

## PicoTLynx™ 3A: Non-Isolated DC-DC Power Modules

2.4Vdc –5.5Vdc input; 0.6Vdc to 3.63Vdc output; 3A Output Current

### Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Typ	Max	Unit
Output Voltage Set-point (with 0.5% tolerance for external resistor used to set output voltage)	All	$V_{O, set}$	-1.5		+1.5	% $V_{O, set}$
Output Voltage (Over all operating input voltage, resistive load, and temperature conditions until end of life)	All	$V_{O, set}$	-3.0	—	+3.0	% $V_{O, set}$
Adjustment Range Selected by an external resistor	All	$V_O$	0.6		3.63	Vdc
Output Regulation (for $V_O \geq 2.5$ Vdc)						
Line ( $V_{IN}=V_{IN, min}$ to $V_{IN, max}$ )	All			—	+0.4	% $V_{O, set}$
Load ( $I_O=I_{O, min}$ to $I_{O, max}$ )	All			—	10	mV
Output Regulation (for $V_O < 2.5$ Vdc)						
Line ( $V_{IN}=V_{IN, min}$ to $V_{IN, max}$ )	All			—	10	mV
Load ( $I_O=I_{O, min}$ to $I_{O, max}$ )	All			—	5	mV
Temperature ( $T_{ref}=T_{A, min}$ to $T_{A, max}$ )	All			—	0.4	% $V_{O, set}$
Remote Sense Range	All				0.5	V
Output Ripple and Noise on nominal output ( $V_{IN}=V_{IN, nom}$ and $I_O=I_{O, min}$ to $I_{O, max}$ $C_O = 0.1\mu F // 10\mu F$ ceramic capacitors)						
Peak-to-Peak (5Hz to 20MHz bandwidth)	All		—	20	35	mV <sub>pk-pk</sub>
RMS				15	25	mV <sub>rms</sub>
External Capacitance <sup>1</sup> Without the Tunable Loop™ ESR $\geq 1$ m $\Omega$	All	$C_{O, max}$	0	—	47	$\mu F$
With the Tunable Loop™ ESR $\geq 0.15$ m $\Omega$	All	$C_{O, max}$	0	—	1000	$\mu F$
ESR $\geq 10$ m $\Omega$	All	$C_{O, max}$	0	—	3000	$\mu F$
Output Current	All	$I_O$	0		3	A <sub>dc</sub>
Output Current Limit Inception (Hiccup Mode )	All	$I_{O, lim}$			200	% $I_{O, max}$
Output Short-Circuit Current ( $V_O \leq 250$ mV) ( Hiccup Mode )	All	$I_{O, s/c}$		0.12		A <sub>dc</sub>
Efficiency $V_{IN} = 3.3$ Vdc, $T_A = 25^\circ C$ $I_O = I_{O, max}$ , $V_O = V_{O, set}$	$V_{O, set} = 0.6$ Vdc	$\eta$		81.2		%
	$V_{O, set} = 1.2$ Vdc	$\eta$		89.4		%
	$V_{O, set} = 1.8$ Vdc	$\eta$		91.4		%
	$V_{O, set} = 2.5$ Vdc	$\eta$		93.9		%
$V_{IN} = 5$ Vdc	$V_{O, set} = 3.3$ Vdc	$\eta$		94.4		%
Switching Frequency	All	$f_{sw}$	—	600	—	kHz
Dynamic Load Response ( $dI_O/dt = 10$ A/ $\mu s$ ; $V_{IN} = 5$ V; $V_{out} = 1.5$ V, $T_A = 25^\circ C$ ) Load Change from $I_O = 0\%$ to $50\%$ of $I_{O, max}$ ; $C_O = 0$						
Peak Deviation	All	$V_{pk}$		90		mV
Settling Time ( $V_O < 10\%$ peak deviation)	All	$t_s$		20		$\mu s$
Load Change from $I_O = 50\%$ to $0\%$ of $I_{O, max}$ ; $C_O = 0$						
Peak Deviation	All	$V_{pk}$		100		mV
Settling Time ( $V_O < 10\%$ peak deviation)	All	$t_s$		20		$\mu s$

<sup>1</sup> External capacitors may require using the new Tunable Loop™ feature to ensure that the module is stable as well as getting the best transient response. See the Tunable Loop™ section for details.

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## General Specifications

Parameter	Min	Typ	Max	Unit
Calculated MTBF (I <sub>o</sub> =0.8I <sub>o,max</sub> , T <sub>A</sub> =40°C) Telcordia Issue 2 Method 1 Case 3		16,139,760		Hours
Weight	—	1.55 (0.0546)	—	g (oz.)

## Feature Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Typ	Max	Units
On/Off Signal Interface (V <sub>IN</sub> =V <sub>IN,min</sub> to V <sub>IN,max</sub> ; open collector or equivalent, Signal referenced to GND) Device is with suffix “4” – Positive Logic (See Ordering Information) Logic High (Module ON) Input High Current Input High Voltage Logic Low (Module OFF) Input Low Current Input Low Voltage	All	I <sub>IH</sub> V <sub>IH</sub> I <sub>IL</sub> V <sub>IL</sub>	— 1.2 — -0.3	— — — —	10 V <sub>IN,max</sub> 0.3 0.3	μA V mA V
Device Code with no suffix – Negative Logic (See Ordering Information) (On/OFF pin is open collector/drain logic input with external pull-up resistor; signal referenced to GND) Logic High (Module OFF) Input High Current Input High Voltage Logic Low (Module ON) Input low Current Input Low Voltage	All	I <sub>IH</sub> V <sub>IH</sub> I <sub>IL</sub> V <sub>IL</sub>	— V <sub>IN</sub> - 1.6 — -0.2	— — — —	1 V <sub>IN,max</sub> 0.2 V <sub>IN</sub> - 1.6	mA Vdc mA Vdc
Turn-On Delay and Rise Times (V <sub>IN</sub> =V <sub>IN,nom</sub> , I <sub>o</sub> =I <sub>o,max</sub> , V <sub>o</sub> to within ±1% of steady state) Case 1: On/Off input is enabled and then input power is applied (delay from instant at which V <sub>IN</sub> = V <sub>IN,min</sub> until V <sub>o</sub> = 10% of V <sub>o,set</sub> ) Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which V <sub>on/Off</sub> is enabled until V <sub>o</sub> = 10% of V <sub>o,set</sub> ) Output voltage Rise time (time for V <sub>o</sub> to rise from 10% of V <sub>o</sub> , set to 90% of V <sub>o</sub> , set)	All	T <sub>delay</sub> T <sub>delay</sub> T <sub>rise</sub>	— — —	2 2 5	— — —	msec msec msec
Output voltage overshoot (T <sub>A</sub> = 25°C) V <sub>IN</sub> = V <sub>IN,min</sub> to V <sub>IN,max</sub> , I <sub>o</sub> = I <sub>o,min</sub> to I <sub>o,max</sub> With or without maximum external capacitance					3.0	% V <sub>o,set</sub>
Over Temperature Protection (See Thermal Considerations section)	All	T <sub>ref</sub>		140		°C
Sequencing Delay time Delay from V <sub>IN,min</sub> to application of voltage on SEQ pin Tracking Accuracy (Power-Up: 2V/ms) (Power-Down: 2V/ms) (V <sub>IN,min</sub> to V <sub>IN,max</sub> ; I <sub>o,min</sub> to I <sub>o,max</sub> V <sub>SEQ</sub> < V <sub>o</sub> )	APTH	T <sub>SEQ-delay</sub> V <sub>SEQ</sub> - V <sub>o</sub> V <sub>SEQ</sub> - V <sub>o</sub>	10		100 100	msec mV mV