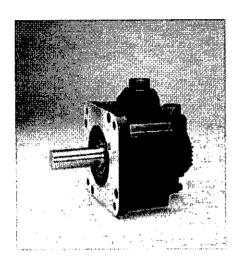
SEMG

High Speed Feed Series

SGMG Servomotors (1500rpm) - With Incremental / Absolute Encoder

Rated Output: 0.45kW, 0.85kW, 1.3kW,

1.8kW, 2.9kW, 4.4kW, 5.5kW, 7.5kW, 11kW



For Additional Information	Page(s)
SGMG Ratings & Specifications SGMG Speed/Torque Curves SGMG Dimensions SGMG Selection/Ordering Information SGMG Optional C€ Selection SGDB Ratings & Specifications SGDB Dimensions	80 81 82 - 87 88 - 92 93 - 95 129 - 130 131 - 137

Design Features

1. Compact

Small sized motor

Lightweight motor designed to have installation compatibility.

Compatible with previous generation G series motors.

Both length and mass have been reduced to 2/3 of previous generation.

2. High Speed

Acceleration performance

Is double that of single motor.

9 types of rated outputs ranging from 0.46 to 11.0kW.

3. Enhanced Environmental Resistance

- Water resistance, IP67 standard (excluding shaft)
- Reinforced lead-out cable access
- Enhanced withstand load

Motor output shaft bearing size is upgraded by one rank.

4. Application Emphasis

- Chip mounters
- PCB drilling machines
- Robots
- Conveyors
- Packaging

3. Certified International Standards

• UL Recognized (File #: E165827), CE compliance (option)

Servomotor Ratings and Specifications

Time Rating: Continuous Insulation: Class F Vibration: 15µm or less Withstand Voltage: 1500VAC

Insulation Resistance: 500VDC

 $10M\Omega$ or more

Enclosure: Totally-enclosed, self-cooled Excitation: Permanent magnet

IP67 (except for shaft opening)

Ambient Temperature: 0 to 40°C Ambient Humidity: 20 to 80%

(non-condensing)

Rated Speed*: 1500 rpm

Instantaneous Max Speed*: 3000 rpm

Excitation: Permanent magne
Drive Method: Direct drive
Mounting: Flange-mounted

	Rated Output	Ra Ton	ted jue		eous Peak	Rated Current*	Instantaneous Max. Current		
MOTORS: SGMG-	kW (HP)	N•m	kgf•cm (lb•in)	N•m	kgf • cm (lb • in)	A (ms)	A (rms)		
05A⊟A	0.45 (0.6)	2.84	29 (25)	8.92	91 (79)	3.8	11		
09A□A	0.85 (1.1)	5.39	55 (48)	13.8	141 (122)	7.1	17		
13A □ A	1.3 (1.7)	8.34	85 (74)	23.3	238 (207)	10.7	28		
20A□A	1.8 (2.4)	11.5	117 (102)	28.7	293 (254)	16.7	42		
30A□A	2.9 (3.9)	18.6	190 (165)	45.1	460 (404)	23.8	56		
44A□A	4.4 (5.9)	28.4	290 (252)	71.1	725 (630)	32.8	84		
55A□A	5.5 (7.4)	35.0	357 (310)	87.6	894 (775)	42.1	110		
75A□A	7.5 (10)	48.0	490 (425)	119	1210 (1050)	54.7	130		
1AA□A	11 (15)	70.0	714 (620)	175	1790 (1550)	58.6	140		

	Torque	Constant	Moment	of Inertia	Holo	ling Brake	Allowable Load	Rated	Rated Angular	Inertia Time	Inducti	
				With the same	Torque	Inertia	Inertia	Rate*	Acceleration*	Constant	Const.	
MOTORS: SGMG-	N • m/A (rms)	kgf • cm/A (lb • in/A) (rms)	kg • m² × 10 ⁻⁴	gf • cm • s ² (lb • in • s ² × 10 °)	N·m	kg - m²	kg • m² × 10 ⁴	kW/s	rad/s ²	ms	ms	
05A∐A	0.82	8.4 (7.3)	7.24	7.39 (6.41)	4.41		36.2	11.2	3930	5.0	5.1	
09A□A	0.83	8.4 (7.3)	13.9	14.2 (12.3)			69.5	20.9	3880	3.1	5.3	
13A□A	0.84	8.6 (7.4)	20.5	20.9 (18.2)	12.7	1.85	103	33.8	4060	2.8	6.3	
20A□A	0.73	7.5 (6.5)	31.7	32.3 (28.1)			159	41.5	3620	2.1	12.5	
30A□A	0.83	8.5 (7.3)	46.0	46.9 (40.7)		7.70	230	75.3	4050	1.9	12.5	
44A□A	0.91	9.2 (8.0)	67.5	68.9 (59.8)	43.1	7.75	338	120	4210	1.3	15.7	
55A□A	0.88	9.0 (7.8)	89.0	90.8 (78.8)			445	137	3930	1.3	16.4	
75A□A	0.93	9.4 (8.2)	125	127 (111)	72.6	7.75	625	184	3850	1.1	18.4	
1 AA □A	1.25	12.8 (11)	281	287 (249)	84.3	13.2	1405	174	2490	1.2	22.6	

^{*} These items and torque-speed characteristics quoted in combination with and SGDB Servo Amplifier at an armature winding temperature of 20°C.

Note: These characteristics can be obtained when the following heat sinks (steel plates) are used for cooling purposes:

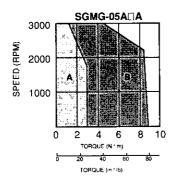
Type $05A \square A$ to $13A \square A$: $400 \times 400 \times 20$ (mm) $(15.75 \times 15.75 \times 0.79$ (in)) Type 20A□A to 75A□A: 550 × 550 × 30 (mm) Type 1AA□A: 650 × 650 × 35 (mm)

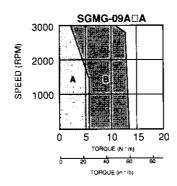
(21.65 × 21.65 × 1.18 (in))

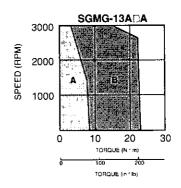
 $(25.59 \times 25.59 \times 1.38 (in))$

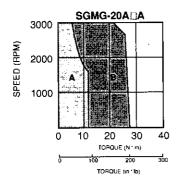
SGMG

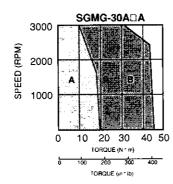
Speed / Torque Curves

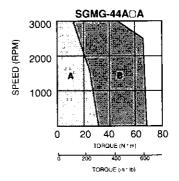


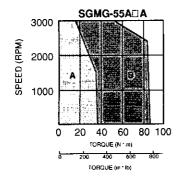


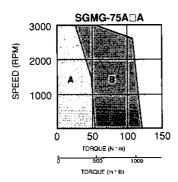


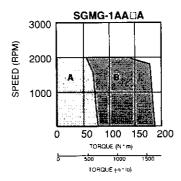










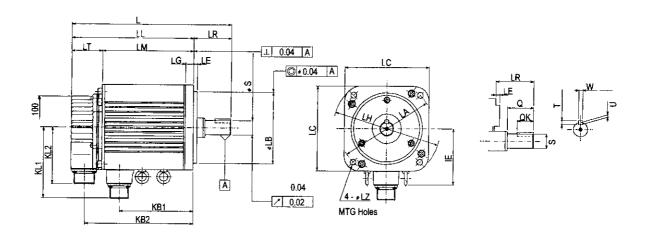


A: CONTINUOUS DUTY ZONE

: INTERMITTENT DUTY ZONE

Dimensions in inches (mm)

(1) 8192 PPR Incremental Encoder



Туре		ii	LM.	LR	LT	кві	KB2	IE	KL1	KL2		e egge	Flange	Dimens	ions				Shaf	t End D	imensio	n n		Approx. Me
: SGMG-		·ĻĻ	E_IVI	LIX		ND I	NDZ	- IE ~·	PVL I	NLZ	⊕LA ·	LB	LÇ.	LE.	LG	UH	LZ	S	⊸Q	QK;	·W:	, · T √	i U	b (kg)
05A2AB	7.72 (196)	5.43 (138)	3.62 (92)	2.28 (58)	1.81 (46)	2.56 (65)	4.61 (117)	-	4.29 (109)	3.46 (88)	5.71 (145)	4.33 (110)_0 ₀₃₅	5.12 (130)	0.24 (6)	0.47 (12)	6.5 (165)	0.35 (9)	0.75 (19) \$ _{.013}	1.57 (40)	0.98 (25)	0.20 (5)	0.20 (5)	0.12 (3)	12.1 (5.5)
09A2AB	8.62 (219)	6.34 (161)	4.53 (115)	2.28 (58)	1.81 (46)	3.46 (88)	5.51 (140)	-	4.29 (109)	3.46 (88)	5.71 (145)	4.33 (110)_8 ₀₃₅	5.12 (130)	0.24 (6)	0.47 (12)	6.5 (165)	0.35 (9)	0.75 (19).8 _{.013}	1.57 (40)	0.98 (25)	0.20 (5)	0.20 (5)	0.12	16.5 (7.5)
13A2AB	9.57 (243)	7.28 (185)	5.47 (139)	2.28 (58)	1.81 (46)	4.41 (112)	6.46 (164)		4.29 (109)	3.46 (88)	5.71 (145)	4.33 (110) ½ ₀₃₅	5.12 (130)	0.24 (6)	0.47 (12)	6.5 (165)	0.35 (9)	0.87 (22).8 ₀₁₃	1.57 (40)	0.98 (25)	0.24 (6)	0.24 (6)	0.14 (3.5)	21.2 (9.6)
20A2AB	9.65 (245)	6.54 (166)	4.69 (119)	3.11 (79)	1.85 (47)	3.5 (89)	5.71 (145)	,	5.51 (140)	3.46 (88)	7.87 (200)	4.5 (114.3) <u></u> 025	7.09 (180)	0.13 (3.2)	0.71 (18)	9.06 (230)	0.53 (13.5)	1.38 (35) *0.01	2.99 (76)	2.36 (60)	0.39 (10)	0.31 (8)	0.20 (5)	30.9 (14)
30A2AB	10.67 (271)	7.56 (192)	5.71 (145)	3.11 (79)	1.85 (47)	4.53 (115)	6.73 (171)	-	5.51 (140)	3.46 (88)	7.87 (200)	4.5 (114.3) ડુ ₀₂₅	7.09 (180)	0.13 (3.2)	0.71 (18)	9.06 (230)	0.53 (13.5)	1.38 (35) ⁺⁰ ⁰¹	2.99 (76)	2.36 (60)	0.39	0.31 (8)	0.20 (5)	39.7 (18)
44A2AB	12.01 (305)	8.9 (226)	7.05 (179)	3.11 (79)	1.85 (47)	5.87 (149)	8.07 (205)	,	5.51 (140)	3.46 (88)	7.87 (200)	4.5 (114.3). _{8.025}	7.09 (180)	0.13 (3.2)	0.71 (18)	9.06 (230)	0.53 (13.5)	1.38 (35) *8 ⁰¹	2.99 (76)	2.36 (60)	0.39 (10)	0.31 (8)	0.20 (5)	50.7 (23)
55A2AB	14.69 (373)	10.24 (260)	8.39 (213)	4.45 (113)	1.85 (47)	6.85 (174)	9.41 (239)	4.92 (125)	5.91 (150)	3.46 (88)	7.87 (200)	4.5 (114.3) -} ₀₂₅	7.09 (180)	0.13 (3.2)	0.71 (18)	9.06 (230)	0.53 (13.5)	1.65 (42).8 ₀₁₆	4.33 (110)	3.54 (90)	0.47 (12)	0.31 (8)	0.20 (5)	66.1 (30)
75A2AB	17.6 (447)	13.15 (334)	11.3 (287)	4.45 (113)	1.85 (47)	9.76 (248)	12.32 (313)	4.92 (125)	5.91 (150)	3.46 (88)	7.87 (200)	4.5 (114.3).§ ₀₂₅	7.09	0.13 (3.2)	0.71 (18)	9.06 (230)	0.53 (13.5)	1.65 (42) 0 ₀₁₈	4.33 (110)	3.54 (90)	0.47 (12)	0.31 (8)	0.20 (5)	88.2 (40)
1AA2AB	17.87 (454)	13.31 (338)	11.46 (291)	4.45 (116)	1.85 (47)	9.88 (251)	12.48 (317)	5.59 (142)	6.61 (168)	3.46 (88)	9.25 (235)	7.87 (200).§ ₀₄₆	8.66 (220)	0.16 (4)	0.71 (18)	10.63 (270)	0.53 (13.5)	1.65 (42).8 ₀₁₆	4.33 (110)	3.54 (90)	0.47 (12)	0.31 (8)	0.20 (5)	126.8 (57.5)

Note

- 1. Incremental Encoder (8192 PPR) is used as a detector.
- 2. SGMG-05A2A to 44A2A do not contain eyebolts.
- 3. Dimensions are the same when using other incremental encoders.
- 4. Tolerances on the dimensions LB of flange type and S of shaft extensions are based on JIS (Japanese Industrial Standard) B0401 "Limits and Fits for Engineering."
- 5. There are no dimensional changes on the CE products.

Connector Wiring on the Incremental Encoder Receptacle: MS3102A20-29P Applicable Plug: (To be prepared by customer)

Plug: MS3108B20-29S (L Type) MS3106B20-29S (Straight Type) Cable Clamp: MS3057-12A



	Connector Wiring on the	ne Incre	mental Encoder
Α	Channel A Output	ĸ	
В	Channel A Output	L	
С	Channel B Output	М	-
D	Channel B Output	N	
E	Channel C Output	P	-
F	Channel C Output	R	-
G	0V	s	-
Н	+5 VDC	T	-
J	FG (Frame Ground)		
Note:	The above-mentioned d	etector	side specifications are

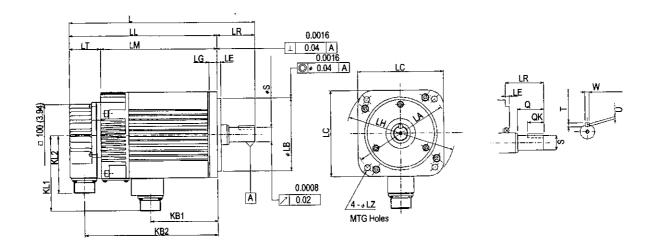
Note: The above-mentioned detector side specifications are common to all the motors with incremental encoders.

Connector Wiring on the Motor Side										
Α	U Phase									
В	V Phase									
С	W Phase									
D	Ground Terminal									



(2) 8192 PPR Incremental Encoder, With Brake

• 0.5 to 4.4kW (0.7 to 5.9HP)



Туре			77.5			122		1		,		Flange I)imensi	ons	******	• .	1	Shaf	End Di	mensio	1 :		Approx. Mass
SGMG-	L	LL	LMF+	~ LR	LT	KB1	KB2	KL1	KL2	LA	LB	LC-	LE:	- LG	· LH "	LZ	S	Q.	- QK	W	∴ T :	U	b (kg)
05A2ABC	9.21	6.93	5.08	2.28	1.85	22	6.1	4.72	3.46	5.71	4.33	5.12	0.24	0.47	6.5	0.35	0.75	1.57	0.98	0.20	0.20	0.12	16.5
	(234)	(176)	(129)	(58)	(47)	(56)	(155)	(120)	(88)	(145)	(110). _{0.035}	(130)	(6)	(12)	(165)	(9)	(19)-\$ ₀₁₃	(40)	(25)	(5)	(5)	(3)	(7.5)
09A2ABC	10.12 (257)	7.83 (199)	5.98 (152)	2.28 (58)	1.85 (47)	3.11 (79)	7.01 (178)	4.72 (120)	3.46 (88)	5.71 (145)	4.33 (110) \$ _{.035}	5.12 (130)	0.24 (6)	0.47 (12)	6.5 (165)	0.35 (9)	0.75 (19).8 _{.013}	1.57 (40)	0.98 (25)	0.20 (5)	0.20 (5)	0.12 (3)	21.2 (9.6)
13A2ABC	11.06	8.78	6.93	2.28	1.85	4.06	7.95	4.72	3.46	5.71	4.33	5.12	0.24	0.47	6.5	0.35	0.87	1.57	0.98	0.24	0.24	0.14	26.5
	(281)	(223)	(176)	(58)	(47)	(103)	(202)	(120)	(88)	(145)	(110) _{0.035}	(130)	(6)	(12)	(165)	(9)	(22) 8 ₀₁₃	(40)	(25)	(6)	(6)	(3.5)	(12)
20A2ABC	11.65	8.54	6.69	3.11	1.85	3.11	7,72	5.75	3.46	7.87	4.5	7.09	0.13	0.71	9.06	0.53	1.38	2.99	2.36	0.39	0.31	0.20	41.9
	(296)	(217)	(170)	(79)	(47)	(79)	(196)	(146)	(88)	(200)	(114.3) \$.025	(180)	(3.2)	(18)	(230)	(13.5)	(35)+0 ⁰¹	(76)	(60)	(10)	(8)	(5)	(19)
30A2ABC	12.68	9.57	7.72	3.11	1.85	4.13	8.74	5.75	3.46	7.8 7	4.5	7.09	0.13	0.71	9.06	0.53	1.38	2.99	2.36	0.39	0.31	0.20	51.8
	(322)	(243)	(196)	(79)	(47)	(105)	(222)	(146)	(88)	(200)	(114).3.8 ₀₂₅	(180)	(3.2)	(18)	(230)	(13.5)	(35)+0.01	(76)	(60)	(10)	(8)	(5)	(23.5)
44A2ABC	14.02 (356)	10.91	9.06 (230)	3.11 (79)	1.85 (47)	5.47 (139)	10.08 (256)	5.75 (146)	3.46 (88)	7.87 (200)	4.5 (114).3 8.025	7.09 (180)	0.13 (3.2)	0.71 (18)	9.06 (230)	0.53 (13.5)	1.38 (35)*8 ⁰¹	2.99 (76)	2.36 (60)	0.39 (10)	0.31 (8)	0.20 (5)	62.8 (28.5)

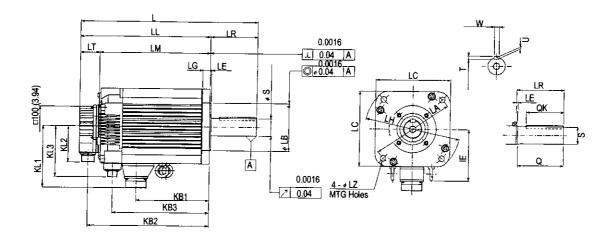
Note:

- 1. Incremental Encoder (8192 PPR) is used as a detector.
- 2. Dimensions are the same when using other incremental encoders.
- 3. Tolerances on the dimensions LB of flange type and S of shaft extensions are based on JIS (Japanese Industrial Standard) B0401 "Limits and Fits for Engineering."
- 4. There are no dimensional changes on the CE products.



	Connector Wiring o	n the 1	Notor Side
A	U Phase	E	Brake Terminal
В	V Phase	F	Brake Terminal
С	W Phase	G	-
D	FG (Frame Ground)		

• 5.5 to 11kW (7.4 to 15HP)



Type SGMG-	~~L ~	ΪĽ	LM	·LR	ĹΤ	KB1	KB2	КВЗ	IF.	KI 1	KL2	KI 3.	141		lange	Dimens	ions (wite 1,	111,841	3	Shaf	t End D	imensi	on -: 🗓 .	1	Appro
SGMG		* - ^	<i>p</i> = ,··		. 3			,,,,,	9	******	TULE	1020	LA	LB	LC	LE	LG	'LH"	·LZ	·S	Q	QK	W	T.	U	Mass b
55A2AAC	16.69 (424)	12 <u>2</u> 4 (311)	10.39 264	4.45 (113)	1.85 (47)	6.85 (174)	11.42 (290)	9.09 (231)	4.92 (125	5.91 (150)	3.46 (88)	4.84 (123)	7.87 (200)	4.5 (114.3) § _{.025}	7.09 (180)	0.13 (3.2)	0.71 (18)	9.06 ((230)	0.53 (13.5)	1.65 (42).§ ₀₁₆	4.33 (110)	0.98 (25)	0.20 (5)	0.20 (5)	0.12	77.2 (35)
75A2AAC	19.61 (498)	15.16 (385)	13.31 (338)	4.45 (113)	1.85 (47)	9.76 (248)	14.33 (364)	12.01 (305)	4.92 (125)	5.91 (150)	3.46 (88)	4.84	7.87	4.5 (114.3) <u></u> 8 ₀₂₅	7.09	0.13 (3.2)	0.71 (18)	9.06 ((230)	0.53 (13.5)	1.65 (42) 8.016	4.33	0.98 (25)	0.20 (5)	0.20 (5)	0.12	100.3 (45.5)
1AA2AAC	19.65 (499)	15.08 (383)	13.39 (340)	4.57 (116)	4.69 (43)	10.16 (258)	14,25 (362)	12.4 (315)	5.59 (142)	6.61 (168)	3.46 (88)	5.59 (142)	9.25	7.87 (200) \$ ₀₄₆	8.66	0.16 (4)	0.71 (18)	10.63 (270)	0.53	1.65 (42)-8 ₀₁₅	4.33 (110)	0.98 (25)	0.24	0.24	0.14 (3.5)	143,3

Note:

- 1. Incremental Encoder (8192 PPR) is used as a detector.
- Dimensions are the same when using other incremental encoders.
 Tolerances on the dimensions LB of flange type and S of shaft extensions are based on JIS (Japanese Industrial Standard) B0401 *Limits and Fits for Engineering.*
 There are no dimensional changes on the CE products.

Connector Wiring on Brake, Motor Side

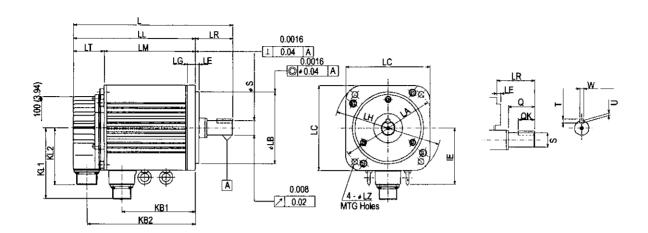


Α	Brake Terminal
В	Brake Terminal
С	



	Α	U Phase
	В	V Phase
	С	W Phase
ĺ	D	FG (Frame Ground)

(3) 8192 PPR Absolute Encoder (15 bit)



Туре	,	LL	LM	LR:	↓ LT	·KB1	KB2	ΙĖ	KL1	KL2			Flange	Dimens	ons .			* * *	Shaft	t End D	imensio	n		Approx. Mass
SGMG-	_	LL	LIVI	LK ·		· ND I	NDZ	IC.	KLI	KLZ	5	LB	LC	LE	LG	LH	LZ	S	ø	QK	W	T	Ü	≇b (kg)
05ASAB	8.27 (210)	5.98 (152)	3.62 (92)	2.28 (58)	2.36 (60)	2.56 (65)	5.16 (131)	•	4.29 (109)	3.46 (88)	5.71 (145)	4.33 (110)_8 _{.035}	5.12 (130)	0.24 (6)	0.47 (12)	6.5 (165)	0.35 (9)	0.75 (19)-3 _{.013}	1.57 (40)	0.98 (25)	020 (5)	020 (5)	0.12 (3)	13 (5.9)
09ASAB	9.17 (233)	6.89 (175)	4.53 (115)	2.28 (58)	2.36 (60)	3.46 (88)	6.06 (154)	•	4.29 (109)	3.46 (88)	5.71 (145)	4.33 (110)_8 ₀₃₅	5.12 (130)	0.24 (6)	0.47 (12)	6.5 (165)	0.35 (9)	0.75 (19)よ ₀₁₃	1.57 (40)	0.98 (25)	020 (5)	0.20 (5)	0.12 (3)	17.6 (8.0)
13ASAB	10.12 (257)	7.83 (199)	5,47 (139)	2.28 (58)	2.36 (60)	4.41 (112)	7.01 (178	-	4.29 (109)	3.46 (88)	5.71 (145)	4.33 (110) \$ ₀₃₅	5.12 (130)	0.24 (6)	0.47 (12)	6.5 (165)	0.35 (9)	0.87 (22) -} ₀₁₃	1.57 (40)	0.98 (25)	0.24 (6)	0.24 (6)	0.14 (3.5)	22 (10)
20ASAB	10.2 (259)	70.9 (1 80)	4.69 (119)	3.11 (79)	2.4 (61)	3.5 (89)	6.26 (159)	•	5.51 (140)	3.46 (88)	7.87 (200)	4.5 (114.3)_8 ₀₂₅	7.09 (180)	0.13 (3.2)	0.71 (18)	9.06 (230)	0.53 (13.5)	1.38 (35)+8 ^{.01}	2.99 (76)	2.36 (60)	0.39 (10)	0.31 (8)	0.20 (5)	30.9 (14)
30ASAB	11.22 (285)	8.11 (206)	5.71 (145)	3.11 (79)	2.4 (61)	4.53 (115)	7.28 (185)		5.51 (140)	3.46 (88)	7.87 (200)	4.5 (114.3)_8 _{.025}	7.09 (180)	0.13 (3.2)	0.71 (18)	9.06 (230)	0.53 (13.5)	1.38 (35)*8 ⁰¹	2.99 (76)	2.36 (60)	0.39 (10)	0.31 (8)	0.20 (5)	40.8 (18.5)
44ASAB	12.56 (319)	9.45 (240)	7.05 (179)	3.11 (79)	2.4 (61)	5.87 (149)	8.62 (219)	•	5.51 (140)	3.46 (88)	7.87 (200)	4.5 (114.3) _{-8.025}	7.09 (180)	0.13 (3.2)	0.71 (18)	9.06 (230)	0.53 (13.5)	1.38 (35)*8 ⁰¹	2.99 (76)	2.36 (60)	0.39 (10)	0.31 (8)	0.20 (5)	52.9 (24)
55ASAB	15.24 (387)	10.79 (274)	8.39 (213)	4.45 (113)	2.4 (61)	6.85 (174)	9.96 (253)	4.92 (125)	5.91 (150)	3.46 (88)	7.87 (200)	4.5 (114.3) _{\$.025}	7.09 (180)	0.13 (3.2)	0.71 (18)	9.06 (230)	0.53 (13.5)	1.65 (42)-0.018	4.33 (110)	3.54 (90)	0.47 (12)	0.31 (8)	0.20 (5)	66.1 (30)
75ASAB	18.15 (461)	13.7 (348)	11.3 (287)	4.45 (113)	2.4 (61)	9.76 (248)	12.87 (327)	4.92 (125)	5.91 (150)	3.46 (88)	7.87 (200)	4.5 (114.3) \$ _{.025}	7.09 (180)	0.13 (3.2)	0.71 (18)	9.06 (230)	0.53 (13.5)	1.65 (42)-8. ₀₁₅	4.33 (110)	3.54 (90)	0.47 (12)	0.31 (8)	0.20 (5)	88.2 (40)
1AASAB	18.43 (468)	13.86 (352)	11.46 (291)	4.57 (116)	24 (61)	9.88 (251)	13.03 (331)	5.59 (142)	6.61 (168)	3.46 (88)	9.25 (235)	7.87 (200).8 ₀₄₆	8.66 (220)	0.16 (4)	0.71 (18)	10.63 (270)	0.53 (13.5)	1.65 (42) \$ _{.016}	4.33 (110)	3.54 (90)	0.47 (12)	0.31 (8)	0.20 (5)	127.9 (58)

Note:

- 1. Absolute Encoder (8192 PPR) is used as a detector.
- 2. SGMG-05A2A to 44A2A do not contain eyebolts.
- 3. Dimensions are the same when using other absolute encoders.
- 4. Tolerances on the dimensions LB of flange type and S of shaft extensions are based on JIS (Japanese Industrial Standard) B0401 "Limits and Fits for Engineering."

 5. There are no dimensional changes on the C∈ products.

Connector Specifications

Receptacle: MS3102A20-29P Applicable Plug: (To be prepared by customer) Plug: MS3108B20-29S (L Type) MS3106B20-29S (Straight Type) Cable Clamp: MS3057-12A





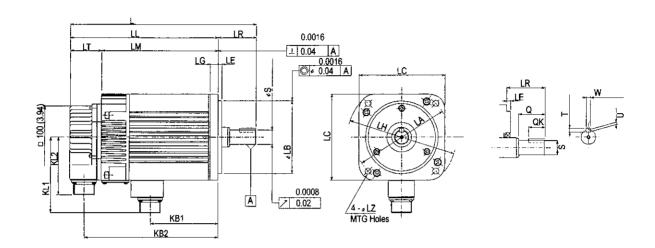
			Connector Wiring on the Incremental Encoder (When using 8192 PPR (15 bits))												
Α	Channel A Output	к	-												
В	Channel A Output	L	-												
С	Channel B Output	М	-												
D	Channel B Output	N	-												
Е	Channel Z (C) Output	P].												
F	Channel Z (C) Output	R	Reset												
G	ov	S	0V (battery)												
Н	+5 VDC	Т	3.6V (battery)												
J	FG (Frame Ground)														

common to all the motors with incremental encoders.

Co	Connector Wiring on the Motor Side									
Α	U Phase									
В	V Phase									
C	W Phase									
D	FG (Frame Ground)									

(4) 8192 PPR Absolute Encoder (15 bit), with Brake

0.5 to 4.4kW (0.7 to 5.9HP)





Type		11 1	-134	ı R		KB1	KB2	KL1	KL2		y lake	lange l	Dimensi	ons		الا مارين د سنده	unany of a	Shaf	t End D	mensio	n , i e	Teledala Nordala	Approx. Mass
SGMG-		.,LE.i.	*LM	LIK	(LLI)	ND I	NDZ :	*FALT	~~****	٠ ١٨ ٥	å. LB∶	LC:	LE	LG	LH:	LΖ	S	a	QK		, T.	~ ∪	lb (kg)
05ASABC	248	190	5.08	2.28	61	2.2	169	4.72	3.46	5.71	4.33	5.12	0.24	0.47	6.5	0.35	0.75	1,57	0.98	0.20	0.20	0.12	17.4
	(9.76)	(7.5)	(129)	(58)	(2.4)	(56)	(6.7)	(120)	(88)	(145)	(110) \$ ₀₃₅	(1 30)	(6)	(12)	(165)	(9)	(19) \$ _{.013}	(40)	(25)	(5)	(5)	(3)	(7.9)
09ASABC	271	213	5.98	2.28	61	3.11	192	4.72	3.46	5.71	4.33	5.12	0.24	0.47	6.5	0.35	0.75	1.57	0.98	020	0.20	0.12	22
	(10.7)	(8.4)	(152)	(58)	(2.4)	(79)	(7.6)	(120)	(88)	(145)	(110) \S_{035}	(130)	(6)	(12)	(165)	(9)	(19)-8 ₀₁₃	(40)	(25)	(5)	(5)	(3)	(9.6)
13ASABC	295	237	6.93	2.28	61	4.06	216	4.72	3.46	5.71	4.33	5.12	0.24	0.47	6.5	0.35	0.87	1.57	0.98	0.24	0.24	0.14	26.5
	(11.6)	(9.3)	(176)	(58)	(2.4)	(103)	(8.5)	(120)	(88)	(145)	(110) \$ ₀₃₅	(130)	(6)	(12)	(165)	(9)	(22) \$ ₀₁₃	(40)	(25)	(6)	(6)	(3.5)	(12)
20ASABC	310	231	6.69	3.11	61	3.11	210	5.75	3.46	7.87	4.5	7.09	0.13	0.71	9.06	0.53	1.38	2.99	2.36	0.39	0.31	0.20	43
	(12)	(9.1)	(170)	(79)	(2.4)	(79)	(8.3)	(1 46)	(88)	(200)	(114.3) _{0.025}	(180)	(3.2)	(18)	(230)	(13.5)	(35)*0°01	(76)	(60)	(10)	(8)	(5)	(19)
30ASABC	336	257	7.72	3.11	61	4.13	236	5.75	3.46	7.87	4.5	7.09	0.13	0.71	9.06	0.53	1,38	2.99	2.36	0.39	0.31	0.20	51.8
	(13)	(10)	(196)	(79)	(2.4)	(105)	(9.3)	(146)	(88)	(200)	(114).3 $^{\circ}_{0.025}$	(180)	(3.2)	(18)	(230)	(13.5)	(35)*0.01	(76)	(60)	(10)	(8)	(5)	(23.5)
44ASABC	370	291	9.06	3.11	61	5.47	270	5.75	3.46	7.87	4.5	7.09	0.13	0.71	9.06	0.53	1.38	2.99	2.36	0.39	0.31	0.20	64
	(15)	(11.5)	(230)	(79)	(2.4)	(139)	(10.6)	(146)	(88)	(200)	(114).3.8 ₀₂₅	(180)	(3.2)	(18)	(230)	(13.5)	(35)*8 ^{.01}	(76)	(60)	(10)	(8)	(5)	(29)

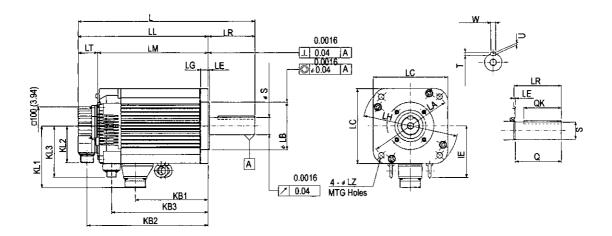
Note:

- 1. Incremental Encoder (8192 PPR) is used as a detector.
- 2. Dimensions are the same when using other incremental encoders.
- 3. Tolerances on the dimensions LB of flange type and S of shaft extensions are based on JIS (Japanese Industrial Standard) B0401 "Limits and Fits for Engineering."
- 4. There are no dimensional changes on the CE products.



	Connector Wiring o	n the M	lotor Side
Α	U Phase	Е	Brake Terminal
В	V Phase	F	Brake Terminal
С	W Phase	G	-
D	FG (Frame Ground)		

5.5 to 11kW (7.4 to 15HP)



Туре	2 7 1	.:				1704	VD0	∠D3	~ ₀ \$	V1.4	1/1.0	KI 3	,	· Serge	vs 13	F	lange E	Dimens	ions	. **;	Ç + 1	1.3	: # ⁵ }	Shaft En	d Dime	nsion	'Approx.'
SGMG-	·· L /	LL	LM.	LR	· L1,	KB1	KB2	KB3	IE.	KL1	KL2	KL3	LA	LB	ÇTC.	%LE~	LF1	LF2	LG	LH	LJ1	LJ2	LZ	8	S	Q	Mess to (kg)
EE LOADO	4.38	325	264	113	61	174	304	231	125	150	88	123	200	114.3	180	3.2	3	0.5	18	230	76	62	13.5	42	45	110	36
55ASABC	(17.24)	(12.80)	(10.39)	(4.45)	(1.85)	(6.85)	(11.97)	(9.09)	(4.92)	(5.91)	(3.46)	(4.84)	(7.87)	(4.5) 8 025	(7.09)	(0.13)	(0.12)	(0.02)	(0.71)	(9.06)	(299)	(2.44)	(0.53)	(1.65).8 _{.016}	(1.77)	(4.33)	(79.4)
7510170	512	399	338	113	61	248	378	305	125	150	88	123	200	114.3	180	32	3	0.5	18	230	76	62	13.5	42	45	110	50
75ASABC	(20.2)	(15.7)	(13.31)	(4.45)	(1.85)	(9.76)	(14.88)	(12.01)	(4.92)	(5.91)	(3.46)	(4.84)	(7.87)	$(4.5)_{-0.025}^{0}$	(7.09)	(0.13)	(0.12)	(0.02)	(0.71)	(9.06)	(2.99)	(2.44)	(0.53)	(1.65) \$ _{.016}	(1.77)	(4.33)	(110.2)
41.40400	513	397	340	116	57	258	376	315	142	168	88	142	235	200	220	4	4		18	270	62		13.5	42	45	110	65.5
1AASABC	(20.2)	(15.6)	(13.39)	(4.57)	(1.69)	(10.16)	(14.80)	(124)	(5.59)	(6.61)	(3.46)	(5.59)	(9.25)	(7.87) \$,046	(8.66)	(0.16)	(0.16)	-	(0.71)	(10.63)	(244)	-	(0.53)	(1.65) ₀₁₆	(1.77)	(4.33)	(144.4)

Note:

- 1. Absolute Encoder (8192 PPR) is used as a detector.
 2. SGMG-05A2A to 44A2A do not contain eyeboths.
 3. Dimensions are the same when using other absolute encoders.
 4. Tolerances on the dimensions LB of flange type and S of shaft extensions are based on JIS (Japanese Industrial Standard) B0401 "Limits and Fits for Engineering."
 5. There are no dimensional changes on the CE products.

Connector Wiring on Brake, Motor Side



Α	Brake Terminal
В	Brake Terminal
С	•

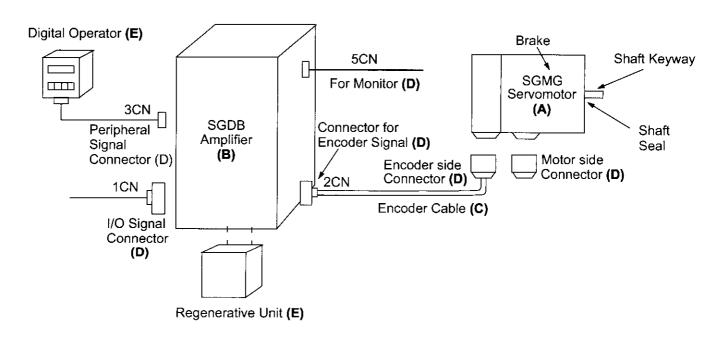


Α	U Phase
В	V Phase
C	W Phase
D	FG (Frame Ground)

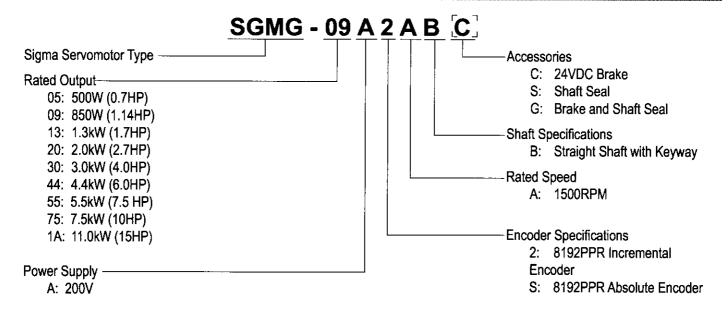
Selecting Your SGMG Sigma Servo System

Use the diagram below to locate and identify the components of your system. Each item is letter-coded and cross-referenced in the option tables on the following pages.

System Configuration



Model Number Designation



Note: Bold items are Stock Products usually available from inventory. Contact your Yaskawa representative for delivery on all other items.

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Servomotor & Amplifier Selection

Use the table below to select the appropriate SGMG Sigma Servomotor and Amplifier.

Description	Peak Torque (in. lb.)	Rated Torque (in. lb.)	Motor Inertia (in. lb. sec ² ¥ 10 ⁻³)	Motor MODEL # (A)	Amplifier MODEL # (B)* Analog/Digital Input SGDB-	Motor & Amplifier Item Class
	79	25	6.41	SGMG-05A2AB	05ADG	
		20	0.41	SGMG-05A2ABC	USABG	
	122	48	12.3	SGMG-09A2AB	10ADG	
	· · · · · · · · · · · · · · · · · · ·	70	12.0	SGMG-09A2ABC	TOADG	
	207	74	18.2	SGMG-13A2AB	15ADG	
200V 3-Phase	207		10.2	SGMG-13A2ABC	ISADG	
8192 PPR	254	102	28.1	SGMG-20A2AB	20ADG	
Incremental	254	102	20.1	SGMG-20A2ABC	2000	
Encoder	404	165	40.7	SGMG-30A2AB	30ADG	
Straight Shaft with	404	103	40.7	SGMG-30A2ABC	SUADG	Stock
Keyway	630	252	59.8	SGMG-44A2AB	44ADG	
3,000 RPM max.	030	232	39.6	SGMG-44A2ABC	44ADG	
	774	0.40		SGMG-55A2AB	60ADG	
MS Connectors	776	310	78.8	SGMG-55A2ABC	Requires Regenerative Unit (E)	:
	4050	405		SGMG-75A2AB	75ADG	
į	1050	425	111	SGMG-75A2ABC	Requires Regenerative Unit (E)	
	1550	1550	240	SGMG-1AA2AB	1AADG	
	1550	620	249	SGMG-1AA2ABC	Requires Regenerative Unit (E)	

Jote: 24VDC brakes for SGMG Sigma servomotors are standard. Contact a local source for 24VDC power supplies. For technical information, request manual number TSE-S800-16 from your Yaskawa representative.

^{*} For more detailed SGDB amplifier specifications and dimensions, refer to page 127.

Pre-wired Cable Selection

Use the table below to select Pre-wired Cables for your SGMG Sigma Servomotor.

		, Motor 🖟	Part N	umber		Item
	scription (C)	Size (kW)	without Brake	with Brake	Comments	Class
		0.5, 0.9, 1.3	B1E-□	B1BE-□		
Power Cable with		2.0, 3.0 4.4	B2E-□ B3E-□	B2BE-□ B3BE-□	Use the following key to	
Connectors		5.5, 7.5 *	B5E-□	B5E-□ B7BE-□	specify required cable length (last digit of part #):	
		11 *	B6E-□	B6E-□ B7BE-□	1: 3 meters 2: 5 meters	
Encoder Cable (incremental or absolute)			DE9407	′237- □ E	3: 10 meters (standard)4: 15 meters5: 20 meters	
Encoder Cable Only for Solder Connections			DP84	09123	Up to 70 feet; for use with mating connector.	
Encoder Cable Only for Solder Connections			DP84	09179	Over 70 feet; splice cable to accommodate connector.	Stock **
Input/Output 1CN Cable & Transition Terminal Block		All	JUSP-	-TA50P	35 mm din rail mountable; the cable length is 0.5 meters.	
Input/Output 1CN Cable with Pigtail Leads			DE940	6969-□	Use the following key to specify required cable length (last digit of part #): 1: 1 meter (standard) 2: 2 meters 3: 3 meters	

- * When ordering these cables for motors with brakes, order the standard power cable and the additional cable for the brake.
- ** Standard cable lengths are Stock items; non-standard cable lengths are Limited Stock items.

Connector Selection

Use the table below to select Mating Connectors for your SGMG Sigma Servomotor.

		Motor		Number :		ltem -
Connector Desc	ription (U)	Size (kW)	without Brake	with Brake	Comments	Class
		0.5, 0.9, 1.3	MS3106B18-10S MS3108B18-10S MS3057-10A	MS3106B20-15S MS3108B20-15S MS3057-12A	Straight-type connector L-type connector Cable clamp	
MS Connector for Motor Power Cable *	272.00	2.0, 3.0, 4.4	MS3106B22-22S MS3108B22-22S MS3057-12A	MS3106B24-10S MS3108B24-10S MS3057-16A	Straight-type connector L-type connector Cable clamp	
		5.5, 7.5, 11	MS3106B32-17S MS3108B32-17S MS3057-20A	MS3106B32-17S+ MS3106A10SL-3S MS3108B32-17S+ MS3108A10SL-3S MS3057-20A MS3057-4A	Straight-type connector L-type connector Cable clamp	
MS Connector for Encoder Cable (incremental or absolute encoder)			MS310	6B20-29S 8B20-29S 057-12A	Straight-type connector L-type connector Cable clamp	Stock
1CN Mating Connector			DE9	406970	Can use 1CN for analog speed and torque monitor service checks.	
2CN Encoder Mating Connector		All	DE9	406973	_	
3CN Peripheral Mating Connector			Stock 9-pin mal	e D-shell connector	Source locally.	-
5CN Connector and 1m Cable with Pigtails			DE9	404559	****	Stock

^{*} Choose either a straight or L-type connector and the associated cable clamp for a complete assembly. For example, L-type connector MS3108B18-10S is compatible with cable clamp MS3057-10A.

Peripheral Device Selection

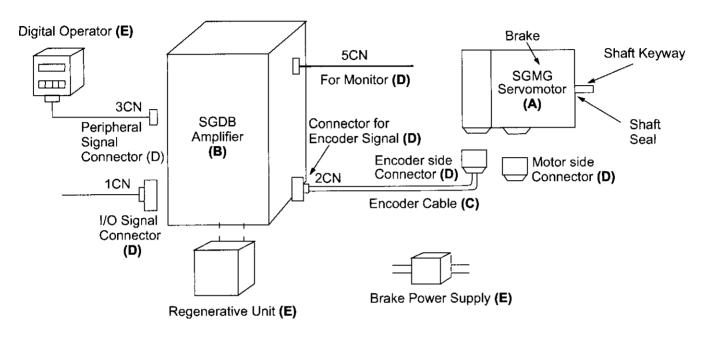
Use the table below to select Peripheral Devices for your SGMG Sigma Servomotor.

Compo	nent (E)	Part Number	Description	Item Class
Hand-held Digital Operator Panel	SERVOPACK SERVOPACK	JUSP-OP02A-1	Portable unit with built-in cable	Stock
Digital Operator Panel	SERVOPACK UP MODESET DOWN OP03A	JUSP-OP03A	Plugs into front of amplifier	Non-Stock
SVMON Software		SVMON	Programming software for DOS 3.3 on a 3.5" floppy disk	
Software Interface Cable		YS-11	Pre-wired 1.5 meter cable with 9-pin connector	
Regenerative Unit for 6.0 kW amplifier (880 watts)		JUSP-RA04	÷	Stock
Regenerative Unit for 7.5 and 11.0kW amplifiers (1760 watts)		JUSP-RA05	-	

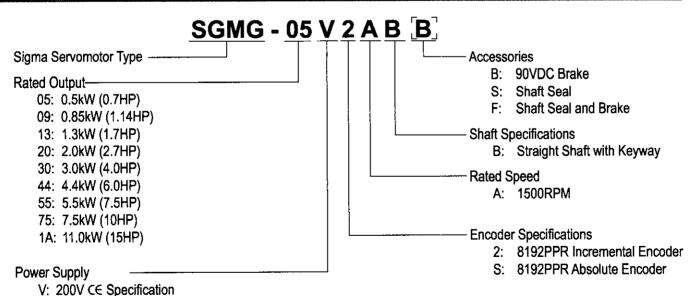
Selecting Your SGMG Sigma Servo System

Use the diagram below to locate and identify the components of your system. Each item is letter-coded and cross-referenced in the option tables on the following pages.

System Configuration



Model Number Designation



Servomotor & Amplifier Selection

Use the table below to select the appropriate SGMG Sigma Servomotor and Amplifier.

Description		Rated Torque	Motor Inertia (in lb: sec ² :x,10 ⁻³)	Motor MODEL#(A)	Amplifier MODEL # (B)* Analog/Digital Input SGDB-	Motor Item Class
	79	25	6.41	SGMG-05V2AB	05VD (Limited Stock)	Limited Stock
				SGMG-05V2ABB	(Littited Stock)	Non-Stock
	122	48	12.3	SGMG-09V2AB	10VD	Limited Stock
				SGMG-09V2ABB	(Limited Stock)	Non-Stock
	207	74	18.2	SGMG-13V2AB	15VD	Limited Stock
200V 3-Phase				SGMG-13V2ABB	(Limited Stock)	Non-Stock
8192 PPR Incremental	254	102	28.1	SGMG-20V2AB	20VD	Limited Stock
Encoder				SGMG-20V2ABB	(Limited Stock)	Non-Stock
Straight Shaft with	404	165	40.7	SGMG-30V2AB	30VD (Limited Stock)	Limited Stock
Keyway				SGMG-30V2ABB	(Limited Stock)	Non-Stock
3,000 RPM max. JL04V Circular	630	252	59.8	SGMG-44V2AB	60VDY6 (Limited Stock)	Limited Stock
Connectors				SGMG-44V2ABB	(Littited Stock)	Non-Stock
	776	310	78.8	SGMG-55V2AB	60VD (Limited Stock)	Limited Stock
				SGMG-55V2ABB	Requires Regen Unit (E)	Non-Stock
	1050	425	111	SGMG-75V2AB	75VD	
				SGMG-75V2ABB	(Non-Stock) Requires Regen Unit (E)	
	1550	620	249	SGMG-1AV2AB	1AVD	Non-Stock
				SGMG-1AV2ABB	(Non-Stock) Requires Regen Unit (E)	

Note: 90VDC brakes for SGMG Sigma servomotors (C€) are standard. See Peripheral Device Selection in this section to order a power supply.

For technical information, request technical document numbers PI-6021 and DE9409784 from your Yaskawa representative.

^{*} For more detailed SGDB amplifier specifications and dimensions, refer to page 127.

Pre-wired Cable Selection

Use the table below to select Pre-wired Cables for your SGMG Sigma Servomotor.

Cable Description (C)		Motor Size (kW)	Part Number		Company of the Section of the Company of the Compan	
			without. Brake	with Brake	Comments	Item Class
Power Cable with Connectors		0.5, 0.9, 1.3	B1CE-□	B1BCE-□		Limited Stock
		2.0, 3.0	B2CE-□	B2BCE-□	Use the following key to specify	
		4.4	В3СЕ-□	ВЗВСЕ-□	required cable length	
		5.5, 7.5, 11	* See note below		(last digit of part #): 1: 3 meters 2: 5 meters	-
Encoder Cable (incremental or absolute)			A10	CE-□	3: 10 meters (standard) 4: 15 meters 5: 20 meters	Limited Stock
Encoder Cable Only for Solder Connections			DP8409123		Up to 70 feet; for use with mating connector.	Stock **
Encoder Cable Only for Solder Connections			DP8409179		Over 70 feet; splice cable to accommodate connector.	
Input/Output 1CN Cable & Transition Ter- minal Block	999	Ali	JUSP-TA50P		35 mm din rail mountable; the cable length is 0.5 meters.	
Input/Output 1CN Cable with Pigtail Leads			DE940	6969-□	Use the following key to specify required cable length (last digit of part #): 1: 1 meter (standard) 2: 2 meters 3: 3 meters	fy

^{*} Pre-wired cables for motors with brakes (5.5, 7.5 & 11kW) are not available, since the applicable mating connectors are compatible with a conduit connection.

^{**} Standard cable lengths are Stock items; non-standard cable lengths are Limited Stock items.

Mating Connector Selection

Use the table below to select Mating Connectors for your SGMG Sigma Servomotor.

Connector Disco	intion (D)	Motor Size	Part N	lumber	Comments	Item
Connector Description (D)		(kW)	without Brake	with Brake	Comments	Class
	.ø	0.5, 0.9, 1.3	JL04V-8A18-10SE-EB JL04-18CK(13)	JL04V-8A20-15SE-EB JL04-2022CK(14)	L-type connector Cable clamp	
	@ 1 0,000 (a 0,000)	2.0, 3.0, 4.4	JL04V-8A22-22SE-EB JL04-2022CK(14)	JL04V-8A24-10SE-EB JL04-2428CK(17)	L-type connector Cable clamp	
Connector for Motor Power Cable *			JL04V-6A32-17SE	JL04V-6A32-17SE	Straight-type connector	
		5.5, 7.5, 11	-	_	No cable clamp, conduit coupled 1.875 inches 16UN-2A	
Connector for Encoder Cable (incremental or absolute encoder)			JA08A-20-29S-J1-EB JL04-2022CKE(12)		L-type connector Cable clamp	Limited Stock
1CN Mating Connector			DE94	Can use 1CN for analog speed and torque mon- itor service checks.		
2CN Encoder Mating Connector		All	DE9406973		_	
3CN Peripheral Mating Connector			Stock 9-pin male D-shell connector		Source locally.	-
5CN Connector and 1m Cable with Pigtails			DE94	-	Limited Stock	

^{*} Choose the connector and the associated cable clamp for a complete assembly.

