

P R O D U C T

SPECIFICATION



MP-FLX 230 Series

•
Single- and
Dual-Axis

At two times the standard industry speed for digital current loop update rates, the new MaxPlus® FLX Series amplifiers are the industry's fastest. Featuring a 25 micro-second loop update rate and low current noise capabilities, this multi-patented, flexible family of digital drives offers increased machine throughput and productivity.

The Single-Axis digital drives are capable of simple torque or velocity loop modes or point-to-point position loop mode including pulse and direction control. They offer continuous output current from 3 to 35 Amps RMS.

The Dual-Axis amplifiers are packaged in one enclosure and share common circuitry such as the

DSP, DSP support circuits, power supply and other power stage circuits. This extremely costefficient use of space and technology translates to a substantial cost savings of approximately 35% or more in multi-axis applications. Available in a variety of power levels with up to 230 VAC line input voltages, the dual-axis models range from 3/3 to 25/12 Amps RMS of continuous output current.

Based on third generation digital technology, the stand-alone, fully digital amplifiers also feature an intelligent drive option (MP-FLXi) for Single- and Dual-Axis coordinated motion control that's built directly into the drives.





MaxPlus® Digital Servo Drive

MP_FLX 230 Series



Standard Features

- High Speed (25µS) Current Loop Update Rate
- Patent Pending 1/T Velocity Estimation for Smooth Low-Speed Performance
- Cost Saving Dual-Axis Package
- · CE, CUL and UL508C Certifications
- · Internal and/or External Shunt Regulation
- ± 10 VDC Analog Command Input (14 bit A/D)
- RS-232 or RS-485 Serial Port Communications
- Windows®-based HMI (Human Machine Interface)
- Up to 240 VAC Nominal (264 VAC max) Line Input
- Up to 35 Amps RMS of Continuous Output Current for Single-Axis Units
- 3/3 to 12/25 Amps RMS of Continuous Output Current Per Axis for Dual-Axis Units
- Drive Enable Input
- ± Limit Switch, Home Inputs
- Fault Relay, Warning/Brake Relay
- Status Indicators (7 Segment Display and Bi-Colored LEDs)
- Resolver or Encoder/Hall Feedback
- · Simulated Encoder Output
- · Sinusoidal Commutation
- Pulse and Direction Input (Stepper Emulation)
- Extensive Fault Protection
- Simple Screw-Type Terminal Interface
- User Supplied AC/DC Inputs for Maintaining Control Circuits During Main Power Loss
- EEPROM to Store Tuning and Setup Parameters
- Programmable Current Limit (0 to 100%)
- Programmable Current Scaling (0 to 100%)

Optional Features

- Intelligent Drive Option with Full Motion Control Programmability (Coordinated Motion, Master/Slaving, Electronic Gearing, Camming, Math Functions, Logic Functions)
- Expanded I/O, 15 User I/O Per Axis (Opto-Isolated, 24VDC)
- Dual Encoder Inputs Per Axis for Master/Slaving or Commutating Encoder with Additional Positioning Feedback Encoder
- MACRO[®] Digital Network Interface (Type I Compatible, Fiber-Optic or RJ45 Twisted Pair)
- D-Type Connectors for High Volume Applications
- 4-20mA Command Input

Fault Protection

- · Phase-to-Phase Shorts
- Phase to Vbus
- · Phase to Vbus Return
- Phase to Chassis (Earth) Ground
- · Over Temperature
- · Over Voltage
- Locked Rotor Over Current
- Shunt Over Power
- · Logic Supply Under Voltage
- Processor Fault
- Application Program Fault

User Programmable Faults and Warnings

- Motor Temperature
- User RMS Current Limit
- Bus Under Voltage
- Amplifier Temperature Warning
- Position Following Error
- Resolver Fault
- Hall Sensor Fault

Single Axis Power Specifications

Amplifier Model		X Axis Current			Enclosure Width			
	M	l₄rms		√ l _p		in		cm
MP-FLX-230/X03	20	3		6		3.7		9.7
MP-FLX-230/X06	200	6	- 2	12	~(3.7	- 2	9.7
MP-FLX-230/X10	200	10	-710	20	-71	3.7	-210	9.7
MP-FLX-230/X20)	20	300	40	300	5.8	.200°	14.8
MP-FLX-230/X35		35	130	70	750	7.8	760	19.9

Peaks can be sustained for at least two seconds.

I_p = peak of sinewave

Peak RMS = $I_p \div \sqrt{2}$

Power ratings are at 40° C ambient.

Dual-Axis Power Specifications

Amplifier Model	X Axis Current		Y Axis Curi	Enclosure Width		
4.	l₀rms	I _p	l _e rms	I _P	in	cm
MP-FLX-230/X03/Y03	3	6	3	6	4.6	11.6
MP-FLX-230/X05/Y05	5	10	5	10	4.6	11.6
MP-FLX-230/X08/Y08	8	16	8	16	5.8	14.8
MP-FLX-230/X12/Y08	12	25	8	16	5.8	14.8
MP-FLX-230/X12/Y12	12	25	12	25	7.8	19.9
MP-FLX-230/X25/Y12	25	50	12	25	7.8	19.9

Peaks can be sustained for at least two seconds.

 I_p = peak of sinewave

Peak RMS = $I_p \div \sqrt{2}$

Power ratings are at 40° C ambient.

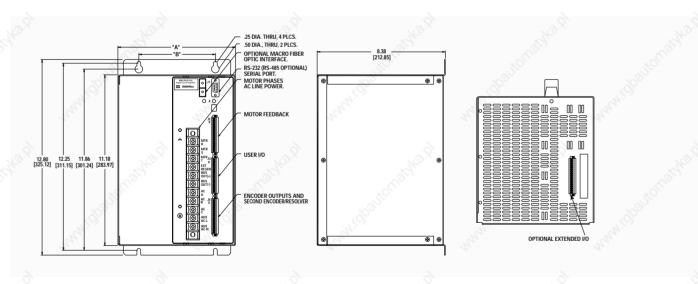


Performance Specifications

Parameter		Units		Value	
\$ ⁸	J-05 ⁵		JON.		J. 0.5
AC Input Voltage (47-63 Hz, 1φ or 3φ)	- Land	VAC	The same	90-240±10%	i The
DC Bus Voltage	7C.	VDC	A 20	127-330±10%	1
Bus Over Voltage	XO, ,	VDC	XO,,	400	×0,,
Shunt Regulator Turn-On Voltage		VDC	- 35	385-395	>-
Output Current Signal to Noise Ratio (@ zero current)	795	dB	70V	>66	
Offset (@ zero current, % of peak rating)	47	%	4.	< 0.05	
Linearity		%		>95	
Efficiency		%		>95	
Current Loop Bandwidth (-3dB point/45 phase shift)		KHz		5/1.5	
Current Loop Update Period	9	μS	9	25	9
Velocity Loop Bandwidth	10.5	Hz	10.0	400	13.
Velocity Loop Update Period	10%	μS	101	100	10%
Position Loop Bandwidth	400	Hz	400	100	400
Position Loop Update Period	1/0.	μS	40.	100	£0.
PWM Switching Frequency	7.0	KHz	~8°	20	
Maximum Encoder Frequency (edge rate)	(0)	MHz	(0)	10	
Maximum Motor Speed*	4.	RPM	Ly.,	30,000	
Minimum Motor Inductance		μH 🌃		25	
Operating Temperature Range**		°C		0-60	
Storage Temperature Range		°C		-25-80	
Relative Humidity (non-condensing)	. 0	%	. 0	5-95	. 0
Application Program Instruction Execution Cycle	150.	μS	150.	800	160.
Application Program Profile Generator Cycle	20,	μS	20	100	20
	- A				AY

^{*}Application Dependent

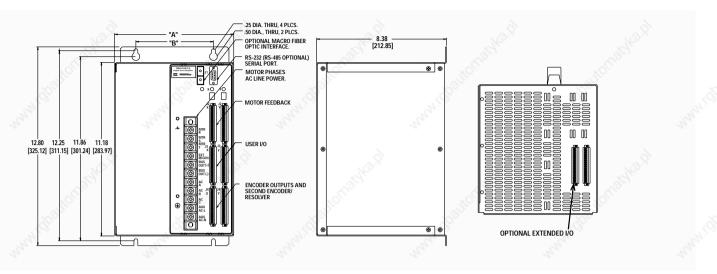
Mechanical Specifications, MP-FLX Single Axis Systems



Power Level	X03	X06	X10	X20	X35
	in/mm	in/mm	in/mm	in/mm	in/mm
"A" "B"	3.7/94.0	3.7/94.0	3.7/94.0	5.7/144.8	7.7/195.6
	2.0/50.8	2.0/50.8	2.0/50.8	3.0/76.2	5.0/127.0

^{**}Continuous current is derated if ambient is above 40° C.

Mechanical Specifications, MP-FLX Series Dual Axis Systems



Power Leve	X03/Y03 in/mm	X05/Y05 in/mm	X08/Y08 in/mm		X12/Y12 in/mm	X25/Y12 in/mm
"A"	4.6/116.8	4.6/116.8	5.8/147.3	5.8/147.3	7.8/198.1	7.8/198.1
"B"	2.0/50.8	2.0/50.8	3.0/76.2	3.0/76.2	5.0/127.0	5.0/127.0

Digital Inputs and Outputs

The MP-FLX Series comes standard with four dedicated inputs (24VDC or TTL) and two user-defined relay outputs. An additional 15 I/O can be added per axis as an option. All I/O are optically isolated with the exception of the relays, which are magnetically isolated.

Dedicated Inputs

Inputs utilize bi-directional opto-couplers and a user-provided reference. Therefore, the user determines the active state, positive or negative. Inputs are available with a 3V or 8V minimum threshold.

ENABLE

Input is active high. When high the amplifier output is enabled and when low the amplifier output is disabled. Toggling the input resets the amplifier.

+LIMIT

Input is active high or low (user definable). When active the amplifier output is disabled in the positive direction.

- LIMIT

Input is active high or low (user definable). When active the amplifier output is disabled in the negative direction.

HOME

Input is active high or low (user definable). When active during the homing sequence the position counter is set to zero. The Home bit can be ANDED with any combination of the encoder index, encoder A, or encoder B.

Relay Outputs

The relays are solid state devices with normally open contacts that are rated for 100VDC and 0.5A. The power-on state is user definable as well as the function. These relays can be used for outputs such as drive ready/fault, brake, or other user defined applications.

Optional I/O

The Expansion I/O provides 8 inputs and 7 outputs per axis or 7 inputs and 8 outputs per axis.

INPUTS

Inputs utilize bi-directional opto-couplers and a user-provided reference. Therefore, the user determines if the inputs are active high or active low.

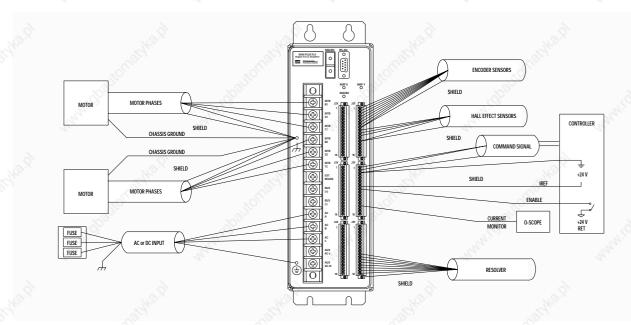
OUTPUTS

Outputs utilize open-collector drivers, can sink up to 350mA, and are active low.

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Signal/Wiring



MACRO® (Motion and Control Ring Optical)

MACRO® is a non-proprietary digital interface developed by Delta Tau Data Systems for connection of multi-axis controllers, amplifiers and I/O on a fiber-optic or twisted-pair copper ring (RJ45 connector).

Features and Benefits:

- Single Plug Connections Minimizes Wiring Complexity Between Controls and Amps
- Noise Immunity Fiber-Optic Cable Transmits Light, Not Electricity
- Speed One of MACRO'®s Most Impressive Features is its 125 Mbits/Sec Rate of Data Transmission
- Simplicity Transmission Across the MACRO® Ring Requires No Software Intervention
- Improved System Performance Digital Communications Minimizes Error in A/D and D/A Conversions and Eliminates Ground Loops and Voltage Offset/Shift Problems
- One Ring, Multiple Masters No Need for Independent Rings for Systems with Multiple Controllers for High-Axis Count.
- Tuning and Set-up Parameters are Downloadable via MACRO®

MACRO® Data Structures Compatible with the MP-FLX

- Phase Current
- Torque
- Velocity
- Position

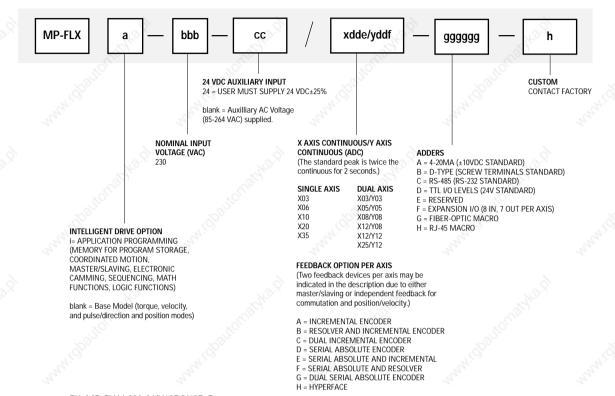
MP-FLX I/Os that are Adjustable through MACRO®

- 4 Digital Inputs
- 1 Analog Input and 1 Analog Output
- 8 Optional Inputs
- 7 Optional Outputs

The User Can Monitor in REAL-TIME Any of the Internal Variables of the MP-FLX Drive including:

- Y Current Feedback
- X Current Feedback
- Motor and Amplifier Temperature Data
- Fault Status
- Command Input
- Current Command
- Bus Voltage
- Torque
- · Position/Velocity

MP-FLX Series Model Number Decode



EX: MP-FLX i-230-24/X12B/Y12B-F



At MTS Automation our experienced application engineers are ready to work with you to design motor, amplifier and motion control packages to meet your performance, size and durability requirements exactly. For specific ordering information, please visit our web site at www.mtsautomation.com, or call the factory at 1-800-967-1785.

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MTS Automation

Custom Servo Motors

2121 South Bridge St. New Ulm, Minnesota 56073 Phone: 507-354-1616 Fax: 507-354-1611

Custom Servo Motors Antriebstechnik GmbH & Co. KG

Leinenweberstr. 14 D-79108 Freiburg Tel: +49 761 1 30 91-0 Fax: +49 761 1 34 42

Performance Controls

433 Caredean Drive Horsham, Pennsylvania 19044 Phone: 215-675-6500 Fax: 215-674-8714

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