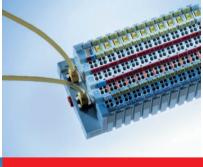
BECKHOFF New Automation Technology

Product Overview 2007



1/0



Motion







Beckhoff Product Overview 2007 | The product overview is a condensed summary of the components and system solutions for Industrial PCs, Fieldbus Components, Drive Technology and automation software. The main "New Automation Technology" catalog and the web pages at **www.beckhoff.com** contain detailed descriptions, technical data and information about accessories.

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Beckhoff New Automation Technology

Beckhoff implements open automation systems based on PC Control technology. The product range covers Industrial PCs, I/O and Fieldbus Components, Drive Technology and automation software. Products that can be used as separate components or integrated into a complete and seamless control system are available for all industries. The Beckhoff "New Automation Technology" philosophy stands for universal and open control and automation solutions that are used worldwide in a wide variety of different applications, ranging from CNC-controlled machine tools to intelligent building automation.

Innovative products and a full range of services

Since the foundation of the company in 1980, continuous development of innovative products and solutions using PC-based control technology has been the basis for the continued success of Beckhoff. Many automation technology standards that are taken for granted today were conceptualised by Beckhoff at an early stage and successfully introduced to the market:

- 1982: P1000 single-board motion controller
- 1986: PC Control first PC-based machine controller
- 1989: Lightbus high-speed fieldbus utilising optical fibre
- 1990: All-in-one PC motherboard
- 1995: Bus Terminal fieldbus technology in terminal block format
- 1996: TwinCAT real-time software package under Windows with PLC and Motion Control functions
- 1998: Control Panel remote IPC Control Panels
- 2002: CX1000 modular Embedded PCs for DIN rail mounting
- 2003: EtherCAT real-time Ethernet fieldbus system
- 2005: TwinSAFE safety solution for the Bus Terminal system
- 2005: AX5000 EtherCAT Servo Drive

The Beckhoff PC Control philosophy and the invention of the Lightbus system, the Bus Terminals and TwinCAT automation software represent milestones in automation technology and have become accepted as high-performance alternatives to traditional control technology. EtherCAT, the real-time Ethernet solution, makes forward-looking, high-performance technology available for a new generation of leading edge control concepts.

World-wide presence on all continents

The central divisions of Beckhoff, such as development, production, administration, distribution, marketing, support and service are located at the Beckhoff Automation GmbH headquarters in Verl, Germany. Rapidly growing presence in the international market is taking place through subsidiaries in Austria, Belgium, Denmark, Finland, France, Italy, Lithuania, Poland, Russia, Spain, Sweden, Switzerland, as well as Australia, Brazil, China, Canada, South Africa and the USA. Through worldwide co-operation with partners, Beckhoff is represented in more than 60 countries.

Automation

Beckhoff | The Automation Company

Beckhoff offers comprehensive system solutions in different performance classes for all areas of automation. Beckhoff control technology is scalable – from high-performance Industrial PCs to mini PLCs – and can be adapted precisely to the respective application. TwinCAT automation software integrates real-time control with PLC, NC and CNC functions in a single package. All Beckhoff controllers are programmed using TwinCAT in accordance with the globally-recognised IEC 61131-3 programming standard.

O D

Beckhoff | The IPC Company

Beckhoff supplies the right Industrial PC for every application. High-quality components based on open standards and the rugged construction of the device housings mean that the Industrial PCs are ideally equipped for all control requirements. Embedded PCs make modular IPC technology available in miniature format for DIN rail mounting. In addition to their application in automation, Beckhoff Industrial PCs are also ideally suited to other kinds of tasks — wherever reliable and robust PC technology is required.

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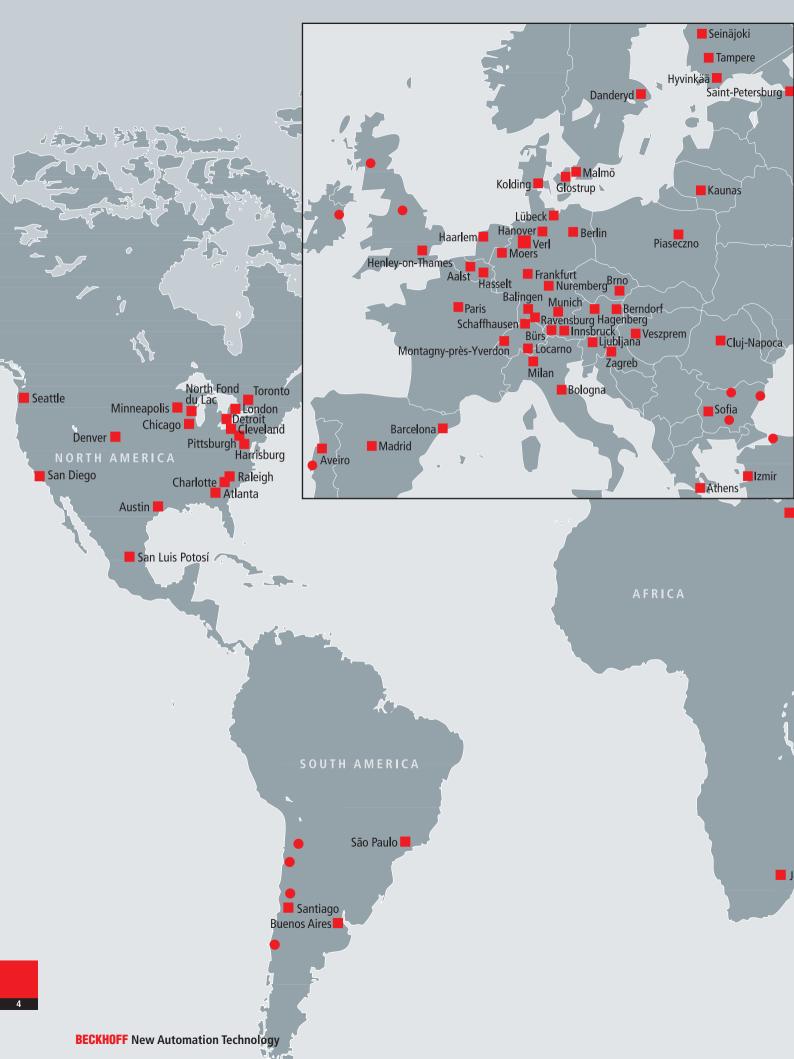
Beckhoff | The I/O Company

Beckhoff has the right technology for every signal and every fieldbus. Beckhoff supplies a complete range of Fieldbus Components for all common I/Os and fieldbus systems. With the Bus Terminals in protection class IP 20, and the Fieldbus Box modules in IP 67, a complete range is available for all important signal types and fieldbus systems. In addition to classic fieldbus systems, high-performance EtherCAT technology opens up great, new potential for control technology.

Motion

Beckhoff | The Motion Company

In combination with the Motion Control solutions offered by the TwinCAT automation software, Beckhoff Drive Technology represents an advanced and complete drive system. PC-based control technology from Beckhoff is ideally suited for single and multiple axis positioning tasks with highly dynamic requirements. The AX5000 Servo Drive series with high-performance EtherCAT system communication offers maximum performance and dynamics.

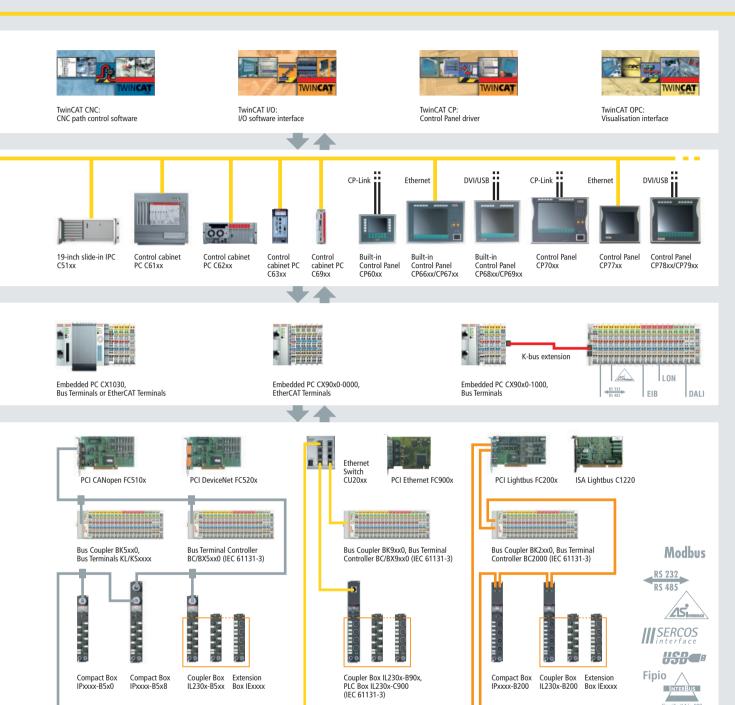


BECKHOFF WORLDWIDE



Beckhoff System Overview





Ethernet TCP/IP



CANopen

DeviceNet²

DALI EIB

LON

Control Net.

CC-Link

Lightbus module

LIGHTBUS

Mxxxx

INDUSTRIAL PC

PC Control for all applications



Robust industrial design PCs with highest performance components

Beckhoff Industrial PCs satisfy industry's demands:

- the right Industrial PC for every controller
- highest performance PCs with Intel® Pentium® 4,
 Intel® Pentium® M and Core™ Duo processors
- open standards following the ATX norm
- components carefully tested to ensure appropriateness for industrial applications
- appealing industrial design housings
- easy access to PC components
- Individual housing construction allows optimum adaptation to controller requirements.
- integration of electromechanical buttons, switches, scanner, handwheel and other components in the Control Panel







The personal computer has experienced an unprecedented success story and has become a firmly established part of everyday life, including industrial environments. Together with associated software, PCs in different shapes and forms are at the core of a wide range of diverse automation tasks such as control of machines, processes or logistics systems, networking of system components, data acquisition, or image processing. For classic control tasks, PC-based control technology offers excellent scalability and flexibility and is therefore increasingly being used in place of hardware PLCs.

Beckhoff is one of the pioneers of PC-based automation: The first PC control system was delivered as early as 1986. Beckhoff Industrial PCs are characterised by a wealth of technology know-how accumulated over recent years. In combination with the TwinCAT automation software, they offer a high-performance control system for PLC, NC and CNC functionalities.

An important feature of the Beckhoff product philosophy is the use of advanced,

high-performance components and processors for the development and design of Industrial PCs: They integrate the latest developments offered by the technology market and are used successfully worldwide.

In addition to long-standing experience, another factor driving the development of our comprehensive IPC product portfolio is customer-orientation. Six IPC series with a wide range of basic PC types form the basis of our product range. For any type of application, a suitable control computer can be configured from a large number of devices and options.

The PC housing is made from stainless steel and varies in size between paper-back format to 14-slot passive backplane, depending on the device type.

Elegant Control Panels

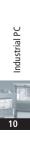
The IPC is complemented by an industrial display unit. The Beckhoff Control Panels are the visual front end for machines or plants. Spatial separation of display/control unit and control computer offers maximum

flexibility. Appealing design, robustness and suitability for industrial applications were important criteria in the development of the Control Panel series, which comes with display sizes between 6.5" and 19".

Careful selection of components

All IPC components are carefully selected to ensure compatibility, long-term availability, mechanical load-bearing capacity, and suitability for industrial applications. The development of Beckhoff all-in-one IPC motherboards, interface cards, low voltage supply units, keyboard and UPS controllers and other electronic modules is based on the stringent requirements for Industrial PC components, in order to ensure safe operation now and in future. International standards and experience in the application of PC systems under difficult industrial conditions provide the basis for Beckhoff system integration.







CP6xxx | Built-in Panel PC









	CP62xx	CP63xx	CP64xx	CP65xx	
Display	12-, 15- or	10-, 12-, 15- or	10-, 12-, 15- or	10-, 12-, 15- or	
	19-inch TFT display	19-inch LC display	19-inch LC display	19-inch LC display	
Processor	Intel® Celeron® M	Intel® Celeron® M	Intel® Celeron® M	Intel® Celeron®, Pentium® 4,	
	or Pentium® M	or Pentium® M	or Pentium® M	Celeron® M, Pentium® M or	
				Core™ Duo, Core™2 Duo*	
Motherboard	3 ¹ / ₂ -inch	passive backplane	passive backplane	ATX	
Slots	1	3	4	7	
Free slots	1 Mini PCI	1 PCI	2 PCI	6 PCI	
Memory	256 MB 2 GB DDR RAM	256 MB 2 GB DDR RAM	256 MB 2 GB DDR RAM	256 MB 2 GB DDR RAM	
Graphic adapter	on-board	on-board	on-board	on-board	
Ethernet	2 on-board	2 on-board	2 on-board	on-board	
Max. card length	Mini PCI	1 x 190 mm	2 x 190 mm	7 x 190 mm	
Hard disks	2 ¹ / ₂ -inch and/or	1 x 2 ¹ / ₂ -inch	1 x 2 ¹ / ₂ -inch	1 x 3 ¹ / ₂ -inch	
	CF card or 2 CF cards				
Possible		CD/DVD-ROM or	CD/DVD-ROM or	CD/DVD-ROM or	
disk drives		multi DVD 4.7 GB	multi DVD 4.7 GB	or multi DVD 4.7 GB	
Power supply	24 V DC	24 V DC	100 240 V AC or 24 V DC	100 240 V AC or 24 V DC	
Dimen. (W x H x D)	depending on built-in Control Pa	anel (see main catalog)			

^{*} The PCs with Core™ Duo or Core™2 Duo processors have 3 free PCI and 3 free PCIe slots as well as 512 MB ... 2 GB DDR RAM memory capacity.



CP7xxx | Panel PC





	CP71xx	CP72xx
	GI 7 IAG	G. 7 2.50
Display	10-, 12-, 15- or 19-inch LC display	12-, 15- or 19-inch TFT display
Processor	Intel® Celeron® M or	Intel® Celeron® M or
	Pentium® M	Pentium® M
Motherboard	passive backplane	3 ¹ / ₂ -inch
Slots	4	1 Mini PCI
Free slots	1 PCI	1 Mini PCI
Memory	256 MB 2 GB DDR RAM	256 MB 2 GB DDR RAM
Graphic adapter	on-board	on-board
Ethernet	2 on-board	2 on-board
Max. card length	1 x 190 mm	
Hard disks	1 x 2 ¹ / ₂ -inch	1–2 x 2 ¹ / ₂ -inch or
		1 x CF card and 1 x 2 ¹ / ₂ -inch
Possible	CD/DVD-ROM	
disk drives	or multi DVD 4.7 GB	
Power supply	24 V DC	24 V DC
Dimen. (W x H x D)	depending on Control Panel (see main catalog/news catalog)	



C33xx | 19-inch Panel PC



	C3320	C3330	C3340	C3350
Display	12-inch TFT display,	12-inch TFT display,	15-inch TFT display,	15-inch TFT display,
	resolution 800 x 600	resolution 800 x 600	resolution 1024 x 768	resolution 1024 x 768
Processor	Intel® Celeron®, Pentium® 4,			
	Celeron® M, Pentium® M or			
	Core™ Duo, Core™2 Duo*			
Motherboard	ATX	ATX	ATX	ATX
Slots	7	7	7	7
Free slots	6 PCI	6 PCI	6 PCI	6 PCI
Memory	256 MB 2 GB DDR RAM			
Graphic adapter	on-board	on-board	on-board	on-board
Ethernet	on-board	on-board	on-board	on-board
Max. card length	3 x fullsize, 4 x 240 mm			
Hard disks	1 or 2 x 3 ¹ / ₂ -inch	1 or 2 x 3 ¹ / ₂ -inch	1 or 2 x 3 ¹ / ₂ -inch	1 or 2 x 3 ¹ / ₂ -inch
Possible	CD/DVD-ROM,	CD/DVD-ROM,	CD/DVD-ROM,	CD/DVD-ROM,
disk drives	multi DVD 4.7 GB			
Power supply	100 240 V AC or 24 V DC	100 240 V AC or 24 V DC	100 240 V AC or 24 V DC	100 240 V AC or 24 V DC
Dimen. (W x H x D)	482.7 x 355 x 282 mm	482.7 x 400 x 282 mm	482.7 x 355 x 282 mm	482.7 x 444 x 282 mm

^{*} The PCs with Core™ Duo or Core™2 Duo processors have 3 free PCI and 3 free PCIe slots as well as 512 MB ... 2 GB DDR RAM memory capacity.





C36xx | Panel PC





	C3620	C3640
Display	12-inch TFT display,	15-inch TFT display,
	resolution 800 x 600	resolution 1024 x 768
Processor	Intel® Celeron®, Pentium® 4,	Intel® Celeron®, Pentium® 4,
	Celeron® M, Pentium® M or	Celeron® M, Pentium® M or
	Core™ Duo, Core™2 Duo*	Core™ Duo, Core™2 Duo*
Motherboard	ATX	ATX
Slots	7	7
Free slots	6 PCI	6 PCI
Memory	256 MB 2 GB DDR RAM	256 MB 2 GB DDR RAM
Graphic adapter	on-board	on-board
Ethernet	on-board	on-board
Max. card length	7 x 220 mm	7 x 235 mm
Hard disks	1 x 3 ¹ / ₂ -inch	1 x 3 ¹ / ₂ -inch
Possible	CD/DVD-ROM,	slimline CD/DVD-ROM,
disk drives	multi DVD 4.7 GB drive	multi DVD 4.7 GB drive
Power supply	100 240 V AC or 24 V DC	100 240 V AC or 24 V DC
Dimen. (W x H x D)	388 x 324 x 201 mm	470 x 348 x 199 mm

^{*} The PCs with Core™ Duo or Core™2 Duo processors have 3 free PCI and 3 free PCIe slots as well as 512 MB ... 2 GB DDR RAM memory capacity.





C51xx | 19-inch slide-in Industrial PC

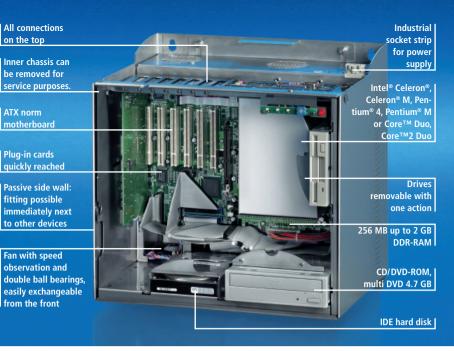




	C5101	C5102
Processor	Intel® Celeron® M or Pentium® M	Intel® Celeron®, Pentium® 4,
		Celeron® M, Pentium® M or
		Core™ Duo, Core™2 Duo*
Motherboard	passive backplane	ATX
Slots	14	7
Free slots	11 PCI	6 PCI
Memory	256 MB 2 GB DDR RAM	256 MB 2 GB DDR RAM
Graphic adapter	on-board	on-board
Ethernet	2 on-board	on-board
Max. card length	8 x fullsize, 6 x 190 mm	7 x fullsize
Hard disks	1, 2 or 3 x 3 ¹ / ₂ -inch	1, 2 or 3 x 3 ¹ / ₂ -inch
Possible	CD/DVD-ROM,	CD/DVD-ROM,
disk drives	multi DVD 4.7 GB	multi DVD 4.7 GB
Power supply	100 240 V AC or 24 V DC	100 240 V AC or 24 V DC
Dimen. (W x H x D)	483 x 177 x 500 mm	483 x 177 x 500 mm

^{*} The PCs with Core™ Duo or Core™2 Duo processors have 3 free PCI and 3 free PCIe slots as well as 512 MB ... 2 GB DDR RAM memory capacity.





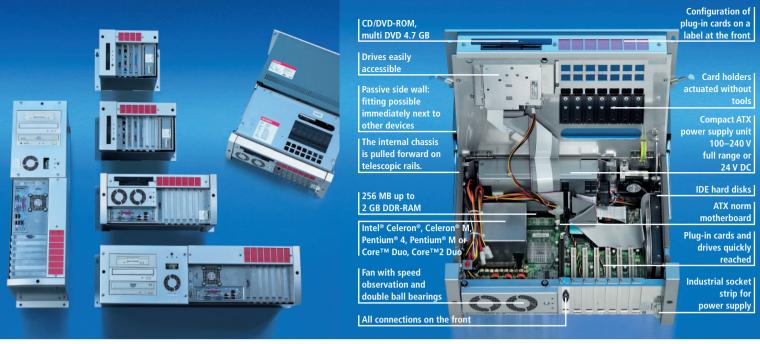
C61xx | Control cabinet Industrial PC



	C6110	C6120	C6130	C6140	C6150
Processor	Intel® Celeron® M	Intel® Celeron® M	Intel® Celeron® M	Intel® Celeron®, Pen-	Intel® Celeron®, Pen-
	or Pentium® M	or Pentium® M	or Pentium® M	tium® 4, Celeron® M,	tium® 4, Celeron® M,
				Pentium [®] M or Core [™]	Pentium® M or Core™
				Duo, Core™2 Duo*	Duo, Core™2 Duo*
Motherboard	passive backplane	passive backplane	passive backplane	ATX	ATX
Slots	4	5	8	7	7
Free slots	1 PCI	2 PCI	6 PCI	6 PCI	6 PCI
Memory	256 MB 2 GB	256 MB 2 GB	256 MB 2 GB	256 MB 2 GB	256 MB 2 GB
	DDR RAM	DDR RAM	DDR RAM	DDR RAM	DDR RAM
Graphic adapter	on-board	on-board	on-board	on-board	on-board
Ethernet	2 on-board	2 on-board	2 on-board	on-board	on-board
Max. card length	4 x 190 mm	5 x fullsize	4 x fullsize, 4 x 25 cm	3 x 270 mm and	7 x fullsize
				4 x 240 mm	
Hard disks	1 x 2 ¹ / ₂ -inch	1 x 3 ¹ / ₂ -inch	1-3 x 3 ¹ / ₂ -inch	1-3 x 3 ¹ / ₂ -inch	1-3 x 3 ¹ / ₂ -inch
Possible		CD/DVD-ROM,	CD/DVD-ROM,	CD/DVD-ROM,	CD/DVD-ROM,
disk drives		multi DVD 4.7 GB	multi DVD 4.7 GB	multi DVD 4.7 GB	multi DVD 4.7 GB
Power supply	100 240 V AC	100 240 V AC	100 240 V AC	100 240 V AC	100 240 V AC
	or 24 V DC	or 24 V DC	or 24 V DC	or 24 V DC	or 24 V DC
Dimen. (W x H x D)	180 x 287 x 250 mm	195 x 423 x 250 mm	295 x 423 x 250 mm	383 x 362 x 265 mm	383 x 423 x 265 mm

^{*} The PCs with Core™ Duo or Core™2 Duo processors have 3 free PCI and 3 free PCIe slots as well as 512 MB ... 2 GB DDR RAM memory capacity.





C62xx | Control cabinet Industrial PC



	C6210	C6220 C6240		C6250
Processor	Intel® Celeron® M	Intel® Celeron® M	Intel® Celeron®, Pentium® 4,	Intel® Celeron®, Pentium® 4,
	or Pentium® M	or Pentium® M	Celeron® M, Pentium® M or	Celeron® M, Pentium® M or
			Core™ Duo, Core™2 Duo*	Core™ Duo, Core™2 Duo*
Motherboard	passive backplane	passive backplane	ATX	ATX
Slots	4	6	7	7
Free slots	1 PCI	3 PCI	6 PCI	6 PCI
Memory	256 MB 2 GB	256 MB 2 GB	256 MB 2 GB	256 MB 2 GB
	DDR RAM	DDR RAM	DDR RAM	DDR RAM
Graphic adapter	on-board	on-board	on-board	on-board
Ethernet	2 on-board	2 on-board	on-board	on-board
Max. card length	4 x 190 mm	6 x 190 mm	7 x 190 mm	7 x 190 mm
Hard disks	1 x 2 ¹ / ₂ -inch	1 x 2 ¹ / ₂ -inch	1 x 3 ¹ / ₂ -inch or 2 x 2 ¹ / ₂ -inch	1, 2 or 3 x 3 ¹ / ₂ -inch
Possible	CD/DVD-ROM,	CD/DVD-ROM,	CD/DVD-ROM,	CD/DVD-ROM
disk drives	multi DVD 4.7 GB	multi DVD 4.7 GB	multi DVD 4.7 GB	and multi DVD 4.7 GB
Power supply	100 240 V AC or 24 V DC	100 240 V AC or 24 V DC	100 240 V AC or 24 V DC	100 240 V AC or 24 V DC
Dimen. (W x H x D)	257 x 170 x 286 mm	307 x 170 x 286 mm	430 x 170 x 274 mm	680 x 184 x 270 mm

^{*} The PCs with Core™ Duo or Core™2 Duo processors have 3 free PCI and 3 free PCIe slots as well as 512 MB ... 2 GB DDR RAM memory capacity.



C63xx | Control cabinet Industrial PC



	C6320	C6325	C6330	C6335	C6340	C6350
Processor	Intel® Celeron® M					
	or Pentium® M					
Motherboard	passive backplane					
Slots	3	3	3	3	5	5
Free slots	1 PCI	1 PCI	1 PCI	1 PCI	3 PCI	3 PCI
Memory	256 MB 2 GB					
	DDR RAM					
Graphic adapter	on-board	on-board	on-board	on-board	on-board	on-board
Ethernet	2 on-board					
Max. card length	1 x 190 mm	3 x 190 mm	3 x 190 mm			
Hard disks	1 x 2 ¹ / ₂ -inch					
Possible			CD/DVD-ROM or	CD/DVD-ROM or		CD/DVD-ROM or
disk drives			multi DVD 4.7 GB	multi DVD 4.7 GB		multi DVD 4.7 GB
Power supply	24 V DC					
Dimen. (W x H x D)	93 x 196 x 226 mm	133 x 196 x 226 mm	107 x 196 x 226 mm	147 x 196 x 226 mm	134 x 196 x 226 mm	148 x 196 x 226 mm





C69xx | Control cabinet Industrial PC





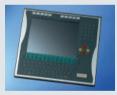
	C6920	C6925
Processor	Intel® Celeron® M 1.5 GHz or Intel® Pentium® M 1.8 GHz	Intel® Celeron® M ULV 1 GHz
Motherboard	3 ¹ / ₂ -inch motherboard	31/2-inch motherboard
Free slots	1 Mini PCI	1 Mini PCI
Memory	256 MB 2 GB DDR RAM	256 MB 2 GB DDR RAM
Graphic system	on-board	on-board
Ethernet	2 on-board	2 on-board
Hard disks	2 ¹ / ₂ -inch and/or CF card	2 ¹ / ₂ -inch and/or CF card
	or 2 CF cards	or 2 CF cards
Power supply	24 V DC	24 V DC
Dimen. (W x H x D)	65 x 231 x 116 mm	65 x 208 x 116 mm



BECKHOFF

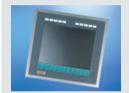


CP60xx | Built-in Control Panel, distance Panel/PC = 100 m



CP70xx | Control Panel, distance Panel/PC = 100 m

Ethernet



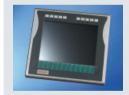
CP67xx | Built-in Control Panel, Embedded PC (Pentium®-MMXcompatible CPU, 300 MHz)



DVI/USB panel

Standard DVI technologies are used for image transfer and USB for touch screen, keyboard, push-button extensions, etc.; USB is only required for equipment with input devices such as touch screen or keyboard.

CP66xx | "Economy" built-in Control Panel, Embedded PC (ARM CPU, 266 MHz)



CP77xx | Control Panel, Embedded PC (Pentium®-MMXcompatible CPU, 300 MHz)

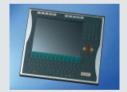
DVI/USB



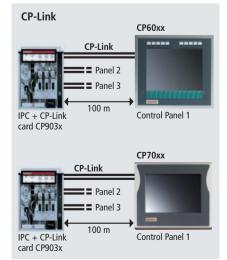
CP68xx | Built-in Control Panel, distance Panel/PC = 5 m (50 m with extension)

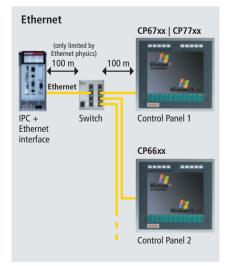


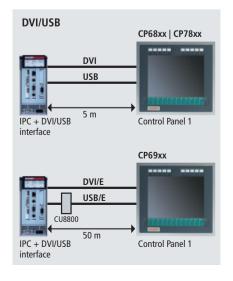
CP69xx | "Economy" built-in Control Panel, distance Panel/PC = 50 m



CP78xx | Control Panel, distance Panel/PC = 5 m (50 m with extension)











	Display	6.5-inch	10-inch	12-inch	15-inch	19-inch
	Resolution	640 x 480	640 x 480	800 x 600	1024 x 768	1280 x 1024
CP-Link interface	without keys	CP6009	CP6000	CP6001	CP6002	
	function keys	CP6019	CP6010	CP6011	CP6012	
	numeric	CP6029	CP6020	CP6021	CP6022	
	alphanumeric		CP6030	CP6031	CP6032	
Ethernet interface	without keys	CP6609		CP6601	CP6602	CP6603
(Embedded PC)	function keys	CP6619		CP6611	CP6612	CP6613
– Intel® IXP420	numeric	CP6629		CP6621	CP6622	CP6623
CPU, 266 MHz	alphanumeric			CP6631	CP6632	CP6633
– Pentium®-MMX-	without keys	CP6709	CP6700	CP6701	CP6702	
compatible CPU,	function keys	CP6719	CP6710	CP6711	CP6712	
300 MHz	numeric	CP6729	CP6720	CP6721	CP6722	
	alphanumeric		CP6730	CP6731	CP6732	
DVI/USB interface	without keys	CP6809	CP6800	CP6801	CP6802	CP6803
	function keys	CP6819	CP6810	CP6811	CP6812	CP6813
	numeric	CP6829	CP6820	CP6821	CP6822	CP6823
	alphanumeric		CP6830	CP6831	CP6832	CP6833
					CP6842	
DVI/USB Extended	without keys	CP6909		CP6901	CP6902	CP6903
nterface	function keys	CP6919		CP6911	CP6912	CP6913
	numeric	CP6929		CP6921	CP6922	CP6923
	alphanumeric			CP6931	CP6932	CP6933
					CP6942	



CP7xxx | Control Panel

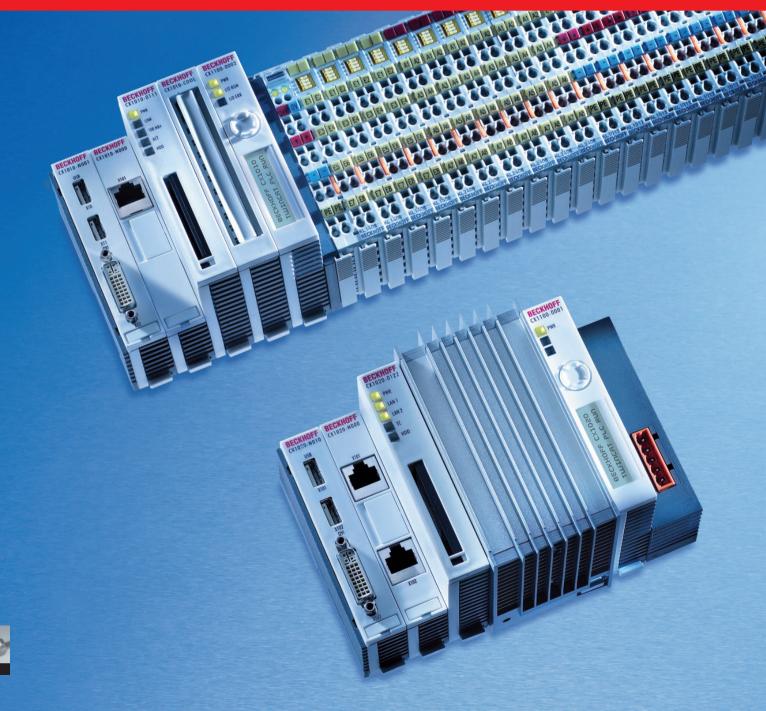


	Display	6.5-inch	10-inch	12-inch	15-inch	19-inch
	Resolution	640 x 480	640 x 480	800 x 600	1024 x 768	1280 x 1024
CP-Link interface	without keys	CP7009	CP7000	CP7001	CP7002	
	function keys	CP7019	CP7010	CP7011	CP7012	
	numeric	CP7029	CP7020	CP7021	CP7022	
	alphanumeric		CP7030	CP7031	CP7032	
				CP7037		
Ethernet interface	without keys	CP7709	CP7700	CP7701	CP7702	
(Embedded PC)	function keys	CP7719	CP7710	CP7711	CP7712	
– Pentium®-MMX-	numeric	CP7729	CP7720	CP7721	CP7722	
compatible CPU,	alphanumeric		CP7730	CP7731	CP7732	
300 MHz						
DVI/USB interface	without keys	CP7809	CP7800	CP7801	CP7802	CP7803
	function keys	CP7819	CP7810	CP7811	CP7812	CP7813
	numeric	CP7829	CP7820	CP7821	CP7822	CP7823
	alphanumeric		CP7830	CP7831	CP7832	CP7833
				CP7837	CP7842	
DVI/USB extended	without keys	CP7909		CP7901	CP7902	CP7903
interface	function keys	CP7919		CP7911	CP7912	CP7913
	numeric	CP7929		CP7921	CP7922	CP7923
	alphanumeric			CP7931	CP7932	CP7933
					CP7942	



EMBEDDED PC

The modular Industrial PC for mid-range control



CX series: modular DIN rail Industrial PCs

With the CX series of Embedded PCs, Beckhoff has combined PC technology and modular I/O level to form a DIN rail unit in the control cabinet. The CX device series combines the worlds of Industrial PC and hardware PLC and is suitable for medium-performance control tasks. The modular control system can be configured to match the task in hand and can be installed in the control cabinet or the terminal box.

The CX system covers the whole range of Beckhoff control technology both in terms of price and performance: This product range is designed for tasks requiring the characteristics and computing capacity of Industrial PCs, but whose budget does not stretch to full-blown Industrial PCs. The system only uses the components that are actually required. For example, a CX can be operated in "headless" mode, i.e. without display or keyboard; in this case, the associated interface is not required.

Scalable performance classes

The CX family includes several basic CPU modules with different processors for optimum adaptation to the respective control task:

CX1030: high-performance CX with Intel® Pentium® M CPU, 1.8 GHz processor CX1020: high-performance CX with Intel® Celeron® M ULV CPU, 1 GHz processor CX1010: basic CX with Pentium® MMX-compatible CPU, 500 MHz processor CX9010: Ethernet controller with Intel® IXP420 XScale® technology, 533 MHz processor

CX9000: Ethernet controller with Intel® IXP420 XScale® technology, 266 MHz processor

Apart from various CPUs, the individual CX types also have different system interfaces and power supply units. Via associated I/O interfaces the CX1030, CX1020, CX1010, CX9000 and CX9010 Embedded PCs support Beckhoff Bus Terminals and also EtherCAT Terminals as I/O system.

The components

The modules of the CX series system are connected with each other via the standardised PC/104 bus (16-bit). The individual system components come as modules with single (19 mm) or double width (38 mm)

that can be connected in series. The basic unit for the CX1030, CX1020 and CX1010 series consists of a CPU module and a power supply module. The CX9000 and CX9010 devices integrate CPU and power supply in a single unit. Depending on the CX type, the controllers can be expanded through further system interfaces. The range of optional modules is complemented by fieldbus connections for PROFIBUS, CANopen, DeviceNet, SERCOS interface and Lightbus, both as master or slave versions.

The software

In combination with the TwinCAT automation software, the CX Embedded PC becomes a powerful IEC 61131-3 PLC that can also handle Motion Control tasks. Depending on the required cycle time, it may be used to control several servo axes. With the CX1030, CX1020 or CX1010 even special functions such as "flying saw", "electronic gearbox" or "cam plate" can be realised. The CX thus becomes a controller that covers PLC, Motion Control and visualisation tasks with a single hardware. Under Windows CE, thanks to the real-time capability of the operating system, user tasks written in high-level languages can be processed in real-time in parallel with TwinCAT.

Wide range of applications

Due to the design and the features of an industrial PC Control, the Embedded PCs can be used in a wide range of applications. Existing applications include mechanical engineering (automatic sawing machines, automatic assembly machines, paper cutting machines, screwdriver control, packing machines, sheet metal processing, handling equipment), process technology (water treatment, power generation, consumption logging), building services (room control, access control) and many more.





CX1100-0910



CX1100-0920



Fieldbus interfaces

Masters CX1500-Mxxx



-M750 -M520 -M510 -M310 -M200



Slaves CX1500-Bxxx



PC interfaces



CPU



CX1010-N0xx

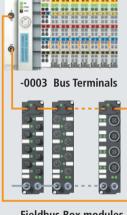


Power supply

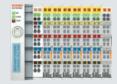
CX1100-000x



-0004 EtherCAT **Terminals**



Fieldbus Box modules



-0002 Bus Terminals



-0001

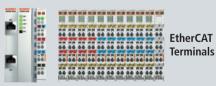
PC interfaces

CX9000-xxxx/CX9010-xxxx



CPU + power supply + I/O interface

CX9000-0x0x/CX9010-0x0x



CX9000-1x0x/CX9010-1x0x



Bus Terminals

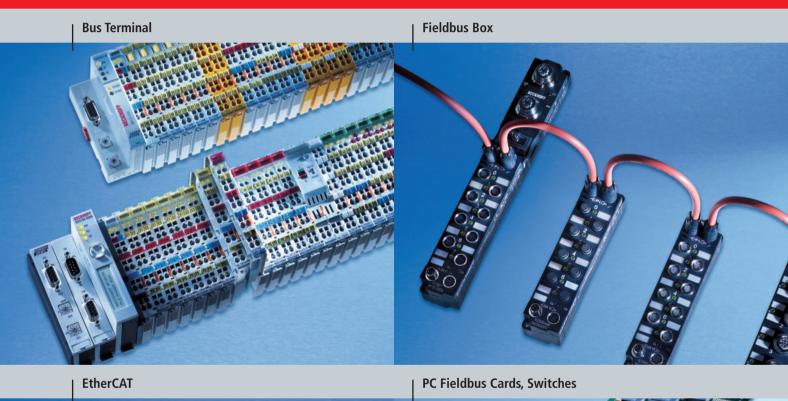
PRODUCT OVERVIEW EMBEDDED PC

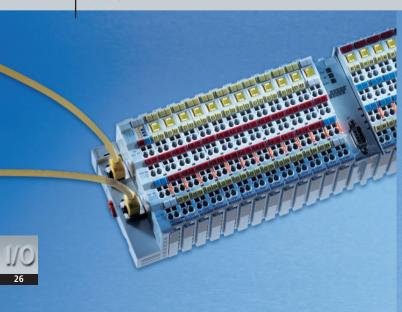
Embedded PC							
Basic CPU	CX90x0-xx0x	CX1010-0xxx	CX1020-0xxx	CX1030-0xxx	Fieldbus i	nterfaces	
Processor	Intel® IXP420 with	compatible with	Intel® Celeron® M	Intel® Pentium® M,	Lightbus	CX1500-M200 master	
	XScale® technology,	Pentium® MMX, clock	ULV, 1 GHz clock	1.8 GHz clock		CX1500-B200 slave	
	clock frequ. 533 MHz	frequency 500 MHz	frequency	frequency			
Flash memory	32 MB Flash (inter-	64 MB Compact	64 MB Compact	64 MB Compact	PROFIBUS	CX1500-M310 master	
	nal, not expandable)	Flash card	Flash card	Flash card		CX1500-B310 slave	
Internal	128 MB RAM	256 MB RAM	256 MB DDR RAM	256 MB DDR RAM			
main memory	(internal, not	(not expandable)	(expandable to	(expandable to	CANopen	CX1500-M510 master	
	expandable)	512 MB, 1 GB)	512 MB, 1 GB)	512 MB, 1 GB)		CX1500-B510 slave	
Interfaces	2 x RJ 45 (Ethernet,	1 x RJ 45 (Ethernet),	2 x RJ 45 (Ethernet,	2 x RJ 45 (Ethernet,			
	internal switch),	10/100 Mbit/s	internal switch),	internal switch),	DeviceNet	CX1500-M520 master	
	10/100 Mbit/s		10/100 Mbit/s	10/100 Mbit/s		CX1500-B520 slave	
Operating	Microsoft Windows	Microsoft Windows	Microsoft Windows	Microsoft Windows			
system	CE	CE or Windows XP	CE or Windows XP	CE or Windows XP	SERCOS	CX1500-M750 master	
		Embedded	Embedded	Embedded	interface		
Control	TwinCAT CE PLC	TwinCAT PLC	TwinCAT PLC run-	TwinCAT PLC run-			
software	run-time or CE NC	run-time or	time, NC PTP run-	time, NC PTP run-			
	PTP run-time	NC PTP run-time	time, NC I run-time	time, NC I run-time	UPS		
Power supply	24 V DC	via system bus	via system bus	via system bus	013		
	(-15 %/+20 %)	(through CX1100	(through CX1100	(through CX1100	24 V DC	CX1100-0900	
		power supply	power supply	power supply		charge = 20 As, max. 550 mA	
		module)	module)	module)		CX1100-0910	
System inter	faces					charge = 20 As, max. 1.1 A	
LICE (D)/I	CV0000 NO40	CV4040 NO40	CV4020 N040	CV4020 N040		CX1100-0920	
USB/DVI	CX9000-N010	CX1010-N010	CX1020-N010	CX1030-N010		charge = 40 As, max. 1.1 A	
DC222	CX9010-N010	CV1010 N020	CV1020 N020	CV1020 N020			
RS232	CX9000-N030	CX1010-N030	CX1020-N030	CX1030-N030			
	CX9010-N030	(COM1/2)	(COM1/2)	(COM1/2)	Power sup	ply unit + I/O interfaces	
		CX1010-N040	CX1020-N040	CX1030-N040	24 V DC	CX1100-0001	
RS422/RS485	CX9000-N031	(COM3/4)	(COM3/4)	(COM3/4)	24 V DC		
K5422/K5485		CX1010-N031	CX1020-N031	CX1030-N030		CX1100-0002	
	CX9010-N031	(COM1/2)	(COM1/2)	(COM1/2)	_	with K-bus interface (Bus Terminals)	
		CX1010-N041	CX1020-N041	CX1030-N041		CX1100-0003	
Audio		(COM3/4)	(COM3/4)	(COM3/4)		with K-bus/IP-Link interface	
Audio		CX1010-N020	CX1020-N020	CX1030-N020		(Bus Terminals, Fieldbus Box modules) CX1100-0004	
Ethernet	CV0000 A001	CX1010-N060		CX1030-N060			
Compact	CX9000-A001					with E-bus interface	
Flash	CX9010-A001					(EtherCAT Terminals)	



FIELDBUS COMPONENTS

I/Os for all common fieldbus systems







The fieldbus toolkit

Beckhoff provides an extensive range of fieldbus components for all common I/O and fieldbus systems. With the bus terminals in protection class IP 20, and the Fieldbus Box modules in protection class IP 67, the complete range is available for all relevant signal types and fieldbus systems. The Beckhoff Lightbus is the fast, secure fieldbus system, specially designed to meet the needs of automation technology. EtherCAT, the new real-time Ethernet fieldbus is a further development of the Lightbus

system. EtherCAT reaches new dimensions in network performance. The PC fieldbus cards have been particularly developed for fast control and for real-time tasks, and can therefore be used in a wide range of applications. The I/O range is completed with the appropriate cord sets, programming and configuration tools. The wide choice of I/O components means that the bus system best suited to the particular application can be chosen:

EtherCAT

EtherCAT (Ethernet for Control Automation Technology) is the Ethernet solution for industrial automation, characterised by outstanding performance and particularly simple handling.

Lightbus

This well proven fibre optics bus system from Beckhoff is characterised by particularly good immunity to EMI, easy installation and a very fast, cyclic and deterministic data flow.

PROFIBUS

PROFIBUS is widely used as a fast bus for decentralised peripheral components (PROFIBUS DP). In addition to PROFIBUS DP and FMS, Beckhoff also supports the standard for drive communication, PROFIBUS MC.

Interbus

Interbus is easy to configure, fast and reliable. The shift register protocol of the master/slave system offers high efficiency in cyclic communication.

CANopen

The effective utilisation of the bus bandwidth allows CANopen to achieve a short system reaction time at comparatively low data rates. The typical advantages of CAN, such as high data security and multimaster capability are retained.

DeviceNet

DeviceNet is a sensor/actuator bus system that originated in the USA, but which meanwhile is increasingly being used in Europe and Asia. DeviceNet is CAN based (Controller Area Net).

ControlNet

ControlNet is an open, standardised fieldbus system. The protocol allows both cyclic and acyclic data to be exchanged over the bus without affecting each other.

SERCOS interface

SERCOS was originally developed as a fast fibre optic bus system for drives. Thanks to the Beckhoff SERCOS interface Bus Coupler, the advantages such as high data rate and short cycle times can now be provided for the I/O peripherals too.

Ethernet

Ethernet is the dominant standard in the office world. The advantages of Ethernet, such as high data transmission rates, easy methods of integration into existing networks, and a wide range of services and interfaces are also found in the Beckhoff Ethernet products.

USB

USB has grown into a standard interface for PC technology. Thanks to its high transmission rate, flexible topology through integrated hubs and the Beckhoff USB Bus Coupler, this system can be used as a substitute for a fieldbus when distances are small.

Modbus

Modbus is an open, serial communications protocol based on the master/slave architecture. Since it is extremely easy to implement on all kinds of serial interface, it has gained wide acceptance.

Fipio

FIP complies with the European standard EN 50170 and receives manufacturer-independent support from the WorldFIP organisation. Through periodic and aperiodic exchange of variables and messages, the performance of the bus can be adjusted to the application.

CC-Link

CC-Link (Control & Communication Link) is an open bus system for communication between the control and fieldbus level. It is predominately used in Asia.

RS232/RS485

The "classic" serial interfaces, RS232 and RS485, continue in wide use. The Beckhoff RS485/RS232 I/O modules use a simple, published serial communication protocol that is easy to implement.





Fieldbus Components

Fieldbus overview





Fieldbus	Bus Terminal		EtherCAT Terminals	Fieldbus Box				
	Bus Couplers	PLC (IEC 61131-3)	Couplers/Gateways	Compact Box	Coupler Box	PLC Box (IEC 61131-3)		
EtherCAT.	BK1120		EK1x00		IL230x-B110			
	BK1250							
LIGHTBUS	BK2xx0	BC2000		IPxxxx-B200	IL230x-B200			
PROFU°	BK3xx0	BC31x0	EL6731	IPxxxx-B31x	IL230x-B31x	IL230x-C31x		
BUS	LC3100	BX3100	fieldbus terminal					
INTERBUS Certified! No. 099	BK4xx0	BC4000		IPxxxx-B400	IL230x-B400			
CANopen	BK51xx	BC5150	EL6751	IPxxxx-B51x	IL230x-B51x			
	LC5100	BX5100	fieldbus terminal					
	BK52x0	BC5250	EL6752	IPxxxx-B52x	IL230x-B52x			
DeviceNet >>>	LC5200	BX5200	fieldbus terminal					
Control Net .	BK7000							
CC-Link	BK7150							
Modbus	BK73x0	BC7300		IPxxxx-B730	IL230x-B730			
Fipio	BK7420							
SERCOS Interface	BK75x0							
RS485	BK8000	BC8000		IPxxxx-B800	IL230x-B800	IL230x-C800		
		BX8000						
RS232	BK8100	BC81x0		IPxxxx-B810	IL230x-B810	IL230x-C810		
Ethernet TCP/IP	BK9xx0	ВС9хх0	EL66xx		IL230x-B90x	IL230x-C900		
		BX9000	Ethernet Switch terminal					
PROPU [®] Media	BK9103							
EtherNet/IP	BK9105							
lien a ⊪	BK9500							
	KL/KS62x1							
ZISIINTERFACE	master terminal							
EIB	KL/KS6301							
	EIB Bus Terminal							
LON	KL/KS6401							
	LON Bus Terminal							
MP-Bus	KL/KS6771							
	master terminal							
DALI/DSI	KL/KS6811							
	master terminal							









Fieldbus Modules	PC Fieldbus Cards, Switches	Embedded PC	Drive Technology	Accessories Connectors/Cables	
Modules	Interfaces	Master/Slave	Servo Drives		
	FC90xx		AX5xxx	ZS1090-0003	
	CU20xx		AX20xx-B110		
	Ethernet Switch				
	FC200x	CX1500-M/B200	AX2xxx-B200	Z1xxx	
FM33xx-B310	FC31xx	CX1500-M/B310	AX2xxx-B310	ZB3100	
				ZK/ZS1031	
				ZB4200	
	FC51xx	CX1500-M/B510	AX20xx	ZS1052	
			AX25xx-B510	ZK/ZS1052	
	FC52xx	CX1500-M/B520	AX20xx-B520	ZS1052	
				ZK/ZS1052	
				ZK/ZS1031	
	F675	CV4500 M750	AV2 P7F0	74,000	
	FC75xx	CX1500-M750	AX2xxx-B750	Z1xxx	
			AX20xx	ZK/ZS1031	
			AX20xx	ZK/ZS1031	
	FC90xx		AX2xxx-B900	ZS1090	
	CU20xx Ethernet Switch			ZB90x0	

Fieldbus Componer

Fieldbus

Signal overview

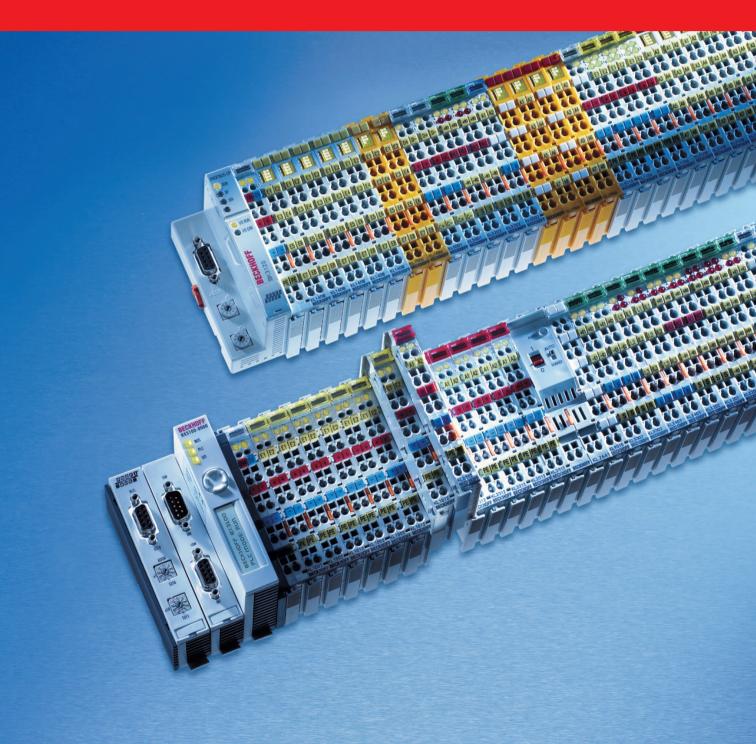
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Signal	Bus Terminal				Terminal Modules	EtherCAT Terminals
	1-channel	2-channel	4-channel	8-channel	4-, 16-, 32-, 64-channel	1-channel
Digital input						
5 V DC			KL/KS1124			
12 V DC						
24 V DC		KL/KS1xx2	KL/KS1xx4	KL/KS1xx8	KM10xx	
48 V DC 120 V AC/DC		KL/KS1032 KL/KS1712				
230 V AC/DC		KL/KS1712 KL/KS17x2				
Safety		KL/K317A2	KL1904			
NAMUR		KL/KS1352	KE1304			
Counter		KL/KS15xx				
Digital output						
5 V DC			KL/KS2124			
24 V DC		KL/KS2xx2	KL/KS2xx4	KL/KS24x8	KM200x	
120 V AC/DC		KL/KS2612				
230 V AC	KL2xx1	KL/KS2xx2			KM2xx4	
400 V AC	KL/KS2631					
Safety			KL2904			
PWM		KL/KS25xx				
Motion Control	KL/KS25x1	KL/KS25x2				EL/ES2521
Digital combi						
24 V DC						
Analog input						
0 2 V, ±2 V		KL/KS31x2				
0 10 V	KL/KS3061	KL/KS3x62	KL/KS3x64	KL/KS3468		EL/ES3x61
±10 V	KL/KS3001	KL/KS30x2	KL/KS3404	KL/KS3408		EL/ES3x01
0 20 mA	KL/KS30x1	KL/KS3xx2	KL/KS3x44	KL/KS3448		EL/ES3xx1
4 20 mA	KL/KS30x1	KL/KS3xx2	KL/KS3x54	KL/KS3458		EL/ES3xx1
Thermocouple	KL3311	KL3312	KL3314			EL3311
Resistance thermometer Resistor bridge	KL/KS3201 KL/KS335x	KL/KS3202	KL/KS3204			EL/ES3201 EL/ES3356
Analog output	KL/K3333X					EL/E33330
0 10 V	KL/KS4001	KL/KS4002	KL/KS4x04	KL/KS4408		EL/ES4001
±10 V	KL/KS4031	KL/KS4x32	KL/KS4xx4	KL/KS4438		EL/ES4031
0 20 mA	KL/KS4011	KL/KS4x12	KL/KS4414	KL/KS4418		EL/ES4011
4 20 mA	KL/KS4021	KL/KS4022	KL/KS4424	KL/KS4428		EL/ES4021
Special functions						
SSI encoder interface	KL/KS50x1					EL/ES5001
Incremental encoder in.	KL/KS51x1					EL/ES51x1
RS232	KL/KS60x1					EL/ES6001
RS485	KL/KS60x1					EL/ES6021
TTY	KL/KS6011					

					(3) (2) (3) (3) (4) (4) (4) (4) (4) (4) (4) (4) (4) (4))
			Fieldbus Box		Fieldbus Modules	Lightbus
2-channel	4-channel	8-channel	Compact Box Coupler/PLC Box	Extension Box	Modules	Modules
	EL/ES1124					
	EL/ES1144					
EL/ES1xx2	EL/ES1xx4	EL/ES10x8	IP10xx-Bxxx	IE10xx		M1110, 1400
EL/EC4740	EL/ES1134					
EL/ES1712						
EL/ES17x2	FI 1004					
	EL1904					
EL/ES15x2			IP1502-Bxxx	IE1502		
LL, LJ I JAZ			II 1302 DAAA	12.1302		
	EL/ES2124					
EL/ES2xx2	EL/ES20x4	EL/ES20x8	IP20xx-Bxxx	IE2xxx		M1110, 1400
EL/ES2xx2						
	EL2904					
EL/ES25xx			IP2512-Bxxx	IE2512		
			IP/IL2xxx-Bxxx	IE2xxx		M1400, 2400
			IL230x-Cxxx			
EL/ES3x62	EL/ES3x64	EL/ES3068				M2510
EL/ES3x02	EL/ES3x04 EL/ES3x04	EL/ES3008	IP3102-Bxxx	IE3102		M2510
EL/ES3xx2	EL/ES3xx4	EL/ES3048	IP3112-Bxxx	IE3102		IVIZOTO
EL/ES3xx2	EL/ES3xx4	EL/ES3058	II 3112 DAAA	123112		M2510
EL3312	EL3314	22,233030	IP3312-Bxxx	IE3312	FM33xx-Bxxx	2310
EL/ES3202	EL/ES3204		IP3202-Bxxx	IE3202	T MISSIAN BAUX	
EL/ES4x02	EL/ES4x04	EL/ES4008				
EL/ES4x32	EL/ES4x34	EL/ES4038	IP4132-Bxxx	IE4132		M2510
EL/ES4x12	EL/ES4x14	EL/ES4018	IP4112-Bxxx	IE4112		
EL/ES4x22	EL/ES4x24	EL/ES4028				
			IP5009-Bxxx	IE5009		
			IP5109-Bxxx	IE5109		M31x0
			IP6002-Bxxx	IE6002		
			IP6022-Bxxx	IE6022		
			IP6012-Bxxx	IE6012		



BUS TERMINAL

The modular fieldbus system for automation



The Bus Terminal system

The Beckhoff Bus Terminal is an open and fieldbus-neutral I/O system consisting of electronic terminal blocks. The head of an electronic terminal block is the Bus Coupler with the interface to the fieldbus. Bus Couplers are available for all common bus systems.

With the master terminals, fieldbus functionalities are also available in form of a standard Bus Terminal. This is particularly advantageous for bus systems that are integrated as subsystems into a higher-level system.

The robust housing, secure contacts and the solidly built electronics are prominent features of our components. A station consists of one Bus Coupler and up to 64 electronic terminal blocks. With the K-bus extension it is possible to operate up to 255 Bus Terminals on one Bus Coupler. The electronic terminal blocks are clipped onto the Bus Coupler. They connect by simply latching together. This means that each electronic terminal block can be exchanged separately and can be mounted on a standard mounting rail. In addition to horizontal type mounting, all other mounting types are permitted.

Design

The Beckhoff Bus Terminal with its outside contour adjusts perfectly to the measurements of terminal boxes. The clear front panel of the terminal with light-emitting diodes for status display, plug-in contact labelling and detachable labelling fields guarantee clarity. The 3-wire system supplemented by a protective conductor terminal makes it possible to wire sensors/actuators directly.

Free mix of signals

The Beckhoff I/O system supports more than 200 Bus Terminals and is thus probably the most comprehensive system on the market. The components enable users to operate mixed signal configurations without restriction at each station. This means that a single non-central input/output node can map all the necessary signals.

Appropriate Bus Terminals are available for any digital or analog automation signal type, for currents and voltages with standardised signal levels and for PT100 and thermocouple signals. Intelligent devices can be connected via Bus Terminals with serial interfaces in accordance with RS232, RS485 or 20 mA TTY.

The fine granularity of the Bus Terminals enables bit-precise composition of the required I/O channels. The digital Bus Terminals are available as 2-, 4- or 8-channel terminals. The standard analog signals of

±10 V, 0 V...10 V, 0...20 mA and 4...20 mA are all available as 1-, 2-, 4-, and 8-channel variants within a standard housing. In the 8-channel variant, analog input and output signals are arranged in an ultra-compact way within a standard Bus Terminal housing across a width of only 12 mm. The system is thus highly modular and can be projected cost-effectively with an accuracy down to a single channel.

Flexible connection system

The Bus Terminal system offers different connection options for optimum adaptation to the respective application. The standard KL type Bus Terminals include electronics and connection level in a single housing. The KS type Bus Terminals feature a pluggable connection level. The KS series Bus Terminals enable the complete wiring to be removed as a plug connector from the top of the housing for servicing.

As an alternative, the KM type terminal modules feature pluggable wiring, combining 16, 32 or 64 digital I/Os in a very small area with high packing density.

Automation standard

The Beckhoff Bus Terminal ensures that control cabinets and terminal boxes are constructed more economically. Using the 4-wire terminating system, all of the usual sensors and actuators with different types of signal can be connected directly without

other connection systems. It is no longer necessary to wire the field devices between the first terminal connection in the control cabinet or in the terminal box and the controller. This significantly reduces the costs involved in controller design and saves space, material, work, and money.

The field devices can be wired using the Beckhoff Bus Terminal system on site where the signals occur. Installation and wiring of the Beckhoff Bus Terminal is thus simple and compact like that of a standard terminal block. The Bus Terminal can be connected to the controller by connecting a Bus Coupler via the fieldbus as required.

The Beckhoff Bus Terminals have been tried and tested in a wide range of sectors worldwide, from machine construction to building management. Beckhoff Bus Terminal technology makes design, construction, wiring, commissioning and maintenance of equipment and machines very cost-effective.



PRODUCT OVERVIEW BUS TERMINALS

System overview Bus Coupler PLC								
Features	Standard BKxx00	Economy BKxx10	Economy plus BKxx20	Compact BKxx50	Low Cost LCxx00	Controller BCxx00	ВСхх50	BXxx00
		00 00 00 00 00 00 00 00 00 00 00 00 00		1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	20 00 00 00 00 00 00 00 00 00 00 00 00 0			
Function	fieldbus slave	fieldbus slave	fieldbus slave	fieldbus slave	fieldbus slave	fieldbus slave, with integrated IEC 61131-3 PLC	fieldbus slave, with integrated IEC 61131-3 PLC	fieldbus slave, with integrated IEC 61131-3 PLC
Program memory	-	-	-	-	-	32/96 kbyte	48 kbyte	256 kbyte
Power supply	1750 mA	500 mA	1750 mA	1000 mA	500 mA	1750 mA	1000 mA	1450 mA
Fieldbus connection	plug (design depends on the fieldbus)	direct to the spring-loaded terminals	plug (design depends on the fieldbus)	plug (design depends on the fieldbus)	plug (design depends on the fieldbus)			
Supported Bus Terminals	all	only digital I/Os (except KL1501, KL25x2)	all	all	only digital I/Os (except KL1501, KL25x2)	all	all	all
Max. number of Bus Terminals	64	64	64 (255 with terminal bus extension)	64 (255 with terminal bus extension)	64	64	64 (255 with terminal bus extension)	64 (255 with terminal bus extension)
Electrical isolation	between fieldbus/ power contacts/ supply voltage	between fieldbus/ power contacts/ supply voltage	between fieldbus/ power contacts/ supply voltage	between fieldbus/ power contacts/ supply voltage	PROFIBUS: yes, CANopen and DeviceNet: no	between fieldbus/ power contacts/ supply voltage	between fieldbus/ power contacts/ supply voltage	between fieldbus/ power contacts/ supply voltage



Bus Coupler						PLC		
Fieldbus	Standard	Economy	Economy plus	Compact	Low Cost	Controller (IE	C 61131-3)	
		only digital I/O			only digital I/O	32/96 kbyte	48 kbyte	256 kbyte
Ether CAT.			BK1120	BK1250				
LIGHTBUS	BK2000	BK2010	BK2020			BC2000		
	BK2500							
	RS485 interface							
PROFII®	BK3000	BK3010						
自由	1.5 Mbaud	1.5 Mbaud						
	BK3100	BK3110	BK3120	BK3150	LC3100	BC3100	BC3150	BX3100
	12 MBaud	12 MBaud	12 MBaud	12 MBaud	12 MBaud	12 MBaud	12 MBaud	12 MBaud
	BK3500		BK3520					
	1.5 Mbaud, fibre op.		12 Mbaud, fibre op.					
INTERBUS	BK4000	BK4010	BK4020			BC4000		
Certified! No. 099	BK4500							
	fibre optic							
CANopen		BK5110	BK5120	BK5150	LC5100		BC5150	BX5100
				BK5151				
DeviceNet	BK5200	BK5210	BK5220	BK5250	LC5200		BC5250	BX5200
Control Net .	BK7000							
CC-Link				BK7150				
Modbus	BK7300			BK7350		BC7300	BC8150	
Fipio			BK7420					
SERCOS interface	BK7500		BK7520					
RS485	BK8000					BC8000		BX8000
RS232	BK8100					BC8100	BC8150	
Ethernet TCP/IP	BK9000			BK9050		BC9000	BC9050	BX9000
	BK9100					BC9100		
	2-channel switch					2-channel switch		
PROF!	BK9103							
NETO	2-channel switch							
•	BK9105							
EtherNet/IP>	2-channel switch							
USD CE	BK9500							

KM1xxx

Bus Terminals in 1-, 2-, 4- and 8-channel modularity with combinations of any desired types of signal

Digital input: KL1xxx | KS1xxx



BELANDEF BELANDEF BEZNADEF BEZNADEF BEZNADEF BEZNADEF BEZNADEF BEZNADEF BEZNADEF BEZNADEF BEZNADEF BEZNADEF

Signal				
	2-channel	4-channel	8-channel	16-/32-/64-channel
5 V DC		KL1124 KS1124		
		filter 0.2 ms		
24 V DC	KL1002 KS1002	KL1104 KS1104	KL1408 KS1408	KM1002
	filter 3.0 ms	filter 3.0 ms	filter 3.0 ms	filter 3.0 ms, 16-channel
	KL1012 KS1012	KL1114 KS1114	KL1418 KS1418	KM1012
	filter 0.2 ms	filter 0.2 ms	filter 0.2 ms	filter 0.2 ms, 16-channel
	KL1052 KS1052	KL1154 KS1154 KL1164 KS1164		KM1004
	filter 3.0 ms, p/n-switching	filter 3.0 ms, p/n-switching filter 0.2 ms, p/n-switching		filter 3.0 ms, 32-channel
	KL1212 KS1212	KL1184 KS1184 KL1194 KS1194	KL1488 KS1488	KM1014
	filter 3.0 ms, short circuit	filter 3.0 ms, n-switching filter 0.2 ms, n-switching	filter 3.0 ms, n-switching	filter 0.2 ms, 32-channel
	protected sensor supply			
	KL1302 KS1302	KL1304 KS1304	KL1498 KS1498	KM1008
	filter 3.0 ms, type 2 sensors	filter 3.0 ms, type 2 sensors	filter 0.2 ms, n-switching	filter 3.0 ms, 64-channel
	KL1312 KS1312	KL1314 KS1314		KM1018
	filter 0.2 ms, type 2 sensors	filter 0.2 ms, type 2 sensors		filter 0.2 ms, 64-channel
	KL1232 KS1232	KL1404 KS1404 KL1414 KS1414		
	pulse expansion	filter 3.0 ms, 4 x 2-wire connection filter 0.2 ms, 4 x 2-wire connection		
	KL1362 KS1362	KL1434 KS1434		
	break-in alarm	filter 0.2 ms, type 2 sensors,		
		4 x 2-wire connection		
	KL1382 KS1382	KL1904	KL1528	
	thermistor	TwinSAFE, 4 safe inputs	multi-function I/O,	
			fast inputs/outputs	
48 V DC	KL1032 KS1032			
	filter 3.0 ms			
120 V AC/DC	KL1712 KS1712			
	power contacts			
230 V AC	KL1702 KS1702			
	power contacts			
	KL1722 KS1722			
	no power contacts			
NAMUR	KL1352 KS1352			
Counter	KL1501 KS1501			
	up/down, 24 V DC, 100 kHz			

07-08

03-04

BECKASFF BECKASFF BECKA

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O I/O RUN

BECKHOF! BK3100

KLxxxx: Standard Bus Terminals, KSxxxx: Bus Terminals with pluggable wiring level

KL1512 | KS1512 up/down, 24 V DC, 1 kHz, 16 bit

KL4012 BECKHOFF

Fast and secure data connections by means of a serial terminal bus

Power contacts for automatic transfer of supply voltage

Digital output: KL2xxx KS2xxx						KM2xxx	
Signal							
	1-channel	2-channel		4-channel		8-channel	4-/16-/32-/64-ch.
5 V DC				KL2124 KS2124			
24 V DC		KL2012 KS2012	KL2022 KS2022	KL2114 KS2114	KL2134 KS2134	KL2408 KS2408	KM2002
		Imax = 0.5 A	Imax = 2.0 A	Imax = 0.5 A	I _{MAX} = 0.5 A, rev. volt. prot.	Imax = 0.5 A	I _{MAX} = 0.5 A, 16-channel
		KL2032 KS2032	KL2212 KS2212	KL2184 KS2184	KL2904	KL2488 KS2488	KM2004
		Imax = 0.5 A,	Imax = 0.5 A,	I _{MAX} = 0.5 A, n-switching	TwinSAFE, 4 safe outputs	I _{MAX} = 0.5 A, n-switching	I _{MAX} = 0.5 A, 32-channel
		reverse voltage	diagnostic, protected	KL2404 KS2404	KL2424 KS2424		KM2008
		protection	sensor supply	I _{MAX} = 0.5 A, 4 x 2-wire	I _{MAX} = 2.0 A, 4 x 2-wire		I _{MAX} = 0.5 A, 64-channel
24 V AC/DC				KL2784 KS2784	KL2794 KS2794		
				I _{MAX} = 1.0 A, solid state	I _{MAX} = 1.0 A, solid state,		
					potential-free contacts		
125 V AC		KL2612 KS2612					
		relay, change-over					
230 V AC	KL2641	KL2602 KS2602	KL2622 KS2622				KM2604
	relay, make contact,	relay, make contact	relay, make contact,				relay, 16 A, 4-channel
	manual operation, 16 A		no power contacts				
		KL2652 KS2652	KL2702 KS2702				
		relay, change-over	solid state relay				
	KL2751 KS2751	KL2712 KS2712	KL2722 KS2722				KM2774
	universal dimmer	triac	triac, mutually locked				triac output for
	terminal, 230 V, 300 W		outputs				4 blind motors
		KL2732 KS2732	KL2692 KS2692				
		triac, mutually locked	cycle monitoring				
		outputs, no power cont.	(watchdog)				
400 V AC	KL2631 KS2631						
	relay, make contact						
PWM		KL2502 KS2502	KL2512				
		24 V DC, 0.1 A	24 V DC, 1.5 A, n-switch.				
		KL2535 KS2535	KL2545 KS2545				
		24 V DC, 1 A,	50 V DC, 3.5 A,				
		current-controlled	current-controlled				
Pulse train	KL2521 KS2521						
Stepper motor	KL2531 KS2531						
	I _{MAX} = 1.5 A						
	KL2541 KS2541						
	I _{MAX} = 5 A						
DC motor		KL2532 KS2532	KL2542 KS2542				
output stage		24 V DC, 1 A	50 V DC, 3.5 A				
	Kl vvvv: Standar	d Duc Torminals V	Syvyy Puc Tormina	ls with nluggable	wiring lovel		

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29 30 31 32 33 34

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KLxxxx: Standard Bus Terminals, KSxxxx: Bus Terminals with pluggable wiring level

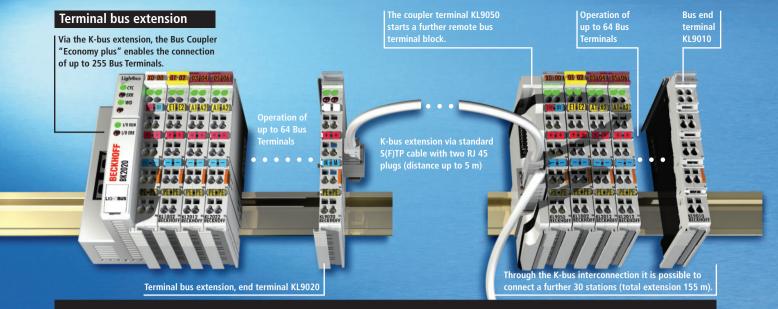
KSxxxx | The KS series Bus Terminals feature a pluggable connection level enabling the complete wiring to be removed as a plug connector from the top of the housing for servicing. KMxxxx | The KM type terminal modules feature pluggable wiring, combining 16, 32 or 64 digital I/Os in a very small area with high packing density.



Analog	input:	KL3xxx	KS3xxx
/ tilalog	mpat.	IXES/AAA	ILO JAMA

Signal				
	1-channel	2-channel	4-channel	8-channel
0 2 V		KL3172 KS3172 16 bit, 0.05%		
± 2 V		KL3182 KS3182 16 bit, 0.05%		
0 10 V	KL3061 KS3061	KL3062 KS3062	KL3064 KS3064	
	single-ended, 12 bit	single-ended, 12 bit	single-ended,12 bit	
		KL3162 KS3162	KL3464 KS3464	KL3468 KS3468
		16 bit, 0.05%	4 x 2-wire connection, 12 bit	8 x 1-wire connection, 12 bit
±10 V	KL3001 KS3001	KL3002 KS3002	KL3404 KS3404	KL3408 KS3408
	differential input, 12 bit	differential input, 12 bit	4 x 2-wire connection, 12 bit	8 x 1-wire connection, 12 bit
		KL3102 KS3102		
		differential input, 16 bit		
		KL3132 KS3132 16 bit, 0.05%		
0 20 mA	KL3011 KS3011	KL3012 KS3012	KL3444 KS3444	KL3448 KS3448
	differential input, 12 bit	differential input, 12 bit	4 x 2-wire connection, 12 bit	8 x 1-wire connection, 12 bit
	KL3041 KS3041	KL3042 KS3042	KL3044 KS3044	
	terminal supply, 12 bit	terminal supply, 12 bit	12 bit	
		KL3112 KS3112 different. input, 16 bit		
		KL3142 KS3142 16 bit, 0.05%		
4 20 mA	KL3021 KS3021	KL3022 KS3022	KL3454 KS3454	KL3458 KS3458
	differential input, 12 bit	differential input, 12 bit	4 x 2-wire connection, 12 bit	8 x 1-wire connection, 12 bit
	KL3051 KS3051	KL3052 KS3052	KL3054 KS3054	
	terminal supply, 12 bit	terminal supply, 12 bit	12 bit	
		KL3122 KS3122		
		differential input,16 bit		
		KL3152 KS3152 16 bit, 0.05%		
Thermocouples	KL3311	KL3312	KL3314	
	type J, K, L,U, 16 bit	type J, K, L,U, 16 bit	type J, K, L,U, 16 bit	
Resistance	KL3201 KS3201	KL3202 KS3202	KL3204 KS3204	
thermometer (RTD)	PT1001000, Ni100, 16 bit	PT1001000, Ni100, 16 bit	PT1001000, Ni100, 16 bit	
Resistor bridge	KL3351 KS3351			
	strain gauge, 16 bit			
	KL3356 KS3356			
	strain gauge, 16 bit, self-calibration			
Oscilloscope	KL3361 KS3361	KL3362 KS3362		
	oscilloscope terminal, ±20 mV	oscilloscope terminal, ±10 V		
Power measurement		KL3403 KS3403		
		3-phase power measurement terminal		
Pressure measuring	KM3701 differential mea., 100 hPa	KM3702 absolute measuring, 10000 hPa		
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KLxxxx: Standard Bus Terminals, KSxxxx: Bus Terminals with pluggable wiring level



Analog output: KL4xxx | KS4xxx

Signal				
	1-channel	2-channel	4-channel	8-channel
0 10 V	KL4001 KS4001	KL4002 KS4002	KL4004 KS4004	
	12 bit	12 bit	12 bit	
			KL4404 KS4404	KL4408 KS4408
			4 x 2-wire connection, 12 bit	8 x 1-wire connection, 12 bit
±10 V	KL4031 KS4031	KL4032 KS4032	KL4034 KS4034	
	12 bit	12 bit	12 bit	
			KL4434 KS4434	KL4438 KS4438
			4 x 2-wire connection, 12 bit	8 x 1-wire connection, 12 bit
		KL4132 KS4132		
		16 bit		
		10 bit		
			VI 4404	
			KL4494 KS4494	
			2 x input, 2 x output, 12 bit	
0 20 mA	KL4011 KS4011	KL4012 KS4012		
	12 bit	12 bit		
			KL4414 KS4414	KL4418 KS4418
			4 x 2-wire connection, 12 bit	8 x 1-wire connection, 12 bit
			TAZ MIC COMICCION, TZ DIC	o x 1 time connection, 12 bit
		KL4112 KS4112		
		16 bit		
4 20 mA	KL4021 KS4021	KL4022 KS4022		
	12 bit	12 bit		
			KL4424 KS4424	KL4428 KS4428
			4 x 2-wire connection, 12 bit	8 x 1-wire connection, 12 bit

Special	functions:	KL/KS5xxx,	KL/KS6xxx

Power terminals: KL8xxx

TwinSAFE terminals: KLx904

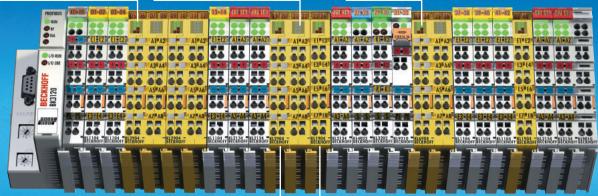
Special func	HORS: KL/KSSXXX, KL/KSGXXX	Power termi	IIdis: KLOXXX	iwinsare te	rminais: KLX904
Signal		Signal		Signal	
Position	KL5001 KS5001	400 V AC 3~	KL8001	24 V DC	KL1904
measurement	SSI encoder interface		switching capacity 5.5 kW,		4-channel digital input
	KL5051 KS5051		nominal current 0.9 to 9.9 A,		terminal, IEC 61508 SIL 3
	bidirectional SSI encoder interface		connection mechanism for		and EN 954 Cat. 4
	KL5101 KS5101		Siemens contactors		
	incremental encoder interface, diff. input		(Sirius 3R series)		
	KL5111 KS5111				
	incremental encoder interface				KL2904
	KL5151 KS5151				4-channel digital output
	incremental encoder interface, 32 bit		KL8601		terminal, IEC 61508 SIL 3
	KL5121 KS5121		communication module for		and EN 954 Cat. 4
	4-channel, incremental encoder interface		Schneider TeSys model U		
	with programmable outputs				
Communi-	KL6001 KS6001				
cation	serial interface RS232, 19.2 kbaud			Controller	KL6904
	KL6031 KS6031		KL8610		TwinSAFE Logic Bus
	serial interface RS232, 115.2 kbaud		adapter terminal for		Terminal with 4 digital
	KL6011 KS6011		Schneider TeSys model U		outputs, IEC 61508 SIL 3
	serial interface TTY, 20 mA current loop				and EN 954 Cat. 4
	KL6021 KS6021				
	serial interface RS422/RS485, 19.2 kbaud				
	KL6041 KS6041				
	serial interface RS422/RS485, 115.2 kbaud				
	KL6023				
	wireless adapter for EnOcean radio technology				
	KL6051 KS6051				
	data exchange terminal, 32 bit				
	KL6201 KS6201				
	AS-Interface master terminal				
	KL6211 KS6211				
	AS-Interface master terminal with power contacts				
	KL6301 KS6301 EIB Bus Terminal				
	KL6401 KS6401 LON Bus Terminal				
	KL6771 KS6771				

MP-Bus master terminal KL6811 | KS6811

DALI/DSI master and power supply terminal

Certification: All TwinSAFE devices are subjected to a prototype test according to IEC 61508 and EN 954.

The TwinSAFE Logic Bus Terminal KL6904 enables communication with up to 31 TwinSAFE devices. The Bus Terminal features certified safety blocks for functions such as emergency stop, safety door monitoring, etc. In addition, the TwinSAFE Logic Bus Terminal has four safe digital 24 V DC outputs.



The Safety Bus Terminal KL2904 is a digital output terminal with four channels. The terminal switches 24 V DC actuators with up to 2 A total current.

The digital input terminal KL1904 for sensors with potential-free contacts for 24 V DC: The Saftey Bus Terminal has 4 fail-safe inputs.

System terminals: KL9xxx | KS9xxx

Signal	System	Signal	Potential supply	Power supply
System	KL9010	24 V DC	KL9100 KS9100	KL9400 KS9400
	bus end terminal			input 24 V DC,
	KL9020			K-bus power supply, 2 A
	terminal bus extension end terminal		KL9110 KS9110	KL9505 KS9505
	KL9050		diagnostic	input 24 V DC,
	terminal bus extension coupler terminal			output 5 V DC, 1 A
	KL9060		KL9200	KL9508 KS9508
	adapter terminal for power terminal		with fuse	input 24 V DC,
	KL8xxx			output 8 V DC, 0.5 A
	KL9080		KL9210	KL9510 KS9510
	isolation terminal		diagnostic, with fuse	input 24 V DC,
	KL9180 KS9180			output 10 V DC, 0.5 A
	potential distribution terminal			KL9512 KS9512
	KL9185 KS9185			input 24 V DC,
	potential distribution terminal,			output 12 V DC, 0.5 A
	only 2 power contacts			KL9515 KS9515
	KL9186 KS9186			input 24 V DC,
	potential distribution, 8 x 24 V			output 15 V DC, 0.5 A
	KL9187 KS9187		KL9520 KS9520	KL9528 KS9528
	potential distribution, 8 x 0 V		AS-Interface potential supply	AS-Interface power supply terminal
	KL9195 KS9195			KL9560 KS9560
	shield terminal			input 24 V DC,
				output 24 V DC, 0.1 A
ilter	KL9540 KS9540			
	surge filter terminal for field supply	120 230 V AC	KL9150 KS9150	
	KL9550 KS9550		KL9160 KS9160	
	surge filter terminal for system/field supply		diagnostic	
			KL9250	
iode array	KL9300 KS9300		with fuse	
	4 diodes, potential-free		KL9260	
	KL9301 KS9301		diagnostic, with fuse	
	7 diodes, common cathode			
	KL9302 KS9302	up to 400 V AC	KL9190 KS9190	
	7 diodes, common anode		KL9290	
			with fuse	

KLxxxx: Standard Bus Terminals, KSxxxx: Bus Terminals with pluggable wiring level



ETHERCAT

Ultra high-speed I/O



Ethernet for Control and Automation Technology

EtherCAT (Ethernet for Control Automation Technology) is the Ethernet solution for industrial automation, characterised by outstanding performance and particularly simple handling. EtherCAT enables the Ethernet star topology to be replaced with a simple line structure. Optionally, EtherCAT may also be wired in the "classic" way using switches, in order to integrate further Ethernet devices. The master requires no special plug-in card and can be implemented on any existing Ethernet controller using a

very simple interface. EtherCAT is therefore also well suited to small and medium control technology, where it will also open up new areas of application for distributed I/Os. The extremely high performance of the EtherCAT technology enables control concepts that could not be realised with classic fieldbus systems. With EtherCAT, a communication technology is available that matches the superior computing capacity of modern Industrial PCs.

Principle of operation

From an Ethernet point of view, an EtherCAT segment is simply a single large Ethernet device, which receives and sends Ethernet frames. However, the device does not contain an Ethernet controller with downstream microprocessor, but a large number of EtherCAT slaves. These slaves process the incoming telegrams directly and extract the relevant user data, or they insert them and transfer the telegram to the next EtherCAT slave. The last EtherCAT slave sends the fully processed telegram back, so that it is returned by the first slave to the master as a kind of response telegram. The telegrams are only delayed by a few nanoseconds.

Naturally, like for any other Ethernet device, direct communication without switch may be established using a "crossover" Ethernet cable, thereby creating a pure EtherCAT system.

Telegrams are processed directly "on the fly". While the telegrams (delayed by only a few bits) are already passed on, the slave recognizes relevant commands and executes them accordingly.

Topology

Line, tree or star: EtherCAT supports almost any topology. The bus or line structure known from the fieldbuses thus also becomes available for Ethernet. Particularly useful for system wiring is the combination of lines and branches or stubs: The required interfaces exist on the couplers; no additional switches are required. Naturally, the classic switch-based Ethernet star topology can also be used. Wiring flexibility is further maximised through the choice of different cables. Flexible and inexpensive standard Ethernet patch cables transfer the signals optionally in Ethernet mode (100Base-TX) or in E-bus signal representation. The Fast Ethernet physics enables a cable length of 100 m between two devices, the E-bus line is intended for distances of up to 10 m.

For each cable distance, the signal variant can be selected individually. Since up to 65,535 devices can be connected, the size of the network is almost unlimited.

EtherCAT components

On the hardware side, EtherCAT technology is located in EtherCAT Terminals, for example. The I/O system in protection class IP 20 is based on the housing of the tried and tested Beckhoff Bus Terminal system. In contrast to Bus Terminals, where the fieldbus protocol data is converted within the Bus Coupler to the internal, fieldbusindependent terminal bus, the EtherCAT protocol remains fully intact down to the individual terminal. In addition to EtherCAT Terminals with E-bus connection. the proven standard Bus Terminals with K-bus connection can also be connected via the BK1120 EtherCAT Bus Coupler. This ensures compatibility and continuity

with the prevalent system. Existing and future investments are protected. The Beckhoff Servo Drives are also available with EtherCAT interface.

EtherCAT will be integrated in further Beckhoff components, such as the Fieldbus Box in protection class IP 67. The Beckhoff Industrial PCs, the Embedded PCs of the CX series, the Control Panels with control functionality, and the Ethernet PCI cards already offer inherent EtherCAT capability.

Openness

The EtherCAT technology is not only fully Ethernet-compatible, but also characterised by particular openness "by design": The protocol tolerates other Ethernet-based services and protocols on the same physical network — usually even with minimum loss of performance. Any Ethernet device can be connected within the EtherCAT segment via a switchport terminal without influencing the cycle time. Devices with fieldbus interface are integrated via EtherCAT fieldbus master terminals.



PRODUCT OVERVIEW ETHERCAT

Digital input: EL1xxx | ES1xxx

	<u> </u>		· ·		
		Signal			
			2-channel	4-channel	8-channel
Coupler	EK1100	5 V DC		EL1124 ES1124	
	E-bus interface			filter 10 μs	
	(EtherCAT Terminals ELxxxx)	12 V DC		EL1144 ES1144	
				filter 10 μs	
		24 V DC	EL1002 ES1002	EL1004 ES1004	EL1008 ES1008
	BK1120		filter 3.0 ms, type 1, p-switching	filter 3.0 ms, type 1, p-switching	filter 3.0 ms, type 1, p-switching
	K-bus interface		EL1012 ES1012	EL1014 ES1014	EL1018 ES1018
	(Bus Terminals KLxxxx)		filter 10 μs, type 1, p-switching	filter 10 μs, type 1, p-switching	filter 10 μs, type 1, p-switching
				EL1024 ES1024	
				filter 3.0 ms, type 2, p-switching	
	EK1000			EL1034 ES1034	
	E-bus interface for operation at			filter 10 μs, potential-free inputs	
	the switch (EtherCAT Terminals			EL1104 ES1104	
	ELxxxx) UDP, MAC-ID			filter 3.0 ms, ±sensor supply	
			EL1202 ES1202	EL1114 ES1114	
			T _{on} /T _{off} 1 μs, fast input	filter 10 μs, ±sensor supply	
			EL1252 ES1252	EL1084 ES1084	EL1088 ES1088
			filter 10 μs, time stamp	filter 3.0 ms, n-switching	filter 3.0 ms, n-switching
Extension	EK1110		EL1262 ES1262	EL1094 ES1094	EL1098 ES1098
system	extension end terminal		filter 10 μs, oversampling	filter 10 μs, n-switching	filter 10 μs, n-switching
	(EtherCAT)			EL1904	
				TwinSAFE, 4 safe inputs	
		48 V DC		EL1134 ES1134	
				filter 10 μs	
		120 V AC/DC	EL1712 ES1712		
			power contacts		
		230 V AC	EL1702 ES1702		
			power contacts		
			EL1722 ES1722		
			no power contacts		
		Counter	EL1502 ES1502		
			up/down, 24 V DC, 100 kHz, 32 bit		
			EL1512 ES1512		
			up/down, 24 V DC, 1 kHz, 16 bit		

Eth

ELxxxx: Standard EtherCAT Terminals, ESxxxx: EtherCAT Terminals with pluggable wiring level

EtherCAT Coupler

The EtherCAT Technology Group (ETG) is an association of automation users and manufacturers aiming to support the development of the EtherCAT technology. The consortium represents a wide range of sectors and application areas. This ensures that the EtherCAT technology functions and interfaces are ideally prepared for a wide range of applications. The organisation ensures that EtherCAT can easily and cost-effectively be

integrated in a wide range of automation devices, and it also ensures interoperability of the implementations. The EtherCAT Technology Group is the official IEC partner organisation for fieldbus standardisation. Membership is open to all companies.

For further information see www.ethercat.org



ignal				
	1-channel	2-channel	4-channel	8-channel
V DC			EL2124 ES2124	
4 V DC		EL2002 ES2002	EL2004 ES2004	EL2008 ES2008
		Імах = 0.5 A	Iмах = 0.5 A	I _{MAX} = 0.5 A
		EL2022 ES2022	EL2024 ES2024	
		I _{MAX} = 2.0 A	I _{MAX} = 2.0 A	
		EL2032 ES2032	EL2034 ES2034	
		I _{MAX} = 2.0 A, with diagnostic	I _{MAX} = 2.0 A, with diagnostic	
		EL2252 ES2252	EL2084 ES2084	EL2088 ES2088
		I _{мах} = 0.5 A, time stamp	IMAX = 0.5 A, n-switching	I _{MAX} = 0.5 A, n-switching
		EL2262 ES2262		
		I _{MAX} = 0.5 A, oversampling		
		EL2202 ES2202	EL2904	
		T _{on} /T _{off} 1 μs, push-pull outputs	TwinSAFE, 4 safe outputs	
elay (up to 230 V AC)		EL2602 ES2602		
		I _{мах} = 2.0 A, make contact,		
		power contacts		
		EL2622 ES2622		
		I _{мах} = 2.0 A, make contact,		
		no power contacts		
		EL2612 ES2612		
		I _{MAX} = 1.0 A, change-over,		
		no power contacts		
riac (up to 230 V AC)		EL2712 ES2712		
		12 230 V, 0.5 A, power contacts		
		EL2732 ES2732		
		12 230 V, 0.5 A, no power contacts		
		EL2722 ES2722		
		12 230 V, 1.0 A, mutually locked		
		outputs		
WM		EL2502 ES2502		
		PWM output, 24 V DC, 1.0 A		
		EL2535 ES2535		
		24 V DC, 1.0 A, current-controlled		
		EL2545 ES2545		
		50 V DC, 3.5 A, current-controlled		
ılse train	EL2521 ES2521			

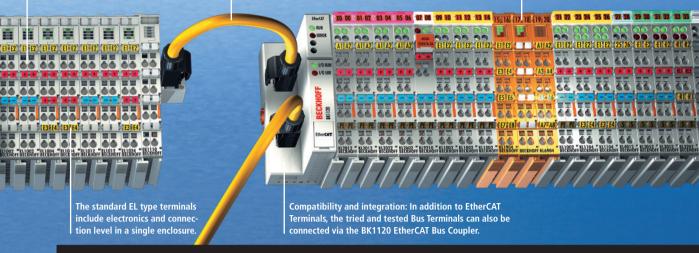
Ether

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ELxxxx: Standard EtherCAT Terminals, ESxxxx: EtherCAT Terminals with pluggable wiring level

Signal				
	1-channel	2-channel	4-channel	8-channel
0 10 V	EL3061 ES3061	EL3062 ES3062	EL3064 ES3064	EL3068 ES3068
	single-ended, 12 bit	single-ended, 12 bit	single-ended, 12 bit	single-ended, 12 bit
	EL3161 ES3161	EL3162 ES3162	EL3164 ES3164	
	single-ended, 16 bit	single-ended, 16 bit	single-ended, 16 bit	
±10 V	EL3001 ES3001	EL3002 ES3002	EL3004 ES3004	EL3008 ES3008
	single-ended, 12 bit	single-ended, 12 bit	single-ended, 12 bit	single-ended, 12 bit
	EL3101 ES3101	EL3102 ES3102	EL3104 ES3104	
	differential input, 16 bit	differential input, 16 bit	differential input, 16 bit	
		EL3702 ES3702		
		differential input, 16 bit, oversampling		
0 20 mA	EL3041 ES3041	EL3042 ES3042	EL3044 ES3044	EL3048 ES3048
	single-ended, 12 bit, terminal supply	single-ended, 12 bit, terminal supply	single-ended, 12 bit	single-ended, 12 bit
	EL3141 ES3141	EL3142 ES3142	EL3144 ES3144	
	single-ended, 16 bit, terminal supply	single-ended, 16 bit, terminal supply	single-ended, 16 bit	
	EL3011 ES3011	EL3012 ES3012	EL3014 ES3014	
	differential input, 12 bit	differential input, 12 bit	differential input, 12 bit	
	EL3111 ES3111	EL3112 ES3112	EL3114 ES3114	
	differential input, 16 bit	differential input, 16 bit	differential input, 16 bit	
		EL3742 ES3742		
		differential input, 16 bit, oversampling		
4 20 mA	EL3051 ES3051	EL3052 ES3052	EL3054 ES3054	EL3058 ES3058
	single-ended, 12 bit, terminal supply	single-ended, 12 bit, terminal supply	single-ended, 12 bit	single-ended, 12 bit
	EL3151 ES3151	EL3152 ES3152	EL3154 ES3154	
	single-ended, 16 bit, terminal supply	single-ended, 16 bit, terminal supply	single-ended, 16 bit	
	EL3021 ES3021	EL3022 ES3022	EL3024 ES3024	
	differential input, 12 bit	differential input, 12 bit	differential input, 12 bit	
	EL3121 ES3121	EL3122 ES3122	EL3124 ES3124	
	differential input, 16 bit	differential input, 16 bit	differential input, 16 bit	
Thermocouples	EL3311	EL3312	EL3314	
	type J, K, L,U, 16 bit	type J, K, L,U, 16 bit	type J, K, L,U, 16 bit	
Resistance thermometer	EL3201 ES3201	EL3202 ES3202	EL3204 ES3204	
(RTD)	PT1001000, Ni100, 16 bit	PT1001000, Ni100, 16 bit	PT1001000, Ni100, 16 bit	
Resistor bridge	EL3356 ES3356			
	strain gauge, 16 bit, self-calibration			
Power measurement		EL3403 ES3403		
		3-phase power measurement terminal		

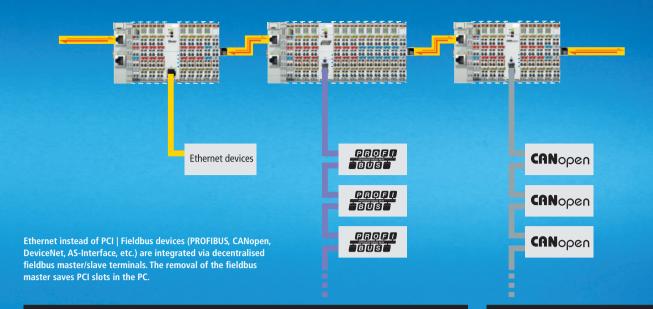
ELxxxx: Standard EtherCAT Terminals, ESxxxx: EtherCAT Terminals with pluggable wiring level



Analog output: EL4xxx | ES4xxx

Signal				
	1-channel	2-channel	4-channel	8-channel
0 10 V	EL4001 ES4001	EL4002 ES4002	EL4004 ES4004	EL4008 ES4008
	12 bit	12 bit	12 bit	12 bit
		EL4102 ES4102	EL4104 ES4104	
		16 bit	16 bit	
±10 V	EL4031 ES4031	EL4032 ES4032	EL4034 ES4034	EL4038 ES4038
±10 V	12 bit	12 bit	12 bit	12 bit
	12 010	12 010	12 510	12 010
		EL4132 ES4132	EL4134 ES4134	
		16 bit	16 bit	
		EL4732 ES4732		
		16 bit, oversampling		
0 20 mA	EL4011 ES4011	EL4012 ES4012	EL4014 ES4014	EL4018 ES4018
	12 bit	12 bit	12 bit	12 bit
		FI 4442	FI 4444	
		EL4112 ES4112	EL4114 ES4114	
		16 bit	16 bit	
		EL4712 ES4712		
		16 bit, oversampling		
		To Did oversampling		
4 20 mA	EL4021 ES4021	EL4022 ES4022	EL4024 ES4024	EL4028 ES4028
	12 bit	12 bit	12 bit	12 bit
		EL4122 ES4122	EL4124 ES4124	
		16 bit	16 bit	
40. 4		E1 4442 0046		
±10 mA		EL4112-0010		
		ES4112-0010		
		16 bit		

ELxxxx: Standard EtherCAT Terminals, ESxxxx: EtherCAT Terminals with pluggable wiring level



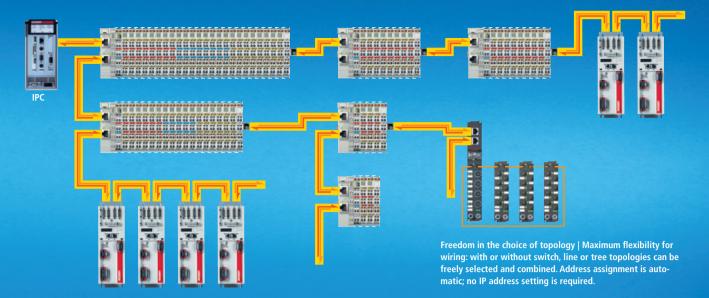
Special funct	tions: EL5xxx ES5xxx,	EL6xxx ES6xxx, EL7x	xx ES7xxx
Signal			
_	1-channel	2-channel	4-channel
Position	EL5001 ES5001		
measurement	SSI encoder interface		
	EL5101 ES5101		
	incremental encoder interface,		
	differential inputs		
	EL5151 ES5151		
	incremental encoder interface, 32 bit		
Communi-	EL6001 ES6001		
cation	RS232, 115.2 kbaud		
	EL6021 ES6021		
	RS422/RS485, 115.2 kbaud		
	EL6201 ES6201		EL6224 ES6224
	AS-Interface master terminal		IO link
	EL6601	EL6692	EL6614
	switch port	EtherCAT bridge terminal	switch port
	EL6731		
	PROFIBUS DP master terminal		
	EL6731-0010		
	PROFIBUS DP slave terminal		
	EL6740-0010		
	Interbus slave terminal		
	EL6751		
	CANopen master terminal		
	EL6751-0010		
	CANopen slave terminal		
	EL6752		
	DeviceNet master terminal		
	EL6752-0010		EL6904
	DeviceNet slave terminal		TwinSAFE logic terminal,
			with 4 digital outputs
Motion	EL7031 ES7031	EL7332 ES7332	EM7004
	stepper motor terminal,	DC motor output stage,	4 incremental encoder,
	Imax = 1.5 A, 24 V	24 V DC, 1.0 A	16 digital inputs 24 V DC,
	EL7041 ES7041	EL7342 ES7342	16 digital outputs 24 V DC,
	stepper motor terminal,	DC motor output stage, 50 V DC,	4 analog inputs ±10 V
	Imax = 5.0 A, 50 V,	3.5 A, incremental encoder	

System terminals: EL9xxx | ES9xxx

	<u> </u>
Signal	System
System	EL9011
	bus end cap
	- 10000
	EL9080
	isolation terminal
	EL9180 ES9180
	potential distribution terminal,
	2 clamping units
	per power contact
	EL9185 ES9185
	potential distribution terminal,
	4 clamping units
	at 2 power contacts
	F10406
	EL9186 ES9186
	potential distribution, 8 x 24 V
	EL9187 ES9187
	potential distribution, 8 x 0 V
	EL9195 ES9195
	shield terminal

ELxxxx: Standard EtherCAT Terminals, ESxxxx: EtherCAT Terminals with pluggable wiring level

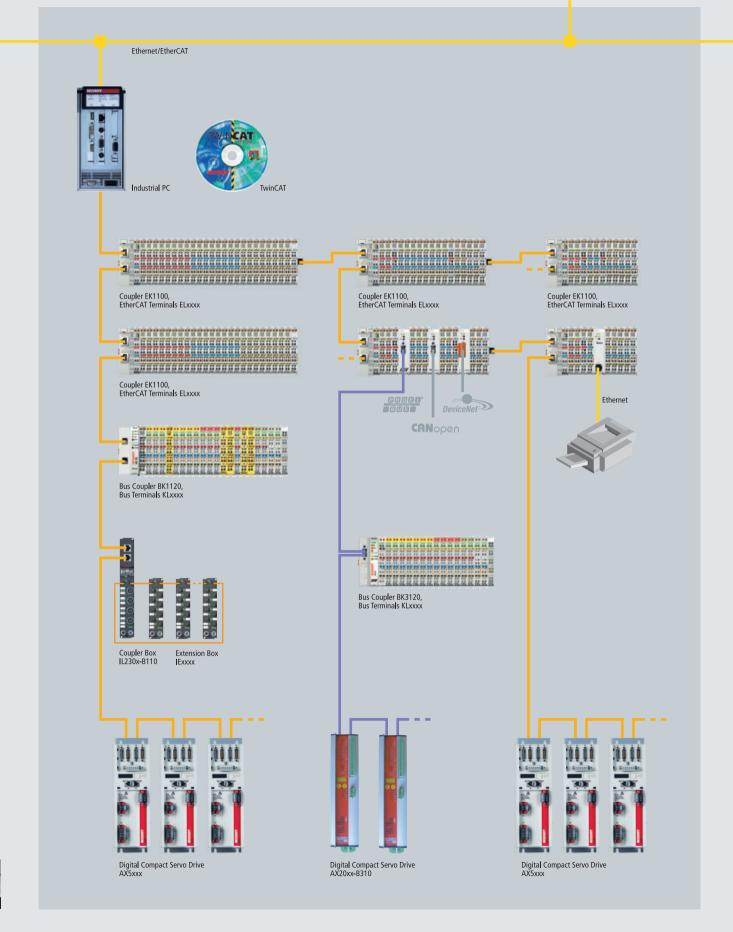
incremental encoder interface

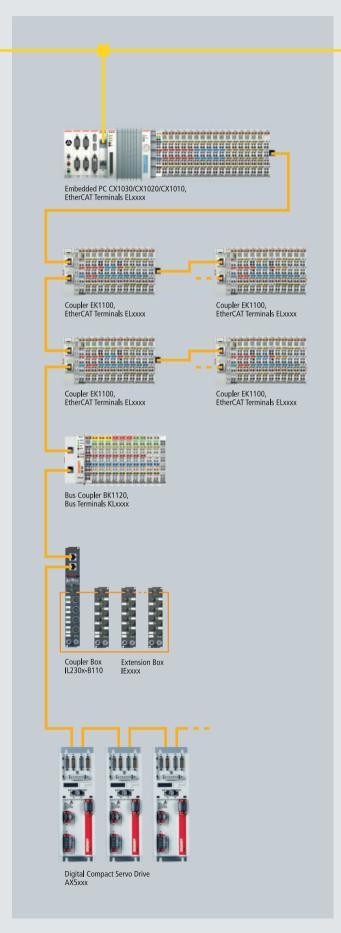


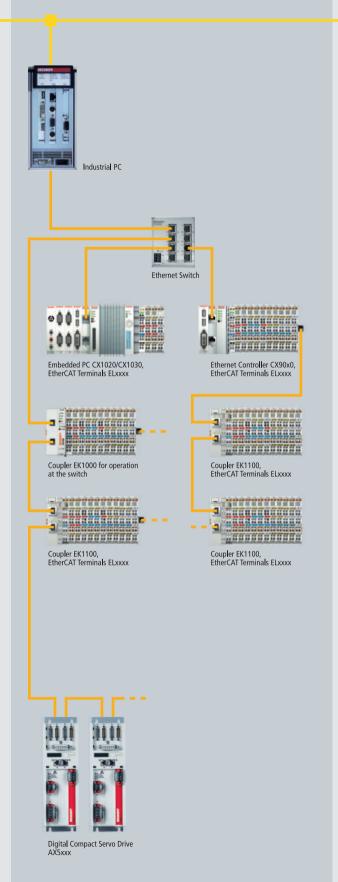
			EtherCAT				
Signal	Potential supply	Power supply	Drive Technology		Components	/Interfaces	
24 V DC	EL9100 ES9100	EL9400 ES9400	Servo Drives	AX5101	Embedded PC	CX1020	
		input 24 V DC,		$I_N=1 \times 1 A$, $P_N=0.8 \text{ kVA}$		Embedded PC, EtherCAT	
		E-bus power supply, 2 A				Terminal integration via	
	EL9110 ES9110	EL9505 ES9505		AX5103		power supply CX1100-0004	
	diagnostic	input 24 V DC,		I _N =1 x 3 A, P _N =2.5 kVA		CX1010	
		output 5 V DC, 0.5 A				Embedded PC, EtherCAT	
	EL9200	EL9508 ES9508		AX5106		Terminal integration via	
	with fuse	input 24 V DC,		$I_N=1 \times 6 A$, $P_N=5 \text{ kVA}$		power supply CX1100-0004	
		output 8 V DC, 0.5 A				CX9000/CX9010	
	EL9210	EL9510 ES9510		AX5112		Embedded PC, with directly	
	diagnostic, with fuse	input 24 V DC,		I _N =1 x 12 A, P _N =10 kVA		integrated E-bus interface	
		output 10 V DC, 0.5 A					
		EL9512 ES9512		AX5201	Fieldbus Box	IL230x-B110	
		input 24 V DC,		$I_N=2 \times 1 A$, $P_N=1.6 \text{ kVA}$		IP 67 Coupler Box with	
		output 12 V DC, 0.5 A				EtherCAT interface	
		EL9515 ES9515		AX5203			
		input 24 V DC,		$I_N=2 \times 3 A$, $P_N=5 kVA$	PCI Ethernet	FC9001	
		output 15 V DC, 0.5 A				1-channel PCI	
	EL9520 ES9520			AX5206		Ethernet card	
	AS-Interface potential			$I_N=2 \text{ x 6 A, } P_N=10 \text{ kVA}$		FC9002	
	supply with filter					2-channel PCI	
		EL9560 ES9560				Ethernet card	
		input 24 V DC,		AX20xx-B110		FC9004	
		output 24 V DC,		Servo Drive with		4-channel PCI	
		0.5 A with electrical isolation		EtherCAT interface		Ethernet card	
						FC9051/FC9151	
120 230 V	EL9150 ES9150					1-channel Mini PCI	
AC	EL9160 ES9160		Servomotors	AM2000		Ethernet card	
	diagnostic			Synchronous Servomotors			
	EL9190 ES9190				Switch	CU2008	
	any voltage up to 230 V			AM3000		Ethernet Switch	
	without LED			Synchronous Servomotors		with 8 ports	
	EL9250					CU2016	
	with fuse			ALxxxx		Ethernet Switch	
	EL9260			Linear Servomotors		with 16 ports	
	diagnostic, with fuse						

EtherCAT system overview









FIELDBUS BOX

The compact IP 67 modules



The Fieldbus Box

A number of considerations led, years ago, to the introduction of the fieldbus systems: The first target was a reduction in the quantity of wiring. Simplified system diagnostics, enabled by intelligent field devices that could send detailed information about malfunctions and errors quickly to the controller, came later. Finally the field devices were given controller functionality for distributed data pre-processing and for simple control tasks.

The Beckhoff Fieldbus Box system is the culmination of the fieldbus concept:

Robust

Robust construction allows fieldbus modules to be fitted directly to machines. Control cabinets and terminal boxes are now no longer required.

Sealed

The modules meet the protection class IP 65, IP 66 or IP 67, are fully casted and thus ideally prepared for use in wet, dirty and dusty working environments.

Small

The modules are extremely small, and are thus suitable for use in applications where there is very little space available. The low weight of the Fieldbus Box modules makes them useful in applications where the I/O interface is in motion (e.g. on a robot arm).

Open

All the most important fieldbus systems are supported. This substantially frees electrical design from the particular bus system in use. Fast, flexible reactions to customers' requirements are possible. The Fieldbus Box modules are, of course, certified by the respective

fieldbus user organisations, and can be combined with Beckhoff Bus Terminals and with devices from third-party manufacturers.

Modular

Extension modules allow the Coupler Box modules to be inexpensively extended.

Quickly wired

The wiring of the fieldbus and of signals is significantly simplified through the use of pre-assembled cables. Wiring errors are minimised, and the system setup is finished quickly.

Flexible

In addition to the pre-assembled cables, field wireable connectors and cables are also available for maximum flexibility.

Economical

Combined I/O modules and fine signal granularity lead to low system costs – you only have to buy what you really need.

Complete

The wide variety of signal types allows the connection of almost any kind of sensor. The communication modules enable decentralised connection of, e.g., label printers, identification systems or special equipment. The

Fieldbus Box range also includes encoder interfaces for displacement and angle measurement.

Fitting

Sensors and actuators are connected through 8 mm diameter snap type or through screw type connectors (M8 or M12). The snap type connectors lock in place positively, forming a vibrationproof connection, while the screw type connectors offer the advantage of high resistance to being pulled out.

Compatible

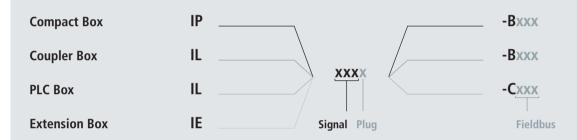
The Fieldbus Box devices behave very much like the Beckhoff Bus Terminals — this means that the ideal distributed peripheral device can be used, whatever the particular application.

Intelligent

Even the standard modules are intelligent fieldbus devices — with self-diagnosis and versatile functions. The Fieldbus Box is furthermore available as a small local controller — the PLC Box. Programmable in all five languages in accordance with IEC 61131-3, with floating point arithmetic and with sufficient performance and memory for the majority of decentralised control and regulation tasks.



The Fieldbus Box: 4 device classes, 9 fieldbuses, 24 signal types, 3 connection options



The system is composed of 4 device classes:

- Compact Box: rugged signal variety for almost any bus system (IPxxxx-Bxxx)
- Coupler Box: bus module with IP-Link extension interface (IL230x-Bxxx)
- PLC Box:
 IEC 61131-3 intelligence in the smallest amount of space, with IP-Link (IL230x-Cxxx)
- Extension Box: for all signal types, connectable over IP-Link (IExxxx)

3 connection options:

- 8 mm: connector 8 mm, snap type, 3 pins
- M8: connector M8, screw type, 3 pins
- M12: connector M12, screw type, 5 pins







Digital I/O				
Input		8 mm	M8	M12
24 V DC	8-channel	IP1000-Bxxx	IP1001-Bxxx	IP1002-Bxxx
•	filter 3.0 ms	IE1000	IE1001	IE1002
	8-channel	IP1010-Bxxx	IP1011-Bxxx	IP1012-Bxxx
	filter 0.2 ms	IE1010	IE1011	IE1012
Counter	2-channel			IP1502-Bxxx
	up/down counter			IE1502
	24 V DC, 100 kHz			
Output		8 mm	M8	M12
24 V DC	8-channel	IP2000-Bxxx	IP2001-Bxxx	IP2002-Bxxx
	I _{MAX} = 0.5 A	IE2000	IE2001	IE2002
	8-channel	IP2020-Bxxx	IP2021-Bxxx	IP2022-Bxxx
	I _{MAX} = 2 A, ∑ 4 A	IE2020	IE2021	IE2022
	8-channel	IP2040-Bxxx	IP2041-Bxxx	IP2042-Bxxx
	I _{MAX} = 2 A, ∑ 12 A	IE2040	IE2041	IE2042
	16-channel			IE2808
	$I_{MAX} = 0.5 \text{ A, } \sum 4 \text{ A, D-sub socket}$			
PWM	2-channel			IP2512-Bxxx
	PWM, 24 V DC, I _{MAX} = 2.5 A			IE2512
Combi		8 mm	M8	M12
24 V DC	8-channel	IP2300-Bxxx	IP2301-Bxxx	IP2302-Bxxx
	4 input + 4 output	IL2300-Bxxx	IL2301-Bxxx	IL2302-Bxxx
	filter 3.0 ms, IMAX = 0.5 A	IL2300-Cxxx	IL2301-Cxxx	IL2302-Cxxx
		IE2300	IE2301	IE2302
	8-channel, 4 input + 4 output	IP2310-Bxxx	IP2311-Bxxx	IP2312-Bxxx
	filter 0.2 ms, I _{MAX} = 0.5 A	IE2310	IE2311	IE2312
	8-channel, 4 input + 4 output	IP2320-Bxxx	IP2321-Bxxx	IP2322-Bxxx
	filter 3.0 ms, $I_{MAX} = 2 A$, $\sum 4 A$	IE2320	IE2321	IE2322
	8-channel, 4 input + 4 output	IP2330-Bxxx	IP2331-Bxxx	IP2332-Bxxx
	filter 0.2 ms, $I_{MAX} = 2 A$, $\sum 4 A$	IE2330	IE2331	IE2332
	16-channel, combi input/output	IP2400-Bxxx	IP2401-Bxxx	

IE2400

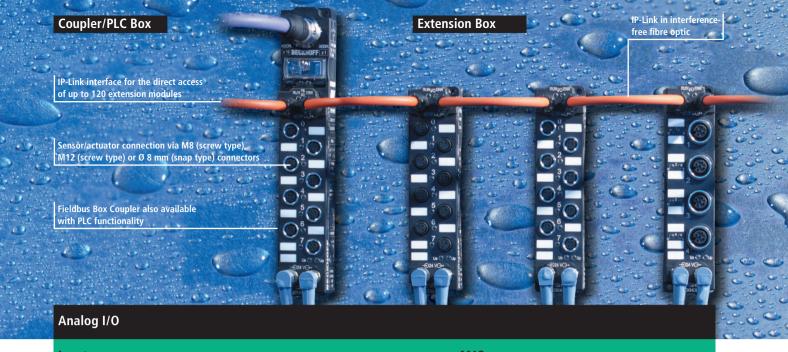
IE2403

(IP 20, snap type)

IE2401

filter 3.0 ms, I_{MAX} = 0.5 A **16-channel**, combi input/output

filter 3.0 ms, $I_{MAX} = 0.5 A$



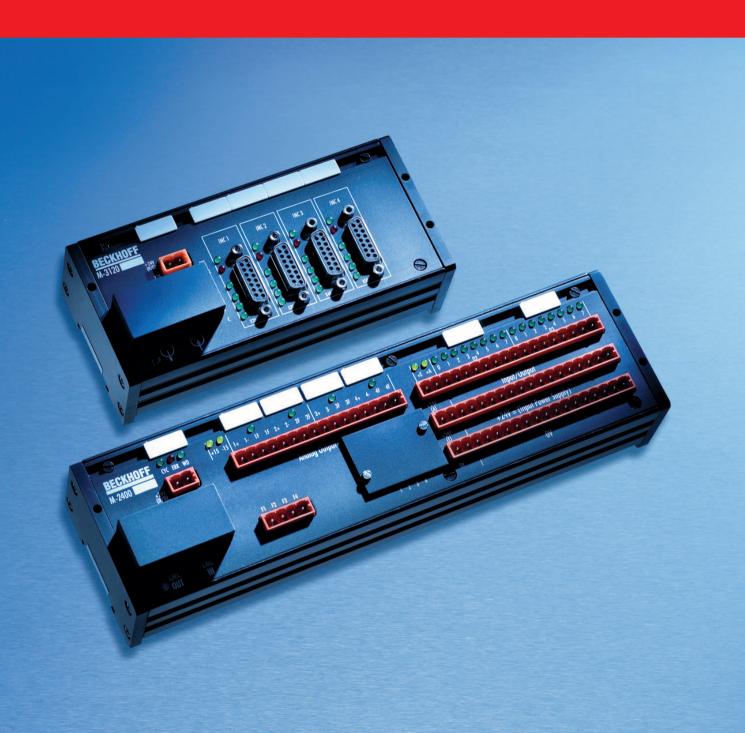
Input		M12
±10 V	4-channel	IP3102-Bxxx
	differential input, 16 bit	IE3102
0/4 20 mA	4-channel	IP3112-Bxxx
	differential input, 16 bit	IE3112
Resistance thermometer	4-channel	IP3202-Bxxx
	resistance thermometer (RTD), PT100, PT200, PT500, PT1000, Ni100, 16 bit	IE3202
Thermocouples	4-channel	IP3312-Bxxx
	thermocouple, type J, K, L, B, E, N, R, S, T, U, 16 bit	IE3312
Output		M12
±10 V	4-channel	IP4132-Bxxx
	16 bit	IE4132
0/4 20 mA	4-channel	IP4112-Bxxx
	16 bit	IE4112

Special functions			
Function		M12	M23
Position measurement	1-channel SSI encoder interface 1-channel incremental encoder interface, 1 MHz 1-channel		IP5009-Bxxx IE5009 IP5109-Bxxx IE5109 IP5209-Bxxx (1 Vss)
Communication	SinCos encoder interface 1-channel serial interface, RS232 1-channel serial interface, 0 20 mA (TTY) 1-channel serial interface, RS422/RS485	IP6002-Bxxx IE6002 IP6012-Bxxx IE6012 IP6022-Bxxx IE6022	IP5209-Bxxx-1000 (11 μAss)
Valve terminal	16-channel Festo valve terminal with IP-Link connection, size 10 mm 16-channel Festo valve terminal with IP-Link connection, size 14 mm 16-channel SMC valve terminal with IP-Link interface	CPV10-VI-IP-8* CPV14-VI-IP-8* EX250*	

^{*} The CPV1x-VI-IP-8 valve terminals can be ordered only from Festo AG & Co. (www.festo.com); the EX250 valve terminals can be ordered only from SMC (www.smceu.com).

LIGHTBUS

The fast fibre optic fieldbus



Interference-free fieldbus communication for fast machine controls

Increasing automation, increasingly complex production equipment, rising demands on speed and communication – this is where conventional cabling and installation technology reaches its limits.

Light up the dark with the Beckhoff Lightbus system by replacing complete cable routes with one single fibre optic conductor. Instead of extensive I/O interfacing units, only one intelligent Beckhoff Lightbus interface board is integrated in the control computer and the decentralised Lightbus modules are directly situated locally.

Installation effort and costs are reduced drastically, handling and maintenance are simplified, and interference immunity and performance are increased.

New ways for control technology with light

The Lightbus was introduced as far back as 1989 as the Beckhoff system bus for fast machine controllers, and has become the market leader in many sectors. These include, for instance, production machines for windows, wood processing machines, presses, packaging machines, machine tools, and applications in metrology and technical building services.

Fast and failsafe industrial communication

The Beckhoff Lightbus system is a fast and failsafe serial fieldbus system that was conceived for the needs of automation technology. Low-cost and easy-to-process standard fibre optic conductor technology is used for transmission. The crucial advantages of the fibre optic conductor are interference immunity to electromagnetic influences, complete electrical isolation of connected modules from one another and a high data transfer rate. In conjunction with an optimised, compact telegram structure, the Lightbus permits a very high user information data transfer rate of up to 2.5 Mbits/s.

With one Lightbus interface board, up to 255 decentralised modules can be operated with a maximum distance of up to 300 m between two modules.

Reliability and flexibility

Reliability is a must — with efficient test and diagnostic functions, functioning of the individual Lightbus modules and communication in the entire Lightbus ring are monitored cyclically and automatically.

Changes or additions to a system configuration can be realized easily and reliably by means of configuration programs in the Lightbus system.

Lightbus features

- 2.5 Mbaud data rate
- 25 µs transmission time for 32 bits of user information
- intelligent commands for read, write, address initialisation, configuration and line test, communication is executed automatically
- up to 255 I/O modules in one ring with up to 65,280 I/O points (e. g. 64 x 4-channel Bus Terminals x 255)
- up to 300 m transmission distance between two I/O modules with HCS fibre, 45 m using PMMA fibre

Lightbus - a system for the future

The Lightbus system is open and universally applicable. Lightbus interfaces are available for common bus and computer architectures, from the standard PC up to VME computers, and for control systems in use around the world.

The wide range of distributed Lightbus components cover the requirements found in automation technology for items from displacement sensors, through universal Bus Terminals up to drive controllers:

- Interface Cards for all common bus standards
- Embedded PC
 the system for control tasks in the medium performance range
- Bus Terminal the modular fieldbus system for automation
- Modules
 the robust modules for fast,
 interference-free communication
- Fieldbus Box the compact modules in protection class IP 67
- Drive Technology
 Digital Compact Servo Drives for dynamic positioning tasks
- TwinCAT the automation software for PLC and Motion Control tasks



PRODUCT OVERVIEW LIGHTBUS

Lightbus					
Interface Car	'ds	Embedded Po	С	Bus Terminal	
PCI bus	FC2001 1-channel FC2002 2-channel	Master	CX1500-M200	Bus Coupler	BK2000 Standard BK2010 "Economy" BK2020 "Economy plus" BK2500
ISA bus	C1200	Slaves	CX1500-B200	PLC	Standard, RS485 BC2000
VME bus	with communication processor			Bus Terminals Digital I/O	KL1xxx KS1xxx digital input KL2xxx KS2xxx
				Analog I/O	KL3xxx KS3xxx analog input KL4xxx KS4xxx analog output
				Special functions	KL5xxx KS5xxx angle and displacement measurement KL6xxx KS6xxx communication
				Power terminals System terminals	KL8xxx power terminals KL9xxx KS9xxx system terminals





Fieldbus Box		Modules	Drive Technology		
Compact Box	IPxxxx-B200	Interface	M1200, M1210	Servo Drive	AX2003-B200
		module	CMOS interface	with Lightbus	In=3 A, Pn=2 kVA
				interface	AX2006-B200
		Digital I/O	M1110		In=6 A, Pn=4.2 kVA
			16-channel digital I/O		AX2010-B200
			(configurable), 24 V DC, 0.5 A, IP 65		In=10 A, Pn=7 kVA
			M1400, M1410		AX2020-B200
Coupler Box	IL230x-B200		16/32-channel digital I/O		In = 20 A, Pn = 14 kVA
			(configurable), 24 V DC, 0.5 A		AX2040-B200
					In=40 A, Pn=30 kVA
		Combi I/O	M2400		AX2070-B200
			16-channel digital I/O, 24 V DC, 0.5 A,		In = 70 A/80 A, Pn = 50 kVA
			4-channel analog output, 12 bits		AX2503-B200
					master module
Extension	IExxxx	Analog input	M2510		$I_N=3$ A, $P_N=7$ kVA
Вох			4-channel analog input, 12 bits		AX2506-B200
					master module
		Special	M3000		$I_N=6$ A, $P_N=7$ kVA
		functions	absolute encoder, 24 bits		AX2513-B200
			M3100		master module
			incremental encoder interface,		$I_N = 3 \text{ A, } P_N = 12 \text{ kVA}$
			24 bits, IP 65		AX2516-B200
			M3120		master module
			incremental encoder interface,		In=6 A, Pn=12 kVA
			1–4-channel, 24 bits		AX2523-B200
			M3200		axes module
			incremental encoder,		In = 3 A
			24 bits, IP 65		AX2526-B200
					axes module
		Operation	M63x0		In = 6 A
		panels	built-in panel, aluminium	Servomotors	AM2000
			or plastic housing		Synchronous Servomotors
					AM3000
					Synchronous Servomotors
					AL2000
					Linear Servomotors

PC FIELDBUS CARDS, SWITCHES

The intelligent interface generation



PC Fieldbus Cards with PCI interface and Ethernet Switches

Beckhoff completes the company's offer of fieldbus components with the PCI-based PC Fieldbus Cards for Lightbus, PROFIBUS, CANopen, DeviceNet, SERCOS interface and Ethernet. The cards have been particularly developed for fast controls and for real-time tasks such as drive position control, and can therefore be applied to a wide range of applications. To enable universal application, the interface cards are fitted with either one or two fieldbus channels. The Ethernet variant FC9004 contains four channels altogether.

Ethernet is a standard communication medium for automation technology. Beckhoff expands this segment with powerful PCI Ethernet cards and Ethernet Switches. The Ethernet components supplement the Beckhoff system solutions, for example for EtherCAT applications, but they can also be used wherever robust industrial technology is required, independent of the automation of IT applications.

Maximum performance from fieldbus to PCI bus

The power of the Fieldbus Cards can be most easily seen in combination with the TwinCAT software PLC and NC. But other applications also benefit from the intelligent PCI cards that handle the fieldbus protocol efficiently on their own processors. The process image is available in the DPRAM interface to the PC. Drivers for Windows NT/2000/XP and convenient configuration tools are included in the TwinCAT I/O software package. High-level language programs use the DLL, Visual Basic applications the ActiveX interface. Applications with OPC interface can access process data and parameters via an OPC server.

All cards are characterised by concentrated fieldbus know-how in the form of the following features:

- fast data exchange through short cycle times (e. g. Lightbus: to 100 μs)
- process data communication is either free running, synchronised, synchronised with delay or equidistant
- powerful parameter and diagnostics interfaces
- freely configurable bus management for every device

Consolidated fieldbus know-how

New Mini PCI cards for PROFIBUS, CANopen, DeviceNet, SERCOS interface and Ethernet enhance the Beckhoff PC Fieldbus Card range. Like the standard PCI cards from Beckhoff, the interfaces are optimised for fast controllers and real-time tasks.

The new generation of Beckhoff Industrial PCs, including the C69xx control cabinet PCs and the CP62xx/CP66xx Control Panel PCs, are extremely compact. With each device featuring two Ethernet ports, they represent high-performance Industrial PCs for Ethernet and EtherCAT-based control applications. The IPCs can optionally be extended with Mini PCI cards, or with fieldbus technology.

Ethernet Switches

The Beckhoff Ethernet Switches offer 8/16 RJ 45 Ethernet ports. Switches relay incoming Ethernet frames to the destination ports. In full duplex mode, they prevent collisions. They can be used universally in automation and office networks. User-friendly installation via integrated DIN rail adapter.

The switches meet the special requirements of real-time-capable industrial

Ethernet solutions through several outstanding features:

- optional broadcast filtering supports the integration of any Ethernet devices in real-time environments
- optional packet-based or port-based prioritisation (QoS, VLAN)

Further benefits underline the particular suitability for the application in industrial environments:

- compact design in stainless steel housing
- 10/100 Mbaud, half or full duplex, with automatic baud rate detection
- cross-over detection: automatic detection and correction of crossover and straight-through Ethernet cables
- clear LED field for quick diagnosis,
 3 LEDs for each Ethernet port
- fast DIN rail mounting
- industrial design







FCxxxx | **PC Fieldbus Cards**

ieldbus	1-channel	2-channel	4-channel
IGHT BUS	FC2001-0000 (PCI interface)	FC2002-0000 (PCI interface)	
рвови°	FC3101-0000 (PCI interface)	FC3102-0000 (PCI interface)	
BUS	FC3101-0002 (PCI interface)	FC3102-0002 (PCI interface)	
	configuration with 32 kbytes NOVRAM	configuration with 32 kbytes NOVRAM	
	FC3151-0000 (Mini PCI interface)		
	FC3151-0002 (Mini PCI interface)		
	configuration with 128 kbytes NOVRAM		
CANopen	FC5101-0000 (PCI interface)	FC5102-0000 (PCI interface)	
	FC5101-0002 (PCI interface)	FC5102-0002 (PCI interface)	
	configuration with 32 kbytes NOVRAM	configuration with 32 kbytes NOVRAM	
	FC5151-0000 (Mini PCI interface)		
	FC5151-0002 (Mini PCI interface)		
	configuration with 128 kbytes NOVRAM		
Device Net	FC5201-0000 (PCI interface)	FC5202-0000 (PCI interface)	
3 0 7 10 C. 10 C	FC5201-0002 (PCI interface)	FC5202-0002 (PCI interface)	
	configuration with 32 kbytes NOVRAM	configuration with 32 kbytes NOVRAM	
	FC5251-0000 (Mini PCI interface)		
	FC5251-0002 (Mini PCI interface)		
	configuration with 128 kbytes NOVRAM		
SERÇOS	FC7501-0000 (PCI interface)	FC7502-0000 (PCI interface)	
interface	FC7551-0000 (Mini PCI interface)		
	FC7551-0002 (Mini PCI interface)		
	configuration with 128 kbytes NOVRAM		
Ethernet	FC9001-0000 (PCI interface)	FC9002-0000 (PCI interface)	FC9004-0000 (PCI interface)
	FC9051-0000 (Mini PCI interface)		
	FC9151-0000 (Mini PCI interface)		





CU20xx | Ethernet Switches

Switches		
Technical data	CU2008	CU2016
Bus system	all Ethernet (IEEE 802.3) based protocols, store-and-forward switching mode	all Ethernet (IEEE 802.3) based protocols, store-and-forward switching mode
Number of Ethernet ports	8	16
Ethernet interface	10BASE-T/100BASE-TX Ethernet with 8 x RJ 45	10BASE-T/100BASE-TX Ethernet with 16 x RJ 45
Cable length	up to 100 m twisted pair	up to 100 m twisted pair
Baud rate	10/100 Mbit/s, IEEE 802.3u auto-negotiation, half or full duplex at 10 and 100 Mbit/s possible, automatic settings	10/100 Mbit/s, IEEE 802.3u auto-negotiation, half or full duplex at 10 and 100 Mbit/s possible, automatic settings
Hardware diagnostics	2 LEDs per channel (link/activity, 10/100 Mbit)	2 LEDs per channel (link/activity, 10/100 Mbit)
Operating temperature	0 °C +55 °C	0 °C +55 °C
Dimensions (W x H x D)	approx. 85 mm x 100 mm x 30 mm	approx. 146 mm x 100 mm x 30 mm
Power supply	24 (1830) V DC, 100 mA, 3-pin cage clamp® connection (+,-,PE)	24 (1830) V DC, 150 mA, 3-pin cage clamp® connection (+,-,PE)





DRIVE TECHNOLOGY

The drive system for high dynamic positioning tasks



Beckhoff Drive Technology

In combination with the Motion Control solutions offered by the TwinCAT automation software, Beckhoff Drive Technology represents an advanced complete drive system. PC-based control technology from Beckhoff is ideally suited for single and multiple axis positioning tasks with highly dynamic requirements. The AX5000 Servo Drive series with high-performance EtherCAT system communication offers maximum performance and dynamics.

TwinCAT offers comprehensive NC and CNC functionalities.

Associated PLC libraries and engineering tools round off the software solution.

The complete Drive Technology solution from Beckhoff consists of:

- Compact Servo Drives AX5000, AX2000, AX2500,
- Synchronous Servomotors AM2000, AM3000,
- Linear Servomotors AL2000, AL2400, AL2800, AL3800,
- Stepper Motors AS1000,
- and a comprehensive range of accessories.

Beckhoff's open control technology is consistently continued into the drive unit. Fieldbus standards such as EtherCAT, Ethernet, PROFIBUS, CANopen, DeviceNet, SERCOS interface or Lightbus enable the drives to be integrated into complex systems.

AX5000 – the new drive generation

The AX5000 Servo Drive product line from Beckhoff sets new standards in Drive Technology. The AX5000 series is available in single- or multi-channel form and is optimised in terms of function and cost-effectiveness. The integrated, fast control technology with a current control cycle of up to 31.25 μs supports fast and highly dynamic positioning tasks. EtherCAT as high-performance system communication enables ideal interfacing with PC-based control technology and supports coupling with other communication systems.

The AX51xx 1-channel Servo Drives are designed for rated motor currents up to 12 A (further variants up to 75 A are in preparation). The AX52xx 2-channel Servo Drive enables operation of two motors with identical or even with different capacity, up to a total current of 12 A. The multi-axis drives with variable motor output allocation optimise packaging density and the cost per drive channel.

The AX5000 is very flexible with regard to motor types: A wide range of motor sizes and types can be connected without additional measures. Examples include synchronous, linear, torque or asynchronous motors. The multi-feedback interface supports all common standards. Several AX5000 devices can be connected easily and quickly to form a multi-axis system using the "AX-Bridge" quick connection system.

AX5000 features:

- high-speed EtherCAT system communication
- 1- or 2-channel Servo Drive
 - optimised for multi-axis applications
 - variable motor output allocation in 2-channel drives
- active DC link and brake energy management
- variable motor interface with:
 - multi-feedback interface
 - flexible motor type selection
 - scalable, wide range motor current measurement
- high-speed capture inputs
- wide voltage range 100 ... 480 V AC ±10 % (class C3)
- integrated mains filter
- integration of safety functions (optional):
 - restart lock
 - TwinSAFE: intelligent safety functions for Motion Control
- compact design for simple control cabinet installation (300 mm depth)
- AX-Bridge the quick connection system for power supply, DC link and control voltage
- variable cooling concept (fanless, forced cooling, cold plate)

Servo Drives AX2000/AX2500

The AX2000 and AX2500 series complement the compact Servo Drive segment with two types: The AX2000 series is a powerful variant designed for a nominal current of up to 20 A. The AX2500 series Servo Drives are modularly expandable and are optimised for applications where space is tight. The maximum nominal current is 6 A.

Servomotors AM2000, AM3000

The Synchronous Servomotors are brushless, three-phase motors meeting DIN 42950, and are equipped with permanent magnets in the rotor. This high quality neodymium magnetic material makes a significant contribution to the motors' exceptional dynamic properties. The AM2000 motors feature angled connectors (up to 90°) for the power supply and the feedback signals. The AM3000 features continuously rotatable connectors. Beckhoff offers resolver, encoder and power leads as ready-assembled accessories in different lengths.

Linear Servomotors ALxxxx

The three-phase Linear Servomotors from the AL2000, AL2400, AL2800 and AL3800 series complement the motor range. The linear motors can be used wherever the rotary design reaches mechanical limits during installation or where special drive characteristics in terms of dynamics, synchronism or acceleration are required.





AX51xx | Digital Compact Servo Drives

Technical data	AX5101	AX5103	AX5106	AX5112
Rated output current	1 x 1 A	1 x 3 A	1 x 6 A	1 x 12 A
Min. rated motor current at full current resolution	0.35 A	1 A	1 A	6 A
Rated supply voltage	1 x 100 3 x 480 V AC ±10 %, 50 60 Hz	1 x 100 3 x 480 V AC ±10 %, 50 60 Hz	1 x 100 3 x 480 V AC ±10 %, 50 60 Hz	1 x 100 3 x 480 V AC ±10 %, 50 60 Hz
DC link voltage	0790 V DC	0790 V DC	0790 V DC	0790 V DC
Peak output current (1)	3 A	9 A	13 A	26 A
Rated connected load for S1 operation	0.8 kVA	2.5 kVA	5 kVA	10 kVA
Continuous braking power (2)	50 W	50 W	150 W	50 W
Max. braking power ⁽²⁾	2.8 kW	2.8 kW	2.8 kW	2.8 kW
System bus	EtherCAT	EtherCAT	EtherCAT	EtherCAT
Height without plugs	266 mm	266 mm	266 mm	266 mm
Width	92 mm	92 mm	92 mm	92 mm
Depth without plugs	233 mm	233 mm	233 mm	233 mm
Weight	4.0 kg	4.0 kg	5.0 kg	5.0 kg

⁽¹⁾ RMS for max. 7 seconds

⁽²⁾ internal brake resistor



AX52xx | Digital Compact Servo Drives

Technical data	AX5201	AX5203	AX5206
Rated output current	2 x 1 A	2 x 3 A	2 x 6 A
Min. rated motor current at full current resolution	0.35 A	1 A	1 A
Max. rated channel current at full current resolution	2 A	6 A	9 A
Rated supply voltage	1 x 100 3 x 480 V AC ±10 %, 50 60 Hz	1 x 100 3 x 480 V AC ±10 %, 50 60 Hz	1 x 100 3 x 480 V AC ± 10 %, 50 60 Hz
DC link voltage	0790 V DC	0790 V DC	0790 V DC
Peak output current (1)	2 x 3 A	2 x 9 A	2 x 13 A
Rated connected load for S1 operation	1.6 kVA	5 kVA	10 kVA
Continuous braking power ⁽²⁾	50 W	150 W	50 W
Max. braking power (2)	2.8 kW	2.8 kW	2.8 kW
System bus	EtherCAT	EtherCAT	EtherCAT
Height without plugs	318 mm	318 mm	318 mm
Width	92 mm	92 mm	92 mm
Depth without plugs	266 mm	266 mm	266 mm
Weight	5.0 kg	6.0 kg	6.0 kg

⁽¹⁾ RMS for max. 7 seconds



⁽²⁾ internal brake resistor



AX20xx | Digital Compact Servo Drives

Technical data	AX2003	AX2006	AX2010	AX2020	AX2040	AX2070
Rated output current	3 A	6 A	10 A	20 A	40 A	70 A/80 A
Rated supply voltage	3x (230 480) V					
	AC ±10%,					
	50 60 Hz					
Rated installed load	2 kVA	4.2 kVA	7 kVA	14 kVA	30 kVA	50 kVA
for S1 operation						
Rated intermediate	(310-675) V DC					
circuit DC voltage						
Rated output current	3 Arms	6 Arms	10 Arms	20 Arms	40 Arms	70 Arms /80 Arms
(rms value 3%)						
Peak output current	6 Arms	12 Arms	20 Arms	40 Arms	80 Arms	140 Arms /160 Arms
(max. approx. 5 s 3 %)						
Continuous output of	80 W	200 W	200 W	200 W	_	-
regen circuit (RBint)						
Continuous output of	250 W	750 W	750 W	750 W	6 kW	6 kW
regen circuit (RBext) max.						
Weight	4 kg	4 kg	5 kg	7.5 kg	19.5 kg	21 kg
Height	275 mm	275 mm	275 mm	275 mm	495 mm	495 mm
without connectors						
Width	70 mm	70 mm	70 mm	120 mm	250 mm	250 mm
Depth	265 mm	265 mm	265 mm	265 mm	300 mm	300 mm
without connectors						

Drive Techno

Fieldbus-Connectivity	EtherCAT.	LIGHTBUS	PROFU°	CANopen	Device Net	## SERCOS	RS232 RS485	Ethernet
Interface AX2000	-B110	-B200	-B310	on-board	-B520	-B750	on-board	-B900



AX25xx | Digital Compact Servo Drives

	AX2503	AX2506	AX2513	AX2516	AX2523	AX2526
Technical data						
Function	master module	master module	master module	master module	axis module	axis module
Rated output current	3 A	6 A*	3 A	6 A*	3 A	6 A*
Rated supply voltage	1 x 115 1/3 x	1 x 115 1/3 x	3 x (230 400)	3 x (230 400)	-	-
	230 V AC ±10 %,	230 V AC ±10 %,	V AC ±10 %,	$VAC \pm 10\%$,		
	50 60 Hz	50 60 Hz	50 60 Hz	50 60 Hz		
Maximum installed	7 kVA	7 kVA	12 kVA	12 kVA	-	-
power for S1 operation						
multi-axis systems						
Rated DC-link voltage	(160 – 310) V DC	(160 – 310) V DC	(310 – 560) V DC	(310 – 560) V DC	(160 – 560) V DC	(160 – 560) V DC
Rated output current	3 A _{rms}	6 Arms*	3 Arms	6 Arms*	3 A _{rms}	6 Arms*
(rms value 3%)						
Peak output current	9 A _{rms}	12 A _{rms} *	9 A _{rms}	12 A _{rms} *	9 Arms	12 A _{rms} *
(max. approx. 5 s 3 %)						
Continuous output	40 W	40 W	40 W	40 W	-	-
of regen circuit (RBint)						
Height	230 mm	267 mm*	230 mm	267 mm*	230 mm	267 mm*
without connectors						
Width	100 mm	100 mm	100 mm	100 mm	50 mm	50 mm
Depth	240 mm	240 mm	240 mm	240 mm	240 mm	240 mm
without connectors						

^{*} with attached fan

Fieldbus-Connectivity	LIGHTBUS	PROFII°	CANopen	Device Net		RS232 RS485	Ethernet
Interface AX2500	-B200	-B310	-B510	on request	-B750	on-board	-B900







AM2xxx | Synchronous Servomotors

AM2000-wxyz	Standstill torque	Standstill current	Rated speed at ra	ited supply voltage	Rotor moment of inertia	Weight
AM217S-0000	0.1 Nm	0.6 A	6000 min ⁻¹	-	0.06 kg cm ²	0.7 kg
AM217M-0000	0.2 Nm	0.93 A	6000 min ⁻¹	-	0.12 kg cm ²	0.8 kg
AM217S-2000	0.1 Nm	0.6 A	6000 min ⁻¹	-	0.06 kg cm ²	0.7 kg
AM217M-2000	0.2 Nm	0.93 A	6000 min ⁻¹	-	0.12 kg cm ²	0.8 kg
AM227M-0000	0.32 Nm	0.8 A	-	4000 min ⁻¹	0.08 kg cm ²	1.1 kg
AM227M-0001	0.32 Nm	0.8 A	-	4000 min ⁻¹	0.15 kg cm ²	1.4 kg
AM227L-0000	0.8 Nm	0.83 A	-	4500 min ⁻¹	0.13 kg cm ²	1.5 kg
AM227L-0001	0.8 Nm	0.83 A	-	4500 min ⁻¹	0.2 kg cm ²	1.8 kg
AM237S-0000	0.5 Nm	1 A	-	6000 min ⁻¹	0.45 kg cm ²	1.9 kg
AM237S-0001	0.5 Nm	1 A	-	6000 min ⁻¹	0.83 kg cm ²	2.3 kg
AM237M-0000	1 Nm	1.6 A	-	6000 min ⁻¹	0.7 kg cm ²	2.3 kg
AM237M-0001	1 Nm	1.6 A	-	6000 min ⁻¹	1.08 kg cm ²	2.7 kg
AM237L-0000	1.5 Nm	1.6 A	-	4000 min ⁻¹	1 kg cm²	2.9 kg
AM237L-0001	1.5 Nm	1.6 A	-	4000 min ⁻¹	1.38 kg cm ²	3.3 kg
AM247M-0000	2.5 Nm	1.78 A	-	3000 min ⁻¹	1.4 kg cm ²	3.3 kg
AM247M-0001	2.5 Nm	1.78 A	_	3000 min ⁻¹	1.78 kg cm ²	3.7 kg
AM247L-0000	3 Nm	2.3 A	-	3000 min ⁻¹	1.6 kg cm ²	3.5 kg
AM247L-0001	3 Nm	2.3 A	-	3000 min ⁻¹	1.98 kg cm ²	3.9 kg
AM257K-0000	2.6 Nm	1.9 A	-	3000 min ⁻¹	2.1 kg cm ²	4.5 kg
AM257K-0001	2.6 Nm	1.9 A	-	3000 min ⁻¹	3.16 kg cm ²	5.25 kg

AM2000-wxyz	Standstill	Standstill	Rated speed	at rated supply voltag	ge Rotor moment	Weight
Alvi2000-wxy2	torque	current	230 V AC	400/480 V AC	of inertia	
AM257S-0000	4.6 Nm	2.8 A	-	3000 min ⁻¹	3.1 kg cm ²	5.7 kg
AM257S-0001	4.6 Nm	2.8 A	-	3000 min ⁻¹	4.16 kg cm ²	6.3 kg
AM257M-0000	8 Nm	4.3 A	-	3000 min ⁻¹	4.5 kg cm ²	7.6 kg
AM257M-0001	8 Nm	4.3 A	-	3000 min ⁻¹	5.56 kg cm ²	8.2 kg
AM257L-0000	9.5 Nm	6.1 A	-	3000 min ⁻¹	6.5 kg cm ²	8.7 kg
AM257L-0001	9.5 Nm	6.1 A	-	3000 min ⁻¹	7.56 kg cm ²	9.45 kg
AM277K-0000	11 Nm	6 A	-	3000 min ⁻¹	12 kg cm²	9.8 kg
AM277K-0001	11 Nm	6 A	-	3000 min ⁻¹	15.6 kg cm ²	11.3 kg
AM277S-0000	17 Nm	10 A	-	3000 min ⁻¹	18 kg cm²	14 kg
AM277S-0001	17 Nm	10 A	-	3000 min ⁻¹	21.6 kg cm ²	15.5 kg
AM277M-0000	22 Nm	13.7 A	-	3000 min ⁻¹	13.1 kg cm ²	17 kg
AM277M-0001	22 Nm	13.7 A	-	3000 min ⁻¹	16.7 kg cm ²	18.5 kg
AM297K-0000	26 Nm	16 A	-	3000 min ⁻¹	82 kg cm²	28 kg
AM297K-0001	26 Nm	16 A	-	3000 min ⁻¹	91.5 kg cm ²	31.3 kg
AM297S-0000	32 Nm	20 A	-	3000 min ⁻¹	104 kg cm ²	32.5 kg
AM297S-0001	32 Nm	20 A	-	3000 min ⁻¹	113.5 kg cm ²	35.8 kg
AM297M-0000	40 Nm	23.4 A	-	3000 min ⁻¹	139.4 kg cm ²	40 kg
AM297M-0001	40 Nm	23.4 A	-	3000 min ⁻¹	148.9 kg cm ²	43.3 kg

Option w = 0: smooth shaft

w = 1: shaft with groove and feather key according to DIN 6885, w = 2: connection cable with plug (only for AM217x)

Option x = 0: standard winding

x = 1: special winding

Option y = 0: resolver, 2-pin

y = 1: single-turn absolute encoder, Heidenhain EnDAT absolute position within one revolution, electronic identification plate

AM227x: 512 sine periods per revolution

AM227x: 512 sine periods per revolution

AM237x...AM297x: 2048 sine periods per revolution

y = 2: multi-turn absolute encoder, Heidenhain EnDAT absolute position within 4096 revolutions, electronic identification plate

AM237x...AM297x: 2048 sine periods per revolution

Option z = 0: without stopping brake

z = 1: with stopping brake

special flange, special shaft and other accessories on request







AM30xx | **Synchronous Servomotors**

	Stand-	Stand-	Rated speed	at rated supply	y voltage	Rotor	Weight	Stores	type
AM30uv-wxyz	still	still				moment		Resol-	BiSS
Ambout myr	torque	current	230 V AC	400 V AC	480 V AC	of inertia		ver	SingleTurn
AM3011-wB00	0.18 Nm	1.16 A	8000 min ⁻¹	_	_	0.017 kg cm ²	0.35 kg		
AM3012-wC00	0.31 Nm	1.51 A	8000 min ⁻¹	_	_	0.031 kg cm ²	0.49 kg	L	
AM3013-wC00	0.41 Nm	1.48 A	8000 min ⁻¹	_	_	0.045 kg cm ²	0.63 kg		
AM3021-wCyz	0.48 Nm	1.58 A	8000 min ⁻¹	8000 min ⁻¹	8000 min ⁻¹	0.107 kg cm ²	0.82 kg	L	L
AM3022-wCyz	0.84 Nm	1.39 A	3500 min ⁻¹	8000 min ⁻¹	8000 min ⁻¹	0.161 kg cm ²	1.10 kg	L	L
AM3023-wCyz	1.13 Nm	1.41 A	2500 min ⁻¹	5500 min ⁻¹	7000 min ⁻¹	0.216 kg cm ²	1.38 kg	L	L
AM3023-wDyz	1.16 Nm	2.19 A	5000 min ⁻¹	8000 min ⁻¹	8000 min ⁻¹	0.216 kg cm ²	1.38 kg		
AM3024-wCyz	1.38 Nm	1.42 A	2000 min ⁻¹	4500 min ⁻¹	5500 min ⁻¹	0.270 kg cm ²	1.66 kg		
AM3024-wDyz	1.41 Nm	2.21 A	4000 min ⁻¹	8000 min ⁻¹	8000 min ⁻¹	0.270 kg cm ²	1.66 kg		
AM3031-wCyz	1.15 Nm	1.37 A	2500 min ⁻¹	5000 min ⁻¹	6000 min ⁻¹	0.330 kg cm ²	1.55 kg	L	L
AM3031-wEyz	1.20 Nm	2.99 A	6000 min ⁻¹	6000 min ⁻¹	6000 min ⁻¹	0.330 kg cm ²	1.55 kg		L
AM3032-wCyz	2.00 Nm	1.44 A	1500 min ⁻¹	3000 min ⁻¹	3500 min ⁻¹	0.590 kg cm ²	2.23 kg	L	L
AM3032-wDyz	2.04 Nm	2.23 A	2500 min ⁻¹	5500 min ⁻¹	6000 min ⁻¹	0.590 kg cm ²	2.23 kg	L	L
AM3033-wCyz	2.71 Nm	1.47 A	1000 min ⁻¹	2000 min ⁻¹	2500 min ⁻¹	0.850 kg cm ²	2.90 kg		
AM3033-wEyz	2.79 Nm	2.58 A	2000 min ⁻¹	4500 min ⁻¹	5000 min ⁻¹	0.850 kg cm ²	2.90 kg	L	L
AM3041-wCyz	1.95 Nm	1.46 A	1200 min ⁻¹	3000 min ⁻¹	3500 min ⁻¹	0.810 kg cm ²	2.44 kg	L	L
AM3041-wEyz	2.02 Nm	2.85 A	3000 min ⁻¹	6000 min ⁻¹	6000 min ⁻¹	0.810 kg cm ²	2.44 kg		
AM3042-wEyz	3.42 Nm	2.74 A	1800 min ⁻¹	3500 min ⁻¹	4000 min ⁻¹	1.450 kg cm ²	3.39 kg		
AM3042-wGyz	3.53 Nm	4.80 A	3500 min ⁻¹	6000 min ⁻¹	6000 min ⁻¹	1.450 kg cm ²	3.39 kg	L	L
AM3043-wEyz	4.70 Nm	2.76 A	1500 min ⁻¹	2500 min ⁻¹	3000 min ⁻¹	2.090 kg cm ²	4.35 kg		
AM3043-wGyz	4.80 Nm	4.87 A	2500 min ⁻¹	5000 min ⁻¹	6000 min ⁻¹	2.090 kg cm ²	4.35 kg	L	L
AM3044-wEyz	5.76 Nm	2.90 A	1200 min ⁻¹	2000 min ⁻¹	2500 min ⁻¹	2.730 kg cm ²	5.30 kg		
AM3044-wGyz	5.88 Nm	5.00 A	2000 min ⁻¹	4000 min ⁻¹	5000 min ⁻¹	2.730 kg cm ²	5.30 kg	L	L
AM3044-wJyz	6.00 Nm	8.80 A	4000 min ⁻¹	6000 min ⁻¹	6000 min ⁻¹	2.730 kg cm ²	5.30 kg	L	L
AM3051-wEyz	4.70 Nm	2.75 A	1200 min ⁻¹	2500 min ⁻¹	3000 min ⁻¹	3.420 kg cm ²	4.20 kg	L	
AM3051-wGyz	4.75 Nm	4.84 A	2500 min ⁻¹	5000 min ⁻¹	6000 min ⁻¹	3.420 kg cm ²	4.20 kg	L	L
AM3052-wGyz	8.43 Nm	4.72 A	1500 min ⁻¹	2500 min ⁻¹	3000 min ⁻¹	6.220 kg cm ²	5.80 kg	L	
AM3052-wKyz	8.60 Nm	9.30 A	3000 min ⁻¹	5500 min ⁻¹	6000 min ⁻¹	6.220 kg cm ²	5.80 kg	L	L
AM3053-wGyz	11.37 Nm	4.77 A	1000 min ⁻¹	2000 min ⁻¹	2400 min ⁻¹	9.120 kg cm ²	7.40 kg		
AM3053-wKyz	11.60 Nm	9.40 A	2000 min ⁻¹	4000 min ⁻¹	4500 min ⁻¹	9.120 kg cm ²	7.40 kg	L	L

	Stand-	Stand-	Rated speed	at rated supply	y voltage	Rotor	Weight	Stores	type
AM30uv-wxyz	still	still				moment		Resol-	BiSS
Alvi50uv-wxyz	torque	current	230 V AC	400 V AC	480 V AC	of inertia		ver	SingleTurn
AM3054-wKyz	14.40 Nm	9.70 A	1800 min ⁻¹	3500 min ⁻¹	4000 min ⁻¹	11.92 kg cm ²	9.00 kg		
AM3062-wKyz	12.20 Nm	9.60 A	2000 min ⁻¹	3500 min ⁻¹	4500 min ⁻¹	16.90 kg cm ²	8.90 kg	L	L
AM3062-wMyz	12.20 Nm	13.40 A	3000 min ⁻¹	6000 min ⁻¹	6000 min ⁻¹	16.90 kg cm ²	8.90 kg		
AM3063-wKyz	16.80 Nm	9.90 A	1500 min ⁻¹	3000 min ⁻¹	3500 min ⁻¹	24.20 kg cm ²	11.1 kg		
AM3063-wMyz	17.00 Nm	13.80 A	2000 min ⁻¹	4000 min ⁻¹	4500 min ⁻¹	24.20 kg cm ²	11.1 kg		
AM3063-wNyz	17.00 Nm	17.40 A	3000 min ⁻¹	5000 min ⁻¹	6000 min ⁻¹	24.20 kg cm ²	11.1 kg		
AM3064-wKyz	20.80 Nm	9.20 A	1200 min ⁻¹	2000 min ⁻¹	2500 min ⁻¹	31.60 kg cm ²	13.3 kg		
AM3064-wLyz	21.00 Nm	12.80 A	1500 min ⁻¹	3000 min ⁻¹	3500 min ⁻¹	31.60 kg cm ²	13.3 kg		L
AM3064-wPyz	20.40 Nm	18.60 A	2500 min ⁻¹	4500 min ⁻¹	5500 min ⁻¹	31.60 kg cm ²	13.3 kg		L
AM3065-wKyz	24.80 Nm	9.80 A	1000 min ⁻¹	2000 min ⁻¹	2200 min ⁻¹	40.00 kg cm ²	15.4 kg		
AM3065-wMyz	25.00 Nm	13.60 A	1500 min ⁻¹	2500 min ⁻¹	3000 min ⁻¹	40.00 kg cm ²	15.4 kg		
AM3065-wNyz	24.30 Nm	17.80 A	2000 min ⁻¹	3500 min ⁻¹	4000 min ⁻¹	40.00 kg cm ²	15.4 kg	L	L
AM3072-wKyz	29.70 Nm	9.30 A	-	1500 min ⁻¹	1800 min ⁻¹	64.50 kg cm ²	19.7 kg		
AM3072-wMyz	30.00 Nm	13.00 A	-	2000 min ⁻¹	2500 min ⁻¹	64.50 kg cm ²	19.7 kg		
AM3072-wPyz	29.40 Nm	18.70 A	1800 min ⁻¹	3000 min ⁻¹	3500 min ⁻¹	64.50 kg cm ²	19.7 kg		L
AM3073-wMyz	42.00 Nm	13.60 A	-	1500 min ⁻¹	1800 min ⁻¹	92.10 kg cm ²	26.7 kg		
AM3073-wPyz	41.60 Nm	19.50 A	1300 min ⁻¹	2400 min ⁻¹	2800 min ⁻¹	92.10 kg cm ²	26.7 kg		
AM3074-wLyz	53.00 Nm	12.90 A	-	1200 min ⁻¹	1400 min ⁻¹	119.7 kg cm ²	33.6 kg		
AM3074-wPyz	52.50 Nm	18.50 A	-	1800 min ⁻¹	2000 min ⁻¹	119.7 kg cm ²	33.6 kg		L

u: flange code v: motor length

Option w = 0: smooth shaft

w = 1: shaft with groove and feather key according to DIN 6885

Option x = winding code A ... P

Option y = 0: resolver, 2-pin

y = 1: single-turn absolute encoder, Heidenhain EnDAT
absolute position within one revolution, electronic identification plate
AM301x...AM304x: 512 sine periods per revolution
AM305x...AM307x: 2048 sine periods per revolution

y = 2: multi-turn absolute encoder, Heidenhain EnDAT
absolute position within 4096 revolutions, electronic identification plate
AM301x...AM304x: 512 sine periods per revolution
AM305x...AM307x: 2048 sine periods per revolution

y = 3: single-turn absolute encoder, Hengstler BiSS absolute position within one revolution, electronic identification plate, 2048 sine periods per revolution

y = 4: multi-turn absolute encoder, Hengstler BiSS absolute position within 4096 revolutions, electronic identification plate, 2048 sine periods per revolution

Option z = 0: without stopping brake z = 1: with stopping brake

special flange, special shaft and other accessories on request



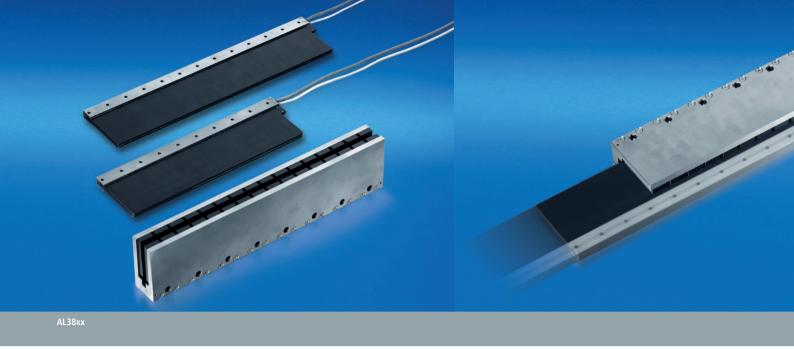


AL20xx, AL24xx, AL28xx | Linear Servomotors, iron core

AL20xx	Peak force	Peak current	Thermal	Weight	Motor length	Motor width	
ALZUAA	3 sec. (F _{peak})	(I _{peak})	resistance (Rth)	of the coil (M _p)			
AL2003 (primary sec.)	225 N	5 A	0.96 °C/W	0.9 kg	98 mm	77 mm	
AL2006 (primary sec.) N S	450 N	5 A 10 A	0.48 °C/W	1.5 kg	146 mm	77 mm	
AL2012 (primary sec.) N S	900 N	10 A 20 A	0.24 °C/W	2.6 kg	244 mm	77 mm	
AL2015 (primary sec.) N S	1125 N	10 A 25 A	0.20 °C/W	3.2 kg	290 mm	77 mm	
AL2024 (primary sec.) N S	1800 N	20 A 40 A	0.12 °C/W	5.1 kg	468 mm	77 mm	
AL2030 (primary sec.) N S	2250 N	20 A 50 A	0.10 °C/W	6.3 kg	562 mm	77 mm	
AL2110 (secondary section)	magnetic assembly	magnetic assembly 192 mm (magnetic path width 80 mm)					
AL2120 (secondary section)	magnetic assembly	nagnetic assembly 288 mm (magnetic path width 80 mm)					

AL24xx	Peak force 3 sec. (F _{peak})	Peak current	Thermal resistance (R _{th})	Weight of the coil (M _P)	Motor length	Motor width
AL2403 (primary sec.)	120 N	3.9 A	1.4 °C/W	0.55 kg	93 mm	51 mm
AL2406 (primary sec.)	240 N	7.9 A	0.7 °C/W	0.9 kg	143 mm	51 mm
AL2510 (secondary section)	magnetic assembly	magnetic assembly 96 mm (magnetic path width 50 mm)				
AL2520 (secondary section)	magnetic assembly 144 mm (magnetic path width 50 mm)					
AL2530 (secondary section)	magnetic assembly 384 mm (magnetic path width 50 mm)					

AL28xx	Peak force 3 sec. (F _{peak})	Peak current (I _{peak})	Thermal resistance (Rth)	Weight of the coil (M _P)	Motor length	Motor width
AL2815 (primary sec.) N S	2250 N	13 A 33 A	0.13 °C/W	6 kg	290 mm	130 mm
AL2830 (primary sec.) N S	4500 N	26 A 66 A	0.065 °C/W	12 kg	568 mm	130 mm
AL2845 (primary sec.) N S	6750 N	39 A 99 A	0.043 °C/W	19 kg	847 mm	130 mm
AL2910 (secondary section)	magnetic assembly 192 mm (magnetic path width 130 mm)					
AL2920 (secondary section)	magnetic assembly	magnetic assembly 288 mm (magnetic path width 130 mm)				



AL38xx | Linear Servomotors, ironless

AL3930 (secondary section) magnet yoke 456 mm (magnet yoke width 48 mm)

AL38xx	Peak force	Peak current	Thermal	Weight	Motor length	Motor width	
71230707	3 sec. (F _{peak})	(I _{peak})	resistance (Rth)	of the coil (M _P)			
AL3803 (primary sec.) N S	700 N	5.6 A 13.9 A	1.04 °C/W	1.5 kg	134 mm	15 mm	
AL3806 (primary sec.) N S	1400 N	11.3 A 28 A	0.52 °C/W	2.6 kg	248 mm	15 mm	
AL3809 (primary sec.) N S	2100 N	16.9 A 42 A	0.35 °C/W	3.2 kg	362 mm	15 mm	
AL3812 (primary sec.) N S	2800 N	22.6 A 56 A	0.26 °C/W	5.1 kg	476 mm	15 mm	
AL3818 (primary sec.) N	4200 N	34 A	0.17 °C/W	6.3 kg	704 mm	15 mm	
AL3910 (secondary section)	magnet yoke 114 m	magnet yoke 114 mm (magnet yoke width 48 mm)					
AL3920 (secondary section)	magnet voke 171 m	magnet voke 171 mm (magnet voke width 48 mm)					

TWINCAT®

PLC and Motion Control on the PC



The Windows Control and Automation Technology

The TwinCAT Software System turns any compatible PC into a real-time controller with a multi-PLC system and NC/CNC axis control. At the same time, TwinCAT integrates the programming environment for all Beckhoff controllers: from high-end Industrial PC control to embedded controller.

TwinCAT replaces conventional PLC and NC/CNC controllers as well as operating devices with:

- open, compatible PC hardware
- embedded IEC 61131-3 software PLC, software NC and software CNC in Windows NT/2000/XP, NT/XP Embedded, CE
- programming and run-time systems optionally together on one PC or separated
- connection to all common fieldbuses
- PC interfaces are supported
- data communication with user interfaces and other programs by means of open Microsoft standards (OPC, ActiveX, DLL, etc.)

TwinCAT architecture

The TwinCAT system consists of run-time systems that execute control programs in real-time and the development environments for programming, diagnostics and system configuration. Any Windows programs, for instance visualisation programs or Office programs, can access TwinCAT data via Microsoft interfaces or can execute commands.

TwinCAT PLC – the central pillar of automation software

Conceived as a pure software PLC, TwinCAT PLC allows up to four virtual "PLC CPUs", each running up to four user tasks, on one PC. The PLC program can be written in one or more of the languages provided for in the IEC 61131-3 standard:

- IL (Instruction List),
- LD (Ladder Diagram),
- FBD/CFC (Function Block Diagram),
- SFC (Sequential Function Chart) and
- ST (Structured Text).

TwinCAT PLC running under the Windows NT/2000/XP operating systems includes both the programming environment and the run-time system, so that an additional programming device is not required. Under the CE operating system and the embedded operating systems for the series BX and BC controllers, only

TwinCAT PLC run-time is available. Program modifications are implemented via network-capable powerful communication with the run-time system. Programming can be done

- locally,
- via TCP/IP or
- via the fieldbus (BXxxxx and BCxxxx).

TwinCAT NC – Motion Control on the PC

A software NC consists of:

- positioning (set value generation and position control)
- integrated PLC with NC interface
- operating programs for commissioning purposes
- I/O connection for axes via fieldbus
 With TwinCAT NC, the position controller is calculated on the PC processor as standard.
 It exchanges data cyclically with drives and measurement systems via the fieldbus.

TwinCAT NC I – axis interpolation in 3 dimensions

TwinCAT NC I (interpolation) is the NC system for linear and circular interpolated path movements of axis groups each involving two or three drives.

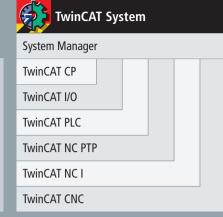
The system includes interpreter, set value generation and position controller. PLC functionality is integrated, as is the connection of the axes with the fieldbus.

TwinCAT CNC – the software CNC for toughest requirements

TwinCAT CNC expanded TwinCAT NC I with classic CNC features: Up to 32 interpolating axes and comprehensive coordinate and kinematic transformations are possible. Parts programming is carried out according to DIN 66025 using high-level language extensions. TwinCAT CNC can operate with up to 64 axes or 32 path axes and controlled spindles that can be distributed across up to 10 CNC channels. In a CNC channel, up to 32 axes can be interpolated simultaneously, enabling even the most difficult motion tasks to be solved. Apart from the classic linear, circular and helical interpolations, TwinCAT CNC offers convenient spline interpolation, optionally based on Akima or B-splines. Real-time transformations enable complex machine kinematics to be realised without problem.

PRODUCT OVERVIEW TWINCAT

Software PLC		Software NC PT	•
	TwinCAT PLC		TwinCAT NC PTP
PC hardware	standard PC/IPC hardware, no extras	TwinCAT PLC	inclusive
Operating systems	Windows NT/2000/XP, NT/XP Embedded, CE	PC hardware	standard PC/IPC hardware, no extras
Real-time	Beckhoff real-time kernel	Operating systems	Windows NT/2000/XP, NT/XP Embedded, CE
I/O system	EtherCAT, Lightbus, PROFIBUS DP/MC, Interbus,	Real-time	Beckhoff real-time kernel
	CANopen, DeviceNet, SERCOS, Ethernet and PC hardware	I/O system	EtherCAT, Lightbus, PROFIBUS DP/MC, Interbus, CANopen, DeviceNet, SERCOS, Ethernet and PC
Run-time system	4 multi-tasking PLCs each with 4 tasks in each		hardware
	PLC run-time system, development and run-time systems on one PC or separately (CE: only run-time)	Programming	performed using function blocks for TwinCAT PLC according to IEC 61131-3 (standardised PLCopen Motion Control libraries), convenient axis com-
Memory	process image size, flags area, program size,	Dun time austana	missioning menus in the System Manager
	POU size, number of variables only limited by	Run-time system	NC point-to-point including TwinCAT PLC
	the size of the user memory (max. 2 GB with NT/2000/XP)	Number of axes Axis types	up to 255 electrical and hydraulic servo drives, frequency
Cycle time	adjustable from 50 μs	Axis types	converter drives, stepper motor drives, switched
Link-time	1 μs (Pentium® 4 2.8 GHz) for 1,000 PLC		drives (fast/crawl axes)
LIIIK-UIIIE	commands	Cycle time	50 µs upwards, typically 1 ms (selectable)
Programming	IEC 61131-3: IL, FBD, LD, SFC, ST, powerful library management, convenient debugging TwinCAT PLC Libraries	Axis functions	standard axis functions: start/stop/reset/ reference, speed override, special functions: master/slave cascading, cam plates, electronic gearings, online distance compensation of segments, "flying saw"
Libraries	TwinCAT PLC Controller Toolbox		
	TwinCAT PLC Temperature Controller		TwinCAT NC PTP Libraries
	TwinCAT PLC Hydraulic Positioning		- IWINCAL NCT IT EIDIGITES
	TwinCAT PLC Modbus RTU	Libraries	TwinCAT NC Camming
	TwinCAT PLC Serial Communication		TwinCAT NC FIFO Axes
	TwinCAT PLC Building Automation		TwinCAT NC Flying Saw
	TwinCAT PLC IEC 60870-5-101/4		TwinCAT PLC Remote Synchronisation



TwinCAT Supplement System Software NC Libraries PLC Libraries

Software CNC

Software NC I	
	TwinCAT NC I
TwinCAT PLC	inclusive
TwinCAT NC PTP	inclusive
PC hardware	standard PC/IPC hardware, no extras
Operating systems	Windows NT/2000/XP, NT/XP Embedded, CE
Real-time	Beckhoff real-time kernel
I/O system	EtherCAT, Lightbus, PROFIBUS DP/MC, Interbus,
	CANopen, DeviceNet, SERCOS, Ethernet and PC
	hardware
Programming	DIN 66025 programs for NC interpolation,
	access via function blocks from TwinCAT PLC
	according to IEC 61131-3
Run-time system	NC interpolation, including TwinCAT NC PTP
	and PLC
Number of axes	max. 3 axes and up to 5 auxiliary axes per group,
	1 group per channel, max. 31 channels
Axis types	electrical servo axes, stepper motor drives
Interpreter	subroutines and jumps, programmable loops,
functions	zeroshifts, tool compensations, M and H
	functions
Geometries	straight lines and circular paths in 3D space,
	circular paths in all main planes, helixes with
	base circles in all main planes
Axis functions	online reconfiguration of axes in groups,
	path override, slave coupling to path axes,
	auxiliary axes

Jordana Circ	
	TwinCAT CNC
TwinCAT PLC	inclusive
TwinCAT NC PTP	inclusive
TwinCAT NC I	inclusive
PC hardware	standard PC/IPC hardware, no extras
Operating systems	Windows NT/2000/XP, Windows NT/XP Embedded
Real-time	Beckhoff real-time kernel
I/O system	EtherCAT, Lightbus, PROFIBUS DP/MC, Interbus,
	CANopen, DeviceNet, SERCOS, Ethernet and PC
	hardware
Programming	DIN 66025 programming language with
	high-level language extensions, mathematical
	functions, programming of parameters/variables,
	user macros, subroutine techniques, spindle and
	help functions, tool functions, zero offset shifts
Run-time system	CNC, including TwinCAT NC I, NC PTP, PLC
Number of axes/	8 path axes/6 controlled spindles, max. of
spindles	64 axes/12 controlled spindles (optional)
Axis types	electrical servo-axes, analog/encoder interface
	via fieldbus, digital interface via fieldbus
	(EtherCAT, Lightbus, PROFIBUS MC, SERCOS)
Geometries	linear, circular, helical interpolation in the main
	planes and freely definable planes, 8 interpolating
	path axes per channel, look-ahead function
Axis functions	coupling and gantry axis function, override, axis
	error and sag compensation, measuring functions
Operation	automatic operation, manual operation (jog/
	inching), single block operation, referencing,
	block search, handwheel operation (motion/
	superposition)
	TwinCAT CNC Options
Options	TwinCAT CNC Axes Pack
	TwinCAT CNC Channel Pack
	TwinCAT CNC Transformation
	TwinCAT CNC Spline Interpolation

PRODUCT OVERVIEW TWINCAT

TwinCAT Level

And I

Real-time

TwinCAT I/O

PC hardware

standard PC/IPC hardware, no extras

Operating systems

Windows NT/2000/XP, NT/XP Embedded, CE (only run-time)

Beckhoff real-time kernel

Multi-purpose I/O interface for all common fieldbus systems, PC Fieldbus Cards and interfaces with integrated real-time driver

TwinCAT CP

PC hardware

standard PC/IPC hardware, no extras
Windows NT/2000/XP, NT/XP Embedded

Operating systems

Beckhoff real-time kernel

Real-time

Windows driver for Beckhoff Control Panel

System software | Motion

TwinCAT Cam Design Tool

tool for designing electronic cam plates, fully integrated in the TwinCAT System Manager

TwinCAT Digital Cam Server

fast camshaft controller as software implementation in TwinCAT, freely configurable via the TwinCAT System Manager

TwinCAT DriveTop Server

communication server for connecting the Indramat DriveTop tool with TwinCAT

TwinCAT DriveCom OPC Server

for communication of drive setup tools right into DriveCom compatible drives

TwinCAT Valve Diagram Editor

graphics-oriented editor for designing the characteristic curves of a hydraulic valve

System software

TwinCAT ECAD Import

tool for importing XML files from ECAD systems

TwinCAT Engineering Interface Server

for coordination of programming tasks via a source code management system

TwinCAT Eventlogger

Alarm and diagnosis system that can be used in all TwinCAT controllers with very little programming effort.

TwinCAT XML Data Server

PLC data can be written directly into an XML file or read from an XML file.

TwinCAT Backup

tool for backing up and restoring of files, operating system and TwinCAT settings

TwinCAT Simulation Manager

simplifies preparation and configuration of a simulation environment

System software | Connectivity

TwinCAT ADS

set of different ADS communication components

TwinCAT OPC Server

for access to TwinCAT variables through OPC clients, for connection to all common visualisation packages

TwinCAT SMS/SMTP Server

enables sending of SMS messages from the TwinCAT PLC to a mobile phone

TwinCAT Modbus TCP Server

for communication with Modbus TCP devices

(server and client functionality)

TwinCAT TCP Server

Server and PLC library for communication via generic TCP server (client functionalities included)

INFORMATION MEDIA



Ordering information	Description
DK1101	Main catalog, German
DK1102	Main catalog, English
DK1301	News catalog, German
DK1302	News catalog, English
DK1401	Product overview, German
DK1402	Product overview, English
DK1405	Product overview, French
DK1406	Product overview, Italian
DK1407	Product overview, Russian
DK4000	Main catalog and software products on CD, German, English, Italian
DK6001	Company magazine PC-Control, German
DK6002	Company magazine PC-Control, English

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Headquarters

Beckhoff Automation GmbH Eiserstraße 5 33415 Verl

Germany Phone: +49 (0) 52 46 / 963 - 0 Fax: +49 (0) 52 46 / 963 - 198 info@beckhoff.de www.beckhoff.de

Germany Office Balingen Beckhoff Automation GmbH Karlstraße 19 72336 Balingen Phone: +49 (0) 7433/26024-0
Fax: +49 (0) 7433/26024-22

Office Berlin Beckhoff Automation GmbH Fasanenstraße 81 10623 Rerlin Germany Phone: +49 (0) 30 / 88 71 16 - 0 Fax: +49 (0) 30 / 88 71 16 - 19 berlin@beckhoff.de

Office Frankfurt Beckhoff Automation GmbH Torhaus Westhafen Speicherstraße 59 60327 Frankfurt am Main

Germany Phone: +49 (0) 69 / 68 09 88 - 0 Fax: +49 (0) 69 / 68 09 88 - 11 frankfurt@beckhoff.de Office Hanover

Beckhoff Automation GmbH Würzburger Straße 13 30880 Laatzen Germany Phone: +49 (0) 511/875758-0

Fax: +49 (0) 511/875758-20 hannover@beckhoff.de

Office Lübeck Beckhoff Automation GmbH Wahmstraße 56 23552 Lübeck Germany Phone: +49 (0) 451/203988-0

+49(0)451/203988-20 luebeck@beckhoff.de

Office Munich Beckhoff Automation GmbH Industriestraße 31 82194 Gröbenzell/Munich Germany Phone: +49(0)8142/41059-0 Fax: +49(0)8142/41059-13 muenchen@beckhoff.de

Office Nuremberg Beckhoff Automation GmbH Ostendstraße 196 90482 Nuremberg Phone: +49 (0) 911/5 40 56 - 0 Fax: +49 (0) 911/5 40 56 - 29 nuernberg@beckhoff.de

Technical Office Ravensburg Beckhoff Automation GmbH Zwergerstraße 15 88214 Ravensburg

Germany Phone: +49(0)751/3541550 +49(0)751/3541552 ravensburg@beckhoff.de

Office Rhein/Ruhr Beckhoff Automation GmbH Eurotec-Ring 40 47445 Moers Germany Phone: +49 (0) 28 41/9 08 16 -6 +49(0) 2841/90816-88 rhein-ruhr@beckhoff.de

Headquarters Beckhoff Automation GmbH Hauptstraße 4 6706 Bürs Phone: +43 (0) 55 52 / 688 13 - 0 Fax: +43 (0) 55 52 / 688 13 - 18 info@beckhoff.at www.beckhoff.at

Oberösterreich Beckhoff Automation GmbH Softwarepark 35 4232 Hagenberg Austria Phone: +43 (0) 72 36 / 2 09 25 - 0

Fax: +43 (0) 72 36 / 2 09 26 oberoesterreich@beckhoff.at Niederösterreich Beckhoff Automation GmbH

Leobersdorferstraße 42 2560 Berndorf Austria Phone: +43 (0) 2672/81975-980 Fax: +43 (0) 2672/81975-915 niederoesterreich@beckhoff.at

Sales Office Tirol Beckhoff Automation GmbH Klammstraße 66/39 6020 Innsbruck Austria

Austria Phone: + 43 (0) 512/236 043 Fax: + 43 (0) 512/236 045 tirol@beckhoff.at

Belgium Beckhoff Automation BVBA

Kempische Steenweg 305 bus 202 3500 Hasselt Belgium Phone: + 32 (0) 11 / 24 08 00 Fax: +32 (0) 11/240801 info@beckhoff.be www.beckhoff.be

Multiprox N.V. Lion d'Ôrweg 12 P.b. 71 9300 Aalst Belgium Phone: + 32 (0) 53 / 76 65 66 Fax: + 32 (0) 53 / 78 39 77 info@multiprox.be www.multiprox.be

Bulgaria

Kastiva GmbH 68-72 Ami Bue Str., 4. Floor 1612 Sofia Bulgaria Phone: +359(2)9504431 Fax: +359(2)9515980 office@kastiva.com www.kastiva.com

Croatia Geneza d.o.o. Bosiljevska 18 10000 Zagreb Croatia Phone: + 3 85 1 3 64 78 49 Fax: +38513636662 geneza@geneza.hr www.geneza.hr

Czech Republic,

Slovac Republic Dyger s.r.o.
Vystaviste 1
648 59 Brno
Czech Republic
Phone: + 420 5 / 41 32 10 04 +4205/41249208 info@dyger.cz www.dyger.cz

Denmark Headquarters
Beckhoff Automation ApS
Naverland 2
2600 Glostrup Denmark Phone: + 45 43 / 46 76 20 +4543/466335 info@heckhoff.dk

Sales Office Beckhoff Automation ApS Centervej 2 6000 Kolding Denmark Phone: + 45 76 / 31 20 72 +4576/312013 info@beckhoff.dk

www.beckhoff.dk

Finland, Estonia

Headquarters Beckhoff Automation Oy P.O. Box 23 Kankurinkatu 4-6 05801 Hyvinkää Finland Phone: +358(0)20/7423800 Fax: +358 (0) 20/7 42 38 01 info@beckhoff.fi
www.beckhoff.fi

Sales Office Seinäioki Beckhoff Automation Oy Kampusranta 9 60320 Seinäjoki Finland Phone: + 358 (0) 20 / 7 42 38 50 Fax: +358 (0) 20 / 7 42 38 51 info@beckhoff.fi

es Office Tampere Beckhoff Automation Ov Hatanpään valtatie 24 33100 Tampere Phone: + 358 (0) 20 / 7 42 38 70

France Beckhoff Automation Sarl Immeuble "Le Montréal ZA de Courtaboeuf 2A de Courtaboeut 19 bis, avenue du Québec 91951 Courtaboeuf Cedex France Phone: + 33 (0) 1 69 29 83 70 Fax: +33 (0) 1 69 28 40 55 info@beckhoff.fr

Fax: +358 (0) 20 / 7 42 38 71 info@beckhoff.fi

Great Britain, Ireland

Hayes Control Systems The Boathouse Station Road Station Road Henley-on-Thames Oxon RG9 1AZ Great Britain Phone: +441491/577267 sales@hayescontrols.co.uk www.hayescontrols.co.uk

Greece, Cyprus L. J. Skourgialos Industrial Automation Systems 241 FL Venizelou 241 EL. Venizelou 176 73 Kallithea/Athens Greece Phone: +30/21 09 51 02 60 Fax: +30/2109511048 ias@otenet.gr

Hungary Controrg Kft. Pajta u. 14 8200 Veszprem Hungary Phone: + 36 / 88 42 40 75 +36/88425601 Fax: +36/8842 info@controrg.hu www.controrg.hu

Italy Headquarters Beckhoff Automation S.r.l. Via E. Majorana, 1 20054 Nova Milanese (MI) Italy Phone: + 39 03 62/36 51 64 Fax: +39 03 62 / 4 09 90 info@beckhoff.it www.beckhoff.it

Sales Office Bologna Beckhoff Automation S.r.l. Via Mazzini, 12 40053 Bazzano (BO) Italy Phone: + 39 05 1/83 40 06 Fax: + 39 05 1/67 29 014

Lithuania, Latvia Kaliningrad, Belarus Beckhoff Automatika UAB Taikos 149

51129 Kaunas 51129 Naura: Lithuania Phone: +37037/451645 Fax: +37037/451645 Fax: +3703// info@beckhoff.lt www.beckhoff.lt

Netherlands

Industrial Automation Link Küppersweg 71 2031 EB Haarlem Netherlands Netherlands Phone: +3123/5185140 Fax: +3123/5185141 sales@ial.nl www.ial.nl

Poland Beckhoff Automation Sp. z o.o. Stara Iwiczna, ul. Sloneczna 116A 05-500 Piaseczno

Poland Phone: +4822/7572610 Fax: +4822/7572607 info@beckhoff.pl www.beckhoff.p

Portugal Bresimar – Sociedade de Equipamentos Eléctricos. Lda. Ouinta do Simão – EN109 – Esgueira Apartado 3080 3801-101 Aveiro Portugal Phone: + 351 234/3033 20 ± 351 234/30 33 28 bresimar@bresimar.pt www.bresimar.pt

Romania Kreatron Automation S.R.L. str. Bucuresti nr. 51, ap. 57 400148 Cluj-Napoca jud. Cluj Romania Phone: +40 264 /48 47 08 Finding. + 40 264 / 48 47 08 Fax: + 40 264 / 48 47 08 office@kreatron.ro www.kreatron.ro

Russia

Representation of Beckhoff Automation GmbH Ul. Nizhnaya Krasnoselskaya 40/12 kor. 20A, office 501 105066 Moscow Russia Phone: +7495/4118882 Fax: +7495/4118883 Support: +7495/4118884 info@beckhoff.ru

Representation North-West Federal District Beckhoff Automation GmbH

V.O., 7-ya Liniya, 76, office 620 199178 Saint-Petersburg Burnsville, MN 55337 USA Phone: + 1 952/890 0000 Russia Phone: + 7812/3326205 Fax: +7812/3326205 north-westfo@beckhoff.ru

Representation Ural Federal District Beckhoff Automation GmbH Uliza Pervomaiskaya 104, Office 108 Office 108 620219 Ekaterinburg Russia Phone: +7343/3799873 Fax: +7343/3799873 uralfo@beckhoff.ru

Representation Volga Federal District Reckhoff Automation GmbH Krasnoarmayskaya ul.1, Office 312 443010 Samara Russia Phone: + 7846/2698067 Fax: +7846/2698067 volgafo@beckhoff.ru

Genera d.o.o. Podmilščakova 18 1000 Ljubljana Slovenia Phone: + 38 61 / 439 30 50 Fax: +3861/4393090 genera@genera.si www.genera.si

Spain

Headquarters Beckhoff Automation S.A. Edificio Testa Sant Cugat Avda. Alcalde Barnils, 64-68 08174 Sant Cugat (Barcelona) Spain Phone: + 34 93 / 5 84 49 97 Fax: +3493/5 info@beckhoff.es www.beckhoff.es +3493/5844084

Sales Office Madrid Beckhoff Automation S.A. Edificio Cimaga Sierra de Cazorla, 1 Planta Baja, Oficina E 28290 Las Matas (Madrid) Snain

Spain Phone: + 3491/6364357 Fax: +3491/6364365 madrid@beckhoff.es

Sweden, Norway Headquarters Beckhoff Automation AB Stenåldersgatan 2B 21376 Malmö

Sweden Phone: + 46 (0) 40 / 6 80 81 60 Fax: +46 (0) 40 / 680 81 61 info@beckhoff.se www.beckhoff.se

Sales Office Beckhoff Automation AB Enebybergsvägen 10B 18236 Danderyd Sweden Phone: +46 (0) 8/4463000 info@beckhoff.se

Switzerland

Headquarters Beckhoff Automation AG Rheinweg 9 8200 Schaffhausen Switzerland Phone: + 41 (0) 52 / 6 33 40 40 Fax: +41 (0) 52 / 633 40 55 info@beckhoff.ch www.beckhoff.ch

Sales + Support Center Suisse Romande Beckhoff Automation AG En Chamard 35 1442 Montagny-près-Yverdon Switzerland Phone: + 41 (0) 24/44727 - 00 +41(0)24/44727-01 yverdon@beckhoff.ch

Turkey Siskon Endüstriyel Otomasyon

Sistemleri 153. Sok. 23/A Nokta 35280 Izmir Turkey Phone: + 90 232 / 245 00 76 Fax: +90232/2449453 mail@siskon.com.tr www.siskon.com.tr **North America**

Beckhoff Automation LLC 12150 Nicollet Avenue South

Fax: +1952/8902888 beckhoff.usa@beckhoff.com www.heckhoff.com

Beckhoff Automation LLC 12150 Nicollet Avenue South Burnsville, MN 55337 USA Phone: +1952/8086513

Fax: +1952/8902888 north.usa@beckhoff.com Reckhoff Automation LLC N6256 Schraven Circle North Fond du Lac, WI 54937

Phone: + 1 920/929 0655 Fax: +1952/8902888 wisconsin@beckhoff.com

Northeast Sales

Reckhoff Automation LLC 6003 Candlestick Drive Harrisburg, PA 17112 USA Phone: + 1 717/651 0591 Fax: +1717/6510592 northeast.usa@beckhoff.com

Northeast/East Application Development Beckhoff Automation LLC 2660 Elaine Drive Lower Burrell, PA 15068 USA

Phone: + 1 724/339 4525 Fax: +1724/3394575 east.application@beckhoff.com

Northwest Sales and Application Development Beckhoff Automation LLC 2122 112th Ave NE Suite B-200 Bellevue, WA 98004 Phone: + 1 425 / 451 4444

Fax: +1425/4514453 northwest.sales@beckhoff.com

Mideast Sales Beckhoff Automation LLC 4757 Ledgewood 7B Medina, OH 44256 Wedina, On 44236 USA Phone: +1330/7252403 Fax: +1330/7254319 ohio@beckhoff.com

Reckhoff Automation LLC 2289 Amsterdam Ave Canton, MI 48188 Phone: + 1 248/230 8835 Fax: +1952/8902888 michigan@beckhoff.com

Midwest Sales Beckhoff Automation LLC 12966 Fairway Drive Lemont, IL 60439 USA Phone: + 1 630 / 631 8467 +1952/8902888 midwest usa@heckhoff.com

Application Development Beckhoff Automation LLC 23041 Arbor Creek Drive Plainfield, IL 60544

USA Phone: +1815/6099984 Fax: +1815/6094483 midwest.application@ beckhoff.com

South Sales Beckhoff Automation LLC 4713 Martin Road Flowery Branch, GA 30542 USA Phone: +1770/9653637 Fax: +1770/9653537 south usa@heckhoff.com

Beckhoff Automation LLC 3305 Breckinridge Blvd. Suite 116 Duluth, GA 30094 Phone: + 1 770/921 7550 Fax: +1770/92175// south.application@beckhoff.com

Southeast Sales Beckhoff Automation LLC 713 Brittley Way Apex, NC 27502 USA Phone: + 1 919/367 0349 Fax: +1919/3670346 southeast.usa@beckhoff.com Southwest Sales and Application Development
Beckhoff Automation LLC 8108 Beauregard Drive Volente, TX 78641

USA Phone: +1512/6531831 Fax: +1512/8286230 southwest.application@ heckhoff com

Beckhoff Automation LLC 5820 Oberlin Drive Suite 111 San Diego, CA 92121 USA Phone: +1858/5461111 Fax: +1858/5461112 west.application@beckhoff.com

Beckhoff Automation LLC 8175-A Sheridan Blvd # 141 Arvada CO 80003-1928 Phone: +1303/4290758 Fax: +1303/4290758 colorado@beckhoff.com

Canada

Headquarters
Application Development
Beckhoff Automation Canada Ltd. 130 Research Lane, Unit 11 Guelph, ON N1G 5G3 Canada Phone: +1905/8521534 Fax: +1905/8521535 canada@beckhoff.com www.beckhoff.com

Sales Beckhoff Automation Canada Ltd. 35 Ioliet Street London, ON NV5 4V9 Canada Phone: +1519/4518572 Fax: +1905/8521535 canada@beckhoff.com

Mexico Sales and Application Development Integra Automation, SA de CV Av. Industrias 325-A 78399 Fracc. Talleres San Luis Potosí, S.L.P. Mexico Phone: +52 444/822 2615 al 17 Fax: +52 444/822 2616 mexico@beckhoff.com

Argentina

eFAI COM Alcorta 2411 CPA B1744HFM Moreno/Buenos Aires Argentina Phone: +54237/4631151 Fax: +54237/4631150 info@efalcom.com www.efalcom.com

Brazil Beckhoff Automação Industrial Ltda. Rua Continental, 146 – Jd. do Mar São Bernardo do Campo São Paulo 09750-060 Brazil Phone: + 55 (11) 4126-3232 Fax: +55(11)4330-3701 info@beckhoff.com.br

Rolec S.A. Panamericana Norte Km 15 1/2,

www.beckhoff.com.b

Post Code: 12 Santiago Post Code: 12 Santiago Santiago Chile Phone: +562/6408000 Fax: +562/7471320 info@rolec.cl www.rolec.cl

Egypt Industrial Control Systems ICS 29 Dr. Mohamed El Harouny Street Nasr City, Cairo 11371 Egypt Phone: +202/2755031 Fax: +202/2635731 info@ics-me.com www.ics-me.com

South Africa

Beckhoff Automation (Pty) Ltd Unit 8, Boskruin Business Park, Randpark Ridge Randburg 2188 South Africa Phone: +27 (0) 11 792 3374 +27 (0) 11 792 5453 info@beckhoff.co.za www.beckhoff.co.za

China Headq

Beckhoff Automation GmbH 5th Floor Sth Floor, No. 163 Jiang Chang San Road Shanghai Shibei Industrial New Zone Shanghai, 200436 Phone: +8621/66312666 Fax: +8621/66315696 info@beckhoff.com.cn www.beckhoff.com.cn

Representation Reijing Representation Beijing Beckhoff Automation GmbH Room 1608, Tower B, Investment Plaza, No. 27 Financial Street Xicheng District Beijing, 100032 Beijing, 100032 P. R. China Phone: +8610/66210991 Fax: +8610/66210992 beijing@beckhoff.com.cr

Representation Guangzhou Beckhoff Automation GmbH Citic Plaza Room 1418 Room 1418 233 Tianhe North Road Guangzhou, 510620 P. R. China Phone: +8620/38773571 Fax: +8620/38773573 guangzhou@beckhoff.com.cn

Inteltek Automation Pvt. Ltd. Sr.no.100/5, Ambegaon Pune 411 046 Maharashtra Phone: +91 20/2431 81 21 Fax: +91 20/2431 81 24 info@inteltekindia.com www.inteltekindia.com

Japan K.MECS Co., Ltd. Yusen Iwamotocho Blg. 3F 2-3-3 Iwamotocho, Chiyoda-City, Tokyo 101-0032

Japan Phone: +81 3 5825 5333 Fax: +81358258550 info@kmecs.co.jp www.kmecs.com

Singapore, Malaysia, Thailand, Philippines, Vietnam, Indonesia TDS Technology (S) Pte Ltd. 64 Sungei Kadut Loop (Hocen Building) (Hocen Building) Singapore 729493 Singapore Phone: +65/63661661 Fax: +65/63621661 sales@tdstech.com

www.tdstech.com Tri-TEK Corp.
717 DaeRyung TechnoTown III
448 KasanDong Kumcheongu

Seoul 153-803 Korea Phone: +822/2107-3242 Fax: +822/2107-3969 tritek@tritek.co.kr www.tritek.co.kr

Taiwan JI-DIEN Co., Ltd. 9F., No. 22, Sec. 1, Jhongshan Rd. Sinjhuang City Taipei County 24250 Taiwan (R.O.C.) Phone: +886 (2) 8522 3237 Fax: +886 (2) 8522 3168 Fax: +886(2)63223. jidien@chgroup.com.tw www.chgroup.com.tw

Australia
Beckhoff Automation Pty. Ltd. Beckhoff Automation Pty. Li Level 16, 10 Queens Road Melbourne, Victoria, 3004 Australia Phone: +61 (3) 9912 54 30 Fax: +61 (3) 83 20 47 30 info@beckhoff.com.au www.beckhoff.com.au

New Zealand W. Arthur Fisher P.O. Box 12747 Penrose Auckland New Zealand Phone: +649/2700100 Fax: +649/2700900 waf@waf.co.nz