



# Particle Sensor HPM Series

**Table 4. Customer Use Protocol**

Command Length (Bytes)	HEAD	LEN	CMD	Data	CS	Example
<b>Read Particle Measuring Results</b>						
Send	0x68	0x01	0x04	NA	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 01 04 93
Response, Pos ACK	0x40	0x05	0x04	“DF1, DF2, DF3, DF4 PM2.5 = DF1 * 256 + DF2 PM10 = DF3 * 256 + DF4”	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	40 05 04 00 30 00 31 56
Response, Neg ACK						0x9696
<b>Start Particle Measurement</b>						
Send	0x68	0x01	0x04	NA	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 01 01 96
Response, Pos ACK						0xA5A5
Response, Neg ACK						0x9696
<b>Stop Particle Measurement</b>						
Send	0x68	0x01	0x02	NA	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 01 02 95
Response, Pos ACK						0xA5A5
Response, Neg ACK						0x9696
<b>Set Customer Adjustment Coefficient</b>						
Send	0x68	0x02	0x08	DF1: 30 ~ 200 (Default, 100)	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 02 08 64 2A
Response, Pos ACK						0xA5A5
Response, Neg ACK						0x9696
<b>Read Customer Adjustment Coefficient</b>						
Send	0x68	0x01	0x10	NA	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 01 10 87
Response, Pos ACK	0x40	0x02	0x10	DF1: 30 ~ 200 (Default, 100)	CS = MOD ( (65536-(HEAD+LEN+CMD+DATA)), 256)	40 02 10 64 4A
Response, Neg ACK						0x9696
<b>Stop Auto Send</b>						
Send	0x68	0x01	0x20	NA	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 01 20 77
Response, Pos ACK						0xA5A5
Response, Neg ACK						0x9696
<b>Enable Auto Send</b>						
Send	0x68	0x01	0x40	NA	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 01 40 57
Response, Pos ACK						0xA5A5
Response, Neg ACK						0x9696

<sup>1</sup>Life may vary depending on the specific application in which the sensor is utilized.