

Electrical data

At T_A = 25 °C, ± U_c = ±15 V, unless otherwise noted. Lines with a * in the comment column apply over the -40 … 85 °C ambient temperature range.

| Parameter | Symbol | Unit | Min | Тур | Мах | | Comment |
|--|-------------------|-----------|--------|--------|--------|---|---|
| Primary continuous direct current | $I_{_{\rm PNDC}}$ | A | -400 | | 400 | * | |
| Primary nominal rms current | I _{PN} | A | | | 400 | * | |
| Primary current, measuring range | I _{PM} | A | -566 | | 566 | * | Peak limit |
| Measuring resistance over supply voltage range | R _M | Ω | 0 | | 15 | | See graph page 4 |
| Secondary current | Is | mA | -377 | | 377 | * | Peak limit |
| Secondary nominal rms current | I _{sn} | mA | | | 266 | * | |
| Conversion ratio | K _N | | | 1:1500 | | * | |
| Resistance of secondary winding | R _s | Ω | | 11 | | | |
| Overload capability 1) | $\hat{I}_{\rm P}$ | A | -2000 | | 2000 | | @ pulse of 100 ms |
| Supply voltage DC | U _c | V | ±14.25 | ±15 | ±15.75 | * | |
| Current consumption | I _c | mA | | 122 | 128 | | Add I _s for |
| | | | | 131 | 139 | * | consumption |
| Output rms noise current 0 10 Hz 2) | I _{no} | ppm | | | 0.1 | | |
| Output rms noise current 0 100 Hz 2) | | | | | 1 | | |
| Output rms noise current 0 1 kHz 2) | | | | | 1.5 | | |
| Output rms noise current 0 10 kHz 2) | | | | | 4.5 | | |
| Output rms noise current 0 50 kHz 2) | 1 | | | | 9 | | |
| Re-injected rms noise on primary bus bar | | μV | | | 5 | | 0 50 kHz |
| Electrical offset current + self magnetization | I | nnm | | ±38 | ±48 | | |
| + effect of earth magnetic field ²⁾ | OE | ppin | | ±42 | ±55 | * | |
| Offset stability 2) | | ppm/month | | | 1 | | |
| Linearity error ²⁾ | ε | ppm | | ±4 | ±11 | | @ $\pm I_{PN DC}$ range |
| | | | | ±5 | ±12 | * | |
| Step response time to 90 % of I _{PN DC} | t _r | μs | | ļ | 1 | | di/d <i>t</i> of 100 A/µs |
| di/dt accurately followed | di/dt | A/µs | | 100 | | | |
| Frequency bandwidth (±1 dB) | BW | kHz | | 200 | | | Small-signal bandwidth, 0.5 % of I _{PN DC} |
| Frequency bandwidth (±3 dB) | BW | kHz | | 300 | | | Small-signal bandwidth, 0.5 % of I _{PN DC} |

¹⁾ Single pulse only, not AC. The transducer may require a few seconds to return to Notes:

normal operation when autoreset system is running

²⁾ All ppm figures refer to full-scale which corresponds to a secondary nominal rms current (I_{SN}) of 266 mA.



IT 405-S ULTRASTAB

Overload protection - Electrical specification - Status

The overload occurs when the primary current I_{P} exceeds a trip level such that the fluxgate detector becomes completely saturated and, consequently, the transducer will switch from normal operation to overload mode.

This trip level is guaranteed to be greater than 110 % of $I_{\rm PM}$ and its actual value depends on operating conditions such as temperature and measuring resistance.

When this happens, the transducer will automatically begin to sweep in order to lock on the primary current again and the measuring can resume when the primary current returns in the measuring range between $-I_{PM}$ and $+I_{PM}$.

In overload mode, the secondary current I_s generated is a low frequency signal between -0.377 A and 0.377 A.

The overload conditions will be:

- The potential-free contact (normal operation status) between pin 3 and 8 (of the D-sub connector) switches off, this contact becomes open.
- The green LED indicator (normal operation status) turns off.

| Max voltage pin 3 and pin 8, off-State | 100 V |
|--|-------------|
| Max current pin 3 and pin 8, on-State | 1000 mA |
| On-State resistance pin 3 and pin 8: | 30 mΩ (max) |

Maximum measuring resistor versus primary current and temperature

