1

# 8BVI0440HWSS.000-1

## **1** General information

- Clearly structured, straightforward implementation via network-based safety technology
- Modular expandability through virtual wiring
- Immediate triggering of safety function thanks to short cycle times
- · Easy implementation with transparent control and status information in the standard application as well
- Compact design

## 2 Order data

Model number	Short description	S.	Figure	
30.	Wall mounting	5		.0
8BVI0440HWSS.000-1	ACOPOSmulti inverter unit, 44 A, HV, wall mounting, SafeMC EnDat 2.2		INTER CONTRACTOR	.295
de.	Required accessories			A.
all a second	Terminal block sets			550
8BZVI0440SS.000-1A	Screw clamp set for ACOPOSmulti 8BVI0440HxSS and 8BVI0440HxSA modules: 1x 8TB2108.2010-00, 1x 8TB2104.203L-00, 1x 8TB4104.204G-10			
NO.	Optional accessories			
20	Fan modules			
8BXF001.0000-00	ACOPOSmulti fan module, replacement fan for ACOPOSmulti modules (8BVP / 8B0C / 8BVI / 8BVE / 8B0K)			300
	Plug-in modules			200
8BAC0120.000-1	ACOPOSmulti plug-in module, EnDat 2.1 interface			14
8BAC0120.001-2	ACOPOSmulti plug-in module, EnDat 2.2 interface			Sec.
8BAC0121.000-1	ACOPOSmulti plug-in module, HIPERFACE interface		20	20
8BAC0122.000-1	ACOPOSmulti plug-in module, resolver interface 10 kHz			
8BAC0123.000-1	ACOPOSmulti plug-in module, incremental encoder and SSI ab- solute encoder interface for RS422 signals			
8BAC0123.001-1	ACOPOSmulti plug-in module, incremental encoder interface for 5 V single-ended and 5 V differential signals			
8BAC0123.002-1	ACOPOSmulti plug-in module, incremental encoder interface for 24 V single-ended and 24 V differential signals			100 St.C
8BAC0124.000-1	ACOPOSmulti plug-in module, SinCos interface			. S
8BAC0125.000-1	ACOPOSmulti plug-in module, SinCos EnDat 2.1/SSI interface			Ser.
8BAC0130.000-1	ACOPOSmulti plug-in module, 2 digital outputs, 50 mA, max. 62.5 kHz, 2 digital outputs, 500 mA, max. 1.25 kHz,2 digital in- puts 24 VDC			34
8BAC0130.001-1	ACOPOSmulti plug-in module, 2 digital outputs, 50 mA, max. 62.5 kHz, 4 digital outputs, 500 mA, max. 1.25 kHz			
8BAC0132.000-1	ACOPOSmulti input module, 4 analog inputs ±10 V			
8BAC0133.000-1	ACOPOSmulti plug-in module, 3 RS422 outputs for ABR en- coder emulation, 1 Mhz			a Sto
1	POWERLINK cables			.81
X20CA0E61.00020	POWERLINK connection cable, RJ45 to RJ45, 0.20 m			all'
X20CA0E61.00025	POWERLINK connection cable, RJ45 to RJ45, 0.25 m			15 <sup>24</sup>
X20CA0E61.00030	POWERLINK connection cable, RJ45 to RJ45, 0.30 m			
X20CA0E61.00035	POWERLINK connection cable, RJ45 to RJ45, 0.35 m			
X20CA0E61.00050	POWERLINK connection cable, RJ45 to RJ45, 0.50 m			
X20CA0E61.00100	POWERLINK connection cable, RJ45 to RJ45, 1.00 m			
18 C	Shield component sets			
8SCS002.0000-00	ACOPOSmulti shield component set: 1x clamping plate; 2x clamps D 4-13.5 mm; 4x screws			350
8SCS007.0000-00	ACOPOSmulti shield component set: 1x shield mounting plate 2x 45°; 4x screws			A. I.C.
8SCS008.0000-00	ACOPOSmulti shield component set: 1x shield plate 2x type 0; 1x hose clamp, B 9 mm, D 23-35 mm			al an
8SCS010.0000-00	ACOPOSmulti shield component set: 1x ACOPOSmulti holding plate SK14-20; 1x shield terminal SK20			
NO.	Terminal blocks			
8TB2104.203L-00	Screw clamp 4-pin, single row, spacing: 5.08 mm, label 3: T- T + B- B+, L coding: 1010			

Table 1: 8BVI0440HWSS.000-1 - Order data

Model number	Short description	Figure
8TB2108.2010-00	Screw clamp 8-pin, single row, spacing: 5.08 mm, label 1: num- bered serially	18 <sup>0</sup>
8TB4104.204G-10	Screw clamp 4-pin, single row, spacing: 10.16 mm, label 4: PE W V U, G coding: 0110	Lon alter

Table 1: 8BVI0440HWSS.000-1 - Order data

## 3 Technical data

Product ID	8BVI0440HWSS.000-1	
General information		
B&R ID code	0xAA20	
Cooling and mounting method	Wall mounting	à
Slots for plug-in modules	2 1)	
Certification	all all all	St.
cULus	Yes	12
DC link connection		
Voltage		
Nominal	750 VDC	
Continuous power consumption <sup>2)</sup>	32.5 kW	
Power loss depending on the switching frequency <sup>3)</sup>		
Switching frequency 5 kHz	$[0.07*I_{M}^{2}+7.3*I_{M}+40]$ W	
Switching frequency 10 kHz	[0.2*I <sub>M</sub> <sup>2</sup> +11.1*I <sub>M</sub> +130] W	
Switching frequency 20 kHz	[1.85*I <sub>M</sub> <sup>2</sup> +3.8*I <sub>M</sub> +300] W	- 20.
DC link capacitance	990 µF	all'
Design	ACOPOSmulti backplane	35 <sup>50</sup>
24 VDC supply		
Input voltage	25 VDC ±1.6%	
Input capacitance	32.9 µF	
Max. power consumption	31 W + P <sub>SMC1</sub> + P <sub>SLOT2</sub> + P <sub>24 V Out</sub> + P <sub>HoldingBrake</sub> + 2 * P <sub>Fan8BOM</sub> <sup>4</sup> )	
Design	ACOPOSmulti backplane	
24 VDC output	0 <u>,</u> 0 <u>,</u> 0 <u>,</u>	
Quantity	2	~
Output voltage	. Š Š.	S.
DC link voltage (U <sub>DC</sub> ): 260 to 315 VDC	25 VDC * (U <sub>DC</sub> /315)	2241
DC link voltage (U <sub>DC</sub> ): 315 to 800 VDC	24 VDC ±6%	
Fuse protection	250 mA (slow-blow) electronic, automatic reset	
Motor connection <sup>5)</sup>		
Quantity	1	
Continuous power per motor connection <sup>2)</sup>	32 kW	
Continuous current per motor connection <sup>2)</sup>	44 A <sub>eff</sub>	
Reduction of continuous current depending on the		
switching frequency <sup>6)</sup>		
Switching frequency 5 kHz	1.57 A/K (from 40 °C) 7)	
Switching frequency 10 kHz	0.5 A/K (from -10 °C) <sup>8)</sup>	Shi
Switching frequency 20 kHz	0.36 A/K (from -77 °C) <sup>8)</sup>	Sec.
Reduction of continuous current depending on the		
altitude		
Starting at 500 m above sea level	4.4 A <sub>eff</sub> per 1000 m	
Peak current	88 A <sub>eff</sub>	
Nominal switching frequency	5 kHz	
Possible switching frequencies 9)	5/10/20 kHz	
Electrical stress of the connected motor in accor- dance with IEC TS 60034-25	Limit value curve A	8
Protective measures	and	Ser.
Overload protection	Yes	
Short circuit and ground fault protection	Yes	
Max. output frequency	600 Hz <sup>10</sup>	
Design	Sa Sa Sa	
U, V, W, PE	Plug	
Shield connection	Yes	
Terminal connection cross section	(d) (d) (d)	
Flexible and fine wire lines	1. 18 <sup>1</sup> . 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1.	
With wire end sleeves	0.5 to 16 mm <sup>2</sup>	
Approbation data	addit addit addit	
UL/C-UL-US	20 to 6	18th
CSA	20 to 6	-
Terminal cable cross section dimension of the	23 to 35 mm	
shield connection	Ý., Ý., Ž., Ž.,	

Table 2: 8BVI0440HWSS.000-1 - Technical data

Product ID	8BVI0440HWSS.000-1	
Max. motor line length depending on the switching	All Marine Marine	
frequency		
Switching frequency 5 kHz	25 m	
Switching frequency 10 kHz	25 m	
Switching frequency 20 kHz	25 m	.82
Motor holding brake connection	All All	AL.
Quantity	8 8 1 8	22
Output voltage <sup>11)</sup>	24 VDC +5.8% / -0% <sup>12)</sup>	
Continuous current	42A	
Max internal resistance	0.15.0	
Extinction potential		
Max autination anarry per awitabing eneration		
Max. extinction energy per switching operation	5 WS	
Max. switching frequency	0.5 Hz	
Protective measures		200
Overload and short circuit protection	Yes	<u></u>
Open line monitoring	Yes	Stor.
Undervoltage monitoring	Yes	Sec.
Response threshold for open line monitoring	Approx. 0.5 A	
Response threshold for undervoltage monitoring	24 VDC +0% / -4%	
Encoder interfaces <sup>13)</sup>		
Quantity	N. N.	
Туре	EnDat 2 2 <sup>14</sup> )	1
Connections	Q_nin DQLIR sockat	
Indicatore		
Inucators	UP/DN LEDS	200
Encoder - ACOPOSmulti	No	22
Encoder monitoring	Yes	St.
Max. encoder cable length	100 m	
	Depending on the cross section of the supply wires on the encoder cable <sup>15</sup> )	
Encoder supply		
Output voltage	Typ. 12.5 V	
Load capability	350 mA	
Protective measures		
Short circuit protection	Yes	~
Overload protection	Yes	200
Synchronous sorial interface	100	20
Signal transmission	DS485	255
Signal transfer rete	R0400	24
	0.25 MDIVS	
Max. power consumption per encoder interface	$P_{SMC}[W] = 19 V * I_{Encoder}[A]^{(6)}$	
Trigger inputs		
Quantity	2	
Wiring	Sink	
Electrical isolation	· · · · · · · · · · · · · · · · · · ·	
Input - Inverter module	Yes	i i i
Input - Input	No	.200
Input voltage	A. The second	- A.
Nominal	24 VDC	Ser.
Maximum		La
Switching threshold	00 400	
	-EV	
LUW	V C>	
nig()	V CI <	
Input current at nominal voltage	Approx. 10 mA	
Switching delay	(O) (O)	
Positive edge	52 $\mu$ s ± 0.5 $\mu$ s (digitally filtered)	
Negative edge	53 μs ± 0.5 μs (digitally filtered)	
Modulation compared to ground potential	Max. ±38 V	A.
Operating conditions		554
Permitted mounting orientations		
Hanging vertically	Yes	
l ving horizontally	Vee	
Standing horizontally	No	
	INU	
installation at altitudes above sea level		
Nominal	0 to 500 m	
Maximum <sup>17)</sup>	4000 m	a di
Degree of pollution in accordance with EN 60664-1	2 (non-conductive pollution)	.87
Overvoltage category in accordance with IEC	14. III 14.	Ali
60364-4-443:1999	and and and	Sal
Protection in accordance with EN 60529	IP20 <sup>18)</sup>	

Table 2: 8BVI0440HWSS.000-1 - Technical data

Product ID	2	8BVI0440HWSS.000	-1	
Environmental conditions	- Ale		Kon	
Temperature		a construction of the second sec	all and a second s	
Operation	×011			
Nominal	and the second sec	5 to 40°C		
Maximum <sup>19)</sup>	. 80	55°C		· 60°
Storage	all'	-25 to 55°C		and in
Transport	San	-25 to 70°C		-5 <sup>23</sup>
Relative humidity				
Operation		5 to 85%		
Storage	() ()	5 to 95%		
Transport	No. 1	Max. 95% at +40°C	: Nor	
Mechanical characteristics		18 A.	1997 - C.	
Dimensions 20)	30.	30,	-8	
Width	25°	106.5 mm		o,
Height		317 mm		. S
Depth	A. C.			N
Wall mounting	524	263 mm		52
Weight		Approx. 5.4 kg	-4	
Module width		2		

#### Table 2: 8BVI0440HWSS.000-1 - Technical data

1) SLOT 1 of the ACOPOSmulti module is occupied by the encoder interface.

 Valid in the following conditions: Bus voltage 750 VDC, switching frequency 5 kHz, 40°C ambient temperature, installation altitudes <500 m above sea level, no derating dependent on cooling type.

3) I<sub>M</sub> ... Current on the motor connection [A].

4) P<sub>SMC1</sub> ... Max. power consumption P<sub>SMC</sub> [W] of the SafeMC module in SLOT1 (see the section "Encoder interfaces")

P<sub>SLOT2</sub> ... Max. power consumption P<sub>BBAC</sub> [W] of the plug-in module in SLOT2 (see the technical data for the respective plug-in module)

 $P_{24 \vee Out}$  ... Power [W] that is output to the connections X2/+24 V Out 1 and X2/+24 V Out 2 on the module (max. 10 W)

- P<sub>Fan8B00...</sub>... Portion of the power [W] that is used by the fan modules in the mounting plate or the 8B0M0040HFF0.000-1 fan module (see the technical data for the respective 8B0M... mounting plate / 8B0M0040HFF0.000-1 fan module)
- 5) B&R 8BCM motor cables must be used when cabling the motor connections.

6) Valid in the following conditions: DC bus voltage 750 VDC The temperature specifications are based on the ambient temperature.

7) Value for the nominal switching frequency.

8) The module cannot supply the full continuous current at this switching frequency. This unusual value for the ambient temperature, at which a derating of the continuous current must be accounted for, ensures that the derating of the continuous current can be determined in the same manner as at other switching frequencies.

9) B&R recommends operating the module at nominal switching frequency. Operating the module at a higher switching frequency for application-specific reasons reduces the continuous current and increases the CPU load.

10) The module's electrical output frequency (SCTRL\_SPEED\_ACT \* MOTOR\_POLEPAIRS) is monitored to protect against dual-use in accordance with EC 428/2009 | 3A225. If the electrical output frequency of the module exceeds the limit value of 600 Hz uninterrupted for more than 0.5 s, then the current motion is aborted and error 6060 is output (Power element: Limit speed exceeded).

11) During project development, it is necessary to check if the minimum voltage can be maintained on the holding brake with the specified wiring. The operating voltage range of the holding brake can be found in the user's manual for the respective motor.

12) The specified values is only valid under the following conditions:

- The 24 VDC supply for the module is provided by an 8B0C auxiliary supply module installed on the same mounting plate.

If the 24 VDC supply for the module is applied to the mounting plate using an 8BVE expansion module, then the output voltage is reduced because of voltage drops on the expansion cable. In this case, undervoltage monitoring must be deactivated.

- 13) B&R 8BCF EnDat 2.2 cables must be used when cabling the encoder interfaces.
- 14) An EnDat 2.2 functional safety encoder is required when using ACOPOSmulti with SafeMC! With standard EnDat 2.2 encoders, only the timing of the functions STO, SBC and SS1 is monitored!
- 15) The maximum encoder cable length I<sub>max</sub> can be calculated as follows (the maximum permissible encoder length of 100 m must not be exceeded):

 $I_{max} = 7.9/I_{G} * A * 1/(2*\rho)$ 

I<sub>G</sub> ... Max. current consumption of the encoder [A]

A ... Cross section of the supply wire [mm<sup>2</sup>]

 $\rho$  ... Specific resistance [ $\Omega$ mm<sup>2</sup>/m] (e.g. for copper:  $\rho$  = 0.0178)

- 16) I<sub>Encoder</sub> ... Max. power consumption of the connected encoder [A].
- 17) Continuous operation at altitudes ranging from 500 m to 4,000 m above sea level is possible (taking the continuous current reductions listed into consideration).
  18) This value only applies with the factory settings (SLOT2 of the module is sealed by a slot cover shield plate). If SLOT2 on the module is not sealed, then the protection level is reduced to IP10. For this reason, we recommend only removing the slot cover shield plate if an ACOPOSmulti plug-in module is being used in SLOT2.

19) Continuous operation at ambient temperatures ranging from 40°C to max. 55°C is possible (taking the continuous current reductions listed into consideration), but results in a shorter lifespan.

20) The dimensions define the true device dimensions including the respective mounting plate. Make sure to leave additional space above and below the devices for mounting, connections and air circulation.





Figure 1: Dimension diagram and installation dimensions

1) n... Necessary width (slots) of the mounting plate.

2) For proper air circulation, at least 60 mm clearance must be available above and below the module.

To ensure that the fan modules in the mounting plate can be replaced easily, at least 250 mm clearance must be available below the module. 3) nnnn indicates the number of slots (e.g. 0160 refers to 16 slots).

## 5 Wiring: Safe double-width inverter modules (single-axis modules)

### 5.1 Overview of pin assignments



Figure 2: Overview of pin assignments

#### 5.2 X2 connector - Pinout

S.	X2	3	Pin	Name	Function
ç.	30	32	1	Trigger 1	Trigger 1
		202	2	COM (1)	Trigger 1 0 V
		19. I	3	COM (2)	+24 V output 1 0 V
	2	25	4	+24V Out 1	+24 V output 1
	3	2	5	Trigger 2	Trigger 2
	4		6	COM (5)	Trigger 2 0 V
			7 👌	COM (8)	+24 V output 2 0 V
			8	+24V Out 2	+24 V output 2
	8	. dpallo	Lato.	dbauton	at

Table 3: X2 connector - Pinout

#### 5.3 X3A, X3B connectors - Pinout

20	X3A, X3B	9	Pin	Name	Function
S	1. S. C.		<u> </u>	RXD	Receive signal
50			2	RXD\	Receive signal inverted
2			3	TXD	Transmit signal
		. N. C.	4	Shield	Shield
		35	5	Shield	Shield
		1	6	TXD\	Transmit signal inverted
			7	Shield	Shield
2		2	8	Shield	Shield



#### 5.4 X4A connector - Pinout

	X4A	12	Name	Function	A.	120
	-4.		T-	Axis 1: Temper	ature sensor -	
À			T+	Axis 1: Temper	ature sensor +	
			B- 1)	Axis 1: Brake -		Q.
No.			B+ 1)	Axis 1: Brake +	Nº.	
100			100	13		
R.O.			Stor.			
	B+ B- T+ T-					

Table 5: X4A connector - Pinout

1) Wiring is not permitted to exceed a total length of 3 m.

## Danger!

The functional fail safe state is enabled if the SBC output B+ is shorted to 24V (i.e. safe pulse disabling is activated). However, the brake always remains on because of the short circuit to 24V!

This can lead to dangerous situations because the motor holding brake is not able to stop the coasting down movement!

Appropriate wiring measures must be implemented to ensure that the SBC output B+ is not shorted to 24V!

## Danger!

The SBC output

- is not permitted to be wired across multiple modules!
- is not permitted to be wired as an open emitter!
- is not permitted to be wired as an open collector!

## Information:

The transistors of the SBC output stage are tested cyclically. When the output channels are active, this test emits low pulses on the output with a maximum length of 600  $\mu$ s.

This must be taken into consideration when choosing the motor holding brake!

## Danger!

The connections for the motor temperature sensors and the motor holding brake are safely isolated circuits. These connections are therefore only permitted to be connected to devices or components that have sufficient isolation in accordance with IEC 60364-4-41 or EN 61800-5-1.

## **Caution!**

If B+ and B- are swapped when connecting the permanent magnet holding brakes, then the brakes cannot be opened! ACOPOSmulti inverter modules cannot determine if a holding brake is connected with reverse polarity!

## Warning!

Temperature sensors are only permitted to be connected to the X4A/T+ and X4A/T- connectors on an ACOPOSmulti module under the following conditions:

• There is no ACOPOSmulti plug-in module in SLOT1 on the ACOPOSmulti module with a temperature sensor connected to T+ and T-.

Otherwise, the temperature monitoring functions on the ACOPOSmulti module may become ineffective, which in extreme cases can cause the hardware (e.g. motors) connected to the ACOPOSmulti module to be destroyed!

### 5.5 X5A connector - Pinout



Table 6: X5A connector - Pinout

## Warning!

B&R 8BCM motor cables must be used when cabling the motor connections.

#### 5.6 Pinout - SafeMC module

Figure	X11 (X12)	Pin	Name	Function		
	S.	1	U+	Encoder supply +12.5 V	18 M 19 M	
EnDat 2.2 Safety		2		0	202	
		3				. 2
6		4	D	Data input	. S <sup>2</sup>	6.
		5	T	Clock output	St.	and and
(0)	1 •	6	COM (1)	Encoder supply 0 V	20	250
	• • •	7				
		8	D\	Data input inverted		
46		9	Σ_ π	Clock output inverted	S	
	5 0	la contra c	www.cdpautomature	www.iobaltomaste	WHIGH BUILDING WAL	and and a second se

9

## Information:

The SafeMC module is only permitted to be used together with 8BCF EnDat 2.2 cables!

### Note:

The SafeMC modules cannot be replaced! SafeMC modules and the corresponding inverter module form a single unit. In the event of an error, the entire inverter module must be replaced.