## WS5-9

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## Suggestions <br> Corrections

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## WS5-9

Power Drive

Issue: b023 March 96
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If you have found any faults within this documentation, or have any suggestions, we cordially invite you to inform us on this form.

## Suggestions and/or Corrections

## Safety requirements

Please read the following safety requirements prior to installation, operation, maintenance and repair of the device.

- The intended use of the device is described in this manual in chapter "Purpose" and must be observed.
- Installation, maintenance and repair of the device shall be performed by a qualified electrician. National regulations concerning
- accident prevention
- installation of electrical and mechanical systems
- radio interference suppression
shall be observed.
- The technical data of the device, particularly the ambient conditions, shall be observed.
- The device shall only be operated by trained personnel.

BERGER LAHR offers training courses.

- The warranty is invalidated in case of unauthorized modification or opening of the device.
- Please ask your BERGER LAHR technical consultant prior to installing accessories not listed in the chapter "Description of accessories".
The address is to be found on the rear cover.
- The safety symbols and notes on the device and in the manual shall be observed.


## Explanation of symbols



ATTENTION
Reference to a danger for the device or components, possibly resulting in the endangering of human life.
DANGER
Reference to a direct endangering of human life.

## DANGER

High voltage at component, do not touch.

## DANGER

High temperature at component, do not touch.

## ATTENTION

Warning against electrostatic discharge (ESD).
Only touch the PC-board or component in an electrostatically-protected environment.


NOTE
Important or additional information concerning the device or the manual.

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## 1 General Description

### 1.1 Construction and Characteristics

## Construction

The power drive WS5-9 has the following components (Figure 1-1):

- Current selection switch for selecting the motor phase current;
- Parameter switch for selecting the functions: current zero-setting, boosting, current reduction, rotation direction, step angle;
- Voltage switch between 115 V AC and 230 V AC;
- LED display for signalling of faults;
- Signal connection for driving of the power unit;
- Motor connection for a 5-phase stepping motor;
- Mains connection for the power supply (115 / 230 V AC);
- Fasteners at the back of the equipment for fixing to mounting rails.


## Characteristics

The power drive WS5-9 has been designed to be fixed to a mounting rail, i.e.:

- the equipment can be fixed to a mounting rail (TS $35 \times 15$ ) by means of the fasteners.
- all the operating controls, indicators and connections are located on the front panel of the equipment.



## NOTE

Because the WS5-9 is designed for an IP 20 degree of protection, the equipment must be incorporated in a switch cabinet or in another enclosed housing.


Figure 1-1 Power Drive WS5-9

## Other characteristics include:

- Operation with mains power supply;
- Short-circuit protection of the power stage when there is shorting between motor phases or between motor phase and earth;
- Undervoltage, excessive temperature and phase monitoring of the power stage.


### 1.2 Application/System Integration

The purpose of the WS5-9 drive is to drive a 5-phase stepping motor up to a current of $2.8 \mathrm{~A}(70 \mathrm{~V} \mathrm{DC})$. It is the link between a positioning controller (e.g. WP-311) or an SPC unit with indexer and the stepping motor (Figure 1-2).


Figure 1-2 System integration

## Motor types

The power drives of the WS5 series are designed for 5-phase stepping motors up to a maximum rated current of 2.8 A per winding.

NOTE
The 5-phase stepping motors are operated in five-point connection (see page 2-4).

### 1.3 Function

Figure $1-3$ shows the most important function blocks of the unit:

- From the mains voltage of 230 V AC or 115 V AC the intermediate circuit voltage of 70 V DC is generated in the power unit.
- The chopper-type power supply unit provides the supply voltages for the internal modules.
- The parameter switches are used to make the basic settings for phase current, direction rotation and step angle (see section 2.5).
- The "control electronics - power stage - current controller" closedloop circuit converts the PULSE and DIRECT. input signals into the output signals for driving the stepping motor. The control electronics block contains the ring counter logic which defines the current pattern. The current controller keeps the phase current constant at the preset value.
- The status of the equipment is recorded in the Monitoring and Protection block. Any possible errors are signalled externally via the fault indicator and via the READY signal output (see sections 3.1.2 and 4.1).

For more details about the meaning and function of the various control signals, see section 3.1


Power unit

Figure 1-3 Function connection
diagram of WS5-9

### 1.4 Technical Data

### 1.4.1 Electrical Data

1.4.1.1 Mains Connection
1.4.1.2 Motor Connection

### 1.4.1.3 Signal Connection

| Mains connection voltage, | $115 \mathrm{~V} \mathrm{AC},-20 \%+15 \%$ <br> switchable to: <br> $230 \mathrm{~V} \mathrm{AC},-20 \%+15 \%$ |
| :--- | ---: |
| Current at make | 30 A |
| Fuse | 6.3 A slow-blow |
| Frequency | $50-60 \mathrm{~Hz}$ |
| Power consumption | max. 600 VA |
| Power dissipation | max. 80 W |


| Protected in case of short-circuit between motor phases |  |
| :--- | ---: |
| Max. cable length | 50 m |
| Cable diameter | $0.75 \mathrm{~mm}^{2}$ for cable length $\leq 30 \mathrm{~m}$ |
|  | 1.5 mm for cable length $>30 \mathrm{~m}$ |
| Screen connection | both sides |
| Motor voltage | 70 V DC |
| Phase current | in 16 stages from 0.55 to 2.8 A |
| Connection system | five-point |

This connection must be safely isolated from the mains.

| Max. voltage (power resistance) to earth | 60 V DC |
| :--- | ---: |
| Cable diameter | $0.25 \mathrm{~mm}^{2}$ |
| Screen connection | the control side only |

## Electrical Characteristics of the Inputs PULSE, DIRECT, ENABLE, PWM, F/H-STEP, BOOST

Optoencoupled and protected against reverse polarity.
The signal voltage level is typespecific (see Equipment Variants)

|  | TTL | or |
| :--- | ---: | ---: |
| 24 V |  |  |
| Max. input voltage | 5.25 V | 30 V |
| Switch on point $U_{E}$ | 2.5 V | 20 V |
| Switch off point $U_{A}$ | 0.4 V | 3 V |
| Typical input current at nominal current |  | 10 mA |

## Electrical characteristics of the output TEMP.INT

Optoencoupled, protected against reverse polarity, inductive resilient, short circuit protected.
Max. voltage drop $U_{R}$ ..... 28 V
Max. switch current IL ..... 10 mA
Voltage drop at 10 mA ..... max. 2 V
Electrical characteristics of the output READY
Relay double-throw contact.

| Max. voltage | $30 \mathrm{~V} \mathrm{AC}, 36 \mathrm{~V} \mathrm{DC}$ |
| :--- | ---: |
| Max. current | $0,2 \mathrm{~A}$ |
| Min. current | 10 mA |
| Max. active power | 5 W |
| Max. apparent power | 6 VA |

1.4.1.5 Equipment ProtectionType of protection
IP 20 as per DIN 40050 / IEC 1401
Power unit shortcircuit- and overvoltage-proof as per VDE 0160 Cl .2
Power stage protection circuits:
Short-circuit monitoring;
Excessive temperature recognition;Monitoring of over/undervoltage and
1.4.2 Mechanical Data

| Dimensions (L x W $\times \mathrm{H})$ | $135 \times 135 \times 157 \mathrm{~mm}$ |
| :--- | ---: |
| Weight | 2.8 kg |



Figure 1-4 Dimensions of the
equipment
1.4.3 Ambient Conditions

Ambient temperature:
Working $\quad 0^{\circ} \mathrm{C}$ to $50^{\circ} \mathrm{C}$
Storage/transportation $-25^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$

Change in ambient temperature:
Working max. $10 \mathrm{~K} / \mathrm{h}$
Storage/transportation
max. $20 \mathrm{~K} / \mathrm{h}$

Humidity class - components
F as per DIN 40040
Humidity class tested according to IEC 68 part 2-3 at:

- air temperature

$$
+40^{\circ} \mathrm{C},+2^{\circ} \mathrm{C}
$$

- relative air humidity

93\%; +2\%-3\%

Radio shielding with external filter (type Timonta FF 390) as per VDE 0871-A
Overvoltage stability as per VDE 0160-2
Resistance to interference as per VDE 0843 / IEC 801

Dew formation not permitted


## NOTE

When the WS5-9 is mounted in a switch cabinet, it must be remembered that the power loss which can be removed depends on the design of the cabinet, its ambient temperature and the arrangement of the equipment. See section 2.3.

## 2 Installation

### 2.1 Parts Specification

The specification must be checked for completeness.
The specification includes (Figure 2-1):

| Q'ty | Description | Order number |
| :--- | :--- | :--- |
| 1 | WS5-9.081-00 (24 V) <br> or <br> WS5-9.181-00 (3.5...5 V) | 64690810006 <br> or <br> 64691810006 |
| 1 | Plug shell Mains connection | 98050060642 |
| 1 | Plug shell Motor connection | 98050060600 |
| 1 | Sub-D socket (37 pole) <br> for signal connection | N4-673-203 |
| 1 | Housing for <br> Sub-D socket (37 pole) <br> for signal connection | N4-673-239 |
| 1 | WS5-9 Technical documentation | Doc. no. 211.367/DGB |



Figure 2-1 Parts specification

### 2.2 Accessories

The following accessories can be supplied by special order:

| Description | Order number |
| :--- | :--- |
| Signal cable | see Appendix |
| Motor cable | see Appendix |
| Stepping motor | see catalogue Doc. no. 350 |
| End bracket EW 35 | 038356 from Fa. Weidmüller |

## NOTE

For a description of the accessories, see Appendix 6.2

### 2.3 Mounting



## CAUTION

The WS5-9 must be housed in a switch cabinet so as to ensure resistance to interference and prevent the equipment from being contaminated. Make sure that there are adequate provisions for the dissipation of heat!

The equipment is fitted to a supporting rail on the mounting wall by means of the fasteners at the back of the equipment and is secured at the sides by the end brackets. The minimum clearance between several WS5 units or from other pieces of equipment must be 10 cm . The outer surfaces of the equipment act as a heat sink to remove the heat. The maximum power dissipation of the equipment is 80 W .

Figure 2-2 Cooling


### 2.4 Cabling

### 2.4.1 General Instructions



## DANGER

- Switch off mains voltage before connecting cables!
- The power connections (motor, mains) should be carried out only by qualified electrical engineers in accordance with VDE 0105!

UTION

- Make sure that the cables are screened and fitted with strainrelief clamps!
- Twist every pair of signalling cables before connecting them!
- Lay mains, motor and signal cables so that there is a space between them!

Figure 2-3 Overview of connections


### 2.4.2 Connection of the Motor

1. Prepare the 5 wires of the motor cable and the screen which are to be connected to the plug end with boot lace ferrules.
2. Insert the 6 wires into cap of the mating plug as shown in Figure 2-4 and tighten the screws.
3. Join the two plug shell halves together.
4. Set the plug to connection 09 and tighten screws.


## CAUTION

To minimise the losses in the cable and the power drive, it is advisable to have as short a cable route as possible.
The maximum length of the motor cable is 50 m .
For cable diameter, see technical data.


DANGER
The locking mechanism of the motor plug may only be opened when the mains voltage has been disconnected.

Figure 2-4 Motor connection


## Circuitry of the motor

The circuitry of the motor uses a five-point connection, see Figure 2-5.


NOTE
In the five-point circuit twice the phase current flows in the motor connecting wires.


Figure 2-5 Circuitry of the motor

### 2.4.3 Adjustment of the Equipment to Mains Voltage

CAUTION
The equipment must be set to the normal national mains voltage of 115 V AC or 230 V AC.

1. Disconnect mains voltage to the WS5-9.
2. Using a screw driver, for example, turn voltage switch 10 into the desired position:
switch at top: 115 V AC
switch at bottom: 230 V AC.
The position which has been set is indicated on the switch.


## CAUTION

The mains voltage must always be turned off before any alteration is made to the position of the voltage switch.


### 2.4.4 Connecting of the Mains Cable

1. Prepare the wires of the mains by fitting boot lace ferrules at the plug end.
2. Insert the 3 wires into mating plug terminal block as shown in Figure 2-7 and tighten screws.
3. Join the plug shell halves together.
4. Set the plug to connection 12 and tighten screws.

## DANGER

Make sure that the mains voltage is disconnected before loosening the mains cable!

Figure 2-7 Mains connection


### 2.4.5 Connecting the Signal Cables

1. Twist the wires of the signal cables in pairs and solder them onto the 37 pins Sub-D-socket, according to figure 2-8.
2. Insert cable into the cable entry clamp (strain relief) and clamp it. Connect the screen on the side of the control with earth (GND).

## NOTE

When using a push-pull drive, it may be useful to connect the screen to the plug shell on both ends of the cable.
3. Put on socket shell.
4. Plug socket to socket connection panel 04 and tighten screws.

## ATTENTION

- Maximum length of the signal cable: 50 m .
- All signal connections shall be safely isolated from the mains (maximum voltage to earth: 60 V DC).

Signal Connection (07)


1) 32-13 bridget not ready
$32-14$ bridget ready
$U \min =5 \mathrm{~V}$
Umax $=30 \vee \mathrm{AC}, 36 \mathrm{VDC}$
$\min =10 \mathrm{~mA}$
$\max =0,2 \mathrm{~A}$
Imax $=0,2 \mathrm{~A}$
$\mathrm{Pmax}=5 \mathrm{~W}$
$S \max =6$ VA

Figure 2-8 Wiring the signal connector

## Circuitry of the signal connections

For the electrical isolation of the signal inputs and outputs optocouplers are used; the internal circuits are shown in figure 2-9.

In the case of an alternating signal voltage level choose the equipment variant with 5 V signal level. Also wire into the external feeder additional protective resistors to ensure a current of approx. 10 mA .


Figure 2-10 shows the possible connections of the signal inputs. The Push-Pull drive (which is also used in the BERGER LAHR Positioning Controller) offers the advantage of a higher signal to noise ratio.

## Signal Inputs PULSE, DIRECT., ENABLE, PWM, F/H-STEP, BOOST

$1^{\text {st }}$ Possibility

$2^{\text {nd }}$ Possibility

npn-Drive (earth switched)
$3^{\text {rd }}$ Possibility
 connection possibilities of signal inputs

### 2.5 Initial Operation

### 2.5.1 Checklist for Initial Operation

### 2.5.2 Basic Settings



DANGER
Disconnect the equipment before starting to make any adjustments!

Figure 2-11 Setting elements

## Setting of the phase current

Setting the phase current using rotary switch 06 .
For the possible settings, see Figure 2-12. If it is found to be impossible to set the phase current indicated on the rating plate of the motor, set the next lowest value.

## CAUTION

- Never set too high a current! The maximum phase current must not be exceeded and, if it is, this must be only momentarily (boost signal). This is to prevent overloading of the motor. Make sure the motor is adequately cooled (temperature on motor housing must not exceed $100^{\circ} \mathrm{C}$ )!
- The phase current must be set to max. 2.65 A for the motors ExRDM 5913/50P and ExRDM 599/50P! Current increase via Boost is not permitted.


## NOTES

- Smaller phase currents are permissible, but of course the torque is correspondingly reduced.
- To reduce power dissipation, the automatic current reduction system should be switched on when the system is at rest (see Figure 2-13).



## Setting of the parameters

Use the DIL switch 05 to set desired parameters as illustrated in Figure 2-13. The basic factory setting is indicated.


## NOTES

- When current reduction is active the motor phase current decreases to $70 \%$ in the idling condition (pulse frequency $<10 \mathrm{~Hz}$ ). This leads to cooling of the motor and reduction of the stopping torque to approx. 70\%.
- The action of the DIRECT. and F/H-STEP signal inputs can be inverted by means of parameter switch 03 (direction of rotation) and 04 (step size).
- In the case of a half step the motor executes 1000 steps per revolution, in the case of a full step it performs 500 steps per revolution.


Figure 2-13 Settings of the parameter switch

## 3 Operation

### 3.1 Signal Description

The power drive WS5-9 is operated by means of control signals from the signal interface.

The meanings and functions of the individual signals are described below.

## NOTE

An 'active' input means a flow of current from + to -, an 'inactive' input means a flow of current from - to + or no current at all.

## ENABLE (Enabling Command)

- Input 'active': enabling of power drive. When operation is troublefree, the standby relay contact of the power drive is at READY.
- Input 'inactive': deletion of a stored fault report (see section 4.2) and resetting of the ring counter. The motor is disconnected from the current. The standby relay contact is at NOT READY.


## CAUTION

When the ENABLE input is 'inactive', the motor is de-energized, i.e. it has no stopping torque.

## NOTE

If the error message is repeated, disconnect the mains voltage and rectify the fault using the troubleshooting table (section 4.2).

Figure 3-1 ENABLE/READY response times
ENABLE
$\mathrm{t}_{1}=\mathrm{t}_{2}<5 \mathrm{~ms}$

| Switch on/off time |
| :--- |
| of power stage |

Waiting time
for ENABLE

## PULSE (step)

With each rising signal edge at the PULSE input the motor executes one step.

## DIRECT. (direction of rotation)

Dependent upon the position of the Parameter Switch 05 (see figure 2-13):

- Input 'inactive': clockwise rotation (Parameter Switch OFF)
- Input 'active': counterclockwise rotation
(Parameter Switch OFF)
or
- Input 'inactive': counterclockwise rotation
- Input 'active':
(Parameter Switch ON)
clockwise rotation (Parameter Switch ON)

NOTE
Rotation Direction when looking at the motor shaft (flange side).
For the signal response times for PULSE and DIRECT. See figure 3-2.

Figure 3-2 PULSE/DIRECT. response times

$\tau_{1}=\tau_{2} \leq 1 \mu \mathrm{~s}$
$t_{1}$ : Preparation time for direction signal $\geq 0 \mu \mathrm{~s}$
$\mathrm{t}_{2}$ : Stop time for direction signal $\quad \geq 5 \mu \mathrm{~s}$
$t_{3}$ : Pulse lenght $\quad \geq 5 \mu \mathrm{~s}$
t4: Pulse interval $\geq 5 \mu \mathrm{~s}$

## F/H STEP (stepangle)

Dependent on the adjustment of the parameter switch 05/04 (see figure 2-13):

- Input 'inactive': Half Step (Parameter Switch ON)
- Input 'active': Full Step (Parameter Switch ON)
or
- Input 'inactive': Full Step (Parameter Switch OFF)
- Input 'active': Half Step (Parameter Switch OFF)


NOTE
When set on 'Half Step'the motor
makes 1000 steps / rotation, on 'Fullstep' it makes 500 steps/ rotation.

## BOOST (current increase)

- Input 'inactive': Nominal current (as set on Rotary Switch 06)
- Input 'active': Double nominal current (but max. 2.8 A)


## ATTENTION

- Current increase via BOOST above the nominal current of the motor is only allowed for short time spans ( $20 \%$ of the switch-ing-on time of the motor, maximum 10 secs).
- The boost function must not be activated for the motors ExRDM 5913/50P and ExRDM 599/50P.


## NOTE

If the BOOST is activated during a motor standstill, an active current reduction on parameter switch 05 is blocked.

## IPWM (current control)

Input for the Pulse Width Modulated signal (PWM) for the Phase Current Control ( $0-100 \%$ or BOOST $0-200 \%$ of the set phase current). The PWM signal lies in the frequency range from $6 \ldots .20 \mathrm{kHz}$.

## NOTE

- The Signal Frequency should be selected from outside of the audio range (approx. 20 kHz).
- If the inputs IPWM and BOOST are activated simultaneously, the BOOST function (current increase) is always dominant.

Figure 3-3 Phase current control via input IPWM

### 3.1.2 Output Signals



## NOTE

'Active' output means low-impedance.
'Inactive' output means high-impedance.

## READY (standby)

When the equipment is ready to operate the contacts $32-14$ are connected. In the case of an error the contacts 32-13 are connected.


## NOTE

For further information on errors see chapter 4.

## TEMP.INT.

If the permissible operating temperature of the unit is exceeded (approx. $75^{\circ} \mathrm{C}$ at the heat sink), the unit is turned off.

Approx. $5^{\circ} \mathrm{C}$ before the point of disconnection the TEMP.INT warning device is switched to "inactive" (high impedance).

The superordinate control unit can still respond therefore and can, for example, reduce the motor current or move into the parking position.

### 3.2 Switching On

Switch on mains voltage at external switch.
After the mains voltage has been switched on, the green LED on the front panel of the equipment lights up and signals that the supply voltage is present at WS5-9. If no red LED lights up on the front panel, the standby relay contact is at READY.

The following precondition must be satisfied:

- ENABLE input active, see Figure 3-1.


### 3.3 Operating Facilities

The equipment is operated by the control signals from the superordinate control unit (see section 3.1); there is no provision for manual operation of WS5-9.


## CAUTION

During operation the outside surfaces of the housing which serve as a heatsink may heat up.

### 3.4 Switching Off

Switch off mains voltage at external switch.


## DANGER

Do not loosen the mains cable until after all phases of the supply voltage have been disconnected!

## 4 Errors / Faults

### 4.1 Status Indicator

Several monitoring and protection functions are used to establish whether the equipment is operating correctly. The status of the equipment is externalised in two ways:

- visually by means of 4 LED's on the front panel of the equipment
- electrically via the READY outputs. In this way the current status of the power drive is reported to the superordinate control unit (e.g. PLC).

The table indicates the possible statuses of the equipment and the respective consequences for the equipment outputs. The following section contains notes on how to rectify faults quickly.

## CAUTION

Depending on the type of fault there will be no current at the motor output. The stopping torque of the motor then falls to zero.

| Signalling by LED's | Meaning | Effect, action |
| :--- | :--- | :--- | :--- |


| Signalling by LED's | Meaning | Effect, action |  |
| :--- | :--- | :--- | :--- |
|  | LED 01 und 02 <br> (Reset) | ENABLE is not present | Motor has no current. <br> READY and the motor <br> outputs inactive |

The equipment can be reset by desactivating the ENABLE input.

### 4.2 Troubleshooting Table

| Indicator | Status | Possible cause of fault | Remedy |
| :--- | :--- | :--- | :--- |

### 4.3 Storage and Shipping

When equipment or insert cards are stored the following points have to be taken into consideration:

- the maximum humidity (see Technical Data) is not to be exceeded!
- the storage temperature (see Technical data) is not to be exceeded!
- the stored parts have to be protected from dirt and dust!
- equipment and insert cards which show the following symbol are obly to be unpacked, stored or installed in working areas which are electrostatically protected!
- equipment and insert cards which have accumulators
 should be connected to the mains at least once a month!
- the original packing has to be saved!

When equipment and insert cards are shipped, the following points have to be taken into consideration:

- equipment and insert cards should, if possible, only be shipped in their original packing!
- insert cards should be packed without batteries or accumulators into covers which convey electrostatic on both sides (if possible use the original packing)!
- insert cards should be packed with batteries or accumulators into covers which convey electrostatic on the outside and anti-electrostatic on the inside (if possible use the original packing)!
- equipment or insert cards with the following symbol should only be packed in electrostatically protected working areas!



## 5 Maintenance

The power drive WS5-9 requires no maintenance.

## 6 Appendix

### 6.1 Equipment Variants

Type Code for Wall Mounted Equipment WS5-9
WS 5-9. x 8 1-0 0

| Signal voltage |  |
| :--- | :--- |
| 0 | 24 V |
| 1 | $3,5 \ldots 5 \mathrm{~V}$ |

### 6.2 Description of Accessories



The following accessories can be supplied by separate order:

| Item in <br> Figure 6-1 | Description | Order number | Reference |
| :--- | :--- | :--- | :--- |
| 1 | Motor cable | $62501316 x x x$ | see section 6.2.1 |
| 2 | Mains filter | 62501100200 | see section 6.2.2 |
| 3 | Signal cable <br> (connector at <br> equipment end) | 62501401 xxx | see section 6.2.3 |
| 4 | Stepping motor |  | see catalogue <br> Doc. no. 350 |

### 6.2.1 Motor Cable

The motor cable can be supplied in the following lengths:

| Cable length | Diameter | Order number |
| :--- | :--- | :--- |
| 5 m | $0.75 \mathrm{~mm}^{2}$ | 62501316005 |
| 10 m | $0.75 \mathrm{~mm}^{2}$ | 62501316010 |
| 15 m | $0.75 \mathrm{~mm}^{2}$ | 62501316015 |
| 20 m | $0.75 \mathrm{~mm}^{2}$ | 62501316020 |
| 30 m | $0.75 \mathrm{~mm}^{2}$ | 62501316030 |

Special lengths in gradations of 1.0 m are available on request.


NOTE
Preferred length: 10 m

### 6.2.2 Mains Filter

Figure 6-2 Mains filter
\&
A mains filter is inserted in the mains cable for the purpose of radio shielding as per VDE 0871/limit class A.


Ambient conditions
Storage temperature $-25^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Operating temperature $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$
Humidity class, componentsF acc. to DIN 40040
Humidity class, tested to IEC 68 part 2-3 at:
Air temperature $+40^{\circ} \mathrm{C},+2^{\circ} \mathrm{C}$
Relative humidity $93 \%,+2 \%,-3 \%$
non-condensing

### 6.2.3 Signal Cable

The signal cable open at the end of the drive side can be ordered in the following length:

| Cable length | Order Number |
| :--- | :--- |
| 1 m | 62501401010 |
| 2 m | 62501401020 |
| 5 m | 62501401050 |
| 10 m | 62501401100 |
| 25 m | 62501401250 |

The Signal Cable includes:

| Description | Order Number |
| :--- | :--- |
| 37 pole socket | N4-673-203 |
| Plug shell (37 pole) | N4-673-239 |
| Cable | $\mathrm{H} 6-928-44$ |

### 6.3 Glossary of Technical Terms

## Boost

Momentary increase of the set phase current for the purpose of increasing the torque when the motor is accelerating or braking

## Clockwise rotation

Clockwise rotation of stepping motors. Positive sense of rotation as seen from the motor shaft (flange side)

## Counterclockwise rotation

Counterclockwise rotation of stepping motors. Negative sense of rotation as seen from the motor shaft (flange side)

## ENABLE

command Signal input for activation of the controller
5-phase stepping motor for wall-mounted equipment Special stepping motor for wall-mounted equipment from BERGER LAHR

## Full step

Rotational angle of the 5-phase stepping motor per 0.72" step (corresponds to 500 steps/revolution)

## Half step

Rotational angle of the 5 -phase stepping motor per 0.36 " step (corresponds to 1000 steps/revolution)

## Phase current

The current flowing through a winding of the stepping motor

## Pulse frequency

Number of driving pulses per second; with each pulse the motor performs one step

## Pulse width modulation PWM

Control of an analogue quantity (e.g. motor current) via the pulse width/pulse spacing ration of an input signal (see also current control)

## Ring counter

Cyclically operating counter with topped decoding logic for generation of the current pattern for the 5 phases of the stepping motor

## Start/Stop frequency

Largest pulse frequency at which the motor with a given load can start and stop without contouring error

## Step

Process in which the motor shaft of the stepping motor executes a movement corresponding to one step angle (see also Half step, Full step)

## Step angle

Nominal angle through which the motor shaft of the stepping motor for each drive pulse (see also Half step, Full step)

Stop time
Period within which a signal condition is maintained.

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## M

Mains cable
Mains connection
Mains filter
Mains power unit
Mains voltage
Maintenance
Minimum clearance
Monitoring functions
Motor cable
Motor connection
Motor connection wires
Motor stand still
Motor types
Motor voltage

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