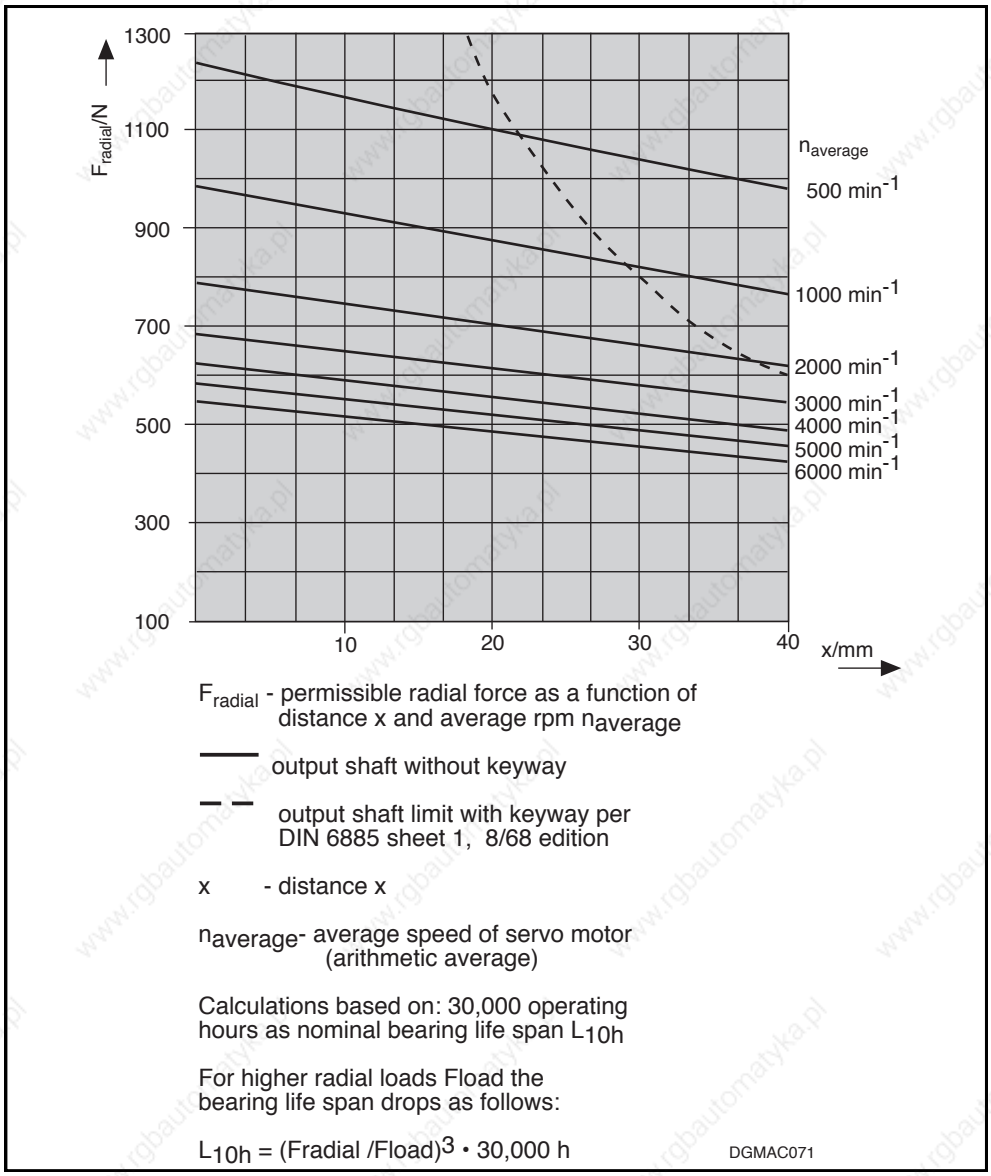


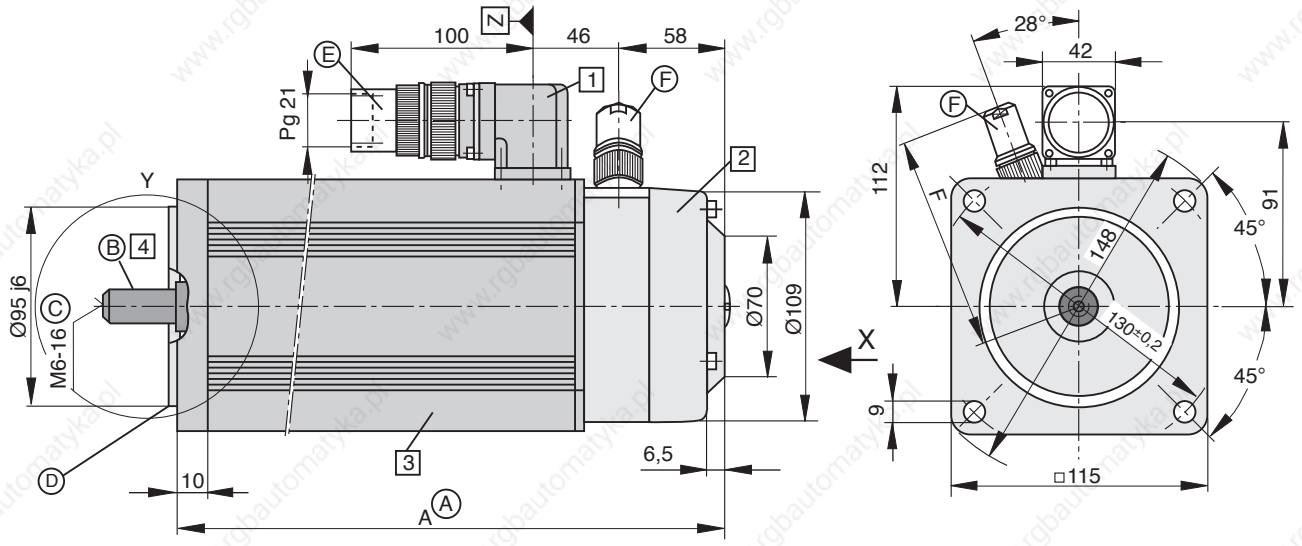
Fig 4.12: Permissible radial force

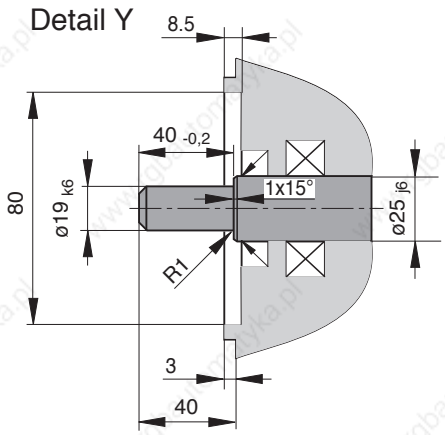
Permissible axial force F_{axial}

F_{axial} = 0.50 • F_{radial}

F_{axial} - Permissible axial force
F_{radial} - Permissible radial force

4.4. Dimensional Data - Natural Convection





Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M6-16 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 2Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)

Ⓔ **Motor power connector**
INS 108 must be ordered separately.

Ⓐ **Dimensional table Dim. A**

Size \ Dim.	A[1)]
MAC 071 A	212
MAC 071 B	252
MAC 071 C	292

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302 INS 102	116 118
angle conn.	INS 352 INS 312	114

MB071-0/1

Fig 4.13: Dimensional data - MAC 071 (natural convection)

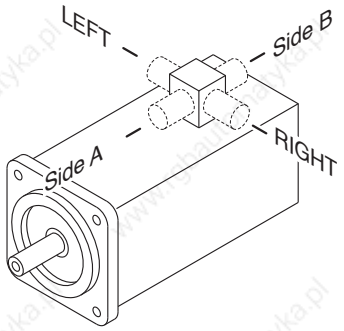
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

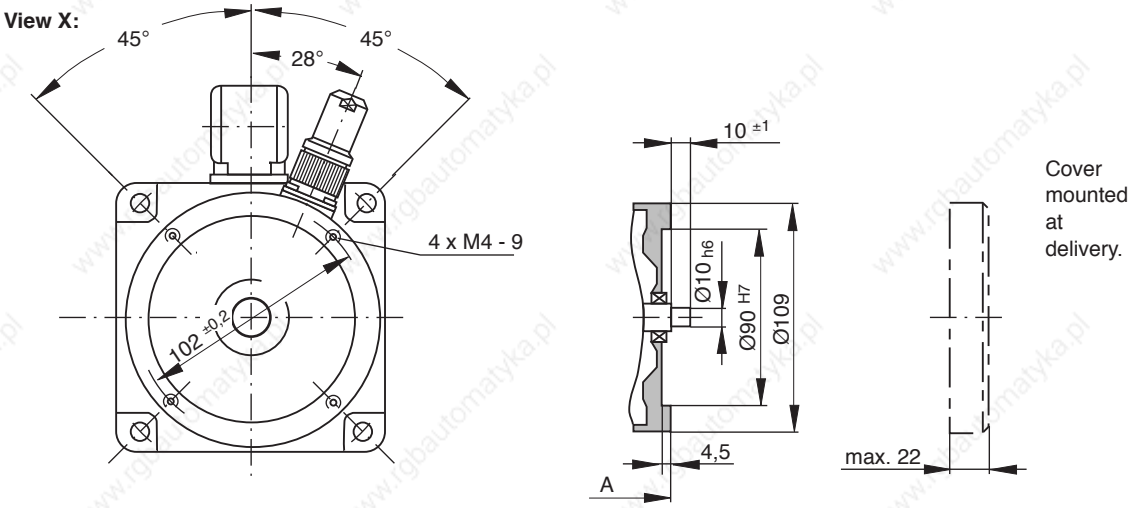
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

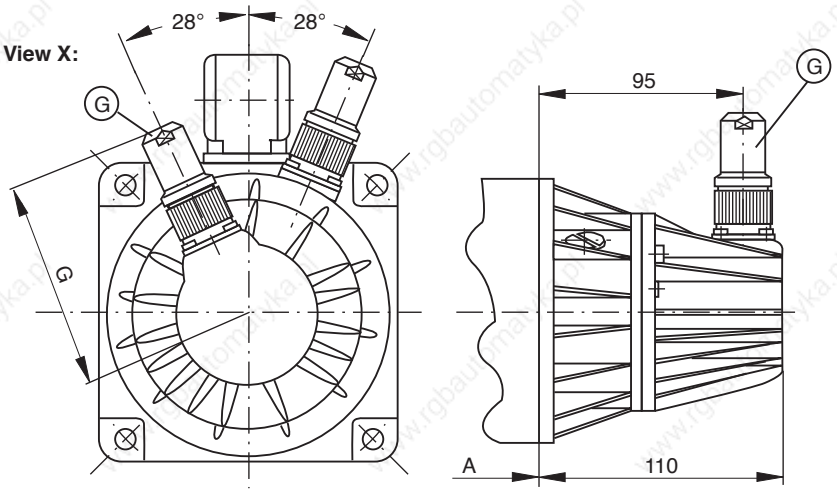


2 Motor version

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



G Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder (see following page)

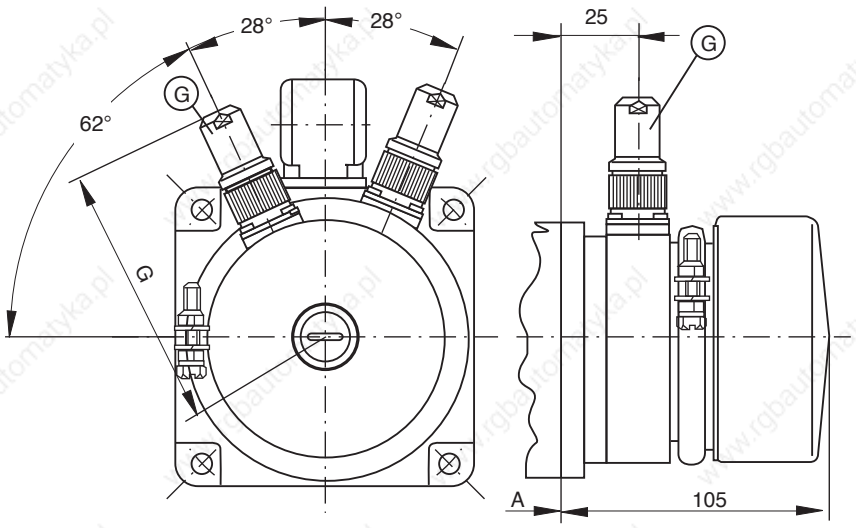
MB071-0/2

Fig 4.14: Dimensional data - MAC 071 - available options - (natural convection)

Available options

• Tachofeedback and mounted absolute encoder

View X:



Ⓖ Absolute encoder conn.

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104
angle conn.	INS 322	102

3 Blocking brake

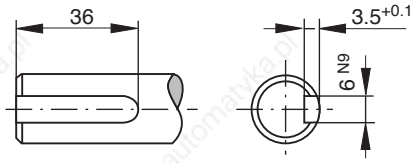
- without blocking brake
  Dim. A retained
- Standard blocking brake: 3 Nm
  Dim. A retained
- heavy-duty blocking brake: 6.5 Nm

Table for blocking brake with 6.5Nm holding torque

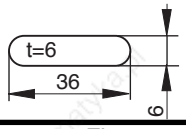
Size \ Dim.	A
MAC 071 A	240
MAC 071 B	280
MAC 071 C	320

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
  (Note! balanced with entire key.)



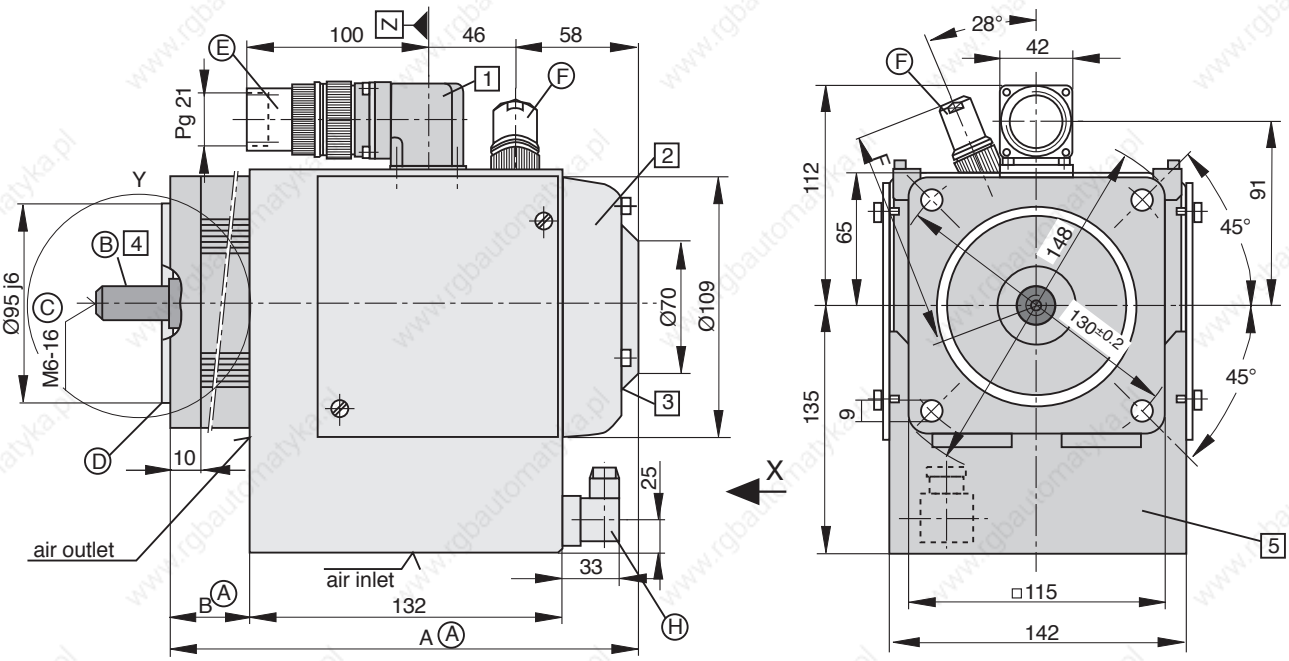
Matching key: DIN 6885-A 6 x 6 x 36
Must be ordered separately.

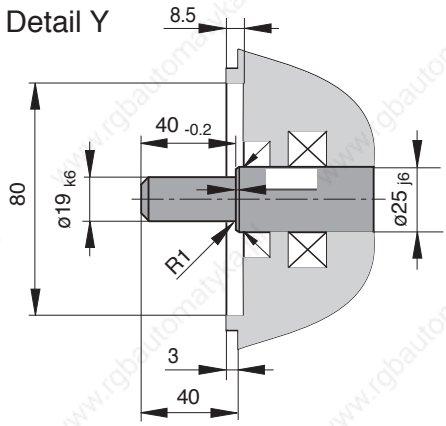


MB071-0/3

Fig 4.15: Dimensional data - MAC 071 - available options - (natural convection)

4.5. Dimensional Data - Radial Cooling





Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M6-16 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 2Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)

Ⓔ **Motor power connector**
INS 108 must be ordered separately.

Ⓐ **Dimensional table**

Size \ Dim.	A 1)	B 1)
MAC 071 A	212	55
MAC 071 B	252	95
MAC 071 C	292	135

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302 INS 102	116 118
angle conn.	INS 352 INS 312	114

Ⓗ **Blower connector: INS 195**
Must be ordered separately.

MB071-1rad/1

Fig 4.16: Dimensional data - MAC 071 (radial cooling)

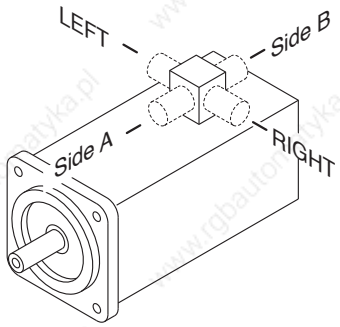
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

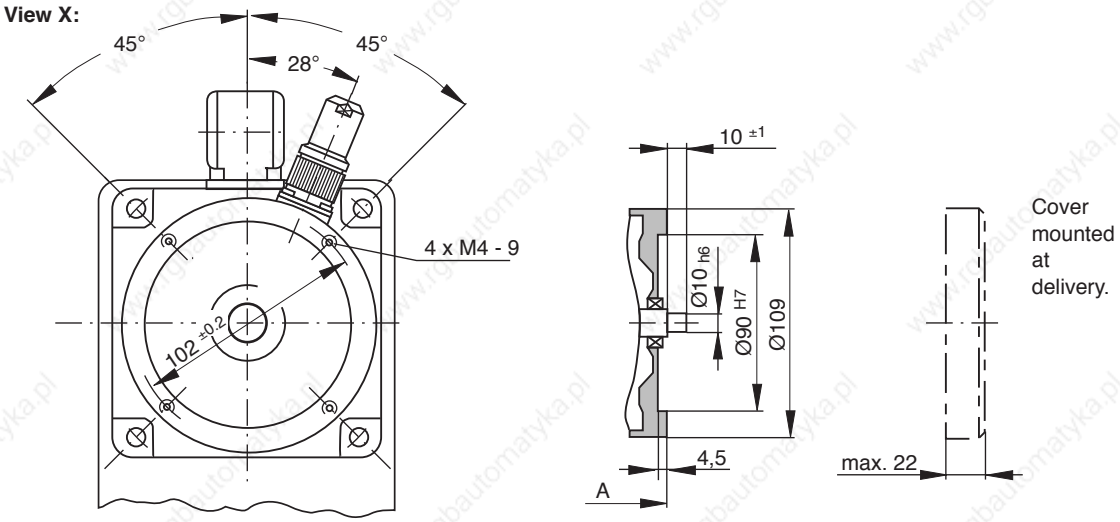
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

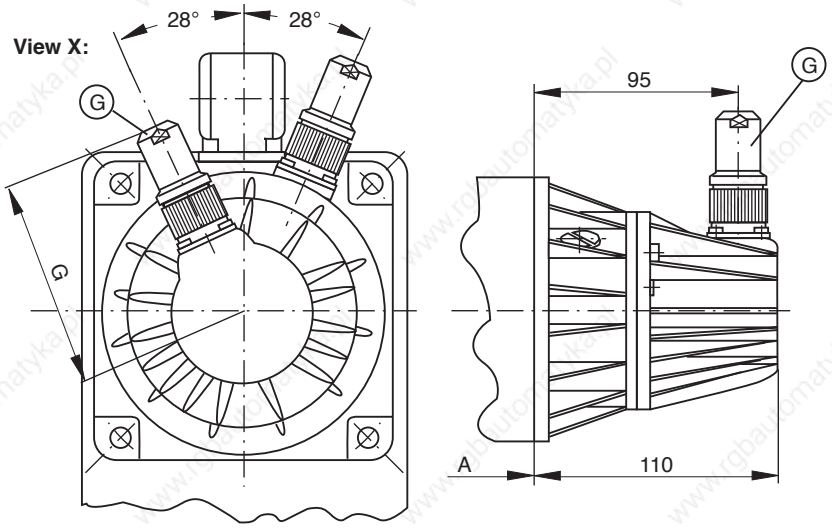


2 Motor version

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



G Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

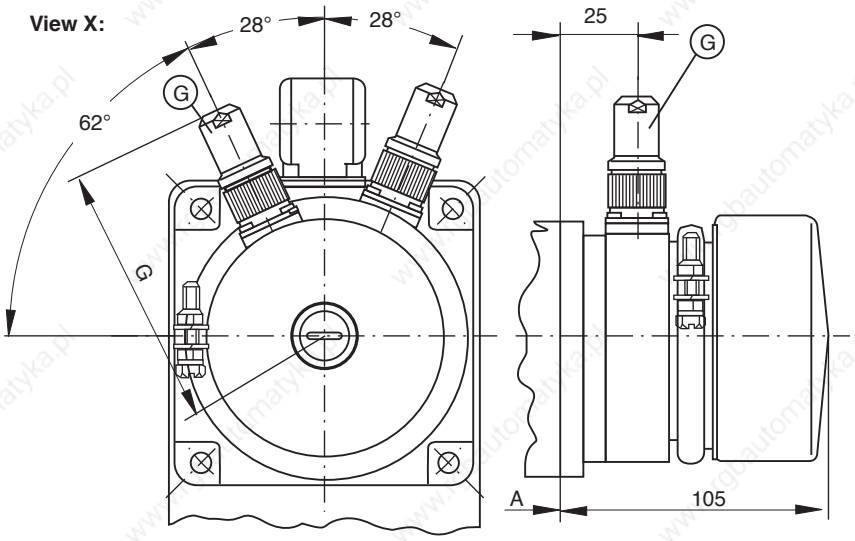
- Tachofeedback and mounted absolute encoder (see following page)

MB071-1rad/2

Fig 4.17: Dimensional data - MAC 071 - available options - (radial cooling)

Available options

• Tachofeedback and mounted absolute encoder



Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104
angle conn.	INS 322	102

3 Blocking brake

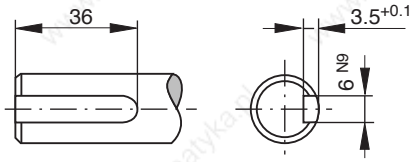
- without blocking brake
  Dim. A and B retained
- Standard blocking brake: 3 Nm
  Dim. A and B retained
- heavy-duty blocking brake: 6.5 Nm

Table for blocking brake with 6.5 Nm holding torque

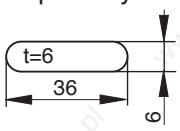
Size \ Dim.	A	B
MAC 071 A	240	83
MAC 071 B	280	123
MAC 071 C	320	163

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
  (Note! balanced with entire key.)

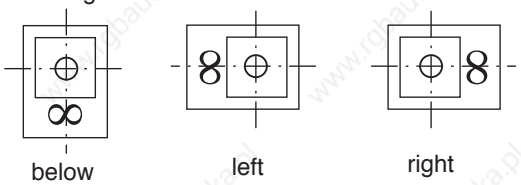


Matching key: DIN 6885-A 5 x 5 x 22
Must be ordered separately.



5 Blower arrangement

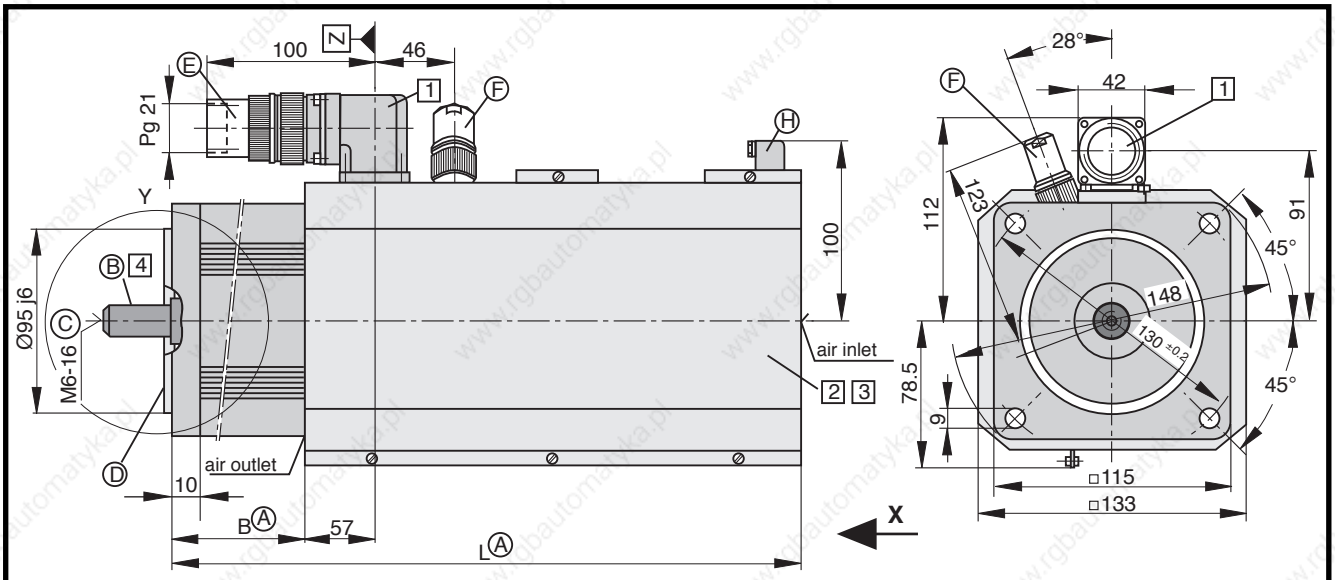
Looking towards motor shaft.

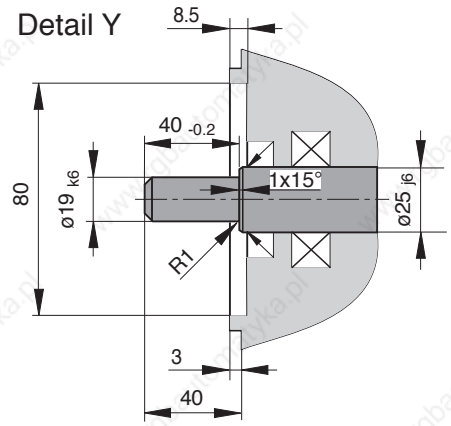


MB071-1rad/3

Fig 4.18: Dimensional data - MAC 071 - available options - (radial cooling)

4.6. Dimensional Data - Axial Cooling





Ⓐ **Dimensional table**

Size \ Dim.	L 1)	B 1)
MAC 071 A	275	50
MAC 071 B	315	90
MAC 071 C	355	130

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M6-16 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 2Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)

Ⓔ **Motor power connector**
INS 108 must be ordered separately.

Ⓕ **Tachofeedback connector:**
Type INS 302 or INS 102
Must be ordered separately.

Ⓗ **Blower connector: INS 195**
Must be ordered separately.

MB071-1/1

Fig 4.19: Dimensional data - MAC 071 (axial cooling)

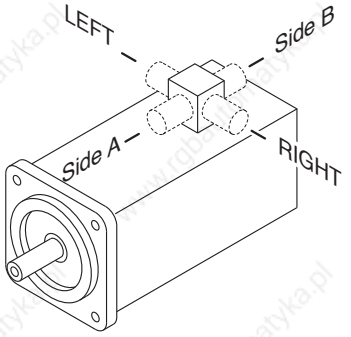
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

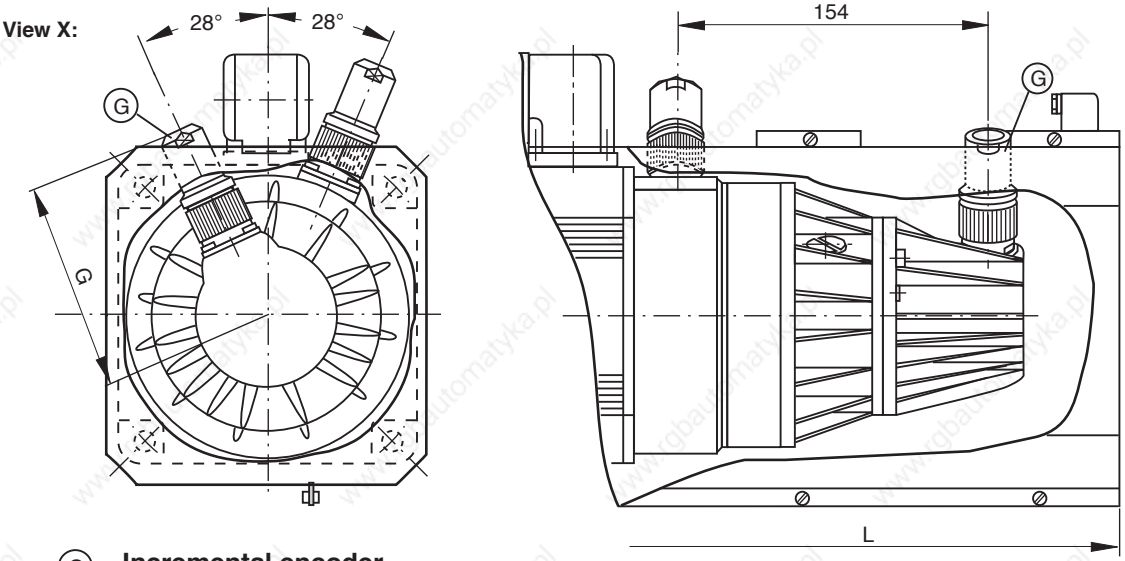
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.



2 Motor version

- Tachofeedback and mounted incremental encoder



Ⓖ Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 302	88
	INS 102	90

Table:

Size \ Dim.	L	B
MAC 071 A	395	78
MAC 071 B	435	118
MAC 071 C	475	158

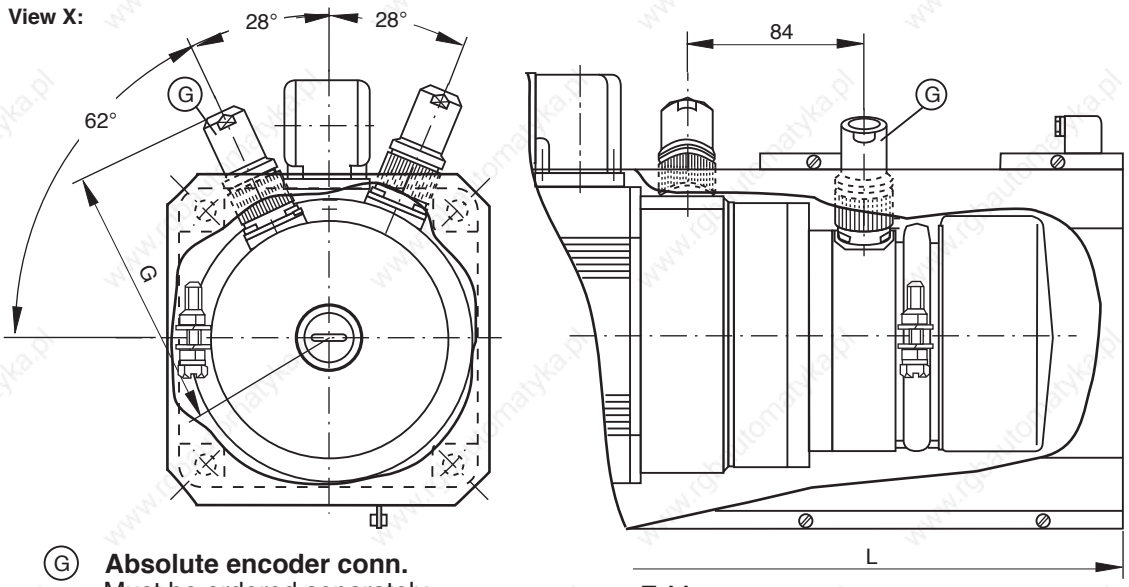
- Tachofeedback and mounted absolute encoder (see following page)

MB071-1/2

Fig 4.20: Dimensional data - MAC 071 -available options - (axial cooling)

Available options

• Tachofeedback and mounted absolute encoder



Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326	104
	INS 92	106

Table

Size \ Dim.	L	B
MAC 071 A	395	78
MAC 071 B	435	118
MAC 071 C	475	158

3 Blocking brake

- without blocking brake
  Dim. L and B retained
- Standard blocking brake: 3 Nm
  Dim. L and B retained
- heavy-duty blocking brake: 6.5 Nm

Table for blocking brake with 6.5Nm holding torque

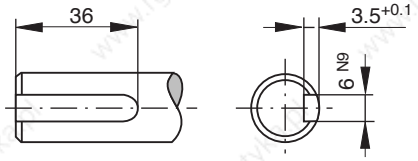
Size \ Dim.	Vers. 2 L	Vers. 2 B	Vers. 4 L	Vers. 4 B
MAC 071 A	303	78	423	106
MAC 071 B	343	118	463	146
MAC 071 C	383	158	503	186

Vers. 2 =
Motor with tachofeedback

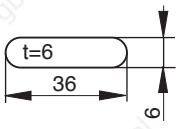
Vers. 4 =
Motor with tachofeedback and mounted encoder

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
  (Note! balanced with entire key.)



Matching key: DIN 6885-A 5 x 5 x 22
Must be ordered separately.



MB071-1/3

Fig 4.21: Dimensional data - MAC 071 - available options - (axial cooling)

4.7. Available Options

Type code fields — Example: MAC 071 A-0-ES-4 - C/095-A-0/WI 520LV/S000

1. Motor for analogue drives — MAC
2. Motor size — 071
3. Motor length — A, B, C
4. Type of cooling:

natural convection	surface cooling							
	axial		radial					
			blower right		blower below		blower left	
	AC 230 V	AC 115 V	AC 230 V	AC 115 V	AC 230 V	AC 115 V	AC 230 V	AC 115 V
0	1 1)	2 1)	6	A	7	B	8	C

5. Type of windings

Nominal rpm	Motor length A	B	C
2000 min -1	HS	FS	US
3000 min -1	OS	TS	NS
4000 min -1	ES	PS	JS
6000 min -1	VS	KS	GS

6. Motor feedback

Motor type
- with tachofeedback — 2
- with tachofeedback and second shaft end — 3
- with tachofeedback and mounted incremental or absolute encoder — 4

Tacho voltage
- set to nominal motor speed (nominal rpm > 3000 min -1 : 1,5 V/1000 min -1) (nominal rpm ≤ 3000 min -1 : 3 V/1000 min -1) — -
- 1.5 V/1000 min -1 — H

Tacho type
- Standard — C
- increased smooth run quality — F

7. Centering diameter
for design B05 and B14 — 095

8. Power connection
- connector to side A — A
- connector to side B — B
- connector to right (looking onto output shaft) — R
- connector to lefth (looking onto output shaft) — L

9. Blocking brake
- without blocking brake — 0
- with standard blocking brake (3 Nm) — 1
- with heavy-duty blocking brake (6.5 Nm) — 2

Mounted encoder

10. Type 2)
- Incremental encoder with standard mounting — WI
- Incremental encoder with shock-damped mounting — DI
- Absolute encoder — AM

11. Encoder code 2)
For available types, see section 2.4 "Motor feedback"

12. Special types
Fixed and documented by INDRAMAT with special number (see Drawing no.: 106-0105-4301-XX)
Does not apply to standard motors.

1) For type 3 motors (with 2nd shaft end and tachofeedback). Not available with axial surface cooling.

2) Type code fields 10 and 11 do not apply to motor types 2 and 3.

TLMAC071

Fig 4.22: Type codes MAC 071

4.8. Special Options

Specification of Option	S001
with keyway per DIN 6885, sheet 1	X

Fig 4.23: Special options with a MAC 071

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5. MAC 090

5.1. Technical Data

Designation	Symbol	Unit	Motor type MAC …			
			090 A - • - Z •	090 B - • - P •	090 C - • - K •	090 C - • - ED
Nominal motor speed [1]	n	min^{-1}	2000	2000	2000	5000
Continuous torque at standstill [2]	M_{dN}	Nm	3.7 (5.0) [5]	7.2 (10.5) [5]	10.4 (16.0) [5]	10.0 (16.0) [5]
Continuous current at standstill	I_{dN}	A	8.1(10.9) [5]	11.9 (17.4) [5]	17.0 (26.1) [5]	35.0 (52.0) [5]
Rotor moment of inertia [3]	J_M	kgm^2	20×10^{-4}	36×10^{-4}	53×10^{-4}	53×10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.51	0.67	0.68	0.31
Windings resistance at 20 °C	R_A	Ohm	1.85	0.97	0.60	0.12
Windings inductance	L_A	mH	1.9	5.1	3.6	0.8
Maximum peak of pulse current	I_{peak}	A	53	86	125	270
Thermal time constant	T_{th}	min	45 (30) [5]	60 (45) [5]	60 (45) [5]	60 (45) [5]
Mass [4]	m_M	kg	12.5	18	23	23
			090 A - • - R •	**090 B - • - N •**	**090 B - • - J •**	**090 C - • - G •**
Nominal motor speed [1]	n	min^{-1}	3000	3000	3000	3000
Continuous torque at standstill [2]	M_{dN}	Nm	3.5 (5.0) [5]	6.7 (10.5) [5]	6.7 (10.5) [5]	9.6 (16.0) [5]
Continuous current at standstill	I_{dN}	A	11.4 (16.3) [5]	13.0 (20.0) [5]	18.2 (28.5) [5]	24.8 (41.3) [5]
Rotor moment of inertia [3]	J_M	kgm^2	20×10^{-4}	36×10^{-4}	36×10^{-4}	53×10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.34	0.58	0.41	0.43
Windings resistance at 20 °C	R_A	Ohm	0.56	0.75	0.38	0.24
Windings inductance	L_A	mH	3.2	3.9	2.0	1.5
Maximum peak of pulse current	I_{peak}	A	76	98	137	196
Thermal time constant	T_{th}	min	45 (30) [5]	60 (45) [5]	60 (45) [5]	60 (45) [5]
Mass [4]	m_M	kg	12.5	18	18	23

[1] The usable motor speed is determined by the drive used.
Only those usable speeds n_{max} found in the selection lists of the motor-drive combinations are binding.
[2] With 60K overtemperature at the motor housing.
Continuous torque can be limited by the drive. See selection data.
[3] With tacho-generator, without holding brake
[4] With tacho-generator, without holding brake, without blower.
[5] Parenthetical values apply to versions with surface cooling.

Fig 5.1: Type-dependent motor data

Designation	Symbol	Unit	Data		
Permissible ambient temperature	T_{um}	°C	0 … + 45		
Permissible storage and transport temperature	T_L	°C	-20 … +80		
Maximum installation elevation		m	1000 m. above sea level		
Protection category			IP 65		
Insulation classification			F		
Housing coat			Black prime coat (RAL 9005)		
Voltage constant of the tachogenerator [1]	C_w	Vs/rad V/min^{-1}	0.0143 1.5/1000	0.0286 3/1000	0.0572 6/1000 [2]

[1] Tachovoltage can be selected application-related.
[2] If the 6 V/1000 min^{-1t} tachometer is used, then the maximum usable speed is limited to 1600 min^{-1}.

Fig 5.2: General data MAC 090

Designation	Symbol	Unit	Data holding brake		
			Standard		heavy-duty
Principle of action				electrically-actuated release	
Holding torque	M_H	Nm	6.5		14
Nominal voltage	U_N	V		DC 24 ± 10%	
Nominal current	I_N	A	0.7		0.7
Moment of inertia	J_B	kgm^2	1.06×10^{-4}		3.6×10^{-4}
Release delay	t_L	ms	60		70
Clamping delay	t_K	ms	20		30
Mass	m_B	kg	0.5		0.5

Fig 5.3: Technical data - holding brake

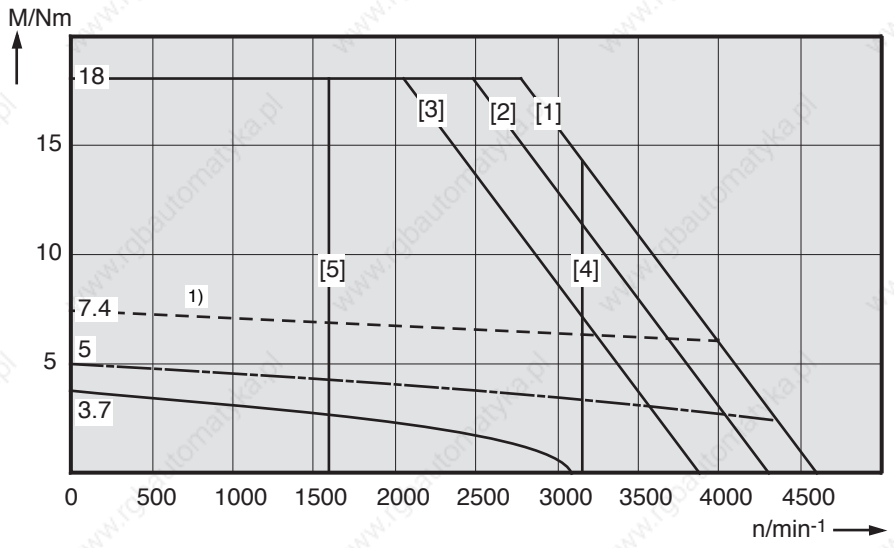
Designation	Symbol	Unit	Data surface cooling	
			Axial cooling	Radial cooling
Power consumption	S_N	VA	40/42	40/42
Nominal voltage	U_N	V	AC 230 or 115 [1]	AC 230 or 115 [1]
Frequency	f	Hz	50/60	50/60
Mass	m_L	kg	approx. 3.3 [2]	approx. 3.2 [2]
Protection category blower unit			IP 24	IP 24
Protection category blower motor			IP 44	IP 44

[1] 115 V special design
[2] Blower shroud for motor with tacho feedback.

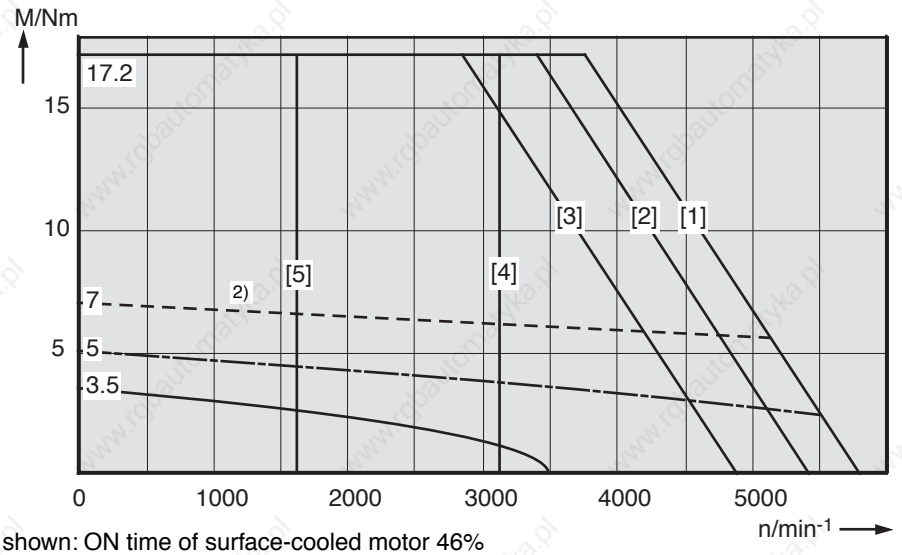
Fig 5.4: Technical data - surface cooling

5.2. Torque-Speed Characteristics

MAC 090 A - • - Z • 2000 min^{-1}



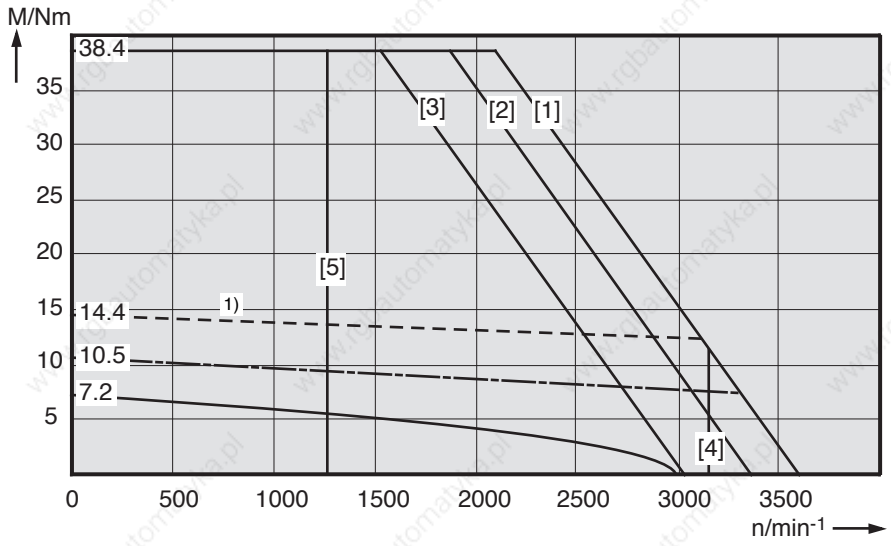
MAC 090 A - • - R • 3000 min^{-1}



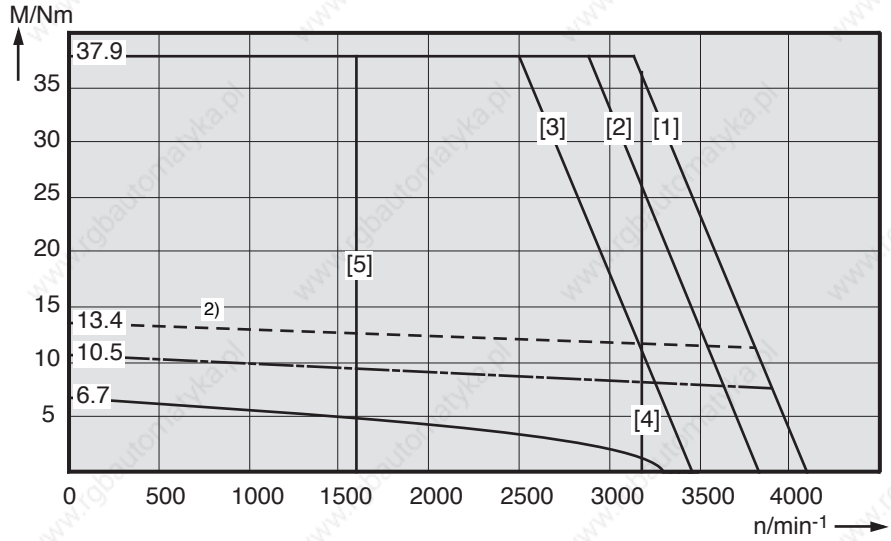
1) shown: ON time of surface-cooled motor 46%
2) shown: ON time of surface-cooled motor 51%

Fig 5.5: Torque-speed characteristics MAC 090

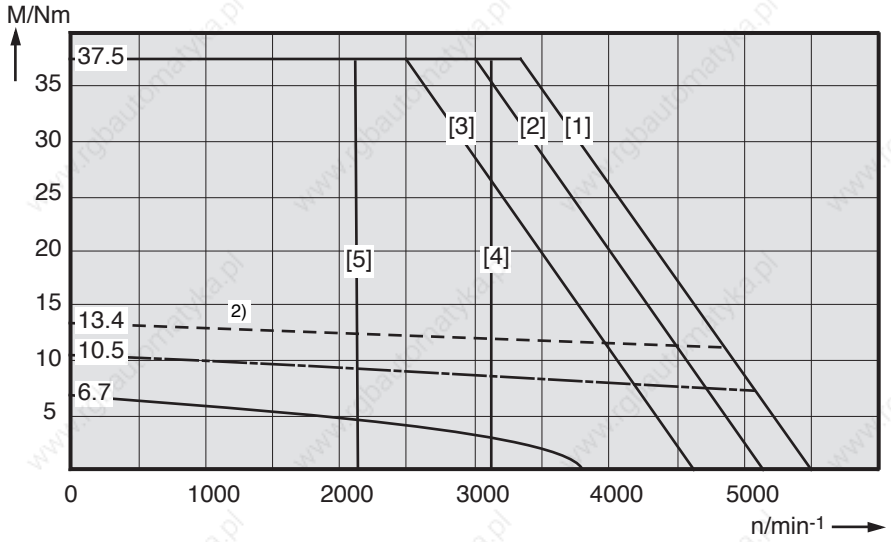
MAC 090 B - • - P •
2000 min^{-1}



MAC 090 B - • - N •
3000 min^{-1}



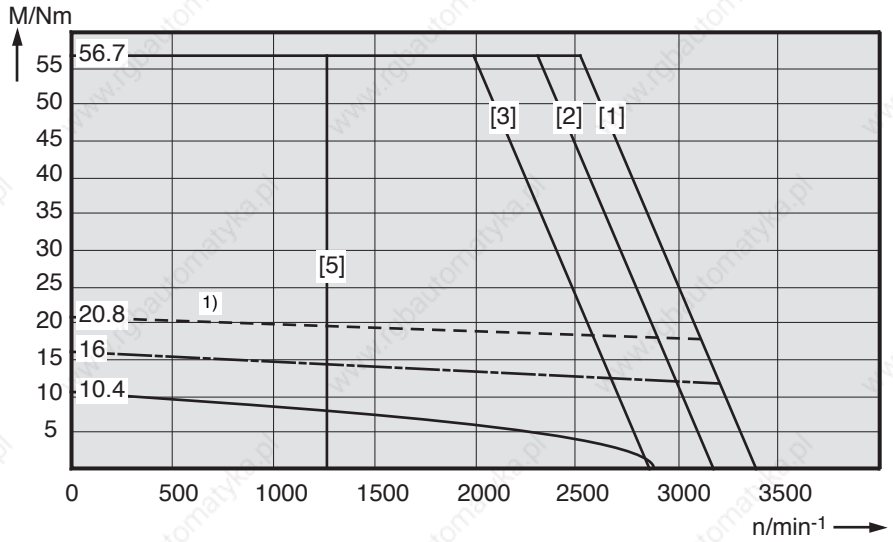
MAC 090 B - • - J •
3000 min^{-1}



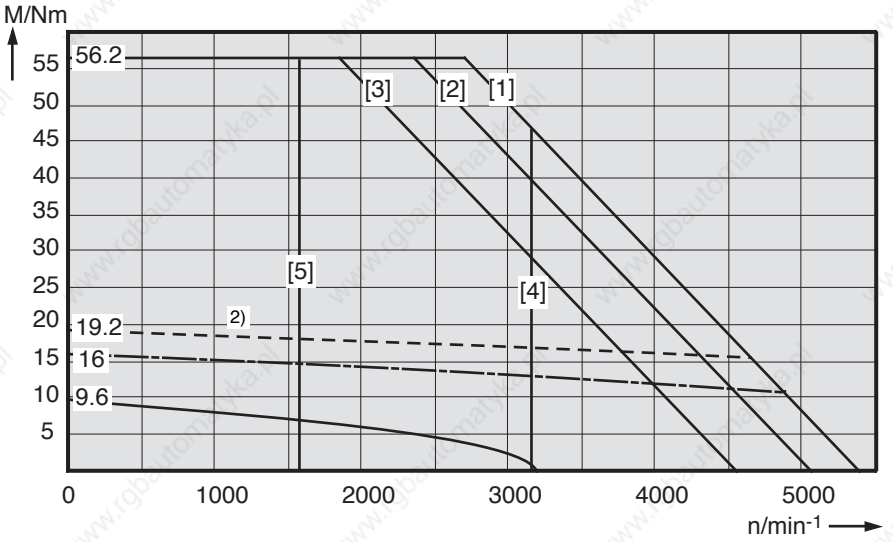
1) shown: ON time of surface-cooled motor 53%
2) shown: ON time of surface-cooled motor 61%

Fig 5.6: Torque-speed characteristics MAC 090

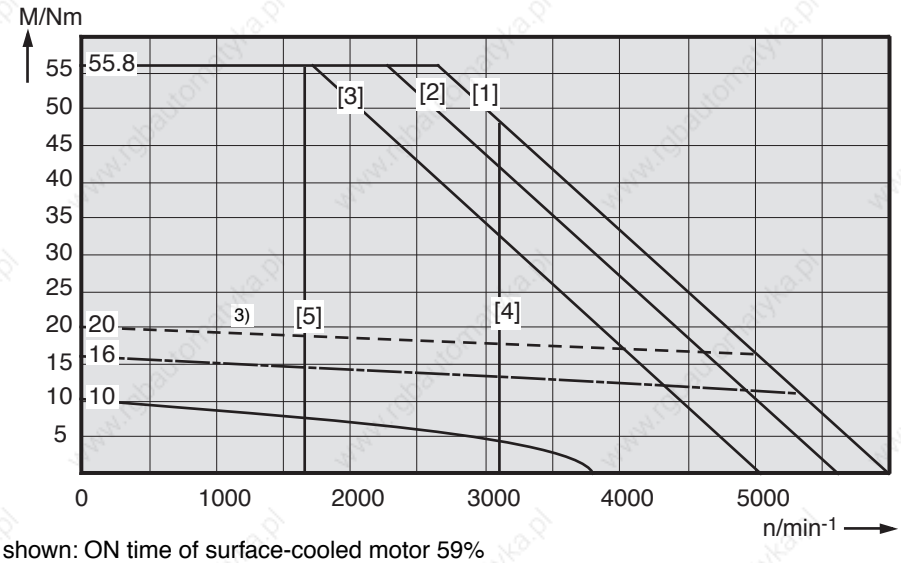
MAC 090 C - • - K •
2000 min^{-1}



MAC 090 C - • - G •
3000 min^{-1}



MAC 090 C - • - E •
5000 min^{-1}



1) shown: ON time of surface-cooled motor 59%
2) shown: ON time of surface-cooled motor 69%
3) shown: ON time of surface-cooled motor 64%

Fig 5.7: Torque-speed characteristics MAC 090

5.3. Shaft load capacity

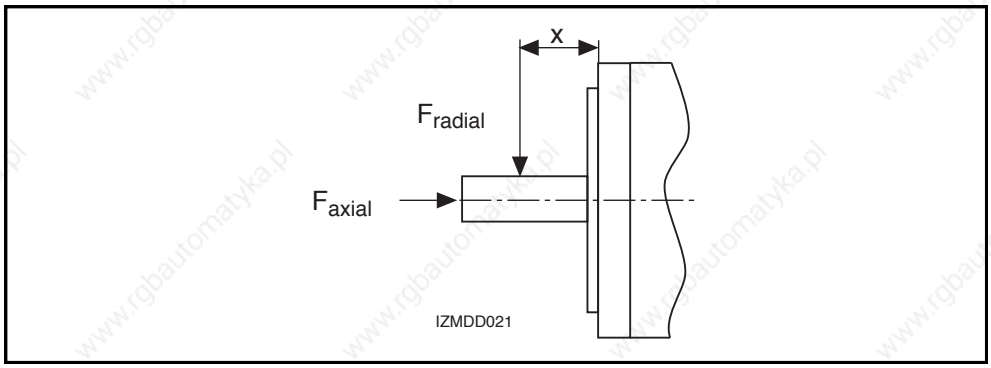


Fig 5.8: Shaft load

Permissible radial force F_{radial}

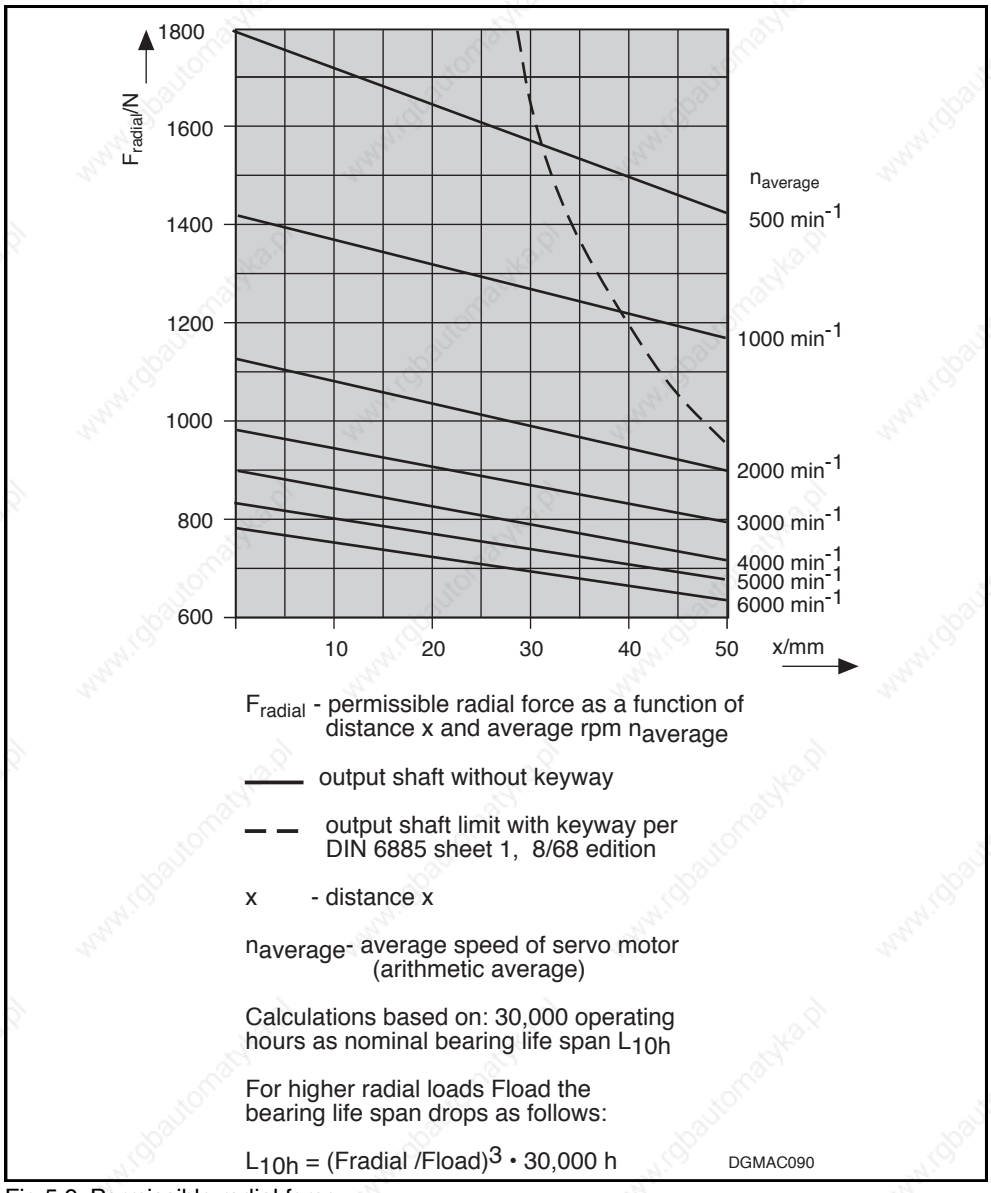


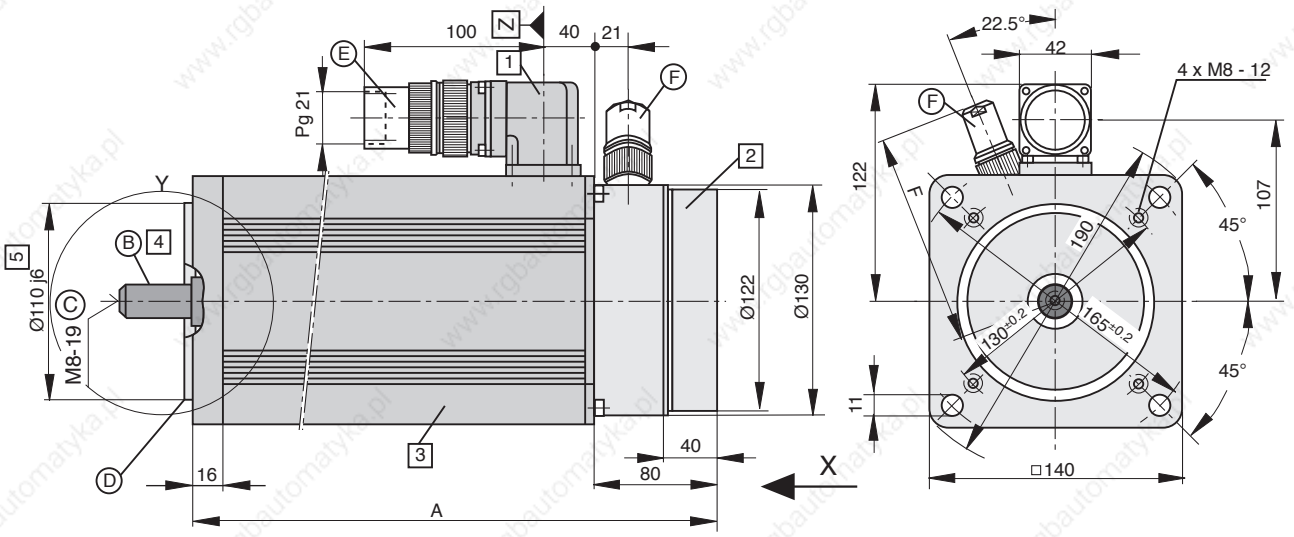
Fig 5.9: Permissible radial force

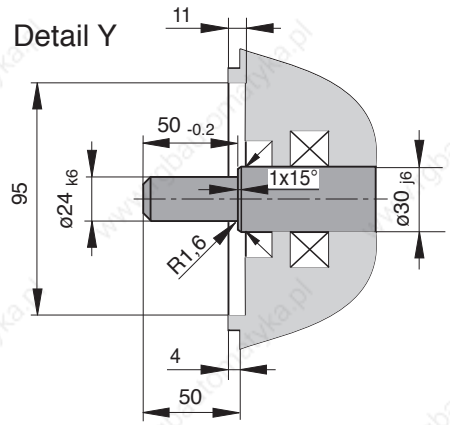
Permissible axial force F_{axial}

F_{axial} = 0.34 • F_{radial}

F_{axial} - Permissible axial force
F_{radial} - Permissible radial force

5.4. Dimensional data - natural convection





Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M8-19 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 5Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)
- as per design B14 (threads in flange)

Ⓐ

Size \ Dim.	A[1)]
MAC 090 A	277
MAC 090 B	342
MAC 090 C	407

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓔ **Motor power connector**
INS 108 must be ordered separately.

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302 INS 102	123 125
angle conn.	INS 352 INS 312	121

MB090-0/1

Fig 5.10: Dimensional data - MAC 090 (natural convection)

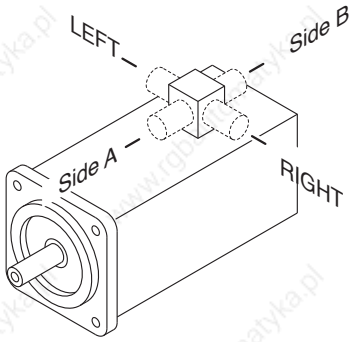
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

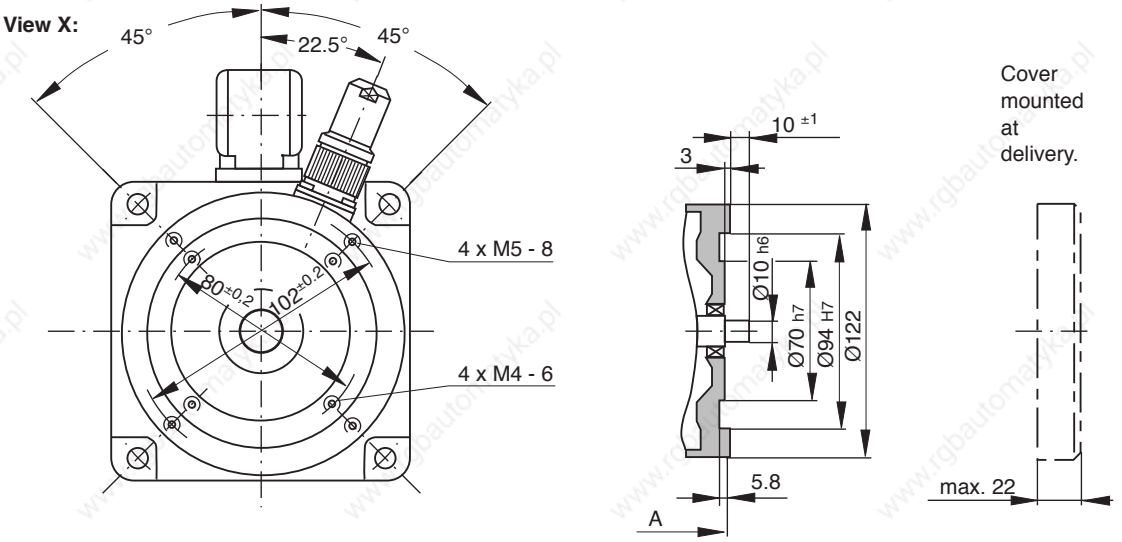
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

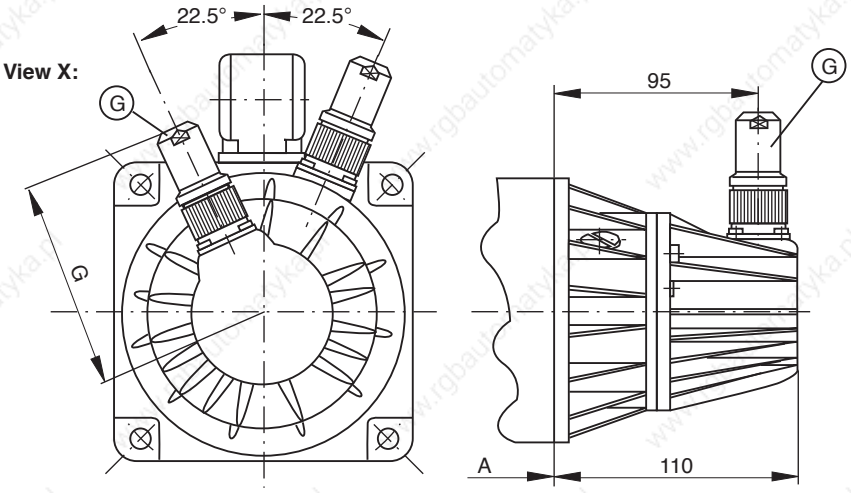


2 Motor version

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



G Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder (see following page)

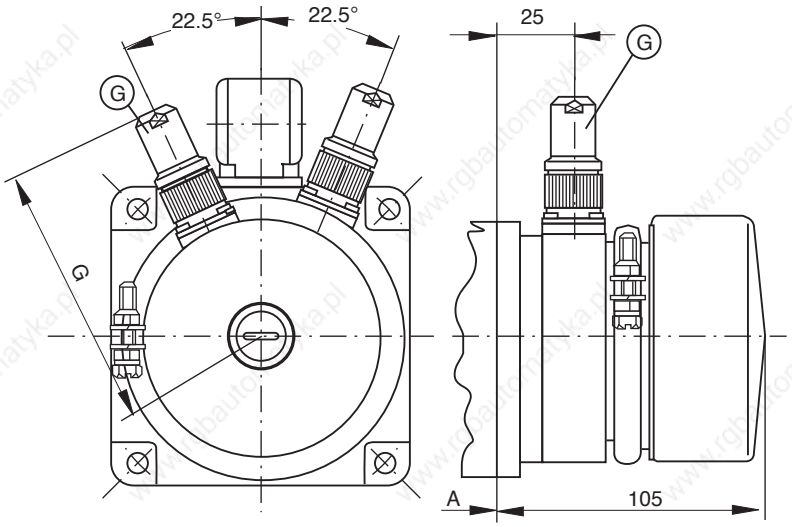
MB090-0/2

Fig 5.11: Dimensional data - MAC 090 - available options - (natural convection)

Available options

• Tachofeedback and mounted absolute encoder

View X:



Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104 106
angle conn.	INS 322	102

3 Blocking brake

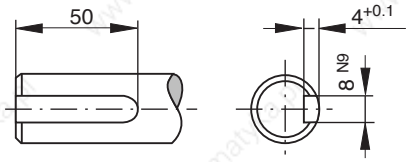
- without blocking brake
  Dim. A retained
- Standard blocking brake: 6.5 Nm
  Dim. A retained
- heavy-duty blocking brake: 14.0 Nm

Table for 14 Nm blocking brake

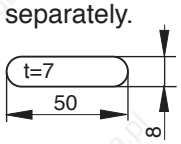
Size \ Dim.	A
MAC 090 A	327
MAC 090 B	392
MAC 090 C	457

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
  (Note! balanced with entire key.)



Matching key: DIN 6885-A 5 x 5 x 22
Must be ordered separately.



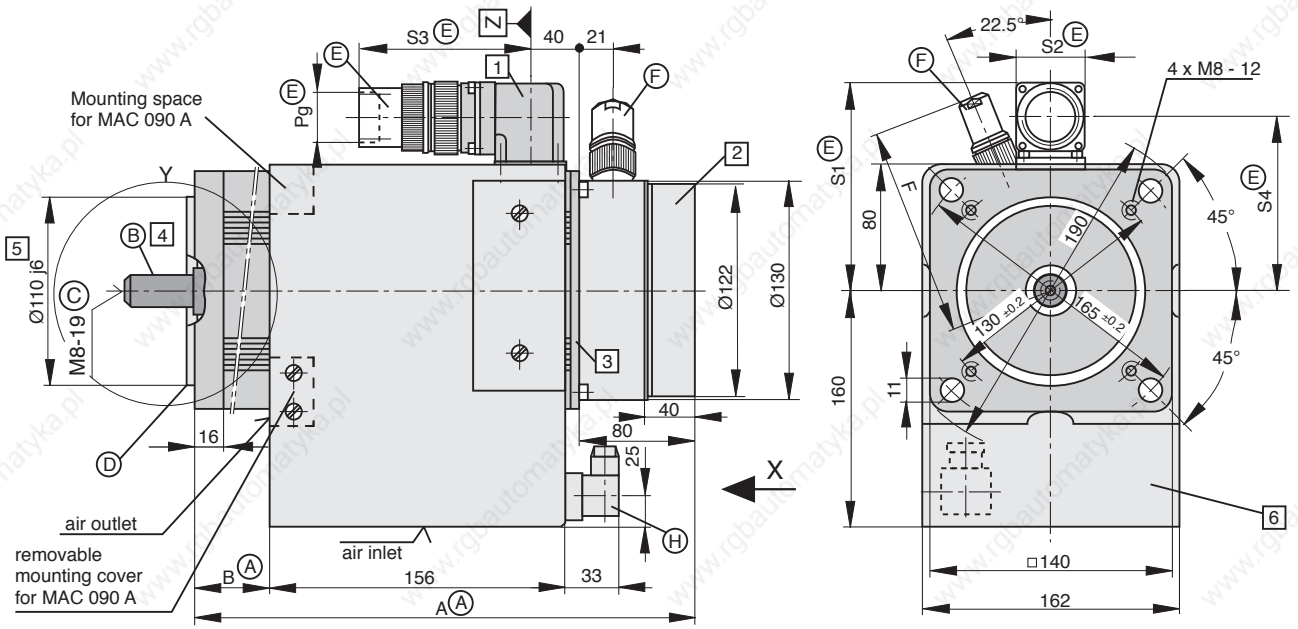
5 Special centering diameter

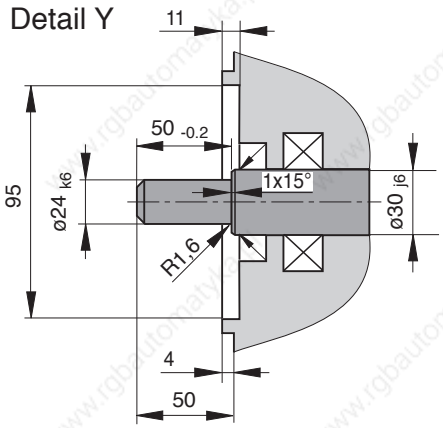
- Ø130 j6

MB090-0/3

Fig 5.12: Dimensional data - MAC 090 - available options - (natural convection)

5.5. Dimensional data - radial cooling





Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M8-19 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 5Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)
- as per design B14 (threads in flange)

Ⓔ **Motor power connector**
Must be ordered separately.

Ⓐ **Dimensional table**

Size \ Dim.	A 1)	B 1)
MAC 090 A	277	78
MAC 090 B	342	86
MAC 090 C	407	151

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Table

Type \ Dim.	S1	S2	S3	S4	Pg
INS 108 3)	122	42	100	107	21
INS 172 2)	135	53	145	109	36

2) with MAC090 C-•-E•
3) other MAC090 •-•-•

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302 INS 102	123 125
angle conn.	INS 352 INS 312	121

Ⓗ **Blower connector: INS 195**
Must be ordered separately.

MB090-1rad/1

Fig 5.13: Dimensional data - MAC 090 (radial cooling)

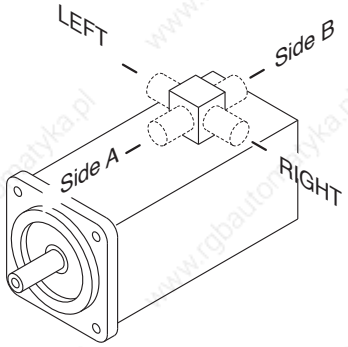
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

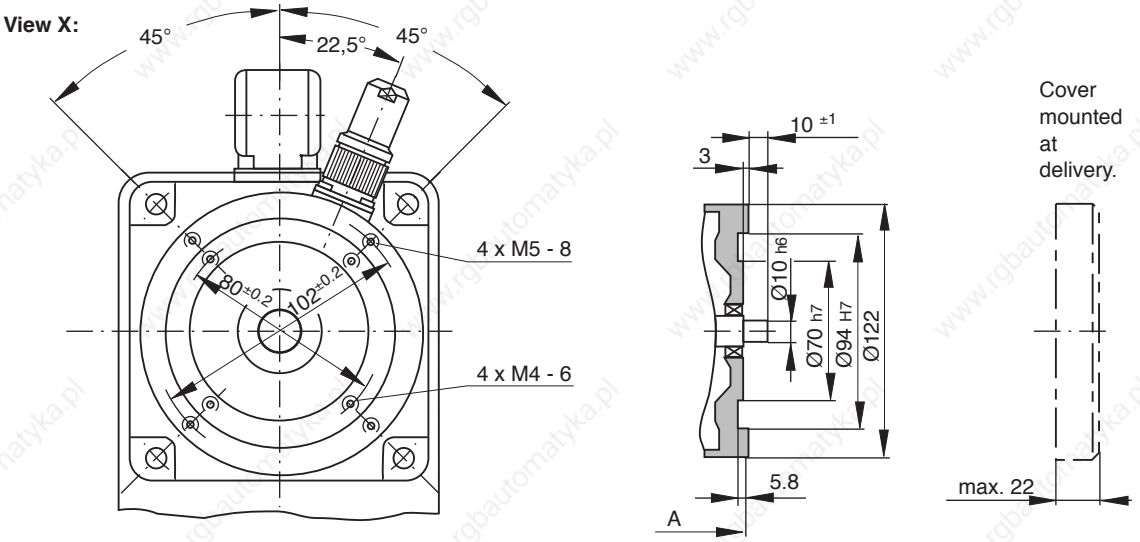
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

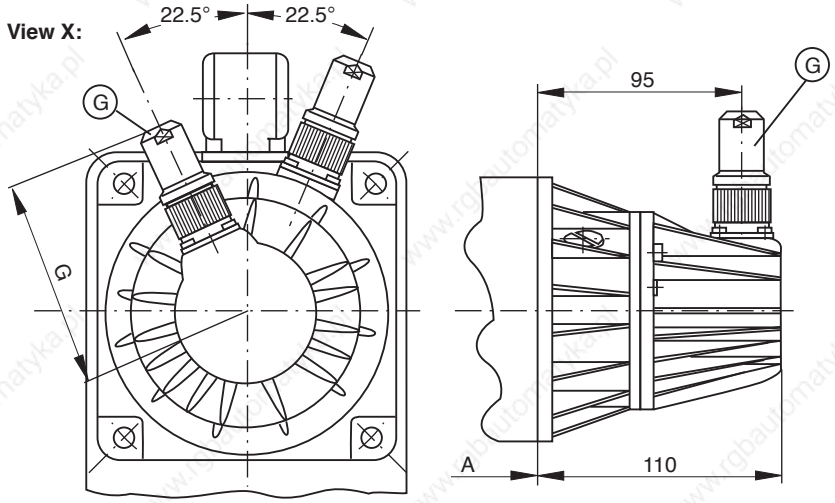


2 Motor version

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



G Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder (see following page)

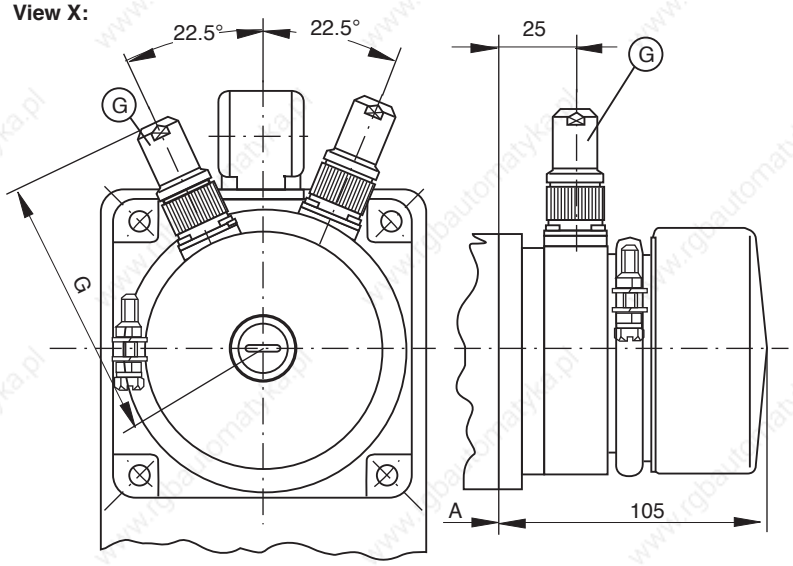
MB090-1rad/2

Fig 5.14: Dimensional data - MAC 090 - available options - (radial cooling)

Available options

• Tachofeedback and mounted absolute encoder

View X:



Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104
angle conn.	INS 322	102

3 Blocking brake

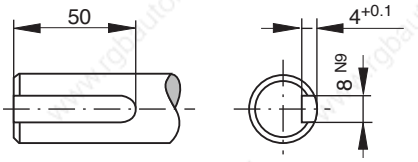
• without blocking brake
Dim. A and B retained
• Standard blocking brake: 6.5 Nm
Dim. A and B retained
• heavy-duty blocking brake: 14.0 Nm

Table for 14 Nm blocking brake

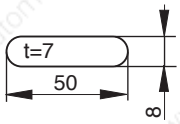
Size \ Dim.	A	B
MAC 090 A	327	128
MAC 090 B	392	136
MAC 090 C	457	185

4 Output shaft

• plain shaft (recommended type)
• with keyway per DIN 6885 sh. 1, 8/68 edition
(Note! balanced with entire key.)



Matching key: DIN 6885-A 5 x 5 x 22
Must be ordered separately.

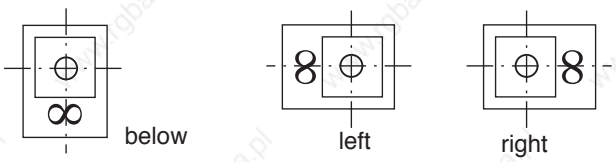


5 Special centering diameter

• Ø130 j6

6 Blower arrangement

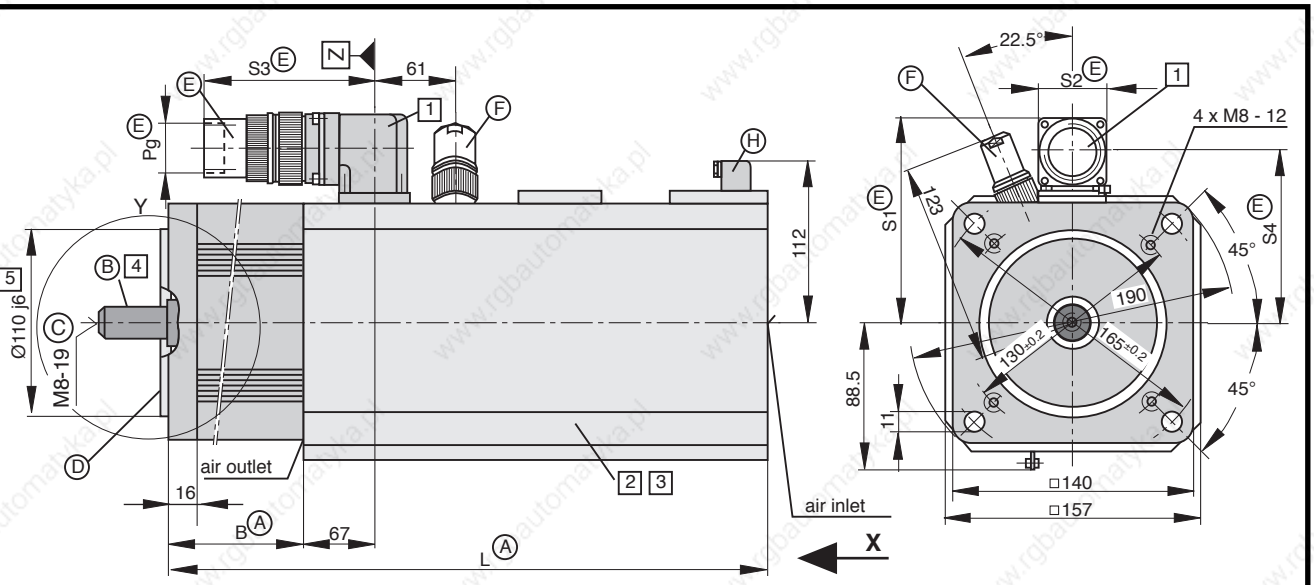
Looking towards motor shaft.

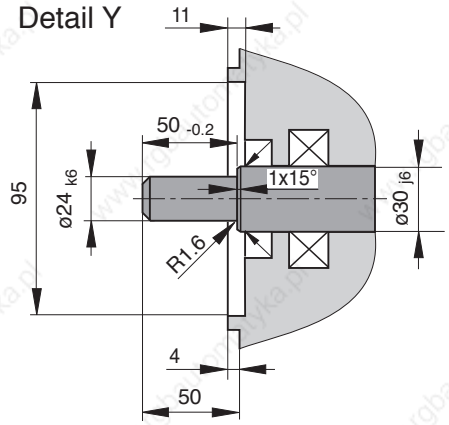


MB090-1rad/3

Fig 5.15: Dimensional data - MAC 090 - available options - (radial cooling)

5.6. Dimensional data - axial cooling





Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M8-19 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 5Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)
- as per design B14 (threads in flange)

Ⓔ **Motor power connector**
Must be ordered separately.

Ⓐ **Dimensional table**

Size \ Dim.	A 1)	B 1)
MAC 090 A	355	90
MAC 090 B	420	155
MAC 090 C	485	220

Table

Type \ Dim.	S1	S2	S3	S4	Pg
INS 108 3)	122	42	100	107	21
INS 172 2)	135	53	145	109	36

2) with MAC090 C-•-E•
3) other MAC090 •-•-•

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓕ **Tachofeedback connector:**
Must be ordered separately:
types INS 302 or INS 102

Ⓗ **Blower connector: INS 195**
Must be ordered separately.

MB090-1/1

Fig 5.16: Dimensional data - MAC 090 (axial cooling)

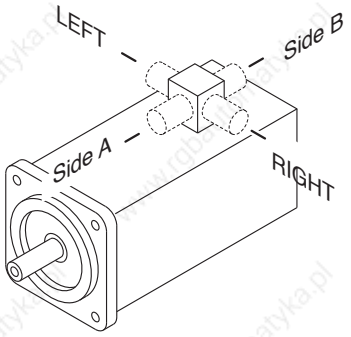
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

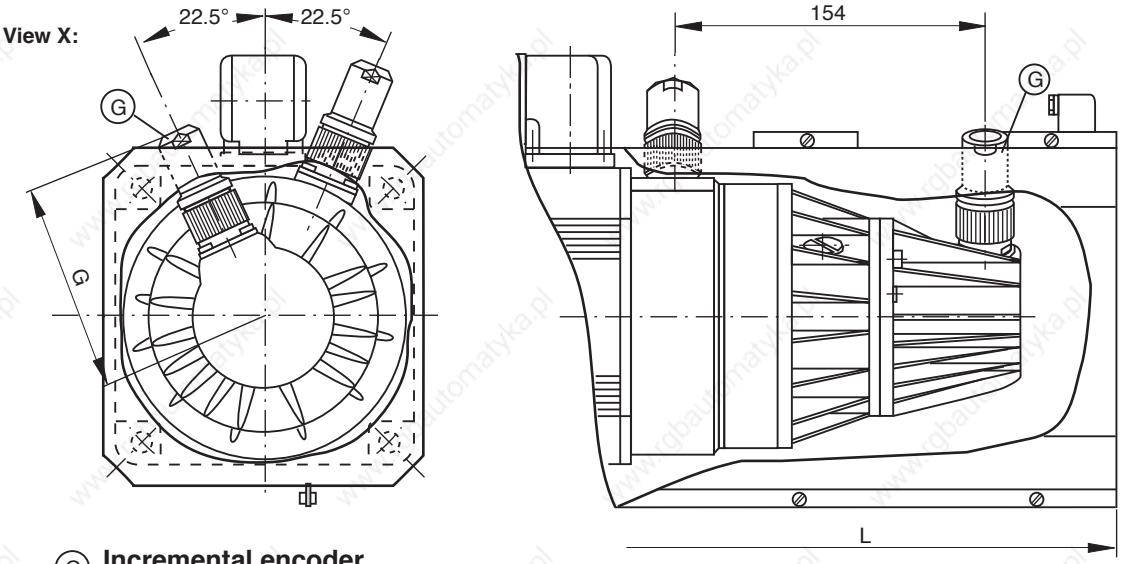
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.



2 Motor version

- Tachofeedback and mounted incremental encoder



Ⓖ Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301	123
	INS 101	125

Table:

Size \ Dim.	L	B
MAC 090 A	455	90
MAC 090 B	520	155
MAC 090 C	585	220

- Tachofeedback and mounted absolute encoder (see following page)

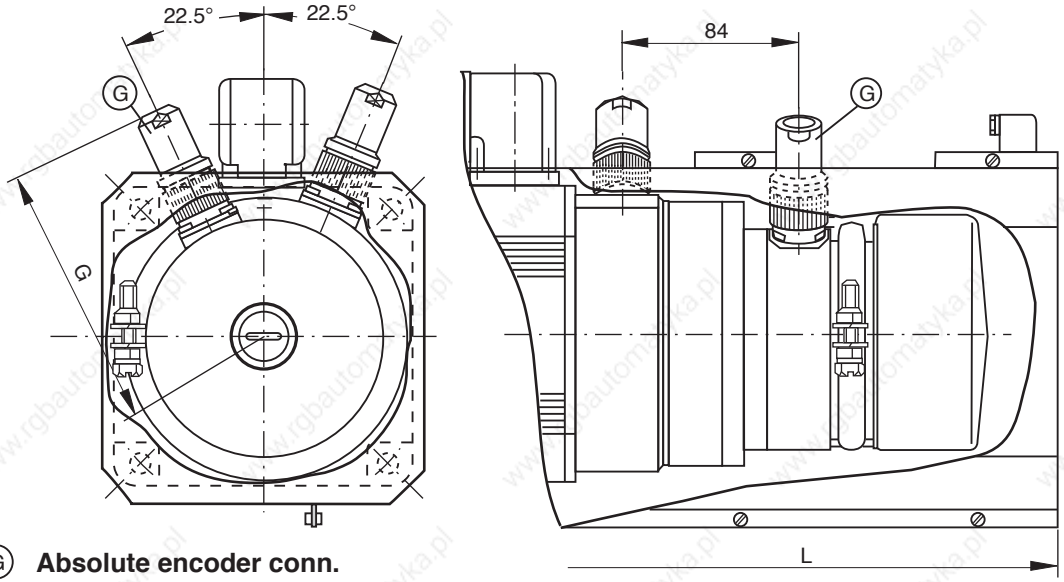
MB090-1/2

Fig 5.17: Dimensional data - MAC 090 - available options - (axial cooling)

Available options

• Tachofeedback and mounted absolute encoder

View X:



Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104 106

Size \ Dim.	L	B
MAC 090 A	455	90
MAC 090 B	520	155
MAC 090 C	585	220

3 Blocking brake

- without blocking brake
  Dim. L and B retained
- Standard blocking brake: 6.5 Nm
  Dim. L and B retained
- heavy-duty holding brake: 14.0 Nm

Table for blocking brake with 14.0 Nm holding torque

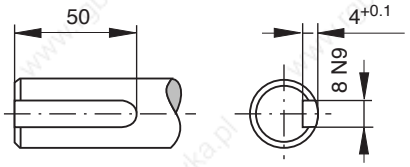
Size \ Dim.	Vers. 2 L	Vers. 2 B	Vers. 4 L	Vers. 4 B
MAC 090 A	405	140	505	140
MAC 090 B	470	205	570	205
MAC 090 C	535	270	635	270

Vers. 2 =
Motor with tachofeedback

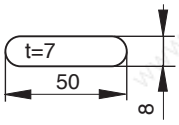
Vers. 4 =
Motor with tachofeedback and mounted encoder

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
  (Note! balanced with entire key.)



Matching key: DIN 6885-A 8 x 7 x 50
Must be ordered separately.



5 Special centering diameter

- Ø130 j6

MB090-1/3

Fig 5.18: Dimensional data - MAC 090 -available options - (axial cooling)

5.7. Available Options

Type code fields — Example: MAC 090 A-0-ES-4 - C/110-A-0/WI 520LV/S000

1. Motor for analogue drives — MAC

2. Motor size — 090

3. Motor length — A, B, C

4. Type of cooling:

natural convection	surface cooling							
	axial		radial					
			blower right		blower below		blower left	
	AC 230 V	AC 115 V	AC 230 V	AC 115 V	AC 230 V	AC 115 V	AC 230 V	AC 115 V
0	1[1]	2[1]	6	A	7	B	8	C

5. Type of windings

Nominal rpm	Standard applications, motor length				with increased smooth run quality, motor length			
	A	B	B	C	A	B	B	C
2000 min $^{-1}$	ZD	PD	--	KD	ZG	PG	--	KG
3000 min $^{-1}$	RD	ND	JD	GD	RG	NG	JG	GG
5000 min $^{-1}$	--	--	--	ED	--	--	--	EG

6. Motor feedback

Motor type

with tachofeedback	2
with tachofeedback and second shaft end	3
with tachofeedback and mounted incremental or absolute encoder	4

Tacho voltage

set to nominal motor speed (nominal rpm > 3000 min $^{-1}$: 1,5 V/1000 min $^{-1}$) (nominal rpm ≤ 3000 min $^{-1}$: 3 V/1000 min $^{-1}$)	-
1.5 V/1000 min $^{-1}$	H
6 V/1000 min $^{-1}$	L

Tacho type

Standard	C
increased smooth run quality	F

7. Centering diameter

for design B05 and B14	110
for design B05 and B14	130 [2]

8. Power connection

connector to side A	A
connector to side B	B
connector to right (looking onto output shaft)	R
connector to left (looking onto output shaft)	L

9. Blocking brake

without blocking brake	0
with standard blocking brake (6.5 Nm)	1
with heavy-duty blocking brake (14 Nm)	2

Mounted encoder

10. Type [3]

Incremental encoder with standard mounting	WI
Incremental encoder with shock-damped mounting	DI

11. Encoder code [3]

For available types, see section 2.4 "Motor feedback"

12. Special types
Fixed and documented by INDRAMAT with special number (see Drawing no.: 106-0105-4301-XX)
Does not apply to standard motors.

1) For type 3 motors (with 2nd shaft end and tachofeedback). Not available with axial surface cooling.

2) additional S0 no. required (see Fig. 5.20)

3) type code fields 10 and 11 do not apply to motor types 2 and 3

TLMAC090

Fig 5.19: Type codes - MAC 090

5.8. Special Options

Specification of Option	S003	S005	S012	S013	S019	S023	S031
Special centering diameter 130	X		X		X		X
Heavy-duty blocking brake				X	X	X	X
output shaft with shaft sealing		X	X			X	X

Fig 5.20: Special options with a MAC 090

6. MAC 093

6.1. Technical Data

Designation	Symbol	Unit	Motor type MAC …		
			093 A - • - WS	**093 B - • - OS**	**093 C - • - KS**
Nominal motor speed [1]	n	min^{-1}	2000	2000	2000
Continuous torque at standstill [2]	M_{dN}	Nm	9.2 (12.0) [5]	14.5 (20.0) [5]	19.5 (28.0) [5]
Continuous current at standstill	I_{dN}	A	11(14) [5]	18 (25) [5]	22 (32) [5]
Rotor moment of inertia [3]	J_M	kgm^2	22 x 10^{-4}	29 x 10^{-4}	42 x 10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.875	0.831	0.910
Windings resistance at 20 °C	R_A	Ohm	1.313	0.625	0.433
Windings inductance	L_A	mH	16.0	9.0	7.0
Maximum peak of pulse current	I_{peak}	A	54	89	110
Thermal time constant	T_{th}	min	50 (30) [5]	50 (45) [5]	50 (45) [5]
Mass [4]	m_M	kg	13.0	16.5	22.0
			093 A - • - PS	**093 B - • - JS**	**093 C - • - FS**
Nominal motor speed [1]	n	min^{-1}	3000	3000	3000
Continuous torque at standstill [2]	M_{dN}	Nm	9.2 (12.0) [5]	14.5 (18.3) [5]	19.5 (28.0) [5]
Continuous current at standstill	I_{dN}	A	15 (20) [5]	27 (34) [5]	35 (50) [5]
Rotor moment of inertia [3]	J_M	kgm^2	22 x 10^{-4}	29 x 10^{-4}	42 x 10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.620	0.554	0.579
Windings resistance at 20 °C	R_A	Ohm	0.659	0.227	0.175
Windings inductance	L_A	mH	8.0	4.0	2.9
Maximum peak of pulse current	I_{peak}	A	76	134	173
Thermal time constant	T_{th}	min	50 (45) [5]	50 (45) [5]	50 (45) [5]
Mass [4]	m_M	kg	13.0	16.5	22.0
			093 A - • - LS	**093 B - • - GS**	**093 C - • - DS**
Nominal motor speed [1]	n	min^{-1}	4000	4000	4000
Continuous torque at standstill [2]	M_{dN}	Nm	9.2 (12.0) [5]	14.5 (20.0) [5]	19.5 (28.0) [5]
Continuous current at standstill	I_{dN}	A	22 (28) [5]	38 (53) [5]	48 (69) [5]
Rotor moment of inertia [3]	J_M	kgm^2	22 x 10^{-4}	29 x 10^{-4}	42 x 10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.438	0.388	0.413
Windings resistance at 20 °C	R_A	Ohm	0.328	0.136	0.089
Windings inductance	L_A	mH	4.0	2.0	1.5
Maximum peak of pulse current	I_{peak}	A	108	192	242
Thermal time constant	T_{th}	min	50 (45) [5]	50 (45) [5]	50 (45) [5]
Mass [4]	m_M	kg	13.0	16.5	22.0
			093 A - • - HS	**093 B - • - ES**	**093 C - • - CS**
Nominal motor speed [1]	n	min^{-1}	6000	6000	6000
Continuous torque at standstill [2]	M_{dN}	Nm	9.2 (9.8) [5]	14.5 (20.0) [5]	19.5 (28.0) [5]
Continuous current at standstill	I_{dN}	A	32 (34) [5]	54 (74) [5]	60 (87) [5]
Rotor moment of inertia [3]	J_M	kgm^2	22 x 10^{-4}	29 x 10^{-4}	42 x 10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.292	0.277	0.331
Windings resistance at 20 °C	R_A	Ohm	0.146	0.069	0.057
Windings inductance	L_A	mH	1.8	1.0	0.9
Maximum peak of pulse current	I_{peak}	A	162	268	302
Thermal time constant	T_{th}	min	50 (45) [5]	50 (45) [5]	50 (45) [5]
Mass [4]	m_M	kg	13.0	16.5	22.0

[1] The usable motor speed is determined by the drive used.
Only those usable speeds n_{max} found in the selection lists of the motor-drive combinations are binding.
[2] With 60K overtemperature at the motor housing.
Continuous torque can be limited by the drive. See selection data.
[3] With tacho-generator, without holding brake
[4] With tacho-generator, without holding brake, without blower.
[5] Parenthetical values apply to versions with surface cooling.

Fig 6.1: Type-dependent motor data

Designation	Symbol	Unit	Data	
Permissible ambient temperature	T_{um}	°C	0 … + 45	
Permissible storage and transport temperature	T_L	°C	-20 … +80	
Maximum installation elevation		m	1000 m. above sea level	
Protection category			IP 65	
Insulation classification			F	
Housing coat			Black prime coat (RAL 9005)	
Voltage constant of the tachogenerator [1]	C_w	Vs/rad	0.0143	0.0286
		V/min^{-1}	1.5/1000	3/1000

[1] Tachovoltage can be selected application-related.

Fig 6.2: General data MAC 093

Designation	Symbol	Unit	Data holding brake		
			Standard	heavy-duty	extra heavy-duty
Principle of action				electrically actuated release	
Holding torque	M_H	Nm	6.5	14	22
Nominal voltage	U_N	V		DC 24 ± 10%	
Nominal current	I_N	A	0.7	0.7	0.7
Moment of inertia	J_B	kgm^2	1.06×10^{-4}	3.6×10^{-4}	3.6×10^{-4}
Release delay	t_L	ms	60	70	70
Clamping delay	t_K	ms	20	30	30
Mass	m_B	kg	0.6	1.1	1.1

Fig 6.3: Technical data - holding brake

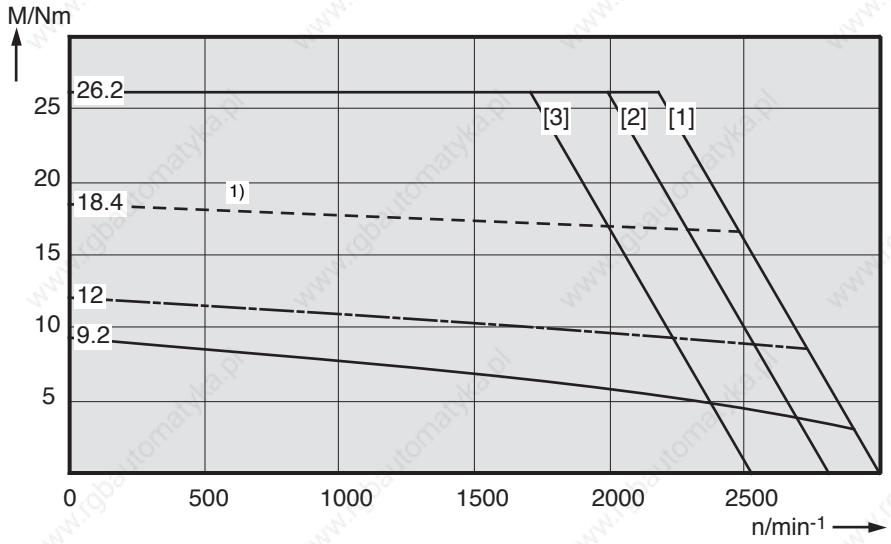
Designation	Symbol	Unit	Axial cooling	Radial cooling
Power consumption	S_N	VA	40/42	40/42
Nominal voltage	U_N	V	AC 230 or 115 [1]	AC 230 or 115 [1]
Frequency	f	Hz	50/60	50/60
Mass	m_L	kg	approx. 3.3 [2]	approx. 3.2 [2]
Protection category blower unit			IP 24	IP 24
Protection category blower motor			IP 44	IP 44

[1] 115 V special design
[2] Blower shroud for motor with tachofeedback.

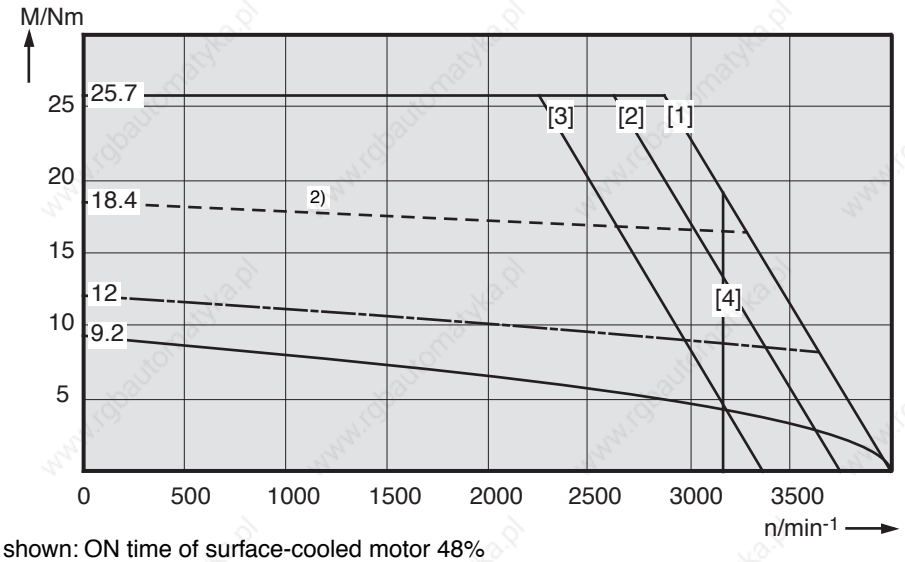
Fig 6.4: Technical data - surface cooling

6.2. Torque-Speed Characteristics

MAC 093 A - • - WS
2000 min^{-1}



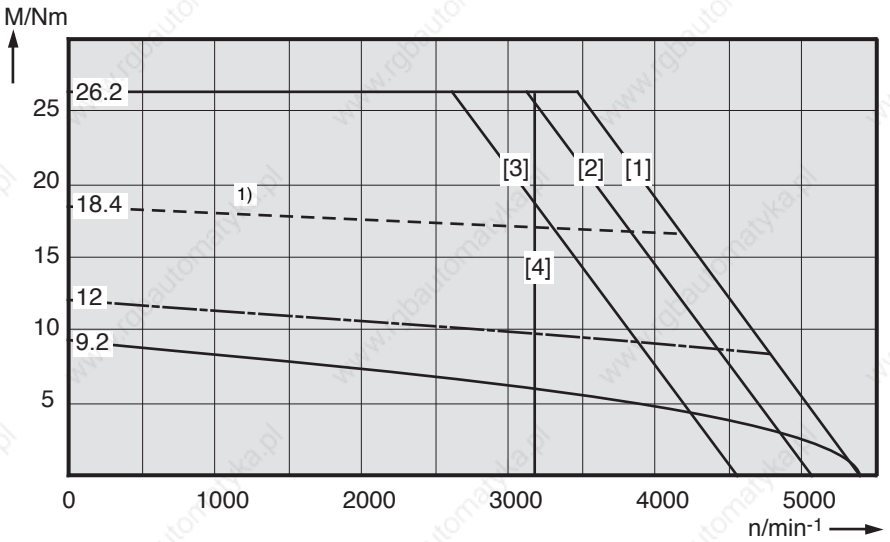
MAC 093 A - • - PS
3000 min^{-1}



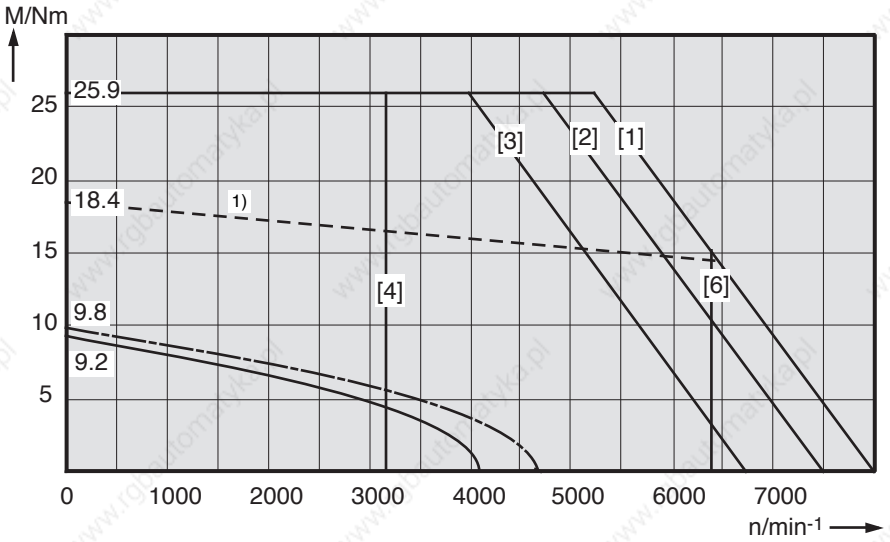
1) shown: ON time of surface-cooled motor 48%
2) shown: ON time of surface-cooled motor 40%

Fig 6.5: Torque-speed characteristics MAC 093

MAC 093 A - • - LS
4000 min^{-1}



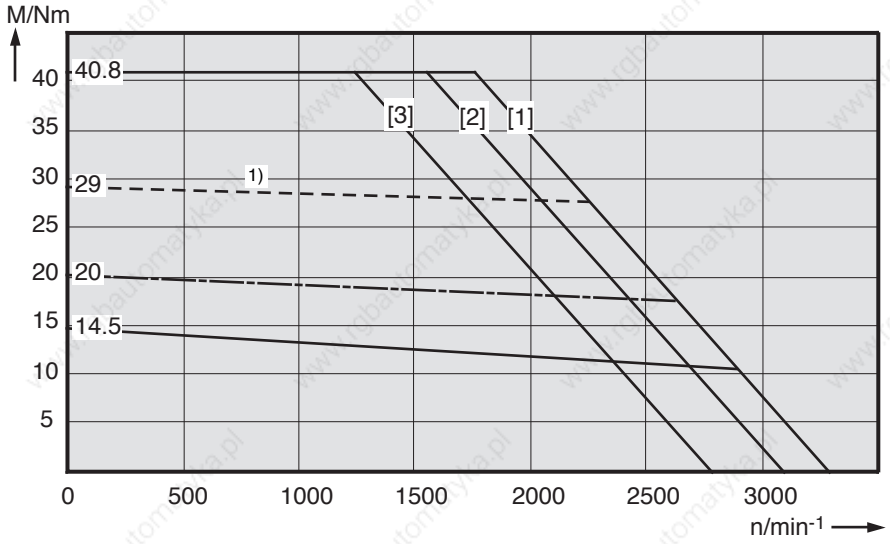
MAC 093 A - • - HS
6000 min^{-1}



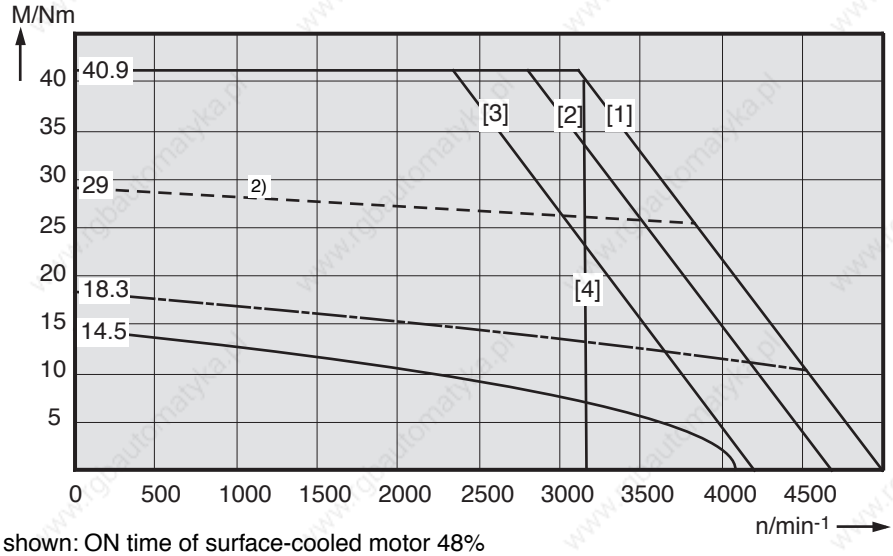
1) shown: ON time of surface-cooled motor 48%

Fig 6.6: Torque-speed characteristics MAC 093

MAC 093 B - • - OS
2000 min^{-1}



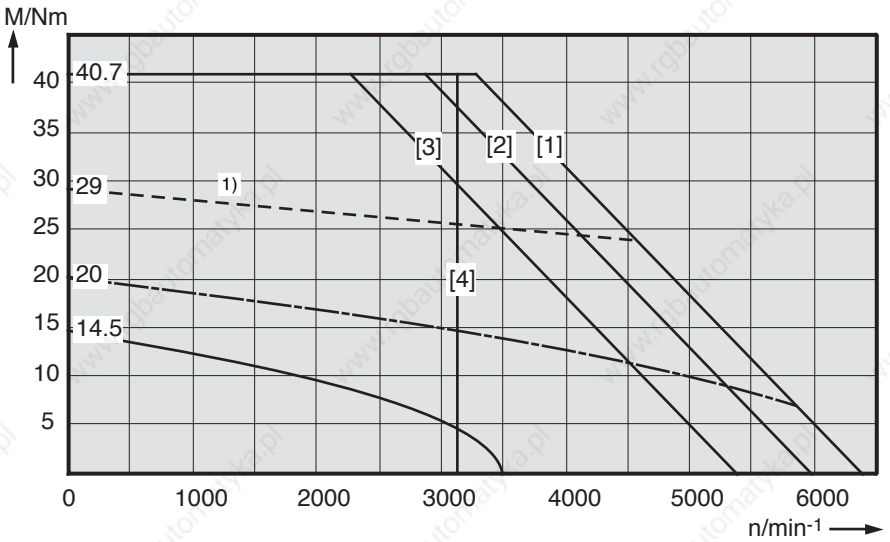
MAC 093 B - • - JS
3000 min^{-1}



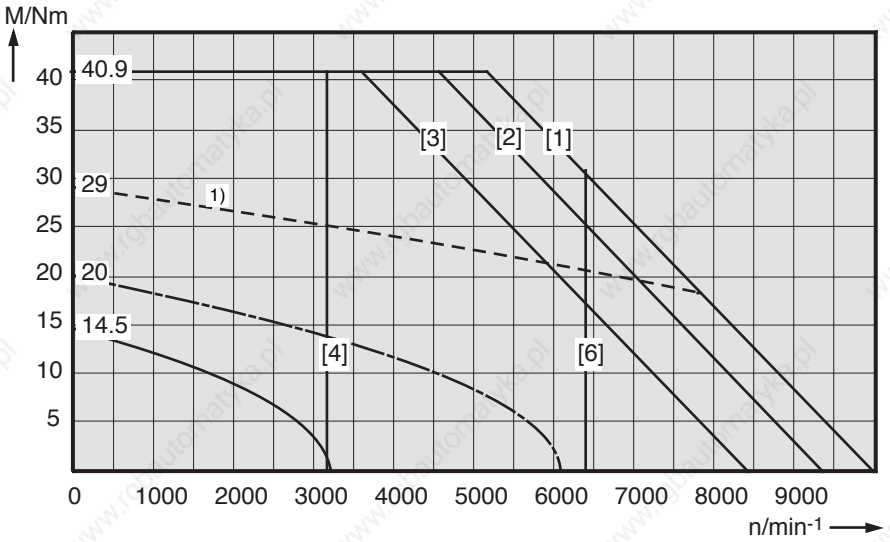
1) shown: ON time of surface-cooled motor 48%
1) shown: ON time of surface-cooled motor 40%

Fig 6.7: Torque-speed characteristics MAC 093

MAC 093 B - • - GS
4000 min^{-1}



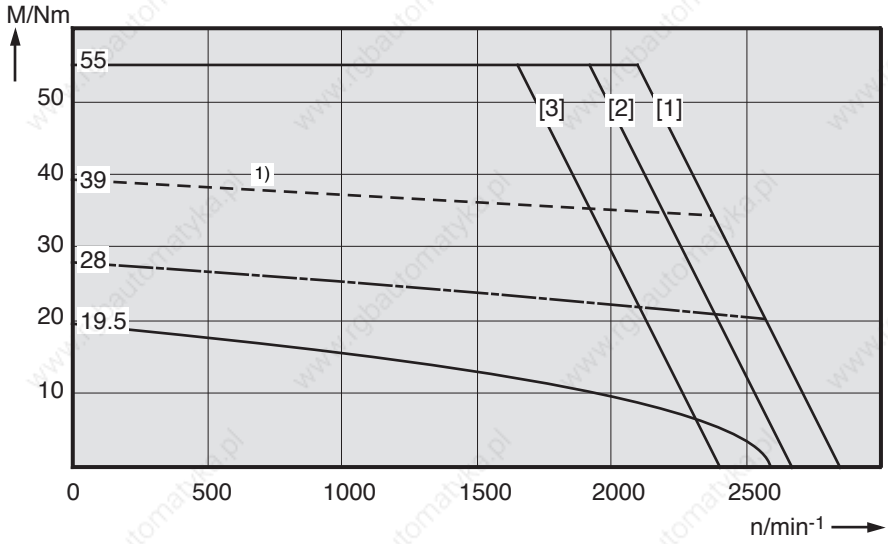
MAC 093 B - • - ES
6000 min^{-1}



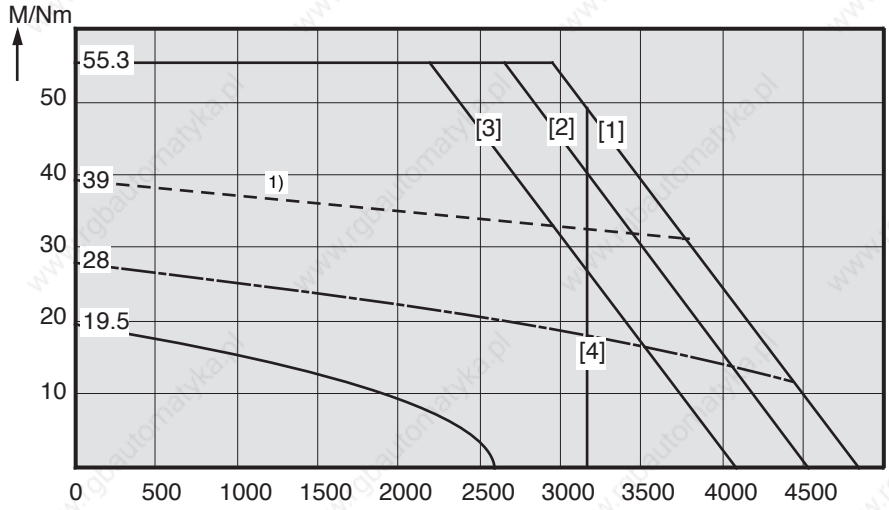
1) shown: ON time of surface-cooled motor 48%

Fig 6.8: Torque-speed characteristics MAC 093

MAC 093 C - • - KS
2000 min^{-1}



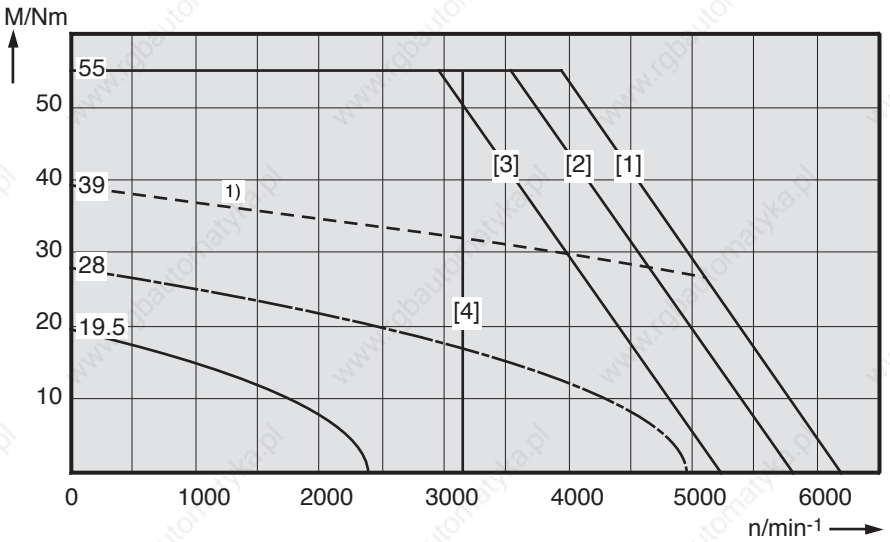
MAC 093 C - • - FS
3000 min^{-1}



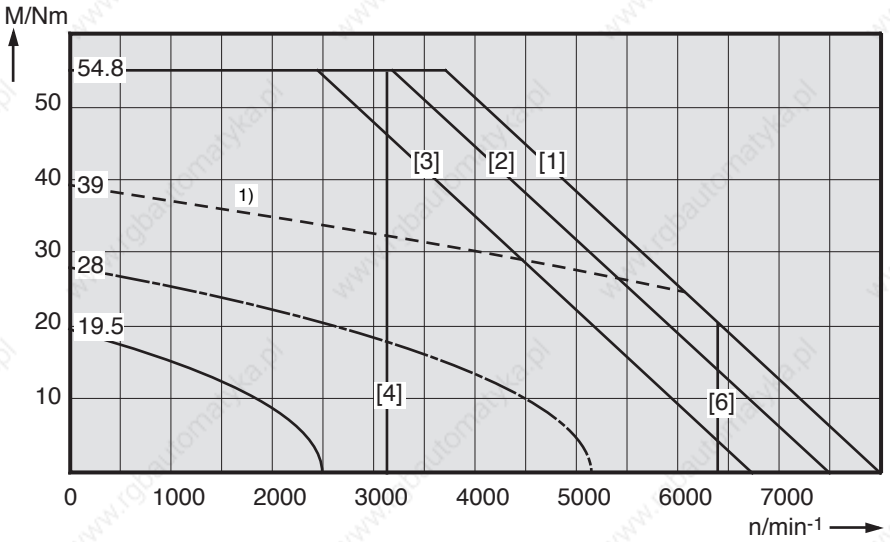
1) shown: ON time of surface-cooled motor 52%

Fig 6.9: Torque-speed characteristics MAC 093

MAC 093 C - • - DS
4000 min^{-1}



MAC 093 C - • - CS
6000 min^{-1}



1) shown: ON time of surface-cooled motor 52%

Fig 6.10: Torque-speed characteristics MAC 093

6.3. Shaft load capacity

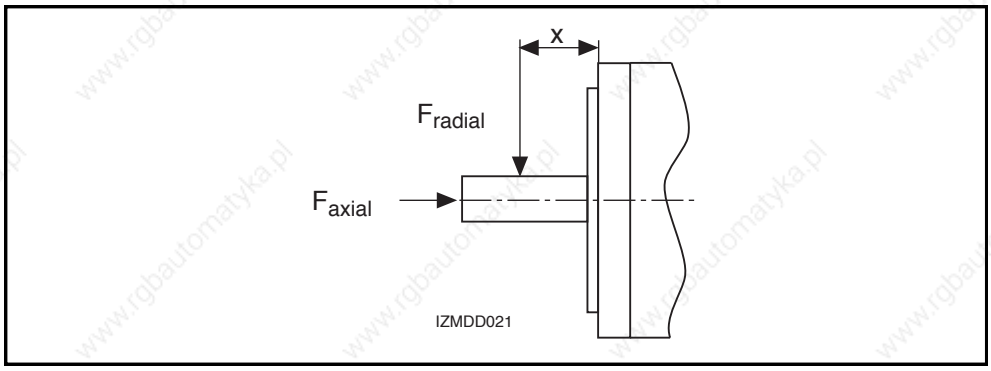


Fig 6.11: Shaft load

Permissible radial force F_{radial}

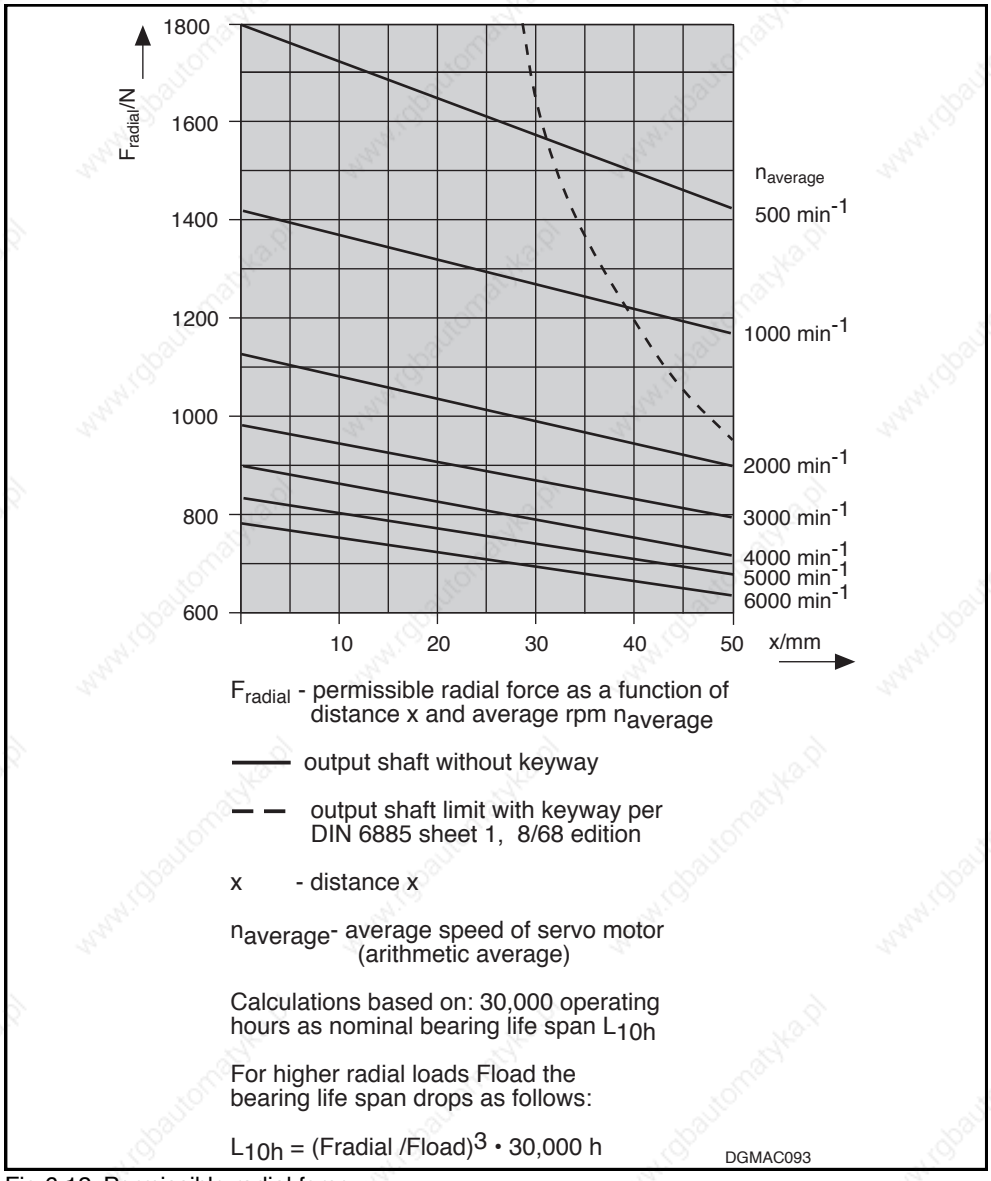


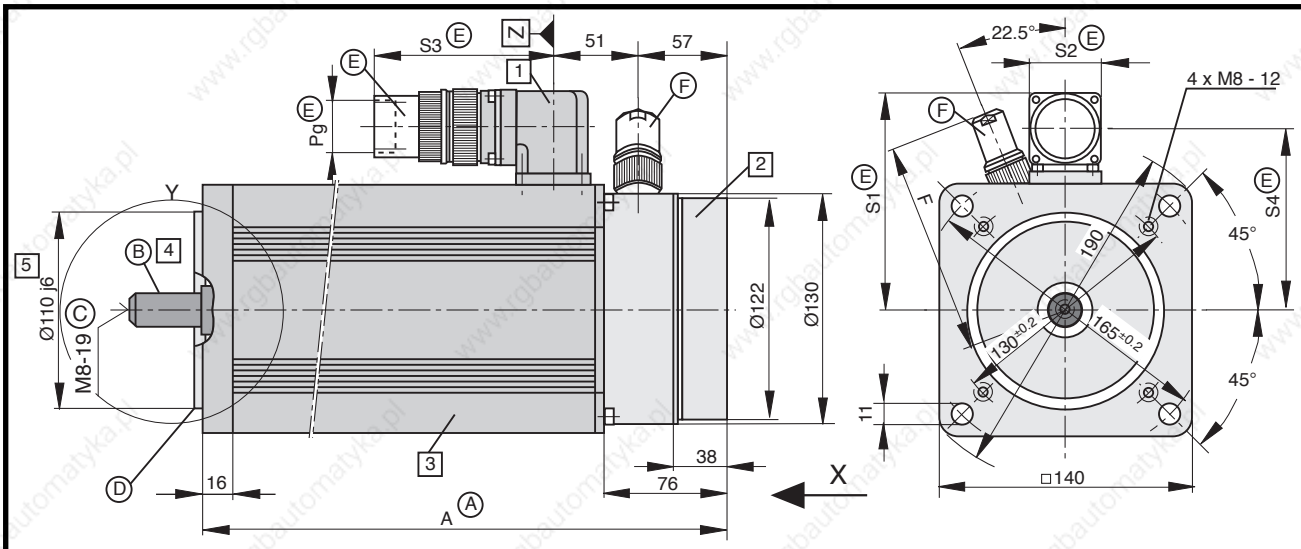
Fig 6.12: Permissible radial force

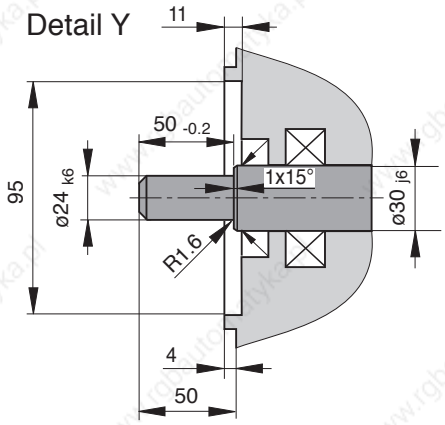
Permissible axial force F_{axial}

F_{axial} = 0.34 • F_{radial}

F_{axial} - Permissible axial force
F_{radial} - Permissible radial force

6.4. Dimensional data - natural convection





Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M8-19 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 5Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)
- as per design B14 (threads in flange)

Ⓔ **Motor power connector**
Must be ordered separately.

Table:

Type	S1	S2	S3	S4	Pg
INS 108 3)	122	42	100	107	21
INS 172 2)	135	53	145	109	36

2) with MAC 093 B-0-GS, MAC 093 B-0-ES
MAC 093 C-0-FS, MAC 093 C-0-DS
MAC 093 C-0-CS

3) other MAC 093 •-•-•

Ⓐ **Dimensional table Dim. A**

Size \ Dim.	A 1)
MAC 093 A	275
MAC 093 B	316
MAC 093 C	375

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302 INS 102	123 125
angle conn. 4)	INS 352 INS 312	121

4) Cannot be used in motors with power connector INS 172 and a power connector mounting direction towards side B.

MB093-0/1

Fig 6.13: Dimensional data - MAC 093 (natural convection)

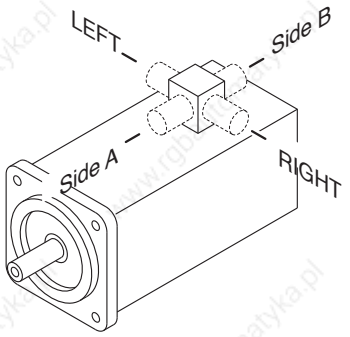
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

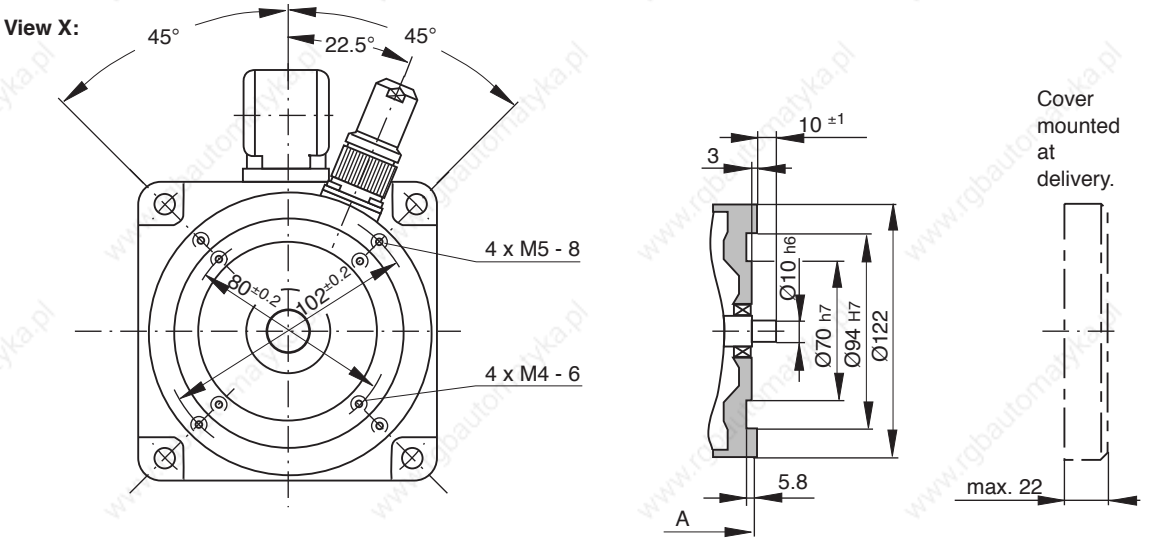
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

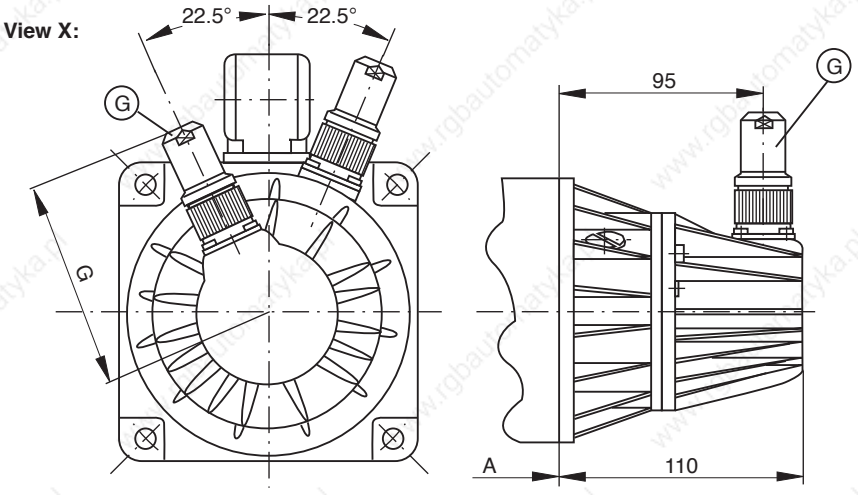


2 Motor version

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



G Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder (see following page)

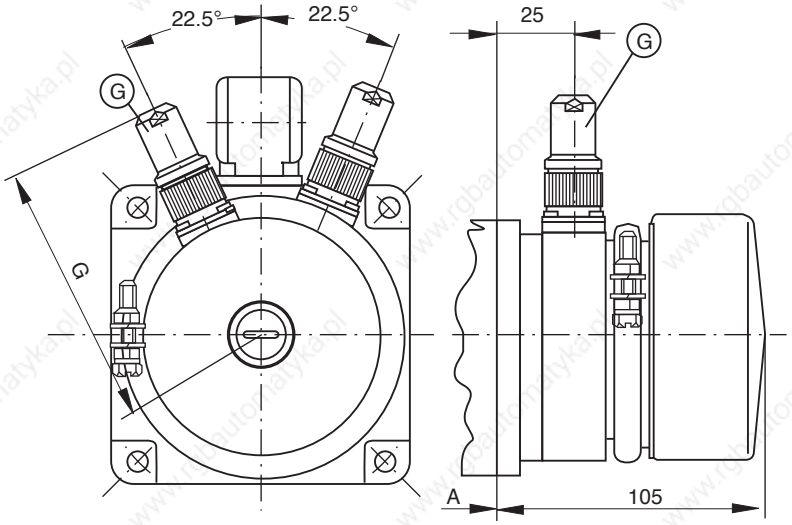
MB093-0/2

Fig 6.14: Dimensional data - MAC 093 - available options - (natural convection)

Available options

• Tachofeedback and mounted absolute encoder

View X:



Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104 106
angle conn.	INS 322	102

3 Blocking brake

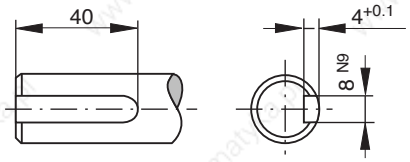
- without blocking brake
  Dim. A retained
- Standard blocking brake: 6.5 Nm
  Dim. A. retained
- heavy-duty blocking brake: 14.0 Nm
- extra heavy-duty blocking brake: 22.0 Nm

Table for blocking brake with 14 and 22 Nm

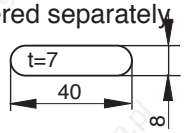
Size \ Dim.	A
MAC 093 A	305
MAC 093 B	346
MAC 093 C	405

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
  (Note! balanced with entire key.)



Matching key: DIN 6885-A 8 x 7 x 40
Must be ordered separately



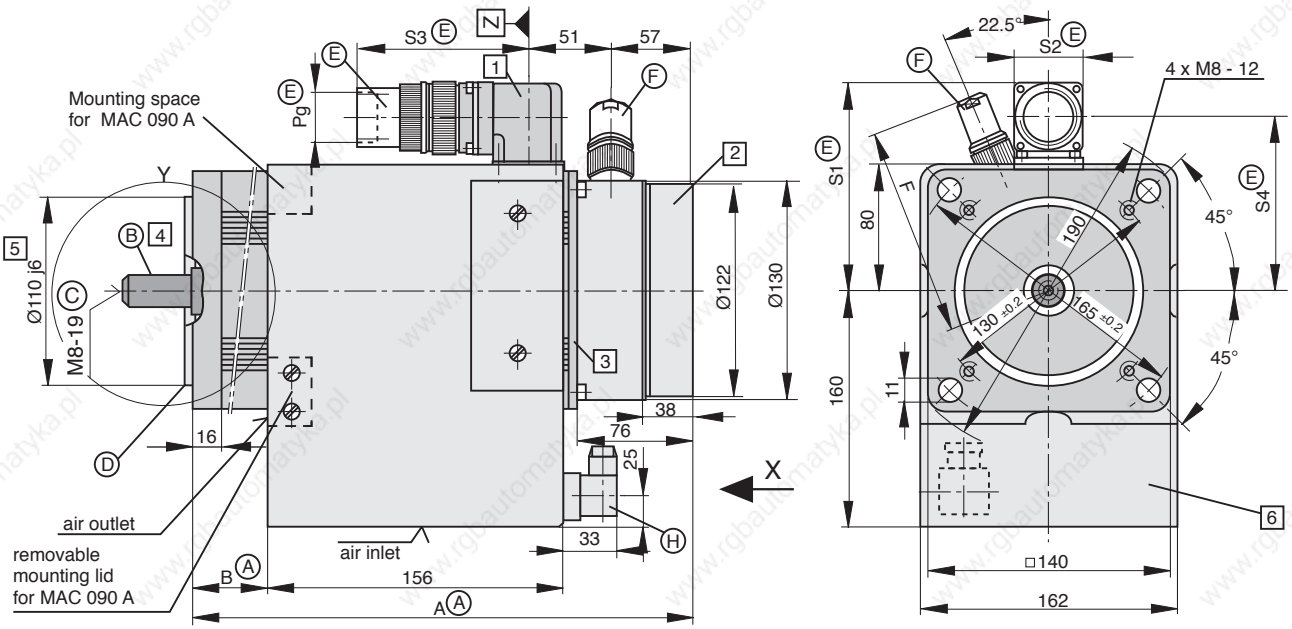
5 Special centering diameter

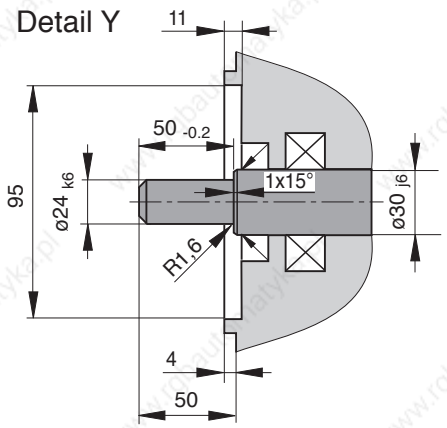
- Ø130 j6

MB093-0/3

Fig 6.15: Dimensional data - MAC 093 - available options - (natural convection)

6.5. Dimensional data - radial cooling





Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M8-19 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 5Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)
- as per design B14 (threads in flange)

Ⓔ **Motor power connector**
Must be ordered separately.

Ⓐ **Dimensional table**

Size \ Dim.	A 1)	B 1)
MAC 093 A	275	76
MAC 093 B	316	73
MAC 093 C	375	132

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Table

Type \ Dim.	S1	S2	S3	S4	Pg
INS 108 3)	122	42	100	107	21
INS 172 2)	135	53	145	109	36

2) with MAC 093 B-•-GS, MAC 093 B-•-ES, MAC 093 C-•-FS, MAC 093 C-•-DS, MAC 093 C-•-CS

3) Other MAC093 •-•-•

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302 INS 102	123 125
angle conn. 4)	INS 352 INS 312	121

MB093-1rad/1

Ⓗ **Blower connector: INS 195**
Must be ordered separately.

4) Not for use in motors with power connector INS 172 and power connector mounting direction towards side B.

Fig 6.16: Dimensional data - MAC 093 (radial cooling)

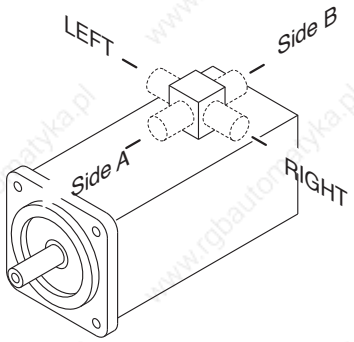
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

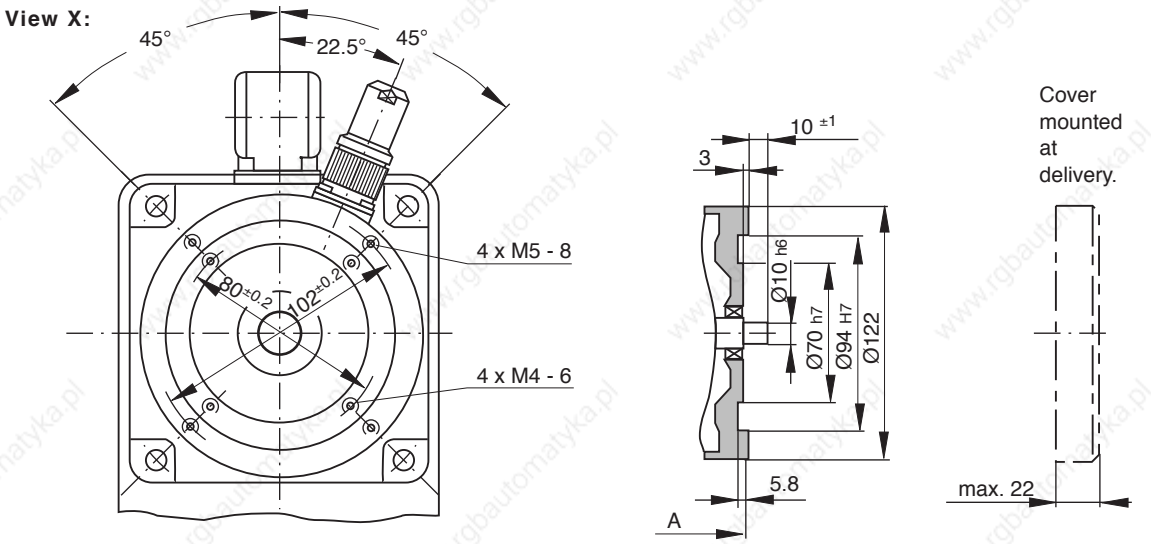
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

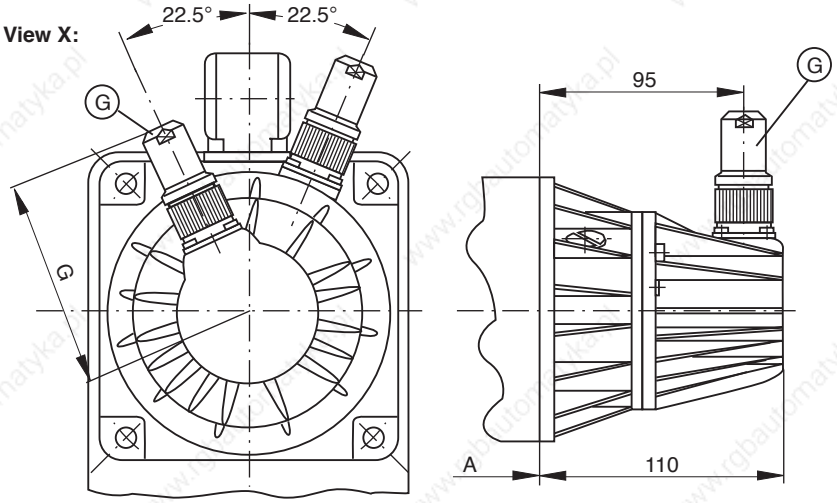


2 Motor version

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



G Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder (see following page)

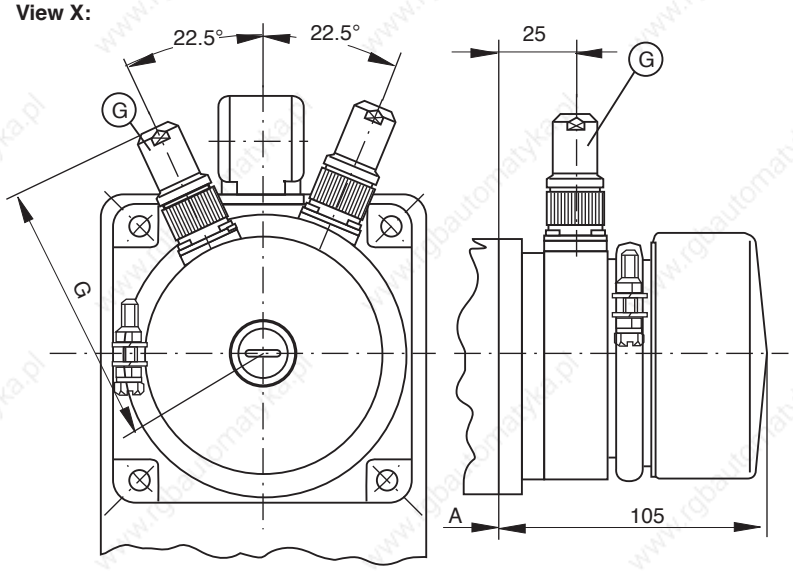
MB090-1rad/2

Fig 6.17: Dimensional data - MAC 093 - available options - (radial cooling)

Available options

• Tachofeedback and mounted absolute encoder

View X:



Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104 106
angle conn.	INS 322	102

3 Blocking brake

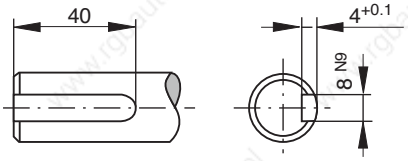
- without blocking brake
  Dim. A and B retained
- Standard blocking brake: 6.5 Nm
  Dim. A and B retained
- heavy-duty blocking brake: 14.0 Nm
- extra heavy-duty blocking brake: 22.0 Nm

Table for blocking brake with 14 and 22 Nm

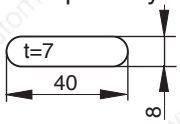
Size \ Dim.	A	B
MAC 093 A	305	106
MAC 093 B	346	103
MAC 093 C	405	162

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
  (Note! balanced with entire key.)



Matching key: DIN 6885-A 8 x 7 x 40
Must be ordered separately.

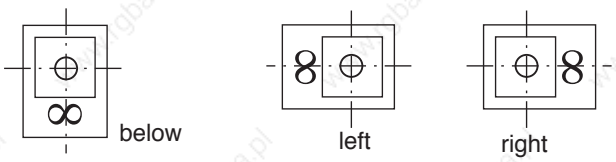


5 Special centering diameter

- Ø130 j6

6 Blower arrangement

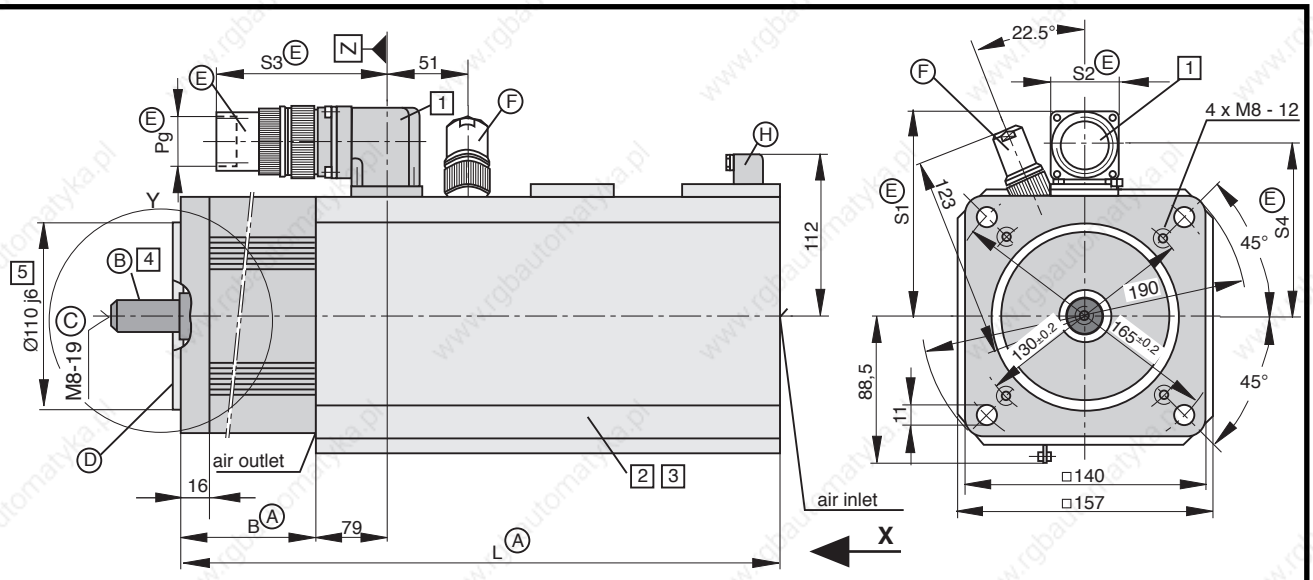
Looking towards motor shaft.

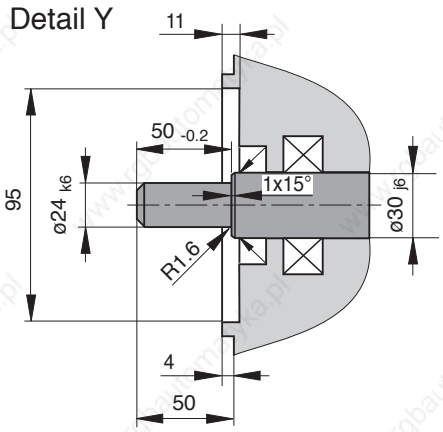


MB093-1rad/3

Fig 6.18: Dimensional data - MAC 093 - available options - (radial cooling)

6.6. Dimensional Data - Axial Cooling





Ⓐ **Dimensional table**

Size \ Dim.	A 1)	B 1)
MAC 093 A	354	89
MAC 093 B	395	130
MAC 093 C	454	189

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M8-19 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 5Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)
- as per design B14 (threads in flange)

Ⓔ **Motor power connector**
Must be ordered separately**.**

Table

Type \ Dim.	S1	S2	S3	S4	Pg
INS 108 3)	122	42	100	107	21
INS 172 2)	135	53	145	109	36

2) with MAC 093 B-•-GS, MAC 093 B-•-ES, MAC 093 C-•-FS, MAC 093 C-•-DS, MAC 093 C-•-CS

3) other MAC093 •-•-•

Ⓕ **Tachofeedback connector:**
Must be ordered separately; types INS 302 or INS 102

Ⓗ **Blower connector: INS 195**
Must be ordered separately.

MB093-1/1

Fig 6.19: Dimensional data - MAC 093 (axial cooling)

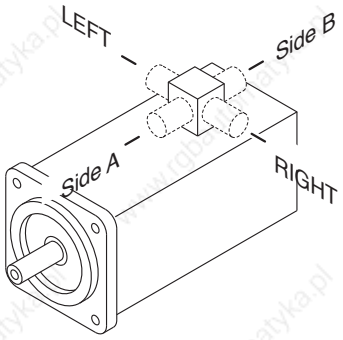
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

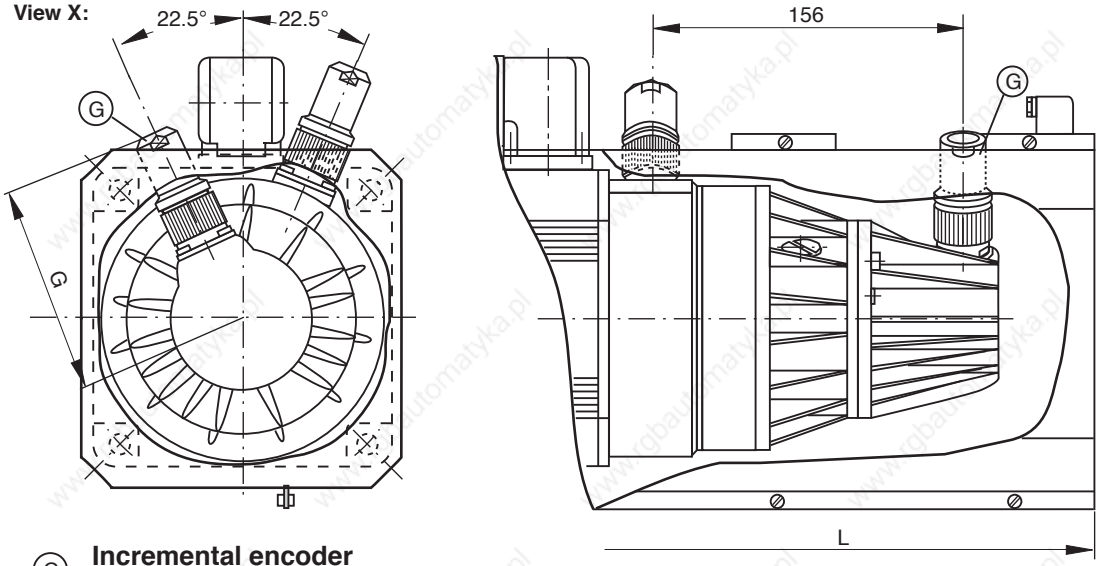
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.



2 Motor version

- Tachofeedback and mounted incremental encoder



Ⓖ Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301	123
	INS 101	125

Table:

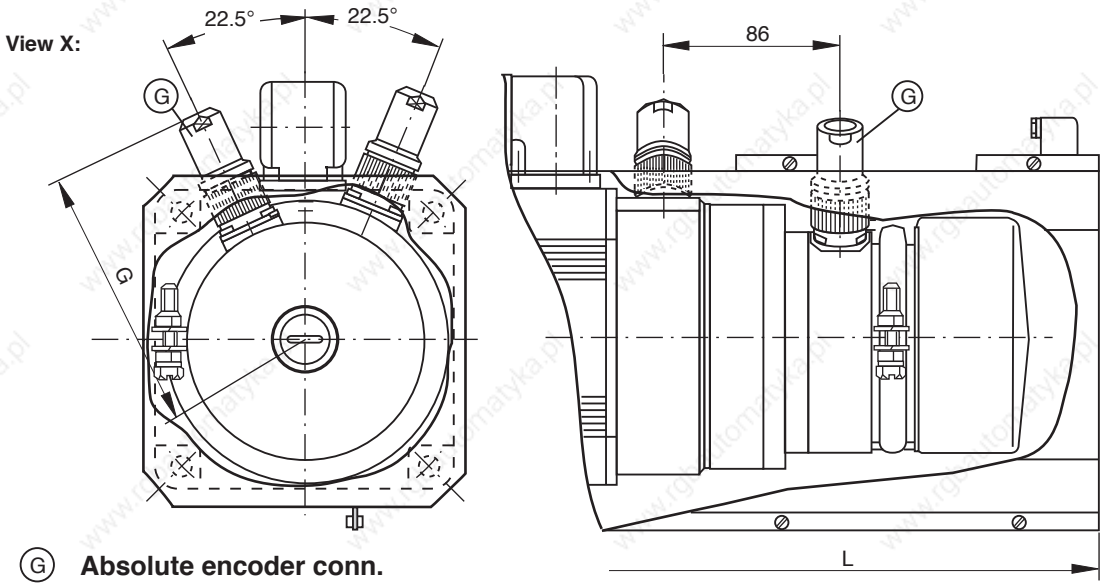
Size \ Dim.	L	B
MAC 093 A	454	89
MAC 093 B	495	130
MAC 093 C	554	189

MB093-1/2

Fig 6.20: Dimensional data - MAC 093 - available options - (axial cooling)

Available options

• Tachofeedback and mounted absolute encoder



Ⓖ **Absolute encoder conn.**

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326	104
	INS 92	106

Size \ Dim.	L	B
MAC 093 A	454	89
MAC 093 B	495	130
MAC 093 C	554	189

3 Blocking brake

- without blocking brake
  Dim. L and B retained
- Standard blocking brake: 6.5 Nm
  Dim. L and B retained
- heavy-duty blocking brake: 14.0 Nm
- extra heavy-duty blocking brake: 22.0 Nm

Table for blocking brake with 14 and 20 Nm

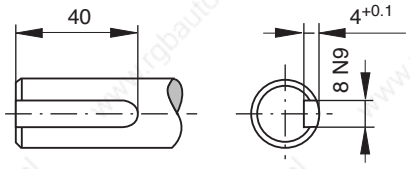
Size \ Dim.	Vers. 2 L	Vers. 2 B	Vers. 4 L	Vers. 4 B
MAC 093 A	384	119	484	119
MAC 093 B	425	160	525	160
MAC 093 C	484	219	584	219

Vers. 2 = Motor with tachofeedback

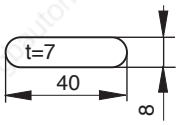
Vers. 4 = Motor with tachofeedback and mounted encoder

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
  (Note! balanced with entire key.)



Matching key: DIN 6885-A 8 x 7 x 50
Must be ordered separately.



5 Special centering diameter

• Ø130 j6

MB093-1/3

Fig 6.21: Dimensional data - MAC 093 - available options - (axial cooling)

6.7. Available Options

Type code fields — Example: MAC 093 A-0-LS-4 - C/110-A-0/WI 520LV/S000

1. Motor for analogue drives	MAC
2. Motor size	093
3. Motor length	A, B, C

4. Type of cooling:

natural convection	surface cooling							
	axial		radial					
			blower right		blower below		blower left	
	AC 230 V	AC 115 V	AC 230 V	AC 115 V	AC 230 V	AC 115 V	AC 230 V	AC 115 V
0	1[1]	2[1]	6	A	7	B	8	C

5. Type of windings

Nominal rpm	Motor length		
	A	B	C
2000 min^{-1}	WS	OS	KS
3000 min^{-1}	PS	JS	FS
4000 min^{-1}	LS	GS	DS
6000 min^{-1}	HS	ES	CS

6. Motor feedback

Motor type	
with tachofeedback	2
with tachofeedback and second shaft end	3
with tachofeedback and mounted incremental or absolute encoder	4

Tacho voltage	
set to nominal motor speed (nominal rpm > 3000 min^{-1} : 1,5 V/1000 min^{-1}) (nominal rpm ≤ 3000 min^{-1} : 3 V/1000 min^{-1})	-
1.5 V/1000 min^{-1}	H

Tacho type	
Standard	C
increased smooth run quality	F

7. Centering diameter

for design B05 and B14	110
for design B05 and B14	130

8. Power connection

connector to side A	A
connector to side B	B
connector to right (looking onto output shaft)	R
connector to left (looking onto output shaft)	L

9. Blocking brake

without blocking brake	0
with standard blocking brake (6.5 Nm)	1
with heavy-duty blocking brake (14 Nm)	2
with extra heavy-duty blocking brake (22 Nm)	3

Mounted encoder

10. Type [2]

Incremental encoder with standard mounting	WI
Incremental encoder with shock-damped mounting	DI
Absolute encoder	AM

11. Encoder code [2]

For available types, see section 2.4 "Motor feedback"

12. Special types
Fixed and documented by INDRAMAT with special number (see Drawing no.: 106-0105-4301-XX)
Does not apply to standard motors.

1) For type 3 motors (with 2nd shaft end and tachofeedback). Not available with axial surface cooling.

2) Type code fields 10 and 11 do not apply to motor types 2 and 3.

TLMAC093

Fig 6.22: Type codes - MAC 093

6.8. Special Options

Specification of Option	S005
with keyway per DIN 6885, sheet 1	X

Fig 6.23: Special options with a MAC 093

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7. MAC 112

7.1. Technical Data

Designation	Symbol	Unit	Motor type MAC …			
			112 A - • - Z •	**112 B - • - P •**	**112 C - • - K •**	**112 D - • - H •**
Nominal motor speed [1]	n	min^{-1}	1500	1500	1500	1500
Continuous torque at standstill [2]	M_{dN}	Nm	10.7 (13.0) [5]	18.2 (29) [5]	28.0 (44.0) [5]	38.0 (57.0) [5]
Continuous current at standstill	I_{dN}	A	14.5 (17.2) [5]	21.0 (33.0) [5]	31.0 (49.0) [5]	42.0 (63) [5]
Rotor moment of inertia [3]	J_M	kgm^2	61×10^{-4}	120×10^{-4}	170×10^{-4}	230×10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.820	0.910	1.000	1.010
Windings resistance at 20 °C	R_A	Ohm	0.990	0.450	0.270	0.176
Windings inductance	L_A	mH	10.0	6.3	4.5	3.2
Maximum peak of pulse current	I_{peak}	A	54	97	141	195
Thermal time constant	T_{th}	min	100 (75)[5]	90 (60)[5]	100 (75)[5]	120 (90)[5]
Mass [4]	m_M	kg	25	36	48	59
			112 A - • - V •	**112 B - • - L •**	**112 C - • - H •**	**112 D - • - F •**
Nominal motor speed [1]	n	min^{-1}	2000	2000	2000	2000
Continuous torque at standstill [2]	M_{dN}	Nm	10.5 (13.0) [5]	17.5 (29) [5]	27.0 (44.0) [5]	38.0 (57.0) [5]
Continuous current at standstill	I_{dN}	A	18.5 (22.9) [5]	26.3 (43.5) [5]	41.0 (67.0) [5]	56.0 (83) [5]
Rotor moment of inertia [3]	J_M	kgm^2	61×10^{-4}	120×10^{-4}	170×10^{-4}	230×10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.630	0.740	0.730	0.760
Windings resistance at 20 °C	R_A	Ohm	0.650	0.260	0.150	0.110
Windings inductance	L_A	mH	6.0	3.5	2.5	1.8
Maximum peak of pulse current	I_{peak}	A	71	130	195	260
Thermal time constant	T_{th}	min	100 (75) [5]	90 (60) [5]	100 (75) [5]	120 (90) [5]
Mass [4]	m_M	kg	25	36	48	59
			112 A - • - L •	**112 B - • - G •**	**112 C - • - E •**	**112 D - • - E •**
Nominal motor speed [1]	n	min^{-1}	3000	3000	3000	3000
Continuous torque at standstill [2]	M_{dN}	Nm	9.8 (13.0) [5]	16.0 (29) [5]	24.0 (44.0) [5]	35.0 (57.0) [5]
Continuous current at standstill	I_{dN}	A	31.0 (41.3) [5]	41.0 (75.0) [5]	57.0 (104) [5]	63.0 (102) [5]
Rotor moment of inertia [3]	J_M	kgm^2	61×10^{-4}	120×10^{-4}	170×10^{-4}	230×10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.350	0.430	0.470	0.620
Windings resistance at 20 °C	R_A	Ohm	0.180	0.090	0.060	0.070
Windings inductance	L_A	mH	1.9	1.2	1.0	1.3
Maximum peak of pulse current	I_{peak}	A	130	223	312	312
Thermal time constant	T_{th}	min	100 (75) [5]	90 (60) [5]	100 (75) [5]	120 (90) [5]
Mass [4]	m_M	kg	25	36	48	59
					112 C - • - C •	
Nominal motor speed [1]	n	min^{-1}			5000	
Continuous torque at standstill [2]	M_{dN}	Nm			27.0	
Continuous current at standstill	I_{dN}	A			87.5	
Rotor moment of inertia [3]	J_M	kgm^2			170×10^{-4}	
Torque constant at 20 °C	K_m	Nm/A			0.330	
Windings resistance at 20 °C	R_A	Ohm			0.030	
Windings inductance	L_A	mH			0.5	
Maximum peak of pulse current	I_{peak}	A			400	
Thermal time constant	T_{th}	min			100	
Mass [4]	m_M	kg			48	

[1] The usable motor speed is determined by the drive used.
Only those usable speeds n_{max} found in the selection lists of the motor-drive combinations are binding.
[2] With 60K overtemperature at the motor housing.
Continuous torque can be limited by the drive. See selection data.
[3] With tacho-generator, without holding brake
[4] With tacho-generator, without holding brake, without blower.
[5] Parenthetical values apply to versions with surface cooling.

Fig 7.1: Type-dependent motor data

Designation	Symbol	Unit	Data		
Permissible ambient temperature	T_{um}	°C	0 … + 45		
Permissible storage and transport temperature	T_L	°C	-20 … +80		
Maximum installation elevation		m	1000 m. above sea level		
Protection category			IP 65		
Insulation classification			F		
Housing coat			Black prime coat (RAL9005)		
Voltage constant of the tachogenerator [1]	C_w	Vs/rad V/min^{-1}	0.0143 1.5/1000	0.0286 3/1000	0.0572 6/1000 [2]

[1] Tachovoltage can be selected application-related.
[2] If 6 V/1000 min^{-1} tachometer is used, then usable speed is limited to 1600 min^{-1}.

Fig 7.2: General data MAC 112

Designation	Symbol	Unit	Data holding brake		
			Standard	heavy-duty [1]	extra heavy-duty [1]
Principle of action				electrically released	
Holding torque	M_H	Nm		40	
Nominal voltage	U_N	V	14	DC 24 ± 10%	60
Nominal current	I_N	A	0.75	1.35	1.35
Moment of inertia	J_B	kgm^2	3.6×10^{-4}	32×10^{-4}	32×10^{-4}
Release delay	t_L	ms	70	150	150
Clamping delay	t_K	ms	30	30	30
Mass	m_B	kg	1.1	3.5	3.5

[1] Not available with MAC 112A .

Fig 7.3: Technical data - holding brake

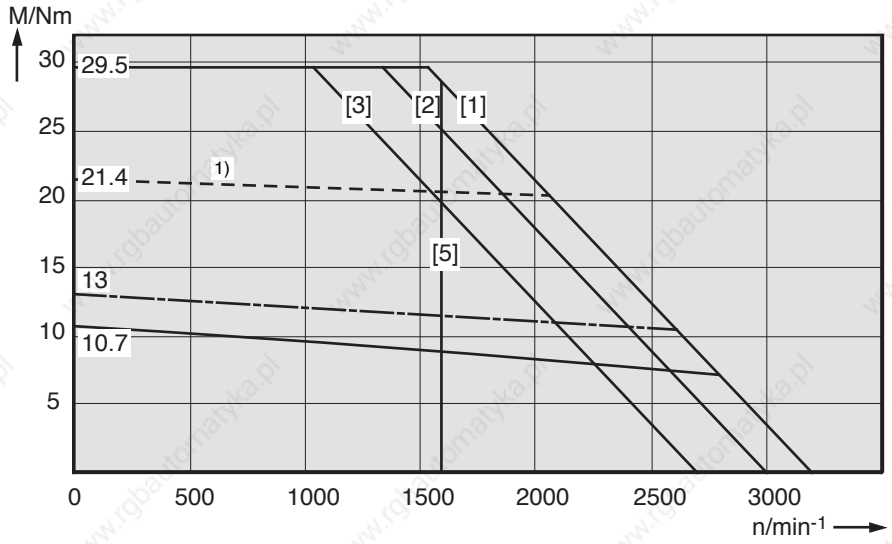
Designation	Symbol	Unit	Axial cooling	Radial cooling
Power consumption	S_N	VA	40/42	40/42
Nominal voltage	U_N	V	AC 230 or 115 [1]	AC 230 or 115 [1]
Frequency	f	Hz	50/60	50/60
Mass	m_L	kg	approx.. 3.3 [2]	approx.. 3.2 [2]
Protection category blower unit			IP 24	IP 24
Protection category blower motor			IP 44	IP 44

[1] 115 V special design
[2] Blower shroud for motor with tacho feedback.

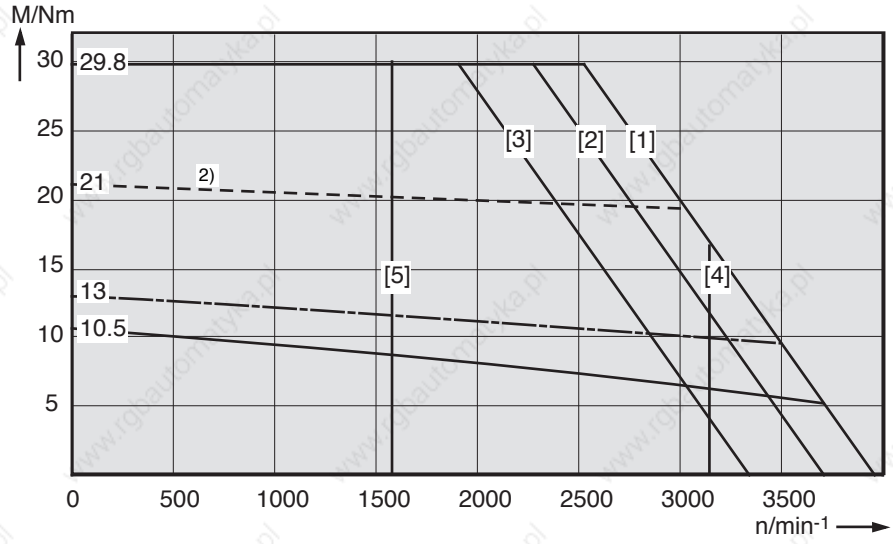
Fig 7.4: Technical data - surface cooling

7.2. Torque-Speed Characteristics

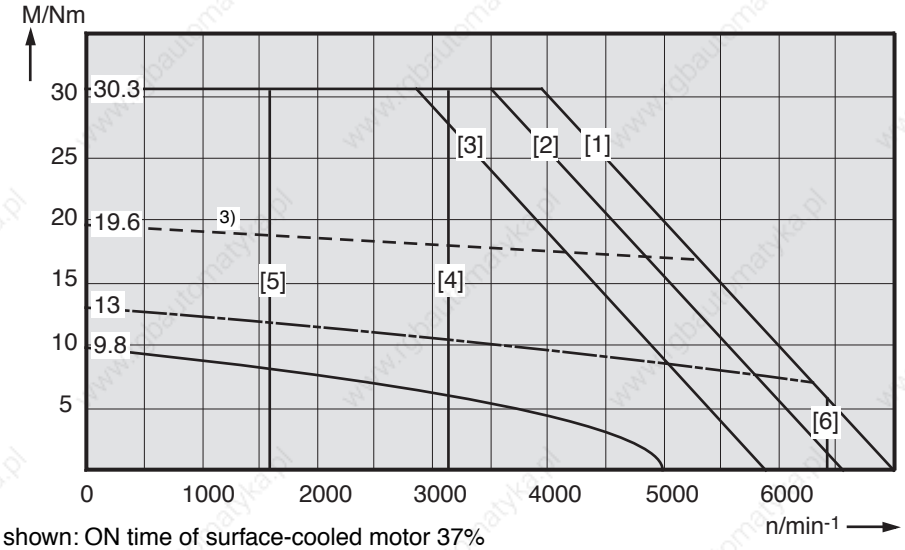
MAC 112 A - • - Z •
1500 min^{-1}



MAC 112 A - • - V •
2000 min^{-1}



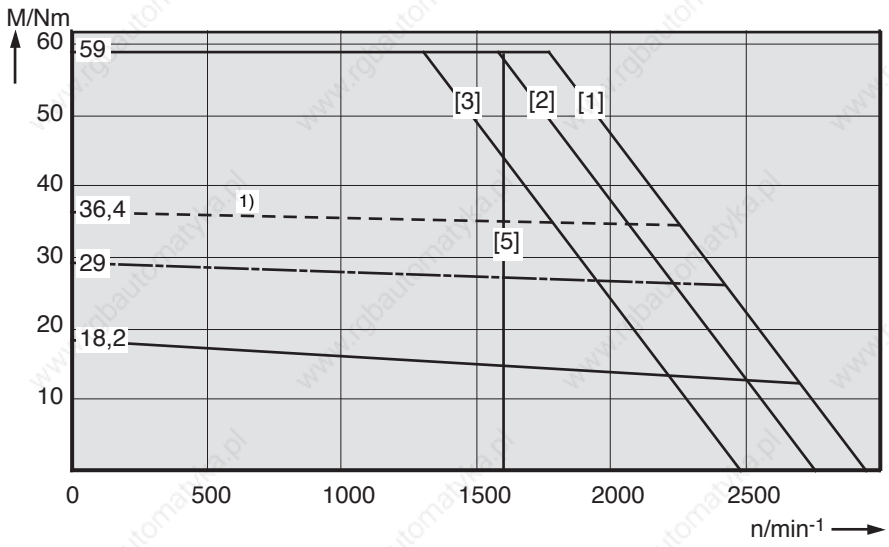
MAC 112 A - • - L •
3000 min^{-1}



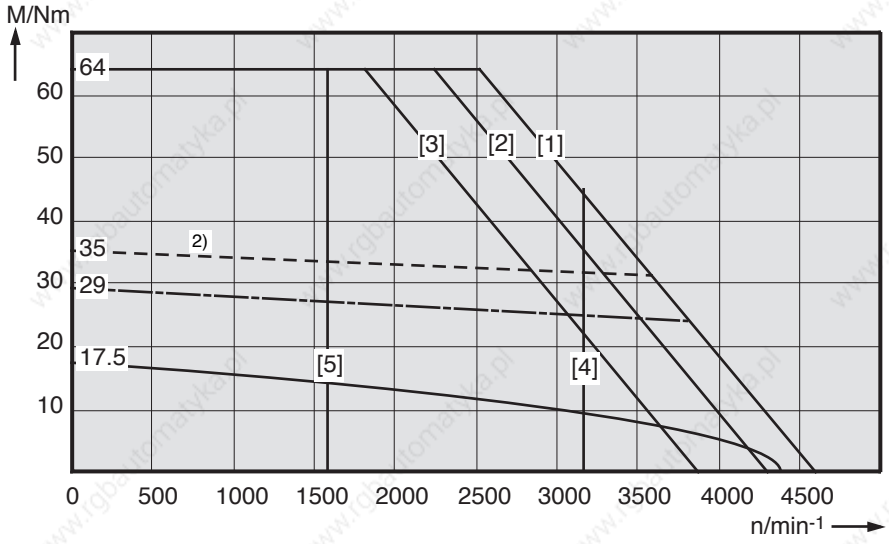
1) shown: ON time of surface-cooled motor 37%
2) shown: ON time of surface-cooled motor 38%
3) shown: ON time of surface-cooled motor 44%

Fig 7.5: Torque-speed characteristics MAC 112

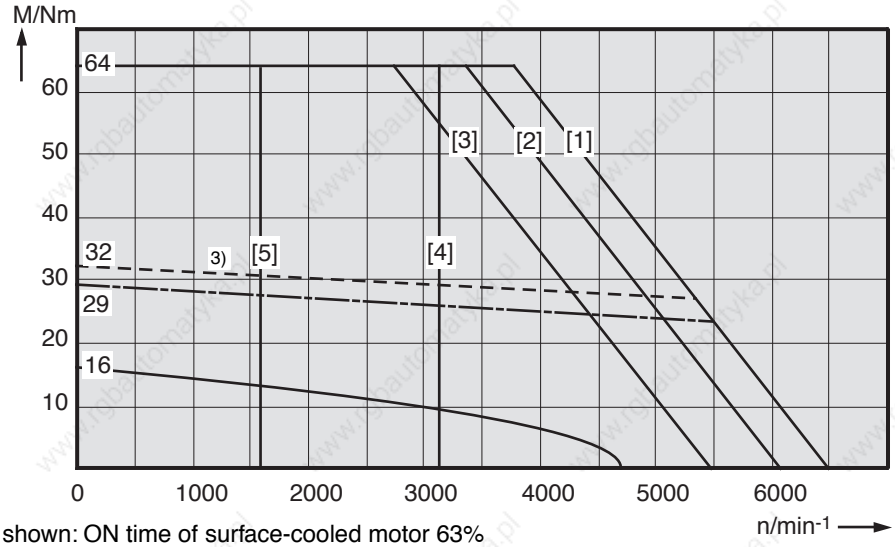
MAC 112 B - • - P •
1500 min^{-1}



MAC 112 B - • - L •
2000 min^{-1}



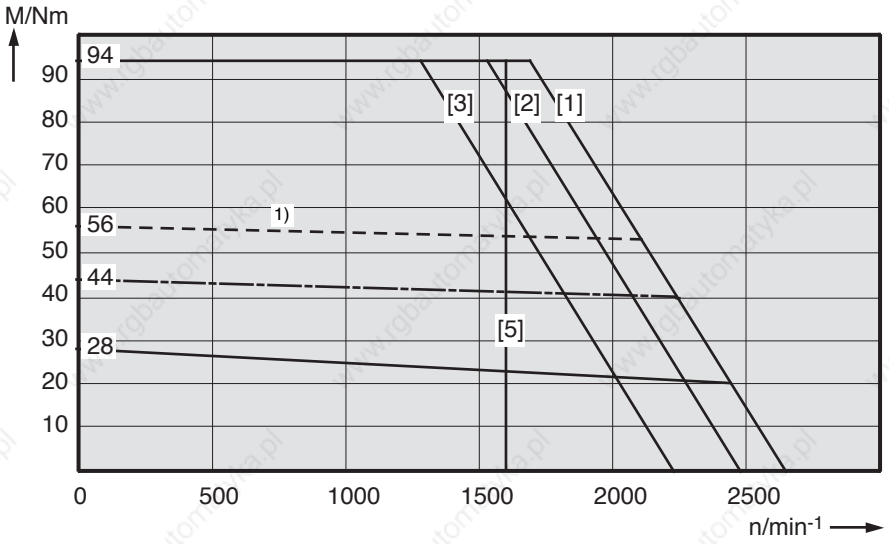
MAC 112 B - • - G •
3000 min^{-1}



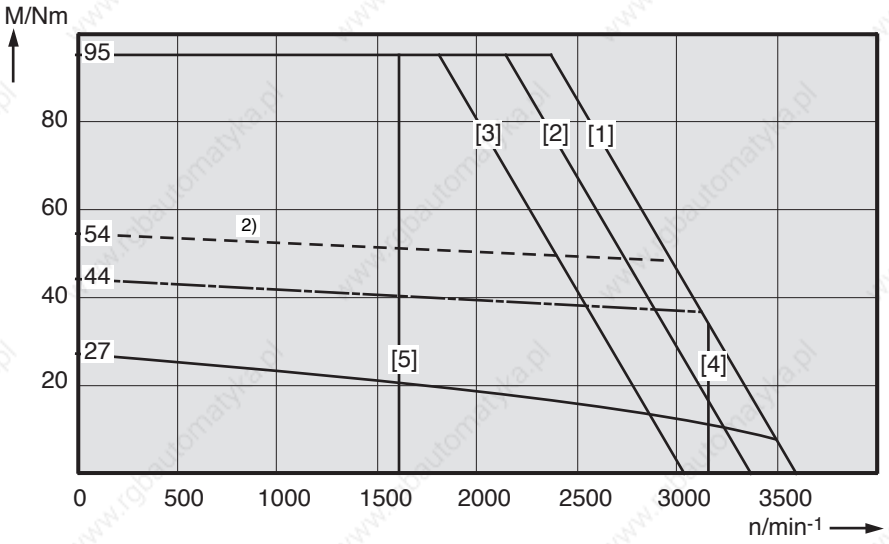
1) shown: ON time of surface-cooled motor 63%
2) shown: ON time of surface-cooled motor 69%
3) shown: ON time of surface-cooled motor 82%

Fig 7.6: Torque-speed characteristics MAC 112

MAC 112 C - • - K •
1500 min^{-1}



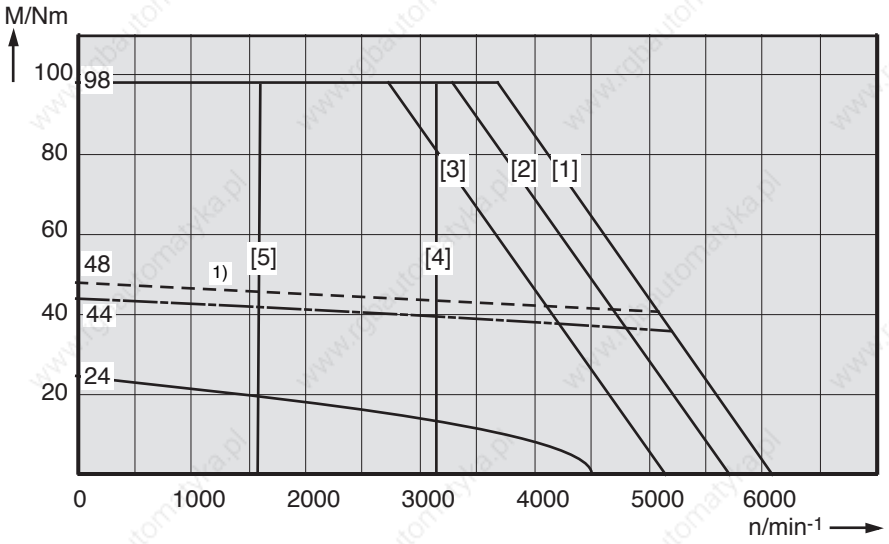
MAC 112 C - • - H •
2000 min^{-1}



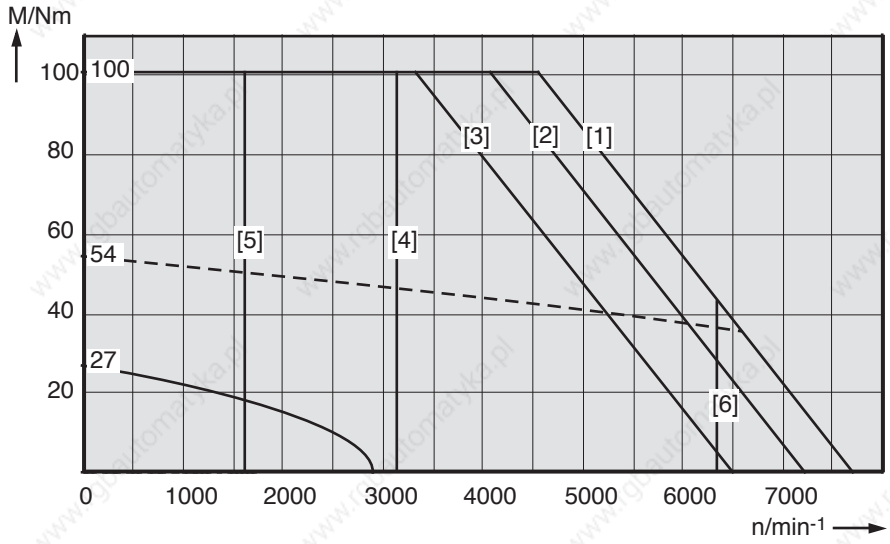
1) shown: ON time of surface-cooled motor 62%
2) shown: ON time of surface-cooled motor 66%

Fig 7.7: Torque-speed characteristics MAC 112

MAC 112 C - • - E •
3000 min^{-1}



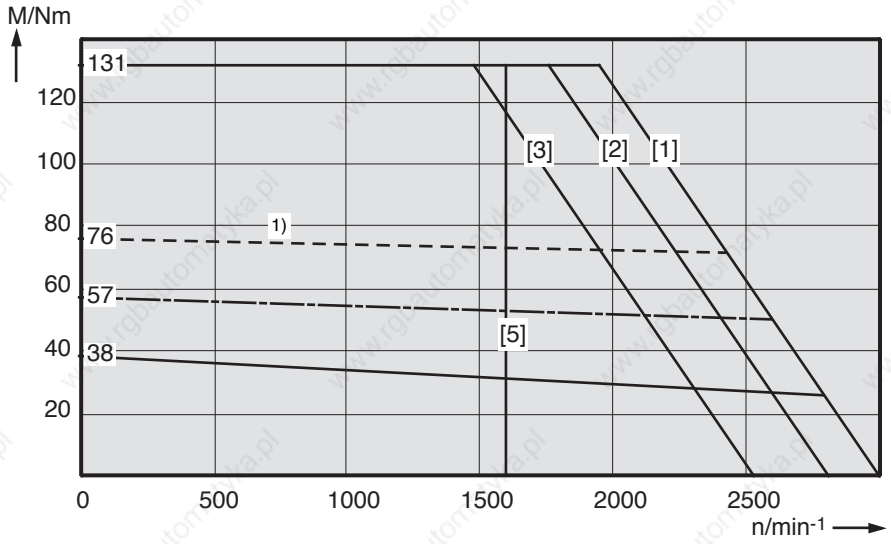
MAC 112 C - • - C •
5000 min^{-1}



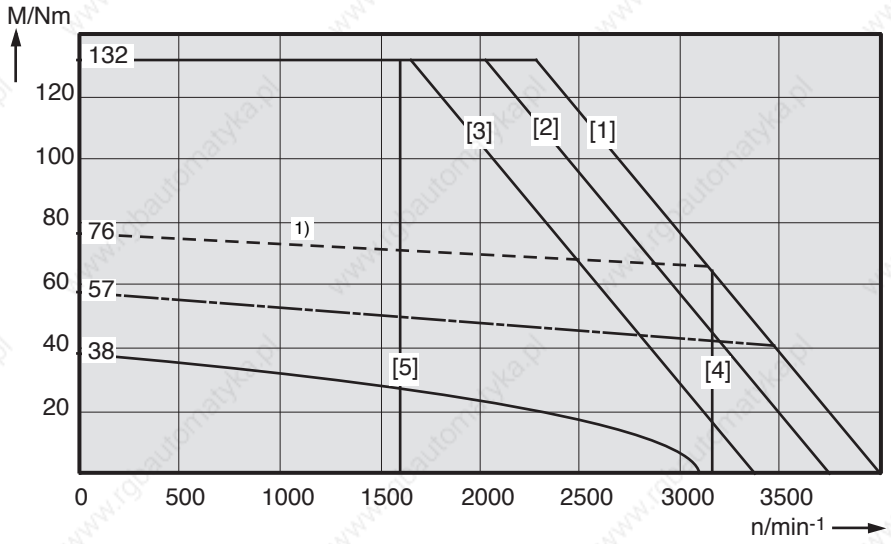
1) shown: ON time of surface-cooled motor 87%

Fig 7.8: Torque-speed characteristics MAC 112

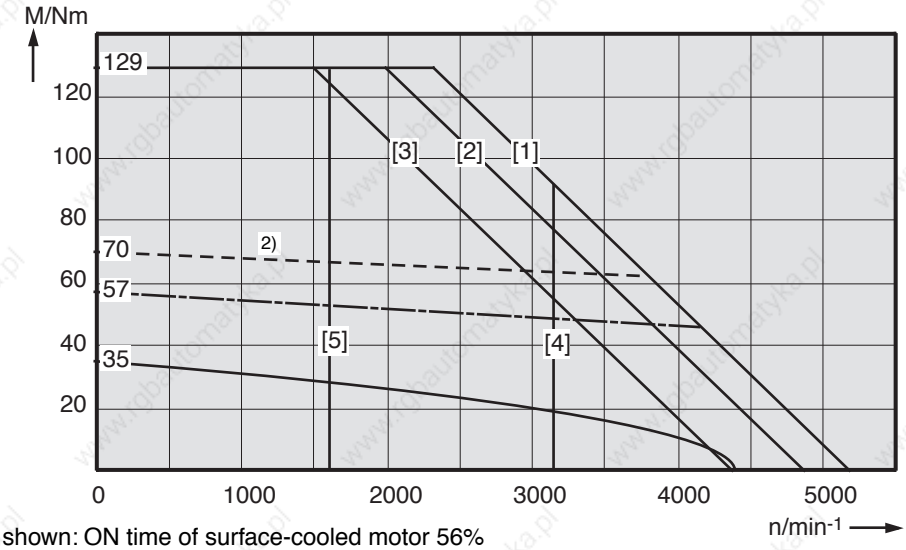
MAC 112 D - • - H •
1500 min^{-1}



MAC 112 D - • - F •
2000 min^{-1}



MAC 112 D - • - E •
3000 min^{-1}



1) shown: ON time of surface-cooled motor 56%
2) shown: ON time of surface-cooled motor 66%

Fig 7.9: Torque-speed characteristics MAC 112

7.3. Shaft load capacity

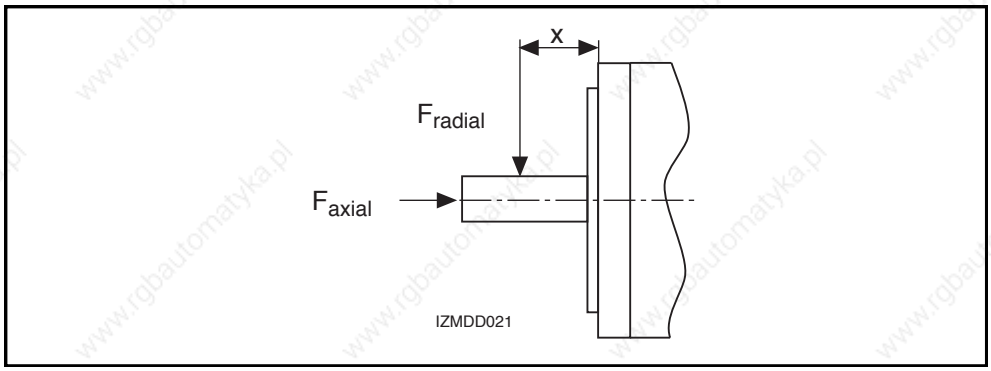


Fig 7.10: Shaft load

Permissible radial force F_{radial}

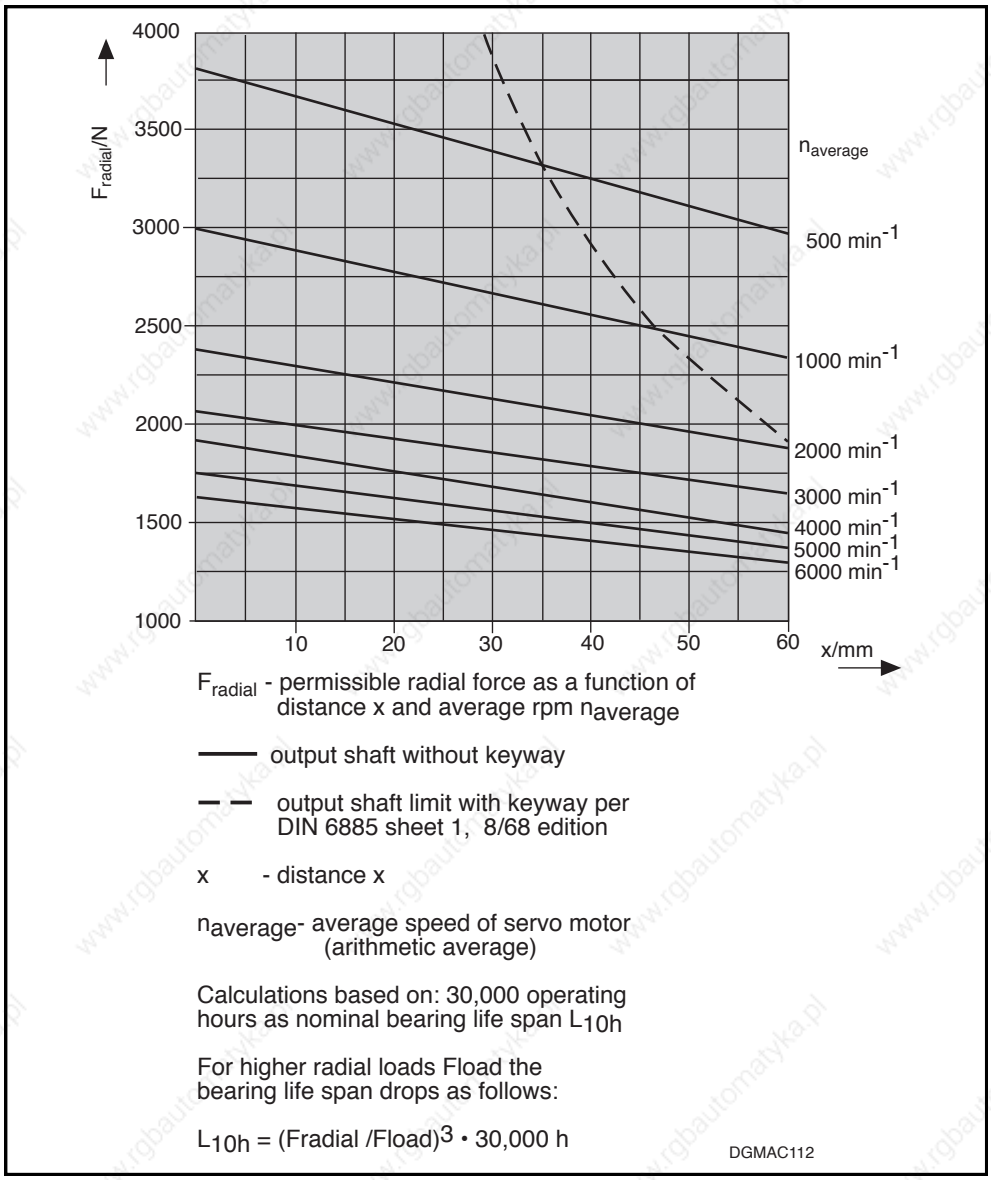


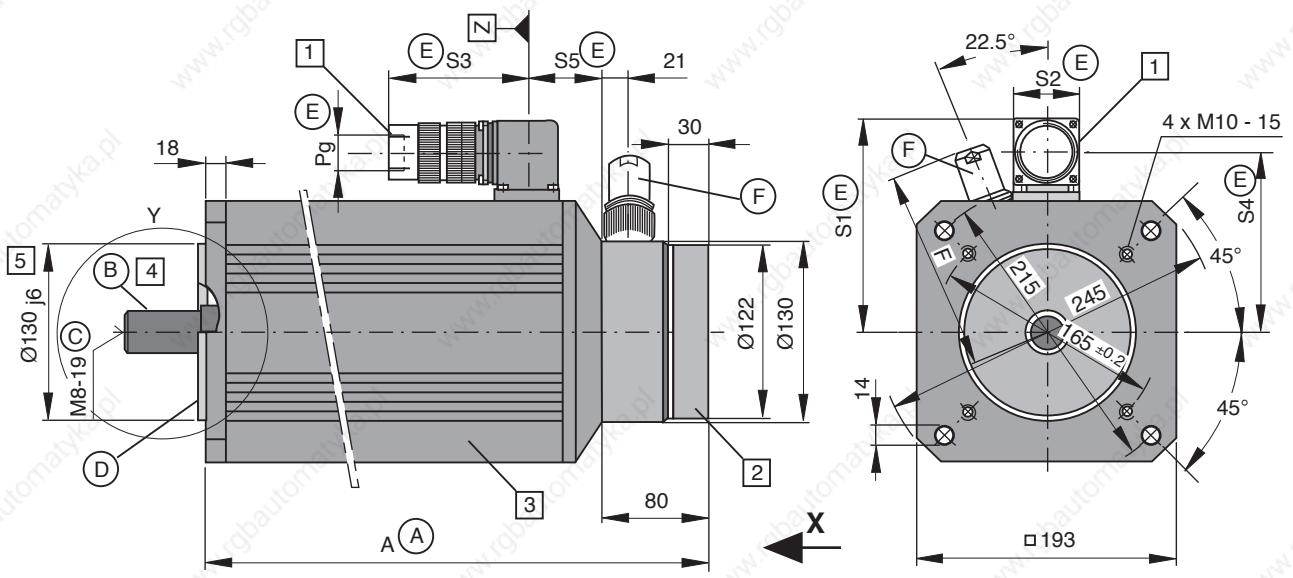
Fig 7.11: Permissible radial force

Permissible axial force F_{axial}

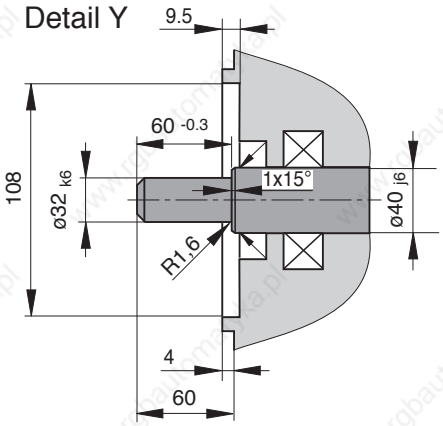
$$F_{axial} = 0.35 \cdot F_{radial}$$

F_{axial} - Permissible axial force
F_{radial} - Permissible radial force

7.4. Dimensional data - natural convection



Detail Y



Ⓐ **Dimensional table Dim. A**

Size \ Dim.	A[1)]
MAC 112 A	310
MAC 112 B	385
MAC 112 C	460
MAC 112 D	535

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M8-19 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 5Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)
- as per deisgn B14 (threads in flange)

Ⓔ **Motor power connector**
Must be ordered separately; depends on motor

Table

Type \ Dim.	S1	S2	S3	S4	S5[1)]	Pg
INS 108 [3)]	150	42	100	133	50	21
INS 172 [2)]	163	53	145	137	50	36

2) with MAC112 C-0-E, MAC112 C-0-C, MAC112 D-0-F, MAC112 D-0-E

3) other MAC112 •-0-•

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302	123
	INS 102	125
angle conn.	INS 352	121
	INS 312	

MB112-0/1

Fig 7.12: Dimensional data - MAC 112 (natural convection)

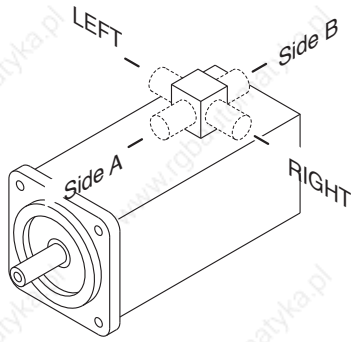
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

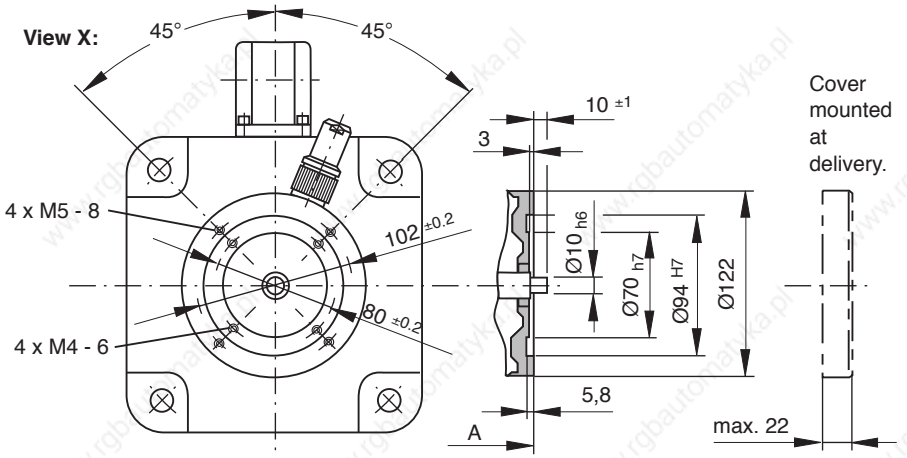
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

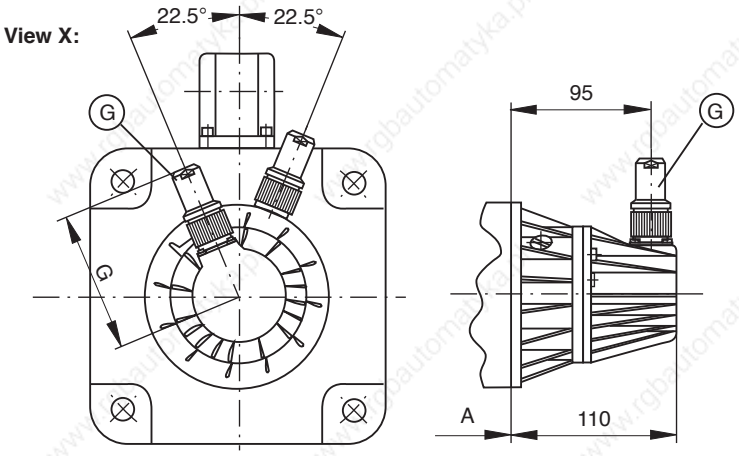


2 Motor version

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



G Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder (see following page)

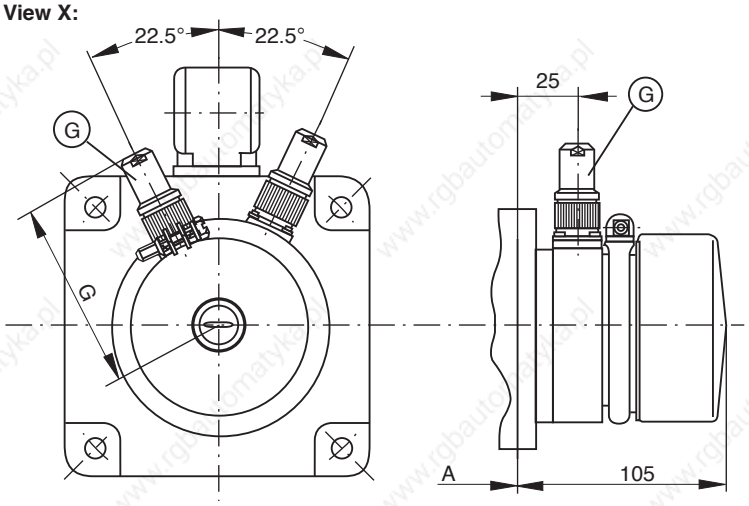
MB112-0/2

Fig 7.13: Dimensional data - MAC 112 - available options - (natural convection)

Available options

• Tachofeedback and mounted absolute encoder

View X:



Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104 106
angle conn.	INS 322	102

3 Blocking brake

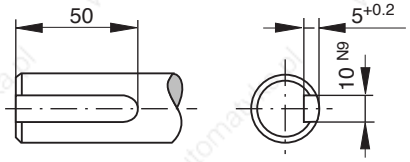
- without blocking brake
  Dim. A and S5 retained
- Standard blocking brake: 14 Nm
  Dim. A and S5 retained
- heavy-duty blocking brake: 40 Nm
  (not available with MAC 112 A ...)
- extra heavy-duty blocking brake: 60 Nm
  (not available with MAC 112 A ...)

Table for blocking brake with 40 and 60 Nm

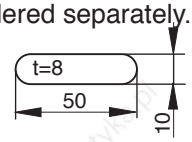
Size \ Dim.	A	S5
MAC 112 B	435	98
MAC 112 C	510	98
MAC 112 D	585	98

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
  (Note! balanced with entire key.)



Matching key: DIN 6885-A 10 x 8 x 50
Must be ordered separately.



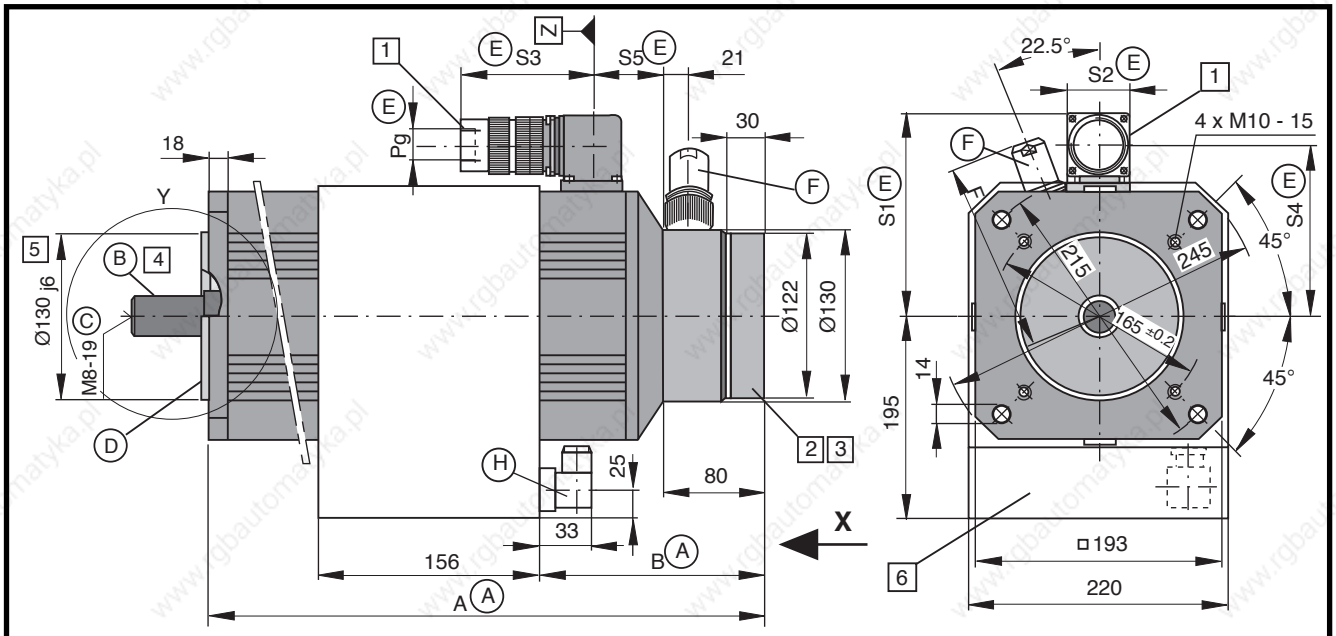
5 Special centering diameter

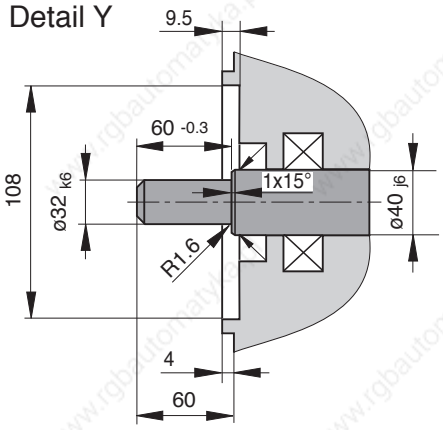
- ø 180 j6

MB112-0/3

Fig 7.14: Dimensional data - MAC 112 - available options - (natural convection)

7.5. Dimensional data - radial cooling





Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M8-19 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 5 Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)
- as per design B14 (threads in flange)

Ⓔ **Motor power connector**
Must be ordered separately.

Table

Type \ Dim.	S1	S2	S3	S4	S5[1]	Pg
INS 108 [2]	150	42	100	133	50	21
INS 172 [3]	163	53	145	137	50	36

[2] with MAC112 A-•-Z, MAC112 A-•-V, MAC112 A-•-C, MAC112 B-•-P, MAC112 B-•-L

[3] other MAC112 •-•-•

Ⓐ **Dimensional table Dim. A and B**

Size \ Dim.	A[1]	B[1]
MAC 112 A	310	110
MAC 112 B	385	110
MAC 112 C	460	205
MAC 112 D	535	205

[1] Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302	123
	INS 102	125
angle conn.	INS 352	121
	INS 312	

Ⓗ **Blower connector: INS 195**
Must be ordered separately.

MB112-1rad/1

Fig 7.15: Dimensional data - MAC 112 (radial cooling)

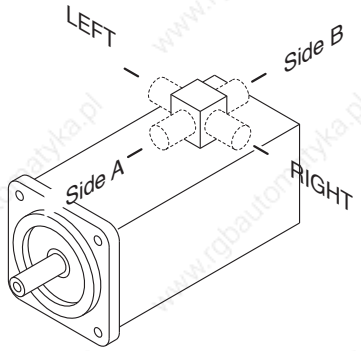
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

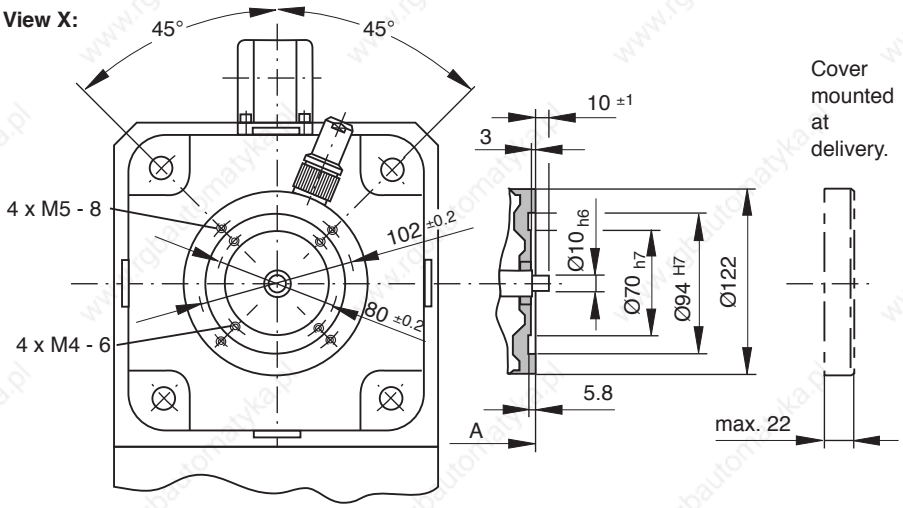
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

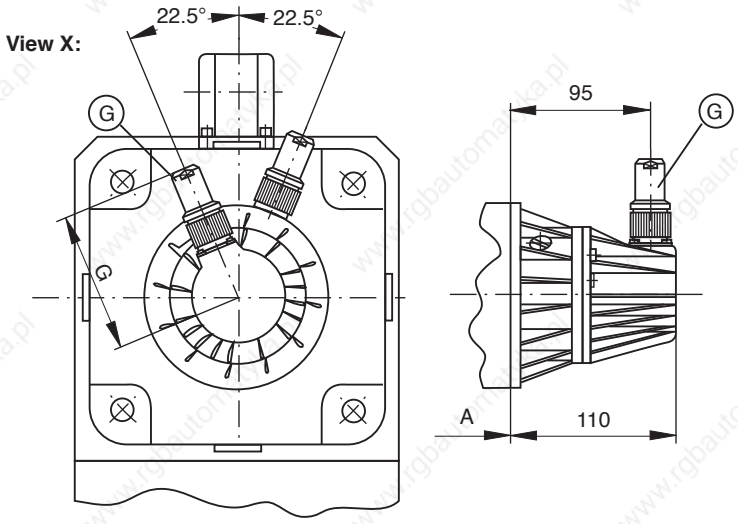


2 Motor version

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



G Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder (see following page)

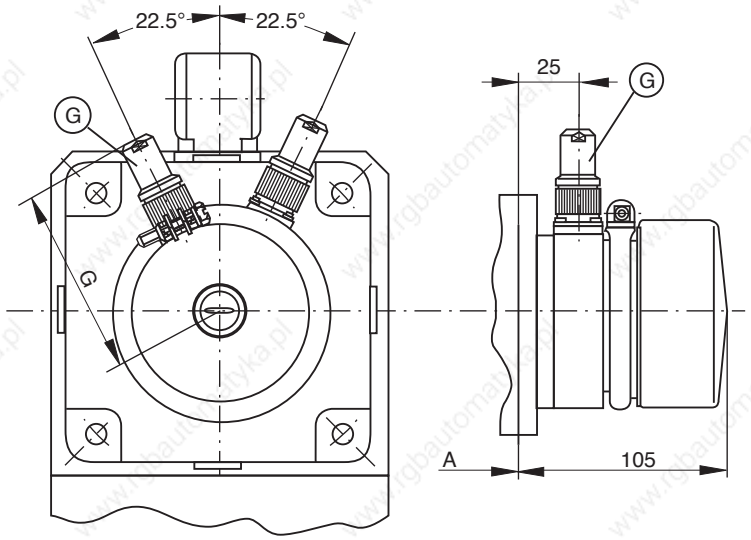
MB112-1rad/2

Fig 7.16: Dimensional data - MAC 112 - available options - (radial cooling)

Available options

• Tachofeedback and mounted absolute encoder

View X:



Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104 106
angle conn.	INS 322	102

3 Blocking brake

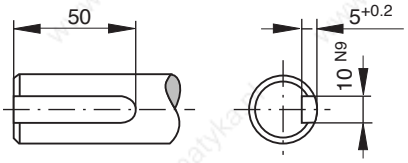
- without blocking brake
  Dim. A, B and S5 retained
- Standard blocking brake: 14 Nm
  Dim. A, B and S5 retained
- heavy-duty blocking brake: 40 Nm
  (not available with MAC 112 A ...)
- extra heavy-duty blocking brake: 60 Nm
  (not available with MAC 112 A ...)

Table for blocking brake with 40 and 60 Nm

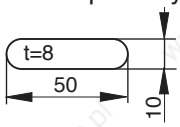
Size \ Dim.	A	S5	B
MAC 112 B	435	98	160
MAC 112 C	510	98	255
MAC 112 D	585	98	255

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
  (Note! balanced with entire key.)



Matching key: DIN 6885-A 10 x 8 x 50
Must be ordered separately.

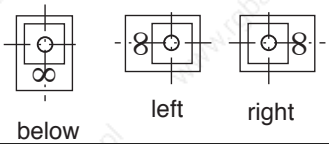


5 Special centering diameter

- ø 180 j6

6 Blower arrangement

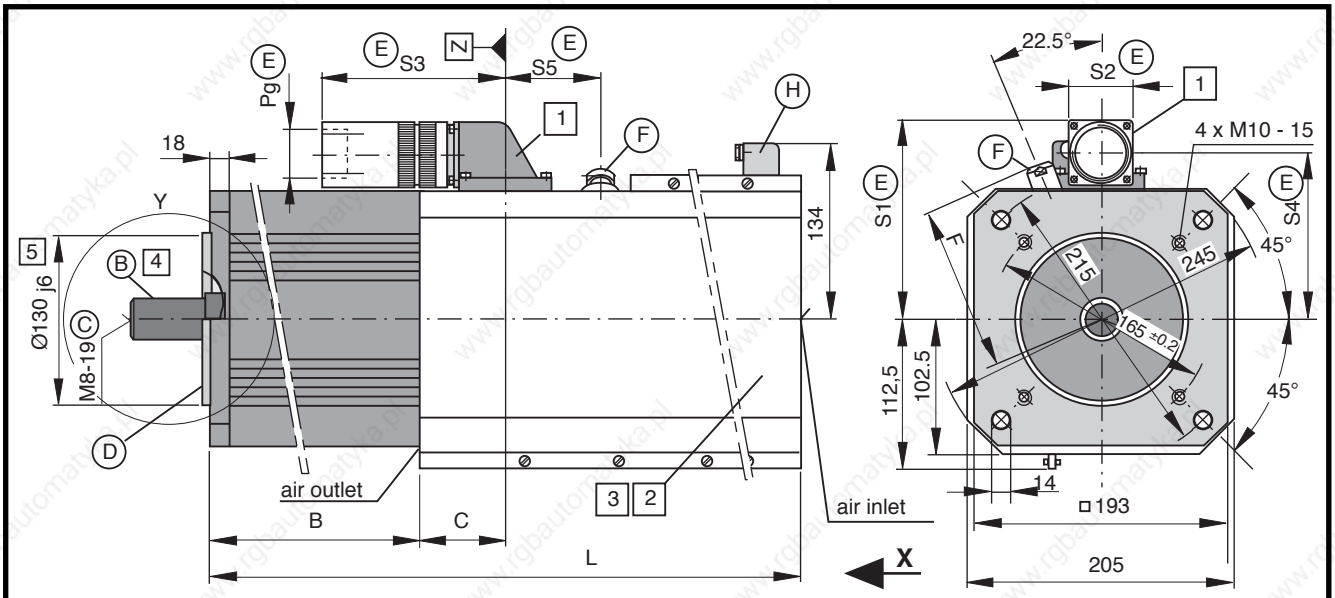
Looking towards motor shaft.

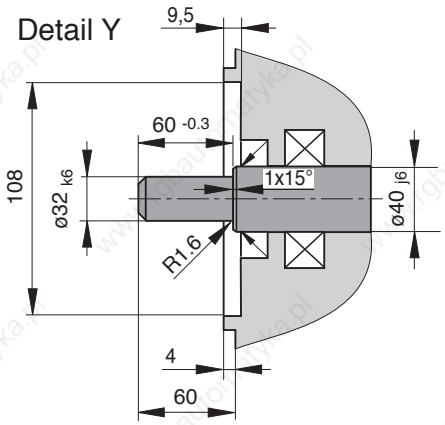


MB112-1rad/3

Fig 7.17: Dimensional data - MAC 112 - available options - (radial cooling)

7.6. Dimensional data - axial cooling





Ⓐ **Dimensional table**

Size \ Dim.	L[1]	B[1]	C[1]
MAC 112 A	387	115	65
MAC 112 B	462	190	65
MAC 112 C	537	265	65
MAC 112 D	612	340	65

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M8-19 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 5Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)
- as per design B14 (threads in flange)

Ⓔ **Motor power connector**

Must be ordered separately; depends on motor

Table

Type \ Dim.	S1	S2	S3	S4	S5[1]	Pg
INS 108 [2]	150	42	100	133	71	21
INS 172 [3]	163	53	145	137	71	36

2) with MAC112 A-•-•, MAC112 B-•-P, MAC112 B-•-L

3) other MAC112 •-•-•

Ⓕ **Tachofeedback connector:**

Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302	123
	INS 102	125

4) Straight connector with extension sleeve: Use part no. 218 277. With this part it is possible to mount and remove the connector if axial blower shroud is in place.

Ⓗ **Blower connector**

Type: INS 195 is part of the delivery.

MB112-1/1

Fig 7.18: Dimensional data - MAC 112 (axial cooling)

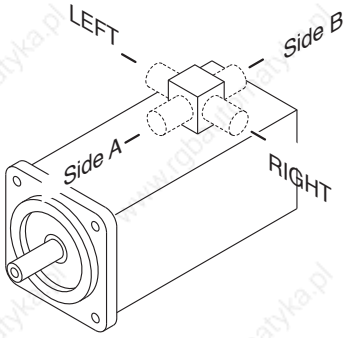
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.



2 Motor version

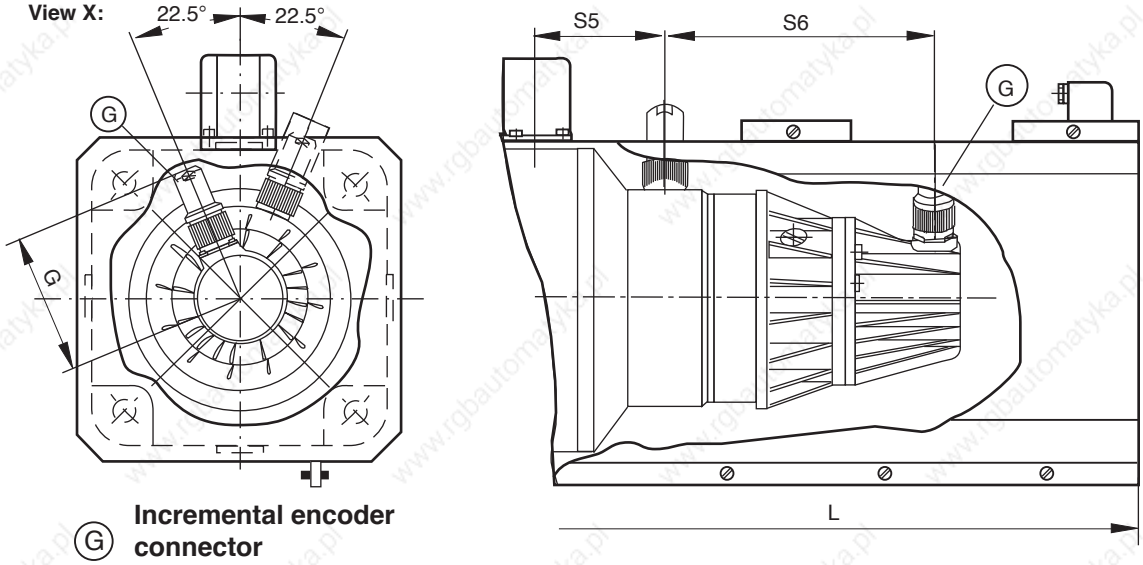
- Tachofeedback and incremental encoder

Table

Size \ Dim.	L	B	C	S5	S6
MAC 112 A	497	115	65	71	154
MAC 112 B	572	190	65	71	154
MAC 112 C	647	265	65	71	154
MAC 112 D	722	340	65	71	154

Table for motors with blocking brakes of 40 Nm and 60 Nm

Size \ Dim.	L	B	C	S5	S6
MAC 112 B	622	192	17	119	154
MAC 112 C	697	267	17	119	154
MAC 112 D	772	342	17	119	154



Ⓖ Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn. 1)	INS 301	123
	INS 101	125

1) Straight connector with extending sleeve: part no.: 218 277

MB112-1/2

- Tachofeedback and mounted absolute encoder (see following page)

Fig 7.19: Dimensional data - MAC 112 - available options - (axial cooling)

Available options

• Tachofeedback and mounted absolute encoder

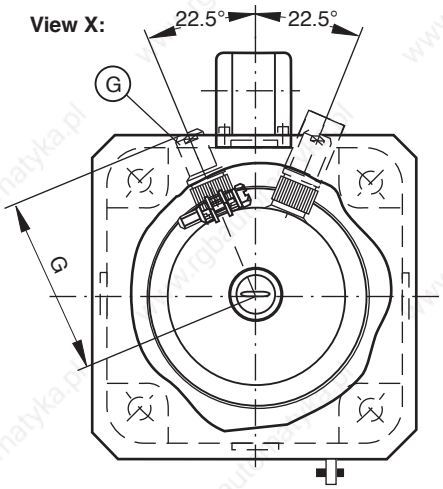
Table

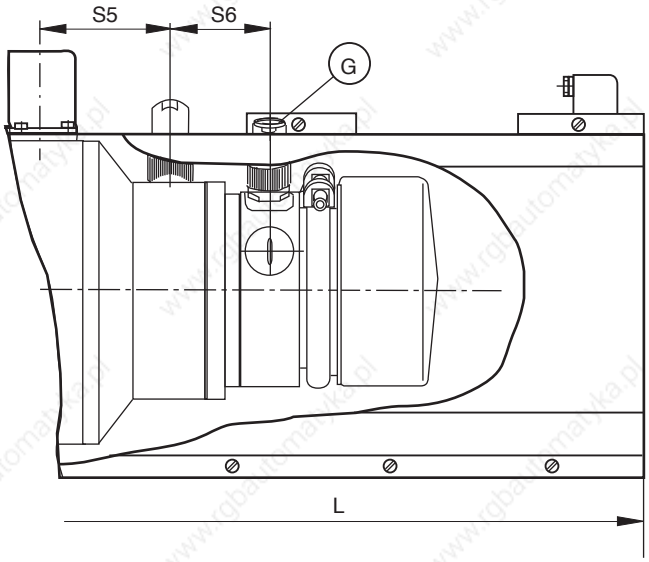
Size \ Dim.	L	B	C	S5	S6
MAC 112 A	497	115	65	71	84
MAC 112 B	572	190	65	71	84
MAC 112 C	647	265	65	71	84
MAC 112 D	722	340	65	71	84

Table with blocking brake with 40 and 60 Nm holding torque

Size \ Dim.	L	B	C	S5	S6
MAC 112 B	622	192	65	119	84
MAC 112 C	697	267	65	119	84
MAC 112 D	772	342	65	119	84

View X:





Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326	104
	INS 92	106

3 **Blocking brake**

- without blocking brake
  Dim. L and B retained
- Standard blocking brake: 14 Nm
  Dim. L and B retained
- heavy-duty blocking brake: 40 Nm
  (not available with MAC 112A ...)
- extra heavy-duty blocking brake: 60 Nm
  (not available with MAC 112A ...)

Table for blocking brake with 40 and 60 Nm

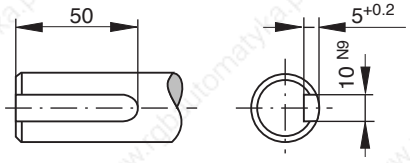
Size \ Dim.	Vers. 2 L	Vers. 2 B	Vers. 4 L	Vers. 4 B
MAC 112 B	512	240	622	240
MAC 112 C	587	315	697	315
MAC 112 D	662	390	772	390

Vers. 2 = Motor with tachofeedback

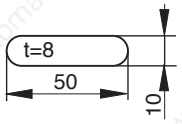
Vers. 4 = Motor with tachofeedback and mounted encoder

4 **Output shaft**

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
  (Note! balanced with entire key.)



Matching key: DIN 6885-A 10 x 8 x 50
Must be ordered separately.



5 **Special centering diameter**

- ø 180 j6

MB112-1/3

Fig 7.20: Dimensional data - MAC 112 - available options - (axial cooling)

7.7. Available Options

Type code fields — Example: MAC 112 A-0-LD-4 - C/130-A-0/WI 520LV/S000

1. Motor for analogue drives	MAC
2. Motor size	112
3. Motor length	A, B, C, D

4. Type of cooling:

natural convection	surface cooling							
	axial		radial					
			blower right		blower below		blower left	
	AC 230 V	AC 115 V	AC 230 V	AC 115 V	AC 230 V	AC 115 V	AC 230 V	AC 115 V
0	1 [1]	2 [1]	6	A	7	B	8	C

5. Type of windings

Nominal rpm	Standard applications, motor length				with increased smooth run quality, motor length			
	A	B	C	D	A	B	C	D
1500 min^{-1}	ZD	PD	KD	HD	ZG	PG	KG	HG
2000 min^{-1}	VD	LD	HD	FD	VG	LG	HG	FG
3000 min^{-1}	LD	GD	ED	ED	LG	GG	EG	EG
5000 min^{-1}	--	--	CD [6]	--	--	--	CG [6]	--

6. Motor feedback

Motor type	
with tachofeedback	2
with tachofeedback and second shaft end	3
with tachofeedback and mounted incremental or absolute encoder	4

Tacho voltage	
set to nominal motor speed (nominal rpm > 3000 min^{-1} : 1,5 V/1000 min^{-1}) (Nenndrehzahl ≤ 3000 min^{-1} : 3 V/1000 min^{-1})	-
1.5 V/1000 min^{-1}	H
6 V/1000 min^{-1} [3]	L

Tacho type	
Standard	C
increased smooth run quality	F

7. Centering diameter	
for design B05 and B14	130
for design B05 and B14	180 [2]

8. Power connection	
connector to side A	A
connector to side B	B
connector to right (looking onto output shaft)	R
connector to lefth (looking towards output shaft)	L

9. Blocking brake	
without blocking brake	0
with standard blocking brake (45 Nm)	1
with heavy-duty blocking brake (60 Nm)	2 [2] [5]
extra heavy-duty blocking brake (60 Nm)	3 [2] [5]

Mounted encoder

10. Type [4]	
Incremental encoder with standard mounting	WI
Incremental encoder with shock-damped mounting	DI
Absolute encoder	AM

11. Encoder code [4]
For available types, see section 2.4 "Motor feedback"

12. Special types
Fixed and documented by INDRAMAT with special number (see Drawing no.: 106-0105-4301-XX)
Does not apply to standard motors.

1) For type 3 motors (with 2nd shaft end and tachofeedback). Not available with axial surface cooling.
2) Type code fields 10 and 11 do not apply to motor types 2 and 3.
3) only with tacho type "F"
4) type code fields 10 and 11 do not apply to motor types 2 and 3
5) not available with motor length A
6) not available with surface cooling

TLMAC112

Fig 7.21: Type codes - MAC 112

7.8. Special Options

Specification of Option	S003	S005	S011	S013	S018	S019	S029
Special centering diameter 180	X		X			X	X
heavy-duty blocking brake				X	X	X	X
with keyway per DIN 6885, sheet 1		X	X		X		X

Fig 7.22: Special options with a MAC 112

8. MAC 115

8.1. Technical Data

Designation	Symbol	Unit	Motor type MAC …			
						115 D - • - ES
Nominal motor speed [1]	n	min^{-1}				1500
Continuous torque at standstill [2]	M_{dN}	Nm				57 (88) [5]
Continuous current at standstill	I_{dN}	A				54 (84) [5]
Rotor moment of inertia [3]	J_M	kgm^2				271 x 10^{-4}
Torque constant at 20 °C	K_m	Nm/A				1.08
Windings resistance at 20 °C	R_A	Ohm				0.084
Windings inductance	L_A	mH				2.4
Maximum peak of pulse current	I_{peak}	A				270
Thermal time constant	T_{th}	min				90 (60) [5]
Mass [4]	m_M	kg				60
			115 A - • - HS	**115 B - • - GS**	**115 C - • - ES**	**115 D - • - DS**
Nominal motor speed [1]	n	min^{-1}	2000	2000	2000	2000
Continuous torque at standstill [2]	M_{dN}	Nm	28 (42) [5]	38 (61) [5]	47 (75) [5]	57 (88) [5]
Continuous current at standstill	I_{dN}	A	32.5 (48.8) [5]	40.9 (66) [5]	55 (87) [5]	68 (104) [5]
Rotor moment of inertia [3]	J_M	kgm^2	123 x 10^{-4}	172 x 10^{-4}	222 x 10^{-4}	271 x 10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.882	0.952	0.880	0.864
Windings resistance at 20 °C	R_A	Ohm	0.170	0.123	0.074	0.054
Windings inductance	L_A	mH	3.6	3.0	2.0	1.6
Maximum peak of pulse current	I_{peak}	A	163	205	274	338
Thermal time constant	T_{th}	min	90 (60) [5]	90 (60) [5]	90 (60) [5]	90 (60) [5]
Mass [4]	m_M	kg	33	41	52	60
			115 A - • - FS	**115 B - • - DS**	**115 C - • - CS**	**115 D - • - CS**
Nominal motor speed [1]	n	min^{-1}	3000	3000	3000	3000
Continuous torque at standstill [2]	M_{dN}	Nm	28 (42) [5]	38 (56) [5]	47	57
Continuous current at standstill	I_{dN}	A	48.8 (73.2) [5]	72 (109) [5]	91	90
Rotor moment of inertia [3]	J_M	kgm^2	123 x 10^{-4}	172 x 10^{-4}	222 x 10^{-4}	271 x 10^{-4}
Torque constant at 20 °C	K_m	Nm/A	0.588	0.544	0.528	0.648
Windings resistance at 20 °C	R_A	Ohm	0.076	0.040	0.027	0.030
Windings inductance	L_A	mH	1.6	1.0	0.7	0.9
Maximum peak of pulse current	I_{peak}	A	244	358	456	451
Thermal time constant	T_{th}	min	90 (60) [5]	90 (60) [5]	90 (60) [5]	90 (60) [5]
Mass [4]	m_M	kg	33	41	52	60

[1] The usable motor speed is determined by the drive used.
Only those usable speeds n_{max} found in the selection lists of the motor-drive combinations are binding.
[2] With 60K overtemperature at the motor housing.
Continuous torque can be limited by the drive. See selection data.
[3] With tacho-generator, without holding brake
[4] With tacho-generator, without holding brake, without blower.
[5] Parenthetical values apply to versions with surface cooling.

Fig 8.1: Type-dependent motor data

Designation	Symbol	Unit	Data	
Permissible ambient temperature	T_{um}	°C	0 … + 45	
Permissible storage and transport temperature	T_L	°C	-20 … +80	
Maximum installation elevation		m	1000 m above sea level	
Protection category			IP 65	
Insulation classification			F	
Housing coat			Black prime coat (RAL 9005)	
Voltage constant of the tachogenerator [1]	C_w	Vs/rad	0.0143	0.0286
		V/min^{-1}	1.5/1000	3/1000

[1] Tachovoltage can be selected application-related.

Fig 8.2: General data MAC 115

Designation	Symbol	Unit	Data holding brake	
			Standard	heavy-duty
Principle of action			electrically actuated release	
Holding torque	M_H	Nm	45	60
Nominal voltage	U_N	V	DC 24 ± 10%	
Nominal current	I_N	A	1.0	1.5
Moment of inertia	J_B	kgm^2	9.5×10^{-4}	32×10^{-4}
Release delay	t_L	ms	55	150
Clamping delay	t_K	ms	18	30
Mass	m_B	kg	1.9	3.5

Fig 8.3: Technical data -holding brake

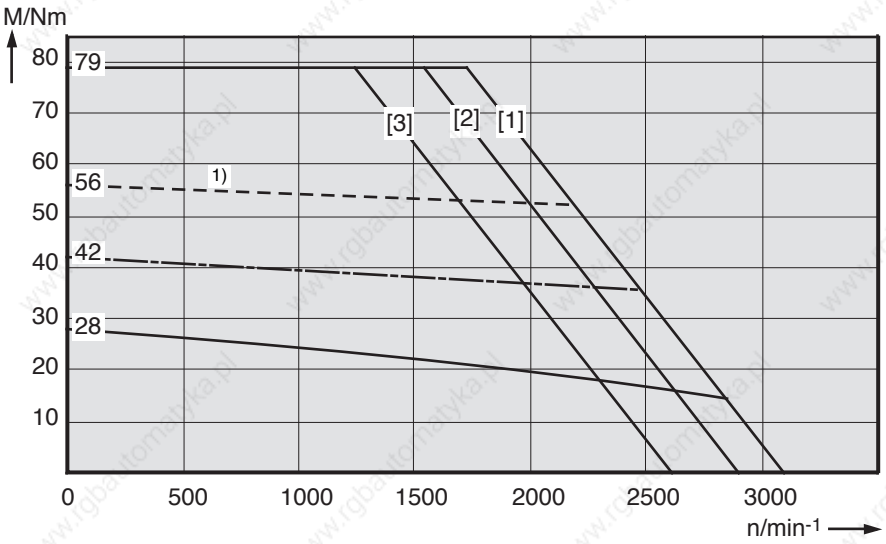
Designation	Symbol	Unit	Axial cooling	Radial cooling
Power consumption	S_N	VA	40/42	40/42
Nominal voltage	U_N	V	AC 230 or 115 [1]	AC 230 or 115 [1]
Frequency	f	Hz	50/60	50/60
Mass	m_L	kg	approx. 3.3 [2]	approx. 3.2 [2]
Protection category blower unit			IP 24	IP 24
Protection category blower motor			IP 44	IP 44

[1] 115 V special design
[2] Blower shroud for motor with tachofeedback.

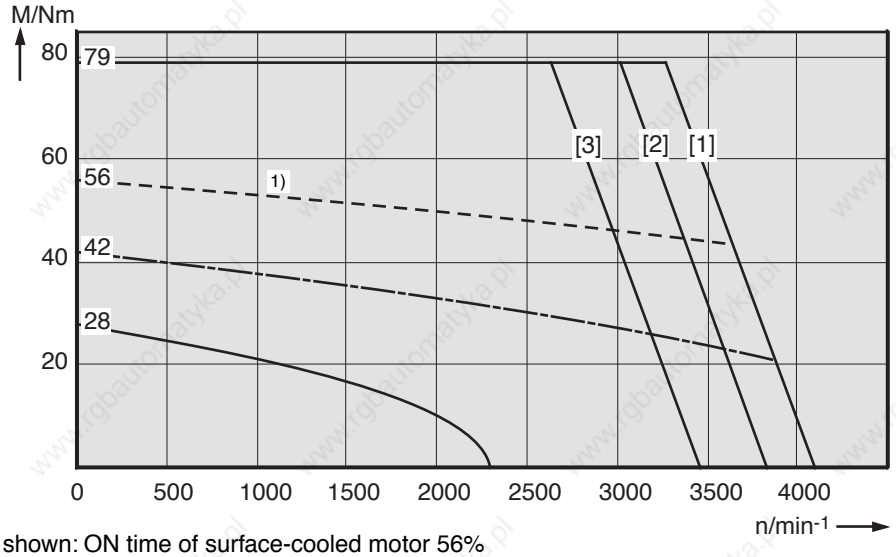
Fig 8.4: Technical data - surface cooling

8.2. Torque-Speed Characteristics

MAC 115 A - • - HS
2000 min^{-1}



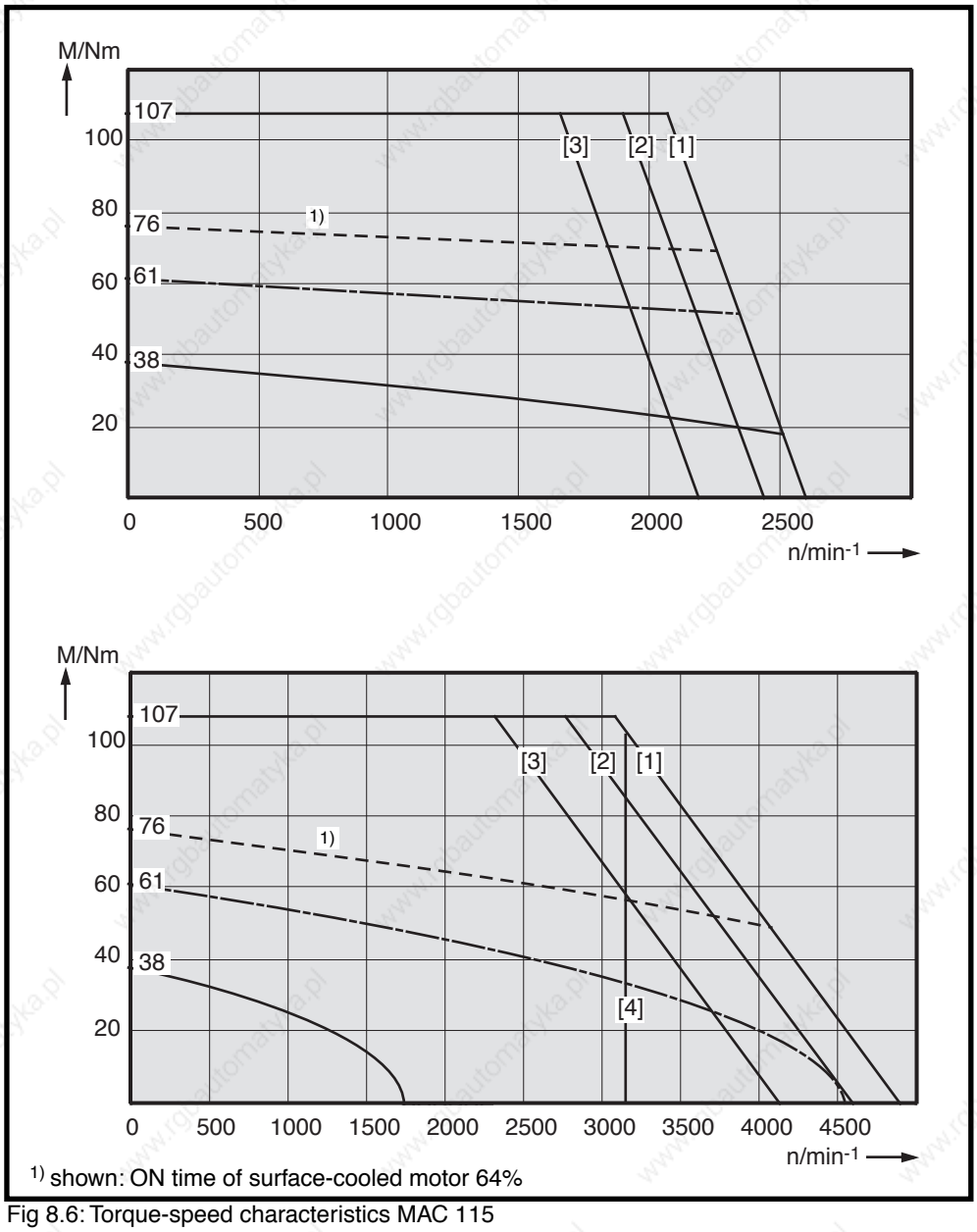
MAC 115 A - • - FS
3000 min^{-1}



1) shown: ON time of surface-cooled motor 56%

Fig 8.5: Torque-speed characteristics MAC 115

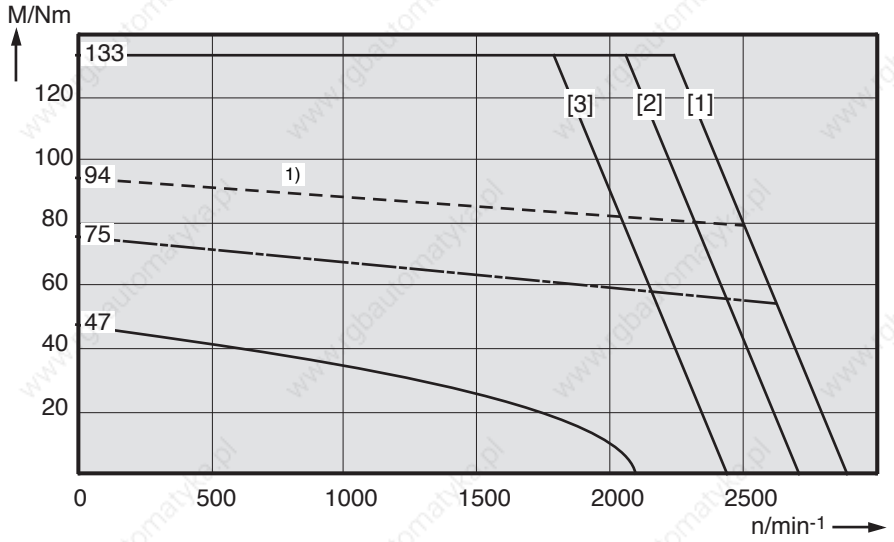
MAC 115 B - • - GS
2000 min^{-1}



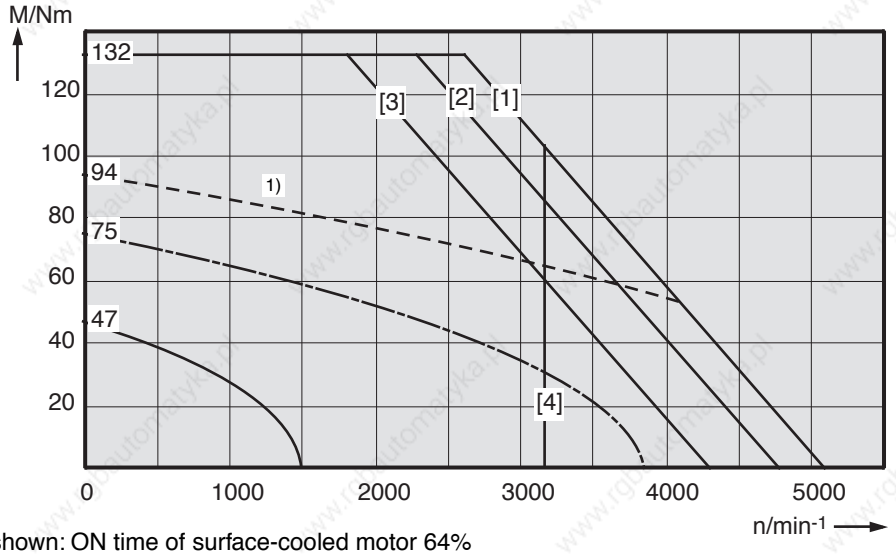
MAC 115 B - • - DS
3000 min^{-1}

Fig 8.6: Torque-speed characteristics MAC 115

MAC 115 C - • - ES
2000 min^{-1}



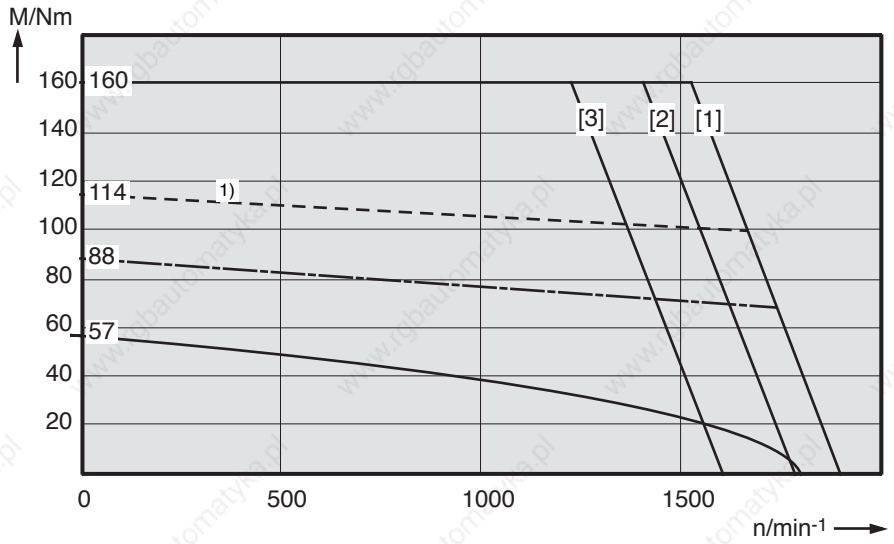
MAC 115 C - • - CS
3000 min^{-1}



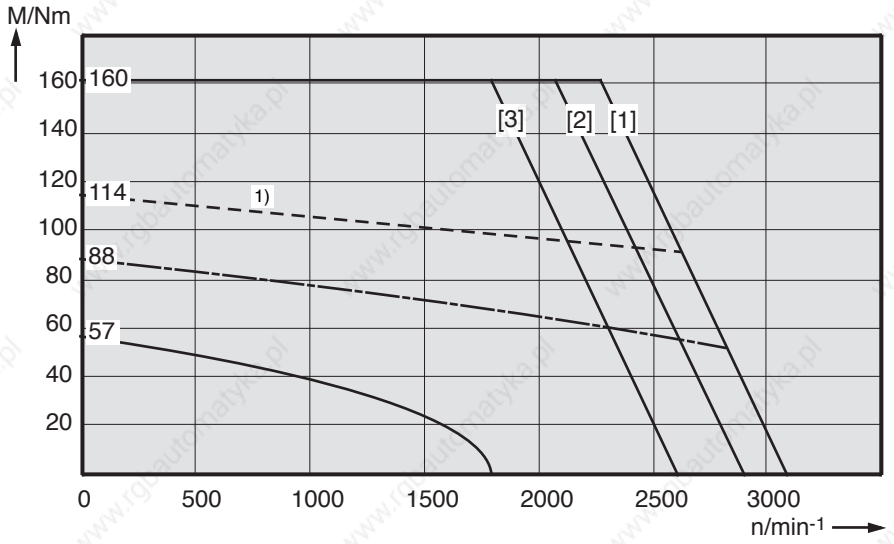
1) shown: ON time of surface-cooled motor 64%

Fig 8.7: Torque-speed characteristics MAC 115

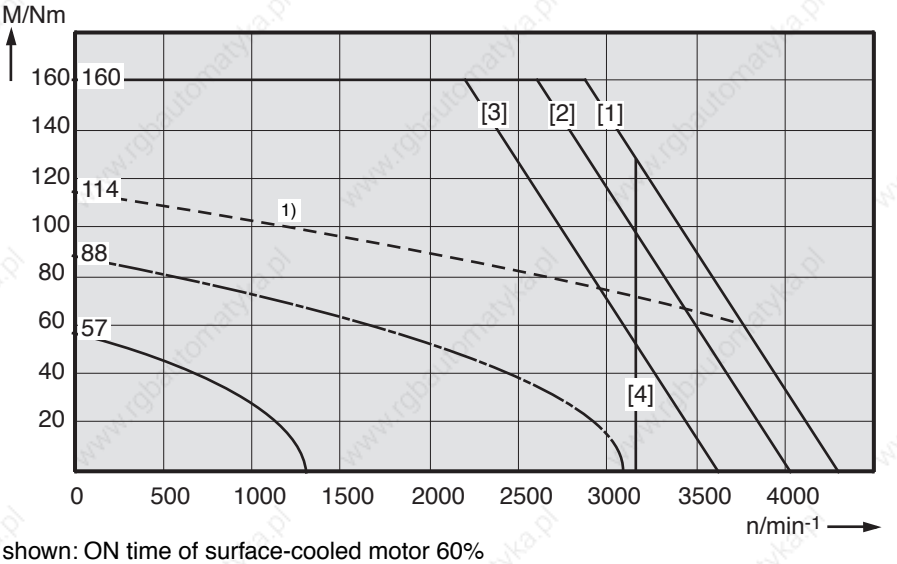
MAC 115 D - • - ES
1500 min^{-1}



MAC 115 D - • - DS
2000 min^{-1}



MAC 115 D - • - CS
3000 min^{-1}



1) shown: ON time of surface-cooled motor 60%

Fig 8.8: Torque-speed characteristics MAC 115

8.3. Shaft load capacity

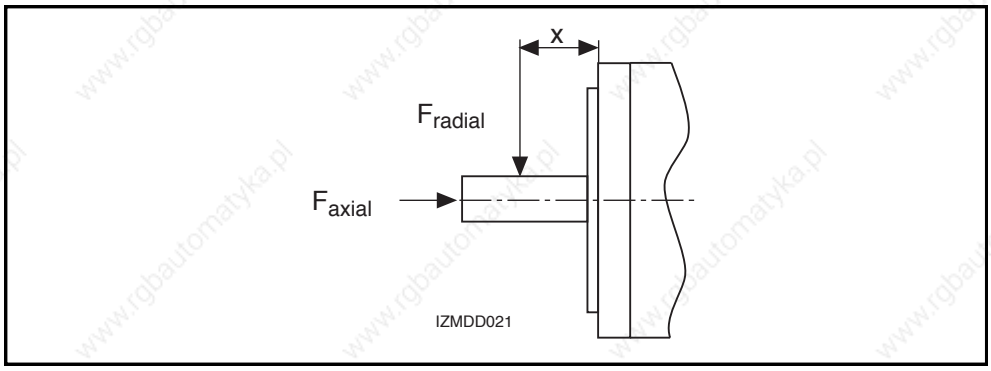


Fig 8.9: Shaft load

Permissible radial force F_{radial}

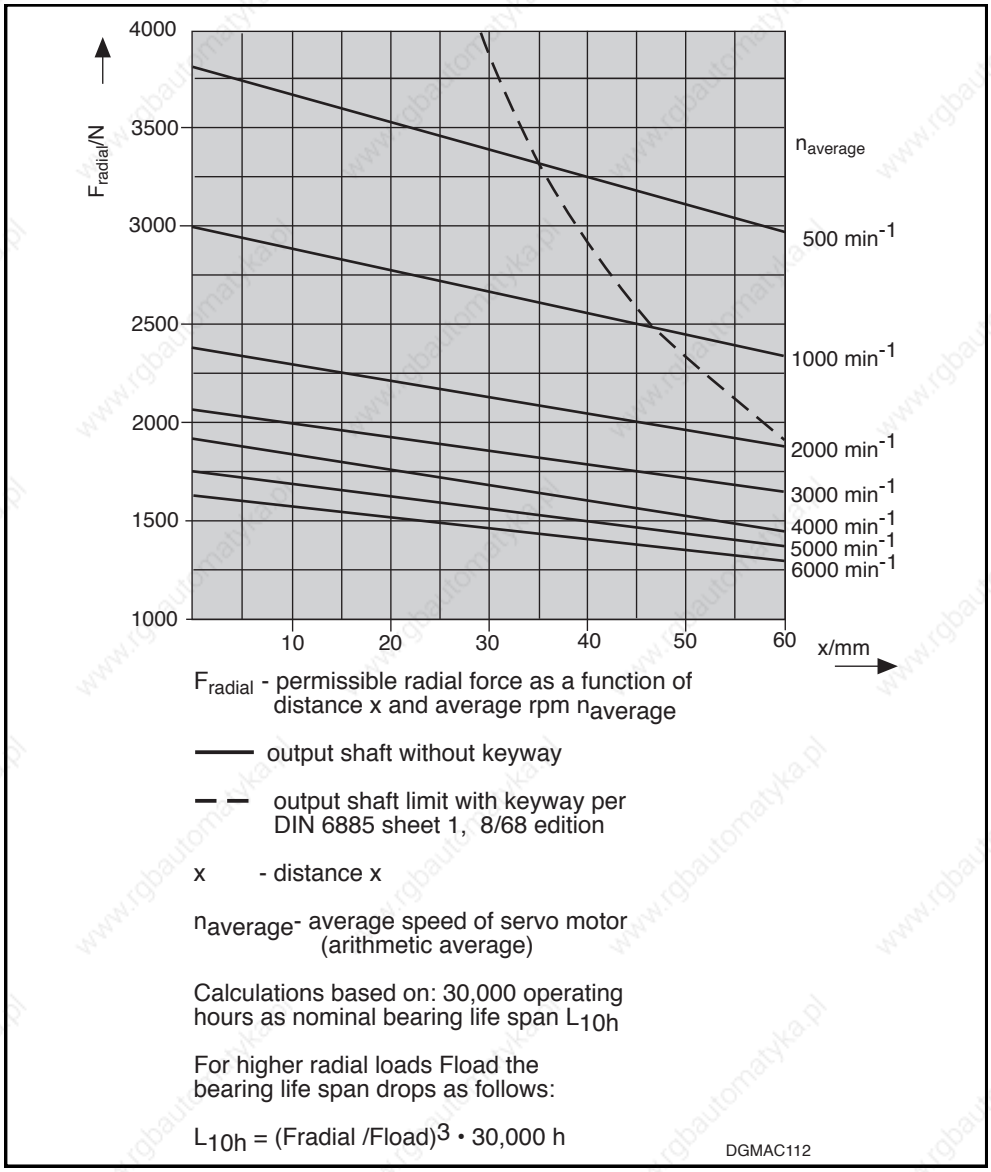


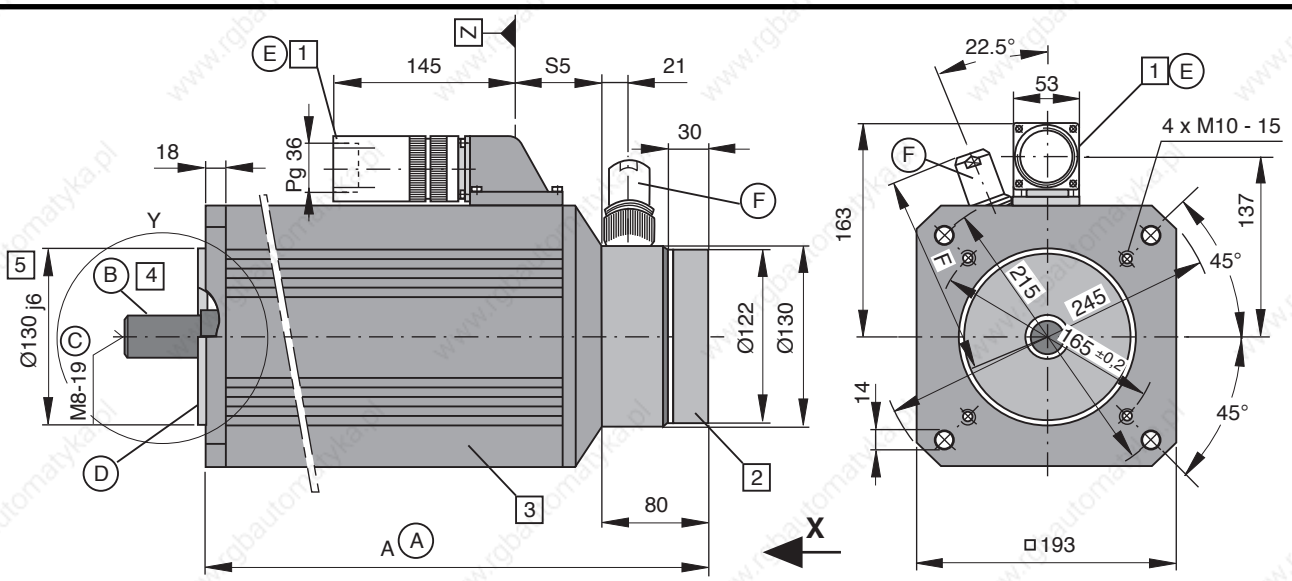
Fig 8.10: Permissible radial force

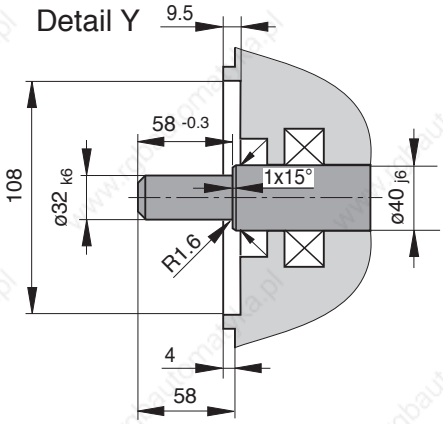
Permissible axial force F_{axial}

F_{axial} = 0.35 • F_{radial}

F_{axial} - Permissible axial force
F_{radial} - Permissible radial force

8.4. Dimensional data - natural convection





Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M8-19 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 5Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)
- as per design B14 (threads in flange)

Ⓔ **Motor power connector**
INS 172 must be ordered separately.

Ⓐ **Dimensional table Dim. A**

Size \ Dim.	A[1]	S5[1]
MAC 115 A	357	52.5
MAC 115 B	407	52.5
MAC 115 C	457	52.5
MAC 115 D	507	52.5

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302	123
	INS 102	125
angle conn.	INS 352	121
	INS 312	

MB115-0/1

Fig 8.11: Dimensional data - MAC 115 (natural convection)

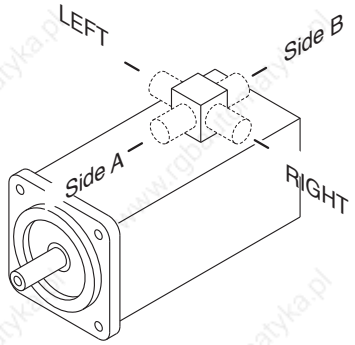
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

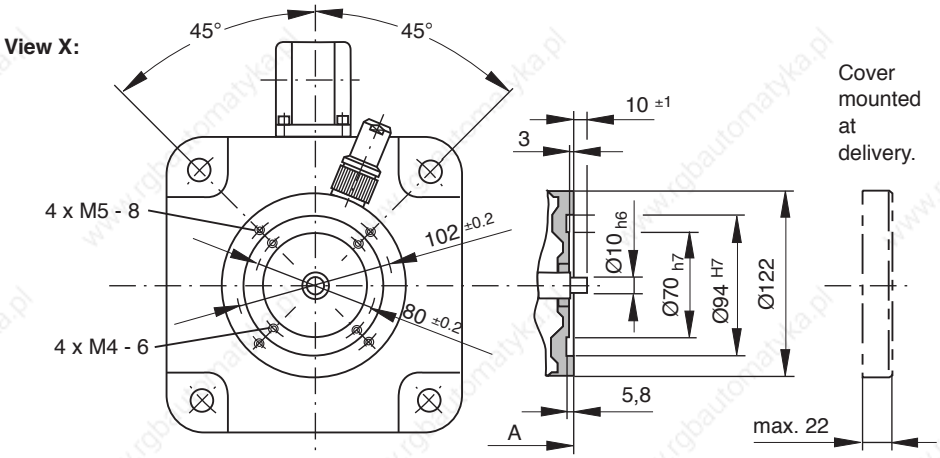
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

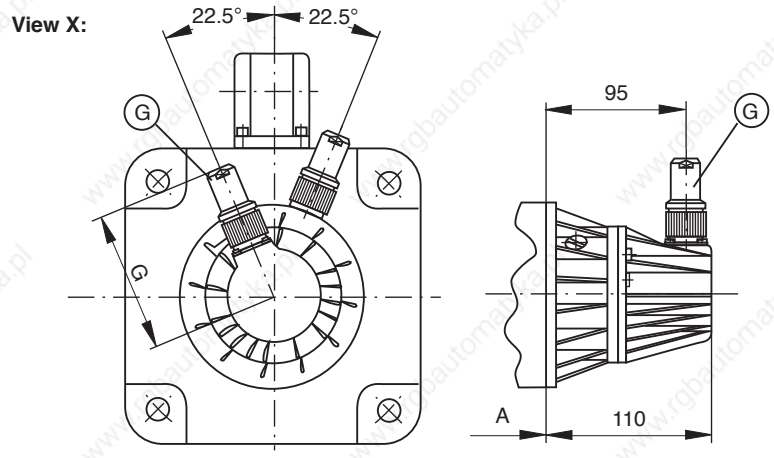


2 Motor version

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



(G) Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

MB115-0/2

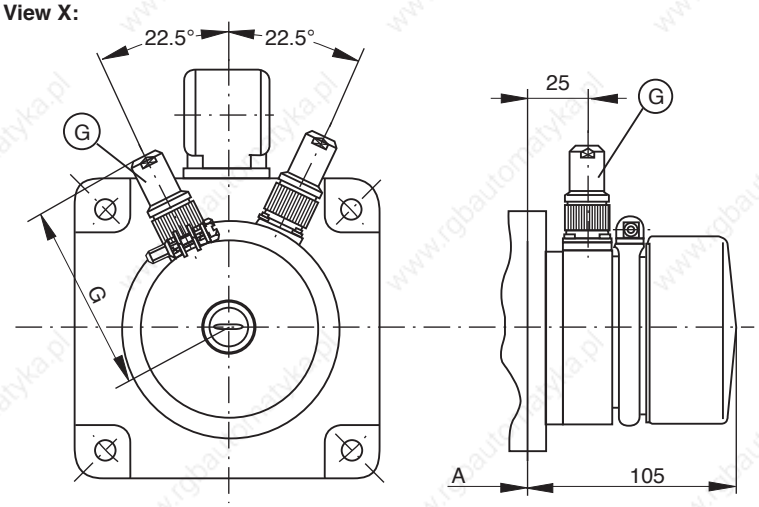
- Tachofeedback and mounted absolute encoder (see following page)

Fig 8.12: Dimensional data - MAC 115 - available options - (natural convection)

Available options

• Tachofeedback and mounted absolute encoder

View X:



Ⓖ **Absolute encoder connector**
Must be ordered separately.

Name	Connector	Dim. G
straight conn.	INS 326 INS 92	104 106
angle conn.	INS 322	102

3 Blocking brake

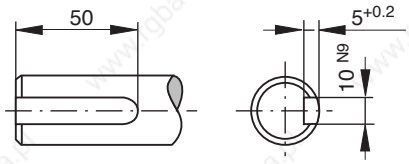
• without blocking brake
Dim. A and S5 are retained.
• Standard blocking brake: 45 Nm
Dim. A and S5 are retained.
• heavy-duty blocking brake: 60 Nm

Table for motors with 60 Nm blocking brakes

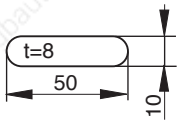
Size \ Dim.	A	S5
MAC 115 A	417	95.5
MAC 115 B	467	95.5
MAC 115 C	517	95.5
MAC 115 D	567	95.5

4 Output shaft

• plain shaft (preferred)
• with keyway as per DIN 6885 sheet 1, 8/68 edition
(Note! Balanced with entire key.)



Matching key: DIN 6885-A 10 x 8 x 50
Must be ordered separately.



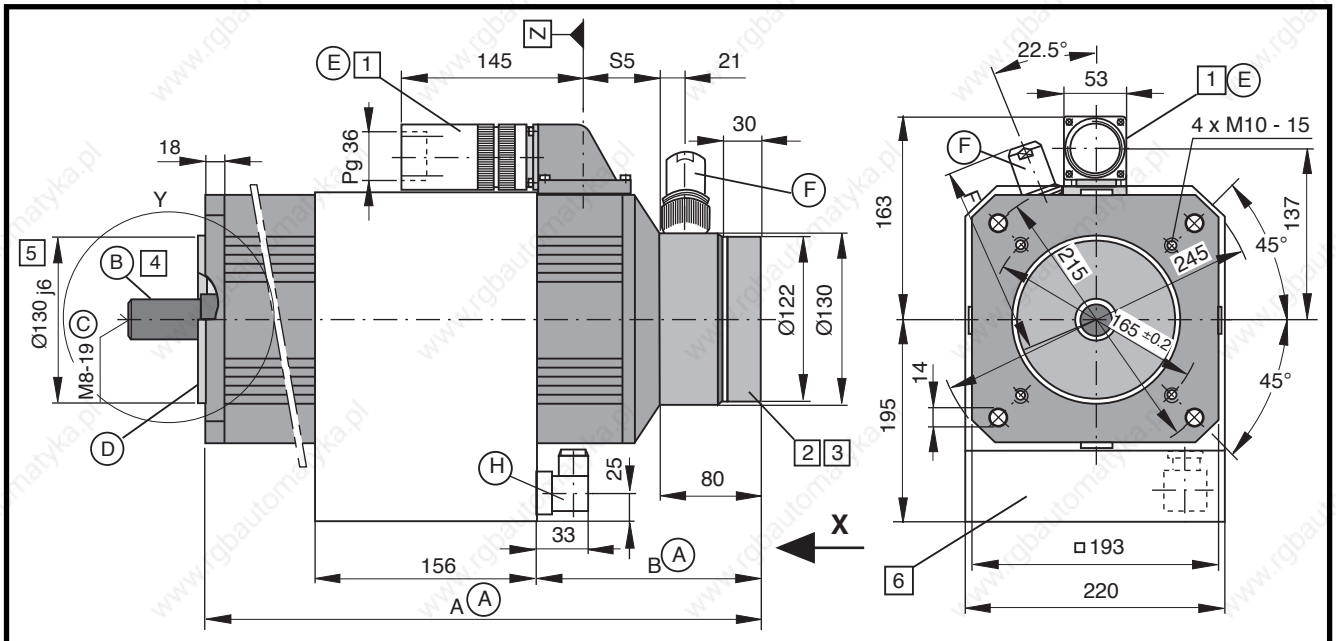
5 Special centering diameter

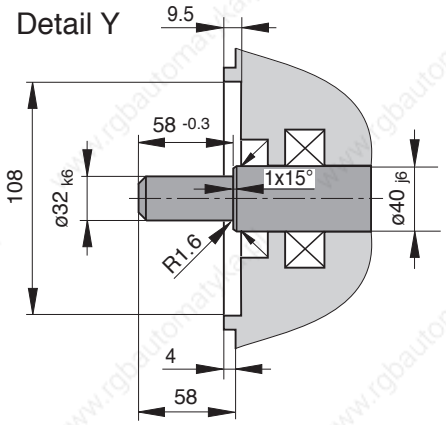
• ø 180 j6

MB115-0/3

Fig 8.13: Dimensional data - MAC 115 -available options - (natural convection)

8.5. Dimensional data - radial cooling





Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M8-19 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 5 Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)
- as per design B14 (threads in flange)

Ⓔ **Motor power connector**
INS 172 must be ordered separately.

Ⓐ **Dimensional table Dim. A and B**

Size \ Dim.	A[1]	B[1]	S5[1]
MAC 115 A	357	110	52.5
MAC 115 B	407	170	52.5
MAC 115 C	457	205	52.5
MAC 115 D	507	205	52.5

1) Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302	123
	INS 102	125
angle conn.	INS 352	121
	INS 312	

Ⓗ **Blower connector: INS 195**
Part of general delivery.

MB115-1rad/1

Fig 8.14: Dimensional data - MAC 115 (radial cooling)

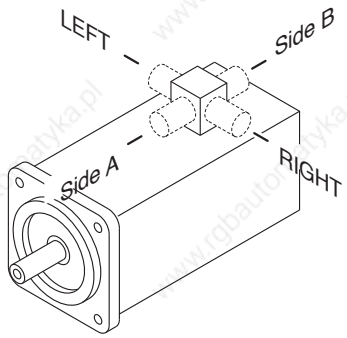
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

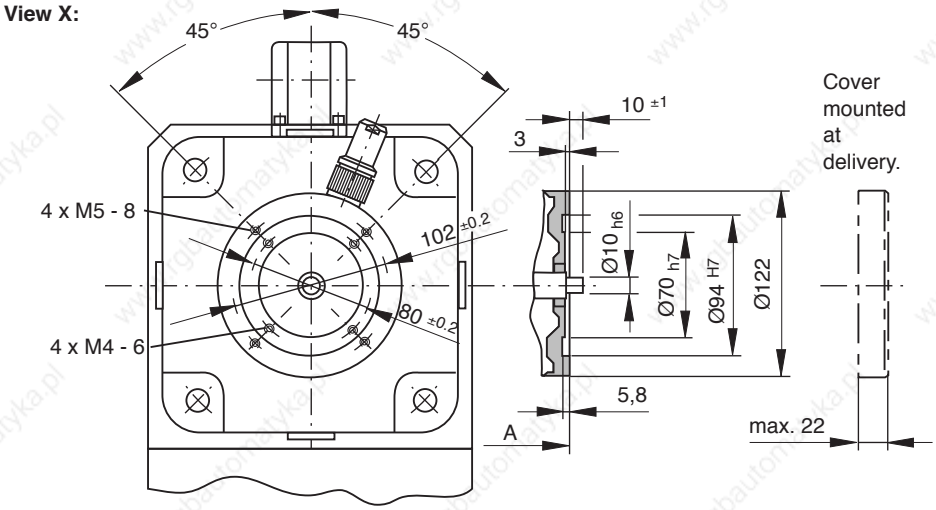
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

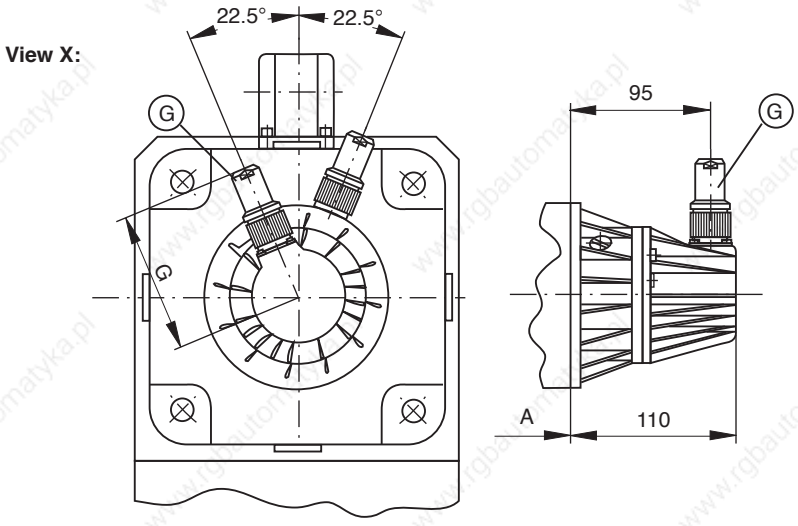


2 Motor version

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



G Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder (see following page)

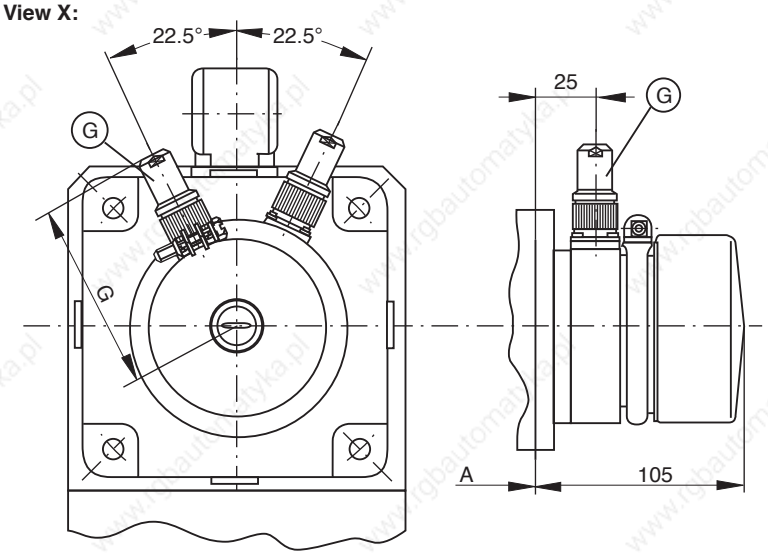
MB115-1rad/2

Fig 8.15: Dimensional data - MAC 115 - available options - (radial cooling)

Available options

• Tachofeedback and mounted absolute encoder

View X:



Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104 106
angle conn.	INS 322	102

3 Blocking brake

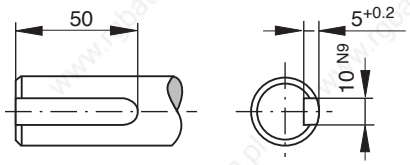
- without blocking brake
  Dim. A, B and S5 retained
- Standard blocking brake: 45 Nm
  Dim. A, B and S5 retained
- heavy-duty blocking brake: 60 Nm

Table for blocking brake with 60 Nm

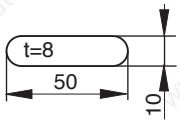
Size \ Dim.	A	B	S5
MAC 115 A	417	155	95.5
MAC 115 B	467	225	95.5
MAC 115 C	517	255	95.5
MAC 115 D	567	255	95.5

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
  (Note! balanced with entire key.)



Matching key: DIN 6885-A 10 x 8 x 50
Must be ordered separately.

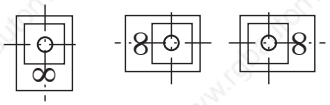


5 Special centering diameter

- ø 180 j6

6 Blower arrangement

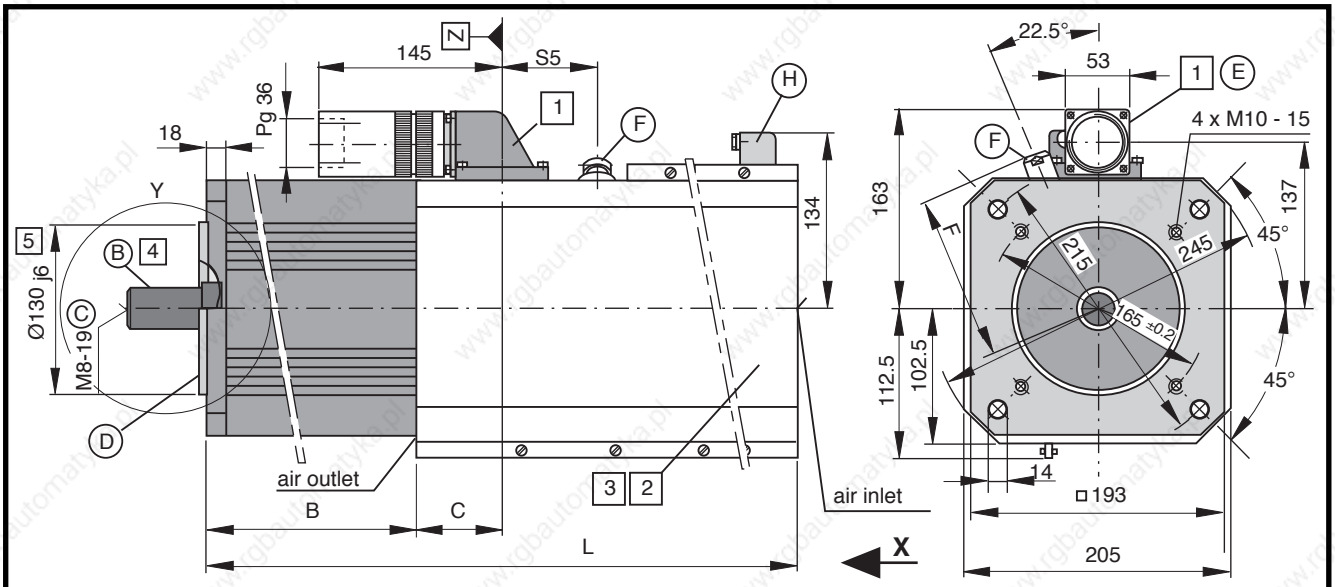
Looking towards motor shaft.

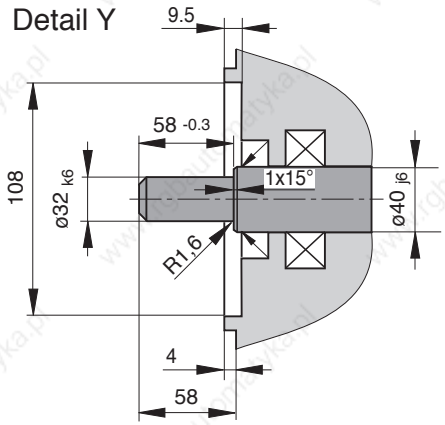


MB115-1rad/3

Fig 8.16: Dimensional data - MAC 115 - available options - (radial cooling)

8.6. Dimensional data - axial cooling





Ⓒ
- Shaft end per DIN 748 section 3, 7/75 edition, IEC 72, 1971 edition, cylindrical
- Center spigot DS M8-19 per DIN 332 section 2, 5/83 edition
- Max. tightening torque M_A for screws in the threads of the center spigot: 1Nm

Ⓓ Flange type per DIN 42948, 11/65 edition, makes mounting possible
- as per design B5 (throughhole in flange)
- as per design B14 (threads in flange)

Ⓐ **Dimensional table**

Size \ Dim.	L [1]	B [1]	C [1]	S5 [1]
MAC 115 A	433	160	65	73.5
MAC 115 B	483	210	65	73.5
MAC 115 C	533	260	65	73.5
MAC 115 D	583	310	65	73.5

[1] Bigger with some options. The then applicable dimension is indicated under the respective feature.

Ⓑ Position accuracy in terms of concentricity, excentricity and coaxiality to the shaft per DIN 42955, tolerance class N, 12/81 edition.

Ⓔ **Motor power connector**
INS 172 must be ordered separately; depends on motor

Ⓕ **Tachofeedback connector:**
Must be ordered separately.

Table

Name	Conn. type	Dim. F
straight connector	INS 302	123
	INS 102	125

[2] Straight connector with extension sleeve: Use part no. 218 277. This makes it possible to mount and remove the connector even if a blower shroud is present.

Ⓗ **Blower connector: INS 195**
Part of general delivery.

MB115-1/1

Fig 8.17: Dimensional data - MAC 115 (axial cooling)

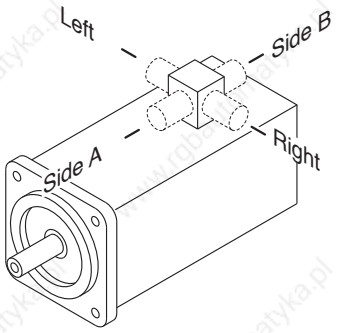
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.



2 Motor type

- Tachofeedback and mounted incremental encoder

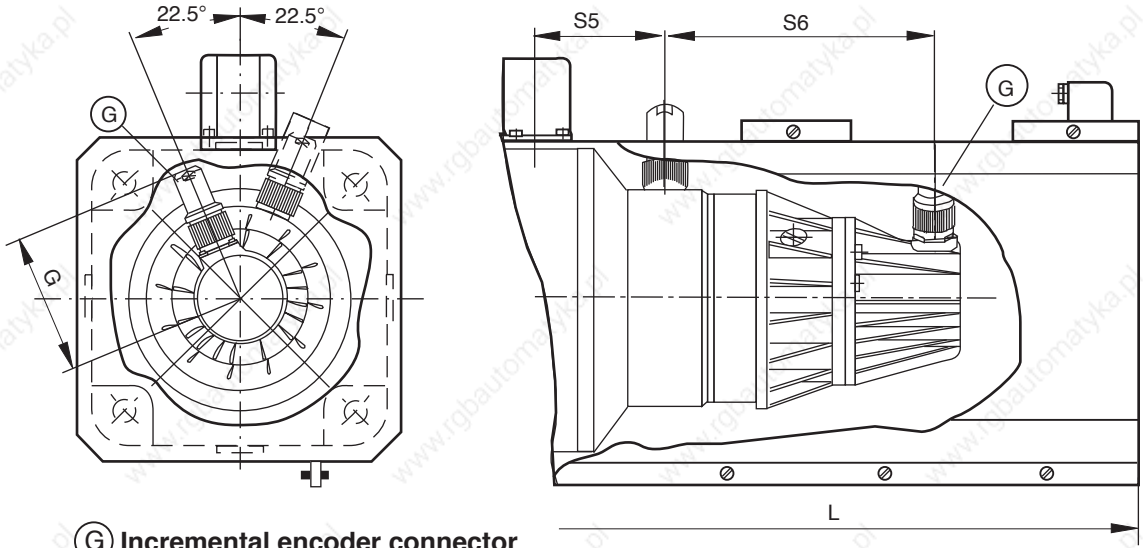
Table

Size \ Dim.	L	B	C	S5	S6
MAC 115 A	543	160	65	73.5	154
MAC 115 B	593	210	65	73.5	154
MAC 115 C	643	260	65	73.5	154
MAC 115 D	693	310	65	73.5	154

Table for motor with 60 Nm blocking brake

Size \ Dim.	L	B	C	S5	S6
MAC 115 A	603	220	22	116.5	154
MAC 115 B	653	270	22	116.5	154
MAC 115 C	703	320	22	116.5	154
MAC 115 D	753	370	22	116.5	154

View X:



Ⓖ **Incremental encoder connector**
Must be ordered separately.

Name	Connector	Dim. G
gerader Stecker [1)]	INS 302 INS 102	123 125

[1)] Straight connector with extension sleeve:
part no.: 218 277

- Tachofeedback and mounted absolute encoder
(see next page)

MB115-1/2

Fig 8.18: Dimensional data - MAC 115 - available options - (axial cooling)

Available options

• Tachofeedback and mounted absolute encoder

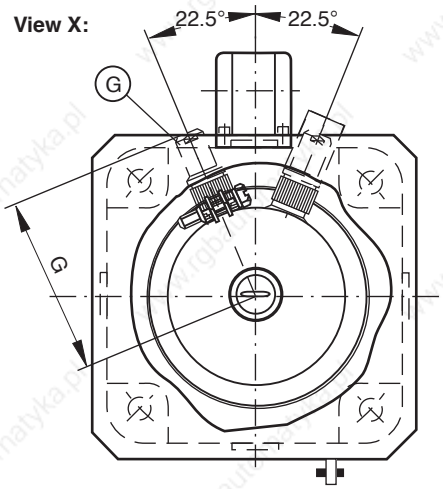
Table

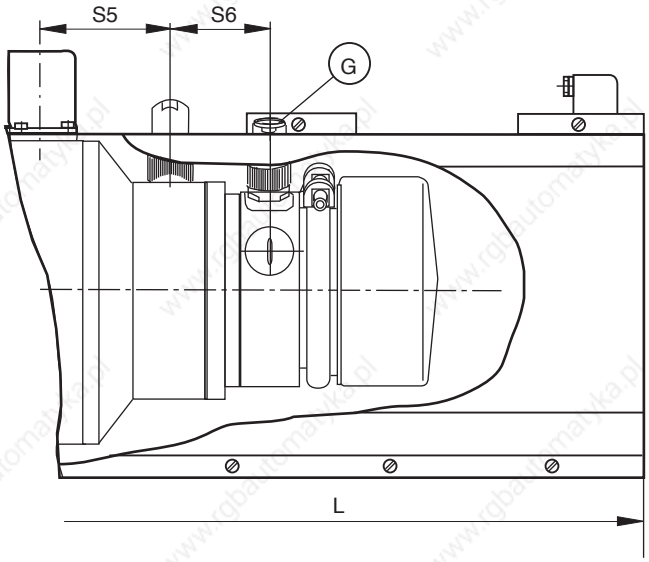
Size \ Dim.	L	B	C	S5	S6
MAC 115 A	543	160	65	73.5	84
MAC 115 B	593	210	65	73.5	84
MAC 115 C	643	260	65	73.5	84
MAC 115 D	693	310	65	73.5	84

Table of blocking brake with 60 Nm holding torque

Size \ Dim.	L	B	C	S5	S6
MAC 115 A	603	220	22	116.5	84
MAC 115 B	653	270	22	116.5	84
MAC 115 C	703	320	22	116.5	84
MAC 115 D	753	370	22	116.5	84

View X:





Ⓖ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326	104
	INS 92	106

3 Blocking brake

- without blocking brake
  Dim. L and B retained
- Standard blocking brake: 45 Nm
  Dim. L and B retained
- heavy-duty blocking brake: 60 Nm

Table for blocking brake with 60 Nm

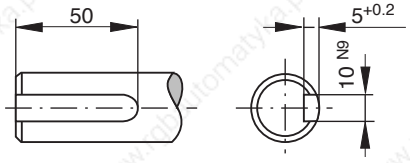
Size \ Dim.	Vers. 2			Vers. 4		
	L	B	S5	L	B	S5
MAC 115 A	543	160	116.5	603	222	116.5
MAC 115 B	593	210	116.5	653	270	116.5
MAC 115 C	643	260	116.5	703	320	116.5
MAC 115 D	693	310	116.5	753	370	116.5

Vers. 2 =
Motor with tachofeedback

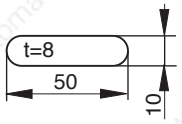
Vers. 4 =
Motor with tachofeedback and mounted encoder

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
  (Note! balanced with entire key.)



Matching key: DIN 6885-A 10 x 8 x 50
Must be ordered separately.



5 Special centering diameter

- ø 180 j6

MB115-1/3

Fig 8.19: Dimensional data - MAC 115 - available options - (axial cooling)

8.7. Available Options

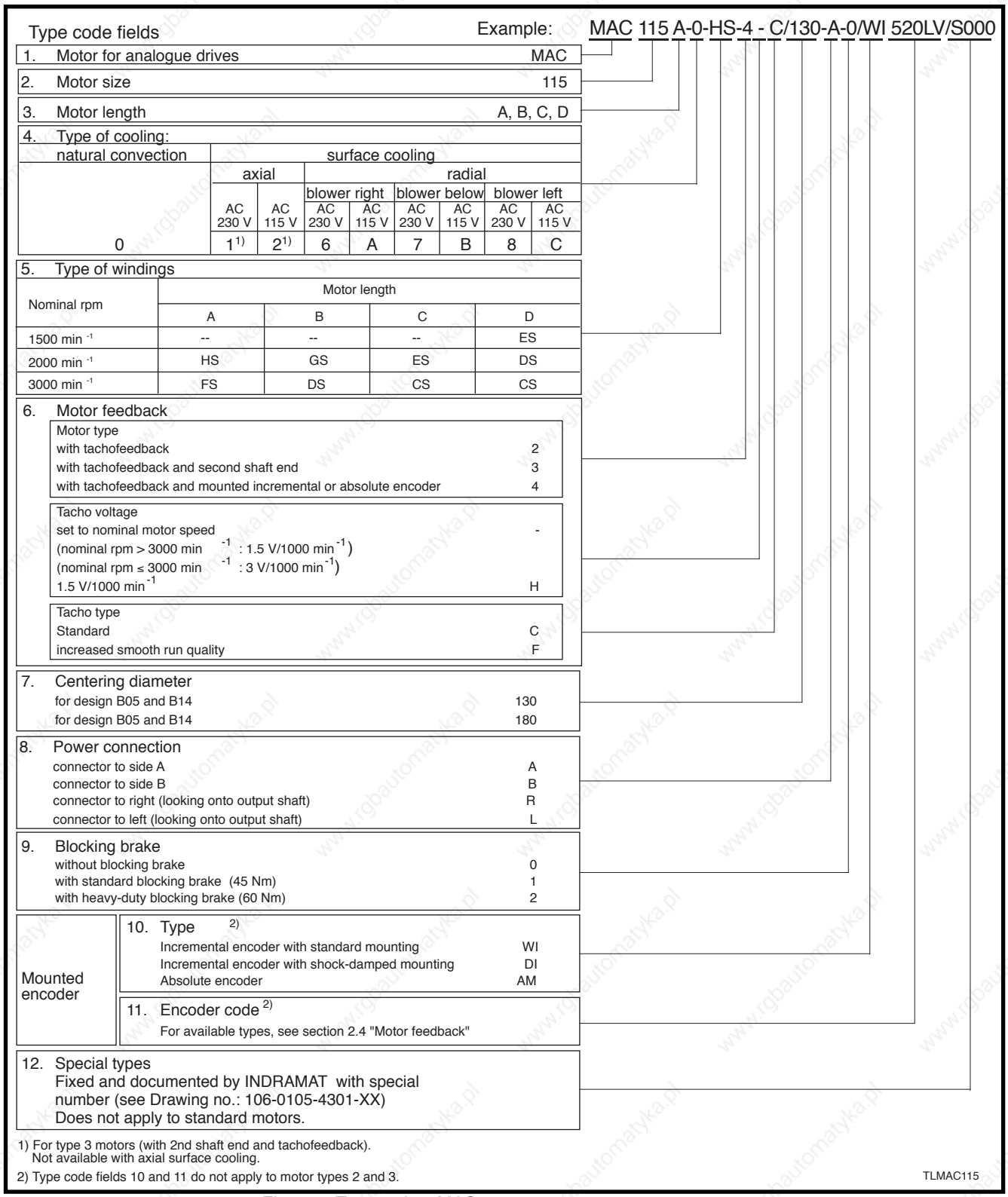


Fig 8.20: Type codes MAC 115

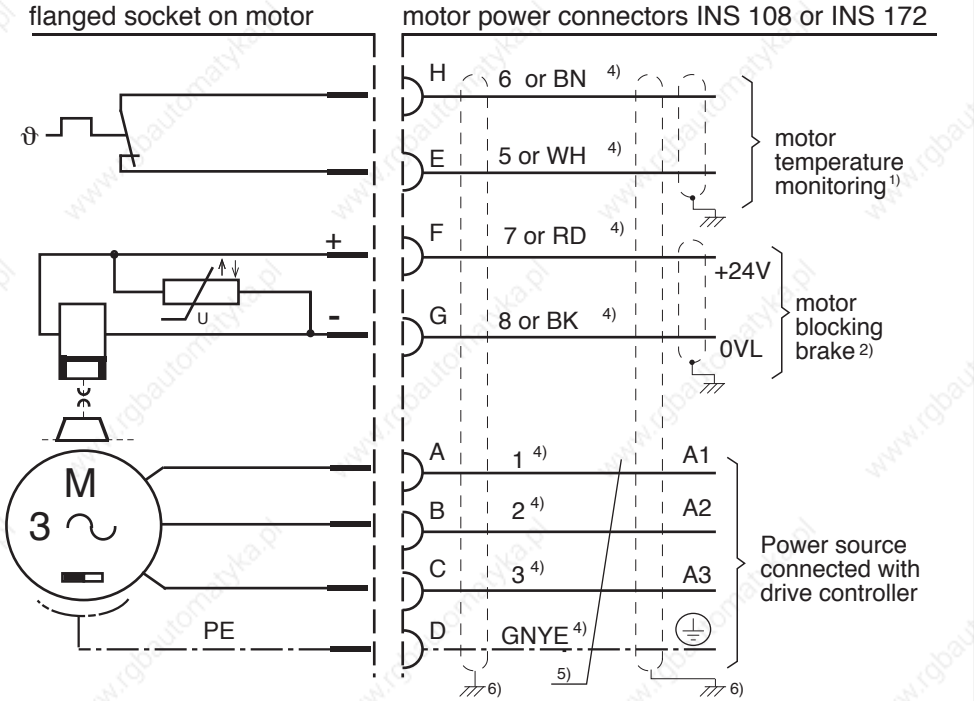
8.8. Special Options

Specification of Option	S001
with keyway per DIN 6885, sheet 1	X

Fig 8.21: Special options with a MAC 115

9. Electrical Power Connection

9.1. Terminal Diagram



Motor power connector 3)

(Looking towards soldering or crimping side of connector)

INS 108 **INS 172**

1) Recommended conductor diameter at least 0.75 mm² or AWG 18

2) If motor equipped with blocking brake:
- blocking brake voltage at motor: DC +24 V, ±10 %;
- recommended conductor diameter at least 0.75 mm² or AWG 18

3) Finishing guidelines for motor power connector see separate cable documentation 209-0050-4399-XX

4) Core identification of INDRAMAT cable

5) See Table in Figure 9.2 for diameters

6) When using the machine in residential or light-industrial areas, it may be necessary to use a totally shielded cable to maintain the values for transmission of interference (rf interference suppression). The motor power connector is earthed on the conduit thread screw.

APALLG

Fig 9.1: Power connection

9.2. Connector-Cable Allocations

Servo motor MAC ...	Cooling	Motor phase current [1]	Power conn. Min. cross section[1]		Motor power connector		INDRAMAT Motor power cable		
					Crimping Type [3]	Soldering type [3]	w/o total shield	with total shield	cross section
		A	mm^2	AWG [2]					mm^2
063 A-0-ES	natural convection	1.8	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 A-0-RS		2.9	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 B-0-GS		3.0	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 B-0-JS		4.7	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 C-0-MS		3.3	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 C-0-HS		5.6	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 D-0-JS		4.2	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 D-0-FS		6.9	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 A-•-ES	surface cooling	2.2	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 A-•-RS		3.6	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 B-•-GS		3.3	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 B-•-JS		5.4	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 C-•-MS		4.3	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 C-•-HS		7.1	0.75	16	---	INS 108/06	INK 253	INK 653	0.75
063 D-•-JS		5.4	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
063 D-•-FS		9.0	0.75	16	---	INS 108/06	INK 253	INK 653	0.75

Continued on next page

[1] Motor phase currents and connection cross sections apply to S1 continuous operation or S6 intermittent operation with those limit values (respective ON time and duty cycle time) given in the torque-speed operating curves.

[2] Minimum cross section of power connection per EN 60 204, sec. 1, table 5, cols. C or E or UL 508 table 50.2, but at least 0.75 mm^2 or AWG 18. Cables per UL 508 may only be soldered not crimped to the motor power connector.

[3] Data following the slash identify the type of bushing contact as either for crimping or soldering.

Servo motor MAC …	Cooling	Motor phase current [1] A	Power conn. Min. cross section [1] mm²	AWG [2]	Motor power connector Crimping Type [3]	Soldering type [3]	INDRAMAT Motor power cable w/o total shield	with total shield	cross section mm²
071 A-0-HS	natural convection	2.1	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
071 A-0-OS		3.1	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
071 A-0-ES		4.1	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
071 A-0-VS		6.0	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
071 B-0-FS		4.2	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
071 B-0-TS		6.0	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
071 B-0-PS		7.8	0.75	16	---	INS 108/06	INK 253	INK 653	0.75
071 B-0-KS		11.6	1.0	14	---	INS 108/06	INK 250	INK 650	1.5
071 C-0-US		6.0	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
071 C-0-NS		9.0	0.75	16	---	INS 108/06	INK 253	INK 653	0.75
071 C-0-JS		12.5	1.5	14	INS 108/02	INS 108/06	INK 250	INK 650	1.5
071 C-0-GS		18.0	2.5	12	INS 108/03	INS 108/06	INK 202	INK 602	2.5
071 A-•-HS	surface cooling	3.3	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
071 A-•-OS		4.9	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
071 A-•-ES		6.4	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
071 A-•-VS		9.5	1.0	16	---	INS 108/06	INK 250	INK 650	1.5
071 B-•-FS		6.4	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
071 B-•-TS		9.5	1.0	16	---	INS 108/06	INK 250	INK 650	1.5
071 B-•-PS		12.4	1.5	14	INS 108/02	INS 108/06	INK 250	INK 650	1.5
071 B-•-KS		18.2	2.5	12	INS 108/03	INS 108/06	INK 202	INK 602	2.5
071 C-•-US		9.6	1.0	16	---	INS 108/06	INK 253	INK 653	1.5
071 C-•-NS		14.4	2.5	14	INS 108/03	INS 108/06	INK 202	INK 602	2.5
071 C-•-JS		20.2	4.0	10	INS 108/04	INS 108/06	INK 203	INK 603	4.0
071 C-•-GS		28.9	6.0	10	INS 108/06	INS 108/06	INK 204	INK 604	6.0

Continued on next page

[1] Motor phase currents and connection cross sections apply to S1 continuous operation or S6 intermittent operation with those limit values (respective ON time and duty cycle time) given in the torque-speed operating curves.

[2] Minimum cross section of power connection per EN 60 204, sec. 1, table 5, cols. C or E or UL 508 table 50.2, but at least 0.75 mm² or AWG 18. Cables per UL 508 may only be soldered not crimped to the motor power connector.

[3] Data following the slash identify the type of bushing contact as either for crimping or soldering.

Servo motor MAC …	Cooling	Motor phase current [1] A	Power conn. Min. cross section[1] mm²	Power conn. Min. cross section[1] AWG [2]	Motor power connector Crimping Type [3]	Motor power connector Soldering type [3]	INDRAMAT Motor power cable w/o total shield	INDRAMAT Motor power cable with total shield	INDRAMAT Motor power cable cross section mm²
090 A-0-Z•	natural convection	6.6	0.75	18	---	INS 108/06	INK 253	INK 653	0.75
090 A-0-R•		9.3	1.0	16	INS 108/02	INS 108/06	INK 250	INK 650	1.5
090 B-0-P•		9.7	1.0	16	INS 108/02	INS 108/06	INK 250	INK 650	1.5
090 B-0-N•		10.6	1.0	14	INS 108/02	INS 108/06	INK 250	INK 650	1.5
090 B-0-J•		14.8	1.5	14	INS 108/02	INS 108/06	INK 250	INK 650	1.5
090 C-0-K•		13.9	1.5	14	INS 108/02	INS 108/06	INK 250	INK 650	1.5
090 C-0-G•		20.2	2.5	10	INS 108/03	INS 108/06	INK 202	INK 602	2.5
090 C-0-E•		28.6	6.0	10	---	INS 108/06	INK 204	INK 604	6.0
090 A-•-Z•	surface cooling	8.9	0.75	16	---	INS 108/06	INK 253	INK 653	0.75
090 A-•-R•		13.3	1.5	14	INS 108/02	INS 108/06	INK 250	INK 650	1.5
090 B-•-P•		14.2	1.5	14	INS 108/02	INS 108/06	INK 250	INK 650	1.5
090 B-•-N•		16.3	2.5	12	INS 108/03	INS 108/06	INK 202	INK 602	2.5
090 B-•-J•		23.2	4.0	10	INS 108/04	INS 108/06	INK 203	INK 603	4.0
090 C-•-K•		21.3	4.0	10	INS 108/04	INS 108/06	INK 203	INK 603	4.0
090 C-•-G•		33.7	6.0	8	---	INS 108/06	INK 204	INK 604	6.0
090 C-•-E•		42.5	10.0	6	INS 172/10	INS 172/25	INK 205	INK 605	10.0

Continued on next page

[1] Motor phase currents and connection cross sections apply to S1 continuous operation or S6 intermittent operation with those limit values (respective ON time and duty cycle time) given in the torque-speed operating curves.

[2] Minimum cross section of power connection per EN 60 204, sec. 1, table 5, cols. C or E or UL 508 table 50.2, but at least 0.75 mm² or AWG 18. Cables per UL 508 may only be soldered not crimped to the motor power connector.

[3] Data following the slash identify the type of bushing contact as either for crimping or soldering.

Servo motor MAC …	Cooling	Motor phase current [1] A	Power conn. Min. cross section [1] mm²	Power conn. Min. cross section [1] AWG [2]	Motor power connector Crimping Type [3]	Motor power connector Soldering type [3]	INDRAMAT Motor power cable w/o total shield	INDRAMAT Motor power cable with total shield	INDRAMAT Motor power cable cross section mm²
093 A-0-WS	natural convection	9.0	1.0	16	INS 108/02	INS 108/06	INK 250	INK 650	1.5
093 A-0-PS		12.3	1.5	14	INS 108/02	INS 108/06	INK 250	INK 650	1.5
093 A-0-LS		18.0	2.5	12	INS 108/03	INS 108/06	INK 202	INK 602	2.5
093 A-0-HS		26.2	4.0	10	INS 108/04	INS 108/06	INK 203	INK 603	4.0
093 B-0-OS		14.8	1.5	14	INS 108/02	INS 108/06	INK 250	INK 650	1.5
093 B-0-JS		22.1	4.0	10	INS 108/04	INS 108/06	INK 203	INK 603	4.0
093 B-0-GS		31.2	6.0	8	INS 172/06	INS 172/25	INK 204	INK 604	6.0
093 B-0-ES		44.3	10.0	6	INS 172/10	INS 172/25	INK 205	INK 605	10.0
093 C-0-KS		18.0	2.5	12	INS 108/03	INS 108/06	INK 202	INK 602	2.5
093 C-0-FS		28.7	6.0	10	INS 172/06	INS 172/25	INK 204	INK 604	6.0
093 C-0-DS		39.4	10.0	8	INS 172/10	INS 172/25	INK 205	INK 605	10.0
093 C-0-CS		49.2	10.0	6	INS 172/10	INS 172/25	INK 205	INK 605	10.0
093 A-•-WS	surface cooling	15.1	1.5	12	INS 108/02	INS 108/06	INK 250	INK 650	1.5
093 A-•-PS		16.4	2.5	12	INS 108/03	INS 108/06	INK 202	INK 602	2.5
093 A-•-LS		23.0	4.0	10	INS 108/04	INS 108/06	INK 203	INK 603	4.0
093 A-•-HS		28.0	4.0	10	INS 108/04	INS 108/06	INK 203	INK 603	4.0
093 B-•-OS		20.5	2.5	10	INS 108/03	INS 108/06	INK 202	INK 602	2.5
093 B-•-JS		28.0	4.0	10	INS 108/04	INS 108/06	INK 203	INK 603	4.0
093 B-•-GS		43.5	10.0	6	INS 172/10	INS 172/25	INK 205	INK 605	10.0
093 B-•-ES		60.7	16.0	4	INS 172/16	INS 172/25	INK 206	INK 606	16.0
093 C-•-KS		26.2	4.0	10	INS 108/04	INS 108/06	INK 203	INK 603	4.0
093 C-•-FS		41.0	10.0	6	INS 172/10	INS 172/25	INK 205	INK 605	10.0
093 C-•-DS		56.6	16.0	4	INS 172/16	INS 172/25	INK 206	INK 606	16.0
093 C-•-CS		71.3	25.0	3	INS 172/25	INS 172/25	INK 207	INK 607	25.0

Continued on next page

[1] Motor phase currents and connection cross sections apply to S1 continuous operation or S6 intermittent operation with those limit values (respective ON time and duty cycle time) given in the torque-speed operating curves.

[2] Minimum cross section of power connection per EN 60 204, sec. 1, table 5, cols. C or E or UL 508 table 50.2, but at least 0.75 mm² or AWG 18. Cables per UL 508 may only be soldered not crimped to the motor power connector.

[3] Data following the slash identify the type of bushing contact as either for crimping or soldering.

Servo motor MAC …	Cooling	Motor phase current 1) A	Power conn. Min. cross section 1) mm²	Power conn. Min. cross section 1) AWG 2)	Motor power connector Crimping Type 3)	Motor power connector Soldering type 3)	INDRAMAT Motor power cable w/o total shield	INDRAMAT Motor power cable with total shield	INDRAMAT Motor power cable cross section mm²
112 A-0-Z•	natural convection	11.8	1.5	14	INS 108/02	INS 108/06	INK 250	INK 650	1.5
112 A-0-V•		15.1	1.5	12	INS 108/02	INS 108/06	INK 250	INK 650	1.5
112 A-0-L•		25.3	4.0	10	INS 108/04	INS 108/06	INK 203	INK 603	4.0
112 B-0-P•		17.1	2.5	10	INS 108/03	INS 108/06	INK 202	INK 602	2.5
112 B-0-L•		21.5	4.0	10	INS 108/04	INS 108/06	INK 203	INK 603	4.0
112 B-0-G•		33.5	6.0	8	---	INS 108/06	INK 204	INK 604	6.0
112 C-0-K•		25.3	4.0	10	INS 108/04	INS 108/06	INK 203	INK 603	4.0
112 C-0-H•		33.5	6.0	8	---	INS 108/06	INK 204	INK 604	6.0
112 C-0-E•		46.5	10.0	6	INS 172/10	INS 172/25	INK 205	INK 605	10.0
112 C-0-C•		71.4	25.0	3	---	INS 172/25	INK 207	INK 607	25.0
112 D-0-H•		34.3	6.0	8	---	INS 108/06	INK 204	INK 604	6.0
112 D-0-F•		45.7	10.0	6	INS 172/10	INS 172/25	INK 205	INK 605	10.0
112 D-0-E•		51.4	16.0	4	INS 172/16	INS 172/25	INK 206	INK 606	16.0
112 A-•-Z•	surface cooling	14.0	1.5	14	INS 108/02	INS 108/06	INK 250	INK 650	1.5
112 A-•-V•		18.7	2.5	10	INS 108/03	INS 108/06	INK 202	INK 602	2.5
112 A-•-L•		33.7	6.0	8	---	INS 108/06	INK 204	INK 604	6.0
112 B-•-P•		26.9	4.0	10	INS 108/04	INS 108/06	INK 203	INK 603	4.0
112 B-•-L•		35.5	6.0	8	---	INS 108/06	INK 204	INK 604	6.0
112 B-•-G•		61.2	16.0	4	INS 172/16	INS 172/25	INK 206	INK 606	16.0
112 C-•-K•		40.0	10.0	6	INS 172/10	INS 172/25	INK 205	INK 605	10.0
112 C-•-H•		54.7	16.0	4	INS 172/16	INS 172/25	INK 206	INK 606	16.0
112 C-•-E•		85.0	25.0	3	---	INS 172/25	INK 207	INK 607	25.0
112 D-•-H•		51.4	16.0	4	INS 172/16	INS 172/25	INK 206	INK 606	16.0
112 D-•-F•		67.8	16.0	4	INS 172/16	INS 172/25	INK 206	INK 606	16.0
112 D-•-E•		83.3	25.0	3	---	INS 172/25	INK 207	INK 607	25.0

Continued on next page

1) Motor phase currents and connection cross sections apply to S1 continuous operation or S6 intermittent operation with those limit values (respective ON time and duty cycle time) given in the torque-speed operating curves.

2) Minimum cross section of power connection per EN 60 204, sec. 1, table 5, cols. C or E or UL 508 table 50.2, but at least 0.75 mm² or AWG 18. Cables per UL 508 may only be soldered not crimped to the motor power connector.

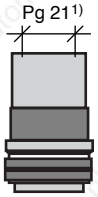
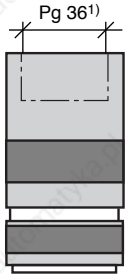
3) Data following the slash identify the type of bushing contact as either for crimping or soldering.

Servo motor MAC …	Cooling	Motor phase current [1] A	Power conn. Min. cross section[1] mm²	Power conn. Min. cross section[1] AWG [2]	Motor power connector Crimping Type [3]	Motor power connector Soldering type [3]	INDRAMAT Motor power cable w/o total shield	INDRAMAT Motor power cable with total shield	INDRAMAT Motor power cable cross section mm²
115 A-0-HS	natural convection	21.8	4.0	10	---	INS 172/25	INK 203	INK 603	4.0
115 A-0-FS		40.0	10.0	8	INS 172/10	INS 172/25	INK 205	INK 605	10.0
115 B-0-GS		33.5	6.0	8	INS 172/06	INS 172/25	INK 204	INK 604	6.0
115 B-0-DS		59.0	16.0	4	INS 172/16	INS 172/25	INK 206	INK 606	16.0
115 C-0-ES		45.1	10.0	6	INS 172/10	INS 172/25	INK 205	INK 605	10.0
115 C-0-CS		74.6	25.0	3	---	INS 172/25	INK 207	INK 607	25.0
115 D-0-ES		44.1	10.0	6	INS 172/10	INS 172/25	INK 205	INK 605	10.0
115 D-0-DS		55.7	16.0	4	INS 172/16	INS 172/25	INK 206	INK 606	16.0
115 D-0-CS		73.8	25.0	3	---	INS 172/25	INK 207	INK 607	25.0
115 A-•-HS	surface cooling	40.0	10.0	8	INS 172/10	INS 172/25	INK 205	INK 605	10.0
115 A-•-FS		60.0	16.0	4	INS 172/16	INS 172/25	INK 206	INK 606	16.0
115 B-•-GS		54.1	16.0	6	INS 172/16	INS 172/25	INK 206	INK 606	16.0
115 B-•-DS		89.0	25.0	2	---	INS 172/25	INK 207	INK 607	25.0
115 C-•-ES		71.3	25.0	3	---	INS 172/25	INK 207	INK 607	25.0
115 D-•-ES		68.6	25.0	4	---	INS 172/25	INK 207	INK 607	25.0
115 D-•-DS		85.3	25.0	2	---	INS 172/25	INK 207	INK 607	25.0

[1] Motor phase currents and connection cross sections apply to S1 continuous operation or S6 intermittent operation with those limit values (respective ON time and duty cycle time) given in the torque-speed operating curves.
[2] Minimum cross section of power connection per EN 60 204, sec. 1, table 5, cols. C or E or UL 508 table 50.2, but at least 0.75 mm² or AWG 18. Cables per UL 508 may only be soldered not crimped to the motor power connector.
[3] Data following the slash identify the type of bushing contact as either for crimping or soldering.

Fig 9.2: Connector to cable assignment of the power connection

9.3. Power Connector (Motor Power Connector)

	Crimping types					Soldering types				
	Connector type	Maximum conn. cross section		Strain relief [1]		Connector type	Maximum conn. cross section		Strain relief[1]	
		Power core mm^2	Control core mm^2	Cable type INK	Mat. Nr.		Power core	Control core[2] max.	Cable type INK	Mat. Nr.
INS 108 Pg 21[1] 	INS 108/02	1.5	1.5	250 650	225 404 225 404	INS 108/06	0.75 - 6.0 mm^2 AWG 18-10	1.5 mm^2 AWG 16	253 250 202 203 204 653 650 602 603 604	260 097 225 404 219 857 218 767 218 767 225 404 225 404 227 526 218 767 218 767
	INS 108/03	2.5	1.5	202 602	219 857 227 526					
	INS 108/04	4.0	1.5	203 603	218 767 218 767					
INS 172 Pg 36[1] 	INS 172/06	6.0	1.5	204 604	220 874 [3] 220 874 [3]	INS 172/25	4.0 - 25.0 mm^2 AWG 10-3	1.5 mm^2 AWG 16	203 204 205 206 207 603 604 605 606 607	220 874 [3] 220 874 [3] 220 472 [3] 220 472 [3] 220 473 220 874 [3] 220 874 [3] 221 554 [3] 220 473 220 473
	INS 172/10	10.0	1.5	205 605	220 472 [3] 221 554 [3]					
	INS 172/16	16.0	1.5	206 606	220 472 [3] 220 473					

[1] Strain reliefs must be mounted in the conduit thread screws of the motor power connector to ensure a problem-free operation. These are not automatically delivered. The suitable strain reliefs must be ordered from Indramat using the relevant Mat.-Nr. .

[2] For motor blocking brake and motor temperature monitoring.

[3] Further reduction requires Mat. Nr. 220 474.

Fig 9.3: Motor power connector

9.4. Motor Power Cable

9.4.1. Technical data

Type	Power core cross section mm²	Control core[1] cross section mm²	Total shield	Power cable cross section mm	Minimum bending radius		Weight kg/m
					fixed routing mm	flexible routing mm [2]	
INK 253	1.0	0.5	—	10.3 ± 0.3	65	105	0.11
INK 250	1.5	0.75	—	11.4 ± 0.4	90	140	0.19
INK 202	2.5	1.5	—	17.8 ± 0.5	120	200	0.47
INK 203	4.0	1.5	—	18.6 ± 0.5	120	270	0.57
INK 204	6.0	1.5	—	19.8 ± 0.5	120	300	0.67
INK 205	10.0	1.5	—	25.4 ± 0.7	200	380	1.10
INK 206	16.0	1.5	—	26.8 ± 0.7	220	390	1.33
INK 207	25.0	1.5	—	30.5 ± 0.7	240	430	1.70
INK 653	1.0	0.75	+	11.5 ± 0.3	75	100 [2]	0.25
INK 650	1.5	0.75	+	12.2 ± 0.4	80	120 [2]	0.39
INK 602	2.5	0.75	+	14.8 ± 0.5	85	140 [2]	0.59
INK 603	4.0	0.75 or 1.0	+	17.8 ± 0.6	110	180 [2]	0.60
INK 604	6.0	0.75 or 1.0	+	19.8 ± 0.6	120	200 [2]	0.81
INK 605	10.0	0.75 or 1.0	+	23.8 ± 0.6	150	240 [2]	1.10
INK 606	16.0	1.0	+	28.2 ± 0.6	160	280 [2]	1.40
INK 607	25.0	1.5	+	31.8 ± 0.8	180	300 [2]	1.73

[1] For motor blocking brake and motor temperature monitoring.
[2] Service life equals 1 000 000 bending loads

Fig 9.4: Type code dependent data of the motor power cable

9.4.2. General data

Designation	Data
Prot. cat. transition cable to connector	IP 65
Chemical features	absolute resistance to mineral oils and greases, hydrolysis resistant, silicone and halogen free
Permissible ambient temperature range for operation and storage	-30 to + 80 °C
Cable surface	poor adhesion, prevents sticking in drag chains
Cable length	maximum 75 meters

Fig 9.5: General data of the motor power cable

9.4.3. Ready-Made Motor Power Cables

Servo motor MAC …	Cooling of the motor	Motor power connector	Motor power cable		Cable ends for …		
			Type	mm²	Direct connection to drives	Intermediate terminals to terminal strip	Intermediate plug-in connection with coupling [1]
063 A-0-ES	natural convection	INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 A-0-RS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 B-0-GS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 B-0-JS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 C-0-MS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 C-0-HS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 D-0-JS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 D-0-FS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 A-•-ES	surface cooling	INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 A-•-RS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 B-•-GS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 B-•-JS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 C-•-MS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 C-•-HS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 D-•-JS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
063 D-•-FS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003

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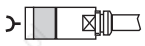
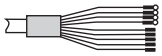
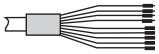
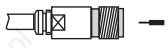
[1] For coupling suitable mate: motor power connector

Servo motor MAC …	Cooling of the motor	Motor power connector 	Motor power cable Type	mm²	Cable ends for … Direct connection to drives 	Intermediate terminals to terminal strip 	Intermediate plug-in connection with coupling [1] 
071 A-0-HS	natural convection	INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
071 A-0-OS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
071 A-0-ES		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
071 A-0-VS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
071 B-0-FS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
071 B-0-TS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
071 B-0-PS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
071 B-0-KS		INS 108/02	INK 250	1.5	IK• 021	IK• 022	IK• 023
071 C-0-US		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
071 C-0-NS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
071 C-0-JS		INS 108/02	INK 250	1.5	IK• 021	IK• 022	IK• 023
071 C-0-GS		INS 108/03	INK 202	2.5	IK• 041	IK• 042	IK• 043
071 A-•-HS	surface cooling	INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
071 A-•-OS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
071 A-•-ES		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
071 A-•-VS		INS 108/02	INK 250	1.5	IK• 021	IK• 022	IK• 023
071 B-•-FS		INS 108/06	INK 253	0.75	IK• 011	IK• 012	IK• 003
071 B-•-TS		INS 108/02	INK 250	1.5	IK• 021	IK• 022	IK• 023
071 B-•-PS		INS 108/02	INK 250	1.5	IK• 021	IK• 022	IK• 023
071 B-•-KS		INS 108/03	INK 202	2.5	IK• 041	IK• 042	IK• 043
071 C-•-US		INS 108/02	INK 250	1.5	IK• 021	IK• 022	IK• 023
071 C-•-NS		INS 108/03	INK 202	2.5	IK• 041	IK• 042	IK• 043
071 C-•-JS		INS 108/04	INK 203	4.0	IK• 061	IK• 062	IK• 063
071 C-•-GS		INS 108/06	INK 204	6.0	IK• 081	IK• 082	IK• 089

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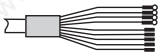
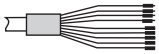
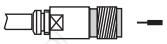
[1] For coupling suitable mate: motor power connector

Servo motor MAC …	Cooling of the motor	Motor power connector	Motor power cable Type	mm²	Cable ends for … Direct connection to drives 	Intermediate terminals to terminal strip 	Intermediate plug-in connection with coupling [1] 
090 A-0-Z•	natural convection	INS 108/06	INK 253	0,75	IK• 011	IK• 012	IK• 003
090 A-0-R•		INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
090 B-0-P•		INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
090 B-0-N•		INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
090 B-0-J•		INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
090 C-0-K•		INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
090 C-0-G•		INS 108/03	INK 202	2,5	IK• 041	IK• 042	IK• 043
090 C-0-E•		INS 108/06	INK 204	6,0	IK• 081	IK• 082	IK• 089
090 A-•-Z•	surface cooling	INS 108/06	INK 253	0,75	IK• 011	IK• 012	IK• 003
090 A-•-R•		INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
090 B-•-P•		INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
090 B-•-N•		INS 108/03	INK 202	2,5	IK• 041	IK• 042	IK• 043
090 B-•-J•		INS 108/04	INK 203	4,0	IK• 061	IK• 062	IK• 063
090 C-•-K•		INS 108/04	INK 203	4,0	IK• 061	IK• 062	IK• 063
090 C-•-G•		INS 108/06	INK 204	6,0	IK• 081	IK• 082	IK• 089
090 C-•-E•		INS 172/10	INK 205	10,0	IK• 121	IK• 122	IK• 128

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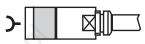
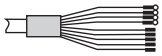
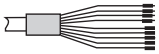
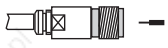
[1] For coupling suitable mate: motor power connector

Servo motor MAC …	Cooling of the motor	Motor power connector 	Motor power cable Type	mm²	Cable ends for … Direct connection to drives 	Intermediate terminals to terminal strip 	Intermediate plug-in connection with coupling [1] 
093 A-0-WS		INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
093 A-0-PS		INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
093 A-0-LS		INS 108/03	INK 202	2,5	IK• 041	IK• 042	IK• 043
093 A-0-HS		INS 108/04	INK 203	4,0	IK• 061	IK• 062	IK• 063
093 B-0-OS		INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
093 B-0-JS	**natural**	INS 108/04	INK 203	4,0	IK• 061	IK• 062	IK• 063
093 B-0-GS	**convection**	INS 172/06	INK 204	6,0	IK• 101	IK• 102	IK• 108
093 B-0-ES		INS 172/10	INK 205	10,0	IK• 121	IK• 122	IK• 128
093 C-0-KS		INS 108/03	INK 202	2,5	IK• 041	IK• 042	IK• 043
093 C-0-FS		INS 172/06	INK 204	6,0	IK• 101	IK• 102	IK• 108
093 C-0-DS		INS 172/10	INK 205	10,0	IK• 121	IK• 122	IK• 128
093 C-0-CS		INS 172/10	INK 205	10,0	IK• 121	IK• 122	IK• 128
093 A-•-WS		INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
093 A-•-PS		INS 108/03	INK 202	2,5	IK• 041	IK• 042	IK• 043
093 A-•-LS		INS 108/04	INK 203	4,0	IK• 061	IK• 062	IK• 063
093 A-•-HS		INS 108/04	INK 203	4,0	IK• 061	IK• 062	IK• 063
093 B-•-OS		INS 108/03	INK 202	2,5	IK• 041	IK• 042	IK• 043
093 B-•-JS	**surface**	INS 108/04	INK 203	4,0	IK• 061	IK• 062	IK• 063
093 B-•-GS	**cooling**	INS 172/10	INK 205	10,0	IK• 121	IK• 122	IK• 128
093 B-•-ES		INS 172/16	INK 206	16,0	IK• 141	IK• 142	IK• 148
093 C-•-KS		INS 108/04	INK 203	4,0	IK• 061	IK• 062	IK• 063
093 C-•-FS		INS 172/10	INK 205	10,0	IK• 121	IK• 122	IK• 128
093 C-•-DS		INS 172/16	INK 206	16,0	IK• 141	IK• 142	IK• 148
093 C-•-CS		INS 172/25	INK 207	25,0	IK• 161	IK• 162	IK• 168

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[1] For coupling suitable mate: motor power connector

Servo motor MAC …	Cooling of the motor	Motor power connector	Motor power cable		Cable ends for …		
			Type	mm²	Direct connection to drives	Intermediate terminals to terminal strip	Intermediate plug-in connection with coupling [1]
112 A-0-Z•	natural convection	INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
112 A-0-V•		INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
112 A-0-L•		INS 108/04	INK 203	4,0	IK• 061	IK• 062	IK• 063
112 B-0-P•		INS 108/03	INK 202	2,5	IK• 041	IK• 042	IK• 043
112 B-0-L•		INS 108/04	INK 203	4,0	IK• 061	IK• 062	IK• 063
112 B-0-G•		INS 108/06	INK 204	6,0	IK• 081	IK• 082	IK• 089
112 C-0-K•		INS 108/04	INK 203	4,0	IK• 061	IK• 062	IK• 063
112 C-0-H•		INS 108/06	INK 204	6,0	IK• 081	IK• 082	IK• 089
112 C-0-E•		INS 172/10	INK 205	10,0	IK• 121	IK• 122	IK• 128
112 C-0-C•		INS 172/25	INK 207	25,0	IK• 161	IK• 162	IK• 168
112 D-0-H•		INS 108/06	INK 204	6,0	IK• 081	IK• 082	IK• 089
112 D-0-F•		INS 172/10	INK 205	10,0	IK• 121	IK• 122	IK• 128
112 D-0-E•		INS 172/16	INK 206	16,0	IK• 141	IK• 142	IK• 148
112 A-••-Z•	surface cooling	INS 108/02	INK 250	1,5	IK• 021	IK• 022	IK• 023
112 A-••-V•		INS 108/03	INK 202	2,5	IK• 041	IK• 042	IK• 043
112 A-••-L•		INS 108/06	INK 204	6,0	IK• 081	IK• 082	IK• 089
112 B-••-P•		INS 172/25	INK 203	4,0	IK• 061	IK• 062	IK• 063
112 B-••-L•		INS 108/06	INK 204	6,0	IK• 081	IK• 082	IK• 089
112 B-••-G•		INS 172/16	INK 206	16,0	IK• 141	IK• 142	IK• 148
112 C-••-K•		INS 172/10	INK 205	10,0	IK• 121	IK• 122	IK• 128
112 C-••-H•		INS 172/16	INK 206	16,0	IK• 141	IK• 142	IK• 148
112 C-••-E•		INS 172/25	INK 207	25,0	IK• 161	IK• 162	IK• 168
112 D-••-H•		INS 172/16	INK 206	16,0	IK• 141	IK• 142	IK• 148
112 D-••-F•		INS 172/16	INK 206	16,0	IK• 141	IK• 142	IK• 148
112 D-••-E•		INS 172/25	INK 207	25,0	IK• 161	IK• 162	IK• 168

Continued on next page

[1] For coupling suitable mate: motor power connector

Servo motor MAC …	Cooling of the motor	Motor power connector	Motor power cable Type	mm²	Cable ends for … Direct connection to drives	Intermediate terminals to terminal strip	Intermediate plug-in connection with coupling [1]
115 A-0-HS	natural convection	INS 172/06	INK 204	6,0	IK• 101	IK• 102	IK• 108
115 A-0-FS		INS 172/10	INK 205	10,0	IK• 121	IK• 122	IK• 128
115 B-0-GS		INS 172/06	INK 204	6,0	IK• 101	IK• 102	IK• 108
115 B-0-DS		INS 172/16	INK 206	16,0	IK• 141	IK• 142	IK• 148
115 C-0-ES		INS 172/10	INK 205	10,0	IK• 121	IK• 122	IK• 128
115 C-0-CS		INS 172/25	INK 207	25,0	IK• 161	IK• 162	IK• 168
115 D-0-ES		INS 172/10	INK 205	10,0	IK• 121	IK• 122	IK• 128
115 D-0-DS		INS 172/16	INK 206	16,0	IK• 141	IK• 142	IK• 148
115 D-0-CS		INS 172/25	INK 207	25,0	IK• 161	IK• 162	IK• 168
115 A-•-HS	surface cooling	INS 172/10	INK 205	10,0	IK• 121	IK• 122	IK• 128
115 A-•-FS		INS 172/16	INK 206	16,0	IK• 141	IK• 142	IK• 148
115 B-•-GS		INS 172/16	INK 206	16,0	IK• 141	IK• 142	IK• 148
115 B-•-DS		INS 172/25	INK 207	25,0	IK• 161	IK• 162	IK• 168
115 C-•-ES		INS 172/25	INK 207	25,0	IK• 161	IK• 162	IK• 168
115 D-•-ES		INS 172/25	INK 207	25,0	IK• 161	IK• 162	IK• 168
115 D-•-DS		INS 172/25	INK 207	25,0	IK• 161	IK• 162	IK• 168

[1] For coupling suitable mate: motor power connector

Fig 9.6: Types of ready-made motor power cable differentiated by cable end

9.4.4. Order guidelines

Example: IK[L] 041 / [12.0]

- 12.0 — Length in meters
- L — L… Standard cable without total shield
- G — G… Cable with total shield

The cable are available in 0.5 meter increments from a length of 5 meters. Shorter lengths available upon request.

10. Electrical Connection Tachofeedback

10.1. Terminal Diagram

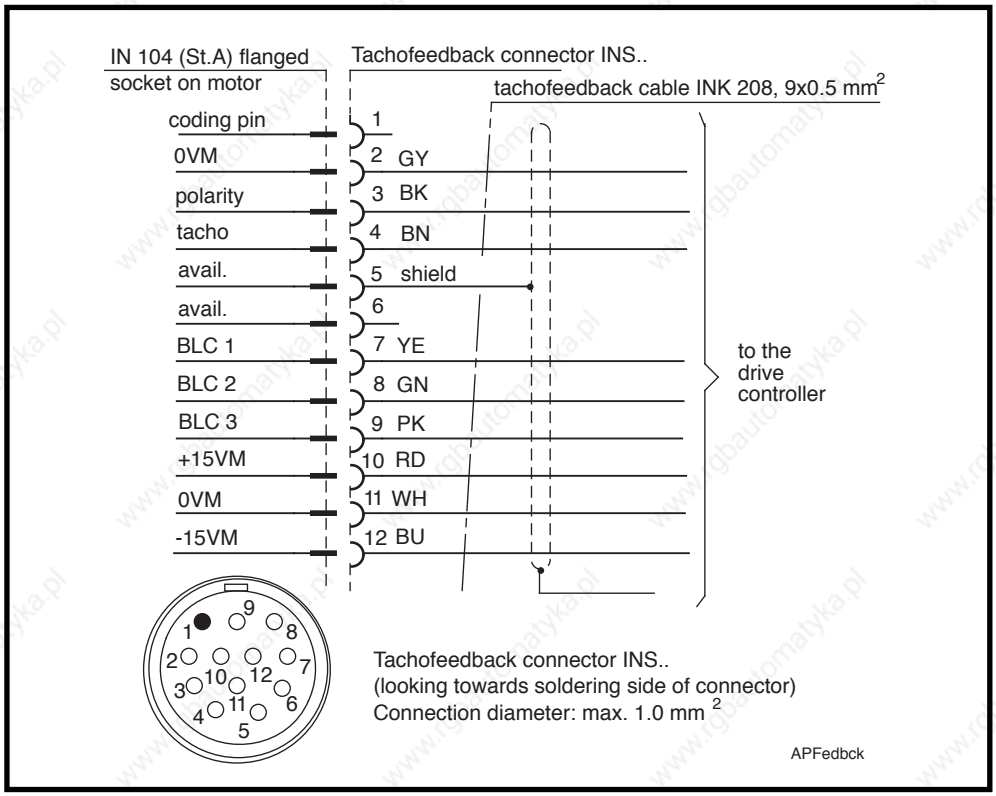
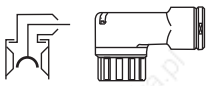
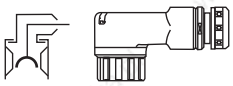


Fig 10.1: Tachofeedback connection

10.2. Tachofeedback Connector

Motor type MAC…	Types of connectors for INDRAMAT cable INK 208		Connector types suitable for cable with external diameter …	
	straight connector	angle connector	(…6.5 - 9.5 mm) straight connector	(…7.0 - 10.5 mm) angle connector
063…	INS 302	–	INS 102	–
071…[1] 090…[1] 093…[1] 112…[2] 115…[2]	INS 302	INS 352 [3] 	INS 102	INS 312 [3] 

[1] With axial surface cooling, use straight connectors only.
[2] With axial surface cooling, use straight connectors with extension sleeves only (part no. 218277).
[3] Do not use with MAC 093 in connection with power connector INS 172, if power connector mounted towards side B.

Fig 10.2: Available tachofeedback connectors

10.3. Tachofeedback Cable

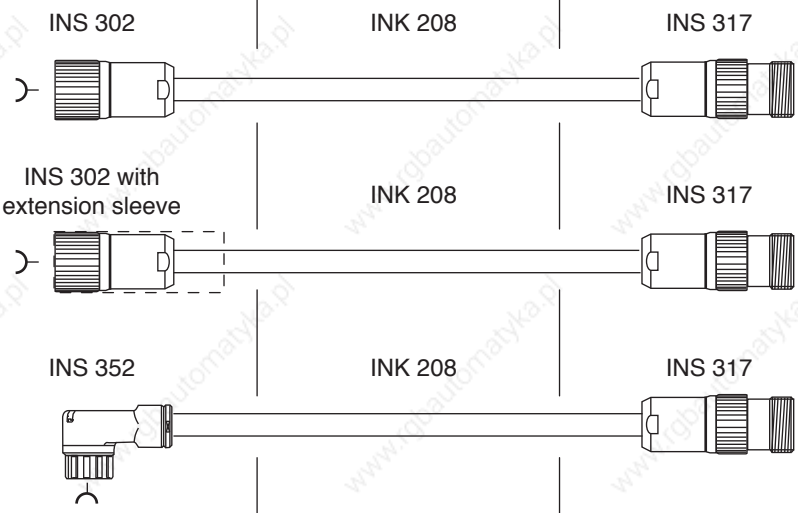
10.3.1. Technical Data

Type designation	INK 208
Prot. cat. transition cable to conn.	IP 65
Cable diameter	8.8 ± 0.3 mm
Minimum bending radius fixed routing	40 mm
Minimum bending radius flexible routing (Service life equals 1,000,000 bend loads)	90 mm
Weight	0.103 kg/m
Permissible ambient temperature for operation and storage	-30 °C to +80 °C
Cable surface	adhesion poor, prevents sticking in drag chains
Chemical characteristics	absolue resistance to mineral oils and greases, hydrolysis resistant, silicone and halogen free
Maximum cable length	75 m

Fig 10.3: Technical data tachofeedback cable INK 208

10.3.2. Ready-Made Tachofeedback Cable

Order codes for ready-made tachofeedback cable	Type codes of tachofeedback connector	INDRAMAT tachofeedback cable	Type of cable end
IKS 255	INS 302	INK 208	INS 317
IKS 256 [1]	INS 302 with extension sleeve	INK 208	INS 317 with coupling unit for connecting matching mate INS 302
IKS 261 [2) 3)]	INS 352	INK 208	INS 317
IKS 251	INS 302	INK 208	
IKS 252 [1]	INS 302 with extension sleeve	INK 208	with ferrules for connecting to terminal strip of drive controller
IKS 259 [2) 3)]	INS 352	INK 208	



1) with MAC 112 and 115 with axial surface cooling
2) do not use in motors with axial surface cooling
3) do not use in MAC 093 together with INS 172 and mounting orientation side B

MZFEEDBACK

Fig 10.4: Ready-made feedbackcable

10.3.3. Order guidelines

Example: IKS 255 / 12.0

length in meters

The ready-made cables are available in increments of 0.5 meters from five meters. Shorter lengths available upon request.

11. Electrical Connection Incremental Encoder

11.1. Terminal Diagram

Encoder with square-wave pulse

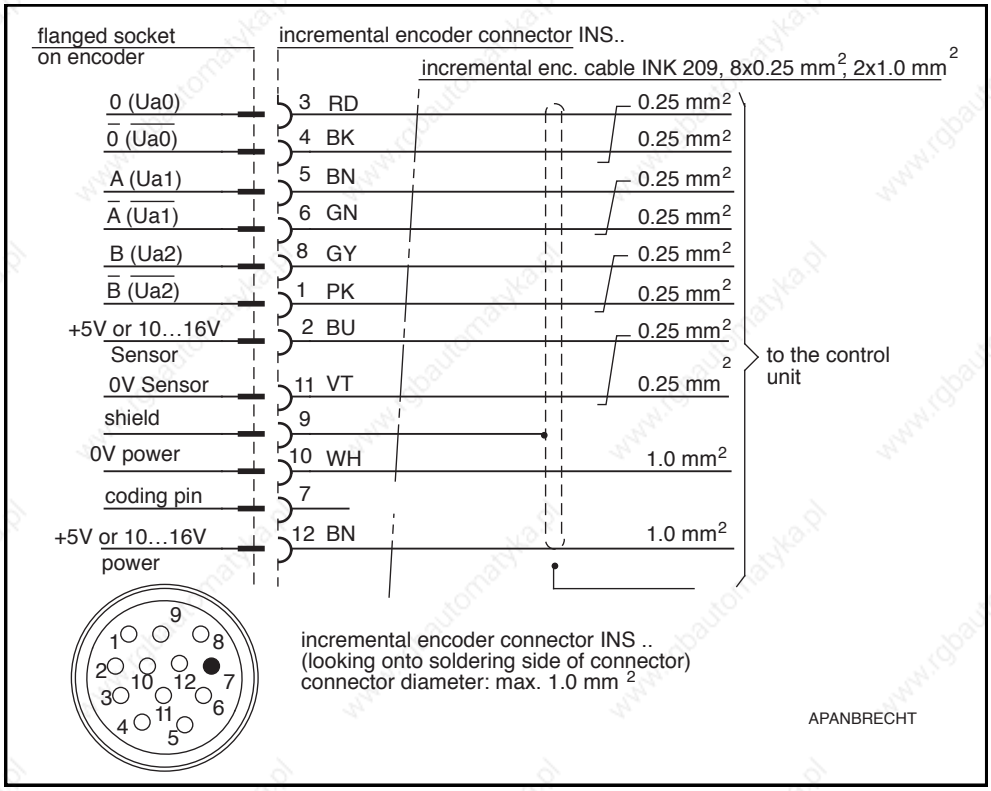


Fig 11.1: Incremental encoder terminal diagram - 5V and 10-16V, square-wave pulse

Encoder with sinusoidal signal

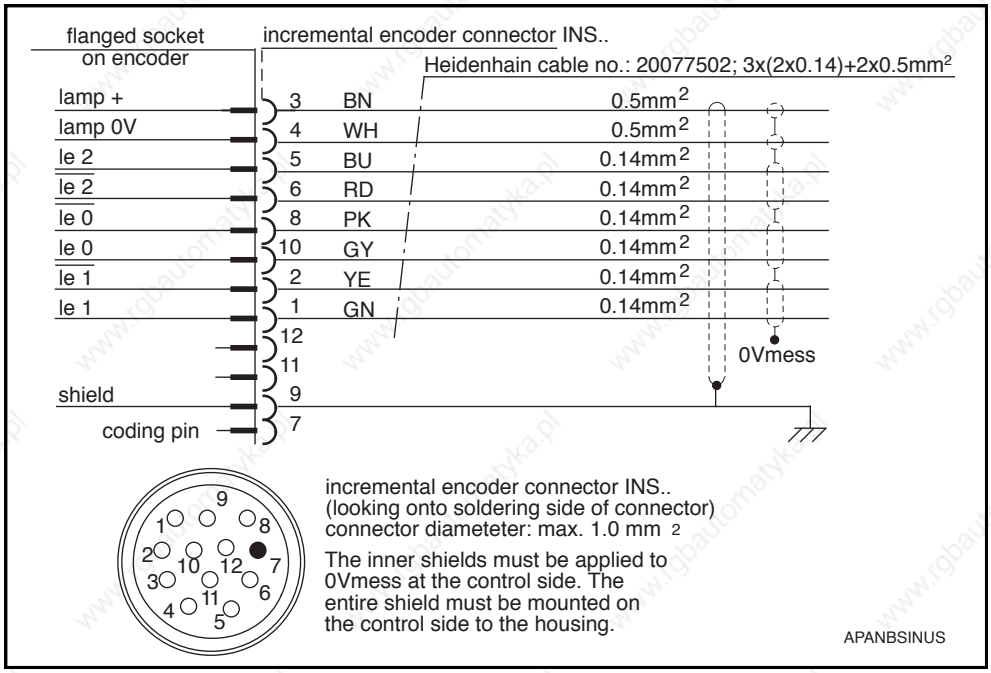
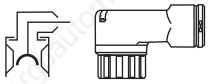
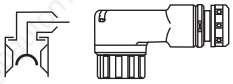


Fig 11.2: Incremental encoder - terminal diagram - sinus signals

11.2. Incremental Encoder Connector

Mototyp MAC…	Types of connectors for INDRAMAT cable INK 209		Connector types suitable for Heidenhain cable or cable with external diameter …	
	straight connector	angle connector	(…6.5 - 9.5 mm) straight connector	(…7.0 - 10.5 mm) angle connector
063… 071…[1] 090…[1] 093…[1] 112…[2] 115…[2]	INS 301	INS 351 	INS 101	INS 311 

[1] With axial surface cooling use straight connector only.
[2] With axial surface cooling use straight connector with extension sleeve only (part no. 218277).

Fig 11.3: Available incremental encoder connectors

11.3. Incremental Encoder Cable

11.3.1. Technical Data

INDRAMAT cable

Type designation	INK 209
Prot. cat. transition cable to conn.	IP 65
Cable diameter	8.8 ± 0.3 mm
Minimum bending radius fixed routing	40 mm
Minimum bending radius flexible routing (Service life equals 1,000,000 bend loads)	90 mm
Weight	0.102 kg/m
Permissible ambient temperature for operation and storage	-30 °C to +80 °C
Cable surface	adhesion poor, prevents sticking in drag chains
Chemical characteristics	resistant to mineral oils and greases, hydrolysis resistant, silicone and halogen free
Maximum cable length	50 m

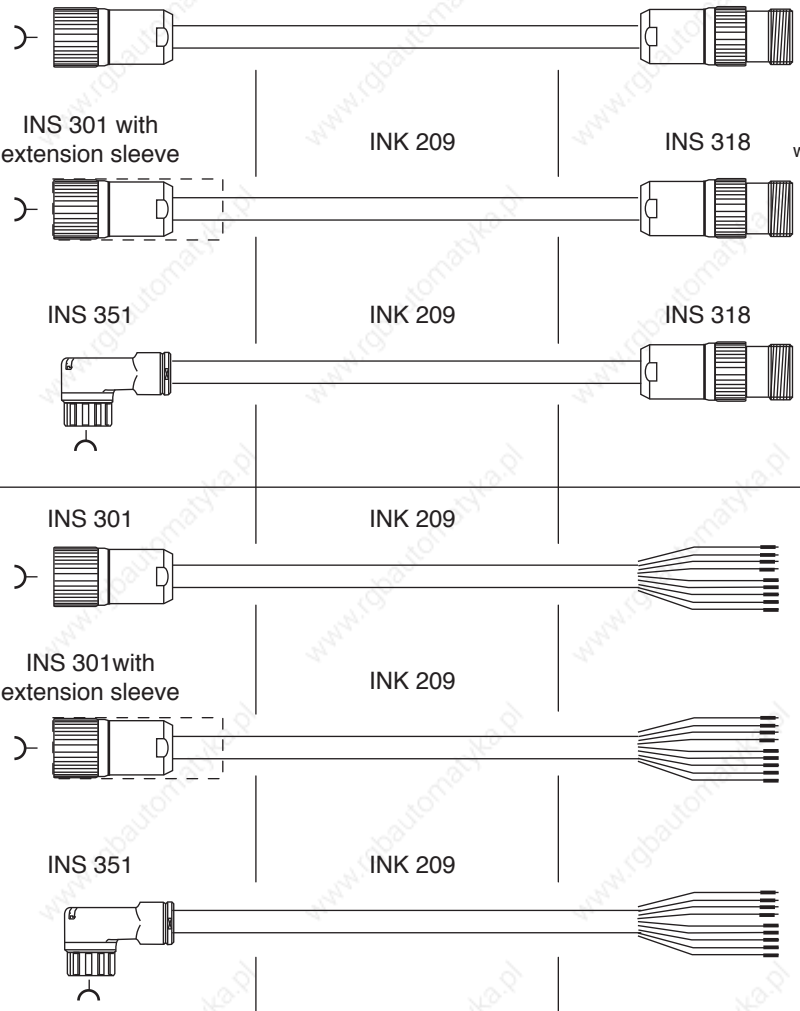
Fig 11.4: Technical data - incremental encoder cable - INK 209

Heidenhain cable

For technical data on the Heidenhain cable, please see the Heidenhain documentation. Maximum cable length equals 50 meters.

11.3.2. Ready-Made Incremental Encoder Cable for Encoders with Square-Wave Pulses

Order code for ready-made incremental encoder cables	Type codes for incremental encoder connectors	INDRAMAT incremental encoder cable	Type of cable end
IKS 303		INK 209	INS 318
IKS 304 1)	INS 301 with extension sleeve	INK 209	INS 318 with coupling unit to connect matching connector INS 301
IKS 309 2)	INS 351	INK 209	INS 318
IKS 301	INS 301	INK 209	
IKS 302 1)	INS 301with extension sleeve	INK 209	with ferrules for connecting to terminal strip 3)
IKS 307 2)	INS 351	INK 209	



1) in MAC 112 and 115 with axial surface cooling
2) do not use in motors with axial surface cooling
3) avoid because of interference in shield

KonfINK

Fig 11.5: Ready-made incremental encoder cable for encoders with square-wave pulses

11.3.3. Order guidelines

Example : IKS 301 / 12.0

Length in meters

The ready-made cables are available in increments of 0.5 meters from five meters. Shorter lengths available upon request.

12. Electrical Connection Absolute Encoder

12.1. Terminal Diagram

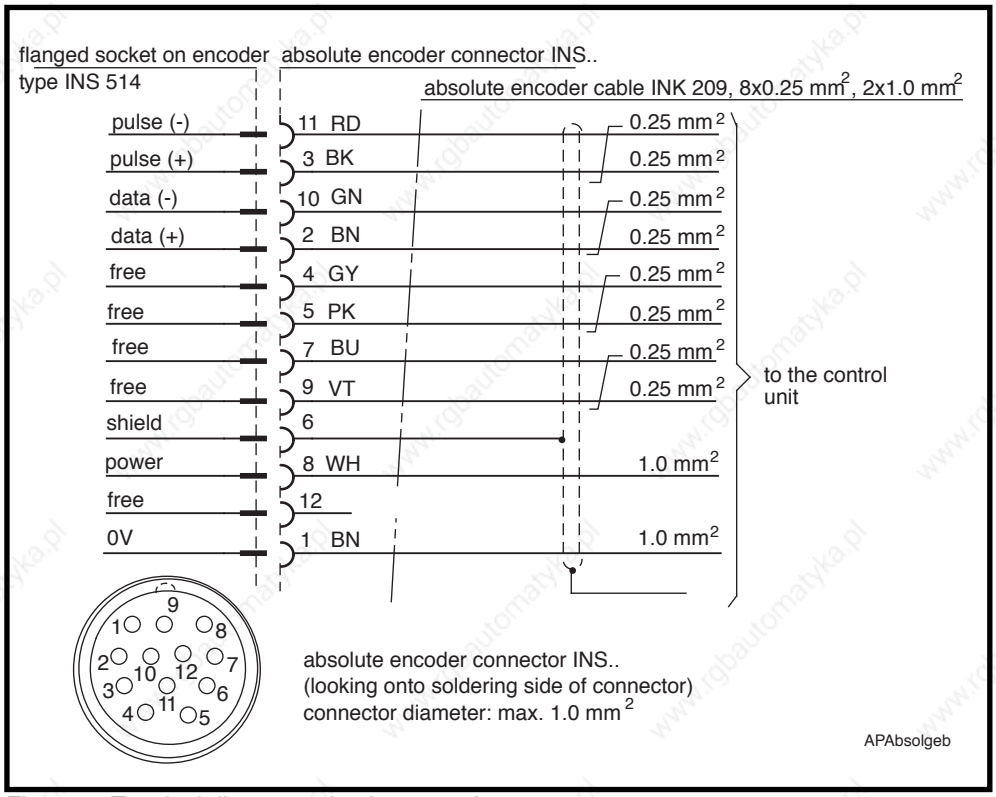


Fig 12.1: Terminal diagram - absolute encoder

12.2. Absolute Encoder Connector

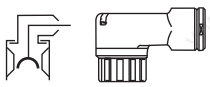
Motor type MAC…	Types of connectors for INDRAMAT cable INK 209		Connector types suitable for cable with external diameter of 6.5 - 9.5 mm
	straight connector	angle connector	straight connector
063… 071…[1)] 090…[1)] 093…[1)] 112…[1)] 115…[1)]	INS 326	INS 322 	INS 092
[1)] Can be used with axial surface cooling straight connector.			

Fig 12.2: Available absolute encoder connectors

12.3. Absolute Encoder Cable

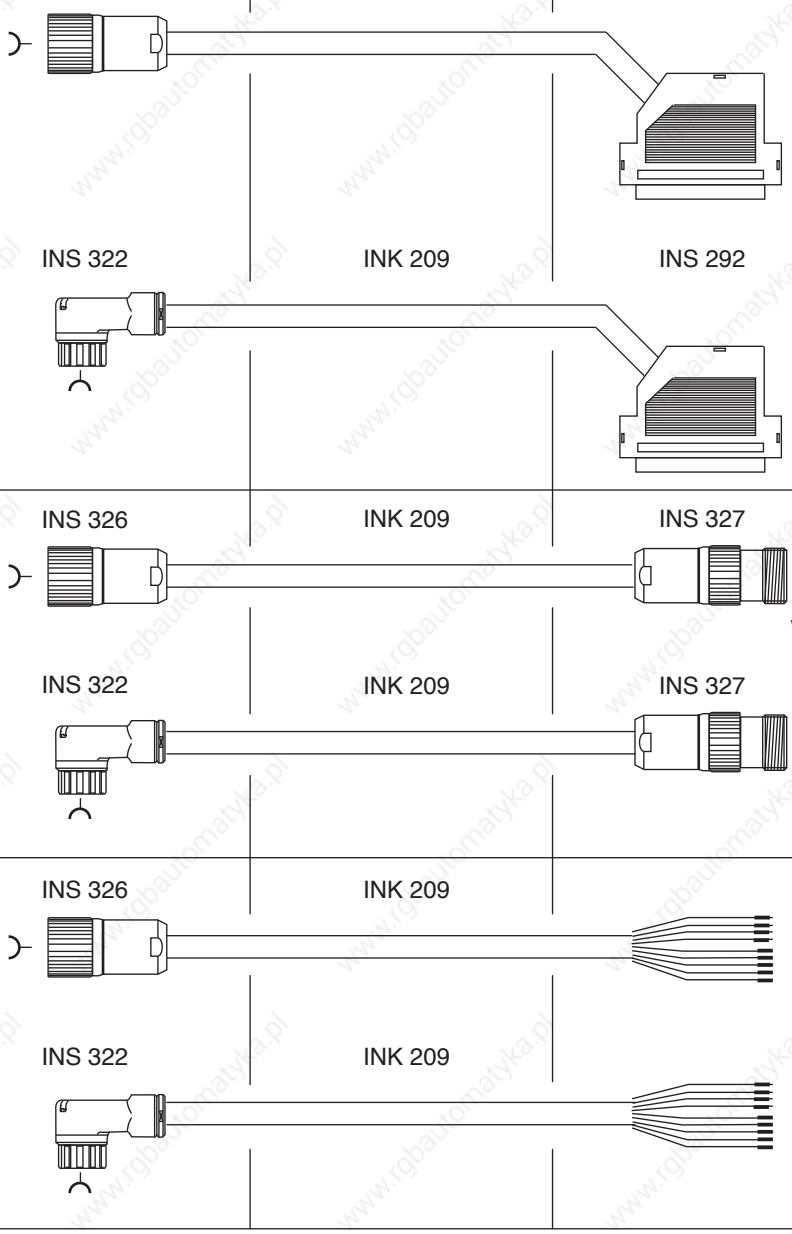
12.3.1. Technical Data

Type designation	INK 209
Prot. cat. transition cable to connector	IP 65
Cable cross section	8.8 ± 0.3 mm
Minimum bending radius fixed routing	40 mm
Minimum bending radius flexible routing (Service life equals 1,000,000 bend loads)	90 mm
Weight	0.102 kg/m
Permissible ambient temperature for operation and storage	-30 °C to +80 °C
Cable surface	adhesion poor, prevents sticking in drag chains
Chemical characteristics	resistant to mineral oils and greases, hydrolysis resistant, silicone and halogen free
Maximum cable length	100 m

Fig 12.3: Technical data absolute encoder cable INK 209

12.3.2. Ready-Made Absolute Encoder Cables

Order code for ready-made absolute encoder cable	Type code of absolute encoder connector	INDRAMAT absolute encoder cable	Type of cable end
IKS 724	INS 326	INK 209	INS 292
IKS 729 [1]	INS 322	INK 209	INS 292
IKS 806	INS 326	INK 209	INS 327
IKS 807 [1]	INS 322	INK 209	INS 327
IKS 801	INS 326	INK 209	
IKS 805 [1]	INS 322	INK 209	



1) do not use in motors with axial surface cooling
2) avoid due to interference in shield

MZFEEDBACK

Fig 12.4: Ready-made absolute encoder cables

12.3.3. Order guidelines

Example : IKS 801 / 12.0

Length in meters

The ready-made cables are available in increments of 0.5 meters from five meters. Shorter lengths available upon request.

13. Guidelines on Routing Encoder Cables

Past experiences in the industry have shown that the design of an installation can be of significant importance for the interference-free transmission of encoder signals. The following should be noted with respect to the routing of the cables:

- Route the cables with shielding and separately of the load voltage lines and mains control lines.
- If the encoder cables are routed parallel to the motor cables, then maintain a minimum distance of 100 mm or equip with a metallic partition to the service cable.
- The shield of the encoder cable should be applied to the NC in the encoder connector.
- The shield may not be applied on the housing but on the motor. The encoders are insulated against the servo motor. This prevents earth loops.
- Neither pull out nor insert the connector while voltage is being applied.

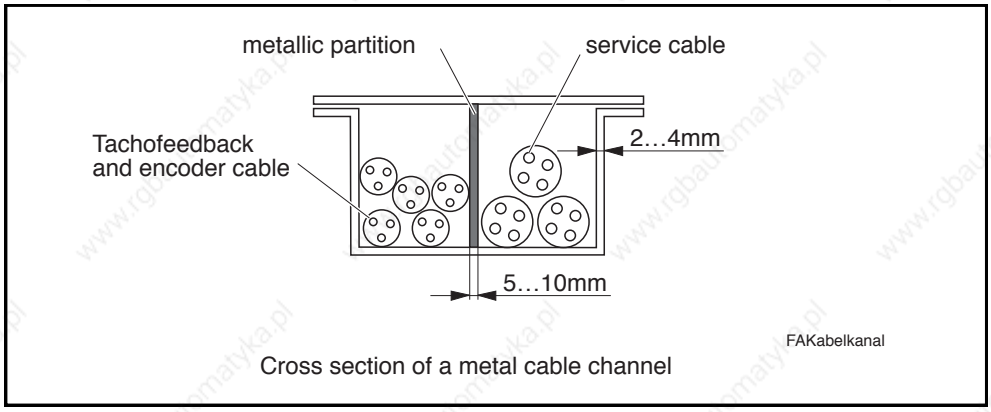


Fig 13.1: Example of a metallic partition of the control cables to prevent interference from power cables.

14. Condition at Delivery

The motors are packed onto a palette or in cartons at the time of delivery. The way they are packed depends upon the numbers and/or sizes of the motor.

If a single motor is packed on a palette, then it is secured against sliding and movement by means of a squared timbers, and then tightly lashed into place with taut metal bands. If several motors are simultaneously delivered, then up to three motors will be on one palette. Pieces of styrofoam or cartons are then used to prevent them from damaging each other.

To prevent damage from inclement weather, a carton is palced over a palette and then affixed to the palette with the use of taut bands.

To unpack without damaging the items, simply cut through the taut bands.

Caution! There is tension in the taut bands!

There exists the danger of injury from uncontrolled lashing out of the taut bands!

Maintain sufficient distance! Cut taught bands open carefully!

There is an envelope containing the delivery slip attached to the carton.

There is also a barcode sticker, or stickers depending on the extent of the delivery, listing the following information:

- type designation of the motor
- customer
- delivery slip number
- consignment
- name of delivering agent

For additional information, please see section 15, "Identifying the Merchandise".

There is no further documentation accompanying the delivery unless specifically requested.

15. Identifying the Merchandise

Only one delivery slip accompanies the entire delivery. This slip lists the merchandise in terms of its name and order designations. In the event that some of the listed items are distributed over several cartons or transport containers, then this will be noted in the delivery or freight slip.

Barcode Sticker

There is a barcode sticker on the packaging of the motor. If several motors are in one carton or container, then there is a sticker for each motor.

The sticker helps to identify the contents of the cartons and is required to complete the order procedure at Indramat.

The following information is on the sticker:

- type designation of the motor
- customer
- delivery slip number
- consignment
- name of the delivering agent

Fig 15.1: An example of a barcode sticker

Rating Plate

The motor is delivered with a rating plate which is attached to the motor housing.

If a second rating plate is ordered, then it is placed over the original one with double-sided tape. Both are on the housing of the motor.

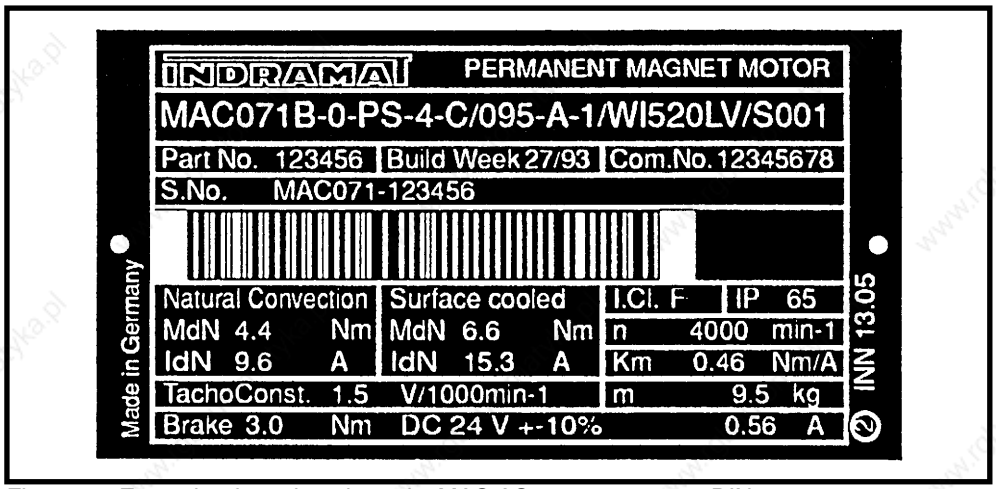


Fig 15.2: Example of a rating plate of a MAC AC servo motor per DIN 42961

16. Storage, Transport and Handling

There are guidelines on storage and transportation printed on the carton. These must be followed.

Achtung
Hochwertige Elektronik
Attention
Fragile Electronics

Vor Nässe schützen	**Nicht werfen**
Nicht belasten	**Nicht kanten**
Do not apply load	**Do not tip**
Do not drop	**Keep dry**

Fig 16.1: Guidelines on storage and transport on packaging

Storing the Motors

The motors must be stored in a dry, dust-free and shock-free environment.

Permissible ambient temperature range: -25 °C to + 85 °C.

There are protective covers on the connector housing as well as the output shaft. These are made of plastic and protect the parts they cover against moisture and damage. Do not remove the protective covers until shortly prior to mounting into the machine.

Transport and Handling

Avoid impacts to the output shaft and heavy loads as otherwise the bearings in the motor could be damaged.

Note the different weights and sizes of the individual types of motors when selecting both the transport and lifting devices.

Do not pick up the motor at the blower. This will damage and possibly tear the blower off of the motor housing.

Figure 16.2 depicts how the heavy motors should be picked up with the help of a crane and belts. It is important that no load be applied to either output shaft or blower housing during this procedure!

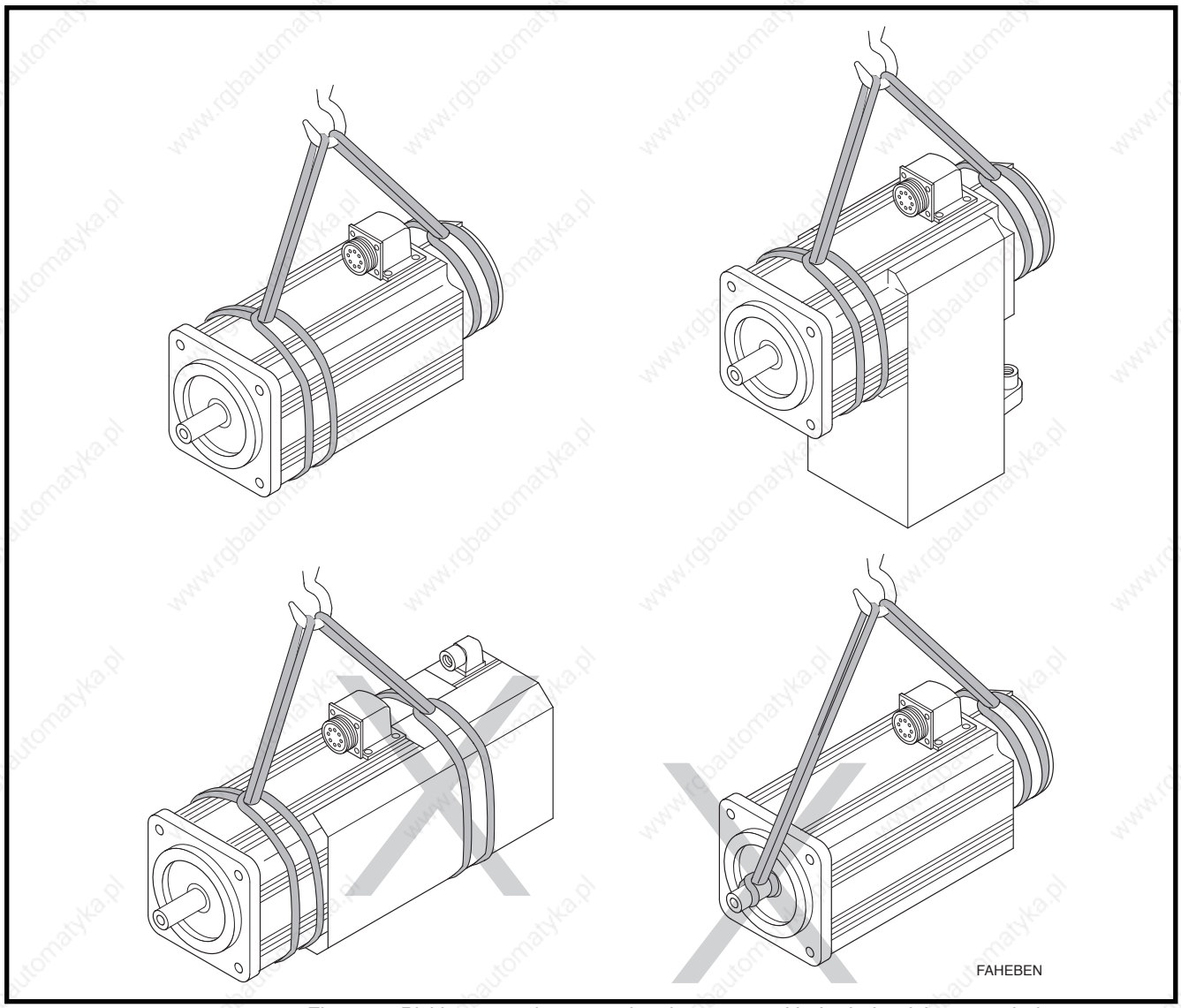


Fig 16.2: Picking up and transporting the motors with the help of the crane belts

There are two M8 tapped holes in the housing of the MAC 112 and MAC 115 line of motors. Lifting screws, per DIN 580, can be screwed into place here. These can then be used for holding the motor in place by a suitable lifting device. The hooks of a chain tackle can, for example, be hooked into place here. See Figure 16.3 for illustration.

INDRAMAT does not automatically deliver these lifting hooks with the motor. The user must, therefore, supply them.

If an axial surface cooling blower is mounted to MAC 112 or 115 motors, then these may only be picked up by the lifting hooks.

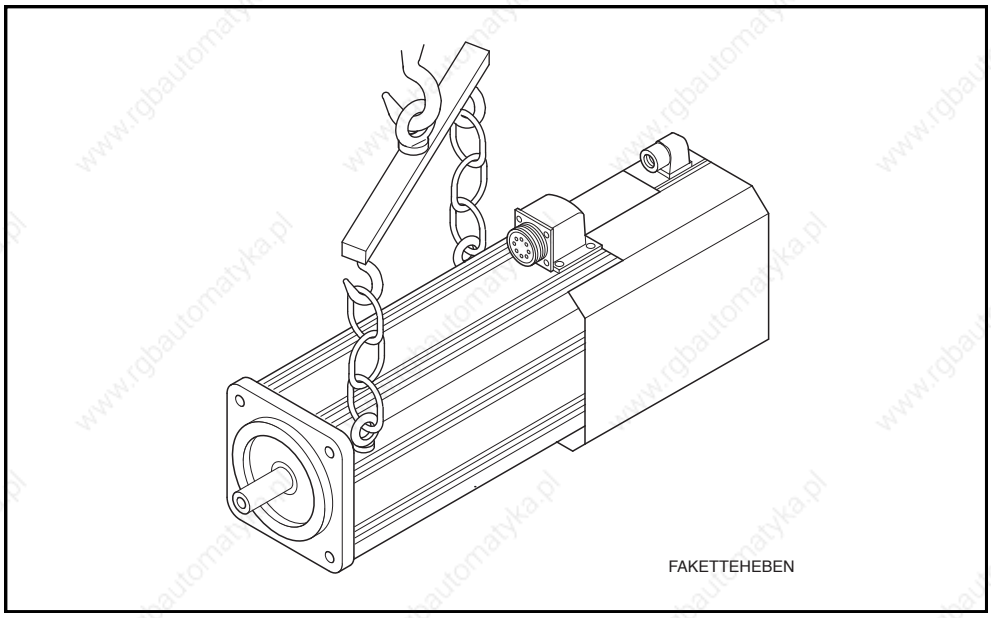


Fig 16.3: Picking up and transporting the MAC 112 and 115 series with chain tackle

17. Mounting and Installation Guidelines

The following guidelines must be followed to avoid damaging the machine when mounting or commissioning:

- The bigger and thus heavier motors may only be transported with the use of suitable lifting devices as described in the guidelines of section 16.
- Avoid impacts to the output shaft and heavy loads at the shaft as otherwise the bearings within the motor could be damaged.
- The motors should only be mounted to the machine by fully trained personnel.
- The spigot nuts on the connectors, e.g., motor power and feedback connectors, must be tightly screwed into place when connecting.
- The motor must be grounded to the drive amplifier.
- The terminal diagrams of the machine manufacturer should be followed when wiring the motor!
- Check the reference point settings when replacing motors (see section 2.4, "Motor feedback").
- The guidelines on cable routing are outlined in section 1.3.
- The guidelines on connecting the motor blower are outlined in section 2.3.

18. Service Notes

18.1. Contacting Customer Service

INDRAMAT customer service can be contacted at the following Service Hotline numbers during the times listed:

Service Hotline

Phone number: 0172-6600406 or 0171-3338826

Monday - Friday	7.00 a.m. to 11.00 p.m. MET
Saturday	8.00 a.m. to 8.00 p.m. MET
Sundays and holidays	9.00 a.m. to 7.00 p.m. MET

We would appreciate your noting the following information prior to contacting Indramat customer service:

- type data of motor and drive
- the problem
- all fault and diagnostics displays

This will make it possible to quickly and definitively locate the problem.

When returning a motor, please include a copy of the repair card on the next page. Fill it out and send it in. This will enable us to locate the problem caused by their particular application.

18.2. Repair Card

Repair Card
for INDRAMAT equipment and components

Name:	Company/Location:		Date:
Part number for exchange of single parts		SN:	Consignment no.:
		SN:	Delivery date:
Machine manufacturer/co.:	Type:	Machine no.:	Commissioning date:
Failure in axis:	☐ horizontal ☐ vertical ☐	Operating time:	Date fault occurred:

Fault:

Fault _____

_____

☐ constantly present
☐ occurs sporadically
☐ occurs after _____ hrs.
☐ occurs with shocks
☐ depends on temperature
☐ other

_____
_____
_____

Additional data:
(e.g., LED diagnosis, error in display)

_____
_____
_____
_____
_____
_____
_____
_____

Cause of fault:

☐ unknown
☐ connection fault
☐ external short circuit
☐ mechanical damage
☐ loose cable(s)
☐ other

_____
_____
_____

Additional Data

General data:

☐ no function
☐ drive not running smoothly
☐ uncontrolled drive motions
☐ error in one direction only
☐ supply unit short-circuit fault
☐ other

Concommitant phenomena:

☐ Problems in mechanical sys.
☐ Mains failure
☐ Control failure
☐ Motor failure
☐ Break in cable
☐ other

Drive, supply unit, amplifier, power section

☐ control voltage faulty
☐ power sect. circuit breaker F ___
☐ blower defective
☐ bleeder resistor defective
☐ power voltage faulty
☐ connecting bolt broke
☐ other

Control:

☐ no function
☐ display failed
☐ no command value output
☐ diagnosis
☐ dim. offset in _____ direction
☐ E-stop loop interrupted
☐ position control loop won't close
☐ program sequence fault
☐ interior auxiliary function faulty (outputs)
☐ acknowledgements not accepted (inputs)
☐ other

_____
_____

Motor:

☐ thermo switch defective
☐ brake defective
☐ blower defective
☐ feedback defective
☐ tachometer signal faulty
☐ BLC-signal faulty
☐ short-circuit to ground
☐ thermal overload
☐ other

_____
_____
_____
_____

Comments:

_____
_____
_____
_____
_____
_____
_____

PlRepBegl

Fig 18.1: Repair card

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