

Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Typ	Max	Unit
Output Voltage Set-point ( $V_{IN}=V_{IN, min}$ , $I_O=I_{O, max}$ , $T_A=25^\circ C$ )	All	$V_{O, set}$	-2.0	$V_{O, set}$	+2.0	% $V_{O, set}$
Output Voltage (Over all operating input voltage, resistive load, and temperature conditions until end of life)	All	$V_{O, set}$	-2.5%	—	+3.5%	% $V_{O, set}$
Adjustment Range Selected by an external resistor	All	$V_O$	0.7525		5.5	Vdc
Output Regulation Line ( $V_{IN}=V_{IN, min}$ to $V_{IN, max}$ )	All		—	0.3	—	% $V_{O, set}$
Load ( $I_O=I_{O, min}$ to $I_{O, max}$ )	All		—	0.4	—	% $V_{O, set}$
Temperature ( $T_{ref}=T_{A, min}$ to $T_{A, max}$ )	All		—	0.4	—	% $V_{O, set}$
Output Ripple and Noise on nominal output ( $V_{IN}=V_{IN, nom}$ and $I_O=I_{O, min}$ to $I_{O, max}$ Cout = 1 $\mu$ F ceramic//10 $\mu$ F tantalum capacitors)						
RMS (5Hz to 20MHz bandwidth)	$V_O \leq 3.63$		—	12	30	mV <sub>rms</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	$V_O \leq 3.63$		—	30	75	mV <sub>pk-pk</sub>
RMS (5Hz to 20MHz bandwidth)	$V_O = 5.0V$		—	25	40	mV <sub>rms</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	$V_O = 5.0V$		—	70	100	mV <sub>pk-pk</sub>
External Capacitance ESR $\geq 1$ m $\Omega$	All	$C_{O, max}$	—	—	1000	$\mu$ F
ESR $\geq 10$ m $\Omega$	All	$C_{O, max}$	—	—	5000	$\mu$ F
Output Current	All	$I_O$	0		16	Adc
Output Current Limit Inception (Hiccup Mode ) ( $V_O = 90\%$ of $V_{O, set}$ )	All	$I_{O, lim}$	—	180	—	% $I_O$
Output Short-Circuit Current ( $V_O \leq 250mV$ ) ( Hiccup Mode )	All	$I_{O, s/c}$	—	3	—	Adc
Efficiency $V_{IN} = V_{IN, nom}$ , $T_A = 25^\circ C$ $I_O = I_{O, max}$ , $V_O = V_{O, set}$	$V_{O, set} = 0.75Vdc$	$\eta$		79.0		%
	$V_{O, set} = 1.2Vdc$	$\eta$		85.0		%
	$V_{O, set} = 1.5Vdc$	$\eta$		87.0		%
	$V_{O, set} = 1.8Vdc$	$\eta$		88.0		%
	$V_{O, set} = 2.5Vdc$	$\eta$		90.5		%
	$V_{O, set} = 3.3Vdc$	$\eta$		92.0		%
	$V_{O, set} = 5.0Vdc$	$\eta$		94.0		%
Switching Frequency	All	$f_{sw}$	—	300	—	kHz
Dynamic Load Response ( $dI_O/dt=2.5A/\mu s$ ; $V_{IN} = V_{IN, nom}$ ; $T_A=25^\circ C$ ) Load Change from $I_O = 50\%$ to $100\%$ of $I_{O, max}$ ; 1 $\mu$ F ceramic// 10 $\mu$ F tantalum Peak Deviation	All	$V_{pk}$	—	200	—	mV
Settling Time ( $V_O < 10\%$ peak deviation)	All	$t_s$	—	25	—	$\mu s$
( $dI_O/dt=2.5A/\mu s$ ; $V_{IN} = V_{IN, nom}$ ; $T_A=25^\circ C$ ) Load Change from $I_O = 100\%$ to $50\%$ of $I_{O, max}$ : 1 $\mu$ F ceramic// 10 $\mu$ F tantalum Peak Deviation	All	$V_{pk}$	—	200	—	mV
Settling Time ( $V_O < 10\%$ peak deviation)	All	$t_s$	—	25	—	$\mu s$

### Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Typ	Max	Unit
Dynamic Load Response ( $dI_o/dt=2.5A/\mu s$ ; $V_{IN} = V_{IN, nom}$ ; $T_A=25^\circ C$ ) Load Change from $I_o= 50\%$ to $100\%$ of $I_{o,max}$ ; $C_o = 2 \times 150 \mu F$ polymer capacitors Peak Deviation	All	$V_{pk}$	—	100	—	mV
Settling Time ( $V_o < 10\%$ peak deviation)	All	$t_s$	—	50	—	$\mu s$
( $dI_o/dt=2.5A/\mu s$ ; $V_{IN} = V_{IN, nom}$ ; $T_A=25^\circ C$ ) Load Change from $I_o= 100\%$ to $50\%$ of $I_{o,max}$ ; $C_o = 2 \times 150 \mu F$ polymer capacitors Peak Deviation	All	$V_{pk}$	—	100	—	mV
Settling Time ( $V_o < 10\%$ peak deviation)	All	$t_s$	—	50	—	$\mu s$

### General Specifications

Parameter	Min	Typ	Max	Unit
Calculated MTBF ( $I_o=I_{o, max}$ , $T_A=25^\circ C$ ) Telecordia SR-332 Issue 1: Method 1 Case 3		9,230,550		Hours
Weight	—	5.6 (0.2)	—	g (oz.)